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- (71) **Applicant:** **SOFTWARE MOTOR CORPORATION** [US/US]; 1295 Forgewood Avenue, Sunnyvale, CA 94089 (US).
- (72) **Inventors:** **KRISHNAMURTHY, Mahesh**; 1295 Forgewood Avenue, Sunnyvale, CA 94089 (US). **CREARY, Trevor**; 1295 Forgewood Avenue, Sunnyvale, CA 94089 (US). **JOHNSTON, Mark**; 1295 Forgewood Avenue, Sunnyvale, CA 94089 (US). **DESAI, Piyush**; 1295 Forgewood Avenue, Sunnyvale, CA 94089 (US).
- (74) **Agent:** **TEMMERMAN, Mathew, J.**; Temmerman Law Office, 36th Floor, One Market Street, Spear Tower, San Francisco, CA 94105 (US).
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[Continued on next page]

(54) **Title:** MIRRORING OF HIGH ROTOR POLE SWITCHED RELUCTANCE MACHINES

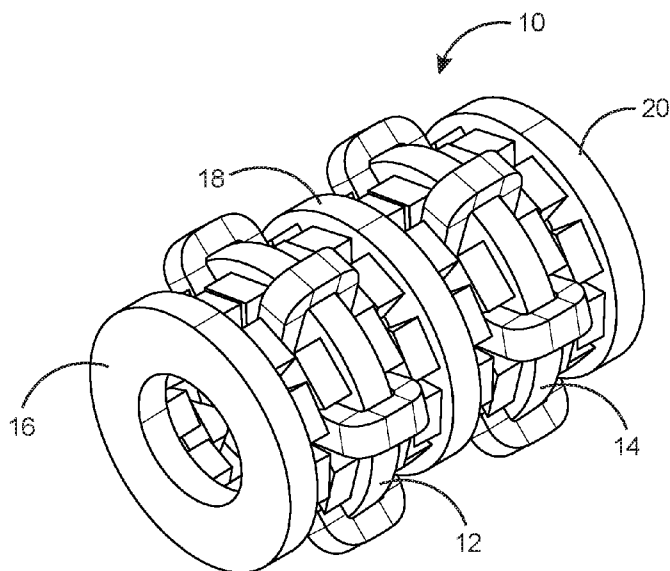


FIG. 1

(57) **Abstract:** A high rotor pole switched reluctance machine (HRSRM) employs an axial and radial mirroring concept and is represented by a first Multiple Rotor Pole (MRP) formula and second Multiple Stator Pole (MSP) formula. A multiple rotor HRSRM comprises at least two rotors each having a plurality of rotor poles and at least one stator having a plurality of stator poles. The at least two rotors and the at least one stator are positioned about a central axis with the stator placed between, and laterally adjacent to the rotors. A multiple stator HRSRM comprises at least two stators having a plurality of stator poles and at least one rotor having a plurality of rotor poles. The at least two stators and at least one rotor are positioned about a central axis with the rotor placed between and laterally adjacent to the stators.



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MIRRORING OF HIGH ROTOR POLE SWITCHED RELUCTANCE MACHINES

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RELATED APPLICATIONS

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[0001] This application claims priority from the United States provisional application with Serial Number 62/173,395, which was filed on June 10, 2015. The disclosure of that provisional application is incorporated herein as if set out in full.

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BACKGROUND OF THE DISCLOSURE

TECHNICAL FIELD OF THE DISCLOSURE

[0002] The present disclosure relates in general to high rotor pole switched reluctance machines. More specifically, the present disclosure relates to mirroring of high rotor pole switched reluctance machines using multiple rotors and stators.

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DESCRIPTION OF THE RELATED ART

[0003] A switched reluctance machine (SRM) is a type of synchronous machine, which can operate as a motor or a generator. Though there are no major differences in construction, an SRM operates as a generator when used to convert mechanical energy into electrical energy or as a motor, when used to convert electrical energy into mechanical energy. Typically, an SRM can be operated in both modes in a cycle. Hence, hereinafter, we shall use the term "machine" instead of motor and/or generator to include both of these operating modes.

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[0004] SRMs typically include a stator having a plurality of salient stator poles and a rotor having a plurality of salient rotor poles. There are phase windings on the stator, but there are no windings or magnets on the rotor. In most SRMs, each pair of diametrically opposite stator poles is connected in series to form an independent phase

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of the multiphase switched reluctance machine. In some cases, the stator has coil windings 90° apart connected in series to form one phase. During operation of the SRM, each of the stator poles are successively excited in a predetermined sequence that is synchronized with the angular position of the rotor to generate a magnetic attraction
5 force between the stator poles and corresponding rotor poles to rotate the rotor.

[0005] A high rotor pole switched reluctance machine (HRSRM) is an SRM where the number of rotor poles is higher than the number of stator poles for any adjacent set of rotor and stator. Alternately, it can be defined as a machine with multiple rotors and stators where the sum of the number of rotor poles from all individual rotors
10 is higher than the sum of the number of stator poles from all individual stators. An HRSRM has a higher static torque capability and lower torque ripples compared to a conventional SRM. The design requirements of the power converters of these two machines can be different, because an HRSRM has a narrower inductance profile and a higher number of strokes than other configurations with the same number of phases.

[0006] One such conventional SRM describes a switched reluctance apparatus having an inner stator having a plurality of poles, a rotor disposed radially outward of the inner stator and having a plurality of segments serving as poles, and an outer stator disposed radially outward of the rotor and having a plurality of poles. A respective winding is disposed between every pair of adjacent poles of either stator. The apparatus
20 operates with a plurality of separately excitable phases, wherein a given phase is excited by energizing the windings corresponding to the given phase. Excitation of a given phase causes induction of magnetic fluxes traversing a region substantially confined to the region of the stators and rotor segments corresponding to the given phase, and causes a substantial amount of flux to enter rotor segments. However, the apparatus does not
25 teach the mirroring of multiple rotors and stators.

[0007] Few other SRMs employing double rotors and double stators have been developed. Some SRMs include a double-rotor switched reluctance motor comprising an outer rotor, a middle stator and an inner rotor, wherein the middle stator is arranged between the inner rotor and the outer rotor, and the inner and outer rotors are
30 mechanically fixed together and rotate synchronously so as to form a fixed mechanical output shaft. Some other SRMs include an electrical machine comprising a first stator, a second stator, and a rotor arranged between the first and second stators. The rotor

comprises a plurality of rotor poles magnetically isolated from each other in the circumferential direction of the rotor. By arranging a rotor between two stators, the rotor does not necessarily need to carry magnetic flux in a circumferential direction, and consequently a lighter rotor construction may be used. The rotor poles are configured to
5 carry magnetic flux in two opposite directions in order to be able to utilize a reluctance principle and give all the rotor poles an identical construction. However, such SRMs do not teach the mirroring of multiple rotors and stators. Further, none of the above mentioned SRMs come under the category of high rotor pole SRM.

[0008] Therefore, there is a need for a high rotor pole switched reluctance
10 machine (HRSRM) that would employ a mirroring concept. The needed HRSRM would be configured to mirror multiple numbers of stators and rotors. Further, the HRSRM would be able to apply the mirroring concept either radially or axially. Such a needed HRSRM would increase the power density and torque density and lower the torque ripples of the machine. Finally, the HRSRM would be designed by a pole definition
15 formula that includes both multiple rotors and multiple stators. The embodiment disclosed herein accomplishes all of these objectives.

SUMMARY OF THE DISCLOSURE

[0009] To minimize the limitations found in the prior art, and to minimize other limitations that will be apparent upon the reading of this specification, the preferred embodiment of the present invention provides a high rotor pole switched reluctance machine (HRSRM) using a mirroring concept and discloses two specific formulas which shall be referred to as a Multiple Rotor Pole (MRP) formula and a Multiple Stator Pole (MSP) formula. The mirroring concept can be applied either axially or radially. Further, the HRSRM can be of two topologies - multiple stator and multiple rotor.

[00010] A multiple rotor HRSRM comprises at least two rotors positioned about a central axis and each of the rotors comprising a plurality of rotor poles on a lateral rotor surface. At least one stator is positioned about the central axis and placed between, and laterally adjacent to, the rotors. The stator comprises a plurality of stator poles extending from a first lateral stator surface adjacent to one of the rotors to a second lateral stator surface adjacent to the other of the rotors. The plurality of rotor poles is in a numerical relationship with the plurality of stator poles defined by the MRP formula:

$$N_{R,tot} = R \times N_R = (S + 1) \times (2N_S - 2)$$

such that $R \geq 2$ wherein $N_{R,tot}$ is the total number of rotor poles, R is the number of individual rotors, S is the number of individual stators, N_R is the number of rotor poles per rotor and N_S is the number of stator poles per stator.

[00011] A multiple axial stator HRSRM comprises at least two stators positioned about a central axis, wherein each of the stators comprises a plurality of stator poles on a lateral stator surface. At least one rotor is positioned about the central axis and placed between and laterally adjacent to the stators. The rotor comprises a plurality of rotor poles extending from a first lateral rotor surface adjacent to one of the two stators to a second lateral rotor surface adjacent to the other of the two stators. The plurality of stator poles is in a numerical relationship with the plurality of rotor poles defined by the MSP formula:

$$N_{R,tot} = R \times N_R = (S - 1) \times (2N_S - 2)$$

such that $S \geq 2$ wherein $N_{R,tot}$ is the total number of rotor poles, R is the

number of individual rotors, S is the number of individual stators, N_R is the number of rotor poles per rotor and N_S is the number of stator poles per stator.

[00012] It is a first objective of the present invention to provide an HRSRM that employs a mirroring concept.

5 [00013] A second objective of the present invention is to provide an HRSRM that is modular or stackable and can include any number of stators and rotors necessary to achieve a desired torque output or any other design consideration.

[00014] A third objective of the present invention is to provide an HRSRM that uses an advanced pole definition MSP and MRP formula for design.

10 [00015] Another objective of the present invention is to provide an HRSRM that is able to apply the mirroring concept either radially or axially.

[00016] Yet another objective of the present invention is to provide an HRSRM that would employ a multiple rotor or a multiple stator mirroring concept.

15 [00017] These and other advantages and features of the present invention are described with specificity so as to make the present invention understandable to one of ordinary skill in the art.

BRIEF DESCRIPTION OF THE DRAWINGS

20 [00018] Elements in the figures have not necessarily been drawn to scale in order to enhance their clarity and improve understanding of these various elements and embodiments of the invention. Furthermore, elements that are known to be common and well understood to those in the industry are not depicted in order to provide a clear view of the various embodiments of the invention. Thus, the drawings are generalized in form in the interest of clarity and conciseness.

25 [00019] FIG. 1 illustrates a perspective view of an HRSRM with an axial configuration having three rotors and two stators in accordance with the preferred embodiment of the present invention;

[00020] FIG. 2A illustrates a perspective view of the stators of the embodiment of FIG. 1;

30 [00021] FIG. 2B illustrates a perspective view of the rotors of the embodiment of FIG. 1;

[00022] FIG. 3A illustrates a perspective view of the rotors of the embodiment of

FIG. 2B without a backiron in one rotor;

[00023] **FIG. 3B** illustrates a perspective view of a plurality of poles of the rotors of the embodiment of **FIG. 2B**;

5 [00024] **FIG. 4** illustrates a perspective view of the HRSRM with an axial configuration having three stators and two rotors in accordance with the preferred embodiment of the present invention;

[00025] **FIG. 5A** illustrates a perspective view of the rotors of the embodiment of **FIG. 4**;

10 [00026] **FIG. 5B** illustrates a perspective view of the plurality of poles of the rotors of the embodiment of **FIG. 5A**;

[00027] **FIG. 5C** illustrates a perspective view of the stators of the embodiment of **FIG. 4**;

[00028] **FIG. 6A** illustrates a perspective view of a stator of the HRSRM in accordance with one embodiment of the present invention;

15 [00029] **FIG. 6B** illustrates a perspective view of the stator of the HRSRM in accordance with another embodiment of the present invention;

[00030] **FIG. 7** illustrates a perspective view of the HRSRM with an axial configuration utilizing the stator embodiment of **FIG. 6A** and **FIG. 6B**;

20 [00031] **FIG. 8A** illustrates a perspective view of the stators of the embodiment of **FIG. 7**;

[00032] **FIG. 8B** illustrates a perspective view of the rotors of the embodiment of **FIG. 7**;

25 [00033] **FIG. 9** illustrates a perspective view of a multiple rotor HRSRM with a radial 10/6/10 configuration consisting of one stator and two rotors in accordance with an alternate embodiment of the present invention;

[00034] **FIG. 10** illustrates a perspective view of the embodiment of **FIG. 1** with an alternative coil position;

30 [00035] **FIG. 11** illustrates a perspective view of an HRSRM with a radial configuration comprising two stators and one rotor in accordance with another embodiment of the present invention;

[00036] **FIG. 12** illustrates a perspective view of an HRSRM with a radial configuration comprising three stators and two rotors in accordance with another

embodiment of the present invention; and

[00037] **FIG. 13** illustrates a perspective view of an HRSRM with a radial configuration having two stators and three rotors in accordance with another embodiment of the present invention.

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DETAILED DESCRIPTION OF THE DRAWINGS

[00038] In the following discussion that addresses a number of embodiments and applications of the present invention, reference is made to the accompanying drawings that form a part hereof, and in which is shown by way of illustration specific
10 embodiments in which the invention may be practiced. It is to be understood that other embodiments may be utilized and changes may be made without departing from the scope of the present invention.

[00039] Various inventive features are described below that can each be used independently of one another or in combination with other features. However, any single
15 inventive feature may not address any of the problems discussed above, or may address one or more of the problems discussed above. Further, one or more of the problems discussed above may not be fully addressed by any of the features described below.

[00040] The present invention provides a family of high rotor pole switched reluctance machines (HRSRM) using a mirroring concept. An HRSRM can be described
20 as any SRM wherein the number of rotor poles is higher than the number of stator poles. There are two ways that the mirroring concept can be applied in the HRSRM. It can either be axial or radial in configuration. At the same time, there can also be two topologies - multiple rotor and multiple stator. The present invention provides a design formula for the two advanced formulations for the design of an HRSRM. The present
25 invention provides a new mathematical formulation for high rotor switched reluctance machines (HRSRM) configured to mirror multiple number of stators and rotors. The present invention provides a design formula for multiple stator and multiple rotor configurations of the HRSRM.

[00041] Turning now to **FIG. 1**, a perspective view of an HRSRM **10** with an
30 axial 10/6/10/6/10 configuration having three rotors **16, 18, 20** and two stators **12, 14** in accordance with the preferred embodiment of the present invention is illustrated.

[00042] In a multiple rotor configuration, the high rotor pole switched reluctance

machine **10** comprises at least two rotors **16, 20** positioned about a central axis (**not shown**) and at least one stator **12** positioned about the central axis (**not shown**) and placed between and laterally adjacent to the at least two rotors **16, 20**. Each of the at least two rotors **16, 20** comprises a plurality of rotor poles **34** (see FIG. 2B) positioned on a first lateral rotor surface **30**. The at least one stator **12** comprises a plurality of stator poles **26** (see FIG. 2A) extending from a first lateral stator surface **22** adjacent to one of the at least two rotors **16** to a second lateral stator surface **24** adjacent to other of the at least two rotors **20** to form a mirroring configuration. The plurality of rotor poles **34** on one of the at least two rotors **16** is positioned opposite the plurality of stator poles **26** on the first lateral stator surface **22** and the plurality of rotor poles **34** on other of the at least two rotors **20** is positioned opposite the plurality of stator poles **26** on the second lateral stator surface **24**. The HRSRM **10** of the present invention provides a three phase type machine with the at least two rotors **16, 20** and the at least one stator **12** arranged axially about the central axis to form an axial mirroring configuration.

[00043] In the high rotor pole switched reluctance machine **10** of the present embodiment, the at least one stator **12** is positioned between the at least two rotors **16, 20** to provide a multi rotor mirroring configuration. The mirroring configuration changes the saliency associated with the at least one stator **12** and changes the magnetic configuration of the machine **10** which in turn increases the power density and torque density of the machine.

[00044] In the multiple rotor configuration, the plurality of rotor poles **34** is in a numerical relationship with the plurality of stator poles **26**, the numerical relationship being defined by a Multiple Rotor Pole (MRP) formula:

$$N_{R,tot} = R \times N_R = (S + 1) \times (2N_S - 2)$$

such that $R \geq 2$, wherein $N_{R,tot}$ is the total number of rotor poles, R is the number of individual rotors, S is the number of individual stators, N_R is the number of rotor poles per rotor and N_S is the number of stator poles per stator.

[00045] Using the MRP formula for a three-phase machine with 6 stator poles, $N_{R,tot}$ will be equal to 20. These 20 poles would be evenly distributed between the two rotors, i.e. each rotor would have 10 poles each ($N_R = 10$) leading to a 10/6/10 configuration. Similarly, using the MRP formula, the following configurations: 14/8/14,

18/10/18, 10/6/10/6/10, 14/8/14/8/14, etc. are possible.

[00046] In FIG. 1, a multiple rotor HRSRM 10 with an axial 10/6/10/6/10 configuration having three rotors 16, 18, 20 and two stators 12, 14 in accordance with the preferred embodiment of the present invention is illustrated. A first stator 12 is positioned between a first rotor 16 and a second rotor 18 and a second stator 14 is positioned between the second rotor 18 and a third rotor 20. Each of the stators 12, 14 and rotors 16, 18, 20 rotate about the central axis (not shown) separated by an axial air gap.

[00047] FIG. 2A illustrates a perspective view of the stators 12, 14 of the embodiment of FIG. 1. The at least two stators 12, 14 have a disk-like shape with a first lateral stator surface 22 and a second lateral stator surface 24. The first lateral stator surface 22 and the opposing second lateral stator surface 24 are generally parallel to each other and each includes a plurality of stator poles 26 evenly distributed about a circumference of the stators 12, 14. The stator poles 26 project outward, and generally perpendicularly, from the corresponding one of the first stator surface 22 and extends to the second stator surface 24. In this embodiment, each of the at least two stators 12, 14 include six stator poles 26 in three-phase pairs. A plurality of coils 28 are wound around a portion of the at least two stators 12, 14 between any two of the plurality of stator poles 26. In this embodiment, the plurality of coils 28 can preferably be toroidal coils. Here a single winding of coils is used to energize the stator poles 26, extending from the first stator surface 22 to the second stator surface 24. In operation, the six stator poles 26 on the opposing sides of the stators 12, 14 operate in sync with each other.

[00048] FIG. 2B illustrates a perspective view of the rotors 16, 18, 20 of the embodiment of FIG. 1. The rotors 16, 18, 20 have a disk-like shape with a first lateral rotor surface 30 and a second lateral rotor surface 32. The first rotor surface 30 and the second rotor surface 32 are positioned on opposite sides of the disk-like shape called the backiron and are generally parallel to each other. The rotors 16, 18, 20 include a plurality of rotor poles 34 evenly distributed about a circumference of the rotors 16, 18, 20. In the present embodiment, the plurality of rotor poles 34 project generally perpendicularly from the first rotor surface 30 in the case of the first rotor 16 and the third rotor 20, and from both the first rotor surface 30 and the second rotor surface 32 in the case of the second rotor 18.

[00049] FIGS. 3A-3B illustrate a perspective view of the rotors 16, 18, 20 of the embodiment of FIG. 2B without the backiron. The backiron is removed from the rotor 18 as shown in FIG. 3A and removed from the rotors 16 and 20 as shown in FIG. 3B. FIG. 3B illustrates a perspective view of the plurality of rotor poles 34 of the rotors 16, 18, 20 of the embodiment of FIG. 2B. The plurality of rotor poles 34 can provide a direct path for the magnetic flux to traverse from the stator 12 to the stator 14. This means that the machine is no longer in 6/10/10/6 configuration but is instead a 6/10/6 configuration and is still a mirrored HRSRM.

[00050] FIG. 4 illustrates a perspective view of a multiple stator HRSRM 40 with an axial configuration having three stators 42, 44, 46 and two rotors 48, 50 in accordance with the preferred embodiment of the present invention. In the multiple stator configuration, the HRSRM 40 comprises at least two stators 42, 44 positioned about a central axis (not shown) and at least one rotor 48 positioned about the central axis (not shown) and placed between and laterally adjacent to the at least two stators 42, 44. Each of the at least two stators 42, 44 comprises a plurality of stator poles 62 on a first lateral stator surface 58 (see FIG. 5C). The at least one rotor 48 comprises a plurality of rotor poles 56 (see FIG. 5A) extending from a first lateral rotor surface 52 adjacent to one of the at least two stators 42 to a second lateral rotor surface 54 adjacent to the other of the at least two stators 44. The plurality of stator poles 62 on the at least two stators 42, 44 is positioned opposite the plurality of rotor poles 56 extending from the first lateral rotor surface 52 to the second lateral rotor surface 54. The at least two stators 42, 44 and the at least one rotor 48 are positioned axially about the central axis to form an axial mirroring configuration.

[00051] In the multiple stator configuration, the plurality of stator poles 62 is in a numerical relationship with the plurality of rotor poles 56, wherein the numerical relationship is defined by the Multiple Stator Pole (MSP) formula:

$$N_{R,tot} = R \times N_R = (S - 1) \times (2N_s - 2)$$

such that $S > 2$, wherein $N_{R,tot}$ is the total number of rotor poles, R is the number of individual rotors, S is the number of individual stators, N_R is the number of rotor poles per rotor and N_s is the number of stator poles per stator.

[00052] Using the MSP formula for a three-phase machine with 6 stator poles,

$N_{R,tot}$ will be equal to 10. The rotor will have 10 poles ($N_{R,tot} = N_R = 10$). This would lead to a 6/10/6 configuration. Similarly, using the MSP formula, the following configurations: 8/14/8, 10/18/10, 6/10/6/10/6, 8/14/8/14/8, etc. are possible.

[00053] When the mirroring concept is applied to the HRSRM, the saliency associated with the rotor in the case of a multiple stator configuration changes the magnetic configuration of the machine, thereby reducing a 6/10/10/6 machine to a 6/10/6 machine. The mirroring concept changes the magnetic configuration of machines with multiple stator configurations and multiple rotor configurations.

[00054] The multiple stator HRSRM **40** with an axial 6/10/6/10/6 configuration consists of three stators **42**, **44**, **46** and two rotors **48**, **50** in accordance with one embodiment of the present invention as illustrated in **FIG. 4**. A first rotor **48** is positioned between a first stator **42** and a second stator **44** and a second rotor **50** is positioned between the second stator **44** and a third stator **46**. Each of the stators **42**, **44**, **46** and rotors **48**, **50** rotate about a central axis separated by an axial air gap.

[00055] **FIG. 5A** illustrates a perspective view of the rotors **48**, **50** of the embodiment of **FIG. 4**. The rotors **48**, **50** have a disk-like shape with the first lateral rotor surface **52** opposite the second lateral rotor surface **54** which are generally parallel to each other and each include the plurality of rotor poles **56** evenly distributed about the circumference of the rotors **48**, **50**. The plurality of rotor poles **56** projects generally perpendicularly from the first lateral rotor surface **52** to the second lateral rotor surface **54**. The magnetic flux flows from the first stator **42** to the second stator **44** through the plurality of rotor poles **56** extending from the first lateral rotor surface **52** to the opposing second lateral rotor surface **54**. **FIG. 5B** illustrates a perspective view of the plurality of rotor poles **56** of the rotors **48**, **50** of the embodiment of **FIG. 5A**. In this configuration, and for ease of understanding, the backiron is removed to show the plurality of poles **56** of the rotors **48**, **50** clearly.

[00056] **FIG. 5C** illustrates a perspective view of the stators **42**, **44**, **46** of the embodiment of **FIG. 4**. The stators **42**, **44**, **46** have a disk-like shape having the first lateral stator surface **58** opposing a second lateral stator surface **60** which are generally parallel to each other. In this embodiment, the stators **42**, **44**, **46** and the plurality of stator poles **62** are evenly distributed about the circumference of the stators **42**, **44**, **46** and project generally perpendicularly from the first lateral stator surface **58** in the case

of the first stator **42** and the third stator **46**, and extends from the first stator surface **58** to the second stator surface **60** in the case of the second stator **44**. In this embodiment, the stator surfaces **58**, **60** include six stator poles **122** in three-phase pairs. A plurality of coils **124** are wound around a portion of the stators **42**, **44**, **46** and adjacent to one of the
 5 corresponding stator poles **62**.

[00057] **FIG. 6A** illustrates a perspective view of one embodiment of the stator **12** with toroidal winding configurations for the plurality of coils **28**. Each of the plurality of coils **28** are wound as toroidal coils around a portion of the stator **12** and adjacent to each of the plurality of stator poles **26**.

10 [00058] **FIG. 6B** illustrates a perspective view of one embodiment of a stator **70** with concentrated winding configurations for a plurality of coils **74**. Each of the plurality of coils **74** is wound as concentrated coils around each of a plurality of stator poles **72**.

[00059] **FIG. 7** illustrates a perspective view of a multiple stator HRSRM **80**
 15 having three stators **82**, **84**, **86** and two rotors **88**, **90** with an axial configuration utilizing the stator embodiments of **FIG. 6A** and **FIG. 6B**. In this embodiment, a first stator **82** and a third stator **86** have a plurality of coils **92** with concentrated winding configurations and a second stator **84** has a plurality of coils **94** with toroidal winding configurations. Each of the plurality of coils **92**, **94** is made of a magnetic wire,
 20 preferably copper.

[00060] **FIG. 8A** illustrates a perspective view of the stators **82**, **84**, **86** of the embodiment of **FIG. 7**. The first stator **82** and the third stator **86** have the plurality of coils **92** with concentrated winding configurations and the second stator **84** has the plurality of coils **94** with toroidal winding configurations. **FIG. 8B** illustrates a
 25 perspective view of the rotors **88**, **90** of the embodiment of **FIG. 7** with a plurality of rotor poles **96**.

[00061] Using the above two formulas, the following configurations of HRSRM are some of those possible: 6/10/6, 10/6/10, 8/14/8, 14/8/14, 10/36/10, 36/10/36, etc. The tables illustrated below shows the general trend of configurations possible for the
 30 mirrored HRSRM concept. Table 1 illustrates the configurations possible with the multiple rotor pole (MRP) formula and Table 2 illustrates some of the configurations possible with the multiple stator pole (MSP) formula.

S	R	N_S	N_{S,tot}	N_R	N_{R,tot}	Configuration
1	2	6	6	10	20	10/6/10
1	2	8	8	14	28	14/8/14
1	2	10	10	18	36	18/10/18
2	3	6	12	10	30	10/6/10/6/10
2	3	8	16	14	42	14/8/14/8/14
2	3	10	20	18	54	18/10/18/10/18

Table 1

S	R	N_S	N_{S,tot}	N_R	N_{R,tot}	Configuration
2	1	6	12	10	10	6/10/6
2	1	8	16	14	14	8/14/8
2	1	10	20	18	18	10/18/10
3	2	6	18	10	20	6/10/6/10/6
3	2	8	24	14	28	8/14/8/14/8
3	2	10	30	18	36	10/18/10/18/10

Table 2

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[00062] FIG. 9 illustrates a perspective view of a multiple rotor HRSRM 100 with a radial 10/6/10 configuration having one stator 102 and two rotors 104, 106 in accordance with an alternate embodiment of the present invention. A stator 102 is positioned between a first rotor 104 and a second rotor 106 which rotates about a central axis concentric to each other separated by a radial air gap. The stator 102 has a cylindrical shape with a first inner stator surface 108 and a second outer stator surface 110. The first inner stator surface 108 and the second outer stator surface 110 each include a plurality of stator poles 112 evenly distributed about a circumference of the stator 102. The stator poles 112 project perpendicularly inwardly from the first stator surface 108 and outwardly from the second stator surface 110. In this embodiment, the stator surface 102 includes six stator poles 112 in three-phase pairs. A plurality of coils 114 are wound around a portion of the stator 102 and adjacent to one of the stator poles 112. Here, a single winding of coils is used to energize a pair of stator poles 112.

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[00063] In this embodiment, the rotors 104, 106 are cylindrical in shape. A first rotor 104 is positioned radially outward to the stator 102 and a second rotor 106 is positioned radially inward to the stator 102. Both the first rotor 104 and the second rotor

106 have an outer rotor surface 118 and inner rotor surface 116. A plurality of rotor poles 120 is evenly distributed about the circumference of the rotors 104, 16 and projects generally perpendicularly inwards from the inner rotor surface 116 of the first rotor 104 and perpendicularly outwards from the outer rotor surface 118 of the second rotor 106. In this embodiment, the magnetic flux flows from the plurality of rotor poles 120 on the first rotor 104 to the plurality of stator poles 112 on the second outer stator surface 110 to the first inner stator surface 108 and then to the plurality of rotor poles 120 on the second rotor 106.

[00064] FIG. 10 illustrates a perspective view of the embodiment of FIG. 1 with an alternative coil position. The plurality of stator poles 112 are arranged on the first inner stator surface 108 and the second outer stator surface 110 (see FIG. 9). In this embodiment, a plurality of coils 122, is collectively wound around each of the plurality of stator poles 112 on the first inner stator surface 108 and the second outer stator surface 110. Each of the coils 122 is made of a magnetic wire, preferably copper, wrapped around a respective stator pole 112 on the first inner stator surface 108 (see FIG. 9) to the second outer stator surface 110 (see FIG. 9). In this configuration, the plurality of coils 122 on the first inner stator surface 108 and the second outer stator surface 110 at any angular position are connected in series to form a single coil.

[00065] FIG. 11 illustrates a perspective view of a multiple stator HRSRM 130 with a radial 6/10/6 configuration having two stators 132, 134 and one rotor 136 in accordance with another embodiment of the present invention. A rotor 136 is positioned between a first stator 132 and a second stator 134 which rotate about a central axis concentric to each other separated by a radial air gap. Both the first stator 132 and the second stator 134 have an inner stator surface 138 and an outer stator surface 140. A plurality of stator poles 142 is evenly distributed along the circumference of each of the stators 132, 134 and project generally perpendicularly from the inner stator surface 138 in the case of the second rotor 134 and from the outer stator surface 140 in the case of the first rotor 132.

[00066] In this embodiment, each of the stators 132, 134 include six stator poles 142 in three-phase pairs. Each stator pole 142 has a coil, collectively 144, wound around it. Each of the coils 144 is made of a magnetic wire, preferably copper, wrapped around the respective stator pole 142. In this embodiment, the rotor 136 is cylindrical in shape

with an inner rotor surface **146** and an outer rotor surface **148**. A plurality of rotor poles **60** extends from the inner rotor surface **146** to the outer rotor surface **148** and is evenly distributed about the circumference of the rotor **136**. The plurality of rotor poles **150** projects perpendicularly from the inner rotor surface **146** to the outer rotor surface **148**.

5 **[00067]** HRSRMs of other sizes and having other than three phases or six stator poles may be designed in accordance with the multiple rotor pole (MRP) formula and multiple stator pole (MSP) formula as illustrated in Table 1 and Table 2, and the extrapolations easily drawn from the patterns therein.

[00068] For example, **FIG. 12** illustrates a perspective view of a multiple stator
10 HRSRM **160** with a radial 6/10/6/10/6 configuration having three stators **162**, **164**, **166** and two rotors **168**, **170**. The HRSRM **160** has a total of 18 stator poles and 20 rotor poles.

[00069] **FIG. 13** illustrates a perspective view of a multiple rotor HRSRM **180**
15 with a radial 10/6/10/6/10 configuration having two stators **182**, **184** and three rotors **186**, **188**, **190**. The HRSRM **180** has 30 rotor poles and 12 stator poles.

[00070] The presently disclosed HRSRM design is advantageous because it is modular or stackable and can include any number of stators and rotors necessary to achieve a desired torque output or any other design consideration.

[00071] The foregoing description of the preferred embodiment of the present
20 invention has been presented for the purpose of illustration and description. It is not intended to be exhaustive or to limit the invention to the precise form disclosed. Many modifications and variations are possible in light of the above teachings. It is intended that the scope of the present invention not be limited by this detailed description, but by the claims and the equivalents to the claims appended hereto.

25

CLAIMS

What is claimed is:

- 5 1. A high rotor pole switched reluctance machine comprising:
 at least two rotors positioned about a central axis, each of the at least two rotors comprising a plurality of rotor poles on a lateral rotor surface; and
 at least one stator positioned about the central axis and placed between
 and laterally adjacent to the at least two rotors, the at least one stator comprising a
 10 plurality of stator poles extending from a first lateral stator surface adjacent to one of the
 at least two rotors to a second lateral stator surface adjacent to other of the at least two rotors to form a mirroring configuration;
 wherein the plurality of rotor poles is in a numerical relationship with the
 plurality of stator poles, the numerical relationship defined by the Multiple Rotor Pole
 15 (MRP) formula:

$$N_{R,tot} = R \times N_R = (S + 1) \times (2N_s - 2)$$

- such that $R \geq 2$, wherein $N_{R,tot}$ is the total number of rotor poles, R is the
 20 number of individual rotors, S is the number of individual stators, N_R is the number of
 rotor poles per rotor and N_s is the number of stator poles per stator.

2. The high rotor pole switched reluctance machine of claim 1 wherein the plurality
 of rotor poles on one of the at least two rotors is positioned opposite the plurality of
 25 stator poles on the first lateral stator surface.

3. The high rotor pole switched reluctance machine of claim 1 wherein the plurality
 of rotor poles on others of the at least two rotors is positioned opposite the plurality of
 stator poles on the second lateral stator surface.
 30

4. The high rotor pole switched reluctance machine of claim 1 wherein the machine
 is a three phase type.

5. The high rotor pole switched reluctance machine of claim 1 wherein the at least two rotors and the at least one stator are arranged axially about the central axis to form an axial mirroring configuration.

5 6. The high rotor pole switched reluctance machine of claim 1 wherein the at least one stator positioned between the at least two rotors provides a multi rotor mirroring configuration.

10 7. The high rotor pole switched reluctance machine of claim 6 wherein the mirroring configuration changes the saliency associated with the at least one stator and changes the magnetic configuration of the machine.

8. The high rotor pole switched reluctance machine of claim 6 wherein the mirroring configuration increases the power density and torque density.

15

9. The high rotor pole switched reluctance machine of claim 6 wherein $S=1$, $R=2$ and $N_s=6$ gives a mirroring configuration of 10/6/10.

20 10. The high rotor pole switched reluctance machine of claim 6 wherein $S=1$, $R=2$ and $N_s=8$ gives a mirroring configuration of 14/8/14.

11. The high rotor pole switched reluctance machine of claim 6 wherein $S=1$, $R=2$ and $N_s=10$ gives a mirroring configuration of 18/10/18.

25

12. A high rotor pole switched reluctance machine comprising:

at least two rotors positioned about a central axis, each of the at least two rotors comprising a plurality of rotor poles on a lateral rotor surface; and

30 at least one stator positioned about the central axis and placed between and laterally adjacent to the at least two rotors, the at least one stator comprising a plurality of stator poles extending from a first lateral stator surface adjacent to one of the at least two rotors to a second lateral stator surface adjacent to other of the at least two rotors;

wherein the at least two rotors and the at least one stator positioned about the central axis provides a multi rotor mirroring configuration and the plurality of rotor poles is in a numerical relationship with the plurality of stator poles, the numerical relationship defined by the Multiple Rotor Pole (MRP) formula:

5

$$N_{R,tot} = R \times N_R = (S + 1) \times (2N_s - 2)$$

such that $R \geq 2$, wherein $N_{R,tot}$ is the total number of rotor poles, R is the number of individual rotors, S is the number of individual stators, N_R is the number of rotor poles per rotor and N_s is the number of stator poles per stator.

10

13. The high rotor pole switched reluctance machine of claim 12 wherein the plurality of stator poles on the first lateral stator surface is adjacent to one of the at least two rotors.

15

14. The high rotor pole switched reluctance machine of claim 12 wherein the plurality of stator poles on the second lateral stator surface is adjacent to others of the at least two rotors.

20

15. The high rotor pole switched reluctance machine of claim 12 wherein the machine is a three phase type.

16. The high rotor pole switched reluctance machine of claim 12 wherein the at least two rotors and the at least one stator are arranged concentrically about the central axis to form a radial mirroring configuration.

25

17. The high rotor pole switched reluctance machine of claim 12 wherein the mirroring configuration changes the saliency associated with the at least one stator and increases the power density and torque density.

30

18. The high rotor pole switched reluctance machine of claim 12 wherein $S=1$, $R=2$ and $N_s=6$ gives a mirroring configuration of 10/6/10.

19. The high rotor pole switched reluctance machine of claim 12 wherein $S=1$, $R=2$ and $N_s=8$ gives a mirroring configuration of 14/8/14.

20. The high rotor pole switched reluctance machine of claim 12 wherein $S=1$, $R=2$ and $N_s=10$ gives a mirroring configuration of 18/10/18.

21. A high rotor pole switched reluctance machine comprising:

at least two rotors positioned about a central axis, each of the at least two rotors comprising a plurality of rotor poles on a lateral rotor surface; and

at least one stator positioned about the central axis and placed between and laterally adjacent to the at least two rotors, the at least one stator comprising a plurality of stator poles extending from a first lateral stator surface adjacent to one of the at least two rotors to a second lateral stator surface adjacent to the other of the at least two rotors;

wherein the at least two rotors and the at least one stator forms a multi rotor mirroring configuration and the plurality of rotor poles is in a numerical relationship with the plurality of stator poles, the numerical relationship defined by the Multiple Rotor Pole (MRP) formula:

$$N_{R,tot} = R \times N_R = (S + 1) \times (2N_s - 2)$$

such that $R \geq 2$, wherein $N_{R,tot}$ is the total number of rotor poles, R is the number of individual rotors, S is the number of individual stators, N_R is the number of rotor poles per rotor and N_s is the number of stator poles per stator.

22. The high rotor pole switched reluctance machine of claim 21 wherein the machine is a three phase type.

23. The high rotor pole switched reluctance machine of claim 21 wherein the at least two rotors and the at least one stator are arranged concentrically about the central axis to form a radial mirroring configuration.

24. The high rotor pole switched reluctance machine of claim 21 wherein the at least

two rotors and the at least one stator are arranged axially about the central axis to form an axial mirroring configuration.

25. A high rotor pole switched reluctance machine comprising:

5 at least two stators positioned about a central axis, each of the at least two stators comprising a plurality of stator poles on a lateral stator surface; and

at least one rotor positioned about the central axis and placed between and laterally adjacent to the at least two stators, the at least one rotor comprising a plurality of rotor poles extending from a first lateral rotor surface adjacent to one of the
10 at least two stators to a second lateral rotor surface adjacent to the other of the at least two stators;

wherein the at least two stators and the at least one rotor forms a multi stator mirroring configuration and the plurality of stator poles is in a numerical relationship with the plurality of rotor poles, the numerical relationship defined by the
15 Multiple Stator Pole (MSP) formula:

$$N_{R,tot} = R \times N_R = (S - 1) \times (2N_s - 2)$$

such that $S \geq 2$, wherein $N_{R,tot}$ is the total number of rotor poles, R is the
20 number of individual rotors, S is the number of individual stators, N_R is the number of rotor poles per rotor and N_s is the number of stator poles per stator.

26. The high rotor pole switched reluctance machine of claim 25 wherein the plurality of stator poles on one of the at least two stators is positioned opposite the
25 plurality of rotor poles on the first lateral rotor surface.

27. The high rotor pole switched reluctance machine of claim 25 wherein the plurality of stator poles on others of the at least two stators is positioned opposite the plurality of rotor poles on the second lateral rotor surface.
30

28. The high rotor pole switched reluctance machine of claim 25 wherein the machine is a three phase type.

29. The high rotor pole switched reluctance machine of claim 25 wherein the at least two stators and the at least one rotor are positioned axially about the central axis to form an axial mirroring configuration.

5 30. The high rotor pole switched reluctance machine of claim 25 wherein the mirroring configuration changes the saliency associated with the at least two stators and changes the magnetic configuration of the machine.

31. The high rotor pole switched reluctance machine of claim 25 wherein S=2, R=1
10 and N_s=6 gives a mirroring configuration of 6/10/6.

32. The high rotor pole switched reluctance machine of claim 25 wherein S=2, R=1 and N_s=8 gives a mirroring configuration of 8/14/8.

15 33. The high rotor pole switched reluctance machine of claim 25 wherein S=2, R=1 and N_s=10 gives a mirroring configuration of 10/18/10.

34. A high rotor pole switched reluctance machine comprising:
at least two stators positioned about a central axis, each of the at least two
20 stators comprising a plurality of stator poles on a lateral stator surface; and
at least one rotor positioned about the central axis and placed between and laterally adjacent to the at least two stators, the at least one rotor comprising a plurality of rotor poles extending from a first lateral rotor surface to a second lateral rotor surface;

25 wherein the at least two stators and the at least one rotor positioned about the central axis provides a multi stator mirroring configuration and the plurality of stator poles is in a numerical relationship with the plurality of rotor poles, the numerical relationship defined by the Multiple Stator Pole (MSP) formula:

30
$$N_{R,tot} = R \times N_R = (S - 1) \times (2N_s - 2)$$

such that $S \geq 2$, wherein N_{R,tot} is the total number of rotor poles, R is the number of individual rotors, S is the number of individual stators, N_R is the number of

rotor poles per rotor and N_s is the number of stator poles per stator.

35. The high rotor pole switched reluctance machine of claim 34 wherein the plurality of rotor poles on the first lateral rotor surface is adjacent to one of the at least
5 two stators.

36. The high rotor pole switched reluctance machine of claim 34 wherein the plurality of rotor poles on the second lateral rotor surface is adjacent to the other of the
10 at least two stators.

37. The high rotor pole switched reluctance machine of claim 34 wherein the machine is a three phase type.

38. The high rotor pole switched reluctance machine of claim 34 wherein the at least
15 two stators and the at least one rotor are positioned radially about the central axis to form a radial mirroring configuration.

39. The high rotor pole switched reluctance machine of claim 34 wherein the mirroring configuration changes the saliency associated with the at least two stators and
20 change the magnetic configuration of the machine.

40. The high rotor pole switched reluctance machine of claim 34 wherein $S=2$, $R=1$ and $N_s=6$ gives a mirroring configuration of 6/10/6.

25 41. The high rotor pole switched reluctance machine of claim 34 wherein $S=2$, $R=1$ and $N_s=8$ gives a mirroring configuration of 8/14/8.

42. The high rotor pole switched reluctance machine of claim 34 wherein $S=2$, $R=1$ and $N_s=10$ gives a mirroring configuration of 10/18/10.
30

43. A high rotor pole switched reluctance machine comprising:
at least two stators positioned about a central axis, each of the at least two

stators comprising a plurality of stator poles on a lateral stator surface; and

at least one rotor positioned about the central axis and placed between and laterally adjacent to the at least two stators, the at least one rotor comprising a plurality of rotor poles extending from a first lateral rotor surface adjacent to one of the
 5 at least two stators to a second lateral rotor surface adjacent to the other of the at least two stators to form a multi stator mirroring configuration;

wherein the plurality of stator poles is in a numerical relationship with the plurality of rotor poles, the numerical relationship defined by the Multiple Stator Pole (MSP) formula:

10

$$N_{R,tot} = R \times N_R = (S - 1) \times (2N_s - 2)$$

such that $S \geq 2$, wherein $N_{R,tot}$ is the total number of rotor poles, R is the number of individual rotors, S is the number of individual stators, N_R is the number of
 15 rotor poles per rotor and N_s is the number of stator poles per stator.

44. The high rotor pole switched reluctance machine of claim 43 wherein the machine is a three phase type.

20 45. The high rotor pole switched reluctance machine of claim 43 wherein the at least two stators and the at least one rotor are arranged radially about the central axis to form a radial mirroring configuration.

46. The high rotor pole switched reluctance machine of claim 43 wherein the at least
 25 two stators and the at least one rotor are arranged axially about the central axis to form an axial mirroring configuration.

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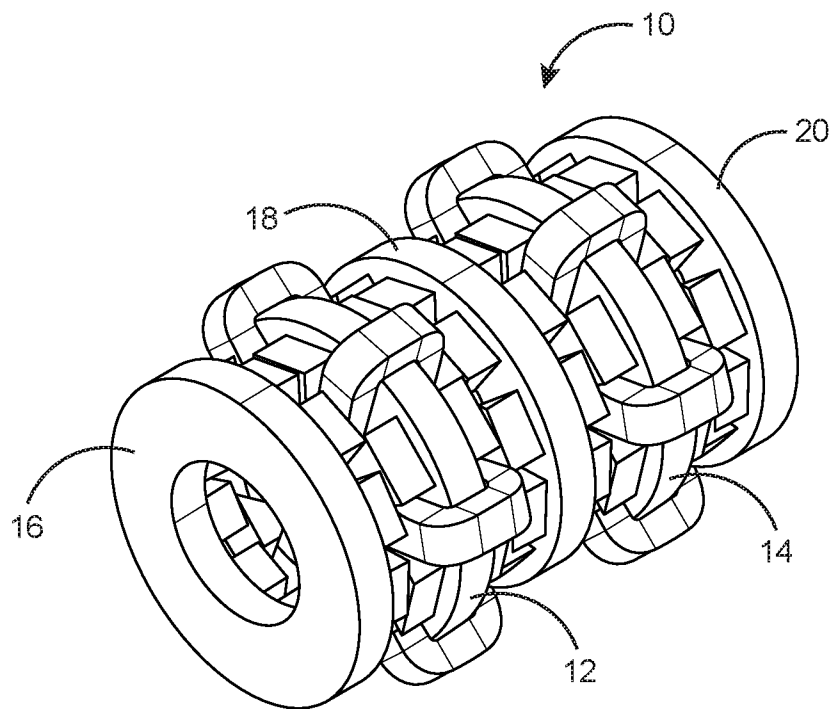


FIG. 1

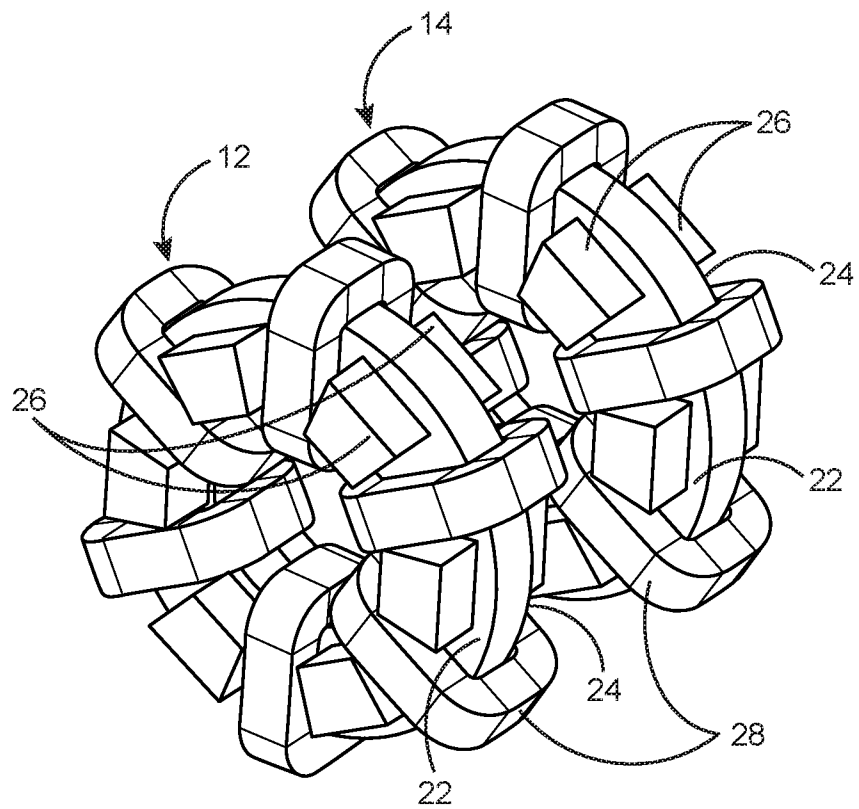


FIG. 2A

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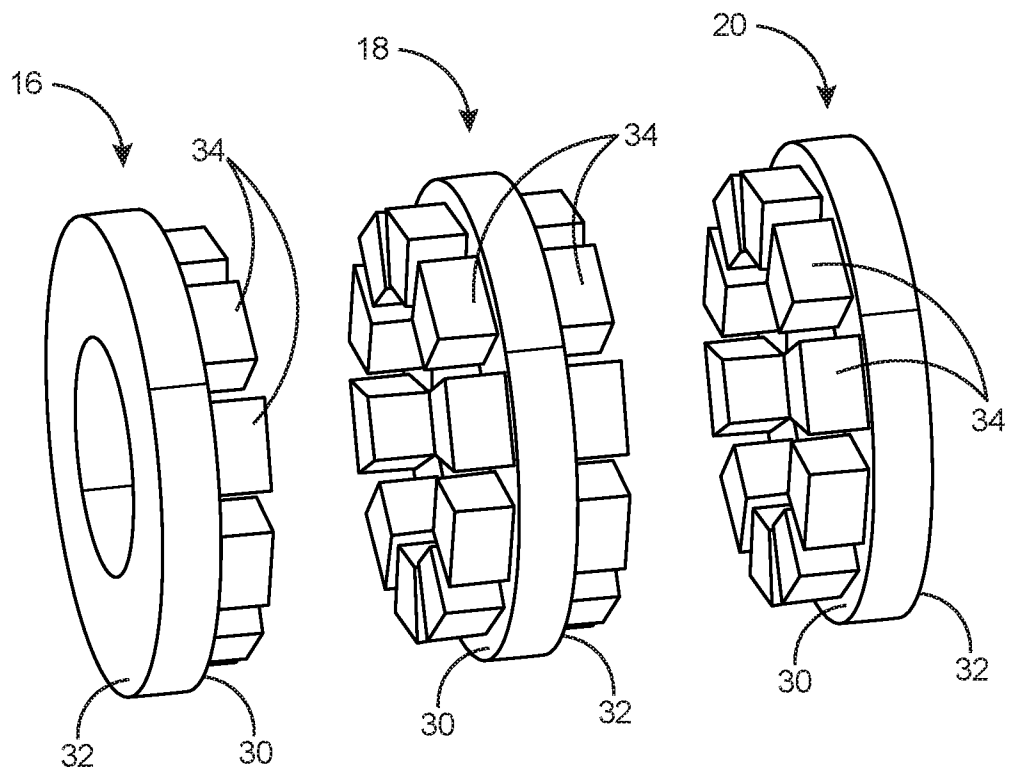


FIG. 2B

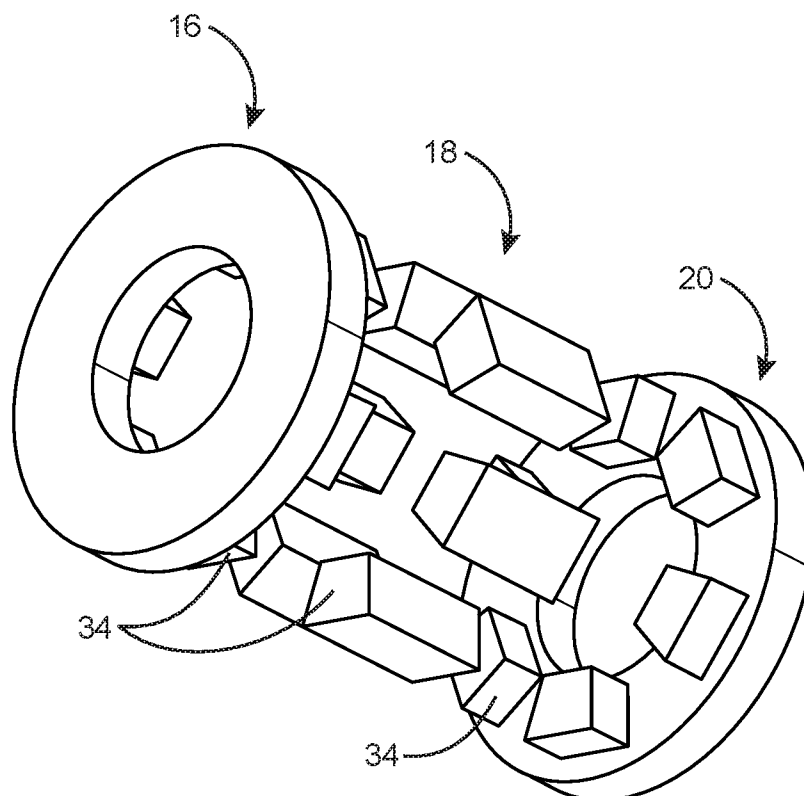


FIG. 3A

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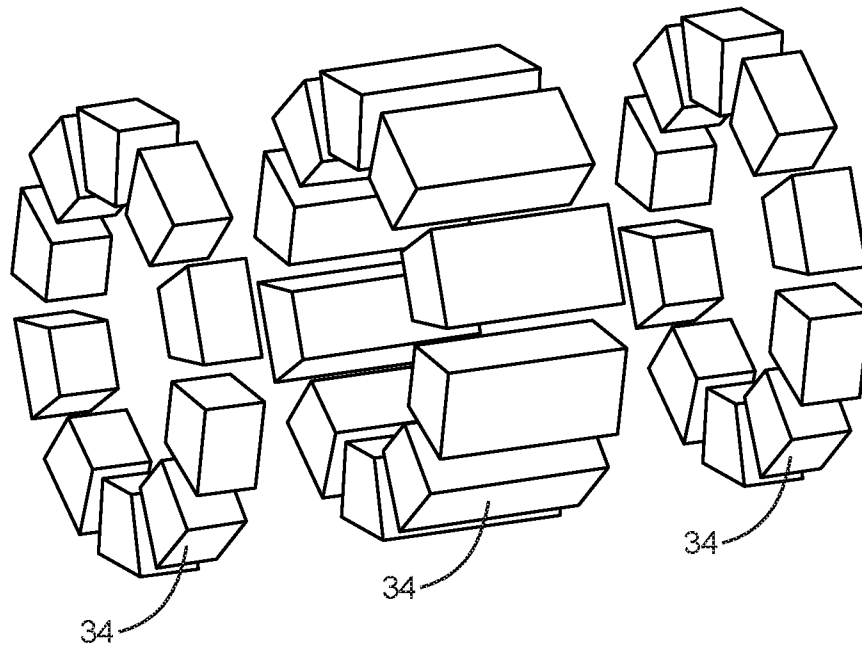


FIG. 3B

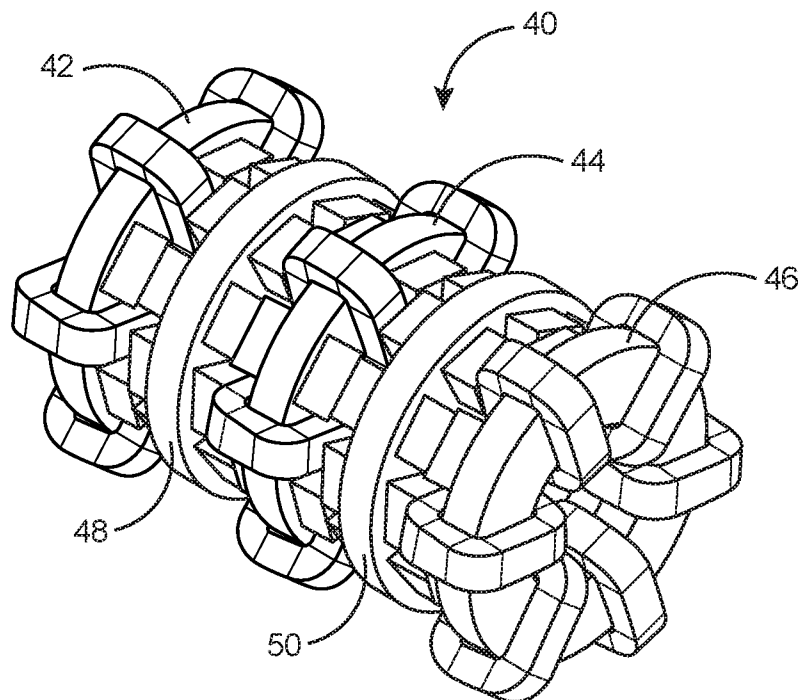


FIG. 4

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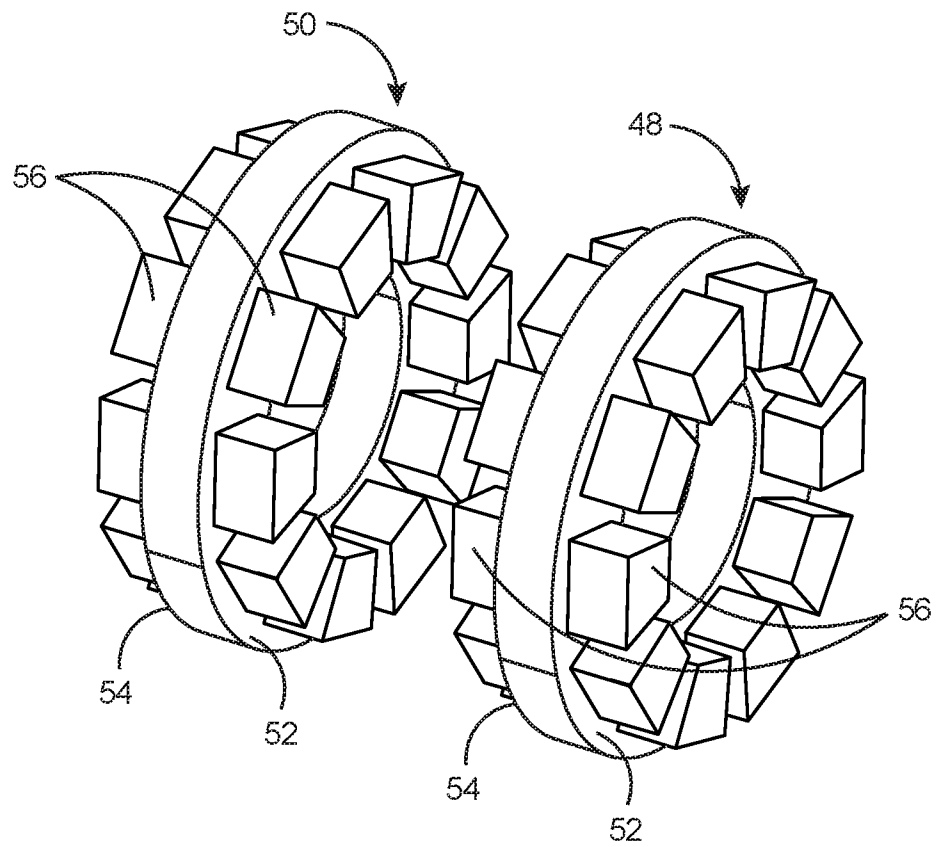


FIG. 5A

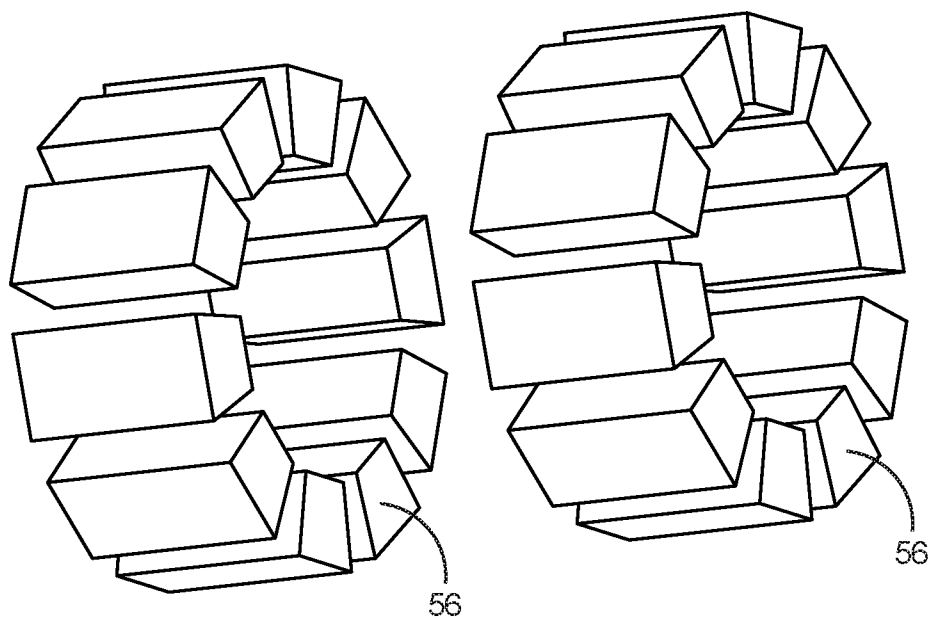


FIG. 5B

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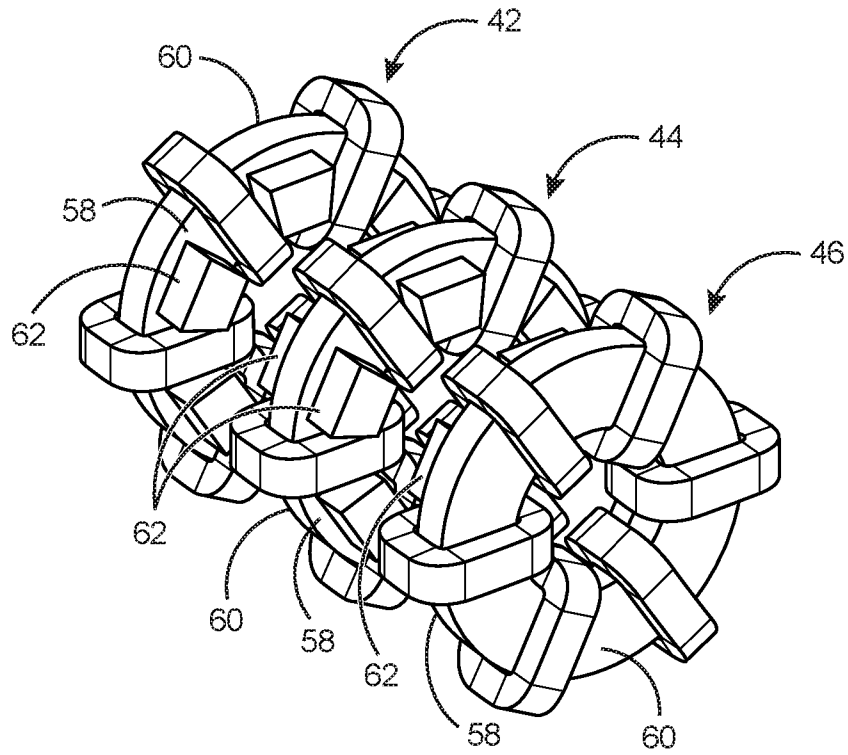


FIG. 5C

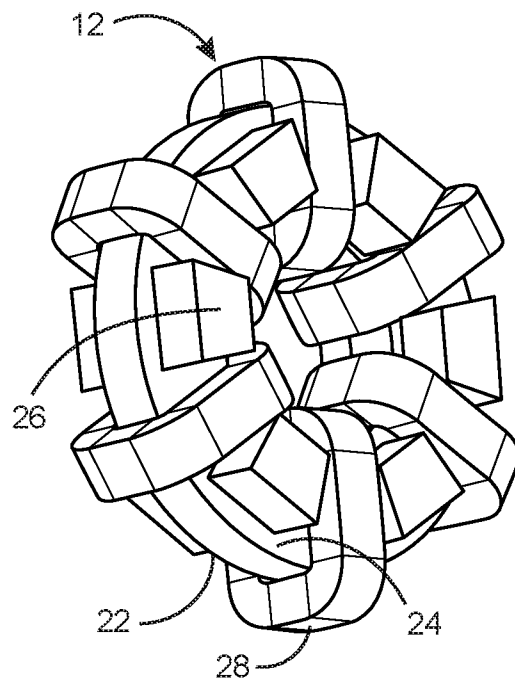


FIG. 6A

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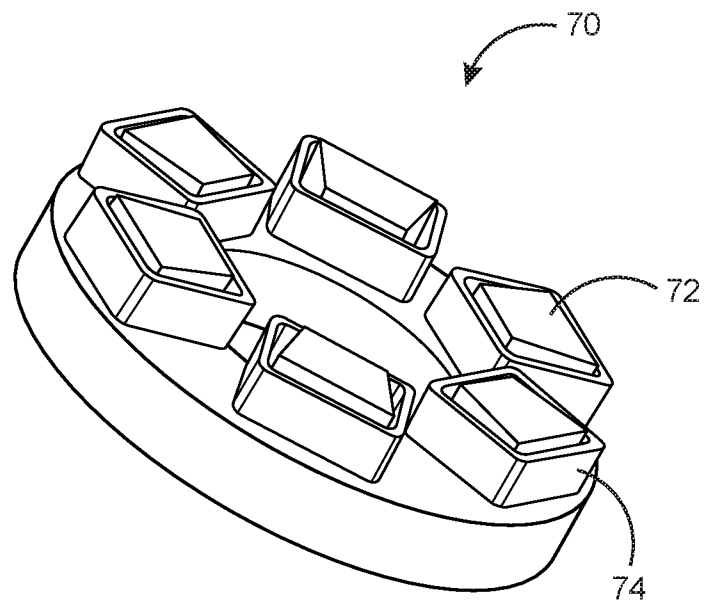


FIG. 6B

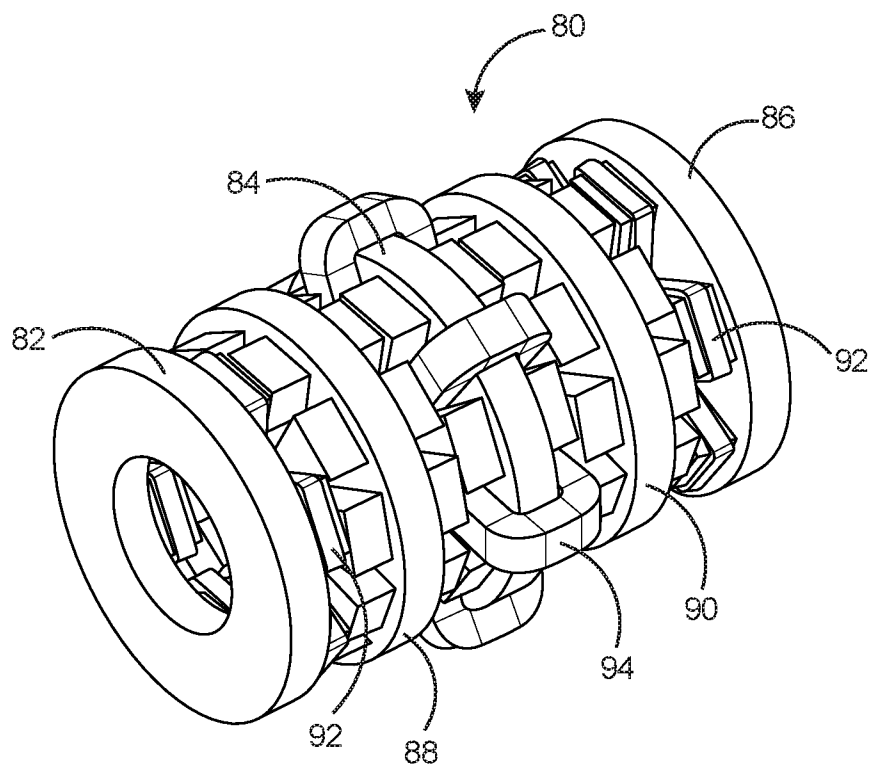


FIG. 7

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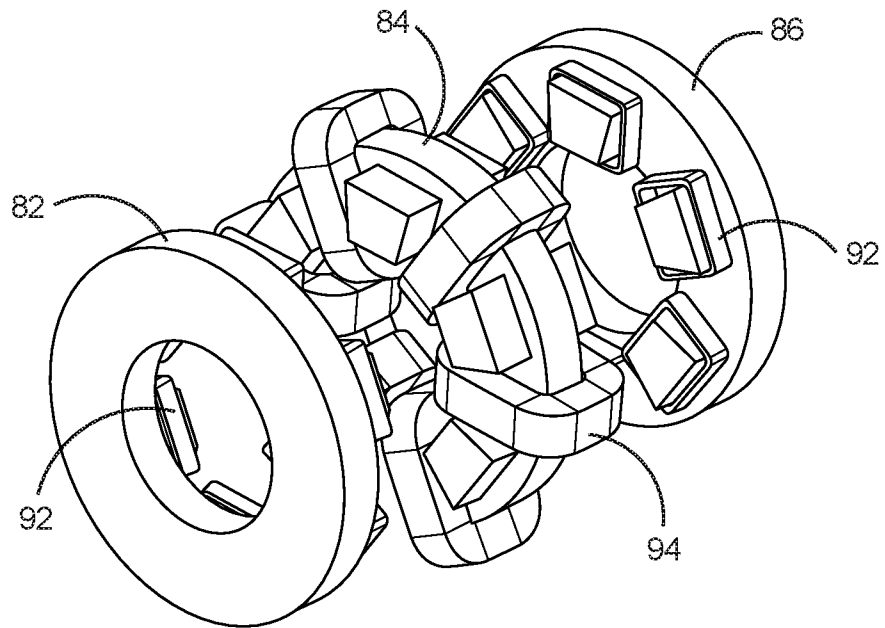


FIG. 8A

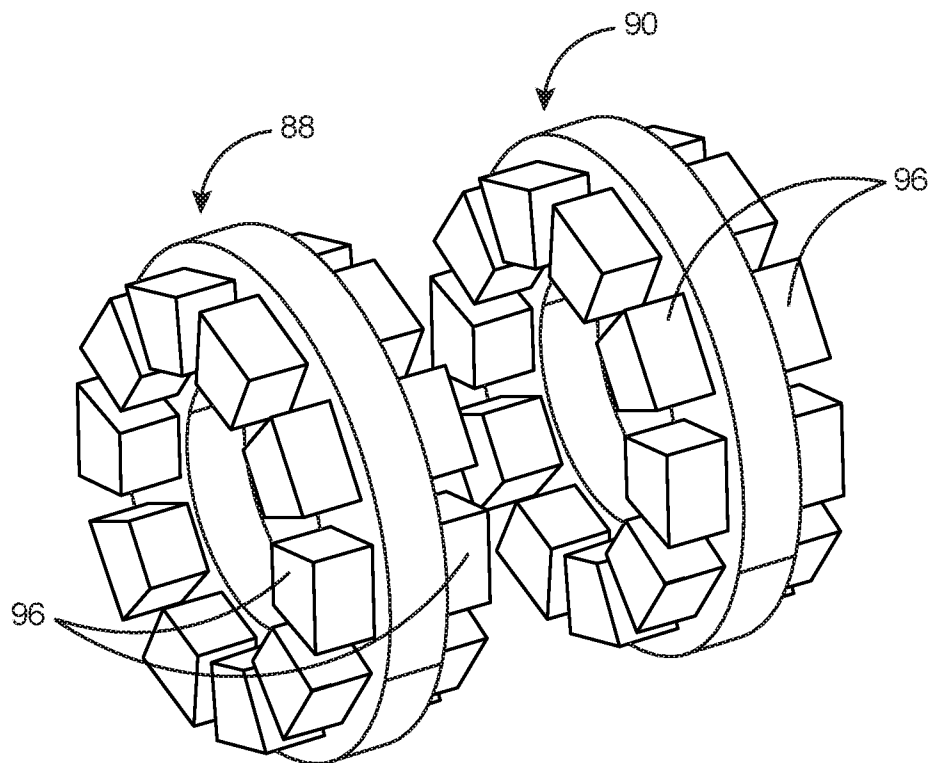


FIG. 8B

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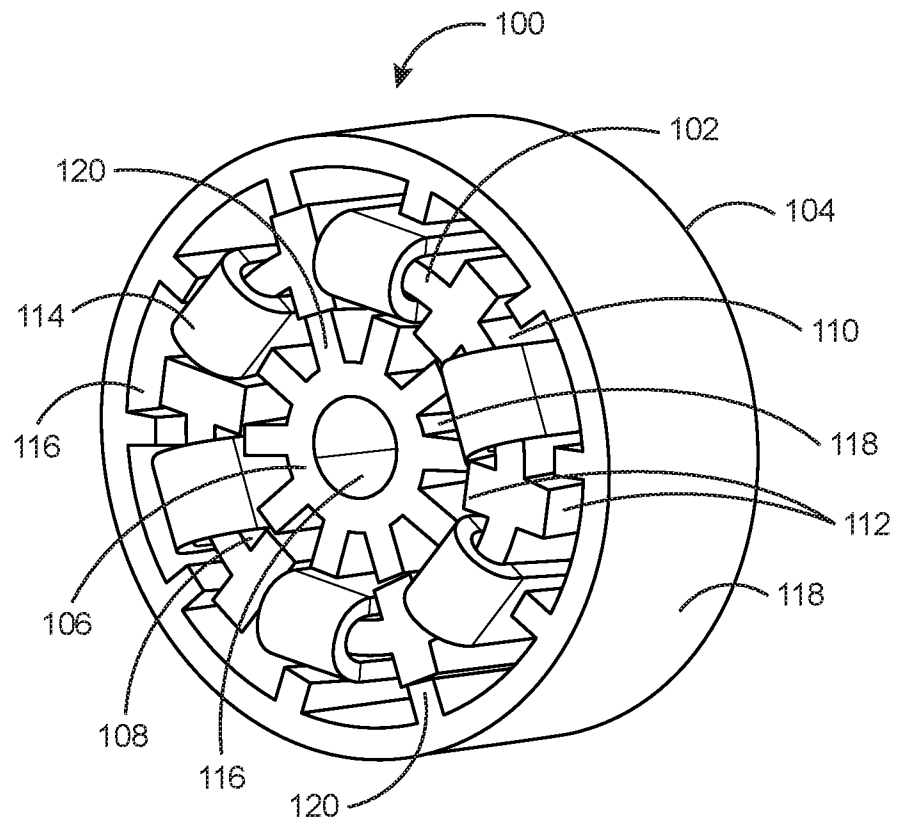


FIG. 9

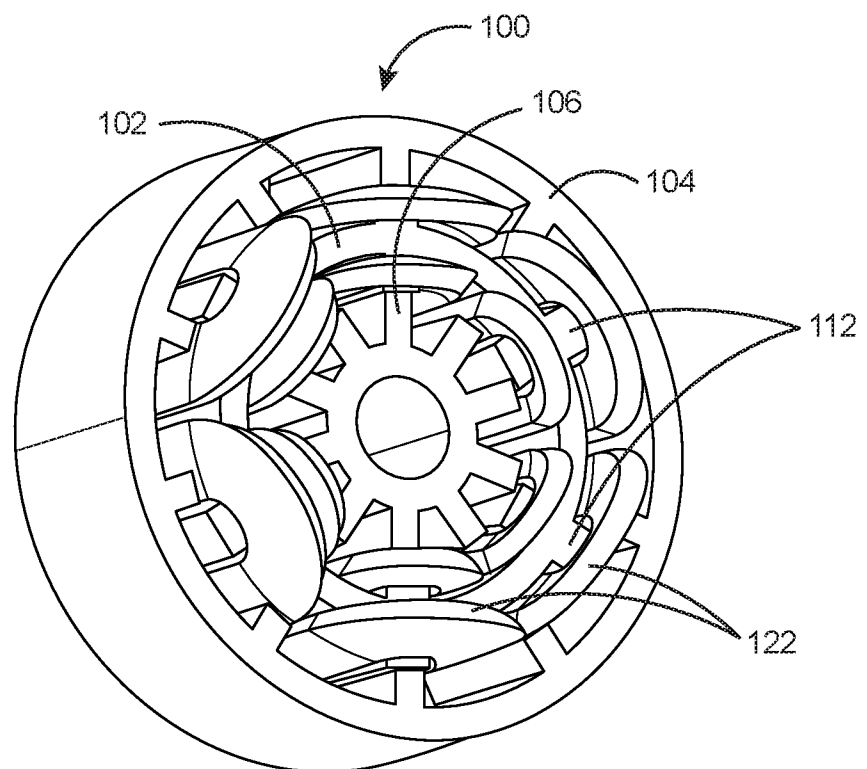


FIG. 10

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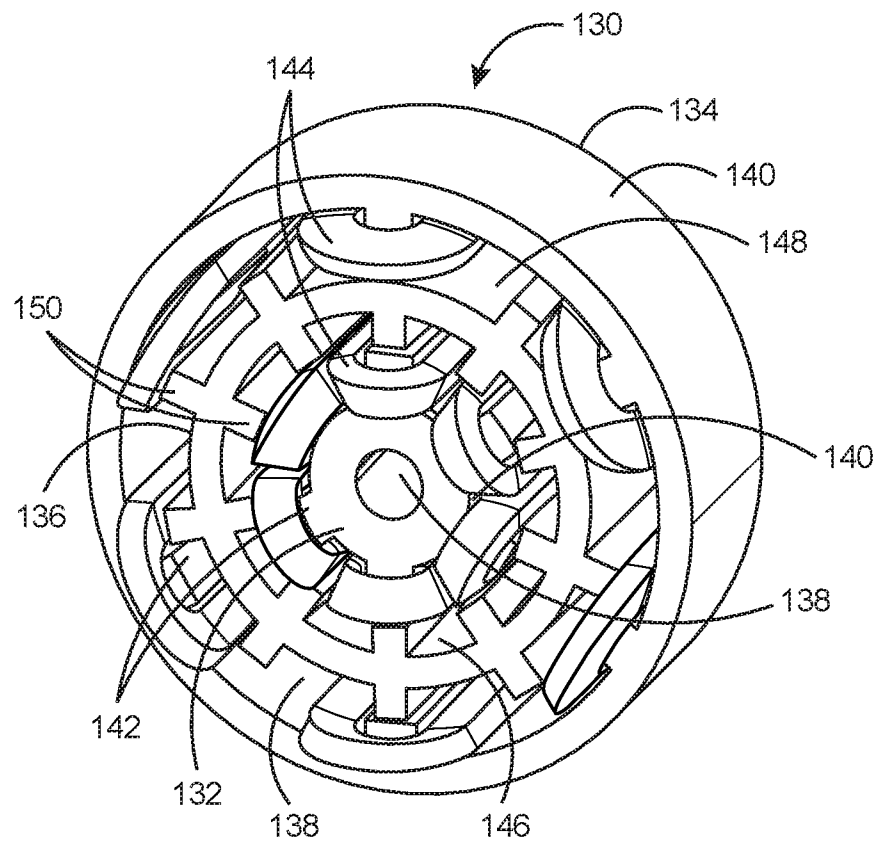


FIG. 11

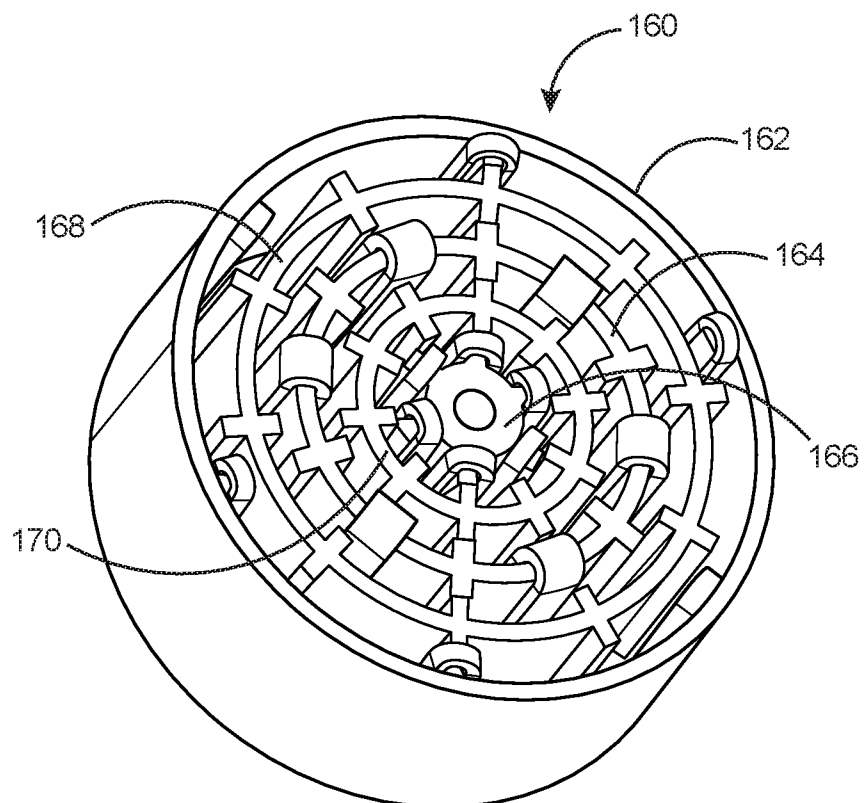


FIG. 12

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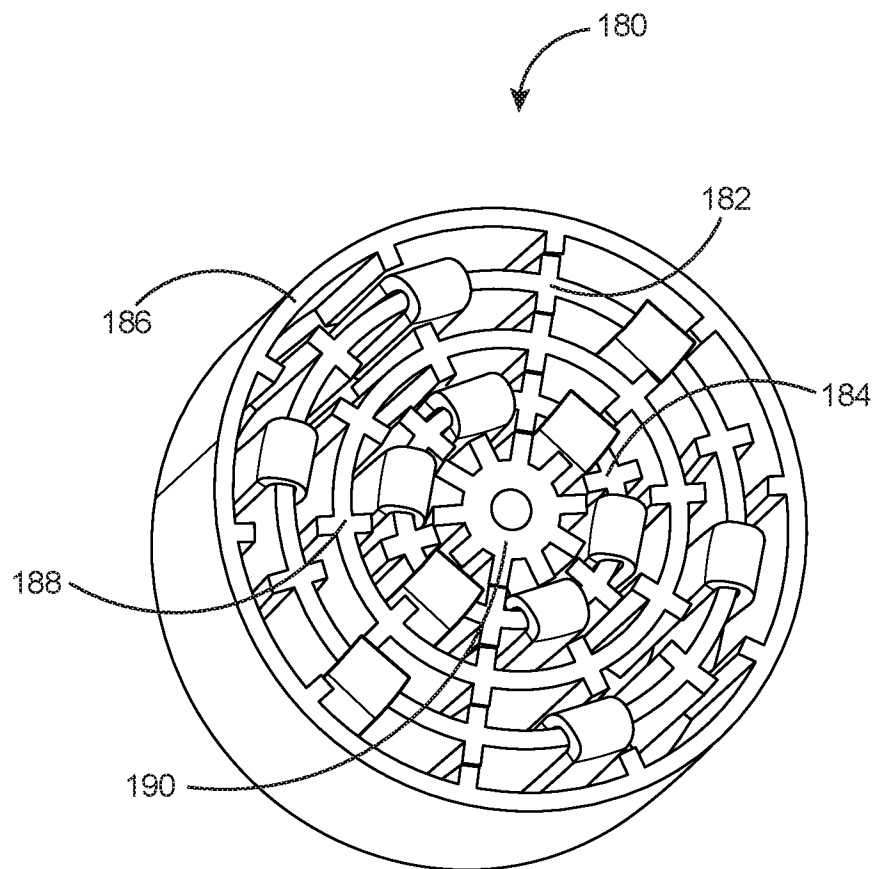


FIG. 13

INTERNATIONAL SEARCH REPORT

International application No.

PCT/US2016/016655

A. CLASSIFICATION OF SUBJECT MATTER

IPC(8) - H02P 25/08 (2016.01)

CPC - H02P 25/08 (2016.01)

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

IPC(8) - H02K 1/14, 21/12, 37/04; H02P 25/02, 25/08 (2016.01)

CPC - H02K 16/00, 19/103, 29/03; H02P 25/08 (2016.01)

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

US: 310/168, 310/216.075; 318/701 (keyword delimited)

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

PatBase, Google Patents, Google Scholar

Search terms used: stators, rotors, stator poles, rotor poles, switched reluctance, formula

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
Y	US 2011/0248582 A1 (DESAI et al) 13 October 2011 (13.10.2011) entire document	1-46
Y	LEITCH et al. Reduction of Unsteady Rotor-Stator Interaction Using Trailing Edge Blowing. 1997. [retrieved on 2016-03-28]. Retrieved from the Internet:<URL: https://vtechworks.lib.vt.edu/bitstream/handle/10919/30527/etd.PDF?sequence=1&isAllowed=y>. entire document.	1-46
A	US 2009/0072083 A1 (HANLON et al) 19 March 2009 (19.03.2009) entire document	1-46
A	US 5,652,493 A (HENDERSHOT, JR.) 29 July 1997 (29.07.1997) entire document	1-46
A	US 5,734,217 A (MORINIGO) 31 March 1998 (31.03.1998) entire document	1-46
A	US 2009/0309442 A1 (QU et al) 17 December 2009 (17.12.2009) entire document	1-46

☐ Further documents are listed in the continuation of Box C.☐ See patent family annex.

* Special categories of cited documents:

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"P" document published prior to the international filing date but later than the priority date claimed

"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone

"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art

"&" document member of the same patent family

Date of the actual completion of the international search

28 March 2016

Date of mailing of the international search report

14 APR 2016

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