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**Fukuzawa**

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(54) **REFERENCE VOLTAGE SUPPLY CIRCUIT, ANALOG CIRCUIT, AND ELECTRONIC INSTRUMENT**

7,619,474 B2 \* 11/2009 Fukuzawa ..... 330/253

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(73) Assignee: **Seiko Epson Corporation**, Tokyo (JP)

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U.S. Appl. No. 11/979,814 filed Nov. 8, 2007.  
U.S. Appl. No. 11/979,824 filed Nov. 8, 2007.

(\*) Notice: Subject to any disclaimer, the term of this patent is extended or adjusted under 35 U.S.C. 154(b) by 101 days.

\* cited by examiner

This patent is subject to a terminal disclaimer.

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(21) Appl. No.: **11/979,764**

(57) **ABSTRACT**

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(51) **Int. Cl.**  
**G05F 3/16** (2006.01)

(52) **U.S. Cl.** ..... 323/314; 330/253

(58) **Field of Classification Search** ..... 323/304, 323/311, 312, 313, 314, 315, 316; 330/253, 330/255; 455/249.1

See application file for complete search history.

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**17 Claims, 23 Drawing Sheets**

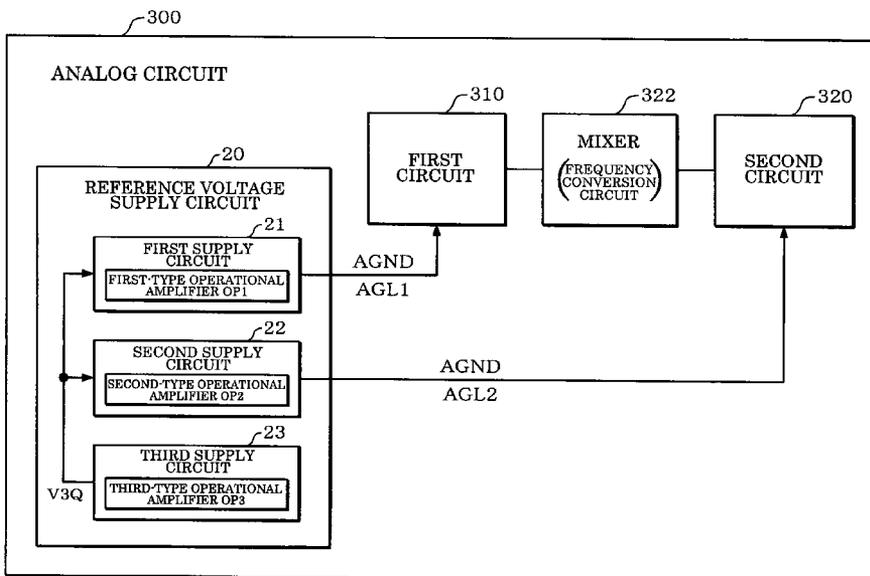


FIG. 1

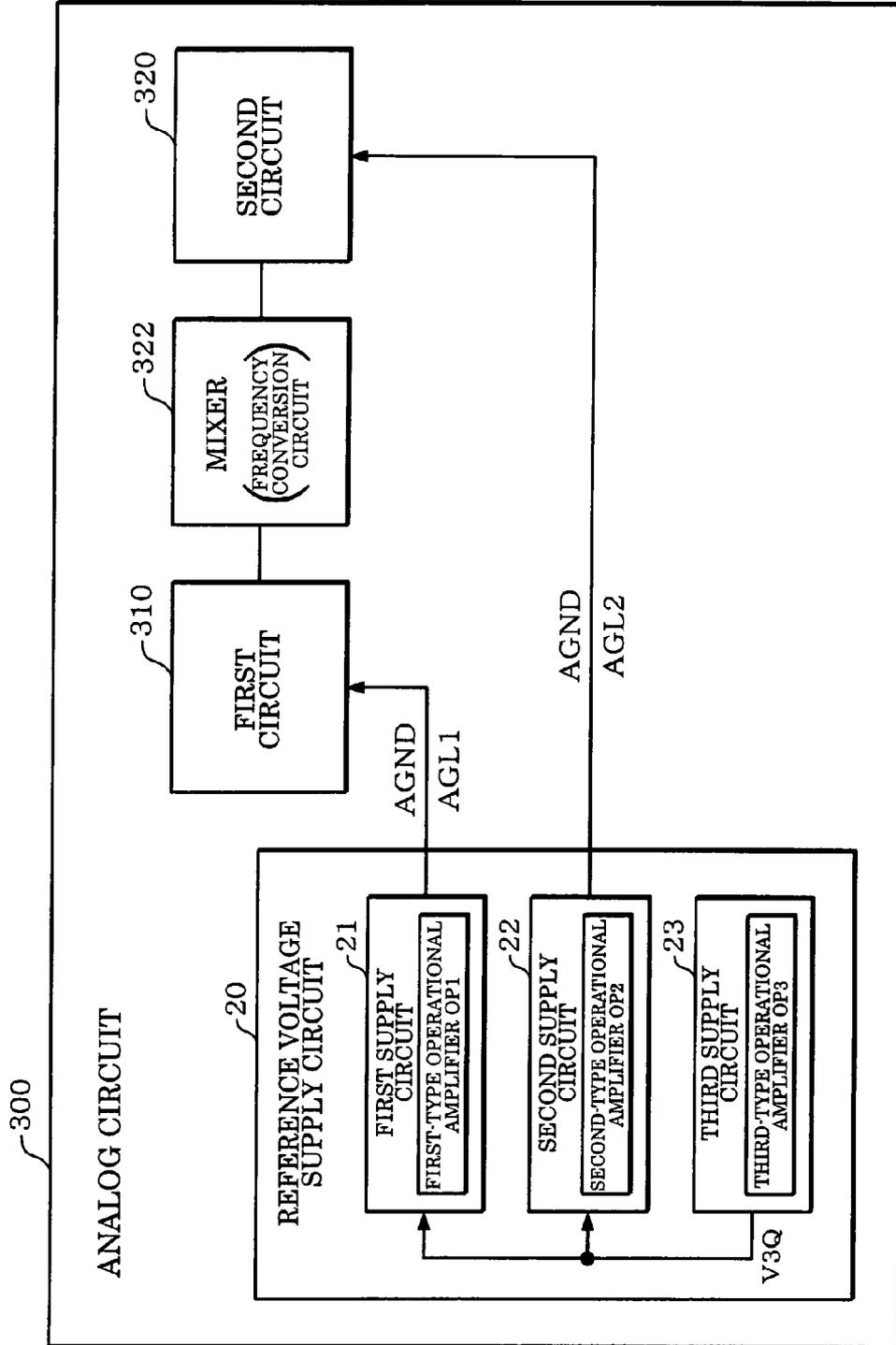


FIG. 2

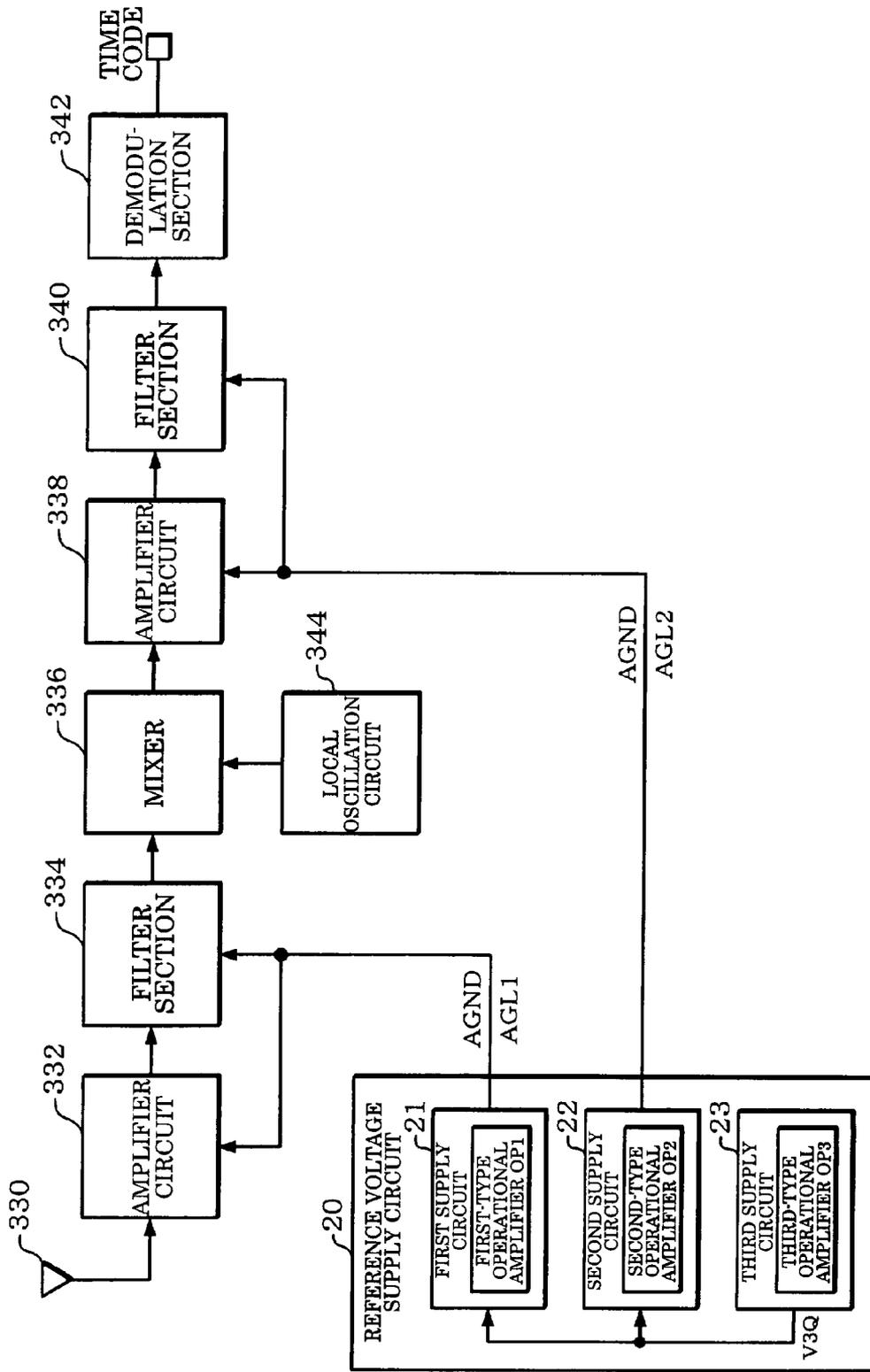


FIG. 3

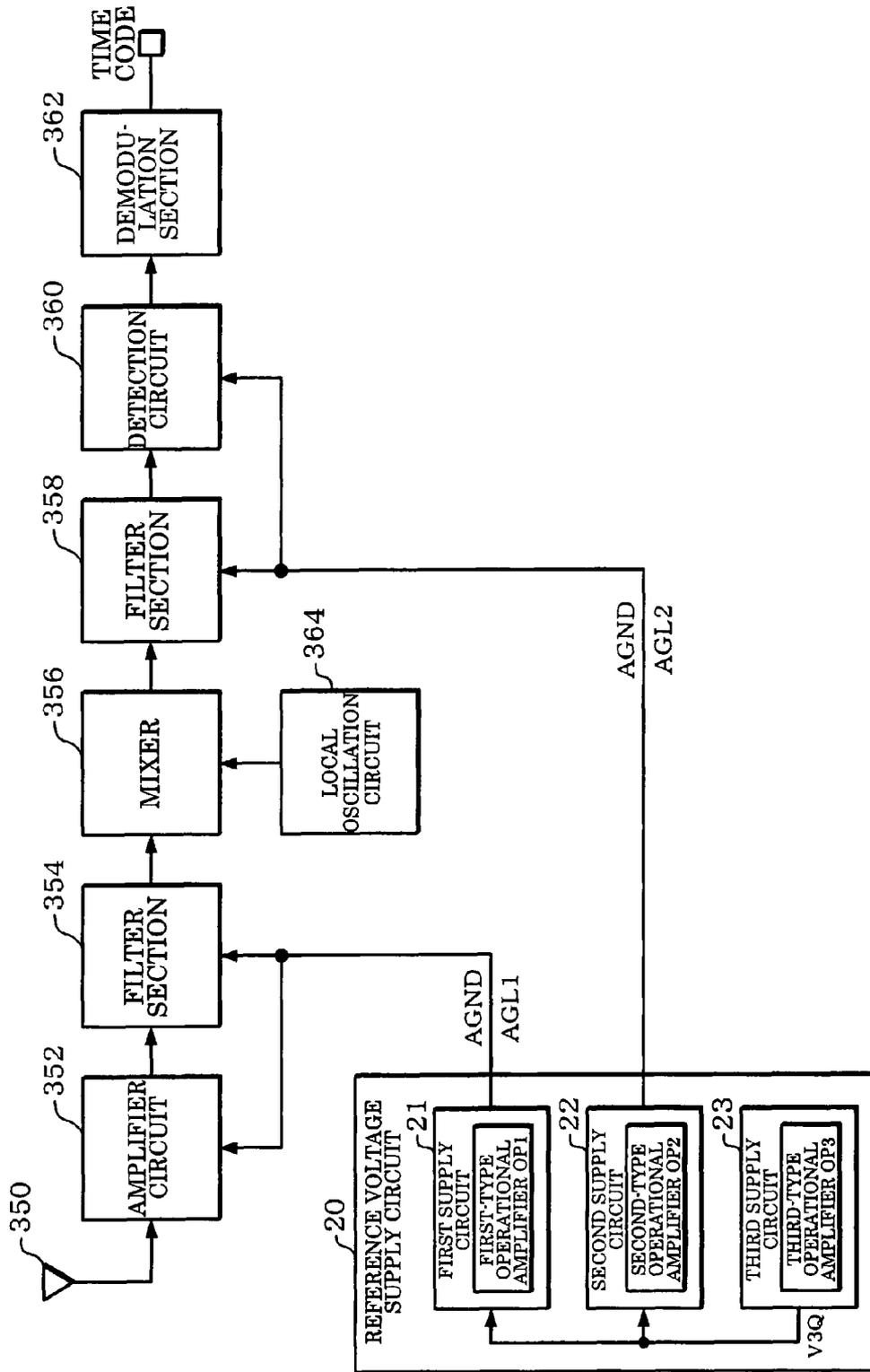




FIG. 5A

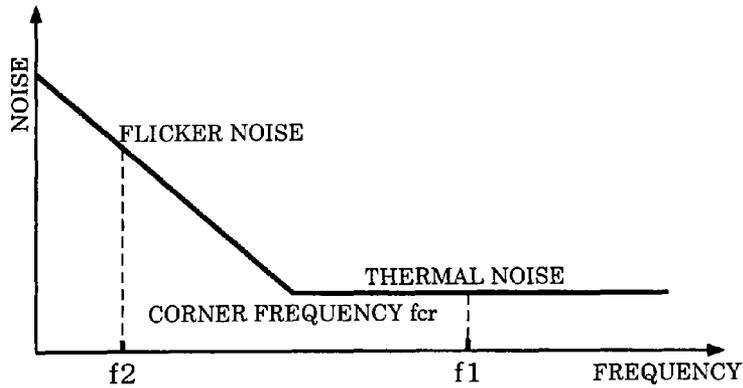


FIG. 5B

<p>FIRST-TYPE OPERATIONAL AMPLIFIER OP1</p> <p><math>W1 \times L1 = W1a \times L1a</math> IBD = Ia fop = f1</p> <p><math>RT1 = RT1a = W1a / L1a</math> <math>RT3 = RT3a = W3a / L3a</math></p>	<p>SECOND-TYPE OPERATIONAL AMPLIFIER OP2</p> <p><math>W1 \times L1 = W1b \times L1b</math> IBD = Ib fop = f2</p> <p><math>L1 / L3 = L1b / L3b</math></p>	<p>THIRD-TYPE OPERATIONAL AMPLIFIER OP3</p> <p><math>W1 \times L1 = W1c \times L1c</math> IBD = Ic</p>
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FIG. 5C

	OP1 (THERMAL NOISE REDUCTION)	OP2 (FLICKER NOISE REDUCTION)	OP3
$W1 \times L1$	SMALL ( $W1a \times L1a$ )	LARGE ( $W1b \times L1b$ )	LARGE ( $W1c \times L1c$ )
IBD	LARGE (Ia)	SMALL (Ib)	LARGE (Ic)
fop	HIGH (f1)	LOW (f2)	
$L1 / L3$		SMALL ( $L1b < L3b$ )	
$RT1 / RT3$	LARGE ( $RT1a > RT3a$ )		

$W1b \times L1b > W1a \times L1a$   
Ia > Ib

$W1c \times L1c > W1a \times L1a$   
Ic > Ib

FIG. 6A

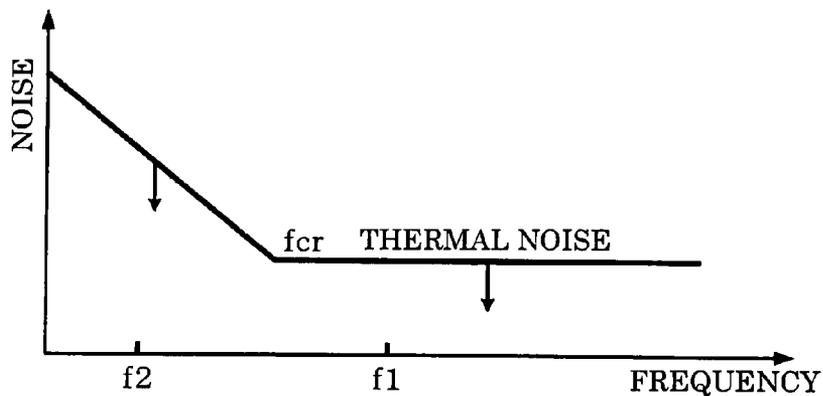


FIG. 6B FIRST-TYPE OPERATIONAL AMPLIFIER OP1

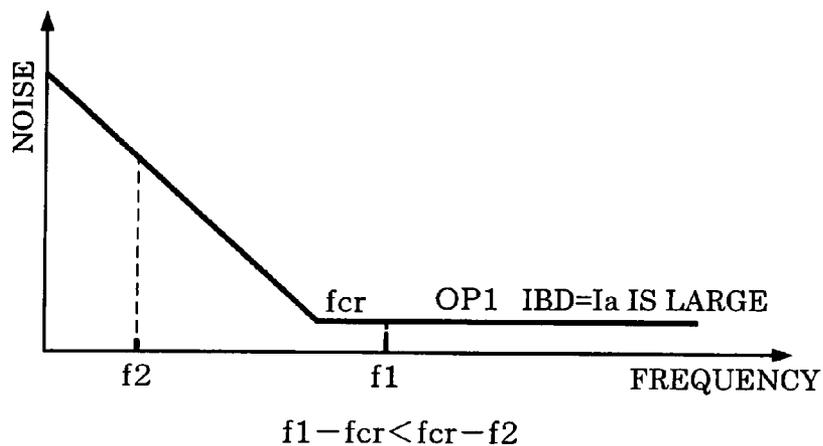


FIG. 6C SECOND-TYPE OPERATIONAL AMPLIFIER OP2

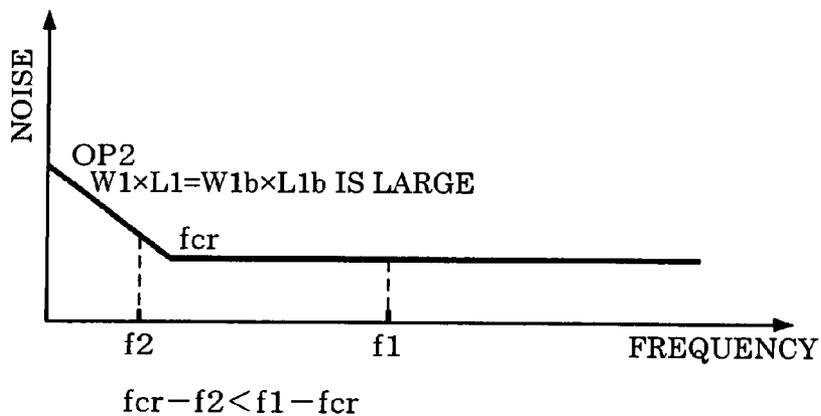


FIG. 7A FIRST-TYPE OPERATIONAL AMPLIFIER OP1

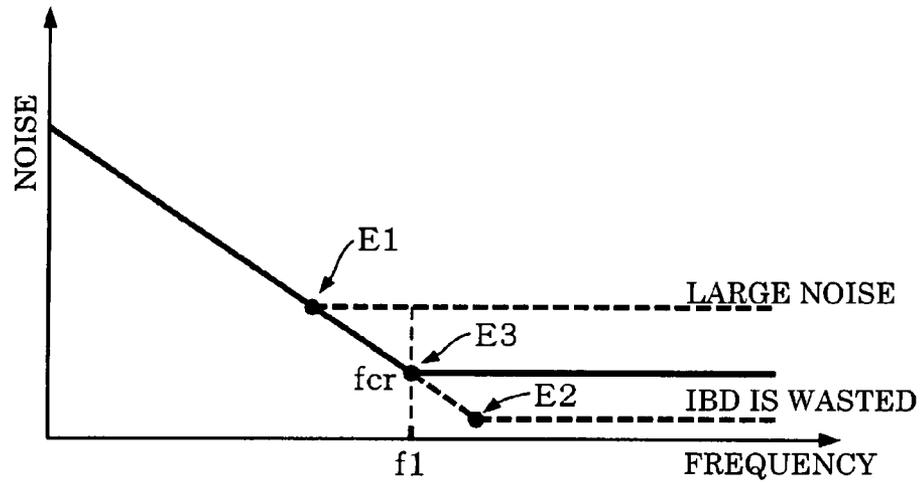


FIG. 7B SECOND-TYPE OPERATIONAL AMPLIFIER OP2

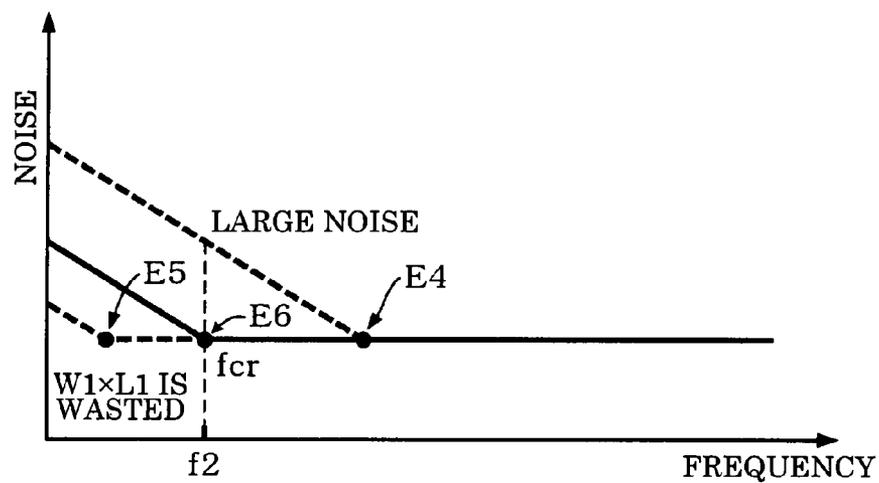


FIG. 8A

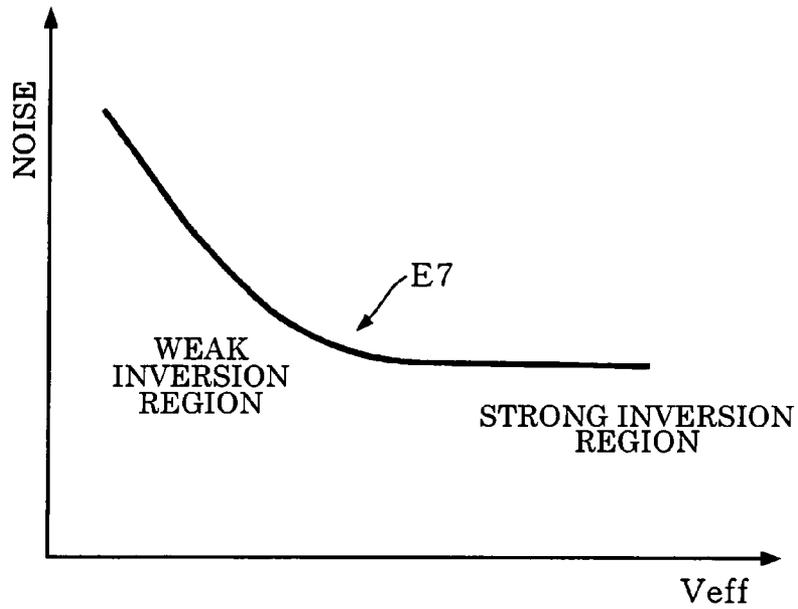


FIG. 8B

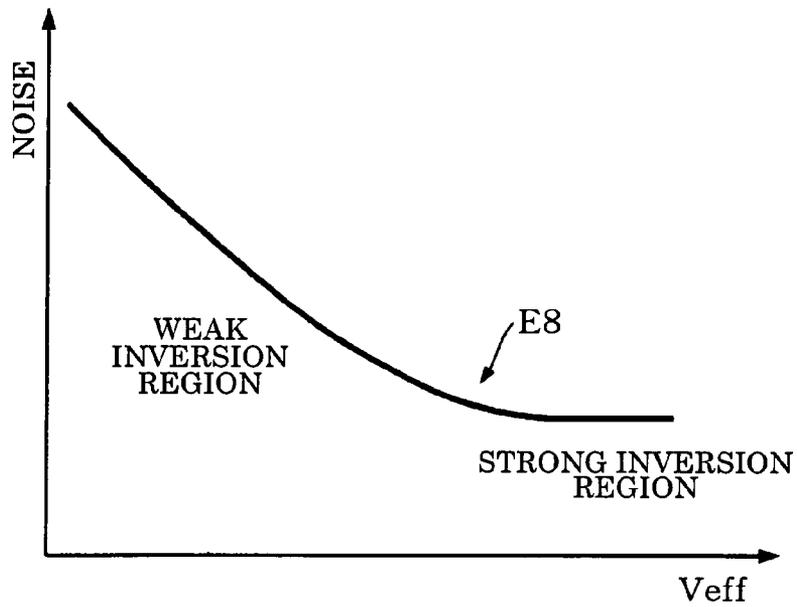


FIG. 9A

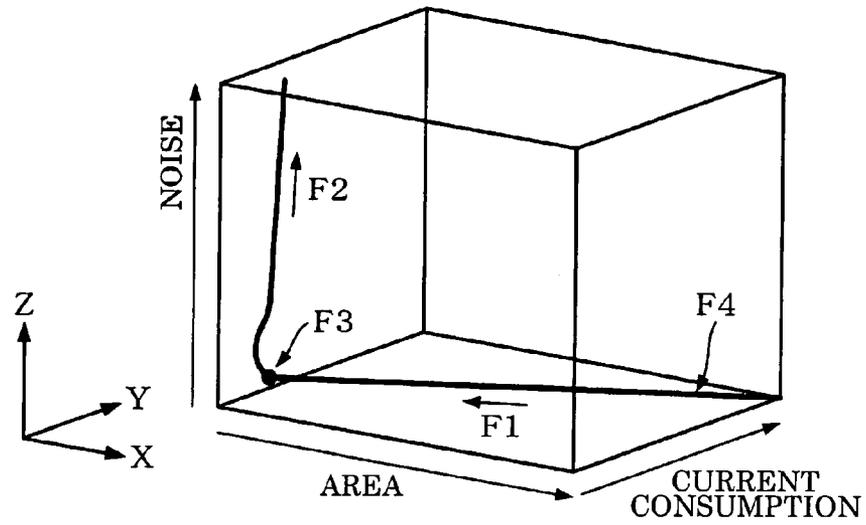


FIG. 9B

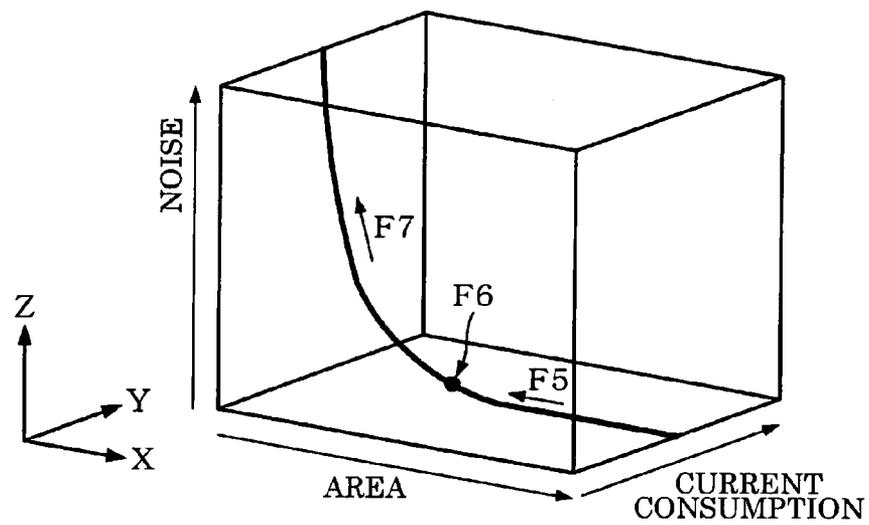


FIG. 10

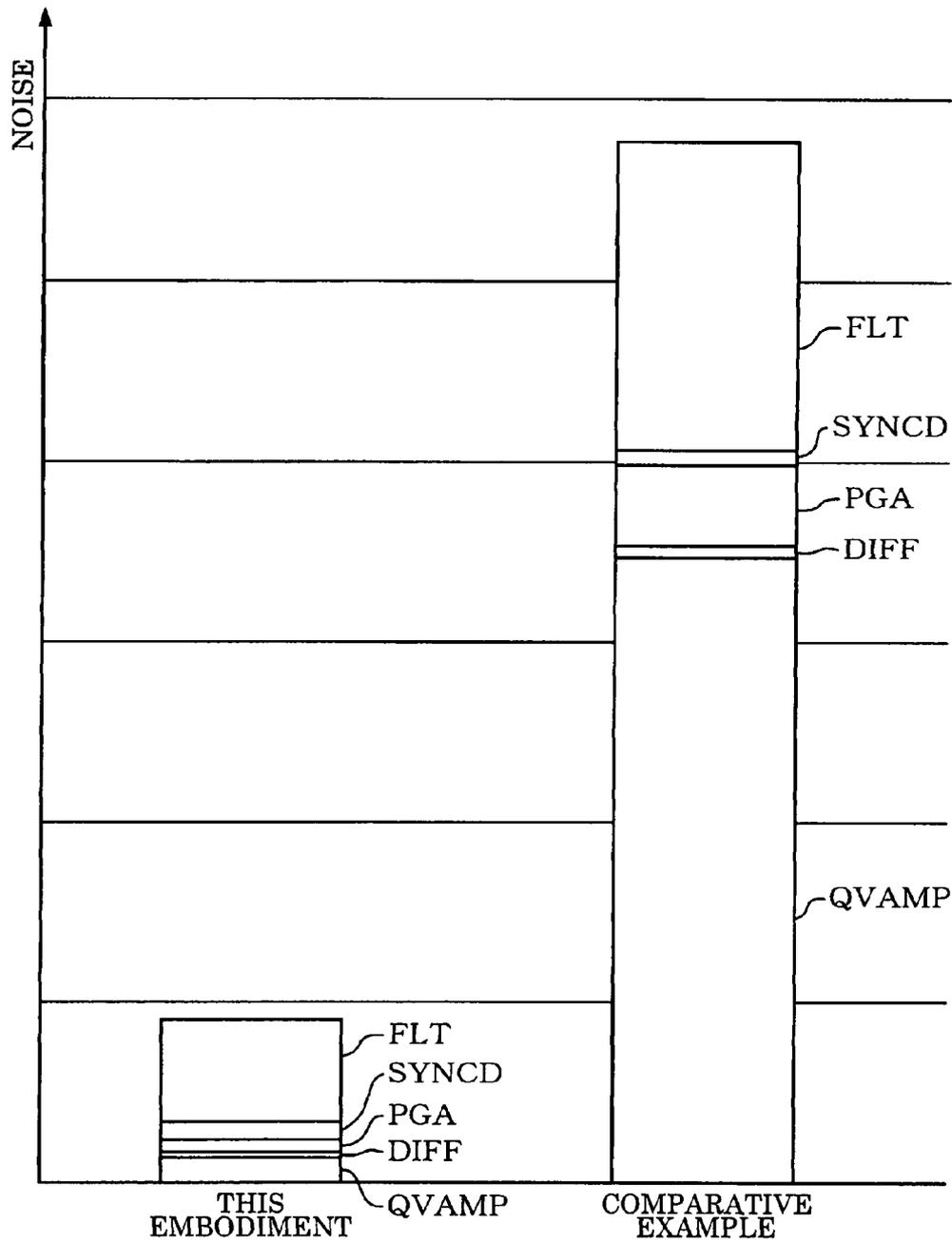


FIG. 11A

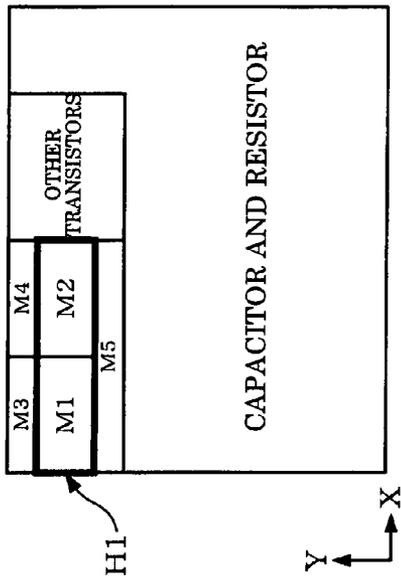


FIG. 11B

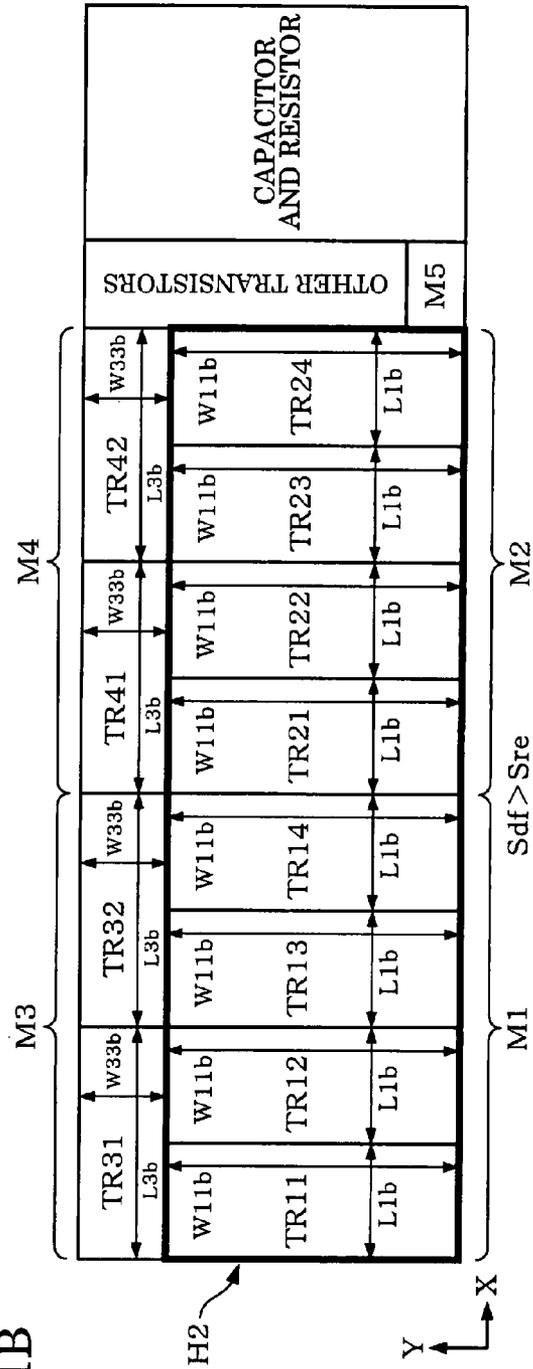


FIG. 12

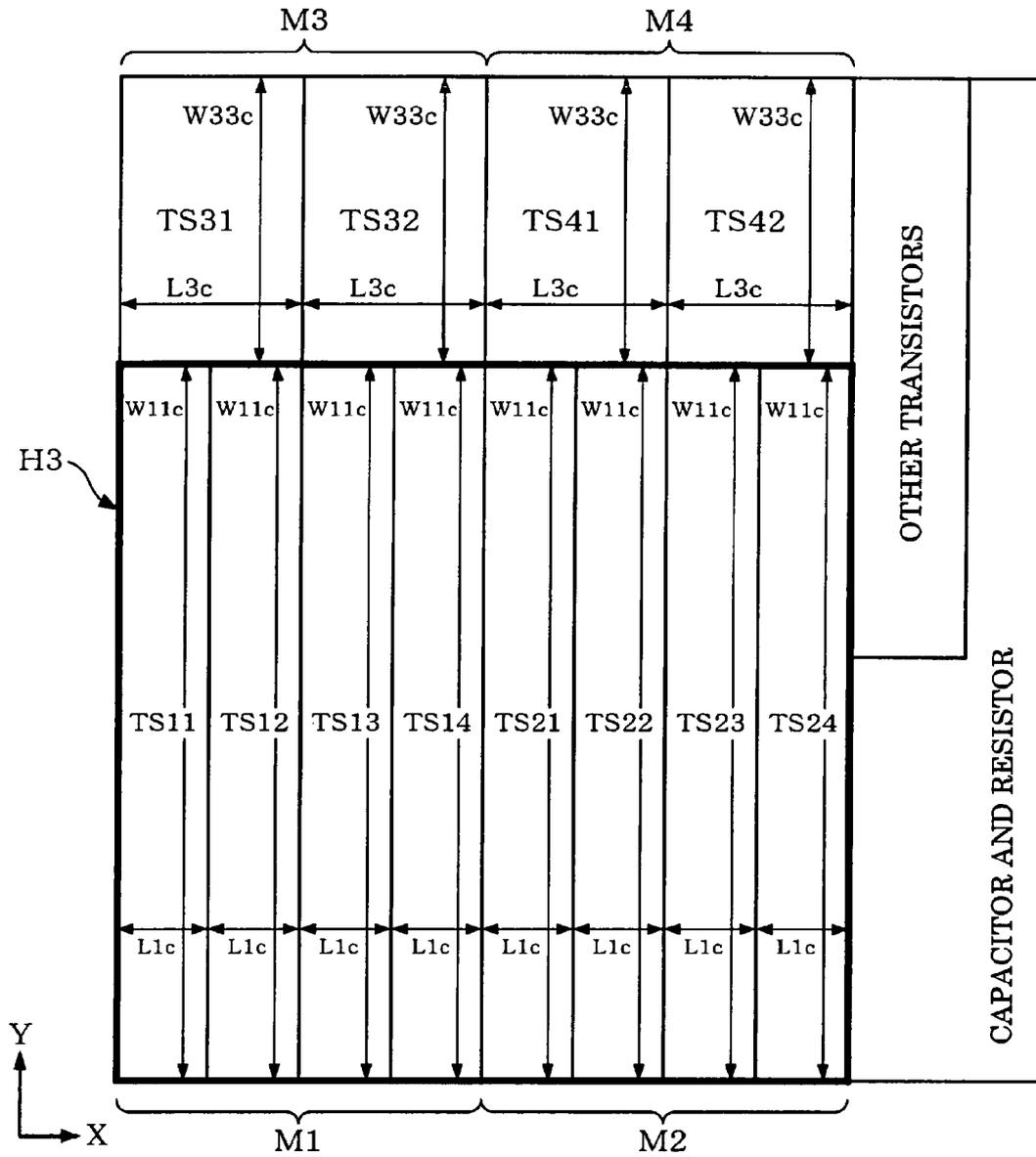


FIG. 13

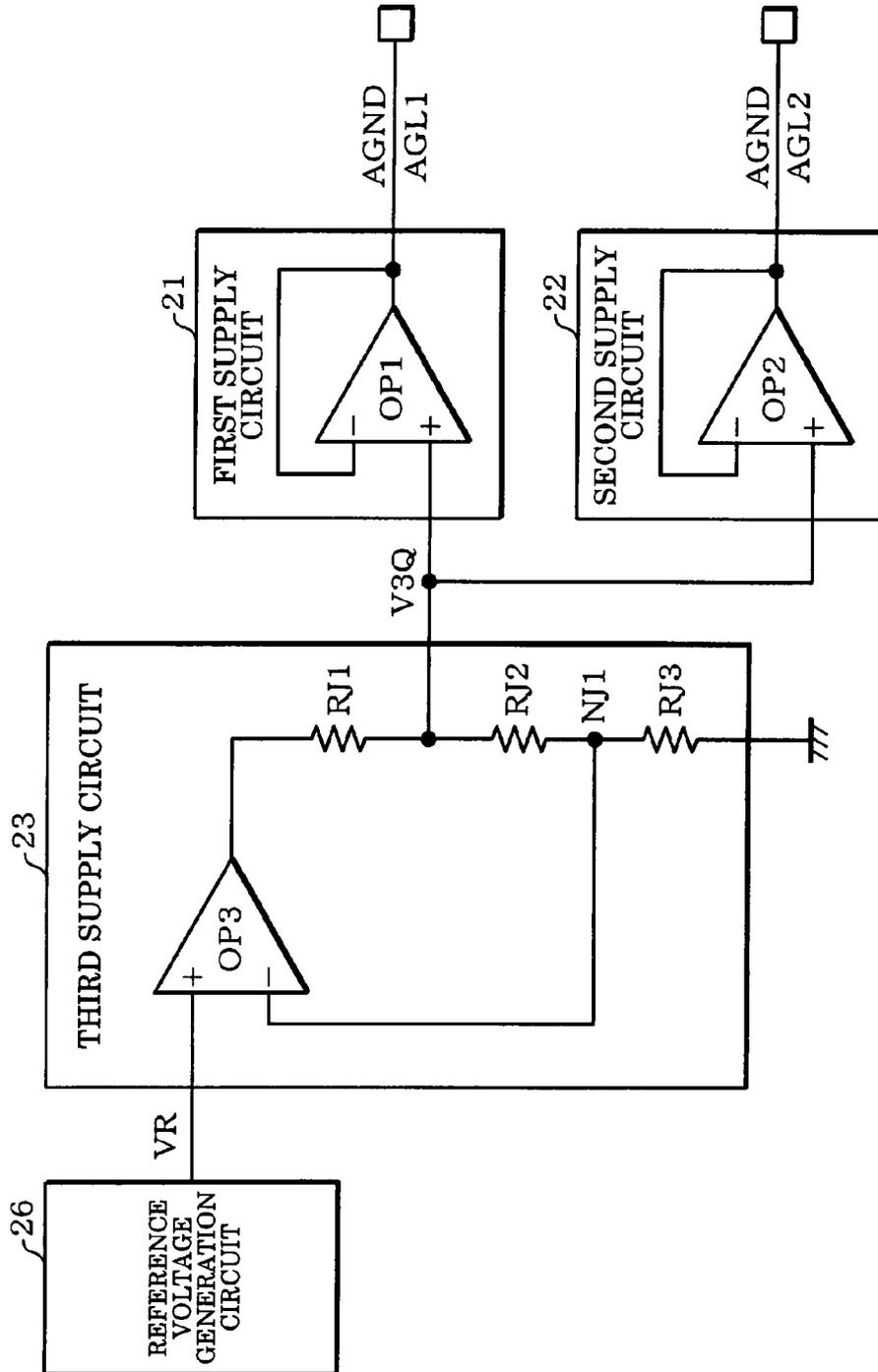


FIG. 14

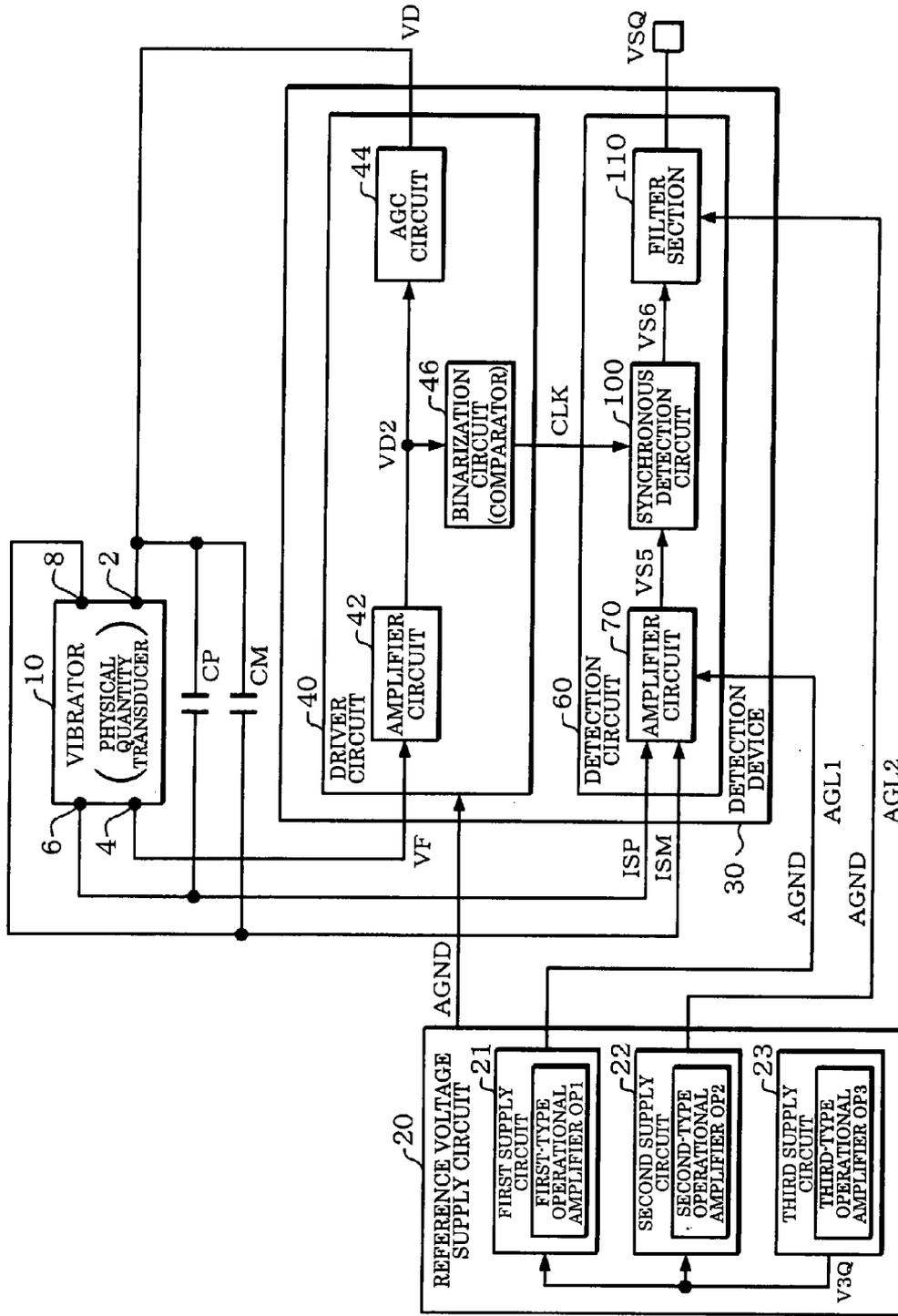


FIG. 15A

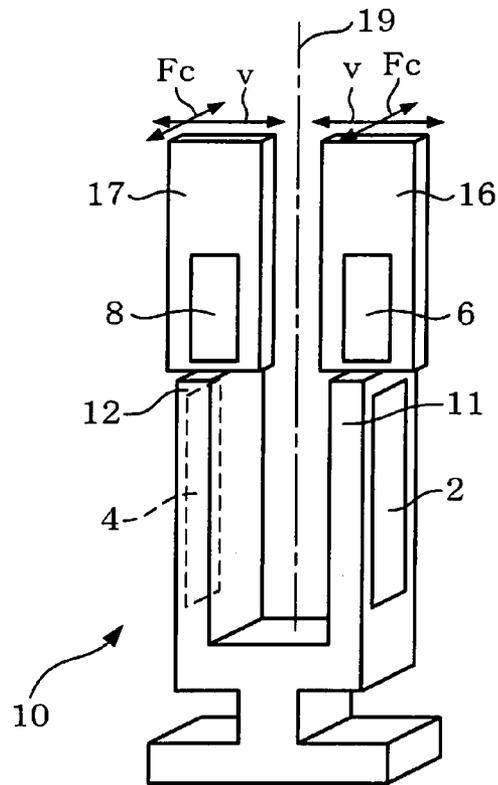


FIG. 15B

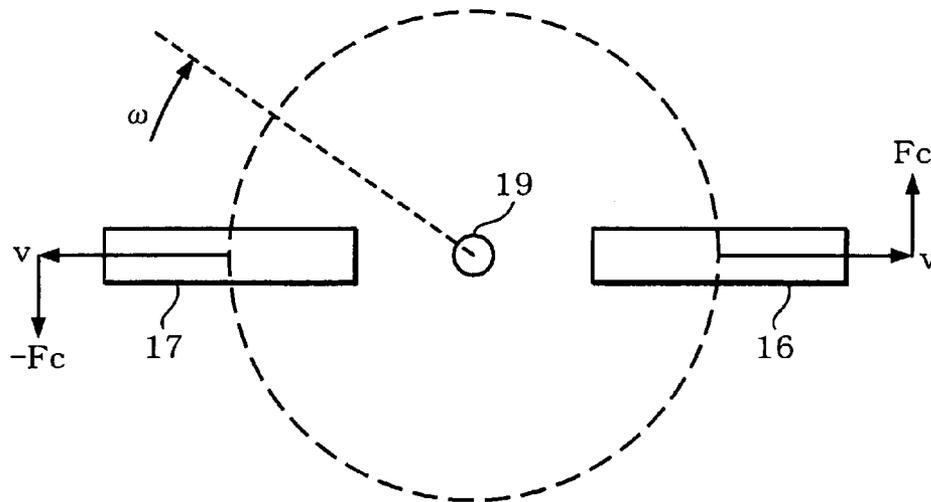


FIG. 16A BEFORE SYNCHRONOUS DETECTION

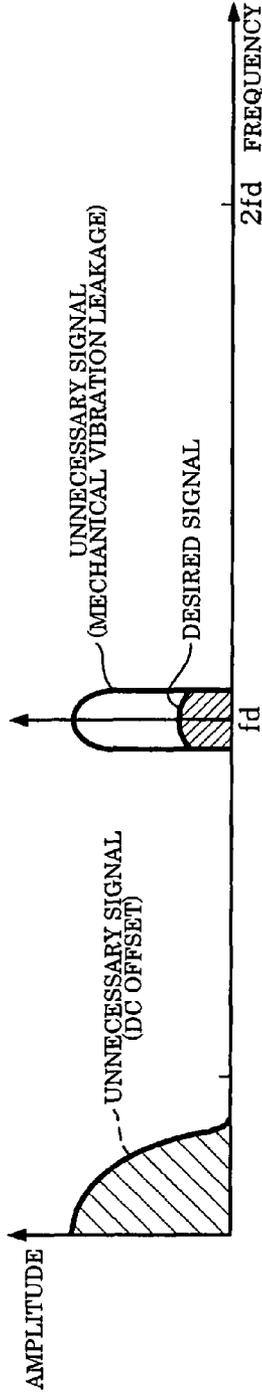


FIG. 16B AFTER SYNCHRONOUS DETECTION

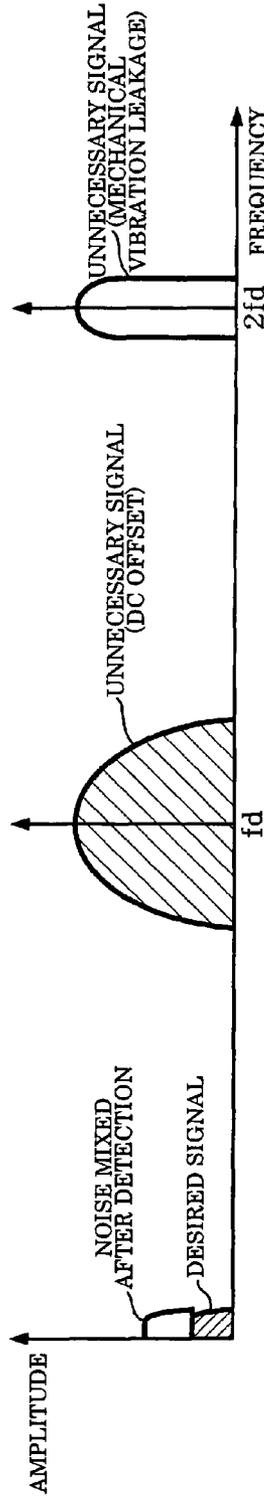


FIG. 16C AFTER FILTERING PROCESS

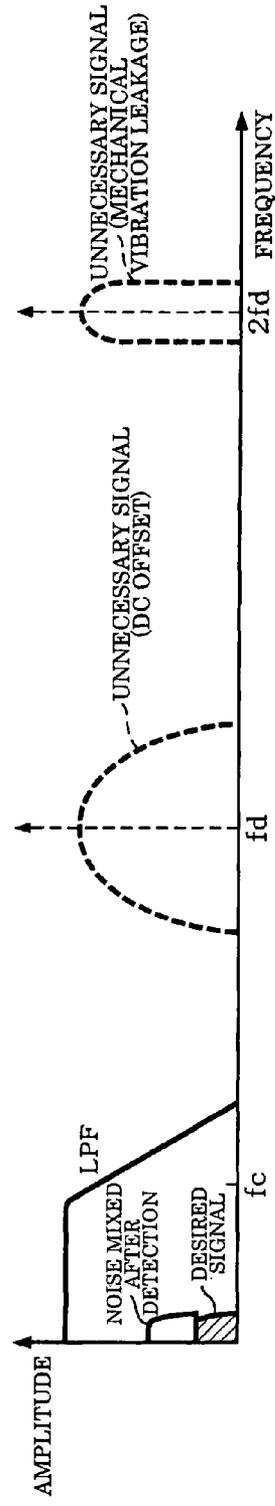


FIG. 17

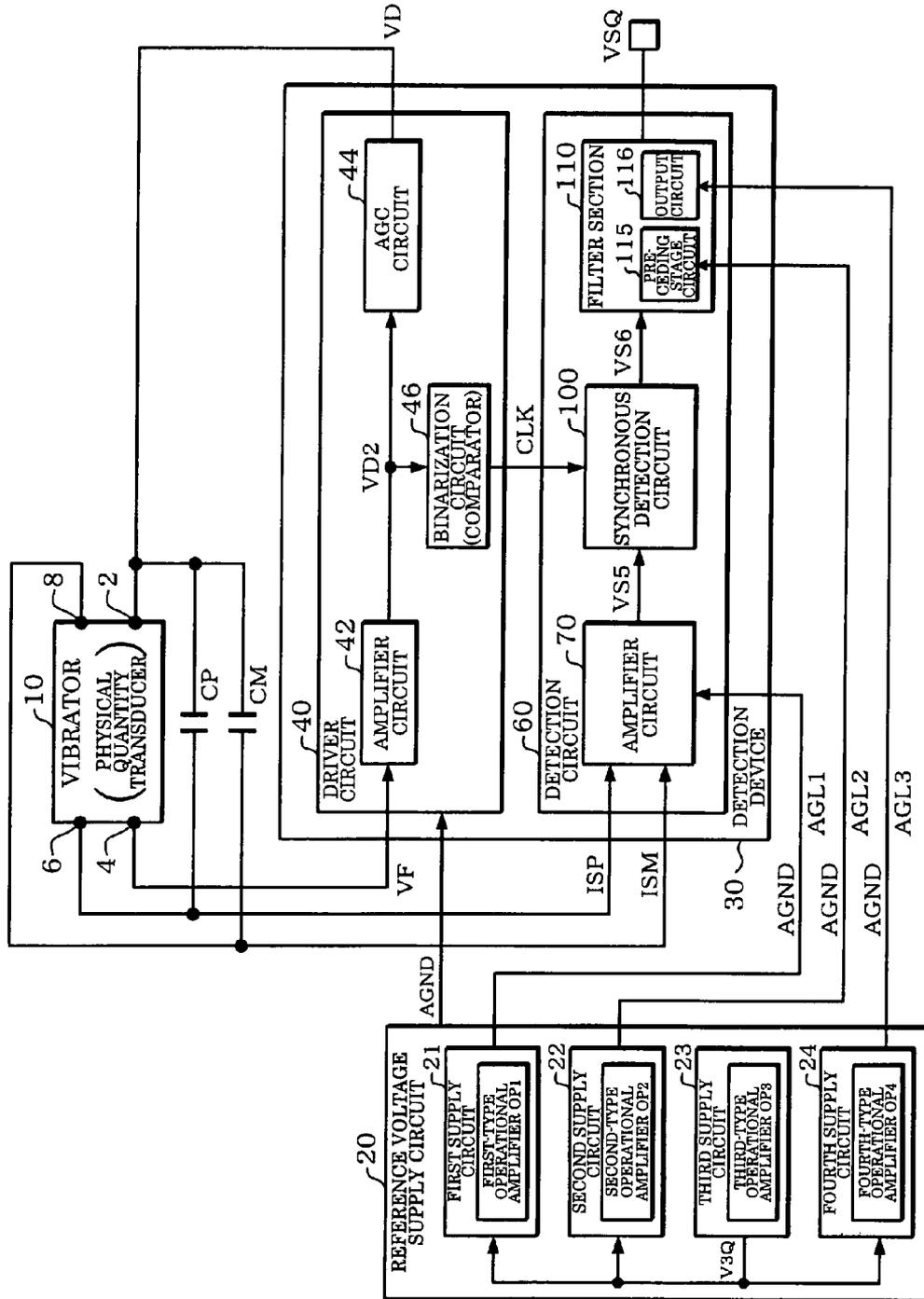


FIG. 18

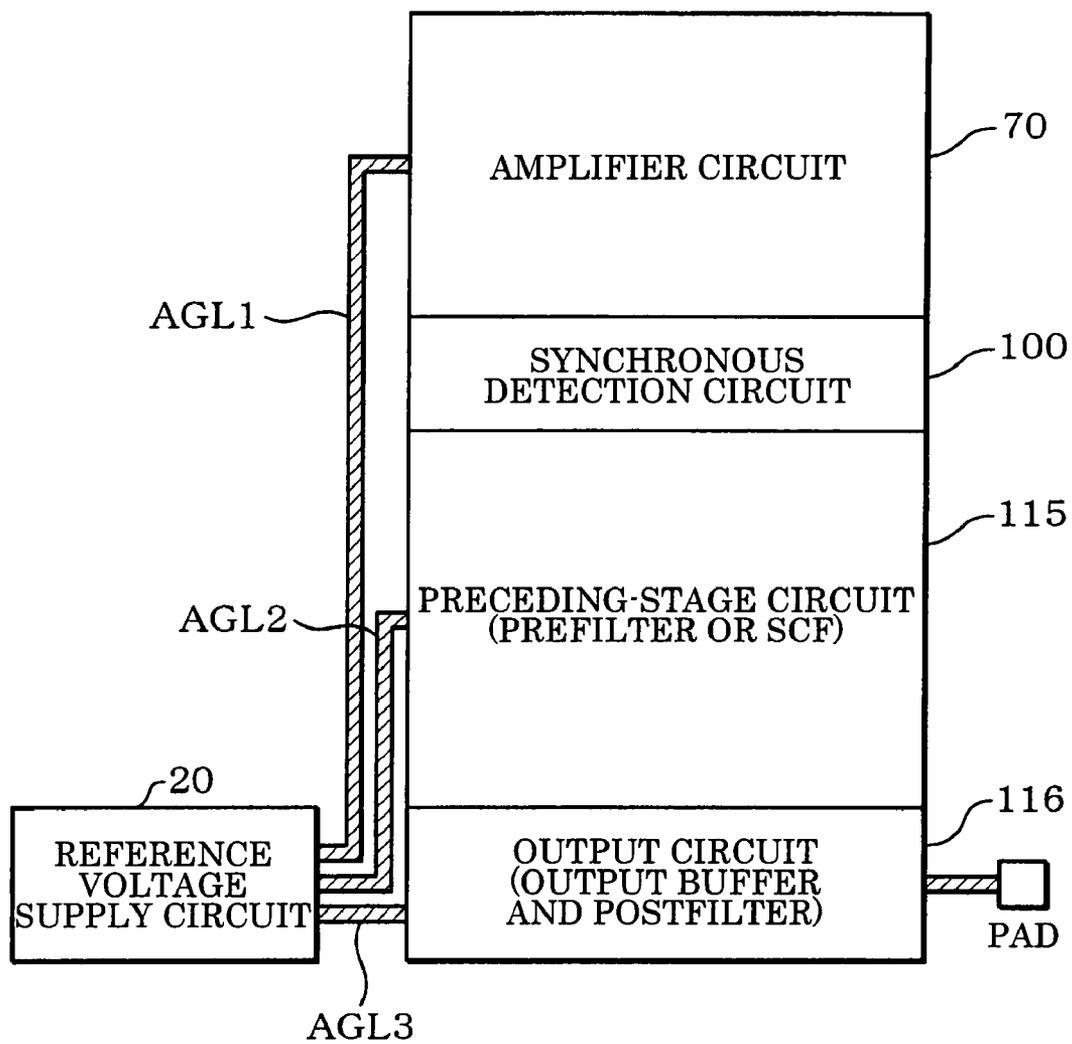


FIG. 19

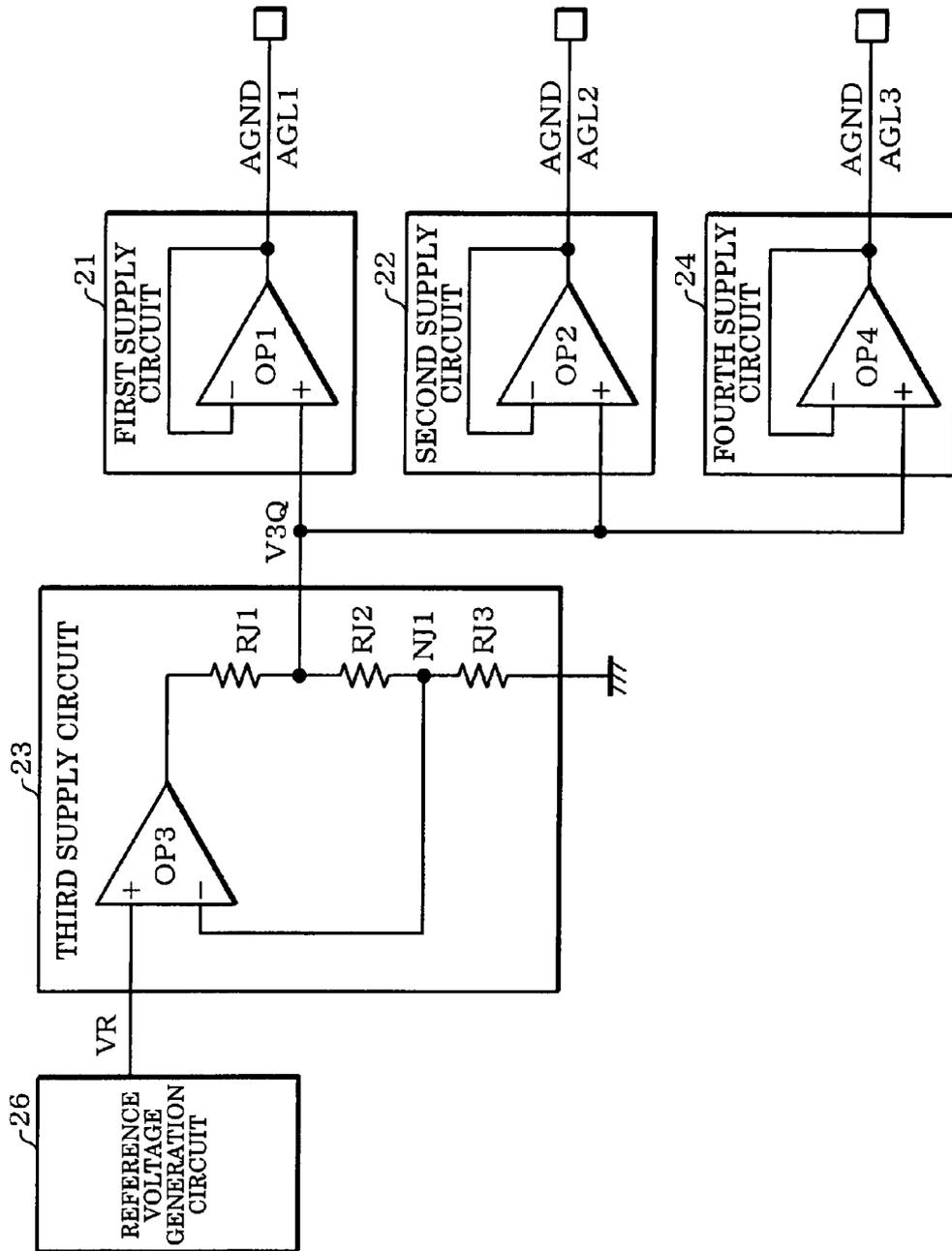


FIG. 20

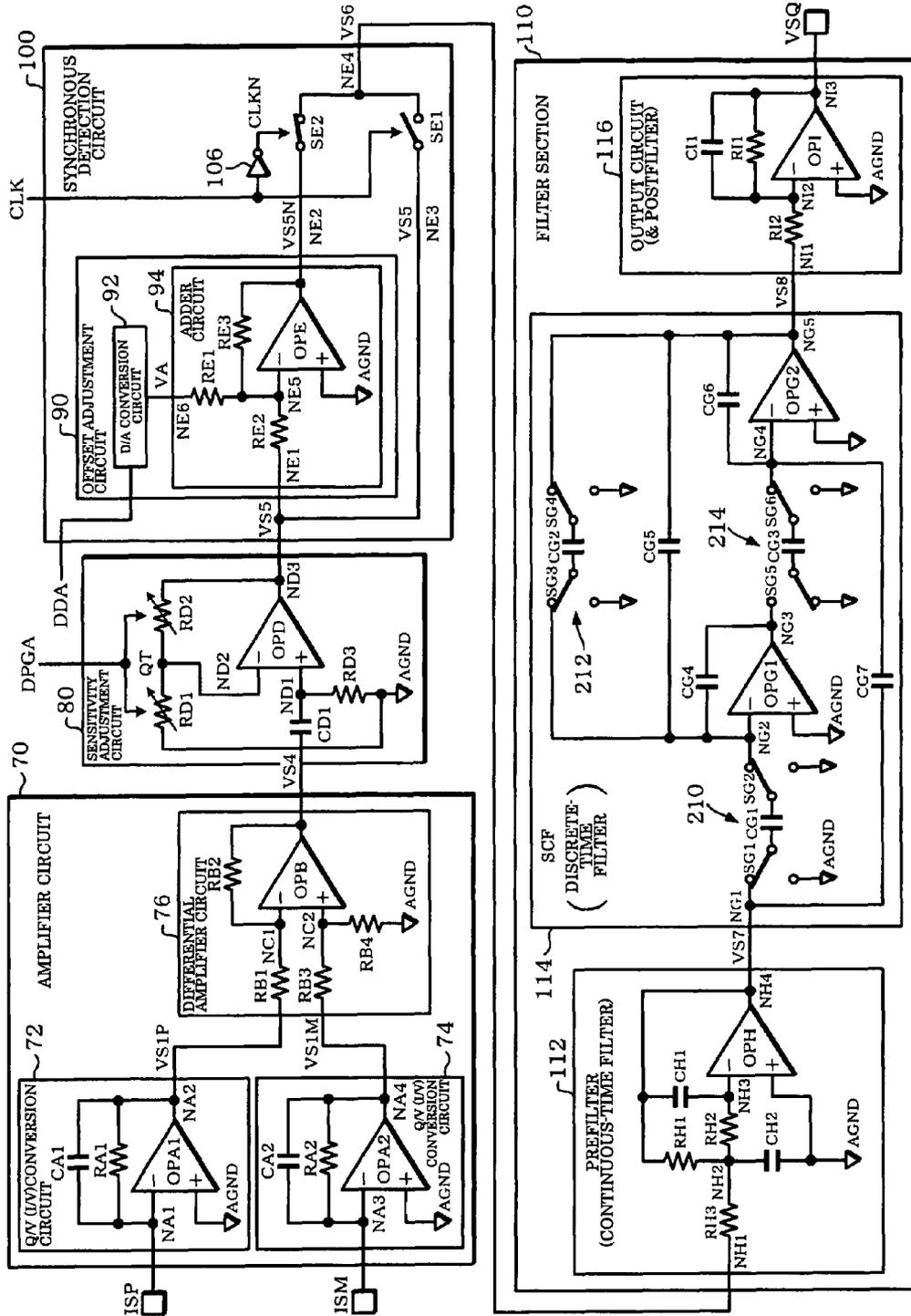


FIG. 21

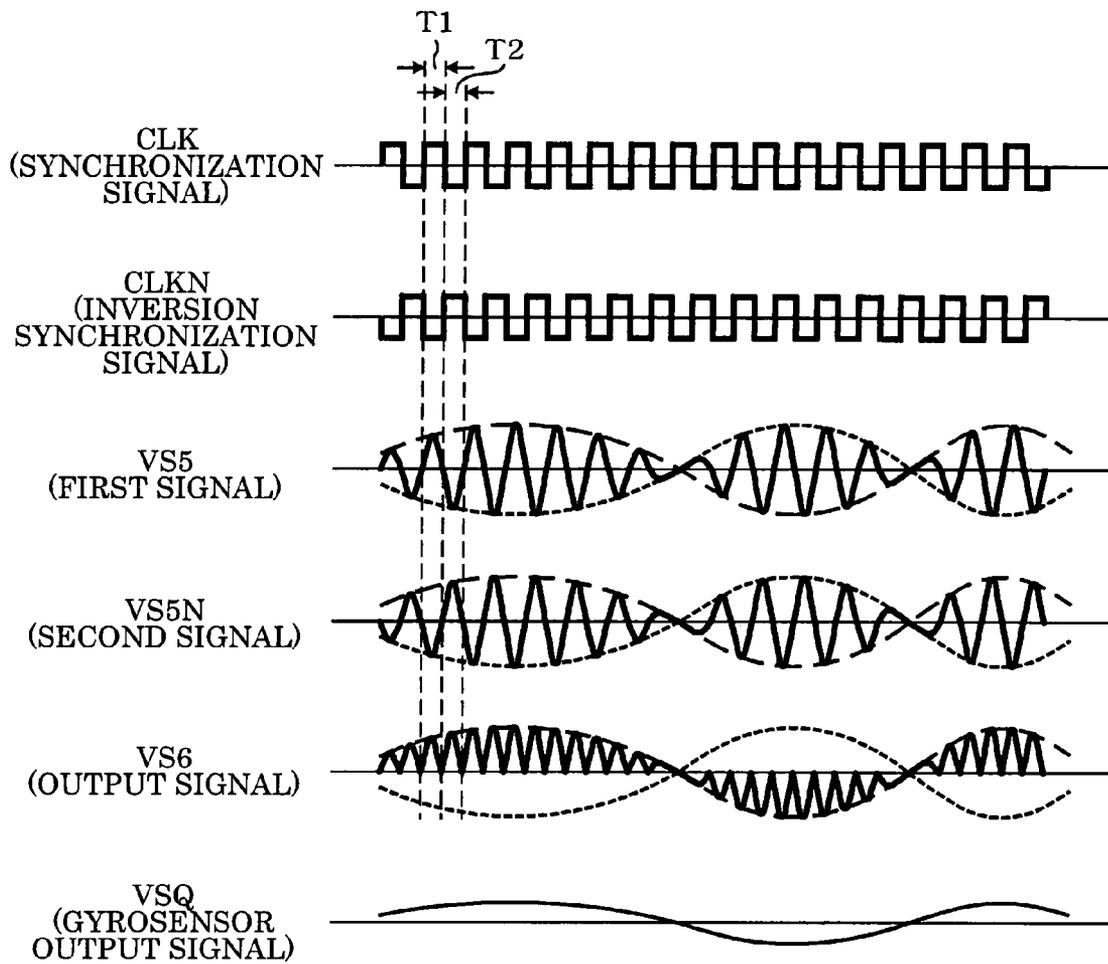


FIG. 22

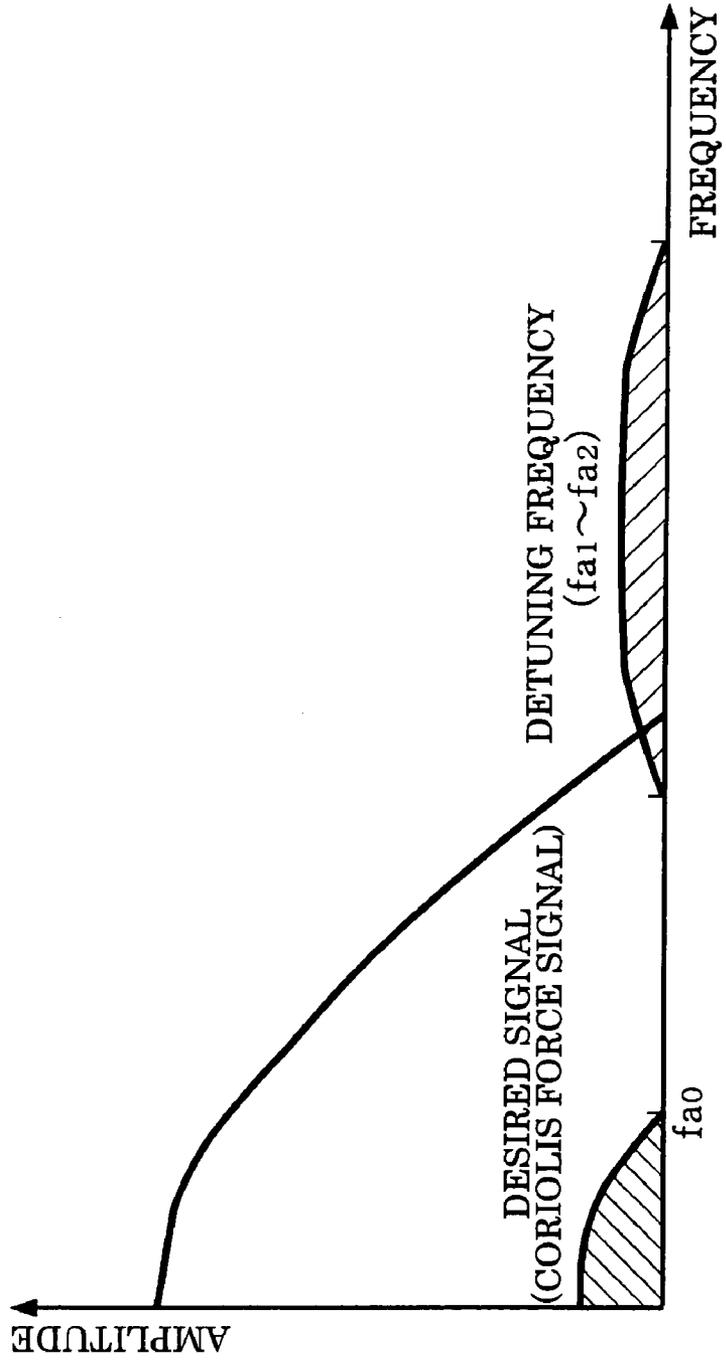
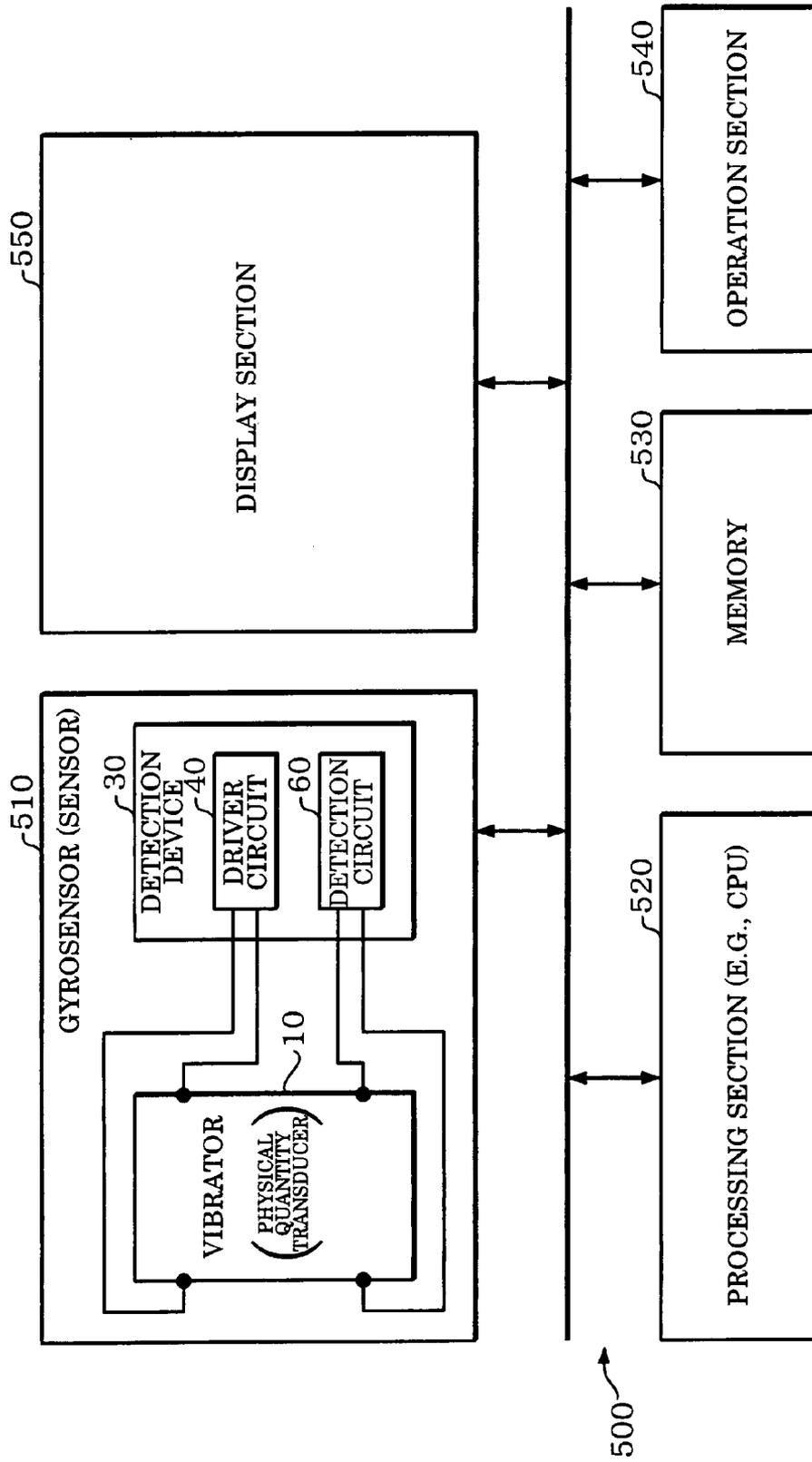


FIG. 23



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## REFERENCE VOLTAGE SUPPLY CIRCUIT, ANALOG CIRCUIT, AND ELECTRONIC INSTRUMENT

Japanese Patent Application No. 2006-305154 filed on 5  
Nov. 10, 2006, is hereby incorporated by reference in its  
entirety.

### BACKGROUND OF THE INVENTION

The present invention relates to a reference voltage supply  
circuit, an analog circuit, and an electronic instrument.

The noise of a transistor forming an analog circuit is clas-  
sified as thermal noise and flicker noise. Thermal noise pre-  
dominantly occurs in a high frequency band and is propor-  
tional to the absolute temperature. Flicker noise  
predominantly occurs in a low frequency band. The noise  
level of flicker noise increases as the signal frequency  
decreases.

In analog circuits such as a radio-controlled clock receiver  
device and a gyrosensor detection device, a frequency is  
converted using a mixer or the like (e.g., JP-A-3-226620).  
Specifically, the frequency of a carrier signal is converted into  
the frequency of a desired signal, for example. Therefore, a  
high signal frequency and a low signal frequency exist in a  
mixed state as the small-amplitude amplification target of an  
operational amplifier forming an analog circuit.

In known a reference voltage supply circuit which supplies  
an analog reference voltage to analog circuits such as a radio-  
controlled clock receiver device and a gyrosensor detection  
device, an operational amplifier has not been optimally sized  
taking such a difference in signal frequency into consider-  
ation. Moreover, a reduction in noise and power consumption  
in combination has not been taken into consideration.

### SUMMARY

According to one aspect of the invention, there is provided  
a reference voltage supply circuit comprising:

a first supply circuit that includes a reference-voltage first-  
type operational amplifier and supplies an analog reference  
voltage to a first analog reference voltage line; and

a second supply circuit that includes a reference-voltage  
second-type operational amplifier and supplies the analog  
reference voltage to a second analog reference voltage line;

when a channel width and a channel length of a differen-  
tial-stage transistor of a differential section of the reference-  
voltage first-type operational amplifier are respectively  
referred to as  $W1a$  and  $L1a$ , a bias current flowing through the  
differential section of the reference-voltage first-type opera-  
tional amplifier is referred to as  $Ia$ , a channel width and a  
channel length of a differential-stage transistor of a differen-  
tial section of the reference-voltage second-type operational  
amplifier are respectively referred to as  $W1b$  and  $L1b$ , and a  
bias current flowing through the differential section of the  
reference-voltage second-type operational amplifier is  
referred to as  $Ib$ ,  $W1b \times L1b > W1a \times L1a$  and  $Ia > Ib$  being sat-  
isfied.

According to another aspect of the invention, there is pro-  
vided an analog circuit comprising:

the above reference voltage supply circuit,

a first circuit to which the analog reference voltage is  
supplied from the first supply circuit of the reference voltage  
supply circuit through the first analog reference voltage line;  
and

a second circuit to which the analog reference voltage is  
supplied from the second supply circuit of the reference volt-  
age supply circuit through the second analog reference volt-  
age line.

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According to a further aspect of the invention, there is  
provided an electronic instrument comprising:  
the above analog circuit; and  
a processing section that performs processes based on  
detection information of the analog circuit.

### BRIEF DESCRIPTION OF THE SEVERAL VIEWS OF THE DRAWING

FIG. 1 shows a configuration example of a reference volt-  
age supply circuit according to one embodiment of the inven-  
tion and an analog circuit including the same.

FIG. 2 shows a configuration example of a radio-controlled  
clock receiver device.

FIG. 3 shows another configuration example of a radio-  
controlled clock receiver device.

FIGS. 4A and 4B are views illustrative of a noise analysis  
of an operational amplifier.

FIG. 5A to 5C are views illustrative of a noise reduction  
method according to one embodiment of the invention.

FIGS. 6A to 6C are views illustrative of the relationship  
among frequencies  $f1$  and  $f2$  and a corner frequency  $fcr$ .

FIGS. 7A and 7B are views illustrative of a method of  
setting a corner frequency  $fcr$  in first-type and second-type  
operational amplifiers.

FIGS. 8A and 8B are views illustrative of the relationship  
between an effective gate voltage and noise.

FIGS. 9A and 9B are views illustrative of simulation  
results according to one embodiment of the invention.

FIG. 10 is a bar graph for comparing one embodiment of  
the invention and a comparative example in terms of the noise  
level.

FIGS. 11A and 11B show layout examples of first-type and  
second-type operational amplifiers.

FIG. 12 shows a layout example of a third-type operational  
amplifier.

FIG. 13 shows a detailed configuration example of a ref-  
erence voltage supply circuit.

FIG. 14 shows a configuration example of a detection  
device.

FIGS. 15A and 15B are views illustrative of a vibrator.

FIGS. 16A to 16C are views illustrative of a frequency  
spectrum.

FIG. 17 shows a first modification of a detection device.

FIG. 18 shows a layout example of a detection circuit.

FIG. 19 shows another configuration example of a reference  
voltage supply circuit.

FIG. 20 shows a second modification of a detection device.

FIG. 21 shows a signal waveform example illustrative of  
synchronous detection.

FIG. 22 is a view illustrative of a detuning frequency.

FIG. 23 shows a configuration example of an electronic  
instrument and a gyrosensor.

### DETAILED DESCRIPTION OF THE EMBODIMENT

Aspects of the invention may provide a reference voltage  
supply circuit, an analog circuit, and an electronic instrument  
capable of reducing noise and power consumption.

According to one embodiment of the invention, there is  
provided a reference voltage supply circuit comprising:

a first supply circuit that includes a reference-voltage first-  
type operational amplifier and supplies an analog reference  
voltage to a first analog reference voltage line; and

a second supply circuit that includes a reference-voltage  
second-type operational amplifier and supplies the analog  
reference voltage to a second analog reference voltage line;

when a channel width and a channel length of a differen-  
tial-stage transistor of a differential section of the reference-

voltage first-type operational amplifier are respectively referred to as  $W1a$  and  $L1a$ , a bias current flowing through the differential section of the reference-voltage first-type operational amplifier is referred to as  $Ia$ , a channel width and a channel length of a differential-stage transistor of a differential section of the reference-voltage second-type operational amplifier are respectively referred to as  $W1b$  and  $L1b$ , and a bias current flowing through the differential section of the reference-voltage second-type operational amplifier is referred to as  $Ib$ ,  $W1b \times L1b > W1a \times L1a$  and  $Ia > Ib$  being satisfied.

According to this embodiment, the first supply circuit of the reference voltage supply circuit supplies the analog reference voltage to the first analog reference voltage line using the first-type operational amplifier. The second supply circuit supplies the analog reference voltage to the second analog reference voltage line using the second-type operational amplifier.

The WL product  $W1a \times L1a$  of the differential-stage transistor of the first-type operational amplifier and the WL product  $W1b \times L1b$  of the differential-stage transistor of the second-type operational amplifier satisfy the relationship  $W1b \times L1b > W1a \times L1a$ . Therefore, since the WL product  $W1b \times L1b$  of the second-type operational amplifier can be increased, flicker noise of the second-type operational amplifier can be reduced. This minimizes flicker noise superimposed on the analog reference voltage supplied from the second supply circuit. On the other hand, since the WL product  $W1a \times L1a$  of the first-type operational amplifier can be reduced, a situation can be prevented in which the circuit area of the first-type operational amplifier is unnecessarily increased.

The bias current  $Ia$  of the differential section of the first-type operational amplifier and the bias current  $Ib$  of the differential section of the second-type operational amplifier satisfy the relationship  $Ia > Ib$ . Therefore, since the bias current  $Ia$  of the first-type operational amplifier can be increased, thermal noise of the first-type operational amplifier can be reduced. This minimizes thermal noise superimposed on the analog reference voltage supplied from the first supply circuit. On the other hand, since the bias current  $Ib$  of the second-type operational amplifier can be reduced, a situation in which the current consumption of the second-type operational amplifier is unnecessarily increased can be prevented.

In the reference voltage supply circuit according to this embodiment,

when a frequency of an amplification target signal of a first circuit to which the analog reference voltage is supplied from the first supply circuit is referred to as  $f1$ , a frequency of an amplification target signal of a second circuit to which the analog reference voltage is supplied from the second supply circuit is referred to as  $f2$ , and a corner frequency of flicker noise and thermal noise in frequency-noise characteristics is referred to as  $fcr$ , the reference-voltage first-type operational amplifier may satisfy  $f1 - fcr < fcr - f2$ , and the reference-voltage second-type operational amplifier may satisfy  $fcr - f2 < f1 - fcr$ .

If the relationship  $f1 - fcr < fcr - f2$  is satisfied, the corner frequency  $fcr$  can be brought close to the frequency  $f1$ , whereby the noise and the power consumption of the operational amplifier can be reduced. If the relationship  $fcr - f2 < f1 - fcr$  is satisfied, the corner frequency  $fcr$  can be brought close to the frequency  $f2$ , whereby the noise and the area of the operational amplifier can be reduced.

In the reference voltage supply circuit according to this embodiment,

when a channel length of an active-load-stage transistor of the differential section of the reference-voltage second-type operational amplifier is referred to as  $L3b$ ,  $L1b < L3b$  may be satisfied.

This further reduces the flicker noise of the second-type operational amplifier.

In the reference voltage supply circuit according to this embodiment,

when a WL ratio of the differential-stage transistor of the reference-voltage first-type operational amplifier is referred to as  $RT1a$  and a WL ratio of an active-load-stage transistor of the reference-voltage first-type operational amplifier is referred to as  $RT3a$ ,  $RT1a > RT3a$  may be satisfied.

This further reduces the thermal noise of the first amplifier circuit.

In the reference voltage supply circuit according to this embodiment,

when an effective gate voltage of the differential-stage transistor of the reference-voltage second-type operational amplifier is referred to as  $Veff$ , a drain-source current is referred to as  $I_{ds}$ , a mobility is referred to as  $\mu$ , a gate capacitance per unit area is referred to as  $Cox$ , a WL ratio is referred to as  $RT1b$ , a Boltzmann constant is referred to as  $k$ , an absolute temperature is referred to as  $T$ , an amount of electronic charge is referred to as  $q$ , and a process variation parameter is referred to as  $P$  ( $P > 1$ ), the WL ratio  $RT1b$  may be set at a value satisfying the relationship

$$P \times (k \times T / q) > V_{eff} \{ 2 \times I_{ds} / (\mu \times Cox \times RT1b) \}^{1/2} > k \times T / q.$$

According to this configuration, since the differential-stage transistor of the second-type operational amplifier can be prevented from operating in the weak inversion region or at the boundary between the weak inversion region and the strong inversion region, an increase in flicker noise due to an excessive increase in the WL ratio  $RT1b$  can be minimized.

In the reference voltage supply circuit according to this embodiment,

when the area of an arrangement region of the differential-stage transistor among elements forming the reference-voltage second-type operational amplifier is referred to as  $Sdf$  and the area of an arrangement region of the elements forming the reference-voltage second-type operational amplifier other than the differential-stage transistor is referred to as  $Sre$ ,  $Sdf > Sre$  may be satisfied.

This enables the differential-stage transistor with a large WL product to be disposed in the arrangement region with an area of  $Sdf$ , whereby flicker noise can be reduced.

In the reference voltage supply circuit according to this embodiment,

the differential-stage transistor of the reference-voltage second-type operational amplifier may include  $J$  ( $J > 2$ ) transistors connected in parallel; and

the  $J$  transistors connected in parallel may be disposed in the arrangement region of the differential-stage transistor.

This enables the WL ratio to be increased while increasing the WL product of the differential-stage transistor, whereby flicker noise can be efficiently reduced.

In the reference voltage supply circuit according to this embodiment,

the active-load-stage transistor of the reference-voltage second-type operational amplifier may include  $I$  ( $I > 2$ ) transistors connected in parallel; and

the  $J$  transistors forming the differential-stage transistor may be arranged along a direction  $X$ , and the  $I$  transistors

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forming the active-load-stage transistor may be arranged along the direction X on a direction Y side of the J transistors.

This enables the J transistors forming the differential-stage transistor and the J transistors forming the active-load-stage transistor to be efficiently disposed symmetrically, whereby the layout efficiency can be increased.

In the reference voltage supply circuit according to this embodiment,

the first supply circuit may be a circuit which performs voltage impedance conversion using the reference-voltage first-type operational amplifier; and

the second supply circuit may be a circuit which performs voltage impedance conversion using the reference-voltage second-type operational amplifier.

This ensures that the analog reference voltage at a stable potential can be supplied.

The reference voltage supply circuit according to this embodiment may further comprise:

a third supply circuit that is provided in a preceding stage of the first and second supply circuits, includes a reference-voltage third-type operational amplifier, and supplies a voltage to the first and second supply circuits;

when a channel width and a channel length of a differential-stage transistor of a differential section of the reference-voltage third-type operational amplifier are respectively referred to as  $W1c$  and  $L1c$  and a bias current which flows through the differential section of the reference-voltage third-type operational amplifier is referred to as  $Ic$ ,  $W1c \times L1c > W1a \times L1a$  and  $Ic > Ib$  may be satisfied.

This minimizes thermal noise and flicker noise of the output voltage of the third supply circuit. This minimizes a situation in which the thermal noise of the output voltage is transmitted to the first analog reference voltage line through the first supply circuit, or the flicker noise of the output voltage is transmitted to the second analog reference voltage line through the second supply circuit.

In the reference voltage supply circuit according to this embodiment,  $W1c \times L1c > W1b \times L1b$  and  $Ic > Ia$  may be satisfied.

According to another embodiment of the invention, there is provided an analog circuit comprising:

one of the above reference voltage supply circuits,

a first circuit to which the analog reference voltage is supplied from the first supply circuit of the reference voltage supply circuit through the first analog reference voltage line; and

a second circuit to which the analog reference voltage is supplied from the second supply circuit of the reference voltage supply circuit through the second analog reference voltage line.

According to this embodiment, the thermal noise of the analog reference voltage supplied to the first circuit from the first supply circuit can be reduced, and the flicker noise of the analog reference voltage supplied to the second circuit from the second supply circuit can be reduced. Therefore, the thermal noise and the flicker noise of the first and second circuits can be reduced, whereby the signal-to-noise ratio (SNR) of the analog circuit can be increased.

The analog circuit according to this embodiment may further comprise:

a mixer that mixes a signal with a specific frequency into a signal including a desired signal;

the first circuit may be a circuit provided on a preceding stage of the mixer; and

the second circuit may be a circuit provided on a subsequent stage of the mixer.

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When providing such a mixer, the signal frequency in the first circuit in the preceding stage of the mixer differs from the signal frequency in the second circuit in the subsequent stage of the mixer. According to this embodiment, noise and power consumption can be reduced by selectively using the first-type operational amplifier and the second-type operational amplifier in the reference voltage supply circuit which supplies the analog reference voltage to the first and second circuits.

In the analog circuit according to this embodiment, the first circuit may be a first amplifier circuit which amplifies an input signal; and

the reference voltage supply circuit may supply the analog reference voltage to the first amplifier circuit through the first analog reference voltage line.

This enables the thermal noise of the first amplifier circuit to be reduced, whereby the noise of the analog circuit can be reduced.

In the analog circuit according to this embodiment, the second circuit may be a second amplifier circuit that amplifies the mixed signal from the mixer or a filter section that filters the mixed signal from the mixer; and

the reference voltage supply circuit may supply the analog reference voltage to the second amplifier circuit or the filter section through the second analog reference voltage line.

This enables the flicker noise of the second amplifier circuit or the filter section to be reduced, whereby the noise of the analog circuit can be reduced.

According to a further embodiment of the invention, there is provided an electronic instrument comprising:

one of the above analog circuits; and

a processing section that performs processes based on detection information of the analog circuit.

Preferred embodiments of the invention are described below in detail. Note that the embodiments described below do not in any way limit the scope of the invention defined by the claims laid out herein. Note that all elements of the embodiments described below should not necessarily be taken as essential requirements for the invention. For example, the following description is given taking a radio-controlled clock receiver device or a gyrosensor detection device as a reference voltage supply circuit to which the invention is applied. Note that the invention is not limited thereto.

#### 1. Configuration of Reference Voltage Supply Circuit and Analog Circuit

FIG. 1 shows a configuration example of a reference voltage supply circuit **20** according to this embodiment and an analog circuit (analog front-end circuit) **300** including the reference voltage supply circuit **20**. The analog circuit **300** includes a first circuit **310** and a second circuit **320**.

The first circuit **310** includes a circuit of which the frequency of the amplification target signal (small-signal amplification target signal of operational amplifier) is a first frequency. The second circuit **320** is a circuit of which the frequency of the amplification target signal is a second frequency lower than the first frequency.

For example, an input signal (reception signal or sensor signal) with the first frequency from an antenna, a sensor, or the like is input to the first circuit **310**. The first circuit **310** includes an amplifier circuit, for example. The amplifier circuit amplifies the input signal. In this case, the input signal (carrier signal) as the amplification target signal is a signal with the high first frequency.

A mixer (frequency conversion circuit) **322** may be provided between the first circuit **310** and the second circuit **320**.

Specifically, the first circuit **310** may be a circuit provided in the preceding stage of the mixer **322**, and the second circuit **320** may be a circuit provided in the subsequent stage of the mixer **322**. The mixer **322** mixes a signal with a given frequency (e.g., station frequency signal or synchronization signal) into a signal including a desired signal.

A signal of which the frequency has been converted into the second frequency due to mixing (frequency conversion) of the mixer **322** is input to the second circuit **320**. An amplifier circuit, a filter section, or an output circuit of the second circuit **320** subjects the signal with the second frequency (amplification target signal) to small-amplitude amplification.

The reference voltage supply circuit **20** supplies a voltage AGND (analog reference voltage in a broad sense) to the first circuit **310** and the second circuit **320**. The reference voltage supply circuit **20** includes a first supply circuit **21** and a second supply circuit **22**. The first supply circuit **21** supplies the voltage AGND (analog ground) to the first circuit **310**. The second supply circuit **22** supplies the voltage AGND to the second circuit **320**. The first supply circuit **21** includes a reference-voltage first-type operational amplifier OP1, and the second supply circuit **22** includes a reference-voltage second-type operational amplifier OP2.

The reference-voltage first-type operational amplifier OP1 is an operational amplifier of which the thermal noise at the first frequency (e.g., carrier frequency, modulation frequency, or resonance frequency) is lower than that of the second-type operational amplifier OP2, for example. The reference-voltage second-type operational amplifier OP2 is an operational amplifier of which the flicker noise at the second frequency (e.g., frequency of a desired signal carried by a carrier signal or maximum frequency in a frequency band of a desired signal) is lower than that of the first-type operational amplifier OP1.

Specifically, the frequency (e.g., several tens of kilohertz to several hundreds of kilohertz) of the amplification target signal of the first circuit **310** (amplification target signal of the operational amplifier included in the first circuit **310**) is referred to as  $f_1$ , the frequency (e.g., several hertz to several hundreds of hertz) of the amplification target signal of the second circuit **320** (amplification target signal of the operational amplifier included in the first circuit **320**) is referred to as  $f_2$ , and the corner frequency of flicker noise and thermal noise is referred to as  $f_{cr}$ . In this case, the first-type operational amplifier OP1 satisfies the relationship  $f_1 - f_{cr} < f_{cr} - f_2$ , for example. Specifically, the first-type operational amplifier OP1 is sized so that the first frequency  $f_1$  is set to be close to the corner frequency  $f_{cr}$ . The second-type operational amplifier OP2 satisfies the relationship  $f_{cr} - f_2 < f_1 - f_{cr}$ , for example. Specifically, the second-type operational amplifier OP2 is sized so that the second frequency  $f_2$  is set to be close to the corner frequency  $f_{cr}$ .

The channel width and the channel length of the differential-stage transistor of the differential section of the first-type operational amplifier OP1 are respectively referred to as  $W1a$  and  $L1a$ , and the bias current (current value) flowing through the differential section is referred to as  $Ia$ . The channel width and the channel length of the differential-stage transistor of the differential section of the second-type operational amplifier OP2 are respectively referred to as  $W1b$  and  $L1b$ , and the bias current flowing through the differential section is referred to as  $Ib$ . In this case, the relationship  $W1b \times L1b > W1a \times L1a$  and  $Ia > Ib$  is satisfied, for example.

As shown in FIG. 1, the reference voltage supply circuit **20** may include a third supply circuit **23**. The third supply circuit **23** is provided in the preceding stage of the first and second

supply circuits **21** and **22**, and supplies an output voltage  $V3Q$  to the first and second supply circuits **21** and **22**. The first and second supply circuits **21** and **22** subject the output voltage  $V3Q$  from the third supply circuit **23** to impedance conversion and outputs the voltage AGND.

The third supply circuit **23** includes a reference-voltage third-type operational amplifier OP3. The reference-voltage third-type operational amplifier OP3 is an operational amplifier of which the thermal noise at the frequency of the carrier signal is lower than that of the second-type operational amplifier OP2 (or the first-type operational amplifier OP1) and the flicker noise at the frequency of the desired signal is lower than that of the first-type operational amplifier OP1 (or the second-type operational amplifier OP2). For example, when the channel width and the channel length of the differential-stage transistor of the differential section of the third-type operational amplifier OP3 are respectively referred to as  $W1c$  and  $L1c$ , and the bias current flowing through the differential section is referred to as  $Ic$ , the relationship  $W1c \times L1c > W1a \times L1a$  and  $Ic > Ib$  is satisfied. Alternatively, the relationship  $W1c \times L1c > W1b \times L1b$  and  $Ic > Ia$  may be satisfied.

FIGS. 2 and 3 show configuration examples of a radio-controlled clock receiver device as an example of the analog circuit **300**. The receiver device is not limited to the configurations shown in FIGS. 2 and 3. Various modification may be made such as omitting some elements or adding another element.

The receiver device shown in FIG. 2 is an example of a direct-conversion receiver device. At present, a long-frequency standard radio wave containing a time code (time data) is transmitted in each country (e.g., Japan, Germany, and the United Kingdom). In Japan, a long-frequency standard radio wave (40 KHz and 60 KHz) amplitude-modulated by the time code is transmitted from two stations. Specifically, the time data is transmitted as binary data in cycles of 60 seconds. The radio-controlled clock receives such time code radio waves and corrects the time data of a clock circuit. Therefore, the receiver device of the radio-controlled clock extracts a signal at a desired frequency by detecting and demodulating the received radio waves to obtain the time code.

In FIG. 2, an antenna **330** formed using a bar antenna or the like receives the long-frequency standard radio wave, and the received radio wave is converted into an electric signal and output. An amplifier circuit (RF amplifier circuit) **332** amplifies and outputs the signal from the antenna **330**. A filter section **334** has high-pass filter frequency characteristics, for example. The filter section **334** filters the signal from the amplifier circuit **332**.

A mixer (frequency conversion circuit) **336** mixes a signal with a local oscillation frequency from a local oscillation circuit **344** into the signal from the filter section **334** to directly convert the signal into a baseband signal (several hertz) (direct conversion).

The amplifier circuit **338** amplifies the signal from the mixer **336**. A filter section **340** has low-pass filter frequency characteristics, for example. The filter section **340** filters the signal from the amplifier circuit **338**. A demodulation section **342** demodulates the signal from the filter section **340**, and outputs the time code obtained by demodulation. The radio-controlled clock corrects the time data using the time code.

The receiver device shown in FIG. 3 is an example of a superheterodyne receiver device. An amplifier circuit **352** amplifies a signal from an antenna **350**. A filter section **354** has band-pass filter frequency characteristics, for example. The filter section **354** filters the signal from the amplifier circuit **352**.

A mixer 356 mixes a signal with a local oscillation frequency from a local oscillation circuit 364 into the signal from the filter section 354 to generate a signal with an intermediate frequency (several hundreds of hertz) (superheterodyne conversion).

A filter section 358 has band-pass filter frequency characteristics, for example. The filter section 358 filters the signal from the mixer 356 so that a frequency component within a specific frequency range around the intermediate frequency passes through and a frequency component outside the specific frequency range is blocked. A detection circuit 360 detects (e.g., envelope detection) the signal from the filter section 358. A demodulation section 362 demodulates the detection signal from the detection circuit 360, and outputs the time code obtained by demodulation.

In FIG. 2, the amplifier circuit 332 (first amplifier circuit) and the filter section 334 correspond to the first circuit 310 shown in FIG. 1, for example. The first supply circuit 21 supplies the voltage AGND (analog reference voltage) to the amplifier circuit 332 and the filter section 334 through an AGND line (analog reference voltage line) AGL1.

In FIG. 2, the amplifier circuit 338 (second amplifier circuit) and the filter section 340 correspond to the second circuit 320 shown in FIG. 1, for example. The second supply circuit 22 supplies the voltage AGND to the amplifier circuit 338 and the filter section 340 through an AGND line AGL2.

In FIG. 3, the amplifier circuit 352 and the filter section 354 correspond to the first circuit 310 shown in FIG. 1, for example. The first supply circuit 21 supplies the voltage AGND to the amplifier circuit 352 and the filter section 354 through the AGND line AGL1.

In FIG. 3, the filter section 358 and the detection circuit 360 correspond to the second circuit 320 shown in FIG. 1, for example. The second supply circuit 22 supplies the voltage AGND to the filter section 358 and the detection circuit 360 through the AGND line AGL2.

The analog circuit 300 to which the voltage AGND (analog reference voltage) is supplied from the reference voltage supply circuit 20 according to this embodiment is not limited to the radio-controlled clock receiver devices shown in FIGS. 2 and 3. For example, the analog circuit 300 may be applied to an infrared remote control receiver device, or may be applied to detection devices of various sensors such as a gyrosensor described later.

The first circuit 310 shown in FIG. 1 may include the first-type operational amplifier OP1, and the second circuit 320 may include the second-type operational amplifier OP2. Likewise, the amplifier circuit 332 and the filter section 334 shown in FIG. 2 and the amplifier circuit 352 and the filter section 354 shown in FIG. 3 may include the first-type operational amplifier OP1. The amplifier circuit 338 and the filter section 340 shown in FIG. 2 and the filter section 358 and the detection circuit 360 shown in FIG. 3 may include the second-type operational amplifier OP2. This reduces the thermal noise and flicker noise of these circuits, whereby the SNR can be further increased.

## 2. Noise Reduction Method

### 2.1 Noise Analysis

FIG. 4A shows a configuration example of an operational amplifier used in this embodiment. The operational amplifier includes a differential section 200 and an output section 210.

The differential section 200 includes differential-stage transistors M1 and M2 and active-load-stage transistors M3 and M4. The differential section 200 also includes a bias-stage transistor M5. The differential-stage transistors M1 and M2 are provided between a node N1 and nodes N2 and N3,

respectively. Differential input signals IM and IP are input to the gates of the differential-stage transistors M1 and M2. The active-load-stage transistors M3 and M4 are provided between the nodes N2 and N3 and a power supply AGND (first power supply), respectively. The node N2 is connected with the gates of the active-load-stage transistors M3 and M4. The bias-stage transistor M5 is provided between a power supply VDD (second power supply) and the node N1. A bias node N4 of a bias circuit 212 formed of a transistor M8 and a current source IS is connected with the gate of the bias-stage transistor M5. This allows a bias current IBD corresponding to a bias current IBS of the bias circuit 212 to flow through the differential section 200.

The output section 210 includes a drive-stage transistor M6 and a bias-stage transistor M7 provided between the power supply VDD and the power supply AGND. The output node N3 of the differential section 200 is connected with the gate of the drive-stage transistor M6, and the bias node N4 is connected with the gate of the bias-stage transistor M7. A phase-compensation capacitor CF and a resistor RF are provided between the nodes N3 and N5.

The configuration of the operational amplifier according to this embodiment is not limited to the configuration shown in FIG. 4A. FIG. 4A shows an example in which the differential-stage transistors M1 and M2 and the bias-stage transistor M5 are P-type transistors and the active-load-stage transistors M3 and M4 are N-type transistors. Note that the transistors M1, M2, and M5 may be N-type transistors and the transistors M3 and M4 may be P-type transistors. Modifications may also be made such as omitting some of the elements (transistor and capacitor) shown in FIG. 4A or adding another element.

Noise analysis on the operational amplifier shown in FIG. 4A is described below. FIG. 4B shows a small-signal equivalent circuit of the transistor. Since noise is expressed in units of  $V^2$  ( $V^2/Hz$ ), the equivalent circuit shown in FIG. 4B is also expressed in units of  $V^2$ . In the equivalent circuit shown in FIG. 4B, in order to calculate the input-referred noise (gate-referred noise) of the transistor, a voltage source with a noise of  $S_{vg}=V_n^2$  is provided at the gate of the transistor. A current source of  $gm^2 (V_{gs}^2+V_n^2)$  and a resistor of  $1/g_{ds}^2$  are provided between the drain and the source.

As shown in FIG. 5A, noise is classified as flicker noise (1/f noise) and thermal noise. Flicker noise occurs when electrons are trapped by or released from dangling bonds at the interface between a gate oxide film and a silicon substrate. Flicker noise increases as the frequency decreases. On the other hand, thermal noise occurs due to random movement of electrons when the channel region of the transistor is considered to be a resistor. Thermal noise is proportional to the absolute temperature.

In the input-referred noise equivalent circuit shown in FIG. 4B, flicker noise and thermal noise are respectively calculated by the following equations (1) and (2).

$$V_n^2 = \frac{K}{C_{OX} \times W \times L \times f} \quad (1)$$

$$V_n^2 = \frac{8}{3} \times \frac{k \times T}{g_m} \quad (2)$$

In the equation (1), Cox represents the gate capacitance of the transistor per unit area, W represents the channel width, L represents the channel length, f represents the frequency, and K represents the flicker noise constant depending on the manufacturing process. In the equation (2), gm represents the

transconductance,  $k$  represents the Boltzmann constant, and  $T$  represents the absolute temperature.

In this embodiment, the transfer function is calculated by replacing the operational amplifier circuit shown in FIG. 4A with the equivalent circuit shown in FIG. 4B. In this case, only the higher-order terms accounting for 99% of the whole are derived by numerical analysis on the assumption that the size (W and L), the noise level, and the drain-source current of all the transistors of the operational amplifier are the same. The noise  $S_{vg}$  (noise spectrum) of the operational amplifier is calculated by the following equation (3).

$$S_{vg} = V_{n1}^2 + V_{n2}^2 + \frac{g_{m3}^2 \times V_{n3}^2}{g_{m1}^2} + \frac{g_{m3}^2 \times V_{n4}^2}{g_{m1}^2} \quad (3)$$

In the equation (3),  $V_{n1}$ ,  $V_{n2}$ ,  $V_{n3}$ , and  $V_{n4}$  represent the gate-noise voltages of the transistors M1, M2, M3, and M4 shown in FIG. 4A, and  $g_{m1}$ ,  $g_{m2}$ ,  $g_{m3}$ , and  $g_{m4}$  represent the transconductances of the transistors M1, M2, M3, and M4.

As is clearly from the numerical analysis result of the equation (3), most of the noise  $S_{vg}$  of the operational amplifier is caused by noise of the differential-stage transistors M1 and M2 and the active-load-stage transistors M3 and M4 of the differential section 200 shown in FIG. 4A. Therefore, the channel widths W and the channel lengths L of the transistors M1, M2, M3, and M4 may be optimized when sizing the operational amplifier.

Flicker noise is analyzed as follows. The gate-noise voltages  $V_{n1}$ ,  $V_{n2}$ ,  $V_{n3}$ , and  $V_{n4}$  with regard to flicker noise are calculated by the following equations (4), (5), (6), and (7) from the equation (1).

$$V_{n1} = \left( \frac{K_p}{C_{OX} \times W1 \times L1 \times f} \right)^{\frac{1}{2}} \quad (4)$$

$$V_{n2} = \left( \frac{K_p}{C_{OX} \times W1 \times L1 \times f} \right)^{\frac{1}{2}} \quad (5)$$

$$V_{n3} = \left( \frac{K_n}{C_{OX} \times W3 \times L3 \times f} \right)^{\frac{1}{2}} \quad (6)$$

$$V_{n4} = \left( \frac{K_n}{C_{OX} \times W3 \times L3 \times f} \right)^{\frac{1}{2}} \quad (7)$$

In the equations (4) to (7), W1 and L1 respectively represent the channel width and the channel length of the differential-stage transistors M1 and M2, and W3 and L3 respectively represent the channel width and the channel length of the active-load-stage transistors M3 and M4. Note that the equations (4) to (7) are given on the assumption that the channel width W2 and the channel length L2 of the transistor M2 are the same as the channel width W1 and the channel length L1 of the transistor M1, and the channel width W4 and the channel length L4 of the transistor M4 are the same as the channel width W3 and the channel length L3 of the transistor M3.  $K_p$  and  $K_n$  respectively represent the process-dependent constants of the P-type transistor and the N-type transistor.

The transconductance  $g_{m1}$  (=  $g_{m2}$ ) of the differential-stage transistors M1 and M2 and the transconductance  $g_{m3}$  (=  $g_{m4}$ ) of the active-load-stage transistors M3 and M4 are calculated by the following equations (8) and (9).

$$g_{m1} = \left( \frac{2\mu_p \times C_{OX} \times W1}{L1} \times I_{ds} \right)^{\frac{1}{2}} \quad (8)$$

$$g_{m3} = \left( \frac{2\mu_n \times C_{OX} \times W3}{L3} \times I_{ds} \right)^{\frac{1}{2}} \quad (9)$$

In the equations (8) and (9),  $\mu_p$  and  $\mu_n$  respectively represent the mobilities of the P-type transistor and the N-type transistor, and  $I_{ds}$  represents the drain-source current of the transistor, provided that the transistors M1 to M4 have the same drain-source current  $I_{ds}$ .

Flicker noise  $S_{vgFlc}$  of the operational amplifier is calculated by the following equation (10) by substituting the equations (4) to (9) into the equation (3).

$$S_{vgFlc} = \frac{2K_p}{C_{OX} \times W1 \times L1 \times f} + \frac{2L1 \times \mu_n \times K_n}{\mu_p \times W1 \times L3^2 \times C_{OX} \times f} \quad (10)$$

Thermal noise is analyzed as follows. The gate-noise voltages  $V_{n1}$ ,  $V_{n2}$ ,  $V_{n3}$ , and  $V_{n4}$  with regard to thermal noise are calculated by the following equations (11), (12), (13), and (14) from the equation (2).

$$V_{n1} = \left( \frac{8}{3} \times \frac{k \times T}{g_{m1}} \right)^{\frac{1}{2}} \quad (11)$$

$$V_{n2} = \left( \frac{8}{3} \times \frac{k \times T}{g_{m1}} \right)^{\frac{1}{2}} \quad (12)$$

$$V_{n3} = \left( \frac{8}{3} \times \frac{k \times T}{g_{m3}} \right)^{\frac{1}{2}} \quad (13)$$

$$V_{n4} = \left( \frac{8}{3} \times \frac{k \times T}{g_{m3}} \right)^{\frac{1}{2}} \quad (14)$$

Thermal noise  $S_{vgThm}$  of the operational amplifier is calculated by the following equation (15) by substituting the equations (11) to (14) into the equation (3).

$$S_{vgThm} = \frac{16}{3} \times \frac{k \times T}{g_{m1}} + \frac{16}{3} \times \frac{g_{m3} \times k \times T}{g_{m1}^2} \quad (15)$$

The thermal noise  $S_{vgThm}$  of the operational amplifier is calculated by the following equation (16) by substituting the equations (8) and (9) into the equation (15).

$$S_{vgThm} = \frac{8}{3} \times \frac{k \times T \times \sqrt{2} \times \sqrt{L1}}{\sqrt{I_{ds}} \times \sqrt{\mu_p \times C_{OX}} \times \sqrt{W1}} + \frac{8}{3} \times \frac{k \times T \times \sqrt{2} \times L1 \times \sqrt{\mu_n \times C_{OX}} \times \sqrt{W3}}{\sqrt{I_{ds}} \times \sqrt{L3} \times \mu_p \times C_{OX} \times W1} \quad (16)$$

When excluding the constant determined by the natural world and the constant which depends only on the process from the equation (10) relating to the flicker noise  $S_{vgFlc}$  and the equation (16) relating to the thermal noise  $S_{vgThm}$ , W1, W3, L1, L3, and  $I_{ds}$  are variables which can be managed in

the design stage. Therefore, the flicker noise  $S_{vgFlc}$  is reduced by satisfying the following items in view of the equation (10).

(P1) Increase the WL product  $W1 \times L1$  (gate area) of the differential-stage transistors M1 and M2 as much as possible. This reduces the first term of the equation (10), whereby the flicker noise  $S_{vgFlc}$  is reduced.

(P2) Reduce the ratio  $L1/L3$  as much as possible. Specifically, the channel lengths  $L1$  and  $L3$  are set so that  $L1 < L3$ , for example. This reduces the second term of the equation (10), whereby the flicker noise  $S_{vgFlc}$  is reduced. As a result, the WL product  $W3 \times L3$  of the active-load-stage transistors M3 and M4 increases.

(P3) The flicker noise  $S_{vgFlc}$  is independent of the drain-source current  $I_{ds}$ . Therefore, when taking only the flicker noise into consideration, power consumption can be reduced by reducing the drain-source current  $I_{ds}$ .

As is clear from the above description, the flicker noise  $S_{vgFlc}$  and power consumption can be reduced by increasing the WL product  $W1 \times L1$  of the differential-stage transistor and reducing the bias current  $I_{BD}$  ( $I_{ds}$ ) flowing through the differential section.

The thermal noise  $S_{vgThm}$  is reduced by satisfying the following items in view of the equation (16).

(Q1) Increase the current  $I_{ds}$  ( $I_{BD}$ ) as much as possible. This reduces the first and second terms of the equation (16), whereby the thermal noise  $S_{vgThm}$  is reduced.

(Q2) Increase the WL ratio  $RT1 = W1/L1$  of the differential-stage transistors M1 and M2 as much as possible, and reduce the WL ratio  $RT3 = W3/L3$  of the active-load-stage transistors M3 and M4 as much as possible. Specifically, the ratios  $RT1$  and  $RT3$  are set so that  $RT1 > RT3$ , for example.

(Q3) The thermal noise  $S_{vgThm}$  is independent of the WL products  $W1 \times L1$  and  $W3 \times L3$ . Therefore, when taking only the thermal noise into consideration, the area of the operational amplifier can be reduced by reducing the WL products  $W1 \times L1$  and  $W3 \times L3$ .

As is clear from the above description, the thermal noise  $S_{vgThm}$  and the area of the operational amplifier can be reduced by increasing the bias current  $I_{BD}$  flowing through the differential section and reducing the WL products  $W1 \times L1$  and  $W3 \times L3$  to provide a small operational amplifier.

## 2.2 Selective Use of Operational Amplifiers

As is clear from the items (P1) and (Q1), the noise of the operational amplifier can be reduced by increasing the WL product  $W1 \times L1$  of the differential-stage transistor to reduce flicker noise and increasing the bias current  $I_{BD}$  of the differential section to reduce thermal noise.

However, the layout area of the operational amplifier is increased by increasing the WL product  $W1 \times L1$ , whereby the circuit scale is increased. On the other hand, the current consumption of the operational amplifier is increased by increasing the bias current  $I_{BD}$ , thereby hindering a reduction in power consumption.

In this embodiment, in order to achieve a reduction in noise, circuit area, and power consumption in combination, the first-type and second-type operational amplifiers OP1 and OP2 are provided and are used selectively.

As transistor noise, flicker noise predominantly occurs in a low frequency region, and thermal noise predominantly occurs in a high frequency region, as shown in FIG. 5A.

As shown in FIG. 5A, the frequency  $f1$  (first frequency) of the amplification target signal (small-signal amplification target signal of the operational amplifier) of the first circuit 310 (amplifier circuits 332 and 352 and filter sections 334 and 354) shown in FIG. 1 is high, and the frequency  $f2$  (second

frequency) of the amplification target signal of the second circuit 320 (amplifier circuit 338, filter sections 340 and 358, and detection circuit 360) is low.

Specifically, the frequency  $f1$  corresponds to the frequency of the carrier signal. For example, the frequency  $f1$  is a frequency in a band of several tens of kilohertz to several hundreds of kilohertz (AC band).

On the other hand, the frequency  $f2$  corresponds to the frequency of the desired signal carried by the carrier signal (maximum frequency in the frequency band of the desired signal). For example, the frequency  $f2$  is a frequency in a band of several hertz to several hundreds of hertz (DC band).

In this embodiment, the first-type operational amplifier OP1 which reduces thermal noise as compared with the second-type operational amplifier OP2 is used in the first supply circuit 21 supplies the voltage AGND to the first circuit 310 in the preceding stage of the mixer 322 (336 and 356) which extracts the desired signal from the carrier signal. Specifically, an operational amplifier is used of which the thermal noise at the frequency  $f1$  of the carrier signal is lower than that of the second-type operational amplifier OP2.

On the other hand, the second-type operational amplifier OP2 which reduces flicker noise as compared with the first-type operational amplifier OP1 is used in the second supply circuit 22 which supplies the voltage AGND to the second circuit 320 in the subsequent stage of the mixer 322. Specifically, an operational amplifier is used of which the flicker noise at the frequency  $f2$  of the desired signal is lower than that of the first-type operational amplifier OP1.

The third-type operational amplifier OP3 of which the thermal noise at the frequency of the carrier signal is lower than that of the second-type operational amplifier OP2 and the flicker noise at the frequency of the desired signal is lower than that of the first-type operational amplifier OP1 is used in the third supply circuit 23 which supplies the voltage  $V3Q$  to the first and second supply circuits 21 and 22. As the third-type operational amplifier OP3, it is more desirable to use an operational amplifier of which the thermal noise at the frequency of the carrier signal is lower than that of the first-type operational amplifier OP1 and the flicker noise at the frequency of the desired signal is lower than that of the second-type operational amplifier OP2.

In FIG. 5B, the WL product of the differential-stage transistor of the first-type operational amplifier OP1 is indicated by  $W1 \times L1 = W1a \times L1a$ , and the bias current flowing through the differential section is indicated by  $I_{BD} = Ia$ , for example. The frequency (operating frequency) of the amplification target signal of the first circuit 310 (first-type operational amplifier OP1) is indicated by  $fop = f1$ . The WL ratio of the differential-stage transistor is indicated by  $RT1 = RT1a = W1a/L1a$ , and the WL ratio of the active-load-stage transistor is indicated by  $RT3 = RT3a = W3a/L3a$ .

The WL product of the differential-stage transistor of the second-type operational amplifier OP2 is indicated by  $W1 \times L1 = W1b \times L1b$ , and the bias current flowing through the differential section is indicated by  $I_{BD} = Ib$ . The frequency of the amplification target signal of the second circuit 320 (second-type operational amplifier OP2) is indicated by  $fop = f2$ . The channel length ratio of the differential-stage transistor and the active-load-stage transistor is indicated by  $L1/L3 = L1b/L3b$ . The WL product of the third-type operational amplifier OP3 is indicated by  $W1 \times L1 = W1c \times L1c$ , and the bias current flowing through the differential section is indicated by  $I_{BD} = Ic$ .

In this embodiment, the relationship  $W1b \times L1b > W1a \times L1a$ ,  $Ia > Ib$ , and  $f1 > f2$  is satisfied between the first-type and second-type operational amplifiers OP1 and OP2, as shown in

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FIG. 5C. The relationship  $RT1a > RT3a$  is satisfied for the first-type operational amplifier OP1, and the relationship  $L1b < L3b$  is satisfied for the second-type operational amplifier OP2. The relationship  $W1c \times L1c > W1a \times L1a$  and  $Ic > Ib$  is satisfied for the third-type operational amplifier OP3. Note that the relationship  $W1c \times L1c > W1b \times L1b$  and  $Ic > Ia$  may be satisfied.

For example, flicker noise can be reduced by increasing the WL product  $W1 \times L1$  of the differential-stage transistor, as shown in FIG. 6A and described in the item (P1), thermal noise can be reduced by increasing the bias current  $IBD = Ia$  of the differential section, as shown in FIG. 6A and described in the item (Q1). The first-type operational amplifier OP1 has the high signal frequency  $f1$ , and the second-type operational amplifier OP2 has the low signal frequency  $f2$ .

In this embodiment, as shown in FIG. 6B, thermal noise which predominantly occurs at the high frequency  $f1$  is effectively reduced by increasing the bias current  $IBD = Ia$  of the first-type operational amplifier OP1 having the high signal frequency  $f1$ , thereby reducing the noise of the entire system. Specifically, the bias current  $Ia$  of the first-type operational amplifier OP1 is set to be about twice to ten times, and preferably about four to seven times the bias current  $Ib$  of the second-type operational amplifier OP2, for example. On the other hand, since the effect of flicker noise is small at the high frequency  $f1$ , the layout area of the operational amplifier is unnecessarily increased when increasing the WL product  $W1 \times L1 = W1a \times L1a$  of the first-type operational amplifier OP1. This does not contribute to a reduction in the noise of the entire system. In this embodiment, since the WL product  $W1a \times L1a$  is set to be smaller than the WL product  $W1b \times L1b$ , a situation in which the layout area is unnecessarily increased can be prevented.

In this embodiment, as shown in FIG. 6C, flicker noise which predominantly occurs at the low frequency  $f2$  is effectively reduced by increasing the WL product  $W1 \times L1 = W1b \times L1b$  of the second-type operational amplifier OP2 having the low signal frequency  $f2$ , thereby reducing the noise of the entire system. Specifically, the WL product  $W1b \times L1b$  of the second-type operational amplifier OP2 is set to be about 10 to 100 times, and preferably about 30 to 60 times the WL product  $W1a \times L1a$  of the first-type operational amplifier OP1, for example. On the other hand, since the effect of thermal noise is small at the low frequency  $f2$ , the current consumption of the operational amplifier is unnecessarily increased when increasing the bias current  $IBD = Ib$ . This contributes to a reduction in power consumption of the entire system to only a small extent. In this embodiment, since the bias current  $Ib$  is set to be lower than the bias current  $Ia$ , a situation in which the current consumption is unnecessarily increased can be prevented.

In the first-type operational amplifier OP1 mainly aiming at reducing thermal noise, thermal noise can be reduced by increasing the WL ratio  $RT1a = W1a/L1a$  as much as possible and reducing the WL ratio  $RT3a = W3a/L3a$  as much as possible, as is clear from the equation (16) and the item (Q2). Therefore, the transistors of the first-type operational amplifier OP1 are sized so that the relationship  $RT1a > RT3a$  is satisfied. Specifically, the WL ratio  $RT1a$  is set to be about twice to eight times, and preferably about three to six times the WL ratio  $RT3a$ , for example. This further reduces the noise of the entire system.

In the second-type operational amplifier OP2 mainly aiming at reducing flicker noise, flicker noise can be reduced by reducing the ratio  $L1b/L3b$  as much as possible, as is clear from the equation (10) and the item (P2).

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Therefore, the transistors of the second-type operational amplifier OP2 are sized so that the relationship  $L1b < L3b$  is satisfied. Specifically, the channel length  $L1b$  is set to be about 0.4 to 0.8 times the channel length  $L3b$ , for example. This further reduces the noise of the entire system.

### 2.3 Corner Frequency

In this embodiment, the transistors of the first-type and second-type operational amplifiers OP1 and IP2 are sized so that frequencies  $f1$  and  $f2$  and the corner frequency  $fcr$  have the relationship shown in FIGS. 6B and 6C, for example.

Specifically, the first-type operational amplifier OP1 is designed so that the relationship  $f1 - fcr < fcr - f2$  is satisfied, as shown in FIG. 6B. The second-type operational amplifier OP2 is designed so that the relationship  $fcr - f2 < f1 - fcr$  is satisfied, as shown in FIG. 6C.

The corner frequency  $fcr$  is the frequency corresponding to the intersection of the flicker noise characteristic line and the thermal noise characteristic line in the frequency-noise characteristics shown in FIGS. 6A to 6C.

For example, when the corner frequency  $fcr$  is set at a position indicated by E1 in the first-type operational amplifier OP1 shown in FIG. 7A, the noise at the frequency  $f1$  increases, whereby thermal noise cannot be effectively reduced. On the other hand, when the corner frequency  $fcr$  is set at a position indicated by E2, the bias current  $IBD$  unnecessarily increases, thereby hindering a reduction in power consumption.

In this embodiment, the transistors of the first-type operational amplifier OP1 are sized so that the corner frequency  $fcr$  is set near the frequency  $f1$ . In this case, the thermal noise and the power consumption of the operational amplifier can be reduced optimally by ideally setting the corner frequency  $fcr$  to be  $fcr = f1$ , as indicated by E3 in FIG. 7A. However, when setting the corner frequency  $fcr$  to be  $fcr = f1$ , the thermal noise level may exceed the desired noise level when process variation occurs.

In FIG. 6B, the first-type operational amplifier OP1 is designed so that the relationship  $f1 - fcr < fcr - f2$  is satisfied, thereby causing the corner frequency  $fcr$  to be close to the frequency  $f1$  as much as possible. This makes it possible to reduce the thermal noise and the power consumption of the operational amplifier while taking process variation into consideration.

In the second-type operational amplifier OP2 shown in FIG. 7B, when the corner frequency  $fcr$  is set at a position indicated by E4, the noise at the frequency  $f2$  increases, whereby flicker noise cannot be effectively reduced. On the other hand, when the corner frequency  $fcr$  is set at a position indicated by E5, the WL product  $W1 \times L1$  unnecessarily increases, thereby hindering a reduction in circuit area.

In this embodiment, the transistors of the second-type operational amplifier OP2 are sized so that the corner frequency  $fcr$  is set near the frequency  $f2$ . In this case, the flicker noise and the layout area of the operational amplifier can be reduced optimally by ideally setting the corner frequency  $fcr$  to be  $fcr = f2$ , as indicated by E6 in FIG. 7B. However, when setting the corner frequency  $fcr$  to be  $fcr = f2$ , the flicker noise level may exceed the desired noise level when process variation occurs.

In FIG. 6C, the second-type operational amplifier OP2 is designed so that the relationship  $fcr - f2 < f1 - fcr$  is satisfied, thereby causing the corner frequency  $fcr$  to be close to the frequency  $f2$  as much as possible. This makes it possible to reduce the thermal noise and the area of the operational amplifier while taking process variation into consideration.

## 2.4 Effective Gate Voltage

As shown in FIG. 5C and the equation (10), flicker noise can be reduced by increasing the WL product  $W1b \times L1b$  of the differential-stage transistor as much as possible and reducing the channel length  $L1b$  as much as possible. Therefore, it is considered that flicker noise can be efficiently reduced by sizing the transistors so that the WL ratio  $W1b/L1b$  is increased.

However, it was found that an effective gate voltage  $V_{eff}$  decreases when increasing the WL ratio  $W1b/L1b$  to a large extent, thereby resulting in an increase in flicker noise. The effective gate voltage  $V_{eff}$  is expressed by the following equation (17).

$$V_{eff} = V_{gs} - V_{th} \quad (17)$$

$$= \left\{ \frac{2 \times I_{ds}}{\mu \times C_{ox} \times RT1b} \right\}^{\frac{1}{2}}$$

Where,  $V_{gs}$  represents the gate-source voltage of the transistor,  $V_{th}$  represents the threshold voltage,  $I_{ds}$  represents the drain-source current,  $\mu$  represents the mobility,  $C_{ox}$  represents the gate capacitance per unit area, and  $RT1b$  represents the WL ratio of the differential-stage transistor, provided that  $RT1b = W1b/L1b$ .

FIGS. 8A and 8B show measurement results of the relationship between the effective gate voltage  $V_{eff}$  and noise (noise level  $S_{vg}$ ), for example. FIG. 8A shows an example of an N-type transistor, and FIG. 8B shows an example of a P-type transistor. In FIGS. 8A and 8B, the effective gate voltage  $V_{eff}$  is changed by changing the noise level  $V_{gs}$ . Note that the drain-source voltage  $V_{ds}$  is equal to the gate-source voltage  $V_{gs}$ .

As indicated by E7 in FIG. 8A and E8 in FIG. 8B, noise increases steeply when the effective gate voltage  $V_{eff}$  decreases. This occurs due to a phenomenon in which the transistor operates in a weak inversion region when the effective gate voltage  $V_{eff}$  as the small-signal reference voltage decreases, whereby flicker noise increases rapidly. In FIGS. 8A and 8B, flicker noise increases rapidly at an effective gate voltage  $V_{eff}$  of 10 mV to 100 mV, for example. Therefore, in order to suppress an increase in flicker noise due to the operation in the weak inversion region, it is desirable to increase the effective gate voltage  $V_{eff}$  to a value greater than 10 mV to 100 mV.

FIG. 9A provides simulation results showing the relationship among the area, current consumption, and noise of the operational amplifier when changing the effective gate voltage  $V_{eff}$ , wherein the X axis indicates the area (the length of one side when the operational amplifier is square), the Y axis indicates the current consumption, and the Z axis indicates the noise level.

In FIG. 9A, the effective gate voltage  $V_{eff}$  is changed by changing the WL ratio  $RT1b = W1b/L1b$  under conditions where the WL product  $W1b \times L1b$  is constant. For example, the directions indicated by arrows F1 and F2 in FIG. 9A are directions in which the effective gate voltage  $V_{eff}$  decreases. The effective gate voltage  $V_{eff}$  is reduced by increasing the WL ratio  $RT1b = W1b/L1b$ .

As indicated by F1 in FIG. 9A, the area and the current consumption of the operational amplifier decrease as the effective gate voltage  $V_{eff}$  decreases. On the other hand, the noise changes to only a small extent.

However, the noise increases rapidly at the point F3 in FIG. 9A. Specifically, when the WL ratio  $RT1b = W1b/L1b$  exceeds

a specific value, the transistor operates in the weak inversion region, as described with reference to FIGS. 8A and 8B, whereby flicker noise increases rapidly so that the noise of the operational amplifier increases rapidly.

At a point F4 in FIG. 9A, since the area and the current consumption of the operational amplifier are large although the noise is small, the area and the current are uselessly consumed.

In this embodiment, the WL ratio  $RT1b = W1b/L1b$  of the differential-stage transistor is determined (the range is narrowed) so that the WL ratio  $RT1b$  is set at the point F3 in FIG. 9A. For example, the WL ratio  $RT1b$  may be a value in the range of 50 to 200. The transistors of the operational amplifier are sized so that the WL product  $W1b \times L1b$  increases and the channel length ratio  $L1b/L3b$  decreases as shown in FIG. 5C under conditions where the WL ratio  $RT1b$  is determined as described above.

Specifically, the transistor is prevented from operating in the weak inversion region by satisfying the following equation (18).

$$V_{eff} = \left\{ \frac{2 \times I_{ds}}{\mu \times C_{ox} \times RT1b} \right\}^{\frac{1}{2}} > \frac{k \times T}{q} \quad (18)$$

Where,  $k$  represents the Boltzmann constant,  $T$  represents the absolute temperature, and  $q$  ( $=1.602 \times 10^{-19}$  coulombs) represents the amount of electronic charge.  $k \times T/q = 25.7$  mV at room temperature ( $25^\circ$ ).

On the other hand, since flicker noise increases at the boundary between the weak inversion region and the strong inversion region, as shown in FIGS. 8A and 8B, it is necessary to take process variation into consideration. Therefore, when process variation parameter (process-dependent parameter) is referred to as  $P$  ( $P > 1$ ), the following equation (19) is satisfied.

$$P \times \frac{k \times T}{q} > V_{eff} = \left\{ \frac{2 \times I_{ds}}{\mu \times C_{ox} \times RT1b} \right\}^{\frac{1}{2}} > \frac{k \times T}{q} \quad (19)$$

The process variation parameter  $P$  may be set at 3.0, for example. The process variation parameter  $P$  may be desirably a value in the range of 1.5 to 2.0.

In this embodiment, the WL ratio  $RT1b = W1b/L1b$  of the differential-stage transistor is determined so that the effective gate voltage  $V_{eff}$  is a value in the range which satisfies the equation (19). The transistors of the operational amplifier are sized so that the WL product  $W1b \times L1b$  increases and the channel length ratio  $L1b/L3b$  decreases under conditions where the WL ratio  $RT1b$  is determined as described above. It is desirable to again perform a fine adjustment by changing the WL ratio  $RT1b$  after determining the WL ratio  $RT1b$  and determining the WL product  $W1b \times L1b$  and the channel length ratio  $L1b/L3b$ .

FIG. 9B provides simulation results showing the relationship among the area, current consumption, and noise of the operational amplifier when changing the ratio  $L1b/L3b$  ( $L3b/L1b$ ) which is the ratio of the gate length  $L1b$  of the differential-stage transistor and the gate length  $L3b$  of the active-load-stage transistor.

When increasing the ratio  $L1b/L3b$  (reducing the ratio  $L3b/L1b$ ), as indicated by F5 in FIG. 9B, noise increases rapidly as indicated by F7 from a point indicated by F6. In this case, the area of the operational amplifier decreases when

increasing the ratio  $L1b/L3b$ , but the current consumption changes to only a small extent.

As is clear from the results shown in FIG. 9B, the ratio  $L1b/L3b$  can be optimally set by setting the ratio  $L1b/L3b$  at the point indicated by F6. Specifically, the ratio  $L1b/L3b$  may be a value in the range of 0.4 to 0.8, for example.

According to this embodiment, a reduction in noise, circuit area, and power consumption is successfully achieved in combination by sizing the transistors of the operational amplifier as described above.

For example, the reference voltage supply circuit 20 supplies the voltage AGND (analog reference voltage) to the first circuit 310 and the second circuit 320. The voltage AGND is a voltage used as a reference for the analog circuit. The signal amplification operation of the operational amplifier is performed based on the voltage AGND. Accordingly, the reference voltage supply circuit 20 must supply the voltage AGND at a stable potential to the first circuit 310 and the second circuit 320.

It is desirable that the first circuit 310 include the first-type operational amplifier OP1 and the second circuit 320 include the second-type operational amplifier OP2. For example, the noise of the first circuit 310 can be reduced by forming the first circuit 310 using the first-type operational amplifier OP1 mainly designed to reduce thermal noise. The noise of the second circuit 320 can be reduced by forming the second circuit 320 using the second-type operational amplifier OP2 mainly designed to reduce flicker noise.

However, even if the first circuit 310 is formed using the first-type operational amplifier OP1 and the second circuit 320 is formed using the second-type operational amplifier OP2, when thermal noise or flicker noise is superimposed on the voltage AGND supplied from the reference voltage supply circuit 20, it becomes difficult to increase the SNR of the entire system.

For example, the frequency  $f1$  of the amplification target signal of the first circuit 310 which operates based on the voltage AGND supplied from the first supply circuit 21 is high, as shown in FIG. 5A, and thermal noise predominantly occurs at the frequency  $f1$ , as described above. Therefore, even if the first-type operational amplifier is used for the first circuit 310, when thermal noise is superimposed on the voltage AGND from the first supply circuit 21, the thermal noise of the first circuit 310 increases.

In this embodiment, the first supply circuit 21 includes the reference-voltage first-type operational amplifier OP1, and supplies the voltage AGND using the reference-voltage first-type operational amplifier OP1. The reference-voltage first-type operational amplifier OP1 is an operational amplifier mainly designed to reduce thermal noise, as described with reference to FIG. 5C and the like. Therefore, thermal noise superimposed on an AGND line AGL1 can be minimized, whereby an increase in thermal noise in the first circuit 310 can be prevented.

The frequency  $f2$  of the amplification target signal of the second circuit 320 which operates based on the voltage AGND supplied from the second supply circuit 22 is low, as shown in FIG. 5A, and flicker noise predominantly occurs at the frequency  $f2$ , as described above. Therefore, even if the second-type operational amplifier is used for the second circuit 320, when flicker noise is superimposed on the voltage AGND from the second supply circuit 22, the flicker noise of the second circuit 320 increases.

In this embodiment, the second supply circuit 22 includes the reference-voltage second-type operational amplifier OP2, and supplies the voltage AGND using the reference-voltage second-type operational amplifier OP2. The reference-volt-

age second-type operational amplifier OP2 is an operational amplifier mainly designed to reduce flicker noise, as described with reference to FIG. 5C and the like. Therefore, flicker noise superimposed on an AGND line AGL2 can be minimized, whereby an increase in flicker noise in the second circuit 320 can be prevented.

The voltage AGND from the first supply circuit 21 is supplied through the AGND line AGL1 (first analog reference voltage line in a broad sense). The voltage AGND from the second supply circuit 22 is supplied through the AGND line AGL2 (second analog reference voltage line in a broad sense). In this case, the AGND lines AGL1 and AGL2 are separately provided from the reference voltage supply circuit 20 to the first and second circuits 310 and 320. Specifically, the two AGND lines AGL1 and AGL2 are connected with the first and second circuits 310 and 320 while being separated in the layout. This prevents a situation in which noise from the AGND line AGL1 is transmitted to the AGND line AGL2 or noise from the AGND line AGL2 is transmitted to the AGND line AGL1.

For example, when thermal noise from the AGND line AGL2 is transmitted to the AGND line AGL1, the thermal noise from the AGND line AGL2 is transmitted to the first circuit 310, even if the first supply circuit 21 is formed using the first-type operational amplifier OP1 mainly designed to reduce thermal noise, whereby the SNR deteriorates. Likewise, when flicker noise from the AGND line AGL2 is transmitted to the AGND line AGL1, the flicker noise from the AGL1 is transmitted to the second circuit 320, even if the second supply circuit 22 is formed using the second-type operational amplifier OP2 mainly designed to reduce flicker noise, whereby the SNR deteriorates.

The above-described situation can be prevented by separately providing the AGND lines AGL1 and AGL2, whereby the SNR of the entire system can be increased.

FIG. 10 shows the results when applying the method according to this embodiment to a gyrosensor detection device described later. QVAMP, DIFF, PGA, SYNCD, and FLT respectively indicate the noise levels of a Q/V conversion circuit, a differential amplifier circuit, a sensitivity adjustment circuit, a synchronous detection circuit, and a filter section.

As shown in FIG. 10, this embodiment successfully and efficiently reduces the noise of the entire system by selectively using the operational amplifiers for the first supply circuit 21 which supplies the voltage AGND to the first circuit 310 which processes the AC signal and the second supply circuit 22 which supplies the voltage AGND to the second circuit 320 which processes the DC signal to achieve an optimum low-noise design.

## 2.5 Layout

A layout method for the first-type and second-type operational amplifiers OP1 and OP2 is described below. FIG. 11A shows a layout example of the first-type operational amplifier OP1, and FIG. 11B shows a layout example of the second-type operational amplifier OP2.

In FIG. 11B, H2 indicates the arrangement region of the differential-stage transistors M1 and M2 among the elements (e.g., transistor, capacitor, and resistor) of the second-type operational amplifier OP2. The area of the arrangement region H2 is referred to as Sdf, and the area of the arrangement region of the elements of the second-type operational amplifier other than the differential-stage transistors M1 and M2 is referred to as Sre. Note that the elements other than the differential-stage transistors M1 and M2 refer to the transistors M3, M4, M5, M6, and M7 other than the transistors M1

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and M2, the capacitor CF, the resistor RF, and the like shown in FIG. 4B, for example. In FIG. 11B, the relationship  $S_{df} > S_{re}$  is satisfied. The WL product  $W1b \times L1b$  can be increased by satisfying such a relationship, whereby flicker noise can be reduced.

In the first-type operational amplifier OP1 shown in FIG. 11A, since the arrangement region of the differential-stage transistors M1 and M2 is a small, as indicated by H1, the relationship  $S_{df} > S_{re}$  is not satisfied. In the first-type operational amplifier OP1, thermal noise is reduced by sizing the transistors so that the bias current  $I_{BD} = I_a$  increases.

In FIG. 11B, the differential-stage transistor M1 of the second-type operational amplifier OP2 includes (J) transistors TR11, TR12, TR13, and TR14 connected in parallel. Likewise, the differential-stage transistor M2 of the second-type operational amplifier OP2 includes transistors TR21, TR22, TR23, and TR24 connected in parallel. The parallel-connected transistors TR11 to TR14 and TR21 to TR24 are disposed in the arrangement region of the differential-stage transistors M1 and M2 indicated by H2.

In FIG. 11B, a direction X is the channel length direction, and a direction Y is the channel width direction. The channel length of each of the parallel-connected transistors TR11 to TR14 and TR21 to TR24 is  $L1b$ . When the number of the parallel-connected transistors TR11 to TR14 or TR21 to TR24 is J (J=4 in FIG. 11B), the channel width of each of the transistors TR11 to TR14 and TR21 to TR24 is  $W11b = W1b/J$ .

The WL ratio  $W1b/L1b$  can be increased while increasing the WL product  $W1b \times L1b$  by disposing the parallel-connected transistors TR11 to TR14 and TR21 to TR24 as shown in FIG. 11B whereby flicker noise can be efficiently reduced.

In FIG. 11B, the active-load-stage transistors M3 and M4 respectively include (I) transistors TR31 and TR32 and (I) transistors TR41 and TR42 connected in parallel. The channel length of each of the parallel-connected transistors TR31 and TR32 and the parallel-connected transistors TR41 and TR42 is  $L3b$ . When the number of the parallel-connected transistors TR31 and TR32 or TR41 and TR42 is I (I=2 in FIG. 11B), the channel width of each of the transistors TR31 and TR32 and the transistors TR41 and TR42 is  $W33b = W3b/I$ .

In FIG. 11B, the J (e.g., J=4) transistors TR11 to TR14 and the J transistors TR21 to TR24 are disposed in the arrangement region of the differential-stage transistors M1 and M2 in the direction X, and the I (I<J; e.g., I=2) transistors TR31 and TR32 and the I transistors TR41 and TR42 are disposed in the arrangement region of the active-load-stage transistors M3 and M4 in the direction X. This enables the transistors TR11 to TR14 and the transistors TR21 to TR24 respectively forming the differential-stage transistors M1 and M2 and the transistors TR31 and TR32 and the transistors TR41 and TR42 respectively forming the active-load-stage transistors M3 and M4 to be efficiently disposed symmetrically in the rectangular arrangement region while satisfying the relationship  $L1b < L3b$  described with reference to FIG. 5C. This increases layout efficiency.

FIG. 12 shows a layout example of the third-type operational amplifier OP3. In FIG. 12, H3 indicates the arrangement region of the differential-stage transistors M1 and M2. In FIG. 12, since the relationship  $S_{df} > S_{re}$  is satisfied in the same manner as in FIG. 11B, the WL ratio  $W1c/L1c$  can be increased. Therefore, flicker noise can be reduced.

In FIG. 12, the differential-stage transistors M1 and M2 respectively include parallel-connected transistors TS11 to TS14 and parallel-connected transistors TS21 to TS24. The (J) parallel-connected transistors TS11 to TS14 and the (J)

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parallel-connected transistors TS21 to TS24 are disposed in the arrangement region of the differential-stage transistors M1 and M2 indicated by H3.

The channel length of each of the parallel-connected transistors TS11 to TS14 and the parallel-connected transistors TS21 to TS24 is  $L1c$ , and the channel width is  $W11c = W1c/J$ .

As is clear from the comparison between FIG. 12 and FIG. 11B, the arrangement region H3 of the differential-stage transistors M1 and M2 of the third-type operational amplifier OP3 shown in FIG. 12 is further increased as compared with FIG. 11B. This realizes an operational amplifier which can further reduce flicker noise as compared with FIG. 11B.

## 2.6 Reference Voltage Supply Circuit

FIG. 13 shows a detailed configuration example of the reference voltage supply circuit 20. The reference voltage supply circuit 20 is not limited to the configuration shown in FIG. 13. Various modification may be made such as omitting some elements or adding another element.

The reference voltage supply circuit 20 includes the first, second, and third supply circuits 21, 22, and 23. The reference voltage supply circuit 20 also includes a reference voltage generation circuit 26.

The first supply circuit 21 (first impedance conversion circuit) performs voltage impedance conversion using the reference-voltage first-type operational amplifier OP1, for example. Specifically, the first-type operational amplifier OP1 included in the first supply circuit 21 is a voltage-follower-connected operational amplifier of which the inverting input terminal (second input terminal in a broad sense) is connected with the output terminal. The output terminal of the first-type operational amplifier OP1 is connected with the AGND line AGL1.

The second supply circuit 22 (second impedance conversion circuit) performs voltage impedance conversion using the reference-voltage second-type operational amplifier OP2, for example. Specifically, the second-type operational amplifier OP2 included in the second supply circuit 22 is a voltage-follower-connected operational amplifier of which the inverting input terminal (second input terminal) is connected with the output terminal. The output terminal of the second-type operational amplifier OP2 is connected with the AGND line AGL2.

The third supply circuit 23 is provided in the preceding stage of the first and second supply circuits 21 and 22, and supplies the output voltage V3Q to the first and second supply circuits 21 and 22. For example, the first and second supply circuits 21 and 22 subject the output voltage V3Q from the third supply circuit 23 to impedance conversion and outputs the voltage AGND.

The third supply circuit 23 includes the third-type operational amplifier OP3 described with reference to FIGS. 5C and 12. The third supply circuit 23 may include a voltage divider circuit including resistors RJ1, RJ2, and RJ3.

The reference voltage generation circuit 26 generates a reference voltage VR for generating the voltage AGND. A circuit which generates the reference voltage VR by a band gap may be employed as the reference voltage generation circuit 26, for example.

In FIG. 13, the voltage of a node NJ1 is equal to the reference voltage VR due to a virtual short circuit of the third-type operational amplifier OP3, for example. Therefore, when the resistances of the resistors RJ2 and RJ3 are respectively referred to as R2 and R3, the output voltage of the third supply circuit 23 is  $V3Q = VR \times \{(R2 + R3)/R3\}$ . The first and second supply circuits 21 and 22 subject the output voltage

V3Q (=AGND=VR×{(R2+R3)/R3}) to impedance conversion. This enables the potential of the voltage AGND to be stabilized.

The channel width and the channel length of the differential-stage transistor of the differential section of the reference-voltage third-type operational amplifier OP3 are respectively referred to as W1c and L1c, and the bias current flowing through the differential section is referred to as Ic. In this case, the relationship  $W1c \times L1c > W1a \times L1a$  and  $Ic > Ib$  is satisfied.

Specifically, the first supply circuit 21 receives the output voltage V3Q from the third supply circuit 23, and supplies the voltage AGND to the amplifier circuit 70. Therefore, when thermal noise is superimposed on the output voltage V3Q of the third supply circuit 23, the thermal noise superimposed on the output voltage V3Q is transmitted to the first circuit 310, even if the first-type operational amplifier OP1 mainly designed to reduce thermal noise is used as the first supply circuit 21. As a result, the SNR of the entire system deteriorates.

The second supply circuit 22 receives the output voltage V3Q from the third supply circuit 23, and supplies the voltage AGND to the filter section 110. Therefore, when flicker noise is superimposed on the output voltage V3Q of the third supply circuit 23, the flicker noise superimposed on the output voltage V3Q is transmitted to the second circuit 320, even if the second-type operational amplifier OP2 mainly designed to reduce flicker noise is used as the second supply circuit 22. As a result, the SNR of the entire system deteriorates.

The third-type operational amplifier OP3 of the third supply circuit 23 shown in FIG. 13 satisfies the relationship  $W1c \times L1c > W1a \times L1a$  and  $Ic > Ib$ . The relationship  $W1c \times L1c > W1b \times L1b$  and  $Ic > Ia$  is desirably satisfied. Therefore, the third-type operational amplifier OP3 is an operational amplifier with low thermal noise and low flicker noise. For example, the third-type operational amplifier OP3 has a large WL product and a large bias current, as shown in the layout example in FIG. 12. Therefore, the third-type operational amplifier OP3 is an operational amplifier with very low thermal noise and very low flicker noise.

As described above, thermal noise and flicker noise superimposed on the output voltage V3Q of the third supply circuit 23 can be minimized using the third-type operational amplifier OP3 with low thermal noise and low flicker noise as the third supply circuit 23. Therefore, a situation can be minimized in which thermal noise superimposed on the output voltage V3Q is transmitted to the first circuit 310 through the first supply circuit 21 or flicker noise superimposed on the output voltage V3Q is transmitted to the second circuit 320 through the second supply circuit 22, whereby the SNR of the entire system can be significantly increased.

### 3. Application of Gyrosensor Detection Device

#### 3.1 Configuration of Detection Device

A case of applying the method according to this embodiment to a gyrosensor detection device is described below. FIG. 14 shows a configuration example of a detection device 30. The detection device 30 includes a driver circuit 40 and a detection circuit 60. The detection device 30 is not limited to the configuration shown in FIG. 14. Various modification may be made such as omitting some elements or adding another element. For example, the configuration of the driver circuit 40 may be omitted when a synchronization signal can be extracted based on a detection signal from a vibrator 10.

The vibrator 10 (vibrating gyroscope) as a physical quantity transducer is a piezoelectric vibrator formed of a piezoelectric material such as a crystal. FIG. 15A shows a tuning-fork piezoelectric vibrator as an example of the vibrator 10.

The vibrator 10 includes driving vibrators 11 and 12 and detection vibrators 16 and 17. The driving vibrators 11 and 12 are respectively provided with driving terminals 2 and 4, and the detection vibrators 16 and 17 are respectively provided with detection terminals 6 and 8. FIG. 15A shows an example in which the vibrator 10 is a tuning-fork vibrator. Note that the vibrator 10 according to this embodiment is not limited to the structure shown in FIG. 15A. For example, the vibrator 10 may be a T-shaped vibrator, double-T-shaped vibrator, or the like. The piezoelectric material for the vibrator 10 may be a material other than a crystal. The vibrator 10 (physical quantity transducer) may be an electrostatic micro electro mechanical system (MEMS) which performs a driving/detection operation utilizing capacitance. The physical quantity transducer is an element for converting a physical quantity (indicating the degree of property of an object and expressed in defined units) into another physical quantity. As the conversion target physical quantity, a force such as Coriolis force and gravity, acceleration, mass, and the like can be given. A physical quantity obtained by conversion may be a voltage or the like in addition to current (charge).

The driver circuit 40 outputs a driving signal (driving voltage) VD to drive the vibrator 10 (physical quantity transducer in a broad sense), and receives a feedback signal VF from the vibrator 10. The driver circuit 40 thus causes the vibrator 10 to vibrate. The detection circuit 60 receives detection signals (detection current or charge) ISP and ISM from the vibrator 10 driven by the driving signal VD, and detects (extracts) a desired signal (Coriolis force signal) from the detection signals.

Specifically, the alternating-current driving signal (driving voltage) VD from the driver circuit 40 is applied to the driving terminal 2 of the driving vibrator 11 shown in FIG. 15A. This causes the driving vibrator 11 to start to vibrate due to the reverse voltage effect, and the driving vibrator 12 also starts to vibrate due to the tuning-fork vibration. A current (charge) generated by the piezoelectric effect of the driving vibrator 12 is fed back to the driver circuit 40 from the driving terminal 4 as the feedback signal VF. An oscillation loop including the vibrator 10 is thus formed.

When the driving vibrators 11 and 12 vibrate, the detection vibrators 16 and 17 vibrate in the directions shown in FIG. 15A at a vibration velocity v. A current (charge) generated by the piezoelectric effect of the detection vibrators 16 and 17 is output from the detection terminals 6 and 8 as the detection signals ISP and ISM. The detection circuit 60 receives the detection signals ISP and ISM, and detects the desired signal (desired wave) which is the signal corresponding to the Coriolis force.

Specifically, when the vibrator 10 (gyrosensor) rotates around a detection axis 19 shown in FIG. 15A, a Coriolis force Fc occurs in the directions perpendicular to the vibration directions at the vibration velocity v. FIG. 15B schematically shows the detection axis 19 shown in FIG. 15A viewed from the upper side. In FIG. 15B, when the angular velocity of the vibrator while the vibrator rotates around the detection axis 19 is referred to as  $\omega$ , the mass of the vibrator is referred to as m, and the vibration velocity of the vibrator is referred to as v, the Coriolis force is expressed as  $Fc = 2m \cdot v \cdot \omega$ . Therefore, the rotation angular velocity  $\omega$  of the gyrosensor (vibrator) can be determined by causing the detection circuit 60 to detect (extract) the desired signal which is the signal corresponding to the Coriolis force.

The vibrator 10 has a driving-side resonance frequency fd and a detection-side resonance frequency fs. Specifically, the natural resonance frequency (natural resonance frequency in driving vibration mode) of the driving vibrators 11 and 12 is

the frequency  $f_d$ , and the natural resonance frequency (natural resonance frequency in detection vibration mode) of the detection vibrators **16** and **17** is the frequency  $f_s$ . In this case, a constant frequency difference is provided between the frequencies  $f_d$  and  $f_s$  in a range so that the driving vibrators **11** and **12** and the detection vibrators **16** and **17** can perform the detection operation and have an appropriate intermode coupling which does not cause unnecessary resonant coupling. A detuning frequency  $\Delta f = |f_d - f_s|$  which is the above difference in frequency is set at a value sufficiently lower than the frequencies  $f_d$  and  $f_s$ .

The driver circuit (oscillation circuit) **40** includes an amplifier circuit **42**, an automatic gain control (AGC) circuit **44** which performs automatic gain control, and a binarization circuit (comparator) **46**. The driver circuit **40** must maintain a constant amplitude of the driving voltage supplied to the vibrator **10** (driving vibrator) in order to maintain constant sensitivity of the gyrosensor. Therefore, the AGC circuit **44** for automatic gain adjustment is provided in the oscillation loop of the driving vibration system. Specifically, the AGC circuit **44** variably and automatically adjusts the gain so that the amplitude of the feedback signal  $FD$  (vibration velocity  $v$  of the vibrator) becomes constant. Note that the phase is adjusted so that the phase shift in the oscillation loop becomes zero degrees (0 deg). In order to enable high-speed oscillation startup, the gain in the oscillation loop is set at a value larger than unity during oscillation startup.

The amplifier circuit **42** amplifies the feedback signal  $FD$  from the vibrator **10**. Specifically, an I/V conversion circuit included in the amplifier circuit **42** converts a current (charge) as the feedback signal  $FD$  from the vibrator **10** into voltage, and outputs the voltage as a driving signal  $VD2$ .

The AGC circuit **44** monitors the driving-side amplified signal  $VD2$  which is the signal amplified by the driving-side amplifier circuit **42**, and controls the gain in the oscillation loop. The AGC circuit **44** may include a gain control amplifier (GCA) for controlling the oscillation amplitude in the oscillation loop, and a gain control circuit which outputs a control voltage for adjusting the gain of the gain control amplifier corresponding to the oscillation amplitude. The gain control circuit may include a rectifier circuit (full-wave rectifier) which converts the alternating-current driving signal  $VD2$  from the amplifier circuit **42** into a direct-current signal, a circuit which outputs the control voltage corresponding to the difference between the voltage of the direct-current signal from the rectifier circuit and a reference voltage, and the like.

The binarization circuit **46** binarizes the driving-side amplified signal  $VD2$  which is a sine wave, and outputs a synchronization signal (reference signal)  $CLK$  obtained by binarization to a synchronous detection circuit **100** of the detection circuit **60**. The binarization circuit **46** may be realized by a comparator to which the sine-wave (alternating-current) signal  $VD2$  from the amplifier circuit **42** is input and which outputs the rectangular-wave synchronization signal  $CLK$ . Note that another circuit may be provided between the amplifier circuit **42** and the binarization circuit **46** or between the binarization circuit **46** and the synchronous detection circuit **100**. For example, a high-pass filter, a phase-shift circuit (phase shifter), or the like may be provided.

The detection circuit **60** includes an amplifier circuit **70**, the synchronous detection circuit **100**, and a filter section **110**. Note that some of these elements may be omitted, or another element may be added.

The amplifier circuit **70** amplifies the detection signals  $ISP$  and  $ISM$  from the vibrator **10**. Specifically, Q/V conversion circuits (I/V conversion circuits) included in the amplifier circuit **70** respectively receive the signals  $ISP$  and  $ISM$  from

the vibrator **10**, and convert (amplify) the charge (current) generated by the vibrator **10** into voltage.

The synchronous detection circuit (detection circuit or detector) **100** performs synchronous detection based on the synchronization signal  $CLK$  (synchronization clock signal or reference signal). A mechanical vibration leakage unnecessary signal can be removed by synchronous detection.

The filter section **110** provided in the subsequent stage of the synchronous detection circuit **100** filters a signal  $VS6$  obtained by synchronous detection. Specifically, the filter section **110** performs a low-pass filtering process of removing high-frequency components.

The detection signal (sensor signal) from the vibrator **10** includes a desired signal (desired wave) and an unnecessary signal (unnecessary wave) in a mixed state. Since the amplitude of the unnecessary signal is generally about 100 to 500 times the amplitude of the desired signal, a high performance is required for the detection device **30**. Examples of the unnecessary signal include an unnecessary signal caused by mechanical vibration leakage, an unnecessary signal caused by electrostatic coupling leakage, an unnecessary signal caused by the detuning frequency  $\Delta f$ , an unnecessary signal caused by the frequency  $2f_d$  ( $2\omega_d$ ), an unnecessary signal caused by DC offset, and the like. The unnecessary signal caused by mechanical vibration leakage occurs due to the imbalance of the shape of the vibrator **10** and the like. The unnecessary signal caused by electrostatic coupling leakage occurs when the driving signal  $VD$  shown in FIG. **14** leaks into input terminals of the signals  $ISP$  and  $ISM$  and the like through the parasitic capacitors  $CP$  and  $CM$ .

FIGS. **16A** to **16C** show Frequency spectra illustrative of unnecessary signal removal. FIG. **16A** shows the frequency spectrum before synchronous detection. As shown in FIG. **16A**, an unnecessary signal caused by DC offset exists in the detection signal before synchronous detection in the DC frequency band. An unnecessary signal caused by mechanical vibration leakage and the desired signal exist in the  $f_d$  frequency band.

FIG. **16B** shows the frequency spectrum after synchronous detection. The desired signal in the  $f_d$  frequency band shown in FIG. **16A** appears in the DC and  $2f_d$  frequency bands after synchronous detection, as shown in FIG. **16B**. The unnecessary signal (DC offset) in the DC frequency band shown in FIG. **16A** appears in the  $f_d$  frequency band after synchronous detection, as shown in FIG. **16B**. The unnecessary signal (mechanical vibration leakage) in the  $f_d$  frequency band shown in FIG. **16A** appears in the  $2f_d$  frequency band after synchronous detection, as shown in FIG. **16B**.

FIG. **16C** shows the frequency spectrum after filtering. The frequency components of the unnecessary signals in the frequency bands of the frequencies  $f_d$ ,  $2f_d$ , and the like can be removed by smoothing (LPF) the signal after synchronous detection using the filter section **110**.

In this embodiment, the first supply circuit **21** of the reference voltage supply circuit **20** supplies the voltage  $AGND$  (analog reference voltage) to the amplifier circuit **70** of the detection circuit **60**, and the second supply circuit **22** supplies the voltage  $AGND$  to the filter section **110** of the detection circuit **60**.

In this case, the first-type operational amplifier  $OP1$  included in the first supply circuit **21** is an operational amplifier of which the thermal noise at the frequency of the carrier signal (e.g., resonance frequency of the vibrator or driving-side resonance frequency) is lower than that of the second-type operational amplifier  $OP2$ , for example. The second-type operational amplifier  $OP2$  included in the second supply circuit **22** is an operational amplifier of which the flicker noise

at the frequency of the desired signal (e.g., maximum frequency in the frequency band of the desired signal) is lower than that of the first-type operational amplifier OP1. The first-type operational amplifier OP1 satisfies the relationship  $f1-fcr < fcr-f2$ , and the second-type operational amplifier OP2 satisfies the relationship  $fcr-f2 < f1-fcr$ , as described above. The relationship  $W1b \times L1b > W1a \times L1a$  and  $Ia > Ib$  is also satisfied. The synchronous detection circuit 100 may include a third-type operational amplifier OP3, for example. In this case, the relationship  $W1c \times L1c > W1a \times L1a$  and  $Ic > Ib$  is satisfied. Alternatively, the relationship  $W1c \times L1c > W1b \times L1b$  and  $Ic > Ia$  may be satisfied.

### 3.2 First Modification

FIG. 17 shows a first modification of the detection device. In the first modification, the filter section 110 includes an output circuit 116, and the reference voltage supply circuit 20 includes a fourth supply circuit 24.

The output circuit 116 is a circuit which subjects the output signal to impedance conversion, and functions as an output buffer. Note that the output circuit 116 may function as a postfilter.

The fourth supply circuit 24 supplies the voltage AGND (analog reference voltage) to the output circuit 116. The fourth supply circuit 24 includes a second-type operational amplifier OP2.

In FIG. 17, the voltage AGND from the first supply circuit 21 is supplied through the AGND line AGL1 (first analog reference voltage line in a broad sense), and the voltage AGND from the second supply circuit 22 is supplied through the AGND line AGL2 (second analog reference voltage line). The voltage AGND from the fourth supply circuit 24 is supplied to the output circuit 116 through an AGND line AGL3 (third analog reference voltage line in a broad sense). Specifically, the voltage AGND is supplied to a preceding-stage circuit 115 (e.g., prefilter or SCF) which is a circuit of the filter section 110 other than the output circuit 116 through the AGND line AGL2, and the voltage AGND is supplied to the output circuit 116 through the AGND line AGL3.

FIG. 18 shows a layout example of the detection circuit 60. As shown in FIG. 18, the AGND lines AGL1, AGL2, and AGL3 are separately provided from the reference voltage supply circuit 20 to the detection circuit 60. Specifically, the three AGND lines AGL1, AGL2, and AGL3 are respectively connected with the amplifier circuit 70, the preceding-stage circuit 115 of the filter section 110, and the output circuit 116 of the filter section 110 while being separated in the layout. This prevents a situation in which noise from the AGND line AGL1 is transmitted to the AGND line AGL2, or noise from the AGND line AGL2 is transmitted to the AGND line AGL3, or noise from the AGND line AGL3 is transmitted to the AGND line AGL1.

Specifically, the frequency of the amplification target signal of the preceding-stage circuit 115 and the output circuit 116 of the filter section 110 is the low frequency  $f2$  at which flicker noise predominantly occurs. Therefore, the second-type operational amplifiers OP2 mainly designed to reduce flicker noise are used for the second supply circuit 22 and the fourth supply circuit 24 which supply the voltage AGND to the preceding-stage circuit 115 and the output circuit 116.

However, when the preceding-stage circuit 115 includes a switched-capacitor filter (SCF) described later, for example, the SNR may deteriorate when a clock signal used in the SCF functions as a noise source. Specifically, clock noise generated by the preceding-stage circuit 115 (SCF) may be superimposed on the output signal VSQ of the output circuit 116. In particular, a gyrosensor detects angular velocity information

by A/D converting the voltage of the output signal VSQ. Therefore, when the voltage of the output signal VSQ varies due to the clock noise, wrong angular velocity information may be detected.

In FIG. 17, although the second and fourth supply circuits 22 and 24 use the second-type operational amplifiers OP2, the AGND line AGL2 of the second supply circuit 22 and the AGND line AGL3 of the fourth supply circuit 24 are separated in the layout. This prevents a situation in which clock noise or the like generated by the preceding-stage circuit 115 is transmitted from the AGND line AGL2 to the AGND line AGL3 and is superimposed on the output signal VSQ, whereby erroneous detection of angular velocity information and the like can be prevented.

FIG. 19 shows a configuration example of the reference voltage supply circuit 20 used in the first modification shown in FIG. 17. In FIG. 19, the fourth supply circuit 24 is additionally provided in the configuration shown in FIG. 13. The fourth supply circuit 24 (fourth impedance conversion circuit) performs voltage impedance conversion using the reference-voltage second-type operational amplifier OP2, for example. Specifically, the second-type operational amplifier OP2 included in the fourth supply circuit 24 is a voltage-follower-connected operational amplifier of which the inverting input terminal (second input terminal) is connected with the output terminal. The output terminal of the second-type operational amplifier OP2 is connected with the AGND line AGL3. A situation in which noise from the AGND line AGL2 is transmitted to the AGND line AGL3 can be effectively prevented by providing the fourth supply circuit 24 having the impedance conversion function.

### 3.3 Second Modification

FIG. 20 shows a second modification of the detection device. The second modification shows a detailed configuration example of the detection circuit 60. The detection circuit 60 shown in FIG. 20 includes the amplifier circuit 70, a sensitivity adjustment circuit 80, the synchronous detection circuit 100, and the filter section 110.

The amplifier circuit 70 includes Q/V conversion circuits 72 and 74 and a differential amplifier circuit 76. The Q/V (I/V) conversion circuits 72 and 74 convert charge (current) generated by the vibrator 10 into voltage. The differential amplifier circuit 76 differentially amplifies output signals VS1P and VS1M from the Q/V conversion circuits 72 and 74.

The Q/V conversion circuit 72 includes a capacitor CA1 and a resistor RA1 provided between nodes NA1 and NA2 and an operational amplifier OPA1, and has low-pass filter frequency characteristics. The input node NA1 is connected with an inverting input terminal (first input terminal) of the operational amplifier OPA1, and the voltage AGND (reference power supply voltage) is connected with a non-inverting input terminal (second input terminal) of the operational amplifier OPA1. The Q/V conversion circuit 74 has the same configuration as the Q/V conversion circuit 72.

The differential amplifier circuit 76 includes resistors RB1, RB2, RB3, and RB4 and an operational amplifier OPB. The differential amplifier circuit 76 amplifies the difference between the input signals VS1P and VS1M with opposite phases by equalizing the resistance ratio of the resistors RB1 and RB2 and the resistance ratio of the resistors RB3 and RB4. Unnecessary signals due to common mode noise, electrostatic coupling leakage, and the like input from the vibrator 10 to the Q/V conversion circuits 72 and 74 can be removed by differential amplification.

In this embodiment, the first supply circuit 21 of the reference voltage supply circuit 20 supplies the voltage AGND

(analog reference voltage) to the Q/V conversion circuits **72** and **74** (first and second charge/voltage conversion circuits or first and second current/voltage conversion circuits) and the differential amplifier circuit **76** using the reference-voltage first-type operational amplifier OP1. It is also desirable to use the first-type operational amplifiers OP1 as the operational amplifiers OPA1, OPA2, and OPB of the Q/v conversion circuits **72** and **74** and the differential amplifier circuit **76** shown in FIG. **20**.

Therefore, the voltage AGND can be supplied to the Q/v conversion circuits **72** and **74** and the differential amplifier circuit **76** which amplify a signal in a high frequency band (driving-side resonance frequency band) in which thermal noise predominantly occurs using the first-type operational amplifiers OP1 mainly designed to reduce thermal noise. As a result, the thermal noise of the Q/v conversion circuits **72** and **74** and the differential amplifier circuit **76** can be reduced, whereby the SNR of the entire system can be increased.

The sensitivity adjustment circuit **80** adjusts the sensitivity (the amount of change in output voltage per unit angular velocity) by variably controlling the gain.

In FIG. **20**, the sensitivity adjustment circuit **80** is provided in the preceding stage of the synchronous detection circuit **100**. A sensitivity adjustment is performed for the signal having the frequency  $f_d$  instead of the DC signal by providing the sensitivity adjustment circuit **80** (programmable gain amplifier) in the preceding stage of the synchronous detection circuit **100**. Therefore, an adverse effect of flicker noise ( $1/f$  noise) which is reduced as the frequency increases can be minimized. Moreover, since the number of circuit blocks provided in the preceding stage of the sensitivity adjustment circuit **80** is reduced in comparison with the case of providing the sensitivity adjustment circuit in the subsequent stage of the filter section **110**, deterioration in SNR which occurs when the sensitivity adjustment circuit **80** amplifies noise generated by these circuit blocks can be minimized.

The sensitivity adjustment circuit **80** shown in FIG. **20** is an example of a non-inverting amplifier circuit. Note that an inverting amplifier circuit may be used as the sensitivity adjustment circuit **80**.

In the sensitivity adjustment circuit **80**, the resistance of a variable resistor RD2 between an output node ND3 and an output tap QT and the resistance of a variable resistor RD1 between the output tap QT and a node of the voltage AGND are variably controlled based on sensitivity adjustment data DPGA. This allows adjustment of the gain of the sensitivity adjustment circuit **80**, whereby the sensitivity is adjusted. For example, when the resistances of the variable resistors RD1 and RD2 are respectively referred to as R1 and R2, the gain of the sensitivity adjustment circuit **80** (PGA) is  $G=(R1+R2)/R1$ .

The sensitivity adjustment circuit **80** shown in FIG. **20** operates as a programmable-gain amplifier and a high-pass filter, for example. Specifically, a capacitor CD1, a resistor RD3, and an operational amplifier OPD form a high-pass active filter. Specifically, the operational amplifier OPD functions as a buffer for the high-pass filter formed of the capacitor CD1 and the resistor RD3. A programmable-gain amplifier is formed of the variable resistors RD1 and RD2 and the operational amplifier OPD. Specifically, the operational amplifier OPD is used in common by the high-pass active filter and the programmable-gain amplifier.

The DC component can be cut off by causing the sensitivity adjustment circuit **80** to operate as the high-pass filter, whereby a situation can be prevented in which the DC signal is amplified by the programmable-gain amplifier (PGA). Therefore, a problem can be prevented in which the program-

mable-gain amplifier of the sensitivity adjustment circuit **80** or the operational amplifier in the subsequent stage (e.g. operational amplifier of the synchronous detection circuit) is saturated due to overinput, whereby the output overflows. Moreover, DC noise can be removed by the high-pass filter, whereby the SNR can be increased.

In the sensitivity adjustment circuit **80**, the operational amplifier OPD is used in common by the high-pass active filter and the programmable-gain amplifier. Therefore, the number of operational amplifiers can be reduced as compared with the case of separately providing an operational amplifier for the active filter and an operational amplifier for the programmable-gain amplifier. Therefore, the circuit scale can be reduced. Moreover, since the number of circuit blocks as the noise source can be reduced, the SNR can be increased.

In this embodiment, the first supply circuit **21** of the reference voltage supply circuit **20** supplies the voltage AGND (analog reference voltage) to the sensitivity adjustment circuit **80** using the reference-voltage first-type operational amplifier OP1 described with reference to FIGS. **5C** and **11A**.

This enables the voltage AGND to be supplied to the sensitivity adjustment circuit **80** which processes a signal in a high frequency band (driving-side resonance frequency band) in which thermal noise predominantly occurs using the first-type operational amplifier OP1 mainly designed to reduce thermal noise. As a result, the thermal noise of the sensitivity adjustment circuit **80** can be reduced, whereby the SNR of the entire system can be increased.

The synchronous detection circuit **100** performs synchronous detection based on the synchronization signal CLK from the driver circuit **40**. The synchronous detection circuit **100** includes a switching element SE1 ON/OFF-controlled based on the synchronization signal CLK, and a switching element SE2 ON/OFF-controlled based on an inversion synchronization signal CLKN. The synchronous detection circuit **100** performs synchronous detection using a single balanced mixer method. A signal VS5 is input to the switching element SE1, and an inversion signal VS5N of the signal VS5 is input to the switching element SE2.

FIG. **21** shows a signal waveform example illustrative of synchronous detection. As shown in FIG. **21**, the input signal VS5 is output to the output terminal as the signal VS6 in a first period T1 in which the synchronization signal CLK is set at the H level, and the inversion signal VS5N of the input signal VS5 is output to the output terminal as the signal VS6 in a second period T2 in which the synchronization signal CLK is set at the L level. The gyrosensor output signal (desired signal) can be detected and extracted by synchronous detection. Note that the synchronous detection circuit **100** may utilize a double balanced mixer method.

In FIG. **20**, the synchronous detection circuit **100** includes an offset adjustment circuit **90** (zero-point adjustment circuit). The offset adjustment circuit **90** removes an initial offset voltage (offset voltage) of the output signal VSQ of the detection device **30**. For example, the offset adjustment circuit **90** performs an offset adjustment process so that the voltage of the output signal VSQ coincides with the reference output voltage at a typical temperature of 25° C.

The offset adjustment circuit **90** includes a D/A conversion circuit **92** and an adder circuit (adder-subtractor circuit) **94**. The D/A conversion circuit **92** converts initial offset adjustment data DDA into an analog initial offset adjustment voltage VA.

The adder circuit **94** adds the adjustment voltage VA from the D/A conversion circuit **92** to the voltage of the input signal VS5. The adder circuit **94** includes resistors RE1, RE2, and RE3 respectively provided between a node NE5 and nodes

NE6, NE1, and NE2. The adder circuit 94 also includes an operational amplifier OPE of which the inverting input terminal is connected with the node NE5 and the noninverting input terminal is connected with a node of the voltage AGND. In FIG. 20, a modification may be made in which the offset adjustment circuit 90 is not provided in the synchronous detection circuit 100.

With regard to the unnecessary signals described with reference to FIGS. 16A to 16C, an unnecessary signal caused by the detuning frequency  $\Delta f = |fd - fs|$  occurs when a signal having the detection-side resonance frequency  $fs$  is mixed into the gyrosensor detection signal and the resulting detection signal is synchronously detected by the synchronous detection circuit 100. For example, the detection vibrator may be allowed to vibrate (idle) with a small amplitude at the natural resonance frequency  $fs$  in order to improve the response of the gyrosensor. Or, the detection vibrator may vibrate at the natural resonance frequency  $fs$  when external vibration from the outside of the gyrosensor is applied to the vibrator. When the detection vibrator vibrates at the frequency  $fs$ , a signal having the frequency  $fs$  is mixed into the signal VS5 input to the synchronous detection circuit 100. Since the synchronous detection circuit 100 performs synchronous detection based on the synchronization signal CLK having the frequency  $fd$ , an unnecessary signal having the detuning frequency  $\Delta f = |fd - fs|$  corresponding to the difference between the frequencies  $fd$  and  $fs$  is generated.

The detuning frequency  $\Delta f = |fd - fs|$  is sufficiently lower than the frequencies  $fd$  and  $fs$ . Therefore, steep attenuation characteristics shown in FIG. 22 are necessary to remove the unnecessary signal of the component having the detuning frequency  $\Delta f$ . Therefore, it is difficult to remove the unnecessary signal of the component having the detuning frequency  $\Delta f$  using only a continuous-time low-pass filter.

In order to solve the above problem, a switched-capacitor filter (SCF) 114 (discrete-time filter) is provided in the filter section 110 in FIG. 20. The SCF 114 has frequency characteristics of removing the component having the detuning frequency  $\Delta f = |fd - fs|$  corresponding to the difference between the driving-side resonance frequency  $fd$  and the detection-side resonance frequency  $fs$  of the vibrator and allowing the frequency component (DC component) of the desired signal to pass through. The filter section 110 also includes a prefilter 112 provided in the preceding stage of the SCF 114, and an output circuit 116 which is provided in the subsequent stage of the SCF 114 and functions as an output buffer and a postfilter. The prefilter 112 and the output circuit 116 are continuous-time filters.

The steep attenuation characteristics shown in FIG. 22 are easily realized by providing the SCF 114 (discrete-time filter in a broad sense) in the filter section 110, as shown in FIG. 20. Therefore, even if the detuning frequency  $\Delta f$  is extremely lower than the frequency  $fd$ , the component of the unnecessary signal in the frequency band of the detuning frequency  $\Delta f$  can be reliably and easily removed without adversely affecting the desired signal in the pass band.

As shown in FIG. 20, the SCF 114 includes switched capacitor circuits 210, 212, and 214, capacitors CG4, CG5, CG6, and CG7, and operational amplifiers OPG1 and OPG2. The configuration of the SCF 114 is not limited to the configuration shown in FIG. 20. Various known configurations may be used.

When providing the SCF 114 in the filter section 110 as shown in FIG. 20, since the SCF 114 samples the signal in discrete time, aliasing occurs which is a frequency fold-over phenomenon caused by sampling.

In order to prevent an adverse effect of such aliasing, the anti-aliasing prefilter 112 (continuous-time filter in a broad sense) is provided in the preceding stage of the SCF 114 in FIG. 20. Specifically, when the sampling frequency is  $f_{sp}$  ( $=fd$ ), the prefilter 112 has anti-aliasing frequency characteristics of removing frequency components equal to or higher than the frequency  $f_{sp}/2$  ( $=fd/2$ ).

In this case, the frequency band of the desired signal is  $fa0$  or less (i.e., the frequency of the desired signal is low), as shown in FIG. 22, for example. On the other hand, the sampling frequency  $f_{sp}$  of the SCF 114 is 50 to 500 times the frequency  $fa0$  (i.e., the sampling frequency  $f_{sp}$  is high), for example. Therefore, steep attenuation characteristics are unnecessary when using a normal anti-aliasing prefilter.

However, it was found that a sensor processing a weak signal such as a gyrosensor cannot remove an unnecessary signal utilizing normal anti-aliasing attenuation characteristics. Specifically, the amplitude of the unnecessary signal included in the gyrosensor detection signal is about 100 to 500 times the amplitude of the desired signal, for example. Therefore, the amplitude of the unnecessary signal becomes higher than the amplitude of the desired signal (DC component) when utilizing normal anti-aliasing attenuation characteristics, whereby the SNR deteriorates due to the fold-over effect on the DC component caused by sampling of the SCF 114, for example.

Therefore, the prefilter 112 (continuous-time filter) preferably has frequency characteristics (filtering characteristics or attenuation characteristics) of attenuating the amplitude of the unnecessary signal, which appears in the frequency band of the frequency  $k \times fd$  ( $k$  is a positive integer) due to synchronous detection by the synchronous detection circuit 100, to a value equal to or smaller than the amplitude of the desired signal (minimum resolution). The amplitude of the desired signal corresponds to the minimum resolution of the desired signal, and corresponds to degrees per second (dps). The amplitude of the desired signal is the amplitude of the desired signal in the DC frequency region.

Therefore, even if the unnecessary signal having an amplitude about 100 to 500 times the amplitude of the desired signal appears at the frequency  $k \times fd$ , the frequency component of the unnecessary signal can be reliably removed using the prefilter 112.

In this embodiment, the second supply circuit 22 of the reference voltage supply circuit 20 supplies the voltage AGND (analog reference voltage) to the prefilter 112 (continuous-time filter) and the SCF 114 (discrete-time filter) using the reference-voltage second-type operational amplifier OP2 described with reference to FIGS. 5B, 5C, and 11B. The fourth supply circuit 24 described with reference to FIG. 19 supplies the voltage AGND to the output circuit 116 by using the reference-voltage second-type operational amplifier OP2. Specifically, the second supply circuit 22 supplies the voltage AGND to the operational amplifiers OPH, OPG1, and OPG2, and the fourth supply circuit 24 supplies the voltage AGND to the operational amplifier OPI. It is also desirable to use the second-type operational amplifiers as the operational amplifiers OPH, OPG1, OPG2, and OPI.

In FIG. 20, the SCF 114 with steep attenuation characteristics is used to remove the unnecessary signal due to the detuning frequency. The operational amplifiers OPG1 and OPG2 are necessary in order to realize the SCF 114.

In FIG. 20, the anti-aliasing prefilter 112 is also used as a filter which removes the unnecessary signal which appears at the frequency  $k \times fd$  due to synchronous detection. Therefore, a second-order active low-pass filter is used as the prefilter

112, for example. The operational amplifier OPH is required for realizing the active low-pass filter.

In FIG. 20, the output circuit 116 functions as the output buffer which subjects the output signal VSQ to impedance conversion and also functions as the postfilter for the SCF 114. The operational amplifier OP1 is required for realizing the function of the output buffer and the function of the postfilter.

As described above, the operational amplifiers OPH, OPG1, OPG2, and OP1 are provided in the filter section 110, and the SNR of the entire system deteriorates to a large extent when these operational amplifier have a high noise level.

In this embodiment, the voltage AGND can be supplied to the operational amplifiers OPH, OPG1, OPG2, and OP1 which process the signal in a low frequency band (frequency band of desired signal) in which flicker noise predominantly occurs using the second-type operational amplifiers OP2 mainly designed to reduce flicker noise. Therefore, even if these operational amplifiers are used, the flicker noise of the filter section 110 can be minimized, whereby the SNR of the entire system can be increased.

#### 4. Electronic Instrument

FIG. 23 shows a configuration example of a gyrosensor 510 (sensor in a broad sense) including the detection device 30 according to this embodiment, and an electronic instrument 500 including the gyrosensor 510. The electronic instrument 500 and the gyrosensor 510 are not limited to the configuration shown in FIG. 23. Various modification may be made such as omitting some elements or adding another element. As the electronic instrument 500 according to this embodiment, various electronic instruments such as a digital camera, a video camera, a portable telephone, a car navigation system, a robot, a game machine, and a personal digital assistant may be considered.

The electronic instrument 500 includes the gyrosensor 510 and a processing section 520. The electronic instrument 500 may also include a memory 530, an operation section 540, and a display section 550. The processing section (e.g., CPU or MPU) 520 controls the gyrosensor 510 and the like, and controls the entire electronic instrument 500. The processing section 520 performs processes based on information (angular velocity information or physical quantity) detected by the gyrosensor 510. For example, the processing section 520 performs processes for image blur correction, position control, GPS autonomous navigation, and the like based on the detected angular velocity information. The memory (e.g. ROM or RAM) 530 stores a control program and various types of data, and functions as a work area and a data storage area. The operation section 540 allows the user to operate the electronic instrument 500, and the display section 550 displays various types of information for the user. The detection device 30 according to this embodiment allows a small sensor to be employed as the gyrosensor 510 incorporated in the electronic instrument 500. This enables a reduction in size and cost of the electronic instrument 500.

Although only some embodiments of the invention have been described in detail above, those skilled in the art would readily appreciate that many modifications are possible in the embodiments without materially departing from the novel teachings and advantages of the invention. Accordingly, such modifications are intended to be included within the scope of the invention. Any term (e.g. vibrator, gyrosensor, AGND, or SCF) cited with a different term (e.g. physical quantity transducer, sensor, analog reference voltage, or discrete-time filter) having a broader meaning or the same meaning at least once in the specification and the drawings can be replaced by

the different term in any place in the specification and the drawings. The configurations of the reference voltage supply circuit, the analog circuit, the receiver device, the detection device, and the electronic instrument are not limited to those described in the above embodiments. Various modifications and variations may be made.

What is claimed is:

1. A reference voltage supply circuit comprising:
  - a first supply circuit that includes a reference-voltage first-type operational amplifier and supplies an analog reference voltage to a first analog reference voltage line; and
  - a second supply circuit that includes a reference-voltage second-type operational amplifier and supplies the analog reference voltage to a second analog reference voltage line;
 when a channel width and a channel length of a differential-stage transistor of a differential section of the reference-voltage first-type operational amplifier are respectively referred to as  $W1a$  and  $L1a$ , a bias current flowing through the differential section of the reference-voltage first-type operational amplifier is referred to as  $Ia$ , a channel width and a channel length of a differential-stage transistor of a differential section of the reference-voltage second-type operational amplifier are respectively referred to as  $W1b$  and  $L1b$ , and a bias current flowing through the differential section of the reference-voltage second-type operational amplifier is referred to as  $Ib$ ,  $W1b \times L1b > W1a \times L1a$  and  $Ia > Ib$  being satisfied.
2. The reference voltage supply circuit as defined in claim 1,
  - when a frequency of an amplification target signal of a first circuit to which the analog reference voltage is supplied from the first supply circuit is referred to as  $f1$ , a frequency of an amplification target signal of a second circuit to which the analog reference voltage is supplied from the second supply circuit is referred to as  $f2$ , and a corner frequency of flicker noise and thermal noise in frequency-noise characteristics is referred to as  $fcr$ , the reference-voltage first-type operational amplifier satisfying  $f1 - fcr < fcr - f2$ , and the reference-voltage second-type operational amplifier satisfying  $fcr - f2 < f1 - fcr$ .
3. The reference voltage supply circuit as defined in claim 1,
  - when a channel length of an active-load-stage transistor of the differential section of the reference-voltage second-type operational amplifier is referred to as  $L3b$ ,  $L1b < L3b$  being satisfied.
4. The reference voltage supply circuit as defined in claim 1,
  - when a WL ratio of the differential-stage transistor of the reference-voltage first-type operational amplifier is referred to as  $RT1a$  and a WL ratio of an active-load-stage transistor of the reference-voltage first-type operational amplifier is referred to as  $RT3a$ ,  $RT1a > RT3a$  being satisfied.
5. The reference voltage supply circuit as defined in claim 1,
  - when an effective gate voltage of the differential-stage transistor of the reference-voltage second-type operational amplifier is referred to as  $V_{eff}$ , a drain-source current is referred to as  $I_{ds}$ , a mobility is referred to as  $\mu$ , a gate capacitance per unit area is referred to as  $C_{ox}$ , a WL ratio is referred to as  $RT1b$ , a Boltzmann constant is referred to as  $k$ , an absolute temperature is referred to as  $T$ , an amount of electronic charge is referred to as  $q$ , and a process variation parameter is referred to as  $P$  ( $P > 1$ ),

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the WL ratio  $RT1b$  being set at a value satisfying the relationship  $P \times (k \times T / q) > V_{eff} = \{2 \times I_{ds} / (\mu \times C_{ox} \times RT1b)\}^{1/2} > k \times T / q$ .

6. The reference voltage supply circuit as defined in claim 1,
- 1, when the area of an arrangement region of the differential-stage transistor of the reference-voltage second-type operational amplifier is referred to as  $S_{df}$  and the area of an arrangement region of the elements forming the reference-voltage second-type operational amplifier other than the differential-stage transistor of the reference-voltage second-type operational amplifier is referred to as  $S_{re}$ ,  $S_{df} > S_{re}$  being satisfied.
7. The reference voltage supply circuit as defined in claim 6,
- 6, the differential-stage transistor of the reference-voltage second-type operational amplifier including  $J$  ( $J > 2$ ) transistors connected in parallel; and
- the  $J$  transistors connected in parallel being disposed in the arrangement region of the differential-stage transistor of the reference-voltage second-type operational amplifier.
8. The reference voltage supply circuit as defined in claim 7, further comprising:
  - an active-load-stage transistor of the reference-voltage second-type operational amplifier including  $I$  ( $I > 2$ ) transistors connected in parallel; and
  - the  $J$  transistors forming the differential-stage transistor of the reference-voltage second-type operational amplifier being arranged along a direction  $X$ , and the  $I$  transistors forming the active-load-stage transistor being arranged along the direction  $X$  on a direction  $Y$  side of the  $J$  transistors.
9. The reference voltage supply circuit as defined in claim 1,
- 1, the first supply circuit being a circuit which performs voltage impedance conversion using the reference-voltage first-type operational amplifier; and
- the second supply circuit being a circuit which performs voltage impedance conversion using the reference-voltage second-type operational amplifier.
10. The reference voltage supply circuit as defined in claim 1, further comprising:
  - a third supply circuit that is provided in a preceding stage of the first and second supply circuits, includes a reference-voltage third-type operational amplifier, and supplies a voltage to the first and second supply circuits;
  - when a channel width and a channel length of a differential-stage transistor of a differential section of the reference-voltage third-type operational amplifier are respec-

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tively referred to as  $W1c$  and  $L1c$  and a bias current which flows through the differential section of the reference-voltage third-type operational amplifier is referred to as  $I_c$ ,  $W1c \times L1c > W1a \times L1a$  and  $I_c > I_b$  being satisfied.

11. The reference voltage supply circuit as defined in claim 10,
- 10,  $W1c \times L1c > W1b \times L1b$  and  $I_c > I_a$  being satisfied.
12. An analog circuit comprising:
  - the reference voltage supply circuit as defined in claim 1,
  - a first circuit to which the analog reference voltage is supplied from the first supply circuit of the reference voltage supply circuit through the first analog reference voltage line; and
  - a second circuit to which the analog reference voltage is supplied from the second supply circuit of the reference voltage supply circuit through the second analog reference voltage line.
13. The analog circuit as defined in claim 12, further comprising:
  - a mixer that mixes a signal with a specific frequency into a signal including a desired signal;
  - the first circuit being a circuit provided on a preceding stage of the mixer; and
  - the second circuit being a circuit provided on a subsequent stage of the mixer.
14. The analog circuit as defined in claim 13,
- the first circuit being a first amplifier circuit which amplifies an input signal; and
- the reference voltage supply circuit supplying the analog reference voltage to the first amplifier circuit through the first analog reference voltage line.
15. The analog circuit as defined in claim 13,
- the second circuit being a second amplifier circuit that amplifies the mixed signal from the mixer or a filter section that filters the mixed signal from the mixer; and
- the reference voltage supply circuit supplying the analog reference voltage to the second amplifier circuit or the filter section through the second analog reference voltage line.
16. An electronic instrument comprising:
  - the analog circuit as defined in claim 12; and
  - a processing section that performs processes based on detection information of the analog circuit.
17. An electronic instrument comprising:
  - the analog circuit as defined in claim 13; and
  - a processing section that performs processes based on detection information of the analog circuit.

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