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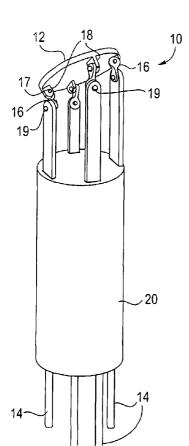
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(54) Title: PLATFORM LINK WRIST MECHANISM



(57) Abstract: The present invention provides a robotic surgical tool (50) for use in a robotic surgical system. The robotic surgical tool (50) includes a wrist mechanism (10) disposed near the distal end of a shaft (52) that connects with an end effector (66). The wrist mechanism (10) includes a distal member (12) configured to support the end effector (66), and a plurality of rods (14) extending generally along an axial direction within the shaft (52) and moveable generally along this axial direction to adjust the orientation of the distal member (12) with respect to the shaft (52). The distal member (12) has a base to which the rods are rotatably connected by orthogonal linkage assemblies (16). This configuration allows for movement of the end effector (66) in pitch, yaw, and roll directions.

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International application No.

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IPC(7) : A61B 17/00					
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U.S.: 901/29; 606/1, 130; 600/141, 102					
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Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)					
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C. DOCUMENTS CONSIDERED TO BE RELEVANT					
Category *	Citation of document, with indication, where a	ppropriate, of the rele	vant passages	Relevant to claim No.	
X	US 5,792,135 A (MADHANI et al) 11 August 1998			1, 5, 8-10, 14-21, 27-	
				36	
Y	30			30	
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X	US 5,715,729 A (TOYAMA et al) 10 February 1998 (10.02.1998), entire document.			1, 5, 7, 10, 14	
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Further documents are listed in the continuation of Box C.		See patent	family annex.		
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"O" document	referring to an oral disclosure, use, exhibition or other means	being obvious to a person skille ' in the art			
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