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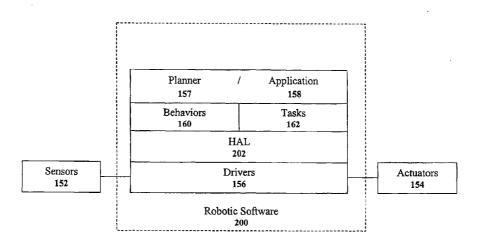
- (71) Applicant (for all designated States except US): EVOLU-TION ROBOTICS, INC. [US/US]; 130 W. Union Street, Pasadena, CA 91103 (US).
- (72) Inventors; and
- (75) Inventors/Applicants (for US only): MURRAY, Thomas, J., IV [US/US]; 451 E. Wilshire Avenue, Fullerton, CA

92832 (US). PHAM, Baoquoc, N. [US/US]; 291 S. Euclid Avenue #PH3, Pasadena, CA 91101 (US), PIRJA-NIAN, Paolo [US/US]; 1731 Golf Club Drive, Glendale, CA 91206 (US).

- (74) Agent: ALTMAN, Daniel, E.; Knobbe, Martens, Olson & Bear, LLP, 2040 Main Street, 14th Floor, Irvine, CA 92614 (US).
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(54) Title: SENSOR AND ACTUATOR ABSTRACTION AND AGGREGATION IN A HARDWARE ABSTRACTION LAYER FOR A ROBOT



(57) Abstract: The invention is related to methods and apparatus that provide a hardware abstraction layer (HAL) (202) for a robot. A HAL (202) can reside as a software layer or as a firmware layer residing between robot control software (157, 158, 160, 162) and underlying robot hardware (152, 154) and/or an operating system (156) for the hardware. The HAL (202) provides a relatively uniform abstract for aggregates of underlying hardware such that the underlying robotic hardware is transparent to perception and control software (157, 158, 160, 162), i.e., robot control software (157, 158, 160, 162). This advantageously permits robot control software (157, 158, 160, 162) to be written in a robot-independent manner. Developers of robot control software are then freed from tedious lower level tasks. Portability is another advantage. For example, the HAL (202) efficiently permits robot control software (157, 158, 160, 162) developed for one robot to be ported to another. In one example, the HAL (202) permits the same navigation algorithm to be ported from a wheeled robot (104) and used on a humanoid legged robot (106).



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Authorized officer

McDieunel Marc

Telephone No. (703) 305-4478

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