

(12) INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(19) World Intellectual Property Organization International Bureau



(43) International Publication Date
11 November 2004 (11.11.2004)

PCT

(10) International Publication Number
WO 2004/096677 A1

(51) International Patent Classification⁷: **B65G 41/00** (74) Agent: FITZPATRICKS; 39 Stukeley Street, London WC2B 5LT (GB).

(21) International Application Number: PCT/GB2004/001922

(22) International Filing Date: 30 April 2004 (30.04.2004)

(25) Filing Language: English

(26) Publication Language: English

(30) Priority Data: 0310177.1 2 May 2003 (02.05.2003) GB

(71) Applicant (for all designated States except US): METSO MINERALS (CAPPAGH) LTD [GB/GB]; 55 Cappagh Road, Galbally, Dungannon, County Tyrone BT70 2PE (GB).

(72) Inventors; and

(75) Inventors/Applicants (for US only): MAKINEN, Marko, Kalevi [FI/FI]; Annalankatu 1 B 13, FIN-33710 Tampere (FI). WHYTE, Stephen, Alexander [GB/GB]; 22 Pinewood Avenue, Hospital Road, Omagh BT79 0DB (GB). ANTILA, Kari, Heikki, Olavi [FI/FI]; Korvenkatu 32 A 4, FIN-33300 Tampere (FI).

(81) Designated States (unless otherwise indicated, for every kind of national protection available): AE, AG, AL, AM, AT, AU, AZ, BA, BB, BG, BR, BW, BY, BZ, CA, CH, CN, CO, CR, CU, CZ, DE, DK, DM, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, HR, HU, ID, IL, IN, IS, JP, KE, KG, KP, KR, KZ, LC, LK, LR, LS, LT, LU, LV, MA, MD, MG, MK, MN, MW, MX, MZ, NA, NI, NO, NZ, OM, PG, PH, PL, PT, RO, RU, SC, SD, SE, SG, SK, SL, SY, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, YU, ZA, ZM, ZW.

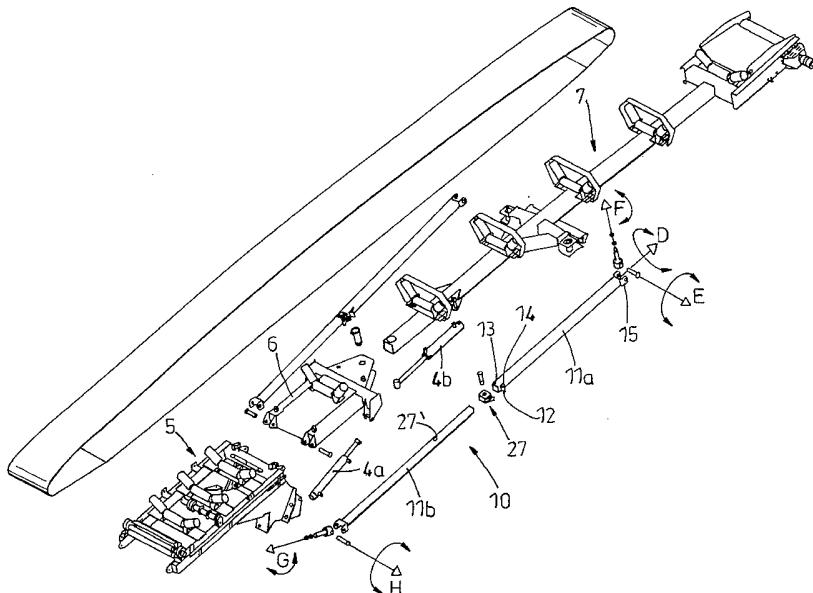
(84) Designated States (unless otherwise indicated, for every kind of regional protection available): ARIPO (BW, GH, GM, KE, LS, MW, MZ, NA, SD, SL, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European (AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IT, LU, MC, NL, PL, PT, RO, SE, SI, SK, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, ML, MR, NE, SN, TD, TG).

Published:

— with international search report

[Continued on next page]

(54) Title: SUPPORT MEANS FOR A LATERAL CONVEYOR ON A MOBILE CHASSIS



(57) **Abstract:** The invention relates to support means (10), which is for supporting a lateral conveyor adapted for mounting upon a mobile chassis, comprising a tail section (5), middle section (6) and at least one head section (7) having pivot points related to the conveyor frame separating said sections from each other. The support means comprises a variable length mounting arm (11a, 11b) comprising at least first (11a) and second sections (11b) and first and second ends, and means for locking the length of the mounting arm into at least one fixed length corresponding to the length of the conveyor in use. The first end is fixed immobile in relation to the mobile chassis and the second end is fixed immobile in relation to the head section of the conveyor.

WO 2004/096677 A1



- before the expiration of the time limit for amending the claims and to be republished in the event of receipt of amendments

For two-letter codes and other abbreviations, refer to the "Guidance Notes on Codes and Abbreviations" appearing at the beginning of each regular issue of the PCT Gazette.

Support MeansField of the invention

This invention relates to improvements in support means for supporting a lateral conveyor particularly adapted for mounting on a mobile, aggregate material processing plant such as screening plant, crushing plant or mining plant, and, more particularly, to improvements in the support arms for supporting a stowable lateral conveyor upon the plant.

Background of the invention

In this specification, the term "aggregate material" means different types of mined or quarried or natural mineral materials, like gravel, sand, ores, coal, different kinds of soil materials like loam and peat, different kinds of construction waste materials like concrete, bricks and asphalt as well as organic materials like timber wood chips, etc.

In this specification, the term "processing" of aggregate materials means feeding, shredding, crushing, screening, separating, washing and conveying of aggregate materials.

In aggregate material processing plant generally, processing capacity is heavily influenced by the ability to quickly and effectively deliver the processed material away from the plant. To achieve this, it is known to provide lateral conveyors which extend transversely of the plant, possibly in addition to longitudinal conveyors. While the manner in which the lateral conveyors are connected to the plant is relatively simple for the operating position, major problems arise in ensuring that the overall width and height of the mobile plant is within certain dimensions when carrying such conveyors during transport. Another problem is ensuring safety, on-site, in movement of the lateral conveyors to a

position for transport of the mobile plant. A further problem lies in the support of the lateral conveyors during operation and when travelling inside the worksite with the conveyors in the working position: the conveyors are subject to high 5 stresses due to their own weight, the weight of the screened material on the belt and vibrations caused by uneven and/or soft soil at the worksite. A still further problem is that of providing for easy and safe maintenance or repair of the lateral conveyors on-site or at a workshop.

10 EP 0641 607B describes a known mobile aggregate material processing plant comprising a chassis having a pair of longitudinal beams mounted on wheels and supported on jack legs.

15 The plant is provided with two lateral conveyors each of which comprises a tail section a middle section and a head section. The head section delivers processed material to form a stockpile of material. The conveyors are folded from the working position to the transport position by a pair of hydraulic rams. In the working position the conveyor is 20 supported on the chassis by a support extending between the middle section and the tail section of the conveyor, the tail section being fixed to the chassis of the mobile plant. The head section of the conveyor is left unsupported.

25 The amount of material which can be processed by the plant is determined in part by the length of the lateral conveyors. The longer the conveyors are the higher and bigger in volume the stockpiles can be and the less you have to reserve resources for transferring the material away from the machine's stockpiles. In some instances, only one feeding machine; e.g. 30 a wheel loader, is used for both feeding the machine and removing the processed material from the stockpiles. The bigger the stockpiles are the more freedom for planning the feeding/removing work and the less unplanned breaks have to be included in the job.

The dimensions of the conveyors in the transport position are limited by the permissible transport dimensions of the machine, as regulated in the road transport regulations. Neither the conveyors nor their supports, nor any other part of 5 the plant is allowed to exceed these dimensions. If, for example, the chassis is dimensioned to be exactly within the permissible transport width, then the conveyors and their supports must not project laterally beyond the chassis.

EP 0641 607B provides a good solution for folding the 10 lateral conveyors from a working position to transport position making it possible firstly to fold the middle section around the first axis being substantially parallel to the longitudinal axis of the chassis of the plant and secondly to fold the head section around the second axis substantially parallel to the 15 lateral axis of the chassis of the plant, and back. So far, it has been a problem, to easily and effectively support such foldable conveyors.

In EP 0641 607B the path of the head section of the 20 conveyor from the working position to the transport position is relatively complicated. So far it has not been possible to provide foldable support beams for the head section, which is easy to use and does not challenge the permissible transport dimensions of the plant. The manufacturers have had to settle with a foldable support beam extending between the middle 25 section and the tail section of the conveyor, as the path of middle section from the working position to the transport position is much simpler than that of the head section. Anyhow, this sort of support leaves the head section unsupported, which makes the conveyors subject to high stresses due to their own 30 weight, the weight of the screened material on the belt and vibrations caused by uneven and/or soft soil at the worksite while working or travelling inside the worksite with the conveyors in the working position.

Manufacturers and users of such plants have tried to solve the problem by extending the length of the middle section of the conveyor to provide a better support with foldable support beams. However, this would challenge the transportation height 5 of the plant. Also detachable, non-foldable, supports between the conveyor's head section and the plant chassis and/or the ground have been used: these have proved to be difficult to use or even dangerous in situations where the support has detached itself accidentally.

10 A still further problem is that of providing for easy and safe maintenance or repair of the lateral conveyors on-site or at a workshop. Head sections often include some parts requiring maintenance, like motor, bearings, belt scraper, safeguarding etc. A safe way of reaching these parts has proved illusive as 15 they are quite high and ground in the worksite is usually soft or uneven, which makes it dangerous to work using ladders. More safe equipment helping the service people to reach high is not often available in the worksites.

It is an object of the present invention to provide a 20 mobile aggregate processing plant which can support lateral conveyors of a greater length than is currently possible with known plant, such as described above in relation to EP 0641607B.

Additionally, it is a further object of the present 25 invention to provide a safe and easy to use support means for a lateral conveyor of an aggregate processing plant which allows the lateral conveyor to be stowed in a transit position within permissible dimensions.

Further, it is an added object of the present invention to 30 provide a support means for a lateral conveyor or an aggregate processing plant which allows the head section of the lateral conveyor to be accessed from the ground for easy maintenance and repair thereof.

Summary of the invention

According to a first aspect of the present invention, there is provided a support means for supporting a lateral conveyor adapted for mounting upon a mobile chassis, said conveyor comprising of tail section, middle section and at least one head section having pivot points related to the conveyor frame separating said sections from each other, said support means comprising a variable length mounting arm, said mounting arm comprising at least two sections and first and second ends, means for locking the length of the mounting arm into at least one fixed length corresponding to the length of the conveyor in the working position, the first end being fixed to said mobile chassis or a part fixed immobile in relation to said mobile chassis and the second end being fixed to the said head section of the conveyor or a part fixed immobile in relation to the said head section of the conveyor, the support means being configured to provide at least three kinematic pairs, in which a first kinematic pair is formed by the first section of the mounting arm and the mobile chassis, a second kinematic pair is formed by the first and second sections of the mounting arm, and the third kinematic pair is formed by the second section of the mounting arm and the head section of the conveyor and is provided by a joint, the support means being further configured such that the first kinematic pair provides for two degrees of freedom of movement, the second kinematic pair provides for one degree of freedom of movement, and the third kinematic pair provides for three degrees of freedom of movement.

More specifically, the support means may be configured such that both the first and third kinematic pairs provide for three degrees of freedom of movement.

Alternatively or in addition, the two degrees of freedom of movement of the first kinematic pair may be provided by a

further joint between the first section of the mounting arm and the mobile chassis.

More specifically, the further joint may comprise a pivot mounting shaft and a swivel mounting shaft, whereby the 5 mounting arm may be elevated in a one plane by pivoting upon the pivot mounting shaft and traversed in another plane by swivelling on the swivel mounting shaft.

Alternatively or in addition, the degree of freedom of movement of the second kinematic pair may be provided by 10 configuring the first and second sections for sliding in relation to each other.

Alternatively or in addition, the degree of freedom of movement of the second kinematic pair may be provided by configuring the first and second sections for substantially 15 linear movement in relation to each other.

More specifically, the second section may move substantially in a direction of its longitudinal axis.

Alternatively or in addition, the three degrees of freedom of movement of the third kinematic pair may be provided by the 20 joint comprising a pivot mounting shaft, a swivel mounting shaft, and a rotational mounting shaft, whereby the mounting arm may be elevated in a first plane by pivoting upon the pivot mounting shaft and traversed in a second plane by swivelling on the swivel mounting shaft, and rotated about its longitudinal 25 axis on the rotational mounting shaft.

More specifically, the first and second planes may be perpendicular.

More specifically, the longitudinal axis of the second section may be substantially parallel to a line of intersection 30 of said planes.

Alternatively or in addition, one of the first and second sections may be located within the other to allow for telescopic length adjustment of the mounting arm.

More specifically, the mounting arm may comprise a hydraulic cylinder.

Alternatively or in addition, the mounting arm may comprise three sections, in which the degree of freedom of 5 movement of the second kinematic pair is provided between at least a first and second section and between the second and a third section.

Alternatively or in addition, the support means may further comprise means for locking the length of the variable 10 length mounting arm into a fixed length corresponding to the length of the conveyor in the transport position and/or service position.

Alternatively or in addition, the head section of the conveyor may consist of at least two separate sections 15 pivotable to each other, the first of the said head sections being supported to said mobile chassis or a part fixed immobile in relation to said mobile chassis with said variable length arm.

Alternatively or in addition, one end of the mounting arm 20 may be connected to a tail section of the conveyor and the other end of the mounting arm may be connected to a head section of the conveyor.

Alternatively or in addition, a collar and a locking pin may be provided to fix the length of the support to correspond 25 to the working position of the conveyor, preferably also to the transport position and to the maintenance position.

By enabling the support means to move in this manner, greater flexibility of positioning and movement of the support means may be available and therefore the length of the support 30 means can be extended in comparison to prior art plant whilst still allowing the support means to lie within the permissible dimensions of the plant when the conveyor is in a transit position. Furthermore, as the length of the support means can be increased from the known plant, the length of the conveyor

itself can be increased thereby allowing for a higher stockpile and higher capacity of the plant.

Alternatively or in addition, the mounting arm may comprise a box section which may be formed of metal or any 5 suitable material. The box section may be extruded or may be cast or may be cut from hollow or even open section in the required lengths.

Alternatively or in addition, the support means may be formed of mild steel.

10 In a form of the aspect of the invention, a C-shaped bracket comprising a top face, a bottom face and a back plate extending between the top and bottom plates may be mounted on at least one end of the mounting arm, through the rotational mounting shaft.

15 More specifically, the top and bottom faces of the C-shaped bracket may be substantially parallel and the back plate may extend substantially perpendicularly to the top and bottom faces.

20 Alternatively or in addition, bearing means may be provided between the end face of the mounting arm and the back plate of the bracket.

Alternatively or in addition, bearing means may be provided between all gliding surfaces.

25 Alternatively or in addition, an aperture may be provided in each of the top and bottom faces of the C-shaped bracket, said apertures being aligned along a common axis through the bracket.

30 Alternatively or in addition, the swivel mounting shaft may be provided with a through bore and said swivel mounting shaft may be mounted within the C-shaped bracket such that the bore is aligned with the apertures in the top and bottom face of the bracket.

Alternatively or in addition, the pivot mounting shaft may extend through the apertures in the top and bottom faces of the

C-shaped bracket and the bore of the swivel mounting shaft to lock the swivel mounting shaft in position within the bracket.

Fine adjustment of the length of the mounting arm may provide for adjustment of tracking of a conveyor belt carried 5 upon the lateral conveyor. Such tracking adjustment can be carried out from ground level whilst the conveyor is operating thereby avoiding downtime of the plant and subsequent loss of production.

Alternatively or in addition, the present aspect of the 10 invention may comprise one or more features of one or more of the other aspects of the present invention.

According to a second aspect of the present invention, there is provided a support means for supporting a lateral conveyor adapted for mounting upon a mobile chassis, said 15 conveyor comprising of tail section, middle section and at least one head section having pivot points related to the conveyor frame separating said sections from each other, said support means comprising a variable length mounting arm, said mounting arm comprising at least two sections and first and 20 second ends, means for locking the length of the mounting arm into at least one fixed length corresponding to the length of the conveyor in the working position, the first end being fixed to said mobile chassis or a part fixed immobile in relation to said mobile chassis and the second end being fixed to the said 25 head section of the conveyor or a part fixed immobile in relation to the said head section of the conveyor, the support means being configured to provide at least three kinematic pairs, in which a first kinematic pair is formed by the first section of the mounting arm and the mobile chassis and is 30 provided by a joint, a second kinematic pair is formed by the first and second sections of the mounting arm, and the third kinematic pair is formed by the second section of the mounting arm and the head section of the conveyor, the support means being configured such that the first kinematic pair provides

for three degrees of freedom of movement, the second kinematic pair provides for one degree of freedom of movement, and the third kinematic pair provides for two degrees of freedom of movement.

5 More specifically, the third kinematic pair may be provided by a further joint between the second section of the mounting arm and the head section of the conveyor.

Alternatively or in addition, the further joint may comprise a pivot mounting shaft and a swivel mounting shaft, 10 whereby the mounting arm may be elevated in a one plane by pivoting upon the pivot mounting shaft and traversed in another plane by swivelling on the swivel mounting shaft.

Alternatively or in addition, the three degrees of freedom of movement of the first kinematic pair may be provided by the 15 joint comprising a pivot mounting shaft, a swivel mounting shaft, and a rotational mounting shaft, whereby the mounting arm may be elevated in a first plane by pivoting upon the pivot mounting shaft and traversed in a second plane by swivelling on the swivel mounting shaft, and rotated about its longitudinal 20 axis on the rotational mounting shaft.

The second aspect of the present invention may comprise one or more features described above with reference to the first aspect of the present invention.

According to a third aspect of the present invention, 25 there is provided a support means for supporting a lateral conveyor adapted for mounting upon a mobile chassis, said conveyor comprising of tail section, middle section and at least one head section having pivot points related to the conveyor frame separating said sections from each other, said support means comprising a variable length mounting arm, said mounting arm comprising at least two sections and first and second ends, means for locking the length of the mounting arm into at least one fixed length corresponding to the length of the conveyor in the working position, the first end being fixed

to said mobile chassis or a part fixed immobile in relation to said mobile chassis and the second end being fixed to the said head section of the conveyor or a part fixed immobile in relation to the said head section of the conveyor, the support 5 means being configured to provide at least three kinematic pairs, in which a first kinematic pair is formed by the first section of the mounting arm and the mobile chassis, a second kinematic pair is formed by the first and second sections of the mounting arm, and the third kinematic pair is formed by the 10 second section of the mounting arm and the head section of the conveyor and is provided by a joint, the support means being further configured such that the first kinematic pair provides for two degrees of freedom of movement, the second kinematic pair provides for two degrees of freedom movement, and the 15 third kinematic pair provides for two degrees of freedom of movement.

More specifically, the two degrees of freedom of movement of the first kinematic pair may be provided by a further joint between the first section of the mounting arm and the mobile 20 chassis.

More specifically, the further joint may comprise a pivot mounting shaft and a swivel mounting shaft, whereby the mounting arm may be elevated in a one plane by pivoting upon the pivot mounting shaft and traversed in another plane by 25 swivelling on the swivel mounting shaft.

Alternatively or in addition, the two degrees of freedom of movement of the second kinematic pair may be provided by configuring the first and second sections for rotation and sliding in relation to each other.

30 More specifically, the second section may be rotated about its longitudinal axis and moved substantially in a direction of its longitudinal axis.

Alternatively or in addition, the two degrees of freedom of movement of the third kinematic pair may be provided by the

joint comprising a pivot mounting shaft and a swivel mounting shaft, whereby the mounting arm may be elevated in a first plane by pivoting upon the pivot mounting shaft and traversed in a second plane by swivelling on the swivel mounting shaft.

5 More specifically, the first and second planes may be perpendicular.

More specifically, the longitudinal axis of the second section may be substantially parallel to a line of intersection of said planes.

10 Alternatively or in addition, one of the first and second sections may be located within the other to allow for telescopic length adjustment of the mounting arm.

More specifically, the mounting arm may comprise a hydraulic cylinder.

15 Alternatively or in addition, co-located portions of the first and second sections may be of substantially circular cross-section.

20 Alternatively or in addition, the mounting arm may comprise three sections, in which a first degree of freedom of movement is provided between a first and second section and a second degree of freedom of movement is provided between the second and a third section.

25 More specifically, the mounting arm may be configured such that the first degree of freedom of movement is sliding of the first and second sections in relation to each other and the second degree of freedom of movement is rotation of the second and third sections in relation to each other.

30 Alternatively, the mounting arm may be configured such that the first degree of freedom of movement is rotation of the first and second sections in relation to each other and the second degree of freedom of movement is sliding of the second and third sections in relation to each other.

More specifically, the support means may be configured such that at least one of the first and third kinematic pairs provides for three degrees of freedom of movement.

Alternatively or in addition, the third aspect of the 5 invention may comprise one or more features of the first aspect of the present invention.

According to a fourth aspect of the present invention there is provided a mobile chassis comprising a lateral conveyor mounted thereon and a support means for supporting a 10 lateral conveyor according to any one of the first to third aspects of the present invention.

More specifically, said mobile chassis is a mobile aggregate processing plant. The chassis may be, for example, wheel- or track-mounted.

15 According to a fifth aspect of the present invention, there is provided a support means for supporting a lateral conveyor adapted for mounting upon a mobile chassis, said conveyor comprising of tail section, middle section and at least one head section having pivot points related to the 20 conveyor frame separating said sections from each other, said supporting means comprising a variable length mounting arm, said mounting arm comprising a first end and a second end, means for locking the length of the variable length mounting arm into at least one fixed length corresponding to the length 25 of the conveyor in the working position, one end being fixed to said mobile chassis or a part fixed immobile in relation to said mobile chassis, said other end of the mounting arm being fixed to the said head section of the conveyor or a part fixed immobile in relation to the said head section of the conveyor 30 via a joint allowing three degrees of freedom of movement of the mounting arm with respect to the head section of the conveyor.

More specifically, said one end of the mounting arm may be connected to said mobile chassis or a part fixed immobile in

relation to said mobile chassis with a joint allowing at least two degrees of freedom of movement.

Alternatively or in addition, the support means may further comprise means for locking the length of the variable 5 length mounting arm into fixed length corresponding to the length of the conveyor in the transport position and/or service position.

Alternatively or in addition, the head section of the conveyor may consist of at least two separate sections 10 pivotable to each other, the first of the said head sections being supported to said mobile chassis or a part fixed immobile in relation to said mobile chassis with said variable length arm.

Alternatively or in addition, said joint having three 15 degrees of freedom of movement may comprise a pivot mounting shaft, a swivel mounting shaft, and a rotational mounting shaft, whereby the mounting arm may be elevated in a first plane by pivoting upon the pivot mounting shaft, and traversed in a second plane by swivelling on the swivel mounting shaft, 20 and rotated about its longitudinal axis on the rotational mounting shaft.

Preferably, the mounting arm may be formed of two sections, one being located within the other to allow for telescopic length adjustment of the mounting arm. 25 Advantageously, one end of the mounting arm may be connected to a tail section of the conveyor and the other end of the mounting arm may be connected to a head section of the conveyor.

The fifth aspect of the invention may comprise one or more 30 features of any one of the first to fourth aspects of the invention.

According to a sixth aspect of the present invention, there is provided a support means for supporting a lateral conveyor adapted for mounting upon a mobile chassis, said

conveyor comprising of tail section, middle section and at least one head section having pivot points related to the conveyor frame separating said sections from each other, said support means comprising a variable length mounting arm, said 5 mounting arm comprising a first end and a second end, means for locking the length of the variable length mounting arm into at least one fixed length corresponding to the length of the conveyor in the working position, one end being fixed to said mobile chassis or a part fixed immobile in relation to said 10 mobile chassis, said other end of the mounting arm is fixed to the said head section of the conveyor or a part fixed immobile in relation to the said head section of the conveyor via a joint allowing first and second degrees of freedom of movement of the mounting arm with respect to the head section of the 15 conveyor, the mounting arm comprising a first section towards the mobile chassis and a second section towards the head section, the first and second sections being configured for their relative movement to provide a third degree of freedom of movement of the first section of the mounting arm with respect 20 to the head section of the conveyor.

More specifically, the third degree of freedom of movement may be provided by configuring the first and second sections for rotation in relation to each other, whereby the second section may be rotated about its longitudinal axis.

25 Alternatively or in addition, the joint having two degrees of freedom of movement may comprise a pivot mounting shaft and a swivel mounting shaft, whereby the mounting arm may be elevated in a first plane by pivoting upon the pivot mounting shaft and traversed in a second plane by swivelling on the 30 swivel mounting shaft.

Alternatively or in addition, the first and second sections may be further configured for their relative movement to provide a fourth degree of freedom of movement of the first

section of the mounting arm with respect to the head section of the conveyor.

More specifically, the fourth degree of freedom of movement may be provided by configuring the first and second 5 sections for sliding movement in relation to each other.

More specifically, one of the first and second sections may be located within the other to allow for telescopic length adjustment of the mounting arm.

More specifically, co-located portions of the first and 10 second sections may be of substantially circular cross-section.

Alternatively or in addition, the sixth aspect of the invention may comprise one or more features of any of the other aspects of the invention.

15 According to a seventh aspect of the present invention, there is provided a support means for supporting a lateral conveyor adapted for mounting upon a mobile chassis, said conveyor comprising of tail section, middle section and at least one head section having pivot points related to the 20 conveyor frame separating said sections from each other, said supporting means comprising a variable length mounting arm, said mounting arm comprising a first end and a second end, means for locking the length of the variable length mounting arm into at least one fixed length corresponding to the length 25 of the conveyor in the working position, one end being fixed to the said head section of the conveyor or a part fixed immobile in relation to the said head section of the conveyor, said other end of the mounting arm being fixed to said mobile chassis or a part fixed immobile in relation to said mobile 30 chassis via a joint allowing three degrees of freedom of movement of the mounting arm with respect to the head section of the conveyor.

The seventh aspect of the invention may comprise one or more features of any of the other aspects of the invention.

According to an eighth aspect of the present invention there is provided a support means for supporting a lateral conveyor adapted for mounting upon a mobile chassis, said conveyor comprising of tail section, middle section and at 5 least one head section having pivot points related to the conveyor frame separating said sections from each other; said supporting means comprising a variable length mounting arm said mounting arm comprising a first end and a second end means for locking the length of the variable length mounting arm into at 10 least one fixed length corresponding to the length of the conveyor in the working position one end being fixed to said mobile chassis or a part fixed immobile in relation to said mobile chassis characterised in that said other end of the mounting arm is fixed to the said head section of the conveyor 15 or a part fixed immobile in relation to the said head section of the conveyor and adjustment means are provided to finely alter the length of the mounting arm when locked into the at least one fixed length.

The eighth aspect of the present invention may comprise 20 one or more features of any of the other aspects of the invention.

Embodiments of the present invention will now be described with reference to and as shown in the accompanying drawings in which:

25

Figure 1 is a schematic view of a known processing plant according to the prior art which illustrates a known support means for a lateral conveyor mounted on the chassis of the plant;

30

Figure 2 is an exploded view of a lateral conveyor including a support means according to an embodiment of the present invention;

Figure 3 is an enlarged schematic side view of one end of the section of the mounting arm shown in Figure 2;

5 Figure 4 is an enlarged schematic side view of the other end of the mounting arm of Figure 2;

Figure 5 is schematic view of the conveyor and support of Figure 2 showing the folding axis of the conveyor,

10 Figure 6 is a schematic view of the collar locking the length of the mounting arm and the adjustment means provided thereon, and

15 Figure 7 is an exploded view of a lateral conveyor including a support means according to another embodiment of the present invention;

Figure 8 is an enlarged schematic side view of one end of the section of the mounting arm shown in Figure 7; and

20 Figure 9 is an enlarged schematic side view of the other end of the mounting arm of Figure 7.

Modes for Carrying out the invention

25 Turning now to the Figures, there is shown in Figure 1 a known mobile aggregate processing plant 1 which comprises a chassis 2 upon which a pair of lateral conveyors 3 are mounted. The plant comprises a screen (not shown) which distributes the 30 screened material on to the lateral conveyors 3. The plant is shown in Figure 1 in an end elevation in order to clearly show the lateral conveyors 3 which are mounted on either side of the chassis 2 of the plant.

Hydraulic rams 4 are operated to extend the conveyors from a stowed position adjacent the chassis for transport to the operating position shown in Figure 1. The lateral conveyors comprise a tail section 5 adjacent to the chassis 2, a middle section 6 and a head section 7 remote from the chassis 2. The head section of the conveyor is mounted to the middle section through a pivot point P1 such that the head section can pivot around the pivot point as shown by axis A in figure 1. Processed material passes along the lateral conveyors from the tail section to the head section and exits the head section to form a stock pile 8 under the head section. The middle section of the conveyor is supported against the tail section of the conveyor, which is immobile in relation to the chassis. The middle section is pivotally connected to the tail section through pivot point P2 such that the middle section can be folded towards the chassis 2 in the direction of Arrow B.

The lateral conveyors are supported on the chassis of the plant by support means 9 (only one of which is shown in Figure 1 for clarity) which are mounted to the tail section and middle section of the conveyor respectively. The tail section of the conveyor is, in turn, firmly mounted to the chassis.

Figure 2 shows an exploded view of a lateral conveyor of the type described above in relation to the prior art but with a support means according to one aspect of the present invention. The support means 10 for the lateral conveyors of the present invention is in the form of a mounting arm 11a, 11b formed of a box section of mild steel. This may be extruded or cast to the appropriate lengths as required or may be a hollow section if preferred. A lateral flange 12 is provided adjacent one end 13 of the mounting arm 11a. Triangular support brackets 14 are formed under the flange 12 between the underside of the flange and the mounting arm 11a.

The other end of the mounting arm, remote from the flange 12 is mounted to a C-shaped bracket 15 through a rotational

mounting shaft **16** shown in more detail in Figure 3. This allows the mounting arm **11a** to rotate around axis D shown in Figure 2 with respect to the bracket **15**. The C-shaped bracket has a substantially flat top face **17** and a substantially flat 5 bottom face **18** and a back plate **19** extending between the two. The top face and bottom face of the bracket are provided with apertures **20** which are aligned on a common axis of the bracket.

The rotational mounting shaft **16** passes through corresponding aperture (not shown) in the back plate **19** of the 10 bracket and the end face **21** of the mounting arm such that the mounting arm can rotate around its longitudinal axis upon the rotational mounting shaft. A bearing (not shown) may be provided between the end face **21** of the mounting arm and the back plate **19** of the bracket in order to facilitate rotation of 15 the mounting arm.

The means for attaching the mounting arm **11a** to the conveyor is shown in detail in Figure 3. This shows the end of the mounting arm **11a** with the C-shaped bracket **15** attached thereto. A swivel mounting shaft **22** is provided to facilitate 20 traversing of the mounting means around axis F in Figure 2 and comprising a cylindrical shaft member **23** which is attached to the conveyor's head section at one end and is provided with a head section **24** at the distal end, the head section having a greater diameter than the shaft.

25 The head section **24** of the cylindrical shaft member is dimensioned to be mounted between the top and bottom faces **17**, **18** of the C-shaped bracket **15** and is provided with a through bore **25** which is aligned with the apertures **20** in the top and bottom faces of the bracket when the head section **24** is 30 presented to the bracket.

A pivot mounting shaft **26** extends through the apertures **20** and the through bore **25** to retain the head section **24** of the swivel mounting means within the bracket **15**. The pivot mounting shaft **26** facilitates elevation of the mounting arm **11a**

around axis E shown in Figure 2 by allowing the bracket 15 to pivot around the shaft 26. Bearings (not shown) may be provided between the head section 24 of the swivel mounting shaft 22 and the top and bottom faces 17, 18 of the bracket.

5 The articulated joint between the head section 7 and the mounting arm 11a, as described above, provides three degrees of freedom.

Figure 4 shows a schematic view of the connection of the mounting arm 11b to the tail section 5 of the conveyor. The 10 distal end of the lower section 11b of the mounting arm is provided with an articulated joint having at least two degrees of freedom. The lower section 11b of the mounting arm is mounted to the chassis through the swivel mounting shaft 22b of the lower articulated joint which is similar to the joint 15 connecting the upper section of the mounting arm 11a to the head section 7. Mounting arm 11b can rotate with the swivel mounting shaft 22b around axis G shown in Figure 2 and can pivot about the pivot mounting shaft 26b around axis H shown in Figure 2.

20 A further rotational mounting shaft may be provided between the end of the mounting arm 11b and the C-shaped bracket 15b to allow for a further rotation of the mounting arm 11b with respect to the bracket 15b. This would provide the joint between the tail section and the mounting arm 11b with a 25 third degree of freedom, which is acceptable but not necessary for carrying out the invention.

Hydraulic cylinders 4 are mounted between the tail section 5 and the middle section 6 and the middle section 6 and the head section 7 of the lateral conveyors 3 for extending the 30 conveyors between the operating and the stowed or transit positions. A first hydraulic cylinder 4a acts to extend the conveyor out from the chassis around axis I shown in Figure 5, and a second hydraulic cylinder 4b is used to fold the head section of the conveyor back towards the chassis around axis J

shown in Figure 5 during transfer from the operating to the transit position as will be described in more detail below.

A collar 27 is provided between the free ends of the mounting arms 11a and 11b as shown in detail in Figure 6. The 5 collar is provided with apertures (not shown) which align with apertures 27' in the mounting 11b, one of which is shown in Figure 2.

A pin 28 is provided through the apertures in the collar and the mounting arm 11b. The collar is provided with a 10 lateral flange 29 of similar dimensions to the lateral flange 12 of the upper mounting arm section 11a and is also provided with triangular brackets 30 similar to the brackets 14 described above. The flange 29 is provided with threaded aperture (not shown) to receive a locking member 31 which is 15 held in position by a threaded nut 32 or other suitable locking means. The collar surrounds the free end of mounting arm section 11b and is fixed thereto with pin 28. The free end of mounting arm section 11a rests on the collar as a result of gravity.

20 In use of the plant, during operation the lateral conveyors are supported on the chassis in an extended position. In the event that the tracking of the belt upon the conveyor requires adjustment during use, the threaded nut 32 is loosened and the locking bolt 31 is turned either to increase or to 25 decrease the distance between the flanges 12 and 29 in order to provide fine adjustment of the length of the arm. It is an advantage of the present invention that adjustment of the tracking of the belt can occur during use of the conveyor 3 from a position remote from the head section of the conveyor as 30 this does not require the head section of the conveyor to be lowered to the ground nor are personnel required to stand in the vicinity of the stock pile 8 under the head section 7 of the conveyor where injuries could occur from falling material

or close to the running belt, which always creates a hazard of drawing-in.

When operation of the plant is completed and the chassis 2 is to be moved to a new location, the lateral conveyors 3 are 5 moved from the operating position when they extend outboard of the chassis to a stored or transit position inboard of the chassis. Nut 32 and the locking bolt 31 are loosened and stopper pin 28 is removed from the apertures in the collar to allow the lower section of the mounting arm 11b to be 10 telescopically received within the upper section of the mounting arm 11a. Hydraulic valves (not shown) are opened to operate the first hydraulic cylinder 4a to fold up the middle section of the conveyor 3 and the second hydraulic cylinder 4b to fold the head section 7 of the conveyor sideways.

15 As the conveyor is lowered towards the ground the mounting arm 11 pivots around the pivot mounting shaft. As the head section is folded towards the middle of the conveyor, the mounting arm swivels on the swivel mounting shaft. During this operation, the length of the mounting arm telescopically alters 20 and the collar and pin are used to lock the length of the mounting arm at the desired length. Furthermore, during this operation, the C-shaped member rotates on the rotational mounting shaft with respect to the mounting arm.

25 The conveyor may be extended through the first plane and then traversed through the second plane, or this order can be reversed, or alternatively, both movements may occur simultaneously.

Once the conveyor is in the transport position, it may be locked in this position by replacement of the pin 28. In the 30 event that service or maintenance of the head section is required, the head section can be folded down without moving the conveyor into the transport position. As with the transport position, the head section may be locked in the

service position by replacement of the stopper pin as described above.

A variable length support means having an articulated joint with 3 degrees of movement in one end and at least 2 degrees of movement in the other end as described above allows for a longer mounting arm to be used than was possible with prior art conveyors as the longer mounting arm of the present invention can still be accommodated within the dimensions of the chassis of the plant when the conveyor is in the transport position. As a longer mounting arm can be used, therefore a longer conveyor can be supported upon the chassis of the plant. Use of a longer conveyor enables a greater capacity of material to be processed during operation of the plant. Furthermore, the load on the conveyor is spread along a greater length of the conveyor frame and provides a more stable plant than was previously available which is not as susceptible to unfavorable working conditions such as soft or uneven ground of the worksite causing extensive vibration.

As described above, the tracking of the belt of the conveyor can be adjusted during operation. This is a significant advantage over prior art conveyors where the tracking is adjusted by altering the position of the belt on rollers within the head section of the conveyor which has to be done by lowering the head section to ground level. Such an operation could only take place during an interruption of the processing operation.

Whilst the present invention has been described as having a support member in the form of a mounting arm, it is envisaged that two such mounting arms will preferably be provided on the chassis to support a lateral conveyor.

Although the lateral conveyor has been described above as having three sections, a tail section, a middle section and a head section, it is envisaged that the head section of the

conveyor can also be divided into separate subsections pivotable with respect to each other.

The embodiment provides a joint between mounting arm 11a and the head section 7 of the conveyor with three degrees of freedom and a joint between mounting arm 11b and the tail section 5 of the conveyor with two degrees of freedom. Within the scope of the claims, these two types of joints can replace each other. Also both joints can provide three degrees of freedom.

10 The embodiment provides a support extending between the head section 7 of the conveyor and the tail section 5 of the conveyor. Within the scope of the claims, the support can also extend between the head section 7 of the conveyor and the chassis 2, or any part of the plant firmly mounted on the

15 chassis.

In addition, instead of hydraulic cylinder driving means other driving means may be used for example, hydraulic motors, pneumatic cylinders, pneumatic motors or electric motors with the necessary power transmission means. These driving means

20 are preferably double acting for forward and backward movement.

Figures 7 to 9 provide schematic views of a lateral conveyor including a support means according to another embodiment of the present invention. Most of the components of the embodiment of Figures 7 to 9 are the same as those of the

25 embodiment of Figures 2 to 4 and thus reference should be made to the description given above with reference to Figures 2 to 4. Here, differences between the embodiment of Figures 2 to 4 and the embodiment of Figures 2 to 4 will be described.

Figure 7 provides an exploded view of the lateral conveyor

30 including the support means according to the other embodiment. This embodiment provides for two degrees of freedom of movement in the connection of the mounting arm 11a to the head section 7 of the conveyor instead of the three degrees of freedom of movement of the previous embodiment. The two degrees of

freedom of movement are: elevation of the mounting arm **11a** around axis E by allowing the bracket **15** to pivot around the shaft **26**; and traversing of the mounting means around axis F by means of the swivel mounting shaft **22**. Figure 8 provides an 5 enlarged schematic side view of the end of mounting arm **11a** shown in Figure 7. It is not required of this embodiment that the mounting arm **11a** rotates around axis D. However, this embodiment may also be configured in the same way as the previous embodiment for rotation of the mounting arm **11a** around 10 axis D.

Turning to Figure 9, it can be seen that mounting arm **11b** is connected to the tail section 5 of the conveyer in the same way as the previous embodiment. The connection of Figure 9 provides for two degrees of freedom of movement in common with 15 the previous embodiment. In addition and in common with the previous embodiment, a further rotational mounting shaft may be provided between the end of the mounting arm **11b** and the C-shaped bracket **15b** to allow for a further rotation of the mounting arm **11b** with respect to the bracket **15b**. This 20 provides the joint between the tail section and the mounting arm **11b** with a third degree of freedom, which is acceptable but not necessary for carrying out the invention.

Returning now to Figure 7, a collar **40** is provided between the free ends of the mounting arms **11a** and **11b**. Although the 25 specific form of the collar **40** of this embodiment is different from the form of the collar **27** of the previous embodiment as described below, reference should be made to Figure 6 for a description of the corresponding component parts of the collar **40**. One of the two mounting arms **11a** and **11b** is received in 30 the other and provides for telescopic variation of the length of the support means **10**. As the co-locating ends **13** and **41** of the two mounting arms **11a** and **11b** are of substantially circular cross-section, the two mounting arms **11a** and **11b** are rotatable in relation to each other about axis D. The collar **40** is

configured to cooperate with the circular cross sections of the ends of the two mounting arms **11a** and **11b**. This means that in this embodiment, two degrees of freedom of movement are provided by the connection between mounting arms **11a** and **11b**, 5 whereas in the previous embodiment there is only one degree of freedom of movement, namely relative linear movement of the two mounting arms **11a** and **11b**.

Operation of the invention in accordance with this embodiment is the same as operation in accordance with the 10 previous embodiment. Thus, the reader is referred to the description given above in relation to the operation of the previous embodiment.

In summary, in this embodiment the connection between the mounting arm **11a** and the head section **7** provides for two 15 degrees of freedom of movement and the connection between the two mounting arms **11a** and **11b** provides for two degrees of freedom of movement. In the previous embodiment, the connection between the mounting arm **11a** and the head section **7** provides for three degrees of freedom of movement and the 20 connection between the two mounting arms **11a** and **11b** provides for one degree of freedom of movement.

Industrial Applicability

The support means of this invention finds use in the 25 aggregate material processing industry.

CLAIMS:

1. A support means for supporting a lateral conveyor adapted for mounting upon a mobile chassis,

5 said conveyor comprising of tail section, middle section and at least one head section having pivot points related to the conveyor frame separating said sections from each other,

said support means comprising a variable length mounting arm,

10 said mounting arm comprising at least two sections and first and second ends, means for locking the length of the mounting arm into at least one fixed length corresponding to the length of the conveyor in the working position,

15 the first end being fixed to said mobile chassis or a part fixed immobile in relation to said mobile chassis and the second end being fixed to the said head section of the conveyor or a part fixed immobile in relation to the said head section of the conveyor,

20 the support means being configured to provide at least three kinematic pairs, in which a first kinematic pair is formed by the first section of the mounting arm and the mobile chassis, a second kinematic pair is formed by the first and second sections of the mounting arm, and the third kinematic pair is formed by the second section of the mounting arm and 25 the head section of the conveyor and is provided by a joint,

the support means being further configured such that the first kinematic pair provides for two degrees of freedom of movement, the second kinematic pair provides for one degree of freedom of movement, and the third kinematic pair provides for 30 three degrees of freedom of movement.

2. The support means according to claim 1, in which the support means is configured such that both the first and third

kinematic pairs provide for three degrees of freedom of movement.

3. The support means according to claim 1 or 2, in which the
5 two degrees of freedom of movement of the first kinematic pair
are provided by a further joint between the first section of
the mounting arm and the mobile chassis.

4. The support means according to claim 3, in which the
10 further joint comprises a pivot mounting shaft and a swivel
mounting shaft, whereby the mounting arm may be elevated in a
one plane by pivoting upon the pivot mounting shaft and
traversed in another plane by swivelling on the swivel mounting
shaft.

15

5. The support means according to any preceding claim, in
which the three degrees of freedom of movement of the third
kinematic pair are provided by the joint comprising a pivot
mounting shaft, a swivel mounting shaft, and a rotational
20 mounting shaft, whereby the mounting arm may be elevated in a
first plane by pivoting upon the pivot mounting shaft and
traversed in a second plane by swivelling on the swivel
mounting shaft, and rotated about its longitudinal axis on the
rotational mounting shaft.

25

6. The support means according to claim 5, in which the first
and second planes are perpendicular.

7. The support means according to claim 6, in which the
30 longitudinal axis of the second section is substantially
parallel to a line of intersection of said planes.

8. A support means for supporting a lateral conveyor adapted
for mounting upon a mobile chassis,

said conveyor comprising of tail section, middle section and at least one head section having pivot points related to the conveyor frame separating said sections from each other,

5 said support means comprising a variable length mounting arm,

said mounting arm comprising at least two sections and first and second ends, means for locking the length of the mounting arm into at least one fixed length corresponding to the length of the conveyor in the working position,

10 the first end being fixed to said mobile chassis or a part fixed immobile in relation to said mobile chassis and the second end being fixed to the said head section of the conveyor or a part fixed immobile in relation to the said head section of the conveyor,

15 the support means being configured to provide at least three kinematic pairs, in which a first kinematic pair is formed by the first section of the mounting arm and the mobile chassis and is provided by a joint, a second kinematic pair is formed by the first and second sections of the mounting arm, 20 and the third kinematic pair is formed by the second section of the mounting arm and the head section of the conveyor,

25 the support means being configured such that the first kinematic pair provides for three degrees of freedom of movement, the second kinematic pair provides for one degree of freedom of movement, and the third kinematic pair provides for two degrees of freedom of movement.

9. The support means according to claim 8, in which the third kinematic pair is provided by a further joint between the 30 second section of the mounting arm and the head section of the conveyor.

10. The support means according to claim 9, in which the further joint comprises a pivot mounting shaft and a swivel

mounting shaft, whereby the mounting arm may be elevated in a one plane by pivoting upon the pivot mounting shaft and traversed in another plane by swivelling on the swivel mounting shaft.

5

11. The support means according to any preceding claim, in which the degree of freedom of movement of the second kinematic pair is provided by configuring the first and second sections for sliding in relation to each other.

10

12. The support means according to any preceding claim, in which the degree of freedom of movement of the second kinematic pair is provided by configuring the first and second sections for substantially linear movement in relation to each other.

15

13. The support means according to claim 12, in which the second section moves substantially in a direction of its longitudinal axis.

20 14. The support means according to any of claims 8 to 13, in which the three degrees of freedom of movement of the first kinematic pair are provided by the joint comprising a pivot mounting shaft, a swivel mounting shaft, and a rotational mounting shaft, whereby the mounting arm may be elevated in a first plane by pivoting upon the pivot mounting shaft and traversed in a second plane by swivelling on the swivel mounting shaft, and rotated about its longitudinal axis on the rotational mounting shaft.

25 30 15. The support means according to claim 14, in which the first and second planes are perpendicular.

16. The support means according to claim 15, in which the longitudinal axis of the second section is substantially parallel to a line of intersection of said planes.

5 17. The support means according to any preceding claim, in which one of the first and second sections is located within the other to allow for telescopic length adjustment of the mounting arm.

10 18. The support means according to claim 17, in which the mounting arm comprises a hydraulic cylinder.

19. The support means according to any preceding claim, in which the mounting arm comprises three sections, in which the 15 degree of freedom of movement of the second kinematic pair is provided between at least a first and second section and between the second and a third section.

20. The support means according to any preceding claim when 20 depending from claim 5 or claim 14, in which a C-shaped bracket comprising a top face, a bottom face and a back plate extending between the top and bottom plates is mounted on at least one end of the mounting arm, through the rotational mounting shaft.

25 21. The support means according to claim 20, in which the top and bottom faces of the C-shaped bracket are substantially parallel and the back plate extends substantially perpendicularly to the top and bottom faces.

30 22. The support means according to claim 20 or 21, in which bearing means is provided between an end face of the mounting arm and the back plate of the bracket.

23. The support means according to any of claims 20 to 22, in which an aperture is provided in each of the top and bottom faces of the C-shaped bracket, said apertures being aligned along a common axis through the bracket.

5

24. The support means according to any of claims 20 to 23, in which the swivel mounting shaft is provided with a through bore and said swivel mounting shaft is mounted within the C-shaped bracket such that the bore is aligned with the apertures in the top and bottom face of the bracket.

10

25. The support means according to claim 24, in which the pivot mounting shaft extends through the apertures in the top and bottom faces of the C-shaped bracket and the bore of the swivel mounting shaft to lock the swivel mounting shaft in position within the bracket.

15

26. A support means for supporting a lateral conveyor adapted for mounting upon a mobile chassis,

20

said conveyor comprising of tail section, middle section and at least one head section having pivot points related to the conveyor frame separating said sections from each other, said support means comprising a variable length mounting arm,

25

said mounting arm comprising at least two sections and first and second ends, means for locking the length of the mounting arm into at least one fixed length corresponding to the length of the conveyor in the working position,

30

the first end being fixed to said mobile chassis or a part fixed immobile in relation to said mobile chassis and the second end being fixed to the said head section of the conveyor or a part fixed immobile in relation to the said head section of the conveyor,

the support means being configured to provide at least three kinematic pairs, in which a first kinematic pair is formed by the first section of the mounting arm and the mobile chassis, a second kinematic pair is formed by the first and 5 second sections of the mounting arm, and the third kinematic pair is formed by the second section of the mounting arm and the head section of the conveyor and is provided by a joint,

the support means being further configured such that the first kinematic pair provides for two degrees of freedom of 10 movement, the second kinematic pair provides for two degrees of freedom movement, and the third kinematic pair provides for two degrees of freedom of movement.

27. The support means according to claim 26, in which the two 15 degrees of freedom of movement of the first kinematic pair is provided by a further joint between the first section of the mounting arm and the mobile chassis.

28. The support means according to claim 27, in which the 20 further joint comprises a pivot mounting shaft and a swivel mounting shaft, whereby the mounting arm may be elevated in a one plane by pivoting upon the pivot mounting shaft and traversed in another plane by swivelling on the swivel mounting shaft.

25

29. The support means according to any of claims 26 to 28, in which the two degrees of freedom of movement of the second kinematic pair is provided by configuring the first and second sections for rotation and sliding in relation to each other.

30

30. The support means according to claim 29, in which the second section is rotatable about its longitudinal axis and moved substantially in a direction of its longitudinal axis.

31. The support means according to any one of claims 26 to 30, in which the two degrees of freedom of movement of the third kinematic pair is provided by the joint comprising a pivot mounting shaft and a swivel mounting shaft, whereby the 5 mounting arm may be elevated in a first plane by pivoting upon the pivot mounting shaft and traversed in a second plane by swivelling on the swivel mounting shaft.

32. The support means according to claim 31, in which the 10 first and second planes are perpendicular.

33. The support means according to claim 32, in which the longitudinal axis of the second section is substantially parallel to a line of intersection of said planes.

15

34. The support means according to any one of claims 26 to 33, in which one of the first and second sections is located within the other to allow for telescopic length adjustment of the mounting arm.

20

35. The support means according to claim 34, in which the mounting arm comprises a hydraulic cylinder.

36. The support means according to any one of claims 26 to 35, 25 in which co-located portions of the first and second sections are of substantially circular cross-section.

30

37. The support means according to any one of claims 26 to 36, in which the mounting arm comprises three sections, in which a first degree of freedom of movement is provided between a first and second section and a second degree of freedom of movement is provided between the second and a third section.

38. The support means according to claim 37, in which the mounting arm is configured such that the first degree of freedom of movement is sliding of the first and second sections in relation to each other and the second degree of freedom of 5 movement is rotation of the second and third sections in relation to each other.

39. The support means according to claim 37, in which the mounting arm is configured such that the first degree of 10 freedom of movement is rotation of the first and second sections in relation to each other and the second degree of freedom of movement is sliding of the second and third sections in relation to each other.

15 40. The support means according to any one of claims 26 to 39, in which the support means is configured such that at least one of the first and third kinematic pairs provides for three degrees of freedom of movement.

20 41. The support means according to any preceding claim, in which the support means further comprises means for locking the length of the variable length mounting arm into a fixed length corresponding to the length of the conveyor in the transport position and/or service position.

25

42. The support means according to any preceding claim, in which the head section of the conveyor consists of at least two separate sections pivotable to each other, the first of the said head sections being supported to said mobile chassis or a 30 part fixed immobile in relation to said mobile chassis with said variable length arm.

43. The support means according to any preceding claim, in which one end of the mounting arm is connected to a tail

section of the conveyor and the other end of the mounting arm is connected to a head section of the conveyor.

44. The support means according to any preceding claim, in
5 which a collar and a locking pin is provided to fix the length of the support to correspond to the working position of the conveyor, preferably also to the transport position and to the maintenance position.

10 45. The support means according to any of preceding claim, in which bearing means is provided between all gliding surfaces.

15 46. The support means according to any preceding claim, in which the mounting arm comprises a box section formed of metal or any suitable material.

47. The support means according to claim 46, in which the box section is at least one of extruded, cast and cut from hollow or open section in required lengths.

20 48. The support means according to any preceding claim, in which the support means is formed of mild steel.

25 49. A mobile chassis comprising a lateral conveyor mounted thereon and a support means for supporting a lateral conveyor according to any preceding claim.

50. The mobile chassis according to claim 49, in which the mobile chassis is a mobile aggregate processing plant.

30 51. A support means for supporting a lateral conveyor adapted for mounting upon a mobile chassis, said conveyor comprising of tail section, middle section and at least one head section having pivot points related to the conveyor frame separating

said sections from each other; said supporting means comprising a variable length mounting arm said mounting arm comprising a first end and a second end means for locking the length of the variable length mounting arm into at least one fixed length
5 corresponding to the length of the conveyor in the working position one end being fixed to said mobile chassis or a part fixed immobile in relation to said mobile chassis characterised in that said other end of the mounting arm is fixed to the said head section of the conveyor or a part fixed immobile in
10 relation to the said head section of the conveyor and adjustment means are provided to finely alter the length of the mounting arm when locked into the at least one fixed length.

52. A support means substantially as described herein with
15 reference to one or more of Figures 2 to 9.

1/7

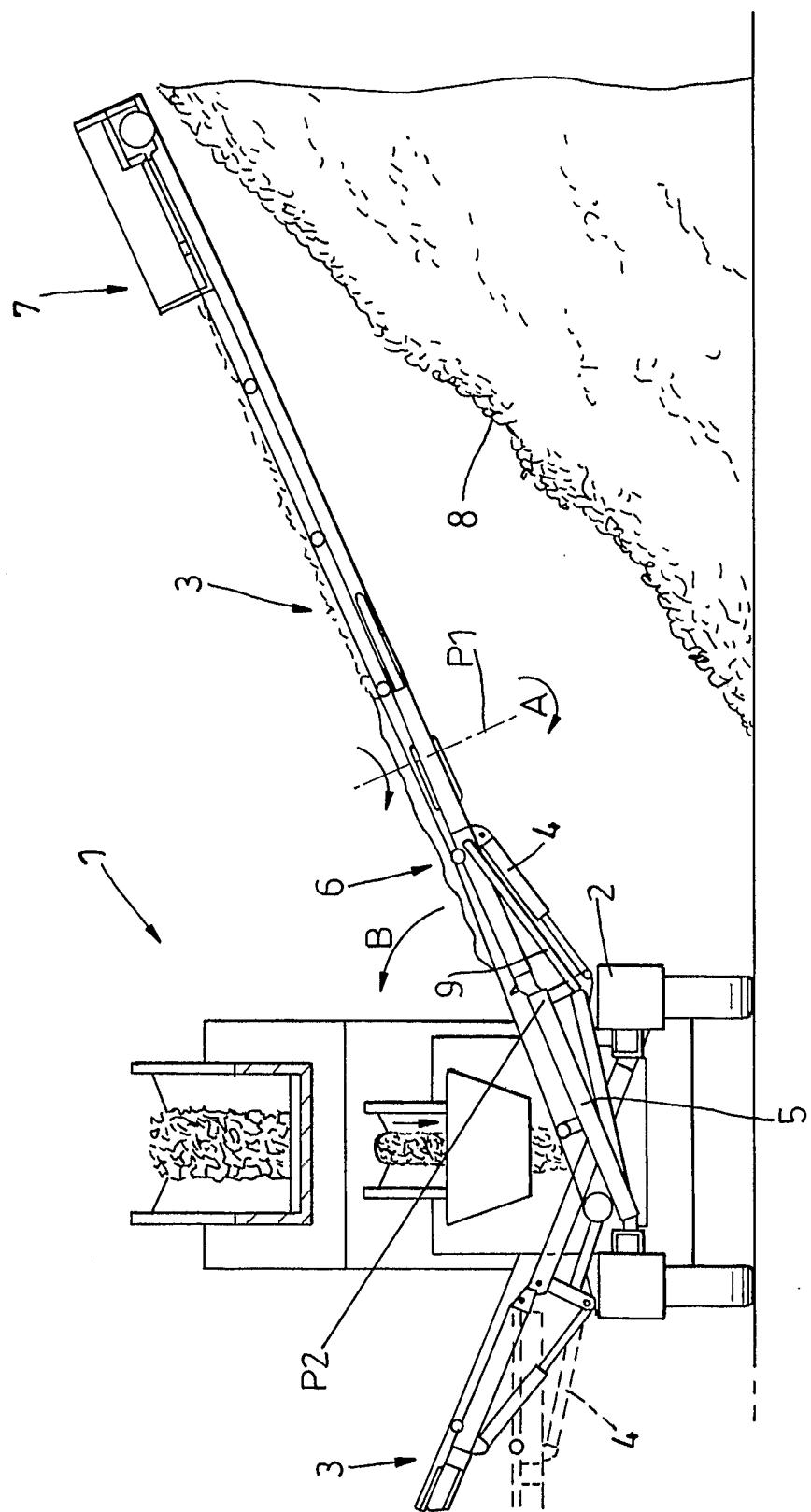


Fig. 1
(PRIOR ART)

2/7

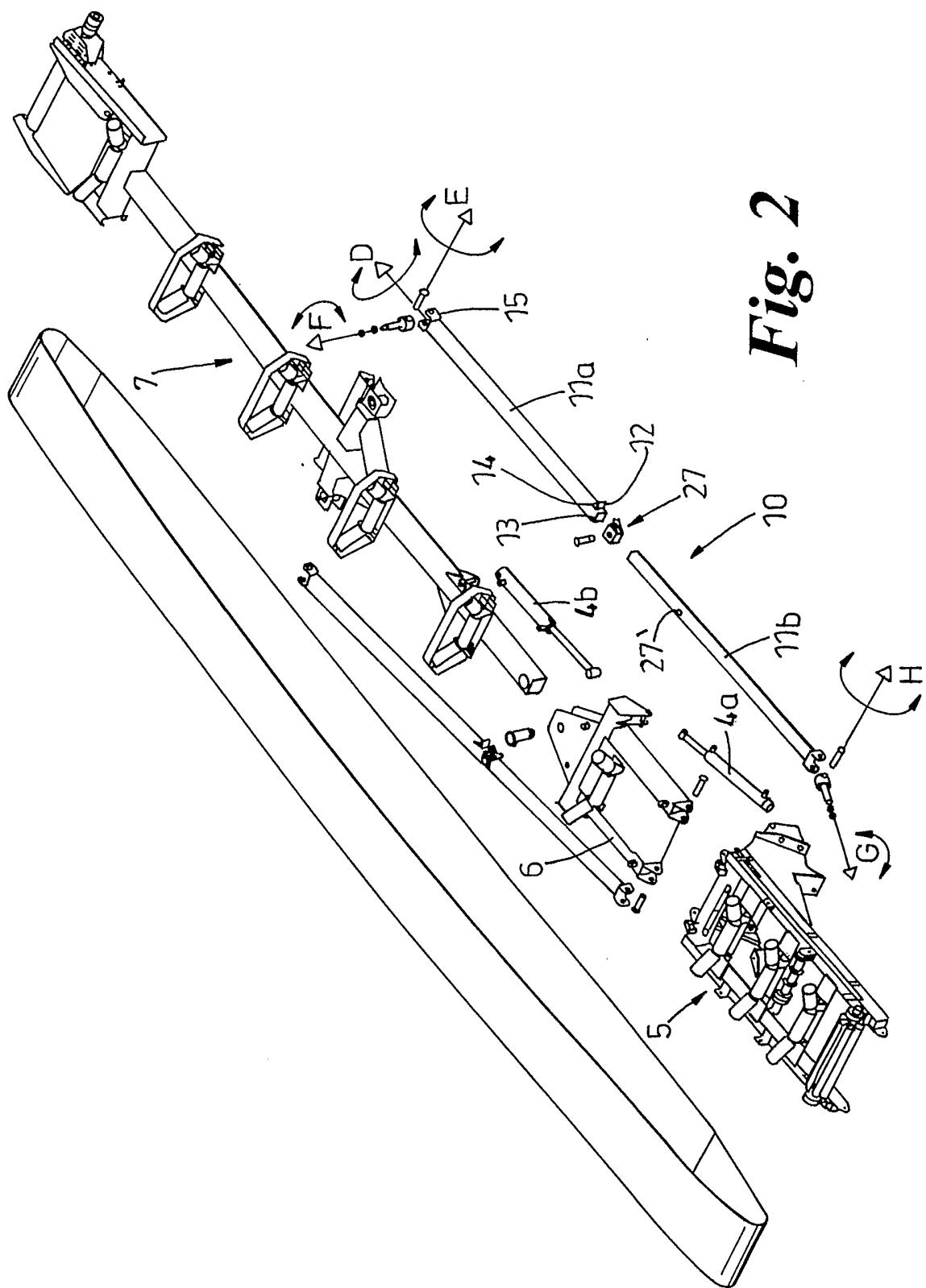


Fig. 2

3/7

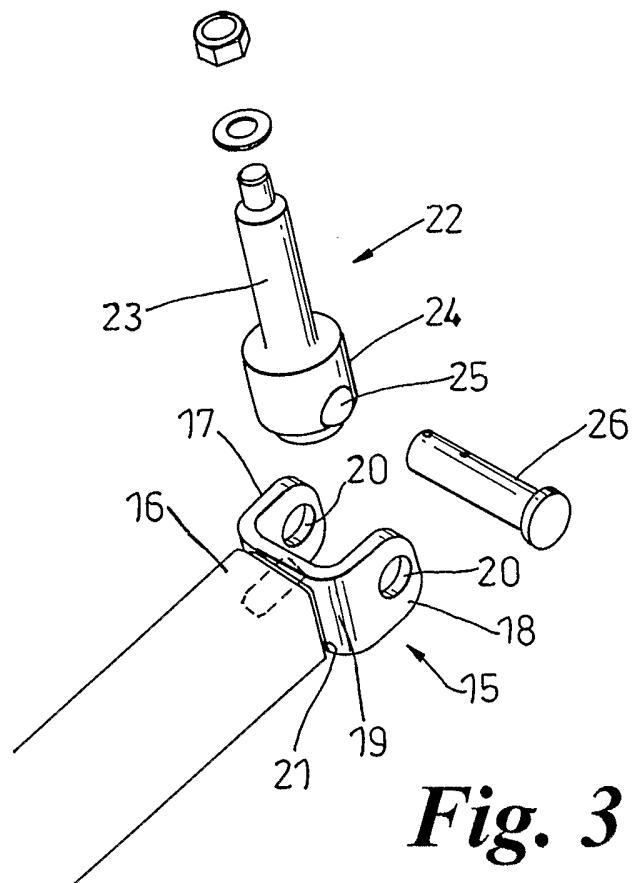


Fig. 3

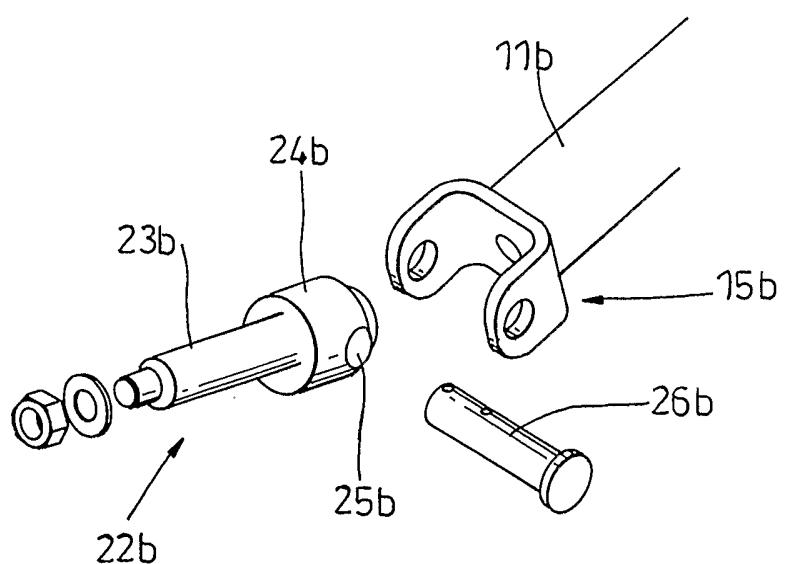
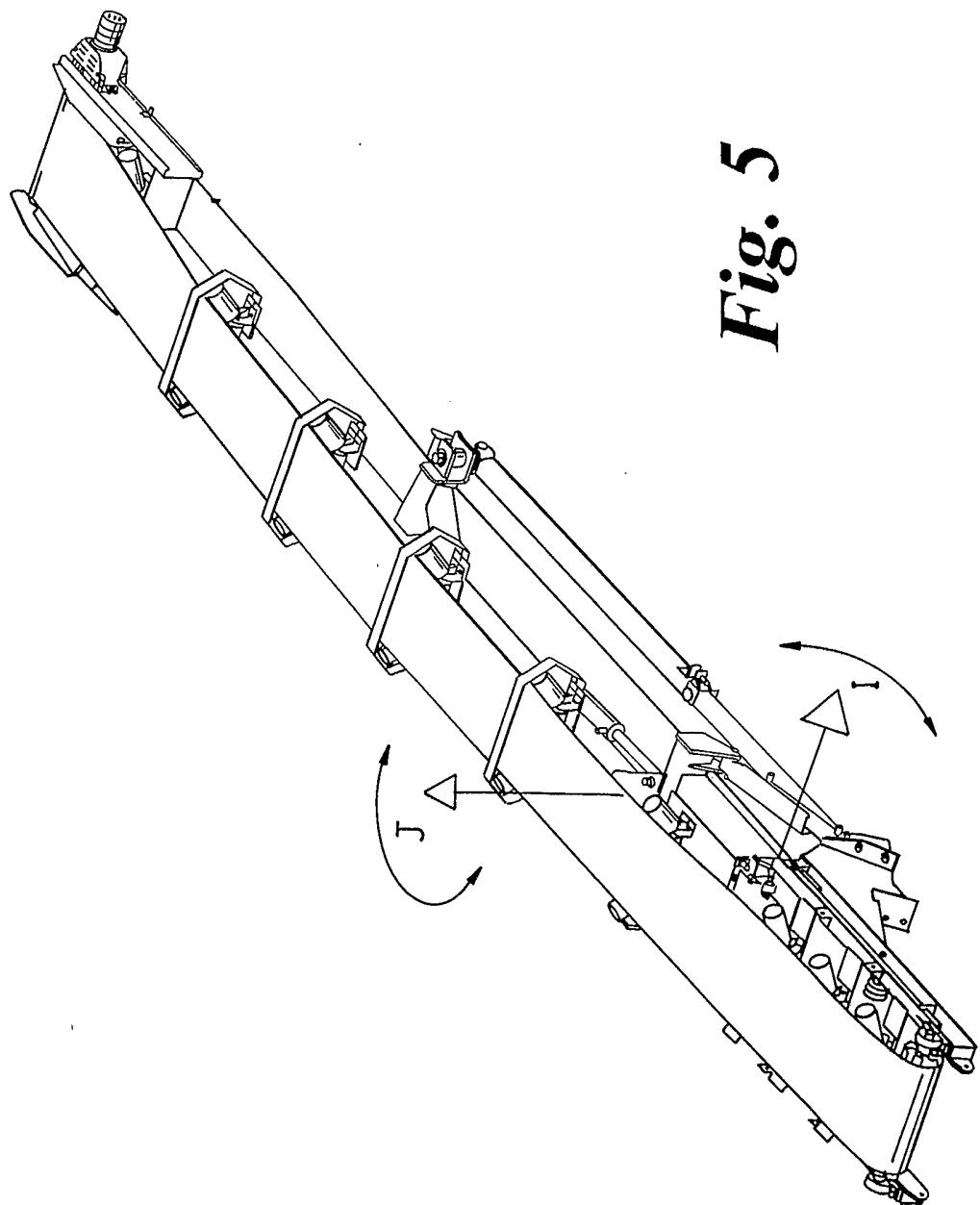


Fig. 4

4/7

Fig. 5



5/7

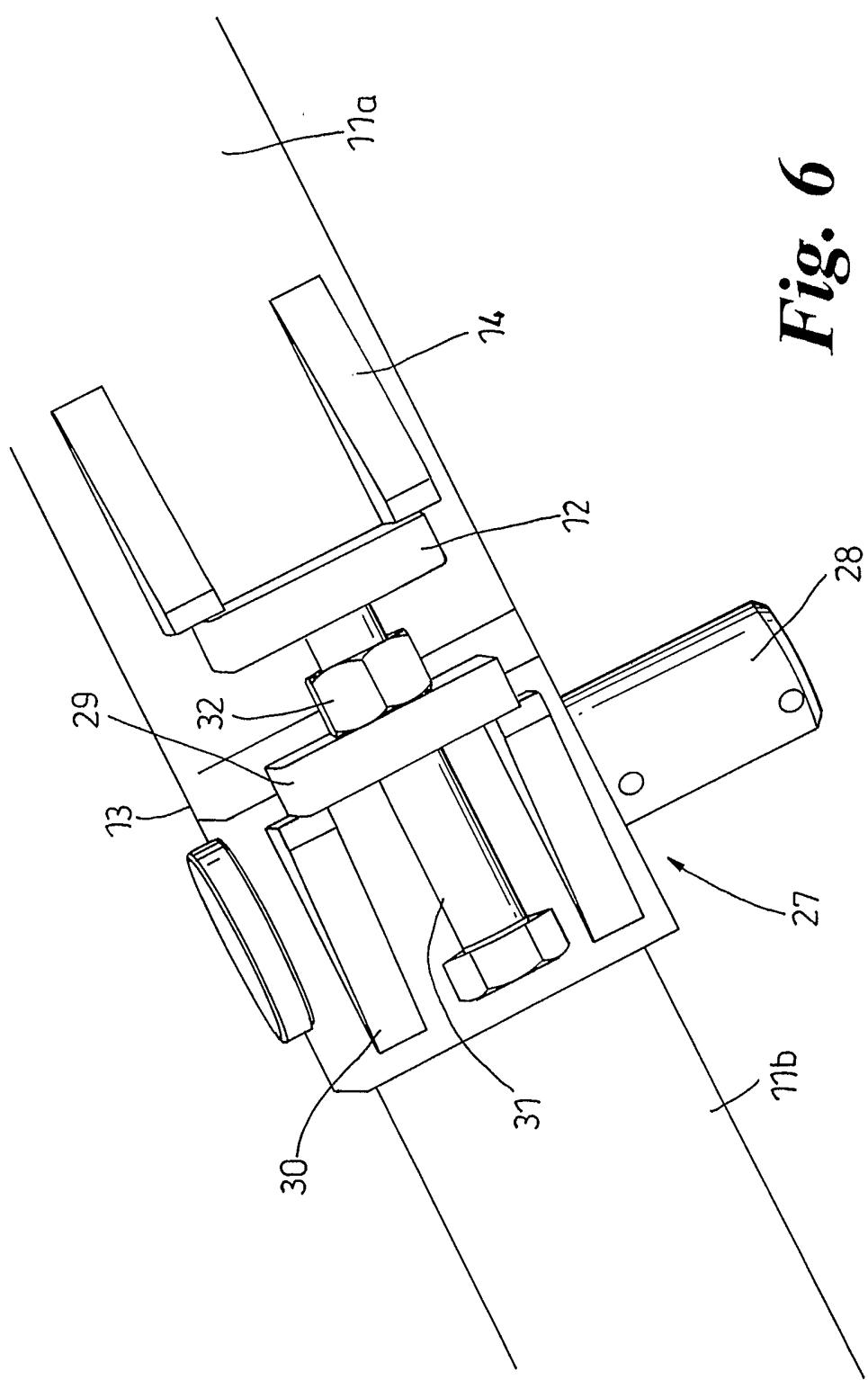


Fig. 6

6/7

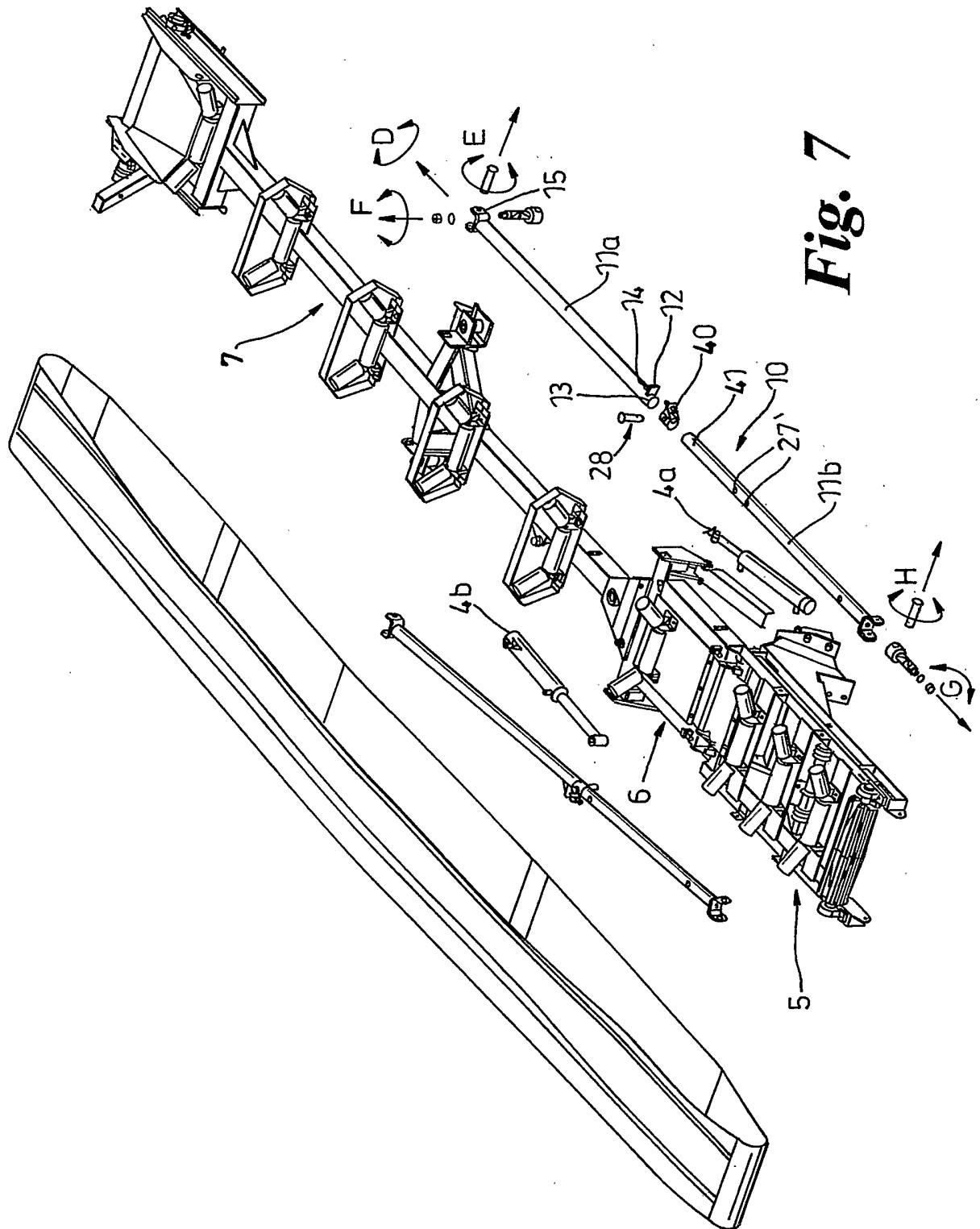


Fig. 7

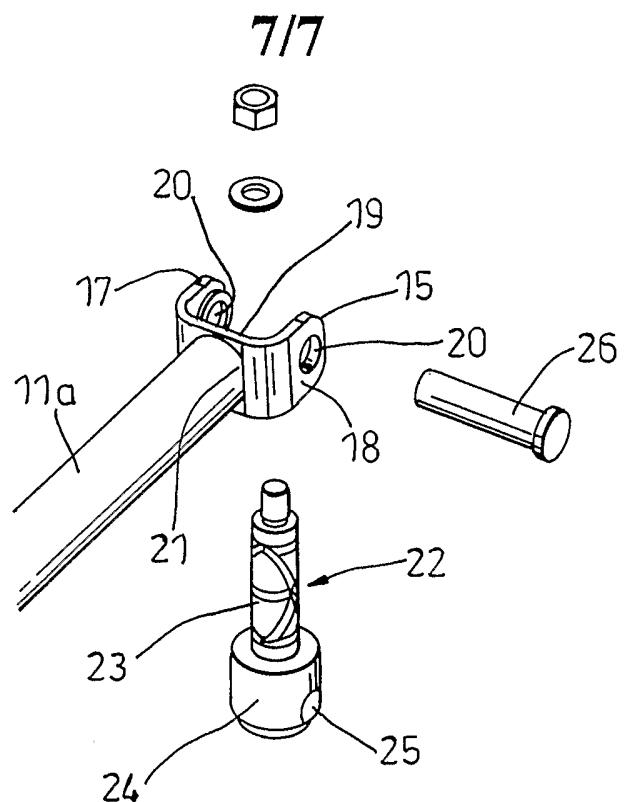


Fig. 8

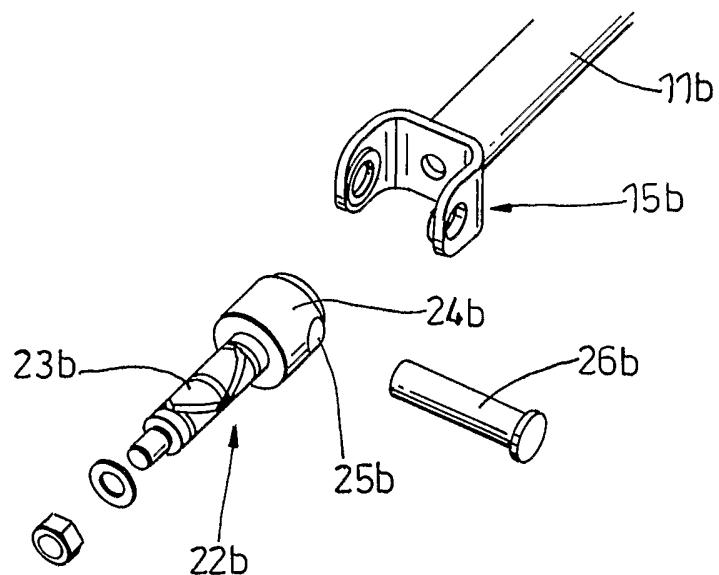


Fig. 9

INTERNATIONAL SEARCH REPORT

national Application No

/GB2004/001922

A. CLASSIFICATION OF SUBJECT MATTER

IPC 7 B65G41/00

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

IPC 7 B65G B28C B60P

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

EPO-Internal

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category °	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	US 3 684 255 A (ROSSI LIONELLO) 15 August 1972 (1972-08-15) the whole document -----	1,8,26, 49,51
A	EP 0 641 607 A (RAFFERTY MALACHY JAMES) 8 March 1995 (1995-03-08) cited in the application column 7, line 34 – column 8, line 36; figures 2,5 -----	



Further documents are listed in the continuation of box C.



Patent family members are listed in annex.

° Special categories of cited documents :

- "A" document defining the general state of the art which is not considered to be of particular relevance
- "E" earlier document but published on or after the international filing date
- "L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)
- "O" document referring to an oral disclosure, use, exhibition or other means
- "P" document published prior to the international filing date but later than the priority date claimed

- "T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention
- "X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone
- "Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art.
- "&" document member of the same patent family

Date of the actual completion of the international search

10 September 2004

Date of mailing of the international search report

21/09/2004

Name and mailing address of the ISA

European Patent Office, P.B. 5818 Patentlaan 2
NL - 2280 HV Rijswijk
Tel. (+31-70) 340-2040, Tx. 31 651 epo nl,
Fax: (+31-70) 340-3016

Authorized officer

Schneider, M

INTERNATIONAL SEARCH REPORT

International application No.
PCT/GB2004/001922

Box II Observations where certain claims were found unsearchable (Continuation of item 2 of first sheet)

This International Search Report has not been established in respect of certain claims under Article 17(2)(a) for the following reasons:

1. Claims Nos.: because they relate to subject matter not required to be searched by this Authority, namely:

2. Claims Nos.: 52 because they relate to parts of the International Application that do not comply with the prescribed requirements to such an extent that no meaningful International Search can be carried out, specifically:
see FURTHER INFORMATION sheet PCT/ISA/210

3. Claims Nos.: because they are dependent claims and are not drafted in accordance with the second and third sentences of Rule 6.4(a).

Box III Observations where unity of invention is lacking (Continuation of item 3 of first sheet)

This International Searching Authority found multiple inventions in this international application, as follows:

1. As all required additional search fees were timely paid by the applicant, this International Search Report covers all searchable claims.

2. As all searchable claims could be searched without effort justifying an additional fee, this Authority did not invite payment of any additional fee.

3. As only some of the required additional search fees were timely paid by the applicant, this International Search Report covers only those claims for which fees were paid, specifically claims Nos.:

4. No required additional search fees were timely paid by the applicant. Consequently, this International Search Report is restricted to the invention first mentioned in the claims; it is covered by claims Nos.:

Remark on Protest

The additional search fees were accompanied by the applicant's protest.

No protest accompanied the payment of additional search fees.

FURTHER INFORMATION CONTINUED FROM PCT/ISA/ 210

Continuation of Box II.2

Claims Nos.: 52

Rule 6.2(a) PCT

The applicant's attention is drawn to the fact that claims relating to inventions in respect of which no international search report has been established need not be the subject of an international preliminary examination (Rule 66.1(e) PCT). The applicant is advised that the EPO policy when acting as an International Preliminary Examining Authority is normally not to carry out a preliminary examination on matter which has not been searched. This is the case irrespective of whether or not the claims are amended following receipt of the search report or during any Chapter II procedure. If the application proceeds into the regional phase before the EPO, the applicant is reminded that a search may be carried out during examination before the EPO (see EPO Guideline C-VI, 8.5), should the problems which led to the Article 17(2) declaration be overcome.

INTERNATIONAL SEARCH REPORT

National Application No

GB2004/001922

Patent document cited in search report	Publication date	Patent family member(s)		Publication date
US 3684255	A 15-08-1972	CA	926382 A1	15-05-1973
		DE	2100680 A1	23-09-1971
		ES	194744 Y	01-07-1975
		FR	2075313 A5	08-10-1971
		GB	1297593 A	22-11-1972
EP 0641607	A 08-03-1995	AT	174821 T	15-01-1999
		DE	69415442 D1	04-02-1999
		DE	69415442 T2	15-07-1999
		DE	641607 T1	04-01-1996
		DK	641607 T3	23-08-1999
		EP	0641607 A2	08-03-1995
		ES	2128534 T3	16-05-1999
		GB	2282361 A ,B	05-04-1995
		GR	3029759 T3	30-06-1999
		IE	940699 A1	08-03-1995
		US	5577618 A	26-11-1996