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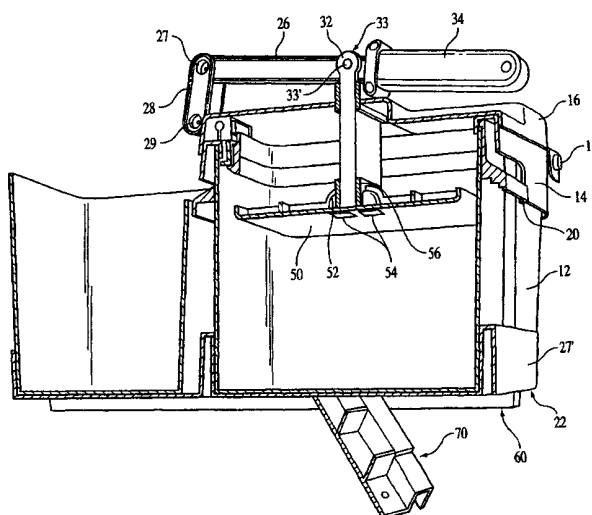
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(54) Title: **MANUAL TRASH COMPACTOR**



(57) Abstract: A manual trash compactor (10) comprising a can (12) for holding the trash, a lever arm (26), at least one coupling arm (28) coupling the lever arm to the can, and a plunging arm (36) connected to the lever arm. There is also a compression plate (50) connected to the plunging arm (36) wherein this compression plate (50) is designed to compress garbage inside the can. Disposed on top of the can is a collar (14) and a cover (16) coupled to the collar. The cover (16) is coupled to the collar (14) via a rotatable hinge (18). In a first embodiment of the invention, the can is disposed in a slidable tray so that the can is able to be stored in a closed compartment. In addition, disposed adjacent to the can in the tray is a bin (24) for storing other materials such as recyclable bottles. Coupled to either the can or the tray is a support element for supporting the can above a surface such as a kitchen floor. In a second embodiment of the invention the trash compactor is designed to be free standing wherein this trash compactor does not sit in a tray and also does not have a support means for supporting the can.

## MANUAL TRASH COMPACTOR

BACKGROUND OF THE INVENTION1. Field of the Invention

5           The invention relates to a manual trash compactor that comprises a can, and a means for the manual compaction of trash attached to the can.

SUMMARY OF THE INVENTION

10           The invention relates to a manual trash compactor that is designed to allow a user to compress his or her trash inside a trash container. This manual trash compactor is designed to allow a user to compress his or her trash without the use of expensive and sometimes faulty machinery.

15           Thus, the invention relates to a manual trash compactor comprising a can for receiving trash, and a means for manually compacting trash housed in the can. This means is attached to the can. There is also means for supporting  
20           this can above a surface.

          In this case, the means for manually compacting trash comprises a compression plate, a plunging arm  
25           connected to the compression plate, and a lever arm coupled to the plunging arm. There is also at least one connecting

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arm for coupling the lever arm to the can. More particularly, the lever arm, the plunging arm and the at least one connecting arm are coupled to each other via a series of hinges. This at least one connecting arm comprises a substantially vertical adjusting arm coupled to the lever arm via a hinge and a connecting arm coupled to the substantially vertical adjusting arm at a first end and coupled to the can at a second end.

10 The compression plate can also be removable from the plunging arm so that it can be more easily cleaned. There is also at least one clip for releasing or securing the compression plate to the plunging arm. In addition, there is a collar for fitting around the can wherein the collar is  
15 removably attached to the can.

Furthermore the compactor also comprises a cover, and a hinge connecting the cover to the collar. So that the cover does not flip open during the compaction of the trash, there is provided a locking means for clamping the cover to the  
20 collar. This locking means comprises a clip attached to the means for manually compacting trash and a flange attached to the collar. In operation, when the means for manually compacting the trash is in a zone for compressing the trash, the clip attaches to the flange to lock the cover to the  
25 collar.

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This trash compactor can be stored in a tray adjacent to a bin. This tray can be used to slide the compactor and the can in and out of a storage compartment. In addition, coupled to the can is a means for supporting the can above a surface such as a kitchen floor.

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In a second embodiment of the invention, there is shown a free standing trash compactor wherein this free standing trash compactor does not contain any means for supporting the can above a surface. In addition, this free standing trash compactor is designed to have a can height that is higher than the trash compactor disposed on the tray.

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Furthermore, the cover on this trash compactor is secured to the collar via a hinge extending along a shortened side of the collar, opposite an open end of the lever arm. With this design, once a user presses down on the lever arm to compact the trash, the collar is held down via the force of the user and would not need to have a clamping means to clamp the cover to the collar.

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In a third embodiment of the invention, there is a free standing trash compactor that has only two rotating arms for driving the trash into the can. With this design there are fewer moving parts so that there is a cost savings from this design.

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BRIEF DESCRIPTION OF THE DRAWINGS

Other objects and features of the present invention will become apparent from the following detailed description considered in connection with the accompanying drawings which disclose three embodiments of the present invention. It should be understood, however, that the drawings are designed for the purpose of illustration only and not as a definition of the limits of the invention.

In the drawings wherein similar reference characters denote similar elements throughout the several views:

FIG. 1 shows a perspective view of the first embodiment of the invention showing the invention from a front-top-right viewpoint;

FIG. 2 shows a side cross-sectional view of the first embodiment of the invention;

FIG. 3 shows a perspective cross sectional view of the first embodiment of the invention;

FIG. 4 shows a perspective view of the first embodiment of the invention showing the invention from a front-bottom-right viewpoint;

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FIG. 5 shows a perspective view of the first embodiment of the invention showing the invention from a back-top-right viewpoint;

5        FIG. 6 shows a perspective view of the second embodiment of the invention;

FIG. 7 shows a cross-sectional view of the second embodiment invention shown in FIG. 6;

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FIG. 8 shows a perspective view of the third embodiment of the invention; and

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FIG. 9 shows a cross-sectional view of the third embodiment of the invention shown in FIG. 9.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

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FIG. 1 refers to a perspective view of the first embodiment of the invention which is manual trash compactor 10 for storable trash cans. With this view, there is shown a garbage can 12, while attached to garbage can 12 is a

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collar 14 which connects to a cover portion 16. Collar 14 contains a peripherally extending rim 14' that is designed to wrap around garbage can 12. Collar 14 rests upon garbage can 12, while cover 16 is secured to collar 14 via a hinge

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18.

Collar 14 contains a flange 14' that extends around can 12. There is an opening 14'' in collar 14 that allows a collapsible flange 20, attached to can 12, to enter there-  
5 through. Collapsible flange 20 collapses down when collar 14 is placed over can 12 and then snaps out through opening 14' when collar 14 is secured on can 12. Collar 14 is also designed so that a plastic bag (not shown) can be placed in  
10 can 12, over a series of top edges of can 12. In this way, once collar 14 is secured over can 12, it locks the plastic bag in place until collar 14 is removed from can 12. Can 12 rests in a tray 22 and is positioned adjacent to a bin 24. Bin 24 can be used to receive recyclable materials such as  
15 cans, bottles etc.

Tray 22 is designed as a slidable tray that allows can 12 to be pulled out of a cabinet or closed space on a track (not shown). This tray 22, is designed to be substantially  
20 rectangular in shape with side flanges 22' extending up from a bottom plate 22''. These side flanges 22' are designed to hold can 12 and bin 24 together on one tray.

In a top region of collar 14 is a compacting means  
25 wherein there is shown a lever arm 26, a substantially vertical adjusting arm 26 connected to lever arm 24, and a

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connecting arm 30 connected to adjusting arm 26. Each of these arms 26, 28, and 30 is connected to each other via a hinge. For example hinge 27 connects arm 26 to arm 28 while hinge 29 connects arm 28 to arm 30. Finally, hinge 31 connects arm 30 to cover 16. With these three arms all joined by hinges, the crushing arm mechanism allows a user to have enough leverage to compress the garbage without the use of complicated machinery.

Lever arm 26 connects to a plunging arm connecting region 32 of plunging arm 36 via a hinge 33 (See FIG. 2). There is also disposed on lever arm 26 a handle 34 that is optionally slidable to give a user more leverage when compressing his or her garbage in can 12. As lever arm 26 is compressed down, it moves into a recessed region 35 within collar 14. Recessed region 35 is a region designed to allow lever arm 26 and handle 34 to fit down into cover 16 giving lever arm 26 more room to rotate.

As shown in FIG. 2, there is a cross sectional view of the first embodiment of compactor 10 wherein this view shows the connection between lever arm 26 and plunging arm 36. Here, connecting region 32 formed by plunging arm 36, lever arm 26, and a tie rod 33' all connect around hinge 33 which allows lever arm 26 to drive plunging arm 36 down into can 12.



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In addition, as lever arm 26 is being driven down (See FIG.7) clip 37, which is attached to connecting arm 30 rotates into flange 38 disposed inside of can 12. Flange 38 is essentially a portion of collar 14 disposed on an inside region of can 12. Here, flange 38 is designed to lock with clip 37 so that it clamps the crushing arm mechanism to collar 14.

In addition, as shown in Fig. 2, there are also guides 39 that are designed to guide plunging arm 36 into the can. These guides 39 are designed to guide plunging arm 36 in a straight line so that it drives into the garbage in can 12.

Attached to plunging arm 36, is a compression plate 50 that contains a support flange 52 that wraps around compression plate 50. Here, support flange 52 is designed to provide lateral stability to compression plate 50 so that compression plate 50 does not alter its orientation while compressing garbage in can 12.

Compression plate 50 can be removed from plunging arm 36 so that compression plate 50 can be easily cleaned. As shown in FIG. 3, compression plate 50 contains a series of holes 54 that are designed to receive a series of clips 56 that extend through holes 54. With this design, a user can pinch clips 56 so that when these clips 56 are pinched,

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compression plate 50 can be easily removed from plunging arm 36. Once compression plate 50 has been cleaned, it can then be reinserted onto plunging arm 36 by pinching clips 56 and then inserting plate 50 onto plunging arm 36.

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FIG. 4 shows a perspective view of manual compactor 10 wherein there is shown a series of guide rails 60 that are attached to tray 24. Guide rails 60 are designed to facilitate the sliding of tray 24 in and out of a storage compartment. Extending out from tray 24 is an adjustable support leg 70 that contains a top section 72 and a bottom section 74. Bottom section 74 can be semi-permanently extended out from top section 72 so as to fit the appropriate length of support from the bottom of tray 24 to a floor. Support leg 70 can be either folded down or folded up depending on whether a user is storing compactor 10 or pulling compactor 10 out of its storage compartment for use.

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This support leg 70 is adjustable in length via a wing nut 80 that is attached to a bolt (not shown). Essentially an inside region of top section 72 and bottom section 74 each have a sawtooth region (not shown) where these sections meet. As wing nut 80 is clamped down, these saw-toothed regions match together to fix top section 72 and bottom section 74 in place.

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With this design, compactor 10 can be supported in a stable position while extended out from its storage compartment. In this way, as lever arm 26 is pushed down (See FIG. 7), there is additional support from support leg 70 which counteracts the downward pressure exerted from lever arm 26.

FIG. 5 shows a perspective view of compactor 10, wherein from this view, there is shown a hinge 18 that comprises a hinge flange 19, connected to collar 14, and a hinge plug 19' that extends through hinge flange 19. Hinge 18 allows top cover 16 to fold up from collar 14. In this way, top cover will open up to allow an individual to insert garbage into can 12. So that top cover 16 does not flip open during the compacting stage, clip 37 (See FIG. 2) is latched to flange 38 during this process. In addition, with this design, cover 16 can be designed to open from a reverse position. For example as shown in FIG. 5, this design is for a compartment having a door with a hinge on its left side. However, if an individual wanted to place this compactor 10 inside a door having a hinge on its right-hand side then cover 16 can be molded to have hinge flanges 19 on the opposite side. Collar 14 could then be rotated 180 degrees so that cover 16 could be attached on the opposite side.

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Can 12, collar 14 and cover 16 are all assembled as interconnected components that are removable from each other. With this first embodiment, as shown in FIGS. 1-5 collar 14 fits over can 12 and is secured to can 12 via flange 20 that fits through an opening 14''. Once flange 20 snaps out from opening 14'' it fastens collar 14 to can 12. Since can 12 has two flanges 20 on opposite ends of can 12, these flanges allow collar 14 to be attached securely to can 12. In addition, cover 16 is secured on at least one edge of collar 14 via a hinge 18. So that cover 16 is securely fastened to collar 14, clip 37 is provided to stop hinge 18 from rotating, thus keeping cover 16 from rotating away from collar 14. Thus, with this design, all of these components, can 12, collar 14, and cover 16 can either be detached from each other, or securely fastened to each other depending on the user's needs.

FIG. 6 shows a perspective view of the second embodiment of the invention. Here, this design differs from the first embodiment because can 112 has a greater height than can 12 (FIG. 1) and this can 112 no longer sits in tray 22. This second embodiment 110 is essentially a free standing version of compactor 10. Here, collar 114 secures over can 112, while cover 116 is hingeably attached to collar 114. With this design, hinge 118 differs in placement from hinge 18. Hinge 118 is secured to a shorter

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side of rectangular shaped can 112. Hinge 118 is designed to allow cover 116 to flip up off of collar 114 to allow a user to place garbage inside of can 112.

5           Cover 116 is automatically secured down to collar 114 because of the momentary force exerted on lever arm 126 in the non-hinged region of cover 116 which is opposite hinge 118. Therefore, as shown in FIG. 7, no clips are necessary to secure cover 116 to collar 114.

10           FIG. 7 shows the movement of lever arm 126 as a user compacts garbage. So that a user would have leverage in compacting the garbage, the user would grab onto an end of lever arm 126, opposite hinge 127, and press down on lever  
15           arm 126. This downward force causes lever arm 126 to rotate about hinge 127. Hinge 127 connects lever arm 126 to substantially vertical adjusting arm 128. Adjusting arm 128 also rotates about hinge 130 so that as lever arm 126 rotates clockwise and down during compaction of the garbage,  
20           adjusting arm 128 also rotates clockwise. Adjusting arm 128 also connects to connecting arm 130 at hinge 129 wherein connecting arm 130 then connects to cover 116 on collar 114 via hinge 131. With this design there are three arms 126, 128 and 130 that rotate and adjust simultaneously while the  
25           garbage is being compacted.

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Because arms 126, 128, and 130 and plunging arm 136 are all adjusting simultaneously, about hinges 127, 129, 131, and 133, plunging arm 136 can maintain a straight line path into can 112. This straight line path is controlled by guides 139 which force plunging arm 136 to travel in this straight line path. In addition, so that plunging arm 136 does not become impinged on guides 139, arms 128 and 130 rotate in a clockwise manner as lever arm 126 rotates down. The rotation of arms 128 and 130 allow lever arm 126 to move axially as well as radially about hinge 127. This axial movement of lever arm 126 results in a substantially vertical downward force on plunging arm 136 which also results in a straight line path. Ultimately this straight line path is important because compression plate 150 retains its orientation as substantially parallel with an opposing surface of can 112. This orientation of compression plate 150 results in a substantially uniform compression of garbage inside can 112.

FIG. 8 shows a third embodiment of the present invention. This embodiment is similar to the embodiment shown in FIG. 6, however, in this embodiment there are only two lever arms 128 and 126 which are used. As shown in FIG. 9, lever arm 126 connects to vertical adjusting arm 128 via hinge 127. Vertical adjusting arm 128 connects to cover 116 via hinge 129. As shown, there is also no clip 137 that

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attaches an adjusting arm to collar 114 to secure cover 116 to collar 114. Rather, with this design, the cover is secured at one end via a hinge 118 that is positioned along a short edge of can 112 while the moment force on lever arm 126 holds the opposite edge of cover 116 down.

As shown in FIG. 9, the movement of lever arm 126 causes the downward movement of plunger 136. In addition, this movement down of lever arm 126 can also cause the rotation of adjusting arm 128 in a clockwise manner. Because adjusting arm 128 rotates in a clockwise manner, lever arm 126 moves axially as it rotates about hinge 127. This axial movement of lever arm 126 keeps the force created by pressing down on lever arm 126 substantially vertical which allows plunging arm 136 to travel in a substantially straight line into can 112.

With this design, the contents inside can 112 can still be crushed without using the additional arm 130 shown in FIGS. 1-7 which leads to an additional cost savings because fewer parts are used.

Accordingly, while three embodiments of the present invention have been shown and described, it is to be understood that many changes and modifications may be made thereunto without departing from the spirit and scope of the invention as defined in the appended claims.

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WHAT IS CLAIMED IS:

1. A manual trash compactor comprising:

5 a) a can for receiving trash;

b) means for manually compacting trash in said can said means being attached to said can; and

10 c) means for supporting said can above a surface, said means being coupled to said can.

2. The manual trash compactor as in claim 1, wherein said means for manually compacting trash comprises a  
15 compression plate, a plunging arm connected to said compression plate, a lever arm coupled to said plunging arm and at least one connecting arm for coupling said lever arm to said can.

20 3. The manual trash compactor as in claim 2, wherein said lever arm, said plunging arm and said at least one connecting arm are each coupled to each other via a hinge.

25 4. The manual trash compactor as in claim 2, wherein said at least one connecting arm comprises a substantially vertical adjusting arm coupled to said lever arm via a hinge



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and a connecting arm coupled to said substantially vertical adjusting arm at a first end via a hinge and coupled to said can via a hinge at a second end.

5           5. The manual trash compactor as in claim 2, wherein said compression plate is removable from said plunging arm.

10           6. The manual trash compactor as in claim 5, further comprising at least one clip for releasing or securing said compression plate to said plunging arm.

15           7. The manual trash compactor as in claim 1, further comprising a collar for fitting around said can wherein said collar is removably attached to said can.

8. The manual trash compactor as in claim 7, further comprising a cover, and a hinge connecting said cover to said collar.

20           9. The manual trash compactor as in claim 8, further comprising a locking means for clamping said cover to said collar when said means for manually compacting trash is compacting the trash.

25           10. The manual trash compactor as in claim 8, wherein said locking means comprises a clip attached to said means

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for manually compacting trash and a flange attached to said collar wherein when said means for manually compacting said trash is in a zone for compressing said trash said clip clips on to said flange to lock said cover to said collar.

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11. A manual trash compactor comprising:

a can for housing trash;

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at least one lever arm rotatably coupled to said can;

at least one plunging arm coupled to said at least one lever arm;

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at least one compaction plate coupled to said plunging arm wherein said trash is compacted in said can when said lever arm is pushed down.

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12. The manual trash compactor as in claim 11, further comprising at least one coupling arm coupling said lever arm to said can.

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13. The manual trash compactor as in claim 12, further comprising at least one additional coupling arm coupling said at least one coupling arm to said can.

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14. The manual trash compactor as in claim 12, further comprising a cover coupled to said can wherein said at least one connecting arm is coupled to said cover.

5           15. The manual trash compactor as in claim 14, further comprising a collar coupled to said can wherein said collar is coupled to said cover.

10           16. The manual trash compactor as in claim 15, wherein said collar is coupled to said cover via a hinge.

17. The manual trash compactor as in claim 15, wherein said collar is coupled to said can via a releasable catch.

15           18. The manual trash compactor as in claim 15, wherein said collar has a flange that extends around an inner region of said can.

20           19. The manual trash compactor as in claim 18, further comprising a clip, attached to said cover, wherein said clip contacts to said flange to secure said cover to said collar when said compaction plate is in a region for compressing said trash.

25           20. The manual trash compactor as in claim 11, wherein said at least one compaction plate is removable from said

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plunging arm.

21. The manual trash compactor as in claim 11, further  
comprising a support leg for supporting said can above a  
5 surface.

22. The manual trash compactor as in claim 11, further  
comprising a tray for housing said can.

10 23. The manual trash compactor as in claim 21, further  
comprising a support leg coupled to said tray for supporting  
said tray above a surface.

15 24. The manual trash compactor as in claim 23, wherein  
said support leg is adjustable in length.

## AMENDED CLAIMS

[received by the International Bureau on 3 May 2001 (03.05.01);  
new claims 25-30 added; remaining claims unchanged (3 pages)]

21. The manual trash compactor as in claim 11, further comprising a support leg for supporting said can above a surface.

22. The manual trash compactor as in claim 11, further comprising a tray for housing said can.

23. The manual trash compactor as in claim 21, further comprising a support leg coupled to said tray for supporting said tray above a surface.

24. The manual trash compactor as in claim 23, wherein said support leg is adjustable in length.

25. A manual trash compactor comprising:

a can;

at least one adjusting arm rotatably coupled to a top portion of said can;

at least one lever arm rotatably coupled to said at least one adjusting arm;

at least one plunging arm coupled to said at least one lever arm; and

at least one compression plate coupled to said plunging arm wherein said trash is compacted in said can when said lever arm is pushed down.

26. The manual trash compactor as in claim 25, further comprising a cover coupled to a top portion of said can wherein said at least one adjusting arm is coupled to said cover.

27. The manual trash compactor as in claim 26, further comprising a first hinge rotatably coupling said at least one adjusting arm to said at least one lever arm and a second hinge rotatably coupling said at least one adjusting arm to said can.

28. The manual trash compactor as in claim 25 wherein said at least one adjusting arm is substantially straight.

29. A manual trash compactor comprising:

a can;

at least one cover releaseably coupled to said can;

at least one adjusting arm rotatably coupled to said at least one cover;

at least one lever arm rotatably coupled to said at least one adjusting arm;

at least one plunging arm coupled to said at least one lever arm; and

at least one compression plate coupled to said plunging arm wherein said trash is compressed in said can when said lever arm is pushed down.

30. The manual trash compactor as in claim 29, further comprising a collar coupled to said can and a hinge, wherein said at least one cover is coupled to said collar via said hinge.

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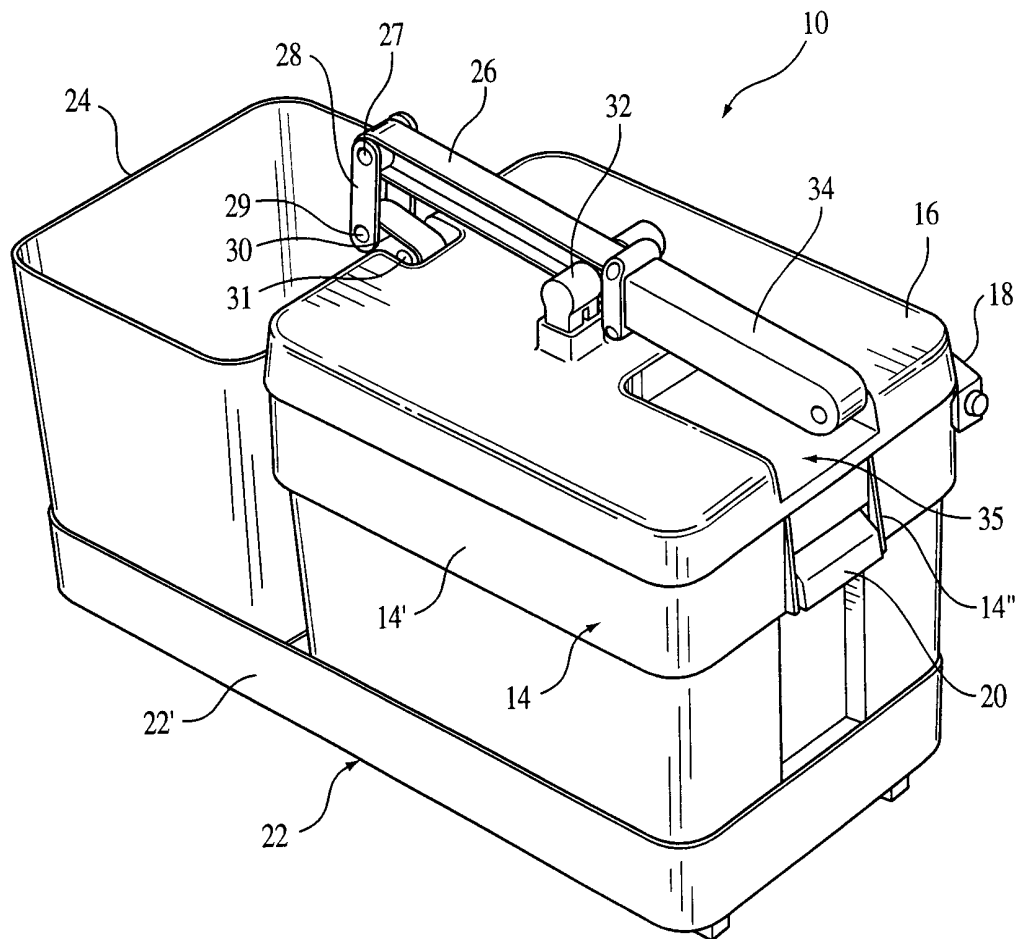


FIG. 1





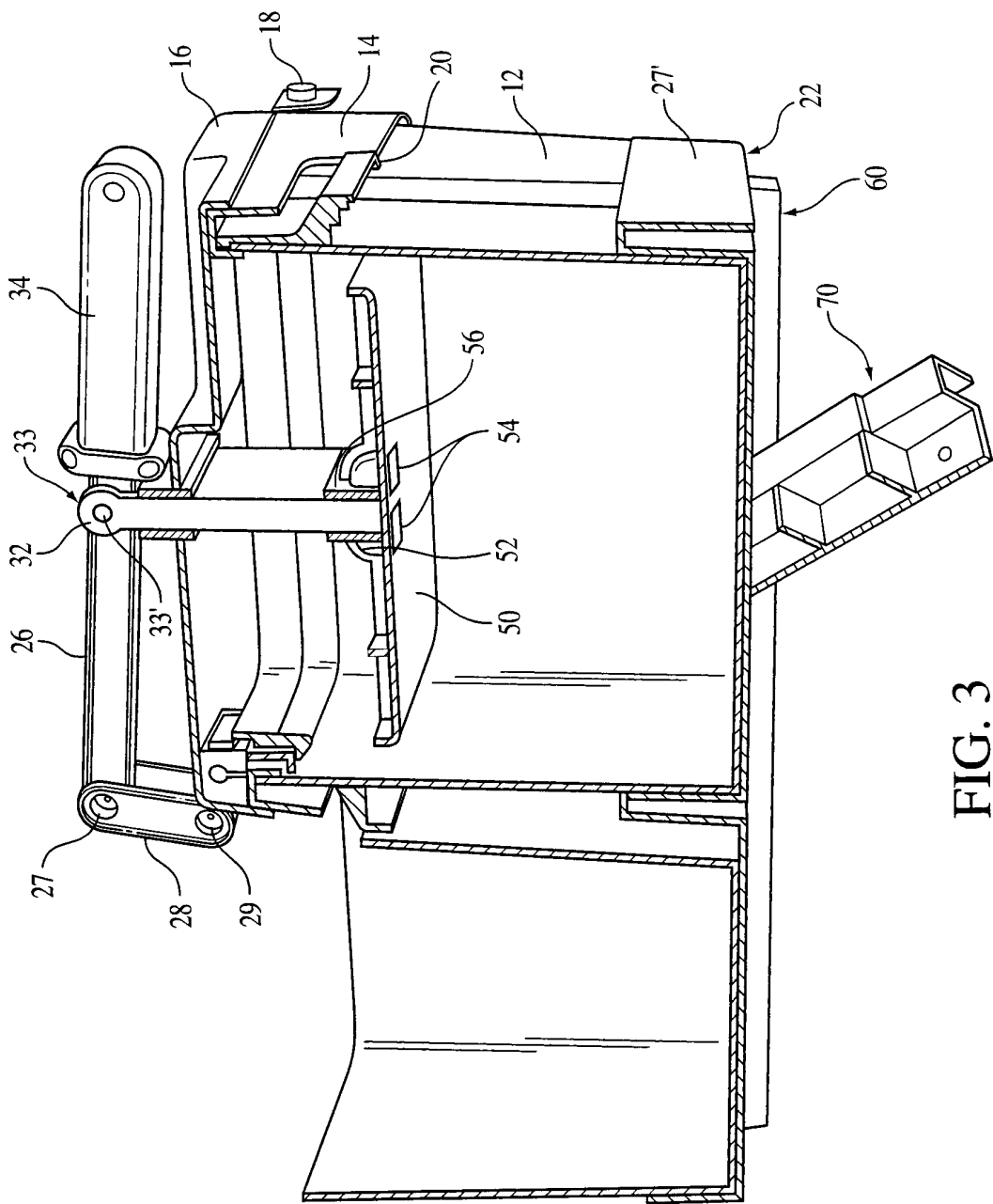


FIG. 3

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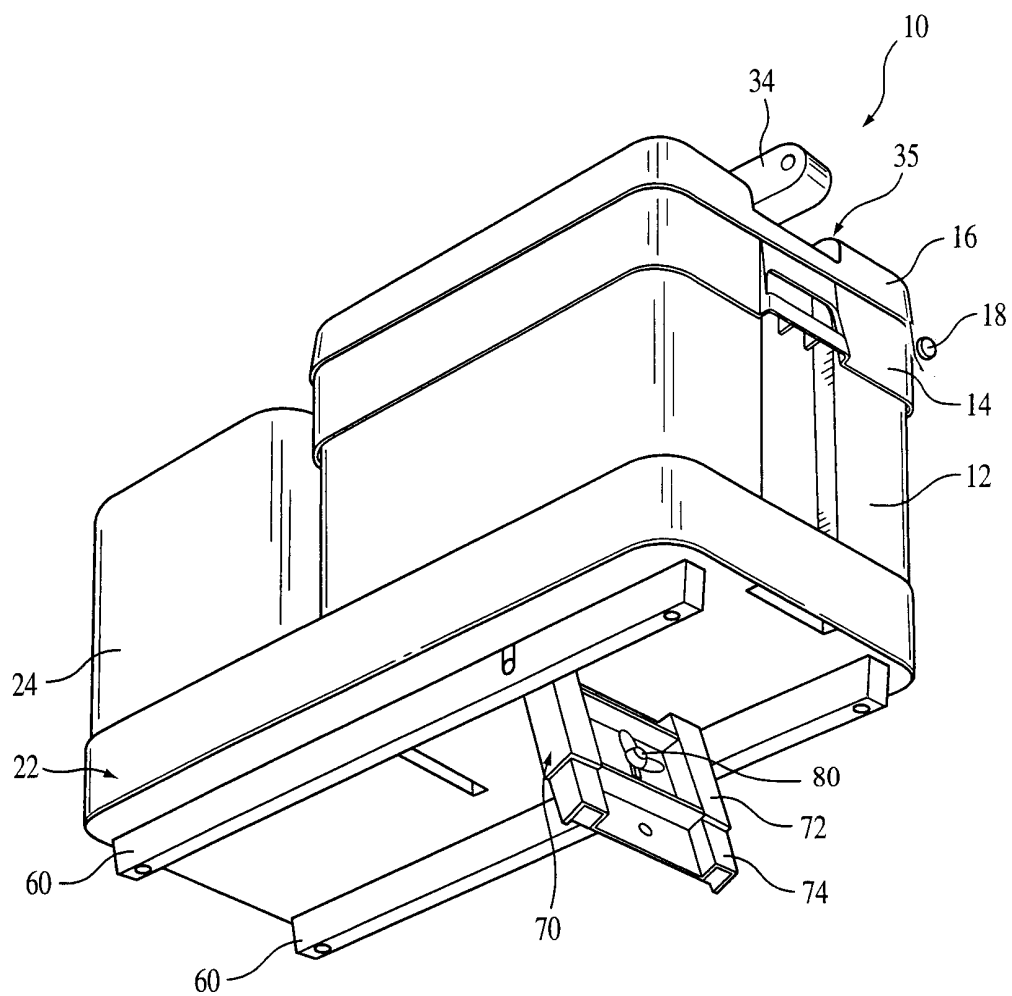


FIG. 4

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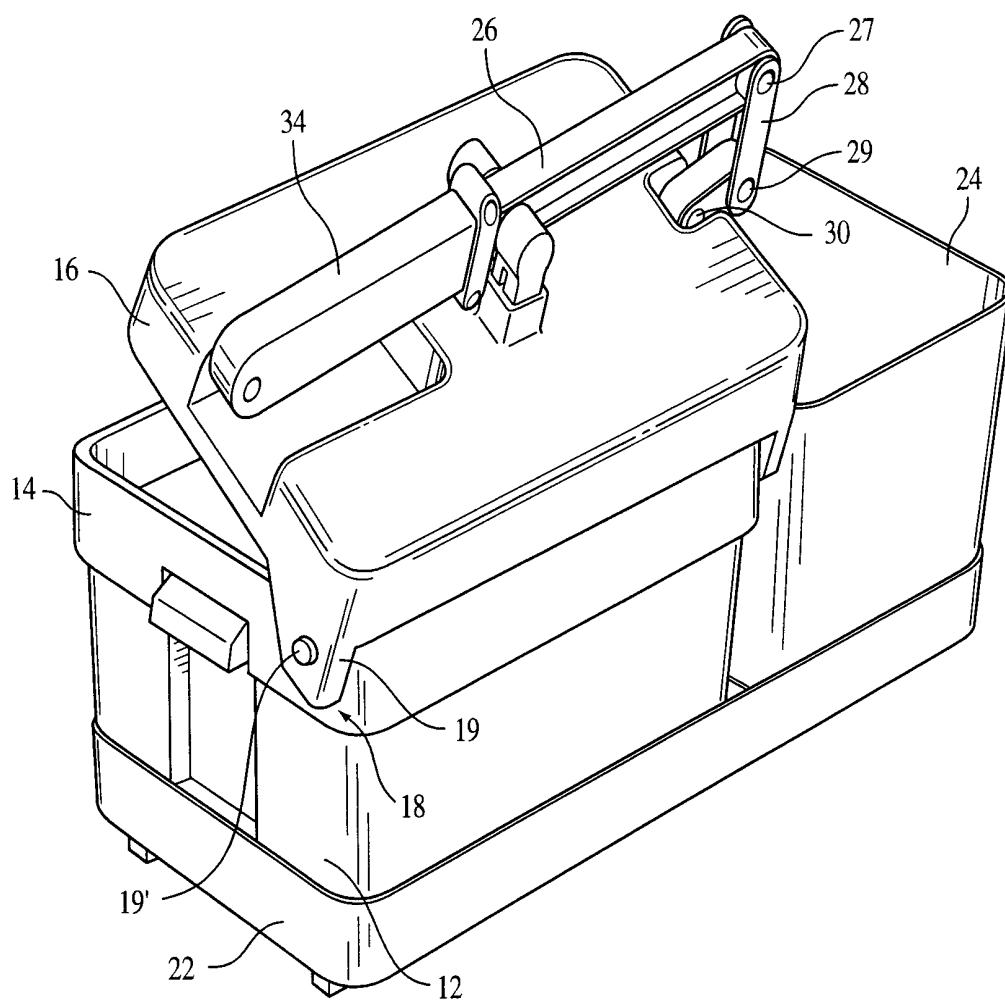


FIG. 5

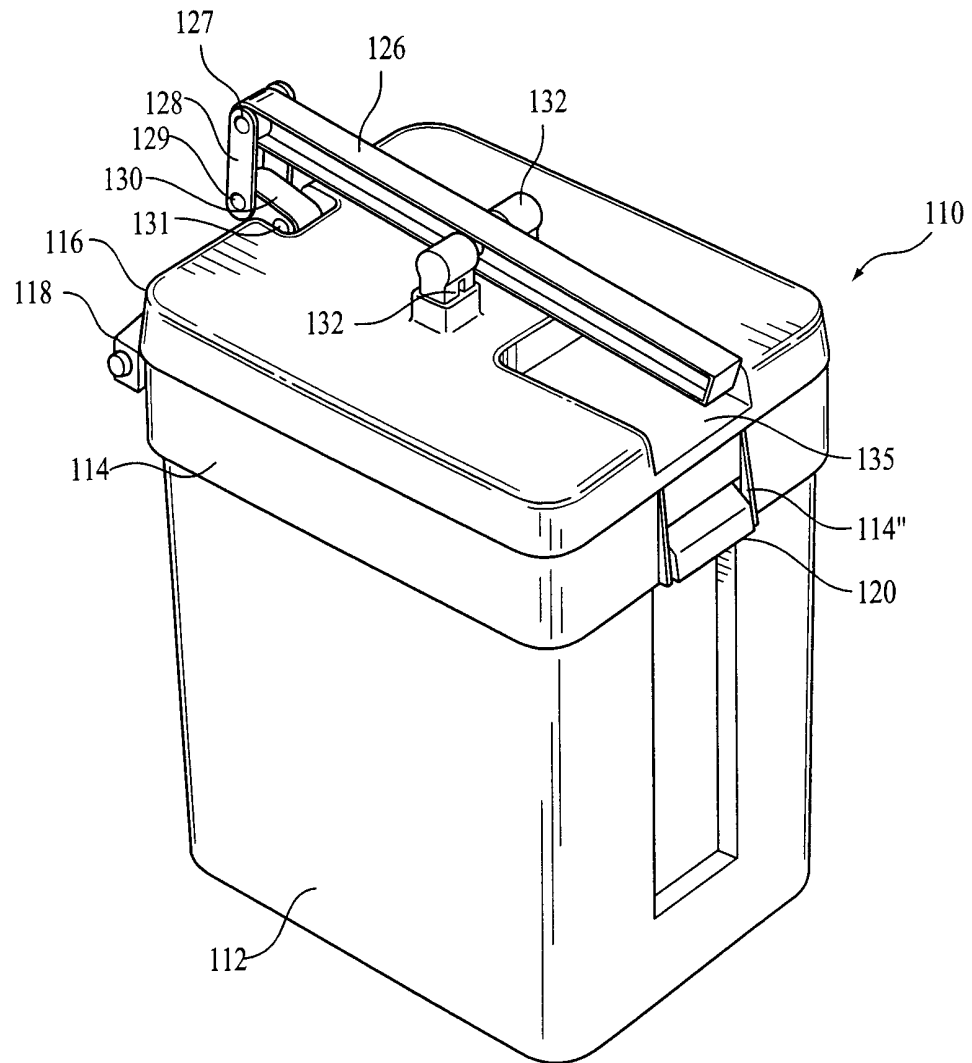


FIG. 6

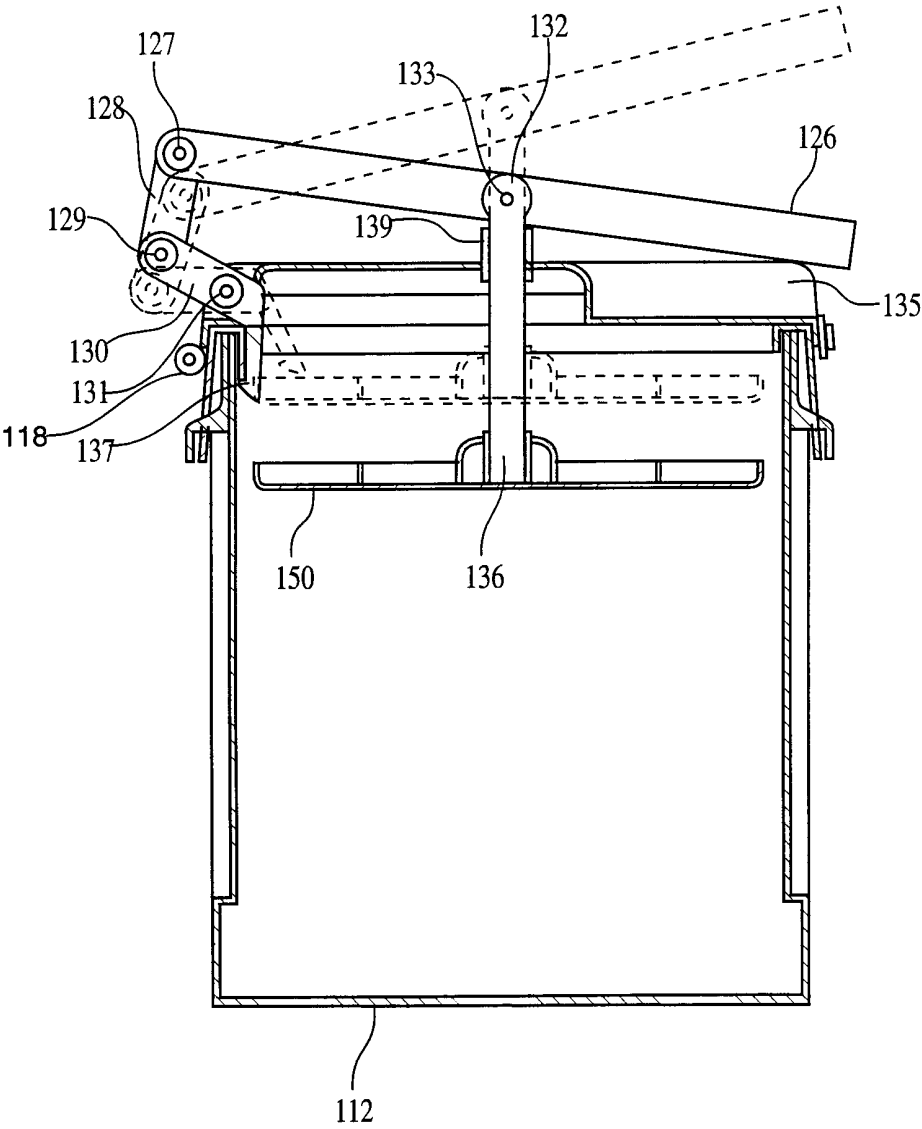


FIG. 7

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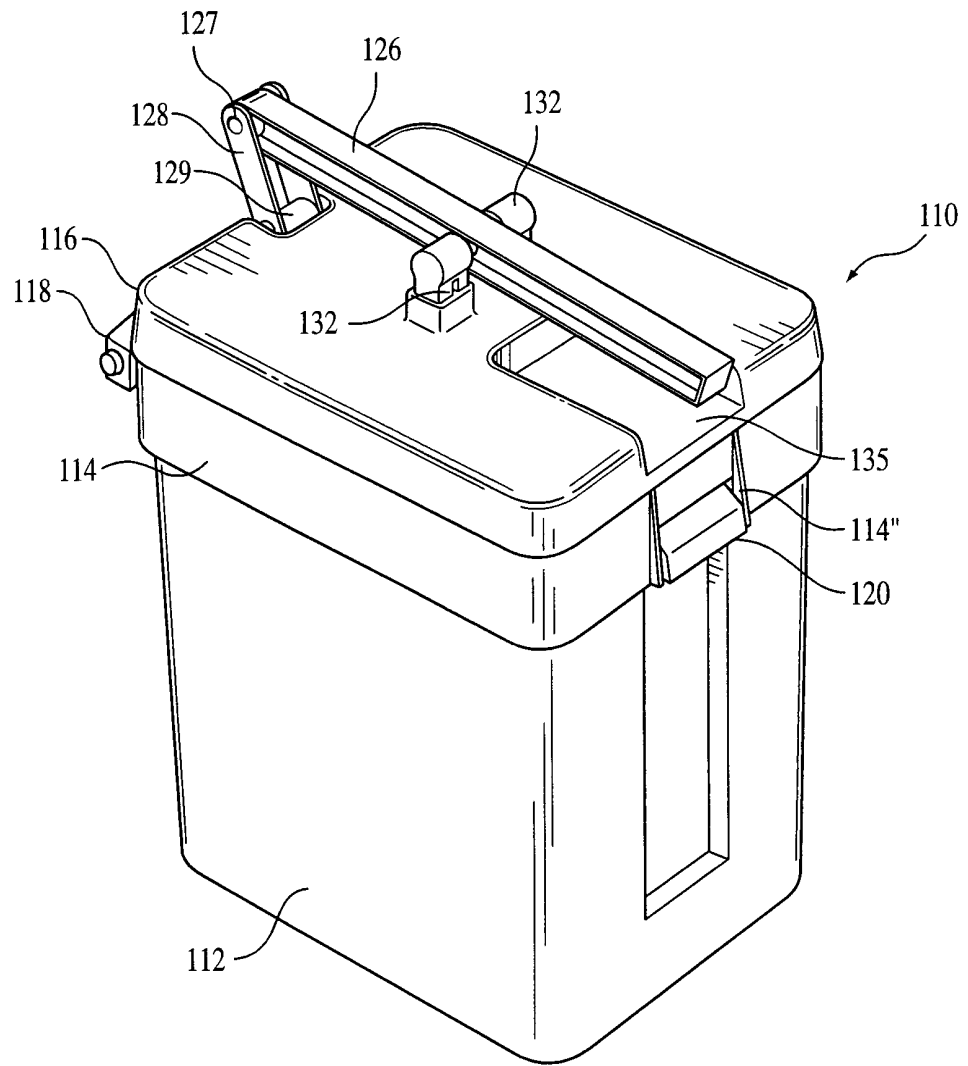


FIG. 8

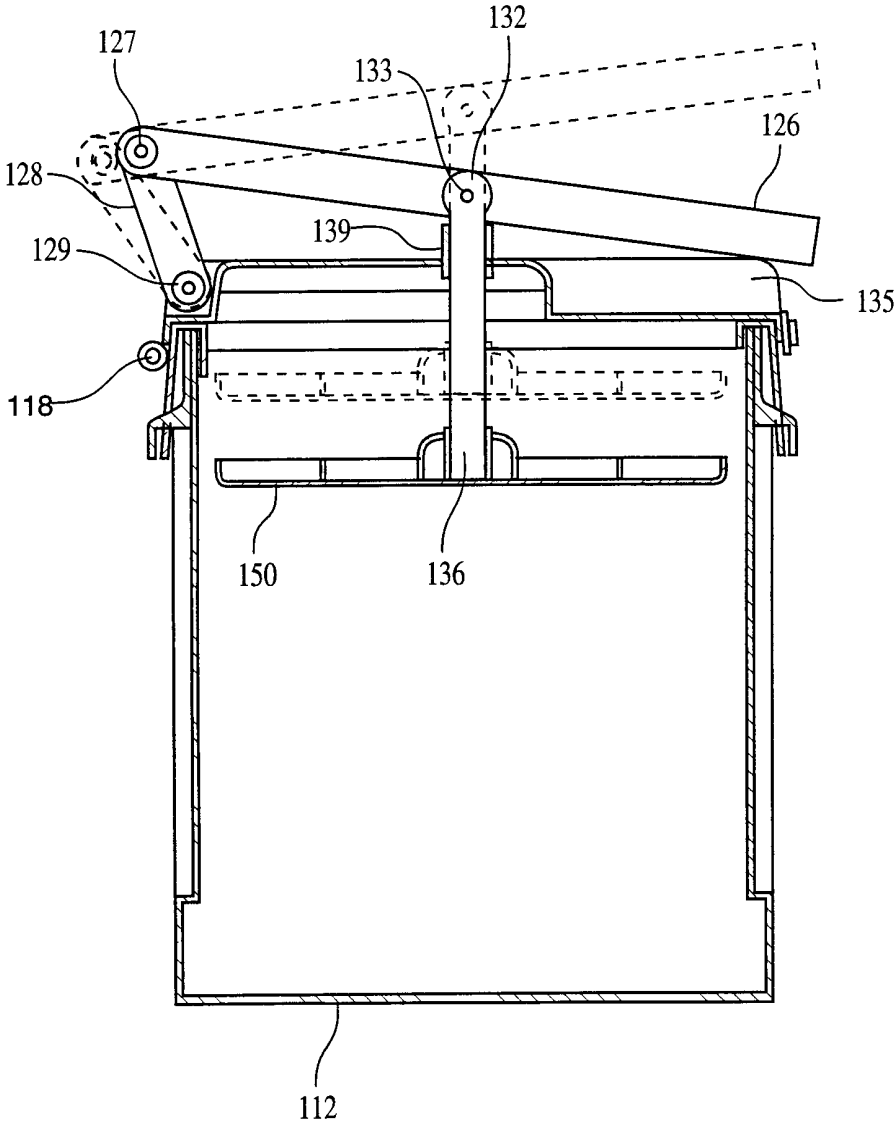


FIG. 9



# INTERNATIONAL SEARCH REPORT

International Application No  
PCT/US 00/31703

## A. CLASSIFICATION OF SUBJECT MATTER

IPC 7 B65F1/14

According to International Patent Classification (IPC) or to both national classification and IPC

## B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)  
IPC 7 B65F B30B

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

EP0-Internal

## C. DOCUMENTS CONSIDERED TO BE RELEVANT

| Category * | Citation of document, with indication, where appropriate, of the relevant passages                                     | Relevant to claim No. |
|------------|------------------------------------------------------------------------------------------------------------------------|-----------------------|
| X          | AT 403 370 B (CONTAINER SYSTEMS GMBH)<br>26 January 1998 (1998-01-26)<br>figures 11,12<br>---                          | 1-3,11,<br>21         |
| X          | NL 8 501 293 A (UNIMETA NEDERLAND B V)<br>1 December 1986 (1986-12-01)<br>figure 10<br>---                             | 11,12                 |
| X          | US 5 730 047 A (LINDSEY H WAYNE)<br>24 March 1998 (1998-03-24)<br>figure 6<br>---                                      | 1,11<br>20            |
| Y          | US 5 619 915 A (WAGNER WILLIAM E ET AL)<br>15 April 1997 (1997-04-15)<br>column 3, line 57 - line 61; figure 10<br>--- | 20                    |
|            | -/--                                                                                                                   |                       |

☒ Further documents are listed in the continuation of box C.

☒ Patent family members are listed in annex.

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Date of the actual completion of the international search

21 February 2001

Date of mailing of the international search report

06/03/2001

Name and mailing address of the ISA

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# INTERNATIONAL SEARCH REPORT

International Application No

PCT/US 00/31703

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