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(71) Applicant: **THE UNIVERSITY OF KANSAS** [US/US]; 245 Strong Hall, 1450 Jayhawk Boulevard, Lawrence, Kansas 66045 (US).

(72) Inventors: **ROSA-MOLINAR, Eduardo**; 1618 Gennesse Street, Lawrence, Kansas 66044 (US). **HASE, Allen**; 245 Strong Hall, 1450 Jayhawk Boulevard, Lawrence, Kansas 66045 (US). **YOUNG, Robert**; 245 Strong Hall, 1450 Jayhawk Boulevard, Lawrence, Kansas 66045 (US). **HORNHUBER, Christian**; 245 Strong Hall, 1450 Jayhawk Boulevard, Lawrence, Kansas 66045 (US).

(74) Agent: **JOHNSON, R. Brian** et al.; 999 Peachtree St. NE, Suite 1300, Atlanta, Georgia 30309 (US).

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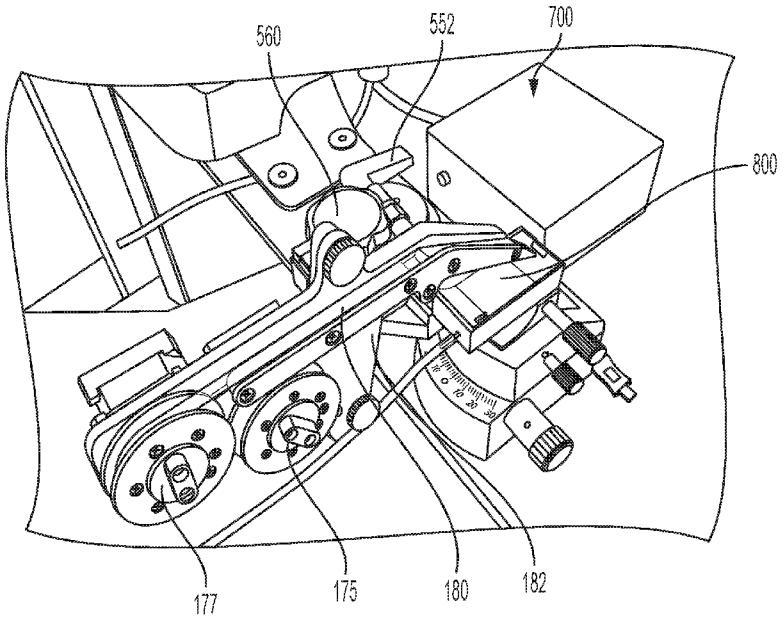


FIG. 9

(57) Abstract: A plurality of accessory components for use in respective reel to real sectioning, serial sectioning, and array tomography sectioning described herein incorporate mechanical and electro-mechanical engineering to provide accessory tools for attachment to and use with a microtome, as shown in several of the figures of this disclosure.

WO 2021/026367 A1

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APPARATUS AND METHODS FOR ULTRAMICROTOME SPECIMEN PREPARATION

CROSS REFERENCE TO RELATED APPLICATIONS

[0001] This application claims priority to and incorporates by reference four United States Provisional Patent Applications including U.S. Application Serial No. 62/883,918, U.S. Application Serial No. 62/883,496, U.S. Application Serial No. 62/891,067, and U.S. Application Serial No. 62/893,534.

BACKGROUND

[0002] Electron microscopy can be advantageously used to investigate the ultrastructure of biological samples such as cells and tissue, polymer resin samples, and crystalline samples such as inorganic substances. Two types of electron microscopes are known: scanning electron microscopes (hereinafter sometimes referred to as SEMs) and transmission electron microscopes (hereinafter sometimes referred to as TEMs).

[0003] In an electron microscope column, incident electrons are accelerated into, for example, epoxy resin-embedded samples (see Figure 1). A number of interactions between the accelerated electrons and atoms contained within the resin-embedded sample result in elastic and inelastic scattering of electrons (known as the electron interaction volume; see Figure 1). A number of signals generated (i.e., secondary electrons, backscattered electrons, cathodoluminescence, auger electrons, characteristic X-rays, and Bremsstrahlung X-rays) can be used for high-resolution electron microscopic imaging of ultrastructural features of cell and tissue organelles.

[0004] To advance different kinds of microscopy, researchers associated with this disclosure have developed a mechanically flexible and bendable conductive film that holds tissue, permits nanoscale cellular imaging, and eliminates charging artifacts resulting from the electron beam in scanning electron microscopes, transmission electron microscopes, etc. The conductive film can also be used for optical light microscopes to transmit light through the substrate for bright-field and fluorescence imaging.

[0005] In one embodiment of these films, graphene is uniformly coated on one side of a 0.5-mil Polyimide Kapton Film (No Additional Adhesive) 6.4 mm [¼ inch] wide x 33m [36 yd] long (PIT0.5N/6.4). Different electrical conductivity can be achieved by controlling the graphene coating's thickness, ranging from tens of nanometers to hundreds of nanometers. Typically, for about 5-10 nm thickness, a sheet resistance of less than 45 ohm/square is achieved.

[0006] The conductive fixation and graphene-based substrates make it possible to take advantage of inelastic scattering of electrons' capabilities to generate many signals (e.g., cathodoluminescence, Bremsstrahlung X-rays characteristic X-ray, secondary electrons, backscatter electrons, and Auger electrons) that scatter in an angular dependent manner. Additional research is exploiting their angle of deflection and their energy loss to gather chemical elemental information (e.g., C, N, Mg, P, Fe, Cu, and Zn) at the tissue, cellular, and subcellular levels. This enables mapping metal ions at electrical synapses on the nanometric-micrometric spatial scale, which is currently impossible to do.

[0007] Co-pending and commonly owned international PCT Application Serial No. PCT/US2019/013051, "Conductive Fixation of Organic Material," filed January 10, 2018 and U.S. Provisional Application Serial No. 62/778,140 "Graphene Based Substrates for Imaging," filed on December 11, 2018, discuss the graphene substrates in more detail, and are incorporated herein as if set forth in their entireties.

[0008] To take advantage of high-resolution microscopies, the life sciences need better sample preparation workflows, reagents that will overcome charging and sample damage caused by electron beam-sample interactions in the electron microscope, and tools for accurate microscopic imaging in both two dimensional and three-dimensional views. These tools are set forth in detail herein.

BRIEF SUMMARY OF THE DISCLOSURE

[0009] Advancements in the kinds of slide mechanisms, or sample substrates, for sample collection have led to a need for more advanced sample collection on better slide surfaces than traditional slides that are known in the art. This disclosure provides a plurality of accessory tools for attachment to and use with an ultramicrotome, particularly for automatically collecting the sample sections onto a specialized sample surface, including but not limited to a graphene-based surface that is configured for accurate imaging under numerous kinds of microscopes and

imagers. As an overview, this disclosure presents accessory tools for a microtome that aid in volume electron microscopy and specimen preparation. This disclosure provides supporting disclosure for at least four (4) different holders for four (4) different volume resin-based electron microcopy techniques (e.g., serial section scanning transmission electron microscopy (ssSTEM; see Figures 27A, 27B); array tomography (Arraytome [AT]; see Figure 31] and reel-to-reel microscopy [rrM; see Figure 8]). In one non-limiting embodiment, each of these configurations (ssSTEM, AT, rrM) are disclosed herein with the appropriate accessory tools that accommodate the microtome depositing ultra-thin (50 nm or less) and/or semi-thin (above 50 nm) sections on the Kapton graphene coated tape, coverslips, stubs, and grids. These sample collection surfaces can be post-stained or immuno-stained using fluorescence and/or chromogens of immunogold and/or immunogold derivative labels.

[0010] In one embodiment, a system for sectioning resin-embedded cells and/or tissues with an ultramicrotome includes a modular reel-to-reel assembly comprising a reel-to-reel frame that connects to an upper region of a knife-stage used with the ultramicrotome, wherein the upper region of the knife-stage is adapted to connect the modular reel-to-reel assembly to the ultramicrotome. The modular reel-to-reel assembly further includes a feeder reel connected to a length of tape, wherein the feeder reel is rotatably coupled to the reel-to-reel frame; a take-up reel connected to the reel-to-reel frame and receiving the tape across the reel-to-reel frame; a feeder motor that drives rotation of the feeder reel; a take-up motor that drives rotation of the take-up reel; at least one cantilever arm position sensor connected to the modular reel-to-reel assembly and/or the ultramicrotome; and at least one electronic control unit controlling respective speeds of the feeder motor and the take-up motor, wherein the electronic control unit adjusts the respective speeds according to a cantilever arm position signals received from the at least one cantilever arm position sensor.

[0011] At least one embodiment further includes a knife stage adapter connecting the upper region of the knife stage to the reel-to-reel frame.

[0012] At least one embodiment further includes the feeder reel and the take-up reel made of aluminum wheels with respective hubs for wrapping the tape, the respective hubs having a calibrated circumference adapted to maintain a controllable speed and a settable tension of the tape extending between the feeder reel and the take-up reel.

[0013] At least one embodiment further includes the feeder reel and the take-up reel being made of aluminum and aluminum alloys having specified conductivity and specified magnetically shielding properties.

[0014] In other embodiments, the reel-to-reel frame is detachable from the upper region of the knife-stage without removing the feeder reel or the take-up reel or the tape.

[0015] In other embodiments, the feeder reel and the take-up reel are adapted to be re-attached to an in-situ scanning electron microscope reel-to-reel imaging system.

[0016] In other embodiments, the in-situ scanning electron microscope reel-to-reel imaging system is selected from secondary electron imaging systems, backscatter electron imaging systems, scanning transmission electron microscopy imaging systems.

[0017] In some non-limiting embodiments, an in-situ scanning electron microscope reel-to-reel imaging system is selected from quantitative measurement imaging systems comprising EDS and EELS systems.

[0018] In some embodiments, a specimen cantilever arm is connected to a specimen block chuck configured to hold a specimen block in engagement with an edge of a blade connected to a knife boat connected to the knife-stage connected to the ultramicrotome, wherein the at least one cantilever arm position sensor comprises at least a first cantilever arm position sensor attached to a base section of the ultramicrotome underneath a second cantilever arm position sensor attached to the specimen cantilever arm.

[0019] In non-limiting embodiments, the tape is a Kapton® polyimide tape positioned to receive thin, semi-thin, semi-thick, and thick resin sections from the edge of the blade connected to a knife boat, connected to a knife-stage, which is connected to the ultramicrotome.

[0020] In non-limiting embodiments, the tape may include a carbon coating.

[0021] In non-limiting embodiments, the carbon coating is a graphene coating.

[0022] In non-limiting embodiments, a graphical user interface is connected to the electronic control unit and configured to receive data entry for programming the electronic control unit.

[0023] The embodiments further include non-limiting concepts such as the data entry including speed selections for the feeder motor and the take-up motor and revolution selections for a hub of the feeder reel and the take up reel.

[0024] In one embodiment, at least one of the motors is an encoded stepper motor.

[0025] In at least one embodiment, a knife stage adapter includes a base portion adapted to bolt into an upper region of a ultramicrotome knife-stage; a platform region receiving at least one adjustment screw attaching the platform region to the base portion at a plurality of selectable heights; an adapter edge configured to receive a plurality of specimen substrate holders in a modular connection.

[0026] In at least one other embodiment, the knife stage adapter is configured to connect to a respective specimen substrate holder in the form of a reel to reel frame.

[0027] In at least one other embodiment, a respective specimen substrate holder is a coverslip vise, referred to also as a clip.

[0028] In at least one embodiment of a central specimen holder attachable to a knife stage adapter a respective specimen substrate holder is a triggered holding apparatus.

[0029] In at least one embodiment, a lever arm on the knife stage adapter is configured for arcuate movement relative to the base portion and configured to adjust a position of the specimen substrate holder along the Z-axis.

[0030] In at least one embodiment, a reel-to-reel frame for tape-based electron microscopy includes a feeder reel adapted to receive a length of tape, wherein the feeder reel is rotatably coupled to the reel-to-reel frame; a take-up reel adapted to receive the tape across the reel-to-reel frame; and wherein the reel-to-reel frame is configured to integrate with a knife-stage and connect to an ultramicrotome that transfers cut resin sections onto the tape.

[0031] In at least one embodiment, the reel to reel frame includes receptacles for bolting the reel-to-reel frame to a knife stage adapter, which connects to a knife stage on the ultramicrotome.

[0032] In at least one embodiment, the feeder reel and the take-up reel are exposed.

[0033] In at least one embodiment, the feeder reel and the take-up reel are modular and separable components that connect to the reel-to-reel frame.

[0034] In at least one embodiment, the reel-to-reel frame is configured to integrate with an ultramicrotome knife-stage.

[0035] In at least one embodiment, a system for receiving a cut sample from an ultramicrotome includes a knife stage adapter configured for removable attachment to a knife carrier on an ultramicrotome, wherein the knife stage adapter defines X, Y, and Z axes relative to the ultramicrotome; a vise attached to the knife stage adapter, wherein the vise is configured to hold a polymer coverslip in a position to receive the cut resin sections thereon; and a lever arm

connected to the knife stage adapter and configured for arcuate movement about the knife stage adapter to position an end of the vise at selectable points along the Z axis and adjacent a specimen block on the ultramicrotome.

[0036] In one embodiment, the system places a cut resin section on the polymer coverslip.

[0037] In one embodiment, the cut resin section is one of a thin resin section, a semi-thin resin section, a semi-thick resin section, and a thick resin section.

[0038] In one embodiment, the vise is so dimensioned to hold a glass coverslip having a thickness in the range of 175 microns to 190 microns, the glass coverslip being compatible with optical microscopes.

[0039] In another embodiment, a scanning electron microscope stub holder is configured for use with an ultramicrotome to receive resin sections thereon and includes a substrate holder body defining a passageway with a first opening at one end of the holder body and a second opening extending from the first opening toward a second end of the holder body; a trigger that fits within the second opening, the trigger being actuated by a spring connected to the trigger and the holder body; a removable surface block configured to fit within the first opening of the holder body, the removable surface block held in place by the trigger biased by the spring.

[0040] In another embodiment, a fastening mechanism connects to a knife stage adapter that connects to a knife stage, wherein the fastening mechanism positions the removable surface block proximate the ultramicrotome.

[0041] In another embodiment, a substrate positioned across the surface block and held in place between sides of the surface block are connected to respective resin sections of the holder body and the trigger.

[0042] In another embodiment, a substrate positioned across the surface block includes a coated Kapton® polyimide layer or sheet.

[0043] In another embodiment, the substrate includes a carbon coated polyimide substrate.

[0044] In another embodiment, the stub holder further includes a graphene coated polyimide substrate.

[0045] In at least one other embodiment, an electronic controller allows for implementing electron microscopy on a sample received onto a coated polymer coverslip or onto a coated Kapton® polyimide tape, advanced from a feeder reel to a take-up reel connected to an ultramicrotome, and the controller includes a computer processor connected to computerized

memory storing computer-implemented software implementing the steps. The steps include positioning the tape or the coverslip at an edge of a blade connected to a knife boat, which is connected to a knife-stage connected to the ultramicrotome, to collect thin, semi-thin, semi-thick, and/or thick resin sections after the sample is floated in water in the knife boat; receiving the sample onto the tape or the coverslip; and for the sample on the tape, advancing the tape to the take up reel.

[0046] In another embodiment, the electronic controller manages the feeder reel and the take up reel that are connected to an exposed reel-to-reel frame, and the computer implemented software further comprises computer implemented commands to position the exposed reel-to-reel frame in a Cartesian X, Y, Z coordinate system to receive cut resin sections on a coated Kapton® polyimide tape.

[0047] In another embodiment, the electronic controller is further configured for data communication with a control computer comprising a graphical user interface adapted to receive specifications for positioning the reel to reel frame.

[0048] In another embodiment, the electronic controller is connected to each of a feeder reel motor and a take up reel motor, wherein the computer implemented software comprises computer implemented commands to set at least one speed of the respective motors.

[0049] In another embodiment, the speed of the respective motors is coordinated by the electronic controller in conjunction with arcuate motion of a specimen block chuck holding a specimen block against a diamond knife-edge connected to the knife boat as controlled by the ultramicrotome, wherein the arcuate motion removes a resin section from the specimen block.

[0050] In another embodiment, the tracking software is stored in the memory, and the tracking software stores position data for the resin section placement on the tape.

[0051] In another embodiment, at least one data port receives a plurality of cantilever arm position signals received from a plurality of sample position sensors, and the cantilever arm position signals correspond to time and position data for each resin section placement on the tape.

[0052] In another embodiment, a position data registry stores the position data, time data, specimen dimensions, and tape dimensions in the memory to track placement of the resin section on the tape.

[0053] This disclosure further includes a method of transferring thin, semi-thin, semi-thick, and thick resin sections from the edge of a blade connected to a knife boat, connected to a knife-stage connected to an ultramicrotome, to a coated Kapton® polyimide tape, the method includes positioning a specimen block onto a nib of a specimen block chuck of the ultramicrotome; connecting a length of a coated Kapton® polyimide tape between a feeder reel and a take-up reel connected to a reel to reel frame; advancing the length of the coated Kapton® polyimide tape from the feeder reel to the take-up reel; positioning the coated Kapton® polyimide tape between the edge of a 35°- 45° angle, 2-8 mm diamond blade and water in the knife boat; receiving cut resin sections from the water onto the coated Kapton® polyimide tape; and advancing the coated Kapton® polyimide tape.

[0054] The method embodiments further include embodiments that advance the coated Kapton® polyimide tape with respective stepper motors that drive rotation of the feeder reel and the take-up reel.

[0055] The method may further include embodiments that advance the coated Kapton® polyimide tape in iterative steps.

[0056] The method may further include embodiments that advance the coated Kapton® polyimide tape by continuously rotating the feeder reel and the take-up reel.

[0057] The method may further include programming an electronic control unit to advance the coated Kapton® polyimide tape.

[0058] The method may further include positioning the coated Kapton® polyimide tape at the edge of a 35°- 45° angle, 6-8 mm diamond blade connected to a knife boat, connected to a knife-stage connected to the ultramicrotome, to collect thin, semi-thin, semi-thick, and thick resin sections after the respectively cut resin section is floated in the water in the knife boat.

[0059] The method may further include exposing the cut resin section to a spreading agent that unfolds the respectively cut resin section prior to collection of the section onto the coated Kapton® polyimide tape.

[0060] The method may further include exposing the respectively cut resin section to a chloroform vapor as the spreading agent.

[0061] The method may further include positioning an exhaust conduit proximate the ultramicrotome to control a concentration of chloroform vapor around the knife stage.

[0062] In yet another method of transferring samples from an ultramicrotome to a coated Kapton® polyimide tape and/or a coated polymer coverslip, the method steps may include positioning a cell and/or tissue resin embedded specimen block onto a nib of the ultramicrotome; connecting a coated Kapton® polyimide tape and/or a coated polymer coverslip to a knife-stage connected to the ultramicrotome; positioning a coated Kapton® polyimide tape and/or a coated polymer coverslip at the edge of a 35°-45° angle, 2-8 mm width diamond blade connected to a knife boat, connected to a knife-stage connected to the ultramicrotome, to collect thin, semi-thin, semi-thick, and thick resin sections after the cut resin section is floated in water in the boat; receiving the sample on a coated Kapton® polyimide tape and/or a coated polymer coverslip.

[0063] The method of transferring samples further includes bolting a knife stage adapter to the knife-stage; connecting the knife stage adapter to an electronic control unit configured to update respective adjustable positions of the knife stage adapter.

[0064] The method of transferring samples may further include embodiments, wherein the respective adjustable positions lie in a Cartesian X, Y, and Z plane defined by the knife stage adapter, and the electronic controller is configured to move the knife stage adapter in at least one direction in the Cartesian X, Y, Z plane.

[0065] The method of transferring samples may further include connecting a reel-to-reel frame with a feeder reel and a take up reel to the knife stage adapter.

[0066] The method of transferring samples may further include connecting a coverslip vise for array tomography to the knife stage adapter.

[0067] The method of transferring samples may include placing the electronic controller in data communication with a control computer having a graphical user interface and programming the electronic controller with the control computer.

[0068] The method of transferring a cut resin section of a specimen block attached to an ultramicrotome onto a coated Kapton® polyimide tape, the steps may include attaching a feeder reel wrapped with a tape to a reel-to-reel frame aligned with a specimen block on the ultramicrotome; placing at least part of the tape onto a tape guide across the reel-to-reel frame, attaching an end of the tape to a take-up reel; rotating the feeder reel and the take-up reel; advancing the tape from the feeder reel to the take-up reel along the tape guide and wrapping the tape around the take-up reel; and receiving the cut resin section onto the tape for storage on the take-up reel.

[0069] The method of transferring samples includes receiving a thin, semi-thin, semi-thick or thick resin sections onto a coated Kapton® polyimide tape.

[0070] The method of transferring samples includes using respective motors to rotate the feeder reel and the take-up reel.

[0071] The method of transferring samples include removing the reel-to-reel frame from the ultramicrotome without changing a position of the feeder reel, the take up reel, or the tape.

[0072] The method may further include storing the reel to reel frame on a stand.

BRIEF DESCRIPTION OF THE DRAWINGS

[0073] These and other features, aspects, and advantages of the present invention will become apparent from the following description and the accompanying exemplary implementations shown in the drawings, which are briefly described below.

[0074] FIG. 1 is a PRIOR ART side view of an ultramicrotome sample preparation device positioned proximately to a knife stage according to the background of this disclosure.

[0075] FIG. 2 is a side perspective view of an ultramicrotome positioned proximately a knife stage to receive cut samples onto a reel to reel tape according to embodiments of this disclosure.

[0076] FIG. 3A is a side perspective view of a knife stage adapter as set forth according to embodiments of this disclosure.

[0077] FIG. 3B is a side view of a reel to reel assembly for collecting cut resin samples from an ultramicrotome positioned proximately to a knife stage according to this disclosure.

[0078] FIG. 3C is a side view of a reel to reel assembly for collected cut resin samples from an ultramicrotome positioned proximately to a knife stage according to this disclosure.

[0079] FIG. 4 is a disassembled view of a modular reel to reel assembly for collecting cut resin samples from an ultramicrotome positioned proximately to a knife stage according to this disclosure.

[0080] FIG. 5 is a side view of a modular reel to reel assembly connected to a knife stage adapter and configured for attaching to a knife stage proximate an ultramicrotome for collecting cut resin samples from the ultramicrotome positioned proximately to the knife stage according to this disclosure.

[0081] FIG. 6 is a rear perspective view of a modular reel to reel assembly for collecting cut resin samples from an ultramicrotome positioned proximately to a knife stage according to this disclosure.

[0082] FIG. 7 is a rear perspective view of a modular reel to reel assembly for collecting cut resin samples from an ultramicrotome positioned proximately to a knife stage according to this disclosure.

[0083] FIG. 8 is a side perspective view of a modular reel to reel assembly for collecting cut resin samples from an ultramicrotome positioned proximately to a knife stage according to this disclosure.

[0084] FIG. 9 is a top perspective view of a modular reel to reel assembly for collecting cut resin samples from an ultramicrotome positioned proximately to a knife stage according to this disclosure.

[0085] FIG. 10 is a rear perspective view of a modular reel to reel assembly for collecting cut resin samples from an ultramicrotome positioned proximately to a knife stage according to this disclosure.

[0086] FIG. 11 is a top side perspective view of a modular reel to reel assembly for collecting cut resin samples from an ultramicrotome positioned proximately to a knife stage according to this disclosure.

[0087] FIG. 12A is a side plan view of a modular reel to reel assembly for collecting cut resin samples from an ultramicrotome positioned proximately to a knife stage according to this disclosure.

[0088] FIG. 12B is a side plan view of a knife stage and associated flanges and connectors for use with an ultramicrotome according to this disclosure.

[0089] FIG. 12C is a side plan view of a knife stage and associated flanges and connectors supporting a knife stage adapter connecting a reel to reel assembly in functional proximity to an ultramicrotome according to this disclosure.

[0090] FIG. 12D is a rear plan view of a knife stage configured for use with a knife stage adapter according to embodiments of this disclosure.

[0091] FIG. 13 is a top perspective view of a reel to reel frame positioning a tape used to collect cut samples from an ultramicrotome according to the embodiments of this disclosure.

[0092] FIG. 14 is a side perspective view of a reel to reel frame positioning a tape used to collect cut samples from an ultramicrotome according to the embodiments of this disclosure.

[0093] FIG. 15 is a side perspective view of a reel to reel frame positioning a tape used to collect cut samples from an ultramicrotome according to the embodiments of this disclosure.

[0094] FIG. 16 is a close-in side perspective view of a nose or snorkel of a reel to reel frame positioning a tape in proximity to an ultramicrotome to receive cut samples on the tape according to the disclosure herein.

[0095] FIG. 17 is a close-in top perspective view of a nose or snorkel of a reel to reel frame positioning a tape in proximity to an ultramicrotome to receive cut samples on the tape according to the disclosure herein.

[0096] FIG. 18 is a close-in top perspective view of a nose or snorkel of a reel to reel frame positioning a tape in proximity to an ultramicrotome to receive cut samples on the tape via a knife boat according to the disclosure herein.

[0097] FIG. 19 is a rear top perspective view of reel motors connected to a reel to reel frame according to embodiments of this disclosure.

[0098] FIG. 20A is a side top perspective view of reel motors connected to a reel to reel frame connected to a knife stage adapter connected to a knife stage of an ultramicrotome according to embodiments of this disclosure.

[0099] FIG. 20B is a side plan view of reel motors connected to a reel to reel frame connected to a knife stage adapter connected to a knife stage of an ultramicrotome according to embodiments of this disclosure.

[0100] FIG. 21 is a rear perspective view of a feeder reel and a take up reel assembly on a reel to reel frame connected to a knife stage according to embodiments of this disclosure.

[0101] FIG. 22 is a top perspective view of a knife stage and associated cartesian positioning control features for positioning a knife boat relative to an ultramicrotome according to embodiments of this disclosure.

[0102] FIG. 23 is a rear perspective view of a reel to reel frame connected to a knife stage adapter with associated cartesian positioning control features for positioning a knife boat relative to an ultramicrotome according to embodiments of this disclosure.

[0103] FIG. 24 is a top perspective view of a knife stage and associated cartesian positioning control features configured for modular removal relative to an ultramicrotome according to embodiments of this disclosure.

[0104] FIG. 25 is a top perspective view of a knife stage and associated cartesian positioning control features configured for modular removal relative to an ultramicrotome according to embodiments of this disclosure.

[0105] FIG. 26 is a top perspective view of a reel to reel frame supporting a tape guide proximate a knife boat of a knife stage according to aspects of this disclosure.

[0106] FIG. 27A is a top perspective view of a trigger holder for a specimen that is adapted to connect to a knife stage adapter that connects to a knife stage of an ultramicrotome according to this disclosure.

[0107] FIG. 27B is a top perspective view of a trigger holder for a specimen that is adapted to connect to a knife stage adapter that connects to a knife stage of an ultramicrotome according to this disclosure.

[0108] FIG. 28 is a side perspective view of a modular reel to reel frame that has been disconnected from a knife stage adapter and configured for storage on a stand according to embodiments herein.

[0109] FIG. 29 is a side perspective view of a knife stage adapter configured for receiving specimen holders according to the embodiments herein.

[0110] FIG. 30 is a top perspective view of a central specimen holder in the form of a vise that clips a substrate that receives a cut specimen from a knife edge proximate an ultramicrotome according to this disclosure.

[0111] FIG. 31 is a top perspective view of a central specimen holder in the form of a vise that clips a substrate that receives a cut specimen from a knife edge proximate an ultramicrotome according to this disclosure.

[0112] FIG. 32A is a top perspective view of a central specimen holder in the form of a vise that clips a substrate that receives a cut specimen from a knife edge proximate an ultramicrotome according to this disclosure.

[0113] FIG. 32B is a side perspective view of a central specimen holder in the form of a vise that clips a substrate that receives a cut specimen from a knife edge proximate an ultramicrotome according to this disclosure.

[0114] FIG. 33 is a schematic view of an example computer environment in which all electronic controls of this disclosure may use with appropriate modification according to the embodiments herein.

DETAILED DESCRIPTION

[0115] This disclosure describes an economical, compact device and system developed under the acronym "STAR", which stands for "Scanning Transmission, Arraytome, Reel-to-Reel Microscopy." Generally, this is a microscopy system that accommodates sample preparation with a commercial microtome and numerous specialized attachment accessories and tools that adapt the microtome for more efficient sample delivery. In one embodiment, STAR is a versatile, all-in-one ultramicrotome knife stage component accessory tool that is adaptable to any commercial ultramicrotome such as, e.g., but not limited to, Sorvall (MT 2; MT 2B; MT 5000; MT 6000); Leica (UC6; UC7); RMC Boeckeler (PowerTome) ultramicrotomes. The tools described herein accommodate the collection of hundreds to thousands of ultra-thin (thickness of 50 nm or less) and/or semi-thin (thickness above 50 nm), semi-thick (thickness between 51nm and 100 nm) and thick (thickness between 101 nm and 200 nm) sample sections that can be automatically and continuously collected from a diamond knife edge onto a graphene-based, or other specialized material, surface. In some non-limiting embodiments, the sample collection surfaces may include coated 0.5-mil Polyimide [Kapton] Film No Adhesive 6.4mm [¼"] wide x 33m [36yd] long (PIT0.5N/6.4) tape for reel-to-reel microscopy, graphene coated coverslips, and graphene coated grids that collect samples cut from the microtome machinery. The references to graphene surfaces described herein are for example only and not limiting of the tools or uses of the tools described herein.

[0116] A plurality of accessory components provide sample sectioning and collection operations that accommodate reel to reel sectioning, serial sectioning, and array tomography sectioning. These components incorporate mechanical and electro-mechanical engineering to provide accessory tools for attachment to and use with an ultramicrotome 150, as shown in several of the figures of this disclosure.

[0117] By way of overview, this disclosure includes reference to one non-limiting commercial embodiment of an ultramicrotome illustrated in PRIOR ART FIG. 1. As shown therein, an ultramicrotome is a sophisticated sampling and sectioning machine that holds a sample (not shown in the figures, but may include samples of biological tissue, tissue in paraffin blocks, cells and/or tissue in resin blocks, as well as samples of inanimate objects made of numerous materials to be analyzed). In a commonly available microtome 150, the tissue samples or sample blocks are held in a microtome sample attachment feature, such as the one illustrated in Figure 8, Ref. 814, and that sample attachment feature, or nib 814, is an interchangeable part of an adjustable and continuously operated ultramicrotome arm 29. The ultramicrotome arm 152 may be configured to move up and down, pivoting along an arc shaped groove or range of motion 27, to continuously shave microscopically thin sample layers (or larger slices if desired) for placement onto a slide or substrate for analysis under various microscopy tools. An ultramicrotome 150, therefore, has associated computerized components that control power, mechanical movement, and general operation of the microtome system. Ultramicrotomes, therefore, accommodate the collection of hundreds to thousands of ultra-thin (thickness of 50 nm or less) and/or semi-thin (thickness above 50 nm) sample sections or sample layers that can be automatically and continuously collected from a diamond knife edge onto a graphene-based, or other specialized material, surface serving as a collection slide. These computer components are accessible for user control via an ultramicrotome controller as described herein.

[0118] Options in the ultramicrotome, such as the example prior art of FIG. 1, allow the user to place appropriate knife assemblies onto a knife stage. For example, and without limiting this disclosure, setting up an ultramicrotome 150 as shown in FIG. 1 includes positioning a knife boat 16 onto a knife carrier 20. The arcuately pivoting sample arm 29 moves in necessary dimensions 21 (up/down/arcuate), 23 (outward), 25 (inward) to continuously force a sample, or specimen block, against a knife blade 14 to shave off layers of ultra-thin and semi-thin sample sections of the overall sample held in the microtome sample attachment feature, or nib 814. The ultramicrotome has computer programmed memory to move the arm in all dimensions to cut sample sections against a knife blade 14. Prior embodiments of microtomes require retrieving the samples from cooling water held in the open chamber of the knife boat 16 and then further require placement of the sample sections on a slide for viewing under a microscope. In some embodiments, the surface of the distilled-deionized-filtered water contained in the knife boat 16

is maintained at the constant level during the sectioning process by a programmable Aladdin Single-Syringe infusion pump 12 (e.g., 60 mL plastic syringe) thus, ensuring proper ultrathin (thickness of 50 nm or less) and/or semi-thin (thickness above 50 nm) sectioning at the edge of the diamond knife. In some embodiments, the knife boat has a triangular shaped bottom forming the reservoir for water or other liquids.

[0119] Development of modern accessories to ultramicrotomes, as shown in one embodiment of this disclosure, includes a knife stage adapter that allows numerous accessories, systems and methods of specimen collection to be used with multiple versions of ultramicrotomes 150. The knife stage adapter 550, therefore, may be seen as one kind of adapter that connects specimen collection systems described herein to an ultramicrotome knife carrier 20 or general knife stage 158. A knife stage adapter 550 is shown in FIGS. 2, 3A, and 29 and includes a base portion 550B adapted to connect to the knife stage 158 on an ultramicrotome 150. A platform region 550C receives at least one adjustment screw 560 attaching the platform region to the base portion 550B at a plurality of selectable heights. An adapter edge 550A is configured to receive a plurality of specimen substrate holders in a modular connection as discussed herein. Accordingly, the knife stage adapter 550 is configured to hold a number of different specimen holders, including but not limited to, at least a reel to reel frame 182, a trigger holder 300 (i.e., a scanning electron microscope stub holder), a coverslip vise 435, and other mechanical devices that can be positioned proximately to an ultramicrotome arm 152, a knife edge (e.g., a diamond knife edge) 439, and a knife boat 800. In some non-limiting embodiments, the diamond knife edge 439 may be connected to the knife boat at a 35 degree to 45 degree angle and may be approximately 2 mm to 8 mm wide. The knife stage adapter places these different specimen holders in positions to receive specimen slices onto a slide, a coverslip, or other specimen substrates (including a coated Kapton® polyimide specimen tape) that receives the specimens as slices or cut resin sections from a specimen attachment feature (e.g., nib 814 of FIG. 16) via the knife edge 439. The knife stage adapter 550 may include a lever arm 552 configured for arcuate movement relative to the base portion 550C and configured to adjust a position of the central specimen substrate holder along the Z-axis as shown in FIG. 2B. Example relationships and functional embodiments of

[0120] In one non-limiting embodiment, the above described knife stage adapter 550 can hold (and release) a reel-to-reel frame 182 for specimen tape-based electron microscopy. The reel-to-

reel frame is shown in detail in FIGS. 3A-21, particularly FIGS. 4, 5, 8, 11 in conjunction with the knife stage adapter 550 attaching the reel-to-reel frame to a knife stage 158 of an ultramicrotome 150. The ultramicrotome may be any commercially available ultramicrotome, and the reel-to-reel frame bolts into the knife stage adaptor, which in turn bolts into the knife stage. In particular, the knife stage adapter bolts into an upper section of the knife stage. The knife stage 158 may be machined for precise dimensions in suitable materials such as aluminum, carbon, copper, chromium, brass, iron, molybdenum, nickel, stainless steel, titanium alloys; typically these materials are susceptible to extremely precise machining. As 3D printing moves forward, other polymers may present equally accurate fabrication opportunities. In one embodiment, the machined knife stage of FIGS. 3B and 3C is modularly attached to a knife carrier 441 defining a receptacle 444 for holding a knife boat 800 in place as described herein. FIG. 3B illustrates the flanges 164, 167 and support pillars 163A, 163B holding the knife stage adaptor 185 to the knife stage 158, as illustrated in FIGS. 12A-12D.

[0121] In one non-limiting embodiment of the reel to reel frame 182 shown in FIGS. 3A-3C, a feeder reel 175 is adapted to receive a length of a specimen tape 190, wherein the feeder reel 175 is rotatably coupled to the reel-to-reel frame 182. A take-up reel 177 is also adapted to receive the specimen tape 190 across the reel-to-reel frame 182, and the reel-to-reel frame 182 is configured to integrate with the knife stage adapter 550 and connect to an ultramicrotome 150 that transfers cut samples onto the specimen support tape 190. The specimen tape is not limited to any one material but can include, without limitation, a graphene coated tape, as described above, and the tape may also be a conductive tape. These tapes hold resin based microscopic sections of cells and tissues thereon and are sufficiently pliable to wind around hubs of the feeder reel 175 and the take up reel 177 at a desirable tension between the reels. In one embodiment, the reel-to-reel frame 182 positions the feeder reel 175 and the take-up reel 177 near the ultramicrotome with the reels being exposed. It is notable that the reel-to-reel frame 182 holds the feeder reel 175 and the take-up reel 177 such that the reels are modular and separable components that connect to the reel to reel frame 182. In this way, the reels can be transferred from specimen collection operations of an ultramicrotome 150 to other machinery such as numerous kinds of microscopes and imaging apparatuses.

[0122] The feeder reel 175 and the take-up reel 177 may be, but are not limited to, machined aluminum wheels having respective hubs 173A, 173B for wrapping the specimen tape 190. The

respective hubs 173A, 173B have a calibrated circumference, produced by precise machining often of aluminum, adapted to maintain a speed and a tension of the specimen tape 190 extending between the feeder reel 175 and the take-up reel 177. The aluminum material for the reels 175, 177, the hubs 173A, 173B, and the wheels on the hubs that secure the tape, is useful for its properties allowing precise control of conductivity and magnetic shielding.

[0123] The feeder reel 175 and the take-up reel 177 include aluminum compositions that are sufficient for withstanding temperatures inside of in-situ scanning electron microscopes that are equipped to use a reel-to-reel imaging system. Such temperatures in the environment of a scanning electron microscope may rise to the range of 1400 degrees Celsius to 1500 degrees Celsius. As noted above and illustrated in FIGS. 18, 24, and 25, , the reel to reel frame 182 is detachable from the knife stage adapter 550 without removing the feeder reel 175 or the take-up reel 177 or the specimen tape 190. The reel to reel frame 182 is adapted to re-attach to additional imaging systems, and the additional imaging systems are selected from but not limited to secondary electron imaging systems, backscatter electron imaging systems, and scanning transmission electron microscopy imaging systems. The additional imaging systems are further selected from quantitative measurement imaging systems comprising EDS and EELS systems. FIGS. 4, 26 illustrate that the modular arrangement of both the knife stage adapter 550 and the various central specimen holders (i.e., a reel to reel frame, a trigger holder, and vise) can be connected and removed numerous combinations to form a plurality of assemblies. In FIGS. 4, 26, one non-limiting assembly shows the reel to reel frame connected to the knife stage adapter and that assembly is removably attached to the knife stage as discussed herein. As shown in FIG. 28, components of this disclosure may be stored on stand 193 for future use.

[0124] This disclosure presents several different kinds of central specimen holders 182, 300, 435 that can be positioned relative to an ultramicrotome knife stage 158 and specimen cantilever arm 152 to receive sliced specimens on a number of different slides, or substrates. The modular, separable components of the knife stage adapter 550 and the numerous kinds of central specimen holders 182, 300, 435 allow for complete versatility in specimen collection and specimen analysis with other kinds of equipment. FIG. 22 illustrates additional versatility by including numerous mechanisms 561 for adjusting a position of the knife stage adapter 550, a reel-to-reel frame 182, a trigger holder 300, a clip holder or vise 435 (FIGS. 30, 31, 32A, 32B), and many other kinds of central specimen holders. As shown in FIGS. 20 - 23, adjustment mechanisms

may be utilized with macro position adjustment knobs 560 and micro position adjustment knobs 561 that can assist in moving the apparatuses in the X, Y, and Z Cartesian coordinates of FIG. 2B. These positional adjustments may also be implemented by many different electronic and software driven machines as described herein.

[0125] The versatility of these operations is shown in a system for preparing cut samples with an ultramicrotome 150. In FIGS. 3-21, the system is shown with a modular reel to reel assembly 185 connected to the knife stage adapter 550 and the ultramicrotome 150. In at least one embodiment, the system includes a reel to reel frame 182 and a knife stage adapter 550, wherein the knife stage adapter 185 is adapted to connect the modular reel to reel assembly 185 to the ultramicrotome 150. The modular reel to reel assembly 185 may be described as incorporating the reel to reel frame 182 along with components and combinations of components including, but not limited to, a feeder reel 175 connected to a length of a specimen tape 190, wherein the feeder reel 175 is rotatably coupled to the reel-to-reel frame 182. A take-up reel 177 is connected to the reel to reel frame 182 and receives the specimen support tape 190 across the reel-to-reel frame 182. In one non-limiting embodiment, the reels are removable from the reel to reel frame with or without disassembling the knife stage 158, the knife stage adapter 550, or the specimen tape 190. The reels 175, 177 may be attached to a separate plate that connects by various fasteners to the reel to reel frame 182.

[0126] As shown in FIGS. 10, 19 and others, the reel to reel frame 182 connects to or supports, a feeder motor 725B that drives rotation of the feeder reel 175 and a take-up motor 725A that drives rotation of the take-up reel 177. It is important to note that in some embodiments, the reel to reel assembly 185 includes only the feeder reel 175 and the take up reel 177 that are separable from the reel-to-reel frame 182. In other embodiments, the system may include a plurality of sample position sensors 1410, 1420 connected to the modular reel to reel assembly 185 and/or the ultramicrotome 150 that sends data to the electronic controller 700 (FIGS. 7, 9) regarding where the ultramicrotome specimen cantilever arm 152 is located in its arcuate path. Other embodiments utilize a single sensor on the platform of the ultramicrotome to detect where the ultramicrotome specimen cantilever arm 152 is located on its path. In this way, the electronic controller described below is updated with the position of the sample on the ultramicrotome specimen cantilever arm 152 and knows when the specimen tape 190 must advance to maintain continuity. The electronics and programming of the electronic controller 700 are discussed in

more detail below. The positions of the sensors 1410, 1420 are not limited to any one installation and can be relocated for the use at hand. With data from the sensors 1410, 1420, at least one electronic control unit 700 is equipped for controlling respective speeds of the feeder motor 725B and the take-up motor 725A, wherein the electronic control unit 700 adjusts the respective speeds according to a sample position signal received from the plurality of sample position sensors 1410, 1420. As shown in the figures, the ultramicrotome specimen cantilever arm connects to an ultramicrotome chuck that has the nib 814 for holding a specimen block to be cut.

[0127] The system of FIGS. 3-21 further illustrates an ultramicrotome specimen cantilever arm 152 holding a specimen block in engagement with a knife edge 439 connected to a knife boat 800, wherein the sample position sensors include at least the first sensor 1410 on the knife boat and a second sensor 1420 on the ultramicrotome specimen cantilever arm 152, but these positions are entirely optional. The specimen tape 190 is positioned to receive samples on the specimen tape 190 from the knife edge 439 attached to the knife boat 800 connected to a knife carrier 20 connected to the ultramicrotome 150. The specimen tape traverses the tape guide 180 across a nose or snorkel 438 as shown in FIG. 20 (i.e., a portion of the tape guide that is submerged into water in the knife boat 800 filled from pump line 1050 (FIG. 10) to pump 1060 (FIG. 10). In one embodiment, the tape guide 180 may include a joint 181 that allows for different heights of the snorkel or nose end 438. The tape guide, therefore, may have multiple degrees of freedom in the x, y, and z directions for the best placement of the tape in receiving a specimen slice. As shown in FIGS. 13-15 and FIG. 17, the nose end 438 of the tape guide is moveable by the various position controllers of the knife stage, the knife stage adapter, and the reel to reel frame. The nose end 438 is positioned relative to a knife edge 439 to receive a cut specimen onto a tape 190.

[0128] As noted above in regard to FIGS. 7 and 9, operation of the system may be coordinated by an electronic controller 700 that may further include a graphical user interface 154 connected to the electronic control unit 700 and configured to receive data entry for programming the electronic control unit. The data entry may include programming optional parameters to maintain variables such as speed selections for the feeder motor 725B and the take-up motor 725A, which in one embodiment may be a stepper motor. The electronic controller 700 may be characterized as having general purpose inputs and outputs that are connected to appropriate

processors, computerized memory, and hardware that is appropriate for customized machine logical operations. In one non-limiting example, the electronic controller receives data from a system of sensors, including a first cantilever arm position sensor and a second cantilever arm position sensor, either of which may be located on the cantilever arm and/or the body of the ultramicrotome. This data, along with speed data for the motors can be used for numerous control systems programmed into the electronic controller. For example, in one embodiment, by using the speed of the motors and the rotation speed of the reels, along with dimensions of the tape and linear speed of the tape, the electronic controller is adapted to track position coordinates of each cut resin section that is located on the tape. In this way, the electronic controller includes a computer registry or database that allows for tracking where a specimen is located along the tape and which sections of the tape are empty. This is useful information when the tape with specimens thereon are "played back" for microscopy purposes.

[0129] This disclosure accounts for multiple, non-limiting versions of the firmware for the control environment, illustrated in FIGS. 7 and 33 at least. Each version consists of several modules for different tasks. In one embodiment, software for the electronic controller 700 includes a tape control module. Its task is to maintain a constant speed of the tape 190 by taking the two spool diameters (i.e., the diameters of hubs 173A, 173B) and spool revolutions per unit time into consideration and using this information to control the two respective step motor speeds, connected to the spools. Another feature of the module is the access of the hardware settings of the motor controller on the board. The communication module uses a transmission protocol to communicate with a user interface software via the USB interface of the hardware.

[0130] One non-limiting version of the firmware is considered for the knife stage 550 with an additional slicer arm monitor module. This module monitors the periodical movement of a slicer arm with the help of a sensor. The information of the slicer arm speed controls the tape speed, which is important to maintain a constant distance between the sliced samples.

[0131] The second version of the firmware may be used for the tape coating hardware of companion disclosures. Besides the tape control module, another module for controlling a third step motor, is included. This motor module handles the coating of the tape by turning at a constant speed. The tape heater module is measuring the temperature of a heater block by an RDT sensor. An implemented PID control maintains a set temperature of the heating block, whose output controls an electric heating element attached to the heating block.

[0132] Using various embodiments of this disclosure to operate a scanning electron microscopy procedure is the third version of the firmware. In addition, for the tape control module, an analog joystick is attached to the controller. The joystick can control the tape speed, tape direction as well as sample position during manual mode. This is important to center the sample for the microscope.

[0133] In non-limiting example embodiments of a controller 700, there are three operations. All three operations have the tape control in common, which can have two different modes. If the source spool motor has no encoder attached, the user has to set the initial revolutions of the sink - spool and source – spool manually on the interface. With an encoder, only the revolution of the sink – spool has to be set. The controller will calculate the revolution of the source – spool automatically. For the knife stage operations, the knife – stage operation can be run with two different modes, depending if the slicer monitor is activated. If the knife –stage runs without the slicer monitor, the user can set the tape speed and the tape direction. With the activated slicer monitor, instead of tape speed and direction the user can set sample distance. In this mode, the tape direction always goes from source – spool to sink – spool. The tape speed is calculated by the sample distance and the monitored speed of the slicer arm.

[0134] When the tape is played back for use with scanning electron microscopy (SEM) operation, the user first has to center the first sample manually with the joystick. On the interface then the user has to set sample distance. This information has to be taken from the interface of the knife –stage controller. Another important setting is the scan time of the sample, which pauses the tape during sample scan.

[0135] In a coating operation of companion embodiments to this disclosure, there are three settings. The first setting is the speed of the coating motor. This determine in combination with the tape speed, how much material will be coated on the tape. The other two settings are heating temperature and heating exposure time. The heating exposure time will determine the speed of the tape. The tape direction is fixed in this mode and can only go from source – spool to sink – spool.

[0136] The figures, such as but not limited to FIGS. 6, 7, and 8, further illustrate that the system may include specimen unfolding additives to the environment. When the sample is sliced from a sample block attached to a nib 814 on the ultramicrotome arm 152, its initial contact with the knife edge 439 moves the sample slice into water of the knife boat 800, and that process tends to

fold the sample or crimple the surface of the sample. Systems of this disclosure utilize additives to the environment of the knife boat 800 to unfold the sample. In one non-limiting embodiment, the unfolding agent is chloroform 614 as shown in the figures emitted from a mister assembly that directs the chloroform toward the sliced sample to unfold it. As shown in FIG. 6, the system also includes an exhaust arrangement 625 to remove excess gaseous additives such as chloroform from the work area.

[0137] As noted above, the knife stage adapter 550 is also accessible for attaching other central specimen holders to the ultramicrotome 150 for sample collection. In this embodiment, a sample substrate holder for receiving a cut sample from an ultramicrotome 150 includes a clip type holder, also called a vise 435, for specimen collection in preparation for array tomography. In one non-limiting embodiment, a knife stage adapter 550 is configured for removable attachment to a knife stage 158 on an ultramicrotome 150, wherein the knife stage adapter 550 defines X, Y, and Z axes relative to the ultramicrotome. As shown in FIGS. 30-32, a clip, or vise, 435 is attached to the knife stage adapter 550, wherein the clip or vise 435 is configured to hold a graphene substrate in a position to receive the cut sample thereon. A lever arm 552 is configured for arcuate movement about the knife stage adapter 550 to position a nose end 437 of the clip 435 at selectable points along the Z axis and adjacent a sample block on the ultramicrotome 150.

[0138] A sample substrate holder may also encompass a trigger holder as illustrated in FIGS. 27A, 28B for array tomography and possibly for additional use with scanning electron microscopes. The trigger holder body 300 is illustrated extensively in FIGS. 27A and 27B for use with an ultramicrotome. As illustrated in FIGS. 27A, 27B, the substrate holder body 300 defines a passageway with a first opening 340 at one end of the holder body 300 and a second opening 335 extending from the first opening 340 toward a second end of the holder body. A trigger 325 fits within the second opening 335, wherein the trigger 325 is actuated by a spring 330 connected to the trigger 325 and the holder body 300. A removable surface block 310 is configured to fit within the first opening 340 of the holder body 300, and the removable surface block 310 is held in place by the trigger 325 biased by the spring 330. In operation, the knife stage adapter 550 positions the removable surface block 310 proximate the ultramicrotome 150. A sample can be collected onto a graphene sample substrate that is positioned across the surface block 310 and held in place between sides 312A, 312B of the surface block 310 connected to respective sections 339A, 339B of the holder body 330 and the trigger 325.

[0139] Any one of the above noted central sample substrate holders, including the reel-to-reel embodiments, the clip embodiments, or the trigger embodiments can be used to perform methods of sample collection. Along these lines, a method of transferring samples from an ultramicrotome to a specimen tape includes positioning a sample block onto a nib 814 (FIG. 16) of the ultramicrotome 150; connecting a length of the specimen tape 190 between a feeder reel 175 and a take-up reel 177 connected to a reel to reel frame 182; advancing the specimen tape 190 from the feeder reel 175 to the take-up reel 177; positioning the specimen tape 190 between the sample block and a knife stage 158 connected to the ultramicrotome 150, wherein a knife edge 439 mounted on the knife stage 158 receives a portion of the sample block against a knife edge 439 to slice at least one sample of the sample block; and receiving the sample on the specimen support tape 190 and advancing the specimen support tape. The method continues by advancing the specimen support tape 190 with respective stepper motors 1410, 1420 that drive rotation of the feeder reel and the take-up reel. Advancing the specimen support tape 190 may occur in iterative steps or on a continuously driven tape. 26.The method of any one of Claims 23 - 25, further comprising programming an electronic control unit 700 to advance the specimen support tape 190.

[0140] The system and apparatuses of this disclosure are configured to provide a maximum flexibility for a method of transferring samples from an ultramicrotome to a specimen substrate. As noted above, the ultramicrotome may be used with a number of different kinds of central specimen holders, including but not limited to a reel-to-reel system, a trigger holder system, and a clip mechanism. Each of these different embodiments enable a method of positioning a sample block onto a nib 814 of the ultramicrotome 150; connecting a specimen substrate to a central specimen holder 185, 300, 435; positioning the specimen substrate between the sample block and a knife stage adapter 550 connected to the ultramicrotome 150, wherein the knife stage adapter 158 receives a portion of the sample block against a knife edge 439 to slice at least one sample from the sample block; and receiving the sample on the sample substrate.

[0141] As noted above, the ultramicrotome 150 has a knife stage 158 that may operate with a knife stage adapter 550 to receive the central specimen holder in adjustable positions and connecting the central specimen holder to an electronic control unit configured to update respective adjustable positions of the central specimen holder. The respective adjustable positions lie in a Cartesian X, Y, and Z plane defined by the knife stage adapter 550, and the

electronic controller 700 is configured to move the central specimen holder in at least one direction in the Cartesian X, Y, Z plane. The method can continue by (i) connecting a reel to reel frame 182 with a feeder reel 175 and a take up reel 177 as the central specimen holder, (ii) connecting a clipping apparatus 435 for array tomography as the central specimen holder, or (iii) connecting a triggered holder apparatus 300 for array tomography as the central specimen holder. By placing the electronic controller 700 in data communication with a control computer having a graphical user interface 154 and programming the electronic controller 700 with the control computer, the methods herein may be automated.

[0142] Automated methods of this disclosure include a method of transferring a cut sample section of a specimen block attached to an ultramicrotome 150 onto an electron microscopy specimen tape 190 by attaching a feeder reel 175 wrapped with the specimen tape 190 to a reel-to-reel frame 182 aligned with the specimen block on the ultramicrotome 150; placing at least part of the specimen tape 190 on a tape guide 180 across the reel-to-reel frame 182, attaching an end of the specimen support tape 190 to a take-up reel 177; rotating the feeder reel 175 and the take-up reel 177; advancing the specimen tape 190 from the feeder reel 175 to the take-up reel 177 along the tape guide 180 and wrapping the specimen tape 190 around the take-up reel 177; and receiving the cut sample section onto the substrate strip for storage on the take-up reel 177. The automated methods enable receiving a semi thick or thin ultramicrotome cut sample onto the sample tape 190 while simultaneously using respective motors 1410, 1420 to rotate the feeder reel 175 and the take-up reel 177 in a controlled way of advancing the specimen tape 190. Upon completion, the method as disclosed herein optionally includes removing the reel-to-reel frame 182 from the ultramicrotome 150 without disrupting the feeder reel 175, the take up reel 177, or the specimen tape 190.

[0143] The automated methods described above are enabled in part by utilizing an electronic controller 700 for implementing tape-based electron microscopy on a sample received onto a sample support tape 190. The electronic controller 700 may move the specimen tape 190 that is advanced from a feeder reel 175 to a take-up reel 177 connected to an ultramicrotome 150. The electronic controller typically includes a computer processor 200 connected to computerized memory storing computer-implemented software implementing programmable, computerized steps of a method. The method includes positioning the specimen support tape 190 between a sample block and a knife stage connected to the ultramicrotome, wherein the knife stage receives a portion

of the sample block against a knife edge to slice at least one sample of the sample block; receiving the sample on the specimen support tape 190; and advancing the specimen support tape.

[0144] As shown in the figures, the feeder reel 175 and the take up reel 177 are connected to an exposed reel to reel frame 182, and the computer implemented software further comprises computer implemented commands to position the exposed reel to reel frame in a Cartesian X, Y, Z coordinate system to receive the sample on the specimen support tape. The computer implemented software comprises computer implemented commands to set at least one speed of the respective motors. The speed of the respective motors is coordinated by the electronic controller 700 in conjunction with arcuate motion 21 of the sample block against the knife edge 439 as controlled by the ultramicrotome 150.

[0145] The terminology used herein is for the purpose of describing particular implementations only and is not intended to be limiting of the invention. As used herein, the singular forms "a", "an" and "the" are intended to include the plural forms as well, unless the context clearly indicates otherwise. It will be further understood that the terms "comprises" and/or "comprising," when used in this specification, specify the presence of stated features, integers, steps, operations, elements, and/or components, but do not preclude the presence or addition of one or more other features, integers, steps, operations, elements, components, and/or groups thereof.

[0146] The corresponding structures, materials, acts, and equivalents of all means or step plus function elements in the claims below are intended to include any structure, material, or act for performing the function in combination with other claimed elements as specifically claimed. The description of the present invention has been presented for purposes of illustration and description, but is not intended to be exhaustive or limited to the invention in the form disclosed. Many modifications and variations will be apparent to those of ordinary skill in the art without departing from the scope and spirit of the invention. The implementation was chosen and described in order to best explain the principles of the invention and the practical application, and to enable others of ordinary skill in the art to understand the invention for various implementations with various modifications as are suited to the particular use contemplated.

[0147] The figures utilize an exemplary computing environment in which example embodiments and aspects may be implemented. The computing device environment of FIG. 33

is only one example of a suitable computing environment and is not intended to suggest any limitation as to the scope of use or functionality.

[0148] Numerous other general purpose or special purpose computing devices environments or configurations may be used. Examples of well-known computing devices, environments, and/or configurations that may be suitable for use include, but are not limited to, personal computers, server computers, handheld or laptop devices, multiprocessor systems, microprocessor-based systems, network personal computers (PCs), minicomputers, mainframe computers, embedded systems, distributed computing environments that include any of the above systems or devices, and the like.

[0149] Computer-executable instructions, such as program modules, being executed by a computer may be used. Generally, program modules include routines, programs, objects, components, data structures, etc. that perform particular tasks or implement particular abstract data types. Distributed computing environments may be used where tasks are performed by remote processing devices that are linked through a communications network or other data transmission medium. In a distributed computing environment, program modules and other data may be located in both local and remote computer storage media including memory storage devices.

[0150] In its most basic configuration, a computing device typically includes at least one processing unit and memory. Depending on the exact configuration and type of computing device, memory may be volatile (such as random-access memory (RAM)), non-volatile (such as read-only memory (ROM), flash memory, etc.), or some combination of the two.

[0151] Computing devices may have additional features/functionality. For example, computing device may include additional storage (removable and/or non-removable) including, but not limited to, magnetic or optical disks or tape. Such additional storage is illustrated in FIG. 2 by removable storage and non-removable storage.

[0152] Computing device typically includes a variety of computer readable media. Computer readable media can be any available media that can be accessed by the device and includes both volatile and non-volatile media, removable and non-removable media.

[0153] Computer storage media include volatile and non-volatile, and removable and non-removable media implemented in any method or technology for storage of information such as computer readable instructions, data structures, program modules or other data. Memory,

removable storage, and non-removable storage are all examples of computer storage media. Computer storage media include, but are not limited to, RAM, ROM, electrically erasable program read-only memory (EEPROM), flash memory or other memory technology, CD-ROM, digital versatile disks (DVD) or other optical storage, magnetic cassettes, magnetic tape, magnetic disk storage or other magnetic storage devices, or any other medium which can be used to store the desired information and which can be accessed by computing device. Any such computer storage media may be part of computing device.

[0154] Computing device 200 may contain communication connection(s) that allow the device to communicate with other devices. Computing device may also have input device(s) such as a keyboard, mouse, pen, voice input device, touch input device, etc. Output device(s) such as a display, speakers, printer, etc. may also be included. All these devices are well known in the art and need not be discussed at length here.

[0155] It should be understood that the various techniques described herein may be implemented in connection with hardware components or software components or, where appropriate, with a combination of both. Illustrative types of hardware components that can be used include Field-programmable Gate Arrays (FPGAs), Application-specific Integrated Circuits (ASICs), Application-specific Standard Products (ASSPs), System-on-a-chip systems (SOCs), Complex Programmable Logic Devices (CPLDs), etc. The methods and apparatus of the presently disclosed subject matter, or certain aspects or portions thereof, may take the form of program code (i.e., instructions) embodied in tangible media, such as CD-ROMs, hard drives, or any other machine-readable storage medium where, when the program code is loaded into and executed by a machine, such as a computer, the machine becomes an apparatus for practicing the presently disclosed subject matter.

CLAIMS

1. A system for sectioning resin-embedded cells and/or tissues with an ultramicrotome, the system comprising:

a modular reel-to-reel assembly comprising a reel-to-reel frame that connects to an upper region of a knife-stage used with the ultramicrotome, wherein the upper region of the knife-stage is adapted to connect the modular reel-to-reel assembly to the ultramicrotome, and wherein the modular reel-to-reel assembly further comprises:

a feeder reel connected to a length of tape, wherein the feeder reel is rotatably coupled to the reel-to-reel frame;

a take-up reel connected to the reel-to-reel frame and receiving the tape across the reel-to-reel frame;

a feeder motor that drives rotation of the feeder reel;

a take-up motor that drives rotation of the take-up reel;

at least one cantilever arm position sensor connected to the modular reel-to-reel assembly and/or the ultramicrotome; and

at least one electronic control unit controlling respective speeds of the feeder motor and the take-up motor, wherein the electronic control unit adjusts the respective speeds according to a cantilever arm position signals received from the at least one cantilever arm position sensor.

2. The system of Claim 1, further comprising a knife stage adapter connecting the upper region of the knife stage to the reel-to-reel frame.

3. The system of Claim 1, wherein the feeder reel and the take-up reel comprise aluminum wheels comprising respective hubs for wrapping the tape, the respective hubs having a calibrated circumference adapted to maintain a speed and a tension of the tape extending between the feeder reel and the take-up reel.

4. The system of Claim 3, wherein the feeder reel and the take-up reel are made of aluminum and aluminum alloys comprising specified conductivity and specified magnetically shielding properties.

5. The system of Claim 1, wherein the reel-to-reel frame is detachable from the upper region of the knife-stage without removing the feeder reel or the take-up reel or the tape.

6. The system of Claim 5, wherein the feeder reel and the take-up reel are adapted to be re-attached to an in-situ scanning electron microscope reel-to-reel imaging system.

7. The system of Claim 6, wherein the in-situ scanning electron microscope reel-to-reel imaging system is selected from secondary electron imaging systems, backscatter electron imaging systems, scanning transmission electron microscopy imaging systems.

8. The system of Claim 6, wherein the in-situ scanning electron microscope reel-to-reel imaging system is selected from quantitative measurement imaging systems comprising EDS and EELS systems.

9. The system of Claim 1, further comprising a specimen cantilever arm connected to a specimen block chuck configured to hold a specimen block in engagement with an edge of a blade connected to a knife boat connected to the knife-stage connected to the ultramicrotome, wherein the at least one cantilever arm position sensor comprises at least a first cantilever arm position sensor attached to a base section of the ultramicrotome underneath a second cantilever arm position sensor attached to the specimen cantilever arm.

10. The system of Claim 9 wherein the tape is a Kapton® polyimide tape positioned to receive thin, semi-thin, semi-thick, and thick resin sections from the edge of the blade connected to a knife boat, connected to a knife-stage, which is connected to the ultramicrotome.

11. The system of Claim 10, wherein the tape further comprises a carbon coating.

12. The system of Claim 11, wherein the carbon coating is a graphene coating.

13. The system of Claim 1, further comprising a graphical user interface connected to the electronic control unit and configured to receive data entry for programming the electronic control unit.

14. The system of Claim 13, wherein the data entry comprises speed selections for the feeder motor and the take-up motor.

15. The system of Claim 14, wherein at least one of the motors is an encoded stepper motor.

16. A knife stage adapter comprising:

a base portion adapted to bolt into an upper region of a ultramicrotome knife-stage;

a platform region receiving at least one adjustment screw attaching the platform region to the base portion at a plurality of selectable heights;

an adapter edge configured to receive a plurality of specimen substrate holders in a modular connection.

17. A knife stage adapter according to Claim 16, wherein a respective specimen substrate holder is a reel to reel frame.

18. A knife stage adapter according to Claim 16, wherein a respective specimen substrate holder is a coverslip vise.

19. A knife stage adapter according to Claim 16, wherein a respective specimen substrate holder is a triggered holding apparatus.

20. A knife stage adapter according to Claim 16, further comprising a lever arm configured for arcuate movement relative to the base portion and configured to adjust a position of the specimen substrate holder along the Z-axis.

21. A reel-to-reel frame for tape-based electron microscopy comprising:

a feeder reel adapted to receive a length of tape, wherein the feeder reel is rotatably coupled to the reel-to-reel frame;

a take-up reel adapted to receive the tape across the reel-to-reel frame; and

wherein the reel-to-reel frame is configured to integrate with a knife-stage and connect to an ultramicrotome that transfers cut resin sections onto the tape.

22. The reel to reel frame of Claim 21, further comprising receptacles for bolting the reel-to-reel frame to a knife stage adapter, which connects to a knife stage on the ultramicrotome.

23. The reel-to-reel frame according to Claim 21, wherein the feeder reel and the take-up reel are exposed.

24. The reel-to-reel frame according to Claim 21, wherein the feeder reel and the take-up reel are modular and separable components that connect to the reel-to-reel frame.

25. The reel-to-reel frame according to Claim 21, wherein the reel-to-reel frame is configured to integrate with an ultramicrotome knife-stage.

26. A coverslip vise system for receiving a cut sample from an ultramicrotome, comprising:

a knife stage adapter configured for removable attachment to a knife carrier on an ultramicrotome, wherein the knife stage adapter defines X, Y, and Z axes relative to the ultramicrotome;

a vise attached to the knife stage adapter, wherein the vise is configured to hold a polymer coverslip in a position to receive the cut resin sections thereon; and

a lever arm connected to the knife stage adapter and configured for arcuate movement about the knife stage adapter to position an end of the vise at selectable points along the Z axis and adjacent a specimen block on the ultramicrotome.

27. The coverslip vise system of Claim 26, further comprising a cut resin section on the polymer coverslip.

28. The coverslip vise system of Claim 27, wherein the cut resin section is one of a thin resin section, a semi-thin resin section, a semi-thick resin section, and a thick resin section.

29. The coverslip vise system of Claim 26, wherein the vise is so dimensioned to hold a glass coverslip having a thickness in the range of 175 microns to 190 microns, the glass coverslip being compatible with optical microscopes.

30. A scanning electron microscope stub holder for use with an ultramicrotome to receive resin sections thereon, comprising:

a substrate holder body defining a passageway with a first opening at one end of the holder body and a second opening extending from the first opening toward a second end of the holder body;

a trigger that fits within the second opening, said trigger being actuated by a spring connected to the trigger and the holder body;

a removable surface block configured to fit within the first opening of the holder body, said removable surface block held in place by the trigger biased by the spring;

31. The stub holder according to Claim 30, further comprising a fastening mechanism that connects to a knife stage adapter that connects to a knife stage, wherein the fastening mechanism positions the removable surface block proximate the ultramicrotome.

32. The stub holder according to claim 30, further comprising a substrate positioned across the surface block and held in place between sides of the surface block connected to respective resin sections of the holder body and the trigger.

33. The stub holder according to claim 32, wherein substrate comprises a coated Kapton® polyimide.

34. The stub holder according to claim 30, further comprising a carbon coated polyimide substrate.

35. The stub holder according to claim 34, further comprising a graphene coated polyimide substrate.

36. An electronic controller for implementing electron microscopy on a sample received onto a coated polymer coverslip or onto a coated Kapton® polyimide tape advanced from a feeder reel to a take-up reel connected to an ultramicrotome, the controller comprising:

a computer processor connected to computerized memory storing computer-implemented software implementing the following steps:

positioning the tape or the coverslip at an edge of a blade connected to a knife boat, which is connected to a knife-stage connected to the ultramicrotome, to collect thin, semi-thin, semi-thick, and/or thick resin sections after the sample is floated in water in the knife boat;

receiving the sample onto the tape or the coverslip; and

for the sample on the tape, advancing the tape to the take up reel.

37. The electronic controller of Claim 36, wherein the feeder reel and the take up reel are connected to an exposed reel-to-reel frame, and the computer implemented software further comprises computer implemented commands to position the exposed reel-to-reel frame in a Cartesian X, Y, Z coordinate system to receive cut resin sections on a coated Kapton® polyimide tape.

38. The electronic controller of Claim 37, further configured for data communication with a control computer comprising a graphical user interface adapted to receive specifications for positioning the reel to reel frame.

39. The electronic controller of Claim 38, connected to each of a feeder reel motor and a take up reel motor, wherein the computer implemented software comprises computer implemented commands to set at least one speed of the respective motors.

40. The electronic controller of Claim 39, wherein the speed of the respective motors is coordinated by the electronic controller in conjunction with arcuate motion of a specimen block chuck holding a specimen block against a diamond knife-edge connected to the knife boat as controlled by the ultramicrotome, wherein the arcuate motion removes a resin section from the specimen block.

41. The electronic controller of Claim 40, further comprising tracking software stored in the memory, said tracking software storing position data for the resin section placement on the tape.

42. The electronic controller of Claim 41, further comprising at least one data port for receiving a plurality of cantilever arm position signals received from a plurality of sample position sensors, said cantilever arm position signals corresponding to time and position data for each resin section placement on the tape.

43. The electronic controller of Claim 42, further comprising a position data registry storing the position data, time data, specimen dimensions, and tape dimensions in the memory to track placement of the resin section on the tape.

44. A method of transferring thin, semi-thin, semi-thick, and thick resin sections from the edge of a blade connected to a knife boat, connected to a knife-stage connected to an ultramicrotome, to a coated Kapton® polyimide tape, the method comprising:

positioning a specimen block onto a nib of a specimen block chuck of the ultramicrotome;

connecting a length of a coated Kapton® polyimide tape between a feeder reel and a take-up reel connected to a reel to reel frame;

advancing the length of the coated Kapton® polyimide tape from the feeder reel to the take-up reel;

positioning the coated Kapton® polyimide tape between the edge of a 35°- 45° angle, 2-8 mm diamond blade and water in the knife boat;

receiving cut resin sections from the water onto the coated Kapton® polyimide tape; and

advancing the coated Kapton® polyimide tape.

45. The method of Claim 44, further comprising advancing the coated Kapton® polyimide tape with respective stepper motors that drive rotation of the feeder reel and the take-up reel.

46. The method of Claim 44, further comprising advancing the coated Kapton® polyimide tape in iterative steps.

47. The method of Claim 44, further comprising advancing the coated Kapton® polyimide tape by continuously rotating the feeder reel and the take-up reel.

48. The method of Claim 47, further comprising programming an electronic control unit to advance the coated Kapton® polyimide tape.

49. The method of Claim 44, further comprising positioning the coated Kapton® polyimide tape at the edge of a 35°- 45° angle, 6-8 mm diamond blade connected to a knife boat, connected to a knife-stage connected to the ultramicrotome, to collect thin, semi-thin, semi-thick, and thick resin sections after the respectively cut resin section is floated in the water in the knife boat.

50. The method of Claim 49, further comprising exposing the cut resin section to a spreading agent that unfolds the respectively cut resin section prior to collection of the section onto the coated Kapton® polyimide tape.

51. The method of Claim 50, further comprising exposing the respectively cut resin section to a chloroform vapor as the spreading agent.

52. The method of Claim 51, further comprising positioning an exhaust conduit proximate the ultramicrotome to control a concentration of chloroform vapor around the knife stage.

53. A method of transferring samples from an ultramicrotome to a coated Kapton® polyimide tape and/or a coated polymer coverslip, the method comprising:

positioning a cell and/or tissue resin embedded specimen block onto a nib of the ultramicrotome;

connecting a coated Kapton® polyimide tape and/or a coated polymer coverslip to a knife-stage connected to the ultramicrotome;

positioning a coated Kapton® polyimide tape and/or a coated polymer coverslip at the edge of a 35°-45° angle, 2-8 mm width diamond blade connected to a knife boat, connected to a knife-stage connected to the ultramicrotome, to collect thin, semi-thin, semi-thick, and thick resin sections after the cut resin section is floated in water in the boat;

receiving the sample on a coated Kapton® polyimide tape and/or a coated polymer coverslip.

54. The method of Claim 53, further comprising:

bolting a knife stage adapter to the knife-stage;

connecting the knife stage adapter to an electronic control unit configured to update respective adjustable positions of the knife stage adapter.

55. The method of Claim 54, wherein the respective adjustable positions lie in a Cartesian X, Y, and Z plane defined by the knife stage adapter, and the electronic controller is configured to move the knife stage adapter in at least one direction in the Cartesian X, Y, Z plane.

56. The method of Claim 53, further comprising connecting a reel-to-reel frame with a feeder reel and a take up reel to the knife stage adapter.

57. The method of Claim 53, further comprising connecting a coverslip vise for array tomography to the knife stage adapter.

58. The method of Claim 53, further comprising placing the electronic controller in data communication with a control computer having a graphical user interface and programming the electronic controller with the control computer.

59. A method of transferring a cut resin section of a specimen block attached to an ultramicrotome onto a coated Kapton® polyimide tape, the method comprising:

attaching a feeder reel wrapped with a tape to a reel-to-reel frame aligned with a specimen block on the ultramicrotome;

placing at least part of the tape onto a tape guide across the reel-to-reel frame,

attaching an end of the tape to a take-up reel;

rotating the feeder reel and the take-up reel;

advancing the tape from the feeder reel to the take-up reel along the tape guide and wrapping the tape around the take-up reel; and

receiving the cut resin section onto the tape for storage on the take-up reel.

60. The method of Claim 59, further comprising receiving a thin, semi-thin, semi-thick or thick resin sections onto a coated Kapton® polyimide tape.

61. The method of Claim 59, further comprising using respective motors to rotate the feeder reel and the take-up reel.

62. The method of Claim 61, further comprising removing the reel-to-reel frame from the ultramicrotome without changing a position of the feeder reel, the take up reel, or the tape.

63. The method of Claim 62, further comprising storing the reel to reel frame on a stand.

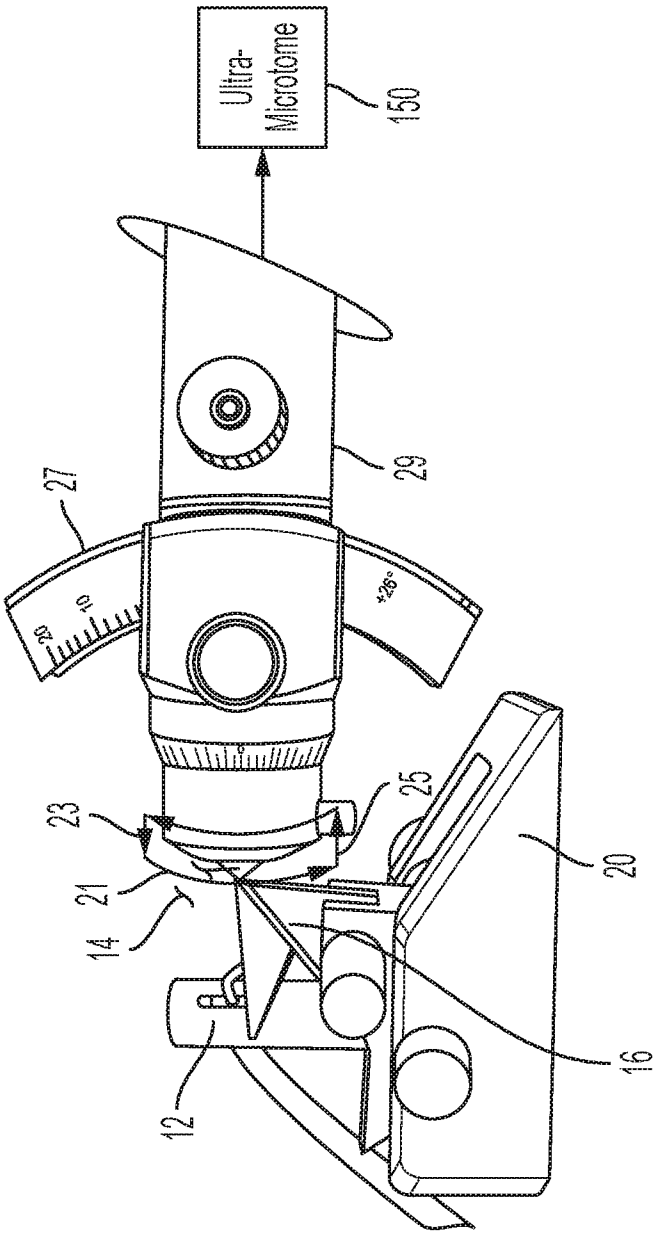


FIG. 1
PRIOR ART

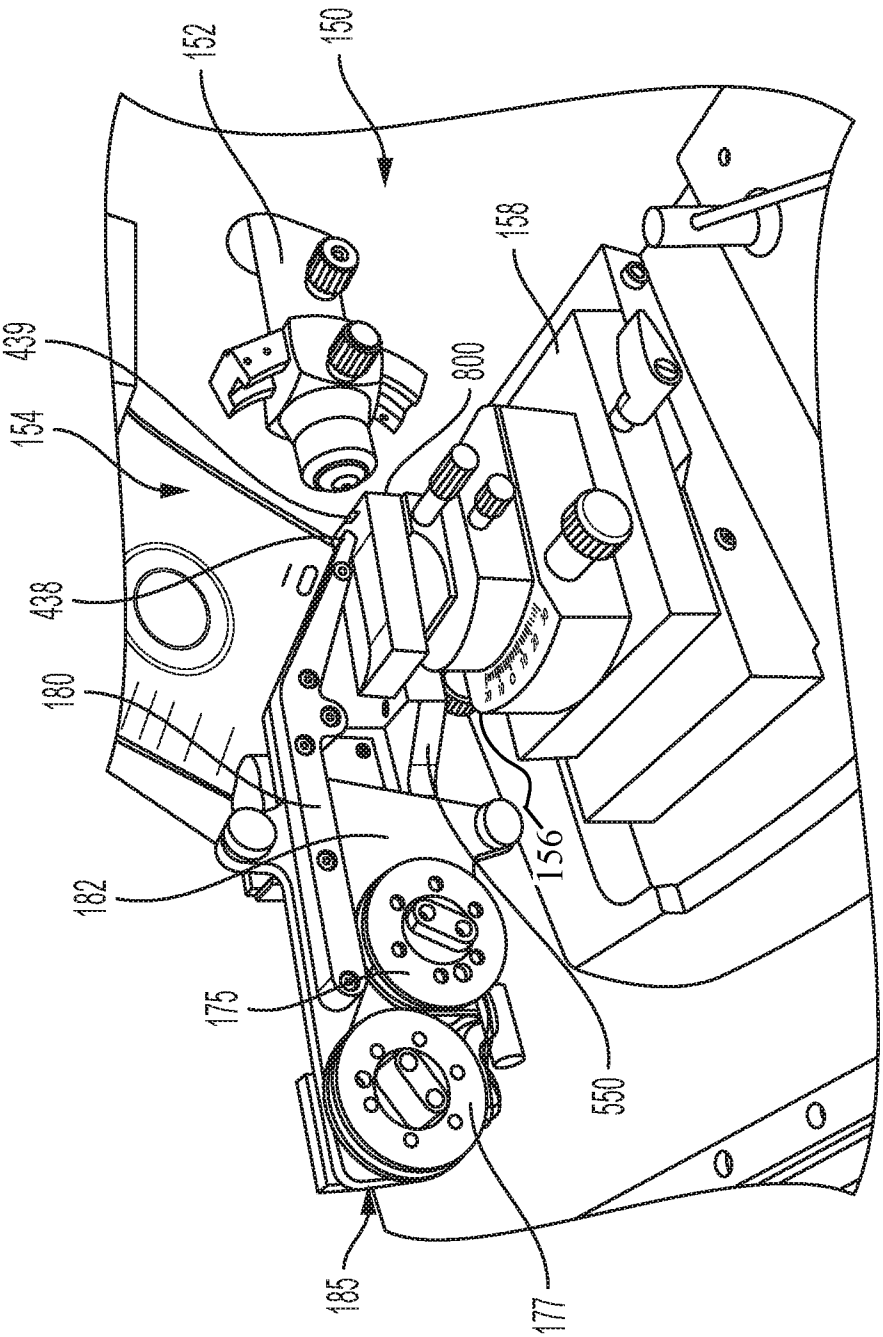


FIG. 2

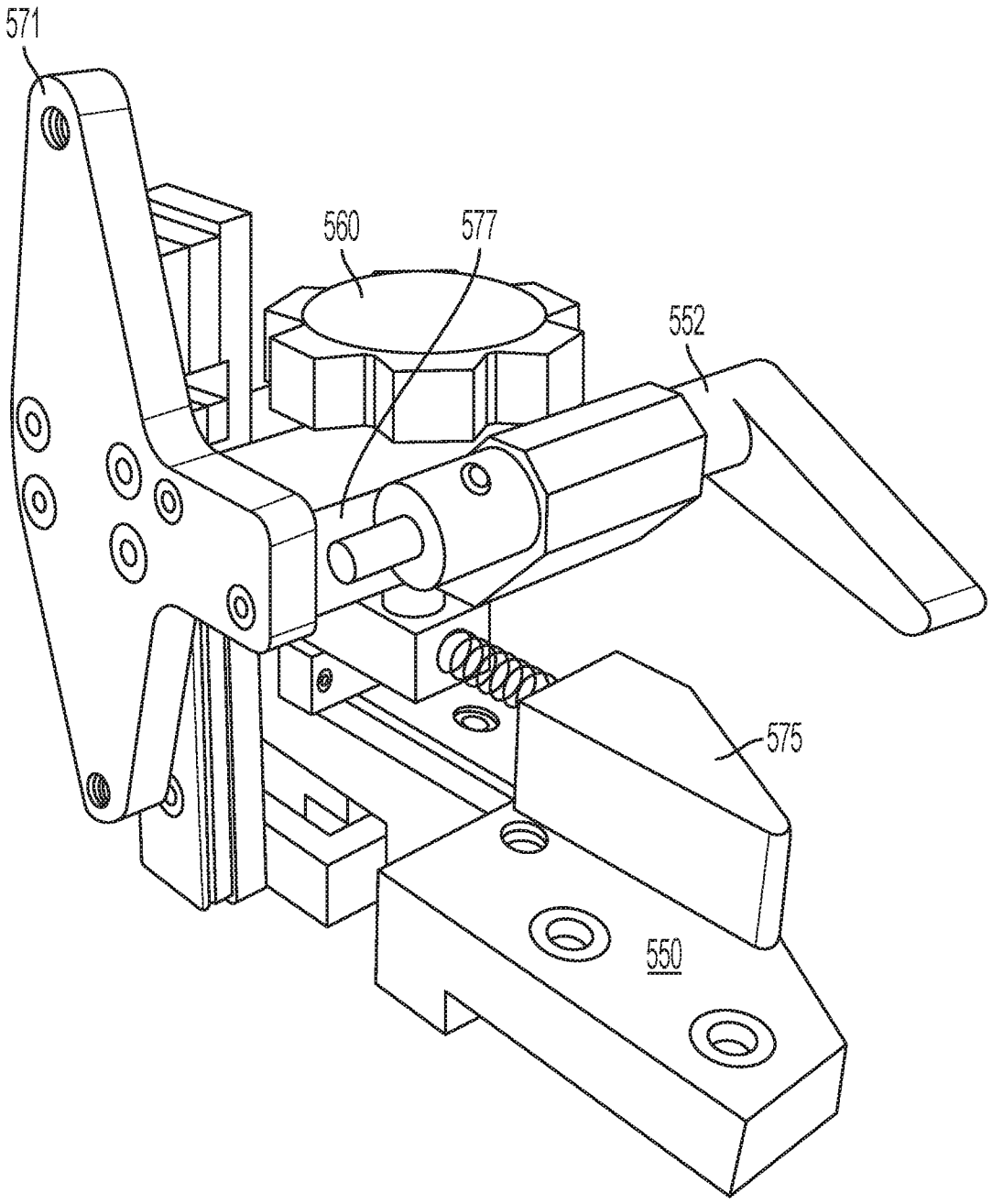


FIG. 3A

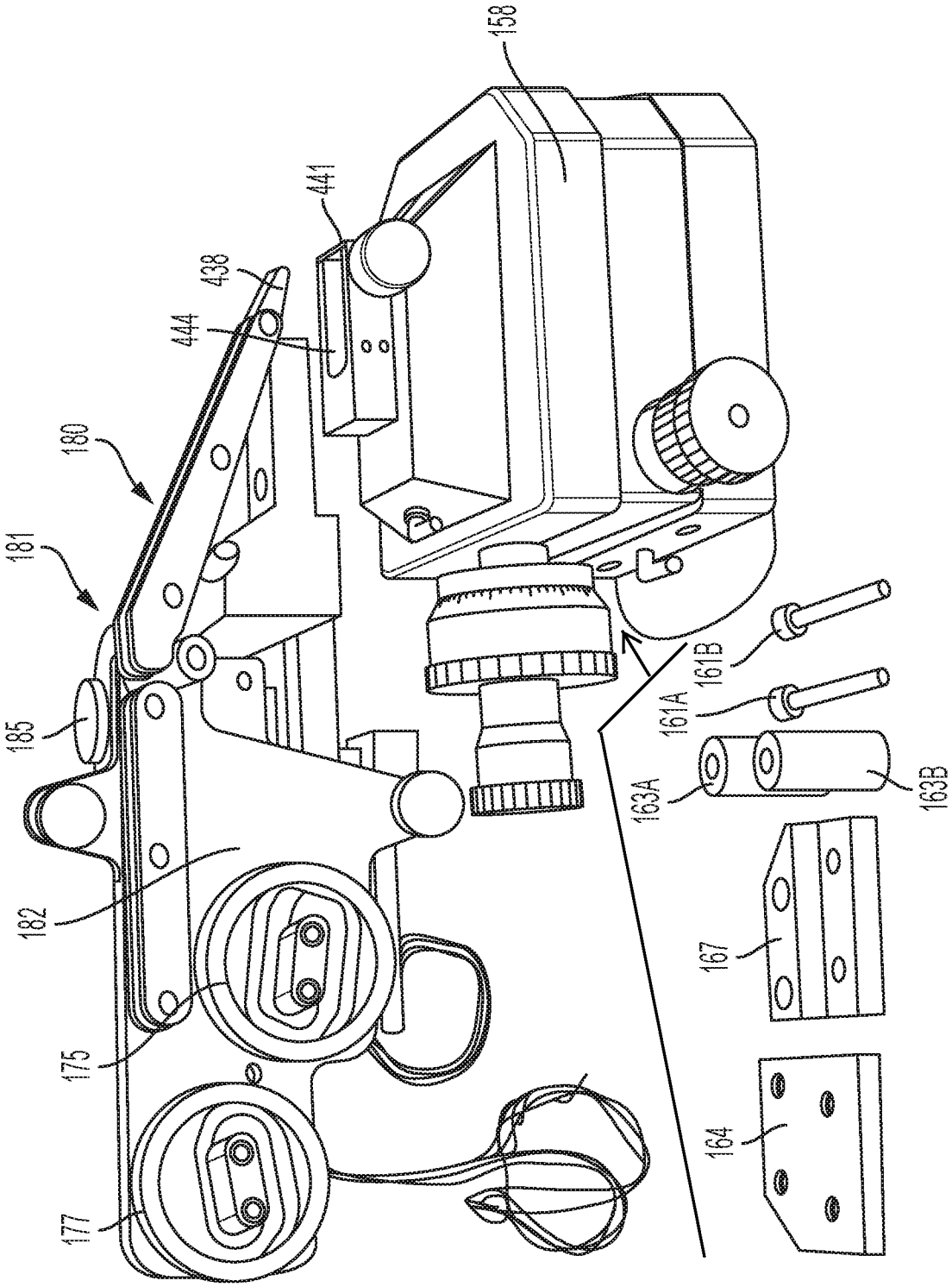

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161B
161A
163A
163B
167
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FIG. 3B

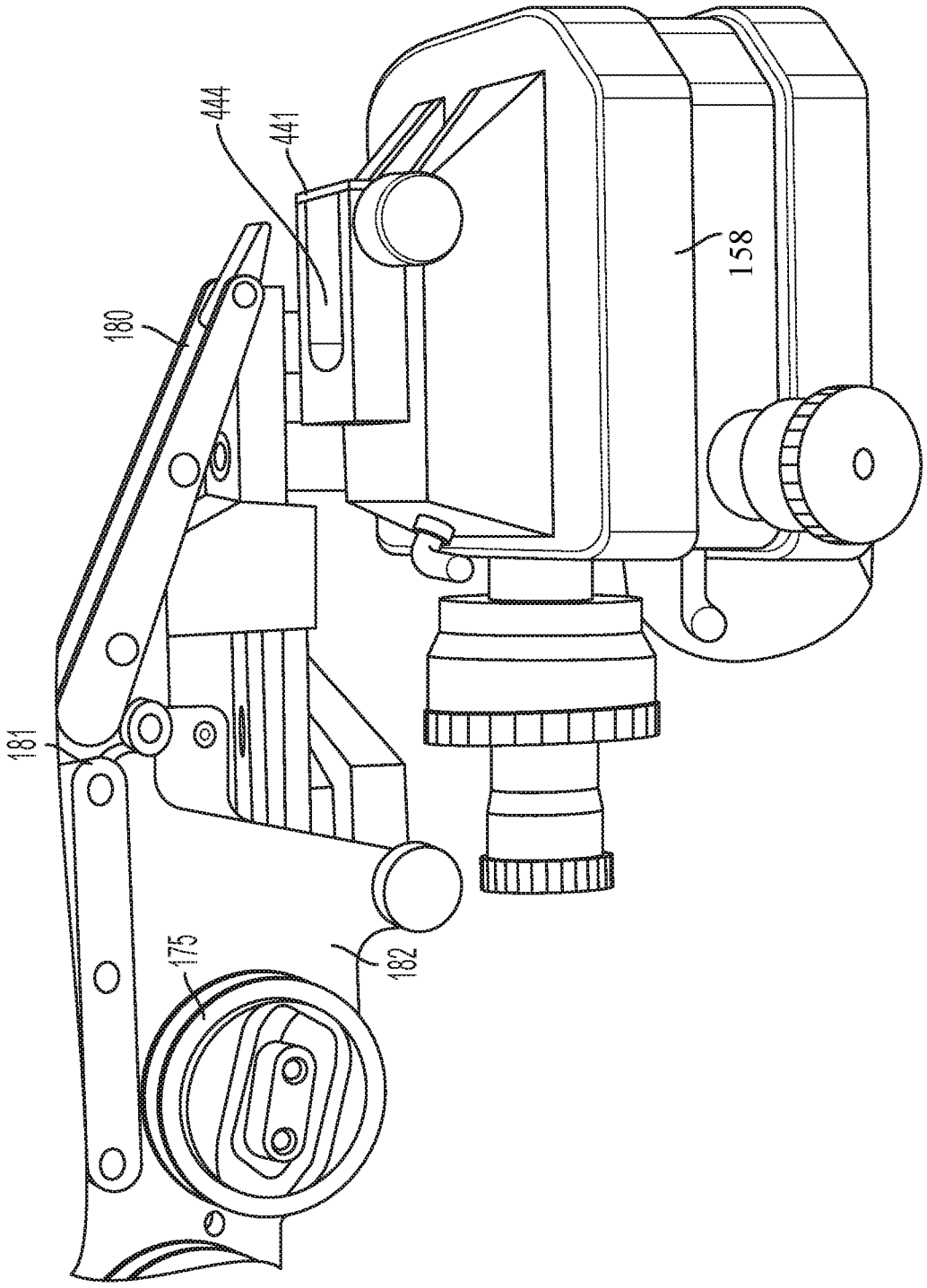


FIG. 3C

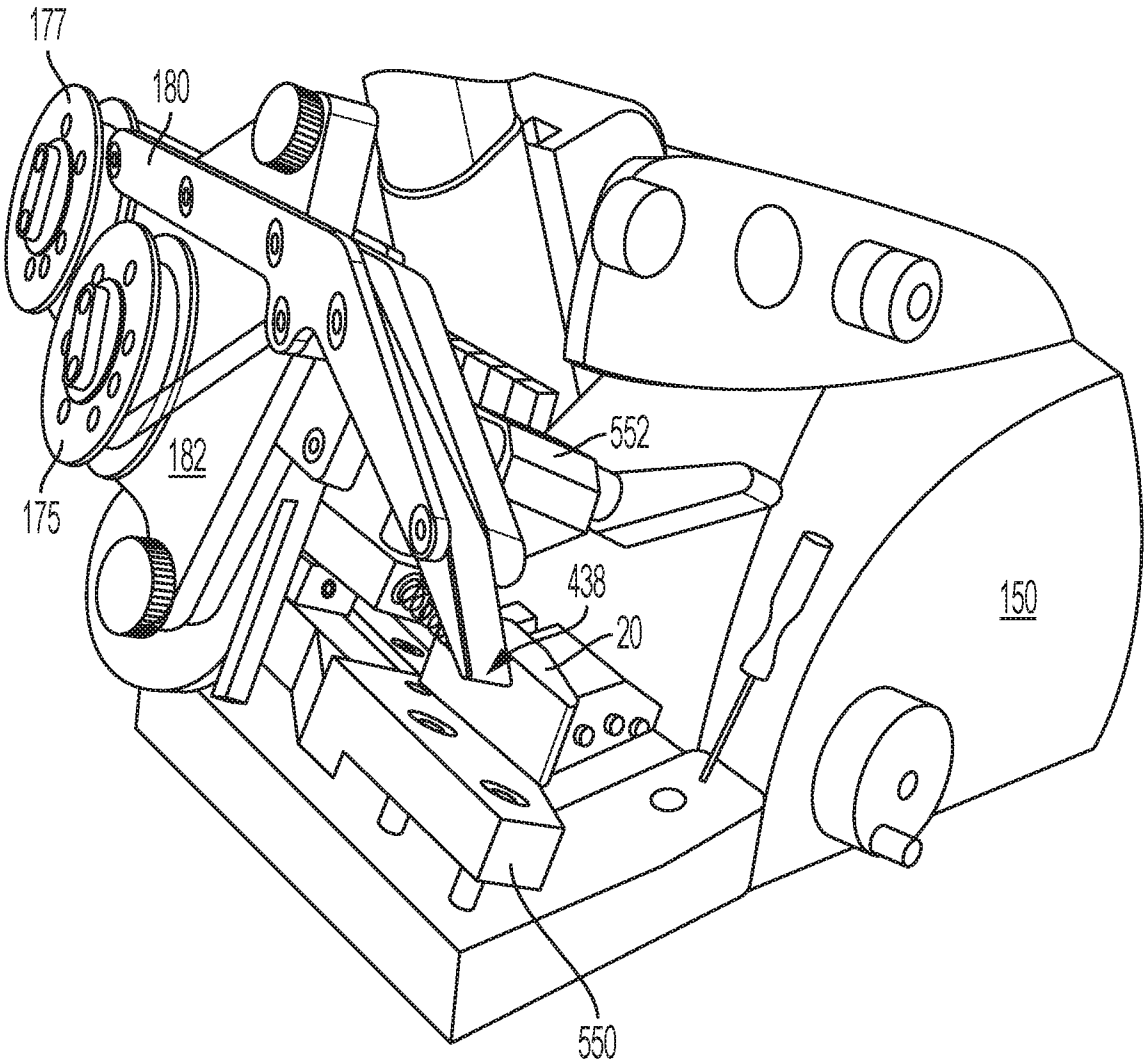


FIG. 4

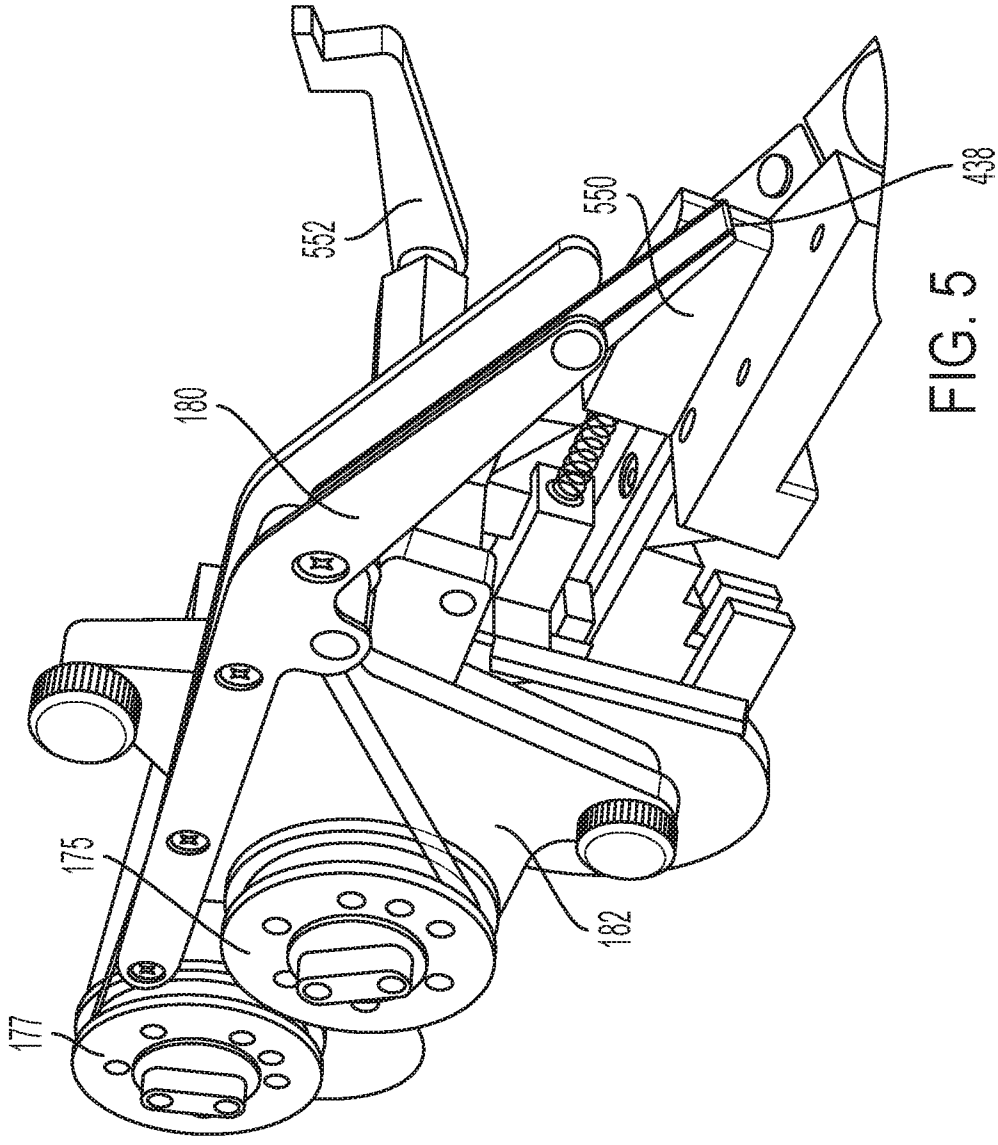


FIG. 5

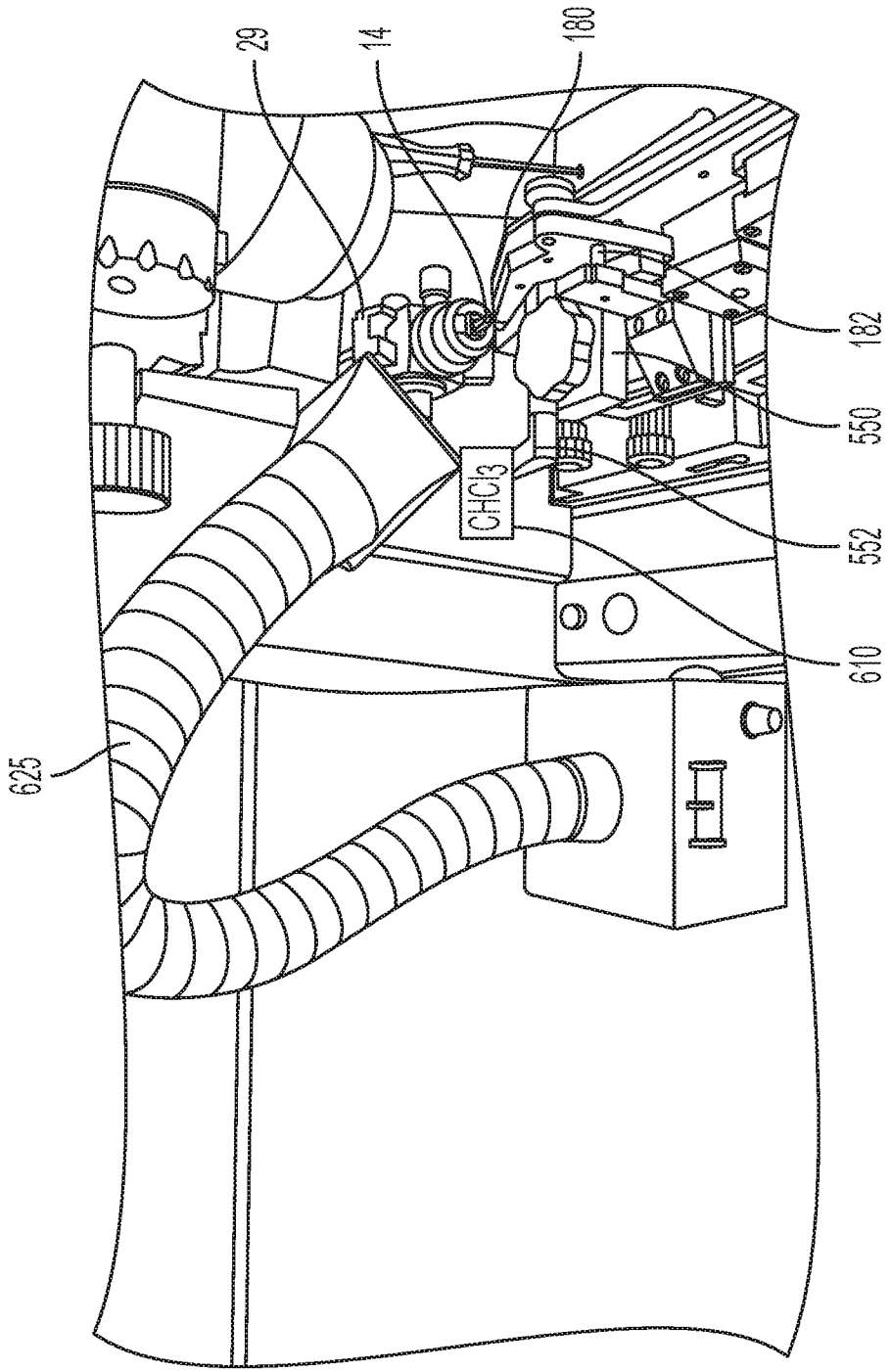


FIG. 6

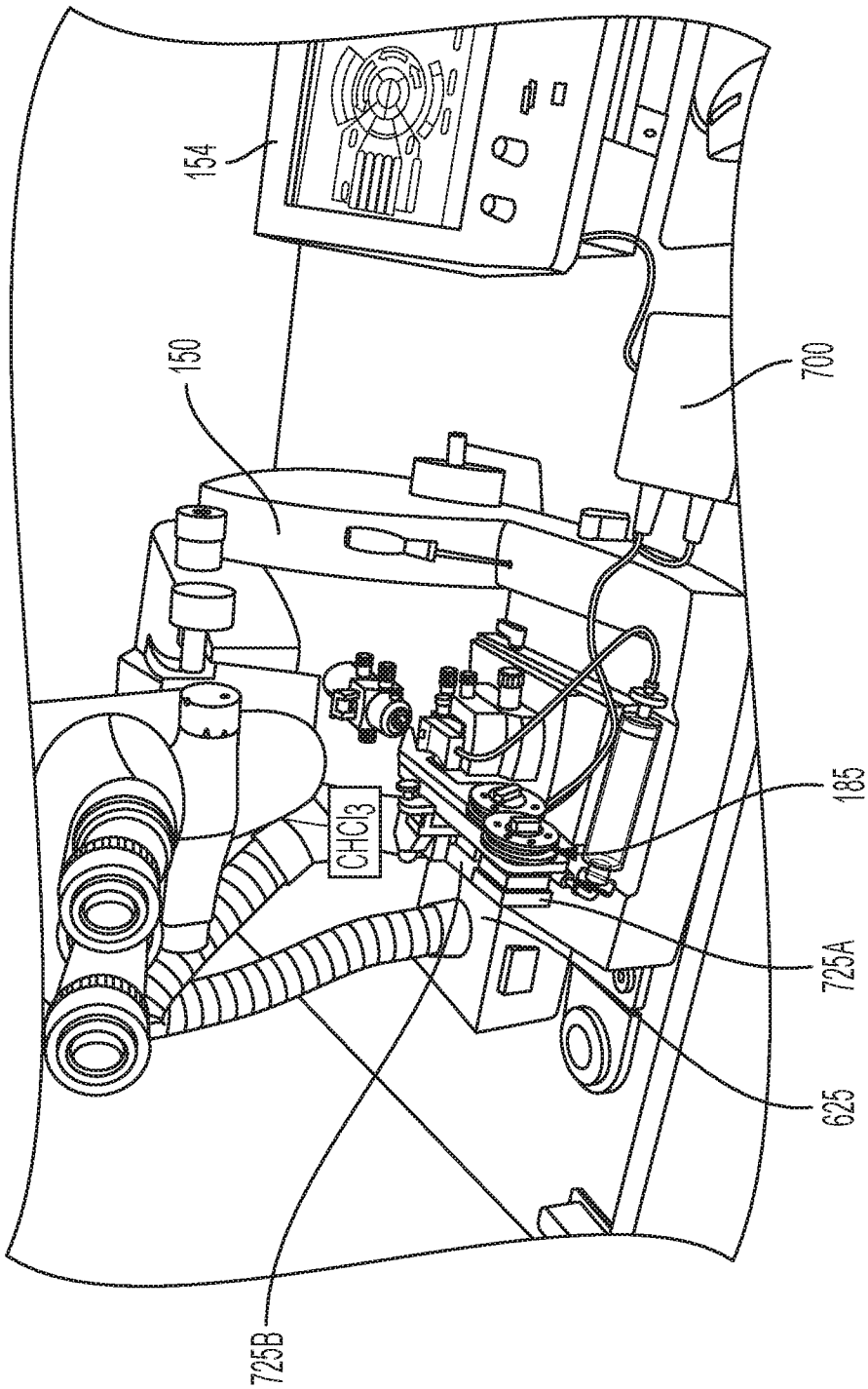


FIG. 7

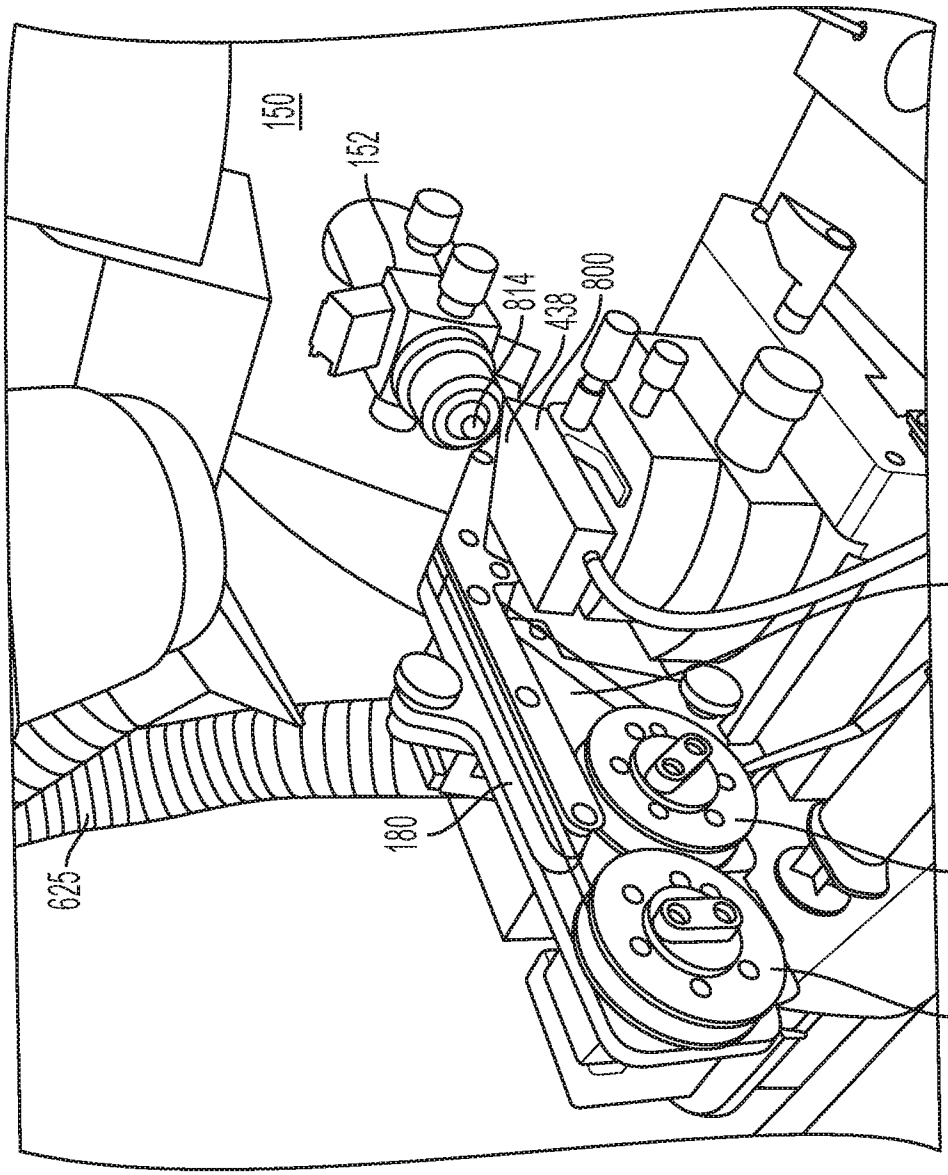


FIG. 8

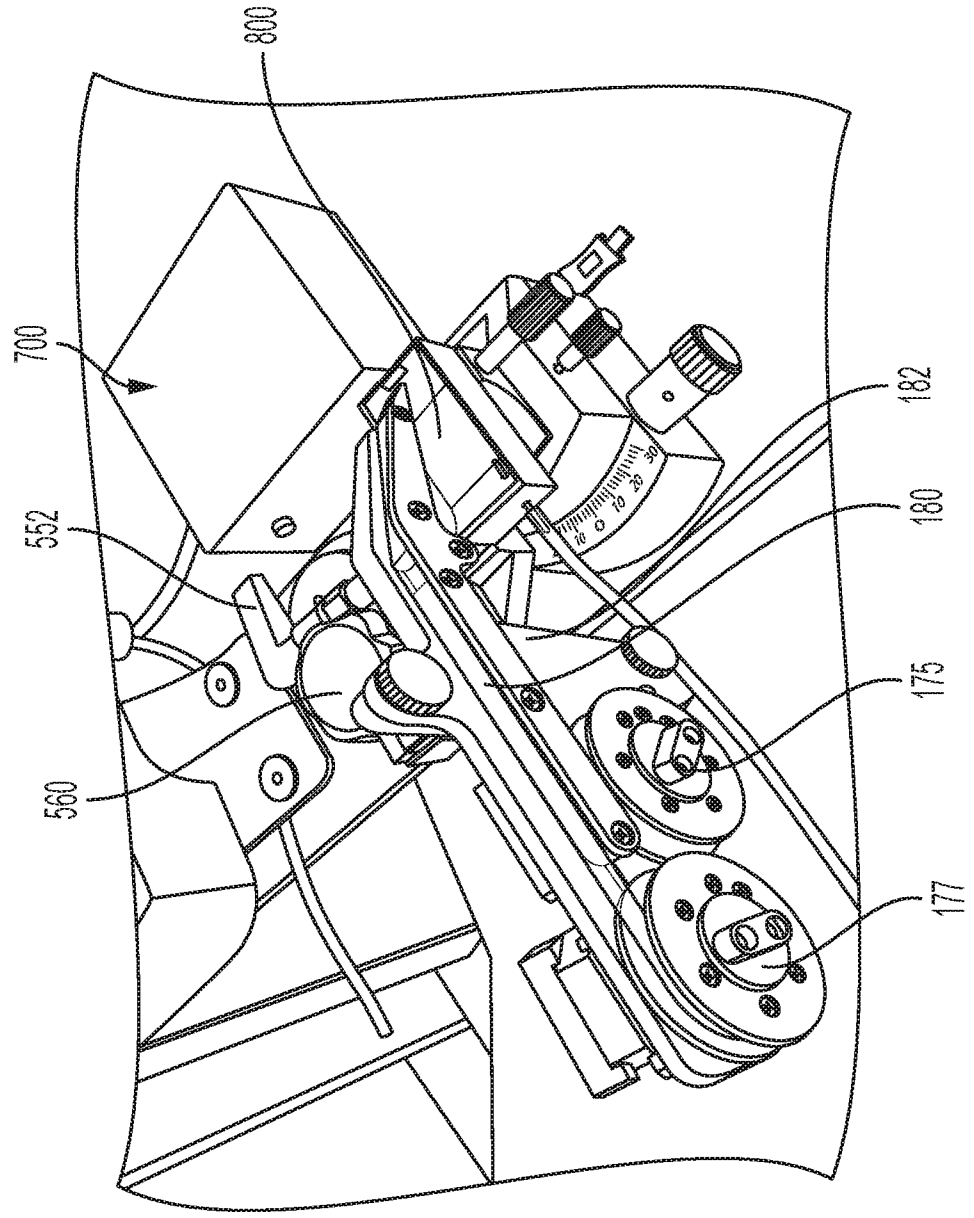


FIG. 9

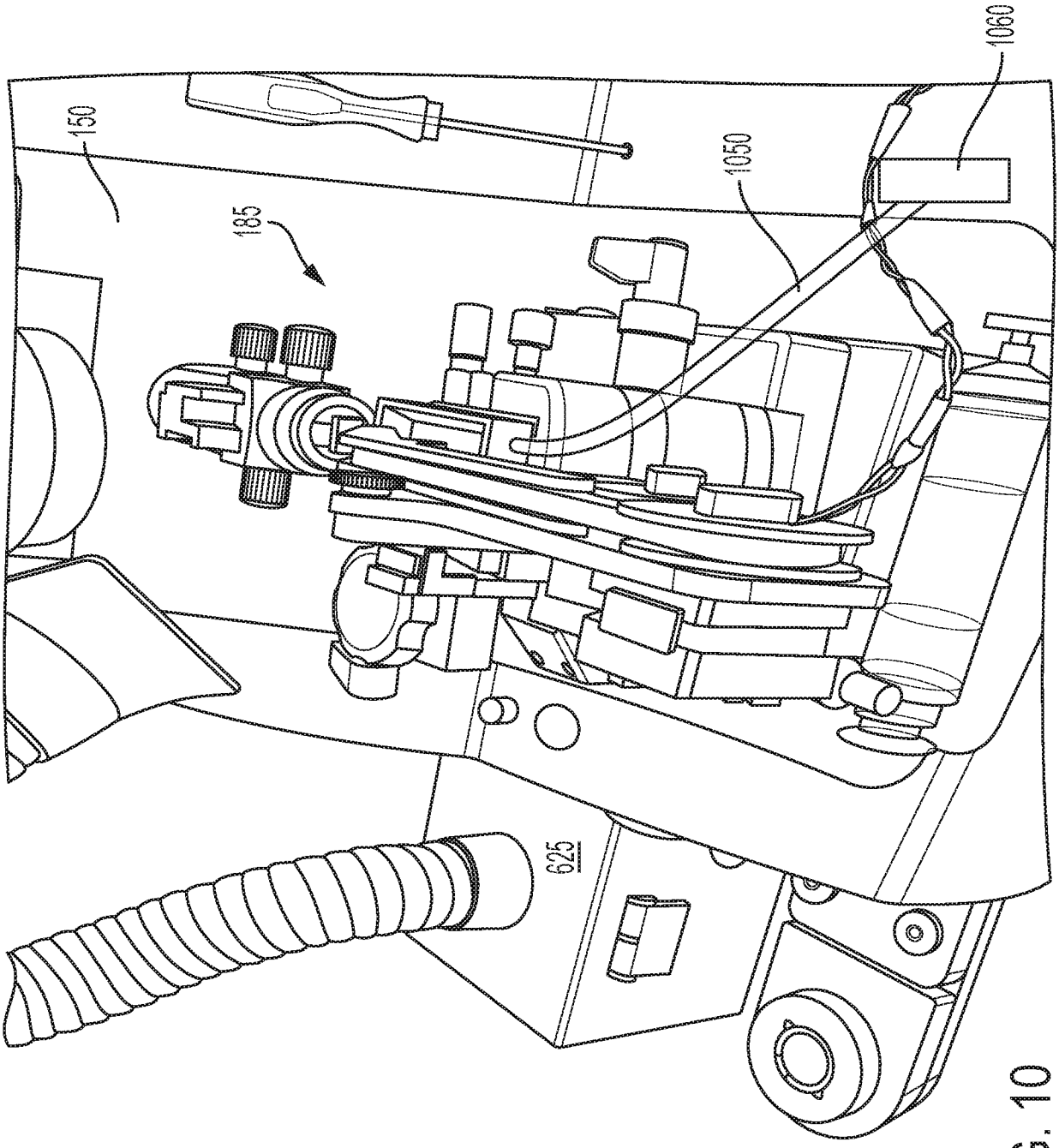


FIG. 10

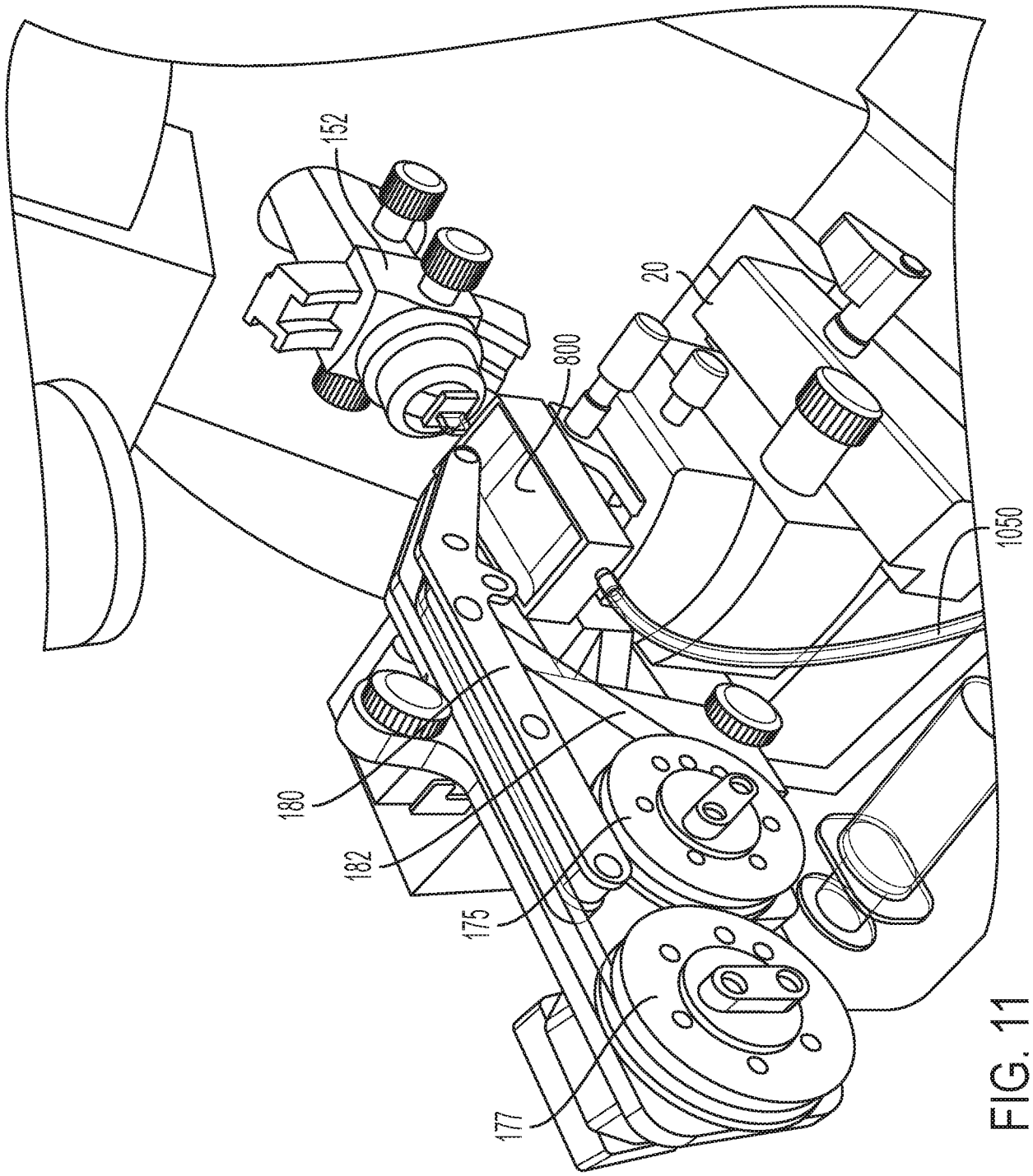


FIG. 11

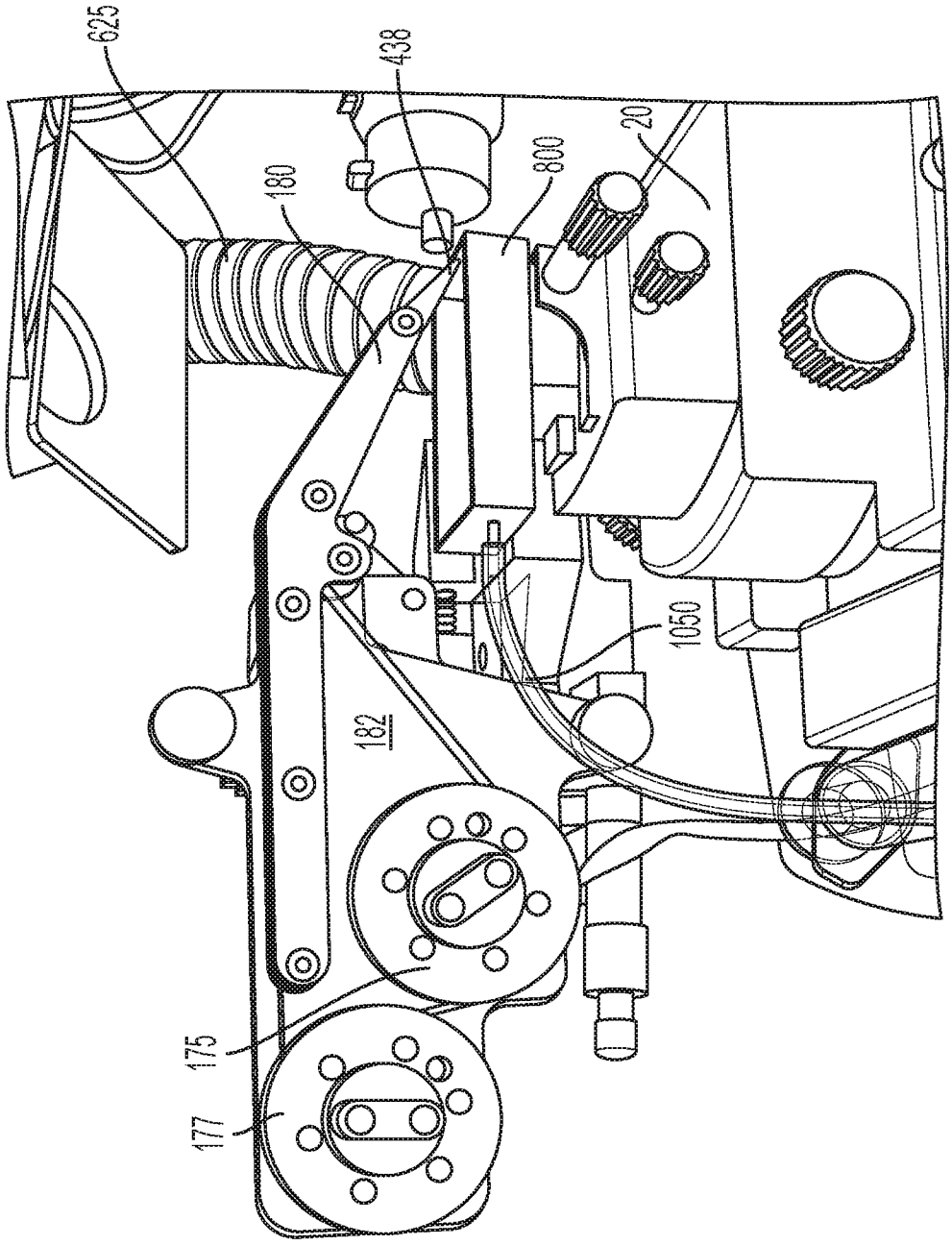


FIG. 12A

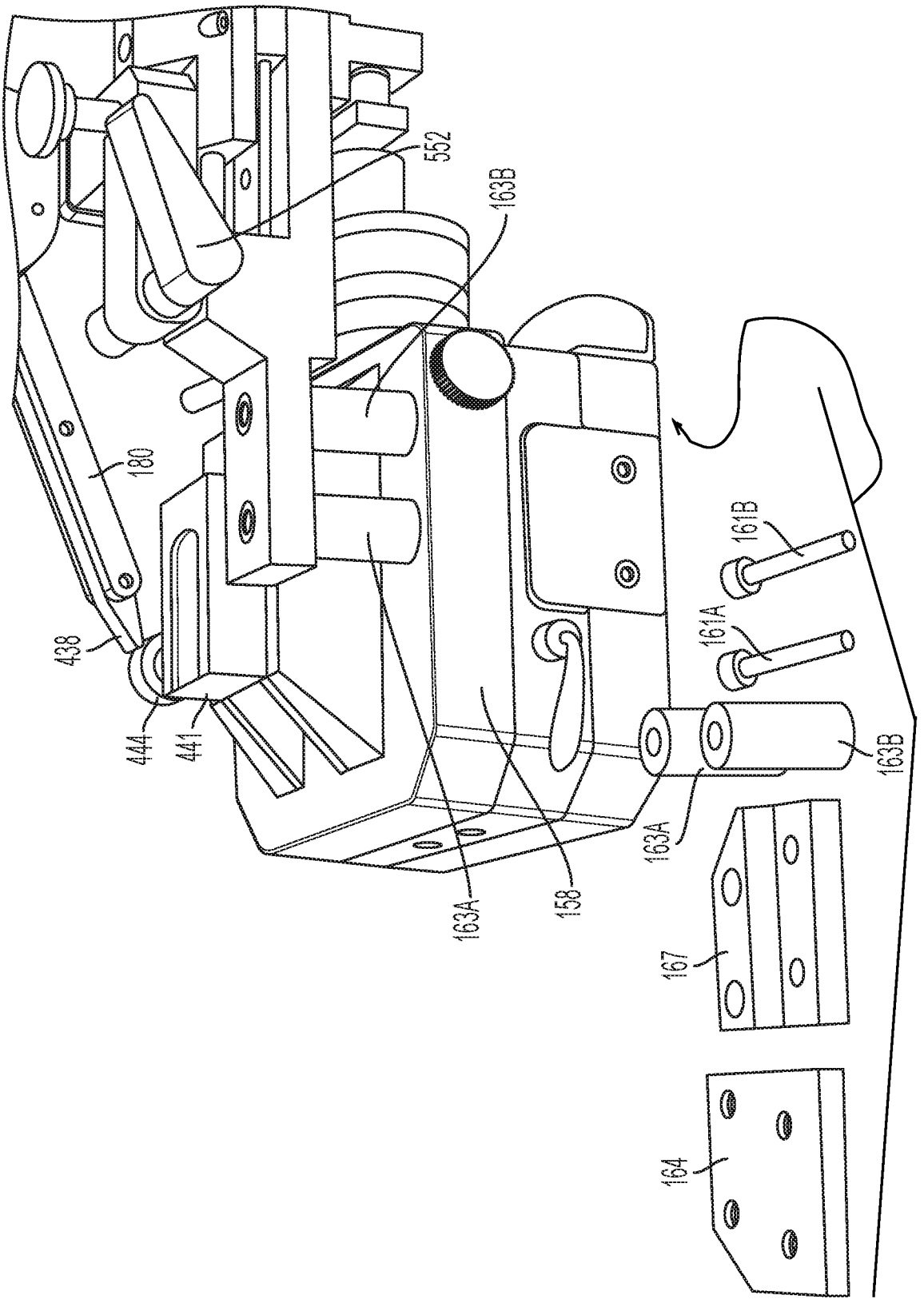


FIG. 12B

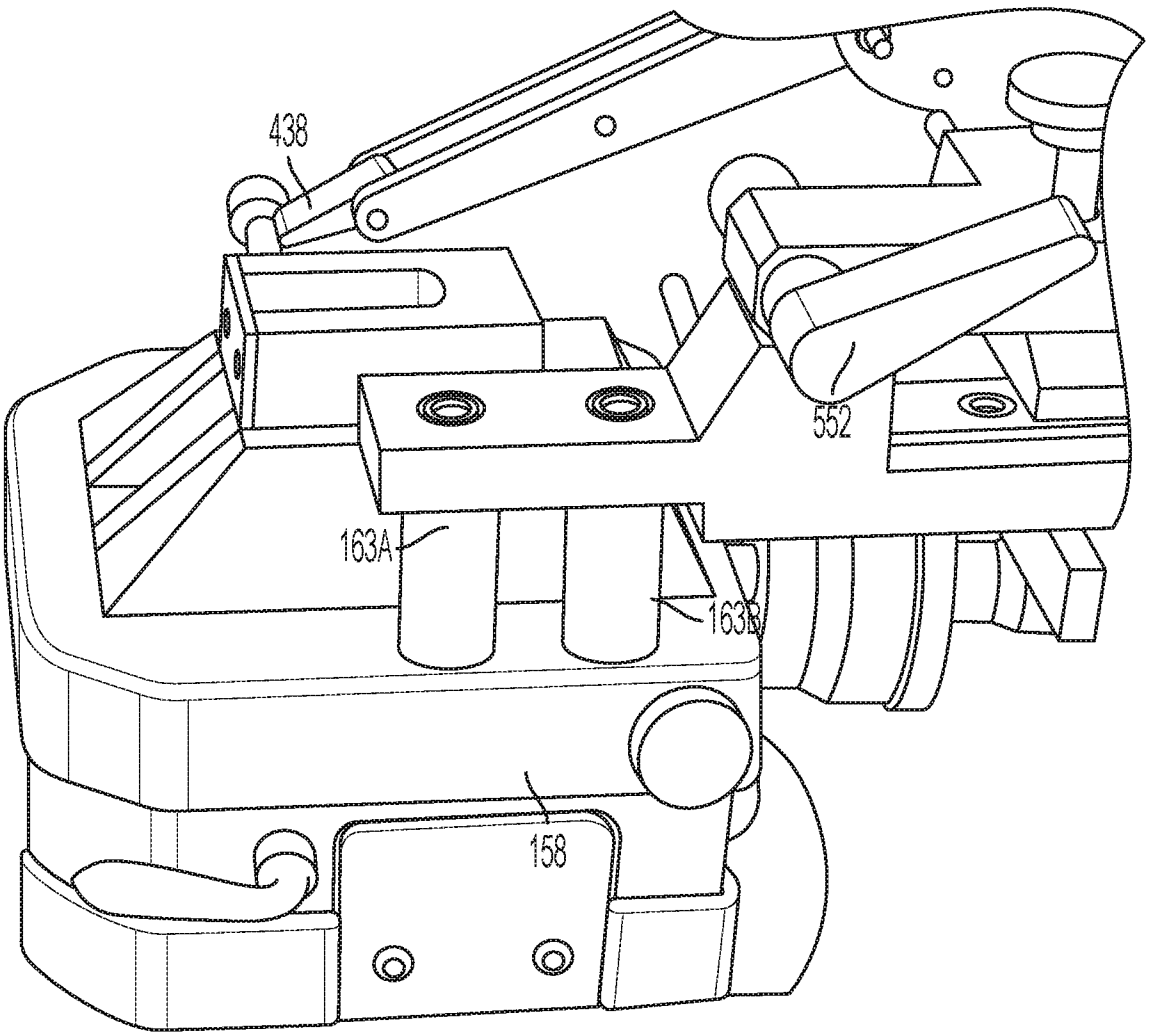


FIG. 12C

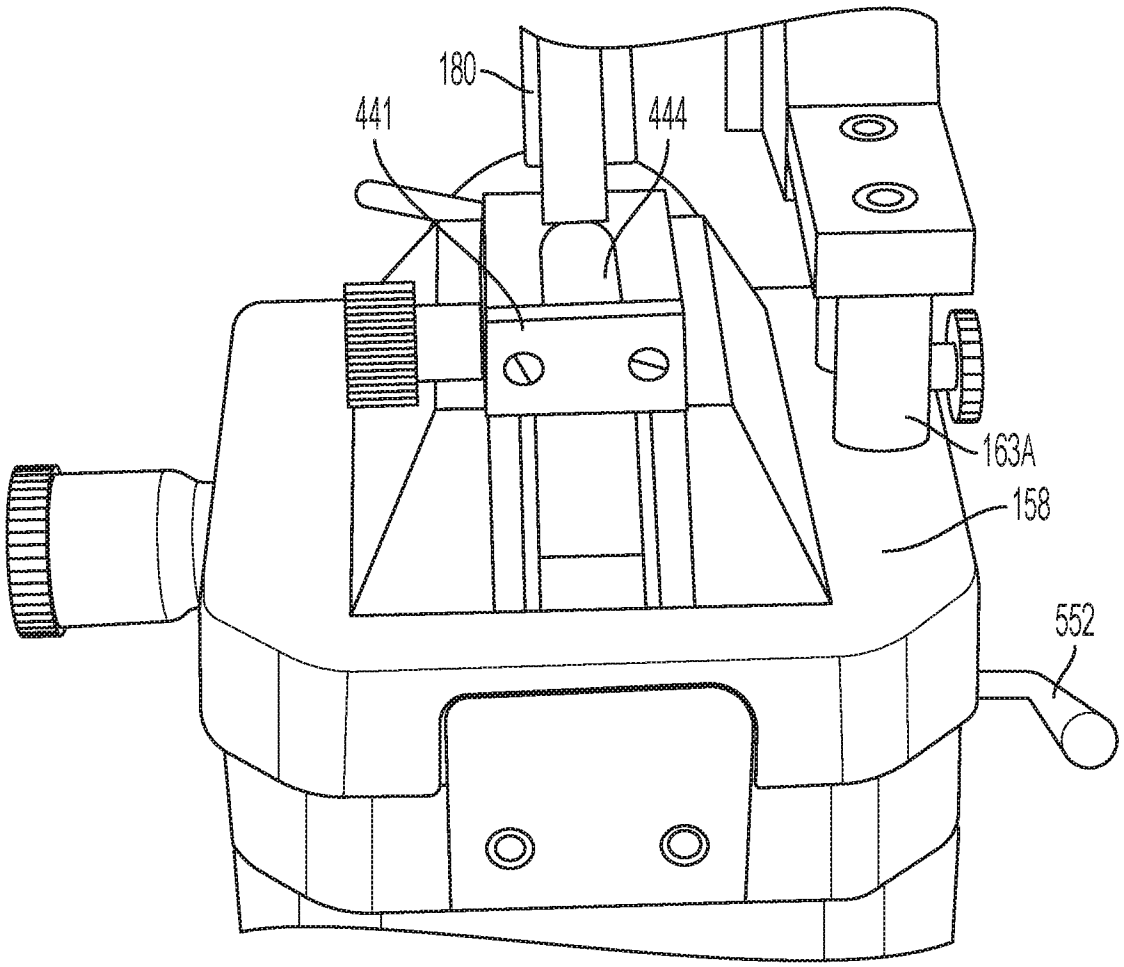


FIG. 12D

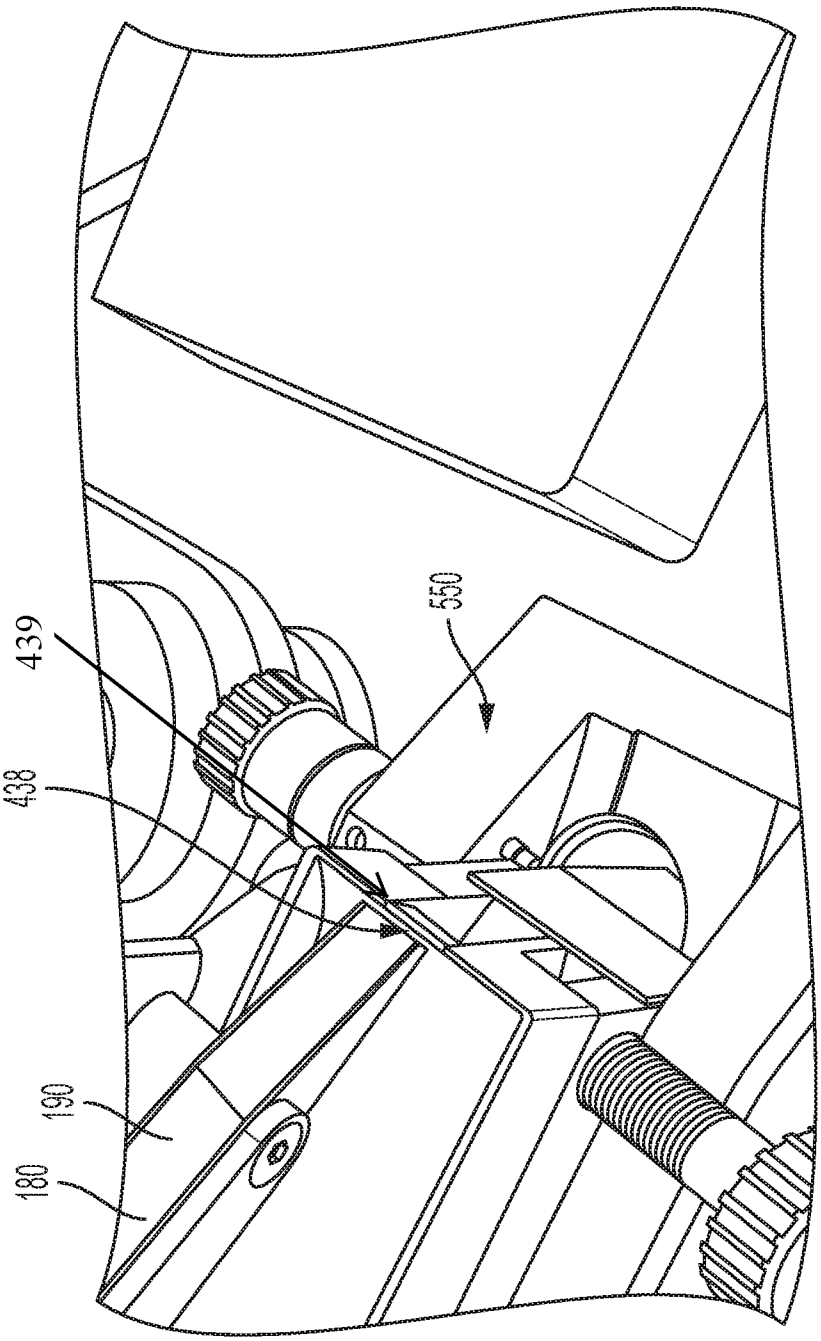


FIG. 13

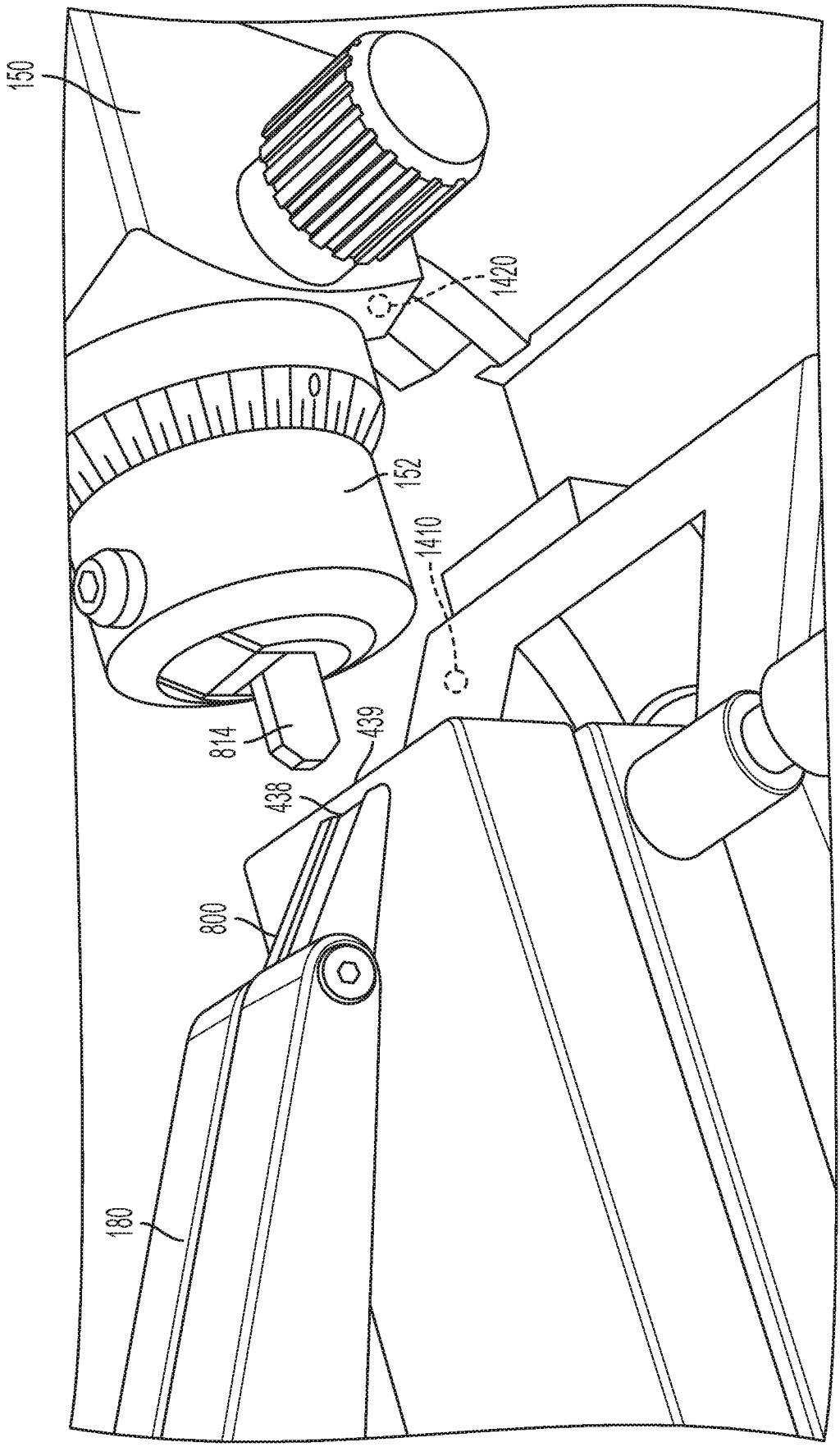


FIG. 14

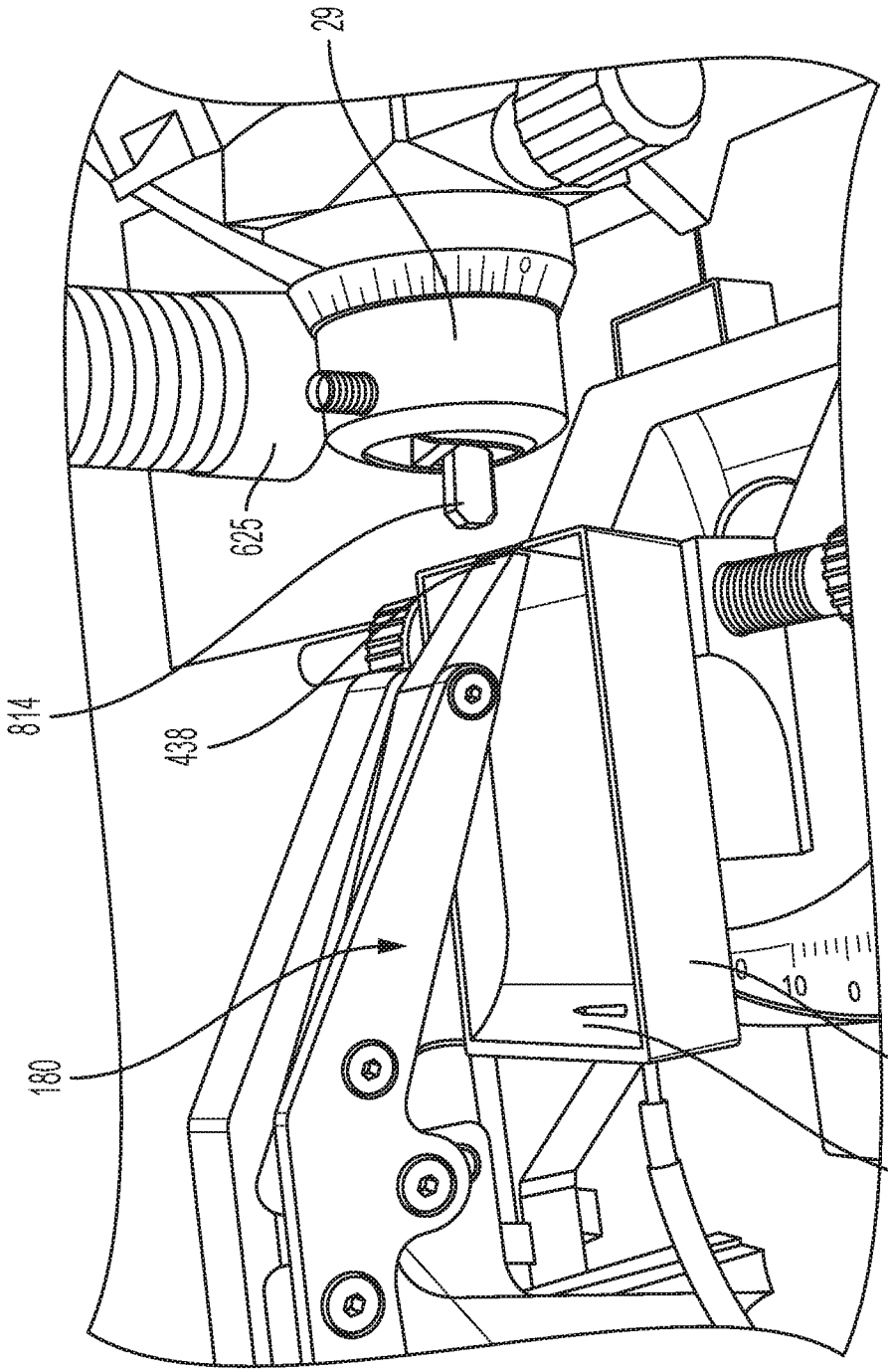


FIG. 15

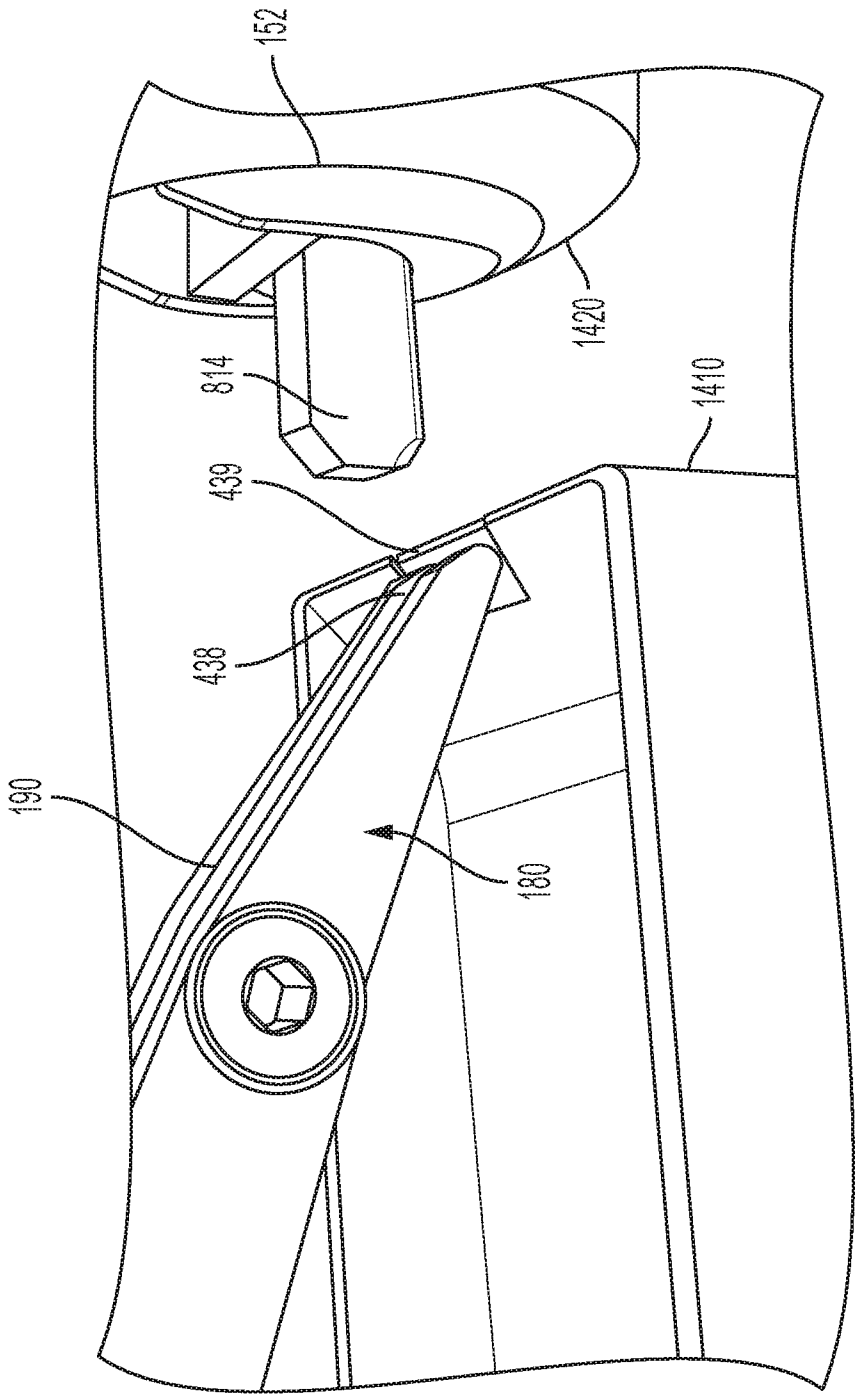


FIG. 16

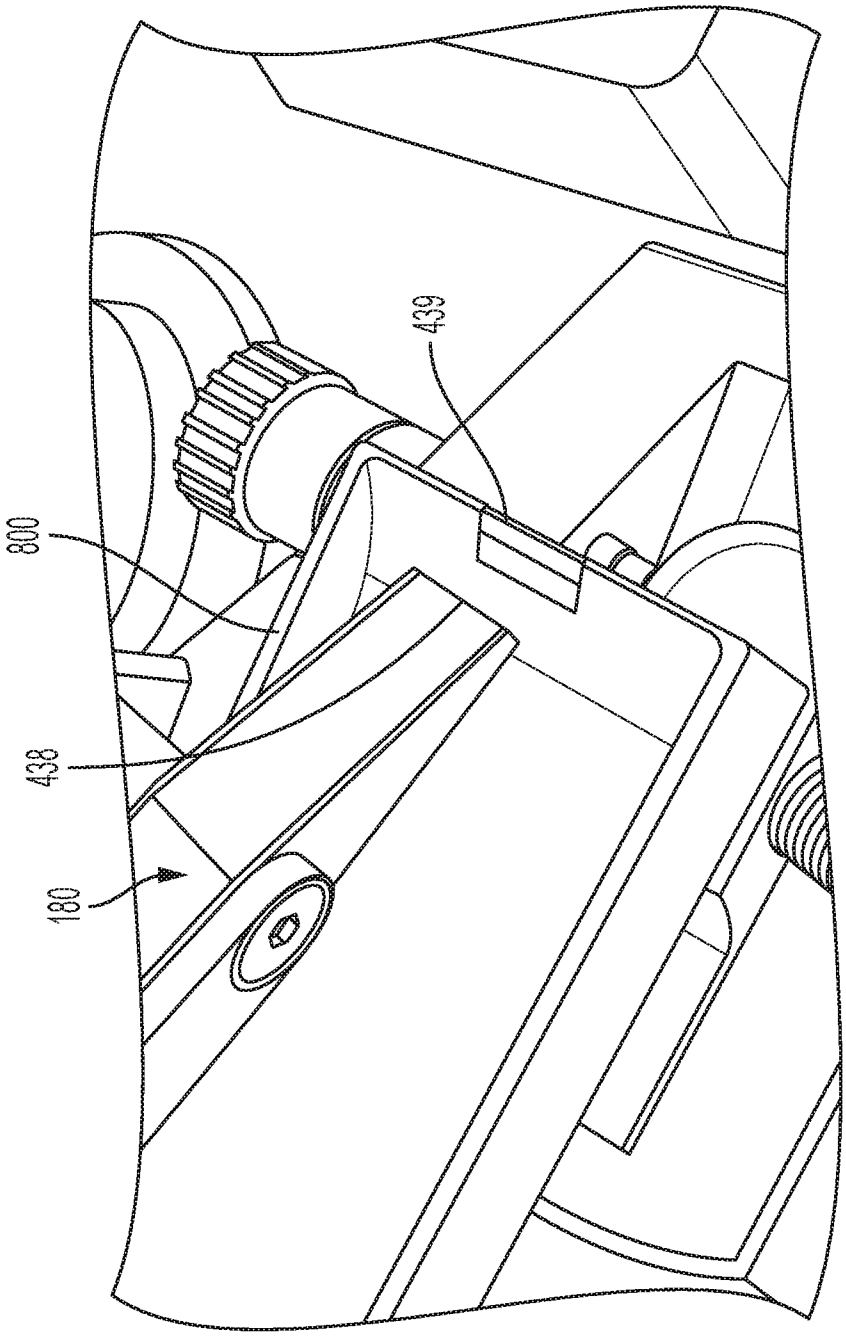


FIG. 17

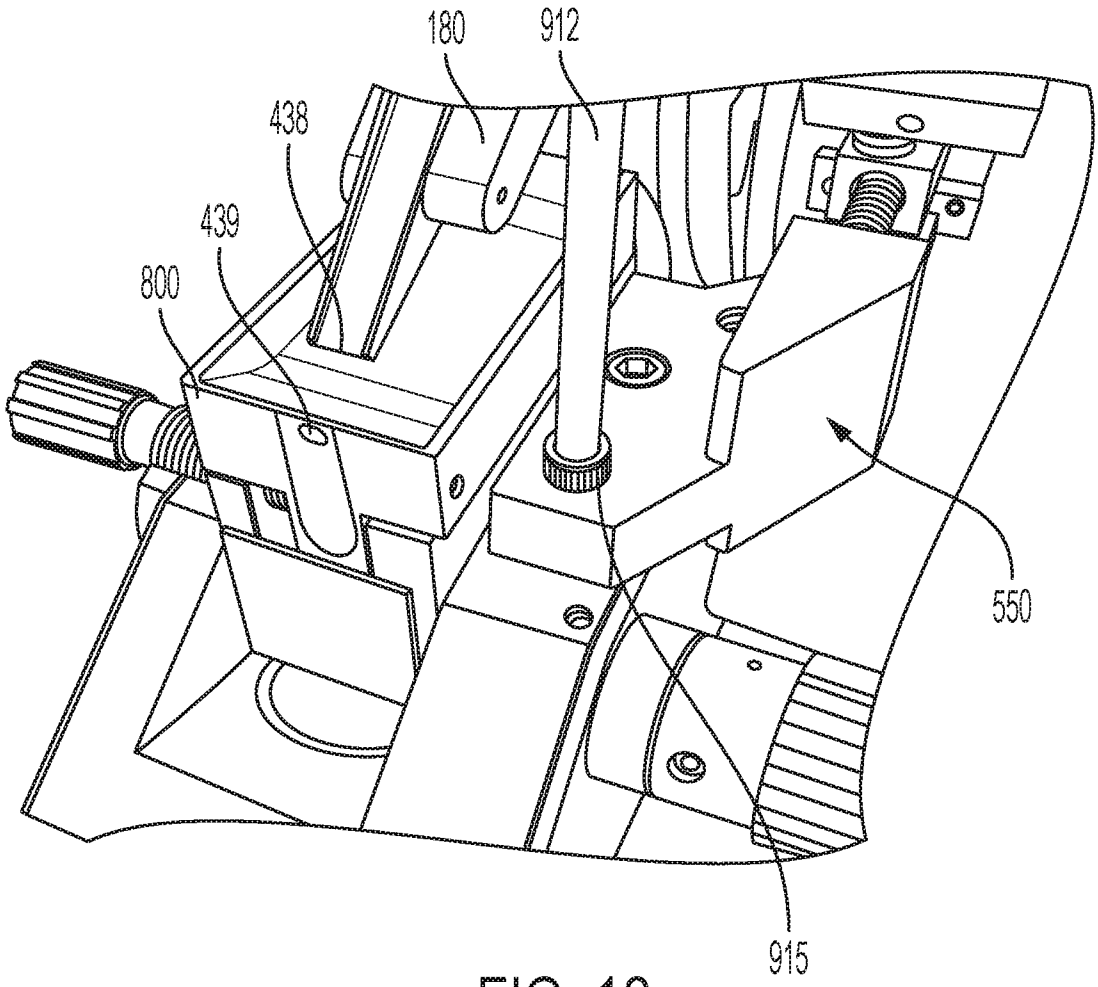


FIG. 18

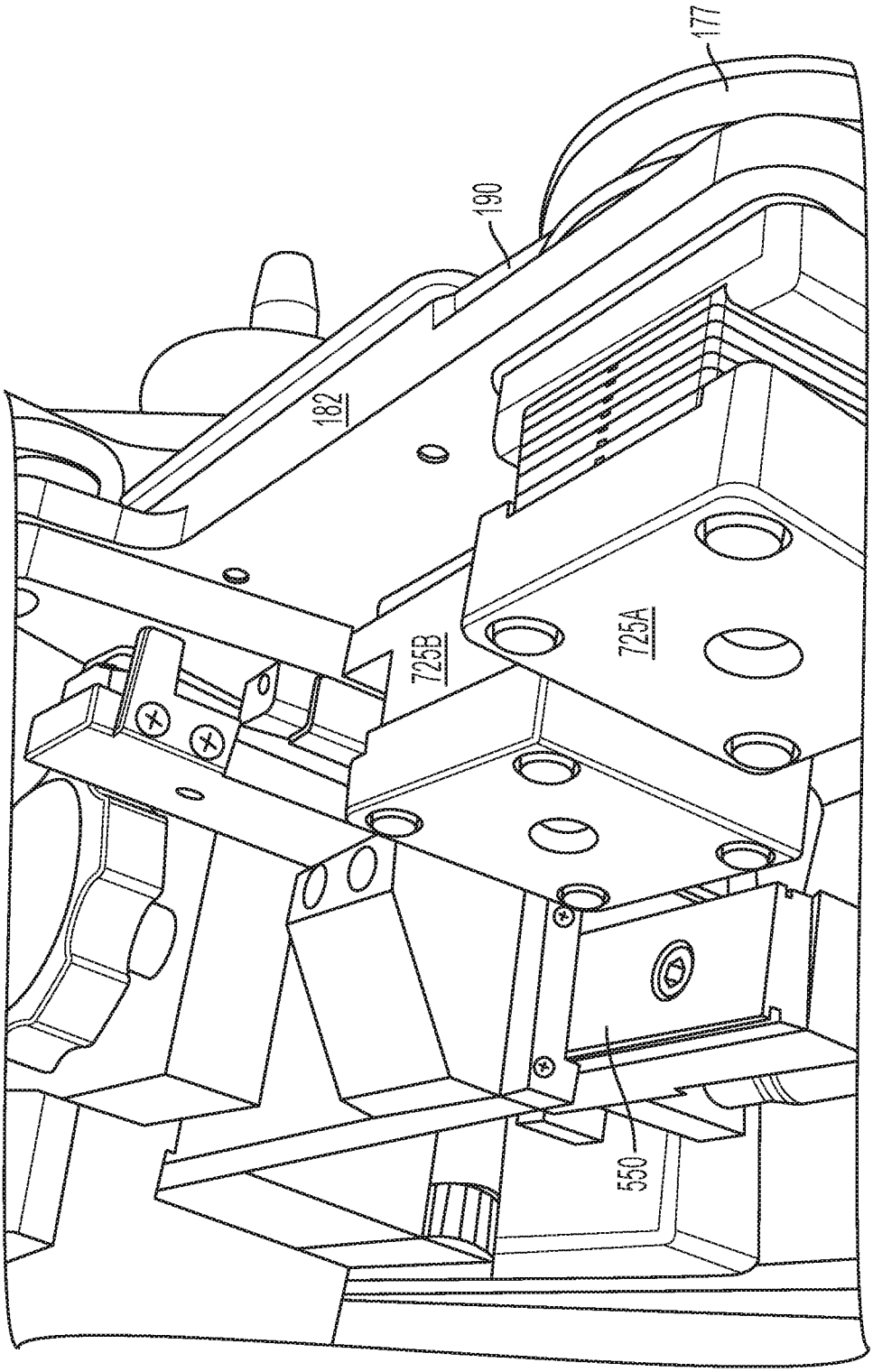


FIG. 19

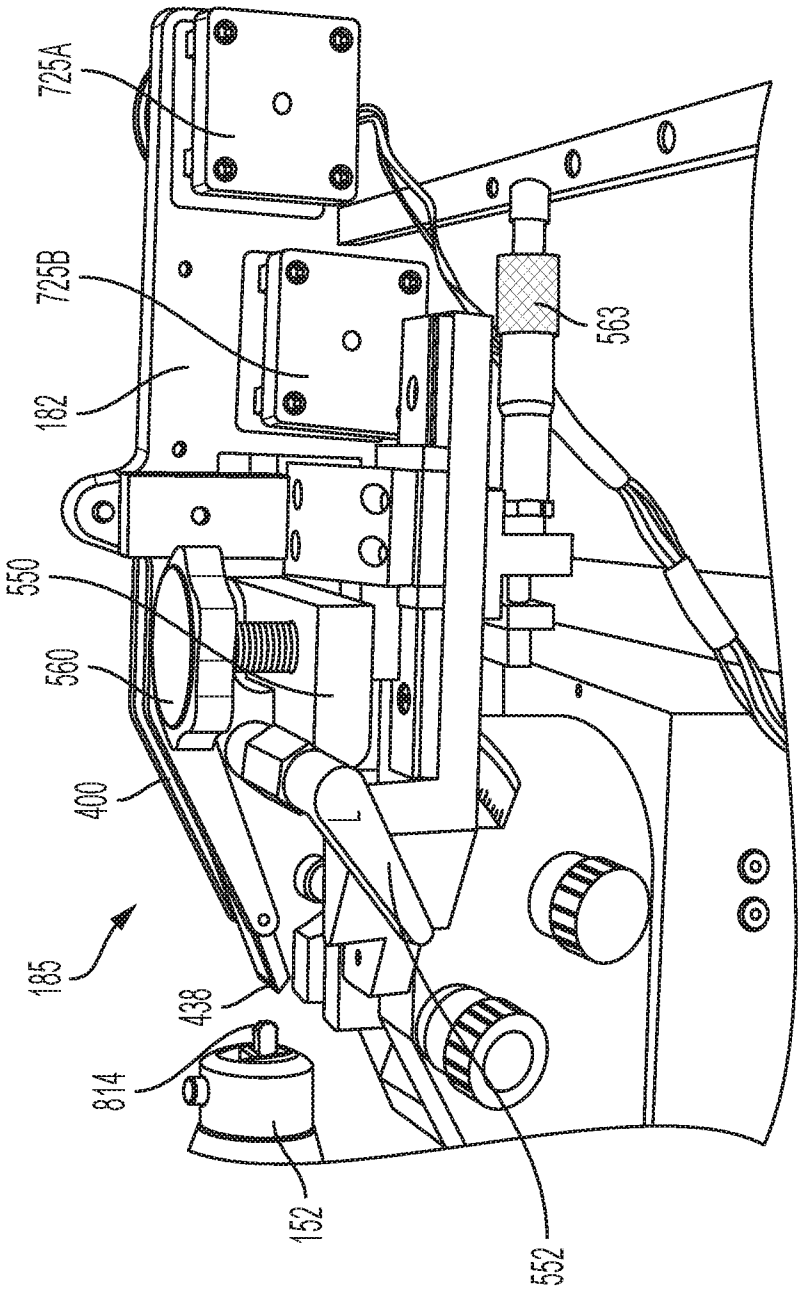


FIG. 20A

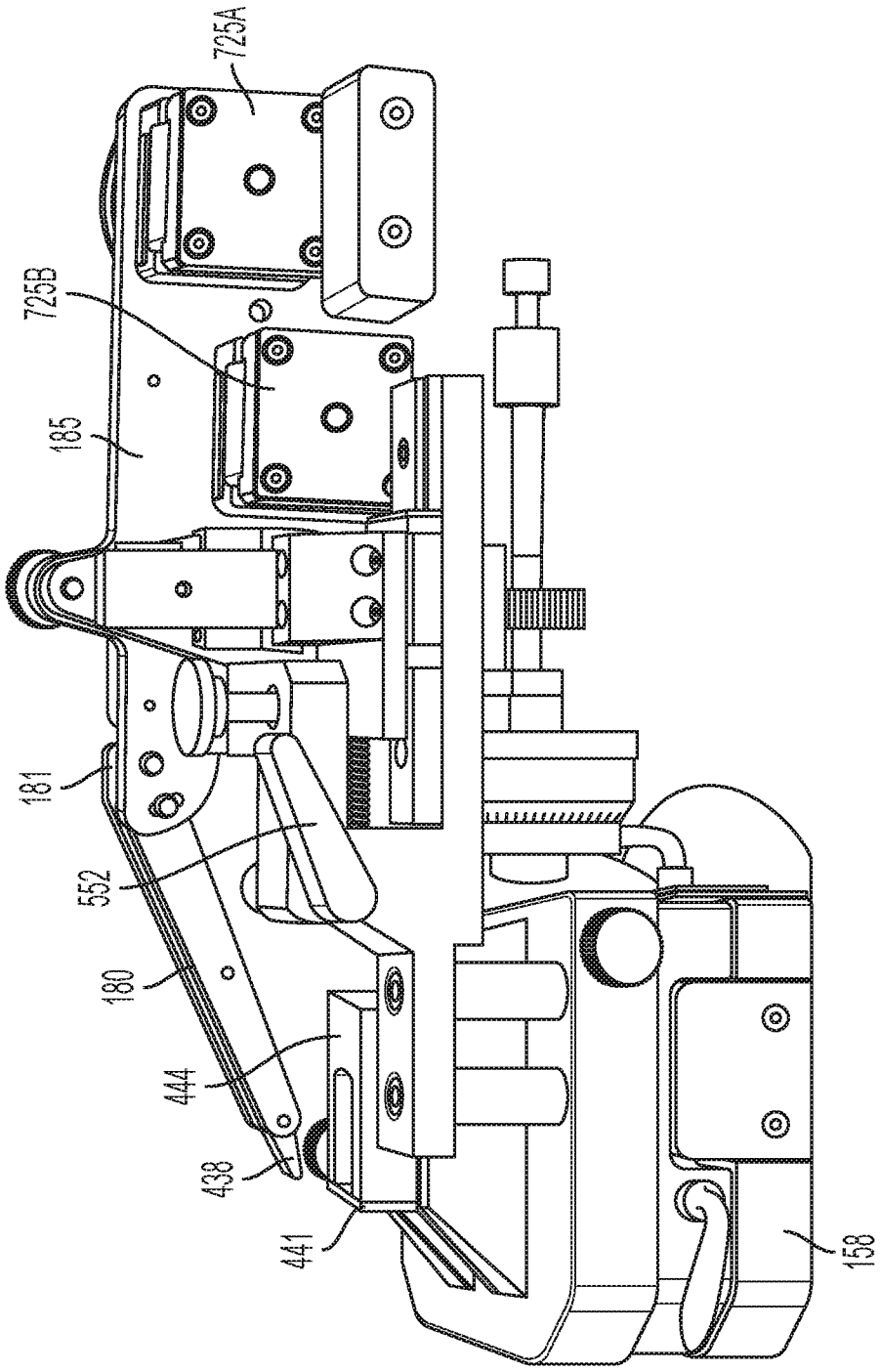


FIG. 20B

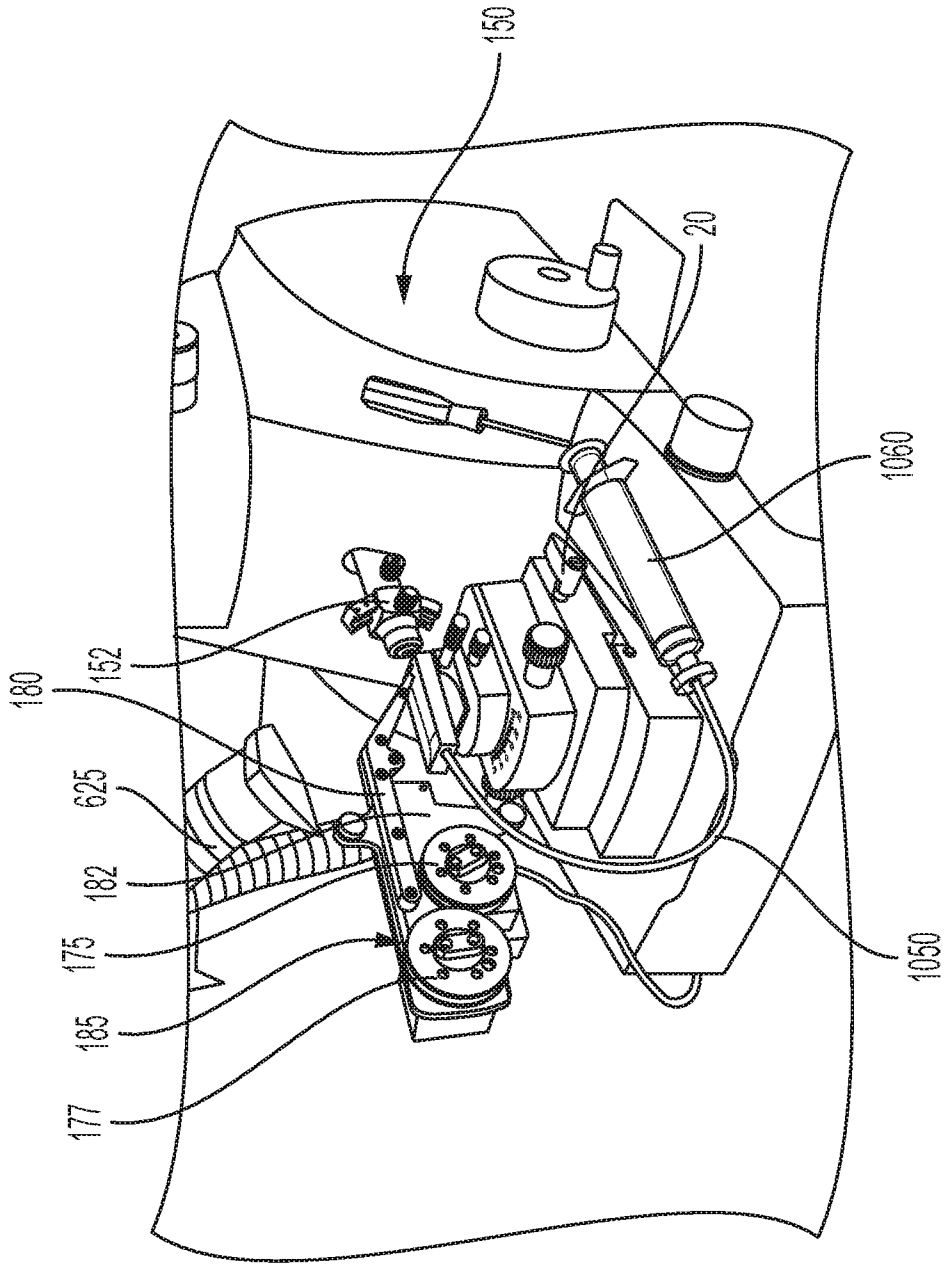


FIG. 21

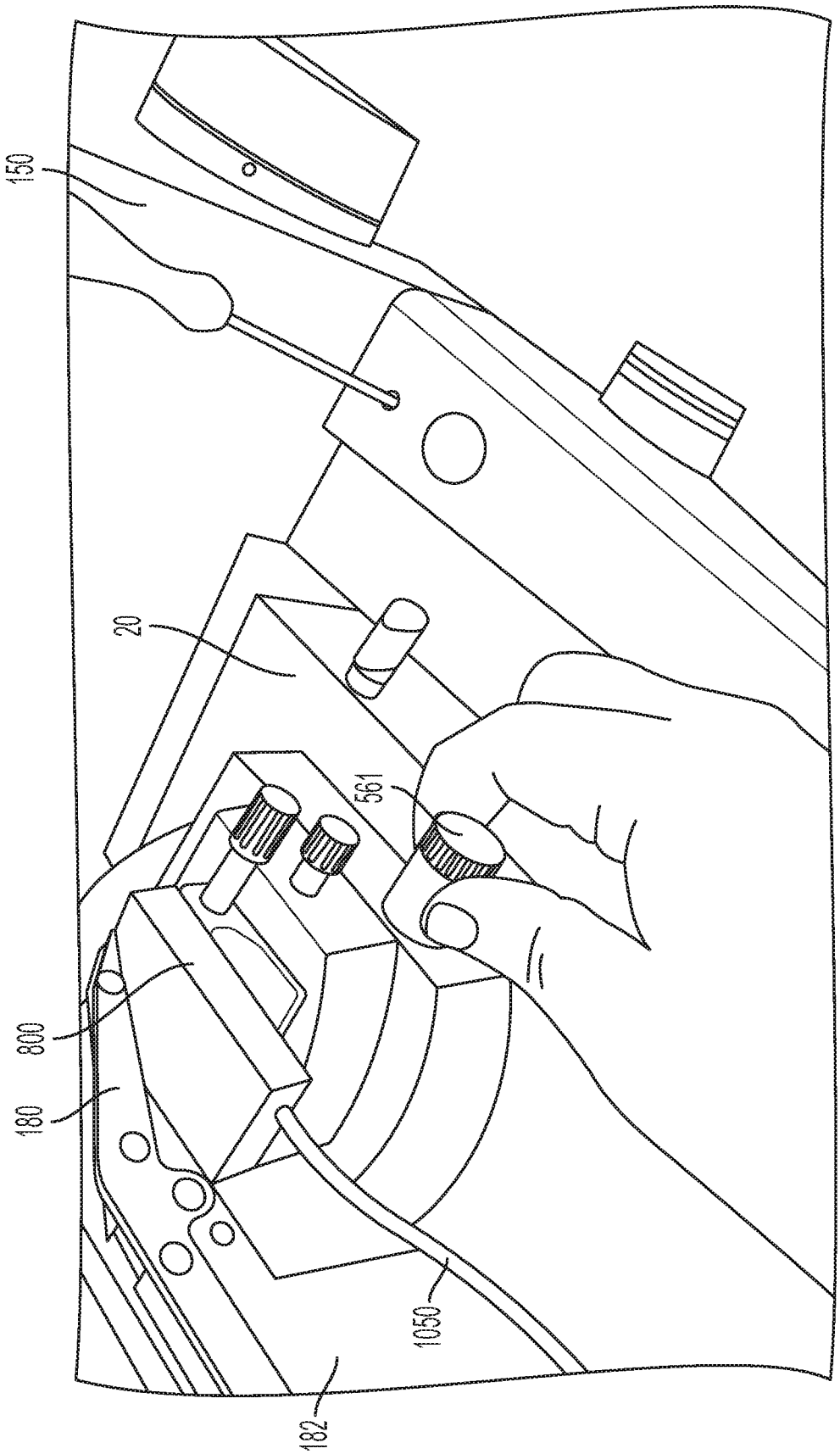


FIG. 22

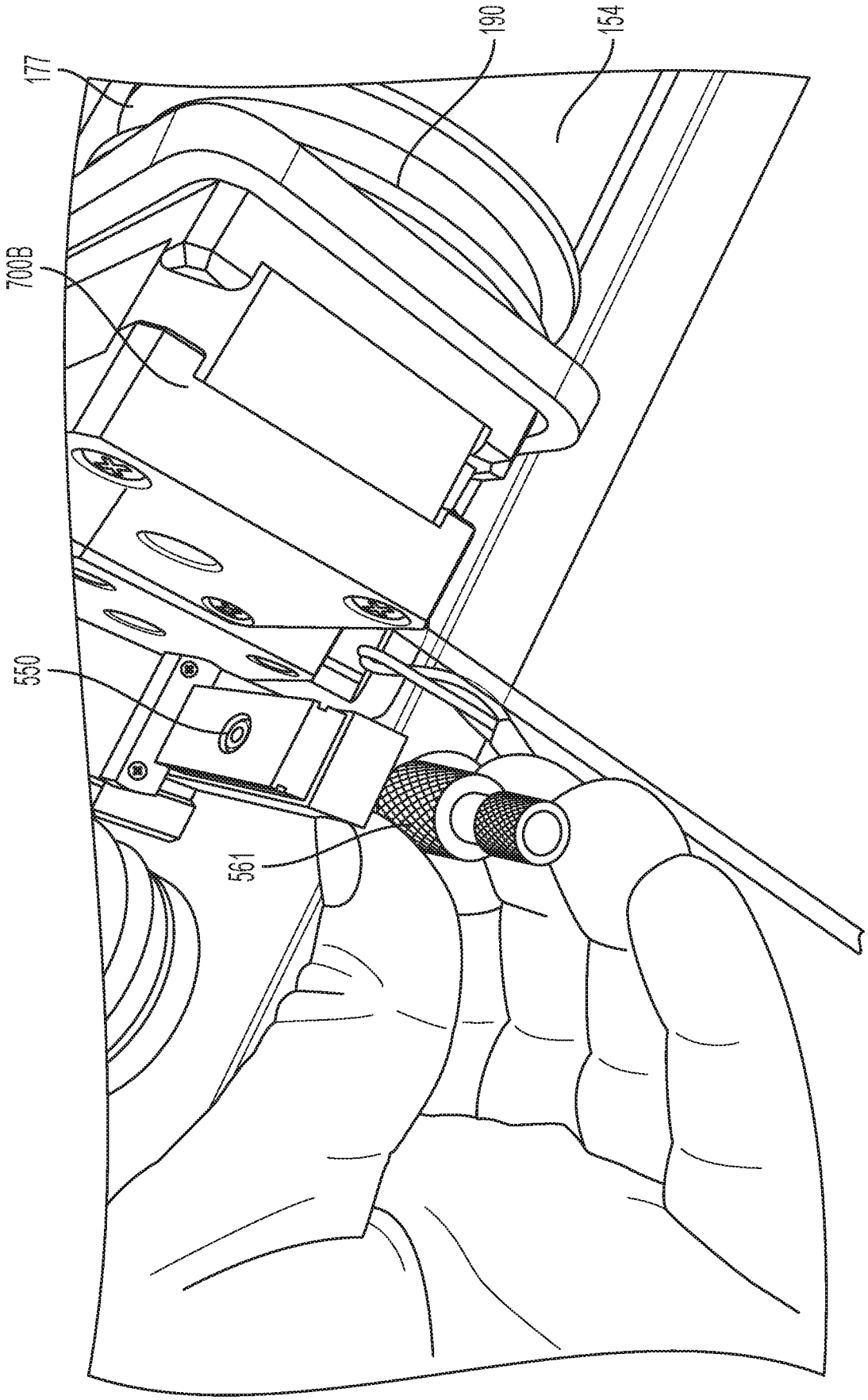


FIG. 23

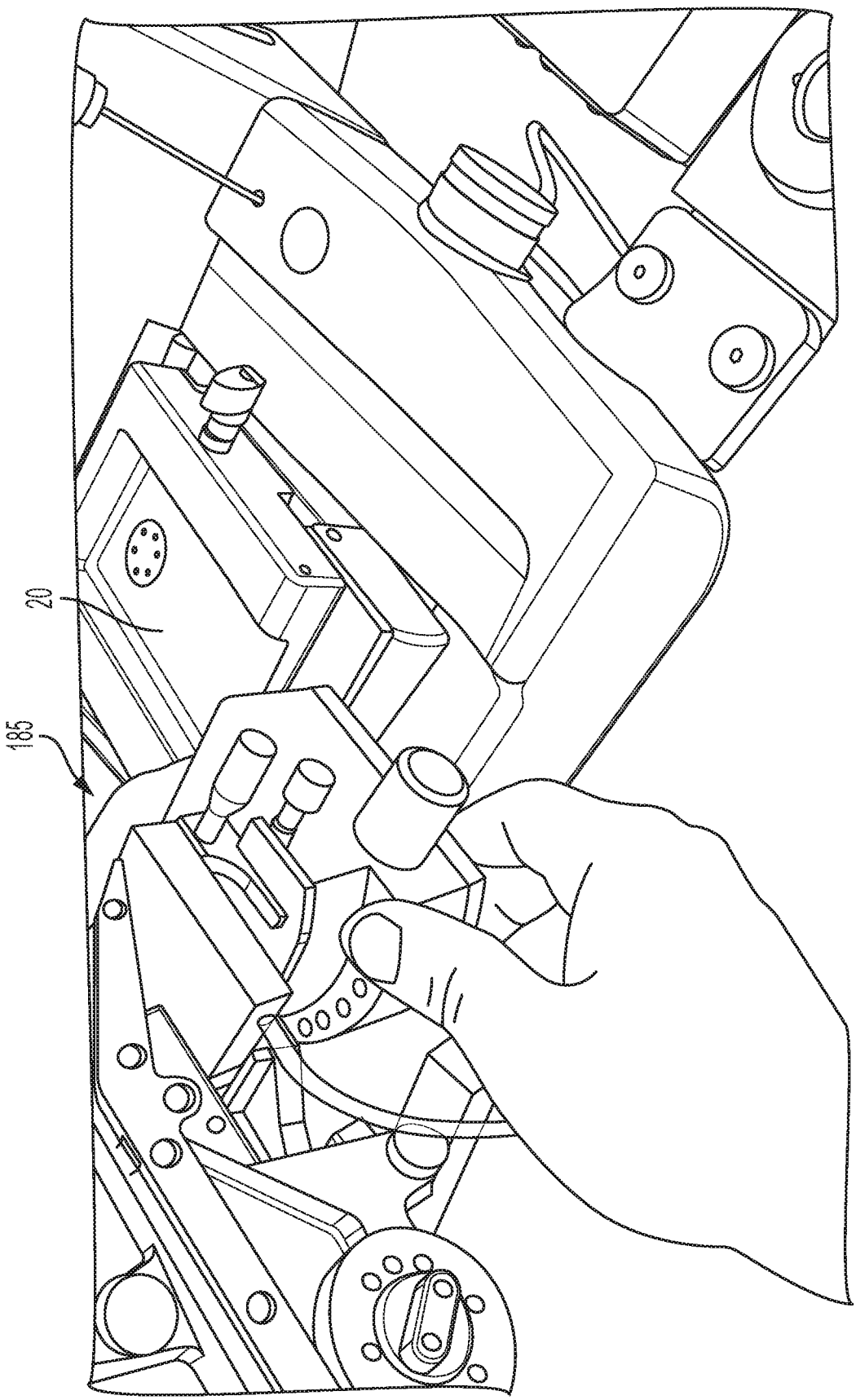


FIG. 24

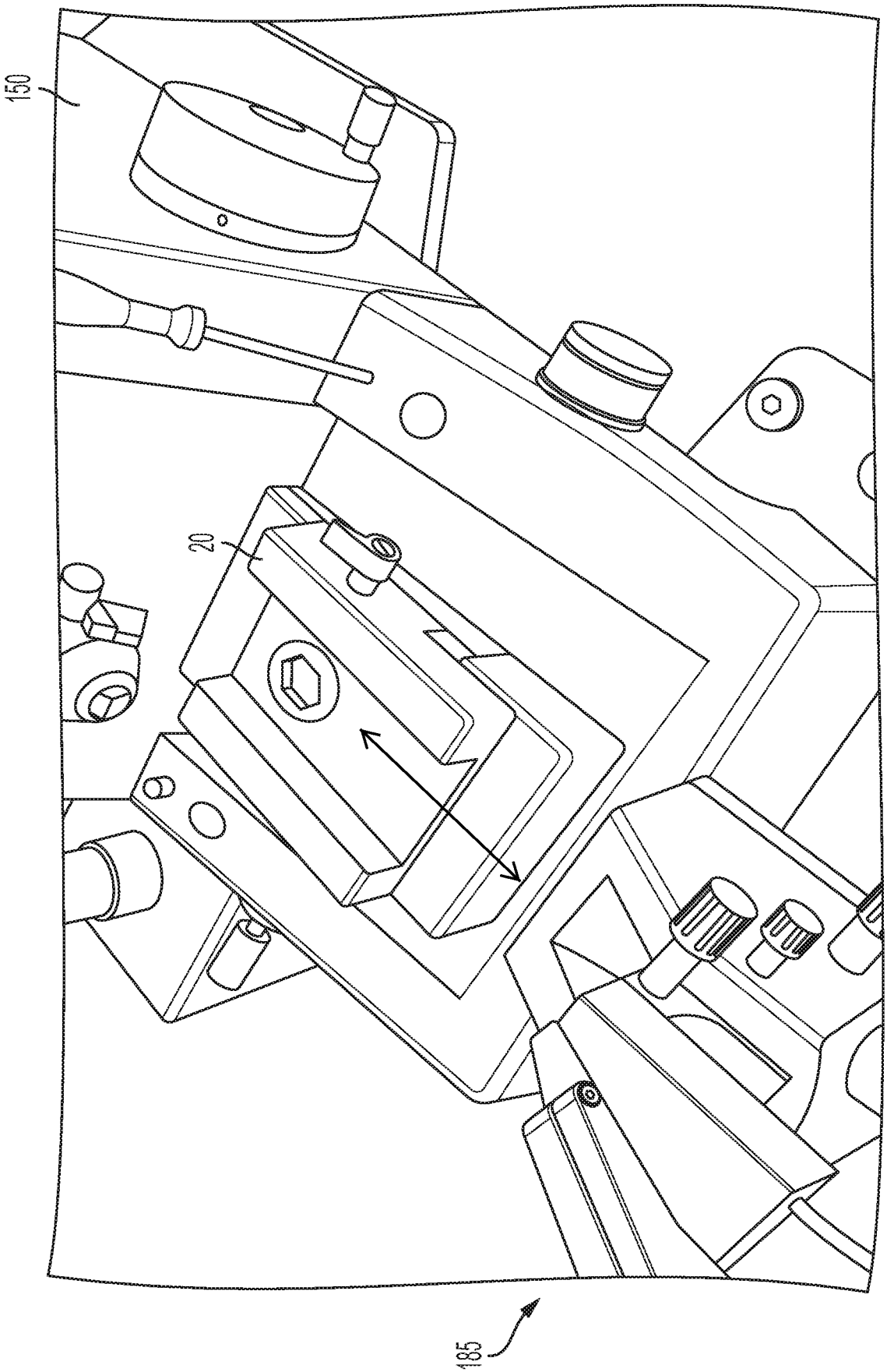


FIG. 25

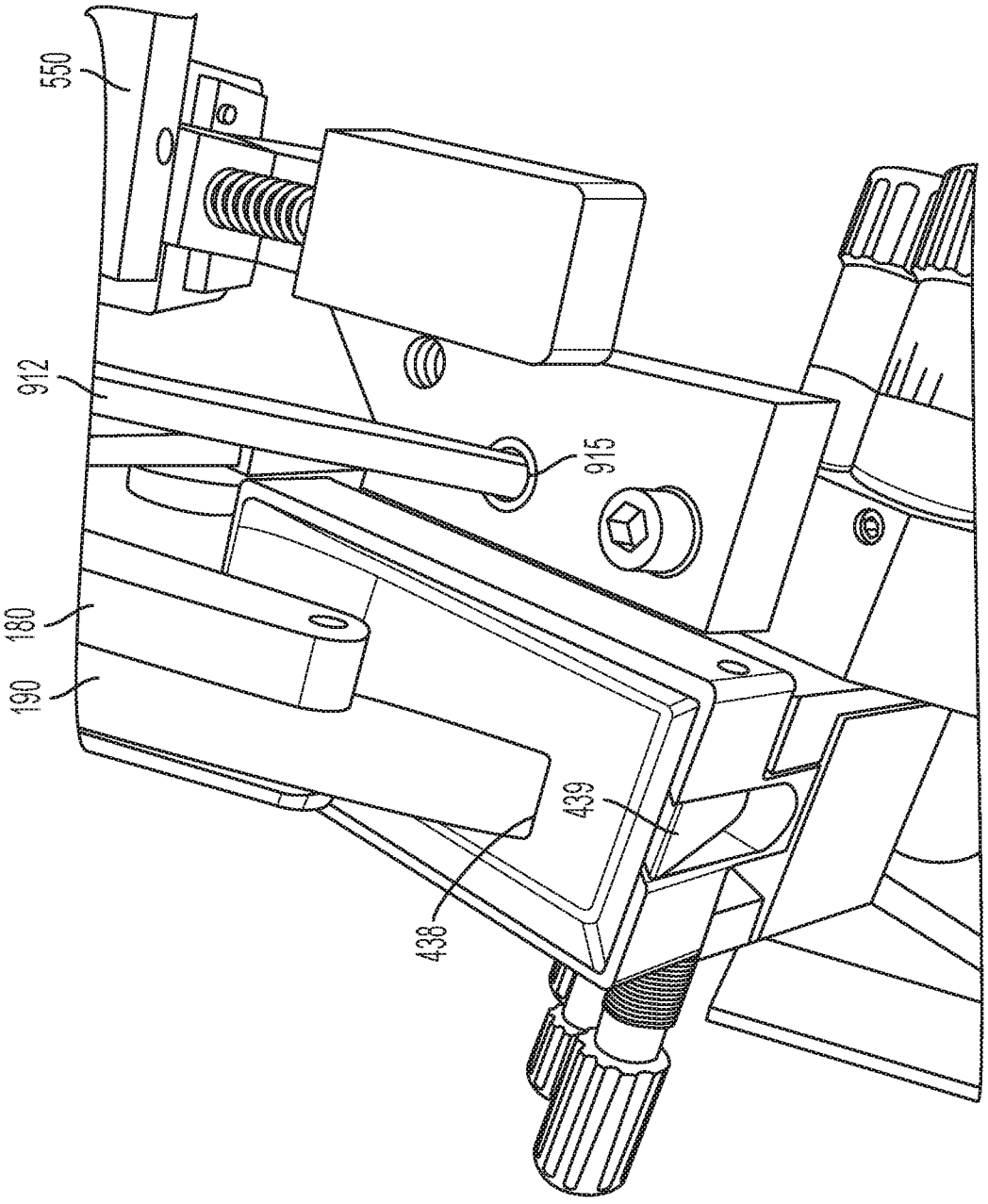


FIG. 26

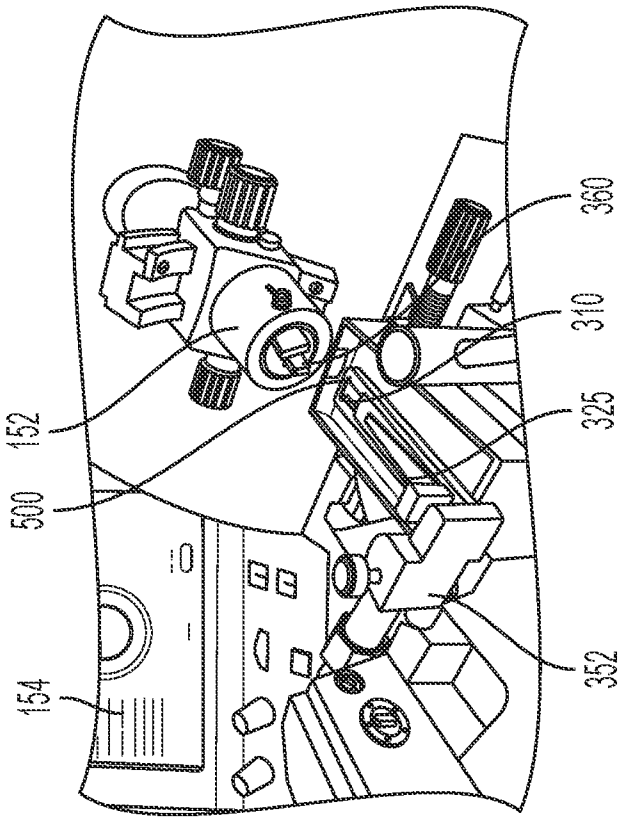


FIG. 27B

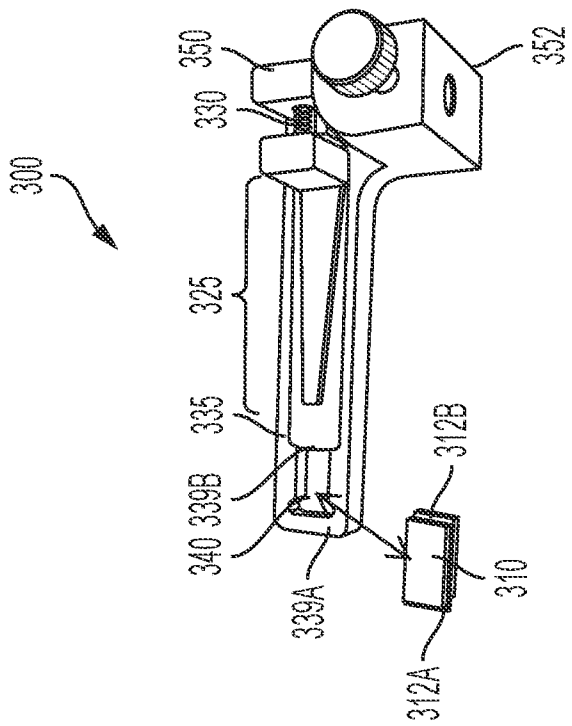


FIG. 27A

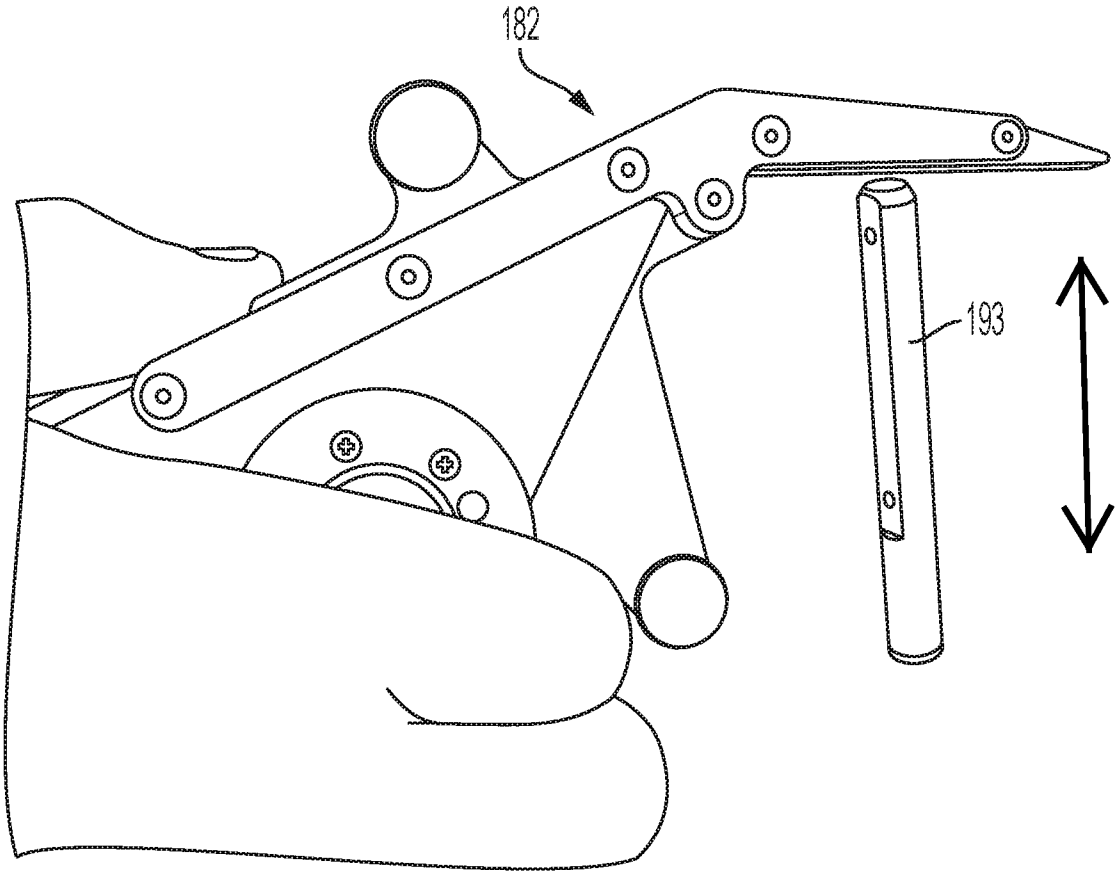


FIG. 28

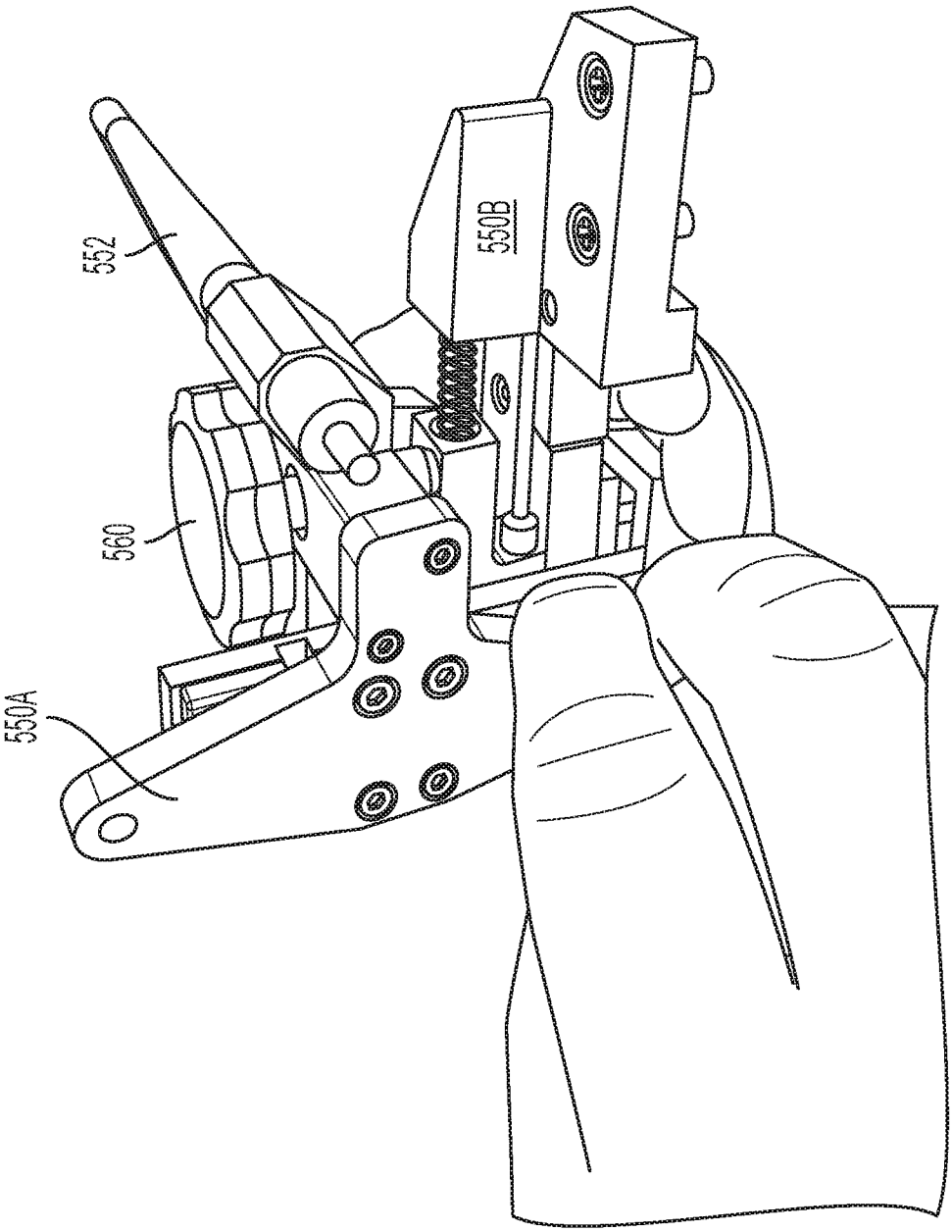


FIG. 29

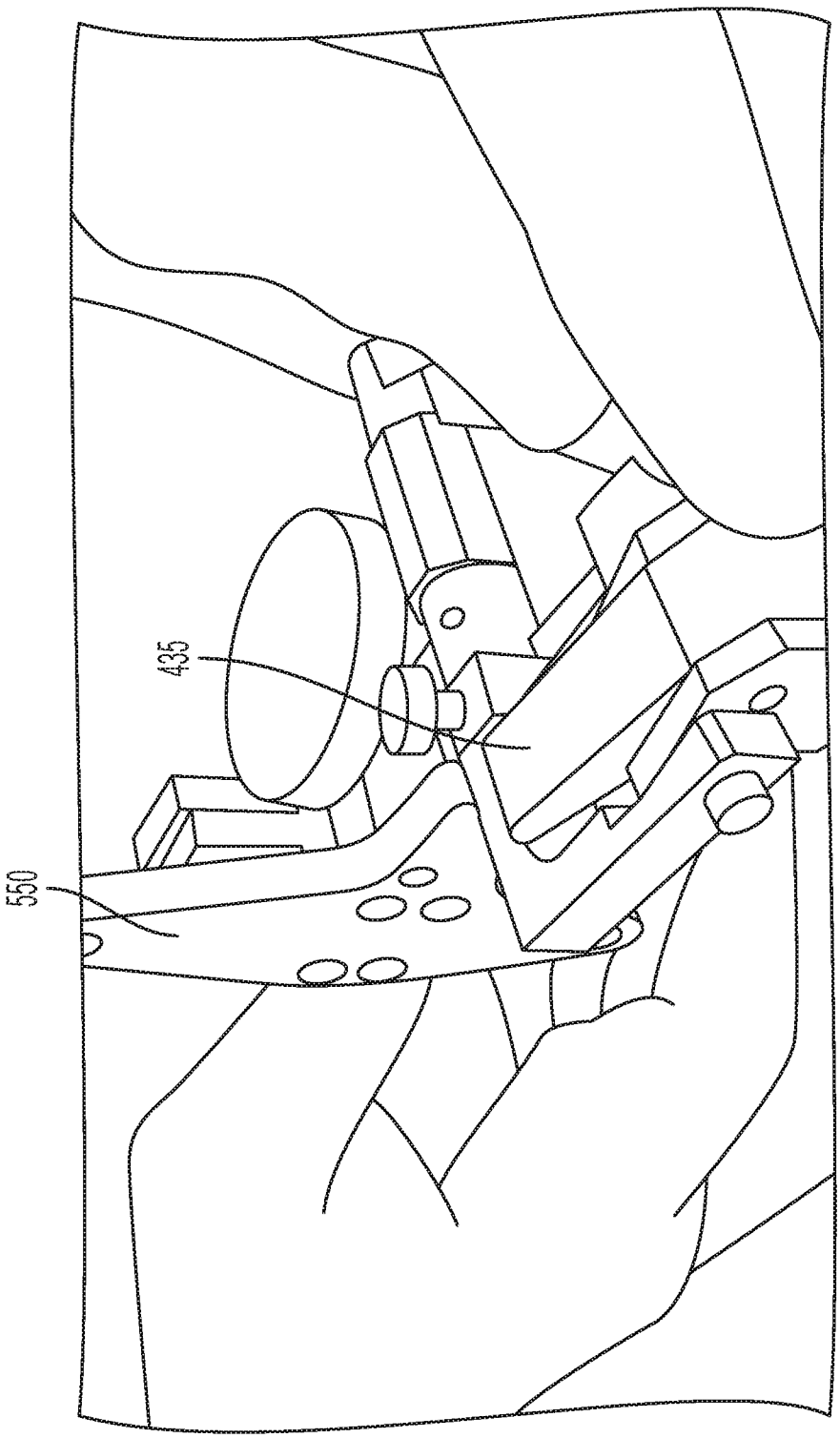


FIG. 30

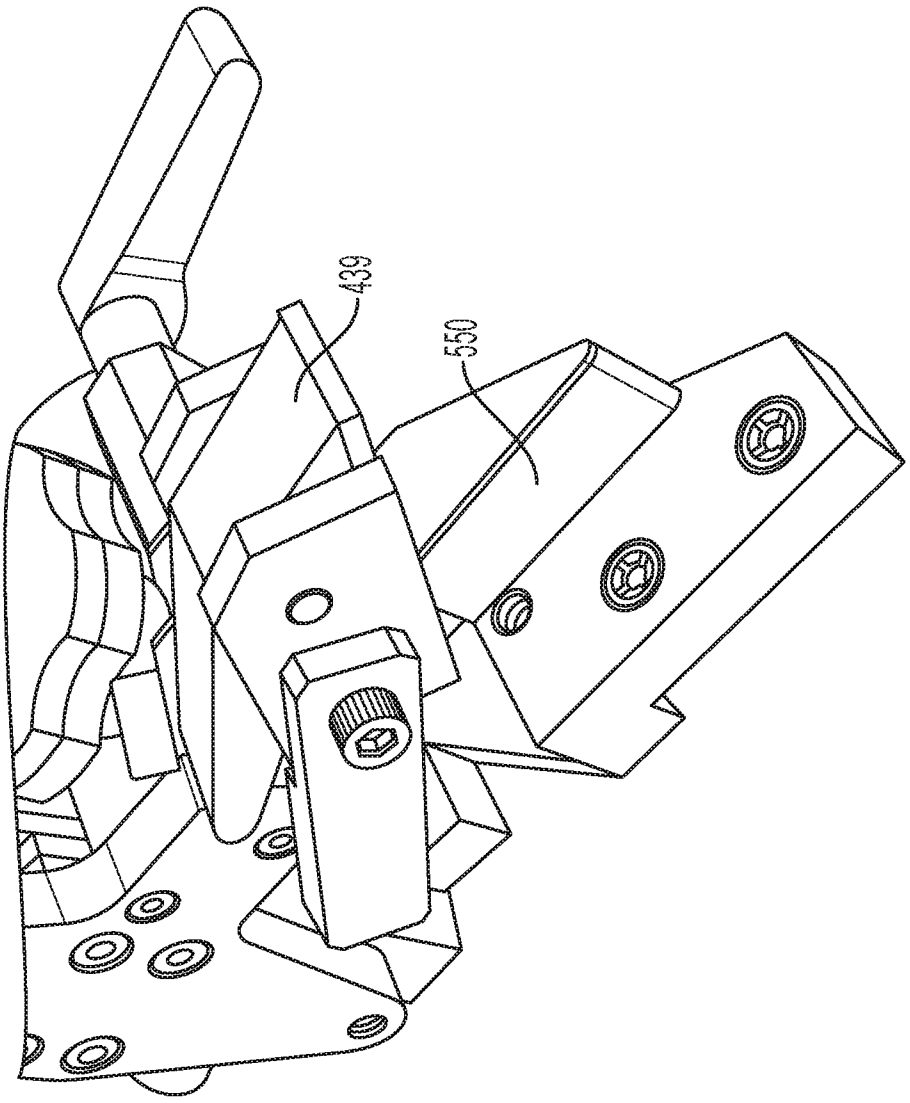


FIG. 31

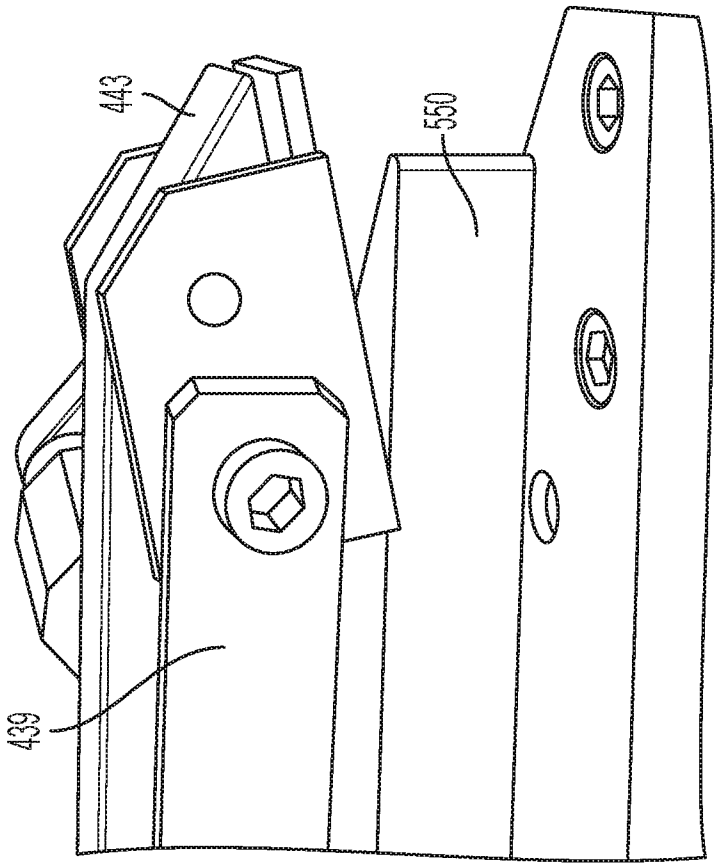


FIG. 32A

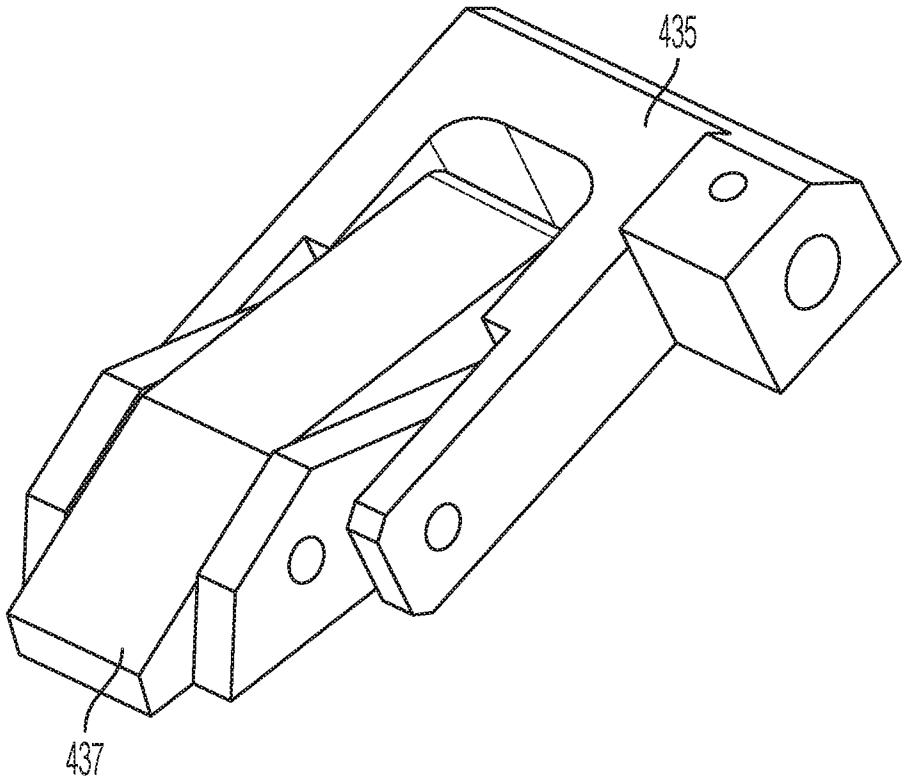


FIG. 32B

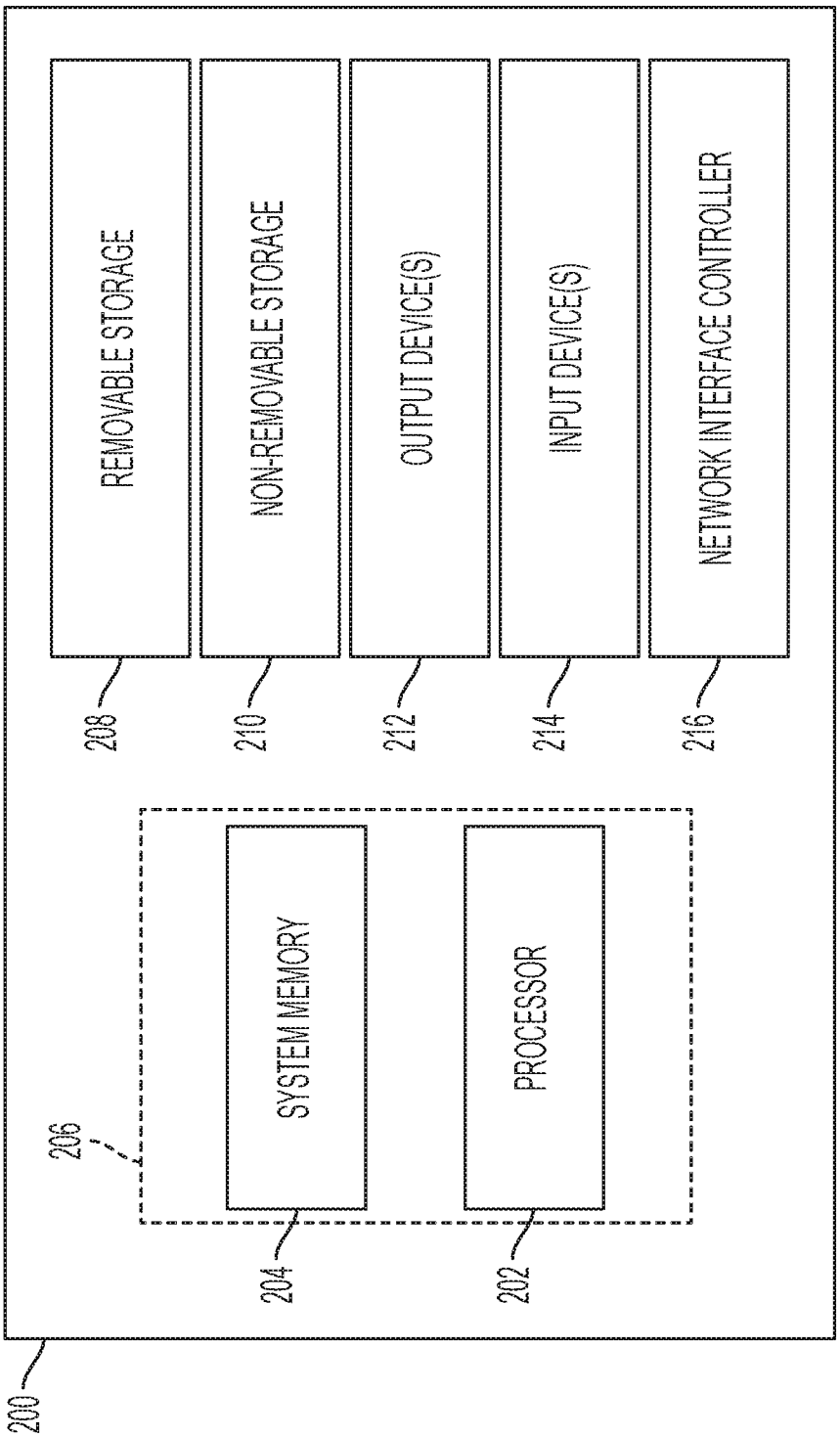

200
206
SYSTEM MEMORY
PROCESSOR
204
202
REMOVABLE STORAGE
NON-REMOVABLE STORAGE
OUTPUT DEVICE(S)
INPUT DEVICE(S)
NETWORK INTERFACE CONTROLLER
208
210
212
214
216

FIG. 33

INTERNATIONAL SEARCH REPORT

International application No.
PCT/US20/45233

A. CLASSIFICATION OF SUBJECT MATTER

IPC - G01N 1/06, 1/04, 1/00, 1/36, 1/28, 35/00 (2020.01)

CPC - G01N 1/06, 1/04, 1/00, 1/36, 1/28, 35/00009, 35/00732, 35/00, 2001/061, 2001/065, 2001/066; Y10T 83/6492

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)
See Search History document

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched
See Search History document

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)
See Search History document

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X --- Y --- A	US 2018/0080856 A1 (PRESIDENT AND FELLOWS OF HARVARD COLLEGE) 22 March 2018 (22.03.2018); abstract; figures 11A-17; paragraphs [0080, 0123, 0136-0144, 0160-0165]	1-2, 5-7, 13-14, 21-25, 36-40 & 59-63 --- 3-4, 8, 15 --- 9-12 & 41-43
Y	JP 3859508 B2 (KOBE STEEL LTD.) 20 December 2006 (20.12.2006); paragraph [0011]	3-4
Y	US 2014/0158883 A1 (CALIFORNIA INSTITUTE OF TECHNOLOGY) 12 June 2014 (12.06.2014); abstract; paragraph [0073]	8
Y	RICE, E. "Benefits of Using Encoders to Improve Step Motor System Performance"; Publication [online]. 01 June 2018 [retrieved 25 November 2020]. Retrieved from the Internet: <URL: https://www.techbriefs.com/component/content/article/tb/supplements/md/features/articles/28998>; entire document.	15
A	US 2017/0220775 A1 (DAKO DENMARK A/S) 03 August 2017 (03.08.2017); abstract; paragraph [0013]	1-15, 21-25, 36-43, 59-63

☐ Further documents are listed in the continuation of Box C. ☐ See patent family annex.

* Special categories of cited documents:
"A" document defining the general state of the art which is not considered to be of particular relevance
"D" document cited by the applicant in the international application
"E" earlier application or patent but published on or after the international filing date
"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)
"O" document referring to an oral disclosure, use, exhibition or other means
"P" document published prior to the international filing date but later than the priority date claimed
"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention
"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone
"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art
"&" document member of the same patent family

Date of the actual completion of the international search	Date of mailing of the international search report
25 November 2020 (25.11.2020)	07 JAN 2021
Name and mailing address of the ISA/US Mail Stop PCT, Attn: ISA/US, Commissioner for Patents P.O. Box 1450, Alexandria, Virginia 22313-1450 Facsimile No. 571-273-8300	Authorized officer Shane Thomas Telephone No. PCT Helpdesk: 571-272-4300

INTERNATIONAL SEARCH REPORT

International application No.
PCT/US20/45233

Box No. II Observations where certain claims were found unsearchable (Continuation of item 2 of first sheet)

This international search report has not been established in respect of certain claims under Article 17(2)(a) for the following reasons:

1. ☐ Claims Nos.:
because they relate to subject matter not required to be searched by this Authority, namely:

2. ☐ Claims Nos.:
because they relate to parts of the international application that do not comply with the prescribed requirements to such an extent that no meaningful international search can be carried out, specifically:

3. ☐ Claims Nos.:
because they are dependent claims and are not drafted in accordance with the second and third sentences of Rule 6.4(a).

Box No. III Observations where unity of invention is lacking (Continuation of item 3 of first sheet)

This International Searching Authority found multiple inventions in this international application, as follows:

See Extra Sheet

1. ☐ As all required additional search fees were timely paid by the applicant, this international search report covers all searchable claims.

2. ☐ As all searchable claims could be searched without effort justifying additional fees, this Authority did not invite payment of additional fees.

3. ☐ As only some of the required additional search fees were timely paid by the applicant, this international search report covers only those claims for which fees were paid, specifically claims Nos.:

4. ☒ No required additional search fees were timely paid by the applicant. Consequently, this international search report is restricted to the invention first mentioned in the claims; it is covered by claims Nos.:
Group I: Claims 1-15, 21-25, 36-43, 59-63

Remark on Protest

☐ The additional search fees were accompanied by the applicant's protest and, where applicable, the payment of a protest fee.

☐ The additional search fees were accompanied by the applicant's protest but the applicable protest fee was not paid within the time limit specified in the invitation.

☐ No protest accompanied the payment of additional search fees.

INTERNATIONAL SEARCH REPORT

International application No.

PCT/US20/45233

-***-Continued from Box No. III Observations where unity of invention is lacking-***-

This application contains the following inventions or groups of inventions which are not so linked as to form a single general inventive concept under PCT Rule 13.1. In order for all inventions to be examined, the appropriate additional examination fees must be paid.

Group I: Claims 1-15, 21-25, 36-43, 59-63 are directed towards a system for sectioning resin-embedded cells and tissue with an ultramicrotome.
Group II: Claims 16-20 are directed towards a knife stage adapter comprising: a base portion, platform, and adapter edge.
Group III: Claims 26-29 are directed towards a coverslip vise system.
Group IV: Claims 30-35 are directed towards a scanning electron microscope stub holder.
Group V: Claim 44-58 are directed towards a method of transferring samples from an ultramicrotome comprising: a coated Kapton polyimide tape.

The inventions listed as Groups I-V do not relate to a single general inventive concept under PCT Rule 13.1 because, under PCT Rule 13.2, they lack the same or corresponding special technical features for the following reasons:

The special technical features of Group I are at least a modular reel-to-reel assembly comprising a reel-to-reel frame that connects to an upper region of a knife-stage used with the ultramicrotome, wherein the upper region of the knife-stage is adapted to connect the modular reel-to-reel assembly to the ultramicrotome, and wherein the modular reel-to-reel assembly further comprises: a feeder reel connected to a length of tape, wherein the feeder reel is rotatably coupled to the reel-to-reel frame; a take-up reel connected to the reel-to-reel frame and receiving the tape across the reel-to- reel frame; a feeder motor that drives rotation of the feeder reel; a take-up motor that drives rotation of the take-up reel; at least one cantilever arm position sensor connected to the modular reel-to-reel assembly and/or the ultramicrotome; and at least one electronic control unit controlling respective speeds of the feeder motor and the take-up motor, wherein the electronic control unit adjusts the respective speeds according to a cantilever arm position signals received from the at least one cantilever arm position sensor, which are not present in Groups II-V.

The special technical features of Group II are at least a base portion adapted to bolt into an upper region of a ultramicrotome knife-stage; a platform region receiving at least one adjustment screw attaching the platform region to the base portion at a plurality of selectable heights; an adapter edge configured to receive a plurality of specimen substrate holders in a modular connection, which are not present in Groups I or III-V.

The special technical features of Group III are at least a coverslip vise system for receiving a cut sample from an ultramicrotome, comprising: a knife stage adapter configured for removable attachment to a knife carrier on an ultramicrotome, wherein the knife stage adapter defines X, Y, and Z axes relative to the ultramicrotome; a vise attached to the knife stage adapter, wherein the vise is configured to hold a polymer coverslip in a position to receive the cut resin sections thereon; and a lever arm connected to the knife stage adapter and configured for arcuate movement about the knife stage adapter to position an end of the vise at selectable points along the Z axis and adjacent a specimen block on the ultramicrotome, which are not present in Groups I, II, IV, or V.

The special technical features of Group IV are at least a scanning electron microscope stub holder for use with an ultramicrotome to receive resin sections thereon, comprising: a substrate holder body defining a passageway with a first opening at one end of the holder body and a second opening extending from the first opening toward a second end of the holder body; a trigger that fits within the second opening, said trigger being actuated by a spring connected to the trigger and the holder body; a removable surface block configured to fit within the first opening of the holder body, said removable surface block held in place by the trigger biased by the spring, which are not present in Groups I-III or V.

The special technical features of Group V are at least a method of transferring thin, semi-thin, semi-thick, and thick resin sections from the edge of a blade connected to a knife boat, connected to a knife-stage connected to an ultramicrotome, to a coated Kapton® polyimide tape, the method comprising: positioning a specimen block onto a nib of a specimen block chuck of the ultramicrotome; connecting a length of a coated Kapton® polyimide tape between a feeder reel and a take-up reel connected to a reel to reel frame; advancing the length of the coated Kapton® polyimide tape from the feeder reel to the take-up reel; positioning the coated Kapton® polyimide tape between the edge of a 35°- 45° angle, 2-8 mm diamond blade and water in the knife boat; receiving cut resin sections from the water onto the coated Kapton® polyimide tape; and advancing the coated Kapton® polyimide tape, which are not present in Groups I-IV.

The common technical features are a system for sectioning resin-embedded cells and/or tissues with an ultramicrotome comprising: connecting a length of a tape between a feeder reel and a take-up reel connected to a reel to reel frame; a knife-stage used with the ultramicrotome, which are previously disclosed by US 2006/0008790 A1 to HAYWORTH, K et al. (hereinafter "HAYWORTH").

HAYWORTH disclosesa system for sectioning resin-embedded cells and/or tissues with an ultramicrotome (a system for sectioning resin embedded tissue with an ultramicrotome; paragraphs [0146]-[0148], [0154]) comprising: connecting a length of a tape between a feeder reel and a take-up reel connected to a reel to reel frame (302 to 304; figure 5A); a knife-stage used with the ultramicrotome (microtome knife 214; figure 4A; paragraph [0154]).

Since the common technical features are previously disclosed by the HAYWORTH reference, the common features are not special and so Groups I-V lack unity.