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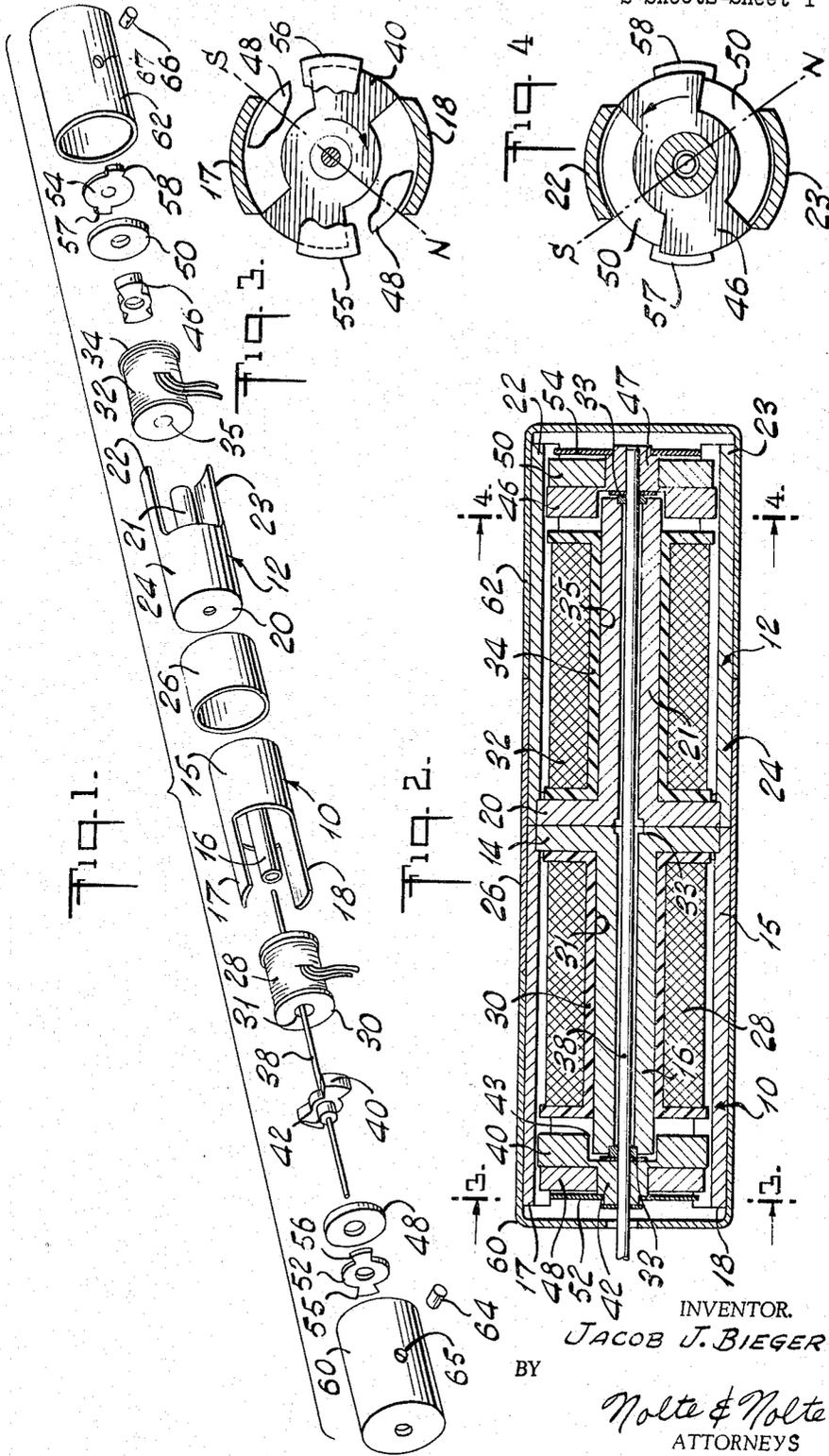
J. J. BIEGER

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ROTARY ELECTROMAGNETIC ACTUATOR

Filed Sept. 12, 1962

2 Sheets-Sheet 1



INVENTOR.
 JACOB J. BIEGER
 BY
Molte & Molte
 ATTORNEYS

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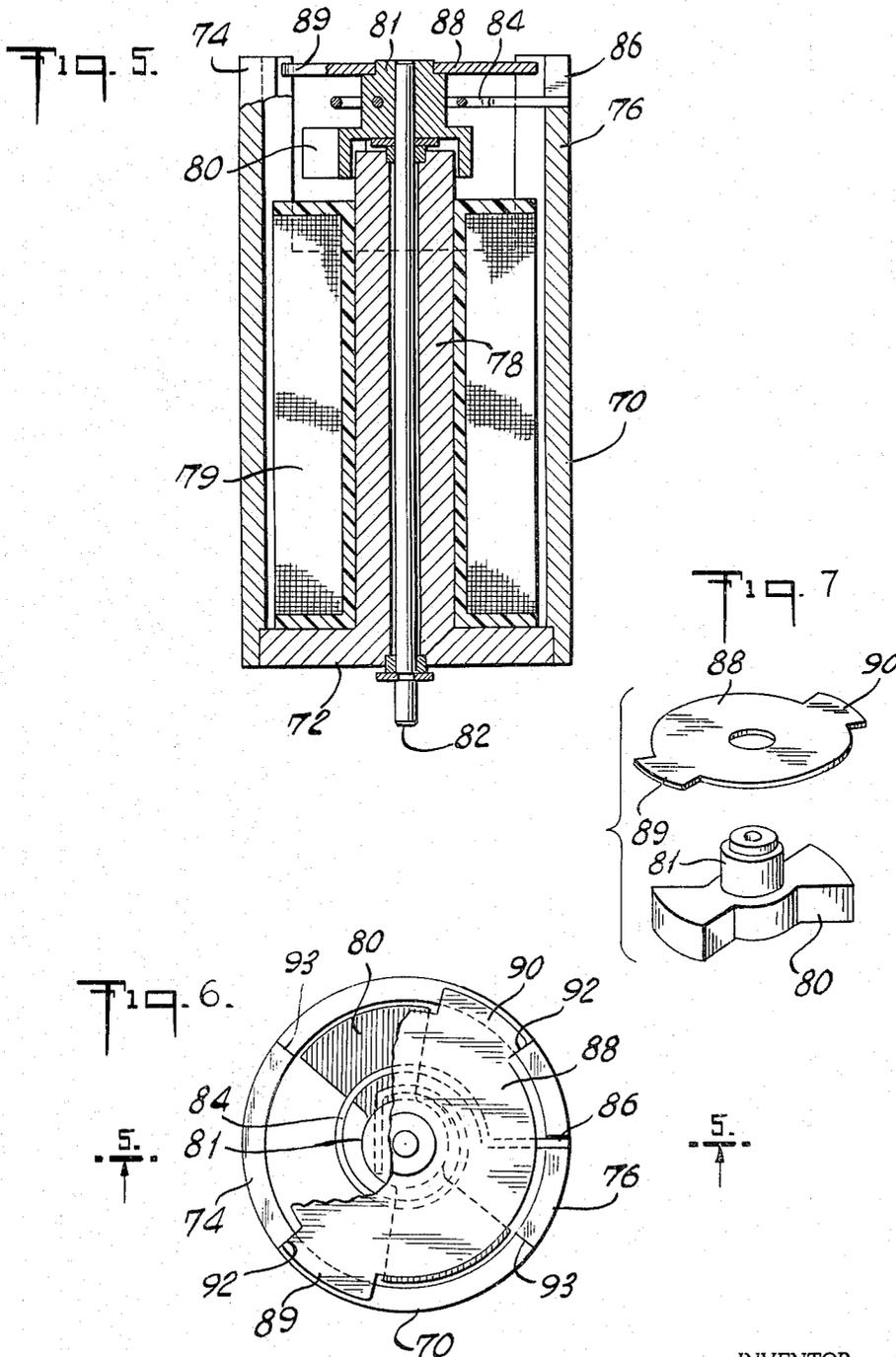
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JACOB J. BIEGER
BY

Molte & Molte
ATTORNEYS

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ROTARY ELECTROMAGNETIC ACTUATOR

Jacob J. Bieger, Queens Village, N.Y., assignor, by mesne assignments, to Daco Instrument Company, Inc., Brooklyn, N.Y., a corporation of New York.
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 7 Claims. (Cl. 317-197)

This invention relates to rotary electromagnetic actuators. More particularly, this invention relates to solenoids having rotatable armatures which may be angularly displaced to one of three distinct positions.

The type of solenoid to which the present invention pertains has particular utility as an indicating device in electrical circuits. It is often necessary to give a visual indication to show which of a plurality of circuits has been energized. As a specific example, it might be desirable to indicate which of two circuits is in an energized state or whether neither has been energized. For purposes of simplicity and economy, such a visual indication may be readily given by placing the coils of a rotary electromagnetic actuator, or solenoid, in the separate circuits whereby a visual indicator may be rotated in one of two directions depending on which circuit is energized. If the indicator remains in its initial position, this would mean that neither circuit has been energized.

Accordingly, it is an object of this invention to provide an improved three-position rotary solenoid.

Another object is to provide a rotary solenoid which is rugged in design, simple in construction and economical to manufacture.

The objects of the invention are accomplished by providing two oppositely disposed stator sections, a rotor shaft extending therethrough, and a pair of rotors rotatably displaced from one another and associated with respective stators, the rotors being individually operable to rotate the shaft in a given direction when the coil of its associated stator is energized. A return means, which may comprise a pair of permanent magnets operative in conjunction with the outer pole pieces of the stators, biases the rotor shaft to its center position, so that when neither coil is energized the shaft will maintain its initial position.

The manner in which these objects are accomplished will be further explained with reference to the following specification and drawings, wherein:

FIG. 1 is an exploded view of the three-position actuator according to the invention;

FIG. 2 is a side view in section of the rotary actuator;

FIG. 3 is a view along the line 3-3 of FIG. 2;

FIG. 4 is a view along the line 4-4 of FIG. 2;

FIG. 5 is a cross-sectional view of another embodiment of the invention;

FIG. 6 is a cut-away top view of the embodiment of FIG. 4; and

FIG. 7 is an exploded view of the rotor and stop member of the second embodiment.

In FIGS. 1 to 3, the three-position rotary solenoid is shown comprising first and second stator sections 10 and 12, respectively. Stator section 10 includes a base 14, a cylindrical wall 15 press-fit thereover, and an outwardly extending center pole piece 16 integrally formed with base 14. In addition, stator section 10 includes two oppositely disposed, outer pole piece members 17 and 18 integrally formed with wall 15. Stator section 12 is constructed identically as stator 10 and includes a base 20, a center pole piece 21, and two outer pole pieces 22 and 23 extending from a cylindrical wall portion 24. The stators are made of a material which will provide suitable flux paths when the solenoid is energized. As shown in FIG. 2, the stators of the assembled solenoid are arranged in end-to-end relationship with base 14 abutting against base

20, and pole pieces 17 and 18 of stator 10 aligned with pole pieces 22 and 23, respectively, of stator 12.

The stators may be held in this relationship by means of a cylindrical sleeve member 26 into which the bottoms of cylindrical walls 15 and 24 may be inserted and secured by friction.

A first coil 28 is wound around a plastic spool-like coil form 30 having a central bore 31 through which center pole piece 16 extends. Similarly, a second coil 32 is wound around a second spool-like coil form 34 having a central bore 35 into which center pole piece 21 extends.

The center pole pieces are slightly longer than their associated coil form, so that when the ends of coil forms 30 and 32 rest against the tops of bases 14 and 20, respectively, the upper portions of the center pole pieces protrude from the coil forms.

A rotor shaft 38 extends through the center of coil forms 30 and 32 and is suitably journaled in bearings 33 in center pole pieces 16 and 21 of stator sections 10 and 12, respectively. A first bow-shaped rotor 40 including an integrally formed hub member 42 is secured to shaft 38 immediately above center pole piece 16. Rotor 40 may be made of solid magnetic material and includes a center recess 43 beneath hub 42 into which the protruding end of center pole piece 16 extends. In a similar manner, a second bow-shaped rotor 46 including an integral hub member 47 is secured to shaft 38 opposite rotor 40. Rotor 46 is also centrally recessed, so that the protruding end of center pole piece 21 extends substantially into the rotor. When one of coils 28 and 32 is energized, a magnetic flux is generated in its associated stator wall and pole pieces. The respective rotor is attracted by the magnetic lines of flux passing transversely through the air gap (between the rotor and outer pole pieces) to the rotor. The salient poles of the rotor are attracted to the stator pole pieces of opposite polarity, thus imparting a rotary motion to the rotor. By utilizing recessed rotors and mounting the mover respective center pole pieces of each stator, the effect of the magnetic thrust which acts downwardly on the rotors, and thus tends to lessen the torque developed during rotation, is minimized. As shown in FIGS. 3 and 4, the rotors are rotatably displaced on shaft 38 with respect to each other so that energization of coil 28 will cause rotor 40 to rotate shaft 38 in a clockwise direction, while energization of coil 32 will cause rotor 46 to rotate the shaft in a counter-clockwise direction.

Rotor shaft 38 is returned to its initial position by means of a pair of flat, annular permanent magnets 48 and 50 which may be press fit to hub members 42 and 47, respectively. Magnets 48 and 50 have magnetic fields as illustrated in FIGS. 3 and 4, which exert forces with respect to their associated outer pole pieces so that magnet 48 tends to rotate shaft 38 counterclockwise, while magnet 50 tends to rotate the shaft in a clockwise direction. Accordingly, when the solenoid is de-energized, the rotor shaft maintains a position in which the opposing magnetic forces are equal or balanced.

The solenoid also includes a pair of thin annular stop members 52 and 54 press fitted to the extremities of hubs 42 and 47, respectively, for limiting the rotary movement of shaft 38. Stop member 52 includes ears 55 and 56 adapted to abut against outer pole pieces 18 and 17, respectively, when shaft 38 is rotated clockwise. Stop member 54 includes ears 57 and 58 adapted to abut against pole pieces 22 and 23, respectively, when shaft 38 is rotated in a counterclockwise direction.

The entire solenoid may be enclosed in a pair of cylindrical end caps 60 and 62. A small insulated tube 64 fits into aperture 65 of tube 60 to receive the leads of

coil 28, and, similarly, a tube 66 extends into aperture 67 of cap 62 to receive the leads of coil 32.

One end of shaft 38 is shown extending outwardly of end cap 60 and may be connected to conventional indicating means. When current is applied to coil 28, a magnetic field is established in the pole pieces of first stator section 10 which will cause rotor 40 to rotate in a clockwise direction until the movement is arrested by abutment of the ears of stop member 52 against outer pole pieces 17 and 18. When the energization of coil 28 is removed, the unbalanced forces of the displaced magnets 48 and 50 return rotor shaft 38 to its original position at which point the forces of the two magnets are again balanced. Similarly, if current is passed through coil 32, rotor 46 rotates shaft 38 in a counterclockwise direction, and when the current is removed, the unbalanced magnetic fields of magnets 48 and 50 return the shaft to its initial position.

An alternate embodiment of the invention, in which a return spring is employed, is illustrated in FIGS. 5-7. Only one stator section is illustrated, since the second section could be substantially identical, as discussed above with reference to FIGS. 1-4. In fact, since the individual stator sections would have utility by themselves in any situation wherein only two separate angular positions are necessary, this embodiment will be described as a single stator, two position, rotary solenoid.

The stator of the second embodiment includes a base 72 and a cylindrical wall 70 press fit thereover. A pair of integral, curved pole pieces 74 and 76 extend upwardly from wall 70 at opposite ends of a diameter. A center pole piece 78 is integrally formed with base 72 and includes a suitable bore for receiving a rotor shaft 82. A rotor 80 including hub member 81 (as shown in FIG. 7), is fixed to shaft 82 near the top thereof.

A spiral return spring 84 is wound around rotor-hub 81 immediately above rotor 80. One end of spring 84 is secured to hub member 81 while the other end is secured to pole piece 76 through a slot 86 in the pole piece. Spring 84 exerts a force which tends to rotate rotor 80 in a clockwise direction.

A stop member, comprising a circular disc 88, is secured to the top of hub 81 immediately above spring 84. Disc 88 includes a pair of oppositely disposed ears 89 and 90 adapted to abut against edges 92 and 93 of pole pieces 74 and 76. The stop member and rotor are slightly offset from one another so that when coil 79 is energized and the rotor is rotated counterclockwise from the deenergized position indicated in FIG. 6, the ears 89 and 90 abut against edges 93 of pole pieces 74 and 76. When excitation is removed, spring 84 rotates the rotor clockwise to its initial position as determined by abutment of ears 89 and 90 against edges 92 of the outer pole pieces.

Although specific embodiments of the invention have been disclosed, many modifications thereof will be obvious to one skilled in the art and the invention is not to be limited except as defined in the following claims.

I claim:

1. A rotary electromagnetic actuator comprising a first coil and first pole pieces associated therewith, a second coil and second pole pieces associated therewith, a rotor shaft passing through said coils, first and second rotors secured to said shaft and operatively associated with said first pole pieces and said second pole pieces, respectively, said rotors being disposed relative to their respective pole pieces whereby energization of said first coil causes said first rotor to rotate said shaft to a first position and energization of said second coil causes said second rotor to rotate said shaft to a second position, and a means biasing said shaft to a third position intermediate said first and second positions.

2. A rotary electromagnetic actuator as recited in claim 1 wherein said biasing means include a permanent magnet.

3. A rotary electromagnetic actuator comprising, a first stator having a first coil and a first rotor associated therewith, a second stator having a second coil and a second rotor associated therewith, said first and second stators each including a central pole piece and a pair of oppositely disposed pole pieces, each of said central pole pieces extending into and being perpendicular to its respective rotor, a rotor shaft passing through said stators, said first and second rotors being secured to said shaft and disposed relative to their respective pole pieces whereby energization of said first coil causes said first rotor to rotate said shaft to a first position, and energization of said second coil causes said second rotor to rotate said shaft to a second position, stop means for limiting the rotation of said shaft in either direction, and means for returning said shaft to an initial position intermediate to said first and second positions when neither of said coils is energized.

4. A rotary electromagnetic actuator according to claim 3 wherein said return means includes magnetic discs secured to said rotor shaft and operatively associated with said first and second stators, the magnetic forces of said discs being directed so as to bias said rotor shaft to said initial position.

5. A rotary electromagnetic actuator according to claim 4 wherein said first and second stators are identical and include a cylindrical base integrally formed with its respective pole pieces, said stators being arranged in end-to-end fashion, one of said rotors being displaced in a counterclockwise direction with respect to its pole pieces, and the other rotor being displaced in a clockwise direction with respect to its pole pieces.

6. A rotary electromagnetic actuator according to claim 5 wherein said stop means includes a member secured to said shaft and adapted to abut against the pole pieces of one of said stators.

7. A rotary electromagnetic actuator comprising a cylindrical stator having three elongated pole pieces arranged in spaced locations, two of said pole pieces comprising opposing portions of the cylindrical surface of said stator, the other pole piece extending axially from the center of said stator, a rotor shaft rotatably mounted in said central pole piece, extending through the central pole piece of said stator, and beyond the opposing pole pieces, a rotor secured to said shaft adjacent the free end of said central pole piece, said central pole piece extending into and being perpendicular to said rotor, said rotor having outer faces arranged to rotate past the inside faces of said opposing pole pieces, electromagnetic means surrounding said central pole for energizing said pole pieces to rotate said rotor in one direction, spring return means to rotate the rotor in the opposite direction when said electromagnetic means is not effective and, stop means for limiting the rotation of the rotor, said stop means including a segmented disc-like member secured to said rotor having means to abut against one of said opposed pole pieces.

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BERNARD A. GILHEANY, *Primary Examiner.*

JOHN F. BURNS, LARAMIE E. ASKIN, *Examiners.*