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## DESCRIPTION

### Field of the invention

[0001] The present invention relates to sensor systems comprising sensor devices for use when implementing smart waste collection systems, for example to sensor devices for smart waste collection systems, wherein the systems include one or more smart trash containers including one or more associated sensor devices, and wherein the one or more sensor devices are wireless-enabled for communicating to a control centre for receiving waste-indicative signals from the one or more smart trash containers for devising an optimal schedule for one or more waste collection vehicles to collect waste from the one or more smart trash containers. Moreover, the present invention concerns methods of installing aforesaid sensor devices to trash containers to convert them to smart trash containers.

### Background of the invention

[0002] As human population grows, as human population's standard of living improves resulting in more use of Earth's resources, and Earth's resources become increasingly depleted with progression of time, there arises an increased need to recycle materials and reduce generation of waste. Moreover, there is also an increasing need to ensure that such recycling is executed in a manner which itself employs as few resources as possible, namely in manner which is most efficient.

[0003] In technologically-advanced countries, waste management industries are growing in importance and need to employ increasingly efficient processes to increase revenue margins, namely such waste management industries need to optimize their resource utilization, for example use of waste collection vehicles, use of waste collection personnel and similar. Based upon contemporary data from *Environmental Business International*, the United States of America (USA) has a solid-waste management industry which has grown in value from 39.4 billion US dollars in the year 2000 to 52.40 billion US dollars in the year 2010.

[0004] An effective manner to increase operating efficiency in waste management industries is to implement waste containers, namely "trash containers", in a smart manner. Such a smart manner requires one or more sensor devices to be attached to each waste container, wherein the one or more sensor devices are wireless-enabled for communicating to a waste-collection coordinating arrangement, for example a waste-collection control centre, and one or more sensors for sensing a quantity and/or state of waste in the container. Moreover, there is also a need to be able to retrofit such one or more sensor devices to existing waste containers to convert them to being smart waste containers.

[0005] Several problems are encountered in practice when implementing an aforementioned waste management system employing a plurality of smart waste containers which are spatially distributed at customer premises. A first problem arising is that the waste containers themselves are often housed outside buildings and hence subject to extremes of weather conditions, for example sub-zero temperatures in winter, and elevated temperatures in summer due to incident solar radiation thereupon; in consequence, their sensor devices need to be able to function over a wide range of environmental temperatures. A second problem is that waste containers often need to be substantially sealed when in a closed state, for example to prevent animals such as rats, mice and insects gaining access to contents of the waste containers that could result in a public health risk; when wet waste is placed into the waste containers, a humidity within the waste containers is potentially high, with a risk of condensation occurring on an inside lid surface and walls of the waste containers, for example when a sudden fall in external temperature outside the waste containers occurs, for example at dusk after a warm summer day. A third problem encountered is that contemporary waste containers are often fabricated from molded plastics materials which are effective thermal insulators, such that internal volumes of the waste containers, especially lid regions thereof, can potentially become very high when the waste containers are exposed to strong sunlight having a energy density of circa 500 W/m<sup>2</sup> to 1000 W/m<sup>2</sup>. A fourth problem encountered is that it is highly desirable that the sensor devices be retrofitted to existing waste containers to render them as smart containers at their locations of deployment, namely installed *in situ*, thereby avoiding a need to transport the waste containers to a fitting centre to have their sensor devices fitted, and then transport the waste containers back to their respective deployment locations again; beneficially, fitting of the sensor devices is executable by a single member of personnel, even when large waste containers having lids with areas in excess of 1 m<sup>2</sup> are to be retrofitted with one or more sensor devices.

[0006] Known sensor devices for implementing smart waste containers are not able to address the aforementioned problems in a satisfactory manner.

**[0007]** In a published Japanese patent publication no. JP09144712A (Koganei Corp.), there is described a mounting structure for a sensor switch. The mounting structure includes a sensor holder which is fixed to a mounted member by employing a screw. Moreover, the sensor switch is installed into the sensor holder by pressing it against the sensor holder, wherein the sensor holder flexes to receive the sensor switch in a secure manner. Although such a mounting structure is suitable for installation of a sensor switch, it is unsuitable for use with the one or more aforementioned one or more sensor devices required for implementing a smart waste container. Document WO 2012/015664 presents a waste enclosure device comprising a waste enclosure employing operational functions including collection and monitoring capacity wherein said device includes one or more programmable logic controllers. Operational functions are performed by electrical components including sensors to determine waste deposits characteristics and contents. Said device operational functions are further adapted to send and receive data, optionally wirelessly, and configured and adapted to utilize solar derived electric power and, optionally, electric power from other sources. Document WO 2011/058287 discloses a device for measuring a filling rate of a container comprising: an attachment means suitable for attaching the device to an inner surface of the container; a sensor suitable for measuring said filling rate and generating data; an electronic module comprising a clock and a telecommunication means and being suitable for triggering the sensor, receiving and sending the data to a remote apparatus; and a source suitable for supplying electric power to the electronic module and the sensor. Document DE 20210495 shows a plastic molded wheeled waste bin having a flexible electrical resistance sensor which conveys a value to a transmitter unit on the outside of the rear wall which inductively communicates with a receiver unit on the collection vehicle to indicate the capacity of the contents. Document US 4282591 discusses a light control and indicating device including a main component adapted for mounting in a cavity of a wall, and a cover plate fitted thereover. The main component includes a frame or holder on which are mounted a plurality of operating members (referred to below) and those members have indicating elements exposed through, or slightly projecting through, openings in the cover plate. Document US 2003/038415 presents a sensor isolation system including a sensor, a package for the sensor, and a compliant interposer disposed between the sensor and the package and interconnecting the sensor to the package to isolate the sensor from thermal and mechanical stresses and yet at the same time providing a physical interconnect between the sensor and the package.

#### **Summary of the invention**

**[0008]** The present invention seeks to provide a sensor system comprising a sensor device for implementing in monitoring a waste container, wherein the sensor device addresses aforementioned problems of installation and during the operation of the sensor device in a hostile environment presented by a waste container when deployed.

**[0009]** According to a first aspect of the present invention, there is provided a sensor system comprising a sensor device implemented in monitoring a waste container in real time and remotely as claimed in appended claim 1: there is provided a sensor system comprising a sensor device for implementing a smart waste container, characterized in that the sensor system comprises one or more spacing elements, a heat reflecting layer and a mounting arrangement for mounting the sensor device to an upper portion of the smart waste container, wherein the mounting arrangement is arranged to provide a thermal barrier between a majority of an area of the sensor device facing towards the upper portion of the smart waste container to which the sensor device is mounted when in operation.

**[0010]** The invention is of advantage in that the thermal barrier assists the sensor device to operate in hostile environmental conditions encountered in operation at the upper portion of the waste container.

**[0011]** Optionally, the sensor device is implemented such that the thermal barrier includes an air gap between a majority of the area of the sensor device and the upper portion of the smart waste container. More optionally, the thermal barrier has a height in a range of 1 mm to 20 mm, when the sensor device is mounted in operation to the upper portion of the smart waste container. More optionally, the thermal barrier has a height in a range of 2 mm to 10 mm, when the sensor device is mounted in operation to the upper portion of the smart waste container.

**[0012]** Optionally, the sensor device is implemented such that the thermal barrier includes reflective metal foil for reflecting thermal radiation from the upper portion of the smart waste container back towards the upper portion.

**[0013]** Optionally, the sensor device is arranged to be attachable to a lid of the waste container.

**[0014]** Optionally, the sensor device includes one or more sensors for sensing an amount of waste and/or an environment within the waste container, a data processing unit for processing sensor signals generated by the one or more sensors indicative of the amount of waste in the container and/or the environment within the container, and a communication interface coupled to the data processing arrangement for enabling the sensor device to communicate information corresponding to the sensor signals

to a location which is spatial remote relative to the sensor device. More optionally, the one or more sensors include one or more of:

1. (a) a sensor for determining the quantity of waste present within the waste container;
2. (b) a temperature sensor for measuring a temperature within the waste container;
3. (c) a gas sensor for monitoring atmospheric conditions within the waste container; and
4. (d) a humidity sensor for measuring humidity within the waste container.

**[0015]** Optionally, the sensor device is implemented such that the heat reflective layer arranged between the sensor device and the upper lid of the waste container is a reflective metal foil to enable the sensor device to maintain a workable operating temperature.

**[0016]** Optionally, the sensor device is implemented such that the one or more spacing elements in combination with an air gap is adapted to maintain the sensor device at an acceptable temperature during operation.

**[0017]** Optionally, in the sensor device, the sensor for determining the quantity of waste present within the waste container is implemented by way of an ultrasonic sensor arrangement. More optionally, the ultrasonic arrangement is included within a housing of the sensor device and has a port, whereat ultrasonic radiation is emitted and received, disposed inside an outwardly-tapered hole implemented through the housing through which condensation is ducted in operation.

**[0018]** Optionally, in the sensor device, the gas sensor for monitoring atmospheric conditions within the waste container is implemented by way of a hydrocarbon gas sensor.

**[0019]** Optionally, the sensor device includes one or more peripheral projections for defining the thermal barrier when the sensor device is mounted to the waste container.

**[0020]** Optionally, the sensor device includes a coupling arrangement for receiving a tool for use in retaining the sensor device to the waste container for enabling one or more fasteners to be installed to attach the sensor device to the waste container.

**[0021]** There is also provided a method of installing a sensor device pursuant to the first aspect of the invention, the method including:

1. (a) attaching a mounting tool to a housing of the sensor device;
2. (b) preparing a configuration of holes in the upper portion of the waste container;
3. (c) using the mounting tool to retain the sensor device attached thereby to the upper portion of the waste container;
4. (d) attaching one or more fasteners to affix the sensor device to the upper portion of the waste container via the configuration of holes; and
5. (e) removing the mounting tool from the housing of the sensor device.

**[0022]** There is further provided a tool for use in implementing the method, wherein the tool is elongate, and includes an arrangement at one end thereof for engaging onto a housing of the sensor device and one or more elements along the tool for retaining the sensor device to the upper portion of the waste container.

**[0023]** It will be appreciated that features of the invention are susceptible to being combined in various combinations without departing from the scope of the invention as defined by the appended claims.

**Description of the diagrams**

**[0024]** Embodiments of the present invention will now be described, by way of example only, with reference to the following diagrams wherein:

FIG. 1

is an illustration of a waste container including an embodiment of a sensor device pursuant to the present invention installed on an underside surface of a lid of the waste container;

FIG. 2

is an illustration of a sensor device pursuant to the present invention mounted to an underside surface of the lid of the waste container of FIG. 1;

FIG. 3

is an illustration of a top part of the sensor device of FIG. 2;

FIG. 4

is an illustration of a bottom part of the sensor device of FIG. 2, wherein the bottom part is couplable to the top part of FIG. 3 to form an external housing for the sensor device;

FIG. 5

is an illustration of an external appearance of the top part of FIG. 3, for example in a manner that enables registered design protection to be sought;

FIG. 6

is an illustration of an external appearance of the bottom part of FIG. 4, for example in a manner that enables registered design protection to be sought;

FIG. 7

is an exploded view of a tool for installing the sensor device of FIG. 2, as well as an exploded view of component parts of the sensor device of FIG. 2;

FIG. 8

is an illustration of steps of a method of installing a sensor device of FIG. 2 to a waste container for implementing a smart waste container of FIG. 1; and

FIG. 10

are illustrations of different views of the sensor device in FIG. 2.

[0025] In the accompanying diagrams, an underlined number is employed to represent an item over which the underlined number is positioned or an item to which the underlined number is adjacent. A non-underlined number relates to an item identified by a line linking the non-underlined number to the item. When a number is non-underlined and accompanied by an associated arrow, the non-underlined number is used to identify a general item at which the arrow is pointing.

#### Description of embodiments of the invention

[0026] Referring to FIG. 1, there is shown an illustration of a smart waste container indicated generally by **10**. The smart waste container **10** includes a main body **30** and a lid **20** which is optionally pivotally mounted at an upper portion of the main body **30**. Optionally, the main body **30** and the lid **20** are fabricated as injection-molded components. In operation, the main body **30** is positioned on a supporting surface, for example on a concrete floor, such that the lid **20** is uppermost and exposed to incident solar radiation  $S_F$  having a solar flux energy density of up to circa  $1\text{kW/m}^2$ . On an underside surface of the lid **20**, facing into an interior volume of the main body **30**, is mounted a sensor device **40**. The sensor device **40** is mounted in a spaced-apart manner in respect to the lid **20** by way of one or more spacing elements **50**, so as to provide an insulation gap, namely a "thermal barrier", for example an air gap **60**, between the underside surface of the lid **20** and an external surface of the sensor device **40**; optionally, the one or more spacing elements **50** are formed integrally into a housing of the sensor device **40**. The sensor device **40** includes one or more sensors **70** for monitoring conditions within the interior volume of the main body **30**, wherein the one or more sensors **70** include at least one of:

1. (a) a sensor for determining a quantity of waste **80** present within the main body **30**, for example implemented by way of an ultrasonic sensor arrangement;
2. (b) a temperature sensor for measuring a temperature within the main body **30**;
3. (c) a gas sensor, for example a hydrocarbon gas sensor, for monitoring atmospheric conditions within the main body **30**, for example in respect of generation of methane gas within the container **10** indicative of organic waste fermentation processes occurring within the container **10**; the gas sensor is beneficially implemented as a periodically-energized pellistor, a solid state gas sensor or an optical absorption gas sensor; and
4. (d) a humidity sensor for measuring humidity within the container **10**.

[0027] The sensor device **40** additionally includes computing hardware **100** for receiving one or more sensor signals from the one or more sensors **70**, and a wireless interface **90** coupled to the computing hardware **100**; the sensor device **40** is thereby

"wireless enabled" for wirelessly transmitting information therefrom indicative of measurements made by using the one or more sensors **70**. Beneficially, the sensor device **40** is capable of enabling remote monitoring of the waste **80**. The waste **80** can be any waste including but not limited to house hold waste, biodegradable waste, liquid waste, industrial waste, solid waste and similar. Optionally, the wireless interface **90** is implemented as a cellular modem, for example complying with contemporary GSM and/or 3G communication standards. The computing hardware **100** is beneficially programmed to send information corresponding to the one or more sensor signals in a constant manner, in a periodic manner, or after the one or more sensors signals exceed one or more threshold values.

[0028] In an alternative embodiment the smart waste container **10** can also be used in applications such as monitoring silos, liquid storage vessels, oil containers, coal container and other applications where the content of the container decreases and when past a lower level or threshold triggers an action such as a refilling or similar.

[0029] A significant practical problem encountered when developing and deploying early prototypes of the sensor device **40** is thermal management, as the interior volume of the container **10**, for receiving the waste **80**, is often not well ventilated, for example for preventing insects and similar small creatures gaining access to the waste **80**. The aforesaid solar radiation absorbed by the lid **20** and the main body **30** and/or heat generated by organic decomposition processes occurring within the waste **80** can cause the lid **20** to become very hot, namely in close proximity to the sensor device **40**. The sensor device **40** includes one or more batteries **110** and active electronic components which have difficulty functioning at temperatures in excess of 150 °C. The one or more spacing elements **50**, in combination with the air gap **60**, were found to be necessary to ensure that the sensor device **40** was maintained at an acceptable temperature during operation. Beneficially, the air gap **60** has a height in a range of 1 mm to 20 mm, and more preferably a height in a range of 2 mm to 10 mm. Beneficially, an upwardly-facing surface of the sensor device **40**, when the sensor device **40** is mounted to the lid **20**, is provided with a reflective metal foil, for example Aluminium foil, heat-reflecting layer, to assist the sensor device **40** to maintain a workable operating temperature.

[0030] A further significant practical problem encountered with the smart waste container **10** is that, when an ambient temperature around the smart waste container **10** falls, for example at dusk, moisture inside the smart waste container **10** condenses on the underside surface of the lid **20** and also on the sensor device **40** itself. Condensed water is potentially capable of interfering with operation of electronic components included in the sensor device **40** and also with its associated one or more sensors **70**, for example ultrasonic sensors which require significant excitation potentials. Moreover, as the ambient temperature further drops, for example on a cold night after the aforementioned dusk, the moisture can freeze which potentially causes further problems. An example of potential mechanical problem associated with freezing can arise if the air gap **60** is too small. If condensed water appears between the sensor device **40** and the lid **20** and happens to freeze the frozen water expands significantly causing possible fractures in the lid **10** or damage to the sensor devices **40**. This can be avoided by ensuring sufficient spacing between the lid and the sensor device **40**. It has been found out that if the spacing is for example below ca 1 mm the likely hood of condensed water droplets to cause mechanical problems when freezing is higher than with air gap **60** of ca 2 mm. Beneficially, the sensor device **40** is designed to cope with such environmental challenges encountered around the underside surface of the lid **20**, as will be described later. Furthermore when the air gap is dimensioned to be more than ca 20 mm the likelihood that objects such as trash or other content in the container being stuck between the sensor device **40** and lid **20** increases. It is preferred that the air gap **60** is dimensioned to be larger than ca 1 mm but smaller at the range of 0.5-1.5 times and more preferably smaller than the range of 0.8-1.2, and most preferably smaller or equal to the smallest dimension of the waste in the container so that the waste does not get caught in the air gap **60**. Additionally mechanical durability of the container **10** and sensor device **40** construction could be compromised if the air gap **60** or other positioned spacing element with insulating properties has a height exceeding ca 20 mm.

[0031] Further example of formation of the ice is related to relative fast temperature changes taking place around and in the waste container **10**. When the outdoor temperature changes, the temperatures of the waste container (also referred to as a trash can) **10**, the air inside of the waste container **10** and the sensor device **40** change in different speeds compared to each others. As an example of temperature falling from -5 degrees Celsius to -20 degrees of Celsius the waste container **10** starts to cool followed by cooling of the air inside of the waste container **10** and further followed by cooling of the sensor device **40**. During the process there can be significant differences between for example the air inside of the waste container **10** and the sensor device **40**. After sufficient time the temperature differences even and the waste container **10**, the air inside of the trash can and the sensor device **40** will be substantially same (for example -20 Degrees Celsius). In most cases the temperature in the waste container **10** is higher than the temperature of the sensor device **40** which will result in condensation of droplets on the surface of the sensor device **40** and further to ice crystals forming on the surface. These ice crystals interfere with the performance of the sensor device **40**. When temperature arises from -20 degrees to -5 degrees the waste container **10** temperature will arise first, followed by arising of the air temperature inside of the waste container **10** and finally the temperature of the sensor device **40**. During warming there will be differences between the temperatures of waste container **10**, air inside of the waste container **10** and the sensor device **40**. Temperature differences between the air and the sensor device **40** will even up over time depending on

mass and heat capacity of the sensor device **40**.

[0032] When the temperature of the surface of the sensor device **40** and/or some of its components is lower than the temperature of the surrounding air (in the waste container) water vapour is likely to condensate in metallic surface of an ultrasonic sensor **300** of the sensor device **40**. The water droplets form ice crystals in the surface of the ultrasonic sensor **300** and might prevent its proper operation.

[0033] Problems arising from the condensation of water and formation of crystals can be avoided if the temperature gradients between the sensor device **40** and air inside of the waste container **10** are small or non-existent. In order to achieve prevent large temperature differences between the sensor device **40** and the temperature in the container **10** the thermal mass of the sensor device should be made smaller to keep total heat capacity of the sensor device **40** minimal. Small heat capacity enables sensor device **40** temperature to follow temperatures in side of the waste container **10** in a fast manner.

[0034] One exemplary way to make sensor device **40** robust and rugged is to have a moulded outer casing or so called shell of e.g. polyurethane or similar which has a high durability and is robust. Then to allow the sensor device **40** to have a small heat capacity it is preferable to have parts or all of the inner portion, which inner portion may be in one or more sections, of the casing hollow i.e. having only air (heat capacity 1,01 kJ/(kg x K)) inside of the sensor device **40** in addition to components. This might however reduce mechanical stability of the device. Based on embodiments in order to construct a mechanically stable device, which does not break easily in harsh usage environment of waste management processes, the interior of the sensor device **40** is preferably filled with a filler material to keep all components immobile in respect to top part **200** and bottom part **202** (housing) of the sensor device **40**.

[0035] Table I shows two exemplary possible filler materials used inside the sensor device and their physical properties that could be used to fill the sensor device **40** to improve mechanical stability. In preferred embodiment polyurethane casing of the sensor device **40** has a filler of polyurethane based foam or similar (such as polystyrene based foam or ETA (ESD (electro sensitive devices) safe polyethylene) based foam) is used in order to have small total heat capacity of the sensor device **40**. This way the sensor device **40** temperature "follows" temperature changes faster than with epoxy thus reducing formation of ice for example on top of ultrasonic sensor compared with filling the sensor device with epoxy or being solid throughout. In general the sensor device **40** should be filled with low density material while still rigid material giving mechanical stability.

[0036] Further based on test made with different configurations of the sensor device **40** it has been found out that performance of wireless interface **90** improves if the filler material has been selected as low density material such as polyurethane based foam in comparison with epoxy. Based on test performed with the sensor device **40** it has been further found out also that selection of the filler material has impact on the energy consumption of radio communication. Preferably the filler material should be polyurethane foam due to its superior radio frequency (RF) characteristics compared to epoxy and to free air. In certain radio antenna setups it has been seen that part of the radio waves are absorbed by epoxy which has significantly higher density than polyurethane based foam.

[0037] Table I, Heat capacities, densities, calculated added mass (using dimensions of 130 mm diameter and 40 mm height for the sensor device **40**) of the sensor device **40** when filling it with the material and needed energy for changing the temperature of the sensor with 1 degrees of Celsius.

Material	Heat capacity (kJ/kg x K),	Density (kg/m <sup>3</sup> )	Added mass from filling material	Energy needed to change temperature of the sensor device with 1 degrees of Celsius (or Kelvin). Assuming weight of the sensor device with out added filling as 0.5 kg and heat capacity of 1 kJ/kg/K.
Epoxy	1.11	2000	1 kg	1,1 kJ + 0.5kJ = 1.6kJ
Polyurethane foam	1.15	10-60	0.005-0.03 kg	0.006kJ + 0.5kJ = 0.506kJ to 0.034kJ +0.5kJ = 0.534kJ

[0038] In overview, embodiments of the present invention are concerned with mounting arrangements for a sensor device **40** for enabling it to be used in combination with waste containers **10** to provide smart waste containers which are capable of providing greater functionality for enabling more efficient waste collection and recycling to be achieved; the mounting arrangement beneficially involves providing an air gap, for example the aforementioned air gap **60**, between an upper lid **20** of a waste container **10** and a sensor device **40**, wherein the air gap **60** functions as a thermal insulator which reduces an impact of heat present at the lid **20** from influencing operation of the sensor device **40**. Optionally, the sensor device **40** is manufactured with a



reflective or white external finish, for example a white painted finish, and/or has a reflective Aluminium foil finish, for reflecting heat therefrom to maintain of the sensor device **40** at a more favourable operating temperature.

[0039] The sensor device **40** for use in the smart waste container **10**, as illustrated schematically in FIG. 1, will now be described in more detail, namely in a manner which would enable a design registration to be made based upon this disclosure, for example, with reference to FIG. 2 and FIG. 10.

[0040] Referring next to FIG. 2, the sensor device **40** is mounted in an upside-down manner onto the lid **20**. The sensor device **40** includes a top part **200** and a bottom part **202** which are operable to engage mutually to one another at a grooved peripheral lip. The lower part **202** includes projections at its lower surface for forming the aforementioned spacing elements **50** for defining an air gap **204** between the bottom part **202** and the lid **20** over a majority of an lower surface area of the bottom part **202** as illustrated; beneficially, there are four projections which serve to receive mounting screws **210**, wherein three of the four projections are disposed at 90° intervals, except that one of the projections is slightly angularly displaced from a 90° position as illustrated. The top part **200** is tapered, in a curved manner, with increasing distance from the lid **20**. Moreover, there is also included an eccentrically-disposed hole **206** extending from the bottom part **202** to the top part **200**, wherein the hole **206** has an internal wall and is included to duct condensation dripping from the lid **20** onto the bottom part **200** through the hole **206**, so that the condensation is guided into the interior volume of the container **10**. At a top of the top part **200**, the hole **206** is provided with a peripheral lip which assists to guide condensation into the interior volume of the container **10** when the sensor device **40** is mounted upon the lid **20** when in operation. Such an implementation guides condensed water away from an ultrasonic sensor of the sensor device **40** which is employed to measure a quantity of waste **80** present within the container **10**. Operating reliability of the sensor device **40** is thereby considerably improved.

[0041] The bottom part **202** and the top part **200** are beneficially manufactured to be of a generally circular form, with the top part **200** being inwardly tapered in a progressively curved manner away from the peripheral lip whereat it engages onto the bottom part **202**. Moreover, the bottom part **202** and the top part **200** are beneficially injection-molded plastics material components, for example manufactured from polyurethane, ABS, Polypropylene, Polycarbonate, Polyethylene, Nylon, Urea formaldehyde resin or similar plastics material. The bottom part **202** optionally has an external diameter in a range of circa 50 mm to 200 mm, more preferably in a range of circa 10 mm to 150 mm, and more optionally a diameter of substantially 131 mm. Moreover, the sensor device **40** optionally has a height, when the bottom part **202** is assembled to the top part **200** in a range of 10 mm to 100 mm, and more optionally substantially 67 mm. The hole **206** is optionally inwardly tapered, along at least a part of its length, from the top part **200** to the bottom part **202** as illustrated, wherein the hole **206** has a widest diameter in a range of 15 mm to 75 mm, more preferably in a range of circa 25 mm to 50 mm, and more optionally a widest diameter of substantially 38 mm. The hole **206** is beneficially synergistically operable to guide ultrasonic radiation emitted and received from an ultrasonic sensor mounted along an inside wall of the hole **206**, to the interior volume of the container **10** wherein the waste **80** is accommodated. The sensor device **40** is optionally used in embodiments of the invention for miniature waste containers **10** or even smaller household bins.

[0042] Referring next to FIG. 3, the top part **200** is illustrated in greater detail, for example in a manner that also provides a basis for a design registration. In FIG. 3, a perspective view of the top part **200** is provided, with a logo "enevo" on its upper surface, and the aforesaid hole **206** in an eccentric position within the top part **200**, wherein the hole **206** is inwardly tapered as aforementioned to provide an improved ultrasonic coupling between the ultrasonic sensor and the interior volume of the container **10**; "enevo" is a trademark. The top part **200** is also illustrated in cross-sectional view, wherein a location of a transmitting/receiving port of the ultrasonic sensor, denoted by **300**, is illustrated near a lower portion of the top part **200**. The peripheral projecting edge of the hole **206** is shown in enlarged detail for guiding aforesaid condensation dripping from the lid **20**. A volume adjacent to the hole **206** and within the top part **200** is designated for housing electronic components, batteries and similar functional parts; beneficially, this volume is hermetically sealed when the top part **200** and the bottom part **202** are joined together, for example by employing synthetic rubber or Silicone gaskets at surfaces whereat the top and bottom parts **200**, **202** mutually abut.

[0043] Referring next to FIG. 4, there is shown an illustration of the bottom part **202** in perspective view as seen from an underside surface **402** of the bottom part **202** which is facing towards the lid **20** of the waste container **10** when the sensor device **40** is mounted upon the lid **20** by way of the screws **210**. Four peripheral projections, namely "towers" or "spacers", denoted by **400A**, are included as an integral part of the bottom part **202** for providing the aforesaid air gap **60**; optionally, a central projection **400B**, as illustrated, is also provided. The projections **400A** present a surface area to the lid **20**, when the sensor device **40** is mounted thereupon, which is small relative to area of the underside surface **402**, for example less than 25% thereof, and more optionally less than 10% thereof. A peripheral recess is provided on the bottom part **202** for making connections to the sensor device **40**, for example for performing field testing and diagnostics for example. Beneficially, the bottom part **202** has a peripheral diameter which is substantially constant along a height of the bottom part **202** as illustrated. The underside surface

**402** beneficially has a recess, requiring one of the peripheral projections **400A** to be slightly angularly displaced relative to its otherwise regular 90° position, as illustrated. The central projection **400B** is beneficially provided with a blind hole as illustrated in the cross-section view of the bottom part **202**; optionally, the blind hole is threaded. As aforementioned, the underside surface **402** beneficially has a white finish, for example a painted white finish, or is provided with a metallic-foil reflector, for example an Aluminium-foil reflector, for reflecting heat back towards the lid **20** when the sensor device **40** is in operation. For design registration purposes, further detailed diagrams are provided in FIG. 5 and FIG. 6 for the top part **200** and the bottom part **202** respectively.

[0044] In FIG. 7, there is shown an exploded view of the sensor device **40**, together with a manner in which the sensor device **40** is mounted to the lid **20** of the container **10**. Moreover, there is also shown a mounting tool **500** which is operable to enable convenient installation of the sensor device **40** to the lid **20**, wherein the mounting tool **500** enables a single person to execute installation of the sensor device **40** to the lid **20**, even when the lid **20** is of inconveniently large size relative to an arm's reach of the person, thereby reducing a cost and time required to retrofit, for example, the sensor device **40** to pre-existing waste containers **10**.

[0045] A practical problem encountered when implementing an automated waste management system relates to the installation and mechanical durability of the sensor device **40** to the waste container **10**, either during initial manufacturing of smart waste containers **10**, so-called original equipment manufacture (OEM), or retrofitting the sensor device **40** to existing non-smart waste containers. In FIG. 8, steps A to D of a method of installing the sensor device **40** to a lid **20** of a non-smart container are illustrated in a schematic manner.

[0046] In the step A, a configuration of holes is drilled into the lid **20** for later receiving the mounting tool **500** and also four screws **210**. The configuration of holes is beneficially implemented by drilling, using a robust metal drilling template, to guide relative positions of the holes in the lid **20**. Optionally, the configuration of holes is pre-molded into the lid **20**, for example in a situation of OEM manufacture of smart waste containers. The configuration of holes includes peripheral holes **502** which align to the peripheral projections **400A** for receiving the screws **210**, and a central hole **504** which aligns with the central projection **400B** when the peripheral holes **502** are aligned to the peripheral projections **400A**. A first end of the mounting tool **500** is threaded and can be engaged into the blind hole of the central projection **400B** of the bottom part **202**, for example by way of a corresponding screw-thread formed into the blind hole as aforementioned. The mounting tool **500** includes a plurality of flexible wings **508** disposed approximately mid-way along an elongate length of the mounting tool **500**. Beneficially, the wings **508** are fabricated from a flexible spring-like material or are rigid elements that are compliantly pivotally mounted at their proximate ends, for example the wings **508** return automatically to retracted position when mutually pressed together, but naturally assumed an outwardly splayed configuration. Thus, in the step A, a person installing the sensor device **40** drills the configuration of holes in the lid **20**, if not already provided. Thereafter, the person attaches the first end of the tool **500** to the blind hole of the central projection **400B** and then forces a second end of the tool **500** through the central hole **504**. The wings **508** are inwardly displaced as they are forced through the central hole **504**, and then assume a splayed configuration when they arrive at an opposite side of the lid **20** relative to the sensor device **40**.

[0047] In the step B, the person forces the mounting tool **500** so that the wings **508**, in retracted position, are also forced through the central hole **504** as illustrated.

[0048] In the step C, the person forces the mounting tool **500** a sufficient distance through the central hole **504** such that the wings **508** become splayed out on an opposite side of the lid **20** to that which the sensor device **40** is facing. Thereafter, with the tool **500** retaining the sensor device **40** held to the lid **20**, the person applies the four screws **210** through the peripheral holes **502** to engage into holes corresponding to the peripheral projections **400A** and then tightens the screws **210**. The screws **210** thereby hold the sensor device **40** firmly to the lid **20**.

[0049] The screws **210** used for the fastening can be of a variety of designs and have an associated functionality to prevent any unauthorised removal of the sensor device **40**. Optionally, the screws **210** have threads, hooks, cone shaped surfaces, wedges, or also be integrated in the sensor device **40** or the lid **20** as required.

[0050] In the step D, the person removes the mounting tool **500** from the sensor device **40** to complete the installation of the sensor device **40**.

[0051] In FIG. 9, there is shown a view of a portion of the mounting tool **500** which is used for attaching the sensor device **40** to the lid **20**.

[0052] In FIG. 10, there are shown different views of the sensor device **40** including:

FIG. 10(a) a front view;

FIG. 10(b) a side view;

FIG. 10(c) a bottom view; and

FIG. 10(d) a perspective view.

[0053] In the foregoing, installation of the sensor device **40** to the lid **20** of the container **10** is described. It will be appreciated that the sensor device **40** is beneficially mounted at an upper portion of the main body **30**. An alternative mounting position for the sensor device **40** is on one or more inside surfaces of side-walls of the main body **30**, preferably where the sensor device **40** will not be in contact with the waste **80** when the container **10** is tipped in operation to remove the waste **80** during waste collection activities.

[0054] It will be appreciated that the sensor device **40** is optionally manufactured as a two-part arrangement, namely an active unit and a support holster which is attached to the lid **20** as aforementioned, or inside-surface side walls at an upper portion of the main body **30**. The holster is operable to retain the active unit in a secure manner, for example via a locking arrangement, such that the active unit can be detached, for example by authorized personnel, in an event that the active unit needs to be serviced or replaced.

[0055] In an alternative embodiment, the sensor device **40** is optionally installed in or attached to the walls of the waste container **10** or to any other suitable part of the waste container **10**. For example, the waste container **10** optionally has a top part with only a small opening with a lid **20**. In this embodiment, it is optionally beneficial to install the sensor device **40** in the top part, known as a "roof" or "ceiling", of the waste container **10**. Moreover, the waste container **10** optionally has a lid **20** or an opening in one or more sides of the waste container **10**. In such an embodiment, it is optionally beneficial to install the sensor device **40** to another part of the waste container **10** other than the lid **20**, for example to the top part or back wall or side walls of the waste container **10**.

[0056] Modifications to embodiments of the invention described in the foregoing are possible without departing from the scope of the invention as defined by the accompanying claims. Expressions such as "including", "comprising", "incorporating", "consisting of", "have", "is" used to describe and claim the present invention are intended to be construed in a non-exclusive manner, namely allowing for items, components or elements not explicitly described also to be present. Reference to the singular is also to be construed to relate to the plural. Numerals included within parentheses in the accompanying claims are intended to assist understanding of the claims and should not be construed in any way to limit subject matter claimed by these claims.

## REFERENCES CITED IN THE DESCRIPTION

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- [WO2012015664A \[0007\]](#)
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## PATENTKRAV

1. Sensorsystem omfattende en sensorindretning (40) til fjernovervågning af en affaldsbeholder (10), hvilken sensorindretning (40) omfatter:
- 5 – én eller flere sensorer (70) til måling af en mængde affald (80) og et miljø i affaldsbeholderen (10);
- en databehandlingsenhed (100) til behandling af sensorsignaler genereret af den éne eller flere sensorer (70) til indikation af mængden af affald (80) i affaldsbeholderen (10) og miljøet i affaldsbeholderen (10);
- 10 – en kommunikationsgrænseflade (90) koblet til databehandlingsenheden (100) til at sætte sensorindretningen (40) i stand til at kommunikere information svarende til sensorsignalerne til en fjern lokation i forhold til sensorindretningen (40); og
- en strømenhed (110) til strømforsyning af sensorindretningen (40);
- 15 **kendetegnet ved, at**
- sensorsystemet yderligere omfatter ét eller flere afstandselementer (50), et varmereflekerende lag og et monteringsarrangement til montering af sensorindretningen (40) på en undersideflade af et øvre låg (20) på affaldsbeholderen (10) i indbyrdes afstand ved anbringelse af det éne eller flere
- 20 afstandselementer (50) i kombination med det varmereflekerende lag anbragt mellem sensorindretningen (40) og det øvre låg (20) på affaldsbeholderen (10), hvorved der tilvejebringes en termisk barriere mellem en undersideflade af affaldsbeholderlåget (20) og en ekstern overflade af sensorindretningen (40).
- 25 2. Sensorsystem ifølge krav 1, hvor det varmereflekerende lag, der er anbragt mellem sensorindretningen (40) og det øvre låg (20) af affaldsbeholderen (10), er en reflekterende metalfolie, så sensorindretningen (40) kan holde en brugbar arbejdstemperatur.
- 30 3. Sensorsystem ifølge krav 1, hvor det éne eller flere afstandselementer (50) i kombination med et luftgab (60) er indrettet til at holde sensorindretningen (40) ved en acceptabel temperatur under drift.

- 4,        Sensorsystem ifølge krav 1, hvor den termiske barriere (60) omfatter luftgabet mellem en hovedpart af området (402) af sensorindretningen (40) og den øvre del (20) af affaldsbeholderen (10).
- 5        5.        Sensorsystem ifølge krav 1, hvor den termiske barriere (60) har en højde i et interval fra 1 mm til 20 mm, fortrinsvis et interval fra 2 mm til 10 mm, når sensorindretningen (40) er monteret operativt til den øvre del af affaldsbeholderen (10).
- 10       6.        Sensorsystem ifølge krav 1, hvor den termiske barriere (60) omfatter en reflekterende metalfolie til refleksion af termisk stråling fra den øvre del af affaldsbeholderen (10) tilbage mod den øvre del.
- 15       7.        Sensorsystem ifølge ethvert af de foregående krav, hvor sensorindretningen (40) er indrettet til fastgøring til et låg (20) på affaldsbeholderen (10) ved hjælp af monteringsarrangementet.
- 20       8.        Sensorsystem ifølge ethvert af de foregående krav, hvor sensorindretningen (40) er fyldt med materiale til tilvejebringelse af mekanisk stabilitet til sensorindretningen (40), og hvor fyldmaterialet eventuelt er polyurethanskum eller lignende for at holde varmekapaciteten af sensorindretningen (40) lav.
- 25       9.        Sensorsystem ifølge krav 1, hvor den éne eller flere sensorer omfatter én eller flere af:
- 30              (a) en sensor til bestemmelse af mængden af affald (80), der befinder sig i affaldsbeholderen (10);
- (b) en temperatursensor til måling af en temperatur i affaldsbeholderen (10).
- (c) en gassensor til overvågning af atmosfæriske forhold i affaldsbeholderen (10); og
- (d) en fugtighedssensor til måling af fugtighed i affaldsbeholderen (10).
10.       Sensorsystem ifølge krav 9, hvor sensoren til bestemmelse af mængden af affald (80), der findes i affaldsbeholderen (10), er implementeret som et

ultralydssensorarrangement (300), og hvor eventuelt ultralydssensorarrangementet (300) indeholdes i et hus (200, 202) tilhørende sensorindretningen (40) og har en port (300), hvorfra ultralydsstrålingen sendes og modtages under drift, og som er anbragt indvendigt i et udad tilspidsende hul (206), der er tilvejebragt gennem huset (200, 202), hvorigennem kondensat bortledes under drift.

11. Sensorindretning (40) ifølge krav 9, hvor gassensoren til overvågning af atmosfæriske forhold i affaldsbeholderen (10) er tilvejebragt i form af en carbonhydridgas-sensor.

12. Sensorsystem ifølge ethvert af de foregående krav, hvor sensorindretningen (40) omfatter ét eller flere periferifremspring (400A) til afgrænsning af den termiske barriere (60), når sensorindretningen (40) monteres på affaldsbeholderen (10).

13. Sensorsystem ifølge ethvert af de foregående krav, hvor sensorindretningen (40) omfatter et koblingsarrangement (400B) til modtagelse af et værktøj (500) til anvendelse ved fastholdelse af sensorindretningen (40) til affaldsbeholderen (10), så ét eller flere fastgøringsorganer (210) kan installeres til fastgøring af sensorindretningen (40) til affaldsbeholderen (10).

14. Sensorsystem ifølge ethvert af de foregående krav, hvor ultralydssensorarrangementet (300) er indbygget i et hus (200, 202) tilhørende sensorindretningen (40), og huset (200, 202) er indvendigt fyldt med et fyldmateriale, der har mindre massefylde end materialet af sensorindretningens (40) hus.

15. Sensorindretning (40) ifølge krav 1, hvor databehandlingsenheden (100) er konfigureret til transmission af information svarende til ét eller flere sensorsignaler på en konstant måde eller på en periodisk måde til en fjernovervågningsstation, når det éne eller flere sensorsignaler overstiger en foruddefineret tærskelværdi.

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DRAWINGS

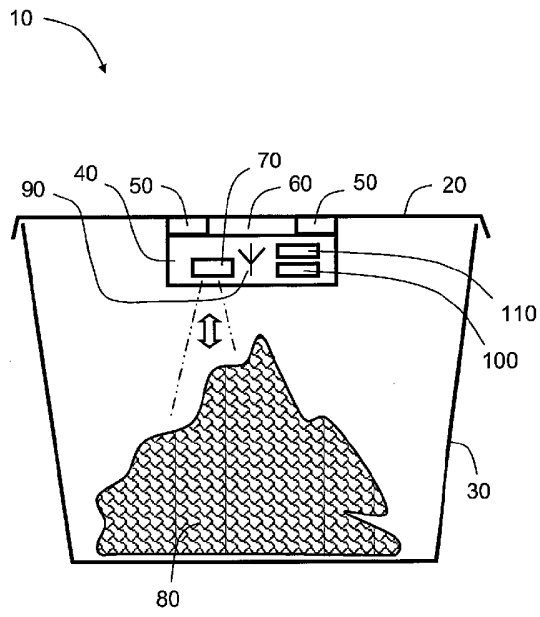


FIG. 1

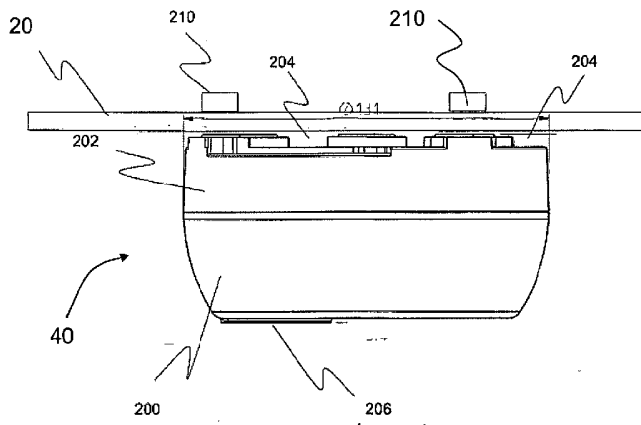


FIG. 2



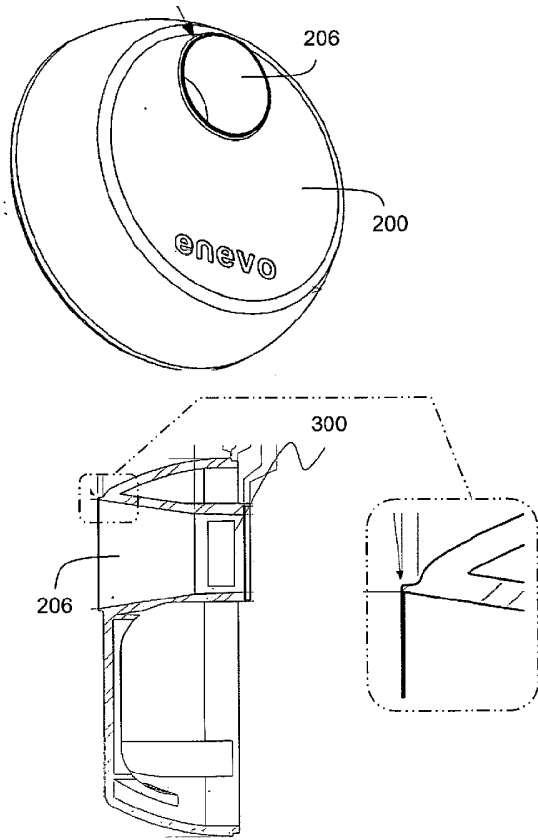


FIG. 3

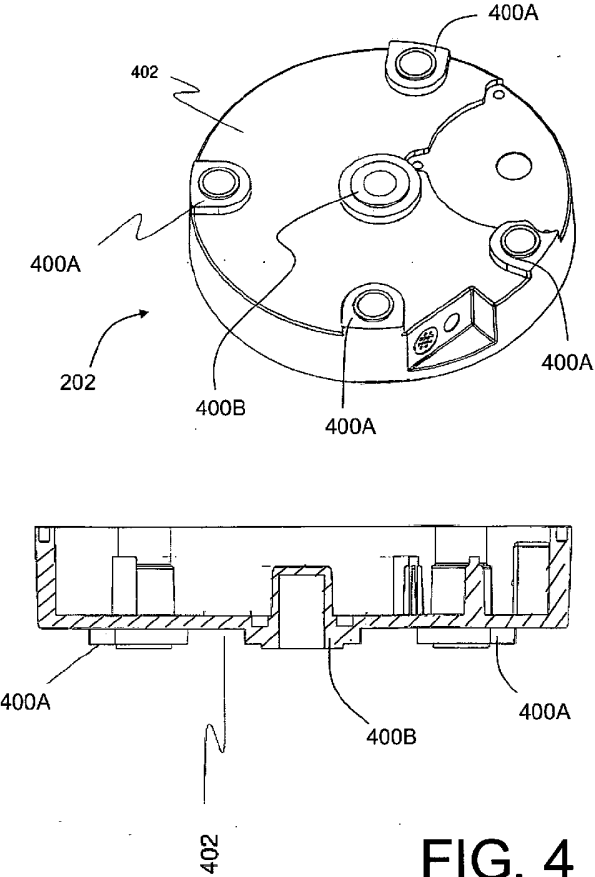


FIG. 4

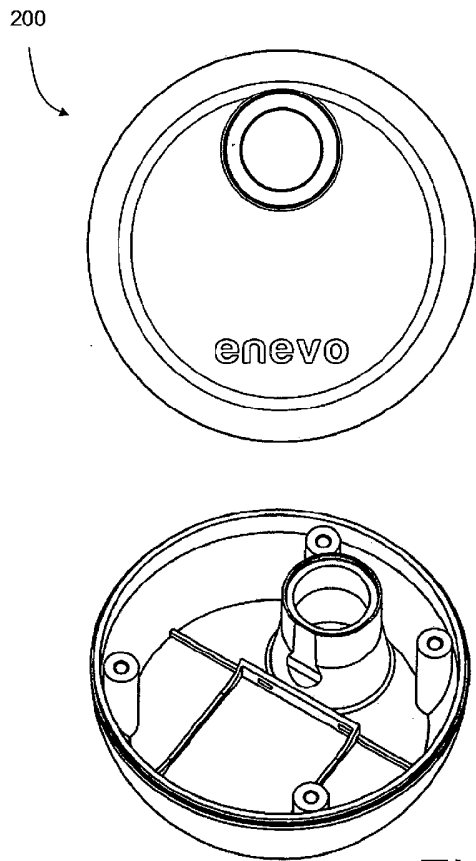


FIG. 5

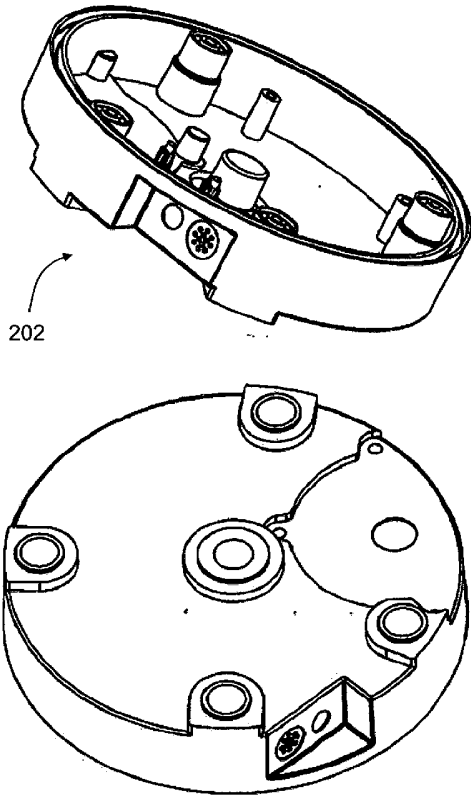


FIG. 6

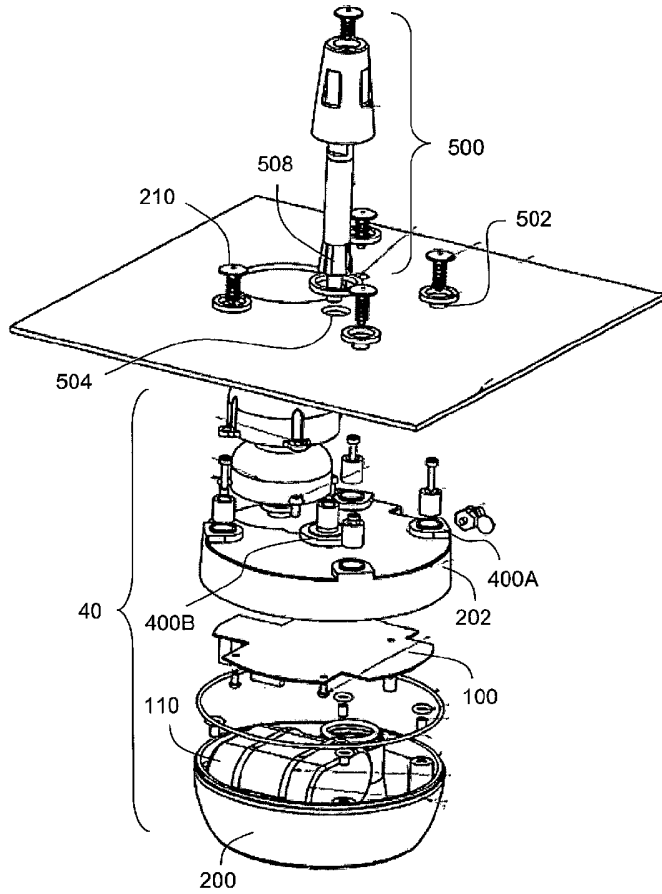


FIG. 7

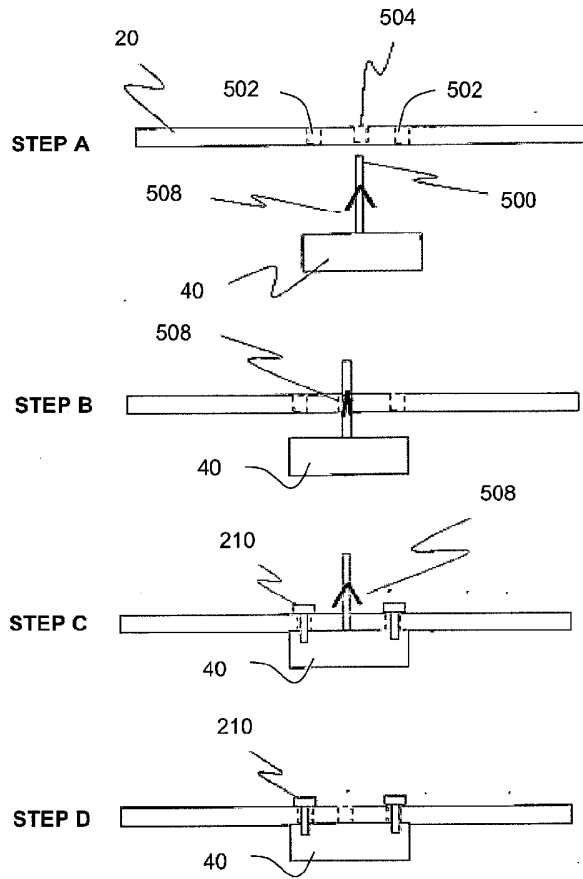


FIG. 8

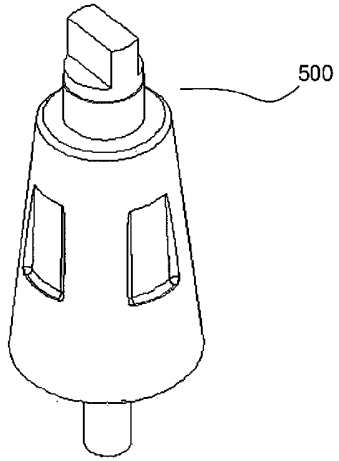


FIG. 9

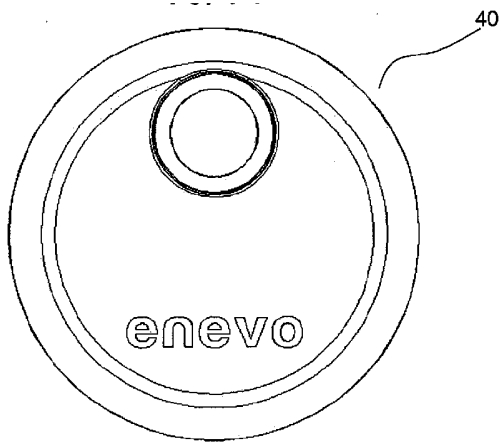


FIG. 10 (a)

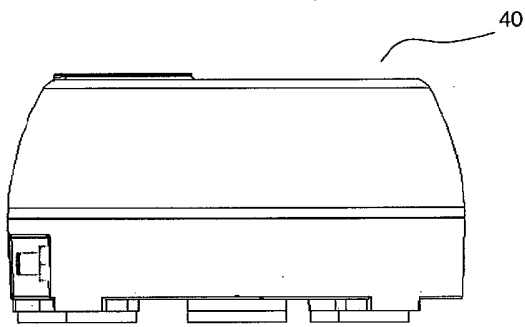


FIG. 10 (b)



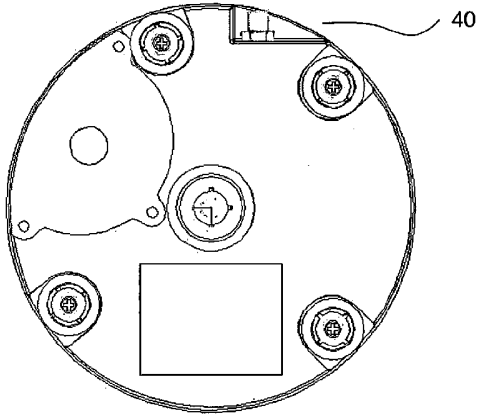


FIG. 10 (c)

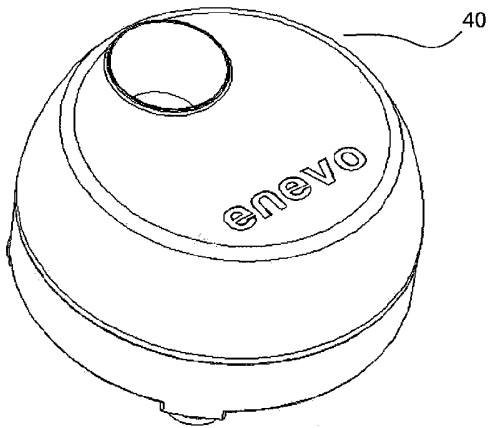


FIG. 10 (d)