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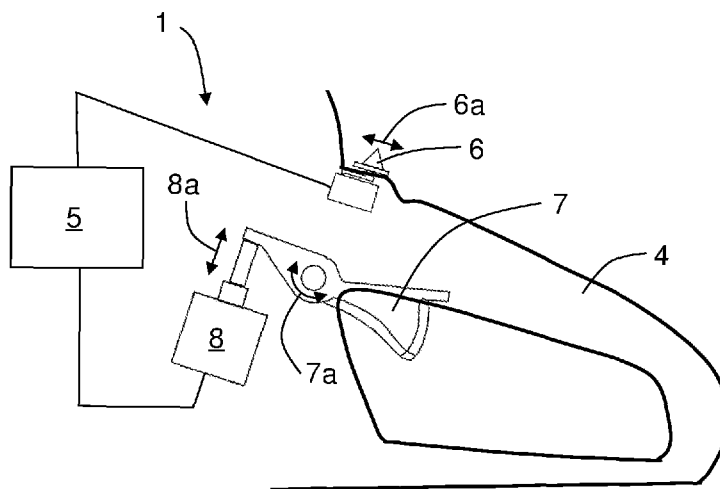


Fig. 2

(57) Abstract: Described herein is a control assembly (1) for selectively controlling actuation of an electric motor arranged to power a hand-held power tool (3) based on combined performance of two dissimilar operator actions and a hand-held power tool (3) comprising such a control assembly (1). A switch member (6) may be closed responsive to an enabling action comprising a first of the two dissimilar operator actions. A throttle control member (7) is configured to become operable responsive to actuation of the throttle control member (7) past a first movement threshold (REF\_LATCH), i.e. a second dissimilar operator action, while the switch member (6) is in the actuated state. The throttle control member (7) remains repeatedly operable above a second movement threshold (REF\_RELEASE), even if the switch member (6) is opened. Actuation of the throttle control member (7) to below the second movement threshold (REF\_RELEASE) will render the throttle control member (7) non-operable until renewed combined performance of the first and second dissimilar operator actions.



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## TRIGGER LOCKOUT WITH DISSIMILAR ACTIONS

Technical field

[0001] The present invention relates generally to a control assembly for selectively controlling actuation of an electric motor arranged to power a working assembly of a hand-held power tool and a hand-held power tool comprising such a control assembly.

Background art

[0002] Hand-held power tools are often used to perform tasks that inherently require such hand-held power tools to be mobile. Emissions, such as e.g. noise and/or pollutants, generated by such hand-held power tools often make electric motors a preferred choice to power such tools.

[0003] However, due to the near instantaneous response time and immediate high torque provided by electric motors upon being actuated, e.g. via a throttling mechanism or trigger, it will normally be prudent to provide some kind of safety mechanism or interlock to ensure that inadvertent actuation of the working assembly is inhibited.

[0004] Thus, prior art hand-held power tools are sometimes provided with a throttle lockout mechanism. Such a throttle lockout mechanism is often provided on a handle portion of the hand-held power tool and must be actuated, e.g. pressed or pushed, in order to allow the throttling mechanism or trigger to be actuated.

[0005] However, an operator may sometimes be able to grasp the handle portion compressing both the throttle lockout mechanism and the throttling mechanism or trigger essentially at the same time, thereby inadvertently powering the working assembly. Thus, addressing this issue is desirable.

[0006] Alternatively, some prior art hand-held power tools are provided with a trigger interlock operator, such as a side-button, that may be moved between a guard position where it resists pressure to move the trigger and at least one armed

position, in which position it allows the trigger to be pressed. This type of interlock operators are commonly arranged to return to the guard position each time the trigger is released making the tool cumbersome and unpleasant to operate. Thus, addressing this issue is also desirable.

### Summary of invention

[0007] An object of the present invention is to improve the safety and operability of hand-held power tools.

[0008] This is provided by a control assembly for selectively controlling actuation of an electric motor arranged to power a working assembly of a hand-held power tool, the control assembly being configured to provide the selective control based on combined performance of two dissimilar operator actions, the control assembly comprising: an electronic control unit; and a switch member configured to be operable to an actuated state responsive to an enabling action comprising a first of the two dissimilar operator actions; and a throttle control member configured to become operable responsive to actuation of the throttle control member past a first movement threshold while the switch member is in the actuated state, and wherein actuation of the throttle control member past the first movement threshold comprises a second of the two dissimilar operator actions, and wherein the throttle control member is configured to remain repeatedly operable responsive to actuation of the throttle control member above a second movement threshold located below the first movement threshold, even if the switch member is brought to a non-actuated state, and wherein actuation of the throttle control member to below the second movement threshold is configured to render the throttle control member non-operable until renewed combined performance of the first and second dissimilar operator actions.

[0009] In a further embodiment the throttle control member is configured to become operable responsive to actuation of the throttle control member to within a span past the first movement threshold and below a third movement threshold while the switch member is in the actuated state.

[0010] In a yet further embodiment the throttle control member is operable to be actuated between an unactuated position located below the second movement threshold and a maximum movement position located above the first movement threshold.

[0011] In a still further embodiment the throttle control member is biased towards the unactuated position.

[0012] In yet another embodiment the throttle control member is arranged to operate a potentiometer upon actuation thereof.

[0013] In an additional embodiment the throttle control member is arranged to provide haptic operator feedback by differentiated resistance to movement above and below the first movement threshold.

[0014] In still another embodiment the electronic control unit is arranged to control the operation of the electric motor starting at zero revolutions per minute responsive to actuation of the throttle control member past the first movement threshold while the switch member is in the actuated state and up to a maximum available revolutions per minute responsive to actuation of the throttle control member towards the maximum movement position.

[0015] In a further additional embodiment the first, second and/or third movement thresholds are defined by potentiometer output values corresponding to predefined amounts of actuation of the throttle control member.

[0016] In another embodiment the span past the first movement threshold and below the third movement threshold is defined by the corresponding potentiometer output values.

[0017] In one particular embodiment the span past the first movement threshold and below the third movement threshold is between 5 and 15 percent of a 100 percent potentiometer value corresponding to the maximum movement position.

[0018] In another alternative embodiment the span past the first movement threshold and below the third movement threshold is between 8 and 13 percent of

a 100 percent potentiometer value corresponding to the maximum movement position.

[0019] According to a further embodiment is also envisaged a hand-held power tool comprising a control assembly according to any one of the above embodiments.

[0020] Furthermore, here envisaged is an embodiment where a hand-held power, as above, is at least one of: a chainsaw; a trimmer; an edger; a mower; a blower or the like.

[0021] The above embodiments have the beneficial effects that: safety and operability of hand-held power tools is improved; a throttle member of hand-held power tools may be repeatedly cycled, without requiring the operator to undertake potentially cumbersome renewed combined performance of first and second dissimilar operator actions; a limited number of mechanical components are required reducing the risk of mechanical failures; cost of the control assembly can be contained whilst ensuring safe and reliable operation.

#### Brief description of drawings

[0022] The invention is now described, by way of example, with reference to the accompanying drawings, in which:

[0023] Fig. 1 illustrates schematically a side view of a chainsaw as an example of a hand-held power tool according to an example embodiment;

[0024] Fig. 2 illustrates schematically a partially cutaway side view of rear handle of a chainsaw comprising a control assembly according to an example embodiment;

[0025] Figs. 3a-c illustrates schematically an example of a control assembly logic of a control assembly according to an example embodiment.

### Description of embodiments

[0026] In the following will be described some example embodiments for a control assembly 1 for selectively controlling actuation of an electric motor, not shown, arranged to power a working assembly 2 of a hand-held power tool 3, such as e.g. a chainsaw, as illustrated schematically in figure 1. It should be appreciated that the chainsaw is merely one example of a hand-held power tool 3 that includes a working assembly 2, such as the chain and guide bar of the chainsaw, which working assembly 2 may require or benefit from employing one of the example control assembly 1 embodiments described in the following. Thus, the following example embodiments could also be practiced in connection with other types of hand-held power tools 3 that may include working assemblies 2 of various kind.

[0027] The control assembly 1, which is configured to provide the selective control based on combined performance of two dissimilar operator actions, will be described more fully with reference to the accompanying drawings, in which some, but not all example embodiments are shown. Like reference numerals refer to like elements throughout.

[0028] The requirement for combined performance of two dissimilar operator actions in order to actuate the electric motor is provided for in order to ensure that an operator is exhibiting positive control of the hand-held power tool 3.

[0029] The hand-held power tool 3 may include an electric power source, such as e.g. a battery, or a corded connection to a mains power outlet (not shown), for supplying the electric motor to power the working assembly 2.

[0030] Illustrated schematically in figure 2 is a partially cutaway side view of rear handle 4 of a chainsaw 3 comprising such a control assembly 1. The control assembly 1 comprises an electronic control unit 5 and a switch member 6 configured to be operable, e.g. in the direction of arrow 6a, to an actuated state responsive to an enabling action comprising a first of the two dissimilar operator actions.

[0031] In a first example embodiment, a throttle control member 7 of the control assembly is also arranged at the rear handle 4 and configured to become operable responsive to actuation of the throttle control member 7, e.g. around a pivot according to arrow 7a, past a first movement threshold REF\_LATCH while the switch member 6 is in the actuated state. Actuation of the throttle control member 7 past the first movement threshold REF\_LATCH comprises a second of the two dissimilar operator actions.

[0032] The throttle control member 7 may be embodied as a trigger, lever, button or other such member that is configured to cause the electric motor to turn at a selective rotational speed when actuated. The term “throttle control member”, as used herein, should be understood to represent any actuator that is capable of being operated by a hand or finger of an operator.

[0033] The throttle control member 7 is configured to remain repeatedly operable responsive to actuation of the throttle control member 7 above a second movement threshold REF\_RELEASE located below the first movement threshold REF\_LATCH, even if the switch member 6 is brought to a non-actuated state. Hereby is ensured that the throttle 7 may be repeatedly cycled, without requiring the operator to undertake potentially cumbersome renewed combined performance of the first and second dissimilar operator actions.

[0034] Actuation of the throttle control member 7 to below the second movement threshold REF\_RELEASE is configured to render the throttle control member 7 non-operable until renewed combined performance of the first and second dissimilar operator actions.

[0035] In another example embodiment, in addition to what is described for the first embodiment above, the throttle control member 7 is configured to become operable responsive to actuation of the throttle control member 7 to within a span past the first movement threshold REF\_LATCH and below a third movement threshold REF\_MAX while the switch member 6 is in the actuated state.

[0036] In a further example embodiment, in addition to what is described for the embodiments above, the throttle control member 7 is operable to be actuated between an unactuated position, i.e. in which the throttle control member 7 protrudes fully from the rear handle 4, located below the second movement threshold REF\_RELEASE and a maximum movement position, i.e. in which the throttle control member 7 is pressed fully towards the rear handle 4, located above the first movement threshold REF\_LATCH. The throttle control member 7 is suitably biased towards the unactuated position, such that it will return to the unactuated position when released. Such biasing is suitably performed using a return spring (not shown) in a manner well known to the skilled person. Thus, such a return spring will ensure that the throttle control member 7 is brought to below the second movement threshold REF\_RELEASE such that the throttle control member 7 is rendered non-operable until renewed combined performance of the first and second dissimilar operator actions.

[0037] In some cases, the physical position of the throttle control member 7 may be allowed to be changed whether or not the first dissimilar operator action is performed. Alternatively, the physical position of the throttle control member 7 may be inhibited to change from the unactuated position until the first dissimilar operator action is performed.

[0038] In still further example embodiments the electronic control unit 5 is arranged to control the operation of the electric motor starting at zero revolutions per minute responsive to actuation of the throttle control member 7 past the first movement threshold REF\_LATCH while the switch member 6 is in the actuated state and up to a maximum available revolutions per minute responsive to actuation of the throttle control member 7 towards the maximum movement position.

[0039] In some further example embodiments, in addition to what is described for the embodiments above, the throttle control member 7 is arranged to provide haptic operator feedback by differentiated resistance to movement above and below the first movement threshold REF\_LATCH.

[0040] In still further example embodiments, in addition to what is described for the embodiments above, the throttle control member 7 is arranged to operate a potentiometer 8 upon actuation thereof. In such embodiments, the first REF\_LATCH, second REF\_RELEASE and/or third REF\_MAX movement thresholds are suitably defined by potentiometer 8 output values corresponding to predefined amounts of actuation of the throttle control member 7. For embodiments where the throttle control member 7 is configured to become operable responsive to actuation of the throttle control member 7 to within a span, the span past the first movement threshold REF\_LATCH and below the third movement threshold REF\_MAX is suitably defined by the corresponding potentiometer 8 output values, e.g. voltage values.

[0041] In some such example embodiments where the throttle control member 7 is configured to become operable responsive to actuation of the throttle control member 7 to within a span, in addition to what is described for the embodiments above, the span past the first movement threshold REF\_LATCH and below the third movement threshold REF\_MAX is between 5 and 15 percent of a 100 percent potentiometer 8 value corresponding to the maximum movement position.

[0042] In yet other such example embodiments where the throttle control member 7 is configured to become operable responsive to actuation of the throttle control member 7 to within a span, in addition to what is described for the embodiments above, the span past the first movement threshold REF\_LATCH and below the third movement threshold REF\_MAX is between 8 and 13 percent of a 100 percent potentiometer value corresponding to the maximum movement position.

[0043] Further herein is also envisaged a hand-held power tool 3 comprising a control assembly 1 according to any one of the example embodiments described in the foregoing. In such embodiments, the hand-held power tool 3 is suitably at least one of: a chainsaw; a trimmer; an edger; a mower; a blower or the like.

[0044] A schematic example of a control assembly logic of a control assembly according to an example embodiment is illustrated in figures 3a-c. No component

values are given in the figures as these may be selected to suit the specific implementation chosen.

[0045] In figure 3a is schematically illustrated a setup of a potentiometer 8 arranged to be operated by throttle control member 7 upon actuation thereof to output a voltage RPM for selecting a desired revolutions per minute operation by the electric motor. Such a potentiometer 8 may be linear and arranged to move in the direction of arrow 8a under the influence of a pivoted throttle control member 7, as illustrated in figure 2, or alternatively rotational and arranged to rotate with the throttle control member 7 in the direction of arrow 7a of figure 2.

[0046] Figure 3b illustrates schematically a setup for generating selective predetermined reference voltages corresponding to desired potentiometer output voltages at the first REF\_LATCH, second REF\_RELEASE and third REF\_MAX movement thresholds. The ENABLE region, i.e. the span past the first movement threshold REF\_LATCH and below the third movement threshold REF\_MAX, is decided by the dividers formed by the resistors R1, R3, R4 and R9.

[0047] Figure 3c illustrates schematically a setup for generating an ENABLE signal responsive to performance of the two dissimilar operator actions. The RPM potentiometer 8 output voltage of figure 3a must be between the voltages REF\_LATCH and REF\_MAX, i.e. within the span past the first movement threshold REF\_LATCH and below the third movement threshold REF\_MAX, in order for the ENABLE output to be latched ON. The two comparators U2A and U2B work to SET the ENABLE output, but ONLY if  $\text{REF\_LATCH} < \text{RPM} < \text{REF\_MAX}$  and the SWITCH 6 signal is high. Then, and only then, will the ENABLE output be turned on. The ENABLE output is turned off only when  $\text{RPM} < \text{REF\_RELEASE}$ , i.e. when the potentiometer 8 output voltage RPM falls below the second movement threshold REF\_RELEASE.

[0048] Considering U2A and U1A, if the potentiometer 8 output voltage  $\text{RPM} < \text{REF\_MAX}$  and the SWITCH 6 is closed than START\_OK, and further considering U2B and U3A, if the potentiometer 8 output voltage  $\text{RPM} > \text{REF\_LATCH}$  and START\_OK then  $\text{SET} \rightarrow \text{ENABLE} = \text{On}$ . Conversely, considering U4A and U3B, if

the potentiometer 8 output voltage  $RPM < REF\_RELEASE$  then  $REL \rightarrow ENABLE = Off$ . U3B acts as an inverter only. U3C and U3D constitutes an ENABLE latch, the truth table of which is as follows.

SET	REL	ACTION
0	0	Not allowed
0	1	ENABLE = 1
1	0	ENABLE = 0
1	1	No change

[0049] Many modifications and other embodiments of the inventions set forth herein will come to mind to one skilled in the art to which these inventions pertain having the benefit of the teachings presented in the foregoing descriptions and the associated drawings. Therefore, it is to be understood that the inventions are not to be limited to the specific embodiments disclosed and that modifications and other embodiments are intended to be included within the scope of the appended claims. Moreover, although the foregoing descriptions and the associated drawings describe exemplary embodiments in the context of certain exemplary combinations of elements and/or functions, it should be appreciated that different combinations of elements and/or functions may be provided by alternative embodiments without departing from the scope of the appended claims. In this regard, for example, different combinations of elements and/or functions than those explicitly described above are also contemplated as may be set forth in some of the appended claims. In cases where advantages, benefits or solutions to problems are described herein, it should be appreciated that such advantages, benefits and/or solutions may be applicable to some example embodiments, but not necessarily all example embodiments. Thus, any advantages, benefits or solutions described herein should not be thought of as being critical, required or essential to all embodiments or to that which is claimed herein. Although specific

terms are employed herein, they are used in a generic and descriptive sense only and not for purposes of limitation.

CLAIMS

1. A control assembly (1) for selectively controlling actuation of an electric motor arranged to power a working assembly (2) of a hand-held power tool (3), the control assembly (1) being configured to provide the selective control based on combined performance of two dissimilar operator actions, the control assembly (1) comprising:

an electronic control unit (5); and

a switch member (6) configured to be operable to an actuated state responsive to an enabling action comprising a first of the two dissimilar operator actions; and

a throttle control member (7) configured to become operable responsive to actuation of the throttle control member (7) past a first movement threshold (REF\_LATCH) while the switch member (6) is in the actuated state, and wherein actuation of the throttle control member (7) past the first movement threshold (REF\_LATCH) comprises a second of the two dissimilar operator actions, and

wherein the throttle control member (7) is configured to remain repeatedly operable responsive to actuation of the throttle control member (7) above a second movement threshold (REF\_RELEASE) located below the first movement threshold (REF\_LATCH), even if the switch member (6) is brought to a non-actuated state, and

wherein actuation of the throttle control member (7) to below the second movement threshold (REF\_RELEASE) is configured to render the throttle control member (7) non-operable until renewed combined performance of the first and second dissimilar operator actions.

2. A control assembly (1) according to claim 1, wherein the throttle control member (7) is configured to become operable responsive to actuation of the throttle control member (7) to within a span past the first movement threshold (REF\_LATCH) and below a third movement threshold (REF\_MAX) while the switch member (6) is in the actuated state.

3. A control assembly (1) according to any one of claims 1 or 2, wherein the throttle control member (7) is operable to be actuated between an unactuated position located below the second movement threshold (REF\_RELEASE) and a maximum movement position located above the first movement threshold (REF\_LATCH).
4. A control assembly (1) according to claim 3, wherein the throttle control member (7) is biased towards the unactuated position.
5. A control assembly (1) according to any one of claims 1 to 4, wherein the throttle control member (7) is arranged to operate a potentiometer (8) upon actuation thereof.
6. A control assembly (1) according to any one of claims 1 to 5, wherein the throttle control member (7) is arranged to provide haptic operator feedback by differentiated resistance to movement above and below the first movement threshold (REF\_LATCH).
7. A control assembly (1) according to any one of claims 3 to 6, wherein the electronic control unit (5) is arranged to control the operation of the electric motor starting at zero revolutions per minute responsive to actuation of the throttle control member (7) past the first movement threshold (REF\_LATCH) while the switch member (6) is in the actuated state and up to a maximum available revolutions per minute responsive to actuation of the throttle control member (7) towards the maximum movement position.
8. A control assembly (1) according to any one of claims 5 to 7, wherein the first (REF\_LATCH), second (REF\_RELEASE) and/or third (REF\_MAX) movement thresholds are defined by potentiometer (8) output values corresponding to predefined amounts of actuation of the throttle control member (7).
9. A control assembly (1) according to claim 8, wherein the span past the first movement threshold (REF\_LATCH) and below the third movement threshold (REF\_MAX) is defined by the corresponding potentiometer (8) output values.

10. A control assembly (1) according to claim 9, wherein the span past the first movement threshold (REF\_LATCH) and below the third movement threshold (REF\_MAX) is between 5 and 15 percent of a 100 percent potentiometer (8) value corresponding to the maximum movement position.

11. A control assembly (1) according to claim 9, wherein the span past the first movement threshold (REF\_LATCH) and below the third movement threshold (REF\_MAX) is between 8 and 13 percent of a 100 percent potentiometer (8) value corresponding to the maximum movement position.

12. A hand-held power tool (3) comprising a control assembly (1) according to any one of claims 1-11.

13. A hand-held power tool (3) according to claim 12, wherein the hand-held power tool (3) is at least one of: a chainsaw; a trimmer; an edger; a mower; a blower or the like.

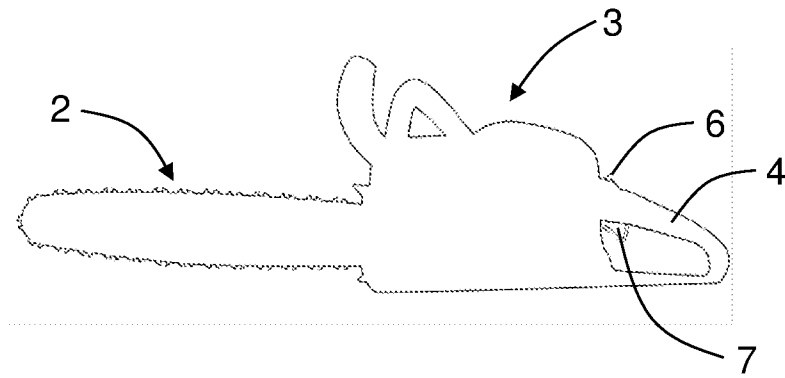


Fig.1

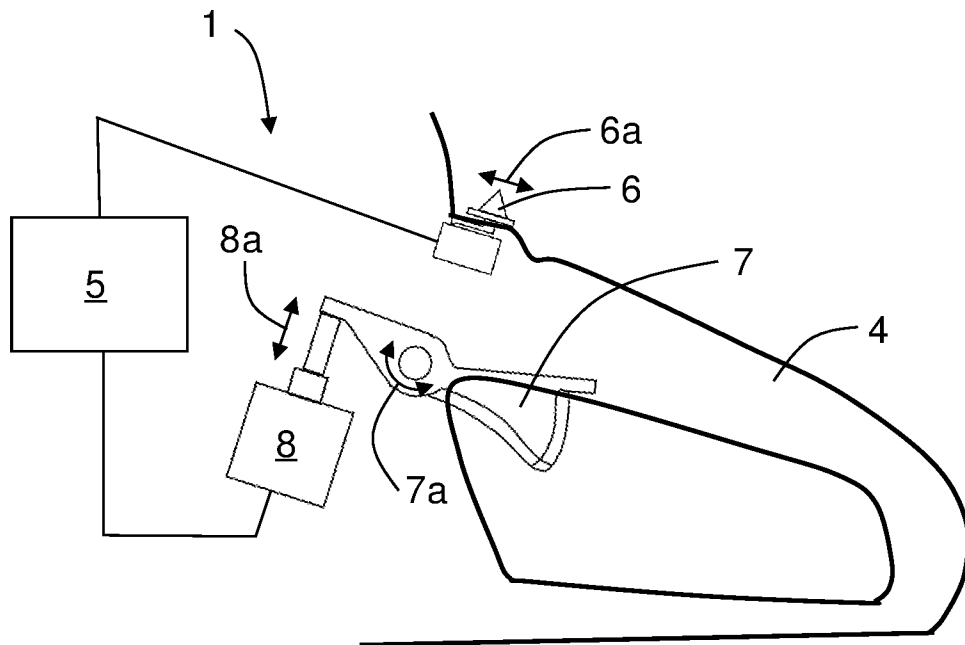


Fig. 2

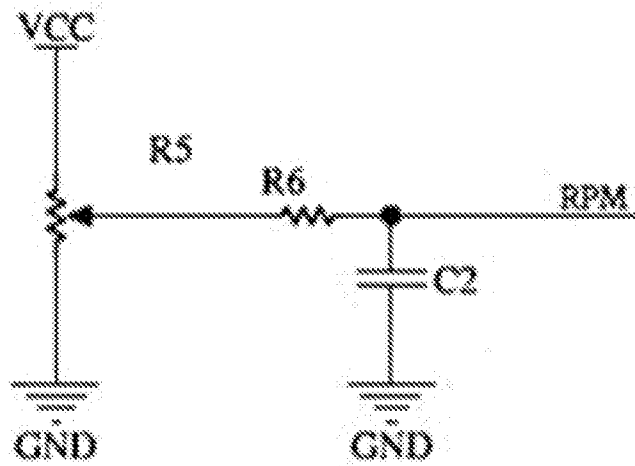


Fig. 3a

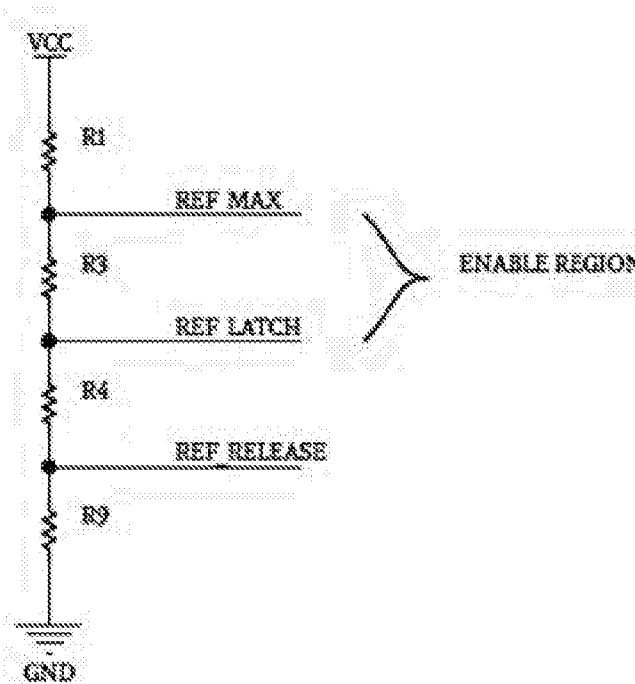


Fig. 3b



## INTERNATIONAL SEARCH REPORT

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<b>A. CLASSIFICATION OF SUBJECT MATTER</b>		
F16P 3/00(2006.01)i; B27B 17/00(2006.01)i; B25F 5/00(2006.01)i		
According to International Patent Classification (IPC) or to both national classification and IPC		
<b>B. FIELDS SEARCHED</b>		
Minimum documentation searched (classification system followed by classification symbols) F16P; B27B; B25F		
Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched		
Electronic data base consulted during the international search (name of data base and, where practicable, search terms used) WPI, EPODOC, CNPAT, CNKI, IEEE: lockout, throttle, action, hand-held, actuation, motor, power, control		
<b>C. DOCUMENTS CONSIDERED TO BE RELEVANT</b>		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 2017051873 A1 (HUSQVARNA AB.) 23 February 2017 (2017-02-23) description, paragraphs [0002], [0025]-[0030], [0052], and figure 1	1-13
A	US 2016268068 A1 (HUBBELL INCORPORATED) 15 September 2016 (2016-09-15) the whole document	1-13
A	US 4155418 A (BOMBARDIER LIMITED) 22 May 1979 (1979-05-22) the whole document	1-13
A	US 2008105243 A1 (PLANET ECLIPSE, LTD.) 08 May 2008 (2008-05-08) the whole document	1-13
<input type="checkbox"/> Further documents are listed in the continuation of Box C. <input checked="" type="checkbox"/> See patent family annex.		
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Name and mailing address of the ISA/CN <b>STATE INTELLECTUAL PROPERTY OFFICE OF THE P.R.CHINA 6, Xitucheng Rd., Jimen Bridge, Haidian District, Beijing 100088 China</b>		Authorized officer <b>ZHAO,Ting</b>
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**INTERNATIONAL SEARCH REPORT**  
**Information on patent family members**

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