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(71) Applicant: INFINITE PICTURES INC. [US/US]; Suite 1, 33 N.W. First Avenue, Portland, OR 97209 (US).

(72) Inventors: GILBERT, Scott; 4309 North Rio Cancion Drive #183, Tucson, AZ 85719 (US). KAIMAN, David; 1694 North Island Cove Lane, Portland, OR 97219 (US). PARK, Michael, C.; 7000 S.W. Vermont Court #102, Portland, OR 97223 (US). RIPLEY, David, C.; 1546 N.W. Benfield Drive, Portland, OR 97229 (US).

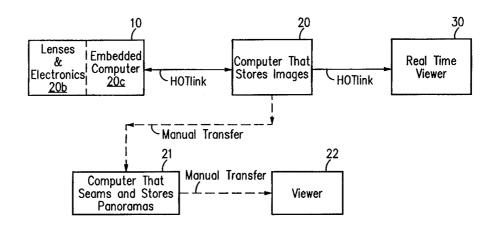
(74) Agent: GALBI, Elmer; 13314 Vermeer Drive, Lake Oswego, OR 97035 (US).

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(54) Title: PANORAMIC MOVIES WHICH SIMULATE MOVEMENT THROUGH MULTIDIMENSIONAL SPACE



(57) Abstract

Movement through multidimensional space is simulated using a series of panoramic images which are projected or displayed in sequence. The user's direction of view, that is the selected view window, is maintained as the series of images is projected or displayed. Motion in directions other than forward or reverse is simulated by utilizing "branch" points in the sequence. Each path from a branch point simulates motion in a different direction. Branch points are generally indicated to a viewer by visual indicators called "hot spots"; however, branch points may also be hidden and activated in response to the viewer's selected direction of view. If a branch point is indicated by a visual indicator, a user can select motion in a desired direction by clicking on a "hot spot". In order to conserve storage space, the image representing each panorama can be stored in a compressed format. Only the portion of the panorama necessary to create a "view window" that is, the portion of the image displayed in response to the user's direction of view, is decompressed at view time. An index methodology is used to store the panoramic images. Use of the indexing methodology allows the images to be retrieved in both the forward and backwrd direction to simulate movement in either direction. Sound is provided in a special format, so that special effects can be provided based on the user's point of view and dependent upon the direction of motion selected by the user.

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1	PANORAMIC MOVIES WHICH SIMULATE MOVEMENT
2	THROUGH MULTIDIMENSIONAL SPACE
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4	Field of the Invention:
5	The present invention relates to photography, digital image processing and to
6	computer graphics. More particularly the present invention relates to a method and
7	system for providing a viewer with a multidimensional view which simulates
8	movement through space or time.
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12	to copyright protection. The copyright owner has no objection to the facsimile
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16	Background of the invention:
17	Motion is usually simulated by means of single view movies. Single view movies
18	consist of a series of single photographs which are sequentially projected on a
19	screen. At any time, a single photograph is entirely projected on the screen. Some
20	movie theaters have screens which partially surround the viewer, so that a viewer
21	can turn and look at a different portion of the screen as the movie progresses
22	However, irrespective of where the viewer's attention is focused, in fact the entire
23	image is being projected on the screen. With some equipment single view movies
24	can be stopped and reversed; however, again at a particular time a selected frame is
25	entirely displayed. In summary, traditional movies do not allow a viewer to control
26	the portion of the image which is projected on the screen. Stated differently, with
27	traditional movies a viewer can not control the "view window" through which each
28	image is viewed.
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30	It should be noted that as used herein the term "screen" refers to either a traditional
31	screen onto which an image is projected or an electronic display which projects or
32	displays an image in such a manner that the image can be seen by a viewer.
33	
34	The technology for producing panoramic images and photographs is well known.
35	Panoramic images are images which represent the visual surroundings from a single

location (or view point) of a particular 3D environment. Panoramic images can be photographic, computer-generated (CG), or a composite of photo and CG imagery. Equipment is available which seams together a series of two dimensional conventional images to form a panoramic image. Panoramic images may consist of any field of view such as a full sphere full cylinder, semi-sphere, etc. however, full sphere views are generally preferred. Panoramic images may be in any of the known projection formats, such as equi-rectangular, Mercator, Peters, fisheye, cube, or hemicube, etc. If the field of view is wide enough to warrant, perspective correction may be applied to the portion of a panoramic image displayed in order to remove projection distortions from the given view of the user. Computer programs and systems which allow one to view a selected portion of, to pan, to rotate, etc a panoramic image or photograph in response to the movement of a computer mouse, joystick, keyboard, etc. are commercially available.

Panoramic image (or photographic image) viewing systems are available which provide a number of panoramas (for example views of adjacent rooms in a building) and which allow a user who is viewing one of the rooms to "click" on a door and to thus bring up the panorama of the next room, thereby, in some sense simulating movement into the next room. However, each of the panoramic views in such systems is static and some explicit action on the part of the viewer is required to move on to a different panorama.

U.S. Patents 5,023,925 and 5,703,604 describe, and Dodeca L.L.C. located in Portland Oregon commercially markets, a system for capturing images using a multi lens camera, for seaming the images into panoramas, and for viewing selected portions of the panoramic images.

Other panoramic image or photographic viewing systems are available which initiate a conventional single view motion picture when a user "clicks" on a spot such as a door in a first panoramic view. The single view movie simulates movement into a different location and at the end of the movie, the user is presented with a second panoramic view.

A company named "Warp" located in the Kingdom of Tonga has demonstrated a system wherein a video sequence is captured using a video camera with a fisheye

lens which is pointed in the vertical or "up" direction (see, VTV Software

- 2 Development Kit Reference Manual 2.01 Win95 1996). This approach provides a
- 3 hemispheric movie in which the user may "pan around" while the movie is playing. In
- 4 the system demonstrated by Warp, the user views the movie "in sequence", meaning
- 5 that each frame of the movie is played according to the temporal sequence in which
- the hemispheric movie was captured. The system demonstrated by Warp was
- 7 limited to sub-spherical panorama dimensions and the camera was located at a fixed
- 8 position.

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Realistic simulation of movement from one location to another can be provided by

three dimensional computer modeling systems, such as those used in some flight

simulators. However, such systems are very computationally intensive

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Summary of the present invention:

The present invention simulates movement through multi-dimensional space using a series of panoramic images which are projected or displayed in sequence. The user's direction of view, that is the selected view window, is maintained as the series of images is projected or displayed. Motion in directions other than forward or reverse is simulated by utilizing "branch" points in the sequence. Each path from a branch point can simulate motion in a different direction. Branch points are generally indicated to a viewer by visual indicators called "hot spots"; however, branch points may also be hidden and activated in response to the viewer's selected direction of view. If a branch point is indicated by a visual indicator, a user can select motion in a desired direction by "clicking" on a "hot spot".

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In order to conserve storage space, the image representing each panorama can be stored in a compressed format. If the images are stored in compressed format, in order to conserve time and processing power, when an image is displayed, only the portion of the panorama necessary to create a "view window" that is, the portion of the image displayed in response to the user's direction of view, is decompressed. Furthermore, the images are stored in a format that does not utilize inter-image compression (such as that used by the MPEG format). Since the images are stored in a format that does not utilize inter-image compression, it is possible to simulate motion in both the forward and backward direction without operating on a series of decompressed images.

1 An index methodology is used to store the panoramic images. Use of the indexing 2 methodology allows the images to be retrieved in both the forward and backward 3 direction to simulate movement in either direction. 4 Sound is provided in a special format, so that special effects can be provided based 6 on the user's point of view and dependent upon the direction of motion selected by 7 the user. 8 9 **Brief Description of the Figures:** 10 Figure 1 illustrates a key frame (that is, panoramic image) with a view window and 11 associated sound tracks. 12 13 Figure 2 is a block diagram showing the major components in the preferred 14 embodiment. 15 16 Figures 3A to 3D shows the sequence of operations performed by the various 17 components in the system shown in Figure 2. 18 19 Figure 4A illustrates a sequence of frames which constitute a panoramic movie. 20 21 Figure 4B illustrates the sound track associated with the frames of a panoramic 22 23 movie. 24 Figure 5A is a perspective view of the multi lens hand held unit that captures a series 25 26 of panoramic images. 27 Figure 5B is top view of the multi lens hand held unit shown in Figure 5A. 28 29 Figure 6 is a block diagram of the electronic components in the hand held unit shown 30 in Figures 5A and 5B. 31 32 Figure. 7 is a diagram of a file containing a pan movie. Figure 7 shows a series of 33 panoramas stored as a series of compressed key-frames and a file index for 34 sequencing playback of the key-frames. 35

1 Figure 8 is a block diagram of a program for inserting hot spots in a pan movie. 2 3 Figure 9A is a block diagram of a system for playback of a 3-D panoramic movie 4 according to the invention. 5 6 Figure 9B is a block diagram of a real time viewing unit. 7 8 Figure 10 is a flowchart of the program for viewing a 3-D movie containing a 9 sequence of panoramas according to the invention. 10 11 Figure 11 is a diagram illustrating the audio information associated with each key 12 13 frame. 14 Figure 12A, 12B and 12C are a spatial sequence of perspectively correct views 15 illustrating movement past a billboard displaying an advertisement which has been 16 superimposed into a scene as a hot spot. 17 18 **Description of Appendices:** 19 Appendix A is a print out of computer code for retrieving images and correcting the 20 perspective of images in a pan movie. 21 Appendix B is a sample of link control file for a pan movie. 22 Appendix C is a print out of computer pseudocode for linking sequences of images to 23 form a pan movie. 24 25 Description of a preferred embodiment: 26 In order to simulate movement through multi-dimensional space, one must first 27 capture a series of panoramic images, the panoramic images must be stored as 28 frames and then the appropriate view window from selected frames must be 29 displayed in an appropriate sequence. 30 31 A panoramic image provides data concerning what is visible in any direction from a 32 particular point in space. At any particular time a viewer or user can only look in one 33 direction. The direction or point of view of a viewer or user determines the "view 34 window", that is, the part of a panoramic image which is projected on a screen at a 35

particular time. Figure 1 shows a key frame (i.e. a panoramic image) or a panorama 1 3a. Panorama 3a has a view window 3b which corresponds to a portion of panorama 2 3a. Panorama 3a also has associated therewith a number of sound tracks 3c. It is 3 noted that for ease and clarity of illustration, no attempt has been made to illustrate in 4 Figure 3 the well know fact that there is a difference in perspective between what is 5 displayed in a view window and what is stored in a flat section of a rectilinear 6 spherical panorama. 7 8 Figure 2 is an overall diagram of a preferred embodiment of the invention. A camera 9 unit 10 captures images. The images are sent to a computer 20 which stores the 10 images. Computer 20 also controls camera unit 10. If desired the images can be 11 viewed by a real time viewer 30. The images are transferred from computer 20 to off 12 line computer 21. Computer 21 seams the images into panoramas, transforms the 13 images to equirectangular format, adds other information to the images, compresses 14 the panoramas, and links the panoramas into a pan movie. Finally the pan movie is 15 viewed on viewer 22. 16 17 The operations performed by the units in Figure 2 are shown in Figures 3A, 3B, 3C 18 and 3D. As shown in Figure 3A, block 11a, camera unit 10 captures a number of 19 single view images. As indicated by block 11b these images are compressed and 20 sent to a computer 20. Computer 20 activates camera 10 to capture the images as 21 indicated by block 20a. It then accepts the images as indicated by block 20b and 22 23 stores them. 24 The stored images are manually transferred to off line computer 21 which is 25 programmed to perform the operations shown in Figure 3C. First the images are 26 decompresses as indicated by block 20a so that they can be manipulated. Next the 27 single view images are seamed into a panorama and transformed to equirectangular 28 format as indicated by block 21b. Hot spots which indicate break points in a 29 sequence of images and sound tracks are added next as indicated by block 21c. 30 Finally the images are compressed as indicated by block 21d and stored with an 31 index file as indicated by block 21e. Each panorama is termed a "key frame". A 32 series of key frames (or more precisely a sequence of view windows) projected in 33 sequence is a pan movie. 34

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A viewer program in viewer computer 22 is used to view the pan movies. The viewer 1 22 displays in sequence a series of images, that is, a series of key frames. For each 2 key frame displayed the viewer 22 determines an appropriate view window as 3 indicated by block 22a. The portion of the key frame which corresponds to the view 4 window is then de-compressed and displayed as indicated by block 22b. As 5 indicated by block 22c, sound is played if appropriate. 6 7 It is noted that the operations indicated by blocks 20a, 20b, 21a to 21e, 22a, 22b, and 8 22c are implemented by means of computer programs which perform the functions 9 shown. Computer programs are given in appendices A, B, C, and D. 10 11 Figure 4A represents or illustrates a sequence or series of panoramic images in a 12 pan movie. Each arrow in Figure 4A represents one key frame. At any particular 13 time, only a part (i.e. the view window) from one key frame is visible to a user or 14 observer. The direction of each arrow indicates the direction of view, that is, the view 15 window or part of the key frame that is projected on a screen for observation. The 16 arrows in Figure 4A are meant to represent a particular "view window" from each key 17 frame. As indicated by the change in direction of the arrows in the area of Figure 4A 18 designated by the letter E, a viewer can change his direction of view as the pan 19 movie progresses. It is noted that when a user is viewing a panorama, a user can 20 point toward the top or bottom of the screen and thus can view images located in a 21 360 degree circle from top to bottom in addition to the horizontal directions illustrated 22 by the arrows shown in Figure 4A. 23 24 The sequence of images begins at the point or at the key frame indicated by the 25 letter A and the sequence proceeds to the point or key frame indicated by the letter 26 B. At this point the viewer can select to either go toward point C or toward point D. 27 The selection may be made by "clicking" on a designated "hot spot" in the panorama 28 designated B or it may be made depending on some other criteria or action by the 29 user. An important point is that at the branch point B, the direction of view (indicated 30

is chosen. The view from the first frame after the branch point will be almost identical 32 in both paths. As time progresses and the viewer moves further from the branch

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by the direction of the arrows) remains the same irrespective of which path of travel

point, the view will gradually change. This is the effect that a person experiences

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when one arrives at a dividing point in a path. When a person takes the first step on 1 a branching path, the persons field of view remains practically identical. 2

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It is noted that at branch point B, the arrows are not pointing in the direction of the 4 path leading to point D. Normally, a viewer would be looking in the direction of a 5 branch point when the viewer selects to travel in the direction of the branch point. 6 7

Thus, a viewer looking in the direction of the arrows shown in Figure 4A would

normally continue to point C rather than selecting the path to point D.

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Sequences of key frames can either be joined at branch points such as branch point B or alternatively a branch point may be located at the end of a sequence of key frames. That is, a branch point may be located at the terminal frame of a sequence of key frames. Such a branch point could have two alternative sequences, one of which can be selected by a user by clicking on one of two hot spots. Alternatively at the end of a sequence of key frames, there can be an implicit branch point. At such an implicit branch point a new sequence of frames would be selected by the system without any action by the user.

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There is a one to one ratio of key frames to possible user positions. Hence, there 19 exists a correlation between frame rate and user motion speed. If the user is moving 20 through the environment, every frame displayed is a new key frame. The faster the 21 frame rate for a given frame spacing, the faster the user travels. Given a fixed frame 22 rate, the user's travel speed may be dictated by the relative spacing of key frames. 23 The closer the key frames are, the slower the user will travel. For example, for a 24 travel speed of approximately 5 mph and a playback frame rate of 15 fps, individual 25 panoramic frames should be captured at about 6 inch increments. The math is as 26 follows: (5 miles/hour * 63,360 inches/mile)/ (3600 sec/hour * 15 frames/sec) = 6 27 inches per frame. When the movie is being displayed, speed of travel can be 28 increased by skipping some of the frames (for example if every other frame is 29 skipped the speed of travel is doubled). Skipping frames reduces the rate at which 30 frames need be sent to the viewer and thus reduces the bandwidth required. 31

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In addition to the spacing of key frames to achieve different travel speeds, the orientation of individual key frames may be adjusted in order to achieve a desired motion effect, such as gate, slumber, waddle, crawl, skip, etc. The orientation of a

key frame is defined to be the default view (or point of focus) of the user within the panoramic image if no other point of view is specifically selected.

Sound can accompany the visual effect provided by pan movies. Figure 4B indicates that each key frame can have one or more associated digital sound tracks. The digital sound tracks are indicated in Figure 4B by the dotted line which is associated with each of the arrows. As shown in Figure 11 and described later, there can be several different sound tracks associated with each key frame.

 Figure 5A is a perspective view of the six lens camera unit 10 which is used to digitally capture panoramic images, that is, key frames. Figure 5B is a top view of camera 10 which is included to show that the unit has six lenses 41a to 41f. Each lens 41a to 41f has a 110 degree field of view. The images captured by lenses 41a to 41f are transmitted to computer 20 through a serial connection. Computer 21 "seams" the individual images from lenses 41a to 41f into panoramic images or key frames, compresses the key frames and stores them for future display. Additionally, a real time viewer can 30 can be used to view the images as they are being captured and seamed.

In the preferred embodiment the connection from camera unit 10 to computer 20 and from computer 20 to real time viewer 30 is a "HOTlink" serial bus. Such connections are commercially available from suppliers such a Cypress Semiconductor Corp. or from Dataforth Corporation which is a division of Burr-Brow Company. Alternatively other types of high speed connections could be used. For example the connection could be a standard SCSI connection.

Figure 6 shows the electronic components in camera 20. The components associated with each lens 41a to 41f are substantially identical to the components in commercially available digital cameras. The internal operation of the camera 20 is controlled by a conventional embedded programmed computer 45 which, for example, may be a model 29000 computer available from Advanced Micro Devices Corporation. Many different suitable embedded processors are commercially available. Embedded computer 45 receives commands from computer 20 which has IO units which allow an operator to enter commands. For example computer 20 sends commands to computer 45 which set the aperture of the lenses 41a to 41f and

which starts and stops the operation of the camera. While computer 20 sends 1 general commands to computer 45 such as set aperture, start, stop, etc., computer 2 45 sends to detailed commands which control CCD arrays 43a to 43f and which 3 control compression chips 44a to 44f. Such commands are conventional. 4 5 Each of the lenses 41b to 41f has a set of associated components similar to the 6 components associated with lens 41a.. The following will discuss the components 7 associated with lens 41a. It should be understood that the other lenses 41b to 41f 8 have a similar sets of components. 9 10 The image from lens 41a is focused on a CCD (Charge Coupled Device) array 43a. 11 CCD array 43a captures the image from lens 41a and send this image to embedded 12 computer 45. CCD arrays 43a is controlled and operated by embedded computer 13 45. By resetting and reading the CCD array 43a in a particular time period, the 14 embedded computer 45 in effect controls or provides an electronic shutter for lens 15 41a. The electronic shutters associated with each of the lenses 40a to 40f open and 16 close simultaneously. Each CCD array 43a to 43f captures 30 images per second 17 18 under normal operation. 19 The output of CCD array 43a is fed into a JPEG data compression chip 44a. Chip 20 44a compresses the image from lens 41a so that the image can be more easily 21 transmitted to computer 40. The output from compression chip 41a fed to an 22 embedded controller 45 which transmits signals to computer 40 on a serial time slice 23 24 basis. 25 The lenses 41 and the CCD arrays 43, and are similar to the components found in 26 commercially available digital cameras. JPEG compression chips 44 and embedded 27 computer 45 are also commercially available components. For example such 28 components are available from suppliers such as Zoran Corporation or Atmel 29 30 Corporation. 31 The electronic shutters associated with lenses 41 operate at 30 cycles per second 32 and hence computer 21 receives six images (one from each lens) each 1/30th of a 33 second. The six images received each 1/30th of a second must be seamed and 34

transformed to equirectangular format to form one panorama as indicated by step 1 2 21b in Figure 2. 3 While the specific embodiment of the invention shown herein utilizes a digital camera 4 to take the initial single view images which are compressed and sent to computer 20 5 for storage, it should be understood that one could use a variety of other types of 6 cameras to take these initial images. For example the images simultaneously taken 7 from a number of lenses could be recorded on tape for later processing by off line 8 computer 21. 9 10 The seaming operation is done by the program in computer 21. In general the 11 seaming operation connects the individual images into a panoramic image by finding 12 the best possible fit between the various individual images. The process of seaming 13 images into a panoramic image is known. For example U.S. patent 5,694,531 14 describes seaming polygons into a panorama which has a low root-mean-square 15 16 error. 17 After the seaming operation is complete each seamed image is a panoramic image 18 (called a panorama) and each panorama is a frame of a pan movie. Prior to storage 19 the seamed images are compressed so as that the file size will be manageable. A 20 commercially available compression program known as "Indeo" is used to compress 21 the images. The Indeo program was developed by and is marketed by the Intel 22 Corporation. The Indeo compression program provides a mode of operation which 23 does not utilize any inter-frame compression. The no inter-frame compression mode 24 of the Indeo program is used with the present embodiment of the invention. Since 25 there is no inter frame compression, the key frames can be accessed and viewed in 26 either the forward or the reverse direction. Furthermore, only the portion of a 27 panorama required for a particular view window is decompressed, thereby saving 28 time and computational resources. 29 30 The compressed panoramic images are stored in files on computer disks, tape or 31 compact discs (CDs). Each file includes a header and an index as shown in Figure 7. 32 The header includes information such as the following: 33 File Type Tag: 34 (total bytes used by the file) File Size: 35

Index Size:

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(Number of entries in frame Index)

(total bytes used by largest compressed frame) Max Frame Size: 2 (Codec used to compress frames. Codec: 3 After the file header, a frame index is provided (see Figure 7). Each frame index 4 points to the location of the associated frame as indicated by the arrows in Figure 7. 5 Thus, individual frames can be read in any order by obtaining their location from the 6 7 frame index. 8 The indexing mechanism would not be necessary if the key frames were always 9 going to be used in frame order. However, in the present embodiment, the system 10 can play the key frames which comprise the pan movie in either forward or backward 11 direction. Hence the system must be able to locate individual frames quickly in any 12 order. Furthermore, it is desirable that the system be able to locate a key frame with 13 only a single disk access. Consider the situation were the user is moving "backward" 14 (in the opposite direction of the key frame disk storage) at a fast travel speed (to 15 increase speed of movement some key-frames are skipped). Without a key frame 16 directory, the disk would have to be searched in a "reverse-linear" manner in order to 17 find and load the next appropriate key frame. With a key frame directory, the next 18 key frame location is located immediately, and loaded with a single disk access 19 (given the directory itself is stored in RAM memory). 20 2.1 As indicated in Figure 4A, a viewer can branch from one sequence of images to 22 another sequence of images. This is indicated by branch point B in Figure 4A. By 23 branching a user in effect changes the direction of the simulated travel. A user 24 indicates a desire to change direction by "clicking" on a visible "hot spot" or by 25 otherwise activating a hidden hot spot. A visible hot spot can be indicated by any 26 type of visible symbol that is visible in a view window. For example a hot spot may 27 be indicated by a bright red dot in the view window. Alternatively, a hot spot may be 28 indicated by the fact that the cursor changes to a different shape when the cursor is 29 over a hot spot. 30 31 It is noted that not all visually apparent alternate paths visible in any panorama are 32 actually available as a pan movie branch. For example, at a street intersection, 33 branches may not be provided to all visible streets. Care must be taken to insure 34

that a viewer is given an indication of the branch points that are actually available to the viewer.

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At a playback rate of 30 frames per second a user would have to be very "fast" (i.e. it would in fact be practically impossible) for a viewer to see and click on a hot spot that appears on a single frame. Without advanced notice, the viewer would have great difficulty actually taking a specific action to activate a branch during a specific single frame since in normal operation a particular frame is only displayed for about 1/30th of a second. In order to be effective and user friendly a user must be given an early indication of a upcoming branch opportunity that requires user action. A hot spot in a pan movie must be visible by a viewer in a relatively large number of key frames. For example a hot spot might be visible in the thirty key frames that precede (or follow for reverse operation) a branch point.

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Hot spots are inserted into a pan movie in the manner illustrated in Figure 8. The hot spots are inserted into the key frames by computer 21 before the frames are compressed as indicated by blocks 21c and 21d in Figure 3C. It is noted that hot spots may be inserted into a pan movie by altering the original panoramic image so that it includes the hot spot or alternately by providing a overlay image which contains the hot spot image. If an overlay is used, the overlay image needs be projected at the same time as the original image. As indicated by block 87a one must first determine how much in advance one wants to warn the user. If a hot spot is to have a particular size at the time action is needed, when viewed in advance (i.e. from a distance) the hot spot will be much smaller. As indicated by block 87b, in order to insert hot spots in a pan movie, one must select the region where the hot spot is to be located. In general this will be in a view looking toward the direction where the branch will take place. The hot spot is then inserted into the panorama by modifying the images. The hot spot may be indicated by a light colored outline superimposed over the region. The area within the outline may be slightly darkened or lightened. The object is to highlight the region without obscuring the image itself. Various other alternative indications can also be used.

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34

The process repeats as indicated by blocks 87d and 87e until the key frame at the branch point is reached. Finally the process is repeated from the opposite direction

from the branch point so that the branch point will be visible if the pan movie is 1 shown in the reverse direction. 2 3 The changes to the individual key frames may be made manually with a conventional 4 image editor, or the process can be automated by a program designed just for this 5 purpose. 6 7 In order to avoid unnecessary user intervention, "hidden" hot spots may be added to 8 connect multiple pan movies. A hidden hotspot is one that does not need to be 9 manually selected by the user. With a hidden hot spot, if the user "travels" into a 10 particular key frame which has a hidden hot spot, and the user is "looking" in the hot 11 spot's general direction, then the system will react based upon the user's implicit 12 selection of the hotspot and the user will be sent along the path directed by the hot 13 spot. 14 15 Figure 9A is a block diagram of the viewer 22 which plays or displays pan movies. 16 The main components of the viewer 22 are a CD disk reader 80, a computer 81, a 17 display 82, a keyboard 84 and a mouse 85. Computer 81 reads key frames from disk 18 80 and displays the view widow from each key frame on display 82. The operator or 19 user utilizes mouse 85 to indicate a view direction. The view direction determines the 20 view window which is displayed on display 82 by computer 81. A program which 21 implements blocks 22a to 22c (shown in Figure 3D) is stored in and executed by 22 computer 81. 23 24 Figure 9B is a block diagram of the real time viewer 30. As an option, the images 25 captured by camera 10 can be viewed in real time. Images are transferred from 26 computer 21 to viewer 22 in real time. The transfer is by means of a HOTlink bus to 27 HOTlink card 86a. The images go from card 86a to RAM memory 86b and then to 28 decompression card 86c which does the de-compression. From the de-compression 29 board 86c the images go back to memory and then to CPU 86d which combines i.e. 30 seams the images as necessary and transfers them to video card 86e which displays 31 them on monitor 86f. Viewer 30 is controlled via a conventional mouse 86m and 32 keyboard 86k. 33 34

Figure 10 is block diagram of a program for displaying pan movies. The program shown in block diagram in Figure 10 is executed by the computer 81 in Figure 9A. The process begins at block 91 with user input. The user must indicate a start location (at the beginning of the process this would normally be the first frame in the movie). The user must also specify direction of motion, speed and direction of view. As indicated by blocks 92, 92a, 92b and 92c the system determines and then reads the appropriate pan frame data. As indicated by block 96 and 96a, the system determines the portion of the pan frame that is in the selected view window and that portion of the frame is decompressed. As indicated by blocks 97 and 97a, the image is re-projected to obtain a perspective view. If the hot spots have not been placed on the actual key frames but are contained in a separate file, the hot spot imagery is overlaid on the image. Finally, as indicated by block 98, the part of the image which

constitutes the view window is projected on the screen.

As a user travels, the next required key frame is determined by the current user position and direction of travel. The location of this key frame within the file of images is determined via the file index directory; and the key frame is loaded into RAM memory, decompressed, and displayed. To increase performance, only the view window (depending on current user view) portions of the key frame need be loaded into RAM. If for ease of programming the entire key frame is loaded into memory, only view window portions of the key frame need be decompressed. If the entire key frame is compressed as a whole, then a de-compressor supporting "local decompression" is more efficient, e.g., Intel Indeo. To determine the portion of the panorama needed to display a particular view, each of the corner coordinates of the perspective view plane (display window) is converted to panorama coordinates. The resulting panorama coordinates do not necessarily represent a rectangle, therefore the bounding rectangle of these panorama data is needed to derive a perspective view at a given view orientation.

Once the corners of the desired bounding rectangle are determined the Indeo de compression program is instructed to decompress only that portion of the key frame needed for the particular view window. In order to do this, the program must call the Video For Windows function ICSetState prior to decompressing the frame. The C code to accomplish this follows.

```
#include "windows.h"
1
2
     #include "vfw.h"
     #include "vfw_spec.h"
3
4
                                              // Opened CODEC (IV41);
                                hic;
5
     extern HIC
                                              // Determined elsewhere
                                *viewRect;
     extern RECT
6
     static R4_DEC_FRAME_DATA
                                       StateInfo;
7
8
     void
            SetRectState
9
10
     (
                                // Opened CODEC (IV41);
            HIC
                  hic;
11
            RECT *viewRect;
                                // Local Rectangle of interest
12
13
     )
14
     {
            R4_DEC_FRAME_DATA
                                       StateInfo;
15
16
            memset(&StateInfo,0,sizeof(R4_DEC_FRAME_DATA));
17
            StateInfo.dwSize = sizeof(R4_DEC_FRAME_DATA);
18
            StateInfo.dwFourCC = mmioStringToFOURCC("IV41",0); // Intel Video 4.1
19
            StateInfo.dwVersion = SPECIFIC_INTERFACE_VERSION;
20
            StateInfo.mtType = MT_DECODE_FRAME_VALUE;
21
            StateInfo.oeEnvironment = OE_32;
22
            StateInfo.dwFlags = DECFRAME_VALID | DECFRAME_DECODE_RECT;
23
24
            StateInfo.rDecodeRect.dwX = min(viewRect->left,viewRect->right);
25
            StateInfo.rDecodeRect.dwY = min(viewRect->top,viewRect->bottom);
26
            StateInfo.rDecodeRect.dwWidth = abs((viewRect->right-viewRect->left)+1);
27
            StateInfo.rDecodeRect.dwHeight = abs((viewRect->bottom-viewRect-
28
29
     >top)+1);
30
            ICSetState(hic,&StateInfo,sizeof(R4_DEC_FRAME_DATA));
31
32
     }
     If the projection used to store the pan-frame is such that there exists a discontinuity
33
     in pixels with respect to the spherical coordinates they represent, then the local
34
     region required may be the combination of multiple continuous regions. For a full
35
```

cylinder/sphere equirectangular projection (centered about 0 degrees), the left pixel

- 2 edge represents -180 degrees and the right pixel edge represents 180 degrees. In
- 3 spherical coordinates, -180 degrees is the same as 180 degrees. Therefore, the
- discontinuous left/right pixels represent a continuous "wrap-around" in spherical
- 5 coordinates.

6

- 7 The math to determine the portion of the source key-frame panorama needed for a
- 8 particular view window depends on the projection used to store the panorama.
- 9 Optionally, the viewer may predict the next key-frame to be loaded (depending on
- user travel direction and speed), and pre-load it in order to increase performance.
- For an equirectangular projection of a full sphere panorama frame, the equations for
- determining the required portion are as follows:
 - where:
- Scaler variables are lower case, vectors are bold lower case, and matrices are bold upper case.
- Panorama point (s,t) is derived from any perspective plane point (u.v).
- The perspective plane has a focal length I from the center of projection.

18 19

20

21

- In addition, the perspective plane can be arbitrarily rotated through a given view orientation, namely heading, pitch, and bank (h,p,b).
 - Any point in the perspective plane is specified by the 3D vector:
- 22 $w = \langle u, v, l \rangle$
- The rotations are applied by using a standard matrix-vector product. The three matrices accounting for Heading, Pitch and Bank are as follows:

25		cos(h)	0	sin(h)	
26	H =	0		1	0	
27		-sin(h	1)0	cos(h)		
28						
29		1	0	0		
30	P =	0	cos(p)	-sin(p)		
31		0	sin(p)	cos(p)		
32						
33		cos(b))	sin(b)	0	
34	B =	-sin(b))	cos(b)	0	

0 0 1 1 2 The vector **w** is rotated using the above matrices to attain **w'** like such" 3 w' = H*P*B*w4 The final step is converting from rectangular to spherical coordinates. Denoting the 3 5 components of the vector w' as x, y, z, then the conversion is: 6 s = atan2(x, z)7 t = atan2(y, sqrt(x*x + z*z))8 Note: atan2(a, b) is a standard C-function very similar to atan(a/b), but atan2 9 correctly handles the different cases that arise if a or b is negative or if b is 0. 10 11 Optionally, the viewer may predict the next key-frame to be loaded (depending on 12 user travel direction and speed), and pre-load this key frame in order to increase 13 performance. 14 15 Due to the one to one ratio of key frames to possible user positions, there exists an 16 exact correlation between frame rate and user motion speed. If the user is currently 17 moving through the environment, every frame displayed is a new key frame, thus the 18 faster the frame rate, the faster the user travels. For this reason, the frame rate is 19 "capped" during user travel to eliminate the problem of excessive user travel speed. 20 In order to retain smooth motion, the frame rate is not decreased to below standard 21 video frame rates (15 frames/sec.) The frame rate is not increased in order to keep 22 the relative spacing of key frames to a manageable distance; the faster the frame 23 rate, the closer the key frames must be to achieve the same user travel speed. The 24 viewer may optionally skip key-frames in order to increase the user's travel speed 25 through the environment. The more key-frames skipped, the faster the user will 26 travel; if no key-frames are skipped, the user will travel at the slowest possible rate 27 (given a constant frame rate.) 28 29 The system can link pan movie segments so as to permit branching and thereby 30 follow a path selected by a user. Multiple linear (one dimensional) pan movies may 31 be linked together to create a "graph" of pan movies (see appendix B). For each pan 32 movie, the end of one segment may be associated with the start of a "next" pan 33 movie. This association (in conjunction with the length of the individual pan movies) 34 is the basis for the graph shape. In order to achieve smooth transitions, the "last" 35

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frame in the "first" pan movie must be the same as (or one frame off from) the "first" 1 frame of the "next" pan movie. In addition to positional correctness, the relative view 2 orientations of the joining frames must be known. For example, if the "last" frame of 3 the "first" pan movie faces "north", and the "first" frame of the "next" Pan Movie faces 4 "east", then the viewing software must be alerted to this orientation change. Without 5 this information, there would be a 90 degree "snap" in the transition between the two 6 Pan Movies. All this graph information may be stored in a separate file (text or binary 7 form.) 8 9 The audio information associated with each frame of a pan movie must take into 10 account the fact that a viewer of a pan movie has a great deal of control over what is 11 presented on the screen. In addition to the ability to select branch points a user may 12 choose to change the direction of view or to stop and backup. The audio information 13 associated with each key frame must accommodate this flexibility. 14 15 As illustrated in Figure 11, the audio information stored with each key frame includes 16 five audio tracks designated A, B, C, D, E and control information. Figure 11 shows 17 eight key frames Fa to Fi each of which has five associated audio tracks and a 18 control field. Audio track A is the track that is played if the pan movie is moving 19 forward in the normal direction at the normal rate of thirty frames per second. Audio 20 track B is the track that is played if the pan movie is being displayed in reverse 21 direction. Audio track C is the audio track that is played if the movie is moving 22 forward at half speed. Audio track D is the track that is played if the movie is being 23 played in the reverse direction at one half speed. Finally audio track E is the track 24 that is repeatedly played if the movie has stopped at one frame. Naturally a variety 25 of other audio tracks could be added for use in a number of other situations. For 26 example, tracks can point to audio clips or to other audio tracks. 27 28 The control information that is recorded with each frame controls certain special 29 effects. For example the control information on one frame can tell the program to 30 continue playing the audio tracks from the following frame even if the user has 31 stopped the movie at one particular frame. As the sound track on each frame is 32 played, the control information on that frame is interrogated to determine what to do 33 next. What sound is played at any particular time is determined by a combination of 34 the control information on the particular frame being viewed and the action being

	the disease of the state of the
1	taken by the viewer at that time. From a programming point of view, the commands
2	associated with each rack are de-compressed and read when the view window for
3	the associated frame is de-compressed and read. As a particular view window is
4	being displayed (or slightly before) the commands stored in the control field are read
5	and executed so that the appropriate sound can be de-compressed and played where
6	the view window is displayed.
7	
8	For example the control information could provide the following types of commands:
9	Stop this audio track if user stops pan movie here (typical setting). If this is
10	not set the audio will continue playing in same direction until audio for this
11	track ends
12	
13	Start or continue to play this audio track if user is viewing pan movie in
14	forward direction (typical setting)
15	
16	Start or continue to play this audio track backwards if user if viewing pan
17	move in a backwards direction. (note if the same audio information is played
18	is reverse it may be distorted)
19	
20	Start this audio track when image frames are in motion and being played in a
21	reverse direction. This allows high quality audio to be played while reverse
22	viewing
23	
24	Continue audio track from / on other file structure (branch most likely has
25	occurred) modify volume This is used to fade out an audio track that may
26	have played ahead earlier
27	
28	Stop all audio tracks
29	
30	Stop this audio track if user slows pan movie playback
31	
32	Start audio file X: where X is a conventional audio file that is separate from
33	the pan movie.
34	

1	A wide variety of other commands may be implements as desired by the
2	designer of a particular movie.
3	
4	The audio information can be recorded with a normal recorder when the initial
5	images are recorded or it can be recorded separately. The audio data is merged with
6	the key frames by computer 21. This can be done manually on a frame by frame
7	basis or the process can be automated. When the sound is merged with the key
8	frames the appropriate control information is added.
9	
10	Figures 12A, 12B and 12C illustrate another aspect of the present invention. A hot
11	spot on a key frame can contain and display information that is independent from,
12	and in addition to the information in the base images which are used to form the
13	panoramas. For example, as a pan movie simulates movement past a billboard, a
14	"regular" motion picture (which might for example be an advertisement for a product)
15	can be displayed on the billboard. The motion picture on the billboard would be
16	integrated with the various key frames in the same manner as hot spots are added to
17	key frames. As illustrated in Figure 12A, 12B and 12C, such images displayed on a
18	billboard passed which motion is simulated must be corrected for the fact that the
19	viewer is not directly viewing the image when he is approaching it. The image is only
20	rectangular when the viewer is adjacent the image as shown in Figure 12C. As the
21	viewer is approaching the image it is distorted as illustrated in Figures 12A and 12B.
22	
23	The attached appendices provide computer programs which implement various
24	aspects of the present invention. These programs are designed to run under a
25	conventional operating system such as the "Windows" operating system marketed by
26	the Microsoft Corporation.
27	
28	The program given in Appendix A will retrieve frames for a move, correct the
29	perspective in accordance with known equations and then display the images of the
30	movie in sequence.
31	
32	Appendix B is an example of a link control file for the frames of a pan movie.
33	Appendix C is pseudocode showing how sequences of images are linked to form a
34	pan movie.
35	

It is noted that in a pan movie the frames do not all have to have the same resolution. 1 Some frames may be of a higher resolution. For example, at the most interesting 2 places in the Pan Movie may have a higher resolution. 3 4 Many alternative embodiments of the invention are possible. For example, the initial 5 capture process could record the images on video tape rather than recording the 6 images digitally. Electronic cameras could be used which include image capture 7 devices other than CCD arrays to capture images. Branching can provide three or 8 more optional paths rather than just two pats as shown in Figure 4; and branching 9 can provide for going left or right at an intersection. 10 11 It is noted that in alternative embodiments, compression schemes or techniques 12 other than Intel Indio can be used. Furthermore, alternative embodiments could use 13 no compression at all if enough storage and bandwidth were available. 14 15 While in the embodiment shown the images files are manually transferred between 16 some of the units in the embodiment shown, in alternative embodiments these files 17 could be transferred between units by electronic connections between the units. 18 19 While in the embodiment described above the camera has six lenses which record all 20 six sides of the cube, in alternative embodiments the camera could record less than 21 an entire sphere. For example the lens pointing down could be eliminated in some 22 embodiments. Still other alternative embodiments could use lenses with wider or 23 narrower fields of view. For example less lenses each with a wider field of view could 24 be used. Furthermore, while the embodiment described above utilizes spherical 25 panorama, other types of panoramas could be used. Various types of projections 26 such as cubic could be used instead of equi-rectangular. 27 28 The embodiment shown includes a number of sound tracks with each key frame and 29 control information which indicates which sound track should be played when the key 30 frame is displayed depending on whether or not certain special conditions exist. 31 Alternatively, there could be a single sound track associated with each frame. In 32

such an embodiment the single sound track on each key frame could be the sounds

recorded when the images is the particular frame were recorded. In other

33

alternatively embodiments, there could be no sound tracks and in such case the 1 images would be displayed without accompanying sound. 2 3 Having described and illustrated the principles of the invention in various 4 embodiments thereof, it should be apparent that the invention can be modified in 5 arrangement and detail without departing from the principles of the invention. We 6 claim all modifications and variation coming within the spirit and scope of the 7 following claims. 8 9 10 11 12

```
APPENDIX A: FRAME RETRIEVAL CODE
1
2
     #include "windows.h"
3
     #include "mmsystem.h"
 4
     #include "vfw.h"
 5
     #include "vfw spec.h"
6
                             sizeof(BITMAPINFOHEADER)
     #define S BMIH
 8
9
     // Externally declared (and allocated) variables
10
     extern UINT currentFrameNumber; // Current Pan Movie file frame number
11
      (user position)
12
      extern HANDLE hFile; // Open file handle of Pan Movie file
13
      extern HIC hic: // Open IC handle (installed compressor)
14
      extern DWORD *Index; // Pan Movie Frame Index (read from file at load
15
16
      time)
      extern LPBITMAPINFOHEADER viewFrame; // Buffer large enough to hold
17
      image the size of the display window
18
      extern LPBITMAPINFOHEADER panFrame; // Buffer large enough to hold
19
20
      largest uncompressed frame
      extern LPBITMAPINFOHEADER compressedFrame; // Buffer large enough to
21
      hold largest compressed frame
22
23
24
      // Function prototypes
      extern void ViewToPan(int viewWidth,int viewHeight,int panWidth,int
25
      panHeight, float heading, float pitch, float bank, float zoom, POINT *point);
26
      static LPBITMAPINFOHEADER RetrievePanFrame(int frameNumber,RECT
27
      *viewRect):
28
29
      //
30
      // This function generates a perspectively correct bitmap image given a
31
      user view orientation and travel speed
32
33
      static LPBITMAPINFOHEADER RetrieveViewFrame(float userHeading,float
34
      userPitch,float userBank,float userZoom,int userTravelSpeed)
35
36
             // Determine Decode BoundingBox
37
             POINT point;
38
             RECT localDecompressionRect;
39
40
             // Upper left corner of viewFrame
41
42
              point.x = 0; point.y = 0;
43
      ViewToPan(viewFrame->biWidth,viewFrame->biHeight,panFrame->biWidth,panFrame->biHei
44
      ght,userHeading,userPitch,userBank,userZoom,&point);
45
              localDecompressionRect.top
                                                    = point.y;
46
             localDecompressionRect.left
                                                    = point.x;
47
48
              // Upper right corner of viewFrame
49
              point.x = viewFrame->biWidth-1; point.y = 0;
50
51
      ViewToPan(viewFrame->biWidth,viewFrame->biHeight,panFrame->biWidth,panFrame->biHei
52
      ght,userHeading,userPitch,userBank,userZoom,&point);
53
                                                    = min(localDecompressionRect.top,point.y);
              localDecompressionRect.top
54
              localDecompressionRect.right = point.x;
55
```

```
// Lower left corner of viewFrame
1
             point.x = 0; point.y = viewFrame->biHeight-1;
2
3
     ViewToPan(viewFrame->biWidth,viewFrame->biHeight,panFrame->biWidth,panFrame->biHei
4
     ght,userHeading,userPitch,userBank,userZoom,&point);
5
             localDecompressionRect.bottom= point.y;
6
             localDecompressionRect.left
7
     min(localDecompressionRect.left,point.x);
8
9
             // Lower right corner of viewFrame
10
             point.x = viewFrame->biWidth-1; point.y = viewFrame->biHeight-1;
11
12
     ViewToPan(viewFrame->biWidth,viewFrame->biHeight,panFrame->biWidth,panFrame->biHei
13
     ght,userHeading,userPitch,userBank,userZoom,&point);
14
             localDecompressionRect.bottom=
15
     max(localDecompressionRect.bottom,point.y);
16
             localDecompressionRect.right =
17
     max(localDecompressionRect.right,point.x);
18
19
             // Get Pan Frame (or "userDecompressionRect" portion thereof)
20
             currentFrameNumber += userTravelSpeed; // userTravelSpeed is negative
21
     if traveling backwards
22
             LPBITMAPINFOHEADER pFrame =
23
     RetrievePanFrame(currentFrameNumber,&localDecompressionRect);
24
25
             if(pFrame == NULL) {
26
                     currentFrameNumber -= userTravelSpeed;
27
                     return NULL;
28
29
             }
30
             // A very slow warping routine (assumes 24-bit pixels)
31
                                           = ((LPBYTE)pFrame) + S_BMIH;
                            srcPixels
32
             LPBYTE
                                            = ((LPBYTE)viewFrame) + S_BMIH;
                            dstPixels
33
             LPBYTE
             for(int y = 0; y < viewFrame->biHeight; y++) {
34
                     for(int x = 0; x < viewFrame->biHeight; x++) {
35
                            point.y = y; point.x = x;
36
37
     ViewToPan(viewFrame->biWidth,viewFrame->biHeight,pFrame->biWidth,pFrame->biHeight,u
38
     serHeading,userPitch,userBank,userZoom,&point);
39
                            memcpy(&dstPixels[3*(x +
40
     y*viewFrame->biWidth)],&srcPixels[3*(point.x
41
     + point.y*pFrame->biWidth)],3); // supports 24-Bit Pixels only
42
43
44
             }
45
46
             return viewFrame;
47
     }
48
49
     // This function reads and decompresses a Pan Frame bitmap image from a
50
51
     Pan Movie file
52
     static LPBITMAPINFOHEADER RetrievePanFrame(int frameNumber,RECT
53
54
     *viewRect)
55
     {
             DWORD d:
56
             UINT frameSize = Index[frameNumber+1]-Index[frameNumber];
57
```

```
1
                         // Set the file pointer to the start of the requested frame and read in
 2
 3
           the bitmap header
                         SetFilePointer(hFile,Index[frameNumber],NULL,FILE\_BEGIN);
 4
                         ReadFile(hFile,panFrame,S_BMIH,&d,NULL);
 5
 6
                         if(panFrame->biCompression == 0) {
                                                                                                 // Uncompressed frame (read rest of
 7
           frame and return)
 8
                                        ReadFile(hFile,((BYTE*)panFrame)+S_BMIH,frameSize-S_BMIH,&d,NULL);
 9
                                        return panFrame;
10
                         }
11
12
                         // Read the remainder of the compressed frame
13
                          *compressedFrame
                                                                  = *panFrame;
14
15
           ReadFile(hFile, ((BYTE*)compressedFrame) + S\_BMIH, frameSize-S\_BMIH, \&d, NULL); \\
16
17
                          // Set up decompressed bitmap header
18
                                                                                    = 0;
                          panFrame->biCompression
19
                                                                                    = 0;
                          panFrame->biSizeImage
20
                          panFrame->biBitCount = 24;
21
                          panFrame->biClrUsed = 0;
22
23
                          LPBITMAPINFOHEADER biSrc = compressedFrame;
24
                          LPBITMAPINFOHEADER biDst = panFrame;
25
                                                                     = (BYTE*)biSrc + S_BMIH;
                          LPBYTE srcPixels
26
                                                                      = (BYTE*)biDst + S_BMIH;
                          LPBYTE dstPixels
27
28
                          // If the frame is compressed with Intel Indeo 4 and a local rect was
29
           requested, then perform local decompression
30
                          if(viewRect && biSrc->biCompression == mmioFOURCC('i','v','4','1')) {
31
           // Intel Indeo 4.1
32
                                                                                                   StateInfo;
                                         R4 DEC FRAME DATA
33
34
                                         memset(&StateInfo,0,sizeof(R4_DEC_FRAME_DATA));
35
                                                                                                                  = sizeof(R4 DEC_FRAME_DATA);
                                         StateInfo.dwSize
36
                                                                                                   = biSrc->biCompression;
                                         StateInfo.dwFourCC
37
                                                                                                   = SPECIFIC INTERFACE VERSION;
                                         StateInfo.dwVersion
38
                                                                                                                  = MT_DECODE_FRAME_VALUE;
                                         StateInfo.mtType
39
                                         StateInfo.oeEnvironment
                                                                                                                  = OE 32;
40
                                                                                                                  = DECFRAME_VALID |
                                         StateInfo.dwFlags
41
            DECFRAME_DECODE_RECT;
42
                                                                                                    = min(viewRect->left, viewRect->right);
                                         StateInfo.rDecodeRect.dwX
43
                                                                                                   = min(viewRect->top,viewRect->bottom);
                                         StateInfo.rDecodeRect.dwY
44
                                         StateInfo.rDecodeRect.dwWidth =
45
            abs((viewRect->right-viewRect->left))+1;
46
                                         StateInfo.rDecodeRect.dwHeight=
47
            abs((viewRect->bottom-viewRect->top))+1;
48
49
                                         ICSetState(hic,&StateInfo,sizeof(R4_DEC_FRAME_DATA));
 50
 51
 52
            if (ICDecompress Ex (hic, 0, biSrc, srcPixels, 0, 0, biSrc-> biWidth, biSrc-> biHeight, biDst, dstPixels, 0, biSrc-> biWidth, biSrc-> biHeight, biDst, dstPixels, 0, biSrc-> biWidth, biWidth, biSrc-> biWidth, 
 53
            0,biDst->biWidth,biDst->biHeight)
 54
 55
            != ICERR_OK )
                                                        return NULL;
 56
 57
                           }
```

```
else { // Decompress entire frame
1
2
      if(ICDecompressEx(hic,0,biSrc,srcPixels,0,0,biSrc->biWidth,biSrc->biHeight,biDst,dstPixels,0,0,biDst->biWidth,biDst->biHeight)
3
4
      != ICERR_OK)
5
                                 return NULL;
6
7
               }
8
               return panFrame;
9
10
      }
11
12
13
14
15
16
17
      © Infinite Pictures 1998
18
```

```
1
                   APPENDIX B: SAMPLE PAN MOVIE LINK CONTROL FILE
2
3
4
                            B ->
             <- C
5
6
7
8
9
                     Α
10
11
12
     [Segment-A (start)]
13
                     "Á.pan"
     File=
14
     North=
                     0
15
16
17
     [Segment-A (end)]
                     "A.pan"
     File=
18
                     0
     North=
19
                     "Segment-B (start)"
     Link 90=
20
                     "Segment-C (start)"
     Link 270=
21
22
23
     [Segment-B (start)]
                     "B.pan"
24
     File=
                     90
25
     North=
                     "Segment-A (end)"
     Link 90=
26
                     "Segment-C (start)"
     Link 180=
27
28
29
     [Segment-B (end)]
     File=
                     "B.pan"
30
     North=
                     90
31
32
     [Segment-C (start)]
33
                     "C.pan"
     File=
34
     North=
                     270
35
                     "Segment-A (end)"
     Link 270=
36
                     "Segment-B (start)"
     Link 180=
37
38
      [Segment-C (end)]
39
                     "C.pan"
      File=
40
                     270
      North=
41
42
43
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```

```
APPENDIX C PSEUDOCODE FOR
         LINKED PAN MOVIES (VIA CONTROL FILE)
2
3
     GLOBAL FILE controlFile // Control file
4
     GLOBAL STRING currentSegment // The name of the current pan movie
5
     GLOBAL INTEGER currentFrameNumber // The current frame number of the
7
     current Pan Movie
8
                     INTEGER currentHeading // The current user view horizontal pan
9
     GLOBAL
10
     orientation
11
12
     // This function will read the control file and determine which linked
13
     segment is closest
14
     // to the current user heading orientation
15
     // It will also determine the new frame number of the new segment
16
17
     BOOLEAN
                     RetrieveLink()
18
19
             INTEGER minAngle
20
             STRING nextSegment
21
22
             if currentFrameNumber == 0
23
                     currentSegment = currentSegment + (start)
24
             else
25
                     currentSegment = currentSegment + (end)
26
27
             if no links in section currentSegment of controlFile
28
                     return FALSE
29
30
                             = link angle closest to currentHeading
             minAngle
31
             nextSegment = GetString(minAngle)
32
33
             if AngleDifference(currentHeading,MinAngle) > 45 degrees
34
                     return FALSE;
35
36
              INTEGER nextNorth = GetNorth(nextSegment)
37
              INTEGER currentNorth = GetNorth(currentSegment)
38
39
              currentHeading = currentHeading + (nextNorth - currentNorth)
40
              currentSegment = nextSegment
41
42
              if stringFind(currentSegment,"(end)")
43
                     currentFrameNumber = -1
44
              else
45
                     currentFrameNumber = 0
46
47
              return TRUE
48
49
      }
50
51
      © Infinite Pictures 1998
52
```

1	I claim:
2	
3	1) A system for simulating movement through multidimensional space comprising in
4	combination,
5	a multi-lens camera for simultaneously capturing a plurality of digital images that
6	cover the entire spherical view field,
7	compression units for individually compressing said images into compressed images,
8	means for transferring said images to a computer,
9	a program operated by said computer which seams said images into panoramas and
10	which links said images into a sequence of images,
11	a viewer which displays said linked images in sequence.
12	
13	2) The system recited in claim 1 wherein said camera has six lenses, one positioned
14	on each side of a cube.
15	
16	3) The system recited in claim 1wherein said computer compresses said images after
17	seaming the images.
18	
19	4) The system recited in claim 3 wherein said compression is single frame
20	compression with no inter-frame compression.
21	
22	5) A method of simulating movement through multidimensional space comprising the
23	steps of:
24	capturing a series of sets of individual images, each set of images covering at least a
25	portion of a spherical view,
26	individually compressing said images,
27	transferring said images to a computer,
28	decompressing said images,
29	seaming the images in each set of images into a panorama,
30	compressing said panoramas without using any inter-frame compression,
31	de-compressing at least a portion of each panorama which corresponds to a view
32	window, and
33	displaying said view windows in sequence.

6) The method recited in claim 5 wherein each set of images comprises six images
 taken from the six sides of a cube.
 7) The method recited in claim 5 where the portion of each panorama de-

8) The method recited in claim 5 wherein said sequence of images has break points which provide at least two alternative sequences of images.

compressed for viewing is selected by an operator who indicates a direction of view.

9) The method recited in claim 5 wherein said the sequence of images displayed after a break point is selected in response to input from a user.

10) The method recited in claim 5 wherein sound is associated with each of said panoramas.

11) A three dimensional (3-D) panorama movie for enabling a user interactively to view movement through a three-dimensional space along a path through a series of viewpoints and to view in any viewing direction in the three-dimensional space, the 3-D panorama movie comprising:

 a computer storage medium for storage of machine readable image data; a file of machine readable image data stored on the storage medium, the image data including a plurality of panorama frames forming a sequence of images of the three dimensional space in which each image in the sequence has a spatially different viewpoint; and

a panframe directory stored on the storage medium in association with the file of machine readable image data, containing a set of frame indexes, each frame index identifying a location in the file of one of the panorama frames.

12) A panorama movie according to claim 11 in which there exists a direction of travel in three-dimensional space from each viewpoint, the direction of travel being stored in the panorama frame associated with each viewpoint as a predetermined point within the panorama frame to define a frame of reference for a viewing direction during playback.

A panorama movie according to claim 12 in which the predetermined point is 1 13) a centerpoint of the panorama frame. 2 3 14) A panorama movie according to claim 11 in which the panorama frames are 4 compressed using intraframe compression, defining a key frame, so that each frame 5 can be decompressed during playback independently of each other frame. 6 7 15) A panorama movie according to claim 11 in which the file includes a hot spot 8 associated with at least one of the frames, the hotspot being operable during 9 playback to superimpose a function on the playback of that frame. 10 11 16) A panorama movie according to claim 15 in which the hotspot includes an image 12 13 having a predetermined geometric shape to be superimposed over a feature in one 14 or more of the panorama frames. 15 17) A panorama movie according to claim 15 in which the hotspot image is stored 16 with an orientation in each panorama frame such that the superimposed image 17 appears in each frame at playback with a position and shape that conforms to a 18 perspective corrected shape and position of the feature over which it is 19 superimposed. 20 21 18) A panorama movie according to claim 11 which includes two or more of said 22 files, each forming a segment of the movie and having its own respective panframe 23 directory which includes terminal file indices defining a firstfile index and a lastfile 24 index for the respective terminal frames of each file, the movie further including a 25 control file containing linking data for linking terminal indices to link segments 26 27 together.

28 29

30

19) A panorama movie according to claim 18 in which the control file includes orientation information defining a new direction of travel to proceed from a terminal frame of first segment along a second segment linked to the first segment.

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33

34

20. A panorama movie according to claim 19 in which a third segments is also linked to the terminal frame of first segment, the control file orientation information

1	includi	ng an alternative new direction of travel selectable by the user during playback				
2	upon r	eaching the terminal frame of first segment, to branch the movie.				
3						
4	21)	A panorama movie according to claim 19 in which the new direction of travel				
5	is sele	ctable by the user selecting a viewing direction that approximately coincides				
6	with th	e new direction of travel.				
7						
8	22)	A panorama movie method for simulating movement through				
9	multidimensional space comprising the steps of:					
10		capturing a plurality of key-frame images consisting of respective panoramic				
11	image	ry taken from a plurality of spatial positions in multidimensional space;				
12		storing said key-frame images in a file in a storage medium;				
13		indexing said key-frame images within a key-frame directory according to a				
14	positio	n of each key-frame within the file and storing said key-frame directory on said				
15	storage medium;					
16		displaying a portion of a first key-frame image according to a user position				
17	and viewing direction within the multidimensional space;					
18		accessing said key-frame directory to determine a next key-frame image to be				
19	displa	yed according to a user travel speed and travel direction; and				
20		displaying a portion of a second key-frame image subsequent to the display				
21	of said	I first key-frame image according to a user position and viewing direction.				
22						
23	23)	The method of claim 22 wherein the step of capturing the plurality of key-				
24	frame	images includes taking photographs.				
25						
26	24)	The method of claim 22 wherein the step of capturing the plurality of key-				
27	frame	images includes rendering the images within a computer system.				
28						
29	25)	The method of claim 22 wherein a forward or reverse travel direction is				
30	deterr	nined by the order in which the keyframes are accessed.				
31						
32	26)	The method of claim 22 wherein a travel speed is determined by accessing				
33	each	nth key frame where n is an integer.				
34						

The method of claim 22 wherein a first segment of key-frame images is linked 27) 1 to a second segment of key-frame images by a control file stored in the storage 2 medium, the control file including stored travel direction for the second segment 3 which is selected by the user selecting a viewing direction at a terminal frame of the 4 fist segment that approximately coincides with the stored travel direction for the 5 second segment. 6 7 The method of claim 22 wherein the user actuates an input device to move 8 28) from a first position through a series of subsequent positions, the method including 9 display successive views of imagery from each of the successive positions. 10 11 The method of claim 22 including changing the viewing direction using the 29) 12 input device. 13 14 The method of claim 22 including superimposing objects into the display of 15 30) multiple successive frames at a location that coincides with apparent movement in 16 the 3-D space. 17 18 The method of claim 22 including compressing each panorama image using 31) 19 intraframe compression to form the key-frame images, and during playback selecting 20 a portion of the key frame that includes the desired viewed selected by the user for 21 local decompression. 22 23 The method of claim 22 including transforming the panorama images to a 32) 24 rectangular projection prior to compression. 25 26 33) The system recited in claim 1 wherein said program adds at least one sound 27 track to each panorama. 28 29 34) The system recited in claim 1 wherein said sequence of images includes break 30 points where said sequence can continue in at least one of two directions. 31 32 35) The system recited in claim 1 wherein the portion of said linked images displayed 33 is determined by the direction of view selected by a uses and wherein said direction 34 of view remains constant at break points until changed by a user. 35

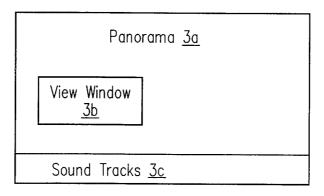


FIG. 1

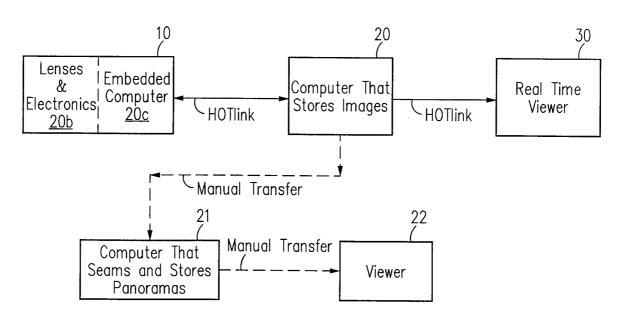
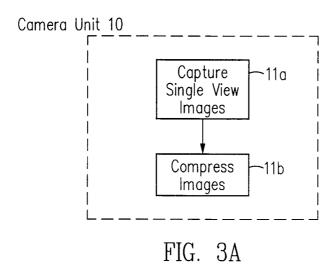
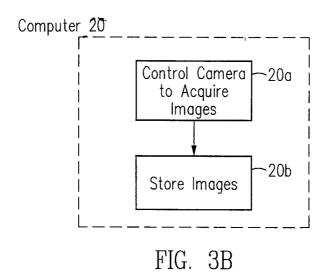
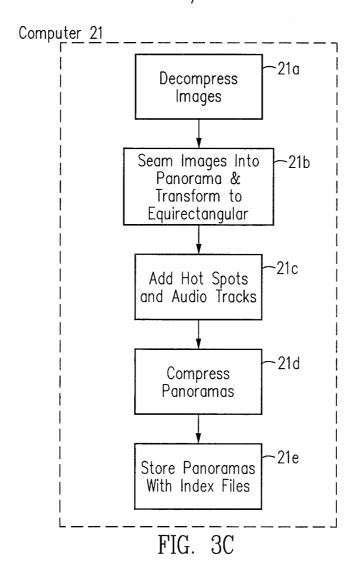
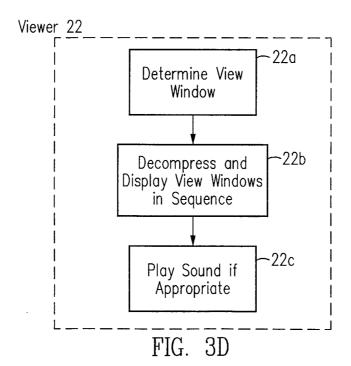


FIG. 2









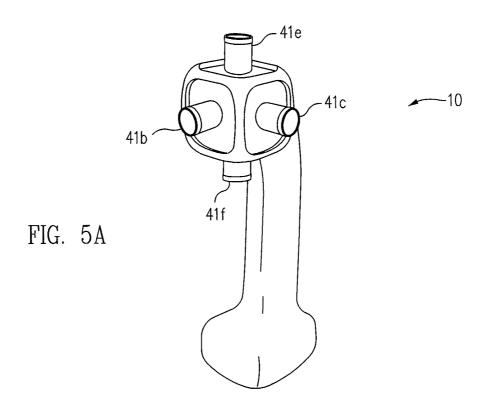
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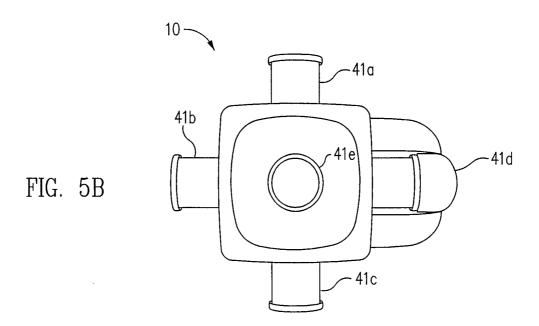
E D

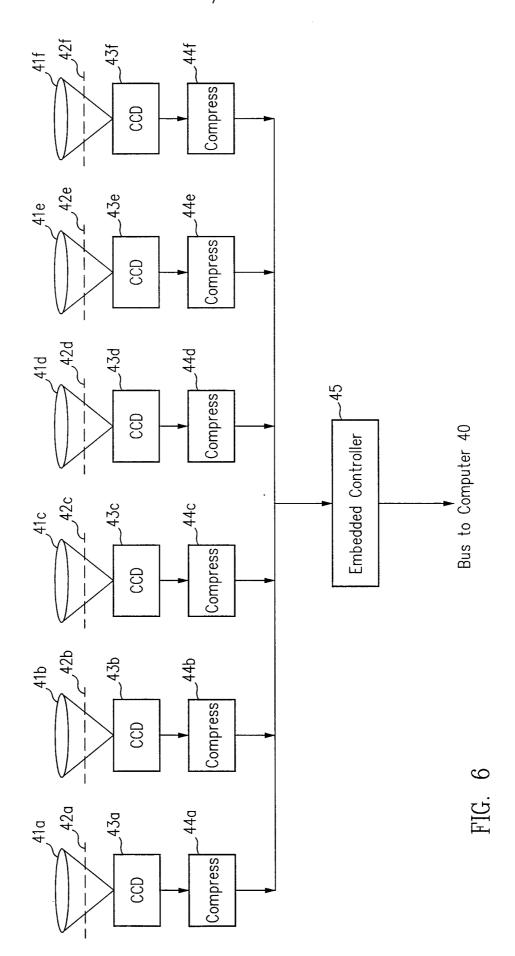
C Million D Mill

FIG. 4B

FIG. 4A







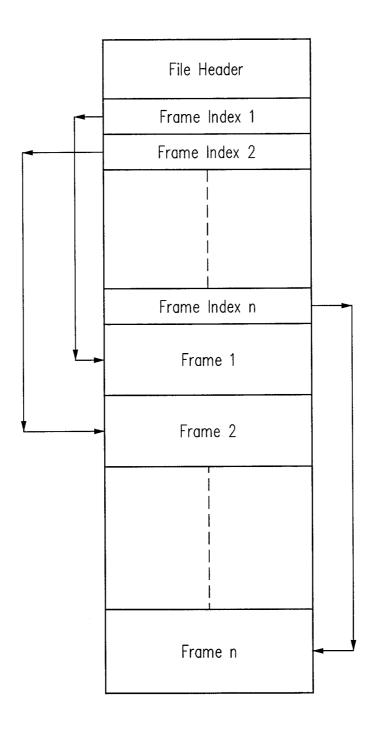


FIG. 7

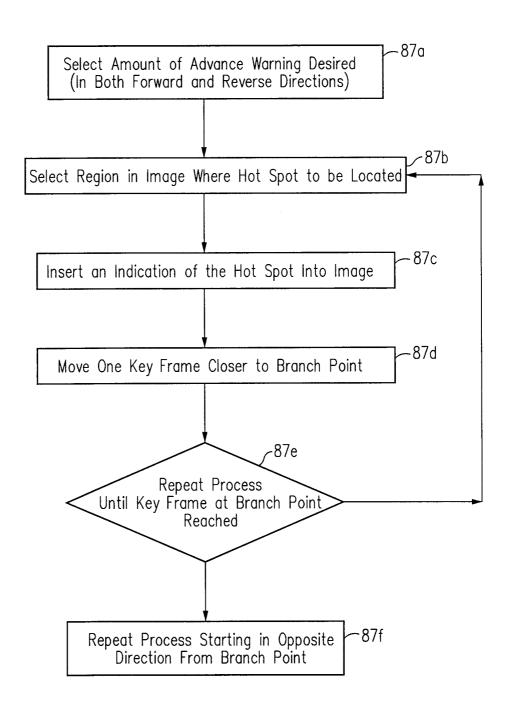
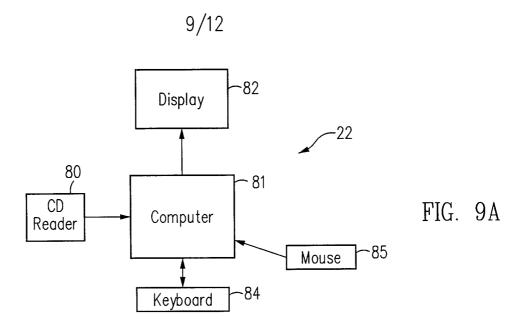
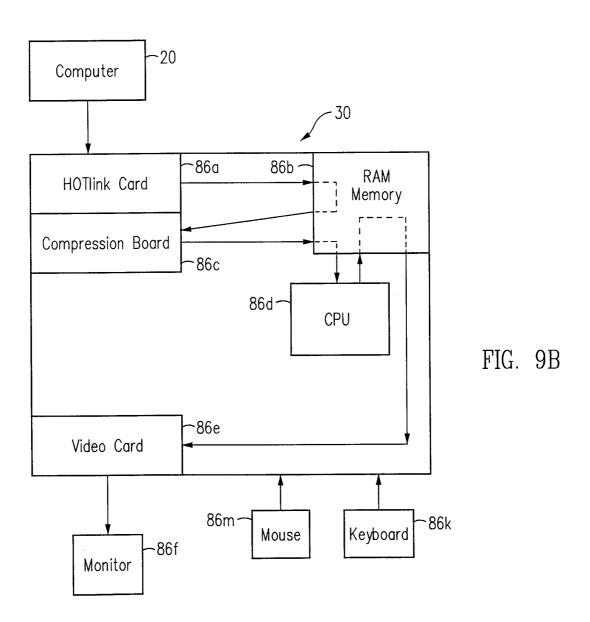


FIG. 8

WO 99/59026 PCT/US99/10403





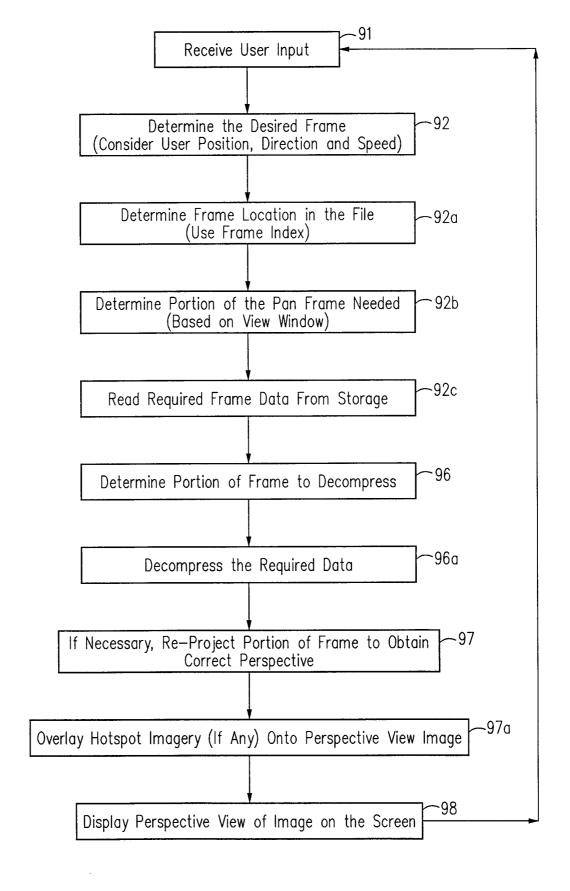


FIG. 10

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Fa	lmage Data	Audio A	Audio B	Audio C	Audio D	Audio E	Control Info
Fb	Image Data	Audio A	Audio B	Audio C	Audio D	Audio E	Control Info
Fc	Image Data	Audio A	Audio B	Audio C	Audio D	Audio E	Control Info
Fd	Image Data	Audio A	Audio B	Audio C	Audio D	Audio E	Control Info
Fe	lmage Data	Audio A	Audio B	Audio C	Audio D	Audio E	Control Info
Fg	lmage Data	Audio A	Audio B	Audio C	Audio D	Audio E	Control Info
Fh	lmage Data	Audio A	Audio B	Audio C	Audio D	Audio E	Control Info
Fi	lmage Data	Audio A	Audio B	Audio C	Audio D	Audio E	Control Info

FIG. 11

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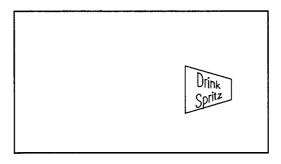


FIG. 12A

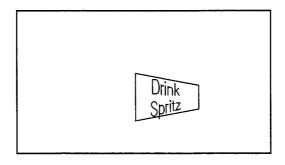


FIG. 12B

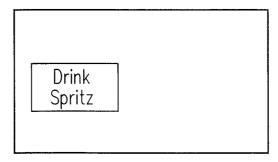


FIG. 12C