

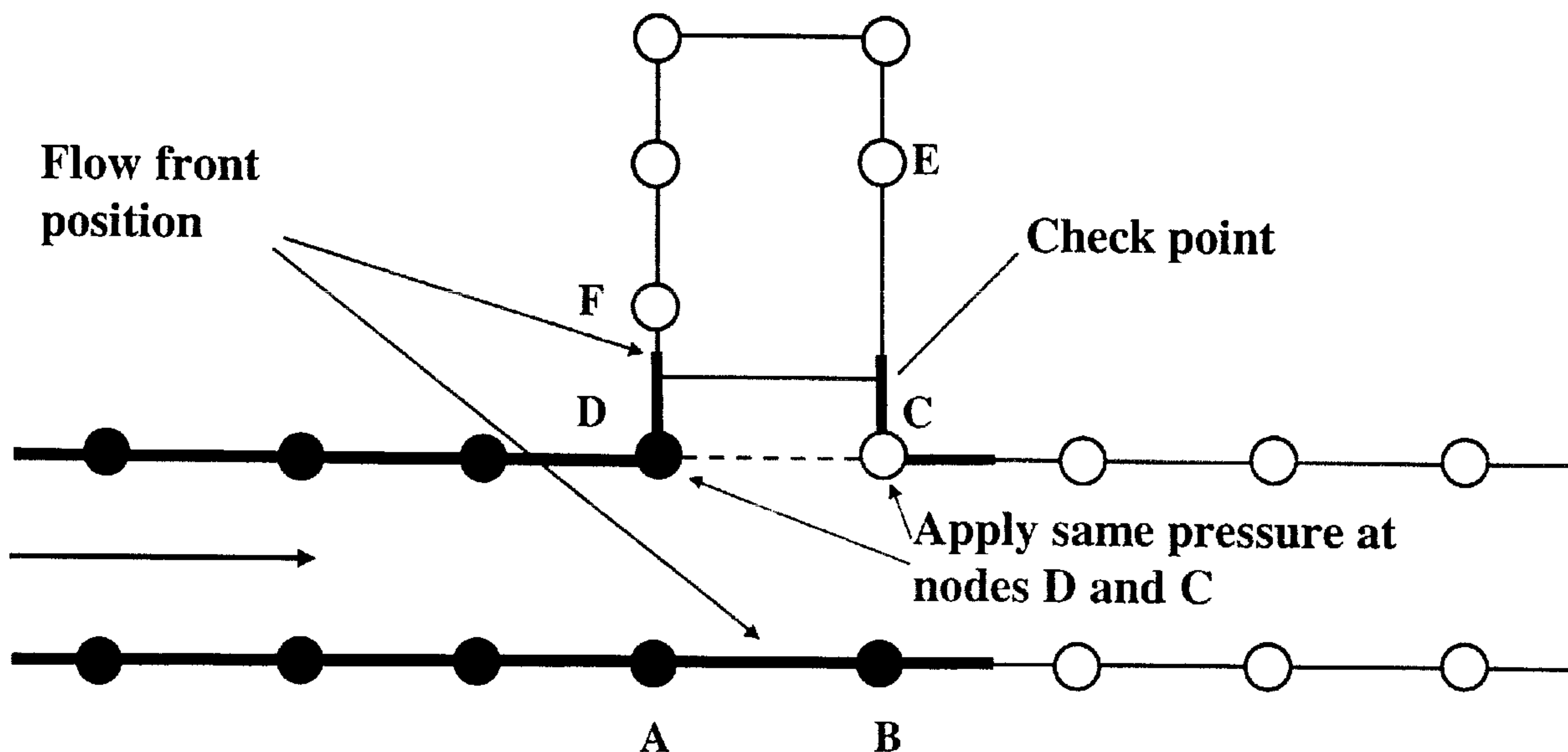


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(54) Title: METHOD FOR MODELLING THREE-DIMENSIONAL OBJECTS AND SIMULATION OF FLUID FLOW



(57) Abrégé/Abstract:

A method for simulating fluid flow within a three-dimensional object having first and second generally opposed surfaces including matching each element (DF) of said first surface with an element (CE) of said second surface between which a reasonable thickness may be defined, wherein matched elements of said first surface constitute a first set of matched elements and matched elements of said second surface constitute a second set of matched elements specifying a fluid injection point, performing a flow analysis using each set of said matched elements, whereby said injection point is linked to all locations on said first and second surfaces from which flow may emanate such that resulting flow fronts along said first and second surfaces are synchronized.

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(54) Title: METHOD FOR MODELLING THREE-DIMENSIONAL OBJECTS AND SIMULATION OF FLUID FLOW 		
(57) Abstract A method for simulating fluid flow within a three-dimensional object having first and second generally opposed surfaces including matching each element (DF) of said first surface with an element (CE) of said second surface between which a reasonable thickness may be defined, wherein matched elements of said first surface constitute a first set of matched elements and matched elements of said second surface constitute a second set of matched elements specifying a fluid injection point, performing a flow analysis using each set of said matched elements, whereby said injection point is linked to all locations on said first and second surfaces from which flow may emanate such that resulting flow fronts along said first and second surfaces are synchronized.		

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METHOD FOR MODELLING THREE DIMENSIONAL OBJECTS
AND SIMULATION OF FLUID FLOW

This invention relates to a method for modelling solid
5 objects, particularly for use in the simulation of fluid
flow, to be used for example to simulate prototypes before
production. In a preferred embodiment the method is used
in the design of articles to be manufactured by injection
molding, preferably from molten plastic materials.

10 The modelling of solid objects is employed in various
fields. Such modelling is used, for example, in the
simulation of injection molding. In that field, it is
widely recognized that the filling and packing phases of
15 injection molding have a significant effect on the visual
and mechanical properties of a molded object. Simulation
is employed to analyse proposed shapes and injection
points, and thus the final quality of the ultimate article.
A requirement of any injection mold is that it can be
20 filled with molten polymer given the pressure limits of a
real injection molding machine. Simulation can provide
information as to whether the mold can be filled and the
fill pattern that will be achieved. By using simulation, it
is possible to determine optimum gate locations and
25 processing conditions. It is possible to predict the
location of weld lines and air traps. Economic benefit is
derived from simulation because problems can be predicted
and solutions tested prior to the actual creation of the
mold. This eliminates costly re-working and decreases the
30 time required to get an object into production.

Simulation technology has been developed and generally uses
finite element/finite difference techniques to solve the
governing equations of fluid flow and heat transfer. In
35 order to minimize the time required for analysis and hence
the required computer resources, the Hele-Shaw
approximation is invoked to simplify the governing

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equations. It has been found that this simplification provides sufficient accuracy for injection molding but does create the need for specific modelling of the computational domain.

5

Injection molding is an excellent process for repetitively manufacturing large numbers of objects or parts having complicated geometries. A characteristic of injection molded components is that the thickness of the wall is generally a small fraction of the overall length of the component. In view of the low thermal conductivity of plastics, this physical characteristic is essential to achieve the rapid cycle times that make the process so attractive.

15

The flow of melt in an injection mold is determined by the familiar conservation laws of fluid mechanics. Solution of the equations in their full generality presents several practical problems. Owing to the characteristically thin walls of molded components, however, it is possible to make some reasonable assumptions that lead to a simplification of the governing equations. These simplified equations describe what is called Hele-Shaw flow and may be readily solved in complex geometries using an appropriate numerical technique such as the finite element and/or finite difference method.

20

Injection molding simulation is now routinely regarded as a desirable aspect of plastic part design. Similarly, improved computer aided drafting (CAD) technology has led to the widespread use of surface and solid modelling. Associated advantages of this are the ability to better visualize an object, to use numerical cutting, and the possibility of achieving more concurrency in engineering design and manufacture. When using the Hele-Shaw approximation, plastic CAE analysis still requires the use of a surface model, representing the midplane of the real

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component, which is then meshed with triangular or quadrilateral elements to which suitable thicknesses are ascribed. The preparation of such a mesh can take a considerable amount of time, and requires substantial user input; owing to the labour intensive nature of this step, model preparation requires the greatest share of time when performing a molding simulation and makes this technique time consuming. In addition, as model preparation is an interactive task, it has a higher cost associated with it than simply running a computer program.

This conventional technique for the simulation of three dimensional bodies is illustrated in figures 1 to 3 of the accompanying drawings in which:

Figure 1 is a representative example of an article to be manufactured by injection molding in the form of a T-shaped component;

Figure 2 is a midplane representation of the component of figure 1 that is meshed; and

Figure 3 is a view of the major results from a conventional analysis showing the position of the advancing melt at given times.

One solution to the above shortcomings is to avoid the use of the Hele-Shaw equations and solve the governing equations in their full generality. This has inherent problems owing to the thin walled nature of injection molded objects and parts. To perform such an analysis, the region representing the mold cavity into which molten polymer will be injected must be divided into small sub-domains called elements. Usually these elements are of tetrahedral or hexahedral shape. This process of subdivision is called meshing and the resultant network of tetrahedra or hexahedra the mesh. Owing to the complicated shape of many injection molded objects and parts it is generally not possible to automatically mesh the cavity with hexahedral elements. It is possible, however, to mesh

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the domain automatically with tetrahedral elements. The thin walled nature of injection molded objects and parts means that the plastic is subject to a huge thermal gradient in the thickness direction of the component. This requires that there be a reasonable number of elements through the thickness. Using existing meshing technology, the result is a mesh consisting of hundreds of thousands or even millions of elements. The high number of elements makes the problem intractable for any but the fastest super computers. These are rarely found in industry, being extremely costly to purchase and maintain. Thus, although three dimensional simulation provides a solution that avoids the requirement of a midplane model, it is not as yet a practical solution.

It is an object of the present invention, therefore, to provide a method for the simulation of flow in a three dimensional object that can produce simulations substantially automatically, without requiring the solution of the governing equations in their full generality.

According to a first broad aspect of the present invention, therefore, there is provided a method for simulating fluid flow within a three dimensional object having first and second generally opposed surfaces including:

matching each element of said first surface with an element of said second surface between which a reasonable thickness may be defined, wherein matched elements of said first surface constitute a first set of matched elements and matched elements of said second surface constitute a second set of matched elements,

specifying a fluid injection point,

performing a flow analysis using each set of said matched elements, whereby said injection point is linked to all locations on said first and second surfaces from which flow may emanate such that resulting flow fronts along said first and second surfaces are synchronized.

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It should be noted that, in this context, generally opposed surfaces may be parallel, inclined to each other, meet at an acute angle or otherwise, and need not be planar, provided that a reasonable thickness or thicknesses may be assigned to the space between the surfaces.

Preferably said injection point is first linked to all said locations from substantially the commencement of said flow analysis.

Preferably said injection point remains so linked at substantially all times in said flow analysis subsequent to said first linking.

Thus, although the injection point must be linked to all these locations at some point in the flow analysis, and essentially continuously thereafter, the injection point may remain unlinked initially. Although this may decrease the accuracy of the final analysis adversely, it may nevertheless allow the analysis to yield useful results.

Preferably said injection is one of a plurality of injection points.

Preferably said synchronization of said flow fronts is checked periodically.

Preferably said flow fronts are synchronized if found not to be or no longer synchronized.

Preferably said checking is performed at each time step.

Thus, although for simple objects it is sufficient to synchronize flow fronts by linking the injection point or points to all locations, more complex parts require this synchronization at each calculational time step.

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Preferably said first and second generally opposed surfaces are one of a plurality of pairs of generally opposed surfaces.

5

Thus, where the existing techniques utilize a single, midplane representation of the object in which flow is to be modelled, and perform a simulation with this representation, the method according to the present invention utilizes only the outer surfaces defining the three dimensional object to create a computational domain. These correspond to representations (in a preferred embodiment, meshed representations) of the domain in which flow is to be simulated, and would comprise, for example, meshed representations of the top and bottom surfaces of a part. Thus, in such an example the invention could be said to utilize an outer skin mesh rather than a midplane mesh. Elements of the two surfaces are matched, based on the ability to identify a thickness between such elements. An analysis, substantially along conventional lines (by means, for example, of the Hele-Shaw equations), is then performed of the flow in each of these domains in which flow is to be simulated, but linked to ensure fidelity with the physical reality being modelled.

25

Preferably any unmatched elements of said first and second surfaces, being elements that could not be matched, are assigned thicknesses being the average of the thicknesses of adjacent matched elements where such adjacent matched elements exist, or of adjacent unmatched elements where such adjacent matched elements do not exist and said adjacent unmatched elements have been assigned thicknesses.

30

Thus, eventually all matched and unmatched elements of the first and second surfaces may be assigned thicknesses.

35

Preferably each element of an edge surface, being a surface

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between said first and second surfaces, and adjacent to either of said first or second surface is assigned a thickness proportional to the thickness of the element of said first or second surface to which said element of said edge surface is adjacent.

Preferably each said element of an edge surface is assigned a thickness between 0.5 and 1.5 times said thickness of the element of said first or second surface to which said element of said edge surface is adjacent.

Preferably each said element of an edge surface is assigned a thickness between 0.7 and 0.9 times said thickness of the element of said first or second surface to which said element of said edge surface is adjacent.

Still more preferably each said element of an edge surface is assigned a thickness 0.75 times said thickness of the element of said first or second surface to which said element of said edge surface is adjacent.

Preferably each element of an edge surface not adjacent to said first or second surface is assigned a thickness being the average of the thicknesses of adjacent elements of said edge surface that have been assigned thicknesses.

Assigning a thickness, therefore, to every element of both surfaces and of edge surfaces ensures that the greatest accuracy will be achieved in the simulation.

Preferably flow is simulated at a rate directly proportional to a desired flow rate for the object.

The desired flow rate will usually be a flow rate selected by a user based simply on the volume of the object to be filled and the desired fill-time.

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Preferably said rate is proportional to the ratio of computational domain volume of said object to real volume of said object.

- 5 More preferably said rate is substantially equal to the ratio of said computational domain volume to said real volume.

10 This approach may be used to compensate for the modification of the effective volume of the object being modelled, owing to the use of two domains (for example, associated with the top and bottom surfaces), rather than one meshed domain as in the midplane approach. The computational domain volume is thus this effective volume
15 used for the purposes of modelling the object, which most preferably will be approximately double the real volume.

Preferably the method is performed with first and second representations of said first and second surfaces
20 respectively comprising first and second meshes or lattices respectively, wherein said elements are interstices of said first and second meshes or lattices.

25 Preferably said elements are triangular or quadrilateral.

Preferably, when said elements are triangular, said elements are substantially equilateral.

30 Preferably said method includes creating said first and second representations.

In one embodiment the method includes creating improved representations of said first and second surfaces, whereby said elements are elements of said improved representations
35 and said method is performed with said improved representations.

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Preferably said first and second representations are, or are a part of, a representation or representations for stereolithography of said object.

5 Thus, computer representations of the two surfaces may be provided as input to the method, may be created by the method, or - if provided with representations of the surfaces - the method may create improved representations. As described above, particularly preferred representations
10 include those with elements comprising equilateral triangles.

In one embodiment of the invention the method described above is performed by a computer running a computer program
15 encoding said method for simulating fluid flow.

Preferably said method optionally includes corrections for non-isothermal temperature fields and/or non-Newtonian fluids.

20 Thus, known techniques for including the effects of non-isothermal temperature fields and non-Newtonian fluids may be included so that more physically faithful simulations may be performed, as well as faster simulations without
25 these corrections when speed is desirable, even at the expense of precision.

According to a second broad aspect of the present invention there is provided a method for simulating fluid flow within
30 a three dimensional object having first and second generally opposed surfaces including:

providing or creating first and second representations of said first and second surfaces respectively,

35 creating first and second improved representations from said first and second representations respectively,

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matching each element of said first improved representation of said first surface with an element of said second improved representation of said second surface between which a reasonable thickness may be defined,
5 wherein matched elements of said first improved representation constitute a first set of matched elements and matched elements of said second improved representation constitute a second set of matched elements,

specifying a fluid injection point,

10 performing a flow analysis using each set of said matched elements, whereby said injection point is linked to all locations on said first and second improved representations from which flow may emanate such that resulting flow fronts along said first and second improved
15 representations are synchronized.

Preferably the first and second representations are, or are a part of, a representation or representations for stereolithography of said object.

20

Preferably the first and second improved representations comprise small equilateral triangular elements.

According to a third broad aspect of the invention there is
25 provided a computer provided with or running a computer program encoding the method for simulating fluid flow described above.

30 In a fourth broad aspect of the invention there is provided a computer storage medium provided with a computer program embodying the method for simulating fluid flow described above.

35 According to a fifth broad aspect of the present invention there is provided a method for modelling a three dimensional object including:

specifying first and second generally opposed

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surfaces of said object,

forming first and second representations of said first and second surfaces respectively, wherein said first and second representations each comprise a plurality of elements,

matching pairs of elements of said first and second surfaces between which a reasonable thickness may be defined.

10 Preferably the first and second representations comprise first and second meshes or lattices respectively, wherein said elements are interstices of said first and second meshes or lattices.

15 Thus, the elements of the first representation are interstices of the first mesh, and the elements of the second representation are interstices of the second mesh.

20 Preferably said elements are triangular or quadrilateral.

Preferably, when said elements are triangular, said elements are substantially equilateral.

25 Preferably each element of each of said matched pairs of elements is assigned respectively said thickness.

30 Preferably any unmatched elements of said first and second surfaces, being elements that could not be matched, are assigned thicknesses being the average of the thicknesses of adjacent matched elements where such adjacent matched elements exist, or of adjacent unmatched elements where such adjacent matched elements do not exist and said adjacent unmatched elements have been assigned thicknesses.

35 Preferably each element of an edge surface, being a surface between said first and second surfaces, and adjacent to either of said first or second surface is assigned a

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thickness proportional to the thickness of the element of said first or second surface to which said element of said edge surface is adjacent.

- 5 Preferably each said element of an edge surface is assigned a thickness between 0.5 and 1.5 times said thickness of the element of said first or second surface to which said element of said edge surface is adjacent.
- 10 Preferably each said element of an edge surface is assigned a thickness between 0.7 and 0.9 times said thickness of the element of said first or second surface to which said element of said edge surface is adjacent.
- 15 Still more preferably each said element of an edge surface is assigned a thickness 0.75 times said thickness of the element of said first or second surface to which said element of said edge surface is adjacent.
- 20 Preferably each element of an edge surface not adjacent to said first or second surface is assigned a thickness being the average of the thicknesses of adjacent elements of said edge surface that have been assigned thicknesses.
- 25 According to a sixth broad aspect of the present invention there is provided a method for simulating fluid flow within a three dimensional object having first and second generally opposed surfaces including:
- 30 matching each element of said first surface with an element of said second surface between which a reasonable thickness may be defined, wherein matched elements of said first surface constitute a first set of matched elements and matched elements of said second surface constitute a second set of matched elements,
- 35 specifying a fluid injection point,
- performing a flow analysis using each set of said matched elements, and

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synchronizing flow fronts resulting from said flow analysis along said first and second surfaces.

Preferably said flow fronts are synchronized from
5 substantially the commencement of said flow analysis.

Alternatively said flow fronts are first synchronized after the commencement of said flow analysis.

10 According to a further broad aspect of the present invention there is provided a method for simulating fluid flow within a three dimensional object having first and second generally opposed surfaces including:

15 matching each element of said first surface with an element of said second surface between which a reasonable thickness may be defined, wherein matched elements of said first surface constitute a first set of matched elements and matched elements of said second surface constitute a second set of matched elements,

20 specifying a fluid injection point,
performing a flow analysis using said first set of matched elements,

adapting said flow analysis to said second set of matched elements, and

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synchronizing flow fronts resulting from said flow analysis and said adaptation of said flow analysis along said first and second surfaces.

5 Thus, it is possible in some cases to perform the method using only one of the sets of elements, and mapping the result onto the other set, and performing minor adaptation of the analysis to allow for any differences between the two surfaces.

10

Preferably the method is performed with first and second representations of said first and second surfaces respectively comprising first and second meshes or lattices respectively, wherein said elements are interstices of said
15 first and second meshes or lattices.

Preferably the elements are triangular, and most preferably equilateral triangles.

20 Preferably the elements are quadrilateral.

Preferably the method includes creating said first and second representations, and more preferably creating improved representations, either from the original surfaces
25 or from the first and second representations, and performing the method with elements of the representations or improved representations.

30 In all the above methods according to the present invention aspects it is preferred that the synchronization comprises matching pressure and temperature.

According to particular aspect of the present invention there is provided a method for simulating fluid flow within
35 a three dimensional object having first and second generally opposed surfaces including:

matching each element of said first surface with

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an element of said second surface between which a reasonable thickness may be defined, wherein matched elements of said first surface constitute a first set of matched elements and matched elements of said second surface constitute a second set of matched elements, specifying a plurality of fluid injection points, performing a flow analysis using each set of said matched elements, whereby said injection points are linked to all locations on said first and second surfaces from which flow may emanate such that resulting flow fronts along said first and second surfaces have matched flow rates.

A preferred embodiment of the invention will be described, by way of example, with reference to the accompanying drawings, in which:

Figure 4 is an example of a stereolithography mesh of the T-shaped object of figure 1;

Figure 5a shows an initial mesh used in a remeshing method according to the present invention;

Figures 5b-f show the mesh of figure 5a progressively remeshed according to the remeshing method;

Figure 6 shows the mesh of figure 4, remeshed according to the preferred embodiment of the present invention;

Figure 7a is a view of a mesh produced by conventional modelling techniques for a flat plate;

Figure 7b is a view of a corresponding mesh produced for a flat plate according to a preferred embodiment of the present invention;

Figure 8 illustrates surface matching for a flat plate according to the preferred embodiment;

Figure 9 is a view similar to figure 8 illustrating in cross-section the edges, matched surfaces and unmatched surfaces of another T-shaped object according to the preferred embodiment;

Figure 10 is a cross-sectional view illustrating

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the edges, matched surfaces, matched tapered surfaces, unmatched surfaces and unmatched edges of yet another T-shaped object according to the preferred embodiment;

Figure 11 is a view of a simple object showing
5 injection points;

Figure 12 is a view of an object comprising intersecting plates with a user selected injection point according to the preferred embodiment;

Figure 13 is a enlarged view of the object of
10 figure 12 showing the injection points required to allow flow to emanate correctly from the selected point according to the preferred embodiment;

Figure 14 is a cross-section of a plate, with a flow front advancing from the left and leading a little on
15 the top surface according to the preferred embodiment;

Figure 15 illustrates in a cross-sectional view the synchronization of flow in a ribbed plate, with the flow splitting and also filling a vertical rib according to the preferred embodiment;

Figure 16 illustrates in a cross-sectional view the assignment of identical pressures at nodes to
20 synchronize flow fronts at a rib according to the preferred embodiment; and

Figure 17 is a view similar to figure 3 generated
25 according to the preferred embodiment of the present invention.

A method for simulating fluid flow within a three dimensional object according to the present invention
30 involves three main steps:

- 1) Preparation of geometry,
- 2) Selection of injection points, and
- 3) Analysis.

Before these steps are effected, however, the input for the
35 simulation is prepared. Mesh generators for producing finite element meshes are generally an expensive addition to the base CAD system. Consequently many CAD

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installations have no finite element analysis (FEA) mesh generation capability. In order to facilitate the implementation of the invention, the method has been designed to avoid the need for a mesh generator. This is
5 done by using the type of mesh available for stereolithography. Stereolithography, a prototyping technology that is widely employed in industry, is used to produce prototype components for assembly or evaluation. It requires a stereolithography apparatus and takes as
10 input a computer file known as a "SLA" file. The ability to output SLA files is common in CAD systems. However, the type of triangulation created is not good enough for FEA. Characteristic of the SLA file is the inclusion of several very long, narrow triangles of high aspect ratio as shown
15 in figure 4.

A method in accordance with the present invention includes, therefore, a remeshing algorithm (or remesher) that uses as
20 input the triangles from a stereolithography SLA (or similar) file and remeshes to produce a mesh that may be used in analysis.

There are several steps involved in the input of a stereolithography mesh and its refinement into elements for
25 analysis. These steps are:

- Input of mesh,
- Checking of mesh,
- Classification of mesh into surfaces, and
- Remeshing.

30 Each of these is described below.

Input of Mesh

In the preferred embodiment, the input mesh is of the form used for stereolithography. Alternatively, however, the
35 input could be IGES surfaces (which would then be meshed internally), a surface mesh of quadrilaterals or a mix of quadrilaterals and triangles, tetrahedral or hexahedral

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meshes.

Checking of mesh

5 The input mesh is checked to ensure that it is closed and orientable. The mesh is consistently oriented so that a unit normal to each element points outward from the internal volume defining the solid region that represents the object or part being modelled. The volume of this region and the surface area of the mesh are calculated and
10 stored. The number of parts defined by the input mesh is also determined.

Classification of mesh into surfaces

15 The following properties for each element in the mesh are noted or calculated, and stored:

- Area,
- Normal at the element centroid,
- Edge lengths of the element,
- Internal angles at the vertices of the elements,
- 20 • Adjacent elements (the elements attached to each side of the element under consideration), and
- Bending angle between adjacent elements (the angle between normals of adjacent elements).

Nodal properties are then noted, calculated and stored.

25 These are:

- Measure of minimum curvature (calculated by looking at the elements attached to a node and noting the angle between each adjacent pair of elements, whereby the measure of minimum curvature is then the smallest such
30 angle between attached pairs of elements),
- Connecting elements (the set of elements connected to the node), and
- Number of edges connected to the node.

Surface edges are then calculated using a value of bending
35 angle to group elements into surfaces. Surfaces so formed are then classified into

- planar surfaces, and

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- low curvature surfaces.

Further classification is then done to produce high curvature surfaces and edges. The following properties of edges are noted or calculated and stored:

- Length,
- Bending angle,
- Direction of bending (in or out), and
- Adjacent Elements.

Surface loops are then created. These are defined to be the oriented edges of surfaces. It should be noted that a surface with a hole in it will have two associated loops - one for the outer edges and one describing the interior hole. Loop properties are then noted or calculated and stored:

- Length, and
- Edges connected to loop.

The following surface properties are noted or calculated and stored:

- Perimeter,
- Area,
- Nodes in surface,
- Elements in surface,
- Edges, and
- Minimum measure of curvature.

Remeshing

With the surfaces classified, the mesh associated with each surface is refined using a bisection algorithm which bisects the longest side of a triangle and creates extra elements. This is illustrated in figures 5a-f. Figure 5a shows the initial mesh. The mesh is refined by defining a node at the mid point of the longest element side and extending lines to vertices to define extra triangles. In figures 5b to 5f, the midpoint of the longest side (denoted by o) and the dotted lines extending from this point define the new elements. Remeshing continues until the elements satisfy a criterion on size.

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The result of the remeshing algorithm when applied to the mesh shown in figure 4 is shown in figure 6. In this regard the ideal triangle is equilateral: it may be seen
5 that the triangles in figure 6 are far more uniform and closer to this ideal.

The method will thus accept as input stereolithography files (usually generated with a ".stl" filename extension)
10 and other files that are similar such as "render" files (produced by "Pro-Engineer" with a ".slp" extension).

In practice any file format that describes a mesh (of, for example, a lattice or quadrilaterals) covering the outer
15 surfaces of the solid region may be used as input to the invention. The remesher is always used to improve the mesh quality and produce the triangular mesh for subsequent processing.

20 The first step is then the preparation of the geometry, in which the geometry of the three dimensional CAD solid model is processed by conventional techniques to provide a surface mesh covering the outer surfaces of a solid body, rather than a midplane mesh as required by the conventional
25 simulation approach. This distinction is depicted in figures 7a and 7b. Figure 7a shows the midplane mesh for a simple plate required by the conventional technique, whereas figure 7b shows the mesh employed according to the present invention for the same object. Further, the flow
30 front must be synchronized on both sides of the surface in which the material flows. If material is injected at the centre of the plate, then, in the conventional case, the material flows to the boundary of the part or object and stops without any difficulty. For the surface mesh on the
35 solid model (figure 7b) the material will flow to the outer edge, across the edge and then under the top surface. This is clearly not indicative of the physical phenomenon of

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flow in a plate and so, according to the invention, there are imposed some constraints on the flow when using the surface mesh. These constraints are that the injection point must link to all surfaces from which flow will emanate and the flow front must be synchronized along the top and bottom meshes of the surface mesh. Preferably this link is established from the commencement of the flow analysis, but a successful (if somewhat less accurate) analysis of the flow can still be performed if this linking commences subsequently. To perform these tasks the surface mesh must be categorized into surfaces which are then further classified to facilitate injection node selection and synchronization. Thus, according to the present invention, the surface mesh is then grouped into individual surfaces and classified. The categories of surfaces are:

- Matched,
- Unmatched, and
- Edges.

Matched surfaces are defined to be those that have a relationship with another surface such that a notion of thickness between them can be sensibly defined. Figure 8 illustrates this idea. Surfaces abcd and efgh may clearly be associated so that the thickness t between them is defined. Surfaces abfe, bcgf, cdhg and daeh are edge surfaces and unmatched.

Figure 9 further clarifies these concepts. This figure shows a cross-section through a filleted rib. Here ab, cd and gh are on edge surfaces. Lines aj and ed are matched to bc, fg and hi are matched and the curved sections ij and ef are unmatched. It should be noted that it is not possible to sensibly define a thickness of unmatched surfaces in the manner described above. As a final example, figure 10 illustrates a tapered rib cross-section. Here ab, cd and gh are edges as in figure 9. Lines aj and ed are matched to line bc, and the curved lines ef and ij are unmatched as in figure 9. However fg and hi are still

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considered matched despite the taper. Clearly, if the taper is extreme it is possible that the surfaces forming the tapered ribs may not be matched.

- 5 When surfaces have been classified it is possible to assign to elements on matched surfaces a thickness equal to the distance between the surfaces. Elements on edge surfaces are given the thickness of the matched surfaces to which they are attached. Finally elements on unmatched surfaces
10 are given the average thickness of surrounding elements on matched surfaces.

According to the present invention, the mesh on each side of the object is analyzed. A key aspect in this is
15 obtaining a similar flow front on each side of the matched surfaces. As the entry point for flow is the injection node and is selected by the user, the method ensures that, regardless of where the user chooses to inject plastic, all matched surfaces near the point are tied to the injection
20 node. "Tied" implies that the same pressure and temperature of melt at the injection node is given to all other tied nodes.

Figure 11 shows a cross-section of a rectangular plate.
25 Point A is where the user chooses to inject plastic, point AA is the corresponding point on the other side of the surface. Point AA is automatically determined in accordance with the invention using the information from the classification of surfaces described above. Injection
30 at this point ensures that the flow is matched on top and bottom surfaces. Similarly, point B is the point chosen by the user and BB is the corresponding point determined by the method in accordance with the invention to ensure that flow is matched along top and bottom surfaces.

35

The selection of injection node(s) can be quite complex. This is illustrated in figure 12, which shows an object

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composed of intersecting plates. The small arrow near the point of intersection of the plates indicates the user selected injection point. Figure 13 is an enlarged view of the injection area and shows the actual injection points required to allow the flow to emanate correctly from the selected point. In this case eight injection points are required one of which is supplied by the user and the other seven are determined by the invention.

10 This method identifies which points need to be linked to the selected injection point with the concept of matching. For a given injection point specified by the user, a set consisting of all surfaces which are matched to all surfaces connected to the injection point is defined. The following steps are then performed:

1. For each surface in this set, the point closest to the selected injection point is noted. These closest points form a set of points that are potentially to be linked to the user selected injection point.
- 20 2. Each member of the set of potential injection points is checked to see if it is already an injection point specified by the user. If it has already been so determined, it is omitted from the set.
3. For each potential injection point remaining, a set consisting of all surfaces which are matched to all surfaces connected to the potential injection point is defined.
- 25

These steps are repeated until the set of potential points is unchanged. The set then forms the set of points to be linked to the user specified injection point.

30

This procedure may be readily understood for the simple geometry of two crossed plates, for which the user specifies injection at the intersection of the plates. In the event that the surfaces connected to the specified injection point(s) are not matched to any other surfaces,

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no attempt is made to link other points to the injection point(s). Instead, flow is allowed to emanate until it reaches points attached to surfaces that are matched to opposing surfaces. The flow fronts are then synchronised
5 on the opposing surfaces by assigning links between points on the opposing surfaces in a manner similar to that described above for linking points to the injection point.

Analysis uses a Hele-Shaw type solver. The injection flow
10 rate is approximately double that for the volume of the object as each element in the surface mesh has a thickness equal to the gap thickness and so the mesh volume is approximately double that of the object. The time step for flow front advancement is determined by the geometric
15 connectivity of the control volumes attached to each node.

The solver has the ability to synchronize flow on matched surfaces during analysis. Figure 14 shows a cross-section of a plate where it is assumed that the flow front is
20 advancing from the left and is leading a little on the top surface. By definition each node may be empty, partially filled or filled. On each time step, whether all the nodes belonging to an element are filled is checked. The instant this occurs the element is defined to be the current last
25 element to fill and a line is drawn from its centroid to its matched element (the matched element is known from the surface classification described above) defining the check point. This "check line" is indicated in figure 14. The nearest node to the check point is then assigned the same
30 pressure as the last node to fill, as indicated in figure 14. Flow synchronization is done for all matched surfaces and all elements near the flow front (on top and bottom surfaces) are checked at each time step.

35 Synchronization is not performed on unmatched surfaces.

An example highlighting the role of synchronization is

- 25 -

shown in figure 15, which shows the cross-section of a ribbed plate. The flow will split physically and fill the vertical rib as well as continuing to the right. Owing to the use of the surface mesh it is necessary to impose synchronization or the flow will continue up through node F to the top of the rib and then down to E and C. This is performed by using matching. Since the element comprising nodes D and F and the element comprising nodes C and E will be matched (as they are associated with matched surfaces) it is possible to assign the same pressures at nodes to synchronize the fronts. This is illustrated in Figure 16. Here a line from the centroid of the element comprising nodes D and F is constructed to its matched element (comprising nodes C and E) to define the check point. As the nearest node to the check point is C, it is given the same pressure as node D for all subsequent time. Flow now emanates from node C as shown and so the flow goes up the rib on both sides as required. When establishing links for synchronization, links are only made to empty nodes to which are attached only empty nodes.

A sample result of the analysis according to the present invention is shown in figure 17. This figure corresponds to figure 3, which shows the results of the comparable, conventional analysis of the same solid model shown in figure 1. As the present invention uses a surface mesh rather than a midplane mesh, the results are displayed on the solid model (figure 17) rather than on the midplane representation as in conventional analysis (figure 3). Apart from being more natural for the operator, the display is visually more meaningful.

Fundamental quantities calculated by the invention, therefore, include:

- the position of the melt front at any time (known as "filling contours"),
- the pressure at the injection node and the

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pressure distribution throughout the plastic at any time during filling or packing phases (known as a "pressure distribution"), and

- the temperature of the plastic melt at any point within the part at any time during filling or packing phases (known as a "temperature distribution").

These may be displayed directly or processed to provide derived information to the user of the program, such as distributions of shear rate, shear stress, velocity, viscosity, direction of flow and orientation of reinforcing material. On the basis of this derived information and the fundamental calculated quantity data, changes to the component geometry, position of injection locations (gates), processing conditions used by the injection molding machine or material for molding may be evaluated for their efficacy in improving the quality or manufacturability of the part. This is generally an iterative process in which an analysis is performed, results are considered and changes made to bring about an improvement. Another analysis is then performed to ensure that the changes have indeed improved the results. Frequently changes to the part geometry are revealed. These are made in the CAD system and the revised model is subjected to further analysis. It is this aspect which is assisted by the invention as the need for the designer to recreate a new model for analysis every time a change is made is removed.

Thus, an increase in the speed of evaluating of proposed part shapes is achieved.

Modifications within the spirit and scope of the invention may readily be effected by persons skilled in the art. For example, linking may be performed in alternative methods such as, where multiple injection points are selected by a user, assigning the same flow rate to the linked nodes. It is to be understood, therefore, that this invention is not

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limited to the particular embodiments described by way of example hereinabove.

CLAIMS:

1. A method for simulating fluid flow within a three dimensional object having first and second generally
5 opposed surfaces including:
 matching each element of said first surface with
 an element of said second surface between which a
 reasonable thickness may be defined, wherein matched
 elements of said first surface constitute a first set of
10 matched elements and matched elements of said second
 surface constitute a second set of matched elements,
 specifying a fluid injection point,
 performing a flow analysis using each set of said
matched elements, whereby said injection point is linked to
15 all locations on said first and second surfaces from which
 flow may emanate such that resulting flow fronts along said
 first and second surfaces are synchronized.
2. A method as claimed in claim 1, including linking
20 said injection point to all of said locations substantially
 at the commencement of said flow analysis.
3. A method for simulating fluid flow within a three dimensional object having first and second generally
25 opposed surfaces including:
 providing or creating first and second
 representations of said first and second surfaces
 respectively,
 creating first and second improved representations
30 from said first and second representations respectively,
 matching each element of said first improved
 representation of said first surface with an element of
 said second improved representation of said second surface
 between which a reasonable thickness may be defined,

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wherein matched elements of said first improved representation constitute a first set of matched elements and matched elements of said second improved representation constitute a second set of matched elements,
5 specifying a fluid injection point,
performing a flow analysis using each set of said matched elements, whereby said injection point is linked to all locations on said first and second improved representations from which flow may emanate such that
10 resulting flow fronts along said first and second improved representations are synchronized.

4. A method as claimed in claim 3, wherein said first and second improved representations comprise small
15 equilateral triangular elements.

5. A method as claimed in claim 1, wherein said elements are substantially equilateral triangles, and
20 comprising representing said first and second surfaces by means of respective representations that are, or are a part of, a representation or representations for stereolithography of said object.

25 6. A method for modelling a three dimensional object including:
specifying first and second generally opposed surfaces of said object,
forming first and second representations of said
30 first and second surfaces respectively, wherein said first and second representations each comprise a plurality of elements,

- 30 -

matching pairs of elements of said first and second surfaces between which a reasonable thickness may be defined.

- 5 7. A method as claimed in claim 6, wherein said first and second representations comprise first and second meshes or lattices respectively, wherein said elements are interstices of said first and second meshes or lattices.
- 10 8. A method as claimed in either claim 6 or 7, wherein each element of each of said matched pairs of elements is assigned respectively said thickness.
- 15 9. A method as claimed in claim 8 wherein unmatched elements of said first and second surfaces are assigned thicknesses being the average of the thicknesses of surrounding, matched elements of said first and second surfaces.
- 20 10. A method for simulating fluid flow within a three dimensional object having first and second generally opposed surfaces including:
- 25 matching each element of said first surface with an element of said second surface between which a reasonable thickness may be defined, wherein matched elements of said first surface constitute a first set of matched elements and matched elements of said second surface constitute a second set of matched elements, specifying a fluid injection point,
- 30 performing a flow analysis using each set of said matched elements, and
- synchronizing flow fronts resulting from said flow analysis along said first and second surfaces.

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11. A method as claimed in claim 10, wherein said flow fronts are synchronized from substantially the commencement of said flow analysis.

5 12. A method as claimed in claim 10, comprising first synchronizing said flow fronts after the commencement of said flow analysis.

13. A method as claimed in any one of claims 10 to 12,
10 wherein said injection point remains linked to all said locations at substantially all times in said flow analysis subsequent to being first so linked.

14. A method as claimed in any one of claims 10 to 13,
15 wherein said injection point is one of a plurality of injection points.

15. A method as claimed in any one of claims 10 to 14,
comprising checking the synchronization of said flow fronts
20 periodically.

16. A method as claimed in claim 15, wherein said checking is performed at each time step.

25 17. A method as claimed in any one of claims 10 to 16, comprising synchronizing said flow fronts if found not to be or no longer to be synchronized.

18. A method as claimed in any one of claims 10 to 17,
30 wherein said first and second generally opposed surfaces are one of a plurality of pairs of generally opposed surfaces.

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19. A method as claimed in any one of claims 10 to 18, wherein any unmatched elements of said first and second surfaces, being elements that could not be matched, are assigned thicknesses being the average of the thicknesses of adjacent matched elements where such adjacent matched elements exist, or of adjacent unmatched elements where such adjacent matched elements do not exist and said adjacent unmatched elements have been assigned thicknesses.
20. A method as claimed in any one of claims 1, 9 and 19, wherein each element of an edge surface, being a surface between said first and second surfaces, and adjacent to either of said first or second surface is assigned a thickness proportional to the thickness of the element of said first or second surface to which said element of said edge surface is adjacent.
21. A method as claimed in claim 20, wherein each said element of an edge surface is assigned a thickness between 0.5 and 1.5 times said thickness of the element of said first or second surface to which said element of said edge surface is adjacent.
22. A method as claimed in claim 21, wherein each said element of an edge surface is assigned a thickness between 0.7 and 0.9 times said thickness of the element of said first or second surface to which said element of said edge surface is adjacent.
23. A method as claimed in claim 22, wherein each said element of an edge surface is assigned a thickness approximately 0.75 times said thickness of the element of said first or second surface to which said element of said edge surface is adjacent.

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24. A method as claimed in claim 23, wherein each element of an edge surface not adjacent to said first or second surface is assigned a thickness being the average of the thicknesses of adjacent elements of said edge surface that have been assigned thicknesses.

25. A method as claimed in any one of claims 10 to 24, wherein flow is simulated at a rate directly proportional to a desired flow rate for the object.

26. A method as claimed in claim 25, wherein said rate is proportional to the ratio of computational domain volume of said object to real volume of said object.

15

27. A method as claimed in claim 26, wherein said rate is substantially equal to the ratio of said computational domain volume to said real volume.

28. A method for simulating fluid flow within a three dimensional object having first and second generally opposed surfaces including:

matching each element of said first surface with an element of said second surface between which a reasonable thickness may be defined, wherein matched elements of said first surface constitute a first set of matched elements and matched elements of said second surface constitute a second set of matched elements, specifying a fluid injection point, performing a flow analysis using said first set of matched elements, adapting said flow analysis to said second set of matched elements, and

30

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synchronizing flow fronts resulting from said flow analysis and said adaptation of said flow analysis along said first and second surfaces.

5 29. A method as claimed in any one of claims 1 to 28, comprising performing said method with first and second representations of said first and second surfaces respectively comprising first and second meshes or lattices respectively, wherein said elements are interstices of said
10 first and second meshes or lattices.

30. A method as claimed in claim 29, wherein said first and second representations are, or are a part of, a representation or representations for stereolithography of
15 said object.

31. A method as claimed in any one of claims 1, 10 and 28, wherein said method includes making corrections for non-isothermal temperature fields, for non-Newtonian fluids
20 or for both non-isothermal temperature fields and/or non-Newtonian fluids.

32. A method as claimed in any one of claims 1, 3, 6 and 28, wherein said elements are triangular.
25

33. A method as claimed in any one of claims 1, 3, 6 and 28, wherein said elements are quadrilateral.

34. A method as claimed in claim 32, wherein said
30 elements are substantially equilateral.

35. A method as claimed in claim 29, wherein said method includes creating said first and second representations.

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36. A method as claimed in any one of claims 29 to 35,
wherein said method includes creating improved
representations of said first and second surfaces, whereby
5 said elements are elements of said improved representations
and said method is performed with said improved
representations.

37. A method as claimed in any one of claims 1, 3 and
10 10, comprising performing synchronization by matching
pressure and temperature.

38. A computer-implemented method for producing
simulations of fluid flows within a three dimensional
15 object, the method comprising:
specifying first and second generally opposed
surfaces of said object,
matching pairs of elements of said first and
second surfaces between which a reasonable thickness may be
20 defined,
specifying a fluid injection point, and
performing a flow analysis whereby resulting flow
fronts along said first and second surfaces are
synchronized.

25 39. A method as claimed in claim 38, further
comprising forming first and second representations of said
first and second surfaces, respectively, wherein said first
and second representations comprise first and second meshes
30 or lattices respectively, and wherein said elements are
interstices of said first and second meshes or lattices.

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40. A method as claimed in either claim 38 or 39, wherein each element of each of said matched pairs of elements is assigned respectively said thickness.

5 41. A method as claimed in any one of claims 38 to 40, wherein matched elements of said first surface constitute a first set of matched elements and matched elements of said second surface constitute a second set of matched elements.

10 42. A method as claimed in claim 41, comprising:
providing or creating first and second
representations of said first and second surfaces
respectively;

creating first and second improved representations
15 from said first and second representations respectively;
performing said method with said first and second
improved representations of said respective surfaces,
whereby each element of said first surface comprises a
respective element of said first improved representation
20 and each element of said second surface comprises a
respective element of said second improved representation,
so that matching each element of said first surface with an
element of said second surface comprises matching each
element of said first improved representation with an
25 element of said second improved representation, said first
set of matched elements comprise matched elements of said
first improved representation, said second set of matched
elements comprise matched elements of said first improved
representation and said injection point is linked to all
30 locations on said first and second improved representations
from which flow may emanate such that resulting flow fronts
along said first and second improved representations are
synchronized.

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43. A method of manufacturing an object having first and second generally opposed surfaces, including simulating fluid flow within said object according to the method of any one of claims 1, 3, 10, 28 and 38.

5

44. A method of manufacturing an object including modelling said object according to the method of claim 6.

45. An object manufactured according to the method of either claim 43 or 44.

10

46. A computer program product stored on a computer readable medium adapted for causing a computer to perform the steps of the method of any one of claims 1 to 42.

15

47. A computer readable medium, having a program recorded thereon, where the program is to make a computer execute a method as defined in any one of claims 1 to 42.

48. A method as claimed in any one of claims 1 to 42, wherein said method is performed by a computer running a computer program encoding said method.

20

49. A computing device provided with or running a computer program encoding a method for simulating fluid flow as claimed in any one of claims 1 to 42.

25

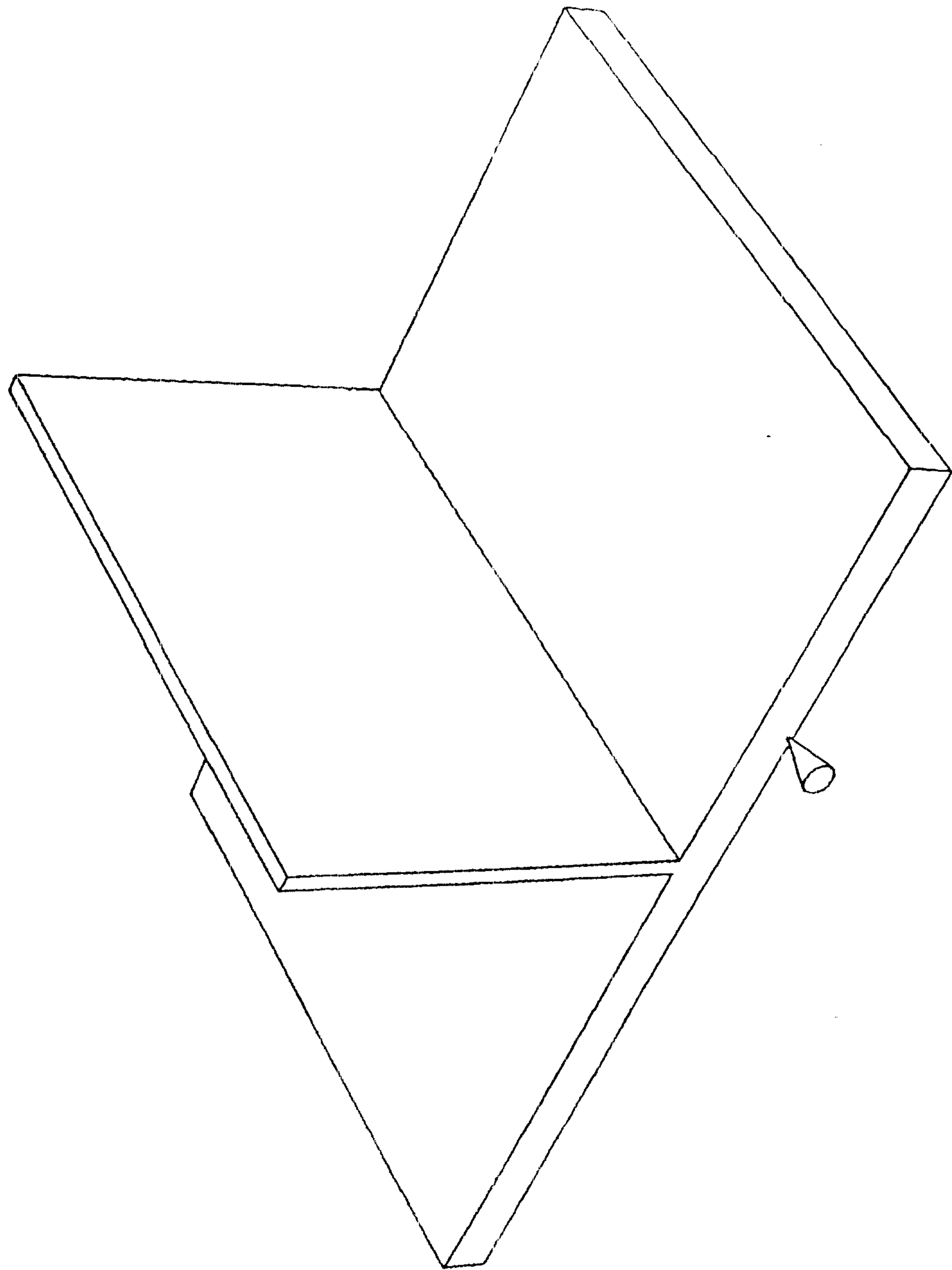


Figure 1

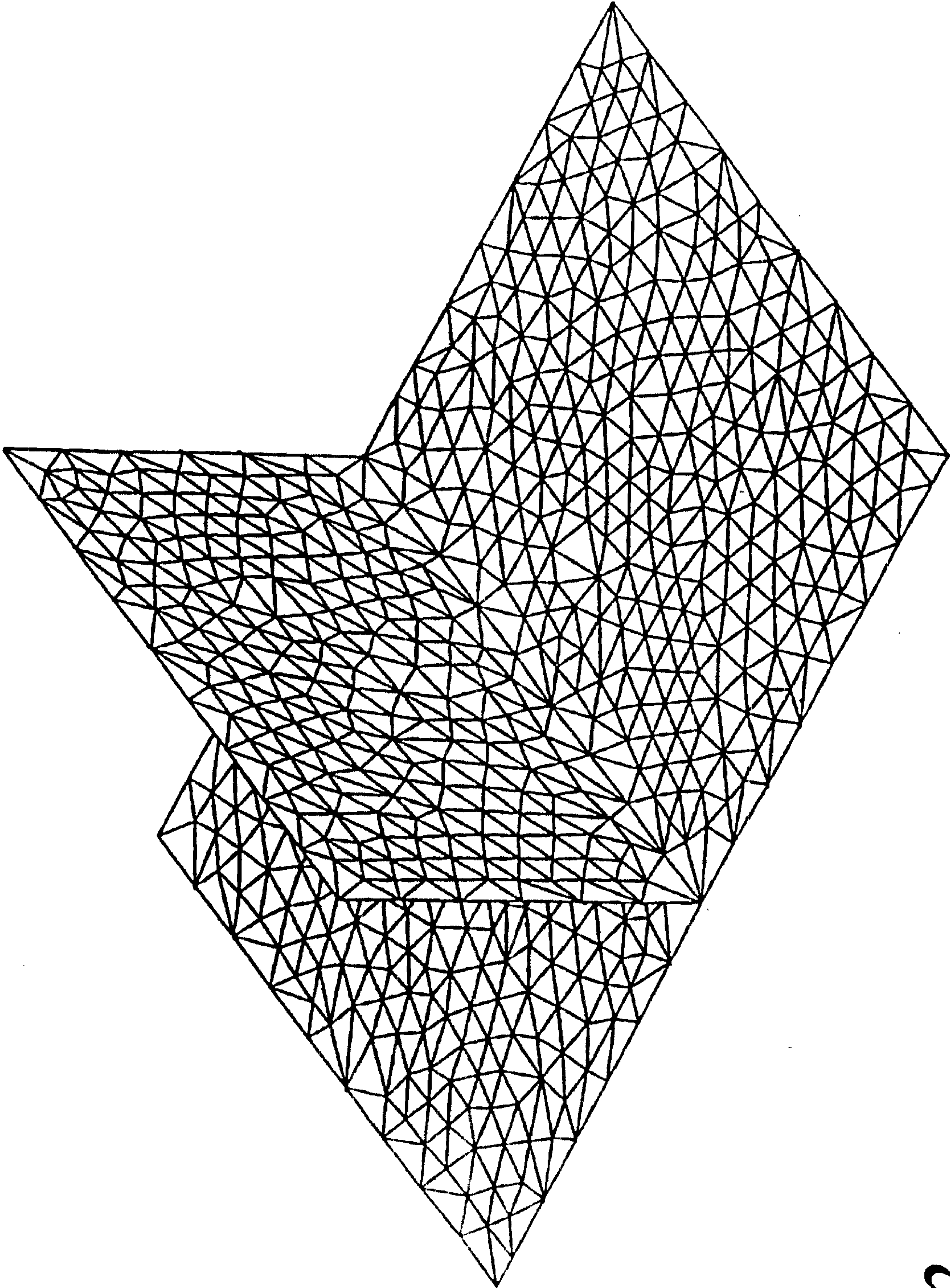


Figure 2

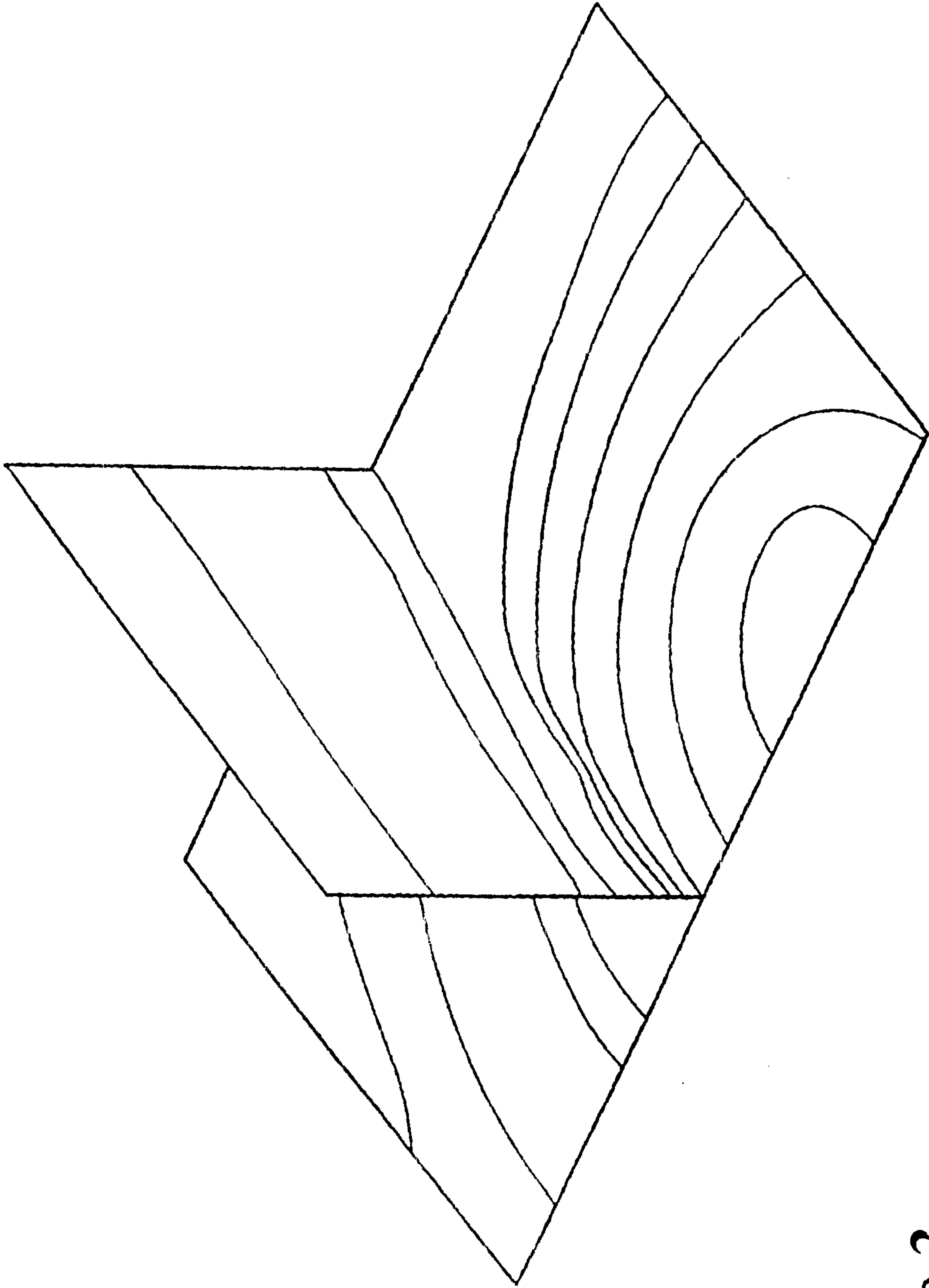


Figure 3

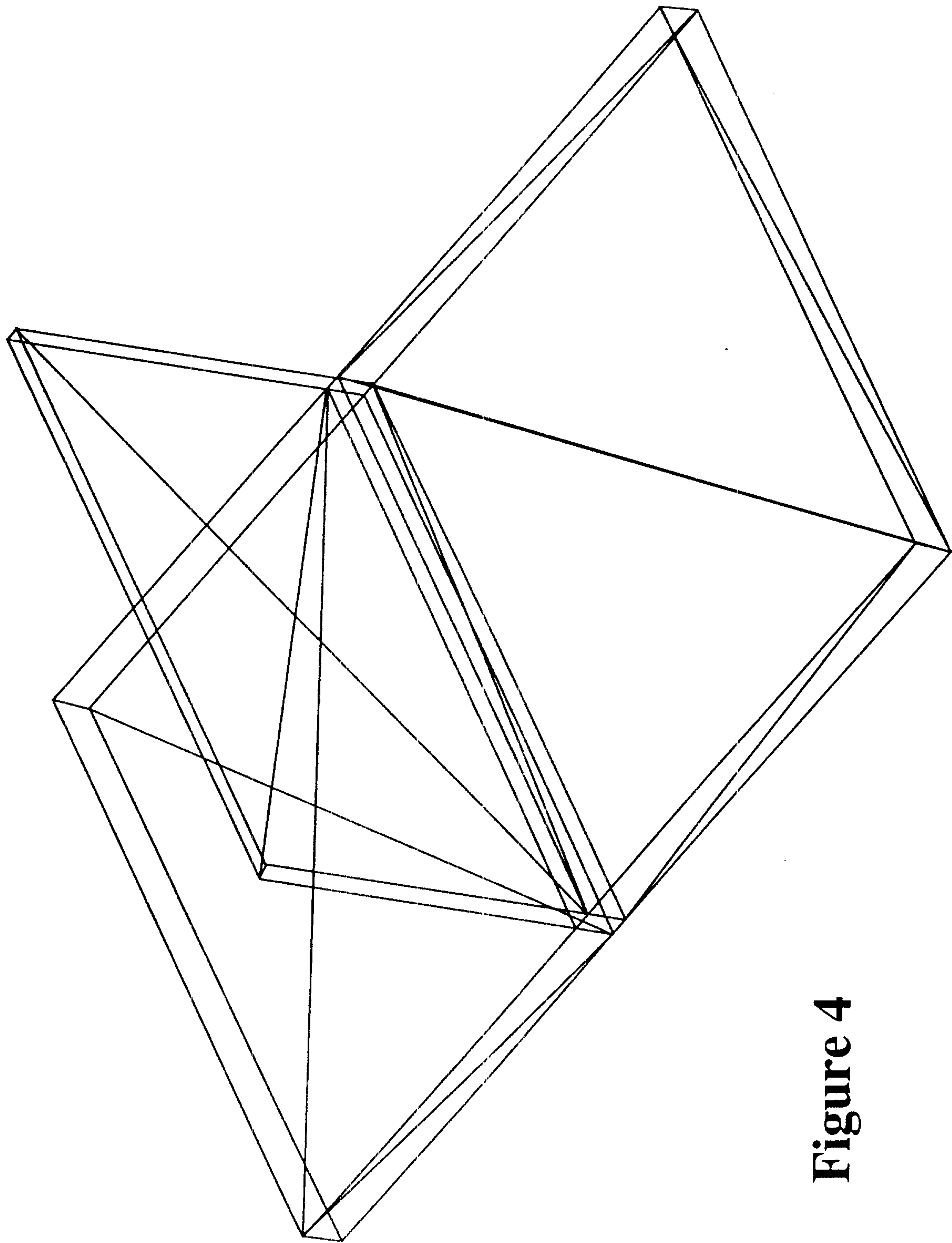


Figure 4

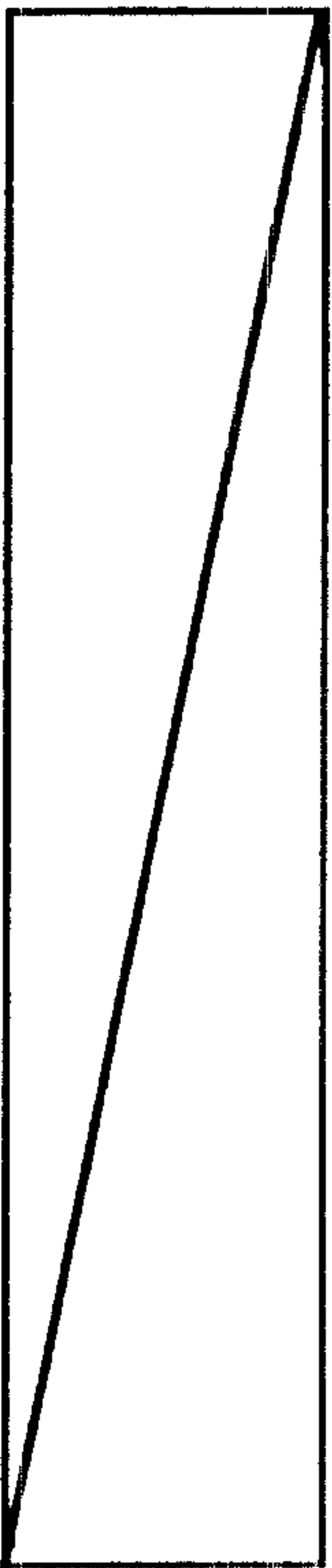


Figure 5a

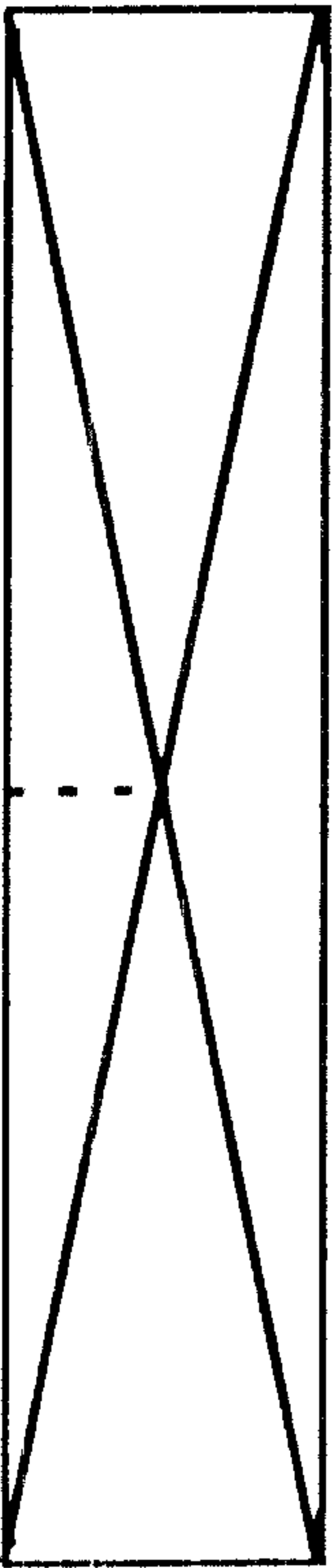


Figure 5c

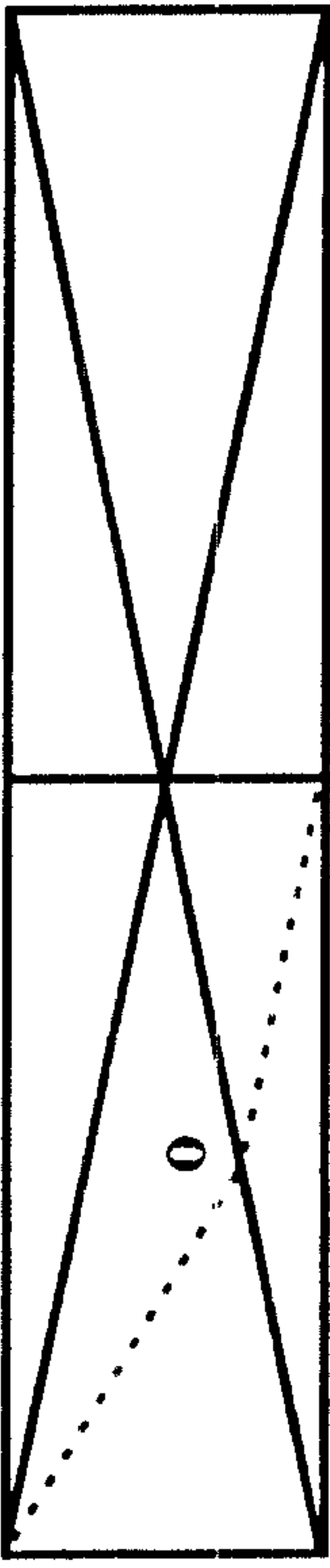


Figure 5e

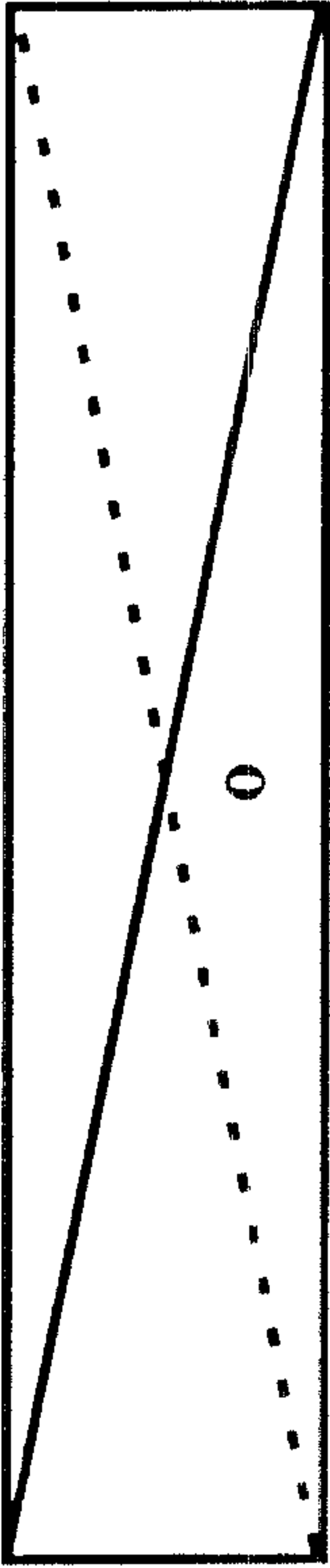


Figure 5b

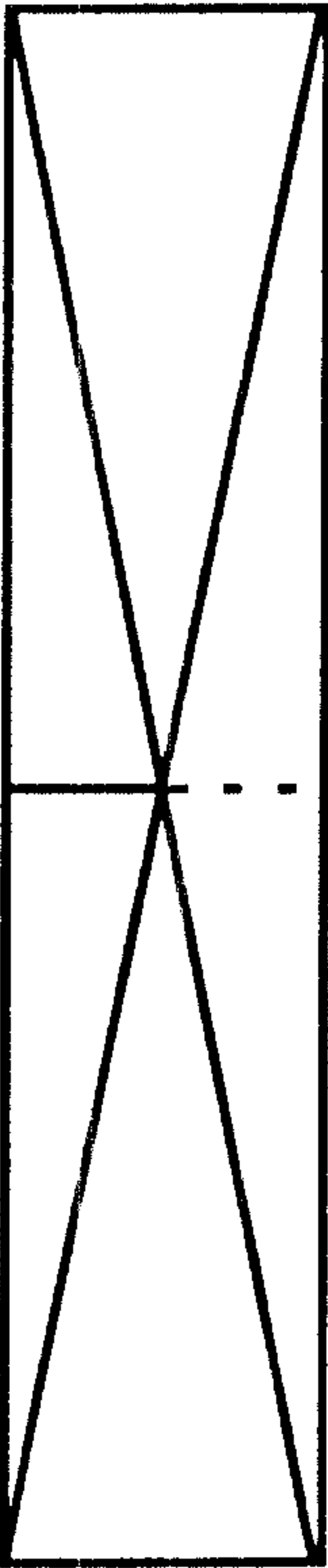


Figure 5d

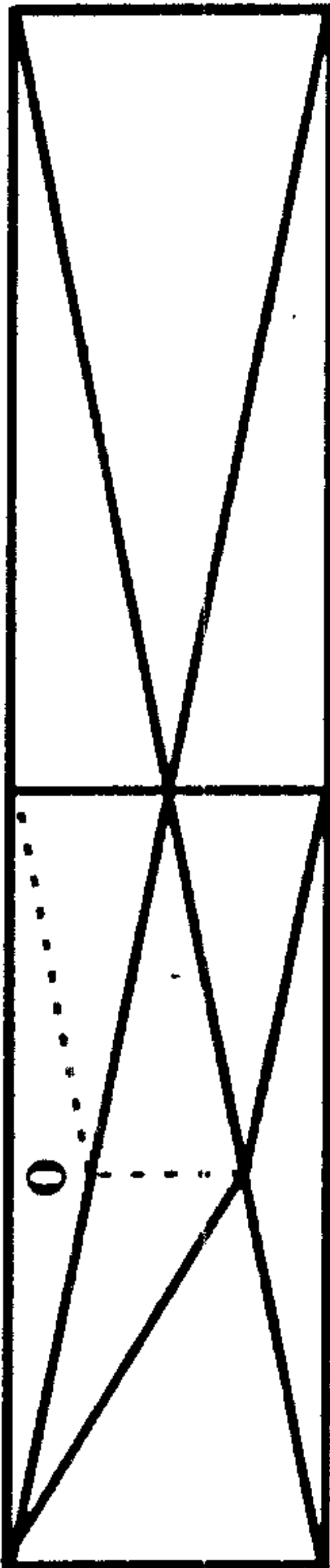


Figure 5f

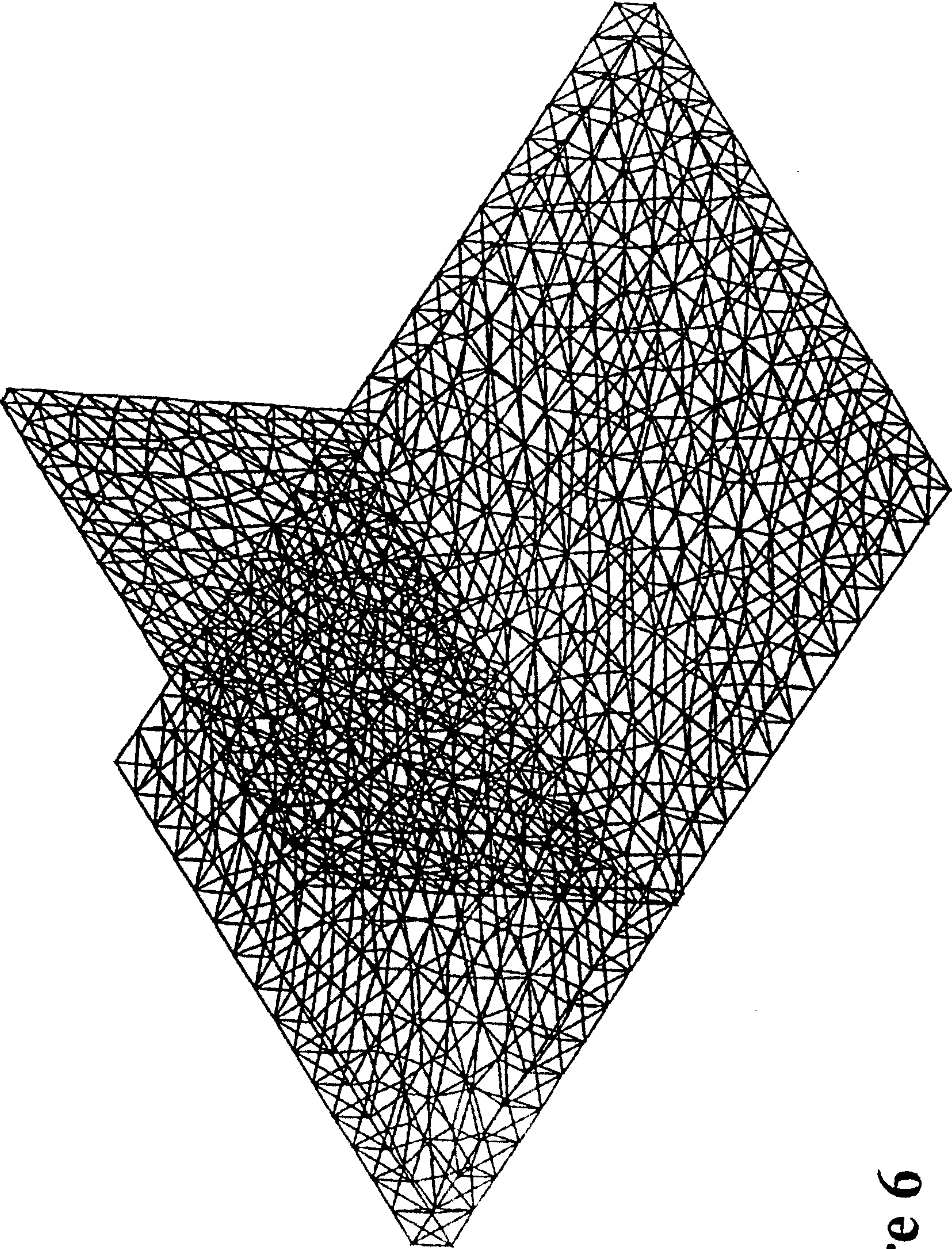


Figure 6

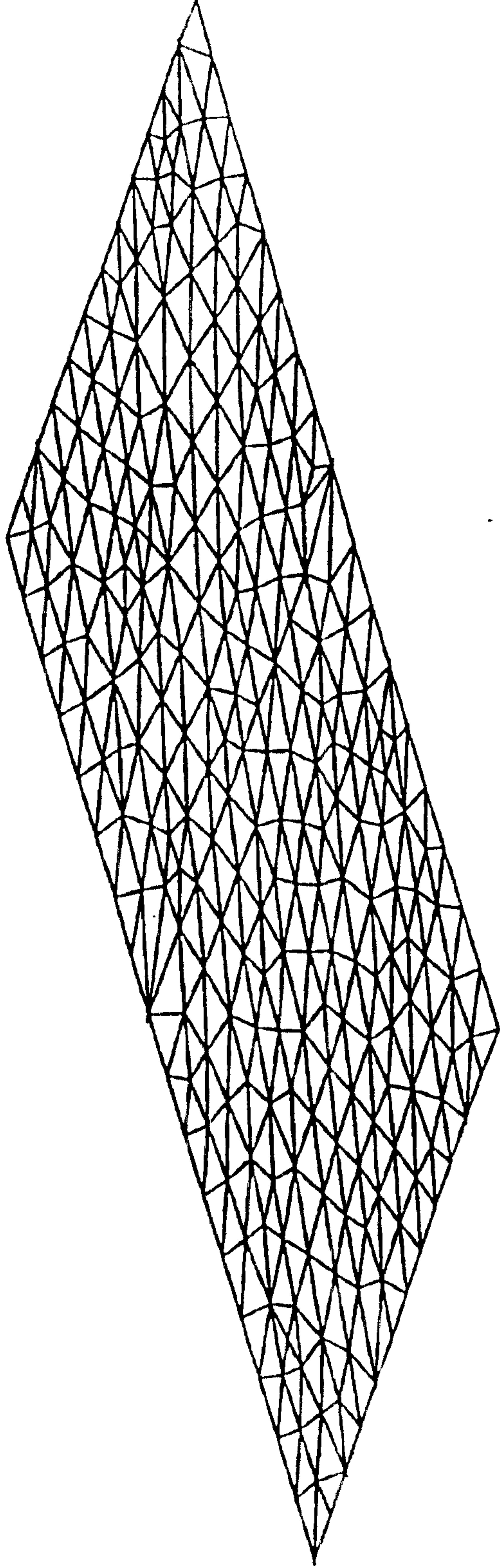


Figure 7a

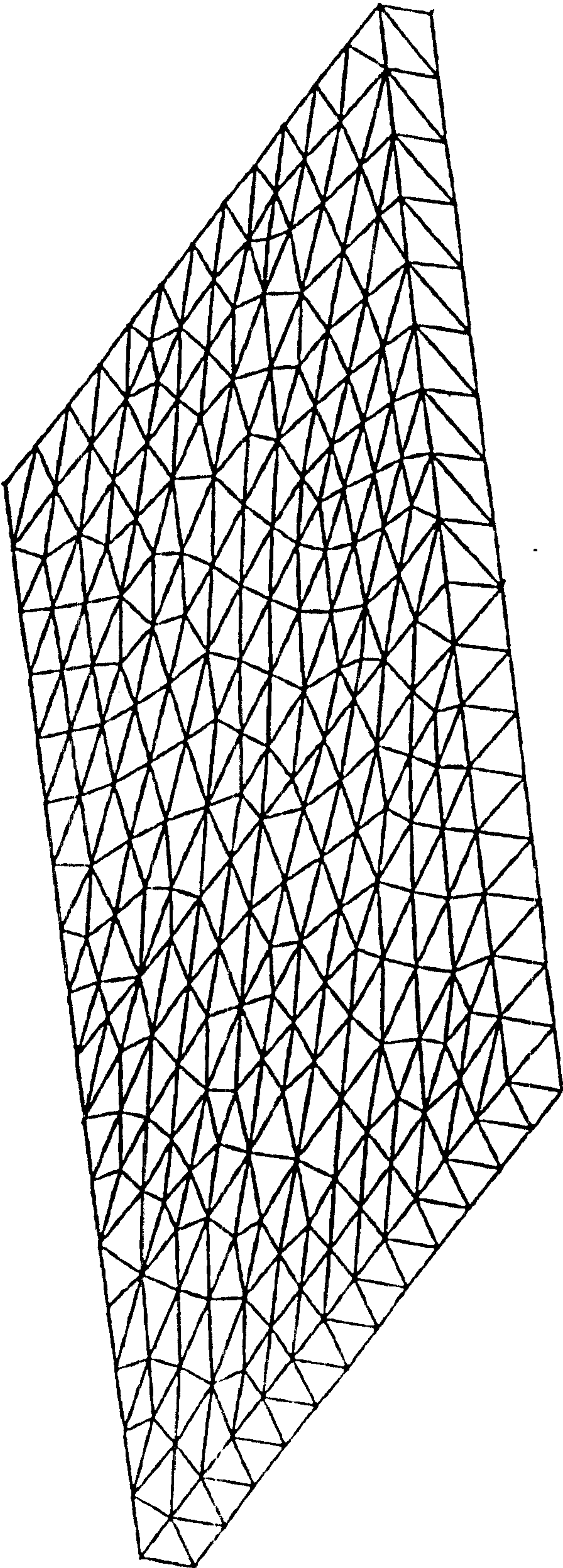


Figure 7b

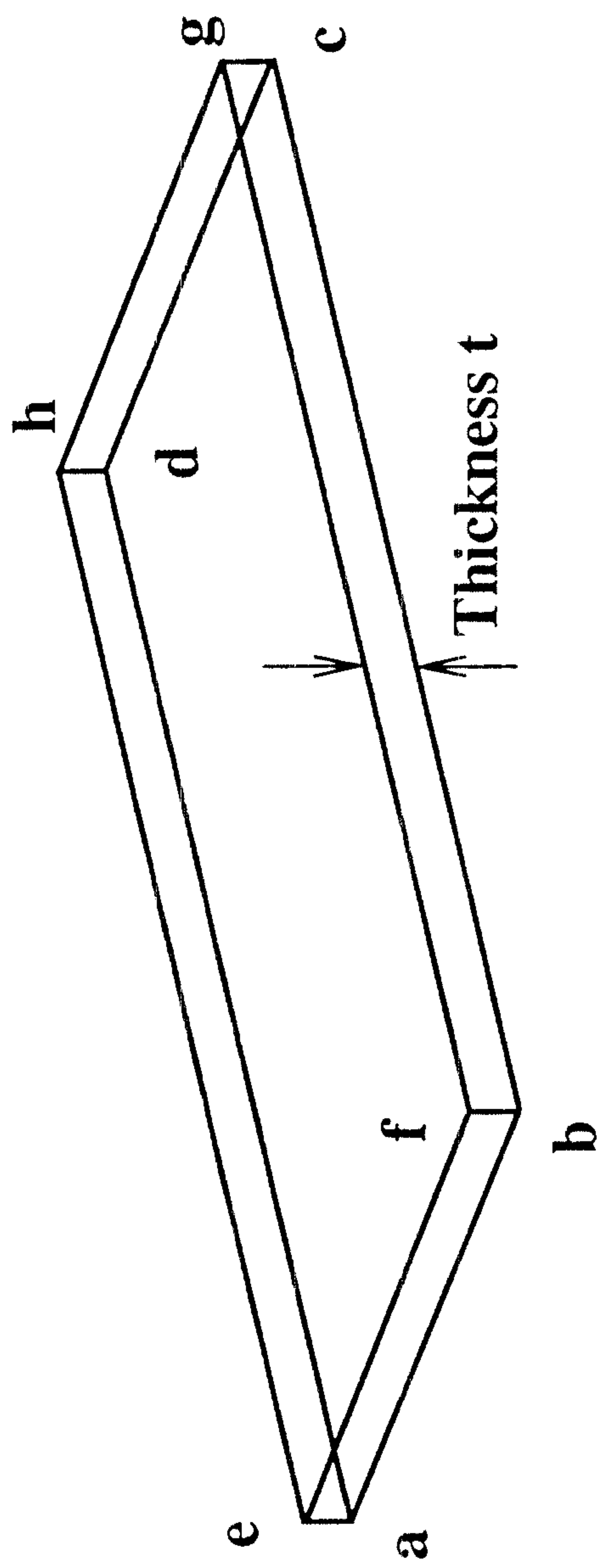


Figure 8

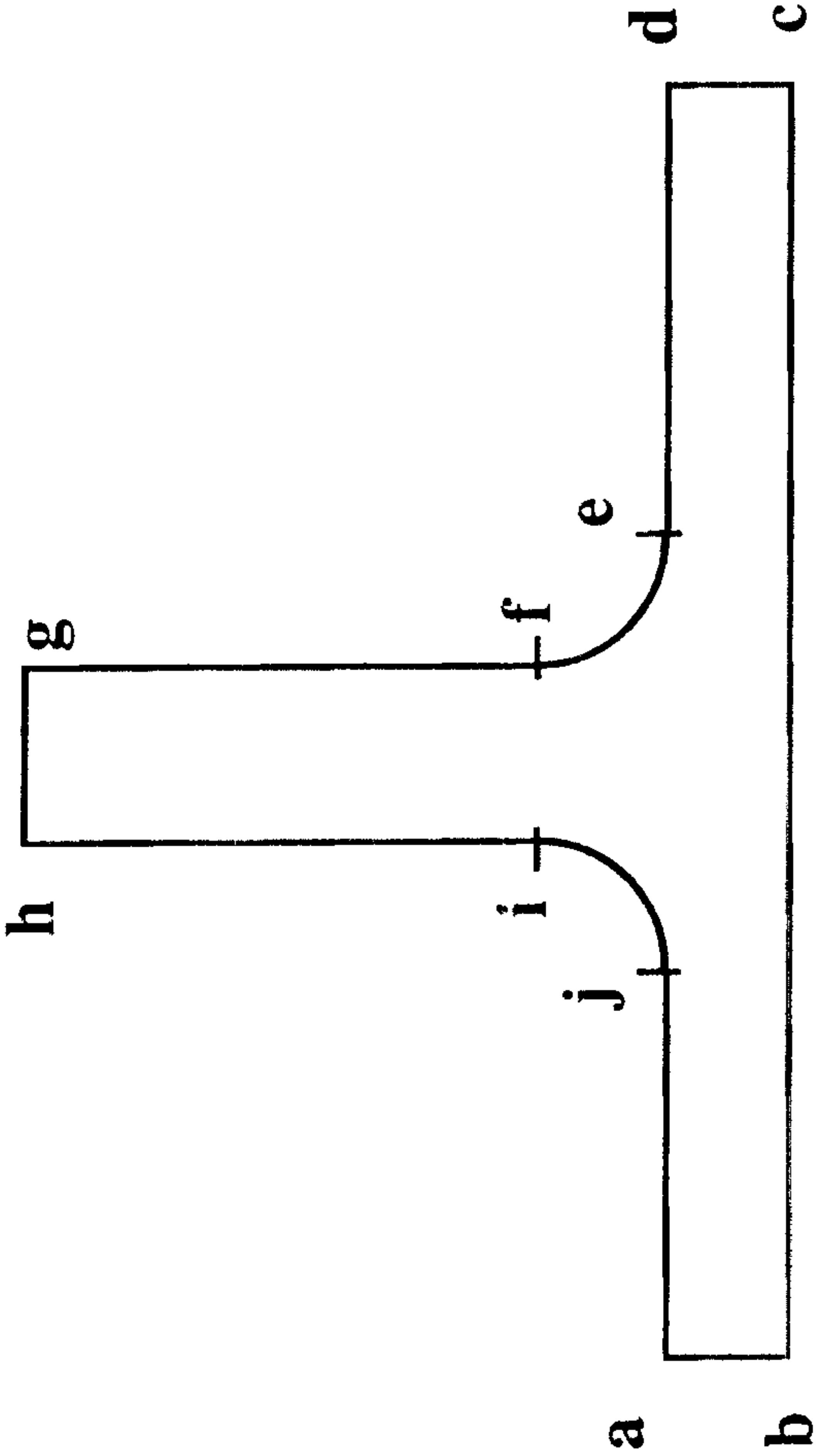


Figure 9

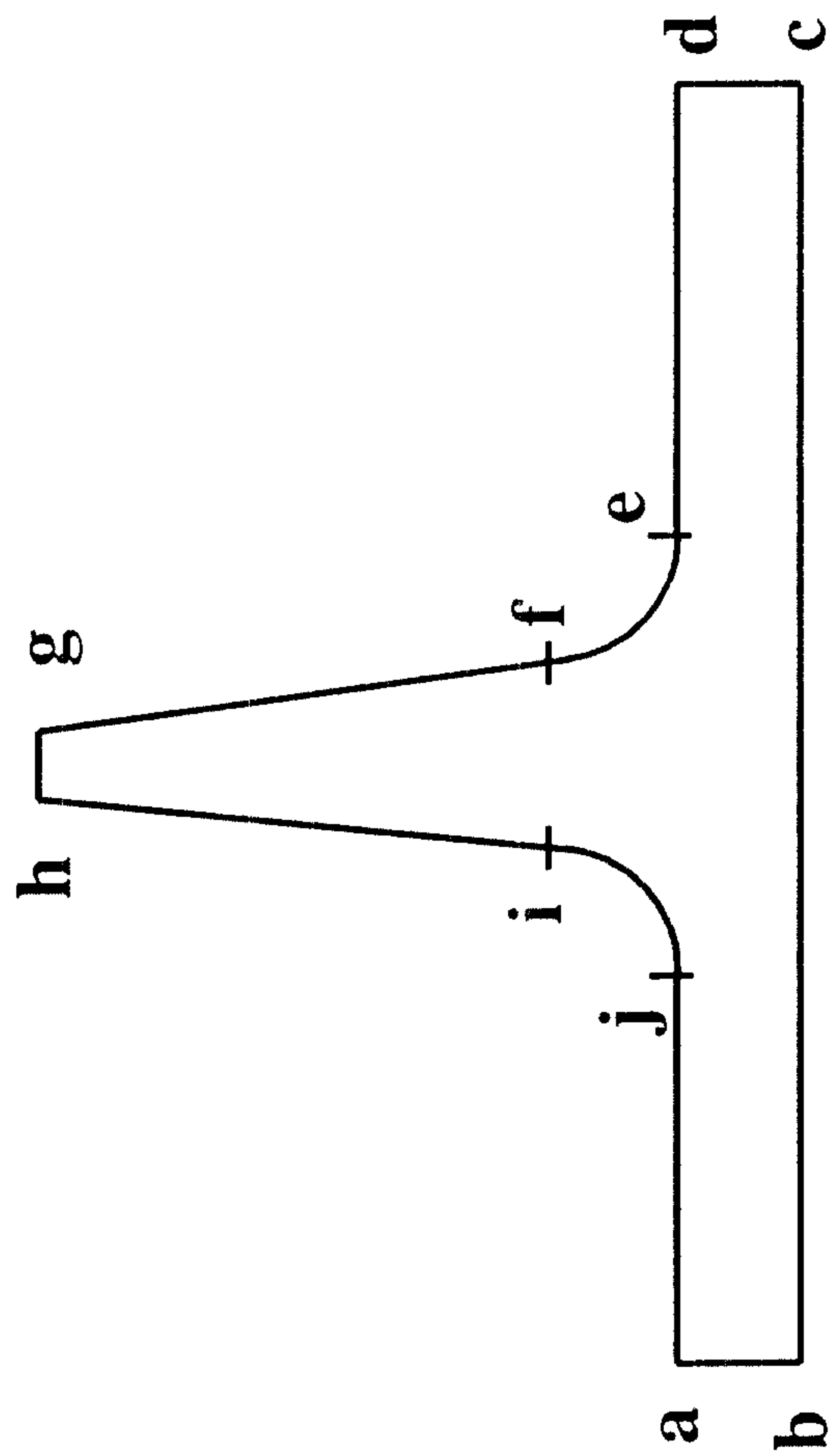


Figure 10

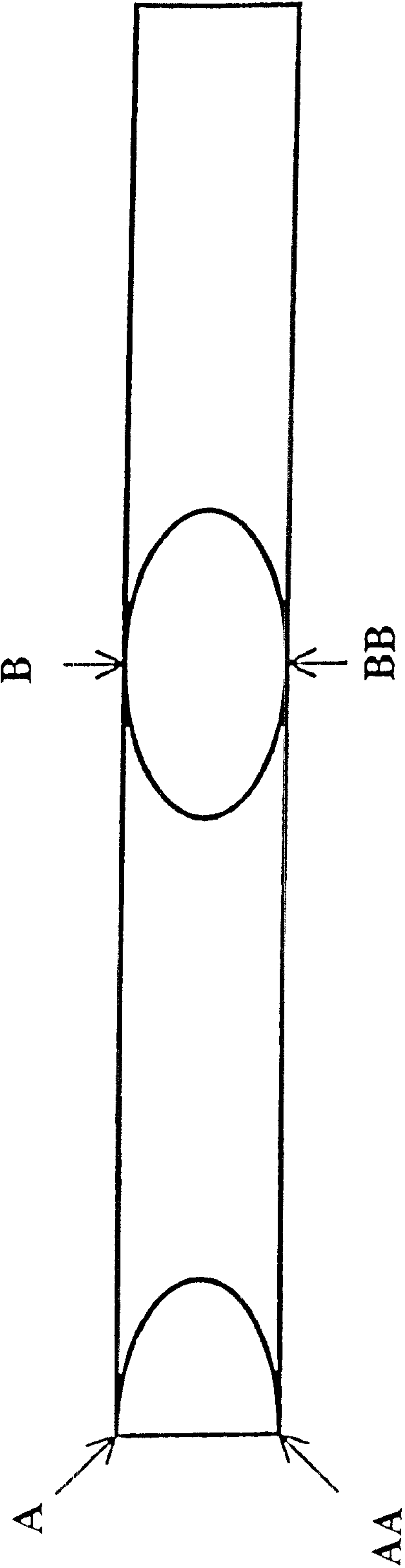


Figure 11

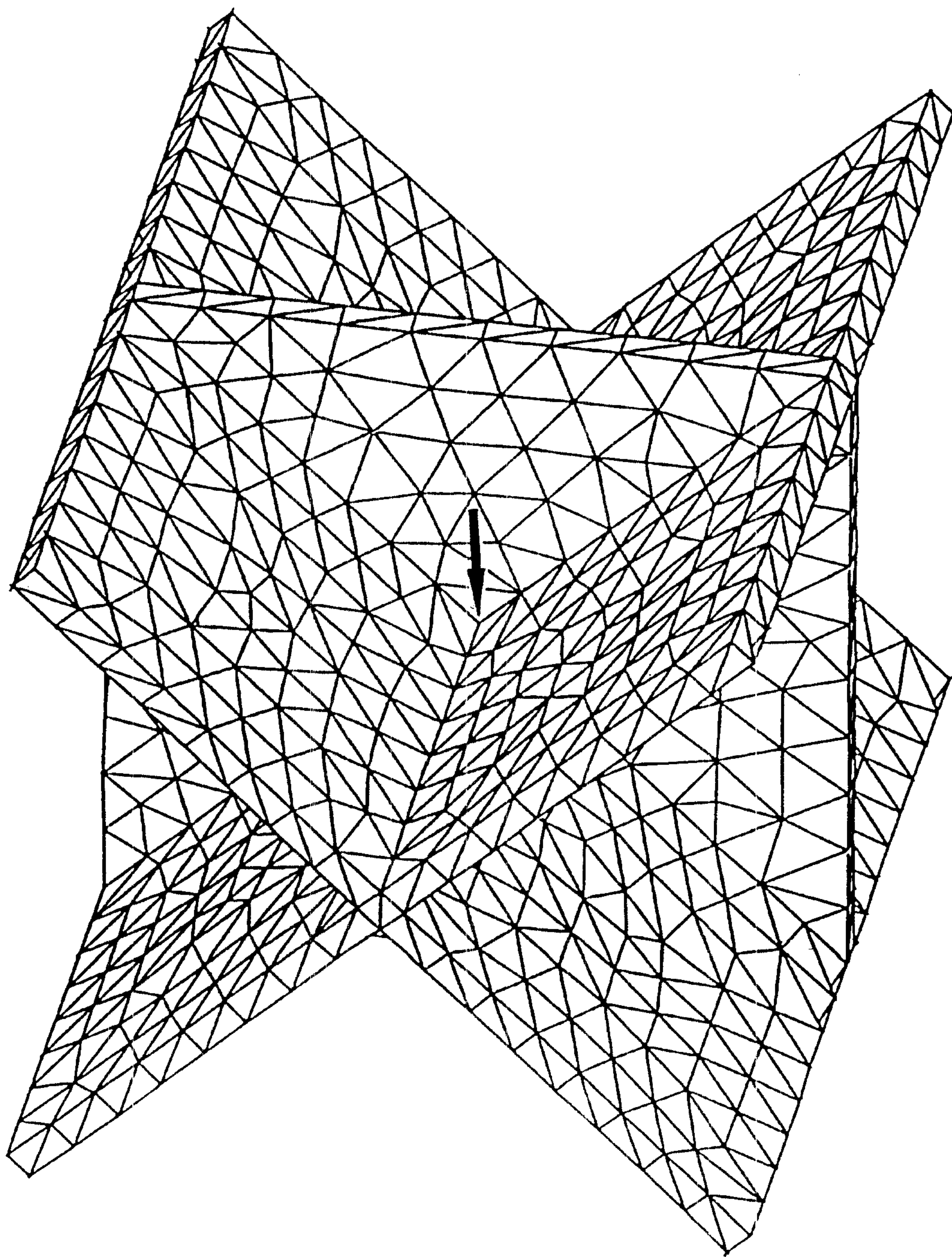


Figure 12

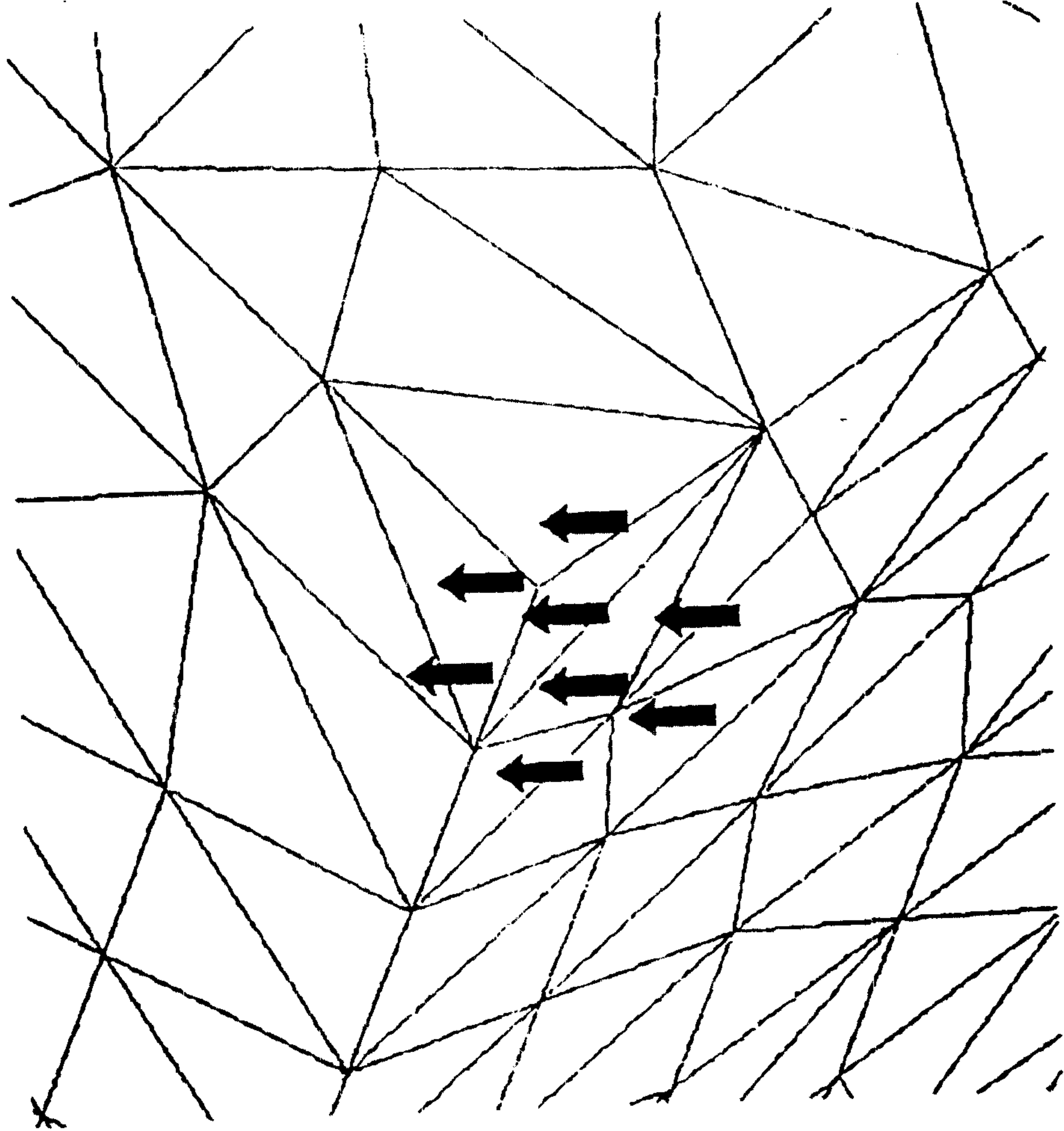


Figure 13

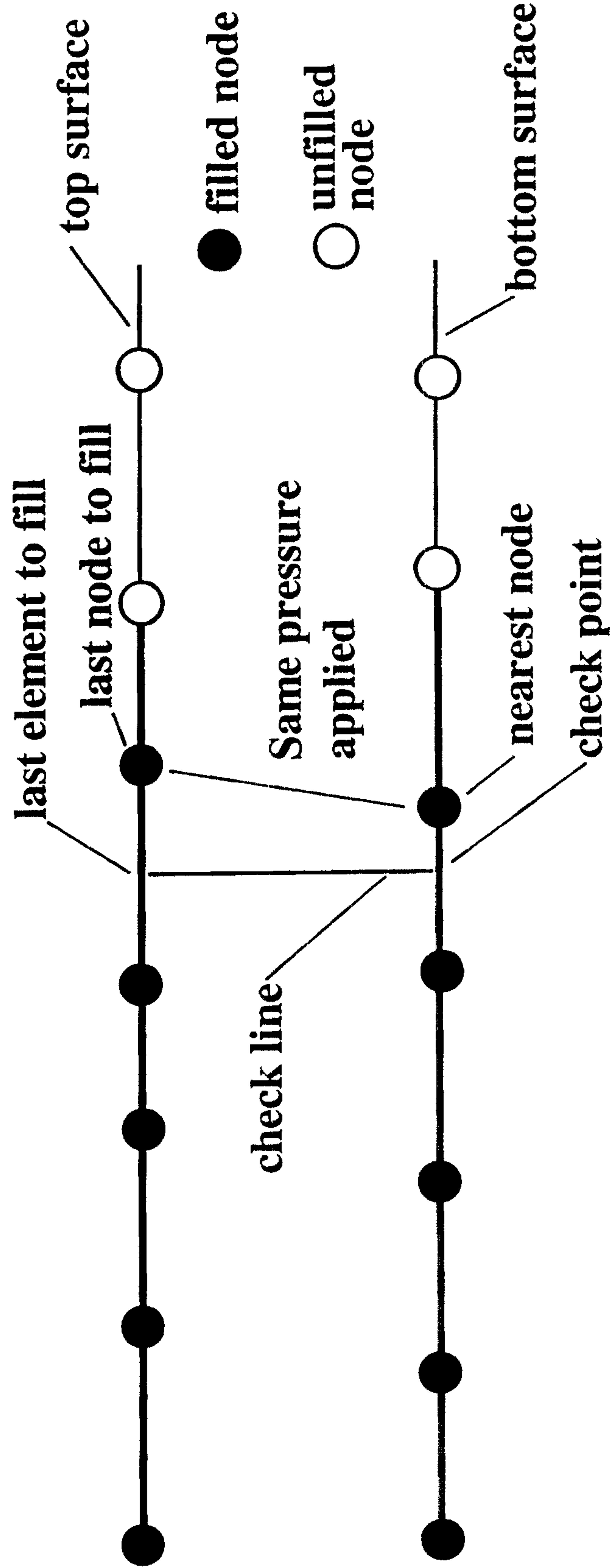


Figure 14

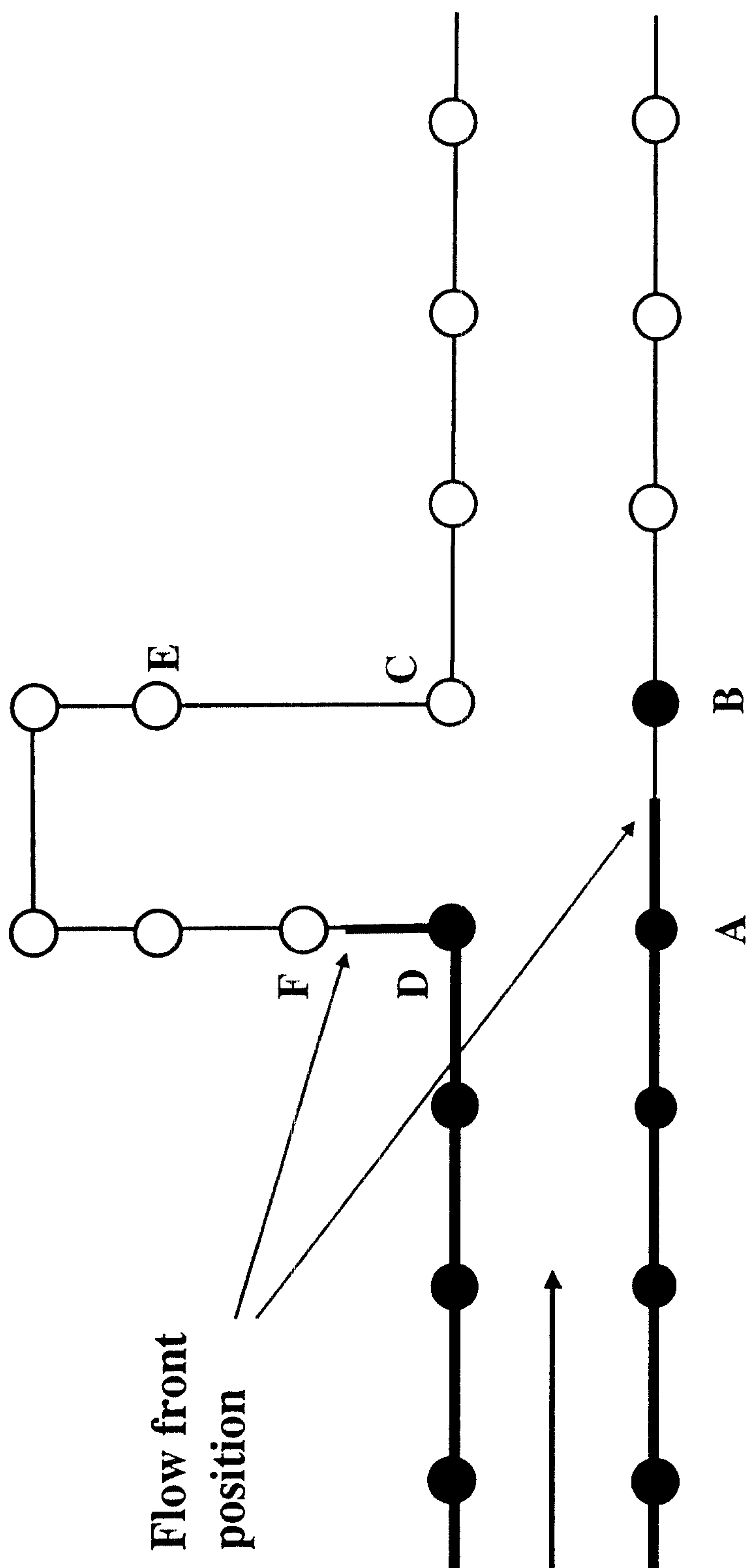


Figure 15

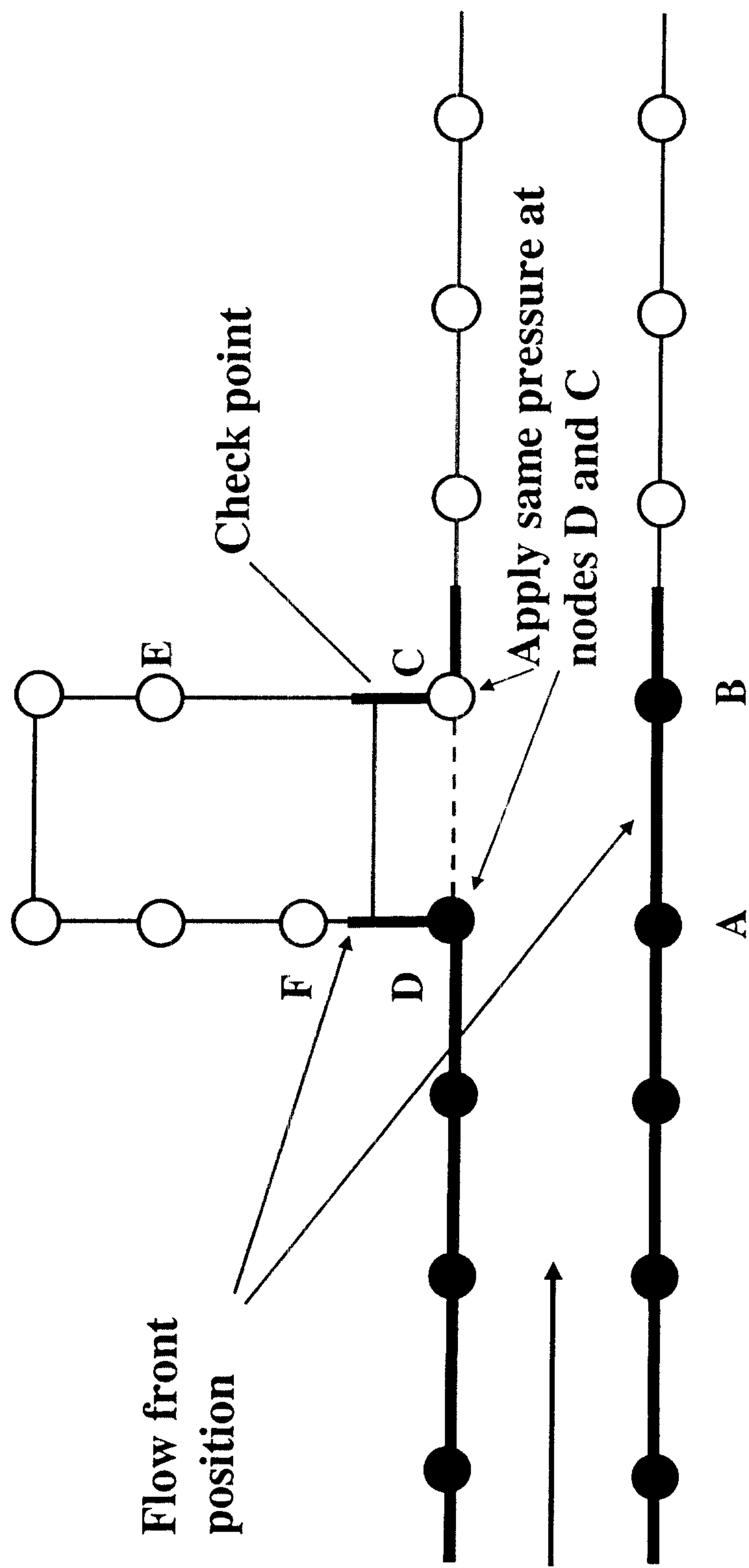


Figure 16

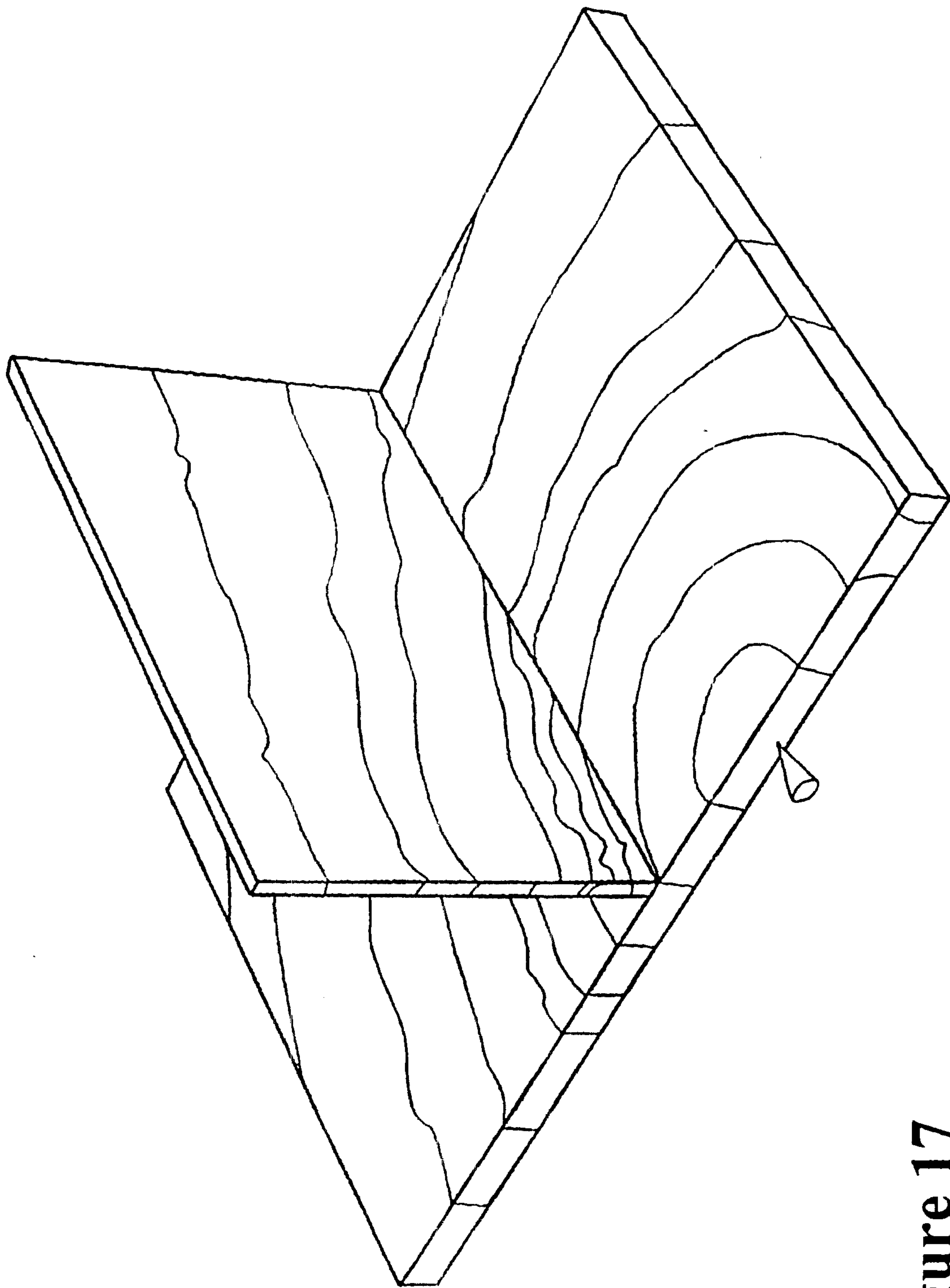


Figure 17

