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(US). GRIECO, Christopher, J. [US/US]; 340 Sycamore Drive, Buelton, CA 93424 (US).

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(74) Agent: LAMB, Owen; c/o Zenz - Patent- und Rechtsanwälte, Huyssenallee 58 - 64, 45128 Essen (DE).

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(71) Applicant (for all designated States except US):  
DEHLSEN ASSOCIATES, L.L.C. [US/US]; 6305  
Carpinteria Avenue, Suite 300, Carpinteria, CA 93013  
(US).

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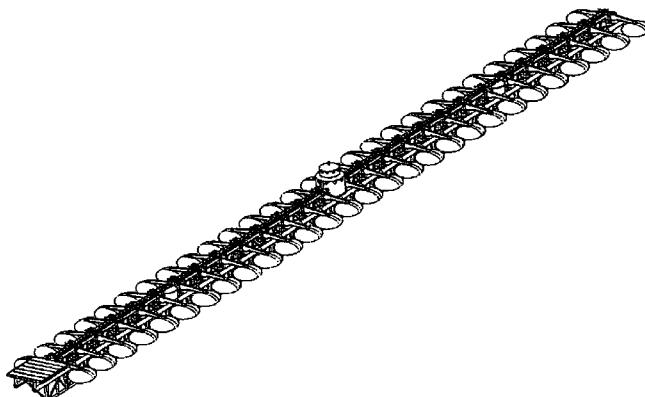
(72) Inventors; and

(75) Inventors/Applicants (for US only): DEHLSEN, James, G., P. [US/US]; 1505 Monte Vista, Montecito, CA 93108 (US). DEHLSEN, James, B. [US/US]; 1505 Monte Vista, Montecito, CA 93108 (US). BROWN, Matthew [US/US]; 4621 Pescadero Ave., San Diego, CA 92107

[Continued on next page]

(54) Title: METHOD AND APPARATUS FOR CONVERTING OCEAN WAVE ENERGY INTO ELECTRICITY

Fig. 40



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(57) Abstract: A power-generating device located in or on the surface of the ocean for generating power utilizing the energy in ocean wave motion. The device is moored to the bow and stern at ~45° to incoming ocean waves, and with a yawing capability to adjust to change in wave direction. The device delivers power to a shore grid via a submarine cable from a generator. A rotational driving torque to the generator is produced by two long counter-rotating drive tubes, which are held by bearings in the bow hull and the stern hull of the device. As an alternative, hydraulics may be employed for energy capture and power smoothing and used to provide the rotational torque through a hydraulic motor to drive a generator. The main body is partially submerged and has multiple pod floats connected to the structure by rocker arms with bearings through which the drive tubes pass or double-acting hydraulic rams between the arms and the main body which capture energy through pod displacement and store it in accumulators. Rotary torque of the drive tubes is produced when the pods move up and down according to motion of the waves and is transmitted to the generator to generate power. In the hydraulic case, energy is stored in accumulators as pressure due to the double-acting hydraulic pistons pumping when the pods move up and down according to the motion of the waves. Hydraulic pressure drives a pump, which provides torque to the generator.



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**METHOD AND APPARATUS FOR CONVERTING OCEAN WAVE ENERGY INTO  
ELECTRICITY**

**BACKGROUND OF THE INVENTION**

5 The present invention relates to a device, which captures energy resident in the motion of ocean waves to rotate a generator and thereby generate electrical power.

A wave energy converter (WEC) captures energy from ocean surface waves, usually for electricity generation. Of the 10 solar energy forms, the energy of the waves provides the highest energy density. However, prior attempts at wave power generation have not been widely accepted for various reasons.

Wave power is available in low-speed, high forces, and the motion of forces is not in a single direction. Most 15 commercial electric generators operate at higher speeds, and require a steady flow of source energy. Furthermore any apparatus deployed on the ocean must be able to survive severe storms, raising the cost of manufacture and maintenance.

The key to commercial viability of wave technology is a 20 competitive levelized cost of energy (LCOE). Wave power is competitive when the total cost of power generation is low. The total cost includes the capital costs, maintenance costs and electric power delivery costs, and this in relation to the 25 electric power generated, determines the "life-cycle" cost of energy. It is therefore desirable to provide a method and apparatus of obtaining optimum energy extraction from ocean waves at the least cost for the generating system.

The system must have minimal impact on the marine environment, such as fishing grounds and beach shoreline and 30 must not interfere with ocean navigation.

United States Patent 4,851,704 to Rubi, titled "Wave action electricity generation system and method" discloses a wave action electricity generation system that includes a floating platform that supports the system components on the 35 water. Wave motion energy is converted into mechanical energy

and an electricity generator converts the mechanical power transfer strokes into electrical energy.

The converter includes a cylinder containing a lubricant, in opposed cylinder chamber portions, a first 5 heavily weighted piston that is slidably and freely disposed within the body of the cylinder. The heavily weighted piston is slidably responsive to the wave motion energy of the body of water and is used to compress the fluid to produce respective compression power strokes in each of the cylinder 10 chamber portions. The energy in the compression stroke is received by a second and third pistons located in the cylinder chamber portions that further produce power transfer strokes through the ends of the cylinder. The power transfer strokes associated with the first and second pistons are further 15 converted by a geared transmission to rotary motion that turns a flywheel coupled to an electricity generator. The electrical energy produced is then distributed to a remote power station via a power transmission line.

United States Patent 5,889,336 to Tateishi "Power 20 generating installation" discloses a power generating installation located in a shallow water area of the sea for generating power utilizing a shallow water wave. The system comprises a mooring located either in the sea or at the sea bottom, a chain having one end connected with the mooring and 25 the other end to which a dead-weight is attached. A float is provided with a generator and a rotary member for rotating engaged with the chain. Rotary force of the rotary member produced when the float moves up and down according to an up-and-down motion of the wave is transmitted to the generator, 30 thereby to generating power.

United States Patent 7,453,165 to Hench "Method and apparatus for converting ocean wave energy into electricity" discloses a method for harnessing power associated with ocean waves and converting that power into electricity. The 35 apparatus is a buoy that houses a vertically oriented central shaft, a pendulum, and a generator. As the buoy tilts from the vertical under the influence of wave motion, the pendulum is

accelerated and rotates about the central shaft. A centrally placed generator is mechanically driven by the rotating pendulum so that the pendulum's kinetic energy is converted into electricity.

5 The prior art systems are not capable of producing cost-effective, utility-scale power output to meet modern energy needs.

What is needed is a power-generating device for capturing power from ocean wave motion that provides a stable 10 platform and allows the mechanically linked floats (or buoys) to have maximum exposure to wave action and thereby energy capture.

It is further desirable to provide a method of capturing energy from ocean waves that is efficient, cost effective to 15 manufacture and maintain and is capable of withstanding severe weather events.

It is desirable to have a method and apparatus that is scalable to gain economies in deployment and servicing of the wave energy converter.

20 It is desirable to provide a method and apparatus of placing a wave energy converter in such a configuration that it is capable of being transported to and from port without interference with ocean navigation.

It is also desirable for the wave energy converter to 25 have an active yaw system to enable optimum/maximum exposure to oncoming waves to maximize energy capture.

The invention relates to an apparatus for generating power utilizing ocean waves. According to one aspect of the invention a plurality of force-transmitting floating pods 30 (buoys) engage a rotary shaft. The rotary shaft drives a generator. The rotary shaft produces a rotary force when the pods move up and down according to an up-and-down motion of an ocean wave. The rotary force is transmitted to the generator to thereby cause the generator to generate power.

35 In accordance with another of the invention, a hydraulic system provides for energy capture in both upward and downward pod motion.

According to the invention floating pods are used which are moving in an up-and-down motion as the waves pass. The pods are coupled or connected to a lever assembly, for example an arm made of a rigid material. The pods are arranged along 5 an elongated base, which may be an open lattice structure allowing waves to pass through it to activate the pods on the opposite side. The length of the base and the number and size of the pods depend on the expected frequency, wavelength, and amplitude of the waves in the target area. The base may be 10 long enough to straddle a multiple of waves, e.g. 2 to 3 long waves thereby minimizing "pitching" of the base, allowing maximum energy capture by the pods. Along the base (e.g. a V-shaped or Box Shape structure), a number of the power generating components are placed. In the case of a mechanical 15 coupling between the arm/lever of the pods and the power generating system the torque transmitting shafts extend along the elongated base. There may be multiple bases rigidly coupled together in order to build a structure extending over several long waves. In the case of a coupling of the 20 arms/levers of the pods to a hydraulic system the base comprises or houses hydraulic cylinders, which are actuated by the force exerted by the moving pods and transmitted by the arms/levers. The base therefore provides a point of application of the leverage force since it does not follow the 25 up-and-down motion of the waves in the same way as the pods. Since the base extends over at least a considerable part of the wavelength of the waves (or even over more than one wavelength) the forces acting on the base are always different from those acting on a single pod (which is extends only over 30 a small fraction of the wavelength). Therefore the pods are moving up and down relative to the base. Since the arms/levers of the pods are coupled to the base so that they are pivotable, they can exert a leverage force on the force transmitting elements.

35 It is therefore one key feature of the invention to couple a multiple of pods to a common open lattice structure. Since the structure extends over a full wavelength or more

than one wavelength, different pods do experience different wave heights or amplitudes. This means the structure as such does not follow the wave motion as the pods do. This gives rise to a relative movement of the pods and the rest of the 5 structure, which in turn is converted into a leverage force and further in rotational torque or into hydraulic pressure.

The structure will actively yaw to be at an angle (~45°) to the oncoming waves in order to optimize exposure to the wavefront and period between waves for minimum pitching and 10 maximum energy capture. As wave direction changes, the system will yaw accordingly.

The base may comprise passive floating elements itself in order to provide for buoyancy. However, the base may also be supported solely by means of the pods coupled to the base. 15

The pods may be made of any appropriate material, which can stand seawater and mechanical stress. The shape of the pods is optimized for wave lift and travel. The pods may be rotated relative to their attached arms (or levers) to facilitate towing from port to the deployment site, or to 20 minimize wave loading under extreme sea states. The pods may have a chamber that can be flooded to allow the entire wave converter system to submerge below potentially damaging wave orbitals.

Along the base the pods may be arranged on two opposite 25 sides of the base thereby keeping the base in balance and providing for a counterforce against the pods on the other side of the base. The open lattice base to which the pods are attached allows waves to pass through the base structure to freely activate pods on the opposite side.

30 The design and operational approach according to the invention avoids structural concepts requiring extensive use of structural materials to resist bending, hogging, and torsion loads to sustain extreme wave loads from the 50-year return wave. The invention does this by providing a 35 compliantly moored backbone structure, with the pods riding on the waves. While some of the loads get transferred to the backbone, the power conversion system controls these loads by

providing the pods less and less resistance as the wave height increases (resulting in a constant power output). Another method to withstand extreme wave loads is to partially flood the pods and allow the wave converter system to submerge to a 5 depth out of the range of the extreme surface wave forces. As the extreme sea state normalizes, the flooded pods are charged with air pressure to evacuate the seawater, and the system resurfaces.

Due to the length of the structure the pitching in 10 minimized which in turn leads to greater energy capture of the apparatus.

In accordance with yet another aspect of the invention a hydraulic system controls the movement of the pods by using the energy of a wave to activate the hydraulic system and a 15 hydraulic turbine such as an impulse turbine or hydraulic motor connected to an electric generator.

In accordance with a further aspect of the invention the hydraulic system includes an impulse turbine and a impulse turbine nozzle in circuit with a pod hydraulic system, which 20 automatically adjusts the force required to move the pods by the waves with changing wave heights.

In accordance with a further aspect of the invention, the pods and shaft are assembled in lengths that result in a stable center structure enabling maximum usable pod 25 displacement and hence energy capture from ocean waves.

In accordance with a further aspect of the invention, the pods impart pumping force in both the upward and downward wave motion using a double-acting piston pump to pressurize hydraulics allow for energy capture.

30 The invention has the advantage that the modular units allow for cost-effective manufacturing and deployment and tailoring of total power per device, given the needs and resources at the site.

The invention has the advantage that the units assembled 35 to lengths that result in a stable center structure enabling maximum usable pod displacement and hence energy captured from the waves.

The invention has the advantage that the system uses soft-stop hydraulics for piston throw.

The invention has the advantage that a cable-stayed structure version of the design in the center, or base 5 structure, results in cost and weight savings.

The invention has the advantage that the pod hydrodynamic and hydrostatic shape is optimized for low cost of energy (maximizing lifting and dropping forces while minimizing undesired loads, lift force from wave orbitals) and 10 may be rotated at the attachment to the arm to minimize drag during towing to the deployment site, to minimize exposure to waves during extreme wave events.

The invention has the advantage that the tubular base structures double as a hydraulic accumulator to level output. 15 The tubular structure may also serve as ballast, and/or pressurized air tanks to clear flooded pods of seawater to resurface the submerged system once extreme wave conditions subside.

The invention has the advantage that the pod variable 20 lift and drop forces maximize energy capture.

The invention has the advantage that system enables multi-directional and frequency energy capture.

The invention has the advantage that the yaw system provides for an individual unit and collective units in an 25 array to manage changes in direction of wind and/or wave travel to maximize energy capture.

The invention has the advantage that mooring systems employed share mooring points, reducing costs

### 30 BRIEF DESCRIPTION OF THE DRAWINGS

FIGURE 1 is a zero force example of the prior art;

FIGURE 2 is a stationary volume example of the prior art;

FIGURE 3 is an example of a theory behind the 35 embodiments of the wave energy converter of the present invention;

FIGURE 4 is chart of wave spectrum versus power;

FIGURE 5 is an illustration of pod motion from the side view a wave energy converter of the first embodiment of the present invention on the surface of the ocean in response to ocean waves;

5 FIGURE 6 is a top view of one example of a first embodiment of the wave energy converter of figure 5;

FIGURE 7 is a top view of a first embodiment of a wave energy converter of the present invention;

10 FIGURE 8 is a side view of the first embodiment of the wave energy converter of the present invention;

FIGURE 9 is an end view of the drive tube, ratchet and float pod of the wave energy converter of FIGURE 7;

FIGURE 10 is a top view of the drive tube, ratchet and float pod of the wave energy converter of FIGURE 7;

15 FIGURE 11 is a diagram of double acting piston pumps employed in the second embodiment of the wave energy converter of the present invention;

FIGURE 12 is a diagram of double acting piston pumps in combination with a hydraulic motor;

20 FIGURE 12a is a more detailed diagram of a hydraulic system as used with the invention;

FIGURE 12b is a more detailed diagram of an alternative hydraulic system as used with the invention;

25 FIGURE 13 is an illustration of pod motion from the side view of the second embodiment of the present invention on the surface of the ocean in response to ocean waves;

FIGURE 14 is a perspective view of a second embodiment of a wave energy converter of the present invention employing a truss system for structure;

30 FIGURE 15 is a side view of the wave energy converter of FIGURE 14;

FIGURE 16 is an end view of the wave energy converter of FIGURE 14;

35 FIGURE 17 is a top view of the wave energy converter of FIGURE 14;

FIGURE 18 is an isometric view of a second embodiment of a wave energy converter employing cable stays and spreaders for structure

FIGURE 19 is a top view of a section of the wave energy 5 converter of FIGURE 18;

FIGURE 20 is an end view of the wave energy converter of FIGURE 18;

FIGURE 21 is a side view of the wave energy converter of FIGURE 18;

10 FIGURE 22 is an isometric view of a wave energy converter utilizing a detachable power pod;

FIGURE 23 is an isometric view of a wave energy converter utilizing a detachable power pontoon;

15 FIGURE 24 shows a possible method to decouple the motion of the power pontoon from the main structure of the wave energy converter;

FIGURE 25 is an end view of a wave energy converter with the power pontoon placed below the surface;

20 FIGURE 26 is an isometric view of a wave energy converter pod housing various electric and/or hydraulic components;

FIGURE 27 is an isometric view of a tethered wave energy converter of FIGURE 14; and

25 FIGURE 28 is a side view of a tethered wave energy converter of FIGURE 14;

FIGURE 29 is an isometric view of a mooring arrangement of a plurality of wave energy converters;

FIGURE 30 is an isometric view of the mooring arrangement of FIGURE 29 with a direction of wave travel;

30 FIGURE 31 is an isometric view of a single wave energy converter mooring and winch system;

FIGURE 32 is an isometric view of the mooring and winch system of FIGURE 31 with a plurality of wave energy converters and shared moorings;

35 FIGURE 33 is an isometric view of the mooring arrangement of FIGURE 32 with a change in direction of wave travel and/or wind direction;

FIGURE 33a is an isometric view of a single wave energy converter mooring system;

FIGURE 33b is a schematic drawing of a mooring and winch system shown rotating counter clockwise with ability to rotate 5 60 degrees;

FIGURE 33c is a schematic drawing of a mooring and winch system shown rotating counter clockwise with ability to rotate 120 degrees;

FIGURE 33d is a schematic drawing of a mooring and winch 10 system shown yawing (rotating) counterclockwise with redundant winches and the ability to yaw 120 degrees;

FIGURE 34 is an isometric view of a wave energy converter according to a third embodiment of the invention;

FIGURE 35 is a diagram depicting optimum energy 15 extraction from a wave by a buoy, such as one of the pods shown in FIGURE 34;

FIGURE 36 is a diagram of the hydraulic system that controls the pods shown in FIGURE 34;

FIGURE 37 is a diagram depicting the operation of the 20 double acting hydraulic pump that extracts energy from the motion of the pods;

FIGURES 38a-38b are diagrams depicting how an impulse turbine nozzle automatically adjusts the locking force of the pod with changing wave heights; and

25 FIGURE 39 is a drawing of the multiple pod wave energy converter shown in FIGURE 34.

FIGURE 40 is a perspective drawing of a fourth embodiment of the invention showing the location of the powerhouse in the center of the structure;

30 FIGURE 41 is a cross-sectional view of the apparatus of FIGURE 40 showing a front view of the powerhouse;

FIGURE 42 is side view of the apparatus of FIGURE 40 showing the location of the main 2MW powerhouse and the location of two 1MW powerhouses;

35 FIGURE 43 is a top view of the apparatus wherein modular 1MW sections have been added to increase power rating and energy capture and the landing platform for service vessels;

FIGURE 44 is a side view of the main 2MW section with a center powerhouse and electrical and power electronic systems; and

FIGURE 45 is a top view of one modular, 1MW section.

5 FIGURE 46 is a front elevation drawing of a fifth embodiment of the invention showing the device subsystems depicted in the operating mode at sea;

FIGURE 47 is an isometric view of the apparatus of FIGURE 46 showing the detail of a pod ballasting system;

10 FIGURE 48 is front elevation view of the apparatus of FIGURE 46 showing the pods rotated, and the device submerged below the ocean surface;

FIGURE 49 is a side view of the submerged device of FIGURE 48;

15 FIGURE 50 is a front elevation view, which shows the pods rotated for the deployment leaving port and bringing the device to the wave farm site;

FIGURE 51 is a combined top and side view of a sixth embodiment of the invention;

20 FIGURE 52 is an isometric drawing of a sixth embodiment;

FIGURE 53 is a front elevation drawing of the sixth embodiment of the invention showing the rectangular backbone (base structure);

25 FIGURE 54a is a schematic side view of a multi-section backbone and relief joint according to the sixth embodiment of the invention;

FIGURE 54b shows a detailed view of the joint between the sections of the backbone;

### 30 DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

Refer to FIGURE 1, which is a zero force example of the prior art. In this example a single buoy that is not fixed, such that there is no force applied to the buoy, so no energy is absorbed from the wave. The wave amplitude remains the same.

Refer to FIGURE 2, which is a stationary volume example of the prior art. In this example, a single buoy is fixed as waves

pass by it. Since there is no displacement there is no energy absorbed. The amplitude of the wave remains the same before and after passing the buoy. While passing the buoy, it is apparent that the forward face of the wave gains height as the 5 buoy is submerged since the volume of the buoy is added to the volume of the wave. The aft face of the wave loses height as the buoy surfaces.

Refer to FIGURE 3, which is an example of a wave energy converter (WEC) of the present invention. In this example, a 10 volume (such as a buoy) has something attached to it to restrict its motion and has a force imparted to it. This force displaces over some distance so energy is absorbed from the wave and the wave amplitude is decreased. The amplitude is decreased because the buoy oscillates in a sinusoidal pattern 15 that is out of phase with the wave. The buoy submerges in the trough, filling it, and surfaces in the peak, reducing its height.

Refer to FIGURE 4, which is chart of wave spectrum versus power and illustrates that the energy of a wave is 20 limited. A 3.5m wave with a period of 9.5 seconds only has the potential power of 55 kW per meter of transverse wave face. At 50% efficiency, it would take 90 meters across the wave to generate 2.5 MW of power. For this reason, the wavefront exposure of the wave energy converter needs to be of a design, 25 which takes the forgoing into consideration.

Refer to FIGURE 5, which is a side view of a wave energy converter of the present invention on the surface of the ocean. The device can be tuned via pod arm stiffness, orientation and length to increase power and has a correction 30 of upto -50% added to the efficiency due to anticipated pitching of the entire wave energy converter unit, which should increase its power output. All of the pods in the "power section" are linked to the torque shaft and rotate about the shaft axis at the same speed. This causes the pods 35 to lift at nearly a constant speed. The shaft rotation speed determines how quickly the pods submerge and their maximum displacement. The speed is chosen for maximum power. The pods

do not have a constant displaced volume, which reduces energy capture. The pods in the "coast section" are not linked to the torque shaft and therefore do not contribute to the power generation in this situation.

5 Refer to FIGURE 6, which is a top view of the wave energy converter of FIGURE 5. For a 2.5 MW device there is a total of 50 pods, 25 for each side, V-shaped. It is assumed that the ocean wave is 3.5 m in height, with a 9.5s period and 140m wave length. This results in 2.8 RPM with 4250 kN-m  
10 torque on the device shafts. The aft width of the V-shaped device is 190m.

#### First Embodiment of the Invention

Refer to FIGURE 7, which is a top view and FIGURE 8, which is a side view of a first embodiment of a wave energy converter of the present invention. The wave energy converter (WEC) is an electric power-generating device, which is driven by ocean wave action. The device is moored from the bow 1 facing the incoming wave usually windward and delivers power to the shore grid via submarine cable from the generating power train 2. In this setup there is a mechanical coupling between the pods and the shafts 3. However, the pods are coupled to the shafts via a device that allows a transmission of a rotary motion from the lever assemblies/arms to the shaft in only one direction, while preventing transmission of a 25 rotary motion in the opposite direction.

In this connection refer to FIGURE 9, which is an end view, and FIGURE 10, which is a top view, of the drive tube, ratchet and float pod of the wave energy converter of FIGURE 7. Two long counter-rotating drive tubes (shafts) 3 produce 30 the rotational driving force to the generators. The drive tubes 3 are held by bearings 4 in the bow hull and the stern hull. The tubes have multiple pod floats 5 connected to the tubes by rocker arms 6 with bearings 7 through which the drive tubes pass.

35 The rocker arms have a ratcheting mechanism 8, which engages with the drive tube as the float pods rise with a wave, thereby applying a turning moment to the drive tube. The

drive tube is fitted with the ratchet receiver 9, which engages with the rocker arm ratchet mechanism. As the wave recedes, the ratchet disengages and the float pod falls to the trough of the wave to again re-engage as the next wave 5 approaches.

As shown in FIGURE 8, multiple float pods along the length of the drive tube enable passing waves to serially lift the group 10 of float pods thereby applying a continuous turning motion to the drive tube 3. Wave intervals may vary 10 and still produce a constant force. More power is generated with higher frequency shorter interval waves and less power with longer frequency waves.

At the bow hull 1, (FIGURE 7) the drive tubes are in close proximity to each other and at the point of entering the 15 aft hull, have increased separation 12. This provides each down stream float pod along the drive tubes to gain added exposure to waves, which would otherwise have diminished wave energy levels if float pods were aligned directly down stream.

In calm waters, the drive tubes with float pods float to 20 approximately the drive tube centerline 13 while the pods float with only the top surface exposed above the water line.

The motion of the pods is in a radial arc 14 of about 90 degrees from the centerline axis of the drive tubes with a rise and fall above and below the drive tube centerline of 45 25 degrees each. This range of motion allows for energy capture from waves up to maximum operating wave height for normal operation. The length 15 of the rocker arms/lever assemblies determines this range of motion of the pods, thus, the system 30 can be "tuned" to wave conditions in the deployment area by optimizing the length of the rocker arms. The pods have a hydrodynamic shape (see fig 10) designed to provide "lift" as the wave moves past with minimum disturbance of the waveform and to minimize the loss of energy in the wave.

#### Second Embodiment of the Invention

35 According the second embodiment, the pods are not coupled mechanically to any rotating shaft. Instead, a double-acting piston is actuated by the up-and-down moving pod. For

that purpose the lever assembly is hinged to the base structure and the piston is coupled to the lever arm between the pod and the hinge. As shown in FIGURES 11 and 12 the piston pumps high-pressure hydraulic fluid from a reservoir to 5 an accumulator. The accumulator is a pressure storage reservoir in which the hydraulic fluid is held under pressure by an external source (e.g. a spring or a compressed gas). The accumulator feeds a hydraulic motor and smoothes out the oscillations in wave energy. The hydraulic motor drives a 10 generator.

FIGURE 12a shows a more detailed view of the hydraulic system. The hydraulic system is an actively controlled, oil-based or seawater system consisting of a series of oscillating pumps (hydraulic rams connected to each pod) supplying 15 variable-displacement hydraulic motors, direct-driving generators at a constant speed. As the approaching wave exerts its buoyant force on the pod (pump piston moves to left) SV-2 remains closed until a prescribed pressure (generator load pressure) is reached. At this point SV-2 20 opens and the pressurized oil is supplied to the hydraulic motor. As the wave passes and the buoyant force on the pod diminishes, SV-1 holds the pod suspended until the pressure reaches the load pressure at which point SV-1 opens and the pressurized fluid is ported to the hydraulic motor. Multiple, 25 out-of-phase pods will help ensure constant flow.

The pods will be ganged together in groups of four to eight supplying a single generator. The displacement of the hydraulic motor will be varied based on the average wave height and period (available flow), allowing the generators to 30 run at constant speed and pressure but variable input torque (output current) - i.e. as the wave height decreases the generator current output will decrease proportionately.

FIGURE 12b, shows a typical four-pod HMG set.

Refer to FIGURE 13, which is an illustration of pod 35 motion in response to ocean waves. These pods are half the density of seawater. The pod on the far left starts on the surface of a trough. It submerges and adds volume to the

trough. When it is almost completely submerged, its buoyancy force overcomes the hydraulic pressure in the piston and it rises to the crest of the wave. There it surfaces from the crest, removing volume, until its weight overcomes the ram 5 force and it drops to the trough.

Compared to the torque shaft first embodiment of the invention, this design has a constant force over its displacement and acts in both the rise and fall of the pod due to the hydraulic coupling. It also has canceling moments 10 applied to the device so there is no net rolling moment. The wave energy converter (WEC) according to this embodiment extracts power from waves on both the up and downswing of the waves. The up and down motion of the waves cause multiple pods to move up and down. The up and motion of the pods actuate 15 hydraulic pistons that pump hydraulic fluid. Again, due to the fact that the energy converter length extends over one or more waves the pods experience different amplitudes of the wave at the same time. There is always a group of pods, which is moved upwards by the waves and a group of pods that moves downward. 20 Even if the pods may always spend a short time span at the turnaround positions during which they do not pump the fluid to a considerable extend, some other hydraulic pistons are pressurized at the same time since the associated pods are in a different stage of the motion.

25 Refer to FIGURE 14, which is a perspective view of the second embodiment of the wave energy converter of the present invention.

A plurality of pods 30 is mounted to lever assemblies/arms 31. The arms are hinged to a support member 34 30 of a base structure 33, 34. The base structure is constructed as a rigid truss system and further comprises two bars 33 arranged in parallel to the support member 34 so that the bars and the support form a triangular shape with the bars in the corners of the triangle. Between the support member and the 35 bars 33 there are stabilizer bars or truss rails to provide stiffness in torsion, tension and bending of the truss system. Coupled to the arms 31 there are hydraulic pistons 32 which

are actuated by the relative motion between the pods 30 and the base when the pods are moved by the waves in an up-and-down motion. In this example there is one piston actuated by each pod.

5 Refer to FIGURE 15, which is a side view of the wave energy converter of FIGURE 14. The main body length is such that the assembled length of modules will ensure optimal deflection of the pods for energy capture.

10 Refer to FIGURE 16, which is an end view of the wave energy converter of FIGURE 14. The rigid truss system is connected to the pod arms and the double-acting piston. The truss rails are used as accumulators for the hydraulic system.

Refer to FIGURE 17, which is a top view of the wave energy converter of FIGURE 14.

15 Refer to FIGURE 18, which is an isometric view of a wave energy converter with a cable-stayed base structure. The cables are arranged to provide stiffness in torsion, tension and bending.

20 Refer to FIGURE 19, which is a top view of a section of the cable-stayed structure. A center tube provides structure and acts as the accumulator for the hydraulic system.

25 Refer to FIGURE 20, which is an end view of the cable-stayed structure. Three spreaders allow for cables to be used throughout the length of the structure. The double-acting piston pump and pod are shown.

Refer to FIGURE 21, which is a side view of the wave energy converter of FIGURE 18.

30 Refer to FIGURE 22, which shows a wave energy converter according to the invention with a power pontoon to house the hydraulics and electrical generating equipment. The pontoon would be removable for service at sea.

Refer to FIGURE 23, which is an additional perspective view of the wave energy converter with a power pontoon.

35 Refer to FIGURE 24, which is an end view of the wave energy converter with a power pontoon decoupled from the wave energy converter main structure.

Refer to FIGURE 25, which is an end view of the wave energy converter with a power chamber below the cable-stayed structure and below the surface.

Refer to FIGURE 26, which is an isometric view showing 5 assorted wave energy converter hydraulic and electric systems being moved into the wave pod, thus eliminating the power pontoon from the wave energy converter.

Refer to FIGURE 27, which is an isometric view of a four-point tethering arrangement for a wave energy converter.

10 The output submarine power cable would run down one of the tethers.

Refer to FIGURE 28, which is a side view of the system in FIGURE 27.

Refer to FIGURE 29, which is an isometric view of a 15 plurality of wave energy converters having a collective yaw control feature. The yaw mechanism is used to turn the wave energy converter for optimum exposure to the waves as the wave direction changes. For this purpose multiple converters are coupled via cables. Further the converters are moored to 20 mooring points. By regulating the length of the cables (e.g. with a winch) the devices can be oriented in the right direction to the waves and a yaw control is provided.

Mooring points can be shared between multiple energy converters to reduce costs.

25 Refer to FIGURE 30, which is a depiction of the yaw control feature of FIGURE 29 when the wave direction changes.

Refer to FIGURE 31, which is an isometric view of a 30 single wave energy converter mooring system with cable winch control providing independent device yaw control to optimize the WEC orientation to the direction of the waves.

Refer to FIGURE 32, which is a top view of the mooring system of FIGURE 31 with a plurality of wave energy converters. Mooring points can be shared reducing costs.

35 Refer to FIGURE 33, which is a depiction of the yaw control feature of FIGURE 31 when the wind and/or wave direction changes. This control feature adds increased

redundancy to multiple wave energy converters as each is controlled independently.

Refer to FIGURES 33a to 33d, which are a depiction of the yaw control feature of FIGURE 31 when the wind and/or wave 5 direction changes. FIGURES 33b to 33d show alternative mooring control systems. In figures 33b to 33d references 20 refers to the energy converter representation (base structure with pods). Reference 21 refers to a cable junction and turning block. The references 22, 23, 24, and 25 indicate the mooring 10 cables guided to the respective corners of the opposite ends of the structure's backbone. Reference 26 indicates the position of a turning block. The system further comprises a traction winch 27 as well as a redundant traction winch 28 (Fig. 33d).

15 Third Embodiment of the Invention

Refer to FIGURE 34, which is an isometric view of a wave energy converter according to a third embodiment of the invention on the surface of the ocean. The device is moored at a variable angle to an incoming ocean wave and delivers power 20 to a shore grid via a submarine cable from a generator located in a central main powerhouse. A hydraulic system controls the movement of the pods by using the energy of a wave to activate the hydraulic system. The hydraulic system includes an impulse turbine and an impulse turbine nozzle, which automatically 25 adjusts a locking force of a pod with changing wave heights. The wave energy converter (WEC) extracts power from waves on both the up and downswing of the waves. The up and down motion of the waves cause multiple pods to move up and down. The up and motion of the pods actuate hydraulic pistons that pump 30 hydraulic fluid to a nozzle that drives an impulse turbine. A Pelton wheel is of a type of impulse turbine. The water under pressure, which is introduced by the nozzle into the casing of the impulse turbine, is accelerated when it is forced to flow through the nozzle. The high-velocity jet from the nozzle 35 impinges on buckets around the turbine wheel to cause the wheel to rotate about a shaft. The shaft is connected to an electric generator. The impulse turbine can be replaced with

any hydraulic turbine such as any rotary engine that takes energy from moving fluid, including hydraulic motor, impulse turbine, or Pelton wheel.

#### A Way To Obtain Optimum Energy Extraction

5 Refer to FIGURE 35. For optimum energy extraction from a wave by a buoy, discounting a resonant situation, the following cycle should be followed:

(1) The buoy should be held at a fixed height (A) until the waterline rises to a depth of  $\frac{1}{4}$  of the wave height above 10 neutral 37c (B).

(2) The buoy should then be allowed to rise to the crest 35 of the wave at a constant buoyancy force generated by the increasing water height (C). The resulting buoy stroke is equal to  $\frac{1}{2}$  of the wave height.

15 (3) When the buoy reaches the crest 35 of the wave it should be held at that height until the water line falls to an amount of  $\frac{1}{4}$  wave height 37b below neutral 37c (D).

(4) The buoy should then be allowed to fall to the trough 36 of the wave at a constant force generated by the 20 decreased water height (E). The resulting buoy stroke is equal to  $\frac{1}{2}$  of the wave height.

#### Hydraulic Circuit

Refer to FIGURES 36 and 37. The hydraulic system can be an open or closed circuit, which can include a reservoir 40, 25 one-way check valves 42, a cushion stop/double acting hydraulic ram pump 41 driven by a pod 48, whose up and down motion about a pivot drives a piston rod. The one-way check valves 42 within the hydraulic manifold 43 open and close to control the flow of fluid in the system. An optional hydraulic 30 accumulator 44 can be provided to level the power output. The hydraulic manifold 43 forces fluid through the high-pressure line 46 to the nozzles to turn the hydraulic motor or impulse turbine 45. A low-pressure line 47 return path returns the fluid to the reservoir 40 or in an open sea water system the 35 fluid is returned to the ocean. A hydraulic motor is a mechanical actuator that converts hydraulic pressure and flow into torque and angular displacement. The term hydraulic

turbine as used herein is any rotary engine that takes energy from moving fluid, including hydraulic motor, impulse turbine, or Pelton wheel.

Sample Hydraulic System Operation

5 At rated power, for example from a 3m wave, the pods would be submerging and surfacing 0.75m before they start moving and they would have a throw of 1.5m. The hydraulic pressure would be 3000 psi (maximum) and a flow rate of 1 unit.

10 If the wave height drops to 1m or 1/3 of rated, the pods would want to submerge and surface 0.25m, which would require a hydraulic pressure of 1/3 of rated or 1000 psi. The throw would also drop to 1/3 of rated or .5m, which would reduce the flow rate to 1/3 units.

15 If utilizing an impulse turbine to power a generator, the fluid is squirted through nozzles that turn a paddle wheel. As the flow rate through the nozzles goes down, the pressure also goes down nearly linearly. So if the pressure powering the wheel drops to 1/3 of original, the back pressure 20 would automatically drop to 1/3. This is the same relationship between pressure and flow rate that the pods need to maintain optimum performance. In this way, the pods are self tuning, maintaining optimal performance automatically.

The impulse turbine, at constant RPM, also stays in its 25 efficiency range for a wide range of wave heights. For larger waves the power is maintained at rated by limiting the hydraulic ram throw and pod size.

If a hydraulic accumulator 44 is used to level the power output, it would also delay the tuning of the pods (i.e. if 30 the max pressure is built up, the pods would have to see enough energy to overcome the stored hydraulic pressure prior to capturing more energy). For this reason it may be preferable to level the power in another way

Refer to FIGURE 37, which illustrates how the hydraulic 35 system accomplishes a locking of motion until a set force is reached as well as causing a constant resistance to pod motion.

Initially, there is no force on the piston because the pressure on either side of the piston 41 is equal. When the force on the piston is less than the activation force, the piston moves an infinitesimal amount and the pressure on one 5 side increases and the pressure on the other side decreases until the forces are balanced and motion stops.

When the force on the piston is equal to the activation force, the inlet and exit valves 42 open. The piston moves with constant activation force. Low-pressure fluid 47 fills 10 the expanding side and high-pressure fluid 46 exits the contracting side.

Refer to FIGURES 38a-38b, which illustrate how an impulse turbine nozzle automatically adjusts the locking force of the pod with changing wave heights.

15 In FIGURE 38a, large waves generate a large stroke and the large stroke gives a large flow rate. The large flow rate causes a high hydraulic backpressure, which requires a large force to move the hydraulic ram. The large force increases the immersion of the pod helping to maintain  $\frac{1}{4}$  wave height and the 20 increased immersion with increased wave height optimizes energy production.

In FIGURE 38b, small waves produce a small stroke, small flow rate, low hydraulic pressure, low ram force, and less immersion of the pod. By setting the nozzle size, hydraulic 25 system and pod number and geometry, the self-tuning of the pod force with wave height helps to maintain optimal performance.

Refer to FIGURE 39, which is a detailed drawing of the wave energy converter shown in FIGURE 34. The hydraulic ram 41 and hydraulic manifold 43 shown in FIGURES 36 and 37 are 30 replicated along the spine of the wave energy converter. A high-pressure line 46 connects the manifolds 43 to a common pressure accumulator 44 and hydraulic motor or impulse turbine 45. The hydraulic motor or impulse turbine 45 drives a common generator 34. The spent fluid from the hydraulic motor or 35 impulse turbine 45 is collected in a hydraulic reservoir 40, which returns the fluid to the manifold 43 via a low-pressure return line 47.

Fourth Embodiment of the Invention

According to a fourth embodiment of the invention the power-generating apparatus includes a center section, one or more outer satellite sections connected to the center section 5 and a powerhouse located at the center section. The hydraulic turbine may be an impulse turbine or hydraulic motor. The device is moored at a variable angle to an incoming ocean wave and delivers power to a shore grid via a submarine cable from a generator located in the central main powerhouse.

10 In accordance with an aspect of the invention the powerhouse collects the satellite module's electrical production and provides an exit from the apparatus to the ocean floor where power is transferred to shore via a submarine cable.

15 In accordance with an aspect of the invention an outer section is modular and contains a single, satellite powerhouse which gathers the outer section's pressurized hydraulic flow and generates electricity that is wired into the main center powerhouse for power conditioning and transmission via the 20 submarine cable.

In accordance with an aspect of the invention the center powerhouse and all satellite powerhouses submerge to avoid wave slapping loads and instances in large storm waves where a 25 large part of the length of the structure may become unsupported by seawater.

Refer to FIGURE 40, which is an isometric view of a wave energy converter of the present invention on the surface of the ocean. The device includes a plurality of force transmitting pods, double-acting hydraulic rams engaged with 30 the arms of the force transmitting pods, and a Pelton wheel driven by high-pressure working fluid which is engaged to a generator.

Refer to FIGURE 42 and FIGURE 43. FIGURE 43 is a top view and FIGURE 42, is a side view of a wave energy converter 35 of the present invention. The wave energy converter (WEC) is an electric power-generating device, which is driven by ocean wave action. The device is moored by its ends and can be yawed

to maximize power extraction and delivers power to a shore grid via a submarine cable from the main powerhouse.

The wave energy converter is designed to optimize the capture of energy from waves using a plurality of pods in 5 modular constructed sections containing powerhouses for electricity production. The advantage of this construction is commonality in a large device for economic, operating and service reasons plus allowing for the device length to exceed long period wavelengths, which results in a stable platform 10 for the pods to work against maximizing wave power extraction. Traditional shipbuilding methods can be employed.

The pods capture energy on the up and downswing of the waves and impart force to two-way, double-acting hydraulic rams. The rams pump a working liquid, such as hydraulic oil or 15 seawater, and liquid pressure is used to drive a Pelton wheel or other hydraulic motor and a generator system to generate electricity.

The construction consists of a center section which houses hydraulic systems, power conditioning, step up 20 transformers and switchgear. This main powerhouse not only produces its own main section's electricity, it collects the entire satellite module's electrical production and provides the exit from the device to the ocean floor where power is transferred to shore via a standard submarine cable.

25 The outer sections shown in FIGURES 43 and 45 are completely modular and contain a single, satellite powerhouse which gathers each section's hydraulic pressure generated and generates electricity that is wired into the main center powerhouse for power conditioning and transmission via a 30 submarine cable to shore.

The center and all satellite powerhouses are designed to submerge to pressures up to several atmospheres to survive extreme weather events. The entire device is designed to submerge to avoid wave slapping loads and instances in large 35 storm waves where a large part of the length of the structure may become unsupported by seawater.

Fifth Embodiment of the Invention

According to a fifth embodiment, the apparatus for generating power utilizing ocean waves includes a plurality of force transmitting pods, double-acting hydraulic rams engaged with the arms of the force transmitting pods, and a hydraulic 5 turbine driven by high-pressure working fluid which is engaged with a generator. The apparatus includes chambers in the pods, which can be flooded with seawater for submerging and evacuating of the seawater for surfacing. The hydraulic turbine may be an impulse turbine or hydraulic motor.

10 In accordance with an aspect of the invention the pods can be raised to a vertical position for submerging and surfacing and for transporting the WEC.

The wave energy converter (WEC) according to the fifth embodiment extracts power from waves on both the up and 15 downswing of the waves. However, this results in an inherent inability to raise the pods and structure out of major storm waves. The current embodiment employs a variable buoyancy apparatus and method to (1) assist in the deployment of the WEC to a wave farm, to (2) optimize energy capture in the 20 operating mode and to (3) totally submerge the device to avoid huge wave slapping loads and avoid instances where a large part of the structure may not be supported by seawater.

The device ballast subsystems are depicted in FIGURE 46 in the operating mode at sea. There is a defined amount of 25 ballast provided by flooding a pod's free flood tank to a certain level. This optimizes wave energy capture on the up and downswing of the waves as previously described.

FIGURE 47 shows the detail of the pod ballasting systems shown in FIGURE 46. The defined flooded area for operational 30 ballast is shown with a small water inlet that is always open and an air exit outlet. One small area (sealed buoyancy chamber) in the pod remains sealed with air to provide for minimal buoyancy in the case of submergence when the balance of the pod is allowed to flood. An air pump and air hose line 35 evacuate the water by air displacement when the device needs to be surfaced for further operation or maintenance.

FIGURE 48 shows a submerged WEC. Upon notification of major storm waves or a singular wave event, which might harm the device, the pods are flooded to add ballast and reduce overall device buoyancy. Hydraulic rams at the pod arm-pod interface 5 are actuated to rotate the pods to the vertical orientation shown. Thus, with the air pump off, the pod flooded with seawater, the pod arms raised with the pod position cylinders extended, the device submerges to a prescribed depth, well below the trough of major storm waves. FIGURE 49 shows the 10 submerged WEC.

FIGURE 50 shows a deployment method for leaving port and bringing the device to a wave farm site. The pods are placed in the vertical orientation fully emptied of seawater ballast and the device towed. Thus, with the air pump on, the pod 15 emptied of seawater, the pod arms raised with the pod position cylinders extended, the device surfaces to the water line of waves.

#### Sixth Embodiment of the Invention

Refer to FIGURE 51 and FIGURE 52. FIGURE 51 is a 20 combined top view and a side view of a wave energy converter of the present invention. The wave energy converter (WEC) is an electric power-generating device, which is driven by ocean wave action. The device is moored by its ends and can be yawed to maximize power extraction and delivers power to a shore 25 grid via a submarine cable from the main powerhouse. The backbone (base structure) of the converter comprises to section connected via a joint structure. FIGURE 52 is perspective drawing of the sixth embodiment.

FIGURE 53 is a front elevation drawing of the sixth 30 embodiment of the invention showing the rectangular backbone (base structure). To achieve a strong and robust backbone a square framing system was developed with four large diameter legs at each corner of the square with small diameter tubular braces at each face of the unit providing the framing system 35 along the length of the backbone as well as each panel level where the pod loadings are transmitted to the backbone through pod arms.

The basis for selecting a combination of large and small diameter tubes is to minimize the applied loading on the backbone. Maximum vertical forces due to water particle velocities on the small diameter tubes occur out-of-phase (90 5 degrees in advance of the crest line) with the maximum vertical forces due to water particle accelerations (and variably buoyancy forces acting in opposition) on the large diameter tubes at the crest line. The converter backbone is a very long and slender structure accommodating 28 sets of 56 10 pods and pod arms. The four tubes of the backbone and the small diameter braces at each of the four sides of the backbone and a total of 30 cross-frames provide the rigidity to the backbone. Twenty-eight of these cross-frames provide the structural integration of the pods and pod arms with the 15 backbone.

The critical loading conditions affecting the backbone are hogging when the wave crest is at the backbone mid-span and the sagging condition when the two wave crests are at each end of the backbone with the trough being at the mid-span. 20 The backbone can be designed to have adequate capacity to accommodate a reasonable level of hogging and sagging loads due to wave loads acting directly on the backbone and the loads being transmitted from the pods to the backbone.

These applied direct and indirect loads acting on the 25 backbone create a bending moment that is the maximum at mid-span. The bending moment translates into axial tension and compression forces on the large diameter corner legs of the backbone. Since the bending moment for each sea state would be different, it is desirable to consider the target capacity for 30 the backbone so that structural integrity of the system is maintained and the overall costs remain reasonable.

According to this embodiment, the backbone is constructed in two equal segments, with one end of the backbone stabbed into the other. Each of the four stab-on 35 elements provide for locking in of each of the four legs to provide continuity of the system. Thus, until a storm event creating a bending moment and axial forces compatible with the

lock-in system capacity, the backbone functions as a single unit.

FIGURE 54a is a schematic side view of a multi section backbone according to the sixth embodiment of the invention.

5 FIGURE 54b shows a detailed view of the joint between the sections of the backbone.

When the axial loads exceed the lock-in capacity, the stab-on legs are released but remain within the guides. In the released condition rotational flexibility is provided to  
10 nullify the effect of applied loads creating bending moment.

The pre-tensioned guy wires are intended to keep the two halves of the unit very close to each other. However, a supplemental safety system is also provided by attaching 2 to 3 m long chains that would prevent the stab on legs from  
15 getting out of their guides. Cushions or rubber bumpers on the system can prevent large movements along the longitudinal axis of the backbone.

The architecture provides for an effective way to reduce cost through scalability. The modular design of the sixth  
20 embodiment allows the system to be scaled to a size which is most cost-effective from a mooring and operational standpoint. The embodiment accomplishes this by combining 56, 80kW point absorber pods onto a single 214m long semi-submerged carrier structure that is exposed to the wavefront at ~45° and can yaw  
25 in response to change in direction of the wavefront. It is planned that the core system will be 2.24 MW with 28 pods. An additional 2.24 MW module completes the 4.5 MW converter, with a compliant section at the middle. Further extensions may be possible in the future.

30 The use of proven technology and commercially available components reduces technical issues, costs, and allows for a more rapid commercialization process. Most components used in the embodiment are available through industrial catalog sources significantly reducing the "teething costs" typically  
35 associated with newly designed components in early stage commercialization. Furthermore, leveraging proven processes and experience from the offshore oil and gas industry for

survivability, operability and safety allows for predictability in the design, implementation, and certification process. The embodiment also benefits from some three decades of experience in heaving point absorbers gained 5 through tank testing, subscale testing, and modeling. As such, the performance and dynamic response is well understood, and commercialization is not hindered by the need for long research projects.

Being able to carry out regular maintenance and repair 10 activities in normal sea-state conditions insures that O&M (Operations & Maintenance) costs are predictable, and if a problem arises, it can be rectified in a timely manner. This requires personnel to be able to access and safely carry out operational activities on-board. The design criteria for this 15 embodiment is to have a > 90% accessibility, which translates directly to improved generating system availability, and significantly enhances LCOE (Levelized Cost of Energy). This is achieved by providing safe access to all critical components by elevated ramps, well above the ocean waves. The 20 elevated ramps also incorporate a rail for the service crane, which can travel the full converter structure length to the boarding platform for the service boat. Personnel transfer is accomplished by service boat or helicopter.

System modularity simplifies manufacturing and reduces 25 O&M costs by allowing for sub-systems to be easily replaced with the on-board service crane. The modularity allows for individual components to be man-manageable with the on-board crane avoiding the expense of shipboard mounted cranes. The float pods, hydraulic rams, hydro-turbines, and generators can 30 be removed using the on-board crane.

Ease of Deployment and reduced installation costs are based on towing the converter structure to site and the use of gravity anchors for mooring, avoiding ocean floor mounted structures as with some wave devices.

35 Redundancy is built into the converter subsystems to gain high availability and reduce the chance of a failure, which would result in a catastrophic loss. There are multiple

levels of redundancy built in, and particular attention is paid to failure modes and how they affect the overall system. All critical systems, including control system, moorings, etc., have some built-in redundancy.

5        Highly efficient absorption and power conversion process, measured as the amount of structural material (cost) that is required to achieve a desired electrical output (kWh/year). Multiple optimally sized, shaped, and tuneable point absorber pods, mounted on the backbone carrier result in  
10 highly efficient wave power conversion. The interaction between the wave action and the timing of the engagement of the hydraulic rams yields a significant increase in energy conversion. Compared with some of the most mature devices under development, the embodiment of the invention has a  
15 structural weight-to-power ratio that is about two to five times better.

Pod efficiency is also enhanced by the length of the carrier designed to "straddle" typically two to three wave lengths, thereby minimizing pitching at the expense of  
20 absorption and power conversion by the pods.

Pod efficiency is also gained with optimized exposure to waveform by the converter according to the invention yawing to about a 45° angle to the oncoming wave line exposing all pods to maximum wave action. The yaw system allows a 90°  
25 change in orientation of the converter.

The architecture has embraced marine best practices by eliminating active systems from the design where possible. A FMEA (Failure Modes & Effects Analysis) process has been adopted early in the design to root out potential failure  
30 modes and track them. This process along, with RAM (Reliability, Availability and Maintenance), will be used to keep track and generate design goals for Mean Time Between Critical Failure, Mean Down Time and availability or uptime (usually expressed in percentages) at component, subsystem and  
35 complete system level.

The inventor believes the LCOE of the invention is a substantial improvement over designs currently deployed, and

in the range of offshore wind power (12 to 18 cents/kWh). The LCOE was calculated based on EPRI's Utility Generator economic methodology and assumes no subsidies. The reference location for this deployment is in Humboldt County, California, at the 5 PG&E WaveConnect project.

It is clear that for wave energy to become commercially successful and gain a wide market acceptance, it must have a relatively benign environmental footprint. Assessing the potential environmental effects composes an integral part of 10 the development process. For the design according to the invention, particular attention is being paid to issues related to hydraulic fluid spill, impingement, toxicity of anti-fouling paints, and mooring arrangements that could potentially interfere with marine life. The following 15 potential impacts and mitigation measures are shown for illustrative purposes:

Issues	Mitigation Measures
Potential hydraulic fluid leakage	Secondary containment of hydraulic elements, clear operational protocol, use of biodegradable fluids, and vegetable oils.
Toxicity of anti-fouling paints	Use of epoxy-based paints with minimal toxicity.
Impingement of seals and other larger animals	Design of structure with few gaps between moving parts (i.e. pod-arms and main structure).
Entanglement of whales with mooring system and riser cables	Making sure that pretension is at a level that makes entanglement unlikely. i.e. > than a few tons.

Operational Spill of hazardous fluids (oil, paint, fuel etc.).	Strict operational procedures and controls to minimize such impacts. Clear response protocol in the event of such spills, and training of personnel.
Noise	Incorporate many of the noise mitigating concepts of submarine design and the noise-sensitive wind power industry.

This is by no means a comprehensive list, but it delineates the critical issues being addressed by design.

Ideally the pods operate and produce energy during all 5 wave conditions. Wave energy extraction is maximized through optimal power take-off control during small waves and will level off at the rated capacity of the generator. As waves become larger and more energetic, excess power is shed by de-tuning the heaving pods. De-tuning is accomplished by 10 applying less than optimal dampening to the pods by means of regulating the hydraulic power take-off in extreme seas. The following table shows the single pod performance as a function of sea-state.

15 Table: Pod electrical output in kW as a function of sea state

As shown in the above performance matrix, the rated capacity of the generator is limiting the electrical power output per pod to about 80kW. In Northern California wave 5 conditions, the above performance table would yield an annual average of 32kW per pod.

While the invention will operate during all of the year, access for O&M servicing may be limited by weather conditions. Operational access to carry out O&M procedures is highly 10 dependent on the ability to access the structure by personnel. In order to do so, the access ramps of the converter according to the invention are sufficiently high above the wave action to allow personnel safe access during normal sea-state operating conditions, which should be the majority of time. 15 Personnel transfer can be done to and from the structure by the service boat or helicopter with methods similar to offshore oil platforms and wind turbines.

Survivability of the design in even the worst storm conditions is critical to the commercial success. The energy 20 converter according to the invention is designed to optimize power production during low power sea-states and will start shedding power approaching extreme conditions. This power shedding is an important and integral aspect of the overall design and is attained by:

25 - Allowing the individual pods to ride-out any extreme event, and minimizing the forces they transfer to the backbone during these conditions.

- Having a compliant moored backbone structure that is allowed to flex with extreme waves, but provides a stable 30 point of reference (minimal pitching) during operational conditions. A critical design aspect is that the systems required for survivability are fail-safe and are not active. By embracing this design philosophy, the converter has a much higher chance of surviving the most severe storm.

35 According to the described embodiment, each Pod generates a maximum of 80kW. According to a further aspect of

the invention a linear generator is used for motion-energy conversion. Wave energy conversion is ideally suited to linear generators whereby the motion of an absorber can be directly coupled. Linear Generators eliminate the need for complex

5 power takeoffs and have the ancillary benefits of improved efficiency and potentially reduced environmental impact. In the are there are theoretical considerations which may serve as a basis for the calculation an design of suitable generators (e.g. work of Oskar Danielsson, Design of a Linear 10 Generator for Wave Energy Plant, University of Uppsala, Master's Degree Project 2003; Wolfbrandt, A., Automated design of a linear generator for wave energy Converters-a simplified model, IEEE Transactions on Magnetics, Volume 42, Issue 7, July 2006 Page(s): 1812 - 1819)

15 As explained above, to achieve competitive costs of energy, the system architecture according to the invention does lend itself to economies of scale, while addressing survivability during extreme wave events. The invention is based on novel architecture and integrates the essential 20 criteria that makes wave power conversion economically viable. This criteria includes:

25 - Inherent Survivability as the overarching design driver, achieved by allowing the structure to shed any excess loads and therefore reduce the structural mass and design requirements

30 - Highly efficient absorption and power conversion processes, measured as the amount of structural material (cost) that is required to achieve a desired electrical output - Sufficient carrier or "backbone" length to straddle oncoming waves to provide longitudinal stability, minimizing carrier pitching and thereby extracting maximum wave force by rise and fall of flotation pods

35 - Orientation of the Centipod to maximize pod exposure to the wavefront with active yawing to adjust the orientation as needed with wavefront shift in direction.

- Scalability of the architecture as an effective way to reduce LCOE by reducing the percentage of total cost attributable to anchoring and power collection to shore

5 - Use of commercially available components for the entire generating system

- Accessibility of all the system components, and ability to take pods off-line individually for O&M servicing during normal operating sea states

10 - Redundancy to reduce the chance of a failure resulting in a catastrophic loss

- Reduced cost of deployment by simple towing single energy generating devices (e.g. 4.5MW systems) to the array site and, in most instances, being able to hold station with low-cost gravity anchors.

Claims

1. Apparatus for generating power utilizing ocean waves,  
5 comprising:

a plurality of force transmitting floating pods 5  
responsive to the motion of ocean waves wherein

each of said pods is coupled to one of a multiple of lever  
assemblies, each lever assembly transmitting the motion of the  
10 pods to a rotary shaft 3 engaged with said lever assembly, the  
pods with the lever assembly being arranged along the rotary  
shaft in an axially direction thereof, wherein said rotary  
shaft 3 produces a rotary torque when said pods move according  
to an up-and-down motion of an ocean wave, and

15 a generator 2 engaged with said rotary shaft 3, such that  
said rotary torque is transmitted to said generator 2 to  
thereby cause said generator to generate power.

2. Apparatus of claim 1 wherein said lever assemblies are  
20 coupled to the rotary shaft via a device that allows a  
transmission of a rotary motion from a lever assembly to the  
shaft in only one direction, while preventing transmission of  
a rotary motion in the opposite direction.

25 3. Apparatus of claim 2 wherein said device is a ratchet  
assembly.

4. Apparatus of claim 1 having at least two rotary shafts  
arranged in a V-shape, each of said pods being coupled via the  
30 respective lever assembly to one of said rotary shafts.

5. Apparatus for generating power utilizing ocean waves,  
comprising:

a plurality of force transmitting floating pods 5 responsive to the motion of ocean waves each of said pods being coupled to one of a multiple of lever assemblies,

5 each lever assembly transmitting the motion of the pods to hydraulic rams engaged with the lever assemblies of the force transmitting pods,

wherein the hydraulic rams are coupled to an hydraulic rotary engine such that the hydraulic pressure produced by said hydraulic rams feed said hydraulic rotary engine when 10 said pods move according to an up-and-down motion of an ocean wave,

a generator 2 coupled with said rotary engine to thereby cause said generator to generate power.

15 6. The apparatus of claim 5 wherein said hydraulic rams are coupled to an accumulator system coupled between the hydraulic rams and the hydraulic rotary engine, the accumulator system thereby feeding the hydraulic motor and smoothing out the oscillations in wave energy.

20

7. The apparatus of claims 5 or 6 wherein the hydraulic rams are double-acting hydraulic rams, the apparatus thereby providing for energy capture with both upward and downward pod motion driving said rotary engine and generator to generate 25 power.

8. The apparatus of claims 5, 6 or 7 wherein said hydraulic rotary engine comprises a hydraulic turbine.

30 9. The apparatus of claim 8 comprising a hydraulic system that controls the movement of the pods by using the energy of a wave to activate the hydraulic system.

35 10. The apparatus of claim 8 wherein said hydraulic turbine is one of a hydraulic motor or impulse turbine.

11. The apparatus of claim 9 wherein said hydraulic turbine comprises:

an impulse turbine;

5 an impulse turbine nozzle, which automatically adjusts a locking force of a pod with changing wave heights; and valving to maintain pod position for maximum force.

12. The apparatus of claim 8 comprising a center section; one or more outer satellite sections connected to said 10 center section; and a main powerhouse located at said center section.

13. The apparatus of claim 12 wherein said main powerhouse collects the satellite module's electrical production and 15 provides an exit from the apparatus to the ocean floor where power is transferred to shore via a submarine cable.

14. The apparatus of claims 12 or 13 wherein an outer section is modular and contains a single, satellite powerhouse 20 which gathers the section's pressurized hydraulic fluid generated and generates electricity that is wired into the main powerhouse for power conditioning and transmission via said submarine cable.

25 15. The apparatus of claims 12, 13 or 14 wherein said main powerhouse and all satellite powerhouses submerge to avoid wave slapping loads and instances in large storm waves where a large part of the length of the structure may become unsupported by seawater.

30

16. The apparatus of claims 8, 9 or 10 comprising means for rotating the pods to a vertical orientation.

17. The apparatus of claim 16 including two flooding 35 chambers in a pod, one for operational ballast with a small water inlet that is always open and an air exit outlet; and one with an air pump, air hose line and water exit holes to

evacuate the water in said flooding chamber by air displacement when the device needs to be surfaced.

18. The apparatus of claim 16 or 17 wherein a sealed 5 buoyancy chamber is provided in said pod, which remains sealed with air to provide for minimal buoyancy in the case of submergence when said flooding chamber is allowed to flood.

19. Relief Joint/Stab enables a compliant backbone to shed 10 loads in extreme sea states essentially decoupling the two sections via a stab arrangement that is set at a predetermined preload that disengages upon excessive bending stresses with guide wire to bring the overall structure back in alignment.

15 20. The apparatus of claims 1 or 5 having an active yaw control system either independent and or collective for a plurality of wave energy converters, allowing for maximized energy capture, lowered costs and system reliability and redundancy.

FIGURE 1 PRIOR ART

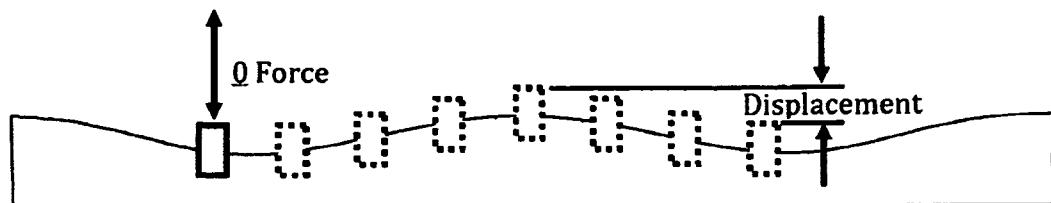


FIGURE 2 PRIOR ART

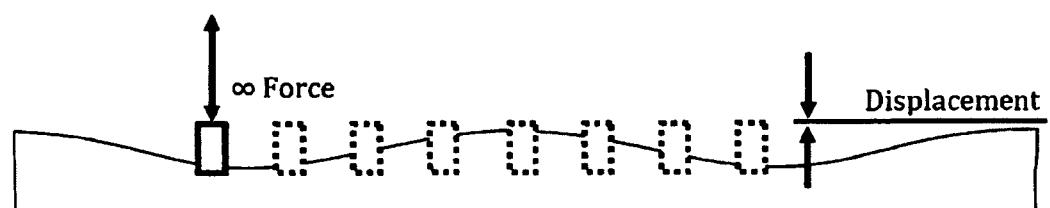


FIGURE 3

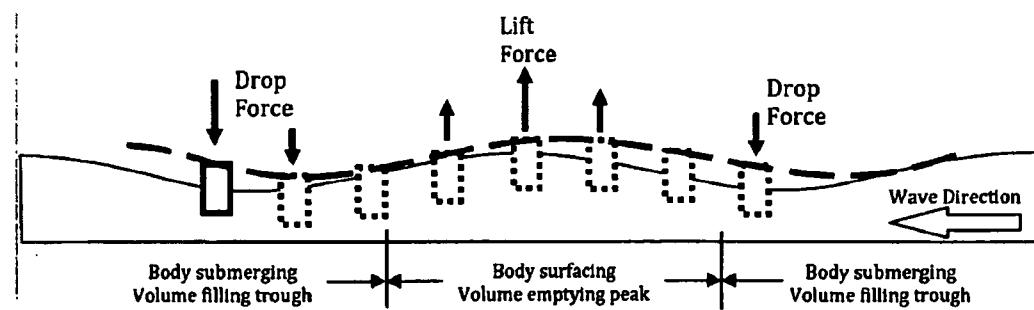


FIGURE 4

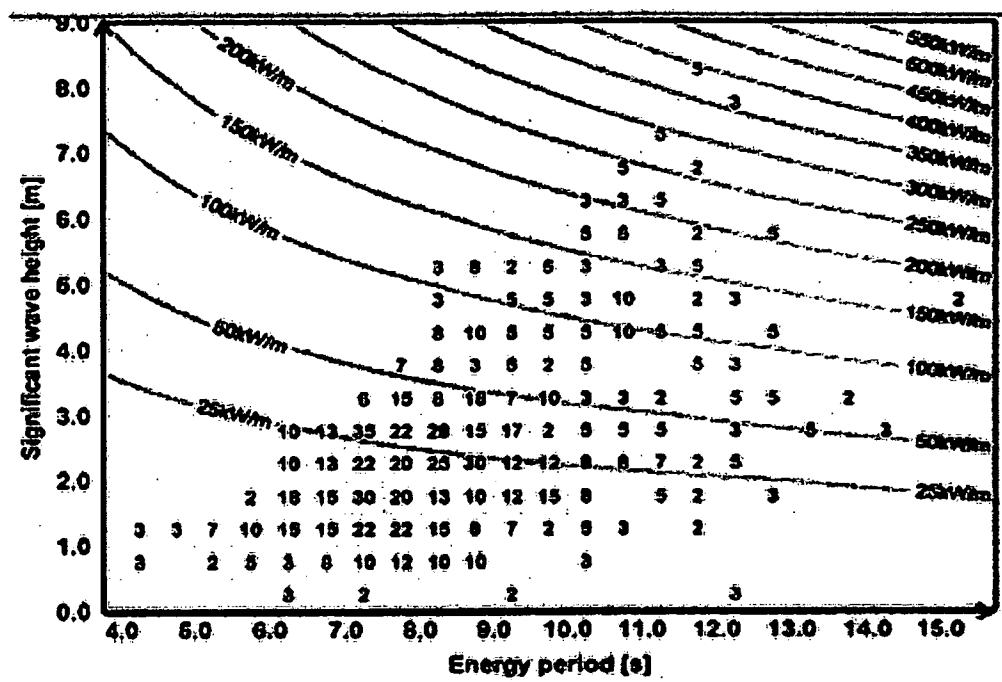


FIGURE 5

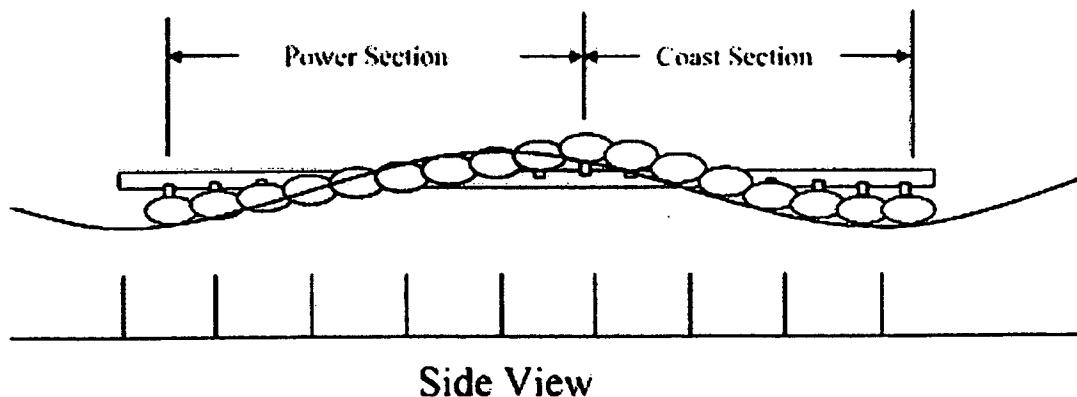


FIGURE 6

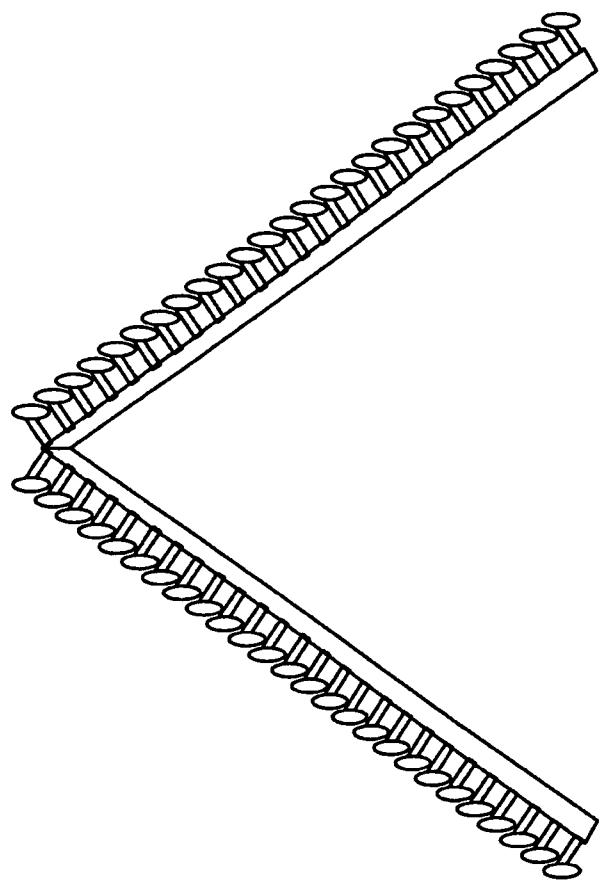


Figure 7

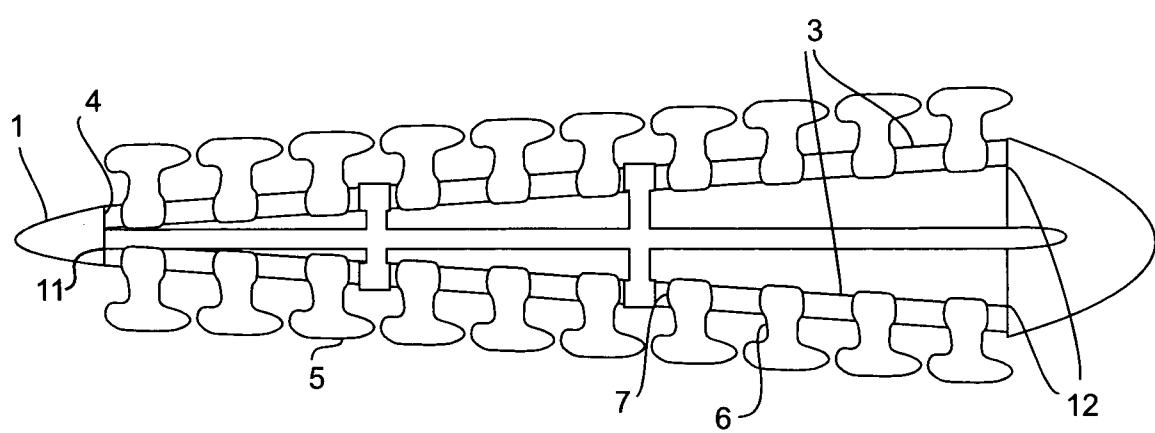


Figure 8

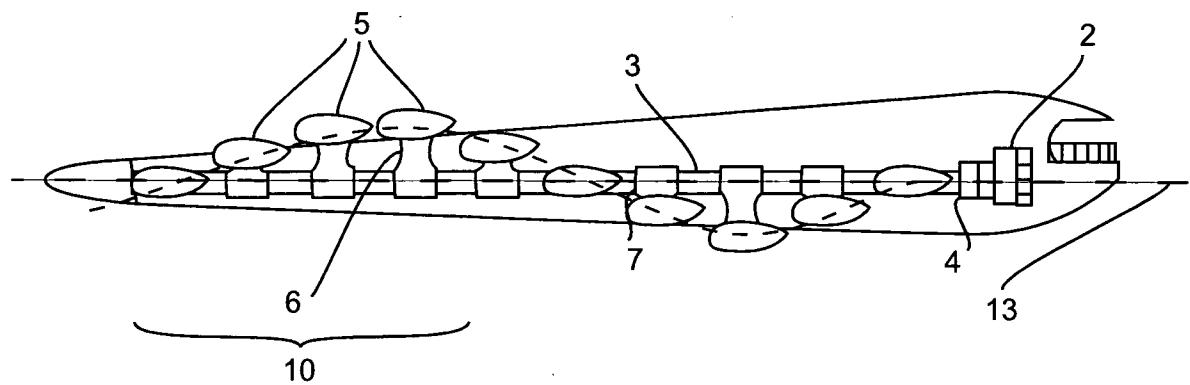


Figure 9

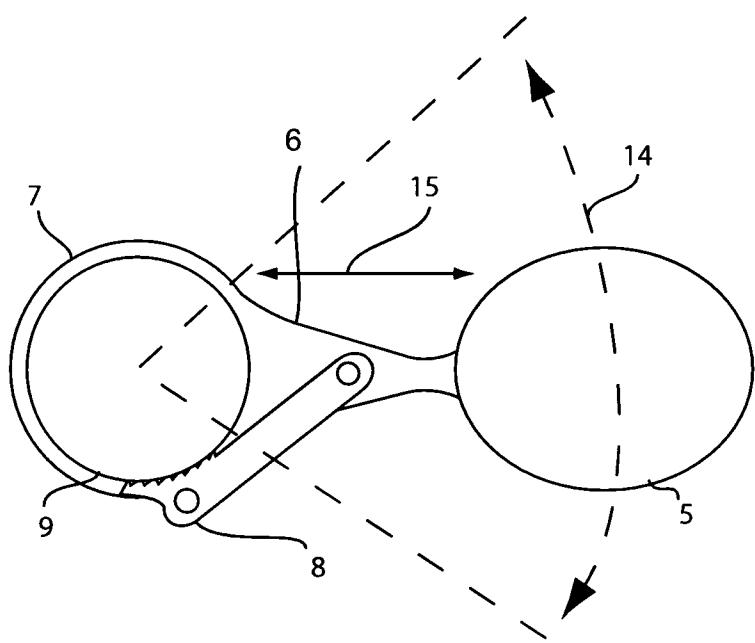


Figure 10

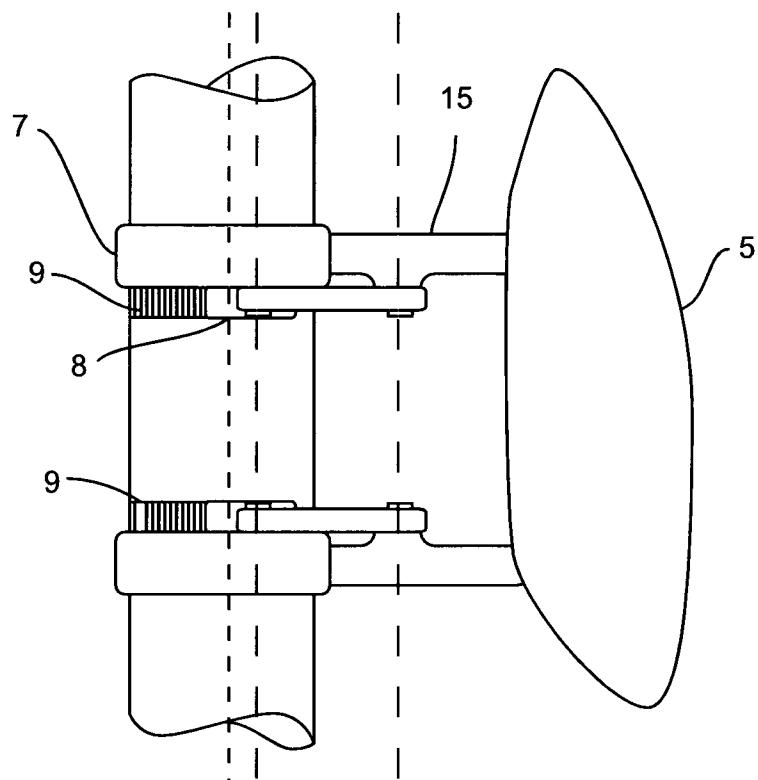


FIGURE 11

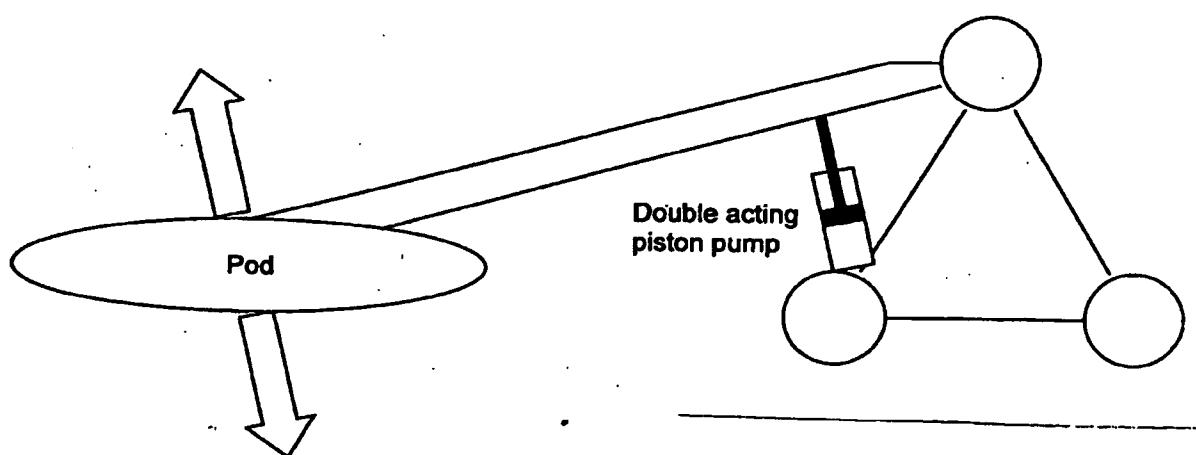


FIGURE 12

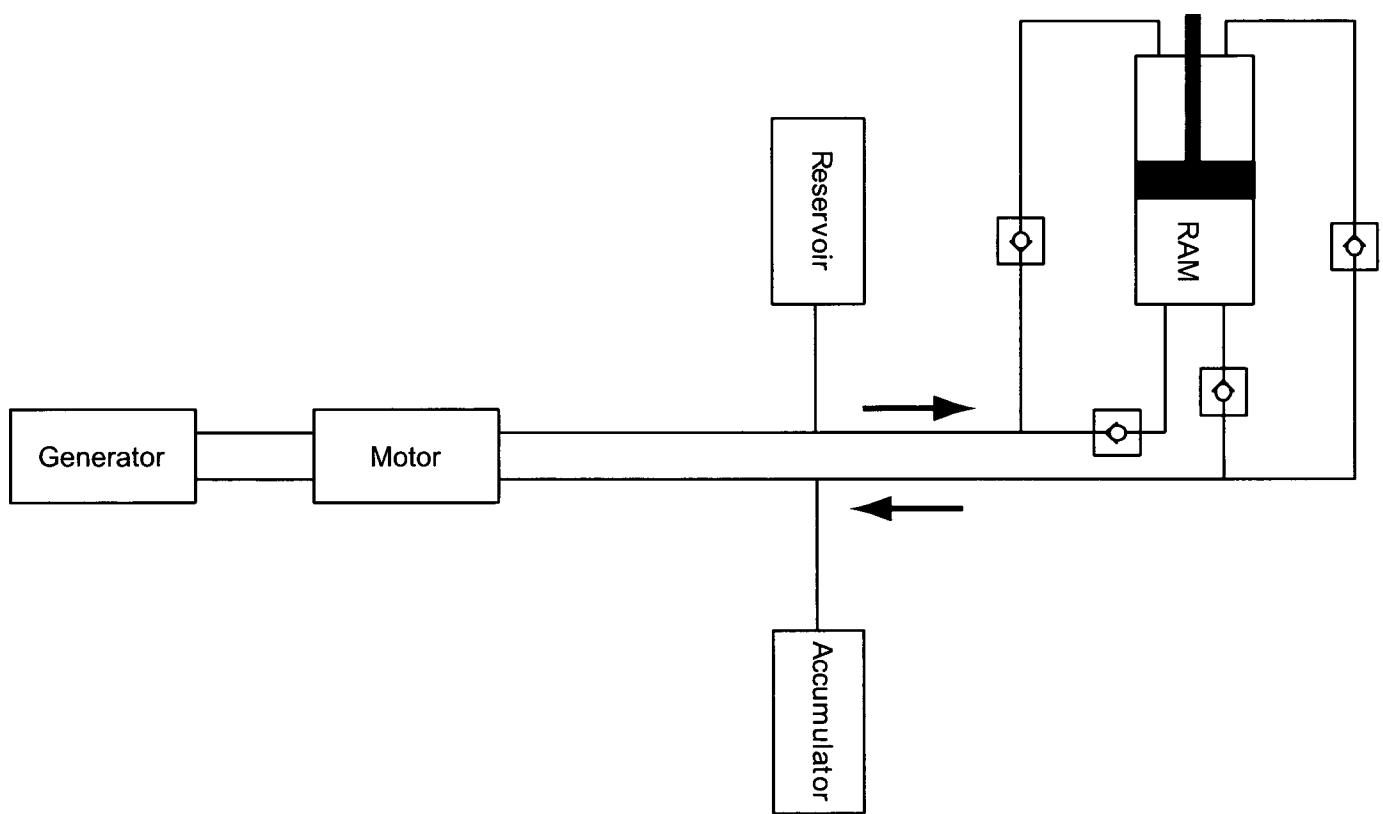


Fig. 12a

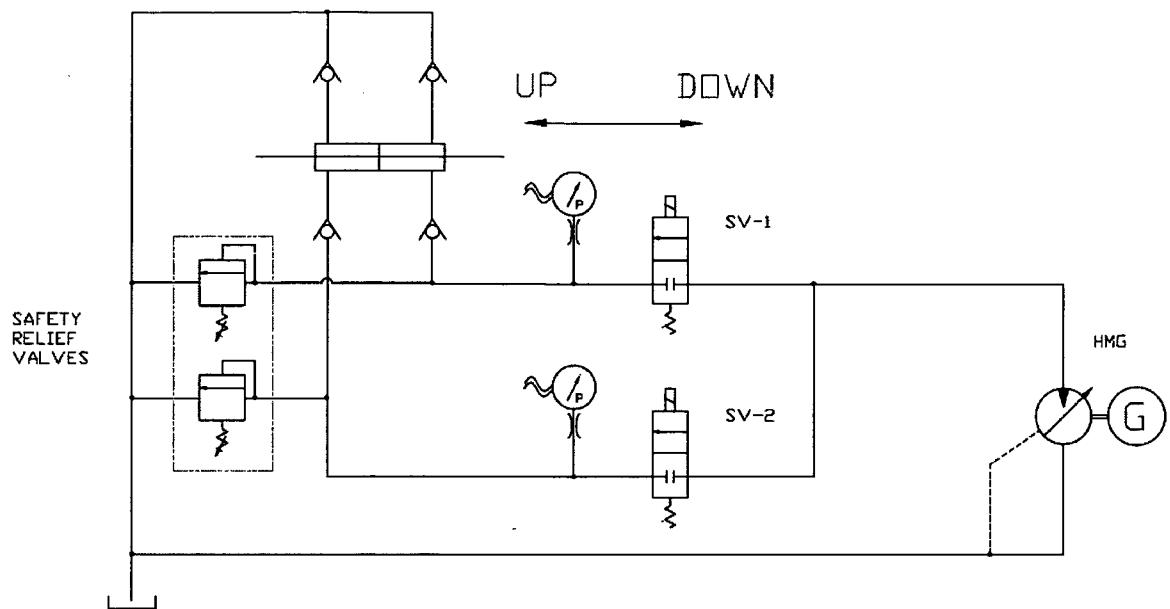


Fig. 12b

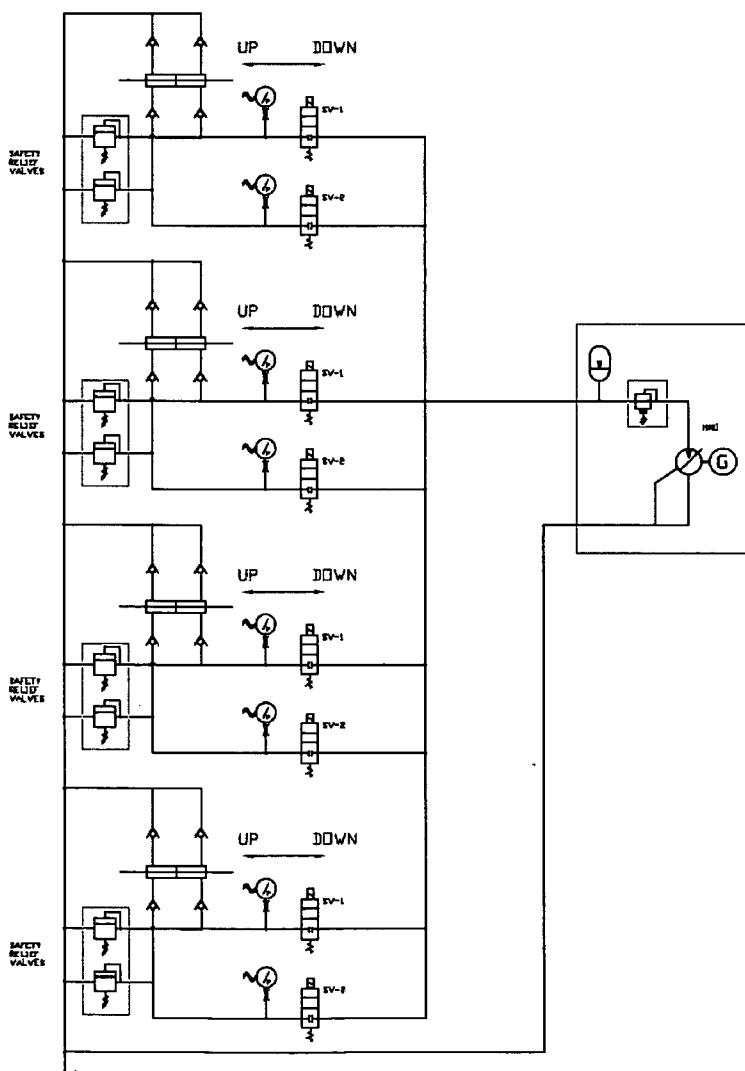


FIGURE 13

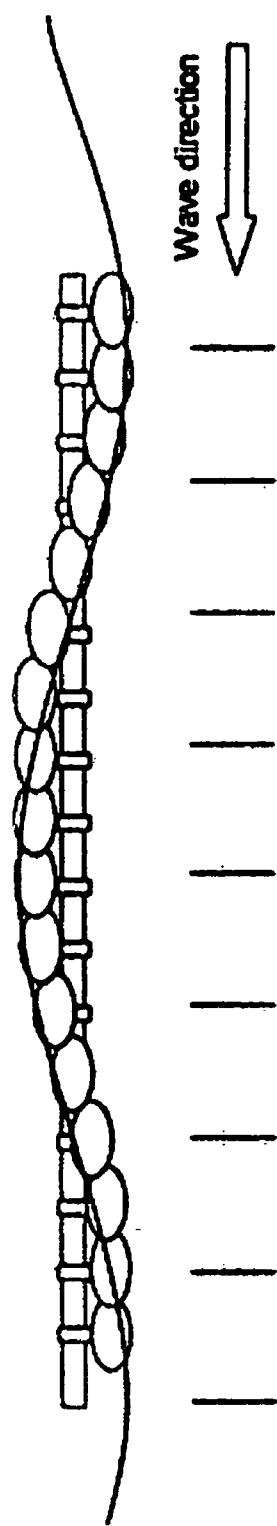


FIGURE 14

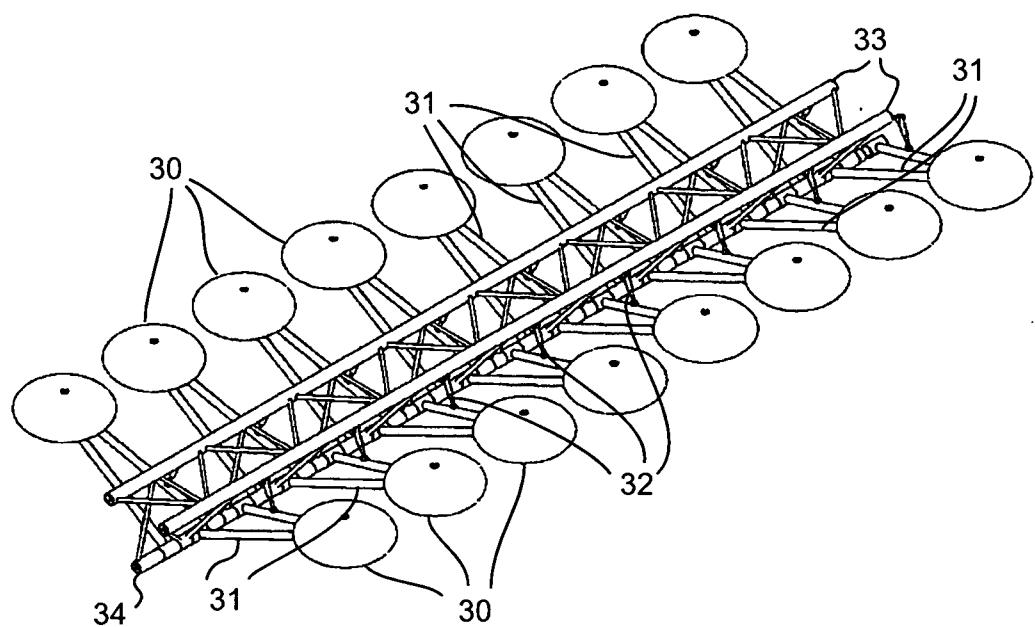


FIGURE 15

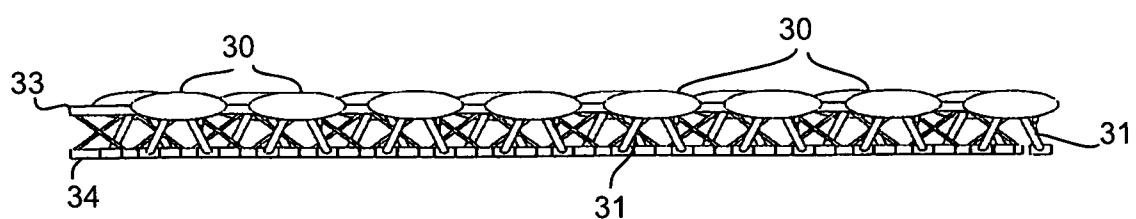


FIGURE 16

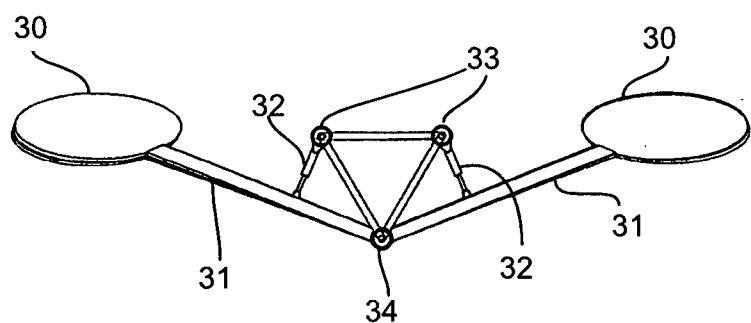


FIGURE 17

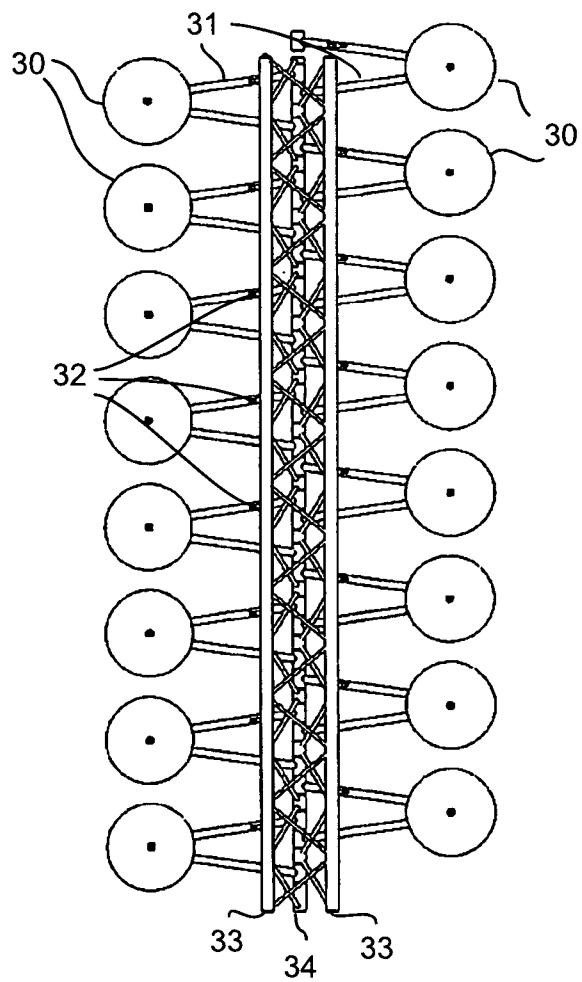


FIGURE 18

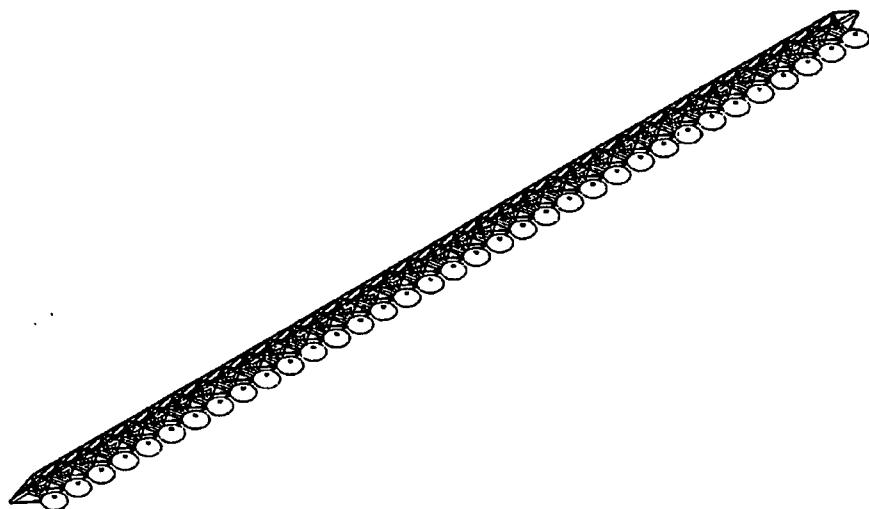


FIGURE 19

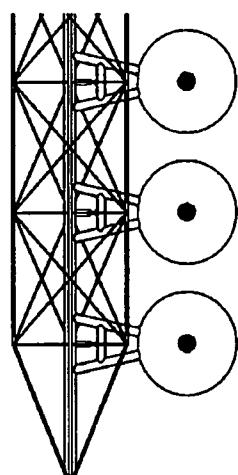


FIGURE 20

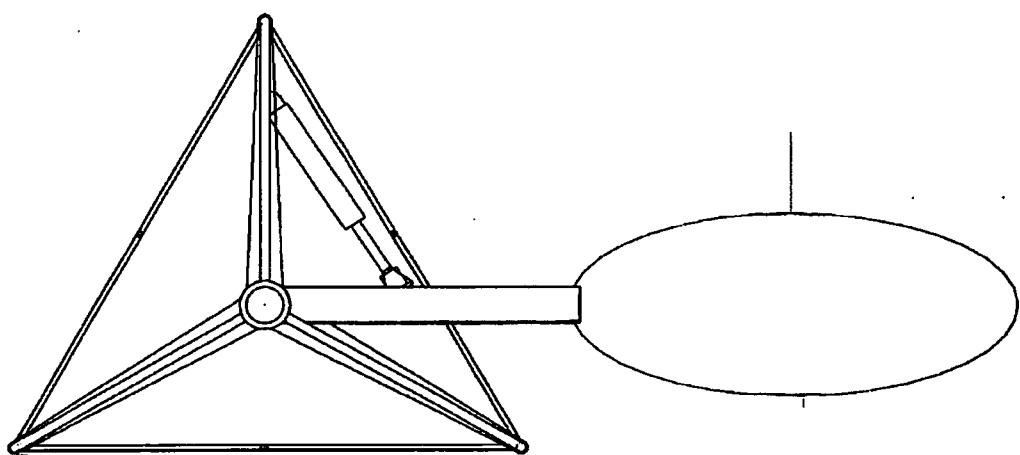


FIGURE 21



FIGURE 22

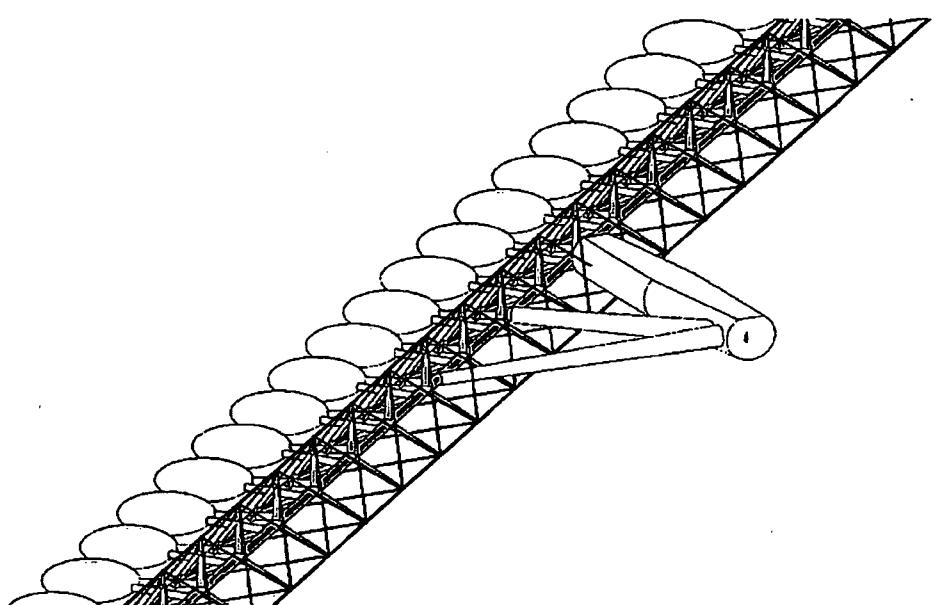
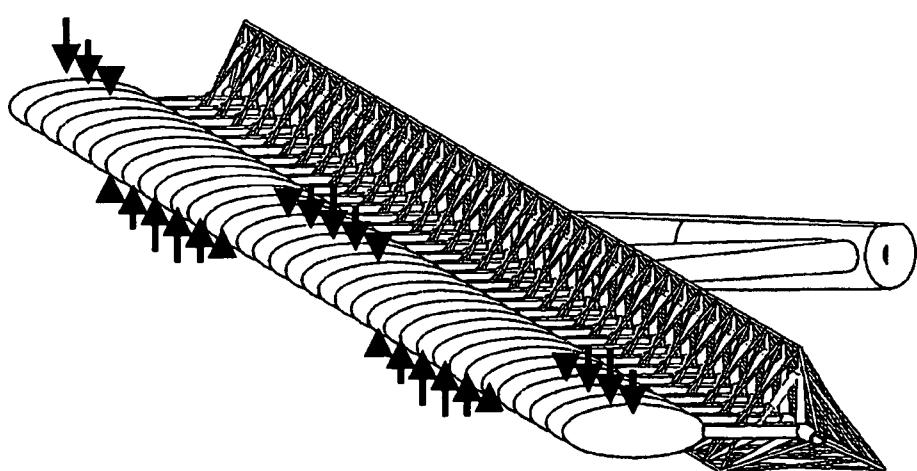
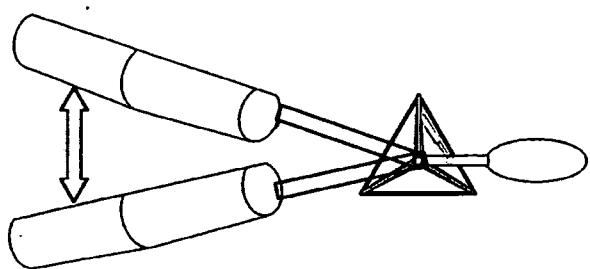
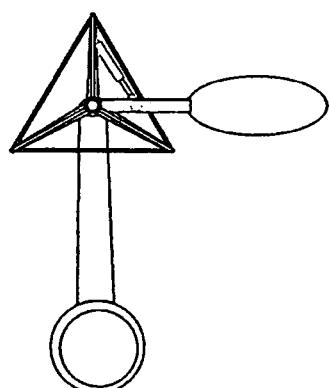
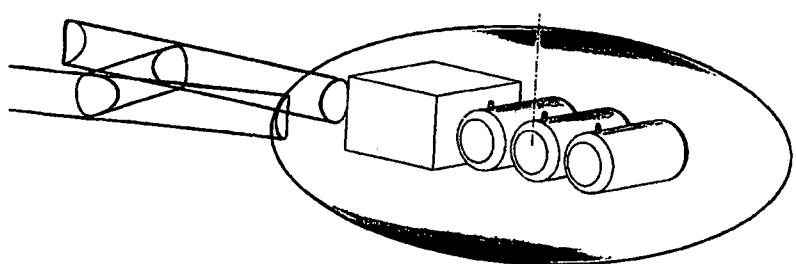


FIGURE 23



**FIGURE 24****FIGURE 25****FIGURE 26**

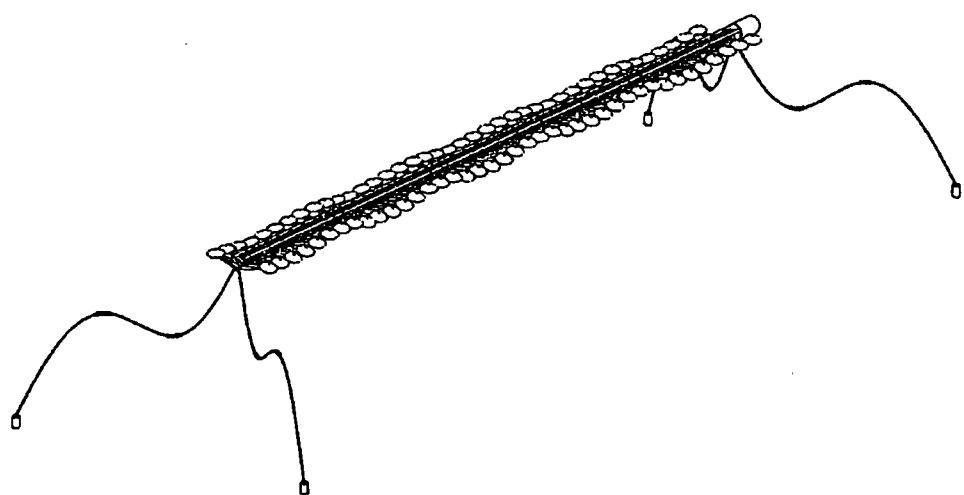
**FIGURE 27****FIGURE 28**

FIGURE 29

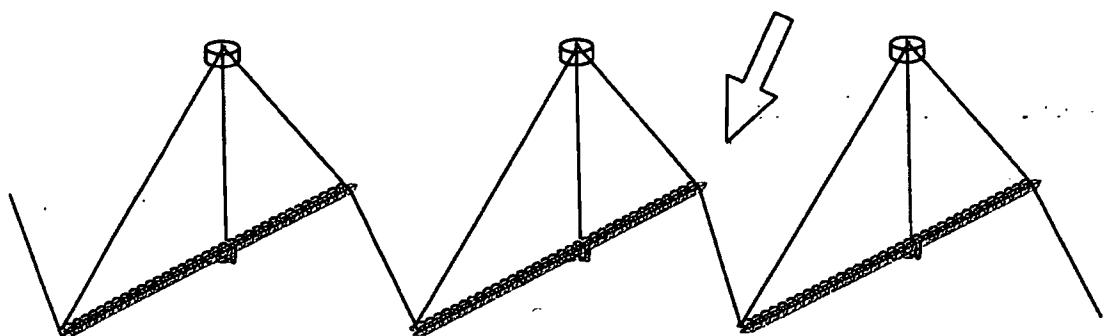


FIGURE 30

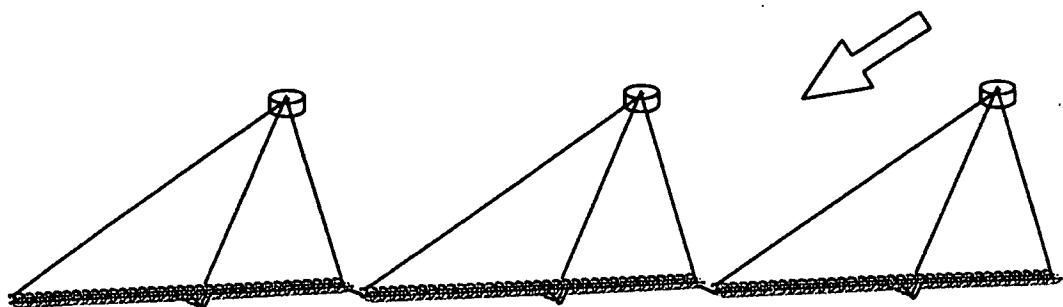


FIGURE 31

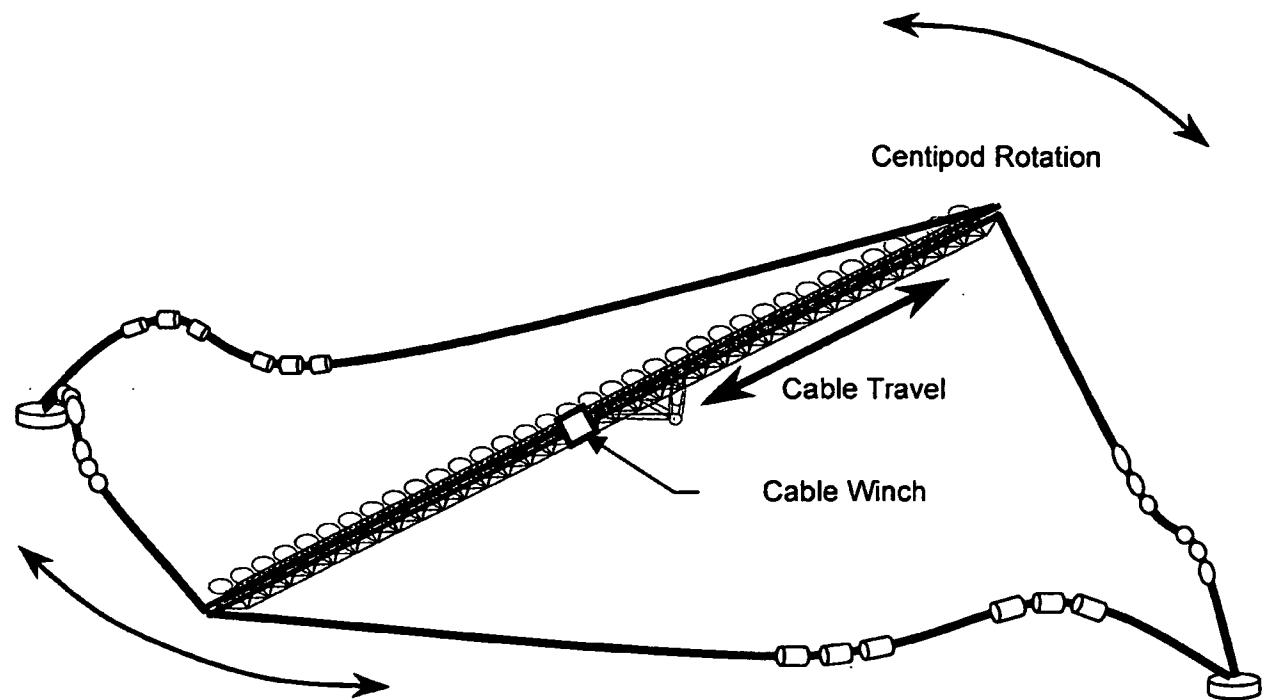


FIGURE 32

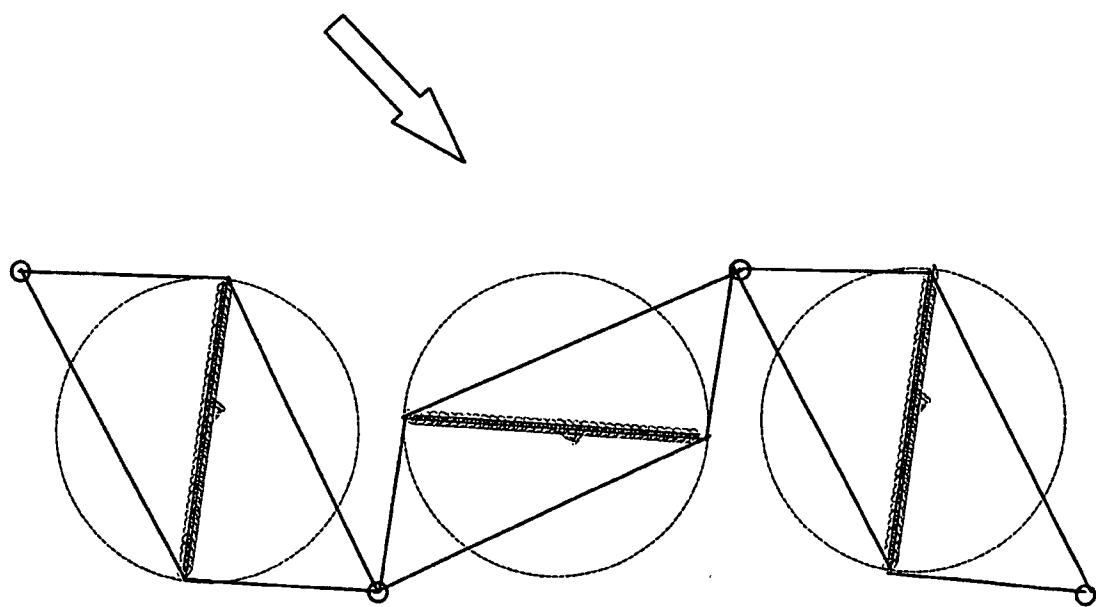


FIGURE 33

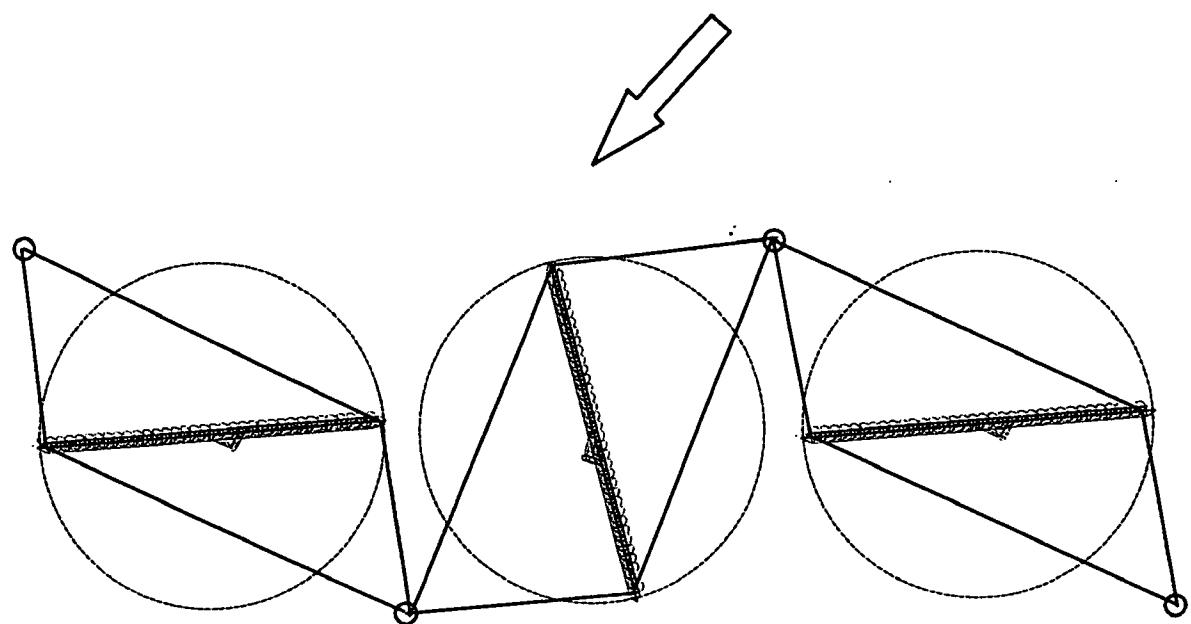


Fig. 33a

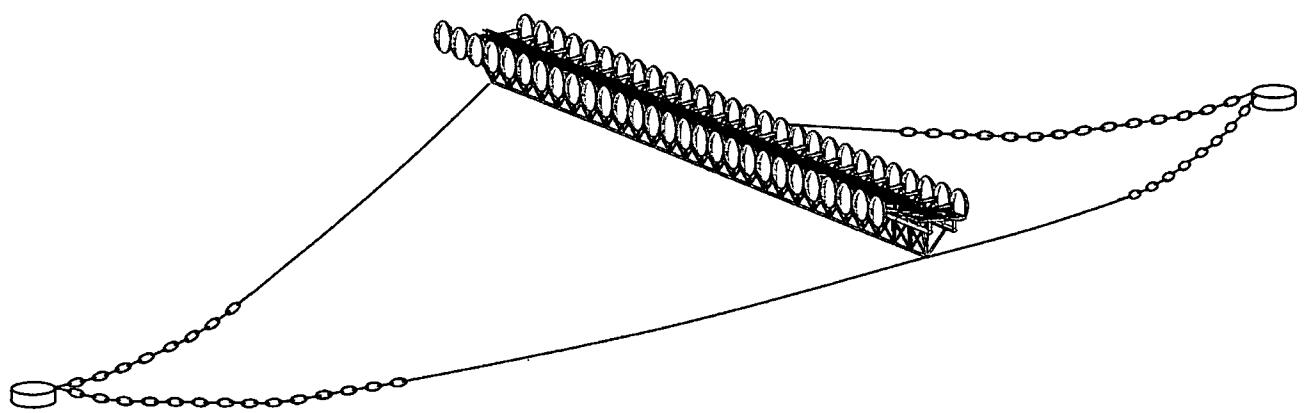


Fig. 33b

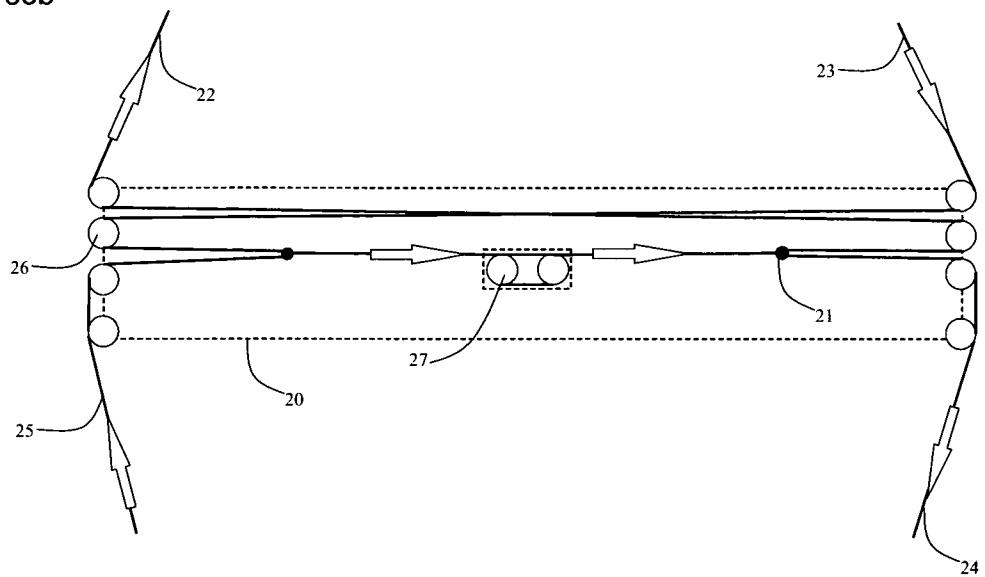


Fig. 33c

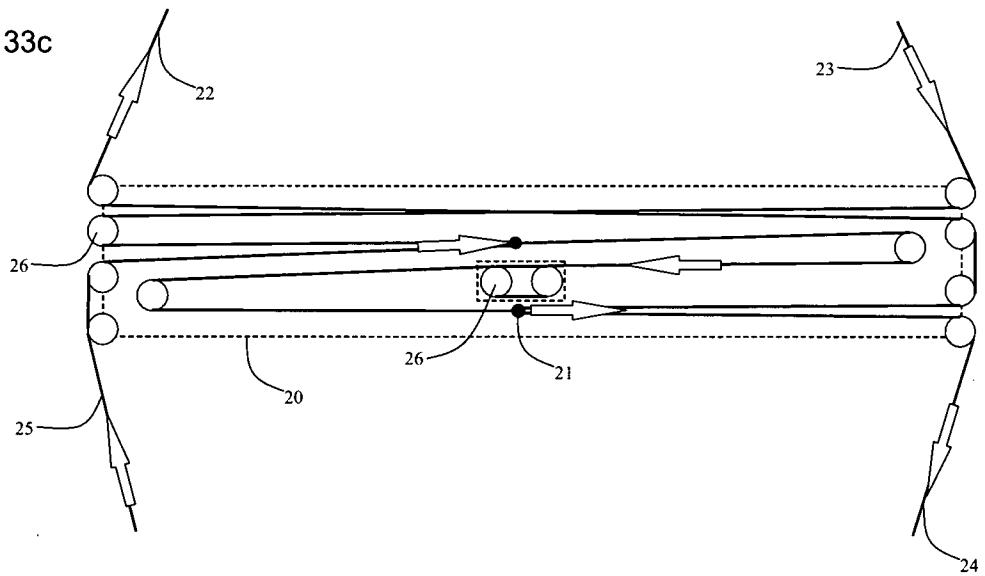


Fig. 33d

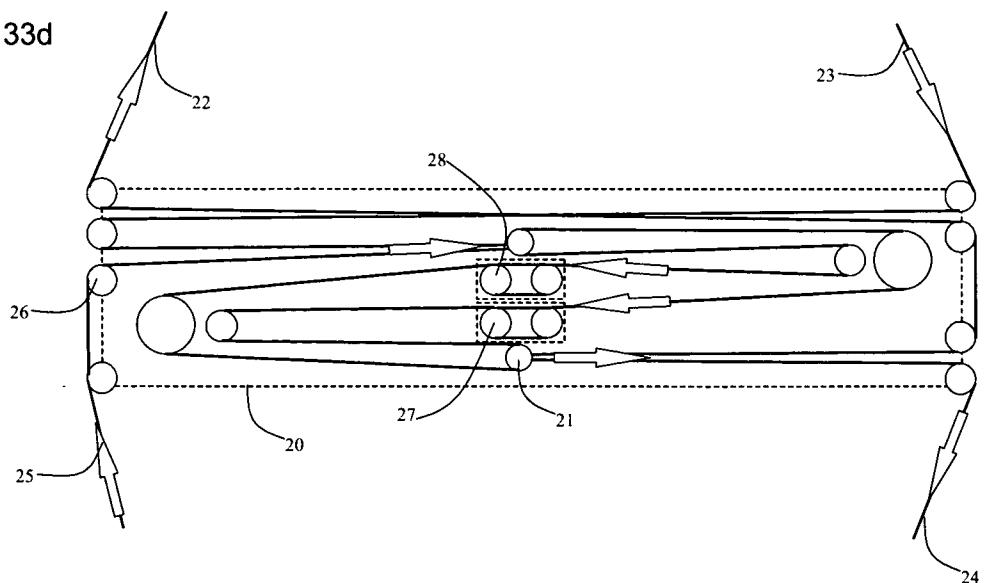


Fig. 34

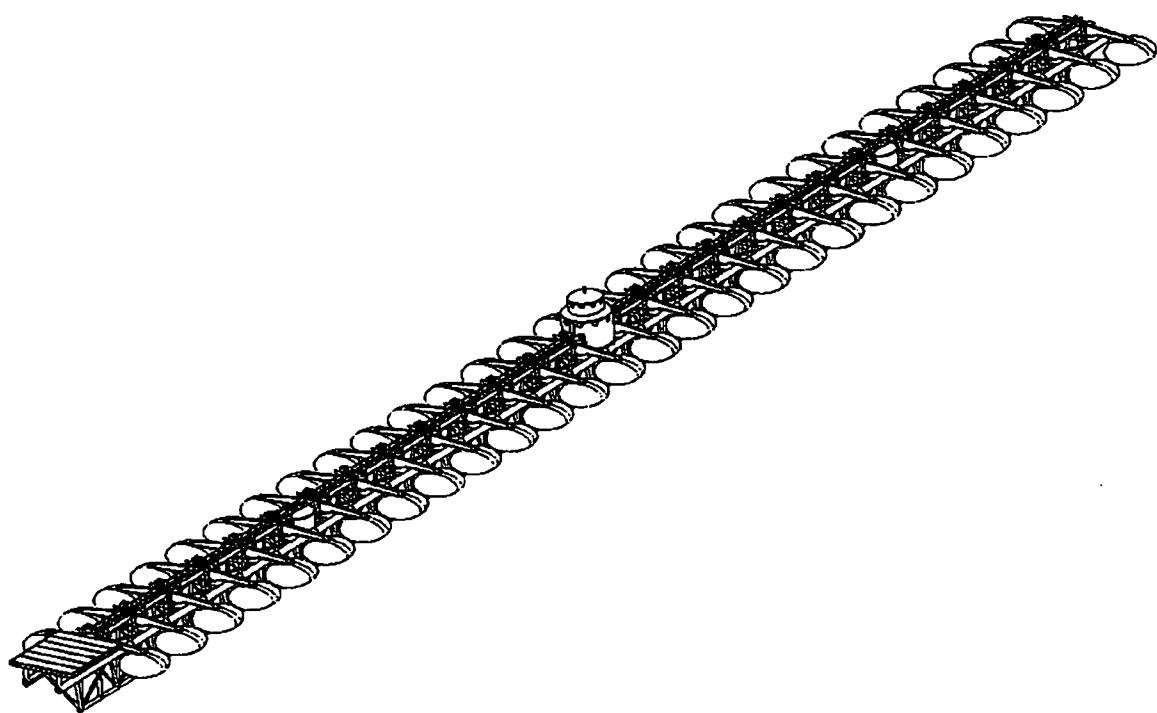


Figure 35

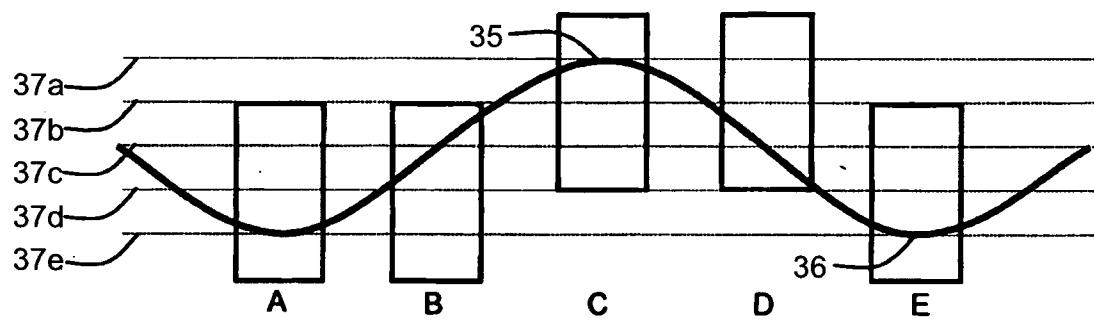


Figure 36

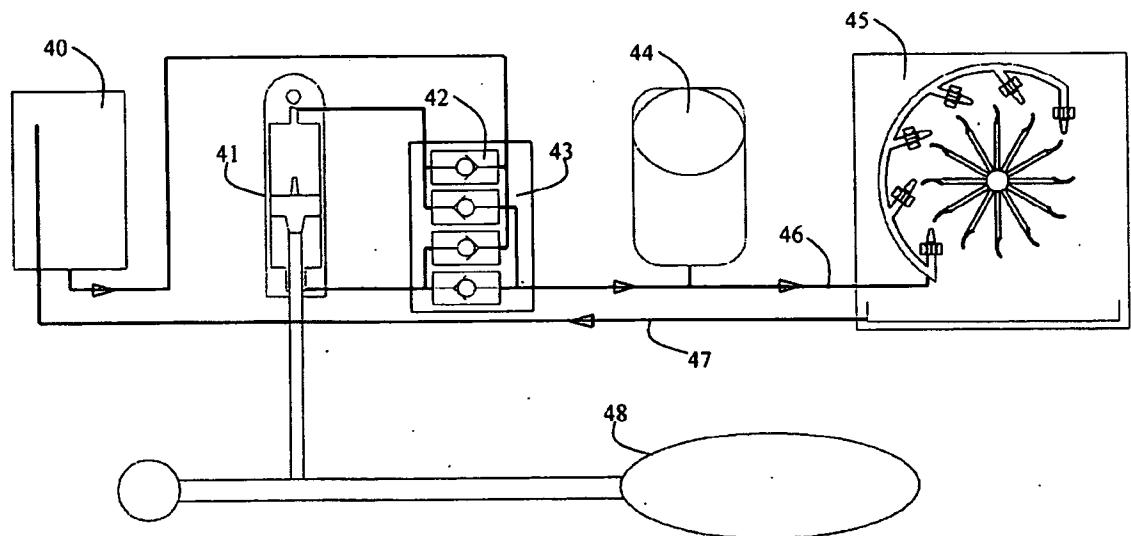


Fig. 37

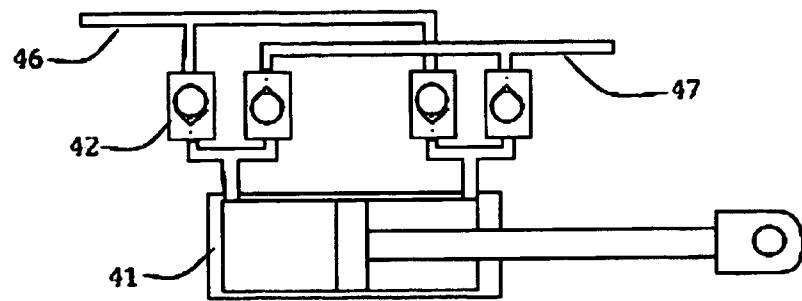


Fig. 38a

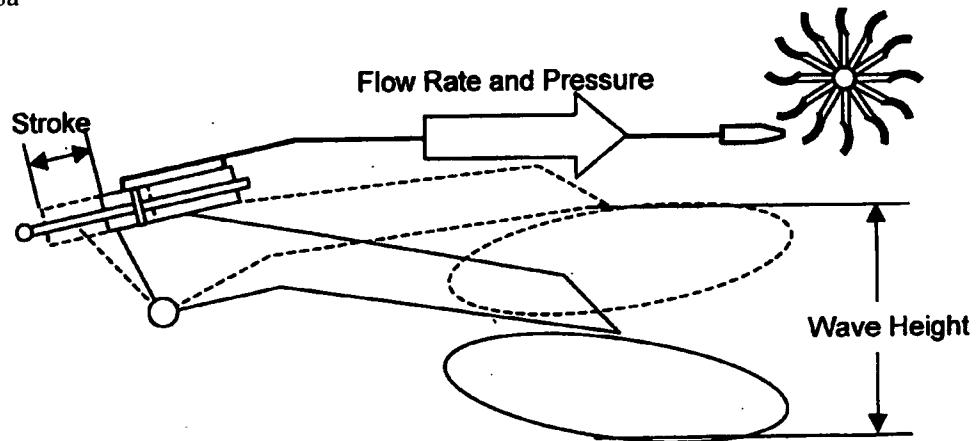


Fig. 38b

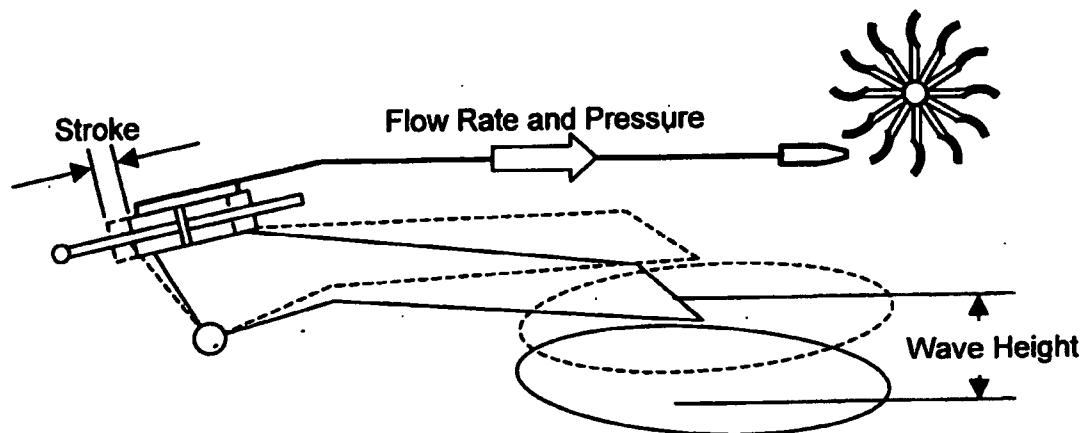


Fig. 39

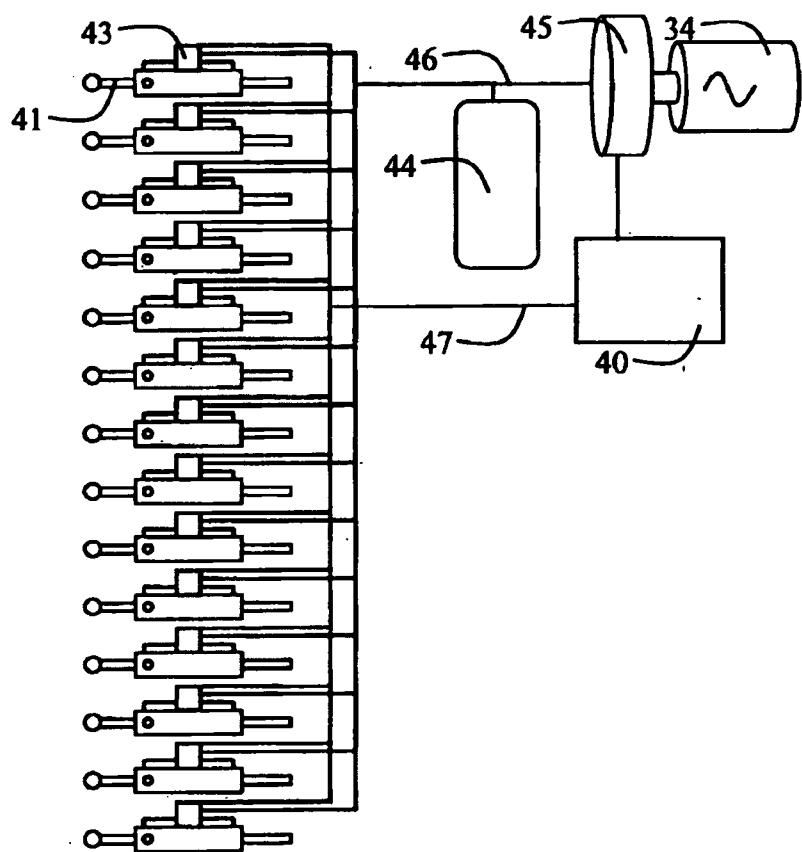


Fig. 40

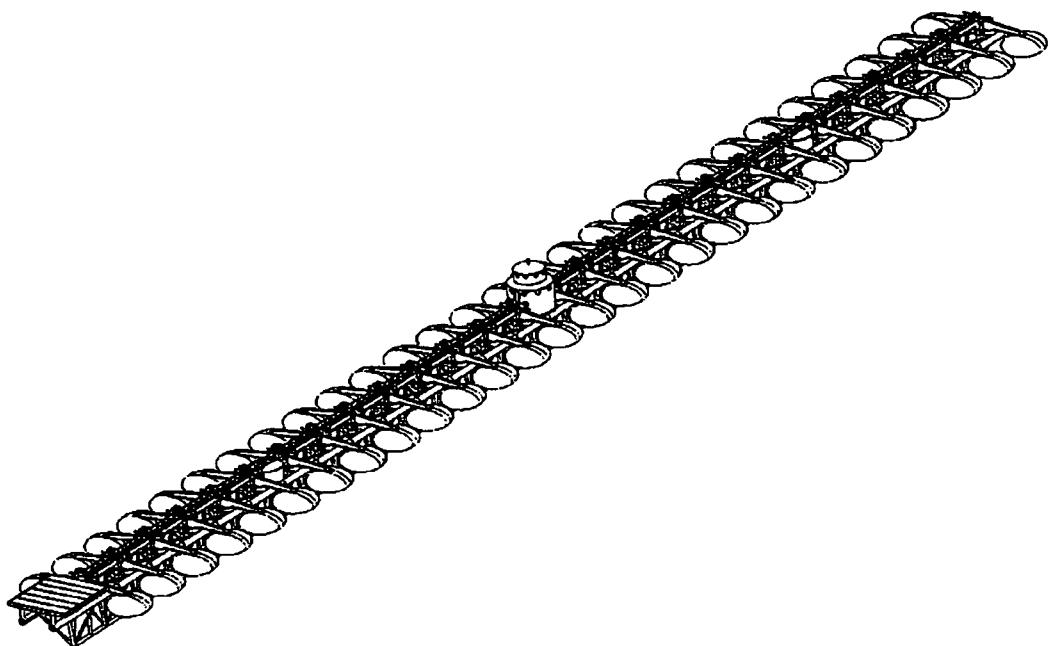


Fig. 41

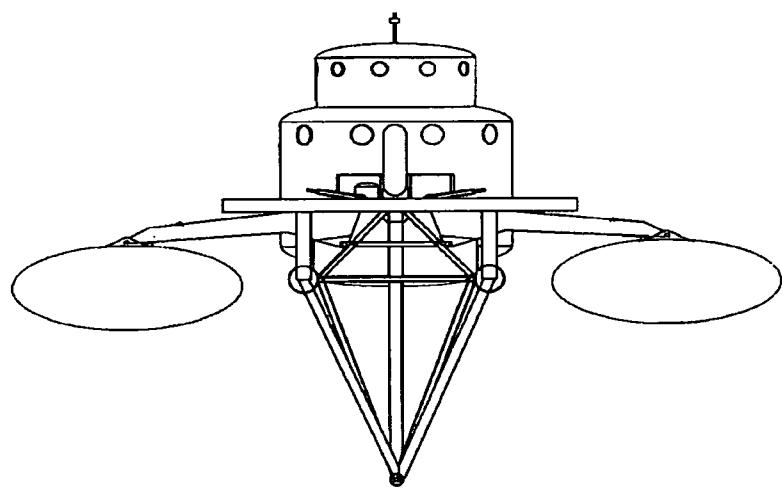


Fig. 42

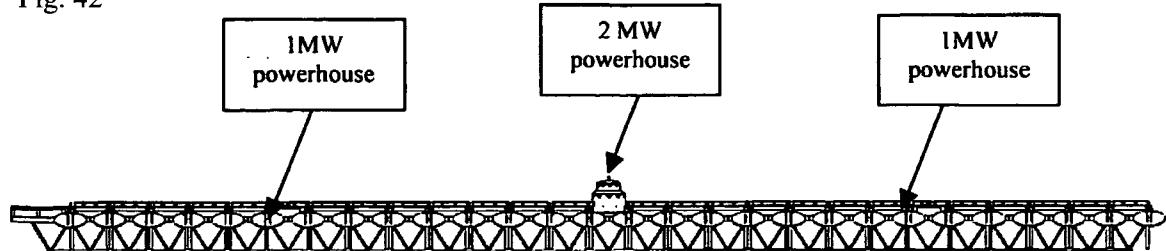


Fig. 43

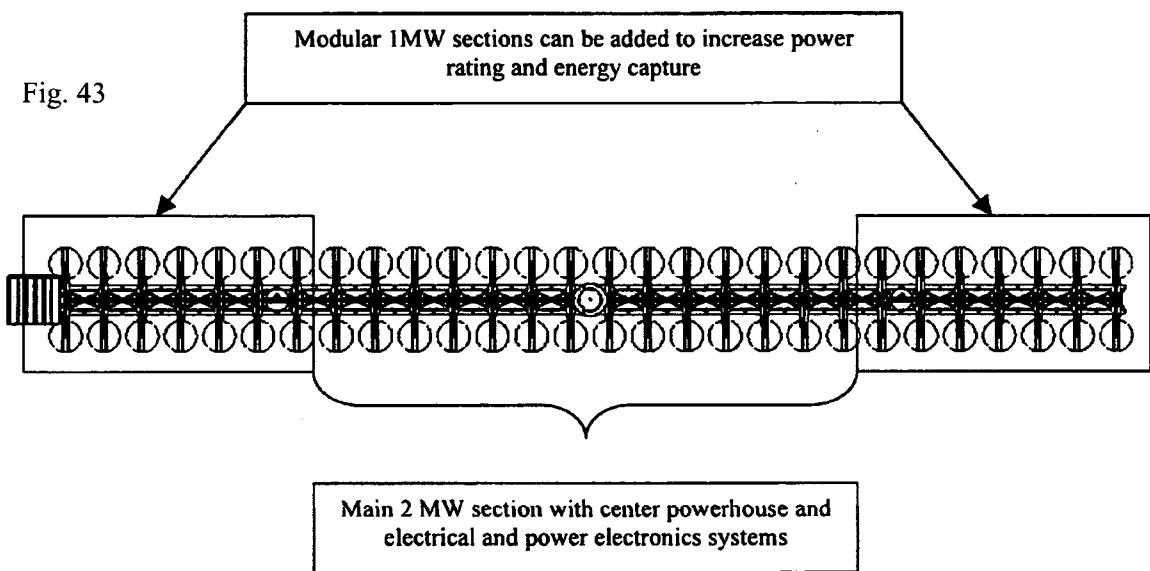


Fig. 44

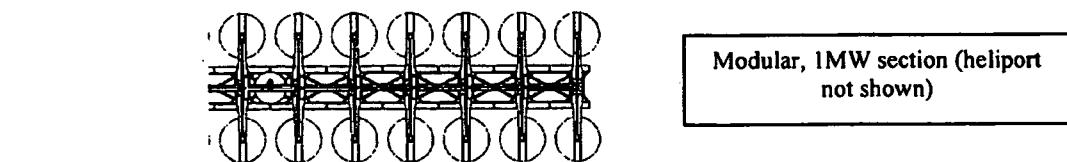


Fig. 45

Fig. 46

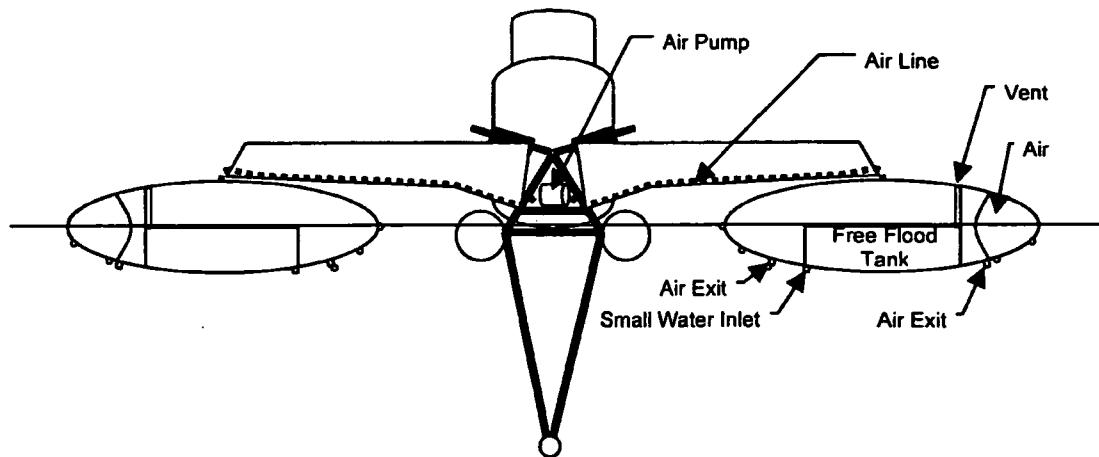


Fig. 47

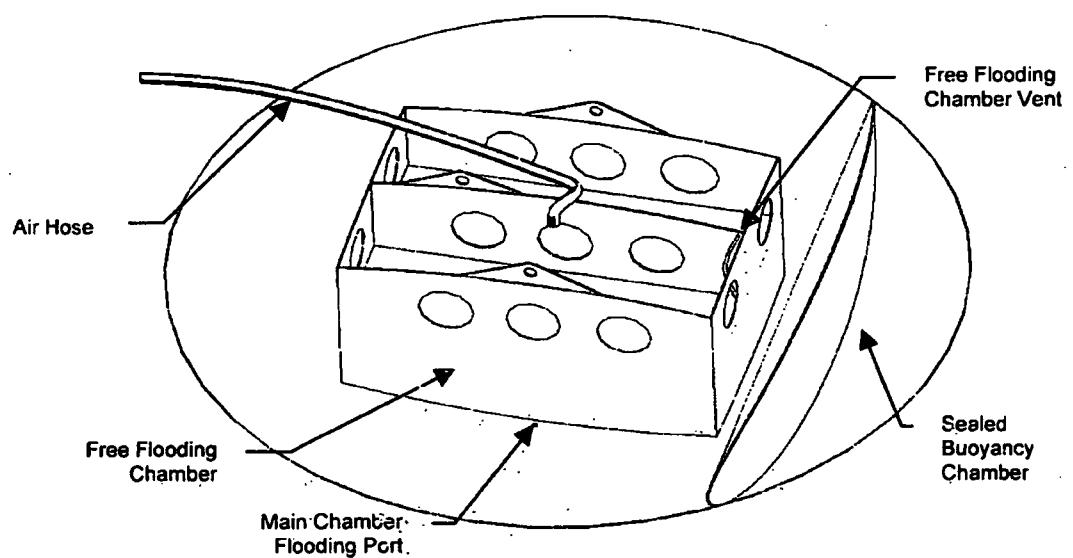


Fig. 48

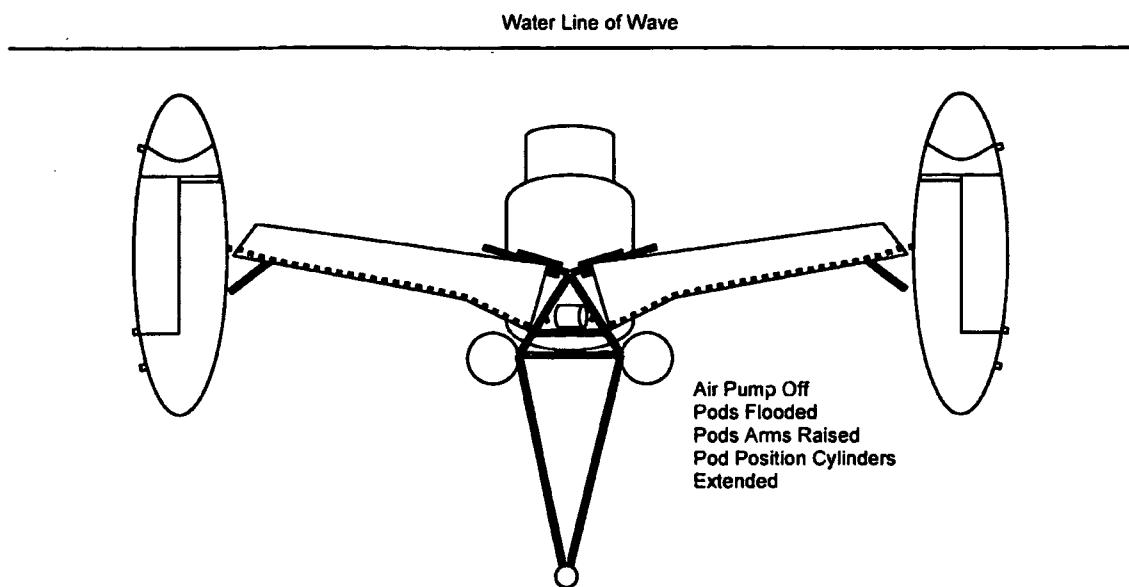


Fig. 49

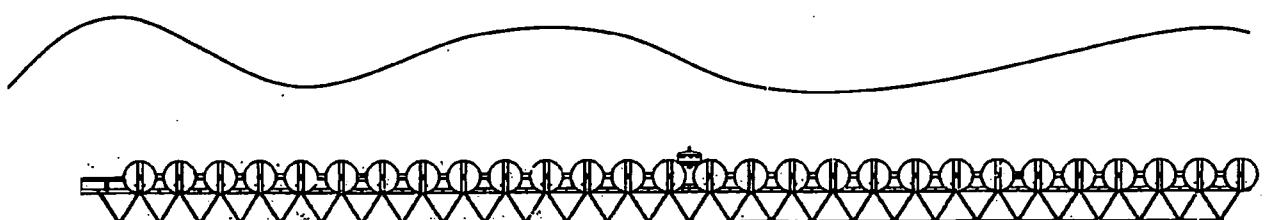


Fig. 50

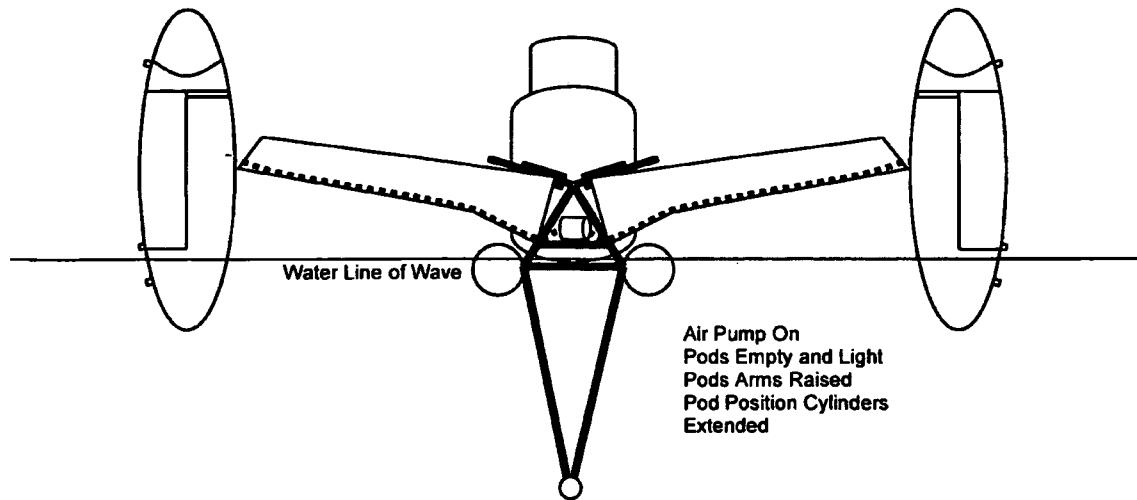


Fig. 51

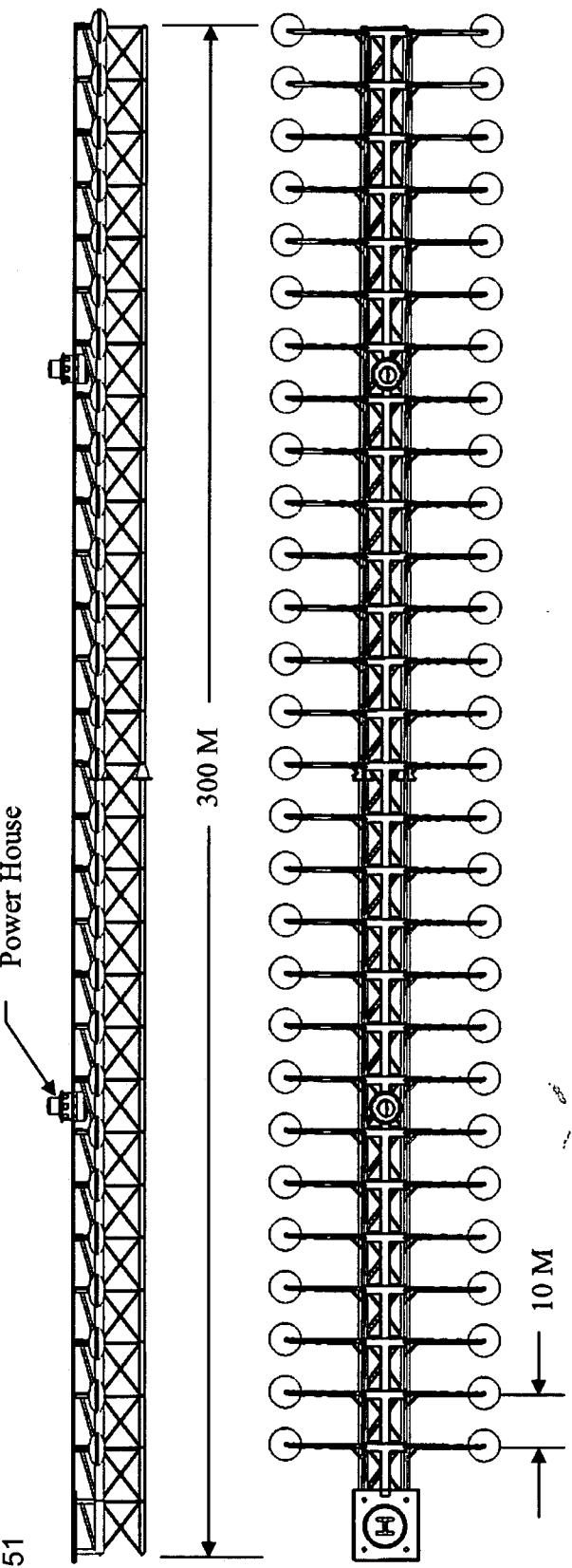


Fig. 52

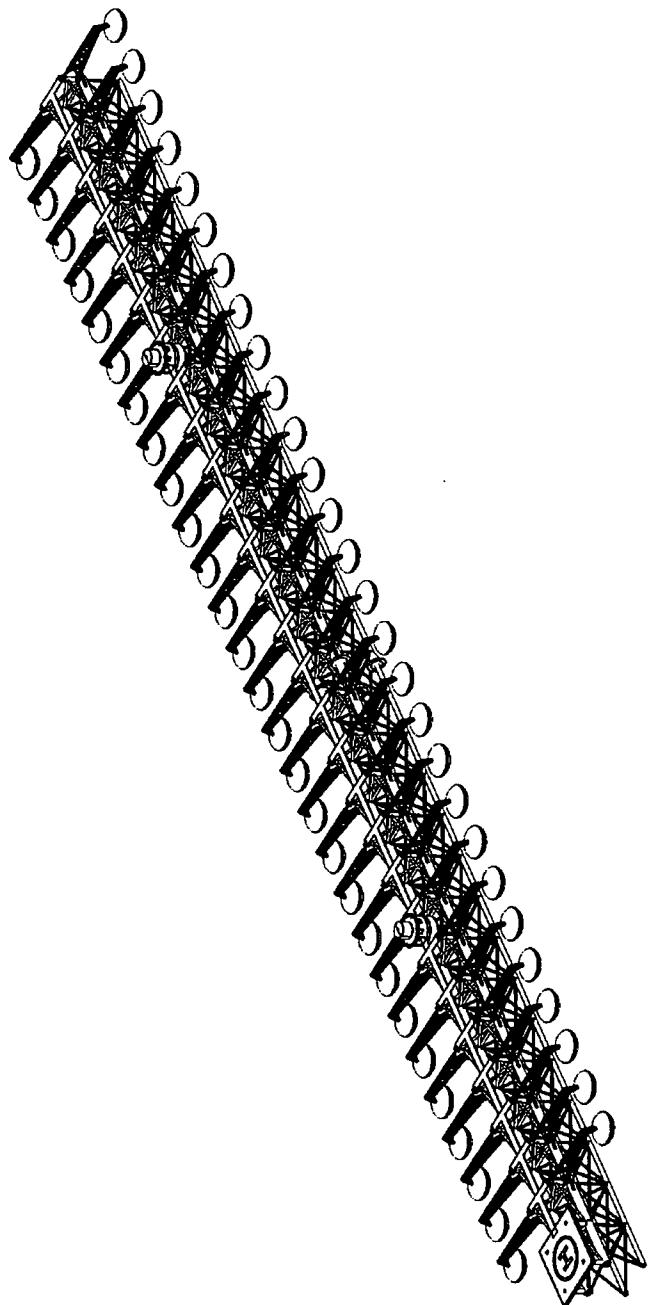


Fig. 53

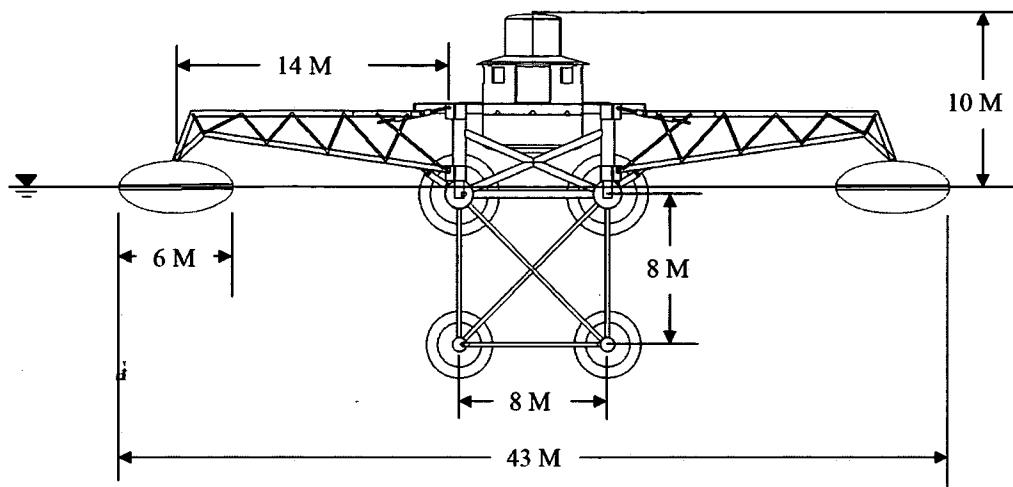


Fig. 54a

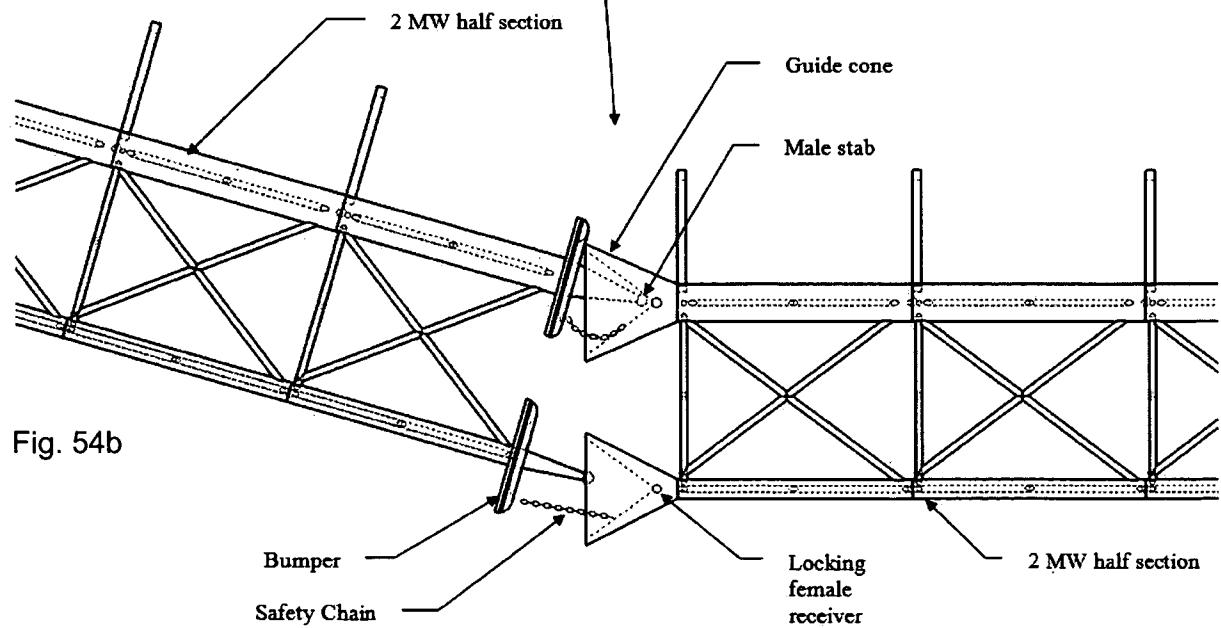
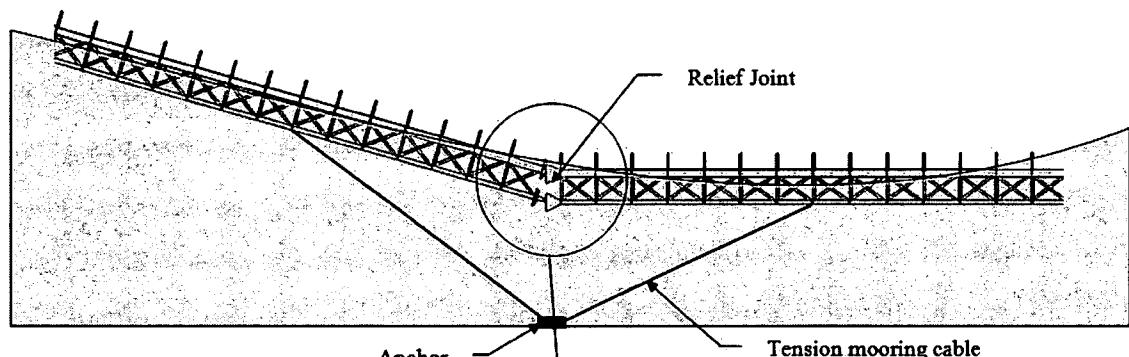


Fig. 54b