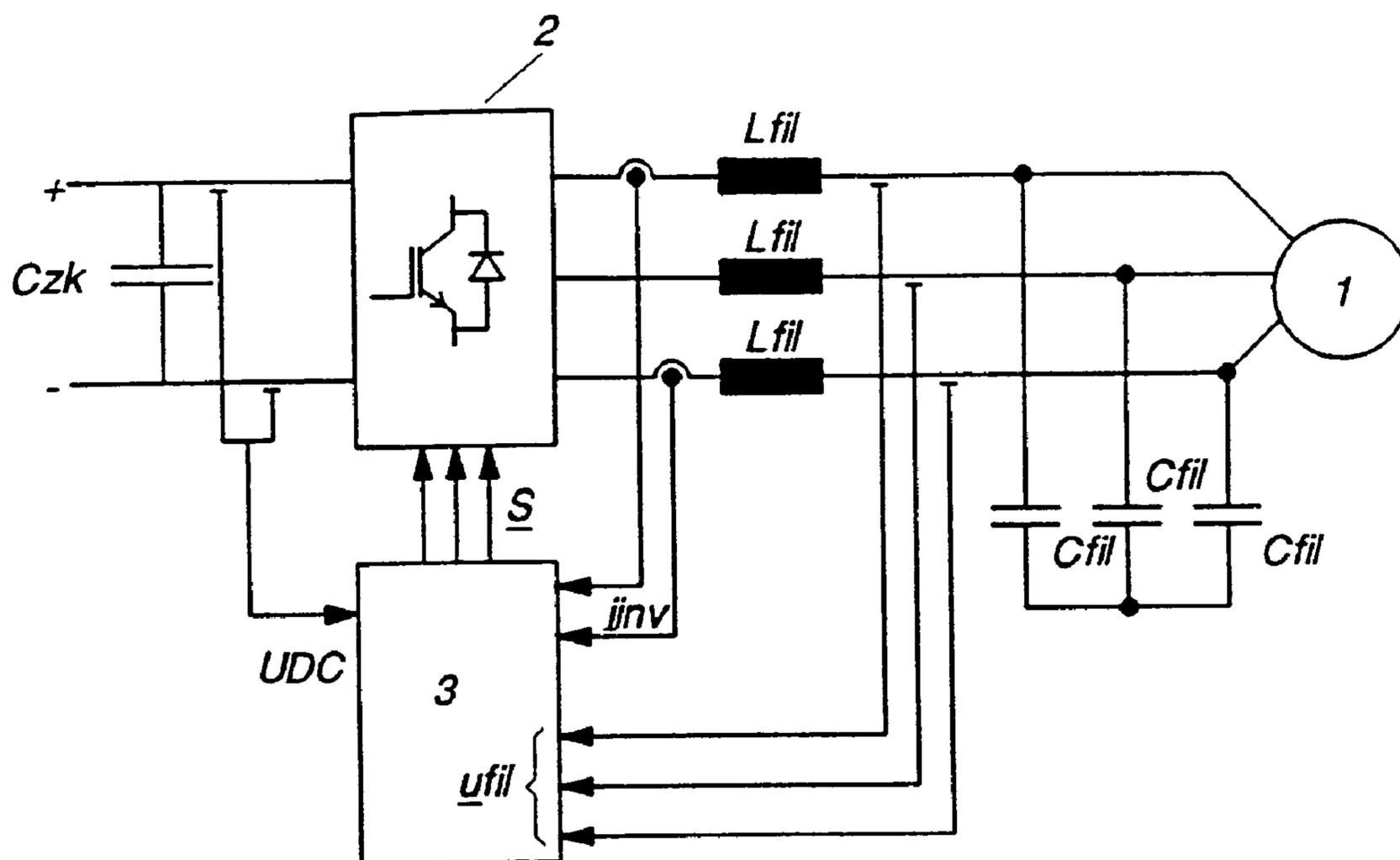




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(54) Titre : METHODE ET APPAREIL POUR LA COMMANDE DIRECTE DE COUPLE D'UNE MACHINE TRIPHASEE
 (54) Title: METHOD AND APPARATUS FOR DIRECT TORQUE CONTROL OF A THREE-PHASE MACHINE



(57) Abrégé/Abstract:

A method and an apparatus for direct torque control are specified for a three-phase machine fed via a harmonic filter, which method manages as far as possible without any major adaptation to already known DTC methods and DTC apparatuses. In addition, the oscillations caused by the filter are intended to be damped effectively. This is achieved in that a current flowing through the filter and/or a filter output voltage are/is measured, and the reference flux value and the reference torque value are corrected on the basis of the measured voltage and/or of the measured current. The correction comprises a transformation of the filter output voltage into a first component at right angles to a stator flux and into a second component parallel to the stator flux, as well as a reduction in the reference torque and flux values in proportion to the oscillating part of the filter output voltage.

ABSTRACT OF THE DISCLOSURE

A method and an apparatus for direct torque control are specified for a three-phase machine fed via a harmonic filter, which method manages as far as possible without any major adaptation to already known DTC methods and DTC apparatuses. In addition, the oscillations caused by the filter are intended to be damped effectively. This is achieved in that a current flowing through the filter and/or a filter output voltage are/is measured, and the reference flux value and the reference torque value are corrected on the basis of the measured voltage and/or of the measured current. The correction comprises a transformation of the filter output voltage into a first component at right angles to a stator flux and into a second component parallel to the stator flux, as well as a reduction in the reference torque and flux values in proportion to the oscillating part of the filter output voltage.

(Figure 3)

02199080TITLE OF THE INVENTION

Method and apparatus for direct torque control of a
5 three-phase machine

BACKGROUND OF THE INVENTIONField of the Invention

10 The invention relates to the field of power electronics. It is based on a method for Direct Torque Control (= DTC) according to the descriptive part of the first claim.

15 Discussion of Background

Such a method and a corresponding apparatus are described in the article "Direkte Drehmomentregelung von Drehstromantrieben" [Direct torque control of three-phase drives], ABB Technik 3/1995, pages 19-24.
20 This method is based on so-called "direct self-control", as is described in EP-B1-0 179 356. The DTC method represents a simple, reliable and highly dynamic torque control method for three-phase machines. In principle, it comprises the following steps:

- 25 · Calculation of an actual flux value from a converter voltage
- Calculation of an actual torque value
- Comparison of the actual flux value and the actual torque value with corresponding reference values
30 by means of a hysteresis controller
- Formation of an optimum control vector for the switches in the converter on the basis of the hysteresis controller.

In order to protect the machine against
35 excessively steep voltage flanks, which may lead to damage to the insulation, it is desirable to connect a harmonic filter between the converter and the motor. A control method is specified, for example, in EP-A2-0 595 319 for a system of pulse-duration-
40 modulated converters with a harmonic filter. The filter

capacitance and the filter inductance represent two
integrators in control engineering terms. There is thus
a 180° phase shift between the motor voltage and the
converter voltage at the switching frequency, in the
5 frequency band. This means that the signals required
for the DTC method are present with an incorrect
mathematical sign. Because of the 180° phase shift,
caused by the harmonic filter, between the motor
voltage and the converter voltage, the known DTC method
10 can no longer be applied directly to an arrangement
with a harmonic filter. In addition, disturbing
oscillations occur because of the filter resonance.

SUMMARY OF THE INVENTION

15

Accordingly, one object of the invention is to
provide a novel method and apparatus for direct torque
control for a three-phase machine fed via a harmonic
filter, which method manages as far as possible without
20 major adaptation to already known methods and
apparatuses. In addition, the oscillations caused by
the filter are intended to be damped effectively.

This object is achieved by the features of the
first claim for a method of the type mentioned
25 initially.

The essence of the invention is thus that a
current flowing through the filter and/or a filter
output voltage are/is measured, and the reference flux
value and the reference torque value are corrected on
30 the basis of the measured voltage and/or of the
measured current.

The correction comprises a transformation of
the filter output voltage into a first component at
right angles to a stator flux and into a second
35 component parallel to the stator flux as well as a
reduction in the reference torque and flux values in
proportion to the oscillating part of the filter output
voltage.

The oscillations caused by the harmonic filter can be effectively damped in this way.

The components can be calculated in various ways. Instead of a filter output voltage, a filter current can also be measured, and a filter voltage can be calculated from this. These variants are the subject matter of dependent claims. In addition, an apparatus for carrying out a method according to the invention is also specified.

Other exemplary embodiments result from the corresponding dependent claims.

The advantage of the design according to the invention is that the three-phase machine can be protected by the use of a harmonic filter against excessively steep voltage flanks which can lead to damage to the insulation, and, nevertheless, that essential parts of the DTC method and of a corresponding apparatus can be used without any major change.

In addition, oscillations caused by the filter can be damped effectively.

According to a further broad aspect of the present invention, there is provided a method direct torque control of a three-phase machine which is fed from a multi-phase converter via a harmonic filter (L_{fil} , C_{fil}) connected in between, which method comprises the following steps:

(a) Calculation of an actual flux value Ψ_{act} from a converter output voltage u_{inv} and a correction variable which corresponds essentially to a voltage drop across a copper resistance of the stator of the three-phase machine;

(b) Calculation of an actual torque value T_{act} from a current i_{inv} emitted by the converter and from the actual flux value Ψ_{act} ;

(c) Comparison of the magnitude of the actual flux value Ψ_{act} and of the actual torque value T_{act} by means of a hysteresis controller using a reference torque value T_{ref} or a reference flux value Ψ_{ref} ;

(d) Formation of an optimum control vector S (S_A , S_B , S_C) for the converter governed by the hysteresis controller and the magnitude of the actual flux value Ψ_{act} ;

5 wherein:

(e) a current i_{fil} flowing through the filter and/or a filter output voltage u_{fil} are/is measured and

(f) the reference flux value Ψ_{ref} and the reference torque value T_{ref} before they are supplied to the hysteresis controller are corrected on the basis of the current i_{fil} flowing through the filter and/or on the basis of the filter output voltage u_{fil} .

According to a still further broad aspect of the present invention, there is provided an apparatus for direct torque control of a three-phase machine which is fed from a multi-phase converter via a harmonic filter (L_{fil} , C_{fil}) connected in between, comprising:

(a) a torque controller, which:

calculates an actual flux value Ψ_{act} from a converter output voltage u_{inv} and a correction variable which corresponds essentially to a voltage drop across a copper resistance of the stator of the three-phase machine;

calculates an actual torque value T_{act} from a current i_{inv} emitted by the converter and by the actual flux value Ψ_{act} ;

compares the magnitude of the actual flux value Ψ_{act} and the actual torque value T_{act} by means of a hysteresis controller with an externally predetermined reference torque value T_{ref} and, respectively, a reference flux value Ψ_{ref} ; and

forms an optimum control vector S (S_A , S_B , S_C) for the converter governed by the hysteresis controller and the actual flux value Ψ_{act} ;

35 wherein:

(b) current and voltage instruments are provided which measure a current i_{fil} flowing through the filter and/or a filter output voltage u_{fil} , and

(c) means are provided which correct the reference flux value Ψ_{ref} and the reference torque value T_{ref} before they are supplied to the hysteresis controller on the basis of the current i_{fil} flowing through the filter and/or the filter output voltage u_{fil} .

BRIEF DESCRIPTION OF THE DRAWINGS

10 A more complete appreciation of the invention and many of the attendant advantages thereof will be readily obtained as the same becomes better understood by reference to the following detailed description when considered in connection with the accompanying
15 drawings, wherein:

Fig. 1 shows a circuit arrangement with a three-phase machine fed from a converter via a harmonic filter;

20

Fig. 2 shows a variant of Figure 1;

Fig. 3 shows a block diagram of an apparatus according to the invention, based on a first exemplary embodiment;

5 Fig. 4 shows a block diagram of an apparatus according to the invention, based on a second exemplary embodiment;

10 Fig. 5 shows a block diagram of an apparatus according to the invention, based on a third exemplary embodiment;

15 Fig. 6 shows a block diagram of an apparatus according to the invention, based on a fourth exemplary embodiment;

20 Fig. 7 shows a block diagram of an apparatus according to the invention, based on a fifth exemplary embodiment.

The designations used in the drawings and their meanings are listed in summary form in the List of Designations.

25 DESCRIPTION OF THE PREFERRED EMBODIMENTS

30 Referring now to the drawings, wherein like reference numerals designate identical or corresponding parts through the several views used, Figure 1 shows a circuit arrangement with a three-phase machine 1 which is fed from a converter 2 via a harmonic filter comprising a three-phase network with filter inductances L_{fil} and filter capacitances C_{fil} . The capacitances of the filter are combined to form a star point, which is not connected to the intermediate circuit. The intermediate circuit is represented by the intermediate-circuit capacitor C_{zk} . A DC voltage U_{DC} is applied to the intermediate-circuit capacitor. A torque controller 3 is provided for torque control of the

motor 1. This is fed, according to Figure 1, from the intermediate-circuit voltage U_{DC} , from a current i_{inv} emitted by the converter, and from a filter output voltage u_{fil} . In the variant according to Figure 2, a filter current i_{fil} may also be measured instead of the filter output voltage u_{fil} . The converter 2 may be either a two-point inverter or a three-point inverter.

Underlined variables in each case designate vectors in the following text. These may be transformed into vectors from the measured conductor currents or conductor voltages in the phases, using the known $120^\circ/90^\circ$ transformation.

The torque controller 3 uses the measured variables as well as a reference flux value Ψ_{ref} and a reference torque value T_{ref} to calculate an optimum control vector $\underline{s}(S_A, S_B, S_C)$ which is used for driving the switches in the converter 2.

Figures 3-7 show block diagrams of various variants of torque controllers 3. That part of the regulator which is above the dashed line corresponds to the already known DTC controllers. The lower part comprises the adaptations according to the invention.

In the following text, the fundamental principle of DTC control will be discussed briefly once again, and the problems on which the invention is based will be explained:

In the DTC method, an actual flux value Ψ_{act} is calculated from a converter output voltage u_{inv} and a correction variable. The correction variable corresponds, to a first approximation, to the voltage drop $R_S \cdot i_S$ across the copper resistance of the stator. The calculation is much more accurate if a motor model is used as an aid. However, this is not important to the invention, so that further reference at this point will be to the said voltage drop.

The actual flux value is thus given by: $\Psi_{act} = \int (u_{inv} - R_S i_S) dt$. The converter output voltage u_{inv} is in this case formed with the aid of a voltage forming element 8 from the intermediate-circuit voltage U_{DC} and

the actual control vector \underline{S} . An actual torque value T_{act} is subsequently formed from the calculated actual flux value Ψ_{act} and a current \underline{i}_{inv} emitted by the converter. The current \underline{i}_{inv} is obtained by measuring two phase currents and by transformation into a vector. The actual torque value T_{act} is obtained, finally, by forming the vector product of the current \underline{i}_{inv} and of the flux Ψ_{act} . In addition, the magnitude Ψ_{act} of the actual flux value Ψ_{act} is also formed. T_{act} and Ψ_{act} are subsequently compared, by means of a hysteresis controller 4, with corresponding externally predetermined reference values Ψ_{ref} and T_{ref} . The result of this comparison and the result of a vector assigner 12, which uses the actual flux value Ψ_{act} to determine an actual flux vector, are supplied to a logic circuit 13 which determines an optimum control vector $\underline{S}(S_A, S_B, S_C)$ for the converter.

However, if a harmonic filter is now connected between the converter and the motor as in the case of the invention, then, on the one hand, there is a 180° phase shift in the current and voltage at the switching frequency because of the double integration of the filter, so that the DTC method can no longer be applied directly. On the other hand, the filter causes resonant oscillations, which are intended to be damped. The known method and the known apparatus must therefore be adapted, as is described in the following text.

The adaptation essentially comprises a current flowing through the filter and/or a filter output voltage being measured, and the reference flux value, or its magnitude, and the reference torque value being corrected on the basis of the measured filter variables. In particular, they are reduced in proportion to an oscillating part of the filter output voltage. There are various variants for calculating these oscillating disturbance variables:

A first exemplary embodiment (Figure 3) comprises measurement of the filter output voltage on each phase and conversion, for example by means of

120°/90° transformation, into a vector \underline{u}_{fil} . In addition, the product $\underline{i}_{inv}L_{fil}$ is subtracted from the actual flux value Ψ_{act} . A multiplier 5 and a subtractor 7 are provided for this purpose. In this way, a variable Ψ_S is obtained, which corresponds to a stator flux. The voltage \underline{u}_{fil} is now split into a component $u_{fil d}$ parallel to Ψ_S and into a component $u_{fil q}$ at right angles to Ψ_S . A vector product forming element 9 and a scalar product forming element 10 are provided for this purpose, which multiply the voltage \underline{u}_{fil} by Ψ_S . The component $u_{fil q}$ is produced from the vector product, and the component $u_{fil d}$ from the scalar product. $u_{fil d}$ represents just that proportion of the filter output voltage causing the oscillations and is therefore multiplied in a further multiplier 5 by the constant K_1 , is supplied to a limiter 6 and is subtracted from the reference flux value Ψ_{ref} in a subtractor 7. The oscillating part of $u_{fil q}$ must also be formed, in contrast. This is done according to Figure 3 by subtracting a constant value $\omega \cdot \Psi_S$ from $u_{fil q}$. ω in this case corresponds to the angular frequency of the stator flux. In the steady state, $u_{fil q}$ should correspond precisely to this value, so that the difference $u_{fil q} - \omega \cdot \Psi_S$ thus corresponds just to the oscillating part $\Delta u_{fil q}$ of $u_{fil q}$. This value is likewise multiplied in a multiplier 5 by a second constant K_2 , and is supplied to a limiter 6. Finally, the reference torque value is reduced by means of a further subtractor 7, using the output of this limiter 6.

The essence of the method and of the apparatus according to the invention is thus based on the fact that the influence of the harmonic filter is included in the control system, in that those elements of the filter output voltage which cause the oscillations are first of all damped and a virtual converter flux and a converter moment, so to speak, are controlled as actual variables instead of directly controlling variables

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which correspond to the motor flux or motor moment upstream of the filter.

5 A second exemplary embodiment (Figure 4) differs from the first in that the oscillating parts of the components $u_{fil d}$ and $u_{fil q}$ are obtained by means of high-pass filtering. Two high-pass filters are provided for this purpose and are connected upstream of the multipliers 5, after the vector and scalar product formation 9, 10.

10 In the case of a third exemplary embodiment (Figure 5), a filter current i_{fil} is measured instead of a filter output voltage u_{fil} . Figure 5 is thus based on Figure 2. i_{fil} is obtained, for example, by measuring two currents flowing through the filter
15 capacitors C_{fil} , and by converting these currents into a vector. Two currents are sufficient, since the sum of all the currents must be zero because of the star connection of the capacitors. The voltage u_{fil} across the capacitor can be calculated from the current i_{fil}
20 by means of limited integration. A limited integrator 15 is provided for this reason in Figure 5 at the input of i_{fil} . Otherwise, the arrangement in Figure 5 corresponds to that in Figure 4.

25 The variant according to Figure 3 can, of course, also be applied to the third exemplary embodiment. According to a fourth exemplary embodiment (Figure 6), the integration can also be carried out after the scalar and vector product formation.

30 Finally, Figure 7 shows an exemplary embodiment based on Figure 2, in which the integration for the component formation is carried out, on the one hand, before the scalar product formation 10 and, on the other hand, after the vector product formation 9. Since the current i_{fil} should be parallel to ψ_s from the
35 start, the remaining part of a vector product represents just the element causing oscillations. The situation with the scalar product is the converse of this, since the voltage multiplied by the ψ_s should result in zero here. For this reason, the voltage is

calculated first for the scalar product formation, and not until after this for the vector product formation.

The invention has the advantage that the known DTC method and the known DTC apparatus can also
5 continue to be used essentially for an arrangement having a harmonic filter. The invention makes available an addition which is suitable for use with a harmonic filter and leaves the known part virtually undisturbed. An existing system can therefore be extended in a
10 simple manner without having to dispense with the advantages of a harmonic filter.

Obviously, numerous modifications and variations of the present invention are possible in light of the above teachings. It is therefore to be
15 understood that within the scope of the appended claims, the invention may be practiced otherwise than as specifically described herein.

1. A method for direct torque control of a three-phase machine which is fed from a multi-phase converter via a harmonic filter (L_{fil} , C_{fil}) connected in between, which method comprises the following steps:

(a) Calculation of an actual flux value Ψ_{act} from a converter output voltage u_{inv} and a correction variable which corresponds essentially to a voltage drop across a copper resistance of the stator of the three-phase machine;

(b) Calculation of an actual torque value T_{act} from a current i_{inv} emitted by the converter and from the actual flux value Ψ_{act} ;

(c) Comparison of the magnitude of the actual flux value Ψ_{act} and of the actual torque value T_{act} by means of a hysteresis controller using a reference torque value T_{ref} or a reference flux value Ψ_{ref} ;

(d) Formation of an optimum control vector S (S_A , S_B , S_C) for the converter governed by the hysteresis controller and the magnitude of the actual flux value Ψ_{act} ;

wherein:

(e) a current i_{fil} flowing through the filter and/or a filter output voltage u_{fil} are/is measured and

(f) the reference flux value Ψ_{ref} and the reference torque value T_{ref} before they are supplied to the hysteresis controller are corrected on the basis of the current i_{fil} flowing through the filter and/or on the basis of the filter output voltage u_{fil} .

2. The method as claimed in Claim 1, wherein the reference flux value Ψ_{ref} and the reference torque value T_{ref} are corrected in that:

(a) a stator flux Ψ_s is formed from a difference between the actual flux value Ψ_{act} and a product of the current i_{inv} emitted by the converter with an inductance L_{fil} of the harmonic filter;

(b) the stator flux Ψ_s is used to convert the filter output voltage u_{fil} into a component $u_{fil d}$ parallel

to the stator flux and into a component u_{filq} at right angles to the stator flux;

(c) the reference flux value Ψ_{ref} is reduced by an amount proportional to the component u_{fild} , and the reference torque value T_{ref} is reduced in proportion to an oscillating element Δu_{qfil} of the component u_{filq} .

3. The method as claimed in Claim 2, wherein the oscillating element Δu_{filq} of the component u_{filq} is produced from a difference between the component u_{filq} and the product $\bar{\omega}\Psi_s$ of the stator flux Ψ_s and an angular frequency $\bar{\omega}$ of the stator flux Ψ_s .

4. The method as claimed in Claim 2, wherein the oscillating element Δu_{filq} of the component u_{filq} is produced by high-pass filtering of component u_{filq} .

5. The method as claimed in Claim 4, wherein the component u_{fild} is also subjected to high-pass filtering.

6. The method as claimed in Claim 3, wherein:

(a) the current i_{fil} flowing through the filter is measured; and

(b) the filter output voltage u_{fil} is produced by integration of the current i_{fil} .

7. The method as claimed in Claim 2, wherein the filter output voltage u_{fil} is converted into the component u_{fild} parallel to the stator flux, and the component u_{filq} at right angles to the stator flux Ψ_s is converted by formation of the scalar product and vector product of u_{fil} and the stator flux Ψ_s .

8. An apparatus for direct torque control of a three-phase machine which is fed from a multi-phase converter via a harmonic filter (L_{fil} , C_{fil}) connected in between, comprising:

(a) a torque controller, which:

calculates an actual flux value Ψ_{act} from a converter output voltage u_{inv} and a correction variable which corresponds essentially to a voltage drop across a copper resistance of the stator of the three-phase machine;

calculates an actual torque value T_{act} from a current i_{inv} emitted by the converter and by the actual flux value Ψ_{act} ;

compares the magnitude of the actual flux value Ψ_{act} and the actual torque value T_{act} by means of a hysteresis controller with an externally predetermined reference torque value T_{ref} and, respectively, a reference flux value Ψ_{ref} ; and

forms an optimum control vector S (S_A , S_B , S_C) for the converter governed by the hysteresis controller and the actual flux value Ψ_{act} ;

wherein:

(b) current and voltage instruments are provided which measure a current i_{fil} flowing through the filter and/or a filter output voltage u_{fil} , and

(c) means are provided which correct the reference flux value Ψ_{ref} and the reference torque value T_{ref} before they are supplied to the hysteresis controller on the basis of the current i_{fil} flowing through the filter and/or the filter output voltage u_{fil} .

9. The apparatus as claimed in Claim 8, wherein the second means comprise:

(a) a first multiplier for forming a product of the current i_{inv} emitted by the converter with an inductance L_{fil} of the harmonic filter;

(b) a first subtractor which calculates a stator flux Ψ_s from a difference between the actual flux value Ψ_{act} and the product of the current i_{inv} emitted by the converter with the inductance L_{fil} of the harmonic filter;

(c) a coordinate transformer, which uses the stator flux Ψ_s to convert the filter output voltage u_{fil}

into a component u_{fild} parallel to the stator flux and a component u_{filq} at right angles to the stator flux; and

(d) a reference value controller which reduces the reference flux value Ψ_{ref} by an amount proportional to the component u_{fild} and reduces the reference torque value T_{ref} in proportion to an oscillating element Δu_{qfil} of the component u_{filq} .

10. The apparatus as claimed in Claim 9, wherein, both for the component u_{fild} and for the component u_{filq} , the reference value controller comprises in each case one multiplier which multiplies the components by a first constant $K1$ or, respectively, by a second constant $K2$, in each case one limiter connected downstream of the multipliers, and in each case one subtractor connected downstream of the limiters, the subtractor assigned to the component u_{fild} acting on the reference flux value Ψ_{ref} , and the subtractor assigned to the component u_{filq} acting on the reference torque value T_{ref} .

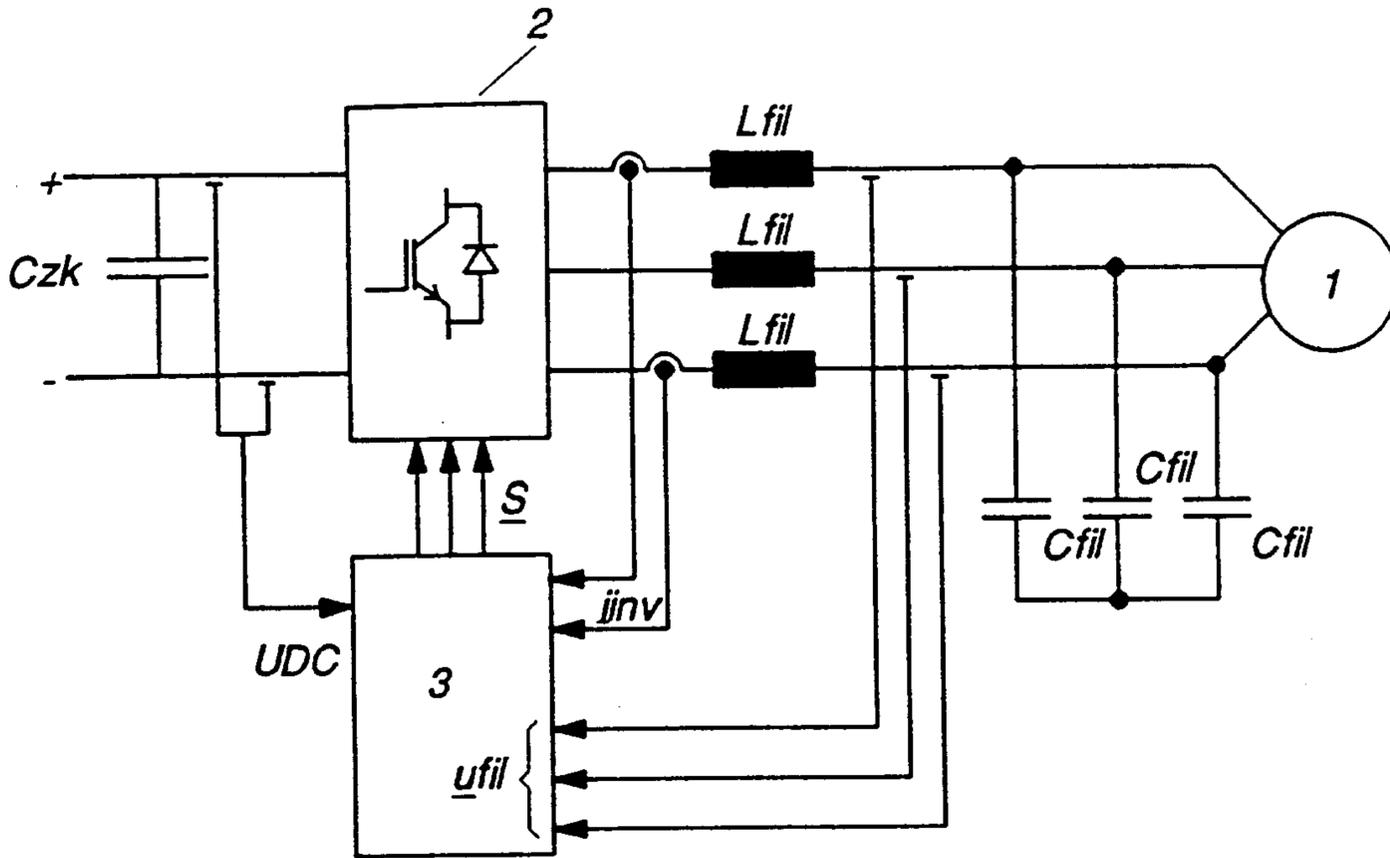


Fig.1

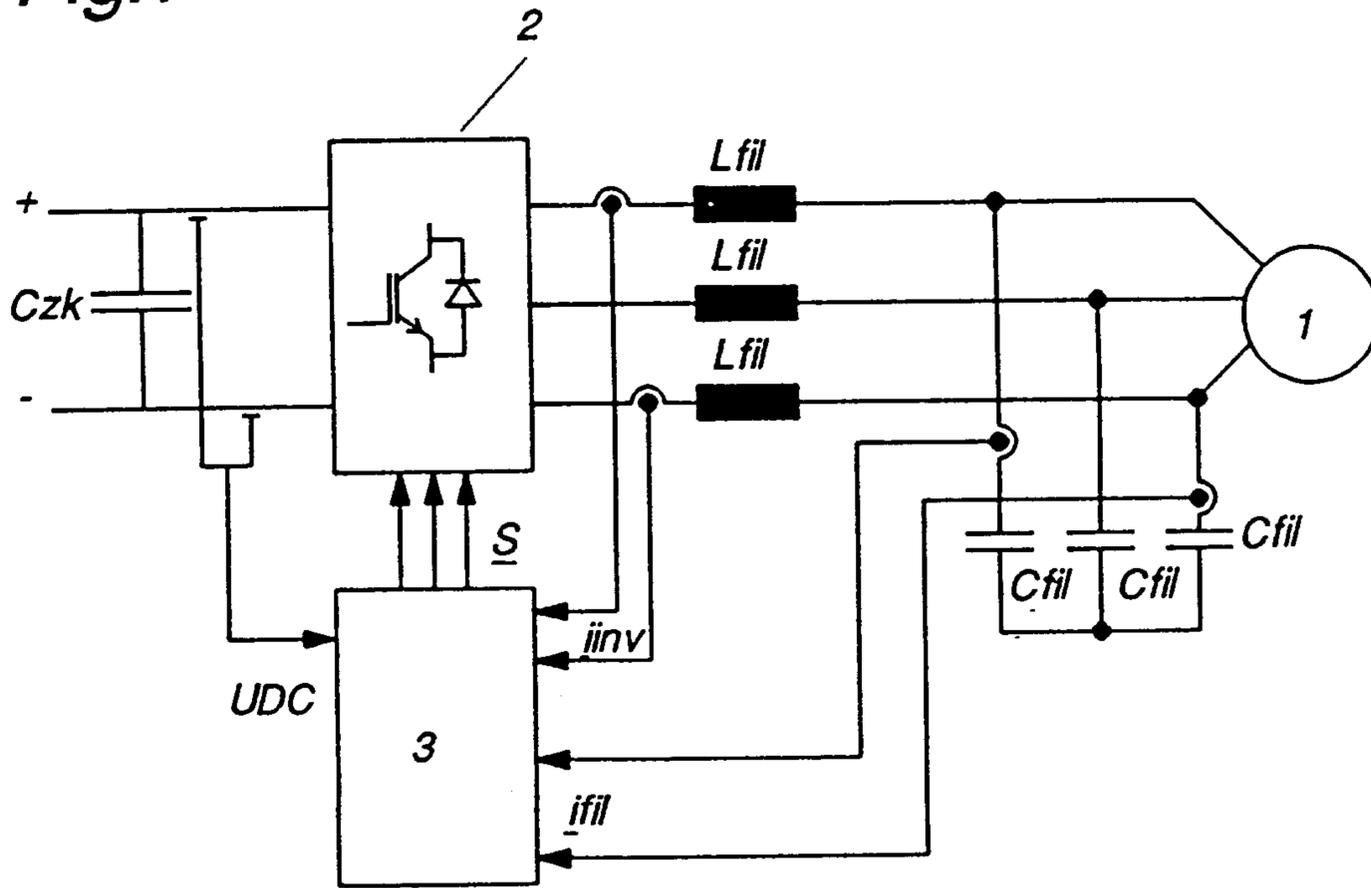


Fig.2

PATENT AGENTS

Dwabej Ogilvy Renault

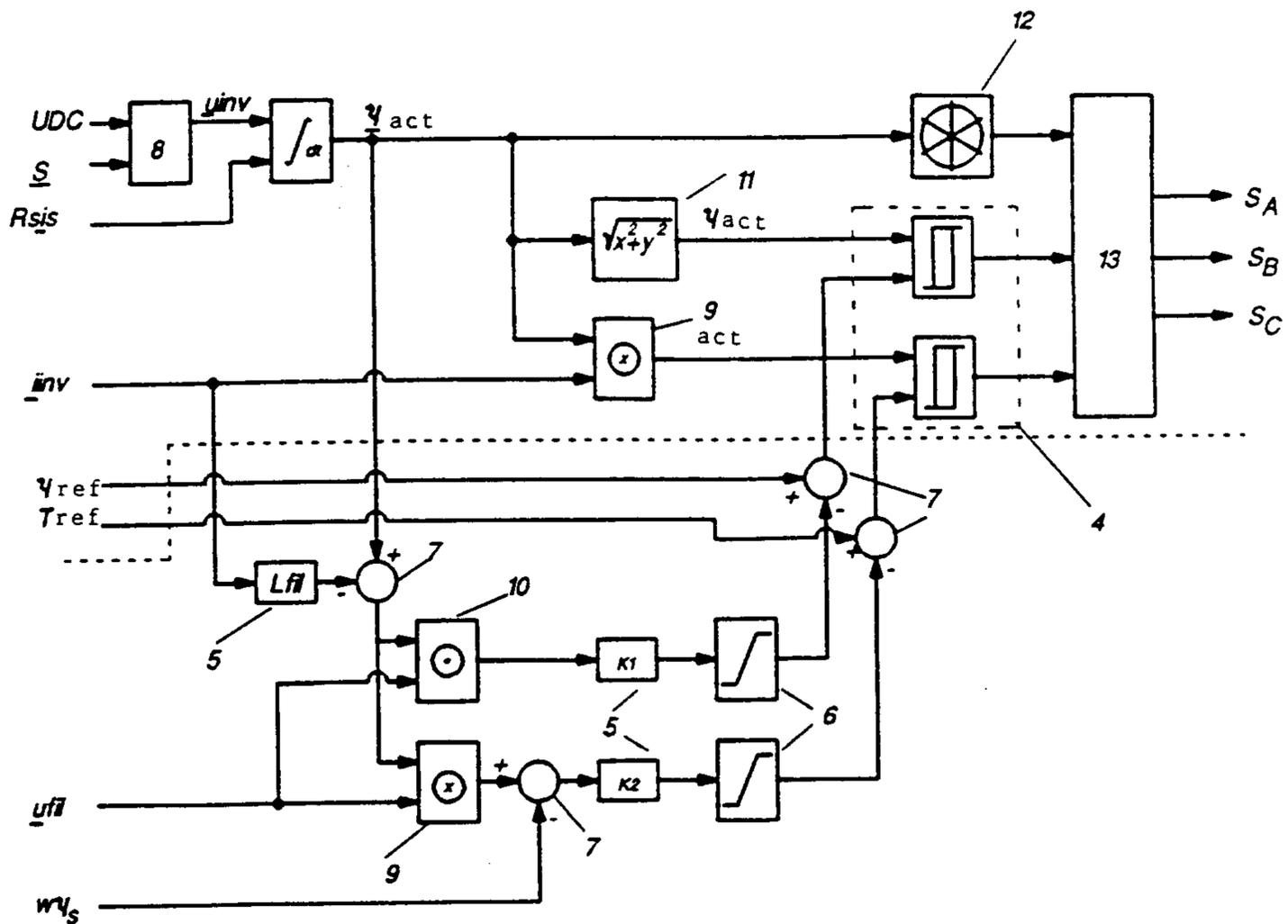


Fig.3

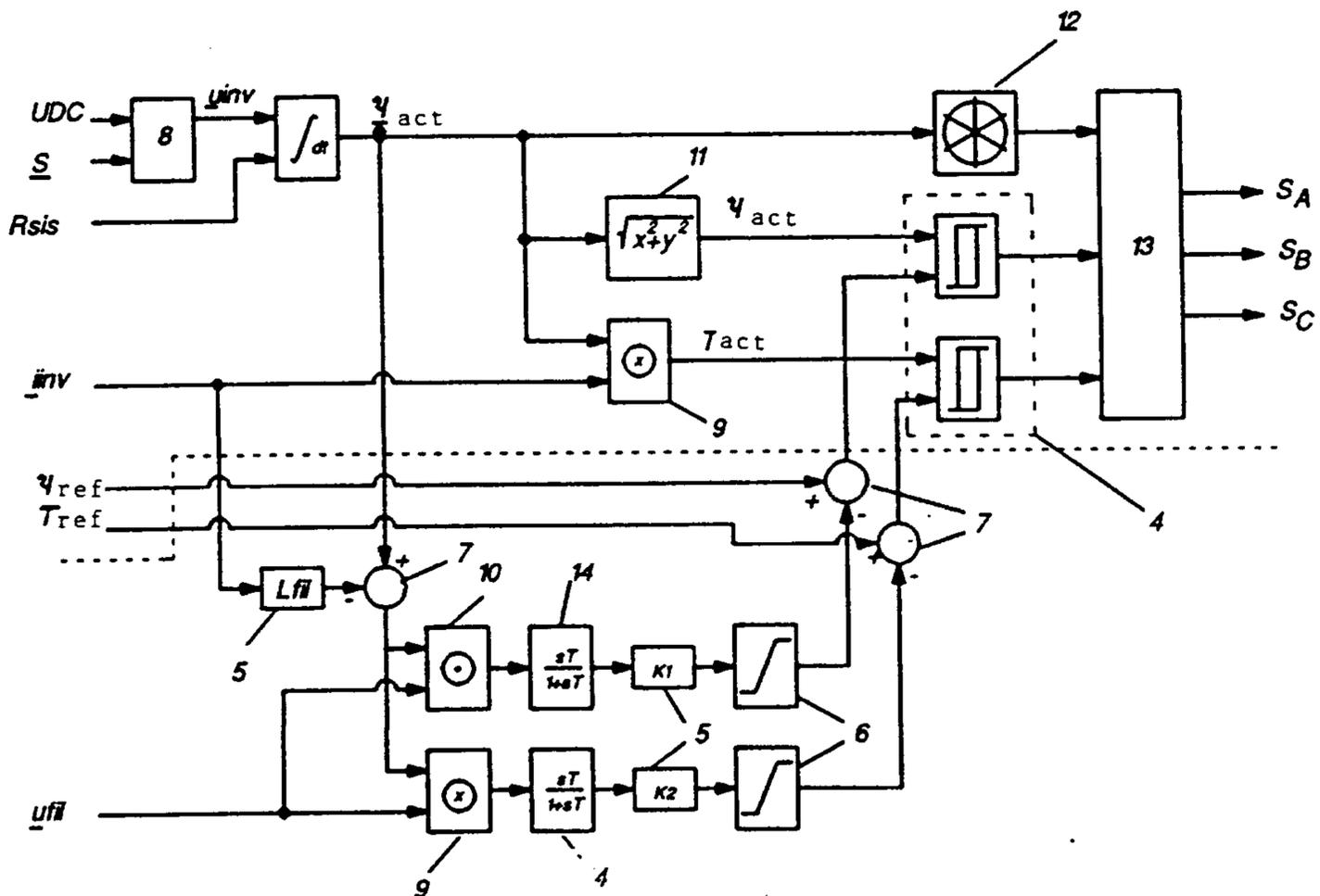


Fig.4

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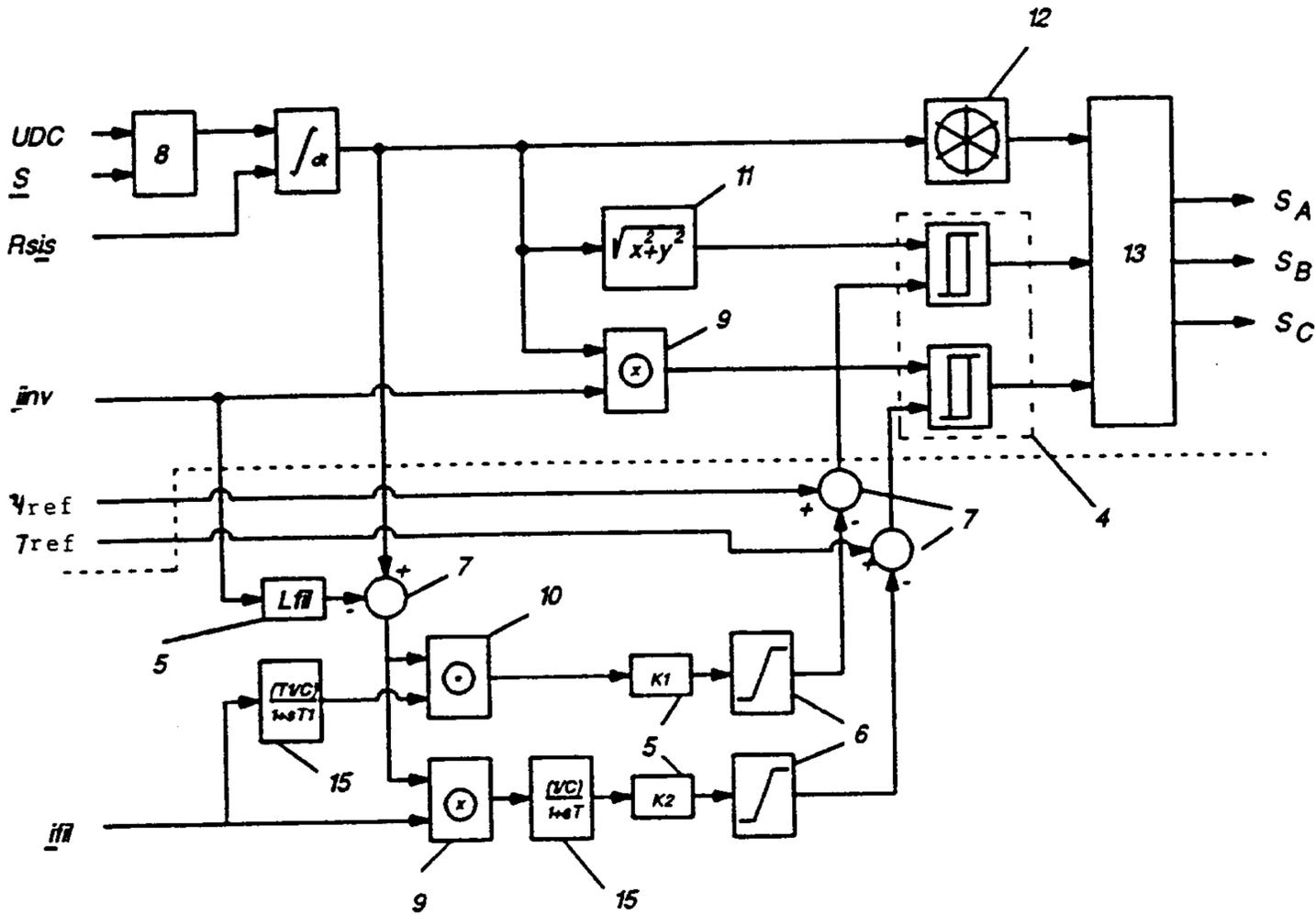


Fig.7

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