

(19) World Intellectual Property Organization
International Bureau



(43) International Publication Date
20 March 2008 (20.03.2008)

PCT

(10) International Publication Number
WO 2008/034036 A2

(51) International Patent Classification:
B23K 26/00 (2006.01) **B23K 26/36** (2006.01)

(21) International Application Number:
PCT/US2007/078460

(22) International Filing Date:
14 September 2007 (14.09.2007)

(25) Filing Language: English

(26) Publication Language: English

(30) Priority Data:
60/844,822 15 September 2006 (15.09.2006) US

(71) Applicant (for all designated States except US): **GSI GROUP CORPORATION** [US/US]; 39 Manning Road, Billerica, MA 01821 (US).

(72) Inventor; and

(75) Inventor/Applicant (for US only): **GU, Bo** [US/US]; 100 Crossbow Lane, North Andover, MA 01845 (US).

(74) Agents: **KUSHMAN, James, A.** et al.; Brooks Kushman, 1000 Town Center, Twenty-second Floor, Southfield, MI 48075 (US).

(81) Designated States (unless otherwise indicated, for every kind of national protection available): AE, AG, AL, AM,

AT, AU, AZ, BA, BB, BG, BH, BR, BW, BY, BZ, CA, CH, CN, CO, CR, CU, CZ, DE, DK, DM, DO, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, GT, HN, HR, HU, ID, IL, IN, IS, JP, KE, KG, KM, KN, KP, KR, KZ, LA, LC, LK, LR, LS, LT, LU, LY, MA, MD, ME, MG, MK, MN, MW, MX, MY, MZ, NA, NG, NI, NO, NZ, OM, PG, PH, PL, PT, RO, RS, RU, SC, SD, SE, SG, SK, SL, SM, SV, SY, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, ZA, ZM, ZW.

(84) Designated States (unless otherwise indicated, for every kind of regional protection available): ARIPO (BW, GH, GM, KE, LS, MW, MZ, NA, SD, SL, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European (AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IS, IT, LT, LU, LV, MC, MT, NL, PL, PT, RO, SE, SI, SK, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, ML, MR, NE, SN, TD, TG).

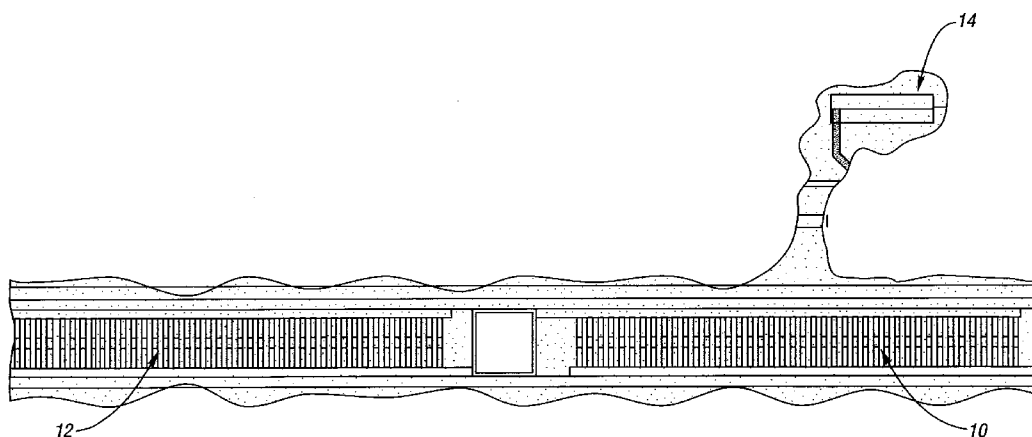
Declarations under Rule 4.17:

- as to applicant's entitlement to apply for and be granted a patent (Rule 4.17(ii))
- as to the applicant's entitlement to claim the priority of the earlier application (Rule 4.17(iii))
- of inventorship (Rule 4.17(iv))

Published:

- without international search report and to be republished upon receipt of that report

(54) Title: METHOD AND SYSTEM FOR LASER PROCESSING TARGETS OF DIFFERENT TYPES ON A WORKPIECE



(57) Abstract: A method and system for laser processing targets of different types on a workpiece are provided. The method includes setting a laser pulse width of one or more laser pulses to selectively provide one or more laser output pulses having one or more set pulse widths based on a first type of target to be processed. The method further includes setting a pulse shape of the one or more output pulses to selectively provide the one or more output pulses having the set pulse shape based on the types of targets to be processed. The method still further includes delivering the one or more output pulses having the one or more set pulse widths and the set pulse shape to at least one target of the first type. The method finally includes resetting the laser pulse width of one or more laser pulses to selectively provide one or more laser output pulses having one or more reset pulse widths based on a second type of target to be processed.

WO 2008/034036 A2

METHOD AND SYSTEM FOR LASER PROCESSING TARGETS OF
DIFFERENT TYPES ON A WORKPIECE

CROSS-REFERENCE TO RELATED APPLICATIONS

This application claims the benefit of U.S. provisional application
5 Serial No. 60/844,822, filed September 15, 2006.

BACKGROUND OF THE INVENTION

1. Field of the Invention

This invention relates to methods and systems for laser processing
targets of different types on a workpiece.

10 2. Background Art

Laser trimming has been a part of manufacturing processes in the
semiconductor and microelectronics industries for more than 30 years. The industry
has been introducing new link materials and structures, as well as different thin
films and structures. One of the challenges for laser processing is to meet the needs
15 to process all these devices with a single laser trimming system. For example, the
processing conditions and the types of lasers needed for copper processing are not
the same for processing conventional polysilicon links. So a laser trimming system
designed for processing polysilicon links may not be able to process copper links
effectively.

20 Another challenge is that the processing conditions and the types of
lasers needed for metal link blowing or cutting may not be the best for the
conventional thin film trimming. For example, a laser trimming system designed
for processing copper links may not be able to process and trim thin film resistors
effectively. In addition, different thin films require different processing conditions
25 as well. In a laser processing system such as the model M310 product of the

assignee of the present application, various thin film trimming jobs require different laser pulse widths, for example 7ns and 50 ns pulse widths. Current M310/M350 systems of the assignee of this application are built with a selected laser having a single desired pulse width. However, the pulse width cannot be tuned or adjusted easily. This limits the system to a narrow range of product processing at the selected pulse width. Currently, when there are different types of targets or circuit elements to be laser processed with different laser pulse widths, multiple processing systems provide the needed different pulse width lasers. These systems may be underutilized depending on a mix of products with varying target types, thus reducing system value to the customer. A system for processing multiple types of devices with a single laser source therefore will add value to the customer.

Except where indicated, the following patents and patent applications are assigned to the assignee of the present invention and are hereby incorporated by reference in their entirety:

15 U.S. Patent No. 5,300,756 (the '756 patent) entitled "Method For Severing Integrated-Circuit Connection Paths By A Phase-Plate-Adjusted Laser Beam."

U.S. Patent No. 5,998,759 (the '759 patent) entitled "Laser Processing."

20 U.S. Patent No. 6,727,458 (the '458 patent) entitled "Energy-Efficient, Laser-Based Method And System For Processing Target Material."

U.S. Patent No. 6,777,645 (the '645 patent) entitled "High-Speed, Precision, Laser-Based Method And System For Processing Material Of One Or More Targets Within A Field."

25 U.S. Patent No. 6,951,995 (the '995 patent) entitled "Method And System For High-Speed, Precise Micromachining An Array Of Devices."

U.S. Patent No. 6,987,786 (the '786 patent) entitled "Controlling Laser Polarization."

Published U.S. Patent Publication No. 2002/0167581 (the '7581 publication) entitled "Methods And Systems For Thermal-Based Laser Processing."

5 Published U.S. Patent Publication No. 2006/0108337 (the '8337 publication) entitled "Method And System For Laser Soft Marking."

Published U.S. Patent Publication No. 2004/0188399 (the '8399 publication) entitled "Energy-Efficient, Laser-Based Method And System For Processing Target Material."

10 U.S. Patent No. 6,151,338 (not assigned to the assignee of the present invention) discloses a high power laser optical amplifier system for material processing.

SUMMARY OF THE INVENTION

15 An object of the present invention is to provide an improved method and system for laser processing targets of different types on a workpiece.

In carrying out the above object and other objects of the present invention, a method of laser processing targets of different types on a workpiece is provided. The method includes setting a laser pulse width of one or more laser pulses to selectively provide one or more laser output pulses having one or more set pulse widths based on a first type of target to be processed. The method further includes setting a pulse shape of the one or more output pulses to selectively provide the one or more output pulses having the set pulse shape based on the types of targets to be processed. The method still further includes delivering the one or more output pulses having the one or more set pulse widths and the set pulse shape to at least one target of the first type. The method finally includes resetting the laser pulse width of one or more laser pulses to selectively provide one or more laser

20

25

output pulses having one or more reset pulse widths based on a second type of target to be processed.

The set and reset pulse widths may be selectable over a continuous range of 1 nanosecond to 200 nanoseconds.

5 The range may be 4 nanoseconds to 50 nanoseconds.

The pulse width may be programmable.

The output pulses may be delivered by a laser beam delivery subsystem. The laser beam may have a flat top profile.

The set pulse shape may be a square pulse shape.

10 The delivered output pulses may have a pulse energy in a range of .1 microjoules to 5 microjoules.

The range may be .2 microjoules to 1.5 microjoules.

The laser pulses may be generated by a pulse-shaped laser. The pulse-shaped laser may have a repetition rate in a range of 1 kHz to 200 kHz.

15 The repetition rate may have a range of 1 kHz to 50 kHz.

The output pulses may have a rise time of less than 1.5 nanoseconds and a fall time of less than 2 nanoseconds.

The output pulses may have a TEM₀₀ mode.

20 The output pulses may have a wavelength in the range of .2 microns to 2.5 microns.

The wavelength may be about 1 micron.

The wavelength may be about 1.2 microns.

The wavelength may be about 1.3 microns.

5 device.
One of the different types of targets may be a thick or thin film-based

The devices may be circuit elements.

The devices may be thin film resistance elements.

The different types of targets may be links.

The links may include metal links.

10 The links may include polysilicon links.

The metal links may include at least one of aluminum, gold and
copper links.

The workpiece may include a semiconductor substrate.

The targets may comprise circuit elements.

15 The circuit elements may include a bank of links of a first material
and a bank of links of a second material different from the first material.

The circuit elements may include a bank of links and a thick or thin
film-based device.

The processing may include trimming.

The trimming may be at least one of passive and functional trimming.

At least one of the steps of setting may be repeated after all targets of the same or similar material on the workpiece are processed.

5 At least one of the steps of setting may be repeated during processing of targets made of different material on the workpiece.

Further in carrying out the above object and other objects of the present invention, a system for laser processing targets of different types on a workpiece is provided. The system includes a laser subsystem for generating one or more laser pulses. The system further includes a controller operatively connected
10 to the laser subsystem to set a laser pulse width of the one or more laser pulses to selectively provide one or more laser output pulses having one or more set pulse widths based on a first type of target to be processed. The controller is also operatively connected to the laser subsystem to set a pulse shape of the one or more output pulses to selectively provide the one or more output pulses having the set
15 pulse shape based on the first type of target, and to reset the laser pulse width of one or more laser pulses to selectively provide one or more laser output pulses having one or more reset pulse widths based on a second type of target to be processed. The system still further includes a laser beam delivery subsystem including an optical subsystem for delivering the output pulses having the set pulse shape and the
20 set and reset pulse widths to the first and second types of targets, respectively.

The laser beam delivery subsystem may selectively deliver the output pulses to the targets based on position information.

The laser subsystem may include a single pulse-shaped and pulse width tunable laser.

25 The laser subsystem may include a fiber laser.

The laser subsystem may include a fast rise, fast fall, pulse-shaped laser.

The laser subsystem may include a Q-switched laser.

5 The laser subsystem may have a MOPA configuration and may include an oscillator and an amplifier.

The oscillator may include a tunable or adjustable pulse width, semiconductor laser.

The amplifier may include a fiber-based amplifier.

10 The laser subsystem may include a laser which may have an output coupler and a laser cavity. The geometry and dimensions of the laser cavity may be adjusted and reflectivity of the output coupler may be adjusted to set the pulse width.

The controller may set the pulse width by changing pulse energy level of a laser of the laser subsystem.

15 The controller may set the pulse width by changing repetition rate of a laser of the laser subsystem.

20 The system may further include a sensor subsystem including an optical sensor for sensing a laser pulse reflected from the workpiece to obtain a signal and a signal processor for processing the signal to obtain alignment information for laser processing.

The laser beam may be initially linearly polarized. The system may further include a LCVR and a LCVR controller for controlling the LCVR so that the LCVR controllably rotates the linearly polarized laser beam based upon alignment of the targets.

The laser beam may have an initial polarization. The system may further include a LCVR and an LCVR controller for controlling the LCVR so that the LCVR controllably converts the initial polarization to a desired polarization.

5 The optical subsystem may adjust at least one of spot size and the focus of the laser beam on the at least one target.

The system may further include a positioning mechanism for providing relative motion between the workpiece and the laser beam.

10 Still further in carrying out the above object and other objects of the present invention, a laser-based material processing method is provided. The method includes providing a first target of a first type on a die and providing a second target of a second type on the die. The first and second types are different types. The method further includes processing the first and second targets with a single pulse-shaped laser having an adjustable pulse width.

15 One purpose of at least one embodiment of this invention is to provide a laser system/processing method and system to process various kinds of links, including polysilicon, aluminum, gold and copper links on a wafer.

20 Another purpose of at least one embodiment of this invention is to provide a laser processing method and system that uses a single laser source for a wide range of processing applications, for example, to cut or blow different kinds of links, as well as to trim thin or thick film resistors on a wafer.

25 One embodiment of the invention improves a link blowing process window by using a pulse-shaped and pulse width adjustable laser, preferably, a fiber laser. In order to achieve that, a fast rise (< 1.5 ns) /fall (< 2 ns), a pulse-shaped (square shape preferred) q-switched laser can be used. One can also use a MOPA configuration. One of the choices for the MOPA oscillator can be a tunable or adjustable pulse width diode laser. One of the choices for the MOPA amplifier can

be a fiber laser amplifier. Beam shaping optics may be used to generate a flat-top beam profile to improve laser processing.

5 A fast rise/fall, pulse-shaped laser gives rise to more efficient processes by better coupling the laser energy into the material. This is especially significant for metal links. Fast fall time prevents excess energy from the tail of the typical Q-switch pulse impinging the material, thus reducing substrate damage. Furthermore, with less residual energy in the neighboring zone near the trim path, less HAZ is generated. It is, therefore, preferred in at least one embodiment of the invention that a fast rise/fall, pulse-shaped laser be used for processing metal links
10 such as copper or gold links.

Another aspect of the laser of embodiments of the invention is the adjustability of the laser pulse duration (pulse width). Different pulse durations can be selected in the laser trimming or processing system to blow or cut both metal links and trim thin or thick film circuit elements, respectively. Flexible adjustment
15 of the pulse duration allows one to independently optimize the process window for the metal link blowing or cutting process, as well as for the thin or thick film trimming process. Flexible adjustment of the pulse duration may also allow one to optimize other laser material processing tasks.

20 Because the pulse widths of the laser suggested here can be easily adjusted, one can optimize the pulse widths together with pulse energy and other beam characteristics like beam size to achieve an improved processing condition for thin and thick film trimming.

By spatially beam shaping the laser beam from the conventional Gaussian to a flat top profile, energy can be efficiently coupled, reducing heating
25 of the area adjacent to and along the trim path and to the underlying substrate. Because energy is more efficiently coupled into the trim kerf, less HAZ will be produced for the same total energy with less damage to the substrate. It is, therefore, suggested here in at least one embodiment of the invention that a spatially shaped beam, preferably a flat-top beam profile, be used for trimming or cutting.

In addition to the shaped pulse, the pulse duration of the laser is also made easily adjustable. One can easily select a particular pulse width for a particular thin or thick film material and structure, thus eliminating the need for multiple laser sources in a single material processing system.

5 The above features and advantages are readily apparent from the following detailed description of the best mode when taken in connection with the accompanying drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

10 FIGURE 1 is a top schematic view, partially broken away, of a die of a semiconductor wafer; there are thin film resistance elements as well as metal links (i.e., copper, gold or Al etc.) on the die; another possible combination of devices to be processed would include thick film-based devices;

 FIGURE 2 is a schematic block diagram of a laser processing system constructed in accordance with an embodiment of the present invention;

15 FIGURE 3 is a graph of power (y-axis) versus time (x-axis) for a laser material processing pulse generated in accordance with one embodiment of the present invention;

20 FIGURE 4 is a graph of energy process window (in micro-joules) versus pulse width which shows the dependence of the energy process window on laser pulse width for copper links; an energy process window (in micro-joules) here is the range of the laser pulse energies between the minimum energy needed for severing the links and the maximum energy at which dark spot observed under the links;

25 FIGURE 5 is a graph of a positioning accuracy half window (in microns) versus pulse energy (in micro-joules) which shows accuracy window with a 4 micron spot on copper links; this graph indicates the variation in maximum pulse

energy that can be applied to the link as a function of spot position relative to the center of the link, without causing the optically observed damage; the half window here represents the maximum spot position deviation from the center of the link achieved at each laser pulse energy without observing optical damage;

5 FIGURE 6 is a graph of energy process window (in micro-joules) versus beam size (in microns) which shows the process window as a function of spot size on copper links; the energy process window (in micro-joules) here is the range of the laser pulse energies between the minimum energy needed for severing the links and the maximum energy at which dark spot observed under the links;

10 FIGURE 7 is a graph of energy process window (in micro-joules) versus laser pulse width (in nsec) which shows energy process window as a function of pulse width (for gold links); the energy process window (in micro-joules) here is the range of the laser pulse energies between the minimum energy needed for severing the links and the maximum energy at which dark spot observed under the
15 links; and

 FIGURE 8 illustrates a pair of graphs, one for 13 ns pulse width and the other for 7 ns pulse width, of positioning accuracy half window size (in microns) versus pulse energy (in micro-joules) which show beam position accuracy window with 4 microns on gold links; this graph indicates the variation in maximum pulse
20 energy that can be applied to the link as a function of spot position relative to the center of the link, without causing the optically observed damage; the half window here represents the maximum spot position deviation from the center of the link achieved at each laser pulse energy without observing optical damage.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT(S)

25 Referring to Figure 1, there is illustrated a portion of a die of a semiconductor wafer having numerous circuit elements formed thereon. The circuit elements include a bank 10 of 2 micron gold links and a bank 12 of 2 micron copper links as well as a SiCr, tantalum nitride or NiCr thin film resistive element 14, any

of which can be processed with the method and system of one embodiment of the present invention.

Referring now to Figure 2, there is shown a laser material processing system constructed in accordance with an embodiment of the present invention. The system includes a laser subsystem as illustrated in Figures 5 and 7 of the above-
5 noted '458 patent and as described in the corresponding portions of the '458 patent.

In a preferred embodiment, the laser subsystem utilizes a master oscillator, power amplifier (MOPA) configuration. This system produces a laser pulse that seeds an amplifier to produce a high power short rise time pulse. A seed
10 laser produces fast rise time, short pulse width at very low energy levels. A laser amplifier produces enough energy to do material processing. In Figure 2, the seed laser in combination with the laser amplifier are commonly referred to as a fiber laser.

A fiber laser amplifier and a high-speed infrared laser diode having an output wavelength suitable for a laser processing application is preferred. This
15 fiber laser system produces a laser pulse of the preferred shape and speed as shown in Figure 3 that is, a fast rise time pulse, square at the top and a fast fall time. This pulse shape, in turn, provides the desired laser material interaction results of reduction in metal reflectivity and low diffusion of the energy into the device.

Preferably, a laser pulse width will be easy to set, and may be
20 programmable. One such example is a fiber laser from IPG Photonics that is used by the assignee of the present invention in certain M430 memory repair systems. Laser pulse widths can be selected over a continuous range from 4 ns to 20 ns.

Published U.S. patent application 2004/0188399, assigned to the
25 assignee of the present invention, discloses various laser system embodiments useable for creating or removing a feature on a surface. By way of example, a MOPA system having a fiber optic amplifier is disclosed. The laser processing system may include an output subsystem having an A-O modulator. The MOPA and

output modulator are controlled to selectively direct one or more laser pulses to the target material based on position information. Each of the output pulses incident of the surface may have a different pulse width.

Another way to set a pulse width is to adjust the laser cavity geometry and dimensions, as well as the reflectivity of the output coupler. The laser pulse width can be changed by varying the cavity length and the output coupler reflectivity. The curvatures of both cavity mirrors (the total reflector and the output coupler) may also be changed when the total cavity length is changed according to the laser resonator configuration. Theory and operation of laser resonators can be found in many text books, handbooks, and catalogs provided by laser manufacturers. One such reference is "Lasers" by Peter Milonni and Joseph Eberly, published by John Wiley & Sons 1988. Chapter 14 entitled "Laser Resonators" describes in detail the theory and principles of the laser cavity.

Another way to set a pulse width is to take advantage of a variable laser characteristic, i.e., the pulse width decreases with the increase of the laser energy. One can run the laser to a higher pulse energy level to obtain the needed pulse width, and then externally attenuate the beam to achieve the required energy density.

In order to set or re-set a pulse width, one may also exploit another variable laser characteristic, i.e., the pulse width increases with the repetition rate of the laser.

Referring again to Figure 2, the laser diode which has sub-nanosecond rise time in response to a modulating drive waveform is a starting point in the fiber laser MOPA configuration, with the laser diode as a seed laser. The laser diode generally has multiple longitudinal modes and the subsystem can be configured for single mode operation or otherwise tuned with bulk components at the output or, alternatively, with integrated fiber gratings in the system.

The system of Figure 2 also includes a lens (not shown) to collimate the fiber output, a conventional shutter, a de-polarizer, a polarizer, an isolator (to prevent back reflection), mirrors, a beam splitter, a relay lens, an AOM (acousto optic modulator) and a pre-expander, all of which are well known in the art and are disclosed in numerous patents which describe fiber lasers.

The system of Figure 2 also includes an optional AC voltage-controlled liquid crystal variable retarder (LCVR) and mount. The LCVR includes a birefringent liquid crystal sandwiched between two plates. As is known in the art, the birefringent liquid crystal can rotate the polarization of a laser beam, because light moves at different speeds along different axes through the birefringent liquid crystal, resulting in a phase shift of the polarization. Here, the LCVR rotates the linearly polarized beam so that one can have any linearly polarized beam on the target (links) with polarization in parallel to or perpendicular to link length orientation. Moreover, the birefringent liquid crystal can also transform the linearly polarized laser input into an elliptically or circularly polarized laser output. Laser beam maintains its polarization as it travels from LCVR to the work surface of the die to be processed.

The voltage applied to the liquid crystal variable retarder is controlled by a digital controller and/or a manual controller, which interface with liquid crystal variable retarder through a cable. The manual controller can be adjusted by a user in order to vary the voltage to the LCVR based on the user's knowledge of whether a link to be processed or blown is vertical or horizontal, for example. Digital controller receives input from the computer in order to automatically vary the voltage to LCVR based on information stored in the computer pertaining to the alignment of the links to be cut. This input from the computer controls the digital controller so as to cause an appropriate voltage to be applied to LCVR. The correct voltages to achieve horizontal polarization, vertical polarization, circular polarization, etc. can be determined experimentally.

In at least one embodiment, the digital controller is programmed to select among three different voltages corresponding to vertical linear polarization,

horizontal linear polarization, and circular polarization. In other embodiments, the digital controller stores different voltages, including voltages corresponding to various elliptical polarizations. Other embodiments are also possible in which the optional liquid crystal variable retarder is capable of rotating linear polarization to numerous angles other than the vertical or the horizontal, in the event that polarization at such angles proves useful for some types of cutting or trimming of certain types of structures.

The system of Figure 2 also includes a subsystem for delivering a focused beam to the targets on a single die of a semiconductor wafer. The laser beam positioning mechanism preferably includes a pair of mirrors and attached respective galvanometers (various available from the assignee of the present application). The beam positioning mechanism directs the laser beam through a lens (which may be telecentric or non-telecentric). Preferably, the lens has a scan field of at least 10 mm by 10 mm, a working distance of at least 40 mm to provide access for contacting probes and produces a spot of 6 microns or less. Most preferably, the laser spot size will be in the range of 4 to 5 microns.

The X-Y galvanometer mirror system may provide angular coverage over the entire wafer when sufficient field size and precision are maintained. Otherwise, various positioning mechanisms may be used to provide relative motion between the wafer and the laser beam. For instance, a two-axis precision step and repeat translator may be used to position the wafer galvanometer based mirror system (e.g., in the X-Y plane). The laser beam positioning mechanism moves the laser beam long two perpendicular axes, thereby providing two dimensional positioning of the laser beam across the wafer region. Each mirror and associated galvanometer moves the beam along its respective x or y axis under control of the computer.

The beam positioning subsystem may include other optical components, such as a computer-controlled, optical subsystem for adjusting the laser spot size and/or automatic focusing of the laser spot at a location of the die of the wafer.

The system of Figure 2 may also include an optical sensor system in an alignment process. In one embodiment, an optical sensor of the system may include a camera (as described in the '995 patent) which operates in combination with a pair of illuminators as shown in Figure 2. In another embodiment, the optical sensor of the system includes a single photo detector wherein a laser pulse is attenuated by the AOM and the attenuated pulse is sensed by the photo detector after being reflected back from the die. The reflection may be from an alignment feature or other structures used for alignment. Preferred alignment feature width is .5x to 2x the spot diameter, most preferred width equals the spot size.

The reflection may also be from a non-alignment feature. For example, the reflection may be from a link in a group of links to be processed whereby the reflection is used to determine a link edge to finely align the group of links for processing. In yet another embodiment, a low power laser (not shown in Figure 2 but shown in Figure 13 of the '7581 publication and described in the corresponding portion of the specification) can be used for optical inspection or detection purposes.

Semiconductor wafers having die which include copper links have been processed by cutting links with the laser material processing system of Figure 2. The copper links were 2 μm wide with a 22 μm pitch. The processing system includes a fiber laser to generate shaped pulses with adjustable pulse widths, in this case, a square pulse shape. The spot size on the targets was about 4 μm . Die reference marks near each link bank (i.e., 28 links per bank) were used to confirm that the focal plane height was correct prior to link processing or blasting.

Links were processed using 7 ns, 13 ns, 16 ns, and 21 ns width pulses. All links were processed using polarization across the links as it gives the best results in terms of process window.

Results

The following table is a summary of the clean blow and darkening thresholds.

	Pulse width (ns)	Link visually severed threshold (μJ)	Link underside dark spot appearance threshold (μJ)
5	7	2.2	2.4
	13	1.2	2.6
	16	1.0	2.4
	21	1.2	1.8

10 It is clear that for processing copper links, the pulse shape, as well as the pulse width, are important for the best process window. In other words, the process window depends on both the pulse width and pulse shape.

The graph of Figure 4 shows the dependence of energy process window on the laser pulse width for copper links.

15 Positioning accuracy tests were carried out by moving the center of the beam deliberately away from the center of the links and the same damage criteria were used to determine the damage, which is optically observed damage. The graph of Figure 5 shows the beam positioning window for 4 μm spot size on copper link wafers using an IPG laser.

20 Since the links are 2 μm wide, there is almost no process window with a 6 μm beam as the damage is always occurring before the link is cleanly blown. The process window is the most when the beam size is around 4 μm , as illustrated in the graph of Figure 6. This graph is for processing copper links with 2 μm width and using the IPG laser at 13 ns pulse width.

In like fashion, gold link wafers were processed with the system of Figure 2. The gold links are 2 μm wide with a 16.5 μm pitch. The trimming system includes a fiber laser to generate shaped pulses with adjustable pulse widths, in this case, a square pulse shape. The spot size on the targets was about 4 μm . Die reference marks near each link bank (i.e., 40 links per bank) were used to confirm that the focal plane height was correct prior to link blasting.

Links were processed using 7 ns, 13 ns, and 21 ns pulse widths. All links were processed using polarization across the links as it gives the best results in terms of process window.

10 Results

The following table is a summary of the clean blow and darkening thresholds.

Pulse width (ns)	Link visually severed threshold (μJ)	Link underside dark spot appearance threshold (μJ)
7	2.2	2.4
13	1.2	2.6
21	1.2	1.8

It is clear that for processing gold links, the pulse shape, as well as the pulse width, are important for the best process window. In other words, the process window depends on both the pulse width and pulse shape.

20 The graph of Figure 7 shows the dependence of energy process window on the laser pulse width for gold links.

Positioning accuracy tests shown in Figures 5 and 8 were carried out by offsetting the center of the beam away from the center of the links and visually

observing damage to each link. Each graph shows the observed damage energy threshold vs. the position offset. Maximum energy values shown correspond to near-ideal, spot-to-link alignment. The energy process window accounts for processing system positioning errors and is generally less than the maximum energies shown in Figures 5 and 8. The graphs of Figures 5 and 8 show the beam positioning window for 4 μm spot size on wafers using copper and gold links, respectively, using an IPG laser. The above-noted tests are similar to the Venier run test described in Chapter 19 of LIA HANDBOOK OF LASER MATERIALS PROCESSING, entitled "Link Cutting Making" (particularly Figure 11 of that chapter).

10 Beam spot sizes have an impact on the process window for gold links, similar to copper links.

An IPG fiber laser may be used in one embodiment of a system of the present invention to generate pulse widths which are adjustable from 5 ns to 21 ns. The duration can be extended to 50 ns or longer, such as 200 ns and can be contracted to 1 ns as indicated in Figure 3.

In another embodiment of the system, a 1.3 micron fiber laser (Erbium-doped amplifier and a 1.3 micron laser diode) may be used to exploit the wavelength-sensitive transmissive property of the silicon substrate and, when combined with the square-shaped pulse and selectable pulse width, may provide further process window improvements.

Typical laser processing conditions:

(A) Metal link blowing:

2 μm wide Copper links: pulse width 13-16 ns, process energy 1 μj
 - 4 μj
 25 2 μm wide gold links: Pulse width 7-16 ns, process energy 0.2 - 4.2 μj

(B) Thin Film resistor trimming:

SiCr: Usually short pulse work better - 7-13 ns, energy 0.05 - 0.5 μ j

NiCr: Usually longer pulse work better: 25-50 ns, 0.1 - 0.5 μ j

5

tantalum nitride: 25-50 ns, 0.1-0.5 μ j

(C) Thick Film resistor trimming:

Pulse width, 7-50 ns, 1-40 μ j.

10 A single pulse-shaped and pulse width tunable laser in a laser processing system may be provided for link blowing as well as thin and thick film resistor trimming.

A pulse of the pulse-shaped laser may have a pulse energy from 0.1 μ j to 100 μ j, typical 20-40 μ j.

The pulse-shaped laser may have a pulse repetition rate of 1 KHz to 200 KHz, typical 1 to 50 KHz.

15 A pulse of the pulse-shaped laser may have a rise time less than 1.5 ns and fall time of less than 2 ns.

A pulse of the pulse-shaped laser may have a square pulse shape.

The pulse-shaped laser may have tunable or adjustable pulse widths (durations) from 1 ns to 200 ns, typical from 4 ns to 50 ns.

20 A pulse of the pulse-shaped laser may have a TEM 00 beam.

The pulse-shaped laser may use a MOPA configuration. The seeder may be either a semiconductor laser or a Q-switched laser, and the amplifiers may be a fiber laser.

The pulse-shaped laser may be a fiber laser.

5 A pulse of the pulse-shaped laser may have a wavelength of 0.2 μm to 2.5 μm . For instance, a green wavelength (532 nm) or ultraviolet wavelength (355 nm) obtained by shifting the output wavelength of a near IR fiber laser amplifier.

10 A pulse of the pulse-shaped laser may have a wavelength of about 1 μm , for example, 1.064 microns.

A pulse of the pulse-shaped laser may have a wavelength of 1.2 μm .

A pulse of the pulse-shaped laser may have a wavelength of 1.3 μm .

15 One such laser may be a conventional fiber laser from IPG, and used in memory repair systems of the assignee of the present application. A plurality of closely-spaced pulses generated in rapid succession may be used in certain embodiments, for example, prior to measurement.

The method and system of one embodiment of the present invention may process:

20 Thin films like SiCr, NiCr-based or tantalum nitride, thin film resistors formed on die of semiconductor wafers; and

Link fuses, such as polysilicon, copper, aluminum, or gold link fuses.

In one embodiment, all targets of the same or similar material on all of the die of the wafer are processed before changing pulse width and/or shape. In

another embodiment, pulse width and/or shape is changed during processing of different materials on a single die.

In one embodiment, both passive and functional trimming can be performed.

- 5 While embodiments of the invention have been illustrated and described, it is not intended that these embodiments illustrate and describe all possible forms of the invention. Rather, the words used in the specification are words of description rather than limitation, and it is understood that various changes may be made without departing from the spirit and scope of the invention.

WHAT IS CLAIMED IS:

1 1. A method of laser processing targets of different types on a
2 workpiece, the method comprising:
3 setting a laser pulse width of one or more laser pulses to selectively
4 provide one or more laser output pulses having one or more set pulse widths based
5 on a first type of target to be processed;
6 setting a pulse shape of the one or more output pulses to selectively
7 provide the one or more output pulses having the set pulse shape based on the types
8 of targets to be processed;
9 delivering at least a portion of the one or more output pulses having
10 the one or more set pulse widths and the set pulse shape to at least one target of the
11 first type; and
12 resetting the laser pulse width of one or more laser pulses to
13 selectively provide one or more laser output pulses having one or more reset pulse
14 widths based on a second type of target to be processed.

1 2. The method as claimed in claim 1, wherein the set and reset
2 pulse widths are selectable over a continuous range of 1 nanosecond to 200
3 nanoseconds.

1 3. The method as claimed in claim 2, wherein the range is 4
2 nanoseconds to 50 nanoseconds.

1 4. The method as claimed in claim 1, wherein the pulse width
2 is programmable.

1 5. The method as claimed in claim 1, wherein the output pulses
2 are delivered by a laser beam delivery subsystem and wherein the laser beam has a
3 flat top profile.

1 6. The method as claimed in claim 1, wherein the set pulse shape
2 is a square pulse shape.

1 7. The method as claimed in claim 1, wherein the delivered
2 output pulses have a pulse energy in a range of .1 microjoules to 5 microjoules.

1 8. The method as claimed in claim 7, wherein the range is .2
2 microjoules to 1.5 microjoules.

1 9. The method as claimed in claim 1, wherein the laser pulses
2 are generated by a pulse-shaped laser and wherein the pulse-shaped laser has a
3 repetition rate in a range of 1 kHz to 200 kHz.

1 10. The method as claimed in claim 9, wherein the repetition rate
2 has a range of 1 kHz to 50 kHz.

1 11. The method as claimed in claim 1, wherein one of the
2 different types of targets is a thick or thin film-based device.

1 12. The method as claimed in claim 11, wherein the devices are
2 thin film resistance elements.

1 13. The method as claimed in claim 12, wherein the thin film
2 resistance elements are at least partially made of at least one of SiCr, NiCr-based
3 and tantalum nitride material.

1 14. The method as claimed in claim 1, wherein the different types
2 of targets are links.

1 15. The method as claimed in claim 14, wherein the links include
2 at least one of polysilicon, aluminum, gold and copper links.

1 16. The method as claimed in claim 1, wherein the targets include
2 a bank of links of a first material and a bank of links of a second material different
3 from the first material.

1 17. The method as claimed in claim 1, wherein the targets include
2 a bank of links and a thick or thin film-based device.

1 18. The method as claimed in claim 1, wherein the processing
2 includes trimming.

1 19. The method as claimed in claim 18, wherein the trimming is
2 at least one of passive and functional trimming.

1 20. The method as claimed in claim 1, wherein at least one of the
2 steps of setting is repeated after all targets of the same or similar material on the
3 workpiece are processed.

1 21. The method as claimed in claim 1, wherein at least one of the
2 steps of setting is repeated during processing of targets made of different material
3 on the workpiece.

1 22. The method as claimed in claim 1, wherein the processing
2 includes trimming and link blowing and wherein the steps of setting and resetting
3 the laser pulse width allows the independent optimization of a process window for
4 not only the trimming but also for the link blowing.

1 23. The method as claimed in claim 1, wherein spot size at the at
2 least one target is in a range of 4 microns to 5 microns with a working distance of
3 40 mm and a field size of at least 10 mm by 10 mm.

1 24. A laser-based material processing method comprising:
2 providing a first target of a first type on a die;
3 providing a second target of a second type on the die, wherein the
4 first and second types are different types; and
5 processing the first and second targets with a single pulse-shaped
6 laser having an adjustable pulse width.

1 25. A method of blowing links and trimming thin film resistors
2 on a workpiece, the method comprising:
3 setting a laser pulse width of one or more laser pulses to selectively
4 provide one or more laser output pulses having either a first pulse width of 13-16
5 ns, or a second set pulse width of 7-16 ns based on links of copper or gold to be
6 blown, respectively, wherein process energy of the one or more output pulses for
7 the copper or gold links is $1 \mu\text{j}$ - $4 \mu\text{j}$ and 0.2 - $4.2 \mu\text{j}$, respectively;
8 setting a pulse shape of the one or more output pulses to selectively
9 provide the one or more output pulses having the set pulse shape based on the type
10 of targets to be laser processed;
11 delivering at least a portion of the one or more output pulses having
12 the set pulse shape and the first or second set pulse widths to the copper or gold
13 links, respectively; and
14 resetting the laser pulse width of one or more laser pulses to
15 selectively provide one or more laser output pulses having either a third pulse width
16 of 7 - 13 ns or a fourth pulse width of 25 - 50 ns based on either an SiCr thin film
17 resistor or an NiCr or tantalum nitride thin film resistor, respectively, wherein
18 process energy of the one or more output pulses for the thin film resistors is 0.05 -
19 $0.5 \mu\text{j}$ or 0.1 - $0.5 \mu\text{j}$, respectively.

1 26. A system for laser processing targets of different types on a
2 workpiece, the system comprising:
3 a laser subsystem for generating one or more laser pulses;
4 a controller operatively connected to the laser subsystem to:
5 set a laser pulse width of the one or more laser pulses to
6 selectively provide one or more laser output pulses having one or more set pulse
7 widths based on a first type of target to be processed;
8 set a pulse shape of the one or more output pulses to
9 selectively provide the one or more output pulses having the set pulse shape based
10 on the first type of target; and

11 reset the laser pulse width of one or more laser pulses to
12 selectively provide one or more laser output pulses having one or more reset pulse
13 widths based on a second type of target to be processed; and
14 a laser beam delivery subsystem including an optical subsystem for
15 delivering at least a portion of the output pulses having the set pulse shape and the
16 set and reset pulse widths to the first and second types of targets, respectively.

1 27. The system as claimed in claim 26, wherein the output pulses
2 have a rise time of less than 1.5 nanoseconds and a fall time of less than 2
3 nanoseconds.

1 28. The system as claimed in claim 26, wherein the output pulses
2 have a wavelength in the range of .2 microns to 2.5 microns.

1 29. The system as claimed in claim 28, wherein the wavelength
2 is one of about 1 micron, about 1.2 microns, about 1.3 microns, about .532 microns
3 and about .355 microns.

1 30. The system as claimed in claim 26, wherein the laser beam
2 delivery subsystem selectively delivers the output pulses to the targets based on
3 position information.

1 31. The system as claimed in claim 26, wherein the laser
2 subsystem includes a single pulse-shaped and pulse width tunable laser.

1 32. The system as claimed in claim 26, wherein the laser
2 subsystem includes a fiber laser.

1 33. The system as claimed in claim 26, wherein the laser
2 subsystem includes a fast rise, fast fall, pulse-shaped laser.

1 34. The system as claimed in claim 33, wherein the laser
2 subsystem includes a Q-switched laser.

1 35. The system as claimed in claim 26, wherein the laser
2 subsystem has a MOPA configuration and includes an oscillator and an amplifier.

1 36. The system as claimed in claim 35, wherein the oscillator
2 includes a tunable or adjustable pulse width, semiconductor laser.

1 37. The system as claimed in claim 35, wherein the amplifier
2 includes a fiber-based amplifier.

1 38. The system as claimed in claim 26, wherein the laser
2 subsystem includes a laser which has an output coupler and a laser cavity and
3 wherein geometry and dimensions of the laser cavity are adjusted and reflectivity of
4 the output coupler is adjusted to set the pulse width.

1 39. The system as claimed in claim 26, wherein the controller sets
2 the pulse width by changing pulse energy level of a laser of the laser subsystem.

1 40. The system as claimed in claim 26, wherein the controller sets
2 the pulse width by changing repetition rate of a laser of the laser subsystem.

1 41. The system as claimed in claim 26, further comprising a
2 sensor subsystem including an optical sensor for sensing a laser pulse reflected from
3 the workpiece to obtain a signal and a signal processor for processing the signal to
4 obtain alignment information for laser processing.

1 42. The system as claimed in claim 41, wherein the laser pulse is
2 reflected from an alignment feature of the workpiece, and wherein the alignment
3 feature has a width from $\frac{1}{2}$ to 2 times the diameter of a laser spot delivered to the
4 target.

1 43. The system as claimed in claim 42, wherein width of the
2 alignment feature is substantially equal to spot diameter.

1 44. The system as claimed in claim 41, wherein the laser pulse is
2 reflected from a link in a group of links to be laser processed.

1 45. The system as claimed in claim 26, wherein the laser beam is
2 initially linearly polarized and wherein the system further comprises a LCVR and
3 a LCVR controller for controlling the LCVR so that the LCVR controllably rotates
4 the linearly polarized laser beam based upon alignment of the targets.

1 46. The system as claimed in claim 26, wherein the laser beam has
2 an initial polarization and wherein the system further comprises a LCVR and an
3 LCVR controller for controlling the LCVR so that the LCVR controllably converts
4 the initial polarization to a desired polarization.

1 47. The system as claimed in claim 26, wherein the optical
2 subsystem adjusts at least one of spot size and the focus of the laser beam on the at
3 least one target.

1 48. The system as claimed in claim 26, further comprising a
2 positioning mechanism for providing relative motion between the workpiece and the
3 laser beam.

1 49. The system as claimed in claim 26, wherein the system has a
2 positioning accuracy half window size less than .6 microns.

1 50. A system for laser processing targets of different types on a
2 workpiece, the system comprising:

3 a laser subsystem including an oscillator having a single tunable or
4 adjustable pulse width, semiconductor laser and a fiber-based amplifier for
5 generating one or more laser pulses;

6 a controller operatively connected to the laser subsystem to:

7 set a laser pulse width of the one or more laser pulses to selectively
8 provide one or more laser output pulses having one or more set pulse widths based
9 on a first type of target to be processed;

10 set a pulse shape of the one or more output pulses to selectively
11 provide the one or more output pulses having the set pulse shape based on the first
12 type of target; and

13 reset the laser pulse width of one or more laser pulses to selectively
14 provide one or more laser output pulses having one or more reset pulse widths based
15 on a second type of target to be processed;

16 a laser beam delivery subsystem including an optical subsystem
17 having a lens for delivering at least a portion of the output pulses having the set
18 pulse shape and the set and reset pulse widths to the first and second types of
19 targets, respectively, based on position information; wherein the optical subsystem
20 adjusts at least one of spot size and the focus of the laser beam on the at least one
21 target; and wherein the lens has a scan field of at least 10 mm by 10 mm, a working
22 distance of at least 40 mm to provide access for contacting probes and produces a
23 spot having a spot size of 6 microns or less;

24 a sensor subsystem including an optical sensor for sensing a laser
25 pulse reflected from the workpiece to obtain a signal;

26 a signal processor for processing the signal to obtain alignment
27 information for laser processing;

28 a LCVR for optically processing the laser beam;

29 an LCVR controller for controlling the LCVR; and

30 a positioning mechanism for providing relative motion between the
31 workpiece and the laser beam.

1/4

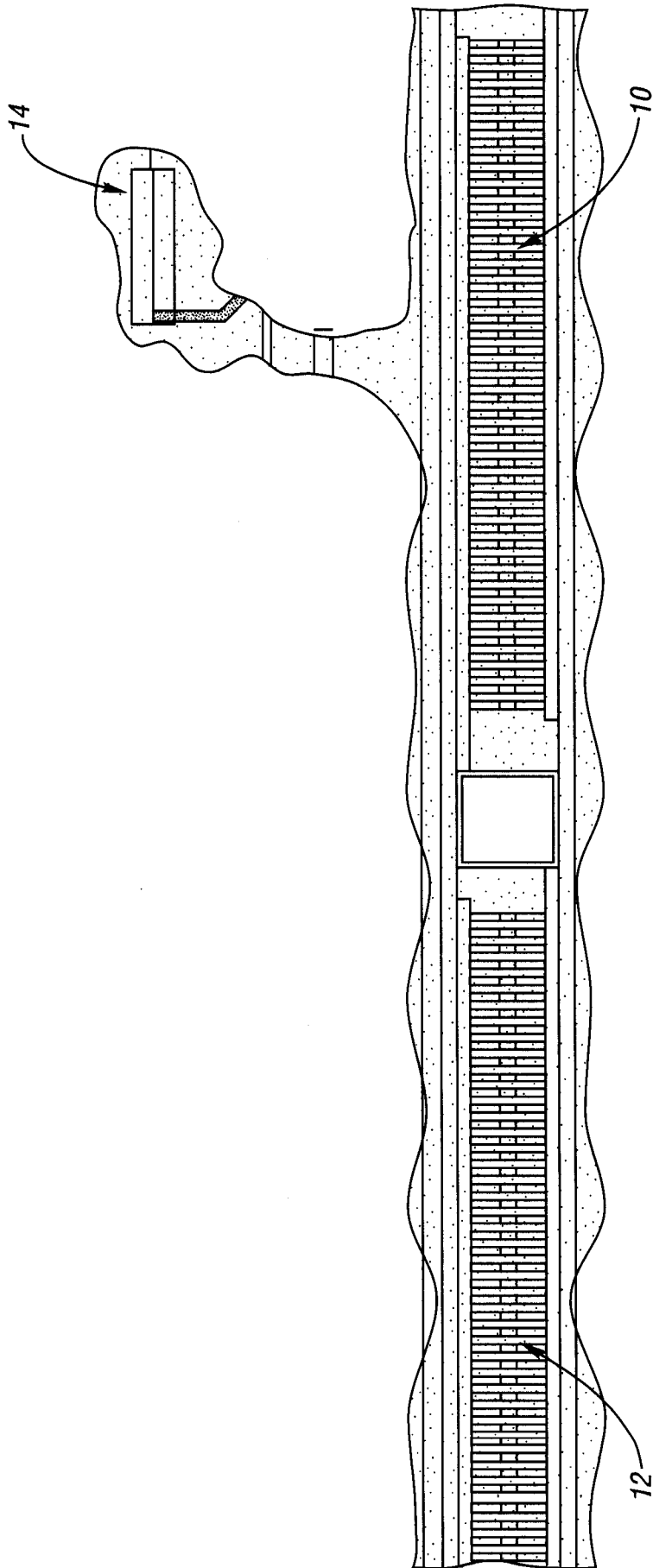
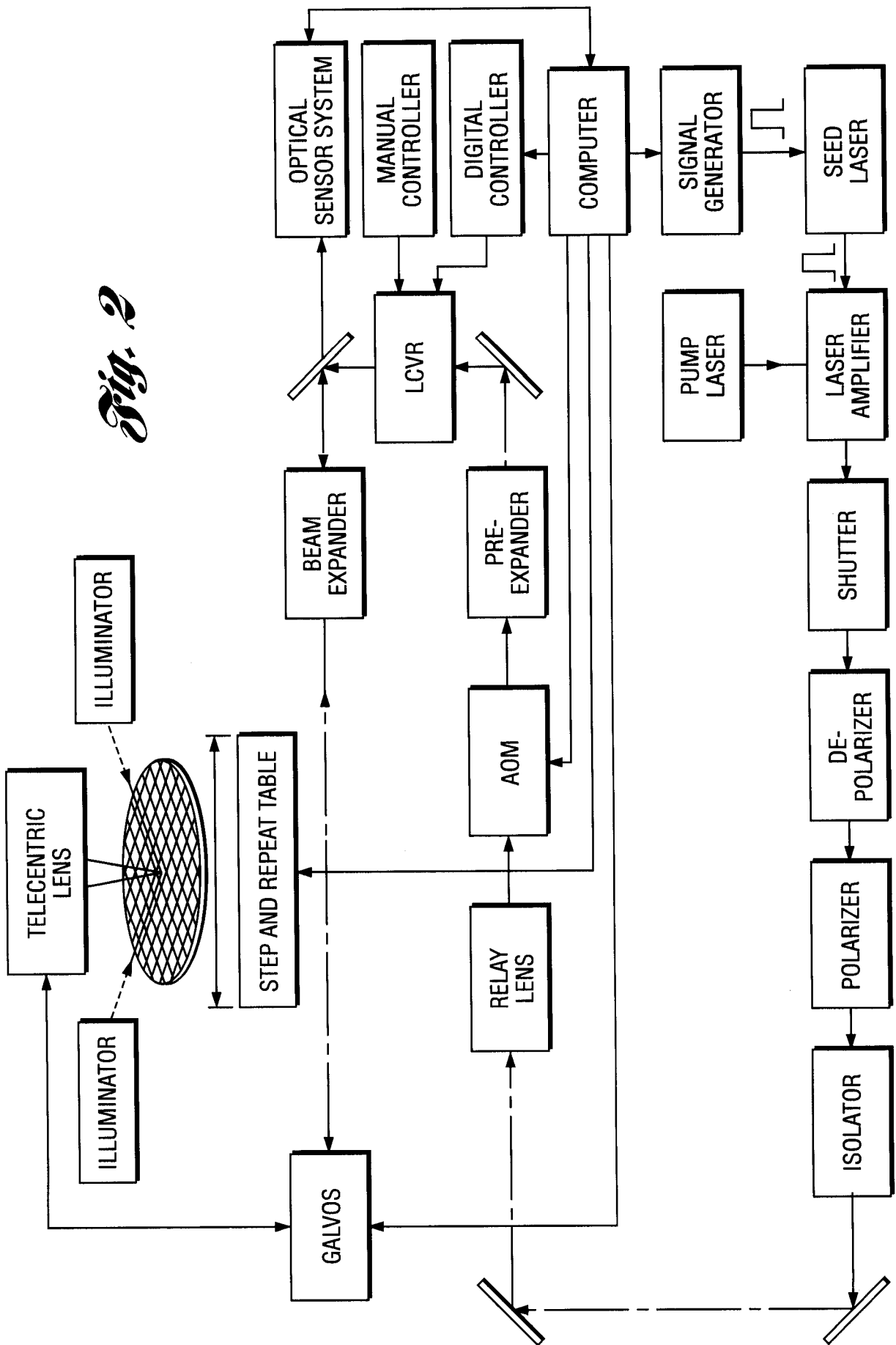


Fig. 1



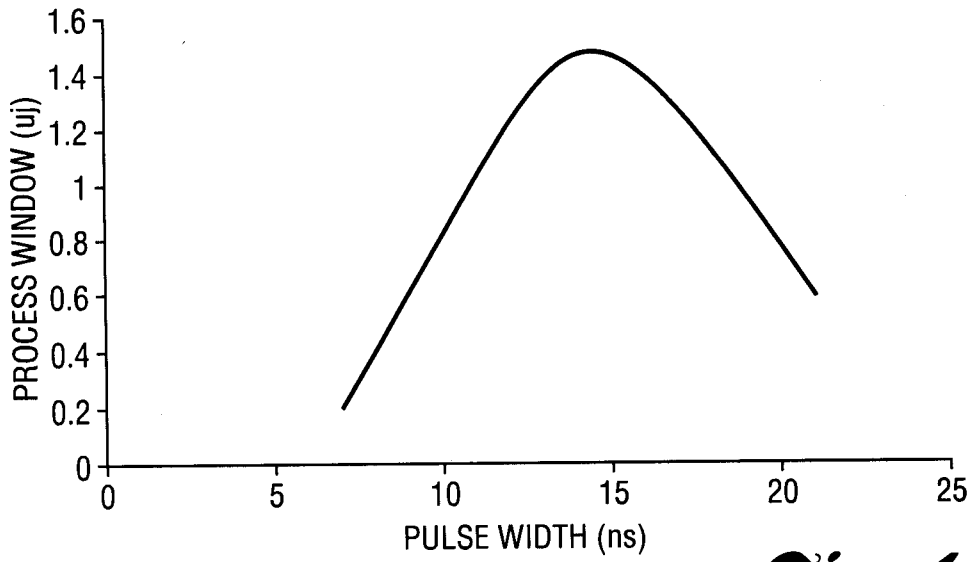
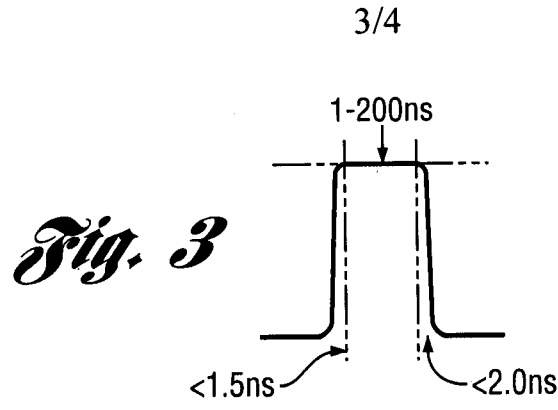


Fig. 4

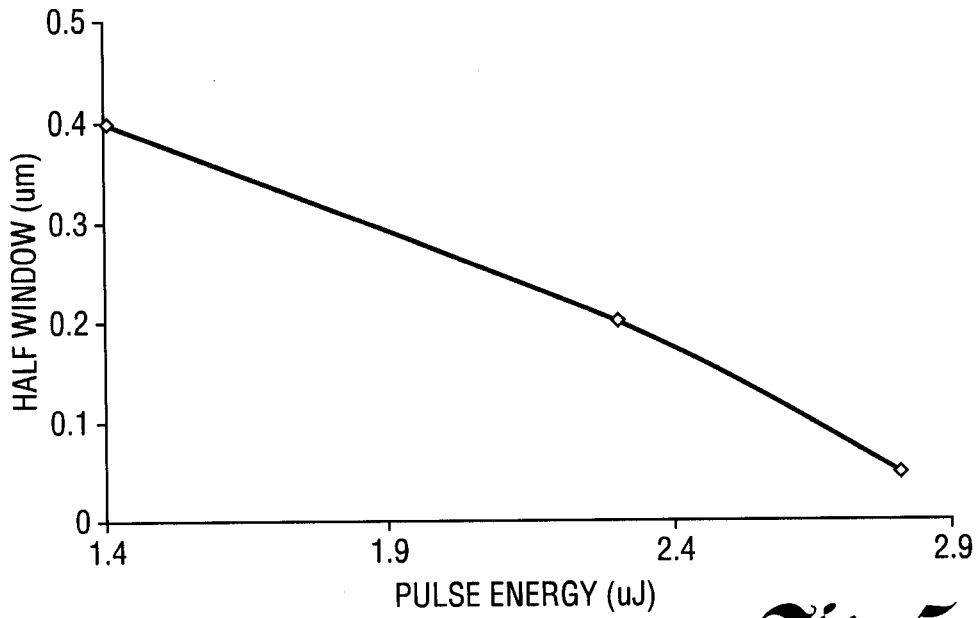


Fig. 5

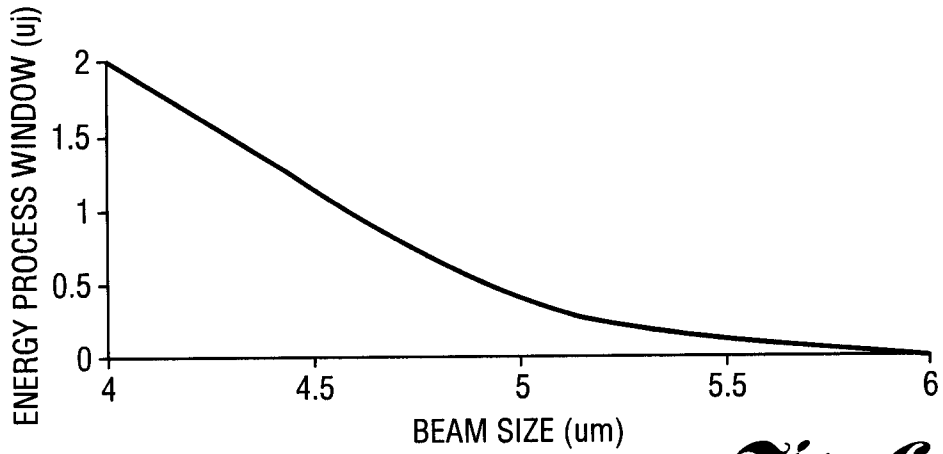


Fig. 6

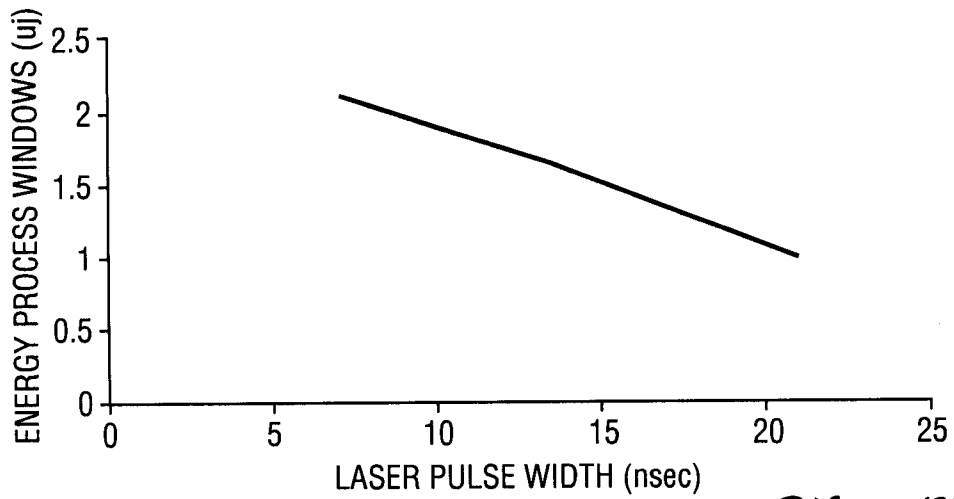


Fig. 7

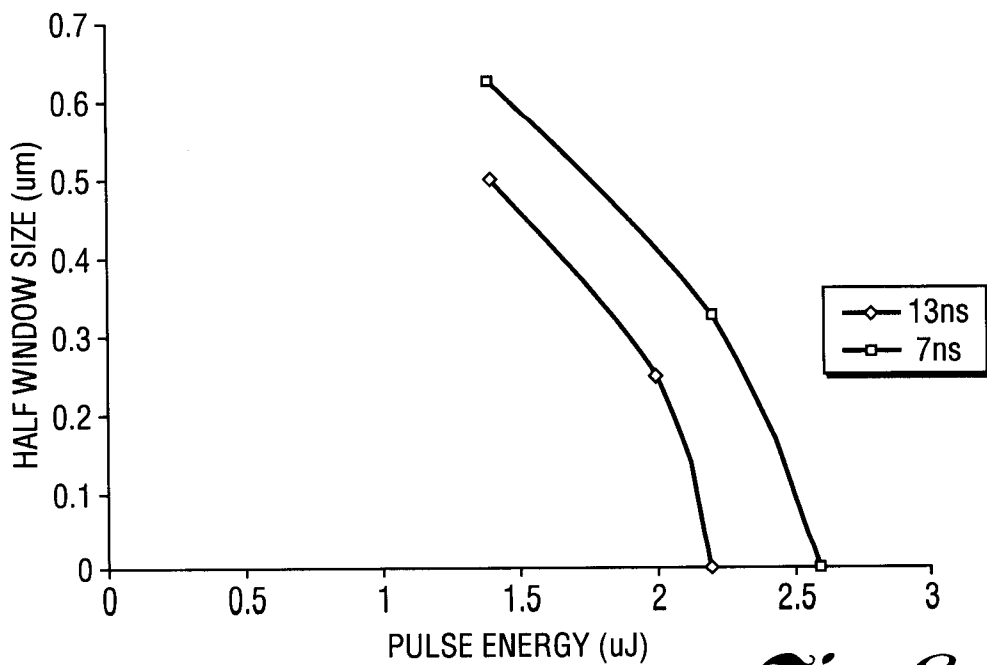


Fig. 8