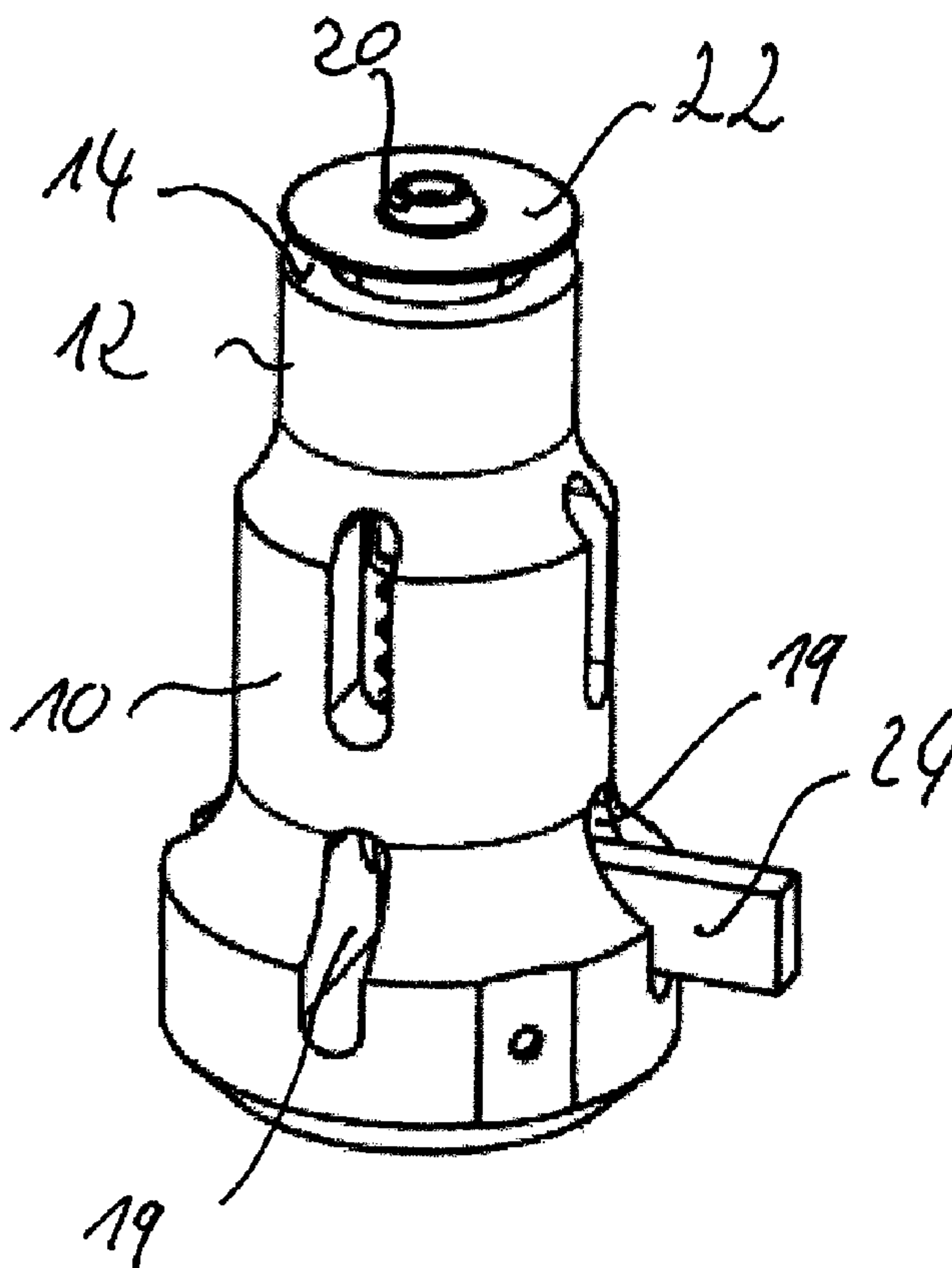




(22) Date de dépôt/Filing Date: 2014/02/19
(41) Mise à la disp. pub./Open to Public Insp.: 2014/08/20
(30) Priorité/Priority: 2013/02/20 (DE10 2013 202 766.4)

(51) Cl.Int./Int.Cl. *B06B 3/00* (2006.01),
B23K 20/10 (2006.01), *B29C 65/08* (2006.01)
(71) Demandeur/Applicant:
MS SPAICHINGEN GMBH, DE
(72) Inventeur/Inventor:
SCHEU, JOCHEN, DE
(74) Agent: GOWLING LAFLEUR HENDERSON LLP

(54) Titre : SONOTRODE ROND
(54) Title: ROUND SONOTRODE



(57) **Abrégé/Abstract:**

A round sonotrode has a sonotrode body which has a receiving space for a workpiece at its front end. The receiving space is surrounded by an annular web which has a weld surface at its front end face. A workpiece holder is furthermore provided in the receiving space.



MS Spaichingen GmbH

M11324PCA - Cs/hf

Abstract

- 5 A round sonotrode has a sonotrode body which has a receiving space for a workpiece at its front end. The receiving space is surrounded by an annular web which has a weld surface at its front end face. A workpiece holder is furthermore provided in the receiving space.

MS Spaichingen GmbH

M11324PCA - Cs/hf

Round sonotrode

5 The present invention relates to a round sonotrode which comprises a sonotrode body which has a receiving space for a workpiece at its front end, wherein the receiving space is surrounded by an annular web which has a weld surface at its front end face.

10 Such a round sonotrode is, for example, known from DE 10 2010 003 268 A1 and there serves for the ultrasonic welding of a plastic closure to a tubular bag.

It is the object of the present invention to further develop a round
15 sonotrode in accordance with the preamble of claim 1 such that an improved positioning of the workpiece is possible with it.

This object is satisfied by the features of claim 1 and in particular in that a workpiece holder is provided in the receiving space. In accordance with
20 the invention, the sonotrode thus does not only serve for the welding of the workpiece to a mating surface. The workpiece itself can rather be held or supported within the receiving space using the round sonotrode in accordance with the invention such that the workpiece adopts a reproducible, exact position on the initiation of the welding process. It is
25 ensured in this manner that a wanted desired position for the workpiece is also adopted in automated production operation on placing the workpiece onto a mating surface.

Advantageous embodiments of the invention are described in the description, in the drawing and in the dependent claims.

In accordance with a first advantageous embodiment, the workpiece
5 holder can have a centering mandrel. On the one hand, a workpiece can hereby be placed onto the workpiece holder in an automated manner. On the other hand, the positioning of the workpiece at the wanted desired position can be facilitated with the aid of the centering mandrel.

10 In accordance with a further advantageous embodiment, the centering mandrel can in particular be movable relative to the sonotrode body, in particular in a linear travel movement against a restoring force, for example a spring, a gas compression spring or a pneumatic cylinder. The sonotrode with the integrated workpiece holder and a workpiece located
15 thereon can hereby be set at a mating surface, with the workpiece being pressed toward the mating surface by the restoring force before the start of the welding process; however, without a contact already taking place between the weld surface and the workpiece.

20 In accordance with a further advantageous embodiment, a sensor can be integrated into the round sonotrode which sensor detects the presence of a workpiece and/or a correct orientation of the workpiece at the workpiece holder. This allows an automated monitoring of the welding process, with it simultaneously being ensured that the workpiece is located in the
25 wanted desired position at the start of the welding process.

It can furthermore be advantageous if the workpiece holder has a mechanical coding element such as a projection or a recess with which a correct orientation of a workpiece at the workpiece holder is ensured.

In accordance with a further advantageous embodiment of the invention, the sonotrode body can have at least one cut-out which connects its outer jacket surface to the receiving space. Such a cut-out can be configured, for example, in the form of an elongated hole which allows a correct
5 vibration of the sonotrode. In accordance with the invention, a holding element of the workpiece holder can be led through the cut-out in this embodiment. It is ensured in this way that the actual sonotrode body, which is set into mechanical vibration in the welding process, is not in contact with the workpiece holder. The holding element, which is led
10 through the cut-out, can rather be fastened to a component which does not vibrate, whereby a vibration-decoupled support of the workpiece holder relative to the sonotrode body is realized. A vibration of the sonotrode body thus does not influence the position of the workpiece holder.

15

The cut-out for the leading through of a holding element of the workpiece holder can have either a closed peripheral contour or a peripheral contour open toward the weld surface. It is furthermore possible to provide the cut-out in a base of the round sonotrode so that the holding element
20 projects into the sonotrode from below.

In accordance with a further embodiment of the invention, sonotrode needles, sonotrode pins or sonotrode projections can be provided at the weld surface which are in particular arranged in two, three or four rings,
25 preferably concentric rings. In this manner, the desired welding energy can be introduced into the workpiece point by point along the entire periphery of the workpiece so that high removal values are obtained after the welding. The sonotrode needles can, for example, be configured as tooth-shaped, conical or cylindrical elevated portions.

30

In accordance with a further advantageous embodiment, the sonotrode body can be configured as a hollow cylinder over at least 50% of its longitudinal extent. Good weld results are hereby possible, on the one hand. On the other hand, the inner space of the hollow cylinder can be
5 used for receiving the workpiece holder.

In accordance with a further advantageous embodiment, a clamping element can be provided at the workpiece holder and a workpiece can be temporarily fixed with it. It can in this way be prevented that, on an
10 automated production, a workpiece accidentally falls out of the workpiece holder when the sonotrode is moved - for example with the aid of a manipulator.

The present invention will be described in the following purely by way of
15 example with reference to an advantageous embodiment and to the enclosed drawings. There are shown:

Fig. 1 a perspective view of a round sonotrode;

20 Fig. 2 a side view of the sonotrode of Fig. 1; and

Fig. 3 a section through the sonotrode of Fig. 1 and Fig. 2 along the line A-A of Fig. 2.

25 The round sonotrode shown in Figs. 1 to 3 has a generally rotationally symmetrical sonotrode body 10 which ends at its front end in an annular web 12 which forms a weld surface 14 at its front end face. The weld surface 14 forms an annular strip in a plan view and can be provided in accordance with an embodiment not shown in the Figures over its whole

surface with sonotrode needles which are arranged in two, three or also four rings, in particular concentric rings.

As in particular Fig. 3 illustrates, the sonotrode body 10 is configured as
5 hollow cylindrical over approximately 80% of its longitudinal extent so that a receiving space 16 which extends in the longitudinal extent of the round sonotrode up to the weld surface 14 is formed in the interior of the sonotrode body 10. In accordance with the invention, a workpiece holder 18 is in this respect provided in the receiving space 16.

10

At its front end, the workpiece holder 18 has a centering mandrel 20 which extends beyond the front end of the sonotrode body 10 and is placed onto a workpiece 22 which, in the embodiment shown, is a component which comprises a hollow cylinder having an annular disk
15 molded thereat. In this respect, other workpiece shapes are naturally also possible such as a hollow cylinder with a plate in square shape molded thereat.

As Fig. 3 furthermore illustrates, the workpiece holder 18 comprises a
20 holding element 24 which is led through one of a plurality of cut-outs 19 in the sonotrode body 10 which connect its outer jacket surface to the receiving space 16. In this respect, in the embodiment shown, a respective four cut-outs are provided both at the middle and in the rear end of the sonotrode body 10 which are distributed evenly over the periphery, which
25 have a closed outer contour and which allow a correct vibration of the sonotrode body. Alternatively, more or fewer cut-outs can also be provided, for example two or six cut-outs. In the embodiment shown, the holding element 24 is only led out of the receiving space 16 through one of the rear cut-outs. It would, however, also be possible to lead the holding
30 element 24 through another cut-out or to lead a plurality of holding

elements through a plurality of cut-outs. In all cases, however, there is no contact between the sonotrode body 10 and the holding element 24 or the workpiece holder 18.

5 As Fig. 3 illustrates, a holding bar 26 is fastened to the holding element 24 which in the embodiment shown is configured as a bar having a rectangular cross-section. In this respect, the centering mandrel 20 is movable in the axial direction relative to the sonotrode body 10 or relative to the holding bar 26 against the force of a spring 28.

10

If a workpiece 22 is to be welded to a mating surface using the above-described round sonotrode, the workpiece 22 is first set onto the centering mandrel 20, either manually or in automated fashion, with a mechanical coding element, not shown, in the form of at least one projection or the
15 like ensuring a correct orientation of the workpiece at the workpiece holder 18.

When the workpiece 22 is then located in the desired position at the workpiece holder 18 (cf. Fig. 1 to Fig. 3), the round sonotrode with the
20 workpiece located thereon can be set at a mating surface which has a circular opening so that the centering mandrel 20 can be introduced into the opening. When the annular disk of the workpiece 22 then contacts the mating surface and the sonotrode is moved further in the direction of the mating surface, the centering mandrel 20 is moved relative to the
25 sonotrode body 12 in the direction of the rear end of the round sonotrode against the force of the spring 28 until the intermediate space between the annular disk of the workpiece 22 and the weld surface 14 has reduced down to zero so that the weld surface 14 contacts the annular disk of the workpiece 22 over the full area along its total periphery. Energy can
30 subsequently be introduced by applying ultrasound so that the workpiece

and the mating surface heat up and can be welded to one another. After a retraction of the round sonotrode, another welding process can subsequently be started.

MS Spaichingen GmbH

M11324PCA - Cs/Cs

Claims

5

1. A round sonotrode, comprising a sonotrode body (10) which has a receiving space (16) for a workpiece at its front end, which receiving space is surrounded by an annular web (12) which has a weld surface (14) at its front end face,
10 characterized in that
a workpiece holder (18) is provided in the receiving space (16).
2. A round sonotrode in accordance with claim 1,
characterized in that
15 the workpiece holder (18) has a centering mandrel (20).
3. A round sonotrode in accordance with claim 2,
characterized in that
the centering mandrel (20) is movable relative to the sonotrode body
20 (10) against a restoring force, for example a spring (28) or a
pneumatic cylinder.
4. A round sonotrode in accordance with at least one of the preceding
claims,
25 characterized in that
a sensor is integrated therein which detects the presence and/or a
correct orientation of a workpiece (22) at the workpiece holder (18).

5. A round sonotrode in accordance with at least one of the preceding claims,
characterized in that
the workpiece holder (18) has a mechanical coding element which
5 ensures a correct orientation of a workpiece (22) at the workpiece holder (18).
6. A round sonotrode in accordance with at least one of the preceding claims,
10 characterized in that
the sonotrode body (10) has at least one cut-out (19) which connects its outer jacket surface to the receiving space (16); and in that a holding element (24) of the workpiece holder (18) is led through the cut-out (19).
15
7. A round sonotrode in accordance with claim 6,
characterized in that
the cut-out (19) has a closed outer contour.
- 20 8. A round sonotrode in accordance with claim 6,
characterized in that
the cut-out has an outer contour open toward the weld surface (14).
9. A round sonotrode in accordance with claim 6,
25 characterized in that
the cut-out is provided in a base of the round sonotrode.
10. A round sonotrode in accordance with at least one of the preceding claims,
30 characterized in that

the workpiece holder (18) is supported in a vibration-decoupled manner relative to the sonotrode body (10).

- 5 11. A round sonotrode in accordance with at least one of the preceding claims,
characterized in that
sonotrode needles, sonotrode pins or sonotrode projections are provided at the weld surface (14) which are in particular arranged in two to four rings, preferably concentric rings.
- 10 12. A round sonotrode in accordance with at least one of the preceding claims,
characterized in that
the sonotrode body (10) is hollow cylindrical over at least 50% of its
15 longitudinal extent.
- 20 13. A round sonotrode in accordance with at least one of the preceding claims,
characterized in that
a clamping element with which a workpiece (22) can be temporarily fixed is provided at the workpiece holder (18).

1/2

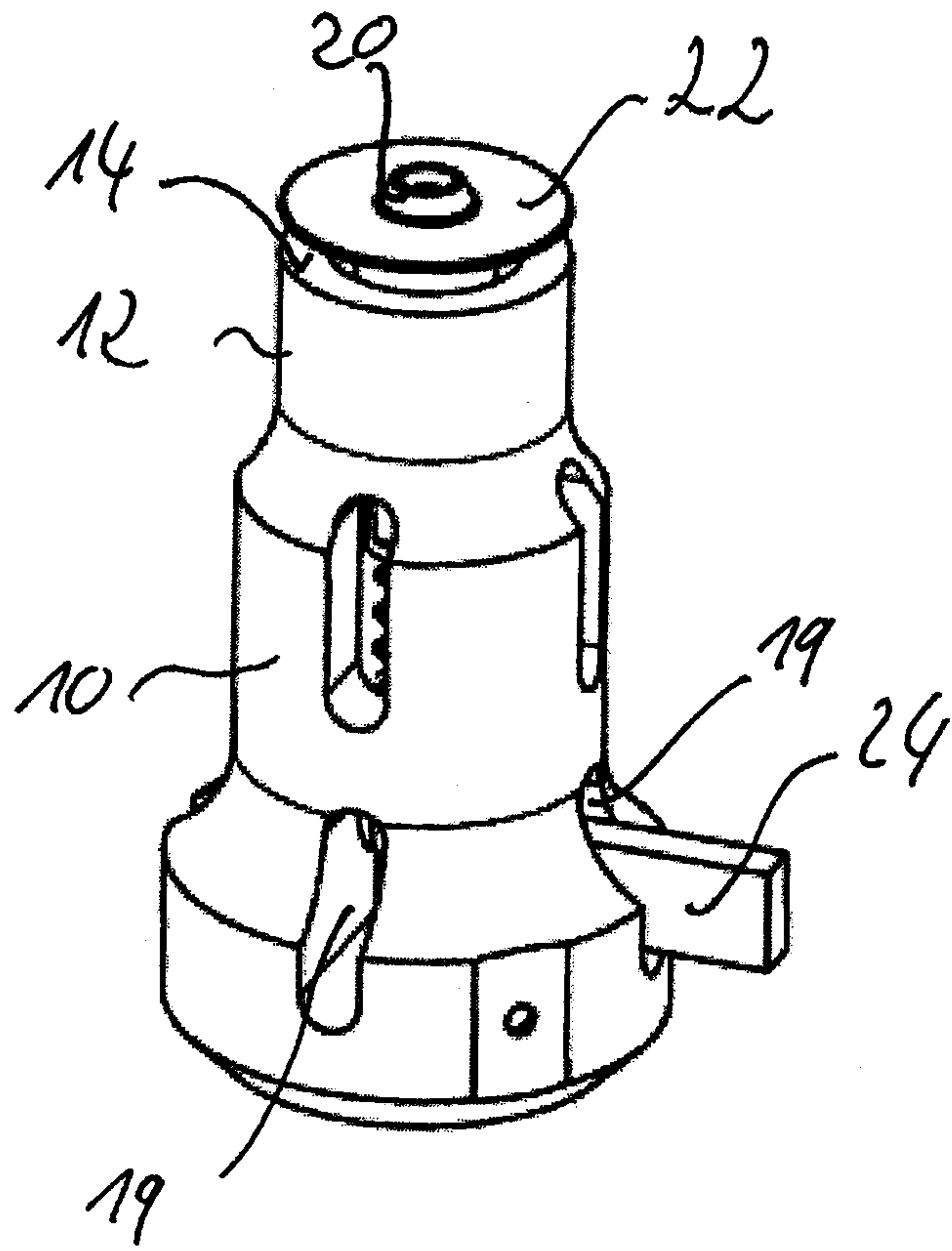


Fig. 1

2/2

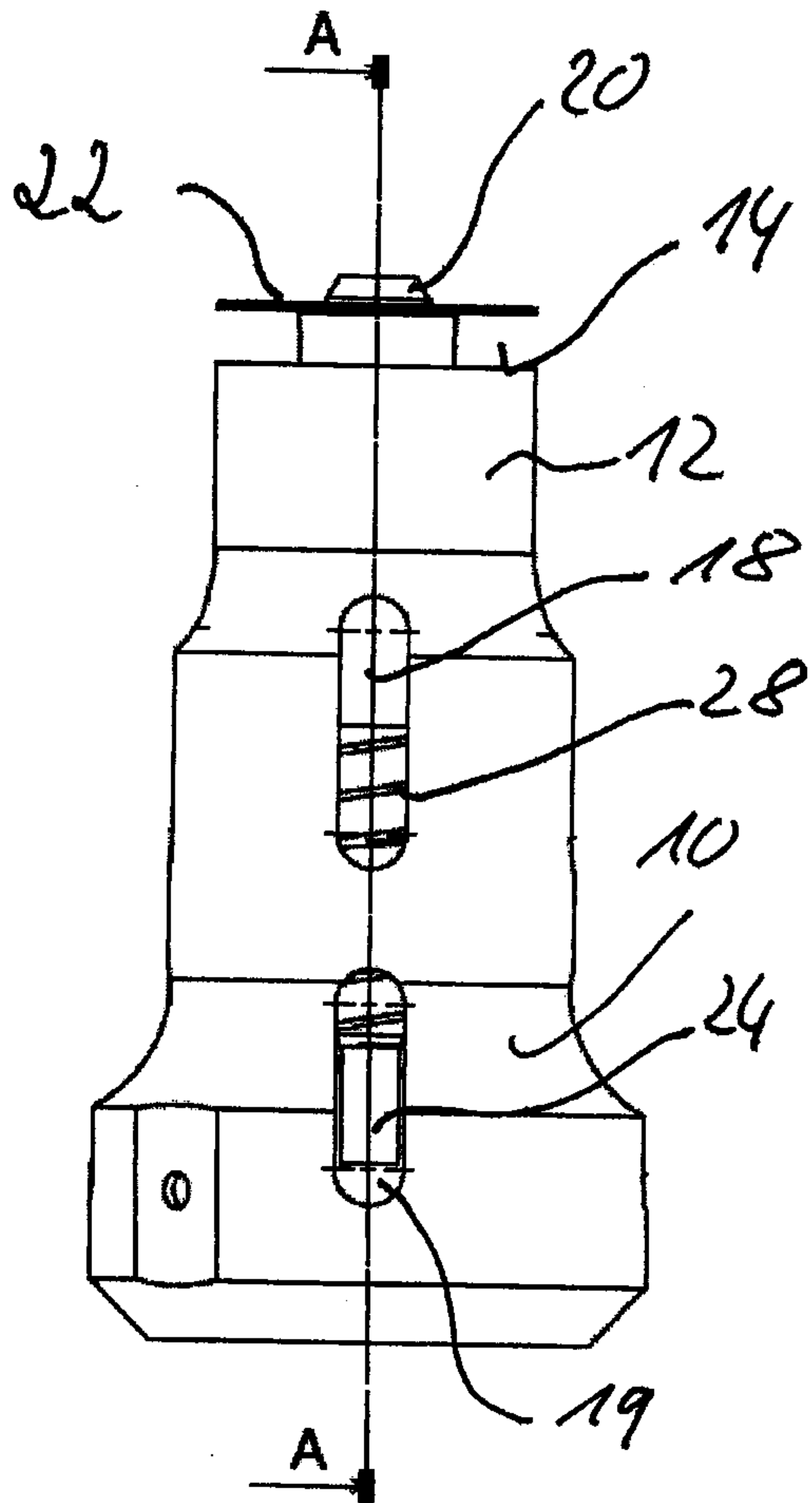


Fig. 2

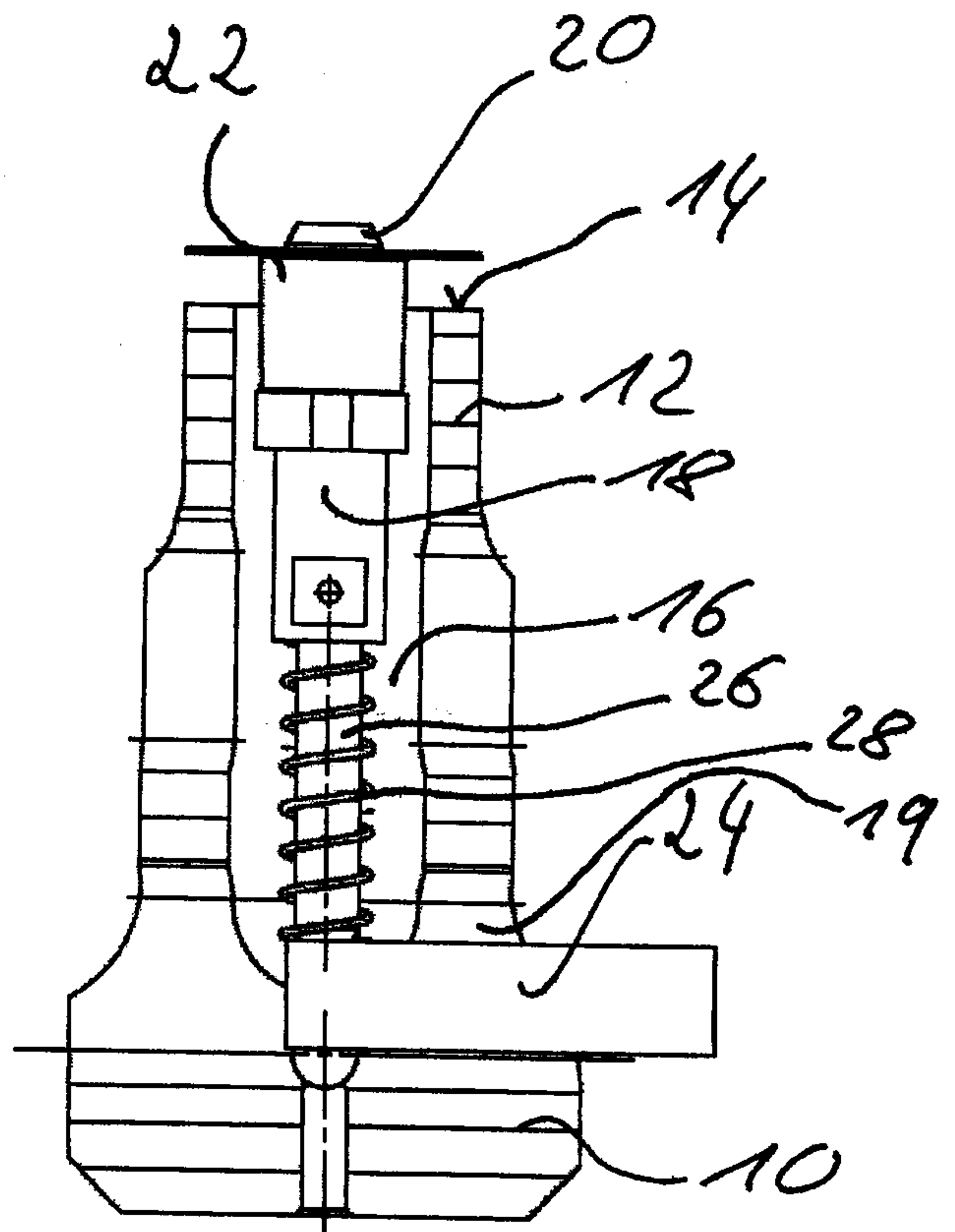


Fig. 3

