

(51) International Patent Classification:

E21B 31/00 (2006.01) *E21B 7/24* (2006.01)
E21B 1/28 (2006.01) *E21B 17/20* (2006.01)
E21B 4/06 (2006.01) *E21B 28/00* (2006.01)
E21B 4/14 (2006.01)

(21) International Application Number:

PCT/US2017/044956

(22) International Filing Date:

01 August 2017 (01.08.2017)

(25) Filing Language:

English

(26) Publication Language:

English

(30) Priority Data:

62/369,878 02 August 2016 (02.08.2016) US

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(81) Designated States (unless otherwise indicated, for every
kind of national protection available): AE, AG, AL, AM,
AO, AT, AU, AZ, BA, BB, BG, BH, BN, BR, BW, BY, BZ,
CA, CH, CL, CN, CO, CR, CU, CZ, DE, DJ, DK, DM, DO,
DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, GT, HN,
HR, HU, ID, IL, IN, IR, IS, JO, JP, KE, KG, KH, KN, KP,
KR, KW, KZ, LA, LC, LK, LR, LS, LU, LY, MA, MD, ME,
MG, MK, MN, MW, MX, MY, MZ, NA, NG, NI, NO, NZ,
OM, PA, PE, PG, PH, PL, PT, QA, RO, RS, RU, RW, SA,
SC, SD, SE, SG, SK, SL, SM, ST, SV, SY, TH, TJ, TM, TN,
TR, TT, TZ, UA, UG, US, UZ, VC, VN, ZA, ZM, ZW.

(84) Designated States (unless otherwise indicated, for every
kind of regional protection available): ARIPO (BW, GH,
GM, KE, LR, LS, MW, MZ, NA, RW, SD, SL, ST, SZ, TZ,
UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, RU, TJ,
TM), European (AL, AT, BE, BG, CH, CY, CZ, DE, DK,
EE, ES, FI, FR, GB, GR, HR, HU, IE, IS, IT, LT, LU, LV,
MC, MK, MT, NL, NO, PL, PT, RO, RS, SE, SI, SK, SM,
TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW,
KM, ML, MR, NE, SN, TD, TG).

Published:

— with international search report (Art. 21(3))

(54) Title: DRILLING TOOL WITH NON-SYNCHRONOUS OSCILLATORS AND METHOD OF USING SAME

(57) Abstract: Apparatus and method for drilling a wellbore using non-synchronous oscillators. An apparatus for drilling a wellbore includes a tubing string and a bottom hole assembly coupled to the tubing string. The bottom hole assembly includes a first oscillator and a second oscillator. The first oscillator is configured to restrict fluid flow and induce pressure pulses in the tubing string at a first frequency. The second oscillator is configured to restrict fluid flow and induce pressure pulses in the tubing string at a second frequency. The first frequency is different from the second frequency.

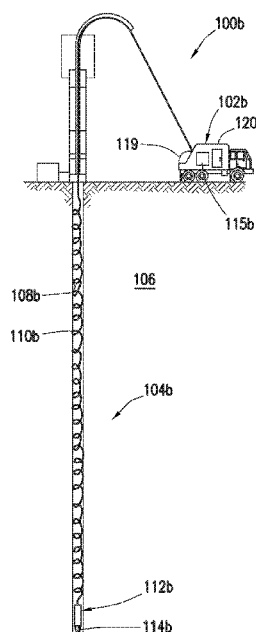


FIG. 1B

DRILLING TOOL WITH NON-SYNCHRONOUS OSCILLATORS AND METHOD OF USING SAME

CROSS-REFERENCE TO RELATED APPLICATIONS

[0001] The present application claims benefit of U.S. provisional patent application Serial No. 62/369,878, filed August 2, 2016, and entitled “Drilling Tool With Non-Synchronous Oscillators and Method of Using Same,” which is hereby incorporated herein by reference in its entirety.

BACKGROUND

[0002] The present disclosure relates generally to techniques for performing wellsite operations. More specifically, the present disclosure relates to operation of wellsite equipment, such as drilling devices.

[0003] Oilfield operations may be performed to locate and gather valuable subsurface fluids. Oil rigs are positioned at wellsites, and subsurface equipment, such as a drilling tool, is advanced into the ground to reach subsurface reservoirs. The drilling tool includes a conveyance, a bottomhole assembly (“BHA”), and a drill bit. The drill bit is mounted on the subsurface end of the BHA, and advanced into the earth by the conveyance (e.g., drill string or coiled tubing) to form a wellbore. The oil rig is provided with various surface equipment, such as a top drive, a Kelly and a rotating table, used to threadedly connect the stands of pipe together to extend the drill string and advance the drill bit. Downhole drilling tools may be deployed into a wellbore via coiled tubing to drill or clean the wellbore.

[0004] The BHA of the drilling tool may be provided with various drilling components to perform various subsurface operations, such as providing power to the drill bit to drill the wellbore and performing subsurface measurements. Examples of drilling components are provided in US Patent/Application Nos. 13/954,793, 2009/0223676, 2011/0031020, 2012/0186878, 7419018, 6508317, 6431294, 6279670, and 4428443, and PCT Application NO. WO2014/089457, the entire contents of which are hereby incorporated by reference herein.

[0005] In some cases, downhole tools, such as the drilling tools, may have difficulty passing through the wellbore and/or may become stuck in the wellbore. Techniques are needed to facilitate movement of the downhole tools.

SUMMARY

[0006] Apparatus and methods for drilling a wellbore using non-synchronous oscillators are disclosed herein. In one embodiment, an apparatus for drilling a wellbore includes a tubing string and a bottom hole assembly coupled to the tubing string. The bottom hole assembly includes a first oscillator and a second oscillator. The first oscillator is configured to restrict fluid flow and induce pressure pulses in the tubing string at a first frequency. The second oscillator is configured to restrict fluid flow and induce pressure pulses in the tubing string at a second frequency. The first frequency is different from the second frequency.

[0007] In another embodiment, a method for drilling a wellbore includes arranging a first oscillator and a second oscillator in a bottom hole assembly. The method also includes positioning the bottom hole assembly in the wellbore via a tubing string coupled to the bottom hole assembly. The method further includes inducing pressure pulses of a first frequency in the tubing string by operating the first oscillator. The method yet further includes inducing pressure pulses of a second frequency in the tubing string by operating the second oscillator. The first frequency is different from the second frequency.

[0008] In a further embodiment, an oscillation assembly for use in drilling a wellbore includes a first oscillator, a second oscillator, and a rotor. The first oscillator is configured to restrict fluid flow in a tubing string at a first frequency. The first oscillator includes a first valve configured to open and close to restrict the fluid flow in the tubing string at the first frequency. The second oscillator is configured to restrict fluid flow in the tubing string at a second frequency. The second oscillator includes a second valve configured to open and close to restrict the fluid flow in the tubing string at the second frequency. The rotor is coupled to the first valve and the second valve to induce opening and closing of the first valve at the first frequency and the second valve at the second frequency. The first frequency is different from the second frequency.

BRIEF DESCRIPTION OF THE DRAWINGS

[0009] A more particular description of the disclosure, briefly summarized above, may be had by reference to the embodiments thereof that are illustrated in the appended drawings. It is to be noted, however, that the appended drawings illustrate examples and are, therefore, not to be considered limiting of its scope. The figures are not necessarily to scale and certain features, and certain views of the figures may be shown exaggerated in scale or in schematic in the interest of clarity and conciseness.

[0010] FIGS. 1A-1D are schematic diagrams of wellsites with various downhole tools deployed into a wellbore, the downhole tools comprising non-synchronous oscillation assemblies.

[0011] FIGS. 2A-2B are schematic diagrams of the downhole drilling tool of Figure 1A and the downhole coiled tubing tool of Figure 1B (or 1C or 1D), respectively.

[0012] FIGS. 3A-3B are longitudinal, cross-sectional views of alternate versions of the downhole drilling tool in a tandem and dual configuration, respectively.

[0013] FIGS. 4A-4B are longitudinal, cross-sectional views of alternate versions of the downhole coiled tubing tool in a tandem and dual configuration, respectively.

[0014] FIGS. 5A-8D are various horizontal cross-sectional views of various valves usable with the oscillation assemblies.

[0015] FIGS. 9A-9B are schematic diagrams of the oscillation assembly comprising dual oscillators having synchronous and non-synchronous frequencies.

[0016] FIG. 10A shows a burst generated using a single valve.

[0017] FIG. 10B shows a burst generated using two valves operating synchronously.

[0018] FIG. 10C shows a burst generated using two valves operating non-synchronously.

[0019] FIG. 11 is a schematic diagram depicting an effect of different frequencies on sinusoidal and helical buckling in the downhole tool.

[0020] FIG. 12 is a flow chart of a method of passing a downhole tool through a wellbore.

DETAILED DESCRIPTION

[0021] The description that follows includes exemplary apparatus, methods, techniques, and/or instruction sequences that embody techniques of the present subject matter. However, it is understood that the described embodiments may be practiced without these specific details.

[0022] A downhole tool is provided with an oscillation assembly to induce movement in the tool. The oscillation assembly includes one or more oscillators including drive assemblies to activate valves to vary flow through the tool. The valves are operated to generate synchronous and/or non-synchronous frequencies to generate pressure pulses that cause movement, such as extension, retraction, and/or oscillations, in the downhole tool.

[0023] Oscillations as used herein refers to movement, such as vibration, reciprocation, and/or other repetitive movement generated about the downhole tool in a direction along an axis of the tool which may be used to apply compressive and tensile forces to the downhole tool. Synchronous refers to the simultaneous movement of the oscillators (e.g., at the same frequencies). Non-synchronous refers to the irregular (non-simultaneous) movement of the oscillators (e.g., at different frequencies). Non-synchronous oscillation may be generated such that the frequency of the pressure pulses and their harmonics move in and out of phase, move into and/or out of sequence, and/or sweep through a frequency range.

[0024] Oscillation may be used to facilitate movement of the downhole tool (e.g., the drill string, BHA, bit, and/or other portions of the work string) about the wellbore, to reduce friction along the downhole tool, to facilitate drilling, to prevent buckling of conveyances (e.g., drill string, coiled tubing, etc.), to reduce friction, to facilitate fishing, and/or to advance further into the wellbore.

[0025] The oscillations may be manipulated to provide frequencies (and/or multiples of frequencies) tailored to individually and/or separately provide frequencies to generated movement intended to address downhole issues, such as buckling (e.g., sinusoidal and/or helical collapse of the conveyance) and/or sticking (e.g., attaching to mud and/or wellbore, and/or stuck in wellbore pockets and/or deviations).

[0026] Figures 1A-1D depict land-based wellsites 100a-b. Figure 1A shows the wellsite 100a during drilling with a downhole drilling tool 104a. Figures 1B – 1D

show the wellsite 100b during drilling with a downhole coiled tubing ("CT") tool 104b. While a land-based wellsite is depicted, the wellsite may be offshore. Also while linear and curved wellbores are shown at the wellsite, a variety of wellbore configurations may be present.

[0027] The wellsite 100a of Figure 1A has a drilling rig 102a with the downhole drilling tool 104a advanced into a subterranean formation 106 to form a wellbore 108a. As shown, the wellbore 108a is curved, but may be any shape. Geometry of the wellbore may define curves, deviations, variations in shape, and/or obstructions that may interfere with the passage of the downhole tool.

[0028] The downhole drilling tool 104a includes a drill string (conveyance) 110a, a BHA 112a, and a drill bit 114a at a downhole end thereof. The wellsite 100a also has a mud pit 115a and a pump 118a for pumping mud through the drill string 110a and the BHA 112a. The mud is pumped out the drill bit 114a and back to the surface in an annulus between the downhole drilling tool 104a and a wall of the wellbore 108a.

[0029] The BHA 112a may include various drilling components, such as motors, measurement while drilling ("MWD"), logging while drilling ("LWD"), telemetry, and other drilling tools, to perform various subsurface operations. The BHA 112a also includes a non-synchronous oscillation (and/or vibration) assembly 116a for oscillating the downhole drilling tool 104a as is described further herein.

[0030] The wellsites 100b of Figures 1B – 1D each show a CT unit 102b positioned above a wellbore 108b and a CT reel 119 carried by a truck 120. As shown, the wellbore 108b is vertical, but may be any shape. The downhole CT tool 104b is deployed into the wellbore 108b via a CT 110b. During deployment, the CT 110b may form a helical coil as shown in Figure 1B or a sinusoidal coil as shown in Figure 1C. In at least some cases, the downhole CT tool 104b is pushed through the wellbore 108b. The downhole CT tool 104b may lack rigidity resulting in sinusoidal and/or helical buckling as shown.

[0031] The CT tool 104b includes the CT (conveyance) 110b, a BHA 112b, and a drill bit 114b. The truck 120 has a fluid source 115b with a pump for pumping fluid through the CT 110b and the BHA 112b. The BHA 112b may include various components, for performing measurement, data storage, and/or other functions. Such components may include, for example, well control devices, such as check valves or flapper vales, emergency safety joints, disconnects, jars, and/or other

components used to perform various CT operations. The BHA 112b also includes a non-synchronous oscillation assembly 116b for oscillating the downhole CT tool 104b as is described further herein.

[0032] Figures 2A and 2B show portions of the downhole tools 104a,b of Figures 1A and 1B, respectively. Figure 2A depicts an example configurations of the BHA 112a of Figures 1A including the non-synchronous oscillation assembly 116a. Figure 2B depicts an example configuration of the BHA 112b of Figure 1B including the non-synchronous oscillation assembly 116b.

[0033] The non-synchronous oscillation assembly 116a includes a pair of oscillators 221 positioned in the BHA 112a. The oscillators 221 may include spring-loaded members capable of generating oscillating movement that may be used to impact the drill bit 114a against the formation during drilling and/or transferring weight to the bit by introducing an axial oscillating motion to keep the drillstring moving. Example oscillators that may be used are disclosed in US Patent/Application Nos. 2012/0186878, 6508317, 6431294, previously incorporated by reference herein.

[0034] The BHA 112a of Figure 2A as shown may also include other motion devices, such as a shock tool 222 and/or other drill string extender to generate movement of the drill string 110a. The shock tool 222 may be connected to the drill string 110a to absorb shocks to the downhole tool 104a. As shown, the shock tool 222 is a spring-loaded telescoping device that extends and retracts to absorb shocks to the downhole tool 104a. The shock tool 222 may also be used to isolate the drill string 110a from axial deflections while permitting vertical movement of the downhole tool 104a during operation. Examples of shock tools 222 that may be used include the BLACK MAX MECHANICAL SHOCK TOOL™ or a GRIFFITH™ shock tool (e.g., 6 ¾" (17.14 cm) with a pump open area of 17.7 in² (43.55 cm²)) commercially available at www.nov.com.

[0035] The shock tool 222 and/or the oscillators 221 (alone or in combination) may generate motion in the downhole drilling tool 104a, for example, to facilitate movement of the downhole drilling tool 104a through the wellbore, to facilitate impact of the drill bit during drilling, and/or to prevent sticking of the downhole tool 104a therein.

[0036] As shown in Figure 2B, the BHA 112b may include the non-synchronous oscillation assembly 116b with the pair of oscillators 221 coupled to the CT 110b. In

this version, no shock tool is provided, but may optionally be provided. In this configuration, the oscillators 221 (alone or in combination) may generate oscillating motion in the downhole CT tool 104b, for example, to facilitate movement of the downhole tool 104b through the wellbore, to extend/retract the CT 110b, and/or to prevent sticking of the downhole tool 104b therein. Such motion may be used, for example, to address the helical and/or sinusoidal coiling of the downhole CT tool 110b which may occur as shown in the examples of Figures 1B – 1D. In particular, the oscillations may be used to selectively restrict flow such that pressure P is increased in the CT 110b which may be used to assist in straightening the downhole CT tool 110b and/or removing helical and/or sinusoidal coils along the downhole CT tool 110b.

[0037] Figures 3A-4B show various versions of oscillation assemblies. Figures 3A - 3B show detailed views of an example BHA 312a, b including oscillation assemblies 316a,b usable in the downhole tool 104a (Figure 1A) in a tandem and a dual configuration, respectively. Figures 4A - 4B show detailed views of an example BHA 412a,b including oscillation assemblies 416a,b usable in the downhole tool 104b (Figures 1B-1D) in a tandem and a dual configuration, respectively.

[0038] In the tandem example of Figure 3A, the oscillation assembly 316a includes a stacked pair of oscillators 321a. Each oscillator 321a includes a top sub 326a, a drive section 328, valves 330a,b, and a bottom sub 332a. The top sub 326a is connectable to the drill string and/or other components of the BHA 312a. The bottom sub 332a may connect to the top sub 326a of an adjacent oscillator 321a or other component in the BHA 312a. The connections as shown are pin and box type connections connectable to matable drill collars or other devices, but can be any connection.

[0039] The drive section 328 may include a motor, turbine or other member capable of driving the valve 330a. In the example shown, the drive section 328 is a positive displacement (e.g., Moineau) motor including a rotor 329 and stator 331 rotationally driven by fluid flow. The rotor is coupled to the valve 330a for rotationally driving the valve to vary flow therethrough.

[0040] The valves 330a,b are rotationally driven by the rotor 329 to selectively permit fluid to pass through the BHA 312a. The valves 330a,b may have ports that fully or partially open and close to control the passage of fluid. Examples of valves and/or rotor/motor driven valves are provided in US Patent/Application Nos.

2012/0186878, 6508317, 6431294, previously incorporated by reference herein. Examples of valves are also shown in Figures 5A-8D.

[0041] The valves 330a,b may be any valve capable of selectively passing fluid through the BHA 312a to generate various frequencies as is described further herein. In the example shown, the valves 330a,b are different valves capable of generating different fluid flow therethrough. Optionally, valves 330a,b may be the same valve operated at different flow rates or otherwise varied to generate the different frequencies therethrough. In an example, the valve 330a may be a rotary valve, such as the valve of Figures 5A-5D, and the valve 330b may be a drum valve, such as the valve of Figure 8A-8D (or vice versa).

[0042] As also shown by Figure 3A, various optional features may be provided. For example, the pair of oscillators 321a,b are joined together by a spacer 333. The uphole end of the upper oscillator 316a is connected to a shock tool 222. The uphole end of the assembly 316a may be coupled directly to the drill string 110a or via components, such as the shock tool 222.

[0043] In the dual example of Figure 3B, the oscillation assembly 316b includes integrated oscillator 321b with top and bottom subs 326b, 332b. This example is similar to Figure 3A, except that only a single drive section is provided with both valves 330a,b driven by the rotor 329. In this configuration, valves 330a,b are different valves with different ports defining different frequencies when rotated by the same rotor 329.

[0044] Figures 4A and 4B are similar to Figures 3A and 3B, except these versions show the oscillation assemblies 416a,b connected to the CT 110b. In the tandem configuration of the BHA 412a of Figure 4A, the upper drive assembly 416a is connected to the CT 110b at an uphole end and to another drive assembly 416a at its lower end. No spacer is needed, but optionally may be provided. As shown by this example, the valves 330a,b may be the same in both oscillation assemblies 416a.

[0045] In the integrated example of Figure 4B, the drive section 328 is uphole of both valves 330b. The valves 330a,b may be connected to the rotor 329 and driven thereby. The valves 330a,b may optionally have one or more spacers 333 as shown. The valves 330a,b are depicted as different valves that are rotatable by rotor 329 to generate different frequencies through the BHA 412b.

[0046] While the embodiments of Figures 3A-4B show example configurations of the oscillators, it will be appreciated that the oscillators and/or assemblies may have various configurations. For example, while valves are shown as the mechanism for varying flow through the BHA, other devices capable of varying flow may be used. Additionally, various drivers may be used to drive the valves at various speeds to provide a desired flow rate through the valve. One or more drivers may drive one or more of the valves. Each valve may have its own driver, or use the same driver. The valve may be selected, for example, based on the drive mechanism configuration (e.g., 1/2 lobe power section versus a multi-lobe power section). Various numbers of valves, oscillators, and/or oscillation assemblies may be provided.

[0047] The drivers and/or valves (or other devices) may be used to define the frequencies of pressure pulses through the BHA. The drivers and/or valves may be configured to provide various frequencies and/or amplitudes as is described further therein. Desired frequencies may be selected to achieve desired operation, such as based on the type of tool, geometry of the wellbore, flow rate, and/or valving. Flow into the BHA may be controlled from the surface, for example, by varying mud pumped from the mud pit (Figure 1).

[0048] Figures 5A-8D depict various example configurations of valves 530-830 usable in as the valves 330a,b of Figures 3A-4B, including neo, legacy, modified neo, and drum valves, respectively. Each of the valves 530-830 have variable openings 540-840 therethrough for controlling the amount of flow through the drive section of the oscillator to achieve the desired flow through the BHA and generate desired oscillations. As shown by these examples, various configurations of valves may be used for varying the flow area through the BHA and thereby defining the pressure pulses and oscillations generated thereby.

[0049] Each of the valves has a housing 536-836 with the passage 540-840 therethrough, and a cover 538-838 rotatable about the housing 536-838 to selectively cover a portion of the passage 540-840, thereby varying the flow area defined therethrough. The cover 538-838 may be rotatable to selectively block at least a portion of the opening 540-840 to vary the flow. This variation may create pressure pulses through the BHA.

[0050] The valves 530-830 each have openings 540-840 that are partially covered by the rotation of the cover 538-838 to cover a portion of the openings 540-840 as it

is oscillated therein (e.g., by rotor 329 of Figures 3A-4B). The covers 538-838 have openings of various shapes that rotate to selectively align and misalign with openings in the housings 536-836 to vary flow area therethrough, thereby creating pressure pulses. As shown, the openings in the housing and/or the covers may be varied to adjust the amount of flow and the frequency of pulses generated thereby. Openings in the cover and/or housings may be the same or different to provide the desired operation.

[0051] The valves may be operated to selectively define the oscillations generated by the oscillation assemblies. The valves may be operated, for example, to provide a desired frequency of oscillation. Various factors, such as type of tool, geometry of the wellbore, flow rate, and/or valving, may apply in determining desired frequencies. The valves may vary flow through the BHA such that oscillations generated by the oscillators of the BHA are different as is described further herein.

[0052] While Figures 5A-8D show specific configurations of two-piece valves with varied, but continuous flow through a passage, the valve may have various configurations. For example, the valve may have drums, plates, or other members movable to define one or more orifices for controlling flow therethrough.

[0053] Figures 9A-9B are schematic diagrams depicting a BHA 912 of a downhole tool 904, and corresponding frequencies generated by the oscillation assemblies 916 therein, which may be similar to the downhole tools, BHAs, and/or oscillators provided herein. The downhole tool 904 includes two valves 930a,b, with each generating a frequency F_1 , F_2 , respectively. The valves 930a,b may vary between the synchronous and non-synchronous modes to achieve the desired operation to facilitate movement of the downhole tool through the wellbore. The valves may be the same or different, and selected and/or operated to vary flow rate through the oscillators to generate the desired frequencies.

[0054] As shown, the valves 930a,b may be operated in unison as shown in Figure 9A to generate equal (synchronous) frequencies $F_1=F_2$ as depicted by the graphs. As shown in Figure 9B, the valves 930a,b may be operated irregularly to generate unequal (non-synchronous) frequencies $F_1<F_2$ as depicted by the graphs. In this version, the frequency F_2 of the downhole valve 930b has been varied to be different from that of the uphole valve 930a. This may be accomplished, for example, by changing the operation of the valve and/or driver of one or both of the oscillation assembly 916.

[0055] As further shown in Figure 9B, non-synchronous operation of the valves 930a,b may lead to a combined, irregular frequency $F1+F2$. The frequencies $F1$, $F2$ interact to generate oscillations that have higher and lower periods with varying amounts of overlap. The dual frequencies may combine to cause harmonics of the frequencies to move in and out of phase, to move into and/or out of sequence, and/or to sweep through a frequency range. Such varying frequencies may be used to yield resonant excitation as the downhole tool 904 moves through the wellbore.

[0056] Figures 10A-10C are graphs 1000a-c depicting examples of bursts generated by various operation modes of the oscillation assembly. The graphs 1000a-c plot magnitude M (y-axis) versus time t (x-axis) for each mode including synchronous, out of phase, and non-synchronous, respectively. Figure 10A shows a baseline case depicting the burst acceleration when the BHA is operated using a single valve. As shown by this graph, the burst generated by the oscillation assembly has a large magnitude (about ± 6 to about ± 8) over most of the duration.

[0057] Figure 10B shows the burst acceleration when the BHA is in a synchronous mode with two valves operating in unison (see, e.g., Figures 9A). As shown by this graph, the burst generated by the oscillation assembly has an increasing magnitude over most of the duration. This graph yields similar burst magnitude (about ± 7 to about negative ± 8) to that of Figure 10A.

[0058] Figure 10C shows the burst acceleration when the BHA in a non-synchronous mode with two valves operates to generate different frequencies (see, e.g., Figure 9B). As shown by this graph, the burst generated by the oscillation assembly has a stepped magnitude that is low for a portion of the duration and then increases (about ± 15 to about negative ± 17). This graph indicates a higher performance generated by the increased magnitude of burst generated by the non-synchronous mode.

[0059] Figure 11 is a schematic diagram depicting the effect of nonsynchronous frequencies on a downhole tool 1104 having sinusoidal coiling 1148a and helical coiling 1148b (see, e.g., Figure 1D). The downhole tool 1104 includes a BHA 1112 and a tubing string 1114. The tubing string 1114 may include coiled tubing or interconnected drill pipes. The BHA 1112 includes an oscillation assembly 1116 having two valves 1130a and 1130b. The two valves 1130a and 1130b can be operated at different frequencies to produce pressure pulses in the tubing string at the different frequencies. For example, the valve 1130a may be operated at a first

frequency and the valve 1130b may be operated at a second frequency that is an integer multiple of the first frequency. In one embodiment, the second frequency may be three times the first frequency (e.g., the first frequency the first frequency may be 7 Hertz (Hz) and the second frequency may be 21 Hz). In another embodiment, the second frequency may be five times the first frequency (e.g., the first frequency the first frequency may be 7 Hertz (Hz) and the second frequency may be 35 Hz). In various embodiments, the second frequency may be any multiple of the first frequency.

[0060] Operation of the valves 1130a and 1130b produces pressure pulses in the tubing string 1114. The pressure pulses correspond in frequency to the frequency of operation of the valves 1130a and 1130b. That is, operation of the valve 1130a at a first frequency produces pressure pulses at the first frequency in the tubing string 1114, and operation of the valve 1130b at a second frequency produces pressure pulses at the second frequency in the tubing string 1114. In Figure 11, the valves 1130a and 1130b are operated such the second frequency is three times the first frequency.

[0061] The graphs 1150a and 1150b show pressure pulses as pressure P (y-axis) versus time t (x-axis) for the valves 1130a and 1130b. In Figure 11, the valve 1130a generates pressure pulses shown in graph 1150a, which may be directed to correction of the sinusoidal buckling 1148a of the tubing string 1114, as indicated by the arrow from 1148a to graph 1150a. Thus, the frequency of the pressure pulses generated by the valve 1130a may be selected to correct or mitigate sinusoidal buckling of the tubing string 1114. Similarly, the valve 1130b generates pressure pulses shown in graph 1150b, which may be directed to correction of the helical coiling 1148b of the tubing string 1114, as indicated by the arrow from 1148b to graph 1150b. Accordingly, the frequency of the pressure pulses generated by the valve 1130b may be selected to correct or mitigate helical buckling of the tubing string 1114.

[0062] Graph 1150c shows the pressure pulses generated by the combination or summation of the pressure pulses of graphs 1150a and 1150b, i.e., combination of the pressure pulses generated by operation of the valves 1130a and 1130b at different frequencies. The combined pressure pulses of graph 1150c include pulses 1152a produced by summation of the peaks of the pressure pulses of graphs 1150a and 1150b. That is, the peaks 1152a occur when peaks of the pressure pulses of

graphs 1150a and 1150b are coincident in time. The peaks 1152a are higher in amplitude than the peaks of the pressure pulses of graphs 1150a and 1150b. The combined pressure pulses of graph 1150c also include pulses 1152b produced at times when the peaks of the pressure pulses of graphs 1150a and 1150b are not time coincident. The pulses 1152a, which occur at the frequency of the pressure pulses in graph 1150a, may be effective for correcting or mitigating sinusoidal buckling of the tubing string 1114, as indicated by an arrow extending from the tubing string 1114 to one of the pressure pulses 1152a. The pulses 1152b, which occur at the frequency of the pressure pulses in graph 1150b, may be effective for correcting or mitigating helical buckling of the tubing string 1114, as indicated by an arrow extending from the tubing string 1114 to one of the pressure pulses 1152b.

[0063] Figure 12 is a flow chart depicting a method of passing a downhole tool through a wellbore penetrating a subterranean formation. The method involves 1250 - operatively connecting a plurality of oscillators to a BHA of the downhole tool. The oscillators comprise at least one driver (e.g., 321a,b of Figures 3A-4B) and a plurality of valves (e.g., 330a-830 of Figures 3A-8). The method also involves 1252 - deploying the downhole tool into the wellbore via a conveyance (e.g., drill string or CT), 1254 - oscillating the downhole tool by driving the valves with the driver; and 1256 - varying the oscillating by passing fluid through the valves to generate different frequencies.

[0064] The method may be performed in any order and repeated as desired.

[0065] It will be appreciated by those skilled in the art that the techniques disclosed herein can be implemented for automated/autonomous applications via software configured with algorithms to perform the desired functions. These aspects can be implemented by programming one or more suitable general-purpose computers having appropriate hardware. The programming may be accomplished through the use of one or more program storage devices readable by the processor(s) and encoding one or more programs of instructions executable by the computer for performing the operations described herein. The program storage device may take the form of, e.g., one or more floppy disks; a CD ROM or other optical disk; a read-only memory chip (ROM); and other forms of the kind well known in the art or subsequently developed. The program of instructions may be "object code," i.e., in binary form that is executable more-or-less directly by the computer; in "source code" that requires compilation or interpretation before execution; or in some

intermediate form such as partially compiled code. The precise forms of the program storage device and of the encoding of instructions are immaterial here. Aspects of the invention may also be configured to perform the described functions (via appropriate hardware/software) solely on site and/or remotely controlled via an extended communication (e.g., wireless, internet, satellite, etc.) network.

[0066] While the embodiments are described with reference to various implementations and exploitations, it will be understood that these embodiments are illustrative and that the scope of the inventive subject matter is not limited to them. Many variations, modifications, additions and improvements are possible. For example, various combinations of part or all of the techniques described herein may be performed.

[0067] Plural instances may be provided for components, operations or structures described herein as a single instance. In general, structures and functionality presented as separate components in the exemplary configurations may be implemented as a combined structure or component. Similarly, structures and functionality presented as a single component may be implemented as separate components. These and other variations, modifications, additions, and improvements may fall within the scope of the inventive subject matter.

[0068] Insofar as the description above and the accompanying drawings disclose any additional subject matter that is not within the scope of the claim(s) herein, the inventions are not dedicated to the public and the right to file one or more applications to claim such additional invention is reserved. Although a very narrow claim may be presented herein, it should be recognized the scope of this invention is much broader than presented by the claim(s). Broader claims may be submitted in an application that claims the benefit of priority from this application.

CLAIMS

What is claimed is:

1. Apparatus for drilling a wellbore, comprising:
a tubing string; and
a bottom hole assembly coupled to the tubing string, the bottom hole assembly comprising:
a first oscillator configured to restrict fluid flow and induce pressure pulses in the tubing string at a first frequency; and
a second oscillator configured to restrict fluid flow and induce pressure pulses in the tubing string at a second frequency;
wherein the first frequency is different from the second frequency.
2. The apparatus of claim 1, wherein the first frequency is an integer multiple of the second frequency.
3. The apparatus of claim 1, wherein the first frequency is three times the second frequency.
4. The apparatus of claim 1, wherein the first frequency is five times the second frequency.
5. The apparatus of claim 1, wherein the first oscillator is configured to restrict the fluid flow in the tubing string over a range of frequencies starting at an initial frequency and ending at a final frequency.
6. The apparatus of claim 1, wherein the tubing string comprises coiled tubing or a plurality of drill pipes.
7. The apparatus of claim 1, wherein the first frequency is selected induce pressure pulses in the tubing string to correct helical buckling of the tubing string and the second frequency is selected to induce pressure pulses in the tubing string to correct sinusoidal buckling of the tubing string.

8. The apparatus of claim 1, wherein the first oscillator comprises a first valve configured to open and close to restrict the fluid flow in the tubing string and the second oscillator comprises a second valve configured to open and close to restrict the fluid flow in the tubing string; wherein the bottom hole assembly comprises a rotor coupled to the first valve and the second valve to induce opening and closing of the first valve and the second valve.
9. A method for drilling a wellbore, comprising:
arranging a first oscillator and a second oscillator in a bottom hole assembly;
positioning the bottom hole assembly in the wellbore via a tubing string coupled to the bottom hole assembly;
inducing pressure pulses of a first frequency in the tubing string by operating the first oscillator;
inducing pressure pulses of a second frequency in the tubing string by operating the second oscillator;
wherein the first frequency is different from the second frequency.
10. The method of claim 9, wherein the first frequency is an integer multiple of the second frequency.
11. The method of claim 9, wherein the first frequency is a three times or five times the second frequency.
12. The method of claim 9, wherein the first oscillator is configured to restrict the fluid flow in the tubing string over a range of frequencies starting at an initial frequency and ending at a final frequency.
13. The method of claim 9, wherein the tubing string comprises coiled tubing or a plurality of drill pipes.
14. The method of claim 9, further comprising restricting fluid flow in the tubing string, by the first oscillator, over a range of frequencies starting at an initial frequency and ending at a final frequency.

15. The method of claim 9, further comprising:
selecting the first frequency to induce pressure pulses in the tubing string to correct helical buckling of the tubing string; and
selecting the second frequency to induce pressure pulses in the tubing string to correct sinusoidal buckling of the tubing string.
16. The method of claim 9, further comprising:
opening and closing a first valve of the first oscillator to restrict the fluid flow in the tubing string and
opening and closing a second valve in the second oscillator to restrict the fluid flow in the tubing string;
rotating a rotor coupled to the first valve and the second valve to induce opening and closing of the first valve and the second valve.
17. An oscillation assembly for use in drilling a wellbore, comprising:
a first oscillator configured to restrict fluid flow in a tubing string at a first frequency, the first oscillator comprising a first valve configured to open and close to restrict the fluid flow in the tubing string at the first frequency; and
a second oscillator configured to restrict fluid flow in the tubing string at a second frequency, the second oscillator comprising a second valve configured to open and close to restrict the fluid flow in the tubing string at the second frequency;
a rotor coupled to the first valve and the second valve to induce opening and closing of the first valve at the first frequency and the second valve at the second frequency;
wherein the first frequency is different from the second frequency.
18. The oscillation assembly of claim 17, wherein the first frequency is an integer multiple of the second frequency.
19. The oscillation assembly of claim 17, wherein the first three times or five times the second frequency.

20. The oscillation assembly of claim 17, wherein the first frequency is selected induce pressure pulses in the tubing string to correct helical buckling of the tubing string and the second frequency is selected to induce pressure pulses in the tubing string to correct sinusoidal buckling of the tubing string.

1/12

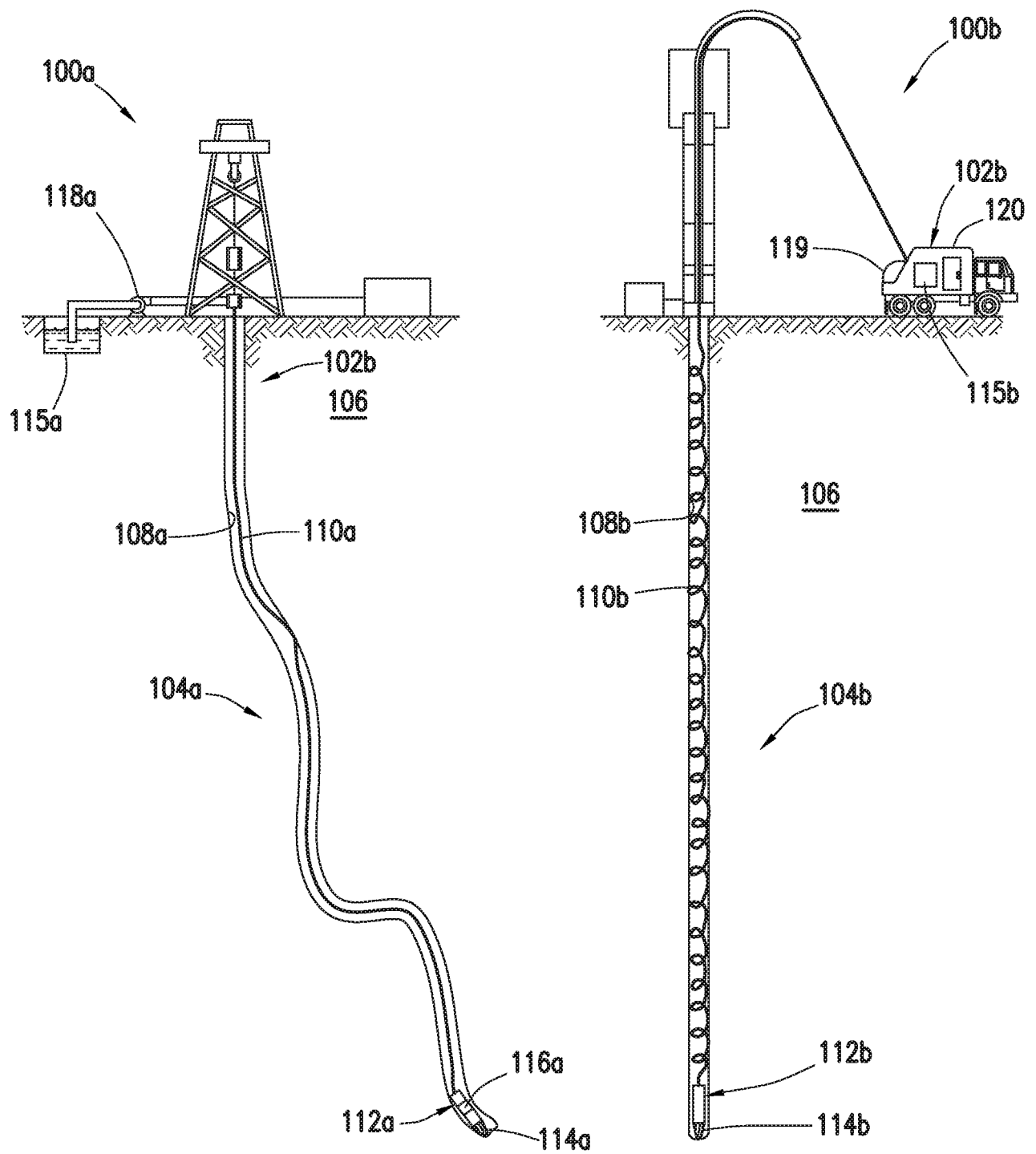


FIG. 1A

FIG. 1B

2/12

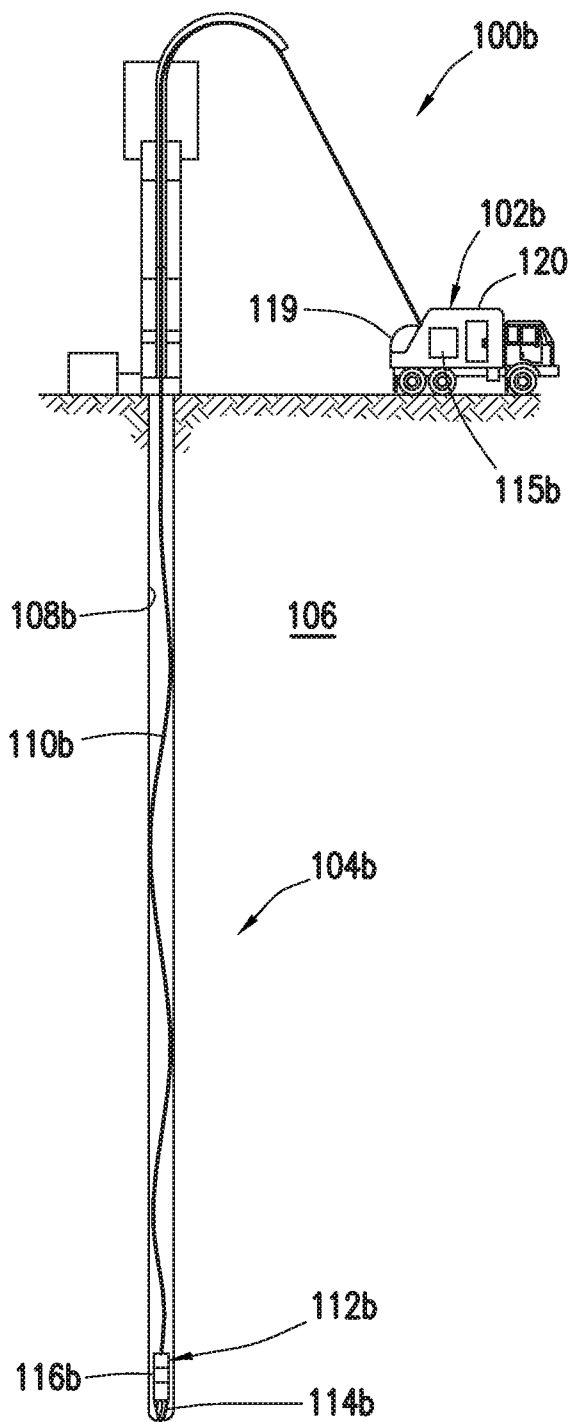


FIG. 1C

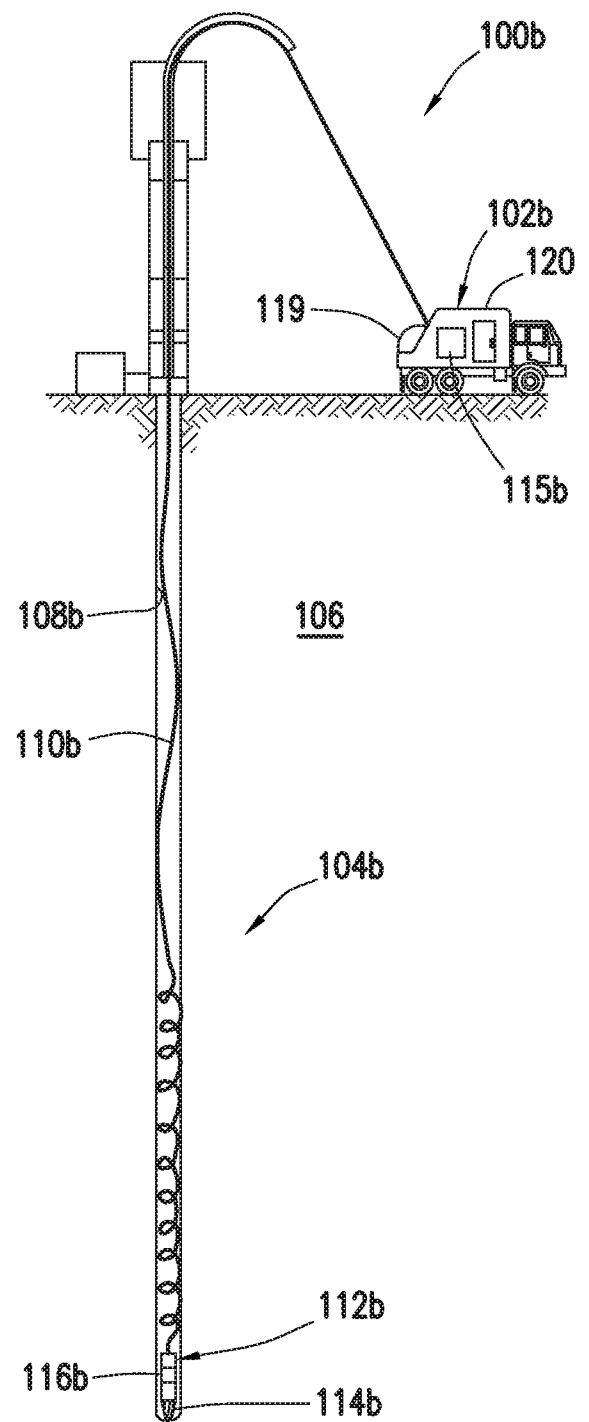


FIG. 1D

3/12

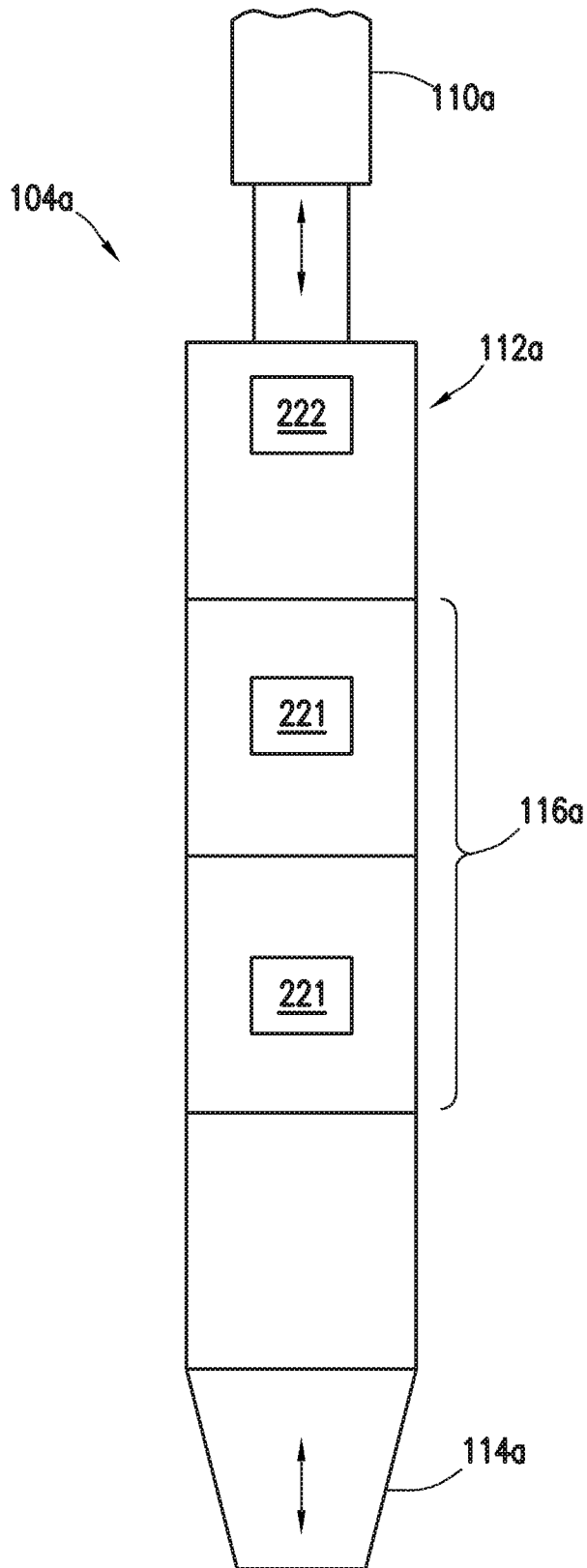


FIG. 2A

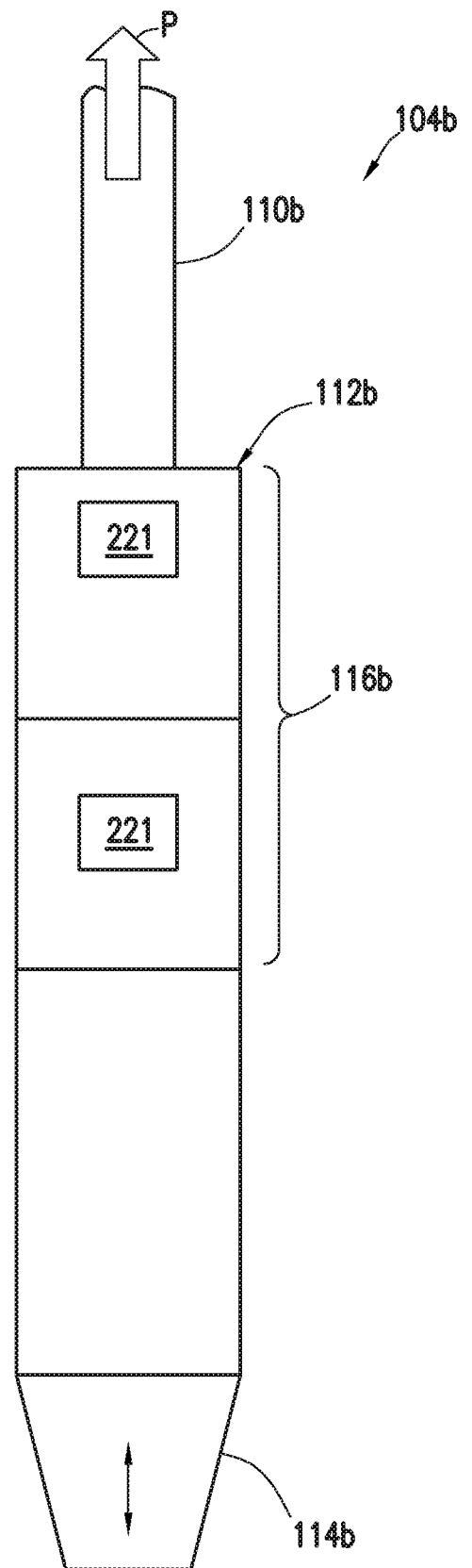
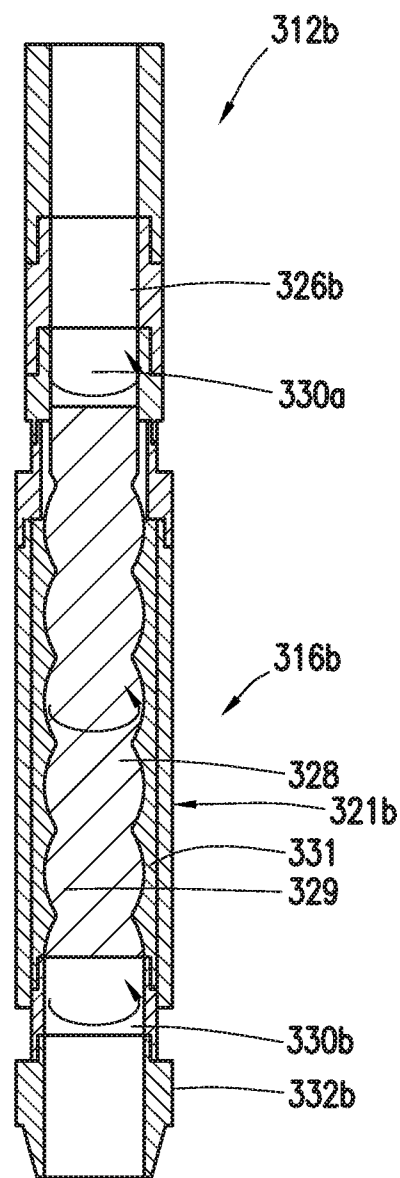
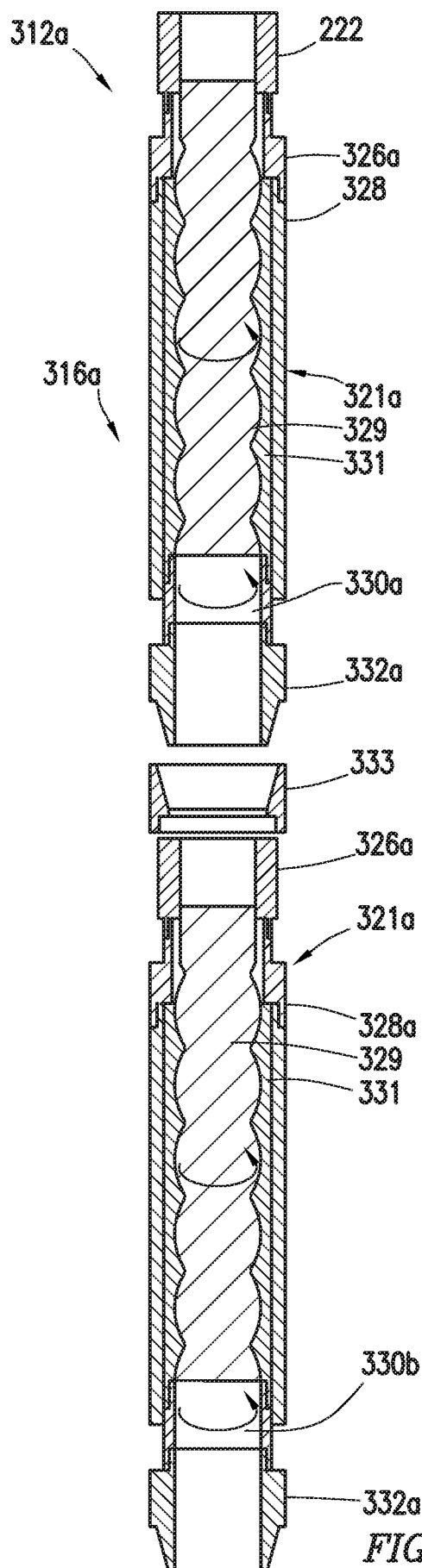
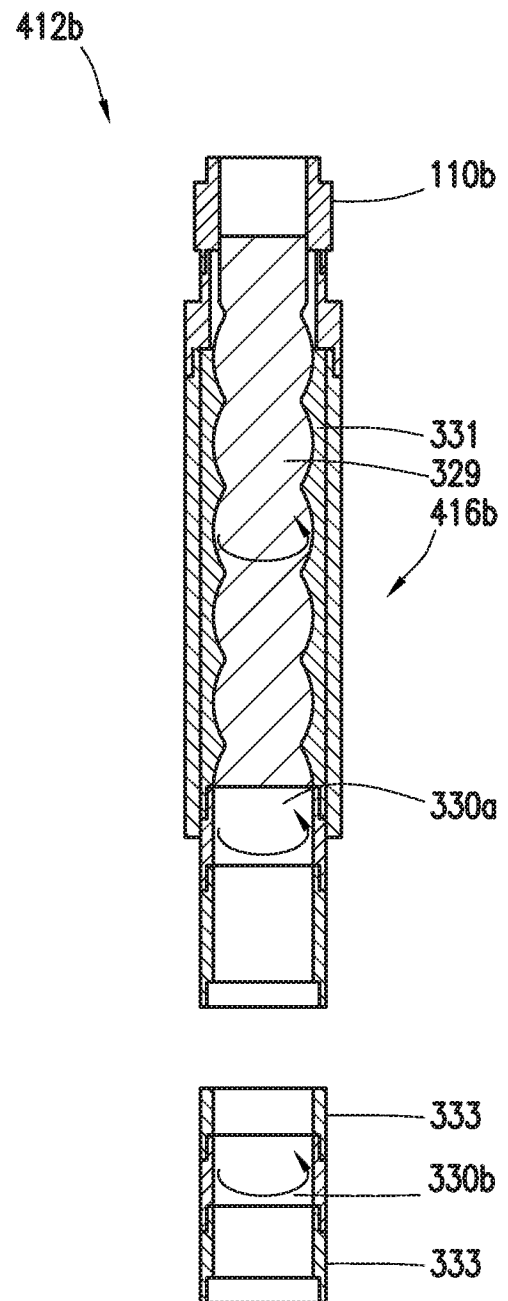
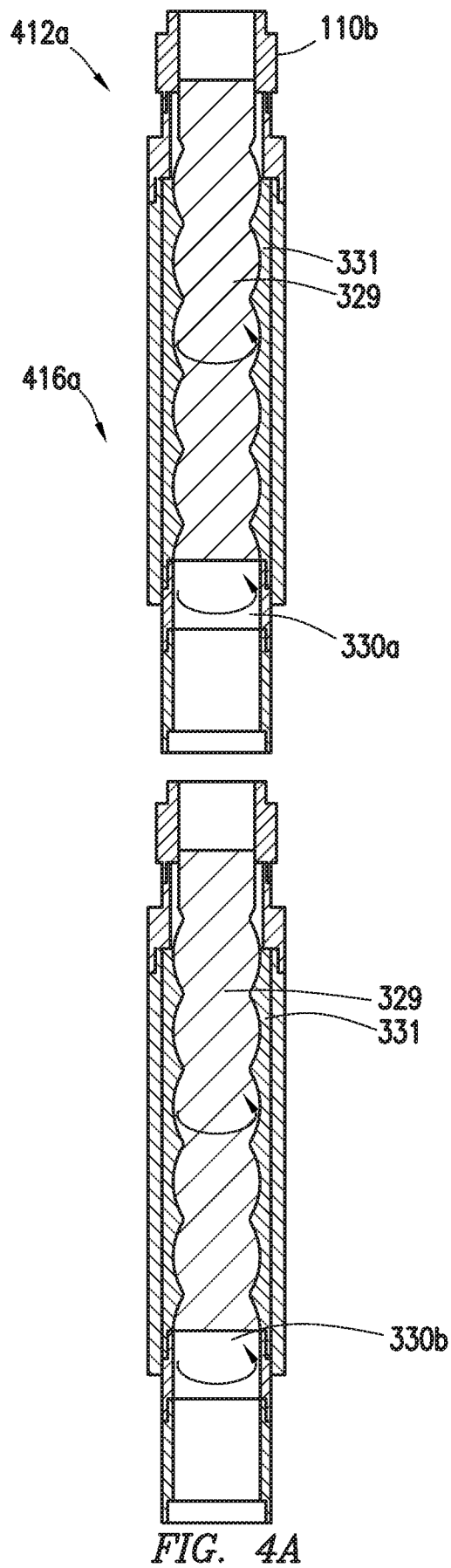


FIG. 2B

4/12



5/12



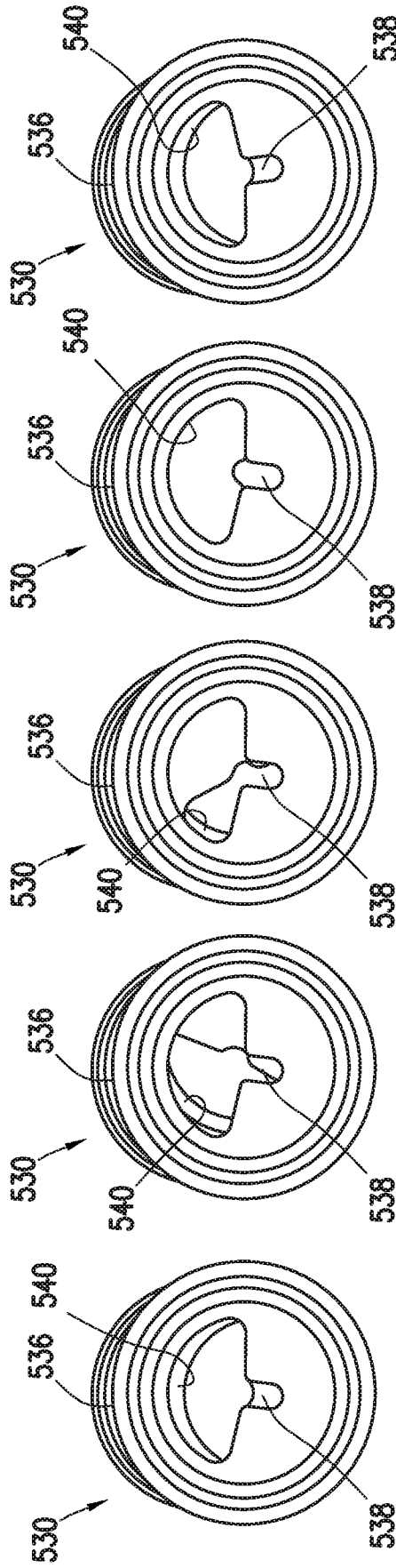


FIG. 5A

FIG. 5B

FIG. 5C

FIG. 5D

FIG. 5E

6/12

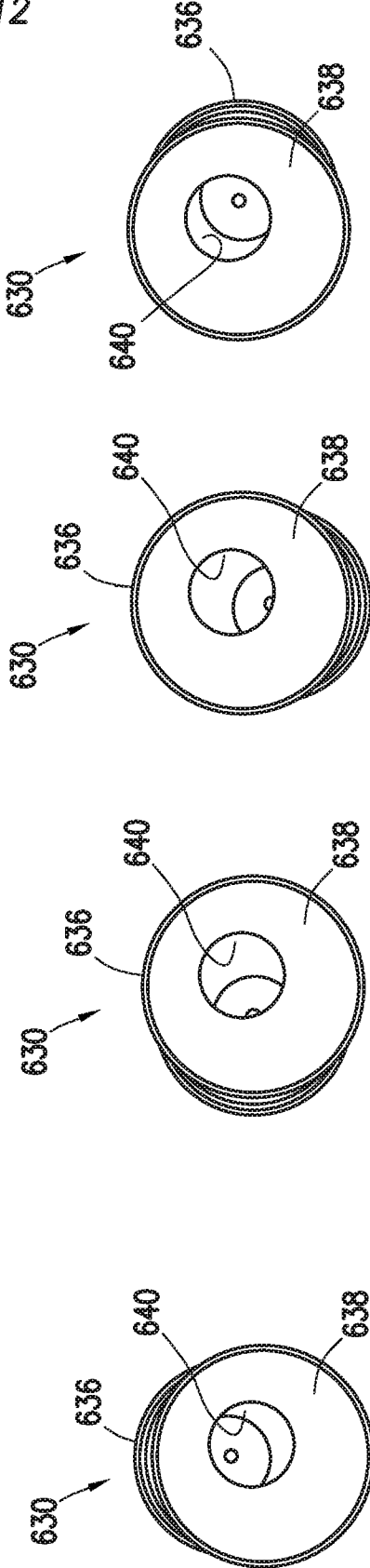


FIG. 6A

FIG. 6B

FIG. 6C

FIG. 6D

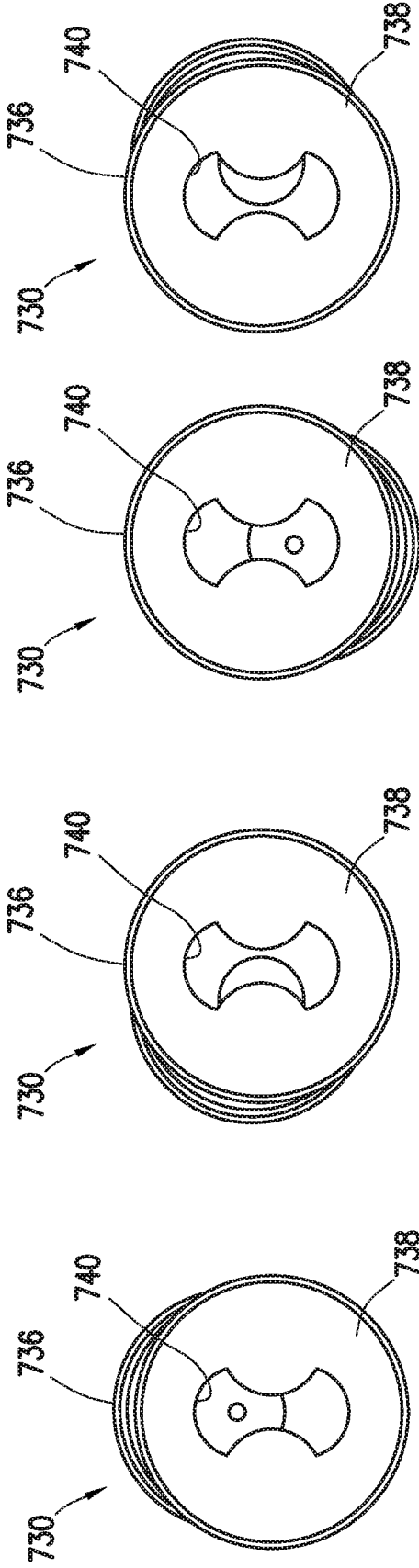


FIG. 7D

FIG. 7C

FIG. 7B

FIG. 7A

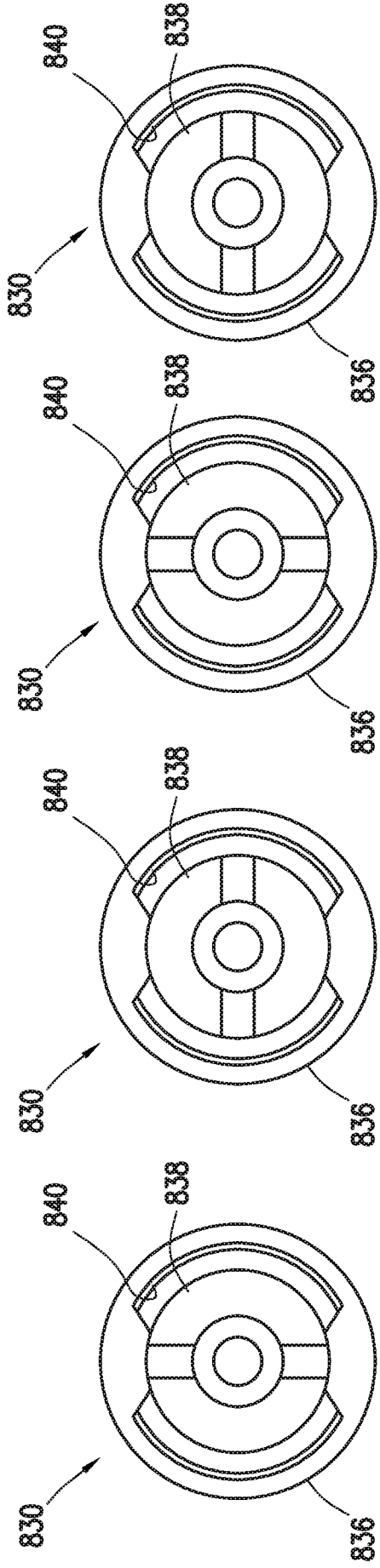


FIG. 8D

FIG. 8C

FIG. 8B

FIG. 8A

8/12

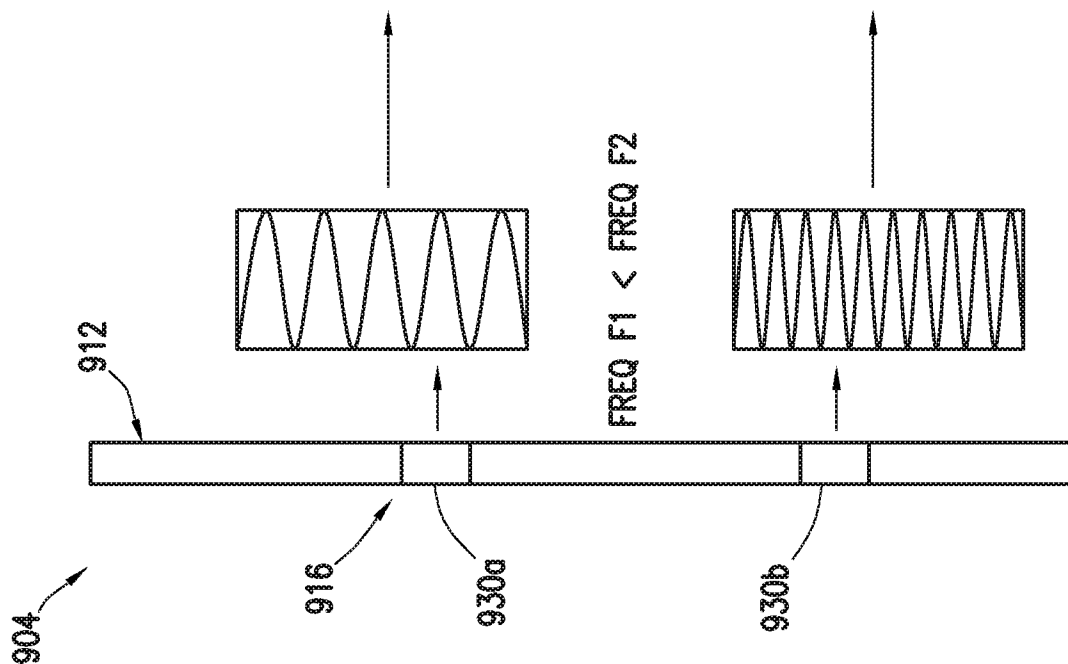
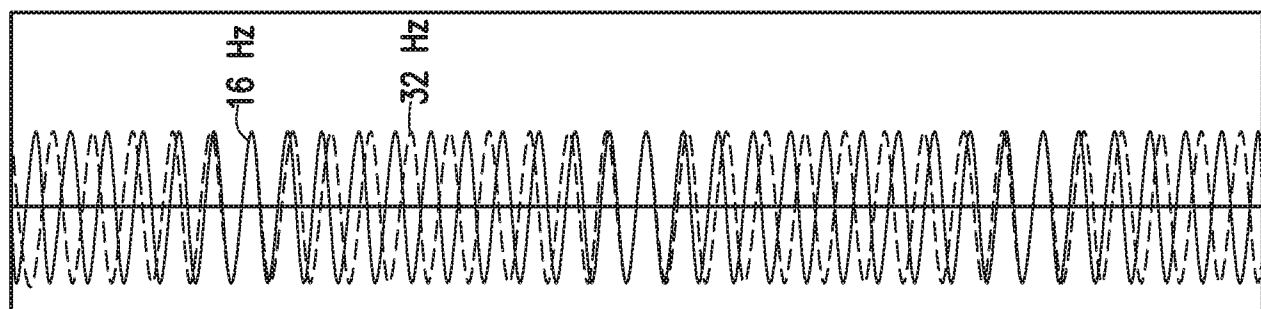


FIG. 9B

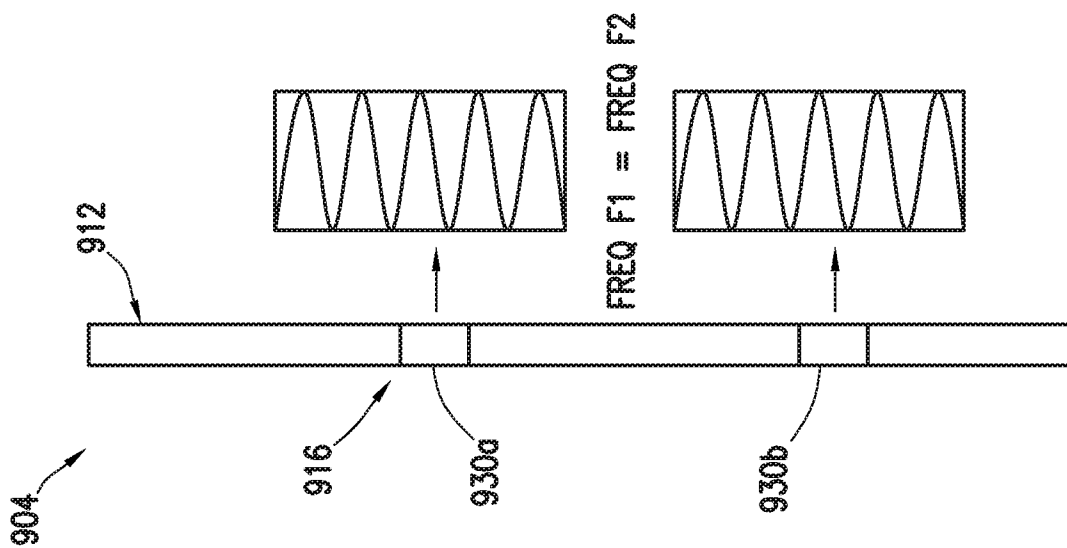
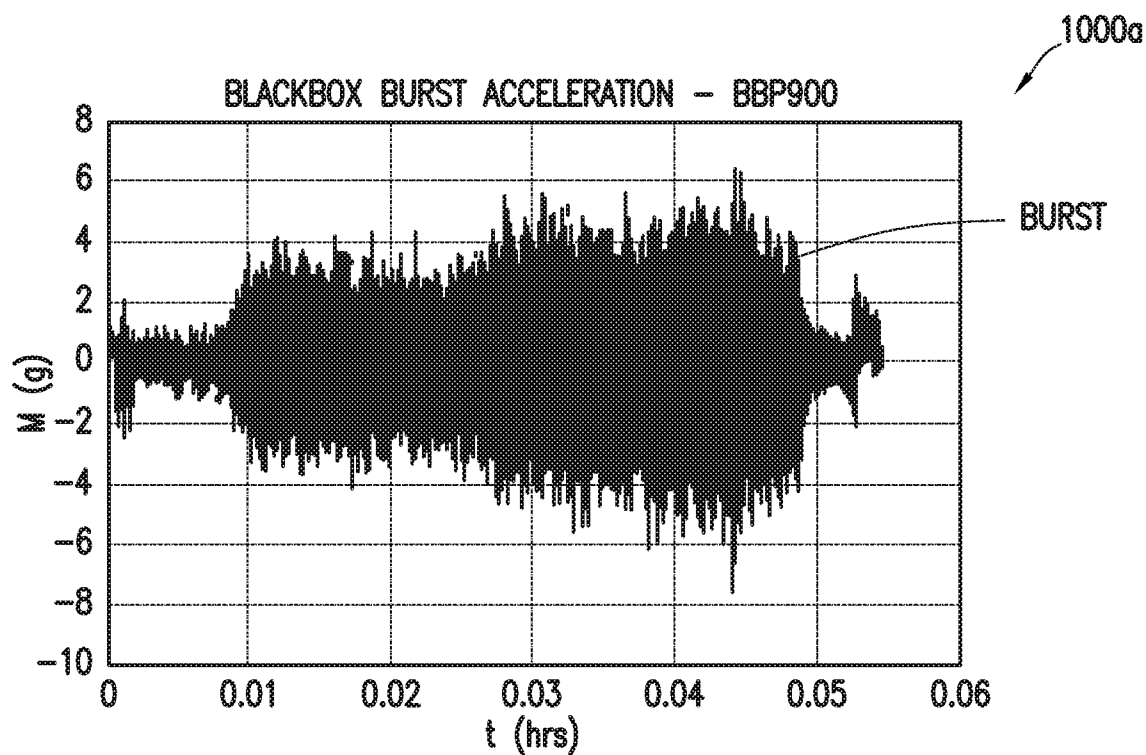


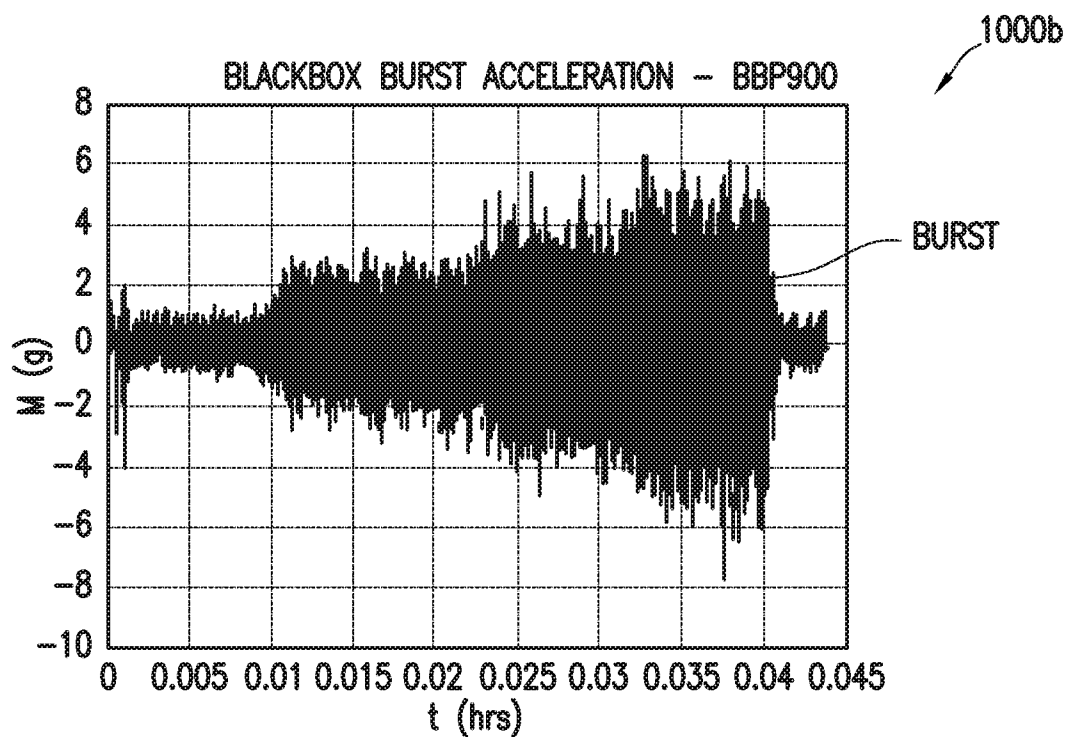
FIG. 9A

9/12



FREQ 1 ONLY

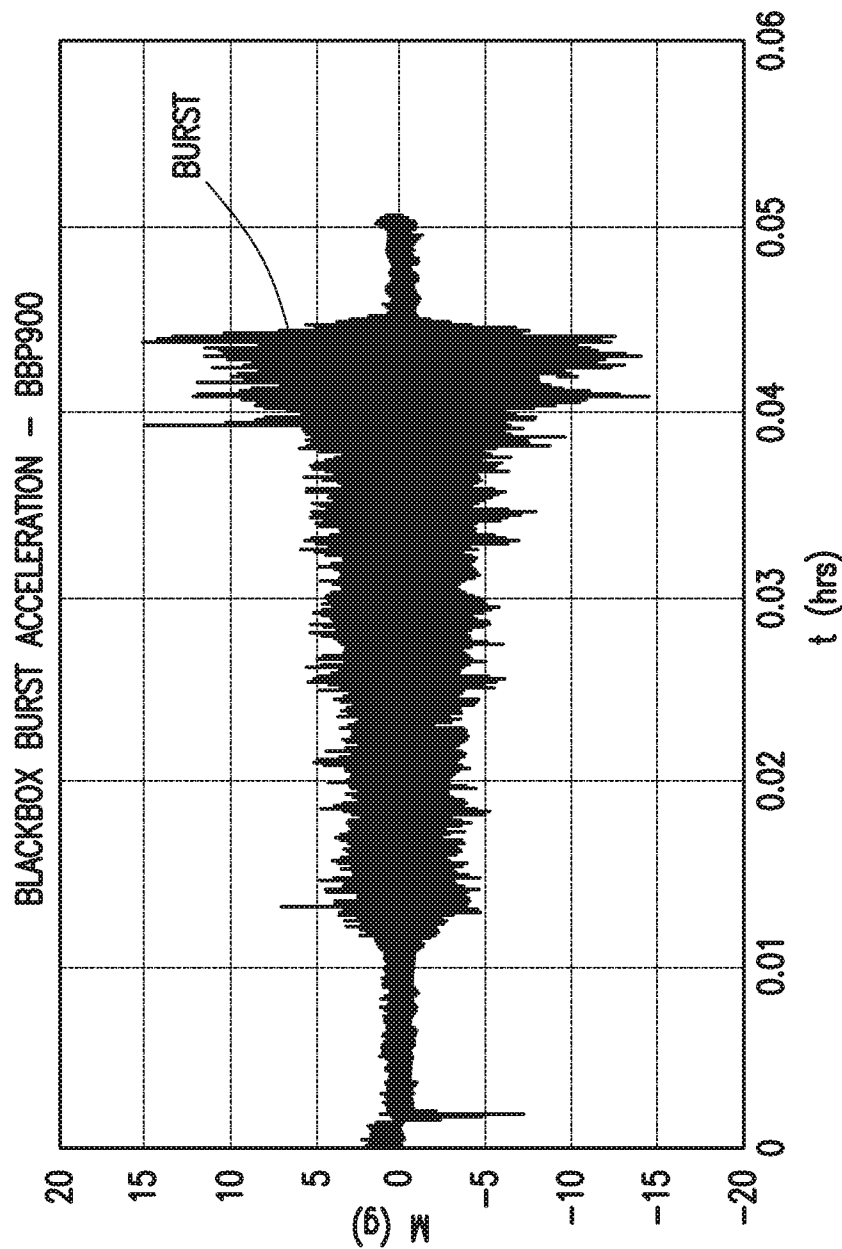
FIG. 10A



FREQ 1 = FREQ 2

FIG. 10B

1000c



FREQ 1 > FREQ 2 (OR FREQ 1 < FREQ 2)
FIG. 10C

11/12

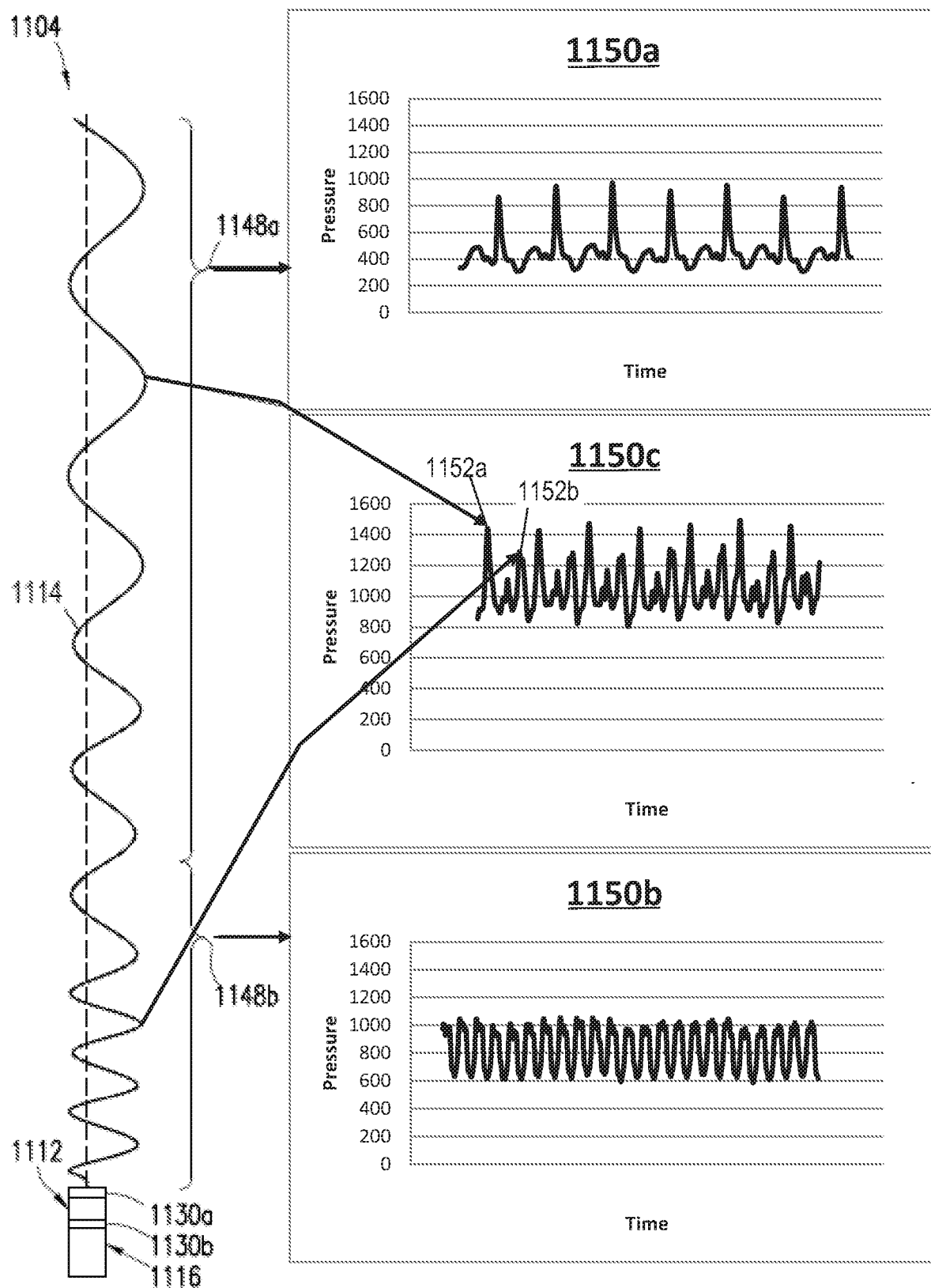


FIG. 11

12/12

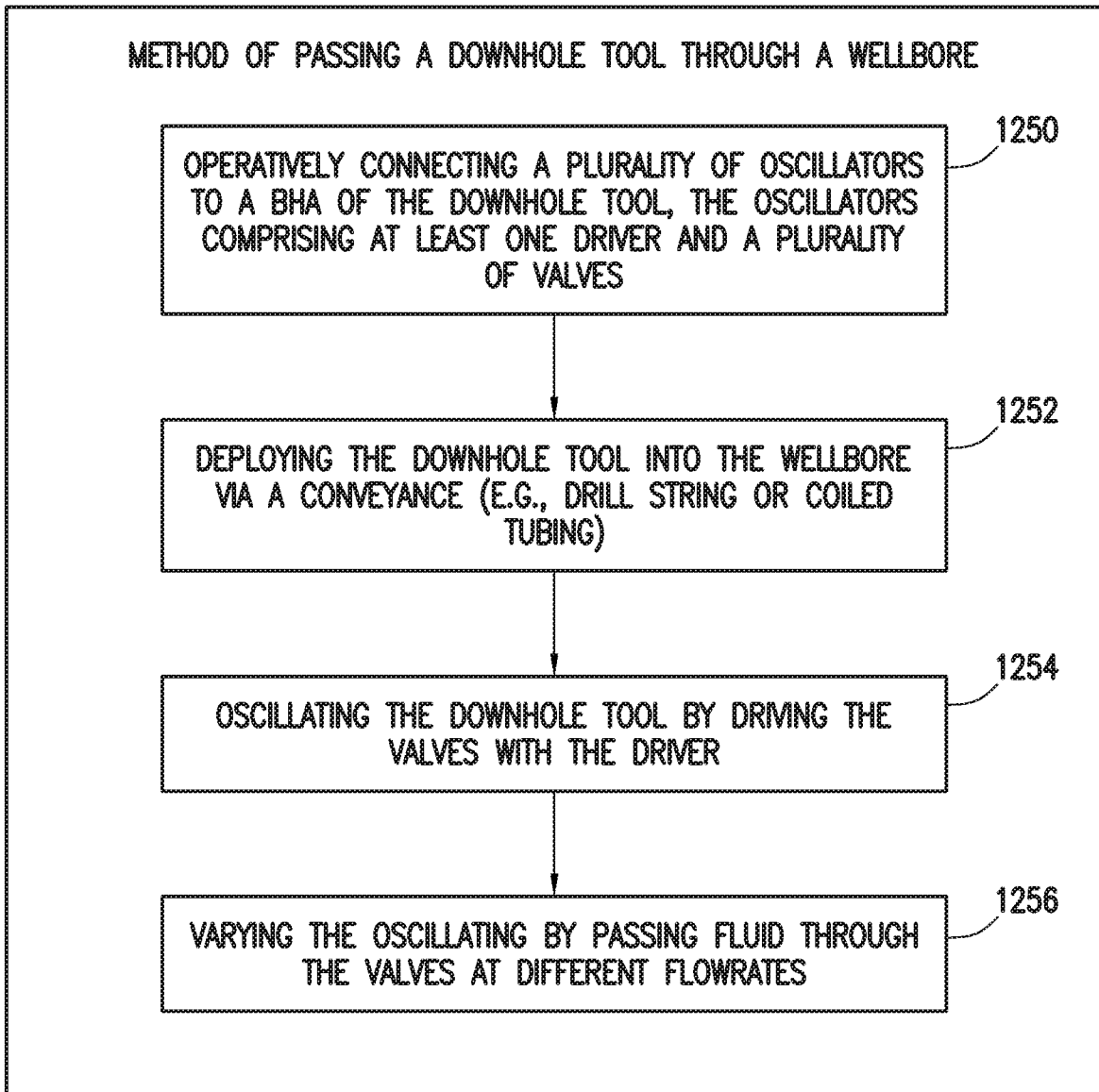


FIG. 12

INTERNATIONAL SEARCH REPORT

International application No.

PCT/US2017/044956

A. CLASSIFICATION OF SUBJECT MATTER

IPC(8) - E21B 31/00; E21B 1/28; E21B 4/06; E21B 4/14; E21B 7/24; E21B 17/20; E21B 28/00 (2017.01)
 CPC - E21B 31/005; E21B 4/06; E21B 4/14; E21B 7/24; E21B 17/20; E21B 28/00; E21B 31/00; E21B 41/00; G01V 1/145 (2017.08)

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

See Search History document

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

USPC - 173/200; 173/201; 340/853.1; 367/83; 367/143 (keyword delimited)

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

See Search History document

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 2013/0048274 A1 (SCHULTZ et al) 28 February 2013 (28.02.2013) entire document	1-5, 9-12, 14

Y		6, 13
Y	US 7,401,656 B2 (WOOD et al) 22 July 2008 (22.07.2008) entire document	6, 13
A	CN 203403820 U (YANGZHOU TIANYE PETROLEUM MACHINERY) 22 January 2014 (22.01.2014) see machine translation	1-20
A	US 2013/0048379 A1 (MACDONALD et al) 28 February 2013 (28.02.2013) entire document	1-20
A	CN 105332655 A (YANGTZE UNIVERSITY) 17 February 2016 (17.02.2016) see machine translation	1-20

☐ Further documents are listed in the continuation of Box C.☐ See patent family annex.

* Special categories of cited documents:

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"O" document referring to an oral disclosure, use, exhibition or other means

"P" document published prior to the international filing date but later than the priority date claimed

"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone

"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art

"&" document member of the same patent family

Date of the actual completion of the international search

21 September 2017

Date of mailing of the international search report

20 OCT 2017

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