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FIG. 3

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CUTTING TOOL

BACKGROUND INFORMATION

5 **1. Field:**

The present disclosure relates generally to cutting materials and in particular to a method and apparatus for cutting slots in materials. Still more particularly, the present disclosure relates to a method and apparatus for creating slots to separate parts.

10 **2. Background:**

During manufacturing and/or maintenance, it may be necessary to remove parts from an aircraft. For example, without limitation, during assembly of an aircraft wing, it may be necessary to remove a spar or some other part for any number of reasons. During maintenance or other post-assembly operations, it may be desirable to replace parts.

15 For example, without limitation, a spar may be removed from the interior of an aircraft wing, and a new spar may be put in its place. When a spar is already present within an aircraft wing, a spar may not be easily removable without cutting the spar into multiple pieces. This situation may arise because of a lack of space within an assembled aircraft wing.

20 When removing a spar from an aircraft wing, it may be necessary to cut through the spar down to near the skin panel to which the spar may be attached. The skin panel may be a metallic, composite and metallic or composite skin panel. As a result, it may be important to not touch and/or cut into the skin panel, while cutting the spar into multiple pieces. It may be undesirable for a cutting tool to touch and/or cut into a skin panel. Touching or trimming the skin panel may extend the rework beyond the original scope of the project.

25 Currently, cuts may be made into the spar by hand. An operator may employ a cutting tool by hand to cut through the spar. The operator may make successive cuts deeper into the spar in an attempt to create a cut that may be deep enough to allow for separation of the spar into multiple pieces without touching and/or cutting into the skin panel. Large portions of the spar may be cut away leaving smaller portions that may be attached to the skin panel. These portions
30 may be removed in pieces. The cuts made into the portions of the spar that may be attached to the skin panel may take the form of slots. These slots may be cut within 1/1,000 at 1/100 of an inch to the surface of the skin panels without touching the skin panels.

This type of operation may be very time consuming. Further, expenses may increase if cuts touch and/or extend into the skin panel.

Accordingly, a need is present for a method and apparatus to minimize the time and effort needed to remove parts that overcome the problems discussed above.

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SUMMARY

The advantageous embodiments provide a method and apparatus for a cutting tool
10 system. In one advantageous embodiment, an apparatus may comprise a carriage that is moveable along an axis, a cutting tool, and a depth controller. The cutting tool may be capable of being removably attached to the carriage. The depth controller may be capable of controlling a cutting depth of the cutting tool with respect to a surface of a workpiece closest to a part.

In another advantageous embodiment, a cutting tool system may comprise a frame, a set
15 of roller tracks, a carriage, an air powered cutting tool, a depth controller, a clamping system, a set of adjustable feet, and a foot-operated power controller. The set of roller tracks may be attached to the frame. The carriage may be configured to move along the set of roller tracks. The air powered cutting tool may be capable of being removably attached to the carriage. The depth controller may be capable of controlling a cutting depth of the cutting tool with respect to a
20 surface of a workpiece. The clamping system may be attached the frame and may be capable of clamping the frame to the workpiece. At least one adjustable foot may be on a side of the frame and may be capable of being adjusted to contact the surface. Power may be supplied to the air powered cutting tool using the foot-operated power controller. The carriage may be capable of moving the air powered cutting tool in a first axis along a plane that is substantially parallel to
25 the surface, and the depth controller may be capable of moving the air powered cutting tool along an axis that is substantially normal to the surface.

In yet another advantageous embodiment, a method for cutting a slot in a workpiece may be present. A cutting tool system may be placed on the workpiece. The cutting tool system may comprise a carriage. A cutting tool may be capable of being removably attached to the carriage.
30 A depth of the slot may be selected using a depth controller. The slot may be cut with the cutting tool system.

In still yet another advantageous embodiment, a method for cutting a slot in a workpiece attached to a skin panel may be present. An access slot may be cut in the workpiece. A cutting

tool system may be placed into the access slot. The cutting tool system may comprise a frame, a set of tracks attached to the frame, a carriage configured to move along the set of tracks, a cutting tool capable of being removably attached to the carriage, and a depth controller capable of controlling a cutting depth of the cutting tool with respect to a surface of a part. The carriage may be positioned at a starting point. A foot system may be adjusted to touch a surface of the skin panel. The cutting tool system may be secured to the workpiece. A depth of the slot may be selected using the depth controller. The cutting tool may be activated. The carriage may be moved along the track system to cut the slot. The positioning step, the selecting step, and the activating step may be repeated until the slot has a desired depth.

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1. An apparatus comprising:
a carriage that is moveable along an axis;
a cutting tool capable of being removably attached to the carriage; and
a depth controller capable of controlling a cutting depth of the cutting tool with respect to
a surface of a workpiece.

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2. The apparatus of claim 1 further comprising:
a frame; and
a set of tracks attached to the frame, wherein the carriage is configured to move along the set of tracks.

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3. The apparatus of claim 1 further comprising:
a foot-operated power controller, wherein power is supplied to the cutting tool using the foot-operated power controller.

4. The apparatus of claim 2 further comprising:
a clamping system coupled to the frame to clamp the frame to the workpiece.

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5. The apparatus of claim 1, wherein the carriage is capable of moving the cutting tool in the axis along a plane that is substantially parallel to the surface.

6. The apparatus of claim 1, wherein the depth controller is capable of moving the cutting tool along the axis that is substantially normal to the surface.

7. The apparatus of claim 1, wherein the cutting tool is an air powered cutting tool.

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8. The apparatus of claim 1, wherein the cutting tool is selected from one of a dove tail cutter, a slotting cutter, a contour cutter, a rotary file, and an end mill cutter.

9. The apparatus of claim 2 further comprising:

a foot system on a side of the frame, wherein the foot system is capable of being adjusted to contact the surface.

10. The apparatus of claim 1, wherein the workpiece is a spar.

11. The apparatus of claim 10, wherein the spar is attached to a skin panel of an aircraft.

5 12. The apparatus of claim 1, wherein the surface of the workpiece is closest to a part.

13. The apparatus of claim 1, wherein the workpiece is comprised of a material selected from one of aluminum, a composite material, steel, wood, ceramic, and titanium.

14. A cutting tool system comprising:

a frame;

10 a set of roller tracks attached to the frame;

a carriage configured to move along the set of roller tracks;

an air powered cutting tool capable of being removably attached to the carriage;

a depth controller capable of controlling a cutting depth of the cutting tool with respect to a surface of a workpiece;

15 a clamping system attached the frame, wherein the clamping system is capable of clamping the frame to the workpiece;

at least one adjustable foot on a side of the frame, wherein the set of adjustable feet is capable of being adjusted to contact the surface; and

20 a foot-operated power controller, wherein power is supplied to the air powered cutting tool using the foot-operated power controller, wherein the carriage is capable of moving the air powered cutting tool in a first axis along a plane that is substantially parallel to the surface, and the depth controller is capable of moving the air powered cutting tool along an axis that is substantially normal to the surface.

25 15. The cutting tool system of claim 13, wherein the cutting tool is selected from one of a dove tail cutter, a slotting cutter, a contour cutter, a rotary file, and an end mill cutter.

16. The cutting tool system of claim 13, wherein the workpiece is comprised of a material selected from one of aluminum, a composite material, steel, wood, and titanium.

17. A method for cutting a slot in a workpiece, the method comprising:

30 placing a cutting tool system on the workpiece, wherein the cutting tool system comprises a carriage and a cutting tool capable of being removably attached to the carriage;

selecting a depth of the slot using a depth controller; and

cutting the slot with the cutting tool system.

18. The method of claim 16 further comprising:

cutting an access slot in the workpiece; and
placing the cutting tool system into the access slot prior to cutting the slot.

19. The method of claim 16 further comprising:

positioning the carriage at a starting point prior to cutting the slot.

5 20. The method of claim 16, further comprising:

adjusting a foot system to touch a surface of a part; and
securing the cutting tool system to the workpiece.

21. The method of claim 19, wherein the cutting step comprises:

activating the cutting tool; and

10 moving the carriage along the set of tracks to cut the slot.

22. The method of claim 17, wherein the cutting stool system further comprises a frame, a set of tracks attached to the frame, and a depth controller capable of controlling a cutting depth of the cutting tool with respect to the surface of the workpiece, wherein the carriage is configured to move along the set of tracks.

15 23. The method of claim 17 further comprising:

repeating the selecting and cutting steps until the slot has a desired depth.

24. A method for cutting a slot in a workpiece attached to a skin panel, the method comprising:

cutting an access slot in the workpiece;

20 placing a cutting tool system into the access slot, wherein the cutting tool system comprises a frame; a set of tracks attached to the frame; a carriage configured to move along the set of tracks; a cutting tool capable of being removably attached to the carriage; and a depth controller capable of controlling a cutting depth of the cutting tool with respect to a surface of a part;

25 positioning the carriage at a starting point;

adjusting a foot system to touch a surface of the skin panel;

securing the cutting tool system to the workpiece;

selecting a depth of the slot using the depth controller;

activating the cutting tool;

30 moving the carriage along the track system to cut the slot; and

repeating the positioning step, the selecting step, and the activating step until the slot has a desired depth.

The features, functions, and advantages can be achieved independently in various embodiments of the present disclosure or may be combined in yet other embodiments in which further details can be seen with reference to the following description and drawings.

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BRIEF DESCRIPTION OF THE DRAWINGS

The novel features believed characteristic of the advantageous embodiments are set forth in the appended claims. The advantageous embodiments, however, as well as a preferred mode
10 of use, further objectives and advantages thereof, will best be understood by reference to the following detailed description of an advantageous embodiment of the present disclosure when read in conjunction with the accompanying drawings, wherein:

Figure 1 is a flow diagram of an aircraft production and service methodology in which an advantageous embodiment may be implemented;

15 **Figure 2** is a block diagram of an aircraft in accordance with an advantageous embodiment;

Figure 3 is a block diagram of a cutting tool system in accordance with an advantageous embodiment;

20 **Figure 4** is a diagram of a cutting tool system in accordance with an advantageous embodiment;

Figure 5 is a perspective view of a cutting tool system attached to a workpiece in accordance with an advantageous embodiment;

Figure 6 is a perspective view of a workpiece and a part in accordance with an advantageous embodiment

25 **Figure 7** is a high level flowchart of a process for cutting a slot in a part in accordance with an advantageous embodiment; and

Figure 8 is a flowchart of a process for cutting a slot in a part attached to a skin panel in accordance with an advantageous embodiment.

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DETAILED DESCRIPTION

Referring more particularly to the drawings, embodiments of the disclosure may be described in the context of aircraft manufacturing and service method **100** as shown in **Figure 1** and an aircraft **102** as shown in **Figure 2**. During pre-production, aircraft manufacturing and service method **100** may include specification and design **104** of aircraft **102** and material procurement **106**.

During production, component and subassembly manufacturing **108** and system integration **110** of aircraft **102** takes place. Thereafter, aircraft **102** may go through certification and delivery **112** in order to be placed in service **114**. While in service by a customer, aircraft **102** is scheduled for routine maintenance and service **116** (which may also include modification, reconfiguration, refurbishment, and so on).

Each of the processes of aircraft manufacturing and service method **100** may be performed or carried out by a system integrator, a third party, and/or an operator (e.g., a customer). For the purposes of this description, a system integrator may include, without limitation, any number of aircraft manufacturers and major-system subcontractors; a third party may include, for example, without limitation, any number of vendors, subcontractors, and suppliers; and an operator may be an airline, leasing company, military entity, service organization, and so on.

As shown in **Figure 2**, aircraft **102** produced by aircraft manufacturing and service method **100** may include airframe **118** with a plurality of systems **120** and interior **122**. Examples of systems **120** include one or more of propulsion system **124**, electrical system **126**, hydraulic system **128**, and environmental system **130**. Any number of other systems may be included in this example. Although an aerospace example is shown, the principles of the disclosure may be applied to other industries, such as the automotive industry.

Apparatus and methods embodied herein may be employed during any one or more of the stages of aircraft manufacturing and service method **100**. For example, without limitation, components or subassemblies corresponding to component and subassembly manufacturing **108** may be fabricated or manufactured in a manner similar to components or subassemblies produced while aircraft **102** is in service.

Also, one or more apparatus embodiments, method embodiments, or a combination thereof may be utilized during component and subassembly manufacturing **108** and system integration **110**, for example, without limitation, by substantially expediting assembly of or

reducing the cost of aircraft **102**. Similarly, one or more of apparatus embodiments, method embodiments, or a combination thereof may be utilized while aircraft **102** is in service, for example, without limitation, to maintenance and service **116**. As a specific example, the different advantageous embodiments may be implemented during maintenance and service **114** to cut slots
5 in parts to be removed from airframe **202** in aircraft **200**. The advantageous embodiments also may be applied to other stages of aircraft manufacturing and service method **100** whenever cuts are to be made into a structure within aircraft **200**.

The different advantageous embodiments recognize and take into account difficulties involved with cutting parts to be removed. In particular, the different advantageous
10 embodiments recognize and take into account that cutting and/or removing a spar from inside of a wing may be a time consuming and difficult operation in order to avoid touching or trimming a skin panel.

Thus, the different advantageous embodiments provide a method and apparatus for cutting a material. In the different advantageous embodiments, an apparatus may include a
15 frame, a set of roller tracks attached to the frame, a carriage, a cutting tool, and a depth controller. A set, as used herein, refers to one or more items. For example, without limitation, a set of roller tracks is one or more roller tracks.

With reference now to **Figure 3**, a block diagram of a cutting tool system is depicted in accordance with an advantageous embodiment. In this example, cutting tool system **300** may
20 include frame **302**, track system **304**, carriage **306**, cutting unit **308**, depth controller **310**, adjustable feet **312**, and clamping system **314**.

Track system **304** may be attached to frame **302**. Track system **304** may take various forms. For example, without limitation, track system **304** may be a set of tracks, such as set of roller bearing tracks **316**. In other examples, track system **304** may include, for example,
25 without limitation, linear motion devices and/or other suitable mechanisms. For example, without limitation, set of roller bearing tracks **316** may be two or more roller bearing tracks that may be positioned parallel to each other on frame **302**. In other illustrative examples, three roller bearing tracks may be present on frame **302**.

Carriage **306** may be configured to move along track system **304**. In this example,
30 carriage **306** may move horizontally along the direction of arrow **318**. In other words, carriage **306** is a moveable carriage that is moveable along an axis as shown by arrow **318**. Further, cutting unit **308** may be removably attached to carriage **306**. Carriage **306** may move cutting

unit **308** along the direction of arrow **318** when cutting operations are performed using cutting unit **308**.

Cutting unit **308** may take various forms. For example, without limitation, cutting unit **308** may be a dove tail cutter, a slotting cutter, a contour cutter, an end mill cutter, a rotary file and/or some other suitable cutting tool. In these examples, depth control **310** may be capable of controlling the movement of cutting unit **308** along a vertical axis, as illustrated by arrow **320**. As depicted, surface **322** of frame **302** may be placed on surface **324** of workpiece **326**. Adjustable feet **312** may comprise adjustable members that may contact surface **324** and/or lower surface **330** of workpiece **326**. In these illustrative examples, workpiece **326** may be, for example, without limitation, spar **328**. Workpiece **326** also may take other forms. For example, without limitation, workpiece **326** may be a rivet to be shaved, a skin panel being trimmed, a rib in which a groove may be formed, and/or some other suitable object.

Clamping system **314** may hold frame **302** in place with respect to workpiece **326**. In this manner, frame **302** may be securely placed and/or attached to workpiece **326** to perform a cutting operation. Clamping system **314** may engage workpiece **326** as shown by arrow **332**.

After frame **302** has been clamped and/or secured to workpiece **326**, cutting unit **308** may be positioned vertically along arrow **320** to cut slot **334** into surface **324** of workpiece **326**. The positioning of cutting unit **308** on carriage **306** may be controlled by depth controller **310**.

Cutting unit **308** may be powered using a motor such as, for example, without limitation, air motor **336**. Use of air motor **336** may allow cutting tool system **300** to be used in locations in which combustible and/or explosive vapors may be present. Of course, in other advantageous embodiments, an electric motor may be used in place of air motor **336**, depending on the particular implementation.

In these examples, operation of air motor **336** may be performed using foot pedal **338**, which may be connected to air motor **336** through connection **340**. Connection **340** may be, for example, without limitation, an air line, in these examples. Foot pedal **338** may allow an operator to free up the operator's hands to control cutting tool system **300** throughout the operation of creating slot **334** in workpiece **326**.

As cutting unit **308** cuts into workpiece **326** to create slot **334**, carriage **306** may be moved along track system **304** to create slot **334**. Depth **342** for slot **334** may be controlled using depth controller **310**. Depth controller **310** may be capable of moving and/or controlling the position of cutting unit **308** along axis **346**, which may be substantially normal to surface

324. In this manner, slot **334** may be cut into workpiece **326** without reaching and/or touching part **344**.

In these illustrative examples, part **344** may be, for example, without limitation, a skin panel or some other suitable component. Workpiece **326** may be comprised of various materials.

5 For example, without limitation, workpiece **326** may be comprised of a material such as aluminum, a composite material, steel, wood, titanium, plastic, ceramic, or some other suitable material.

The illustration of cutting tool system **300** in **Figure 3** is provided for purposes of illustrating different features that may be present in various advantageous embodiments. The
10 illustration of cutting tool system **300** in **Figure 3** is not meant to imply physical and/or architectural limitations to the manner in which different advantageous embodiments may be implemented.

For example, without limitation, although the different examples illustrate a capability of moving cutting unit **308** in one axis in a horizontal direction and in a vertical direction, in other
15 advantageous embodiments, cutting unit **308** may be moveable around three axes.

In yet other advantageous embodiments, adjustable feet **312** may not be present within cutting tool system **300**. In still other advantageous embodiments, cutting tool system **300** may include an additional carriage in addition to carriage **306** and/or carriage **306** may support a second cutting tool to provide a capability to cut or form another slot in addition to slot **334**.

20 With reference now to **Figure 4**, a diagram of a cutting tool system is depicted in accordance with an advantageous embodiment. In this example, cutting tool system **400** is an example of one implementation of cutting tool system **300** in **Figure 3**.

As illustrated, cutting tool system **400** includes frame **402** with track system **404**. Track system **404** may be comprised of roller bearing track **406** and roller bearing track **408**. Cutting
25 tool system **400** also may include carriage **410**, which may be attached to and removed from roller bearing track **406** and roller bearing track **408**.

In this depicted example, cutting unit **412** may be attached to and removed from carriage **410**. Cutting unit **412** may include air motor **414**, air supply inlet **416**, and end mill cutter **418**.

Cutting tool system **400** also may include clamping system **420**. In this illustrative
30 example, clamping system **420** may include clamp bar **422**, clamp lock **424**, clamp lock **426**, and clamp bar thrust screw **428**. Frame **402** is shown with a cutaway to allow viewing of clamp bar thrust screw **428**. Clamp bar thrust screw **428** may push foot **444** and foot **446** to a surface (not shown). Clamp bar **422** may move vertically along the direction of arrow **430** in these examples.

When positioned in a desired level and/or location, clamp bar **422** may be locked into place using clamp lock **424** and/or clamp lock **426**.

In these illustrative examples, depth controller **432** may comprise cut stop **434**, adjustment screw **436**, lock nut **438**, and depth set unit **440**. Cut stop **434** may be connected to cutting unit **412** through adjustment screw **436** and lock nut **438**. Further, depth set unit **440** may lock cutting unit **412** into place within carriage **410**. Cut stop **434** may be adjusted to control the depth at which cutting unit **412** may reach. Cut stop **434** may allow for a number of different cutting positions. Cut stop **434** may be implemented using any mechanism that may be capable of providing different cutting positions. In particular, cut stop **434** may be used to adjust the depth of cutter **418** along axis **442**.

Cutting tool system **400** also may include a set of feet, such as, for example, without limitation, foot **444** and foot **446**. Two other feet may be present, which are not shown in this view.

Air supply inlet **416** may be connected to air hose **448**. Air supplied to air motor **414** by air hose **448** may be controlled by foot pedal **450**. With the use of foot pedal **450**, an operator may control cutting unit **412** with a foot, allowing both hands to be free to handle cutting unit **412** and/or frame **402**. For example, without limitation, an operator may use one or both hands to move cutting unit **412** on carriage **410** along track system **404** while performing cutting operations.

With reference now to **Figure 5**, a perspective view of a cutting tool system attached to a workpiece is depicted in accordance with an advantageous embodiment. In this example, cutting tool system **400** is shown in a perspective view with respect to spar **500**.

Spar **500** may be attached to skin panel **502**. In this illustrative example, spar **500** may be selected for removal from skin panel **502**. In this illustration, access slot **504** may be present in spar **500**. Access slot **504** may allow cutting tool system **400** to be placed onto surface **506** of spar **500**.

Foot **444**, foot **446**, and foot **507** may touch surface **508** of skin panel **502**. Adjustable foot **510**, also on frame **402**, may be adjusted to touch surface **508** of skin panel **502**. In this illustrative example, carriage **410** may be positioned at starting point **505**.

Clamp bar **422** may be positioned to touch surface **512**, of spar **500**, to secure and/or lock cutting tool system **400** into place. Clamp lock **424** and clamp lock **426** (not shown) may be adjusted to clamp bar **422** in place on surface **512** of spar **500**.

Cut stop **434** may be adjusted to a lowest position for creating slot **514** in spar **500** with end mill cutter **418**. This adjustment may be made to provide a depth leaving around 0.01 inches in section **516**, in this illustrative example. Of course, other depths may be left in section **516** depending on the particular implementation. For example and without limitation, a depth of
5 around 0.1 inches, around 0.001 inches, or some other suitable depth may be selected for section **516**. The depth may depend on the number of steps present within cut stop **434**.

Thereafter, cut stop **434** may be adjusted to a highest setting in preparation for an initial cut. Cutting unit **412** may be locked into place using depth set unit **440**.

Cutting unit **412** may then be activated by activating the air supply to air supply unit **416**.

10 Carriage **410** may be moved along roller bearing track **406** and roller bearing track **408** in the direction of axis **518** to cut slot **514** into spar **500**. When a cut is made into slot **514**, carriage **410** may be moved back to starting point **505**. Cut stop **434** may be adjusted to lower end mill cutter **418** to a next level. Then, another cut may be made into spar **500** to increase the depth of slot **514**. This process may be repeated until section **516** is reached. Section **516** may be reached
15 without touching and/or cutting into surface **508** of skin panel **502**.

The dimensions of cutting tool system **400** may vary depending on the particular implementation. In these examples, cutting tool system **400** may have a size that makes this system portable and useable within a wing of an aircraft to cut slots into structures such as, for example, without limitation, spar **500**. Cutting tool system may have length **519** of around 21.0
20 inches, height **520** of around 13.0 inches, and width **522** of around 5.0 inches. Of course, the dimensions may vary depending on the particular implementation selected. Further, cutting tool system **300** also may provide a size advantage based on its design and/or configuration in these examples.

The illustration of cutting tool system **400** in **Figures 4 and 5** has been presented as one
25 implementation of cutting tool system **300** in **Figure 3**. This illustration is not meant to imply physical and/or architectural limitations to the manner in which other advantageous embodiments may be implemented.

For example, without limitation, in other advantageous embodiments, a different tool other than end mill cutter **418** may be used. For example, without limitation, a bit and/or tool in
30 the form of a dove tail cutter, a slotting cutter, a contour cutter, or some other suitable tool may be used. As another non-limiting example, three tracks may be used instead of roller bearing track **406** and roller bearing track **408**.

With reference now to **Figure 6**, a perspective view of a workpiece and a part is depicted in accordance with an advantageous embodiment. In this example, spar **500** is shown with access slot **504** and slot **514** after cutting operations have been completed using cutting tool system **400**.

5 With reference now to **Figure 7**, a high level flowchart of a process for cutting a slot in a part is depicted in accordance with an advantageous embodiment. The process illustrated in **Figure 7** is an example of a process that may be implemented using cutting tool system **300** in **Figure 3**.

10 The process may begin by placing cutting tool system **300** on surface **324** of a material (operation **700**). The final depth of a cutter may be set (operation **702**). The process may select a depth of a pass using depth controller **310** in the cutting tool system (operation **704**). In operation **704**, the pass may be one of a number of passes used to form the slot. Each pass may make a deeper cut into the part to form the slot. Thereafter, the process may cut the slot using the cutting tool system (operation **706**). A determination may be made as to whether the final
15 depth has been reached (operation **708**). If the final depth has been reached, the process may terminate. Otherwise, the process may return to operation **704** to select a new depth for a pass.

20 With reference now to **Figure 8**, a flowchart of a process for cutting a slot in a workpiece attached to a skin panel is depicted in accordance with an advantageous embodiment. The process illustrated in **Figure 8** may be implemented using a cutting tool system, such as cutting tool system **300** in **Figure 3**.

25 The process may begin by cutting access slot **504** in workpiece **326** (operation **800**). This access slot may be cut having a width to allow placement of cutting tool system **400** onto surface **506** of workpiece **326** where slot **514** may be desired. This operation may be performed by an operator using an existing access hole or port in the aircraft. This operation may be performed using cutting tool system **400**, or some other suitable tool. Cutting tool system **400** may be placed into the access slot (operation **802**). Carriage **410** may be positioned at starting point **505** (operation **804**).

30 Next, clamp bar **432** may be positioned touching a top surface of a portion of workpiece **326** (operation **806**). The process may then lock clamp bar **432** in place (operation **808**). This operation may secure the cutting tool system to part **344**. A foot system, such as adjustable feet **312**, may be positioned to touch the surface of skin panel **502** (operation **810**). Feet **444** and **446** may be clamped to the surface (operation **811**). In operation **811**, clamp bar thrust screw **428** may be tightened to clamp the feet to the surface of skin panel **502**.

Cut stop **434** may be rotated to a lowest position to set a depth of slot **514**(operation **812**). In the illustrative examples, the lowest position may identify the amount of material left in the part when slot **514** is complete. The process may move cut stop **434** to the high setting for the first cut (operation **814**). The process may then lock cutting unit **412** in place in the carriage
5 (operation **816**).

The air supply, such as, for example, without limitation, air motor **414**, may be attached to air supply inlet **416** (operation **818**). The air supply may be activated using foot pedal **450** (operation **820**). Carriage **412** may be moved along track system **404** to cut slot **514** (operation **822**). The process then may return to the starting point (operation **824**).

10 A determination may be made as to whether slot **514** is complete (operation **826**). If slot **514** is not complete, cut stop **434** may be adjusted to a next lower position (operation **828**). The process may lock cutting unit **412** in place (operation **830**). The process may activate the air supply provided by air motor **414** (operation **832**). The process may then move carriage **410** to further cut slot **514** (operation **834**), with the process returning to operation **824**. In these
15 examples, each cut may increase the depth of slot **514**. With reference back to operation **826**, if slot **514** has been completed, the process terminates.

Thus, the different advantageous embodiments may provide a method and apparatus for cutting slot **344** in workpiece **344**. In the different advantageous embodiments, an apparatus may have frame **302**, track system **304**, carriage **306**, cutting unit **308**, and depth controller **310**.

20 Track system **304** may be attached to frame **302** with carriage **306** being configured to move along track system **304**. Cutting unit **308** may be removably attached to carriage **306**. Depth controller **310** may control the cutting depth of cutting unit **308** with respect to surface **324** of workpiece **326**.

Thus, the different advantageous embodiments provide a capability to remove older
25 workpieces. The different advantageous embodiments provide a capability to control the depth of a slot cut to remove a workpiece. These cuts may be selected to avoid touching and/or cutting into a workpiece that may be below the workpiece being removed. The amount of time and effort needed and risk to cut a slot may be substantially reduced using the different advantageous embodiments.

30 The description of the different advantageous embodiments has been presented for purposes of illustration and description, and is not intended to be exhaustive or limited to the embodiments in the form disclosed. Many modifications and variations will be apparent to those of ordinary skill in the art. Further, different advantageous embodiments may provide different

advantages as compared to other advantageous embodiments. The embodiment or embodiments selected are chosen and described in order to best explain the principles of the embodiments, the practical application, and to enable others of ordinary skill in the art to understand the disclosure for various embodiments with various modifications as are suited to the particular use

5 contemplated.

CLAIMS:

What is claimed is:

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1. An apparatus comprising:
a carriage that is moveable along an axis;
a cutting tool capable of being removably attached to the carriage; and
a depth controller capable of controlling a cutting depth of the cutting tool with respect to
10 a surface of a workpiece.

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2. The apparatus of claim 1 further comprising:
a frame; and
a set of tracks attached to the frame, wherein the carriage is configured to move along the
set of tracks.

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3. The apparatus of claim 1 further comprising:
a foot-operated power controller, wherein power is supplied to the cutting tool using the
foot-operated power controller.

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4. The apparatus of claim 2 further comprising:
a clamping system coupled to the frame to clamp the frame to the workpiece.

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5. The apparatus of claim 1, wherein the carriage is capable of moving the cutting tool in
the axis along a plane that is substantially parallel to the surface.

6. The apparatus of claim 1, wherein the depth controller is capable of moving the cutting
tool along the axis that is substantially normal to the surface.

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7. The apparatus of claim 2 further comprising:
a foot system on a side of the frame, wherein the foot system is capable of being adjusted
to contact the surface.

8. The apparatus of claim 1, wherein the workpiece is a spar.

9. The apparatus of claim 1, wherein the surface of the workpiece is closest to a part.

5 10. A method for cutting a slot in a workpiece, the method comprising:
placing a cutting tool system on the workpiece, wherein the cutting tool system comprises
a carriage and a cutting tool capable of being removably attached to the carriage;
selecting a depth of the slot using a depth controller; and
cutting the slot with the cutting tool system.

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11. The method of claim 10 further comprising:
cutting an access slot in the workpiece; and
placing the cutting tool system into the access slot prior to cutting the slot.

15 12. The method of claim 10 further comprising:
positioning the carriage at a starting point prior to cutting the slot.

13. The method of claim 10, further comprising:
adjusting a foot system to touch a surface of a part; and
20 securing the cutting tool system to the workpiece.

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14. The method of claim 12, wherein the cutting step comprises:
activating the cutting tool; and
moving the carriage along the set of tracks to cut the slot.

15. The method of claim 17, wherein the cutting stool system further comprises a frame, a set
of tracks attached to the frame, and a depth controller capable of controlling a cutting depth of
the cutting tool with respect to the surface of the workpiece, wherein the carriage is configured to
move along the set of tracks.

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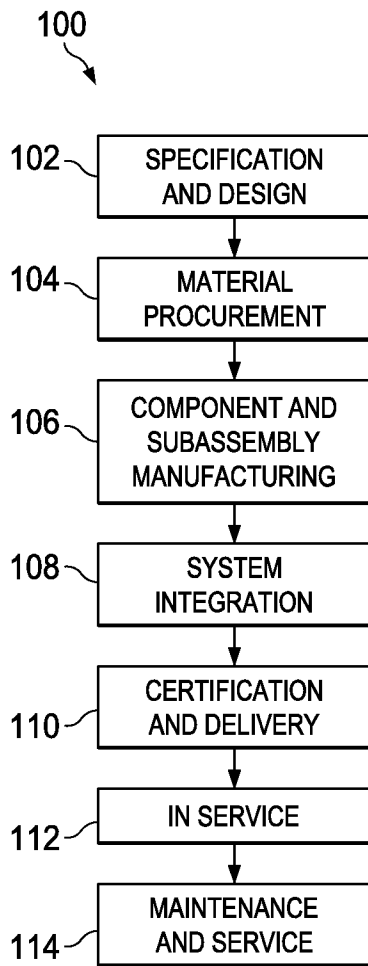


FIG. 1

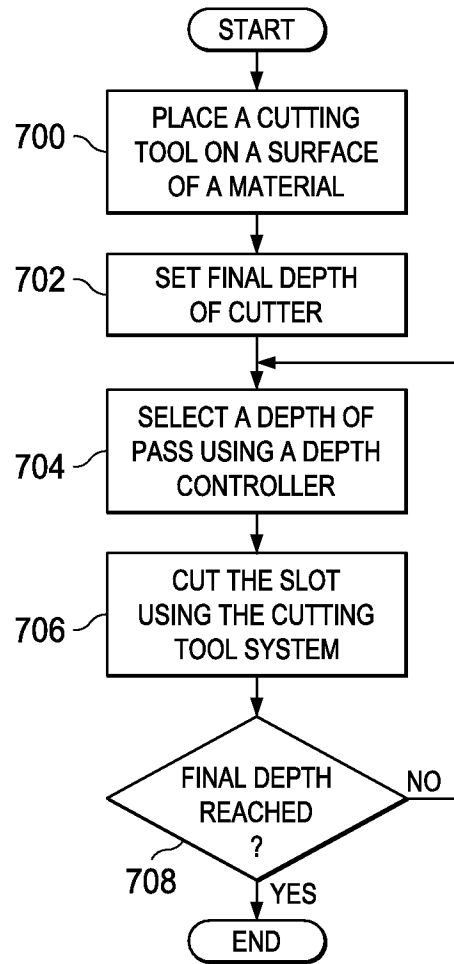


FIG. 7

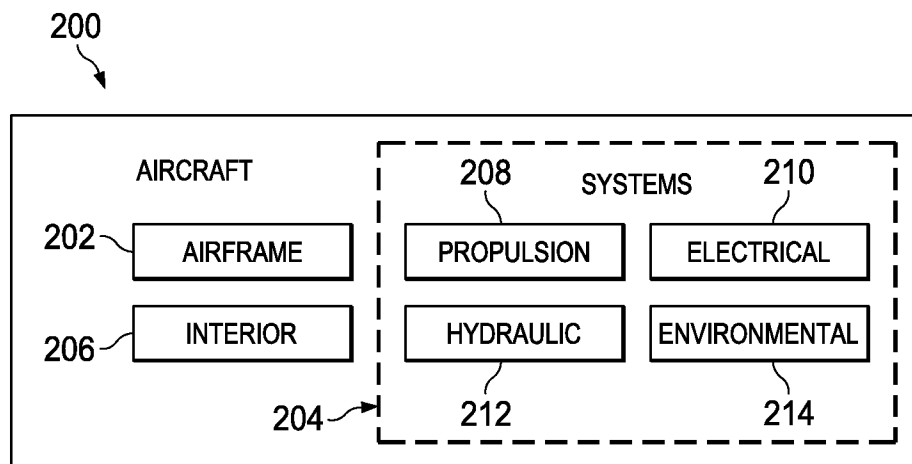


FIG. 2

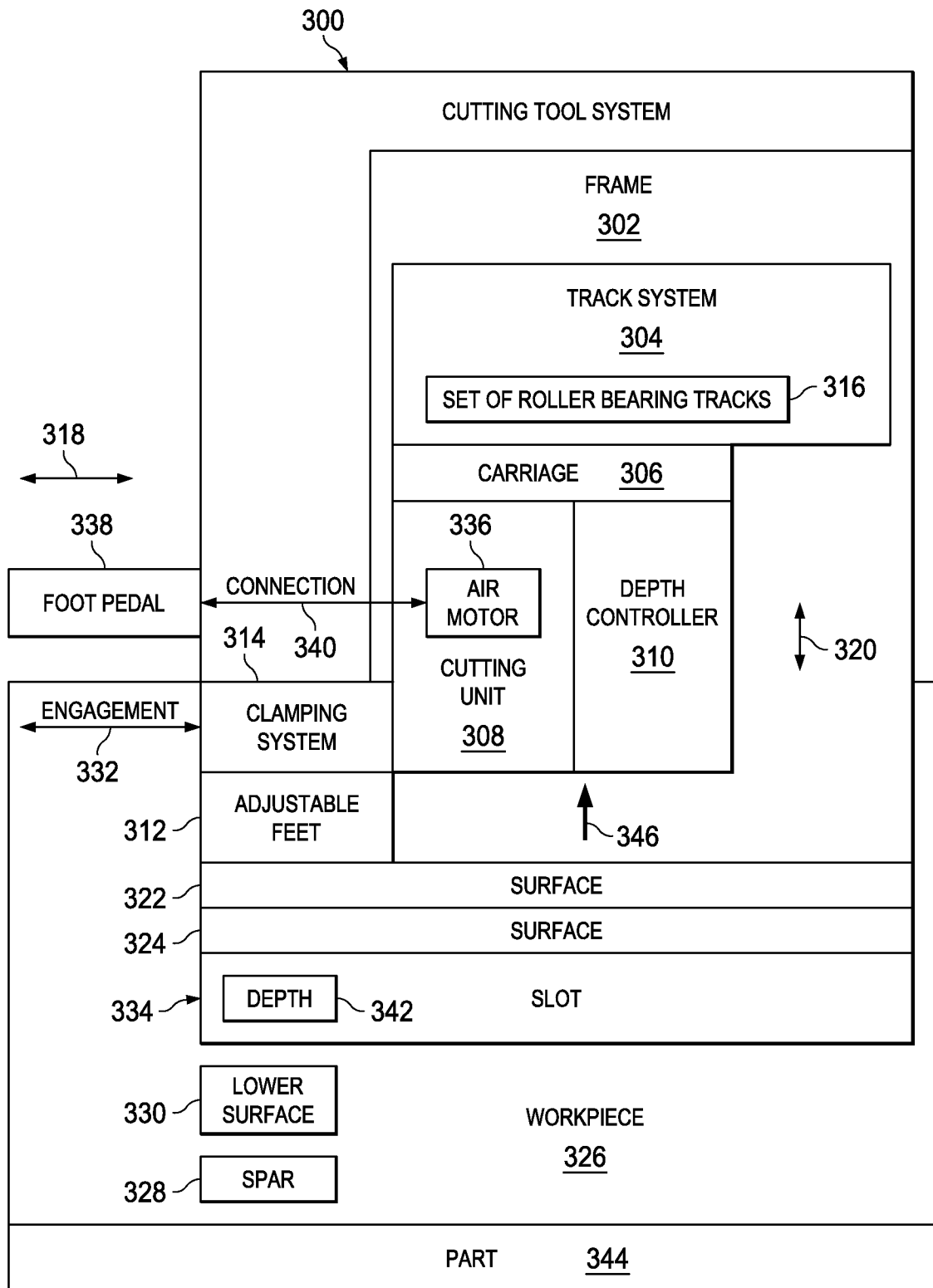


FIG. 3

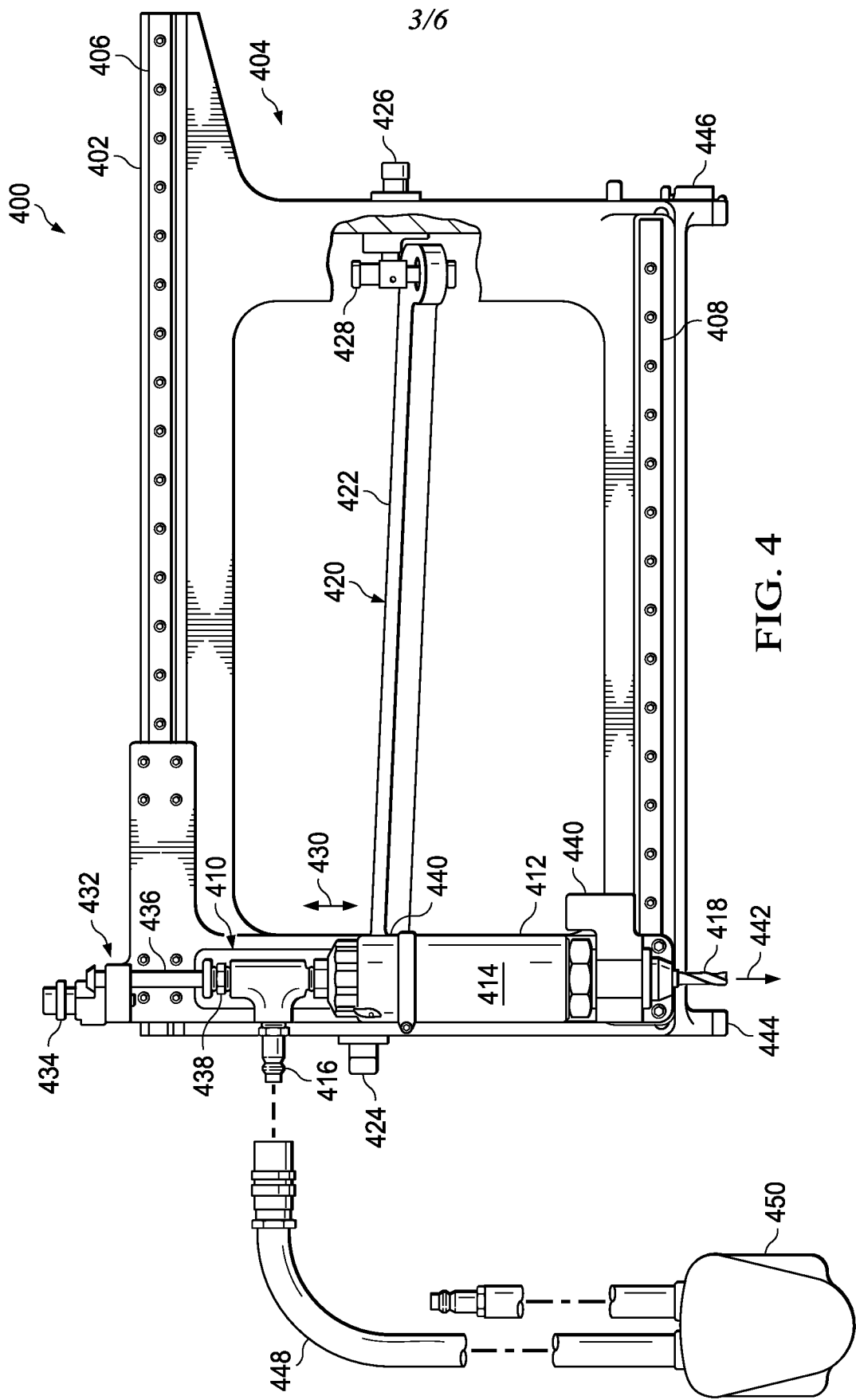


FIG. 5

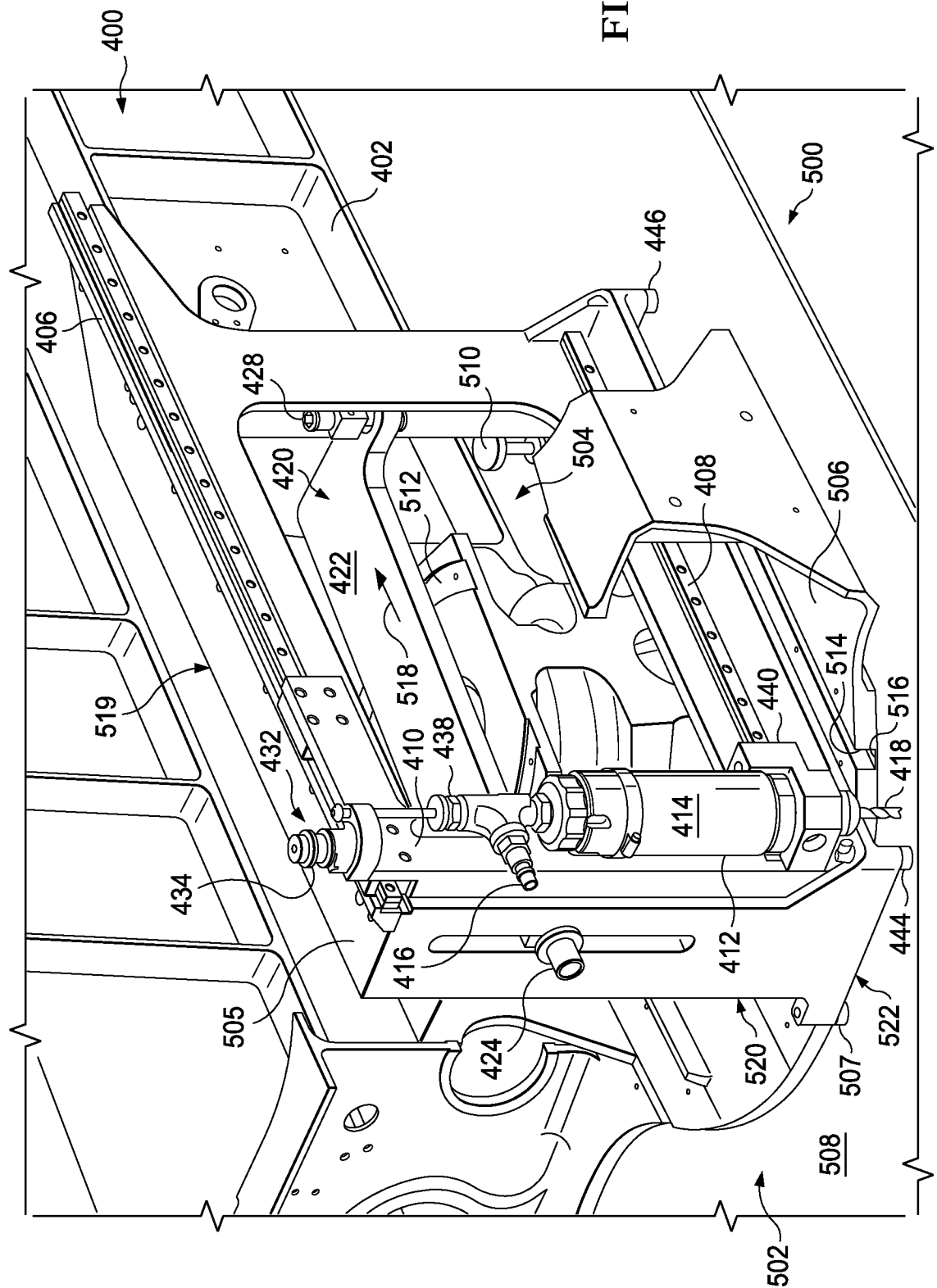
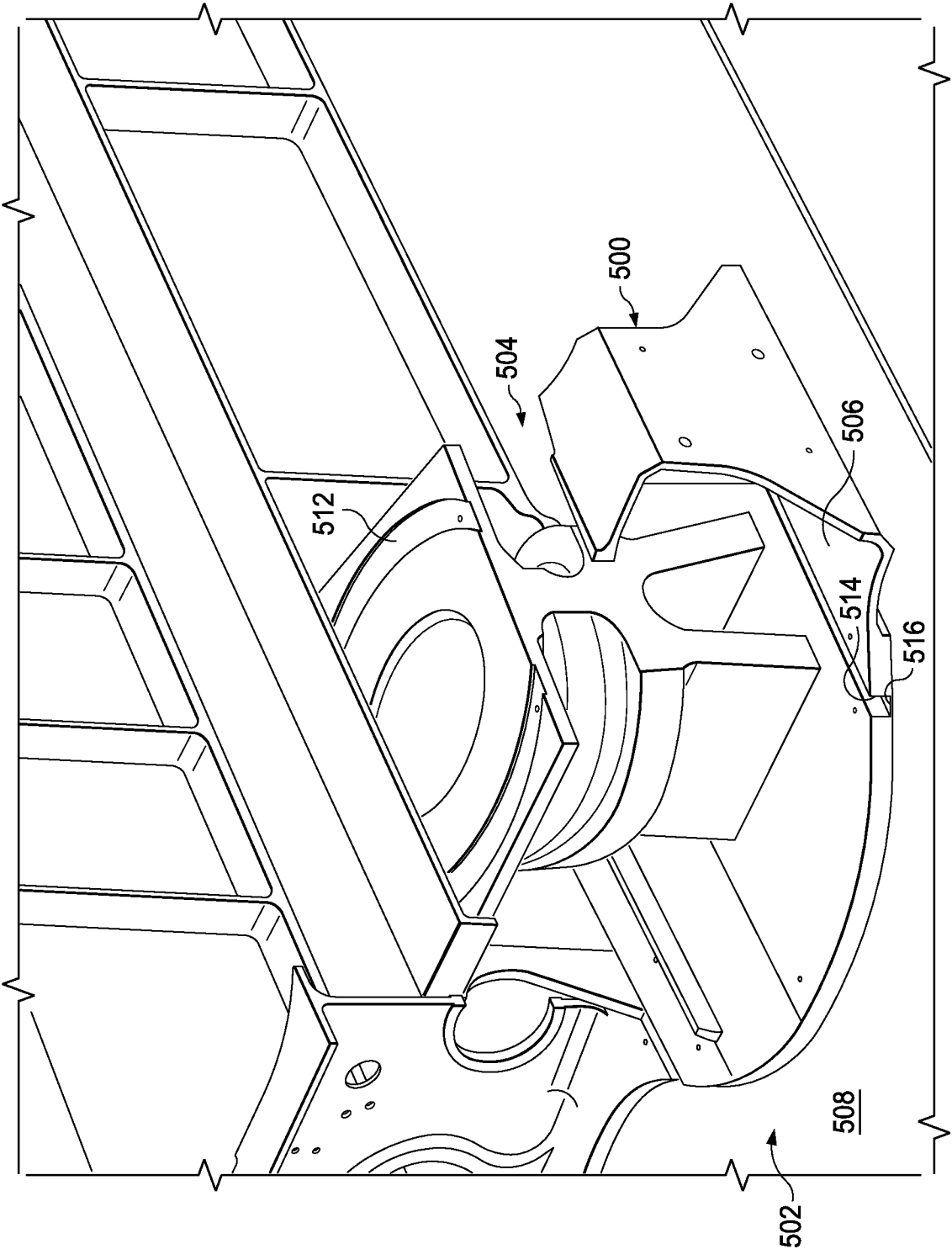
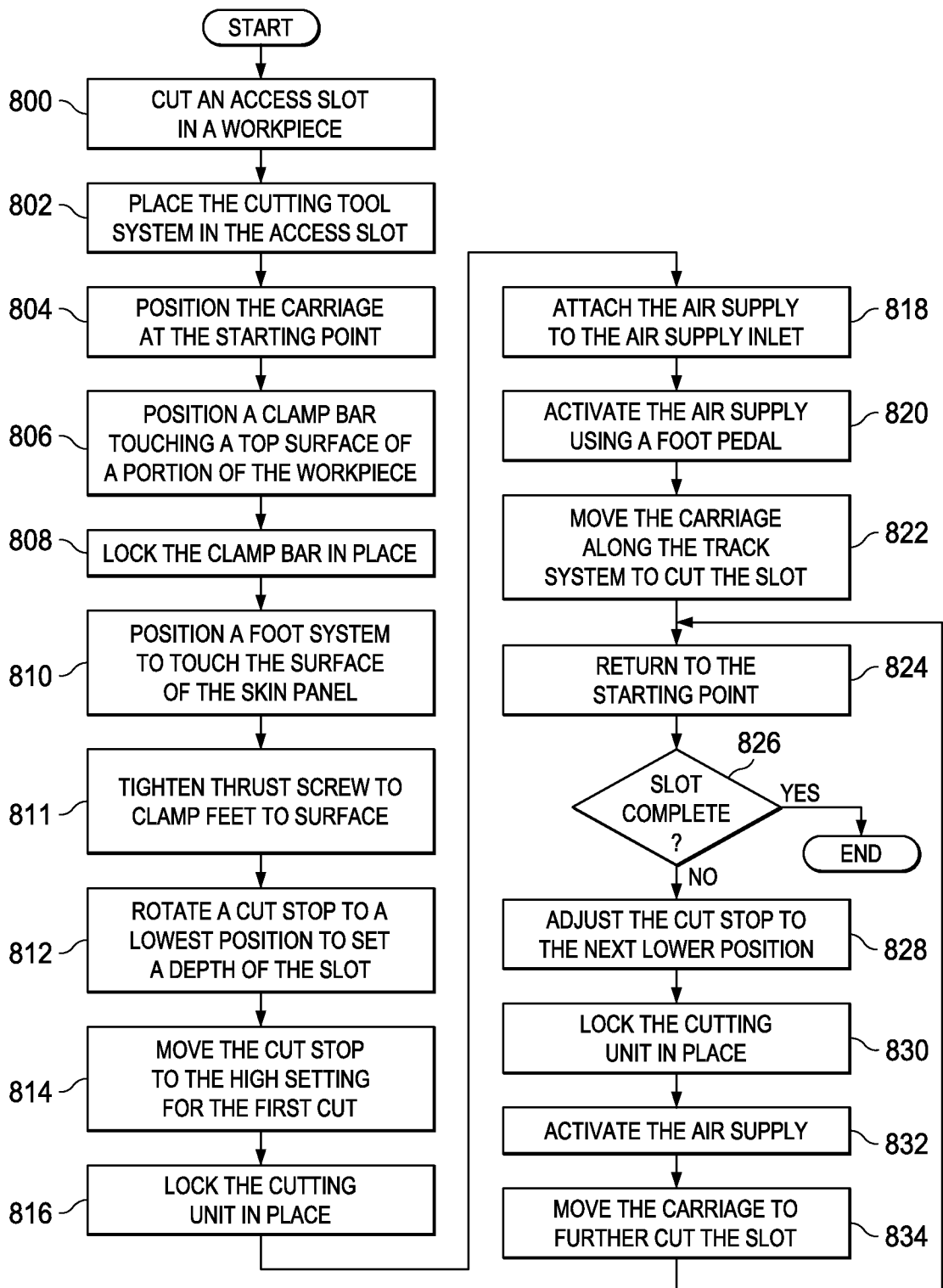


FIG. 6



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FIG. 8



INTERNATIONAL SEARCH REPORT

International application No
PCT/US2009/048903

A. CLASSIFICATION OF SUBJECT MATTER
INV. B23Q9/00

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)
B23Q

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

EPO-Internal

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	EP 1 918 067 A (TORRES INGENIERIA DE PROCESOS [ES]) 7 May 2008 (2008-05-07)	1,2,4-9
Y	paragraphs [0008], [0009], [0013], [0020]	10,13
X	WO 2006/012268 A (TRI TOOL INC [US]) 2 February 2006 (2006-02-02)	1,2,4-6, 8-12,14, 15
Y		13
X	US 3 722 497 A (HIESTAND J ET AL) 27 March 1973 (1973-03-27) abstract; figure 1	10,12, 14,15
Y	US 5 123 790 A (KING FREDDIE G [US]) 23 June 1992 (1992-06-23) claim 1; figures 1,2	10



Further documents are listed in the continuation of Box C.



See patent family annex.

* Special categories of cited documents :

A document defining the general state of the art which is not considered to be of particular relevance

E earlier document but published on or after the international filing date

L document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)

O document referring to an oral disclosure, use, exhibition or other means

P document published prior to the international filing date but later than the priority date claimed

T later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

X document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone

Y document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art.

* & * document member of the same patent family

Date of the actual completion of the international search

30 September 2009

Date of mailing of the international search report

27/01/2010

Name and mailing address of the ISA/

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Authorized officer

Lasa Goñi, Andoni

INTERNATIONAL SEARCH REPORT

International application No.
PCT/US2009/048903

Box No. II Observations where certain claims were found unsearchable (Continuation of item 2 of first sheet)

This international search report has not been established in respect of certain claims under Article 17(2)(a) for the following reasons:

1. ☐ Claims Nos.:
because they relate to subject matter not required to be searched by this Authority, namely:
2. ☐ Claims Nos.:
because they relate to parts of the international application that do not comply with the prescribed requirements to such an extent that no meaningful international search can be carried out, specifically:
3. ☐ Claims Nos.:
because they are dependent claims and are not drafted in accordance with the second and third sentences of Rule 6.4(a).

Box No. III Observations where unity of invention is lacking (Continuation of item 3 of first sheet)

This International Searching Authority found multiple inventions in this international application, as follows:

see additional sheet

1. ☐ As all required additional search fees were timely paid by the applicant, this international search report covers all searchable claims.
2. ☐ As all searchable claims could be searched without effort justifying an additional fees, this Authority did not invite payment of additional fees.
3. ☐ As only some of the required additional search fees were timely paid by the applicant, this international search report covers only those claims for which fees were paid, specifically claims Nos.:
4. ☒ No required additional search fees were timely paid by the applicant. Consequently, this international search report is restricted to the invention first mentioned in the claims; it is covered by claims Nos.:

see additional sheet(s)

Remark on Protest

- ☐ The additional search fees were accompanied by the applicant's protest and, where applicable, the payment of a protest fee.
- ☐ The additional search fees were accompanied by the applicant's protest but the applicable protest fee was not paid within the time limit specified in the invitation.
- ☐ No protest accompanied the payment of additional search fees.

FURTHER INFORMATION CONTINUED FROM PCT/ISA/ 210

This International Searching Authority found multiple (groups of) inventions in this international application, as follows:

1. claims: 1-2,4-15

Apparatus or method according to claim 1 or 10 respectively,
with a carriage configured to move along the set of tracks.
Problem solved: provide alternative means for guiding the
tool along an axis parallel to the surface of the workpiece.

2. claim: 3

Apparatus according to claim 1, with a foot-operated power
controller for supplying power to the cutting tool.
Problem solved: provide alternative means for controlling
the power of the tool.

INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No

PCT/US2009/048903

Patent document cited in search report		Publication date		Patent family member(s)	Publication date
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			WO	2007010066 A2	25-01-2007
WO 2006012268	A	02-02-2006	JP	2008504137 T	14-02-2008
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US 5123790	A	23-06-1992	NONE		