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(54) Title: FIBER OPTIC CATHETER FOR ACCURATE FLOW MEASUREMENTS		
(57) Abstract <p>An improved fibre optic sensor for remote flow measurements is disclosed. The sensor consists of two optical fibres (16, 18) placed parallel to each other with a reflective surface (32) (flat or concave) at the end. The fibres and the reflective surface are encased in a flexible tube (24) with an opening (28) in the side of the tube to allow light to be reflected through the opening into a measurement volume of the flow. The cavity created by this opening in the flexible tube is preferably filled with optical cement (34). This surface is polished so that it is flushed with the surface. Light is transmitted to the measurement volume from one of the optical fibres (Transmitting fibre) where it is scattered by scattering particles within this measurement volume. Part of backscatter light is collected by the other fibre (receiving fibre) and the backscatter signal is compared with the transmission signal to determine a Doppler shift.</p>		

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5 FIBRE OPTIC CATHETER FOR ACCURATE FLOW
MEASUREMENTS

BACKGROUND OF THE INVENTION

1. FIELD OF THE INVENTION

10 The present invention relates to an improved fibre optic probe, or sensor, for remote flow measurements. In particular, this sensor is designed for accurate flow measurements of fluids flowing in remote vessels, such as blood flow within arteries or veins or flows within pipes.

15 2. BACKGROUND INFORMATION

Fibre-optic anemometry is employed in velocimetry to measure flow rates, velocity gradients, and turbulence at remote points which are otherwise inaccessible. For example, by
20 measuring the velocity of blood flow in an artery before, during, and after an angioplasty procedure, the success of the procedure can be ascertained. Laser light is transmitted, via optic fibres, into the flow where it is scattered.
25 A portion of the scattered light is collected and transmitted, also via optic fibres, to an anemometer for analysis. By analyzing the Doppler shift between the transmitted light and the collected scattered light, the velocity of fluid
30 flow can be ascertained.

Optical fibres were first used in laser Doppler anemometers for the measurement of localized blood flow velocities by T. Tanaka and G.B. Benedek and described in an article entitled
35 Measurement of the Velocity of Blood Flow (In Vivo) Using Fibre Optic Catheter and Optical Mixing Spectroscopy, 14 Applied Optics 189-196 (1975). In their system they used a 500 μ m core

5 diameter monofibre to deliver the laser beam into
the femoral vein of a rabbit. The immersed distal
end of the fibre was cut and polished at 30°
relative to the fibre axis in an attempt to
minimize flow disturbance caused by the mere
10 presence of the fibre in the blood stream. A
laser beam was projected out through the fibre
wall, opposite the cut end surface, into the flow
by total internal reflection at the angled
polished distal end of the fibre. Light scattered
15 by the erythrocytes at the fibre tip was collected
by the same fibre and mixed with the reference
beam on the surface of a photomultiplier tube.
Analysis of the resultant signal was done on an
18-channel digital autocorrelator.

20 The sensor of the Tanaka-Benedek system
suffers from a number of disadvantages.
Projection of light out of the side of the fibre
necessitates that the fibre be stripped to its
core, thus leaving the brittle and fragile fibre
25 core exposed and unprotected. Cutting and
polishing the distal end of the fibre is a
difficult operation to perform, thus causing
manufacturing complications. Finally, due to the
small radius of curvature of the exposed fibre,
30 the curved outer surface of the fibre could cause
most of the light scattered back to the fibre to
be lost at the fibre-fluid interface, especially
if there are irregularities on the surface.

R.B. Dyott, in an article entitled The
35 Fibre-Optic Doppler Anemometer, 2 Microwaves,
Optics and Acoustics 13-18 (1978), discusses
making flow measurements using a single optic
fibre laser Doppler anemometer with the fibre
normally terminated. He reported that the region
40 in which light is back-scattered into the fibre
extends only to a few tens of the core diameter in

5 front of the fibre tip. As demonstrated in FIG.
10, the flow in this region, indicated at 70, is
perturbed by the presence of the distal end of the
fibre which could seriously affect the accuracy of
any measurements of flow velocity. The Dyott
10 system is well suited, however, to measurements in
situations where the medium is stationary and the
particles are moving.

For flow measurements, G.A. Holloway,
Jr. and D.W. Watkins modified the Tanaka-Benedek
15 system by using separate fibres for delivering the
laser beam and receiving the scattered light as
described in Laser Doppler Measurement of
Cutaneous Blood Flow, 69 J. Investigative
Dermatology 306-309 (1977). They applied such a
20 modified system for non-invasive measurement of
cutaneous microcirculation. The disadvantages
described above regarding the single fibre Tanaka-
Benedek system are exacerbated by the inclusion of
a second fibre.

25 For invasive flow measurements, D.
Kilpatrick adapted Dyott's system by modifying the
analyzing components and described the adapted
system in Laser Fibre Optic Doppler Anemometry in
the Measurement of Blood Velocities In Vivo,
30 Computers in Cardiology, IEEE, 467-470 (1980). By
using this system, he showed that, despite flow
perturbation caused by the presence of the fibre,
the system could still be used to measure blood
flow velocities both in vitro and in vivo. With
35 the fibre positioned parallel to fluid flow he
obtained a broad spectrum, declining monotonically
with width, that is proportional to the flow
velocity. The maximum Doppler shift frequency was
taken as representative of the flow velocity and
40 this agreed with the calculated theoretical value
of 4.2Mhz/ms^{-1} (i.e. the maximum shift frequency is

5 absolutely calibrated). A linear relationship was
obtained between the maximum shift frequencies and
the flow velocities for flows of up to 1.5ms^{-1} in
the forward direction (advancing towards the fibre
tip) but only 20cms^{-1} for flows in the reverse
10 direction (moving away from the fibre distal end
tip).

Concurrently with the work of Kilpatrick
described above, M. Imamura, F. Kajiya, and N.
Hoki independently developed a similar system, but
15 with an added advantage of being able to measure
directional flow, as reported in Blood Velocity
Measurement By Laser Doppler Velocimetry With
Optical Fibre, Proc. 12th Int. Conf. Med. and
Biol. Eng. 35 (1979). They achieved this by using
20 a Bragg cell (acousto-optic modulator) to shift
the reference signal by 40MHz. In vivo flow
measurements in blood were made via the fibre's
distal end and with the whole fibre oriented at a
60° angle to the flow (see FIG. 11), and a broad
25 rectangular spectrum was obtained. A linear
relationship was again found between the maximum
shift frequencies and flow velocities as in the
Kilpatrick adaptation of the Dyott system.

It is interesting to note the absolutely
30 calibrated linear relationship between the maximum
Doppler shift frequency and flow velocity obtained
for the Kilpatrick and Imamura-Kajiya-Hoki systems
described above. This relationship implies that
single fibre systems measure the free stream flow
35 velocity (i.e, velocity outside the perturbed
region), but only within certain velocity limits.
Outside these limits, however, the system will
either have to be modified or improved to allow an
accurate measurement of flow velocity. The broad
40 spectrum observed by both systems was assumed to
be due to multiple frequency shifts from the

5 particles of varying velocity in the perturbed
region at the tip of the fibre.

The slight difference in spectral shape
reported by the Kilpatrick and the Imamura-Kajiya-
Hoki studies is due to the area of turbulence at
10 the measurement region adjacent the fibres' distal
end, and this has been theoretically addressed by
M.D. Stern in Laser Doppler Velocimetry in Blood
and Multiply Scattering Fluids: Theory, 24 Applied
Optics 1968-1986 (1985). The difference was
15 attributed to different thicknesses of the
boundary layer at the distal end tip of the fibre,
with Kilpatrick's system having a thicker layer.
To overcome the effect of the boundary layer for
obtaining accurate flow measurements, it is
20 necessary to project the probe volume (i.e., the
volume in which flow measurements are made) away
from or beyond the boundary layer and into the
laminar flow region. To do this Stern suggested
use of two fibres, with one fibre delivering the
25 incident light and the other collecting the
scattered light. The sensor proposed by Stern,
however, projected the probe volume from the blunt
ends of the fibres.

A two fibre laser Doppler anemometer
30 with the fibres oriented at 60° to the direction
of flow was developed, tested, and reported by Y.
Ogasawara, O. Hiramatsu, K. Mito, and others in A
New Laser Doppler Velocimeter With a Dual Fibre
Pickup For Disturbed Flow Velocity Measurement,
35 Circulation, 76, Suppl. 4, 328 (1987) and by F.
Kajiya, O. Hiramatsu, Y. Ogasawara, and others in
Dual-Fibre Laser Doppler Velocimeter and its
Application to the Measurements of Coronary Blood
Velocity, 25 Biorheology 227-235 (1988). In both
40 systems, two step-index fibres with a core
diameter of 50µm and a cladding diameter of 62.5µm

5 were used. The scattered light collected by the
receiving fibre was mixed with the reference beam
and detected using an avalanche photodiode. The
spectrum analyzer showed a narrow spectrum (as
10 compared with the single fibre system) with a peak
value that varied with flow velocity. The
separation between the cores of the two fibres in
these systems was 12.5 μ m.

By varying the core separation and using
different fibre combinations, S.C. Tjin, D.
15 Kilpatrick, O. Hiramatsu, Y. Ogasawara, and F.A.
Kajiya obtained better linearity between the
Doppler frequencies and flow velocities as the
core separation was increased with their system
and findings described in A Dual-Fibre Laser
20 Doppler Anemometer for in Vitro Measurements,
Proc. 13th Aust. Conf. Optical Fibre Technology,
245-248 (1988). This improved linearity, however,
was obtained at the expense of a decreased signal-
to-noise ratio, and the probe volume was still
25 projected from the distal end of the fibre.

However, with a fibre probe placed
parallel to the flow, S.C. Tjin, D. Kilpatrick,
and P.R. Johnston found that a two-fibre probe
with the fibre tips normally terminated is
30 inadequate for accurate flow measurements,
especially for flows moving away from the fibre
tips, as described in Evaluation of the Two-Fibre
Laser Doppler Anemometer for In Vivo Blood Flow
Measurements, Experimental and Flow Simulation
35 Results, 34 Optical Engineering, 460-469 (1995).
This is because the flow at the fibre distal end
tips is perturbed, and the region of perturbation
extends away from the fibre tips with increasing
flow velocity. For flow towards the fibre tips,
40 the region of flow perturbation decreases towards
the fibre tips with increasing flow velocity.

5 These changes in the region of flow perturbation
with flow velocities and the direction of flow
give rise to a non-linear calibration between the
Doppler frequency and the flow velocity. This
limits the usefulness of the system for in vivo
10 flow measurements because, in most practical
systems, the fibre optic probe must be placed
parallel to the flow.

 A two fibre sensor adapted to project a
probe volume to the side of the catheter wall by
15 means of reflective surfaces was proposed by S.C.
Tjin in Fibre Optic Laser Doppler Anemometry,
Ph.D. Thesis, University of Tasmania, 1991,
available at the University of Tasmania. Such a
sensor was, however, never constructed. In the
20 proposed embodiment of the sensor, two fibres are
embedded in the wall of a larger catheter.
Proximate each fibre distal end tip, a separate
opening is formed in the catheter sidewall. An
angled reflective surface is positioned in the
25 opening axially opposite the fibre distal end tip
to reflect light from the fibre radially outwardly
through the opening directly into the flow, which
is parallel to the fibre axes. This proposed
embodiment, if built, would have had a number of
30 disadvantages. The uncovered openings at the
reflective surfaces would themselves cause
turbulence and would also provide a place for
blood clots to form or collect. To minimize the
size of the openings, and thus the amount of
35 turbulence caused thereby, it was proposed that
two small, circumferentially spaced apart openings
be provided in the catheter wall rather than a
single large opening and single reflective surface
that would be able to accommodate both fibres.
40 Polishing, mounting, and aligning dual reflective
surfaces, however, would introduce manufacturing

5 complexity and alignment problems to developing a
suitable probe volume and would add cost to the
manufacture of the sensor. Also, the embodiment,
as proposed, included no provision for focusing
the transmitted and received light beams to
10 minimize the width of the Doppler spectrum and
maximize the signal-to-noise ratio.

SUMMARY OF THE INVENTION

An object of the present invention is to
provide a two-fibre probe that avoids the problem
15 of non-linear calibration between the Doppler
frequency and the flow velocity due to flow
perturbation caused by the sensor. In addition,
an object of the present invention is to provide a
sensor that projects a probe volume to the side of
20 the sensor to avoid turbulence caused by the
sensor, the sensor being relatively simple to
manufacture and eliminating structural features
that would themselves cause turbulence or collect
blood clots.

25 Consistent with this object, a new two
fibre optic measuring probe has been designed,
which can be incorporated into any existing
catheter, to provide accurate fluid flow
measurements, not axially via the distal end of
30 the fibre, but radially with respect to the axes
of the fibres. The measuring probe comprises two
or more optical fibres placed alongside each other
within a flexible tube. Light is transmitted into
the blood stream through one of the fibres, termed
35 the transmitting fibre. A reflective surface,
located axially within the flexible tube relative
to the terminal ends of the fibres, is polished or
otherwise formed with the reflective surface
oriented at an angle with respect to the axes of
40 the fibres. The reflective angled surface will

5 reflect the light from the transmitting fibre,
through an optically transparent window in the
sidewall of the tube. Thus, light is reflected
into the blood stream alongside the catheter where
blood flow is not usually perturbed by the
10 presence of the catheter and is more likely to be
laminar.

This radially projected light is
scattered by scattering particles within the probe
volume, thus developing backscatter light with
15 part of the backscatter light being collected by
the other fibre, termed the receiving fibre.

A cavity surrounding the ends of the
optical fibres and the reflective surface is
filled with an appropriate optical cement to both
20 fix the optical fibres and the reflective surface
in place and to provide an optical window for the
sensor that is flush with the outer surface of the
catheter tube. This minimizes flow perturbations
along the side of the sensor and also prevents
25 blood from entering a cavity where it may
contribute to the formation of undesirable clots.

Variations on this design include a
variety of shapes for the fibre tips, including
tips that are normal to the fibre axes or tips
30 that are concave or convex. Concave and convex
fibre tips serve the additional purpose of being
able to effectively focus the incident and
received beams at more specific locations to
increase the intensity of the incident beam and to
35 narrow the field of view of the receiving beam to
effectively shrink the size of the probe volume
and thus improve the signal to noise ratio and the
Doppler spectrum

Another variation of the measuring probe
40 of the present invention includes a reflective
surface that is concave instead of flat. This

5 concave surface also helps focus the beam from the
transmission fibre to a point above the surface of
the optical cement surface. Part of the light
scattered by scattering particles in this region
is collected by the receiving fibre via the
10 concave reflecting surface. A concave reflective
surface can be combined with fibres having concave
or convex tips.

Other objects, features and
characteristics of the present invention will
15 become apparent upon consideration of the
following description with reference to the
accompanying drawings, and in the appended claims,
all of which form a part of the specification, and
wherein reference numerals designate corresponding
20 components of the figures.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 shows a conventional catheter
incorporating an improved measuring probe, or
sensor tip, according to the present invention;

25 FIG. 2 is an enlarged view of the sensor
tip of the present invention from above the
reflective surface;

FIG. 3 is a cross-sectional view of the
sensor tip of the present invention along the line
30 III-III in FIG. 2;

FIG. 4 is an enlarged view of a second
embodiment of the sensor tip according to the
present invention from above the reflective
surface;

35 FIG. 5 is a cross-sectional view of the
second embodiment of the sensor tip of the present
invention along the line V-V in FIG. 4;

FIG. 6 is a cross-sectional view of the
of the sensor tip of the present invention along
40 the line VI-VI in FIG. 2;

5 FIG. 7 is a cross-sectional view of the sensor tip of the present invention along the line VII-VII in FIG. 4;

10 FIG. 8A is a cross sectional view of the sensor of the present invention depicting a third embodiment thereof;

 FIG. 8B is a cross sectional view of the sensor of the present invention depicting a fourth embodiment thereof;

15 FIG. 9A is a cross sectional view of the sensor of the present invention depicting a fifth embodiment thereof;

 FIG. 9B is a cross sectional view of the sensor of the present invention depicting a sixth embodiment thereof;

20 FIG. 10 shows flow perturbation occurring at the blunt end of a prior art sensor tip; and

 FIG. 11 shows the flow perturbation occurring at the end of a prior art sensor tip oriented at 60° to the flow.

25

DETAILED DESCRIPTION OF THE INVENTION

A fibre optic catheter 10 having a measuring sensor 14 according to the present invention is shown in FIG. 1. The catheter 10 includes first and second optic fibres 16, 18 enclosed within a flexible tube 24. The fibres are conventional optical fibres and can, for example, be comprised of glass or plastic. Glass fibres are preferred because of their superior light transmission qualities. The flexible tube is preferably a medical grade tubing, such as heparin (an anticoagulant) coated latex, which is conventionally used in a variety of in vivo applications.

30

35

5 A sensor tip, or region, 14 is located adjacent, but proximally of, a distal end of the catheter 10, or at any desired location therealong. Conventional connectors 20, 22 are fixed to the proximal ends of the optic fibres 16, 18, respectively. The connectors 20, 22 connect the catheter 10 to an anemometer or other suitable analyzing device. With the exception of the use of the present invention sensor, the catheter 10, including the connectors 20, 22, is of conventional construction and design for a two optic fibre catheter.

 The construction of the sensor in the sensing region 14 is shown in more detail in FIGS. 2 and 3. The optic fibres 16, 18 are enclosed by the flexible tube 24 and may terminate within the tube 24 near, but spaced proximally from, the distal end 21 of the catheter. It is presently preferred to use multimode fibres having a step refractive index profile with a core diameter of 50 μm and a cladding diameter of 125 μm (denoted a 50/125 fibre). A single mode fibre, having a core diameter of 8 μm and a cladding diameter of 125 μm (a 8/125 fibre), may also be used. It is also possible to use a combination of one single mode fibre and one multimode fibre. For single mode fibres, the preferred core diameter is dependent on the wavelength of light to be used.

 The distal end 21 of tube 24 is preferably closed by a cap 26, or the like, to prevent the intrusion of blood into the probe which might form undesirable clots.

 An opening 28 is initially formed in a sidewall of the tube 24. The terminal ends 17, 19 of the optic fibres 16, 18, respectively, are located within the tube 24 adjacent opening 28.

5 A plug 30 composed of reflective
material is disposed within the tube 24 between
the terminal ends 17, 19 of the optic fibres 16,
18 and the distal end cap 26 of the tube 24. The
10 plug 30 may be composed of any suitable reflective
material, such as copper, stainless steel, silver,
mirrored glass, or the like. Presently a portion
of stainless steel wire having a diameter of 0.2
mm has been employed.

15 One end of the plug 30 nearest the
terminal ends 17, 19 is ground and polished to
form a finished reflective surface 32 that is
oriented at an angle with respect to the
longitudinal fibre axes of the fibres 16, 18. It
is presently contemplated that the preferred angle
20 of the reflective surface be within the range of
about 25-35° with respect to the longitudinal
fibre axes of the fibres 16, 18, with an angle of
about 30° being preferred.

25 Once the fibres and the reflective
surface are appropriately aligned, the cavity
within the opening 28 surrounding the optic fibres
16, 18 and the plug 30 is filled with an optical
cement 34. The optical cement may include any
30 suitable optically transparent material having an
initial liquid phase and which hardens after being
poured into the cavity, such as clear polymeric
materials which harden upon exposure to certain
radiation. When set, the optical cement 34 locks
the fibres and the reflective surface 32 together
35 into an integral unit. The cement 34 also
provides a smooth surface over the opening that is
flush with the outer peripheral surface of tube
24. To this end, it is necessary that the optical
cement, forming an optical window 35 when
40 finished, be polished smooth to minimize
turbulence caused by the surface and to prevent

5 blood clots from forming in voids and other
irregularities in the cement. The preferred
optical cement is Norland™ Optical Adhesive 61.
It should be understood, however, that other
optical quality cements can also be employed.

10 In operation, with the catheter inserted
into the blood vessel of a patient or into a flow
within a pipe, a transmission, or incident, beam
of light from a laser, such as, preferably, a
laser diode, such as, for example, the 7350 Series
15 Diffraction Limited Laser Diode, operating in the
wavelength range of 670-680 nm, produced by SDL,
Incorporated of San Jose, California, U.S.A., or
an HeNe laser, exits the terminal end 17 of the
optical fibre 16, here designated as the
20 transmitting, or transmission, fibre. The
wavelength of the light may be any wavelength
within the scattering spectrum of blood, which
ranges from 450-850 nm. Wavelengths within the
red portion of the spectrum, 600-720 nm, are
25 preferred because they provide the most scattering
within blood.

The incident beam reflects off the
reflecting surface 32 in a direction having a
component normal to the fibre axes out of the
30 optical window 35 formed over the opening 28 in
the tube 24 (see FIG. 6). The light within the
incident beam is reflected into a measurement, or
probe, volume of fluid flow outside of and
alongside the tube 24 in the region near the
35 optical window 35. The reflected light is
scattered by particles flowing within the
measurement volume. A portion of the light is
also scattered back (the backscatter) through the
optical window 35 where it is reflected by the
40 reflecting surface 32 into the terminal end 19 of
the optical fibre 18, here designated as the

5 receiving fibre. The light received by the
receiving fibre 18 is known as the backscatter
signal.

As shown in FIG. 6, the reflected light
emitted from the transmitting fibre 16 covers a
10 diverging area denoted between lines 36, that can
be considered as a transmitted acceptance cone.
The receiving fibre 18 collects light from a
diverging area, or acceptance cone or field of
view, denoted between lines 38. The overlap of
15 the transmitted acceptance cone 36 with the field
of view 38, as shown by the cross-hatched area 40,
represents the probe volume region wherein the
incident beam and the backscatter transmission
overlap. It is in this probe volume where fluid
20 flow is measured.

The design parameters and the preferred
values of those parameters will now be described.

Depending on the angle of the reflective
surface, the probe volume may be projected out of
25 the optical opening normal to the fluid flow
(i.e., normal to the fibre axes) or forwardly or
rearwardly with respect to the fibre tips. To
obtain the largest Doppler shift, however, it is
preferred that the probe volume be projected as
30 far forwardly or rearwardly as possible. If the
probe volume is projected normally to the fibre
axes, there is no Doppler shift and the flow
velocity cannot be ascertained.

In addition, the height of the probe
35 volume above the wall of the catheter 24 (i.e.,
the distance the probe volume 40 in FIG. 6 is
spaced radially from the optic window 35) is also
critical. The probe volume must be a sufficient
distance, or at a sufficient projection height,
40 from the catheter so that the probe volume is out
of the boundary layer of the flow along the

5 sidewall of catheter 24. On the other hand, if
the probe volume is too far from the catheter
sidewall, the laser transmission light cannot
sufficiently penetrate the opaque fluid, such as
blood. The projection height of the probe volume,
10 thus, depends on a number of factors, including
the index of refraction of the optical cement and
the angle of the reflective surface. The greater
the reflective surface angle, the higher the
projection height. Projection height also depends
15 on the position of the reflective surface with
respect to the fibre tips. The closer the
reflective surface is to the fibre tips, the
higher the projection height. Finally, the
projection height depends on the separation
20 between the two fibres. The greater the
separation, the greater the projection height.

To ensure that the acceptance cones of
the transmission fibre and the receiving fibre are
correctly projected out of the catheter and window
25 35, the two cones should intersect beyond the
reflective surface. In other words, the two
cones, between lines 36 and 38, respectively,
cannot overlap until they are projected into the
flow as shown in FIG. 6. To avoid overlap of the
30 acceptance cones prior to their exiting optical
window 35, the fibre core centers must be spaced
at least 260 μm apart.

In addition, the reflective surface
cannot be too far from the fibre tips. The beam
35 angle of the transmission light depends on the
index of refraction of the optical cement. Using
the preferred optical cement, Norland™ Optical
Adhesive 61, which has an index of refraction of
1.5562, the acceptance cones of two 50/125
40 multimode fibres, whose cores are separated by 260
 μm , will intersect each other at a distance of 290

5 μm from the fibre tips. Therefore, the intersection of the fibre axes with the reflective surface must be within 290 μm of the fibre tips.

Although it is preferred that the probe volume 40 be projected as far forwardly or
10 rearwardly along the catheter 24 as possible, the angle of the reflective surface cannot be so great or so small that the reflected transmission light does not leave the optical window due to total internal reflection. To avoid total internal
15 reflection, the angle of the reflective surface must be between 25-65° from the fibre axes, but not, preferably, exactly at 45°. Where the angle is progressing greater than 45°, the probe volume will be progressively projected rearwardly; as the
20 angle becomes less than 45°, the probe volume will be progressively projected forwardly. At a 45° reflective angle, the probe volume is projected normal to the fibre axes.

A forwardly projected probe volume is
25 preferred. A normally projected probe volume would not capture sufficient Doppler shift, as noted above. While a rearwardly projected probe volume may be blocked by the fibres themselves, this could be avoided by moving the fibres away
30 from the reflective surface. This can, however, result in the acceptance cones of the fibres overlapping before reaching the reflective surface.

As noted previously, the angle of the
35 reflective surface is preferably within the range of 25 - 35°, with 30° being preferred. If the angle is less than 25° total internal reflection will result. If the angle is greater than 35° the projection height will be too high.

40 The optical opening must be large enough so that the acceptance cones of the fibres are not

5 blocked by the tube wall. For a sensor having
 50/125 multimode fibres with a 260 μm separation
 between the fibre axes, an optical cement having
 an index of refraction of 1.5562, and a reflective
 surface with an angle of 30°, the optical opening
 10 must have an axial length of at least 600 μm
 measured axially from the fibre tips 17, 19 and a
 circumferential width of at least 530 μm that is
 centered between the optical fibres.

The plug 30 must have a sufficient
 15 diameter such that the acceptance cones of the
 fibres are entirely captured by the reflective
 surface. The diameter of the catheter primarily
 preferred herein is 1.2 mm. For a 1.2 mm diameter
 sensor having 50/125 multimode fibres with 135 μm
 20 separation therebetween, an optical cement having
 an index of refraction of 1.5562, a reflective
 surface at an angle of 30°, and with the fibre
 axes intersecting the reflective surface at a
 distance of 108.25 μm from the fibre tips, the
 25 outer diameter of the plug must be at least 204
 μm .

For a sensor employing two 8/125 single
 mode fibres, the design parameters are summarized
 below:

30	Refractive index of optical cement -	1.5562
	Recommended reflective angle -	27°
	Minimum plug diameter -	150 μm
	Minimum optical opening length -	400 μm
	for a 1.2 mm diameter sensor.	

35 It must be noted that the above preferred
 parameters have been developed for prototype
 sensors having flat reflective surfaces and
 normally positioned fibre tips. Any or all of the
 parameter values may differ in a preferred
 40 commercial embodiment from those cited above. In

5 addition, it is important to understand that all
of the parameters are directly interdependent and
that variation of any one of the preferred values
would necessarily change the remaining values.

10 In manufacturing the sensor of the
present invention, the fibres are inserted into
the tube with the plug on which the reflective
surface is polished. Incident light transmitted
through the transmission fibre and a received
15 light signal are both monitored. The relative
orientation of the fibres with respect to the
protective surface is adjusted until the signal to
noise ratio is maximized. The optical cement is
then added to fix the relative positions of the
fibres and the reflective surface.

20 The sensor of the present invention has
been described thus far as having a single optical
opening and window and a single reflective surface
whereby the single window and reflective surface
are associated with both fibres and each,
25 respectively, transmits and reflects both the
incidence signal and the backscatter signal. The
sensor of the present invention could, however,
include two or more reflective surfaces axially
disposed with respect to associated fibre tips in
30 a corresponding number of optical openings having
associated optical windows. In this embodiment,
it is contemplated that the incidence beam,
emitted from a transmitting fibre, is reflected by
its associated reflective surface out its
35 associated optical window. Similarly, the
backscatter signal passes through an optical
window and is reflected by a reflective surface
associated with a receiving fibre.

40 The sensor of the present invention has
also be described as having a single transmitting
fibre and a single receiving fibre. It is

5 presently contemplated, however, that the sensor of the present invention could include two or more transmitting fibres and/or two or more receiving fibres, at least one optic transmitting path and at least one optic receiving path being required.

10 It is desirable that the Doppler spectrum be as narrow as possible and that the signal to noise ratio be as large as possible. To maximize the signal to noise ratio from the sensor, and to minimize the width of the Doppler
15 spectrum, it is desirable that the probe volume be as small as possible and that the transmission beam be as concentrated as possible. To that end, a sensor with the capability to focus the transmission signal and to focus the field of view
20 of the receiving fibre would provide significant advantages over sensors without such capabilities.

An alternate embodiment of the fibre optic catheter of the present invention, which includes such focusing capability, is shown in
25 FIGS. 4, 5, and 7. The sensor tip 42 of the catheter of the alternate embodiment is, in most respects, identical to the sensor tip 14 of the first embodiment. The reflective surface 46 of the plug 44 is not, however, ground flat as in the first embodiment, but is ground with a concave
30 shape as shown schematically in FIG. 5. As demonstrated in FIG. 7, the concave surface helps focus the incident beam 48 from the transmission fibre 16 to a smaller region above the surface of the sensor. Furthermore, by virtue of the concave
35 reflective surface 46, the region from which light is collected by the receiving fibre 18, indicated between lines 50, is also focused so as to be narrower than without such focusing. This results
40 in a narrower probe volume 52 which causes a stronger signal to noise ratio and a narrower

5 Doppler spectrum.

As noted above the index of refraction of the optical cement presently used is 1.5562. The index of refraction of the fibre core typically ranges from about 1.4 - 1.5.

10 Accordingly, the acceptance cone of the transmission beam is enlarged upon being emitted from the fibre tip into the optical cement. This results in an undesired enlargement of the probe volume and a decrease in the light intensity. If
15 the index of refraction of the optical cement were less than that index of refraction of the fibre core, however, the acceptance cone would shrink, resulting in built-in focusing effect.

As noted above, the shape of the
20 reflective surface can itself be modified to focus the transmission signal and the field of view of the receiving fibre. Similarly, the tips of the fibres may be shaped so as to produce such a focusing effect.

25 Further embodiments of the sensor of the present invention are shown in FIGS. 8 and 9. The sensor of FIG. 8A, has fibre tips 60 that are convex in shape. Where the index of refraction of the optical cement 64 is less than the index of
30 refraction of the fibre core, the convex fibre tips 60 of the sensor of FIG. 8A will result in a more focused probe volume and thus a stronger signal to noise ratio and narrower Doppler spectrum. Conversely, where the index of
35 refraction of the optical cement 64 is greater than the index of refraction of the fibre core, the convex fibre tips 60 of the sensor of FIG. 8A will result in a less focused probe volume.

The sensor of FIG. 8A has a flat
40 reflective surface 32. The sensor of FIG. 8B, has fibre tips 60 that are convex combined with a

5 concave reflective surface 46 resulting in even more focusing of the probe volume.

 The sensor of FIG. 9A, has fibre tips 62 that are concave. Where the index of refraction of the optical cement 66 is greater than the index
10 of refraction of the fibre core, the concave fibre tips 62 of sensor of FIG. 9A will result in a more focused probe volume and thus a stronger signal to noise ratio and narrower Doppler spectrum. Conversely, where the index of refraction of the
15 optical cement 66 is less than the index of refraction of the fibre core, the concave fibre tips 62 of sensor of FIG. 9A will result in a less focused probe volume.

 The sensor of FIG. 9A has a flat
20 reflective surface 32. The sensor of FIG. 9B, has fibre tips 62 that are concave combined with a concave reflective surface 46 resulting in even more focusing of the probe volume.

 In analyzing the signals received by the
25 receiving fibre of the two-fibre sensor, the backscatter signal is compared to the incident signal in a known manner so as to determine the Doppler shift of the backscatter signal. As is well known in the art, the flow velocity of fluid,
30 such as blood, is directly proportional to Doppler shift frequency. The velocity may be represented mathematically by the expression:

$$V = K \cdot f_D$$

where,

35 V = Blood Flow Velocity;

 K = Doppler shift constant to be determined in a known manner;
 and

40 f_D = the Doppler shift frequency,
 to also be determined in a known manner.

5 The Doppler shift constant K is
calculated by the following equation:

$$K = - \frac{2n}{\lambda} \cos \theta$$

where,

10 n = index of refraction of blood \approx
 1.33;

θ = obtuse angle between direction
 of flow and the bisection of
15 the transmission cone
 projected from the optical
 window; and

λ = wavelength of the light.

 While the invention has been described
in connection with what are presently considered
20 to be the most practical and preferred
embodiments, it is to be understood that the
invention is not to be limited to the disclosed
embodiments, but, on the contrary, it is intended
to cover various modifications and equivalent
25 arrangements included within the spirit and scope
of the appended claims.

 Such modifications, which would be
included within the scope of the appended claims,
include, but are not limited to, a fibre optic
30 sensor having two or more transmitting fibres
and/or two or more receiving fibres and a sensor
having two or more reflective surfaces axially
disposed with respect to associated fibre tips in
a corresponding number of optical openings having
35 associated optical windows.

 Thus, it is to be understood that
variations in the particular parameters used in
defining the improved fibre optic probe can be
made without departing from the novel aspects of
40 this invention as defined in the claims.

5 WHAT IS CLAIMED IS:

1. A sensor for remote fluid flow measurements, said sensor comprising:

a flexible tube having an optical opening formed in a sidewall thereof;

10 first and second optical fibres disposed within said tube, said first and second optical fibres each having a longitudinal fibre axis and a terminal end disposed within said tube proximate said optical opening; and

15 a single reflective surface disposed within said tube adjacent said terminal ends of said first and second optical fibres,

wherein said optical opening and a portion of said tube surrounding said terminal ends of said first and second optical fibres and
20 said reflective surface define a cavity, said cavity being filled with an optical cement forming an optical window,

said single reflective surface being
25 oriented such that light emitted from said terminal end of one of said first and second optical fibres is reflected by said single reflective surface in a direction having a component normal to the fibre axes through said
30 optical cement into a measurement volume of the flow located outside and alongside said sensor, the reflected light being scattered within the measurement volume such that a portion of the scattered light that is within a field of view of
35 the other of said first and second optical fibres is scattered back through said optical cement and is reflected by said single reflective surface into said terminal end of the other of said first and second optical fibres.

5 2. The sensor of claim 1 wherein said
single reflective surface is flat.

 3. The sensor of claim 1 wherein said
single reflective surface is concave.

 4. The sensor of claim 1 wherein said
10 single reflective surface is disposed adjacent the
distal end of said tube.

 5. The sensor of claim 1 wherein said
single reflective surface is composed of stainless
steel.

15 6. The sensor of claim 2 wherein said
single reflective surface is oriented at an angle
of between 25 and 35 degrees with respect to the
longitudinal fibre axes of said first and second
optical fibres.

20 7. The sensor of claim 1 wherein said
terminal ends of said first and second optical
fibres are normal with respect to the longitudinal
fibre axes of said first and second optical
fibres.

25 8. The sensor of claim 1 wherein at least
one of said single reflective surface and said
terminal ends of said first and second optical
fibres is shaped so as to focus the light
reflected into the flow and to focus the field of
30 view of the other of said first and second optical
fibres.

 9. The sensor of claim 1 wherein said first
and second optical fibres each comprises a core
and a surrounding cladding layer and wherein said

5 optical cement has an index of refraction that is greater than an index of refraction of said cores.

10 10. The sensor of claim 1 wherein said first and second optical fibres each comprises a core and a surrounding cladding layer and wherein said optical cement has an index of refraction that is less than an index of refraction of said cores.

11. The sensor of claim 9 wherein said terminal ends of said first and second optical fibres are concave in shape.

15 12. The sensor of claim 10 wherein said terminal ends of said first and second optical fibres are convex in shape.

20 13. The sensor of claim 3 wherein said terminal ends of said first and second optical fibres are normal with respect to the fibre axes of said first and second optical fibres.

14. The sensor of claim 11 wherein said single reflective surface is concave.

25 15. The sensor of claim 12 wherein said single reflective surface is concave.

16. The sensor of claim 1 wherein at least one of said first and second optical fibres is a multimode optical fibre.

30 17. The sensor of claim 1 wherein at least one of said first and second optical fibres is a single mode optical fibre.

5 18. A sensor for remote fluid flow
measurements, said sensor comprising:
a flexible tube having at least one optical
opening formed in a sidewall thereof;
transmitting and receiving optical fibres
10 disposed within said tube, said transmitting and
receiving optical fibres each having a terminal
end disposed within said tube proximate an
associated opening of said at least one optical
opening; and
15 at least one reflective surface disposed
within said tube adjacent said terminal ends of
said transmitting and receiving optical fibres, a
reflective surface of said at least one reflective
surface being associated with said transmitting
20 optical fibre and a reflective surface of said at
least one reflective surface being associated with
said receiving optical fibre,
said at least one reflective surface being
oriented such that light emitted from said
25 terminal end of said transmitting optical fibre is
reflected by said reflective surface associated
with said transmitting optical fibre out said
optical opening associated with said transmitting
optical fibre into said fluid and so that back
30 scattered light within a field of view of said
receiving optical fibre reenters said optical
opening associated with said receiving optical
fibre to be reflected by said reflective surface
associated with said receiving optical fibre into
35 said terminal end of said receiving optical fibre,
said emitted light and said field of view
being focused.

19. The sensor of claim 18 wherein said
reflective surface associated with said
40 transmitting optical fibre and said reflective

5 surface associated with said receiving optical fibre comprise a common reflective surface.

20. The sensor of claim 18 wherein said optical opening associated with said transmitting optical fibre and said optical opening associated with said receiving optical fibre comprise a
10 common optical opening.

21. The sensor of claim 19 wherein said optical opening associated with said transmitting optical fibre and said optical opening associated with said receiving optical fibre comprise a
15 common optical opening.

22. The sensor of claim 18 wherein at least a one of said at least one reflective surface and said terminal ends of said transmitting and
20 receiving optical fibres are shaped so as to focus the emitted light and said field of view.

23. The sensor of claim 18 wherein said at least one optical opening and a portion of said tube surrounding said terminal ends of said
25 transmitting and receiving optical fibres and said at least one reflective surface define a cavity, said cavity being filled with an optical cement forming at least one optical window.

24. The sensor of claim 23 wherein said
30 transmitting and receiving optical fibres each comprises a core and a surrounding cladding layer and wherein said optical cement has an index of refraction that is greater than an index of refraction of said cores.

5 25. The sensor of claim 23 wherein said
transmitting and receiving optical fibres each
comprises a core and a surrounding cladding layer
and wherein said optical cement has an index of
refraction that is less than an index of
10 refraction of said cores.

26. The sensor of claim 24 wherein said
terminal ends of said transmitting and receiving
optical fibres are concave in shape.

15 27. The sensor of claim 25 wherein said
terminal ends of said transmitting and receiving
optical fibres are convex in shape.

28. The sensor of claim 18 wherein at least
one of said transmitting and receiving optical
fibres is a multimode optical fibre.

20 29. The sensor of claim 18 wherein at least
one of said transmitting and receiving optical
fibres is a single mode optical fibre.

30. The sensor of claim 18 wherein said at
least one reflective surface is flat.

25 31. The sensor of claim 30 wherein said at
least one reflective surface is oriented at an
angle of between 25 and 35 degrees with respect to
longitudinal axes of said transmitting and
receiving optical fibres.

30 32. The sensor of claim 18 wherein said at
least one reflective surface is disposed adjacent
the distal end of said tube.

5 33. The sensor of claim 18 wherein said at
least one reflective surface is composed of
stainless steel.

10 34. The sensor of claim 18 wherein said at
least one reflective surface is concave.

35. The sensor of claim 26 wherein said at
least one reflective surface is concave.

15 36. The sensor of claim 27 wherein said at
least one reflective surface is concave.

37. The sensor of claim 34 wherein said
terminal ends of said transmitting and receiving
optical fibres are normal with respect to
longitudinal fibre axes of said transmitting and
20 receiving optical fibres.

38. A method for making remote fluid flow
measurements, said method comprising the steps of:
transmitting an incident light beam through a
first optical fibre, said first optical fibre
25 disposed within a flexible tube;

reflecting the incident light beam emitted
from a terminal end of the first optical fibre out
of an optical opening formed in a sidewall of the
tube into a measurement volume of the flow located
30 outside and alongside the tube, the reflected
light beam being scattered within the measurement
volume;

receiving, through a terminal end of a second
optical fibre disposed within the tube, a portion
35 of the scattered light beam that is within a field
of view of the second optical fibre;

5 focusing the incident light beam to increase
intensity of the light beam reflected into the
flow; and

focusing the field of view of the second
optical fibre.

10 39. The method of claim 38 wherein said
incident light beam focusing step and said field
of view focusing step include shaping the terminal
ends of the first and second optical fibres.

15 40. The method of claim 38 wherein said
incident light beam focusing step and said field
of view focusing step include shaping the
reflective surface.

20 41. The method of claim 36 wherein said
incident light beam focusing step and said field
of view focusing step include shaping the
reflective surface.

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DRAWINGS

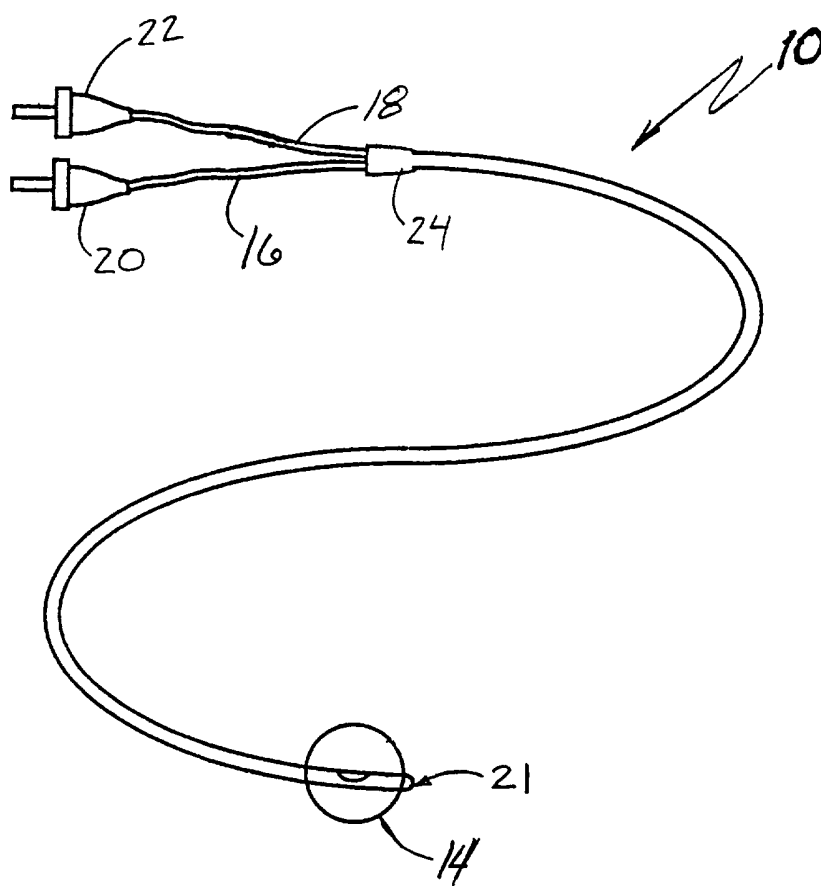
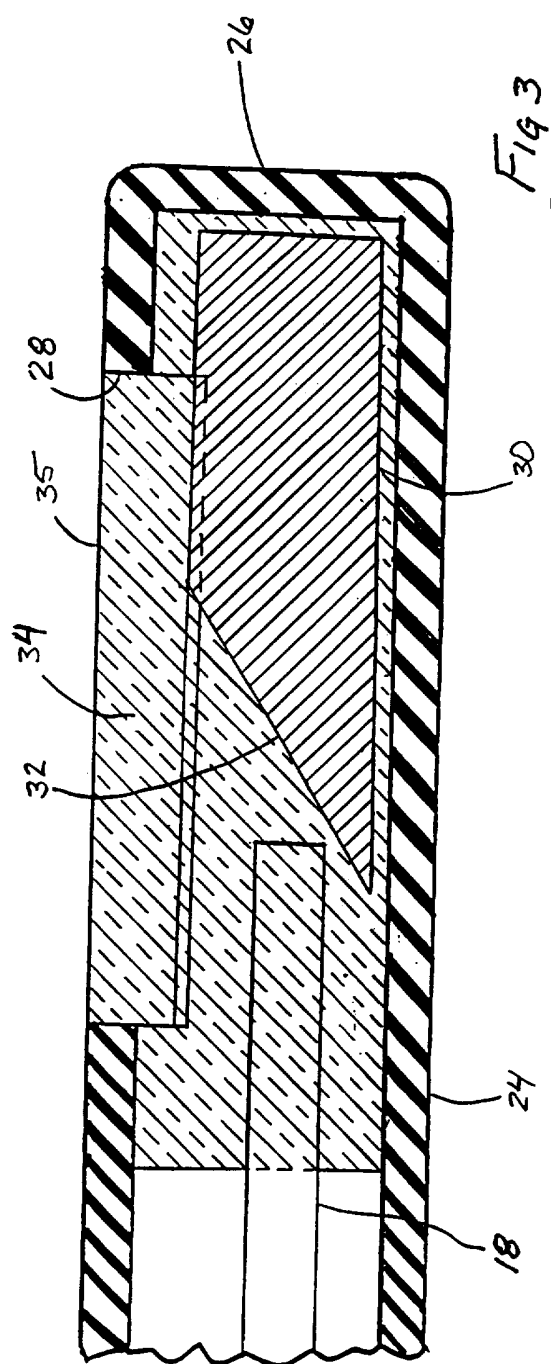
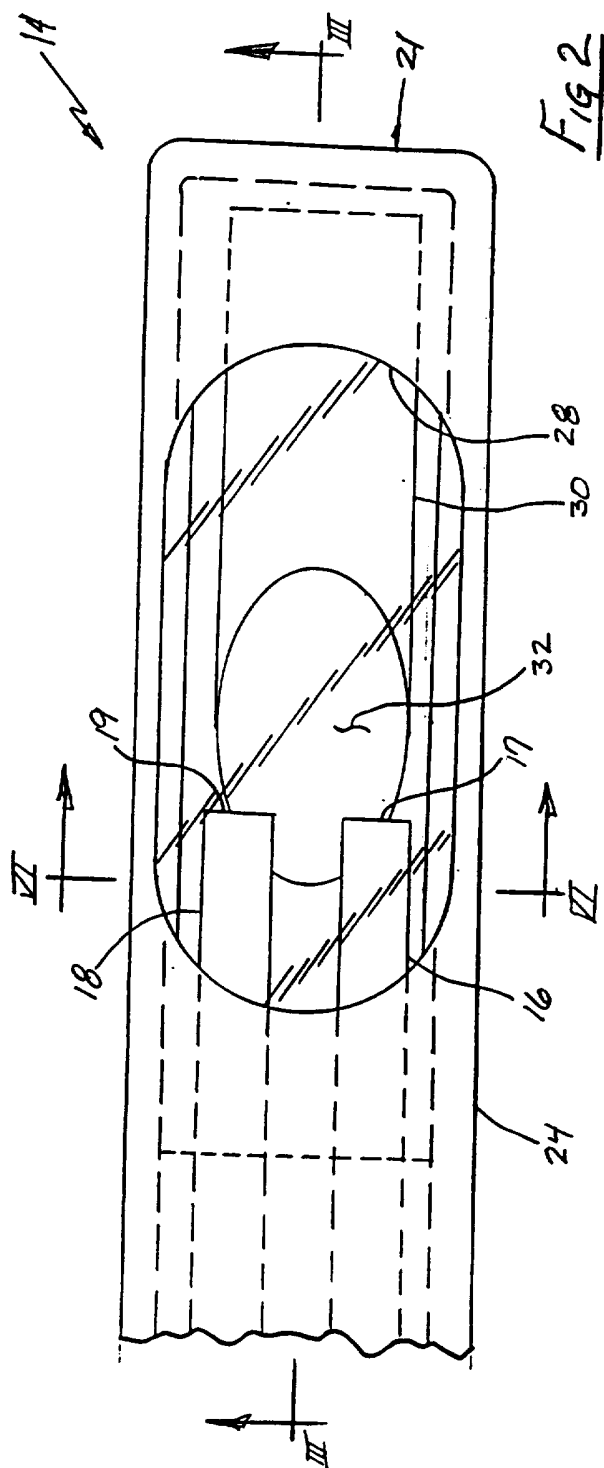


Fig. 1



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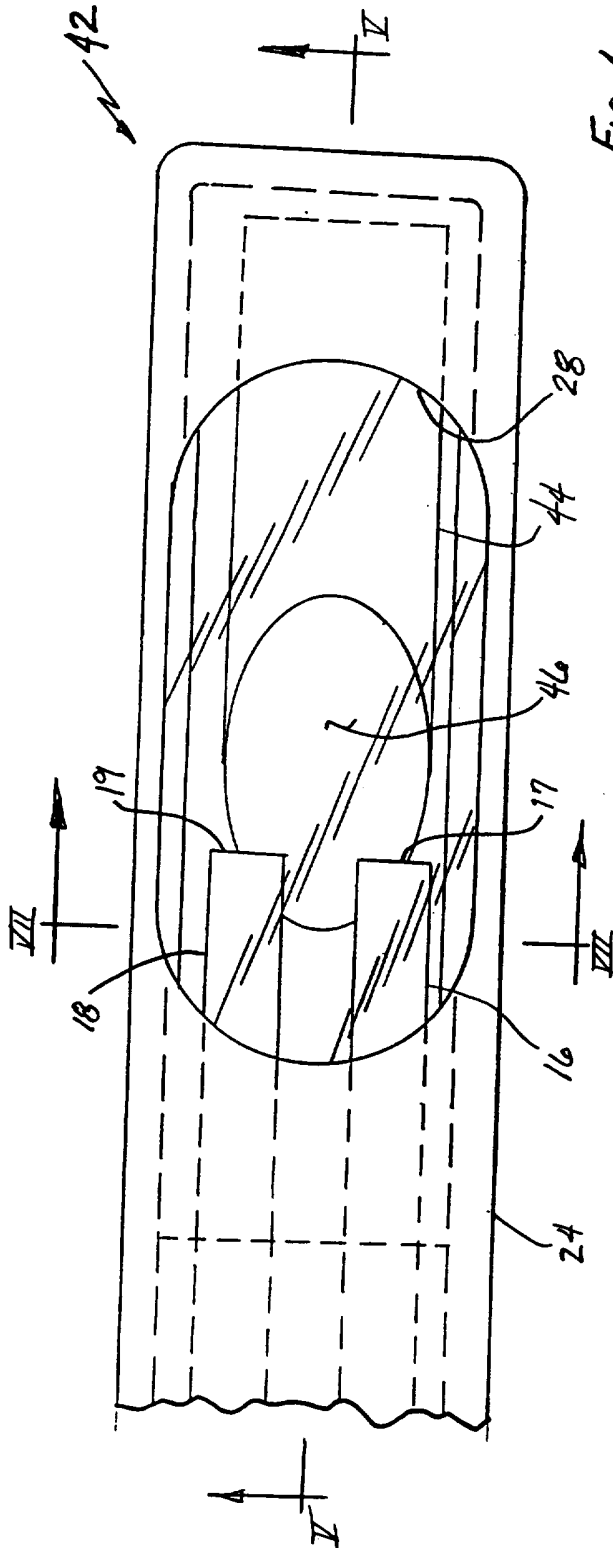


Fig. 4

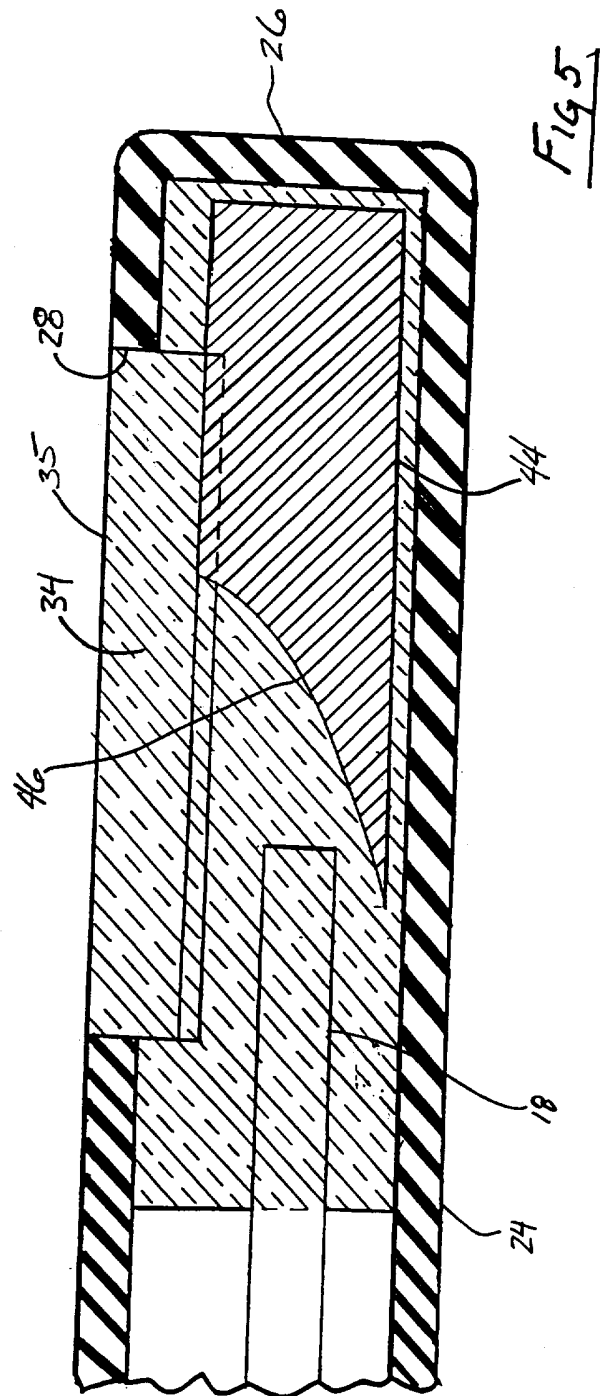
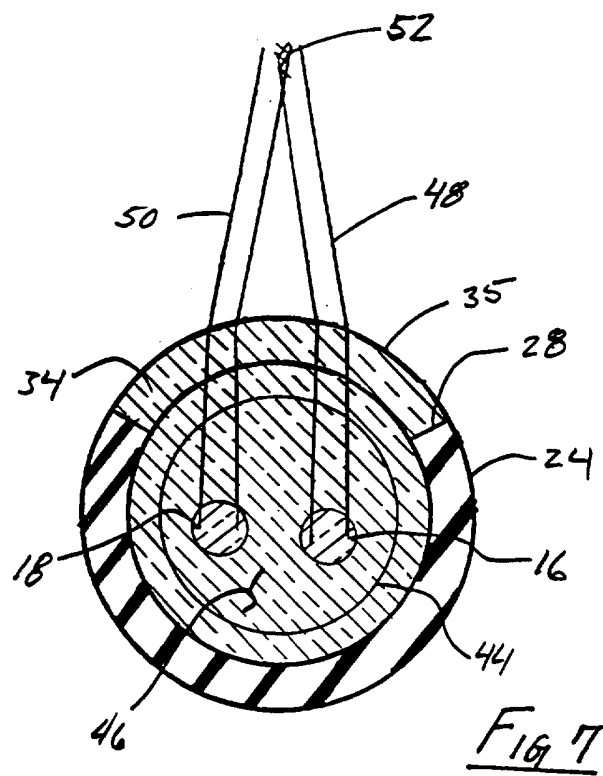
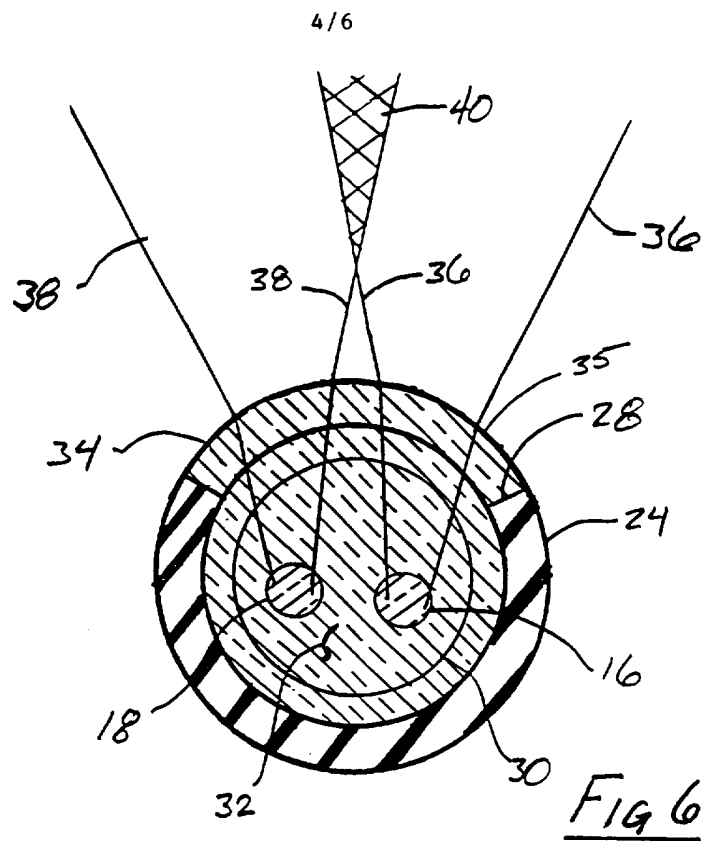


Fig. 5



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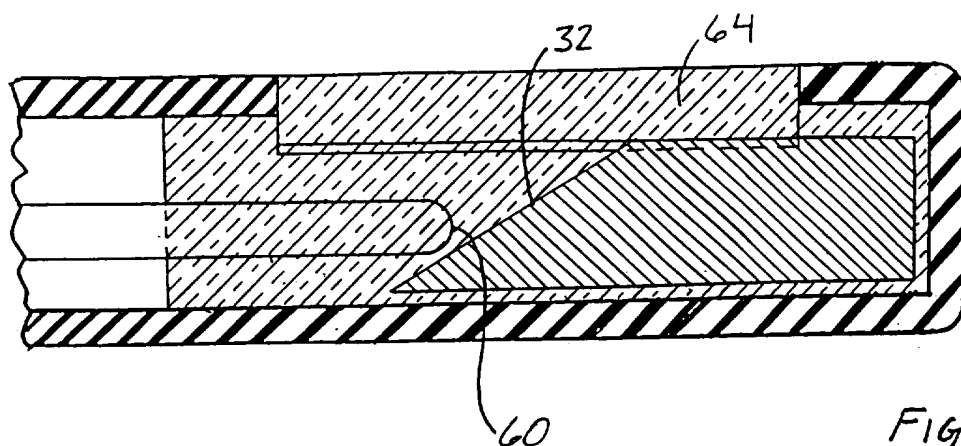


FIG 8A

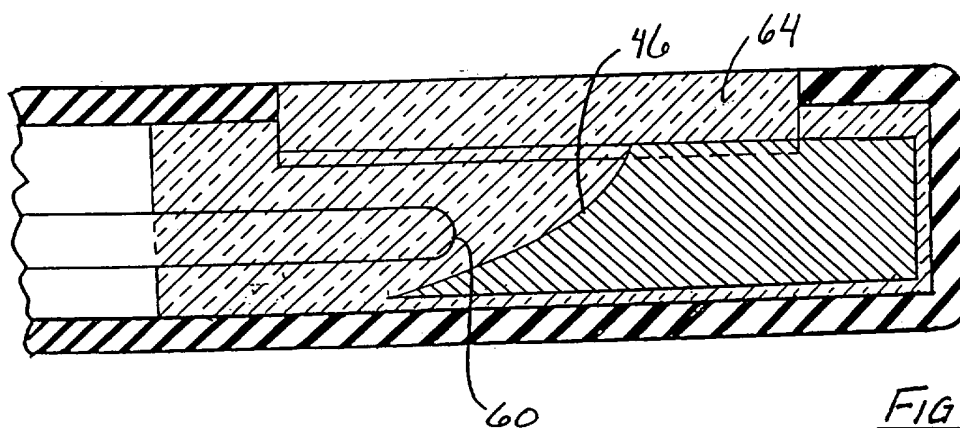


FIG 8B

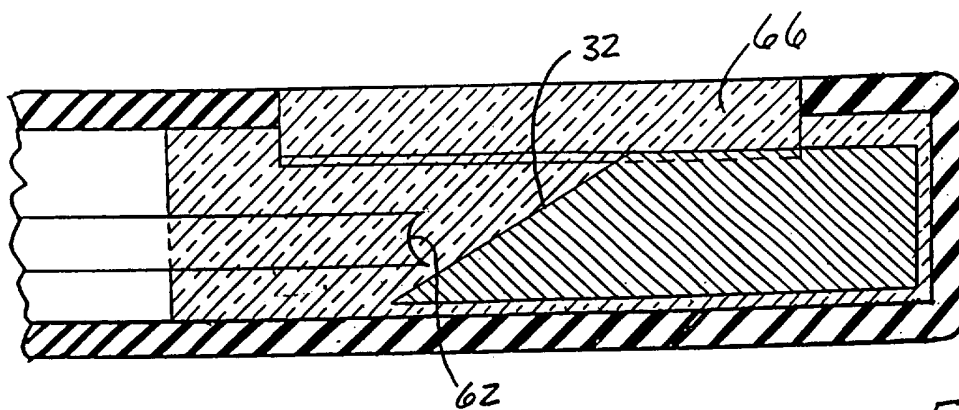


FIG 9A

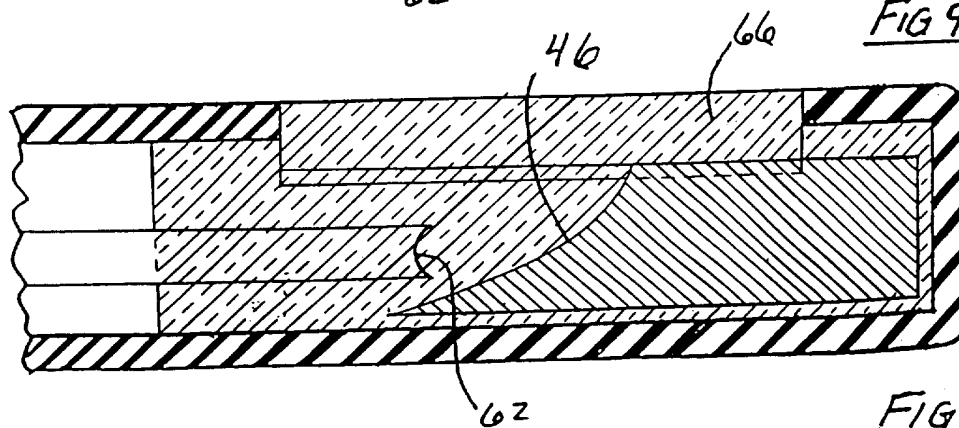
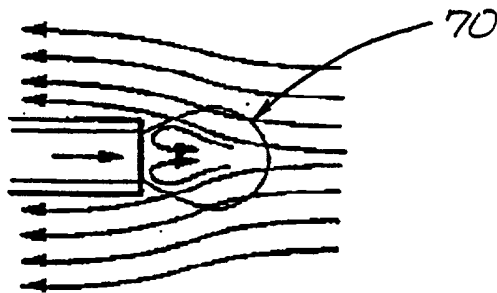


FIG 9B

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(PRIOR ART)

FIG 10



(PRIOR ART)

FIG 11

INTERNATIONAL SEARCH REPORT

International Application No.
PCT/SG 95/00012

A. CLASSIFICATION OF SUBJECT MATTER		
Int Cl ⁶ : G01F 1/66, 1/72, A61B 5/027, 5/0285		
According to International Patent Classification (IPC) or to both national classification and IPC		
B. FIELDS SEARCHED		
Minimum documentation searched (classification system followed by classification symbols) IPC: G01F 1/66, 1/72, A61B 5/02, 5/027, 5/0285		
Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched AU: IPC as above		
Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)		
C. DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
Y	WO 90/12537 A (RADI MEDICAL SYSTEMS AB) 1 November 1990 See Abstract and Fig 2.	1,2,4,6,18-21,30-32,38
Y	US 3674013 A (POLANYL) 4 July 1972 See Whole document	1,18,38
A	WO 95/19138 A (PACESETTER AB) 20 July 1995 See Abstract, Fig 6 and page 10	1,18,38
<input type="checkbox"/> Further documents are listed in the continuation of Box C <input checked="" type="checkbox"/> See patent family annex		
* Special categories of cited documents: "A" document defining the general state of the art which is not considered to be of particular relevance "E" earlier document but published on or after the international filing date "L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified) "O" document referring to an oral disclosure, use, exhibition or other means "P" document published prior to the international filing date but later than the priority date claimed "T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention "X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone "Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art "&" document member of the same patent family		
Date of the actual completion of the international search 29 February 1996		Date of mailing of the international search report 11th March 1996
Name and mailing address of the ISA/AU AUSTRALIAN INDUSTRIAL PROPERTY ORGANISATION PO BOX 200 WODEN ACT 2606 AUSTRALIA Facsimile No.: (06) 285 3929		Authorized officer S. Clark Telephone No.: (06) 283 2164

INTERNATIONAL SEARCH REPORT

International Application No.

PCT/SG 95/00012

C (Continuation) DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	Patent Abstracts of Japan, P-596, page 160 JP 62-38335 A (NIPPON KAGAKU KOGYO K.K.) 19 February 1987 See Abstract	1,18,38

INTERNATIONAL SEARCH REPORT

Information on patent family members

International Application No.

PCT/SG 95/00012

This Annex lists the known "A" publication level patent family members relating to the patent documents cited in the above-mentioned international search report. The Australian Patent Office is in no way liable for these particulars which are merely given for the purpose of information.

Patent Document Cited in Search Report				Patent Family Member			
WO	9012537	SE	8901358				
US	3674013	CA	943834	DE	2132864	FR	2107329
		GB	1345375	IL	37185	NL	7110850
END OF ANNEX							