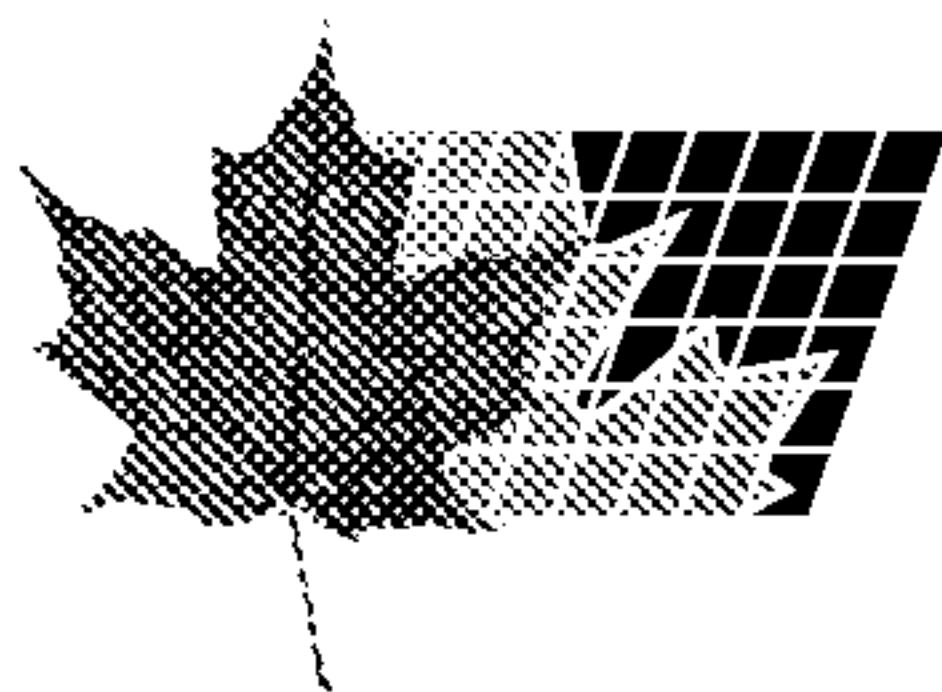




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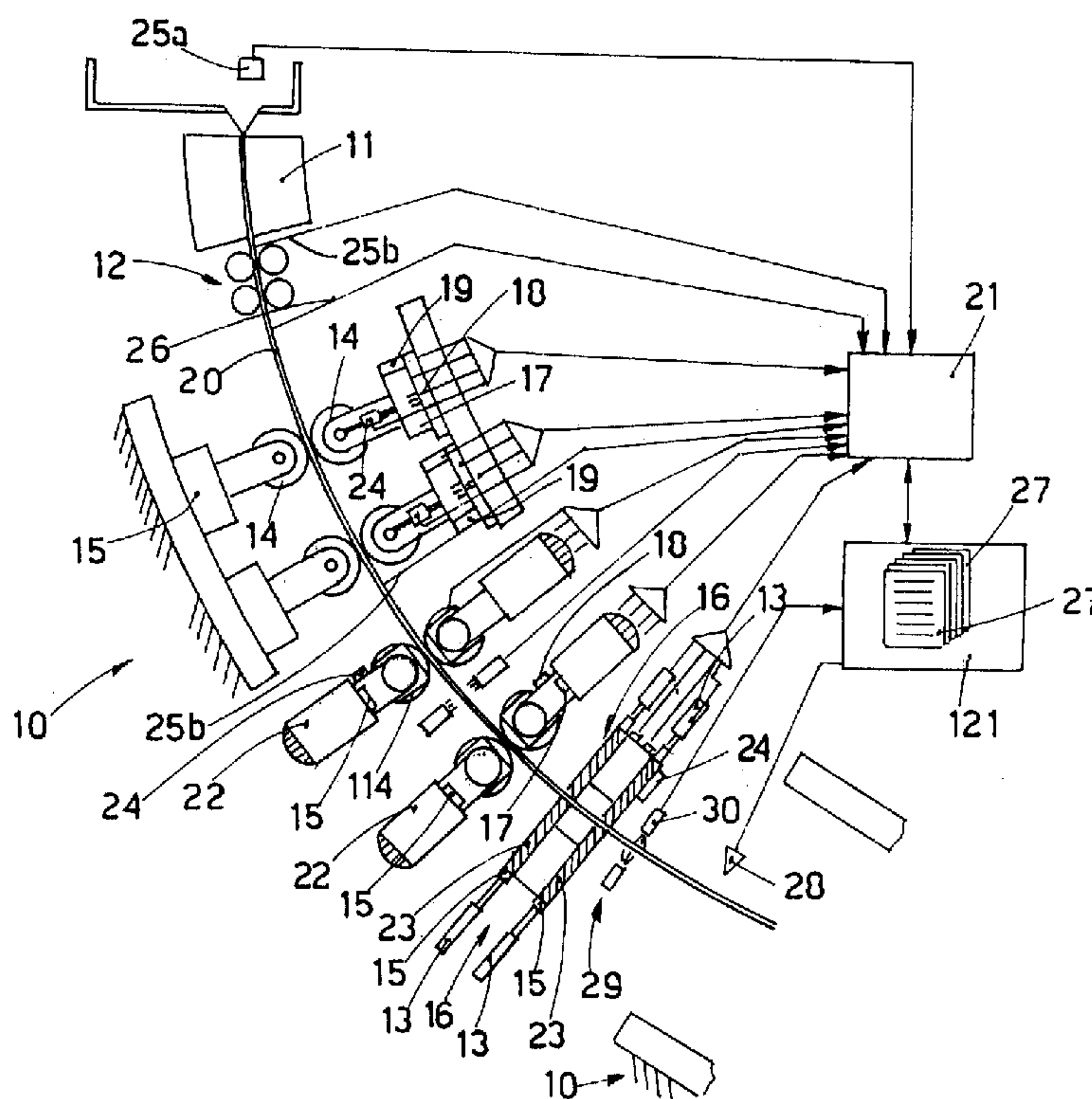
(51) Int.Cl.⁶ B22D 11/16, B21B 1/38

(30) 1995/11/28 (UD95A000233) IT

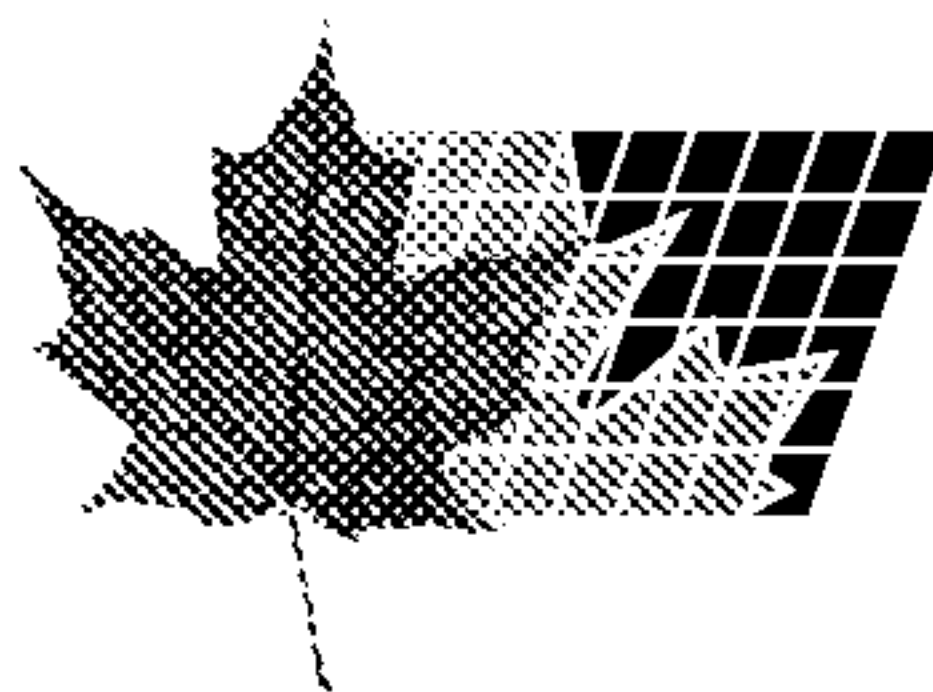
(30) 1995/11/28 (UD95A000232) IT

(54) **METHODE DE CONTROLE DE PRE-LAMINAGE DE BRAMES
MINCES A LEUR SORTIE D'UNE INSTALLATION DE
COULEE EN CONTINU**

(54) **METHOD FOR THE CONTROLLED PRE ROLLING OF THIN
SLABS LEAVING A CONTINUOUS CASTING PLANT**



(57) Method for the controlled pre-rolling of slabs, advantageously thin slabs, leaving a continuous casting plant, whereby the pre-rolling is carried out with pairs of pre-rolling elements (14, 114, 16) such as idler rolls, powered rolls, plates, belts, scrapers or other means assembled in at least one pre-rolling assembly (10), the first of these pre-rolling assemblies (10) being positioned immediately downstream of the foot rolls (12) of a crystalliser (11), all or a part of these pre-rolling elements being associated with at least pressure transducer means (18), hydraulic actuator jack means



(11) (21) (C) **2,191,180**
(22) 1996/11/25
(43) 1997/05/29
(45) 2001/02/27

(17) and position transducer means (24), there being also included means (28) monitoring the liquid core within the slab (20), means (25a) monitoring the temperature in the tundish and means (25b) monitoring the temperature of the slab both as it leaves the crystalliser (11) and when it is inside the pre-rolling unit (10), there also being included means monitoring the para of secondary cooling, and means (26) monitoring the casting speed, all these transducer and/or monitoring means being connected to at least one data processing and controlling unit (21), which governs the positioning and the adjustment of the pre-rolling elements (14, 114, 16), the final pre-rolling zone being pre-defined by a specific pair (No. X) of pre-rolling elements positioned along the path of extraction of the slab (20), the data processing and controlling unit (21) having access to an inner memorised archive where there is a plurality of pre-defined tables or technological cards (27) containing the map of the desired values of reduction in thickness in the pre-rolling step as a function of the working parameters pre-set and/or monitored and/or detected continuously, each significant variation of at least two of these parameters causing a new table or technological card (27) to be selected with a resulting re-definition of the position and/or action of the pre-rolling elements (14, 114, 16).

ABSTRACT

Method for the controlled pre-rolling of slabs, advantageously thin slabs, leaving a continuous casting plant, whereby the pre-rolling is carried out with pairs of pre-rolling elements (14, 114, 16) such as idler rolls, powered rolls, plates, belts, scrapers or other means assembled in at least one pre-rolling assembly (10), the first of these pre-rolling assemblies (10) being positioned immediately downstream of the foot rolls (12) of a crystalliser (11), all or a part of these pre-rolling elements being associated with at least pressure transducer means (18), hydraulic actuator jack means (17) and position transducer means (24), there being also included means (28) monitoring the liquid core within the slab (20), means (25a) monitoring the temperature in the tundish and means (25b) monitoring the temperature of the slab both as it leaves the crystalliser (11) and when it is inside the pre-rolling unit (10), there also being included means monitoring the para of secondary cooling, and means (26) monitoring the casting speed, all these transducer and/or monitoring means being connected to at least one data processing and controlling unit (21), which governs the positioning and the adjustment of the pre-rolling elements (14, 114, 16), the final pre-rolling zone being pre-defined by a specific pair (No. X) of pre-rolling elements positioned along the path of extraction of the slab (20), the data processing and controlling unit (21) having access to an inner memorised archive where there is a plurality of pre-defined tables or technological cards (27) containing the map of the desired values of reduction in thickness in the pre-rolling step as a function of the working parameters pre-set and/or monitored and/or detected continuously, each significant variation of at least two of these parameters causing a new table or technological card

- 1 (27) to be selected with a resulting re-definition of the
- 2 position and/or action of the pre-rolling elements (14, 114,
- 3 16).

1 "METHOD FOR THE CONTROLLED PRE-ROLLING OF THIN SLABS LEAVING
2 A CONTINUOUS CASTING PLANT"

3 * * * * *

4 This invention concerns a method for the controlled pre-
5 rolling of thin slabs leaving a continuous casting plant, as
6 set forth in the main claim.

7 To be more exact, the method according to the invention is
8 carried out immediately downstream of the foot rolls of a
9 mould on thin slabs leaving the mould performing continuous
10 casting of thin slabs.

11 By thin slabs are meant slabs with a width from 800 to
12 2500 mm. or more and with a thickness from 25 to 90 mm.

13 The invention is applied advantageously, but not only, to
14 slabs having a final thickness between 30 and 60 mm. at the
15 outlet of the continuous casting machine.

16 The invention can also be applied to the continuous
17 casting of billets, whether they be round, square,
18 rectangular, etc.

19 The invention can be applied to straight and curved
20 continuous casting plants.

21 EP-A-625.388 in the name of the present applicants
22 discloses a controlled pre-rolling method whereby a thin
23 slab is subjected to a pre-rolling action in a zone
24 downstream of the foot rolls.

25 This document provides for the performance of a controlled
26 pre-rolling with reduction with a liquid core, or soft
27 reduction, of the slab leaving the crystalliser so as to
28 produce a slab with a reduced thickness at the end of the
29 casting machine.

30 As is disclosed in that prior art document, the main
31 advantages of the controlled pre-rolling are the ability to
32 obtain at the outlet of the casting machine a slab with a
33 slender thickness (30-60 mm.) when using a crystalliser of a

1 greater thickness, and also the ability to obtain a refining
2 of the structure of solidification of the metal and the
3 elimination of the central segregation in the slab.

4 The soft reduction, if it is to be effective, has to take
5 place with a continuous controlled reduction of the
6 thickness of the slab, and this condition can be achieved
7 with a substantially tapered conformation of the segment of
8 slab subjected to the soft reduction.

9 The above prior document states that this tapered segment
10 has to have a length between about 0.8/1 metres and about 7
11 metres, in which the greater length corresponds to the end
12 of the containing zone produced by idler containing rolls
13 included downstream of the crystalliser and of the foot
14 rolls.

15 Moreover, the pre-rolling method described in that
16 document is based on an ON LINE solidification model which,
17 on the basis of the actual casting conditions, determines
18 the exact profile of solidification of the slab.

19 This method arranges to reduce in a controlled and
20 required manner the thickness of the slab with a liquid core
21 according to the main casting parameters (speed of
22 extraction, difference of temperature in the tundish,
23 secondary cooling downstream of the mould, type of steel,
24 thicknesses) which are partly set at the start-up of the
25 process and are partly continuously monitored by suitable
26 sensors and/or transducers.

27 The rolls which perform the pre-rolling are associated
28 with load cells and/or pressure transducers, which monitor
29 the pressure exerted on the thin slab and check that this
30 pressure, for each pair of rolls or for each assembly of
31 pairs of rolls, corresponds to the pressure which the
32 dynamic programme sets for obtaining the desired effect on
33 the slab and for performing the desired pre-rolling.

1 Moreover, each pair of rolls is associated with a position
2 transducer which monitors the distance or gap between the
3 opposed rolls of each pair.

4 In this case too the task of the position transducer is
5 primarily to check that the positioning of the pairs of
6 rolls or of the assemblies of pairs of rolls corresponds to
7 the value which the program sets for that pre-rolling cycle.

8 The whole system is governed by a data processing unit
9 controlling the pre-rolling which receives signals from
10 pressure transducers and position transducers, which may be
11 transducers working with assemblies of rolls or with single
12 rolls, and also from monitors of the speed of the slab,
13 monitors of the secondary cooling parameters and monitors of
14 the temperature of the molten metal in the tundish and of
15 the temperature of the slab leaving the crystalliser.

16 There may also be included a monitor to identify the
17 presence or absence of a liquid core within the slab.

18 The data processing and control unit of the prior art
19 document processes these parameters and provides the pairs
20 of rolls in real time with the best adjustment values.

21 By rolls are meant here continuous rolls, rolls covering
22 sectors, belts, etc. that is to say, any system of the state
23 of the art.

24 With the pre-rolling assembly are associated means for the
25 secondary cooling of the slab which consist, for instance,
26 of a plurality of sprayer nozzles.

27 Moreover, at least one descaling assembly may be
28 associated with the pre-rolling assembly.

29 US-A-5,018,569 discloses a pre-rolling method whereby the
30 slab leaving a mould and the foot rolls is caused to
31 cooperate with a plurality of pairs of successive rolls so
32 as to achieve the desired reduction of thickness with a
33 liquid core.

1 This document of the prior art arranges to identify and to
2 determine the end of the liquid cone by reading the pressure
3 exerted by the rolls on the slab passing through.

4 To be more exact, the adjustment of the hydraulic pressure
5 of the actuator jacks associated with the rolls acting on
6 the slab is set by a control element so as to obtain the
7 desired reduction of thickness of the slab passing through.

8 However, in that document the opposed rolls of a pair are
9 separated by stationary spacers and therefore can approach
10 each other until the supports abut against these spacers.

11 Therefore, when the position of these spacers has been
12 determined, the machine can no longer be adjusted and
13 therefore cannot be adapted to the specific requirements
14 which may occur from time to time.

15 Moreover, the adjustment and clamping in position of the
16 rolls based only on the adjustment of the pressure of the
17 actuator jacks is very unstable and not at all reliable.

18 In fact, the required pressure which the rolls have to
19 exert on the slab changes during the casting steps in
20 particular because in the various steps the temperature and
21 the speed cannot always remain perfectly constant; these
22 changes of pressure cannot be foreseen in so exact a manner
23 as to be able to be balanced with variations of pressure in
24 the adjustment actuator jacks and thus to enable the
25 relative roll to remain in the desired position
26 corresponding to that pre-rolling pass.

27 If the rolls do not remain fixed in the desired position,
28 cracks and bends may be caused in the slab being processed.

29 In the case of this document of the prior art, when the
30 pressure of the actuator jacks exceeds a given value, the
31 speed of extraction is altered so as to alter the length of
32 the liquid cone within the slab.

33 The alteration of the extraction speed, however, entails a

1 plurality of drawbacks.

2 First of all, an alteration of the speed has an effect on
3 all the working parameters and makes necessary a re-
4 programming and a re-adaptation of the whole casting machine
5 according to that alteration.

6 Furthermore, an alteration of speed may entail
7 consequences regarding the quality of the product and the
8 output of the plant.

9 Besides, each change of speed entails transient conditions
10 which may alter the planar condition of the meniscus and
11 therefore the surface quality of the cast product.

12 Moreover, the alteration of speed may be slow in terms of
13 adaptation times, and this fact may entail a delay in
14 reaching the conditions of the best disposition.

15 A further shortcoming of systems known to the state of the
16 art, as has been demonstrated, is that the regulation of the
17 position of the pre-rolling elements present downstream from
18 the foot rolls, which is based exclusively or mostly on
19 values obtained ON LINE and used in a dynamic programme
20 continuously up-dated with the results of the monitoring,
21 cannot always give satisfactory results.

22 In particular, in some cases there have been delays in
23 adapting and regulating times, difficulties in obtaining the
24 required precision, and malfunctionings deriving from the
25 large amounts of calculations which have to be done every
26 time one of the parameters being monitored is changed.

27 This means that extremely complex software has to be used,
28 as the software has to elaborate a very large amount of
29 data, re-calculate in real time the correct values of the
30 reduction in thickness which has to be applied according to
31 the parameters monitored, and then supply the output data to
32 regulate and adapt a very high number of devices, all of
33 which makes the machine too reactive and instable.

1 The present applicants have designed, tested and embodied
2 this invention to overcome these drawbacks and to perfect
3 the controlled pre-rolling method according to EP-A-625.388
4 and also to achieve further advantages.

5 This invention is set forth and characterised in the main
6 claim, while the dependent claims describe variants of the
7 idea of the main embodiment.

8 The purpose of the invention is to obtain a method for the
9 controlled pre-rolling of thin slabs leaving a continuous
10 casting plant whereby the method perfects the system of
11 dynamic adjustment of the action of the pre-rolling elements
12 on the slab passing through.

13 In this invention, by pre-rolling elements are meant
14 rolls, plates, belts, scraper blades or other means
15 performing the same function.

16 A further purpose of the invention is to provide a method
17 which reduces the complexity of the software to manage and
18 control the system, and to reduce the amount of calculations
19 which have to be carried out every time to regulate the
20 position and/or function of the pre-rolling elements, yet
21 maintain an efficient control and monitoring of the whole
22 system.

23 In positioning and adjusting the pre-rolling elements,
24 whether single or in assemblies, the method according to the
25 invention, in a first embodiment, arranges to use a
26 plurality of tables or technological cards pre-set by the
27 technician and present in the memory of the data processing
28 unit governing the means to position and adjust the pre-
29 rolling elements.

30 In these tables or technological cards, the invention
31 defines set values in relation to the reduction in thickness
32 of the slab leaving the crystalliser, these values being
33 referred to the distance starting from the outlet of the

1 crystalliser.

2 In other words, each of these tables is pre-set by the
3 technician, who knows the specific optimum conditions of
4 pre-rolling based on data known in advance (type of steel,
5 shape, temperature in the tundish, temperature of the slab,
6 casting speed, cooling conditions, etc.); each of these
7 tables then, contains the values relating to the progressive
8 reduction of thickness that are required.

9 For example, it is possible to pre-set a reduction in
10 thickness of 10% in the first two metres downstream of the
11 crystalliser, a further reduction of 5% in the following two
12 metres, and so on.

13 These fixed values for the reduction in thickness
14 substantially correspond to the average optimum values
15 foreseen in proportion to the principal parameters of the
16 casting process, such as the temperature of the metal in the
17 tundish, casting speed, parameters of primary and secondary
18 cooling, type of steel, temperature of the slab leaving the
19 crystalliser, parameters of the oscillation of the ingot
20 mould, etc.

21 Every time, during the casting process, that a significant
22 variation in at least two of these parameters is monitored,
23 the data processing unit passes automatically, or by manual
24 control, to a new table containing the fixed optimum values
25 including the new value of the parameter which has changed.

26 All the other parameters being equal, each parameter
27 continuously controlled and monitored will be associated
28 with a plurality of tables, as many as are needed to contain
29 all the different values which can cause a significant
30 variation in the pre-rolling conditions.

31 In other words, for each of these parameters there will be
32 a table which, with all the other parameters remaining
33 fixed, will remain valid for a range of values included in a

1 field of tolerance around an average value.

2 This solution makes it possible to reduce considerably the
3 amount of calculations which have to be carried out every
4 time there is a variation in the casting process, because
5 everything is referred to a tabular selection of pre-set
6 data, data which is certainly reliable because it is pre-set
7 to ensure optimum pre-rolling conditions.

8 This also brings a reduction in the costs of the control
9 system, and makes it possible, when so desired, to pass to a
10 semi-automatic control (with a manual control of the tables)
11 which is very efficient and simple to use.

12 In a further embodiment of the invention the pre-rolling
13 passes are adjusted dynamically by the data processing unit
14 according to the signals received and indicating the actual
15 force of closure of the rolls against the slab.

16 These signals are obtained, in a manner disclosed in EP-A-
17 625.388, by measuring the pressure acting in the hydraulic
18 actuator jacks which act on the pre-rolling rolls, or else
19 by means of load cells coupled directly to those rolls.

20 When these signals indicate that the force of closure is
21 greater than a pre-set threshold, as a function of the
22 ferrostatic pressure at that point, this indicates that the
23 rolls are acting on a slab which is already fully
24 solidified.

25 In this case the final pre-rolling zone is displaced onto
26 the pair of adjustable rolls positioned immediately
27 upstream.

28 Monitoring of the threshold value is repeated until the
29 force of closure found at a given pair of rolls does not go
30 below that threshold value.

31 When this situation is found, the disposition of the
32 casting machine stabilises and is maintained until a new
33 condition of exceeding the threshold occurs.

1 According to a variant, two thresholds are provided,
2 namely a maximum threshold and a minimum threshold.

3 In this case, when the force of closure measured exceeds
4 the maximum threshold value, the final pre-rolling zone is
5 displaced to the pair of adjustable rolls positioned
6 immediately upstream, whereas when the force of closure
7 descends below the minimum threshold value, the final pre-
8 rolling zone is displaced to the pair of adjustable rolls
9 positioned immediately downstream.

10 In a limit condition these two thresholds may coincide.

11 According to another preferred embodiment of the invention
12 the pre-rolling passes are adjusted dynamically by the data
13 processing unit according to the signals received from the
14 position transducers and indicating the actual position of
15 the rolls in relation to the slab.

16 On the basis of this monitoring, the casting machine
17 adapts the configuration of the pairs of rolls dynamically
18 when the data processing unit discloses that the actual
19 distance between the opposed rolls of each pair is greater,
20 after allowing for a pre-set value of tolerance, than the
21 pre-set value for that specific pair.

22 This signal indicates the fact that the rolls are acting
23 on a slab which is already fully solidified.

24 In this case, therefore, the set value of the distance
25 between the opposed rolls of a pair is used for the pair of
26 rolls positioned upstream, and so on until the best
27 configuration conditions set for the pre-rolling are re-
28 established.

29 In the method according to the invention the length of the
30 soft reduction zone is between 0.3 and 14 metres, depending
31 on the casting parameters relating at least to the
32 extraction speed, the intensity of cooling, the type of
33 steel and the thicknesses in question.

1 This long pre-rolling segment makes possible a wider and
2 more flexible range of options of the working conditions of
3 the rolls and also a better and more extended distribution
4 of the action of the pre-rolling assemblies on the slab
5 being extracted.

6 Besides, the surface tensions on the material and the
7 forces supported by the rolls during working are less, and
8 therefore there is less overheating of the rolls and a
9 longer working life thereof.

10 In one variant of the method according to the invention at
11 least some of the rolls or assemblies of rolls forming the
12 pre-rolling elements located downstream of the foot rolls
13 and having the task of carrying out in a controlled manner
14 the reduction of the slab with a liquid core are powered.

15 In another variant at least one containing scraper means
16 is included as an element to replace or complement the rolls
17 and not only performs in a desired manner the action of
18 reduction with a liquid core but also exerts on the slab
19 passing through an action of removing the scale and residues
20 of lubrication slag on the surface of the slab.

21 The attached tables, which are given as a non-restrictive
22 example, show a preferred solution of the method according
23 to the invention as follows:

24 Fig.1 is a part view of a pre-rolling assembly according
25 to the invention;

26 Figs.2 and 3 are block diagrams of two preferred solutions
27 of the invention.

28 In Fig.1 the pre-rolling method according to the invention
29 is carried out by at least one pre-rolling assembly 10
30 consisting of a plurality of pairs of rolls 14.

31 This pre-rolling method is performed so as to reduce
32 progressively the thickness of a slab 20 leaving a
33 crystalliser 11 to a desired value; this reduction may

1 amount to between 10% and 50% of the value of the thickness
2 of the slab 20.

3 Fig.1 shows only the first of the pre-rolling assemblies
4 10 associated with foot rolls 12 and with a crystalliser 11,
5 which produces continuously a thin slab 20; a second pre-
6 rolling assembly 10 installed immediately downstream is only
7 partly shown.

8 The first pre-rolling assembly is fitted immediately
9 downstream of the crystalliser 11 at a distance of about 0.3
10 to 0.4 metres.

11 In the form of embodiment shown merely as an example the
12 first pre-rolling assembly 10 comprises two pairs of idler
13 rolls 14 followed by two pairs of powered rolls 114
14 associated with respective motors 22 and by a scraper means
15 16, which also has the function of reducing the thickness of
16 the slab 20 being extracted.

17 The pairs of rolls 14, 114 shown can be continuous
18 assemblies or be divided into sectors or into assemblies of
19 two or more pairs or be of any known type.

20 The rolls 14, 114 and the blades 23 of the scraper means
21 16 are associated singly or in assemblies with at least one
22 load cell 15, which sends signals to a data processing unit
23 21 controlling the pre-rolling means.

24 In the form of embodiment shown the rolls 14, 114 are
25 associated singly or in assemblies with at least one capsule
26 or hydraulic actuator jack 17, whereas the blades 23 of the
27 scraper means 16 are associated with hydraulic actuator
28 jacks 13 or with screw-threaded type jacks.

29 Each actuator jack 13, 17 is controlled by a servovalve 19
30 and is associated with a pressure transducer 18; the
31 servovalves 19 are controlled by the data processing and
32 controlling unit 21 of the pre-rolling means, so that the
33 unit 21 obtains the data relating to actual force of closure

1 exerted by the rolls 14, 114 and by the blades 23 against
2 the slab 20.

3 In this case each pair of rolls 14, 114 and the scraper
4 means 16 are associated with their own individual position
5 transducers 24.

6 Further position transducers working with the assemblies
7 of rolls may be included but are not shown in this case.

8 Each pressure transducer 18, each individual position
9 transducer 24 and each possible position transducer working
10 with an assembly transmit their own signals to the data
11 processing and controlling unit 21.

12 In order to control the pre-rolling process and obtain the
13 desired reduction in the thickness of the slab 20, the
14 method includes monitors of the temperature 25a in a tundish
15 and 25b at the outlet of the crystalliser 11, speed monitors
16 26, monitors 28 of the liquid core and means 29 to adjust
17 the secondary cooling with nozzles 30, all these monitors
18 and means sending and/or receiving signals to/from the data
19 processing and controlling unit 21.

20 At the beginning of a rolling campaign there are set or
21 inserted in the data processing and controlling unit 21 the
22 parameters linked to the pre-rolling which it is intended to
23 carry out, these parameters being possibly associated with
24 the type of material cast and with the dimensions of the
25 thin slab 20.

26 As a function of these parameters the data processing and
27 controlling unit 21 pre-arranges the configuration of the
28 pairs of rolls 14, 114 and of the scraper means 16 so as to
29 obtain the desired pre-rolling passes, and in particular the
30 pair of rolls is selected, indicated in this case
31 generically with No. X, in which there is the end of the
32 pre-rolling, that is to say, in which there is a fully
33 solidified slab 20.

1 This step is referenced with the pass 31 in Figs.2 and 3.

2 The data processing and controlling unit 21 intervenes, if
3 necessary, to modify the configuration of the pre-rolling
4 elements 14, 114, 16, in this case, based on a specific and
5 pre-determined table, or technological card, 27 contained,
6 in this case, in the memory of the central data processing
7 unit 121; when casting is started, when the dummy bar is
8 extracted, the data processing and controlling unit 21
9 controls and adjusts, one by one, the pairs of rolls 14,
10 114, and the scraping device 16 in such a way that the
11 desired pre-rolling is achieved.

12 In the event that at least two of the continuously
13 monitored parameters are subject to variation, be it
14 natural, accidental or imposed from outside, in relation to
15 the pre-set value, the data processing and controlling unit
16 21 selects a new table 27 which is present in the memory, or
17 inner archive, of the central processing unit 121; this new
18 table 27 will contain inside, as identification data, the
19 parameters monitored during processing, with the value which
20 has varied as monitored by the relative monitoring means
21 and, as output data, the values to position and adjust the
22 pre-rolling elements 14, 114, 16.

23 According to this embodiment, each variation outside a
24 defined field of at least two of the parameters monitored
25 causes a new table 27 to be selected, this new table 27
26 having the new values to position and adjust the pre-rolling
27 elements 14, 114, 16 in their entirety.

28 The data processing and controlling unit 21 can also act
29 on the motors 22 of the powered rolls 114 and if necessary
30 on the jacks 13, of the screw threaded or hydraulic type,
31 associated with the blades 23 of the scraping device 16.

32 In this case, both the flow and the pressure of delivery
33 of the sprayer nozzles 30 of the secondary cooling means 29

1 are advantageously adjusted by the data processing and
2 controlling unit 21 and/or the central processing unit 121,
3 thus ensuring a continuous monitoring of the conditions of
4 the slab 20.

5 According to the programme pre-set in the data processing
6 and controlling unit 21 or 121, the reduction in thickness
7 can be progressive with a constant gradient or in sections
8 with a different gradient of reduction.

9 In a further solution of the invention shown in Fig.2, in
10 an initial step two thresholds (pass 32) are pre-arranged,
11 namely a maximum **P1** and a minimum **P2** respectively, which
12 correspond to values of the force of closure which the rolls
13 14, 114 or the other pre-rolling elements, such as the
14 blades 23, for instance, exert on the surface of the slab
15 20.

16 During the process the values corresponding to the force
17 of closure for each pair of pre-rolling elements are
18 monitored continuously by controlling the pressure in the
19 hydraulic actuator jacks 17, 13 or else by controlling the
20 monitoring performed by the load cells 15.

21 In particular, there is checked the value of the force of
22 closure **Px** found at the pair of rolls No. **X** in relation to
23 the thresholds **P1** and **P2** (pass 33).

24 As can be seen in Fig.2 (pass 34), if the force of closure
25 **Px** is greater than the maximum threshold **P1**, this means that
26 the rolls are acting on a slab 20 which has already become
27 solidified, and therefore the final zone of the pre-rolling
28 is displaced to the pair of rolls No. **X - 1** positioned
29 immediately upstream.

30 If the force of closure **Px** lies between the two thresholds
31 **P1** and **P2**, then the disposition of the pre-rolling elements
32 is not changed (pass 35), whereas if the force of closure **Px**
33 is less than the minimum threshold **P2**, this means that the

1 liquid core exceeds the programmed value and that therefore
2 the final zone of pre-rolling is to be displaced to the pair
3 of rolls No. $X + 1$ positioned immediately downstream (pass
4 36).

5 These steps of checking are carried out until the
6 condition corresponding to the pass 35 is found.

7 In a conceptually analogous manner, which may be an
8 alternative or complementary to what we have said above, the
9 dynamic checking of the correct development of the pre-
10 rolling may be carried out on the basis of the actual values
11 of the gap, or distance, between the opposed rolls as
12 monitored by the position transducers 24, whether the latter
13 be monitors of individual rolls or of assemblies of rolls.

14 In this case, in the initial pre-arrangement step a value
15 of tolerance D (pass 37) is set which, for instance, is
16 calculated as a fixed percentage of the gap G or according
17 to precise and specific algorithms of calculation.

18 During the process the actual value of the gaps and in
19 particular the value of the gap G_x corresponding to the pair
20 of rolls positioned in the zone designated as the final pre-
21 rolling zone (pass 38) is continuously checked.

22 In this case, as can be seen in Fig.3, if the actual value
23 of the gap G_x exceeds the value G plus the set tolerance D ,
24 this means that the rolls are acting on a slab which is
25 already solidified, and therefore the final pre-rolling zone
26 is displaced to the upstream pair of rolls No. $X - 1$ (pass
27 39).

28 If the contrary is the case, the disposition of the
29 machine is kept as previously pre-arranged by the data
30 processing unit 21 (pass 40).

31 All the above adjustments can be achieved dynamically by
32 recalculating on the basis of the new monitored parameters
33 the entire disposition of the casting machine or else by

1 selecting the tables 27 described above.

2 The method according to the invention provides for the
3 pre-rolling of the slab 20 to be able to be carried out up
4 to a distance of about 14 metres from the outlet of the
5 crystalliser 11 by using pre-rolling assemblies 10
6 positioned in sequence and comprising only idler 14 or
7 powered 114 rolls or else rolls positioned alternately with
8 containing scraper means 16.

CLAIMS

1. Method for the controlled pre-rolling of a slab leaving a continuous casting plant, comprising pre-rolling the a slab with pairs of pre-rolling elements assembled in at least one pre-rolling assembly, a first of these pre-rolling assemblies being positioned immediately downstream of foot rolls of a crystallizer, all or a part of these pre-rolling elements being associated with at least pressure transducer means, hydraulic actuator jack means and position transducer means, there being also included means monitoring the liquid core within the slab, means monitoring the temperature in a tundish feeding the crystallizer and means monitoring the temperature of the slab, both as it leaves the crystallizer and when it is inside the at least one pre-rolling assembly, there also being included means monitoring the parameters of secondary cooling, and means monitoring the casting speed, all these transducer and/or monitoring means being connected to at least one data processing and controlling unit, and governing the positioning and the adjustment of the pre-rolling elements with the data processing and controlling unit, the final pre-rolling zone being pre-defined by a specific pair (No. X) of pre-rolling elements positioned along the path of extraction of the slab, wherein the data processing and controlling unit has access to an inner memorized archive where there is a plurality of pre-defined tables or technological cards containing the map of the desired values of reduction in thickness during pre-rolling, as a function of working parameters, the working parameters including at least two of the temperature of the melted metal in the tundish, the

temperature of the slab as it leaves the crystallizer, the temperature of the slab at several points along the pre-rolling step, the casting speed, the parameters of secondary cooling, the type of steel, the presence and/or entity of a liquid core inside the slab, the parameters of primary cooling, and the course and frequency of the oscillations to which the crystallizer is subject, each significant variation of at least two of these parameters causing a new table or technological card to be selected with a resulting re-definition of the position and/or action of the pre-rolling elements.

2. Method as in claim 1, in which each variation of at least one of the plurality of working parameters outside a field of tolerance pre-defined around an average value, with all the other parameters being equal, causes a new table or technological card to be selected.

3. Method as in claim 1, in which the reduction in thickness of the slab is obtained in a travel which can vary from a minimum distance of 0.3 meters to a maximum distance of 14 meters from the outlet of the crystallizer.

4. Method as in claim 1, in which during the process the data processing and controlling unit receives continuously the actual values relating to the closure force (P) and/or the gap (G) at least of the pair (X) of pre-rolling elements positioned at the final pre-rolling zone, those values being respectively (Px) and (Gx), compares those values with pre-set threshold values and configures the disposition of all the pairs of pre-rolling elements included on the path of extraction on the basis of that comparison.

5. Method as in claim 4, in which if the closure force (P_x) is greater than the value of the maximum pre-set threshold (P_1) the data processing and controlling unit (21) displaces the final pre-rolling zone to the pair of rolls ($X-1$) positioned immediately upstream and repeats the operation n times until (P_x) (pass n) $\leq (P_1)$ is obtained.

6. Method as in claim 5, in which if the closure force (P_x) is less than the value of the minimum pre-set threshold (P_2), the data processing and controlling unit (21) displaces the final pre-rolling zone to the pair of rolls ($X+1$) positioned immediately downstream and repeats the operation n times until (P_2) $\leq (P_x)$ (pass n) $\leq (P_1)$ is obtained.

7. Method as in claim 6, in which ($P_1=P_2$).

8. Method as in claim 4, in which if the gap (G_x) is greater than the pre-set value (G_1) increased by a pre-set value of tolerance (D), the data processing and controlling unit (21) displaces the final pre-rolling zone to the pair of rolls ($X-1$) positioned immediately upstream and repeats the operation n times until (G_x) (pass n) $\leq (G_1) + (D)$ is obtained.

9. Method as in claim 8, in which the value of tolerance (D) is obtained as a percentage of the value of the relative gap (G).

10. Method as in claim 4, in which the reduction of the thickness of the slab is achieved in a travel which may vary from a minimum distance of 0.3 meters to a maximum distance of 14 meters starting from the outlet of the crystallizer.

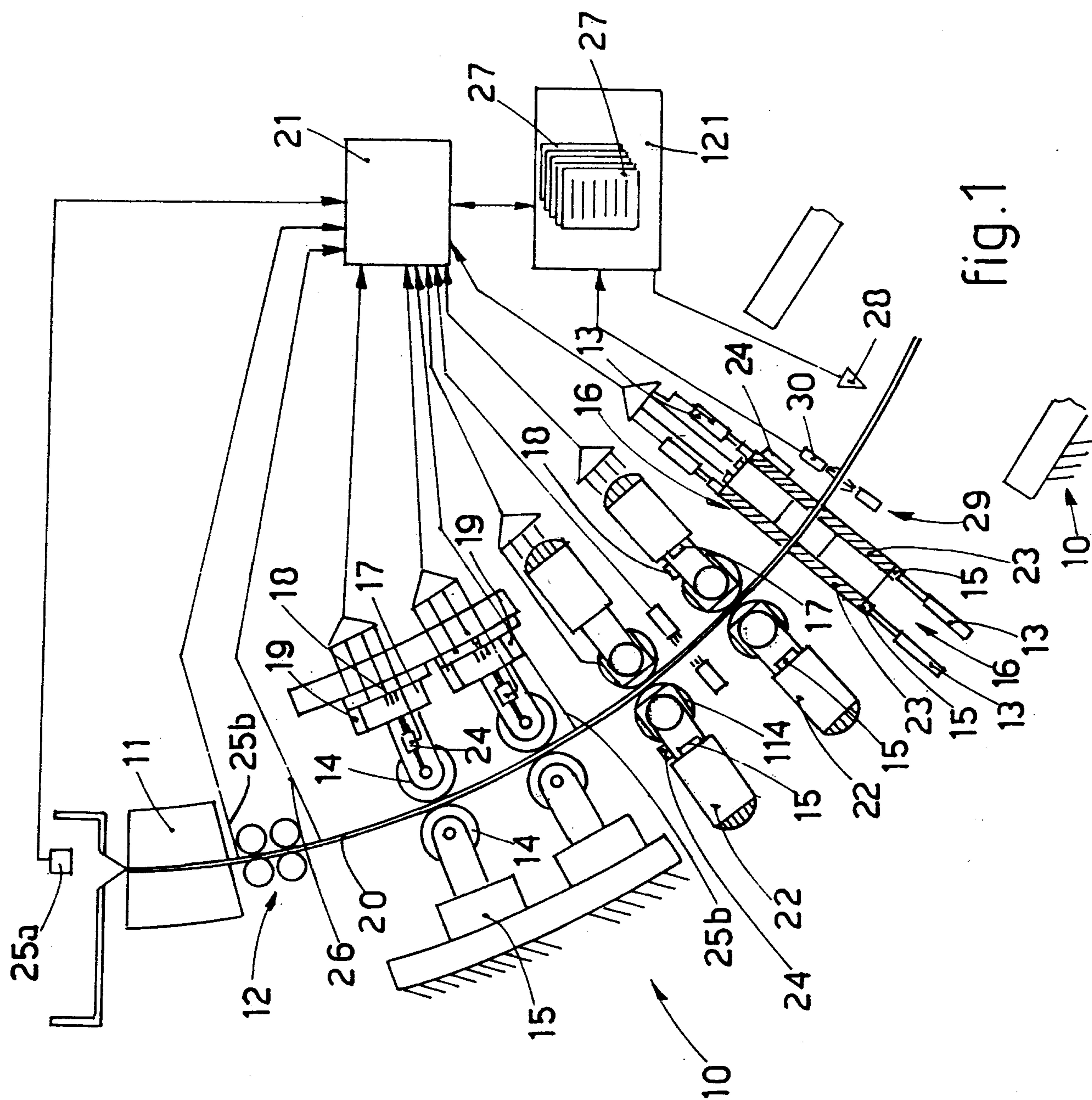


fig. 1

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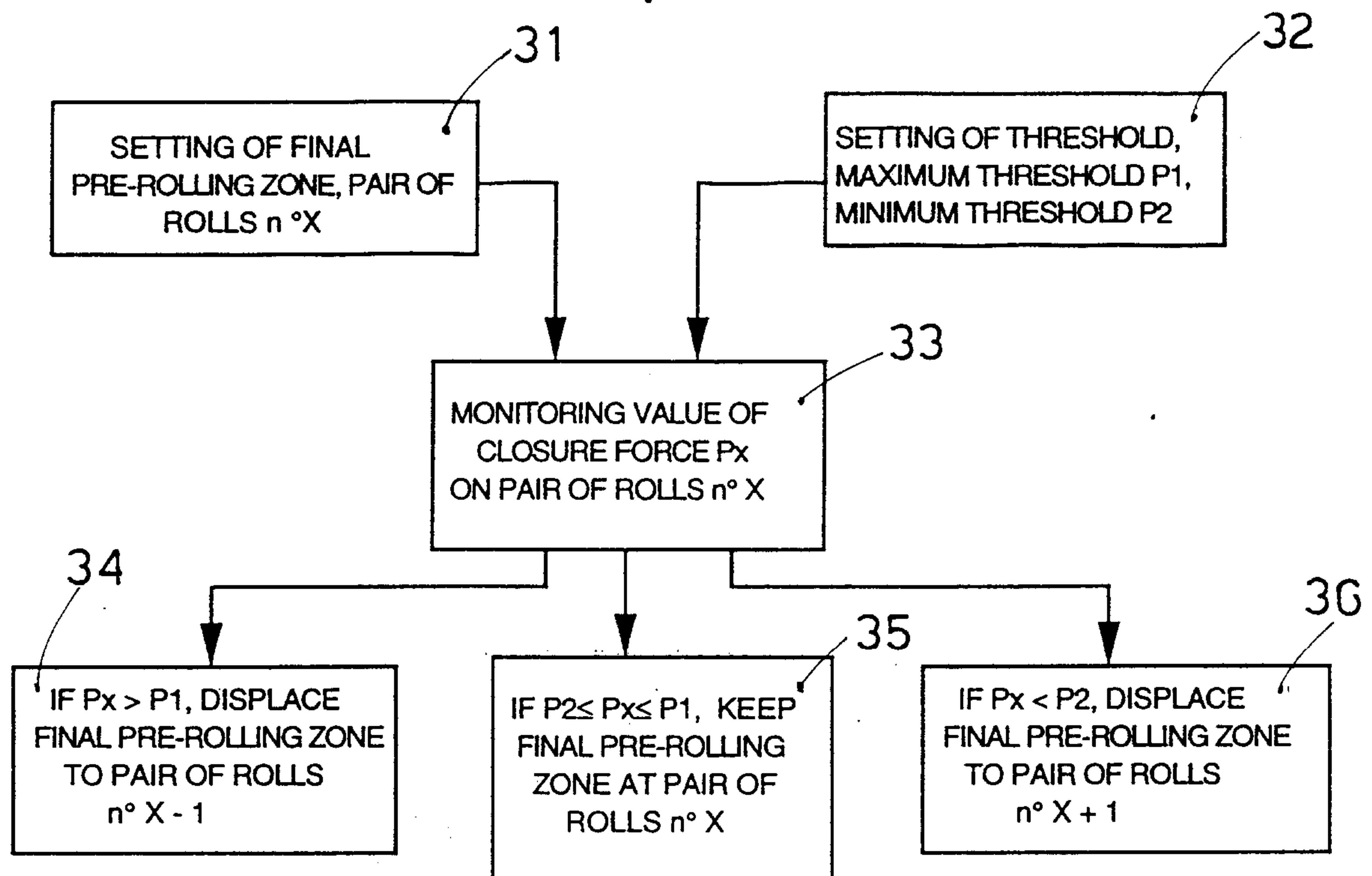


fig.2

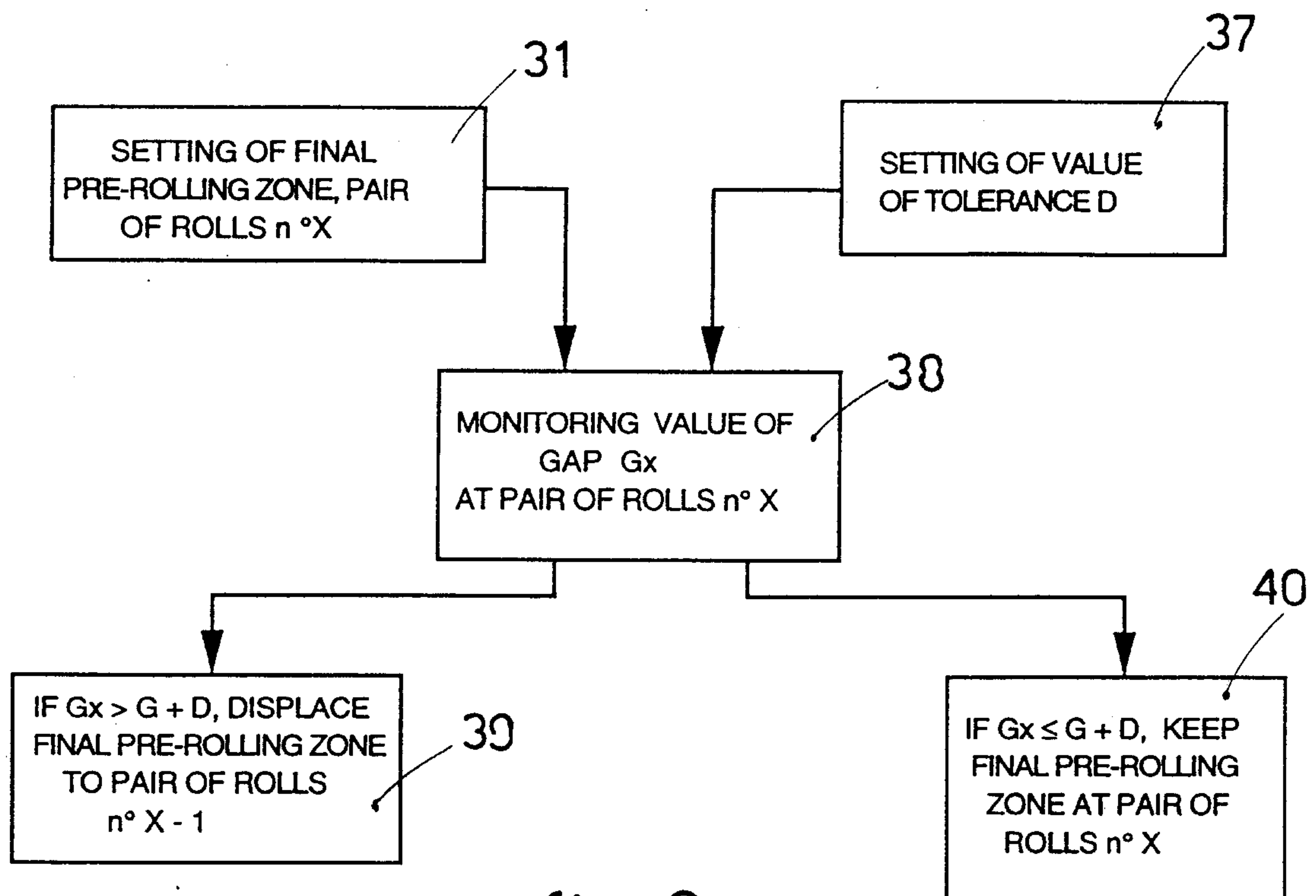


fig.3

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