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A method is disclosed for optimization of a production of frozen ice cream products (6), such as extruded edible ice cream products, from a freezing system (1) comprising a freezing apparatus (2), comprising the steps of recording one or more properties of the production, such as one or more measured values related to the freezing system during the production process (STM), and using the one or more recorded properties for controlling one or more operational parameters of the freezing system (REG). In an aspect of the invention, it comprises the steps of conveying pre-products to be frozen into the freezing apparatus (PPIN), cooling the pre-products to form frozen products inside the freezing apparatus (FRZ), conveying the frozen products out of the freezing apparatus (FPOUT), measuring one or more surface temperatures of frozen products leaving the freezing apparatus (STM), and using the one or more measured surface temperatures for controlling one or more operational parameters of the freezing apparatus (REG).

Fortsættes ...

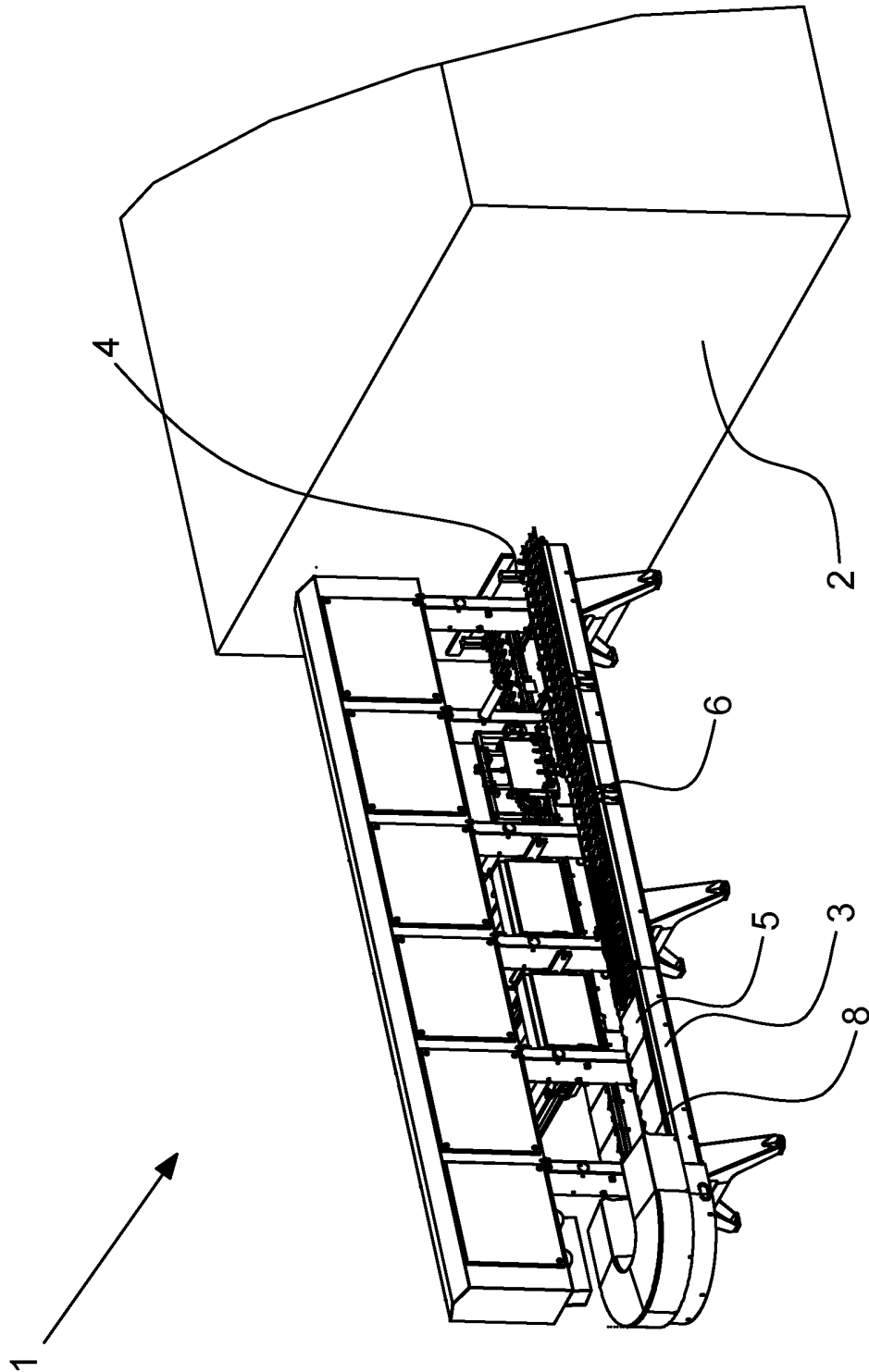


Fig. 1

METHOD FOR PRODUCING FROZEN ICE CREAM PRODUCTS

The present invention relates to a method for producing frozen ice cream products, such as extruded edible ice cream products, using a freezing system comprising a
5 freezing apparatus.

Background of the invention

When producing frozen extruded ice cream products, it is a common practice to
10 place extruded pre-products to be frozen onto product plates arranged on a conveyor and then to convey the pre-products through a freezing apparatus, often in the form of a freezing tunnel, for cooling the pre-products so that they leave the freezing apparatus again as frozen products.

15 The degree, to which the products are frozen when passing through the freezing apparatus, is a very important parameter of the production process. Whereas the pre-products are relatively sticky and, to some extent, adhere to the product plates, the frozen products are less sticky the harder they are frozen.

20 This means that, if the products are not sufficiently frozen, they stick too much to the product plates and may be damaged when trying to remove them therefrom. On the other hand, if the products are subject to excessive freezing, they may loosen completely from the product plates and fall off the product plates on their way through the freezing apparatus. This may, for instance, happen, where there is a
25 curve or a turn on the conveyor, or due to flows of cooling air inside the freezing apparatus.

In freezing systems known in the art, it requires skilled and experienced operators to ensure that the freezing process is performed optimally, so that neither insufficient
30 nor excessive freezing of the products takes place in the freezing apparatus.

Brief description of the invention

It is an object of the present invention to provide a freezing system with a higher degree of automated control so that less demand is put on the operator but high-quality products can still be obtained.

The present invention relates to a method for producing frozen ice cream products, such as extruded edible ice cream products, using a freezing system comprising a freezing apparatus, said method comprising the steps of conveying pre-products to be frozen into the freezing apparatus, cooling the pre-products to form frozen products inside the freezing apparatus, conveying the frozen products out of the freezing apparatus, measuring one or more surface temperatures of frozen products leaving the freezing apparatus, and using the one or more measured surface temperatures as input for a control device for controlling one or more operational parameters of the freezing apparatus.

Using surface temperatures for controlling operational parameters of the freezing apparatus allows for a more automated optimization of the production process and reduces the dependency on skilled operators of the freezing system for obtaining frozen ice cream products of the desired optimum quality.

In an embodiment of the invention, the method further comprises the steps of placing the pre-products to be frozen onto a number of product plates before conveying them into the freezing apparatus, cooling the pre-products to form frozen products while conveying them around inside the freezing apparatus by exposing them to cold air provided and circulated by means of fans and/or evaporators, and lifting the frozen products off the product plates, after conveying them out of the freezing apparatus, by means of a product handling system driven by a driving arrangement, such as one or more servo motors.

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Placing the pre-products on product plates before conveying them into the freezing apparatus results in an easy and safe handling of the pre-products and the frozen products before, during and after the step of cooling.

5 In an embodiment of the invention, the freezing system further comprises a work table and the product plates are placed on the work table when the pre-products to be frozen are placed onto the product plates and/or when the frozen products are lifted off the product plates.

10 The use of a work table for handling the pre-products before the cooling and the products after the cooling enables for an easy and safe handling of the pre-products and the products.

The expression “work table” is to be understood as any platform by which the
15 product plates are supported when outside the freezing apparatus. Preferable, a single conveyor system is used for transporting the product plates around inside the freezing apparatus and across an upper surface of the work table.

In an embodiment of the invention, the method further comprises, before the step of
20 lifting the frozen products off the product plates, the step of loosening the frozen products from the product plates by tapping the product plates while holding the frozen products in place thereon.

The introduction of this step has proven to ease the separation of the frozen products
25 from the product plates without damaging the frozen products.

In an embodiment of the invention, one or more torque values exerted by the driving arrangement are measured during the step of lifting the frozen products off the product plates and used as input for a control device for controlling one or more
30 operational parameters of the freezing system.

In an embodiment of the invention, the one or more measured torque values include the maximum torque exerted by the driving arrangement during the lifting process.

5 The torque, especially the maximum torque, exerted by the driving arrangement is a useful input for a control system because it is closely related to the force necessary to lift the frozen products off the product plates, which force, in turn, is a very good indicator of the ability of the frozen products to be released from the product plates.

10 In an embodiment of the invention, the one or more controlled operational parameters include one or more evaporation temperatures and, thereby, one or more air temperatures within the freezing apparatus.

15 In an embodiment of the invention, the one or more controlled operational parameters include one or more fan speeds and, thereby, one or more speeds of air circulated within the freezing apparatus.

20 In an embodiment of the invention, the one or more controlled operational parameters include the period of time passed from a given product to be frozen enters the freezing apparatus to the same product leaves the freezing apparatus again as a frozen product.

25 The correct degree of freezing of the frozen products can be obtained by controlling the air temperature(s) and speed(s) within the freezing apparatus and/or the period of time spent by any given product within the freezing apparatus.

In an embodiment of the invention, the period of time passed is controlled by regulating a speed of a conveyor extending within the freezing apparatus.

30 A simple way of controlling the period of time spent by a given product within the freezing apparatus is by regulating the speed of a conveyor extending within the freezing apparatus, which has a direct influence on the period of time passed from a

given product to be frozen enters the freezing apparatus to the same product leaves the freezing apparatus again as a frozen product.

5 In an embodiment of the invention, the control of the one or more operational parameters are performed in such a way that the one or more measured surface temperatures are kept within ranges, which are calculated taking into account certain product-specific parameters, such as the size and shape of the products and the materials from which the products are made.

10 In an embodiment of the invention, the control of the one or more operational parameters are performed in such a way that the one or more measured torque values are kept within ranges, which are calculated taking into account certain product-specific parameters, such as the size and shape of the products and the materials from which the products are made.

15 In an embodiment of the invention, an algorithm for controlling the one or more operational parameters takes into account certain product-specific parameters, such as the size and shape of the products and the materials from which the products are made.

20 Using product-specific parameters as basis for the ranges within which the measured surface temperatures and torque values are allowed to vary and as basis for the control algorithms enables the control system to be optimized for production of the specific products being produced.

25 In an embodiment of the invention, the control of the one or more operational parameters is performed using a control loop feedback mechanism, such as PID control or PI control.

30 In an aspect of the invention, it relates to a control system for a freezing system comprising a freezing apparatus, said control system comprising one or more

temperature sensors for measuring surface temperatures of frozen products leaving the freezing apparatus and a control device for setting operational parameters of the freezing apparatus in dependency of the measured surface temperatures.

- 5 In an embodiment of the invention, the one or more temperature sensors are infrared sensors.

In an aspect of the invention, it relates to a freezing system for production of frozen products, such as edible ice cream products, said freezing system comprising a
10 freezing apparatus and a control system as described above.

In an aspect of the invention, it relates to a computer program product stored on a computer readable medium comprising software instructions for performing one or more of the method described above.

15

Figures

A few exemplary embodiments of the invention are described in more details in the following with reference to the figures, of which

20

Fig. 1 is a perspective view of a freezing system according to an embodiment of the invention,

25 Fig. 2 is a perspective view of a product plate of a freezing system according to an embodiment of the invention,

Fig. 3 is a closer perspective view of a first specific part of a freezing system according to an embodiment of the invention,

30 Fig. 4 is a closer perspective view of a second specific part of a freezing system according to an embodiment of the invention,

Fig. 5 is a closer perspective view of a third specific part of a freezing system according to an embodiment of the invention, and

Fig. 6 is a flow diagram showing the basic method steps of a production process according to a preferred embodiment of the invention.

Detailed description of the invention

Fig. 1 is a perspective view of a freezing system 1 according to an embodiment of the invention. The illustrated embodiment comprises a freezing apparatus 2 in the form of a freezing tunnel, and a work table 3, which is arranged in close connection with the freezing apparatus 2.

An endless conveyor 8 extends along the surface of the work table 3, into the freezing apparatus 2, around inside the freezing apparatus 2 along a path therein, out of the freezing apparatus 2 again, and back onto the work table 3.

A plurality of product plates 5 are placed on top of the conveyor 8. In Fig. 1, the product plates 5 on the back side of the illustrated work table 3 carry pre-products to be frozen into the freezing apparatus 2, whereas the product plates 5 on the front side of the illustrated work table 3 carry frozen ice cream products 6, which have just come out of the freezing apparatus 2.

This figure further illustrates how one or more temperature sensors 4, for instance in the form of infrared sensors, are arranged near the place, where the conveyor 8 leaves the freezing apparatus 2, for measuring the surface temperature(s) of the frozen ice cream products 6 leaving the freezing apparatus 2.

A closer view of a product plate 5 carrying a number of frozen ice cream products 6 is illustrated in Fig. 2. The illustrated frozen ice cream products 6 are of a type including an ice cream stick 7. The invention, however, is not limited to methods and

systems related to the freezing of such types of frozen ice cream products 6. Rather, the invention is relevant for any method or system for producing frozen ice cream products 6 from pre-products conveyed through a freezing apparatus 2.

- 5 Fig. 3 shows a closer view of a part of the work table 3 just outside the freezing apparatus 2. A temperature sensor 4, such as for instance an infrared sensor, is arranged over the conveyor 8, which is covered with product plates 5 carrying frozen ice cream products 6 with ice cream sticks 7.
- 10 The temperature sensor 4 is used for measuring surface temperatures of the frozen ice cream products 6, which have just left the freezing apparatus 2. The measured surface temperatures are used in a control device (not shown) of the freezing system 1 for setting operational parameters of the freezing apparatus 2. These operational parameters can, for instance, include one or more evaporation temperatures and,
- 15 thereby, one or more air temperatures within the freezing apparatus 2, one or more fan speeds and, thereby, one or more speeds of air circulated within the freezing apparatus 2 and/or a speed of a conveyor 8 extending within the freezing apparatus 2 and, thereby, the period of time passed from a given product to be frozen enters the freezing apparatus 2 to the same product leaves the freezing apparatus 2 again as a
- 20 frozen product 6.

Apart from measured surface temperatures, the control device can take other properties into account when regulating and controlling the operational parameters of the freezing apparatus 2. For instance, one or more torque values, such as the

25 maximum torque value, exerted by a driving arrangement when lifting the frozen products 6 off the product plates 5 or vision control or other methods to make sure that the frozen products 7 do not stick to the product plates 5 when being lifted off can be used as input for the regulation loop together with the measured surface temperatures for obtaining an even better control of the operational parameters of the

30 freezing apparatus 2.

Preferably, the control of the one or more operational parameters are performed in such a way that the one or more measured surface temperatures and, if applicable, the one or more measured torque values are kept within ranges, which are calculated taking into account certain product-specific parameters, such as the size and shape of the products 6 and the materials from which the products 6 are made.

Similarly, the algorithms for controlling the one or more operational parameters takes into account certain product-specific parameters, such as the size and shape of the products 6 and the materials from which the products 6 are made.

10

Fig. 4 illustrates a closer view of the subsequent part of the work table 3 reached by the product plates 5 on the conveyor 8.

A number of product holders 9 corresponding to the number of frozen ice cream products 6 on each product plate 5 are arranged around a product plate hammer 10 and over the conveyor 8. For each product plate 5 passing by, this arrangement is lowered so that each of the product holders 9 holds one of the frozen ice cream products 6 in place against the product plate 5 while the product plate hammer 10 is activated and strikes the product plate 5 a few times. If the frozen ice cream products 6 are sufficiently frozen, oscillations through the product plate 5 caused by the strokes of the product plate hammer 10 will loosen the frozen ice cream products 6 from the product plate 5.

The next part of the work table 3 reached by the product plates 5 on the conveyor 8 is illustrated in a closer view in Fig. 5.

Here, a pick and place product transfer 11 is arranged, comprising a plurality of gripper tongs 12 for gripping the frozen ice cream products 6 and lifting them off the product plates 5 for transferring them to further processing or packaging. In the illustrated embodiment, in which the frozen ice cream products 6 are equipped with ice cream sticks 7, the gripper tongs 12 preferably grip the frozen ice cream products

30

6 by these sticks 7. In other embodiments, where there may be no ice cream sticks 7, the gripper tongs 12 can grip the frozen ice cream products 6 directly at the ice cream material, or other tools than gripper tongs 12 can be used for lifting the frozen ice cream products 6 off the product plates 5.

5

Fig. 6 is a flow diagram showing the basic method steps of a production process according to a preferred embodiment of the invention.

Pre-products are to be frozen are conveyed into the freezing apparatus 2 (PPIN),
10 inside which they are cooled to form frozen ice cream products 6 (FRZ). After having conveyed the frozen ice cream products 6 thus produced out of the freezing apparatus 2 again (FPOUT), one or more surface temperatures of the frozen ice cream products 6 are measured (STM), for instance by means of one or more infrared temperature sensors 4, and the frozen ice cream products 6 are transferred to further
15 processing or packaging (FP).

During the production process, the measured surface temperatures are continuously fed to and used by a control device (not shown) of the freezing system 1 for setting operational parameters of the freezing apparatus 2 so that the freezing process (FRZ)
20 can be optimized for subsequent pre-products to be frozen passing through the freezing apparatus 2.

List of reference numbers

- | | | |
|----|--------|--|
| | 1. | Freezing system |
| | 2. | Freezing apparatus |
| 5 | 3. | Work table |
| | 4. | Temperature sensor |
| | 5. | Product plate |
| | 6. | Frozen ice cream product |
| | 7. | Ice cream stick |
| 10 | 8. | Conveyor |
| | 9. | Product holder |
| | 10. | Product plate hammer |
| | 11. | Gripper tongs |
| | 12. | Pick and place product transfer |
| 15 | | |
| | PPIN. | Conveying of pre-products into freezing apparatus |
| | FRZ. | Cooling of pre-products to form frozen products |
| | FPOUT. | Conveying of frozen products out of freezing apparatus |
| | STM. | Surface temperature measurement |
| 20 | FP. | Further processing or packaging of frozen products |
| | REG. | Regulation of operational parameters of freezing apparatus |

Patentkrav

1. Fremgangsmåde til fremstilling af frosne flødeisprodukter (6), såsom ekstruderede konsumisprodukter, under anvendelse af et frysesystem (1), som
5 omfatter et fryseapparat (2), hvilken fremgangsmåde omfatter følgende trin:
- transport af præprodukter, som skal fryses, ind i fryseapparatet (PPIN),
 - 10 - nedkøling af præprodukterne til dannelse af frosne produkter inde i fryseapparatet (FRZ), og
 - transport af de frosne produkter ud af fryseapparatet (FPOUT),
- 15 kendetegnet ved, at fremgangsmåden endvidere omfatter følgende trin:
- måling af en eller flere overfladetemperaturer af frosne produkter, som forlader fryseapparatet (STM), og
 - 20 - anvendelse af den ene eller de flere målte overfladetemperaturer som input til en styreindretning til styring af en eller flere af fryseapparatets driftsparametre (REG).
2. Fremgangsmåde ifølge krav 1, som endvidere omfatter følgende trin:
- 25
- anbringelse af de præprodukter, som skal fryses, på et antal produktplader (5) før transport af dem ind i fryseapparatet,
 - nedkøling af præprodukterne til dannelse af frosne produkter under
30 transport af dem omkring inde i fryseapparatet ved at eksponere dem

for kold luft, som tilvejebringes og cirkuleres ved hjælp af ventilatorer og/eller fordampere, og

- 5 - løftning af de frosne produkter fra produktpladerne, efter at have transporteret dem ud af fryseapparatet, ved hjælp af et produkt håndteringssystem, som drives af et drivarrangement, såsom en eller flere servomotorer.

- 10 3. Fremgangsmåde ifølge krav 2, hvor frysesystemet endvidere omfatter et arbejdsbord (3), og hvor produktpladerne anbringes på arbejdsbordet, når de præprodukter, som skal fryses, anbringes på produktpladerne, og/eller når de frosne produkter løftes fra produktpladerne.

- 15 4. Fremgangsmåde ifølge krav 2 eller 3, som før trinnet til løftning af de frosne produkter fra produktpladerne endvidere omfatter følgende trin:
 - løsning af de frosne produkter fra produktpladerne ved at banke på produktpladerne, mens de frosne produkter holdes på plads herpå.

- 20 5. Fremgangsmåde ifølge et hvilket som helst af kravene 2-4, hvor en eller flere momentværdier, som udøves af drivarrangementet, måles under trinnet til løftning af de frosne produkter fra produktpladerne og anvendes som input til en styreindretning til styring af en eller flere af frysesystemets driftsparametre.

- 25 6. Fremgangsmåde ifølge krav 5, hvor den ene eller de flere målte momentværdier indbefatter det maksimale moment, som udøves af drivarrangementet under løfteprocessen.

- 30 7. Fremgangsmåde ifølge et hvilket som helst af de foregående krav, hvor den ene eller de flere styrede driftsparametre indbefatter en eller flere

fordampningstemperaturer og dermed en eller flere lufttemperaturer inde i fryseapparatet.

- 5 8. Fremgangsmåde ifølge et hvilket som helst af de foregående krav, hvor den ene eller de flere styrede driftsparametre indbefatter en eller flere ventilatorhastigheder og dermed en eller flere hastigheder af luft, som cirkuleres inde i fryseapparatet.
- 10 9. Fremgangsmåde ifølge et hvilket som helst af de foregående krav, hvor den ene eller de flere styrede driftsparametre indbefatter det tidsrum, der går, fra et givet produkt, som skal fryses, kommer ind i fryseapparatet, til det samme produkt forlader fryseapparatet igen som et frosset produkt.
- 15 10. Fremgangsmåde ifølge krav 9, hvor det tidsrum, der går, styres ved at regulere en hastighed af et transportbånd (8), som strækker sig inde i fryseapparatet.
- 20 11. Fremgangsmåde ifølge et hvilket som helst af de foregående krav, hvor styringen af den ene eller de flere driftsparametre udføres på en sådan måde, at den ene eller de flere målte overfladetemperaturer holdes inden for intervaller, der beregnes således, at de tager højde for visse produktspecifikke parametre, såsom produkternes størrelse og form og de materialer, produkterne er fremstillet af.
- 25 12. Fremgangsmåde ifølge et hvilket som helst af de foregående krav, hvor styringen af den ene eller de flere driftsparametre udføres på en sådan måde, at den ene eller de flere målte momentværdier holdes inden for intervaller, der beregnes under hensyntagen til visse produktspecifikke parametre, såsom produkternes størrelse og form og de materialer, produkterne er fremstillet af.
- 30 13. Fremgangsmåde ifølge et hvilket som helst af de foregående krav, hvor en algoritme til styring af den ene eller de flere driftsparametre tager højde for

visse produktspecifikke parametre, såsom produkternes størrelse og form og de materialer, produkterne er fremstillet af.

14. Fremgangsmåde ifølge et hvilket som helst af de foregående krav, hvor
5 styringen af den ene eller de flere driftsparametre udføres under anvendelse af en styresløjfetilbagekoblingsmekanisme, såsom PID-styring eller PI-styring.
15. Styresystem til et frysesystem (1), som omfatter et fryseapparat (2), hvilket
10 styresystem omfatter
- en eller flere temperatursensorer (4) til måling af overfladetemperaturer af frosne produkter (6), som forlader fryseapparatet, og
- en styreindretning til indstilling af fryseapparatets driftsparametre i
15 afhængighed af de målte overfladetemperaturer.
16. Styresystem ifølge krav 15, i hvilket den ene eller de flere temperatursensorer er infrarøde sensorer.
- 20 17. Frysesystem (1) til fremstilling af frosne produkter (6), såsom konsumisprodukter, hvilket frysesystem omfatter
- et fryseapparat (2) og
- 25 et styresystem ifølge krav 15 eller 16.
18. Computerprogramprodukt lagret på et computerlæsbart medium, som omfatter softwareinstruktioner til udførelse af fremgangsmåden ifølge et hvilket som helst af kravene 1-14.

1/6

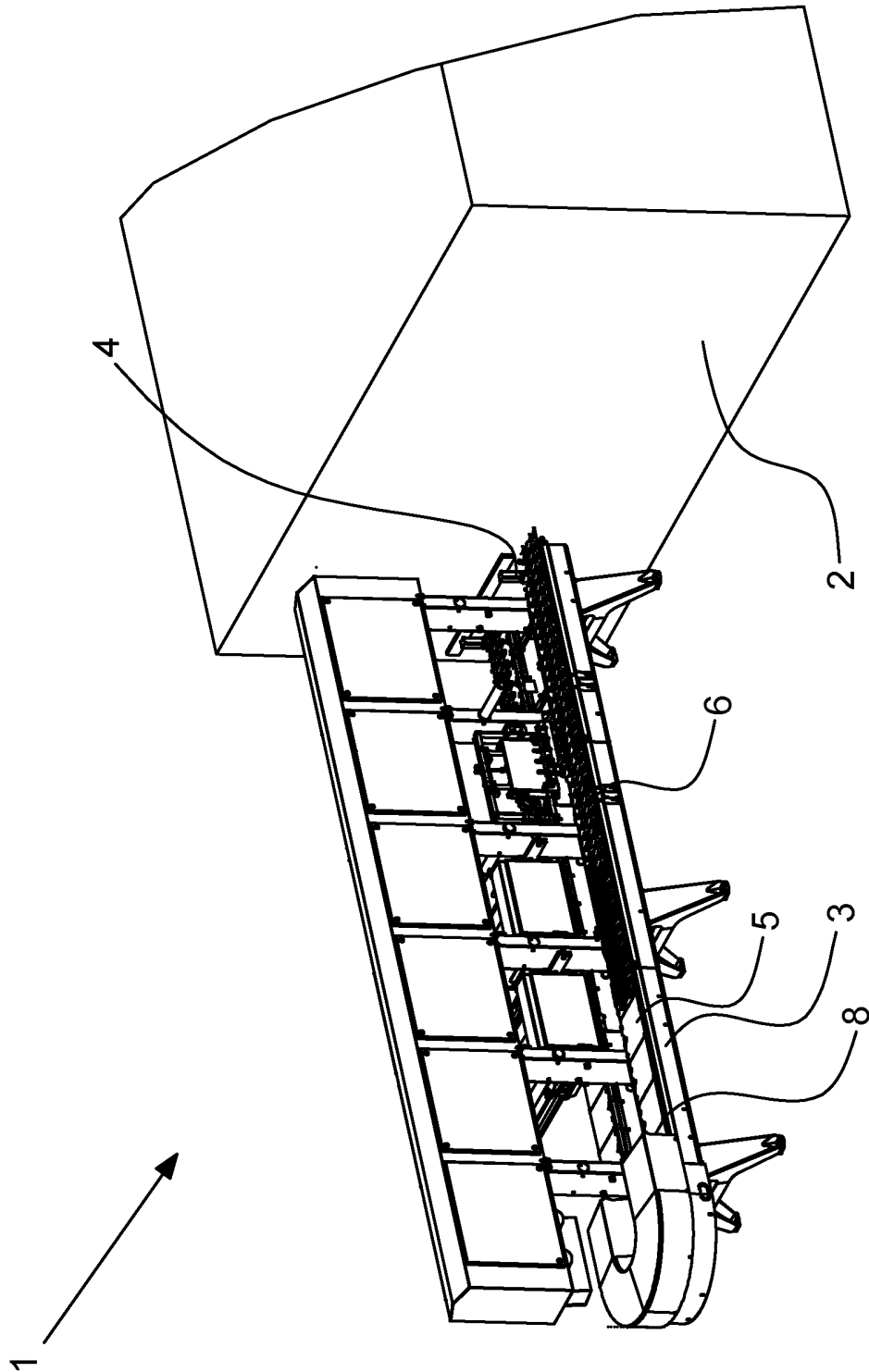


Fig. 1

2/6

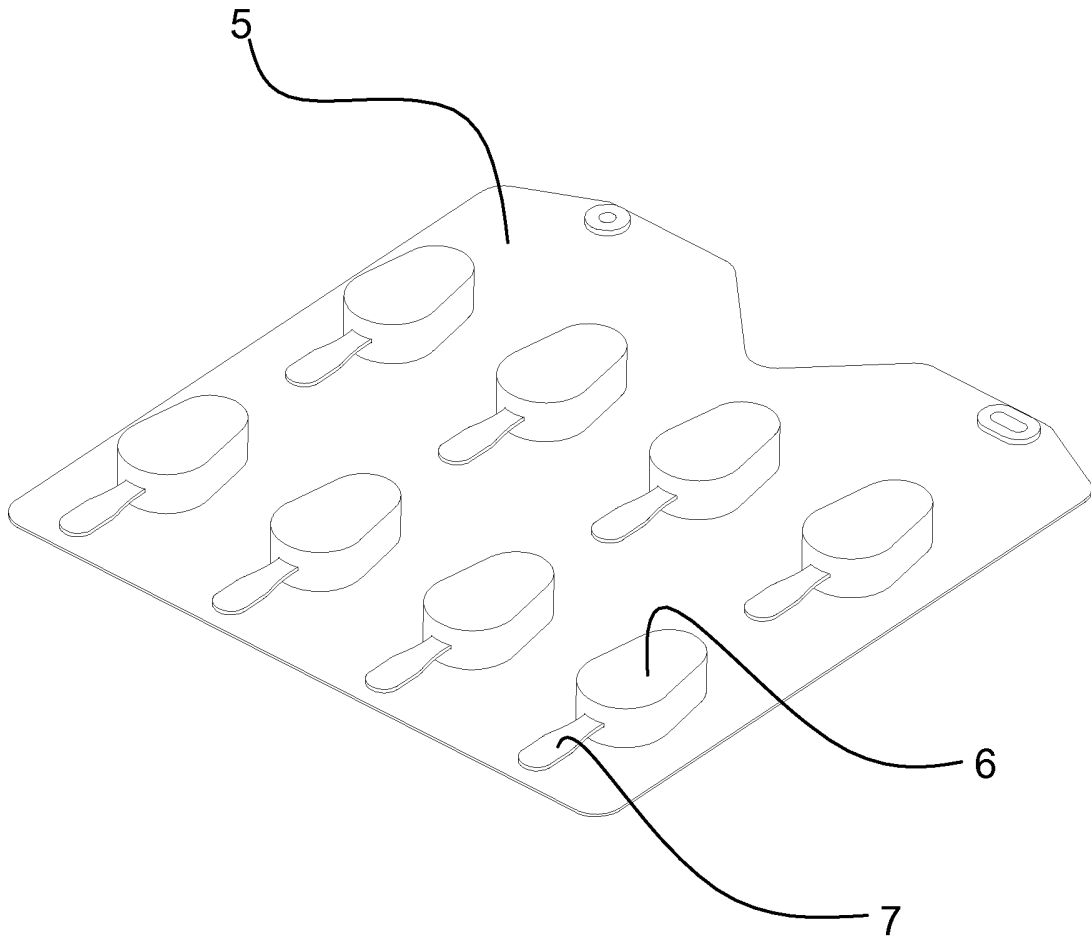


Fig. 2

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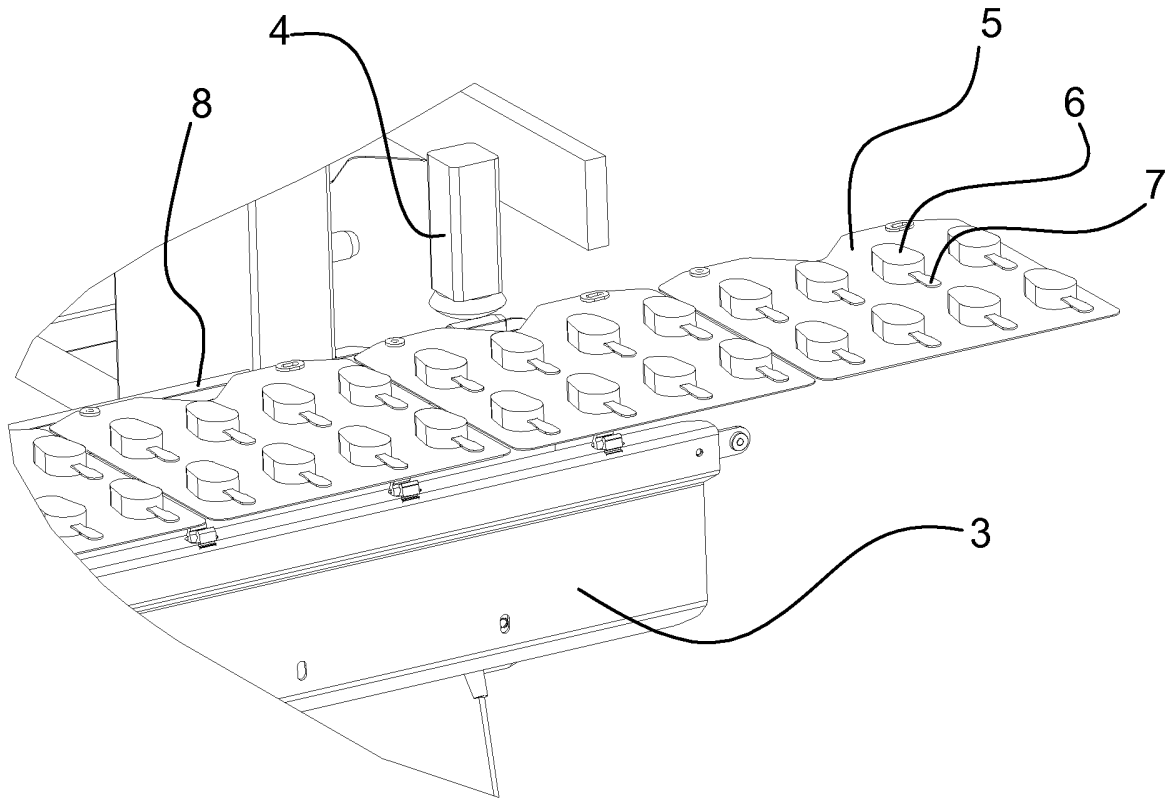


Fig. 3

4/6

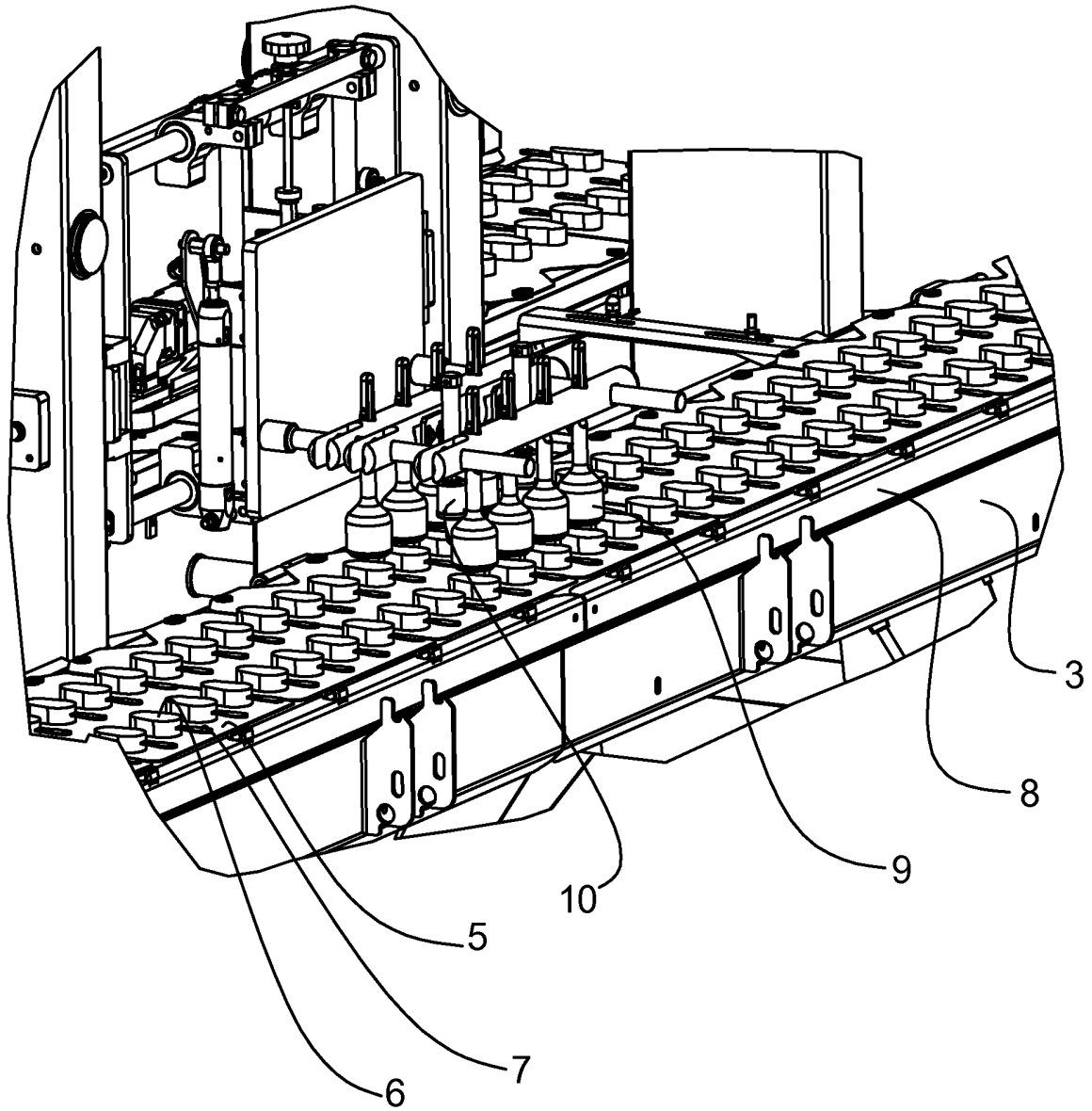


Fig. 4

5/6

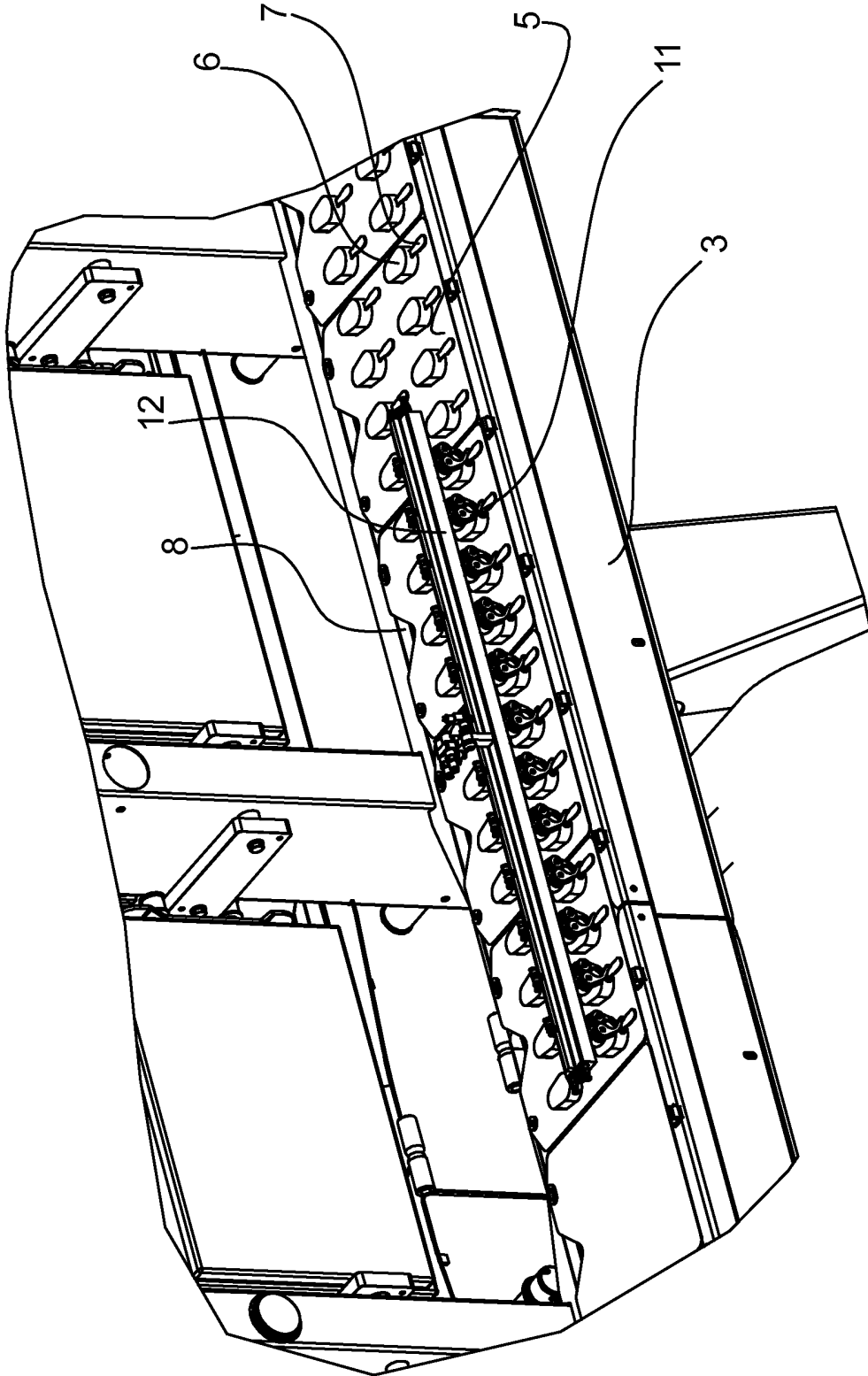


Fig. 5

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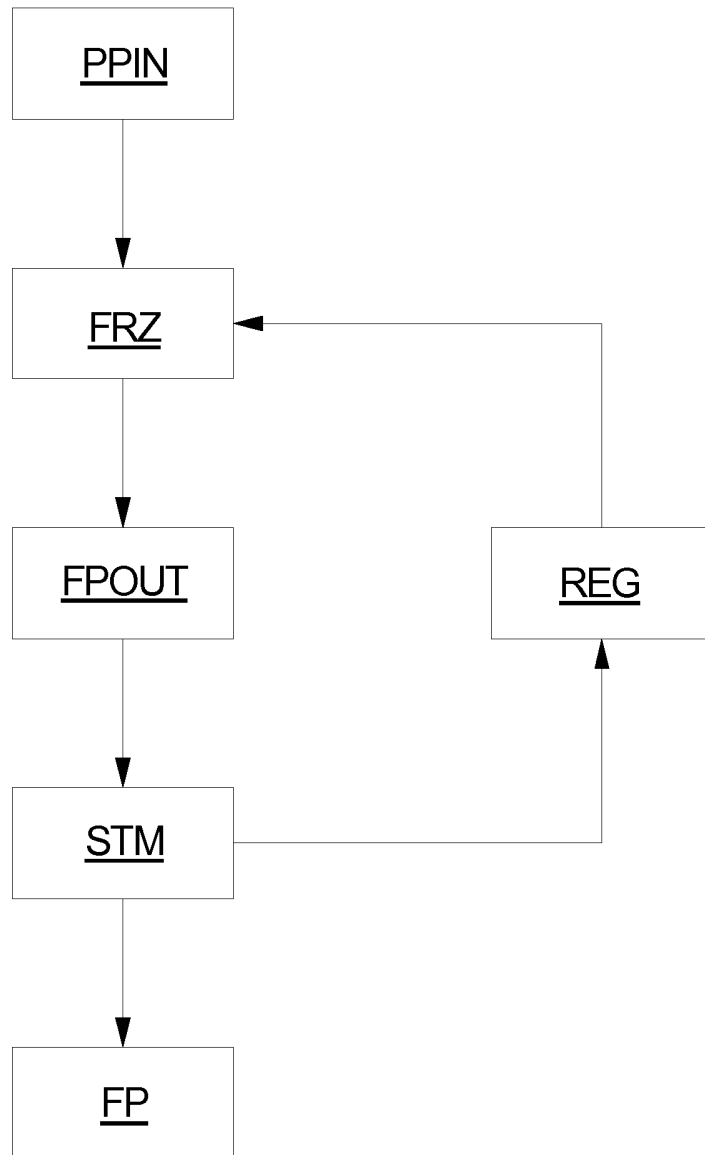


Fig. 6