

[54] CONTROL SYSTEM FOR TORPEDOES

[75] Inventor: **Harvey M. Jensen**, State College, Pa.

[73] Assignee: **The United States of America as represented by the Secretary of the Navy**, Washington, D.C.

[22] Filed: **Feb. 26, 1960**

[21] Appl. No.: **11,384**

[52] U.S. Cl. **114/20 R; 340/3 R**

[51] Int. Cl. ... **F42b 19/10; F42b 19/01; F42b 19/06**

[58] Field of Search **114/20, 21.1, 21.2, 23, 114/25, 24; 340/1, 2, 3, 5, 6**

[56] **References Cited**

UNITED STATES PATENTS

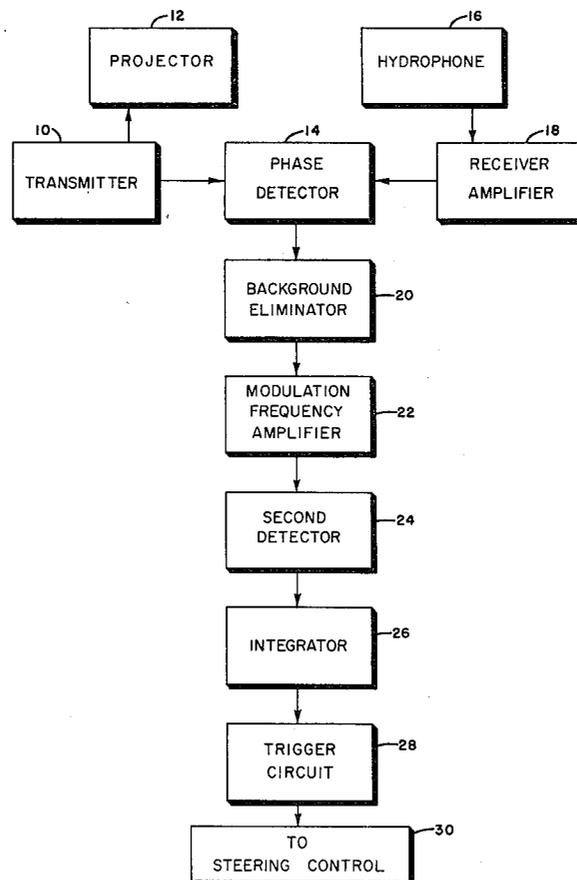
2,913,700 11/1959 Brody 340/1

Primary Examiner—Benjamin A. Borchelt
Assistant Examiner—Thomas H. Webb
Attorney, Agent, or Firm—R. S. Sciascia; Henry Hansen

EXEMPLARY CLAIM

1. In a detection system, the combination comprising: transmitter means capable of driving a projector with a continuous-acoustic signal; receiver means adapted to receive said signal transmitted by said transmitter; phase detection means capable of detecting the phase difference between said continuous transmitted signal and said received signal, and trigger means adapted to respond to phase differences produced by the characteristics of medium between said transmitter means and said receiver means.

6 Claims, 2 Drawing Figures



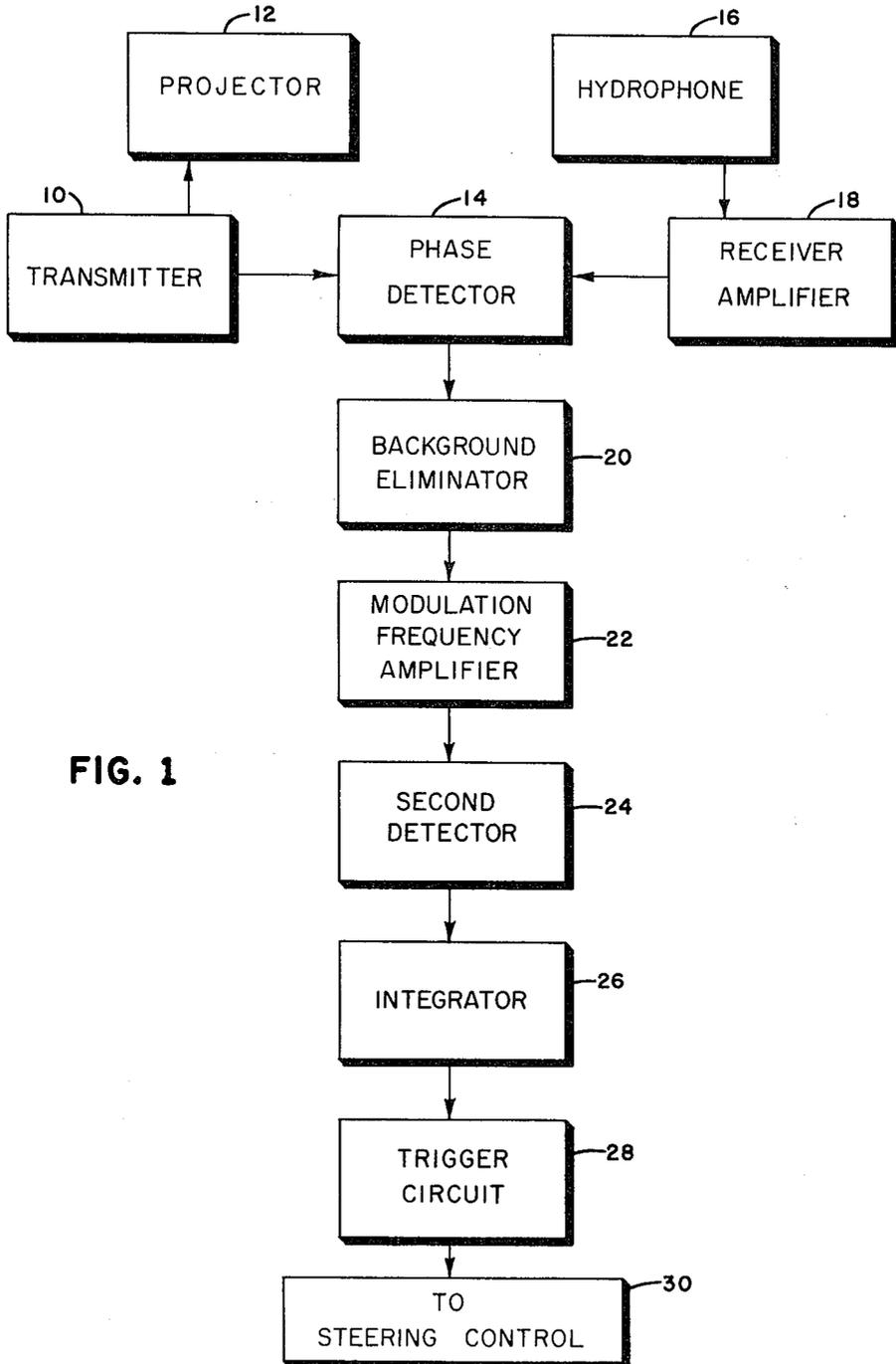


FIG. 1

HARVEY M. JENSEN
INVENTOR.

BY

W. E. Muller
ATTORNEYS

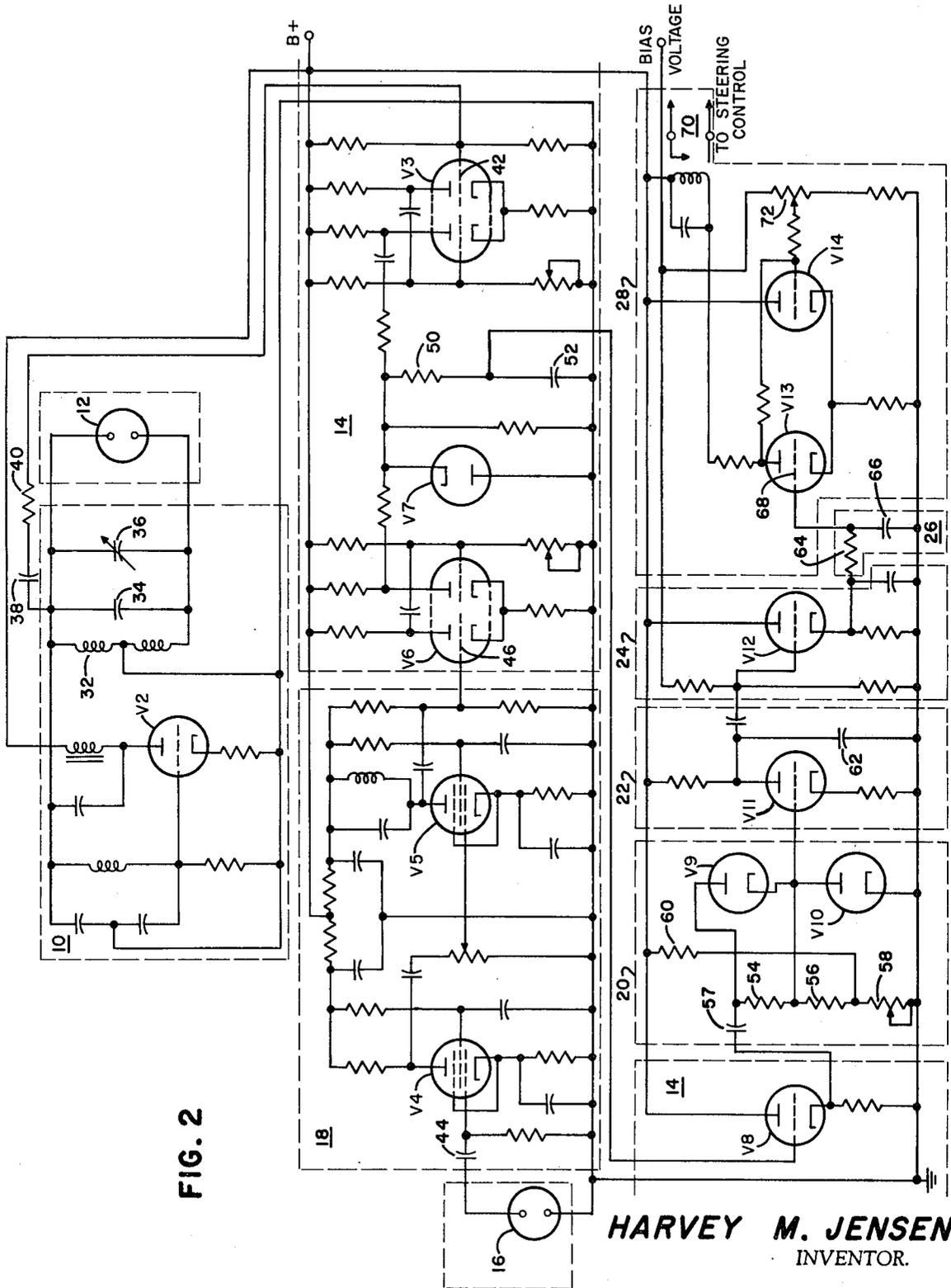


FIG. 2

HARVEY M. JENSEN
INVENTOR.

BY

V. E. Muller
ATTORNEYS

CONTROL SYSTEM FOR TORPEDOES

This invention relates to a control system for self-propelled torpedoes, and more particularly to a system adapted to guide the torpedo down the wake of a target vessel until it collides with the vessel.

Numerous systems are in existence for guiding self-propelled torpedoes to a target vessel. Some of these are acoustical in nature, depending upon the detection of the sound from the target vessel to actuate steering mechanisms. Other systems project acoustical vibrations to the target vessel and detect the reflective waves coming therefrom to actuate steering means designed to direct the torpedo to the target. The devices of the type described depend upon the clear detection of acoustical waves over long distances in the water, and the rejection of unwanted waves. The present invention depends upon the detection of the wake emanating from the target vessel and the actuation of a control mechanism to steer the self-propelled torpedo along the wake towards the target until it collides with it. This invention is designed to detect the wake by providing a device that will respond to a phase variation between a transmitted acoustical signal and a received signal caused by the effect of bubbles in the wake.

It is the object of this invention, therefore, to provide a wake detecting-guiding means for a self-propelled torpedo that will automatically guide the torpedo down the wake in the direction of the target vessel causing the torpedo to collide with it.

Another object of this invention is to provide a means whereby the wake of a vessel may be positively and surely detected.

Still another object of this invention is to provide an electronic phase-detecting device capable of detecting phase variation caused by minute bubbles in water.

Referring to the drawings:

FIG. 1 represents a block diagram of the system.

FIG. 2 indicates a schematic diagram of the blocks shown in FIG. 1, showing the electrical components and wiring.

Referring now to FIG. 1, transmitter 10 drives the projector 12 to emit acoustical vibrations to the water and at the same time, furnishes a comparison voltage to the phase detector 14 for a later comparison with the received signal. The hydrophone 16 receives, through the water, the transmitted signal which is amplified by receiver amplifier 18 and applied to the phase detector 14 for comparison with the transmitted signal. Phase detector 14 is of the conventional type such that the output is substantially a direct voltage, proportional to the phase angle between the transmitted and received signal. The output of phase detector 14 is introduced to background eliminator 20, also of the conventional type, designed to remove or suppress the phase angle fluctuation or phase modulation produced as a torpedo moves through the water outside of the wake. The phase modulation above a predetermined level is passed by the background eliminator 20 and amplified by conventional modulation-frequency amplifier 22; the output of which is applied to the second detector 24, which detects peak values of the phase modulation. The direct voltage of the second detector, proportional to the positive peaks appearing at its input, is passed into integrator 26, consisting of a conventional resistance-capacitance network having a time delay to prevent triggering upon a disturbance of very short duration. The integrator 26 is designed to operate so that

when a predetermined level of modulation in its input persists for a given duration, the trigger circuit 28 will be actuated. By this means, the circuit will not operate upon false signals, but is sensitive enough to respond to the wake signals received. The modified Schmitt trigger circuit 28, in turn, puts into operation steering control device 30 which programs the torpedo's rudder (not shown) to steer the torpedo down the wake until it collides with the target vessel.

In the present embodiment of this invention, the transducer head (not shown) is comprised of the projector 12 and the hydrophone 16 which consists of two barium titanate piezoelectric transducers (not shown) mounted in the forward portion of the torpedo. Although other transducers may be used, with appropriate modification, they must be sufficiently omnidirectional to permit direct transmission from the projector to the hydrophone. The electrical impedance of the transducer used is approximately represented by its capacitive reactance which is inversely proportional to the frequency. The equivalent capacitance of the transducer is about 1,200 micro-microfarads; hence, the reactance at a frequency of 27 kilocycles is 4,910 ohms. To achieve a sufficient signal-to-noise ratio, a projector current of about 50 milliamperes is necessary; thus, requiring a projector voltage of about 245 volts obtained by parallel tuning of the projector 12.

Referring now to FIG. 2, the primary function of transmitter 10 is to drive the projector 12 at the required frequency and voltage. This is accomplished by a modified Colpitts type oscillator operating in a parallel-tuned load. The load for the transmitter tube V_2 is comprised of a center-tapped toroid inductor 32, a fixed capacitor 34, a trimmer capacitor 36, and the projector 12 connected in parallel so that resonance is obtained at a frequency of 27 kilocycles.

Although the output of the projector is a fraction of a watt of acoustic power, it is sufficient for operation of the system. A reference voltage is taken from the transmitter through capacitor 38 and resistor 40 and is connected to the grid 42 of tube V_3 in phase detector 14. This tube presents a high impedance load and, hence, does not effect the resonance circuit appreciably.

The hydrophone 16 is connected through capacitor 44 to the receiver amplifier 18 comprised of vacuum tubes V_4 and V_5 . The receiver amplifier is a two-stage tuned amplifier of conventional design for obtaining a voltage suitable for the operation of the phase detector. Sufficient gain of, for example, 50 to 80 decibels is provided to maintain an adequate phase-detector input for a low-hydrophone output signal. With such an arrangement, phase detection is relatively unaffected by variations of signal amplitude. The bandwidth of the amplifier at the 3-decibel-down points is preferably 300 cycles per second, which is sufficiently narrow to provide an adequate signal-to-noise ratio, but wide enough to pass the carrier side band required for detection of the phase modulation. The phase detector 14, comprised of vacuum tubes V_6 , V_7 , V_3 , and V_8 , produces a direct voltage which varies in proportion to the phase angle between the receiver amplifier output voltage and the transmitter voltage input to the phase detector. The output signal of the receiver amplifier 18 is connected to the grid 46 of vacuum tube V_6 and the reference signal from the transmitter is connected to grid 42 of vacuum tube V_3 . The transmitter signal is subsequently

constant in amplitude and phase, and provides a reference by which phase variation of the signal from the receiver amplifier may be detected. For example, when a phase modulation at a rate of 100 cycles per second occurs, the detector output from the cathode follower of tube V_8 will be a direct voltage with a 100 cycle per second alternating voltage superimposed upon it.

Vacuum tubes V_6 and V_3 are cathode-coupled clippers which produce square-wave output signals of nearly constant amplitude with inputs in a range of about 2 to 100 volts. Addition to the two square-wave output signals of tubes V_6 and V_3 , rectification of the combined signals by tubes V_7 , and integration thereof by the resistance-capacitance circuit, 50 and 52, provide a direct voltage that is proportional to the phase angle between the two input voltages. The direct voltage is applied to the cathode-follower tube V_8 which gives the proper impedance match for supplying the output signal of the phase detector 14 to the background eliminator 20.

The background eliminator 20 is of a conventional type comprised of resistors 54 and 56, capacitor 57, a voltage divider network consisting of resistors 58 and 60, and two diodes, V_9 and V_{10} . The direct voltage component of the phase detector output is blocked by capacitor 57, allowing only the alternating voltage component to pass. Outside of the wake, this alternating component has a small amplitude and is known as background noise. When a wake is encountered, the amplitude of the component is substantially increased. To obtain a greater signal-to-background ratio at the trigger input, a background eliminator 20 is provided to eliminate the background noise. Variable resistor 58 provides a variable and adjustable cutoff level. Resistor 58 may be adjusted to provide 0 to 5.5 volts wherein an increase in the voltage will raise the level of modulation to be eliminated.

Signal variations above the previously mentioned background noise which are passed by the background eliminator 20, are amplified by the conventional modulation frequency amplifier 22 comprised of vacuum tube V_{11} . The modulation frequency amplifier should have a frequency response which eliminates low and high frequency components. Capacitor 62 eliminates any of the carrier voltage (27 kilocycles) which may still be present at the output of the modulation-frequency amplifier 22. The bandwidth of the modulation-frequency amplifier is approximately 2 kilocycles with the 3-decibel-down points at approximately 40 cycles per second and 2,000 cycles per second.

The second detector 24, comprised of vacuum tube V_{12} and the conventional integrator 26, consisting of resistor 64 and capacitor 66, produces a direct voltage output proportional to the positive peaks occurring at the grid of tube V_{12} . The integrator is a resistance-capacitance network with a time constant of about 0.1 seconds and is so designed to prevent triggering on a disturbance of very short duration. The output signal of the integrator is applied to the grid 68 of the tube V_{13} . The trigger circuit 28 is a modified Schmitt trigger comprised of tubes V_{13} , V_{14} , and relay 70 and adapted to provide positive operation of relay 70, when the input voltage to the trigger circuit 28 exceeds a predetermined level. The triggering level of the trigger circuit is rendered adjustable by the means of a potentiometer 72. Relay 70 is used to initiate steering of the torpedo.

A steering control system 30, actuated by relay 70, automatically guides the torpedo down the wake in the direction of the target until it collides with it. Although various well known means employing servomechanism techniques could be devised to cause the torpedo to proceed along the wake towards the target, the present embodiment of this invention, a simple steering control system, is used to demonstrate the wake detection and guidance capability of this system. At the first encounter of the wake, relay 70 initiates full rudder deflection in a preset direction to cause the torpedo to turn in the direction of the target vessel until it again encounters the wake. A turn in the opposite direction is then initiated, and in this fashion, the torpedo proceeds along the wake in a weaving course.

A steering control system (not shown) of a type well known in the art is comprised of two auxiliary relays and a motor-driven timer with four cam-operated switches. At each wake encounter, relay 70 is kept energized for a sufficient time to avoid more than one steering operation while passing through the wake. The cam-operated switches alternately connect port and starboard rudder solenoids at successive wake encounters, causing the torpedo to steer a weaving course down the wake until it strikes the target vessel.

While the present invention has been described in its preferred embodiment, it is realized that modifications may be made, and it is desired that it be understood that no limitations upon the invention are intended other than may be imposed by the scope of the appended claims.

Having now disclosed our invention, what we claim as new and desire to secure by Letters Patent of the United States is:

1. In a detection system, the combination comprising: transmitter means capable of driving a projector with a continuous-acoustic signal, receiver means adapted to receive said signal transmitted by said transmitter; phase detection means capable of detecting the phase difference between said continuous transmitted signal and said received signal, and trigger means adapted to respond to phase differences produced by the characteristics of medium between said transmitter means and said receiver means.

2. In a wake-detection system for torpedoes, the combination comprising: a projector adapted to transmit acoustic signals; a transmitter for driving said projector; a hydrophone disposed adjacent to said projector for receiving said projector's acoustic signals; first amplifying means connected to said hydrophone adapted to amplify the output signal of said hydrophone; phase-detector means capable of receiving the output signal of said amplifier means and the output signal from said transmitter, whereby said signals are combined and rectified to produce a phase-detector output signal proportional to the phase difference between said transmitter and amplifier means output signals; blocking means for receiving said phase-detector output signal adapted to block variations of said signal below a predetermined level; second amplifier means capable of amplifying the output signal of said blocking means above a predetermined level; a trigger circuit adapted for receiving and being actuated by said output signal of said blocking means; and rudder-control means actuated by said trigger circuit adapted to control the direction of travel of said torpedo.

5

3. The combination as claimed in claim 2 in which said second amplifier means is comprised of a detector means and an integrator means.

4. The combination as claimed in claim 2 in which said projector means and said hydrophone is each comprised of a piezoelectric transducer.

5. The combination as claimed in claim 4 in which

6

said transmitting means is comprised of a Colpitts type oscillator having a parallel load.

6. The combination as claimed in claim 5 in which said trigger means is comprised of a Schmitt trigger-type circuit adapted to operate when its input voltage exceeds a preset level.

* * * * *

10

15

20

25

30

35

40

45

50

55

60

65