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(54) SINGLE-GRIPPER WEAVING LOOM

EINZELGRIFF-WEBMASCHINE

MÉTIER À TISSER À UNE SEULE PINCE

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Description

Field of the invention

[0001] The present invention relates to a single-gripper weaving loom and to a weaving method for a single-gripper loom.

Background of the invention

[0002] In the technical context of weaving looms it is known the use of double-gripper looms. According to a typical embodiment, such looms comprise a first carrying gripper, which receives one or more weft threads from a weft selector and transports them into a weaving shed consisting of a passage delimited by two pluralities of warp threads arranged according to respective planes extending from a common edge consisting of the last weft thread inserted into the fabric with the aid of the last beat-up of the loom reed. During weaving, before being transferred onto the carrying gripper, each weft thread extends from a respective rock to the strip of already produced fabric. Once a weft thread has been grasped by the carrying gripper, the portion of said weft threat that extends from the fabric that has already been produced to the carrying gripper is cut before insertion of the weft thread in the weaving shed. Thus, at each insertion of the carrying gripper into the weaving shed, it only carries weft thread, which unwinds from the respective rock, without interesting the portion of thread from the part of the fabric that has already been produced. The use of a cutting device, placed between the position in which the carrying gripper receives the thread and the weaving shed, is envisaged in order to carry out the cutting of the weft thread. While the carrying gripper advances within the weaving shed a second receiving gripper moves in the opposite direction. The grippers meet half way into the weaving shed and interpenetrate each other. The weft thread or threads are released by the carrying gripper and gripped by the receiving gripper with the aid of suitable lever controls that are actively moved, by means of external control, or passively moved, by the said weft threads. Following the exchange, the movement of each gripper is inverted and the carrying gripper returns to the initial position while the receiving gripper carries the weft threads along the second half of the weaving shed.

[0003] The above-described double-gripper loom permits high weaving speeds to be achieved, while at the same time permitting fabrics of a considerable width to be produced. It however presents a plurality of drawbacks, the main ones being:

- the exchange difficulty between grippers for certain types of weft, such as thick, fine, multi-filament, slub or other wefts,
- the number of structural defects that this exchange difficulty produces in the fabric, which for certain types of fabric, for example technical fabrics or filtering fabrics for medical application, can be unacceptable,
- the low production flexibility since considerable time is required to adjust the loom in order to pass onto a different item produced, in the event of frequent item changes, calibration times can become excessively high.

[0004] In addition to double-gripper looms there are also known single-grip looms that envisage the use of a single gripper, which carries the weft threads through the whole weaving shed. With these looms is possible to overcome the drawbacks connected to the transfer of the weft threads from one gripper to the other, while accepting lower weaving speeds and product width. For example, it is known the production of looms comprising a single receiving gripper that directly receives the weft threads from a fixed weft presentation device. After having gripped the weft thread the receiving gripper carries it through the weaving shed from a first end close to the presentation device to a second, remote end, upon reaching which the gripper releases the weft thread and returns towards the first end of the shed to receive more weft thread.

[0005] The above-described single-gripper loom does not represent an optimal solution being improvable upon under multiple aspects, in particular as concerns flexibility and item change times.

[0006] Also known is the content of document WO 2010/142264 A1. This document shows a device and method for introducing the weft into a gripper weaving machine. Specifically, on an a gripper weaving machine, two weft threads are selected simultaneously from a number of weft threads for a web cycle according to a pattern, and presented to a bringer gripper head, gripped by same, and introduced into a shed. The weft threads are guided and clamped in the bringer gripper head by separate elements, and positioned in such a way that they remain separated during the introduction of the weft.

[0007] Furthermore, document DE 10 2009 036589 A1 is also known. This document shows a device for transferring a preferably band-shaped weft material from a feed unit to an insertion element of a weaving machine comprises a clamping device for clamping a free end of the weft material. The clamping device is conveyable essentially in the direction of motion of the insertion element between at least two different operating positions. The device includes a drive for conveying the clamping device. In a method for transferring a preferably band-shaped weft material from a bobbin or a feed unit to an insertion element of a weaving machine, a free end of the weft material is clamped in a clamping device, the free end is transferred to the insertion element, and then the clamping device is opened and the weft material is inserted.; The clamping device is conveyed by means of a drive essentially in the direction of motion of the insertion element between at least two different operating positions.

Summary

[0008] The aim of the present invention is that of providing a new single-gripper loom, capable of overcome the drawbacks reported with reference to the prior art, while permitting a high production flexibility, being characterised by a wide range of produceable fabrics and by shorter item change times.

[0009] Another aim is that of making available a loom of the above-indicated type, capable of producing fabrics characterised by a low level of structural defects and therefore particularly usable in the production of technical fabrics.

[0010] According to the invention, the aforementioned technical problem is resolved with the aid of a single-gripper according to claim 1.

[0011] With the present invention it is therefore possible to obtain a single-gripper loom wherein a single receiving gripper received the weft threads from a weft feeder, which acts between the weft selector and the receiving gripper, therefore having a function analogous to that of the carrying gripper of a double-gripper loom, but permitting a plurality of advantages to be achieved. Among these, the fact that in the present invention the weft feeder places each of the weft threads lowered by the selector into an optimal position for fastening by the receiving gripper, before the weft thread is cut. This permits the weft feeder to be made constructively simpler than a carrying gripper, no gripping element for retaining the weft threads on the weft feeder being in fact necessary. This makes the release of the weft threads from the weft feeder simpler and allows a more reliable grip on the part of the receiving gripper. In addition, by cutting the thread after it has been fastened by the receiving gripper into the optimal position achieved by means of the weft feeder, weft thread waste is minimised.

[0012] The greater simplicity of this loom compared to a conventional double-gripper loom also makes the change of processed item phases simpler and quicker, while improving production flexibility.

[0013] A further advantage consists in that the exchange of the thread between the weft feeder and receiving gripper presents less critical issues since it takes place outwith the weaving shed and before the weft thread is cut. This significantly reduces the structural defects of the fabrics obtained with the loom of the present invention.

[0014] Other advantages of the present invention are achieved by means of a single-gripper loom according to the dependant claims. In particular, the present invention allows the obtaining of a loom wherein the angle of the weft thread with respect to a sliding plane of the receiving gripper can be changed by means of rotation of the weft feeder. This further contributes to increasing the production flexibility of the loom of the present invention.

Brief description of the drawings

[0015] Further characteristics and advantages of the present invention will become clearer from the following detailed description of a preferred, but non-exclusive embodiment, illustrated by way of a non-limiting example, with reference to the accompanying drawings, wherein:

- figure 1 is an axonometric view of a significant portion of a single-gripper loom according to the present invention,
- figure 2 is an axonometric view of a detail of the loom of figure 1;
- figure 3 is an axonometric view of the detail of figure 2 in a different operational configuration,
- figure 4 is an axonometric view of another detail of the loom of figure 1 in a different operational configuration than that of figure 1,
- figures 5 and 6 are two axonometric views of the detail of figure 4, in two different respective operational configurations,
- figure 7 is a schematic bottom view of the detail of figure 2,
- figure 8 is a front view of the detail of figure 2,
- figure 9 is a top view of the detail of figure 2.

Detailed description of the invention

[0016] With reference to the accompanying drawings, a single-gripper loom according to the present invention is overall indicated by 1.

[0017] Figure 1 shows a strip of fabric T during weaving, which is fixed to the loom 1. The strip of fabric T comprises two pluralities of respective weft 2, 3 and warp 4a, 4b threads, orthogonally woven together.

[0018] The loom 1 comprises a receiving gripper 5 that moves by means of sliding through a weaving shed 10 consisting of a first portion 4a and of a second portion 4b of warp threads, respectively arranged along respective planes extending from one common edge 10a of weft consisting of the last weft thread inserted by the receiving gripper 5 into the strip of fabric T, as better described hereunder. The weaving shed 10 is extended between a first opening 10b, aligned with a first edge T1 of the fabric T and a second opening (not represented) aligned with a second edge (not show), parallel to the first edge T1.

[0019] The angle between the planes of the warp threads 4a and 4b that constitute the weaving shed is adjustable by means of a plurality of heddles, schematically represented by the lines 30 of figure 1, structurally and functionally in themselves known to the prior art. Between the heddles 30 and the weft edge 10a, a reed 31 is provided, which is also schematically represented in figure 1, to push each weft thread inserted into the weaving shed 10 towards the stripe of fabric T. The shape and the operation of the reed 31 are in themselves known.

[0020] The receiving gripper 5 is movable across the

weaving shed 10 along a sliding guide 6 produced with the aid of a semi-rigid driving tape 6a, that is partially wound around a driving gear (not represented) so as to slide in the space between the reed 31 and the fabric T in a sliding direction F1 parallel to the weft edge 10a. The tape 6a, in a preferred embodiment thereof, is flat in shape with two flat, opposing main faces that are arranged parallel to a sliding plane B of the tape 6a, on one of which the receiving gripper 5 is mounted.

[0021] According to another variant embodiment of the invention (not represented), the sliding guide 6 is obtained by means of a rigid driving rod.

[0022] In general, according to other variant embodiments of the invention, the sliding guide 6 is obtained by means of a driving element other than a tape or a rod, so long as it is able to produce the sliding movement required by the receiving gripper.

[0023] Rotation of the driving gear and the consequent translation of the driving tape 6a determines the sliding of the receiving gripper 5 from and to a gripping position P2 (figure 4), wherein the receiving gripper 5 receives one or more weft threads 2, 3 so as to insert them in the weaving shed 10 from the first opening 10b to the second opening of the weaving shed 10. The gripping position P2 is outside the weaving shed 10, on the side of the first opening 10b.

[0024] According to another variant embodiment of the invention, the gripping position P2 is inside the weaving shed 10, in proximity to the first opening 10b.

[0025] The receiving gripper 5 is of a known and conventional type and comprises one hook end 5a which receives and holds the weft threads 2, 3. The receiving gripper 5 is operated with the aid of the tape 6a to pass through the entire weaving shed 10 up to an end stroke position (not represented), positioned beyond the second opening of the weaving shed 10. In proximity of the end stroke position, the receiving gripper 5 releases the weft threads 2, 3 to return to the gripping position P2, so as to be able to receive other weft threads to insert in the weaving shed 10. The weft threads 2, 3 that must be taken by the receiving gripper 5, are selected on the basis of the characteristics of the fabric T, by a weft selector 8 that is active on a plurality of weft threads, each of which extends from one respective rock (not represented) towards the fabric T being woven. The weft selector 8 is positioned outside the weaving shed 10, on the side of the first opening 10b, and comprises a plurality of rods 8a, each of which is provided, at one end, with an eyelet 8b through which a respective weft thread passed. Each rod is movable between a raised resting position, represented in figure 1, spaced from the sliding plane B, and a lowered position, represented in figure 2, close to the sliding plane B.

[0026] The weft selector 8 is of a known type, for example according to that which is described in patents EP0894882 and EP0894883, and for this reason not described in further detail.

[0027] In the example of figures 2 et seq there is represented the case in which the weft selector 8 selects two wefts to be inserted into the weaving shed 10. In general, according to other variant embodiments that are not represented, any number of wefts can be selected between 1 and the maximum number of wefts on which the weft selector 8 is active.

[0028] The loom 1 further comprises a weft feeder 12 to transfer the weft threads 2, 3 from the rods of the weft selector 8 in the lowered position to the receiving gripper 5, in the gripping position P2. The weft feeder 12 is movable along a second sliding guide 7, produced with the aid of a semi-rigid driving tape 7a, partially wound around a respective driving gear (not represented) so as to be able to slide in a sliding direction F2 aligned with the sliding direction F1 of the tape 6a. According to another variant embodiment of the invention (not shown), the sliding guide 7 is obtained by means of a rigid driving rod.

[0029] In general, according to other variant embodiments of the invention, the sliding guide 7 is produced by means of a driving element other than a tape or a rod, so long as it is able to produce the sliding movement required by the receiving gripper 12.

[0030] The tape 7a is also flat in shape with two flat, opposing main faces that are arranged parallel to the sliding plane B, on one of which is mounted the weft feeder 12. The movement of the tape 7a is synchronised with that of the tape 6a of the receiving gripper 5, so that the weft feeder 12 can slide along the second guide 7, between an intercepting position P1, outside the weaving shed 10 on the side of the first opening 10b, wherein the weft feeder 12 intercepts the weft threads 2, 3 in the lowered position, and the gripping position P2, wherein the receiving gripper 5 receives the weft threads 2, 3 from the weft feeder 12.

[0031] The movement of the weft feeder 12 is such that the gripping position P2 is interposed between the intercepting position P1 and the first opening 10b of the weaving shed 10. After having ceded the weft threads 2, 3 to the receiving gripper 5 in the gripping position P2, the weft feeder 12 is activated with the aid of the tape 7a to move along an outside starting position (not represented), placed beyond the intercepting position P1. The weft feeder can be activated from the starting position with the aid of the tape 7a to return to the intercepting position P1, so as to be able to intercept other weft threads to transfer to the receiving gripper 5. The weft feeder 12 is provided with a cavity 13 that is elongated and adjustable according to the sliding direction F1 of the receiving gripper 5. The cavity 13 is susceptible to housing the hook end 5a of the receiving gripper 5 when it reaches the gripping position P2. The cavity 13 of the weft feeder 12 is defined between a first flat lower face 14, adjacent to the tape 7a of the second guide 7, a second flat upper face 15 that is opposed to the first face 14. The weft feeder 12 has an almost hollow parallelepiped shape and further comprises two opposing flat lateral faces 21, 22 extending between the first and second lower and upper face 14, 15. Correspondingly, the cavity 13 also has a

parallelepiped shape.

[0032] The cavity 13 comprises a front opening 13a facing the receiving gripper 5 and susceptible to intercepting the weft threads 2, 3 when the weft feeder 12 reaches the intercepting position P1.

[0033] The first and second face 14, 15 respectively comprise a first notch 18 and a second notch 19, extending from the front opening 13a and susceptible to receiving the weft threads 2, 3 when the weft feeder is between the intercepting P1 and gripping P2 positions. The weft threads 2, 3 are positioned in the respective end grooves of the notches 18, 19 so that they cross the cavity 13 from one to the other first and second face 14, 15. The weft feeder 12 and, in particular, the notches 18, 19 are not provided with any gripping element for holding the weft threads 2, 3. The gripping position P2 is conveniently close to the intercepting position P1 and to the first opening 10b of the weaving shed 10, so that the weft threads 2, 3 are transferred by the weft selector 8 to the receiving gripper 5 with the aid of the weft feeder 12, without there being any need of gripper elements to hold the weft threads 2, 3 in the weft feeder 12.

[0034] According to another variant embodiment of the invention (not represented), at least one of the notches 18, 19 is produced on one of the lateral faces 21, 22 of the weft feeder 12.

[0035] According to a further variant embodiment of the invention (not represented), the weft feeder 12 comprises a single notch produced on the lower face 14 or on the upper face 15 or on one of the lateral faces 21, 22.

[0036] The weft threads 2, 3 cross the cavity 13, from one to the other first and second face 14, 15, forming a pre-defined angle A with the sliding plane B. The angle A is in general of between 0° and 180° and is selected on the basis of the type and of the processing parameters executed by the loom 1.

[0037] In order to change the angle A it is possible to substitute the weft feeder 12 with another weft feeder of a different size or position of the notches 18, 19 or to change the inclination of the weft feeder by rotating around a rotation axis Y that is parallel to the sliding direction F1.

[0038] Alternatively, according to a variant embodiment of the invention, the weft feeder 12 is optionally provided with a rotating actuator M so as to be rotatable in operation, also while the weft feeder 12 is sliding along the direction F2, around the rotation axis Y, to change the angle A while in operation.

[0039] In the end part of its stroke towards the gripping position P2, the receiving gripper 5 interpenetrates the weft feeder 12, entering the cavity 13 through the front opening 13a and moving aside the weft threads 2, 3 with the external part of the hook end 5a. In the first part of its return stroke, the weft threads 2, 3 held in the cavity 13 between the first and the second notch 18, 19, are gripped by the internal part of the hook end 5a and carried towards the weaving shed 10 (figure 5).

[0040] The loom 1 comprises a weft cutter 11 that can be operated to cut the weft threads 2, 3 after the receiving gripper 5 has received these, as schematically represented in figure 6 wherein the weft cutter 11 is indicated by a pair of scissors.

[0041] The weft cutter 11 can be operated to cut the weft threads 2, 3 when the receiving gripper has reached an intermediate cutting position P3 between the gripping position P2 and the first opening 10b of the weaving shed 10, so that only weft thread that is unwound from the respective rock is inserted into the weaving shed, without affecting the section of thread from the part of the fabric T.

[0042] Alternatively, according to another variant embodiment of the invention, the cutting position P3 is inside the weaving shed 10, in proximity to the first opening 10b.

[0043] In possible variant embodiments of the present invention, the cutting position P3 is arranged so that the weft threads 2, 3 are cut after they have been gripped by the receiving gripper 5. The receiving gripper 5 thus reaches the cutting position P3 following the gripping position P2.

[0044] In all possible variant embodiments of the present invention, the cutting position P3 is conveniently close to the gripping position P2, so as to minimise weft thread waste.

[0045] The weft cutter 11, as represented in figure 1, is in itself known and conventional and is therefore not described in detail.

[0046] The loom 1 can be operated according to a weaving method comprising the below-described weaving methods.

[0047] In a first step, one or more weft threads 2, 3 are selected with the aid of a weft selector 8. The weft threads are gripped in a lowered position (figure 2) in which they can be intercepted by the weft feeder 12. In this step the weft feeder 12 is located between the starting position and the weft intercepting position P1 while the receiving gripper 5 is located between the end stroke position and the gripping position P2.

[0048] In a second step, the weft threads 2, 3 in a lowered position are intercepted with the aid of a weft feeder 12 (figure 3), so as to arrange themselves between the first and the second notch 18, 19, through the cavity 13. Interception of the weft threads 2, 3 takes place the weft feeder 12 is in the intercepting position P1, reached by means of the sliding of the starting position towards the weaving shed 10.

[0049] In a third step, the weft feeder 12 is translated from the intercepting position P1 to the gripping position P2, outside the weaving shed 10, wherein it meets the receiving gripper 5, which interpenetrates the weft feeder 12, entering into the cavity 13 (figure 4). In this step, the motion of the weft feeder 12 allows the weft threads 2, 3 gripped within it to be effectively stretched, so as to facilitate the gripping on the part of the receiving gripper 5.

[0050] In a fourth step, in the gripping position P2, the weft threads 2, 3 are transferred by the weft feeder 12 to the receiving gripper 5, which holds them at the level of the hook end 5a and transports them towards the weav-

ing shed 10, while translating (figure 5) from the gripping position P2 towards the end stroke position.

[0051] In a fifth step, the weft threads 2, 3 are cut with the aid of the weft cutter 11 after they have been transferred to the receiving gripper 5, before insertion into the weaving shed 10.

[0052] In a sixth step, the weft threads 2, 3 are inserted into the weaving shed 10, with the aid of a receiving gripper 5, until the end stroke position has been reached, in proximity to which the weft threads 2, 3 are released. In the course of the fifth and sixth step, the weft feeder 12 returns to the starting position.

[0053] According to other variant embodiments of the present method, the gripping position P2 and/or the cutting position P3 are inside the weaving shed 10 in proximity to the first opening 10b, as described in detail above.

[0054] The above-described method can also be operated on looms other than the above-described loom 1 so long as they are equipped with a single receiving gripper for the insertion of the weft inside the weaving shed and of a weft feeder for the transfer of the weft from a weft selection device to the receiving gripper. The described technical solutions allow the set aims and objects to be fully achieved with reference to the cited prior art, among which there is highlighted the fact of allowing a high production flexibility through the wide range of weft threads that can be processed, in particular thick, fine, multi-filament, slub or other wefts for which the holding and exchange difficulties between the grippers normally used in double-gripper looms are known.

Claims

1. A single-gripper loom (1) comprising:

- a receiving gripper (5), which is movable along a first sliding guide (6) through a weaving shed (10) from and to a gripping position (P2) wherein said receiving gripper (5) receives one or more weft threads (2, 3) so as to insert said weft threads into said weaving shed (10) from a first opening (10b) to a second opening of said weaving shed (10), said gripping position (P2) being outside said weaving shed (10) or close to said first opening (10b),
- a weft selector (8), which acts on said weft threads to move each of said weft threads (2, 3) between a raised position spaced from said first guide (6) and a lowered position close to said first guide (6),

characterized in that it further comprises:

a weft feeder (12) to transfer said weft threads (2, 3) from said weft selector (8) to said receiving gripper (5),
said weft feeder (12) being couplable and movable along a second sliding guide (7) of said loom (1) between an intercepting position (P1) outside said weaving shed (10), wherein said weft feeder (12) intercepts said weft threads (2, 3) in said lowered position, and said gripping position (P2) wherein said receiving gripper (5) receives said weft threads (2, 3) from said weft feeder (12),
said weft feeder (12) also comprising a cavity (13) for housing said receiving gripper (5) of said loom (1) within said weft feeder (12) and a first and a second notches (18, 19) susceptible to receiving one or more weft threads (2, 3) so that said weft threads (2, 3) cross said cavity (13) to be gripped by said receiving gripper (5) when said receiving gripper (5) is housed within said weft feeder (12),
said weft feeder (12) also being devoid of any gripping element for holding said weft threads (2, 3).

2. A single-gripper loom (1) according to claim 1, wherein a cutting element (11) is provided, which is activatable to cut said weft threads (2, 3) once said receiving gripper (5) has received said weft threads (2, 3).

3. A single-gripper loom (1) according to one of the preceding claims, wherein said first and second guides (6, 7) are aligned with each other and said weft feeder (12) is provided with said cavity (13), which is susceptible to housing at least one portion of said receiving gripper (5) in at least said gripping position (P2), said weft threads (2, 3) being susceptible to crossing said cavity (13) when said weft feeder (12) is between said intercepting (P1) and gripping (P2) positions.

4. A single-gripper loom (1) according to claim 3, wherein said cavity (13) of said weft feeder (12) is defined between at least a first lower face (14), adjacent to said second sliding guide (7), and at least a second upper face (15) opposed to said first face (14), said weft feeder (12) comprising said first and second notches (18, 19) susceptible to receiving said weft threads (2, 3) between said intercepting (P1) and gripping (P2) positions.

5. A single-gripper loom (1) according to claim 4, wherein said first and second notches (18, 19) are dimensioned so that said weft threads (2, 3) cross said cavity (13), between said intercepting (P1) and gripping (P2) positions, thus forming a 0°-180° angle (A) with a sliding plane (B) parallel to said first and second guides (6, 7).

6. A single-gripper loom (1) according to claim 5, wherein said weft feeder is rotatable around a rota-

tion axis (Y) parallel to said second sliding guide (7), in order to vary said angle (A) in use.

7. A single-gripper loom (1) according to claim 4 wherein said first and second notches (18,19) of said feeder (12) being respectively provided on said first and second face (14, 15).

8. A weaving method for a single-gripper loom comprising the steps of:

- selecting one or more weft threads (2, 3) by means of a weft selector (8),
- intercepting said weft threads (2, 3) by means of a weft feeder (12),
- translating said weft feeder (12) to a gripping position (P2) of said weft threads (2,3), said gripping position (P2) being outside a weaving shed (10) or close to a first opening (10b) of said weaving shed (10), said weft feeder (12) being movable along a second sliding guide (7), between an intercepting position (P1) outside said weaving shed (10), wherein said weft feeder (12) intercepts said weft threads (2, 3) in said lowered position, and said gripping position (P2),
- in said gripping position (P2), transferring said weft threads (2,3) from said weft feeder (12) to a receiving gripper (5) of said loom (1),
- inserting said weft threads (2,3) into a weaving shed (10) by means of said receiving gripper (5),

wherein said weft feeder comprises a cavity (13) for housing said receiving gripper (5) within said weft feeder (12) and a first and second notches (18,19) susceptible to receiving one or more weft threads (2,3) so that said weft threads (2,3) cross said cavity (13) to be gripped by said receiving gripper (5) when said receiving gripper (5) is housed within said weft feeder (12), said weft feeder (12) also being devoid of any gripping element for holding said weft threads (2,3).

9. A weaving method according to claim 98, further comprising the step of cutting said weft threads (2, 3) once they have been transferred to said receiving gripper (5).

Patentansprüche

1. Einzelgreifer-Webmaschine (1), umfassend:

- einen Nehmergreifer (5), der entlang einer ersten Gleitführung (6) durch ein Webfach (10) von und zu einer Greifposition (P2) bewegt werden kann, wobei der Nehmergreifer (5) einen oder mehrere Schussfäden (2, 3) aufnimmt, um die Schussfäden von einer ersten Öffnung (10b) zu einer zweiten Öffnung des Webfachs (10) in das Webfach (10) einzuführen, wobei sich die Greifposition (P2) außerhalb des Webfachs (10) oder nahe der ersten Öffnung (10b) befindet,
- einen Schusswähler (8), der auf die Schussfäden wirkt, um jeden der Schussfäden (2, 3) zwischen einer angehobenen Position, die von der ersten Führung (6) beabstandet ist, und einer abgesenkten Position nahe der ersten Führung (6) zu bewegen,

dadurch gekennzeichnet, dass sie weiter umfasst:

eine Schusszuführung (12), um die Schussfäden (2, 3) vom Schusswähler (8) zum Nehmergreifer (5) zu transferieren,
wobei die Schusszuführung (12) gekoppelt und entlang einer zweiten Gleitführung (7) der Webmaschine (1) zwischen einer Fangposition (P1) außerhalb des Webfachs (10), wobei die Schusszuführung (12) die Schussfäden (2, 3) in der abgesenkten Position fängt, und der Greifposition (P2) bewegt werden kann, wobei der Nehmergreifer (5) die Schussfäden (2, 3) von der Schusszuführung (12) aufnimmt,
wobei die Schusszuführung (12) ebenfalls einen Hohlraum (13) zum Unterbringen des Nehmergreifers (5) der Webmaschine (1) innerhalb der Schusszuführung (12) und eine erste und eine zweite Einkerbung (18, 19) umfasst, die einen oder mehrere Schussfäden (2, 3) so aufnehmen können, dass die Schussfäden (2, 3) den Hohlraum (13) kreuzen, um vom Nehmergreifer (5) gegriffen zu werden, wenn der Nehmergreifer (5) innerhalb der Schusszuführung (12) untergebracht ist,
wobei die Schusszuführung (12) ebenfalls frei von jedem Greifelement zum Halten der Schussfäden (2, 3) ist.

2. Einzelgreifer-Webmaschine (1) nach Anspruch 1, wobei ein Schneidelement (11) bereitgestellt ist, das aktiviert werden kann, um die Schussfäden (2, 3) durchzuschneiden, sobald der Nehmergreifer (5) die Schussfäden (2, 3) aufgenommen hat.

3. Einzelgreifer-Webmaschine (1) nach einem der vorstehenden Ansprüche, wobei die erste und zweite Führung (6, 7) zueinander ausgerichtet sind und die Schusszuführung (12) mit dem Hohlraum (13) versehen ist, der mindestens einen Teil des Nehmergreifers (5) in mindestens der Greifposition (P2) unterbringen kann, wobei die Schussfäden (2, 3) den Hohlraum (13) kreuzen können, wenn sich die Schusszuführung (12) zwischen der Fang- (P1) und Greifposition (P2) befindet.

4. Einzelgreifer-Webmaschine (1) nach Anspruch 3,

wobei der Hohlraum (13) der Schusszuführung (12) zwischen mindestens einer ersten unteren Fläche (14), die an die zweite Gleitführung (7) angrenzt, und mindestens einer zweiten oberen Fläche (15) definiert ist, die der ersten Fläche (14) gegenüberliegt, wobei die Schusszuführung (12) die erste und zweite Einkerbung (18, 19) umfasst, die die Schussfäden (2, 3) zwischen der Fang- (P1) und Greifposition (P2) aufnehmen können.

5. Einzelgreifer-Webmaschine (1) nach Anspruch 4, wobei die erste und zweite Einkerbung (18, 19) so bemessen sind, dass die Schussfäden (2, 3) den Hohlraum (13) zwischen der Fang- (P1) und Greifposition (P2) kreuzen, wodurch ein 0° - 180°-Winkel (A) zu einer Gleitebene (B) gebildet wird, die zur ersten und zweiten Führung (6, 7) parallel ist.

6. Einzelgreifer-Webmaschine (1) nach Anspruch 5, wobei die Schusszuführung um eine Drehachse (Y) gedreht werden kann, die zur zweiten Gleitführung (7) parallel ist, um den Winkel (A) im Gebrauch zu variieren.

7. Einzelgreifer-Webmaschine (1) nach Anspruch 4, wobei die erste und zweite Einkerbung (18,19) der Zuführung (12) jeweils auf der ersten und zweiten Fläche (14, 15) bereitgestellt sind.

8. Webverfahren für eine Einzelgreifer-Webmaschine, umfassend die Schritte des:

- Auswählens von einem oder mehreren Schussfäden (2, 3) mittels eines Schusswählers (8),
- Fangens der Schussfäden (2, 3) mittels einer Schusszuführung (12),
- Translatierens der Schusszuführung (12) zu einer Greifposition (P2) der Schussfäden (2,3), wobei sich die Greifposition (P2) außerhalb eines Webfachs (10) oder nahe einer ersten Öffnung (10b) des Webfachs (10) befindet, wobei die Schusszuführung (12) entlang einer zweiten Gleitführung (7) zwischen einer Fangposition (P1) außerhalb des Webfachs (10), wobei die Schusszuführung (12) die Schussfäden (2, 3) in der abgesenkten Position fängt, und der Greifposition (P2) bewegt werden kann,
- Transferierens der Schussfäden (2,3) in der Greifposition (P2) von der Schusszuführung (12) zu einem Nehmergreifer (5) der Webmaschine (1),
- Einführens der Schussfäden (2,3) mittels des Nehmergreifers (5) in ein Webfach (10),

wobei die Schusszuführung einen Hohlraum (13) zum Unterbringen des Nehmergreifers (5) innerhalb der Schusszuführung (12) und eine erste und zweite Einkerbung (18,19) umfasst, die einen oder mehrere Schussfäden (2,3) so aufnehmen können, dass die Schussfäden (2,3) den Hohlraum (13) kreuzen, um vom Nehmergreifer (5) gegriffen zu werden, wenn der Nehmergreifer (5) innerhalb der Schusszuführung (12) untergebracht ist, wobei die Schusszuführung (12) ebenfalls frei von jedem Greifelement zum Halten der Schussfäden (2,3) ist.

9. Webverfahren nach Anspruch 8, weiter den Schritt des Durchschneidens der Schussfäden (2, 3) umfassend, sobald dieselben zum Nehmergreifer (5) transferiert wurden.

Revendications

1. Métier à tisser à une seule pince (1) comprenant :

- une pince de réception (5), qui est mobile le long d'un premier guide coulissant (6) à travers une foule (10) vers une position de pincement (P2) et à partir de celle-ci dans lequel ladite pince de réception (5) reçoit un ou plusieurs fils de trame (2, 3) de façon à insérer lesdits fils de trame dans ladite foule (10) d'une première ouverture (10b) vers une deuxième ouverture de ladite foule (10), ladite position de pincement (P2) étant à l'extérieur de ladite foule (10) ou à proximité de ladite première ouverture (10b),
- un sélecteur de trame (8), qui agit sur lesdits fils de trame pour déplacer chacun desdits fils de trame (2, 3) entre une position relevée espacée dudit premier guide (6) et une position abaissée à proximité dudit premier guide (6),

caractérisé en ce qu'il comprend en outre :

un fournisseur de trame (12) pour transférer les fils de trame (2, 3) dudit sélecteur de trame (8) vers ladite pince de réception (5),
ledit fournisseur de trame (12) pouvant être couplé et déplacé le long d'un deuxième guide coulissant (7) dudit métier à tisser (1) entre une position d'interception (P1) à l'extérieur de ladite foule (10), dans lequel ledit fournisseur de trame (12) intercepte lesdits fils de trame (2, 3) dans ladite position abaissée, et ladite position de pincement (P2) dans lequel ladite pince de réception (5) reçoit lesdits fils de trame (2, 3) à partir dudit fournisseur de trame (12),
ledit fournisseur de trame (12) comprenant également une cavité (13) pour le logement de ladite pince de réception (5) dudit métier à tisser (1) à l'intérieur dudit fournisseur de trame (12) et une première et une deuxième encoches (18, 19) susceptibles de recevoir un ou plusieurs fils de trame (2, 3) de sorte que lesdits fils de trame (2,

3) traversent ladite cavité (13) devant être pincée par ladite pince de réception (5) lorsque ladite pince de réception (5) est logée à l'intérieur dudit fournisseur de trame (12),
ledit fournisseur de trame (12) étant donc exempt de tout élément de pincement pour retenir lesdits fils de trame (2, 3).

2. Métier à tisser à une seule pince (1) selon la revendication 1, dans lequel un élément de coupe (11) est prévu, qui peut être activé pour couper lesdits fils de trame (2, 3) une fois que ladite pince de réception (5) a reçu lesdits fils de trame (2, 3).

3. Métier à tisser à une seule pince (1) selon l'une quelconque des revendications précédentes, dans lequel lesdits premier et deuxième guides (6, 7) sont alignés l'un sur l'autre et ledit fournisseur de trame (12) est doté de ladite cavité (13), qui est susceptible de loger au moins une portion de ladite pince de réception (5) dans au moins ladite position de pincement (P2), lesdits fils de trame (2, 3) étant susceptibles de traverser ladite cavité (13) lorsque ledit fournisseur de trame (12) est entre lesdites positions d'interception (P1) et de pincement (P2).

4. Métier à tisser à une seule pince (1) selon la revendication 3, dans lequel ladite cavité (13) dudit fournisseur de trame (12) est définie entre au moins une première face inférieure (14), adjacente audit deuxième guide coulissant (7), et au moins une deuxième face supérieure (15) opposée à ladite première face (14), ledit fournisseur de trame (12) comprenant lesdites première et deuxième encoches (18, 19) susceptibles de recevoir lesdits fils de trame (2, 3) entre lesdites positions d'interception (P1) et de pincement (P2).

5. Métier à tisser à une seule pince (1) selon la revendication 4, dans lequel les première et deuxième encoches (18, 19) sont dimensionnées de sorte que lesdits fils de trame (2, 3) traversent ladite cavité (13), entre lesdites positions d'interception (P1) et de pincement (P2), formant ainsi un angle de 0° - 180° (A) avec un plan de coulissement (B) parallèle auxdits premier et deuxième guides (6, 7).

6. Métier à tisser à une seule pince (1) selon la revendication 5, dans lequel ledit fournisseur de trame est rotatif autour d'un axe de rotation (Y) parallèle audit deuxième guide coulissant (7), afin de varier ledit angle (A) en cours d'utilisation.

7. Métier à tisser à une seule pince (1) selon la revendication 4, dans lequel lesdites première et deuxième encoches (18,19) dudit fournisseur (12) étant respectivement prévues sur ladite première et deuxième face (14, 15).

8. Procédé de tissage pour un métier à tisser à une seule pince comprenant les étapes de :

- sélection d'un ou plusieurs fils de trame (2, 3) au moyen d'un sélecteur de trame (8),
- interception desdits fils de trame (2, 3) au moyen d'un fournisseur de trame (12),
- déplacement en translation dudit fournisseur de trame (12) vers une position de pincement (P2) desdits fils de trame (2,3), ladite position de pincement (P2) étant à l'extérieur d'une foule (10) ou à proximité d'une première ouverture (10b) de ladite foule (10), ledit fournisseur de trame (12) étant mobile le long d'un deuxième guide coulissant (7), entre une position d'interception (P1) à l'extérieur de ladite foule (10), dans lequel ledit fournisseur de trame (12) intercepte lesdits fils de trame (2, 3) dans ladite position abaissée, et ladite position de pincement (P2),
- dans ladite position de pincement (P2), transfert desdits fils de trame (2,3) dudit fournisseur de trame (12) vers une pince de réception (5) dudit métier à tisser (1),
- insertion desdits fils de trame (2,3) dans une foule (10) au moyen de ladite pince de réception (5),

dans lequel ledit fournisseur de trame comprend une cavité (13) pour le logement de ladite pince de réception (5) à l'intérieur dudit fournisseur de trame (12) et une première et deuxième encoches (18,19) susceptibles de recevoir un fil de trame (2,3) ou plus de sorte que lesdits fils de trame (2,3) traversent ladite cavité (13) devant être pincée par ladite pince de réception (5) lorsque ladite pince de réception (5) est logée à l'intérieur dudit fournisseur de trame (12), ledit fournisseur de trame (12) étant donc exempt de tout élément de pincement pour retenir lesdits fils de trame (2,3).

9. Procédé de tissage selon la revendication 8, comprenant en outre l'étape de coupe pour desdits fils de trame (2, 3) une fois qu'ils ont été transférés vers ladite pince de réception (5).

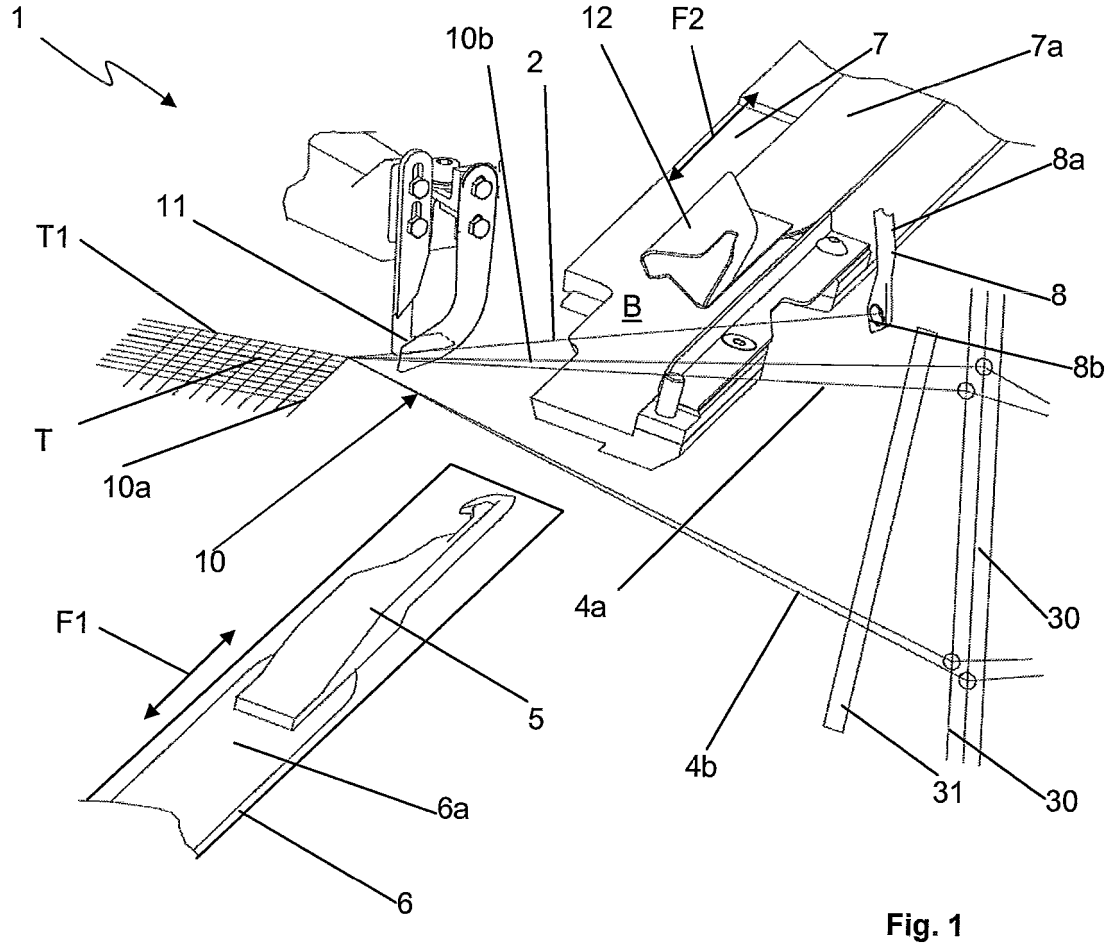

Fig. 1

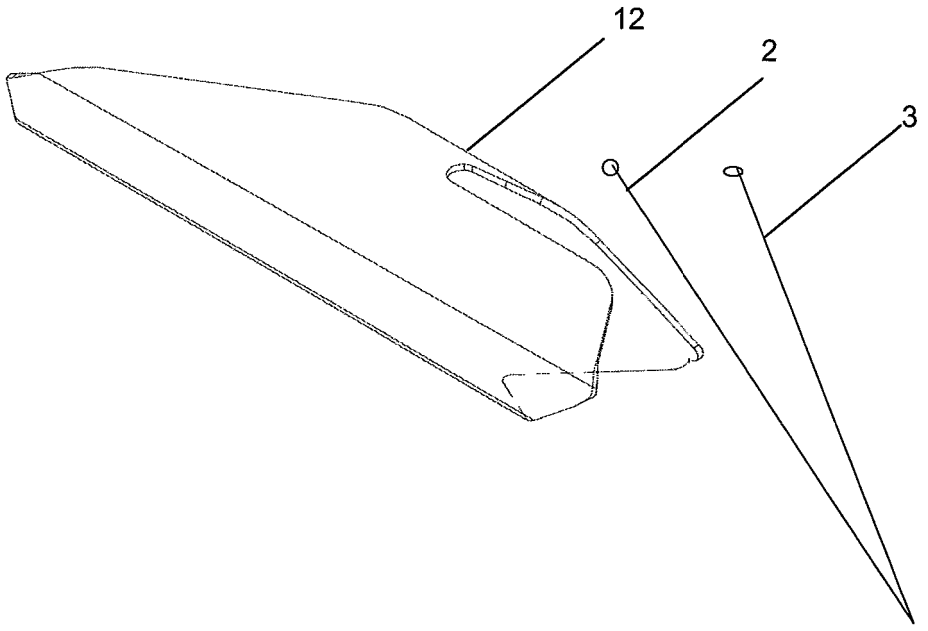

Fig. 2

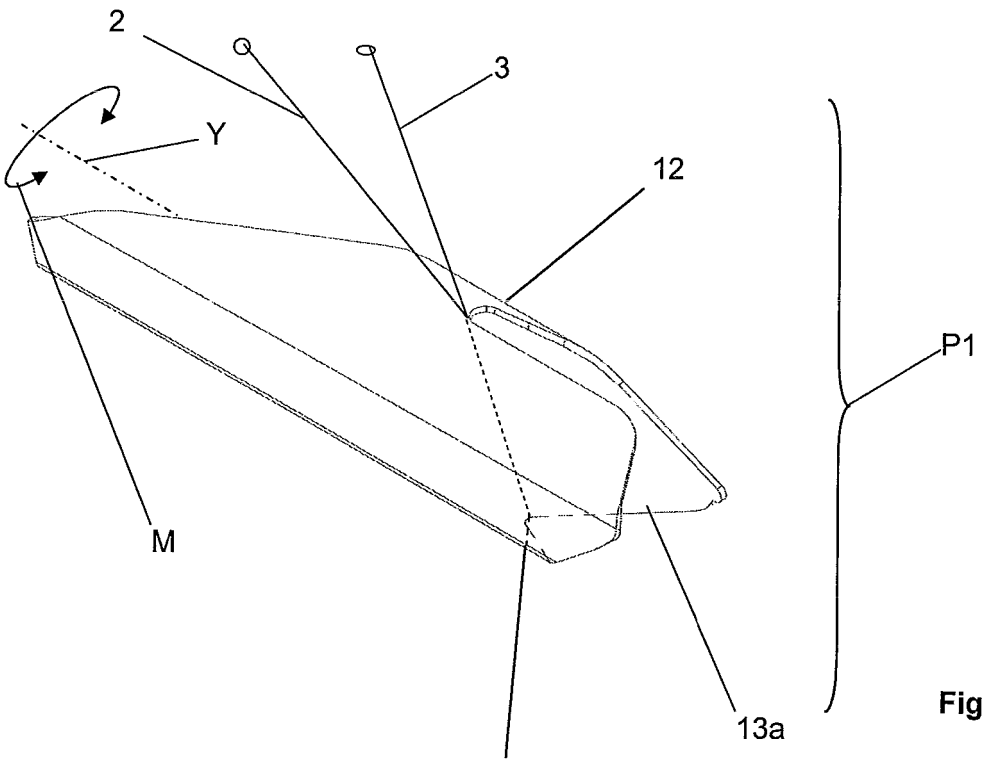

Fig. 3

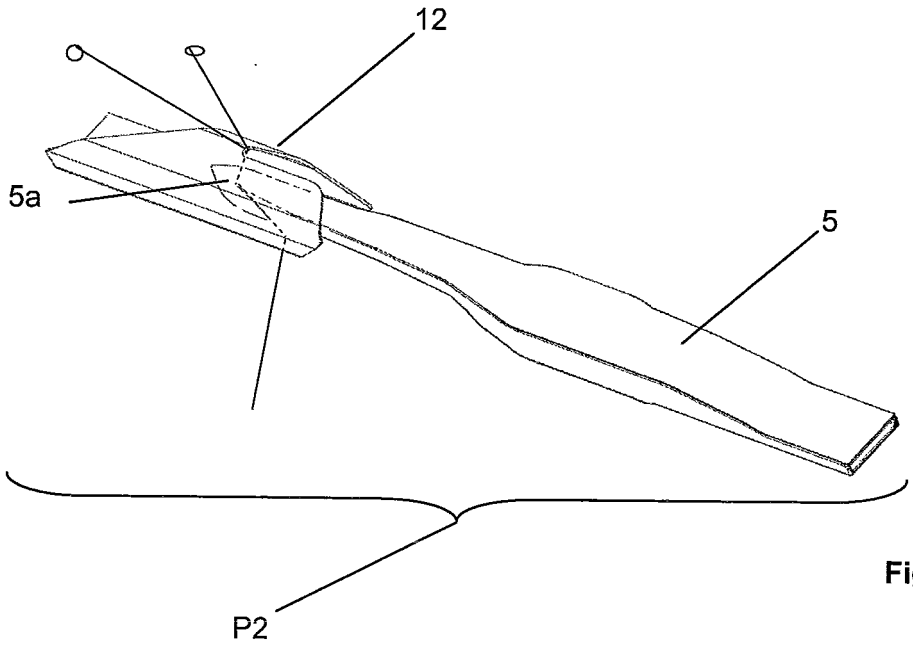

Fig. 4

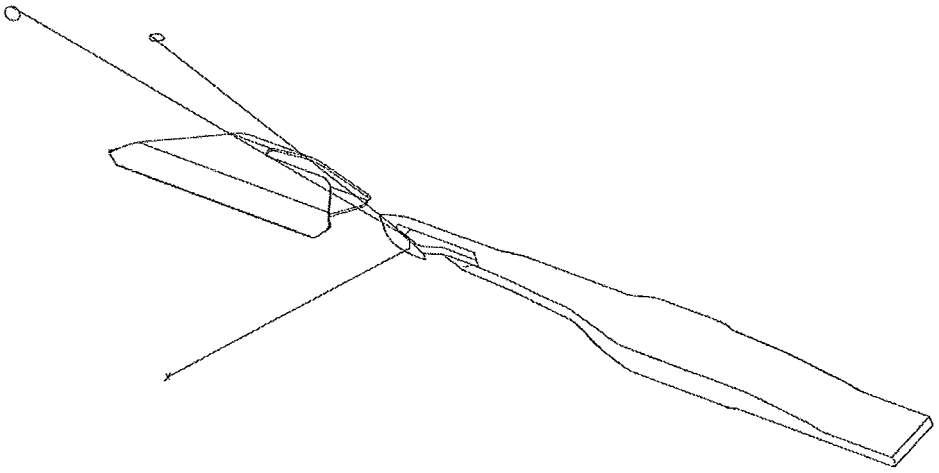

Fig. 5

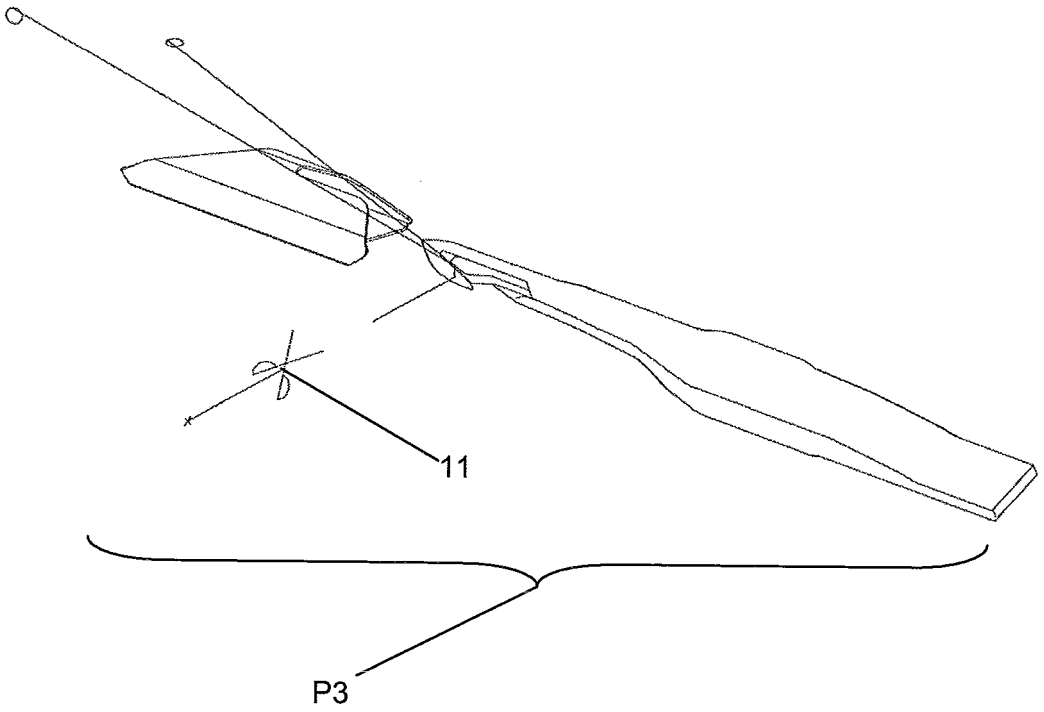

Fig. 6

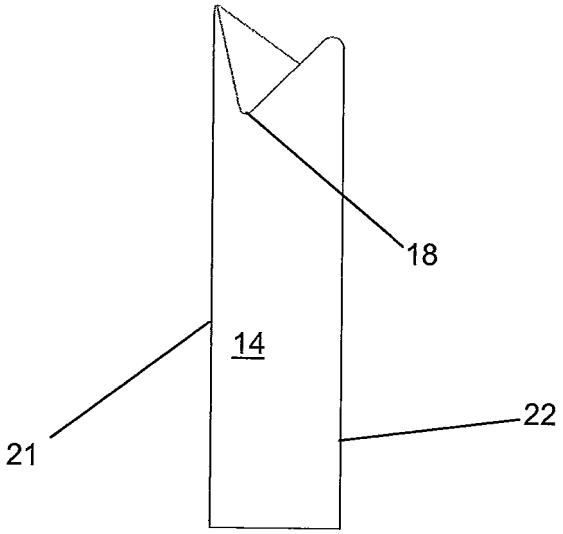

Fig. 7

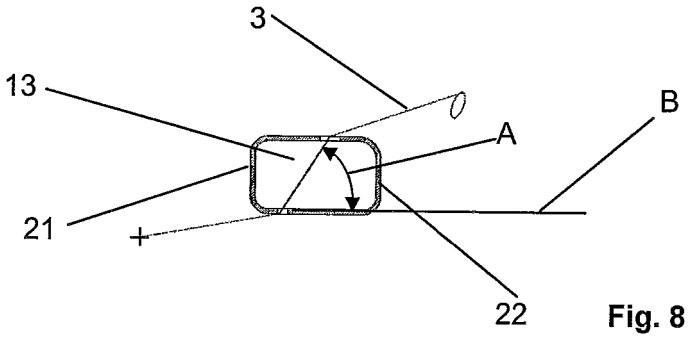

Fig. 8

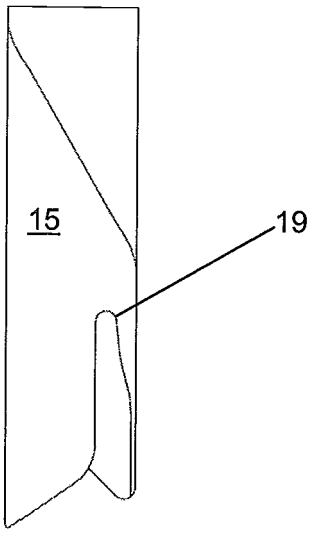

Fig. 9

REFERENCES CITED IN THE DESCRIPTION

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