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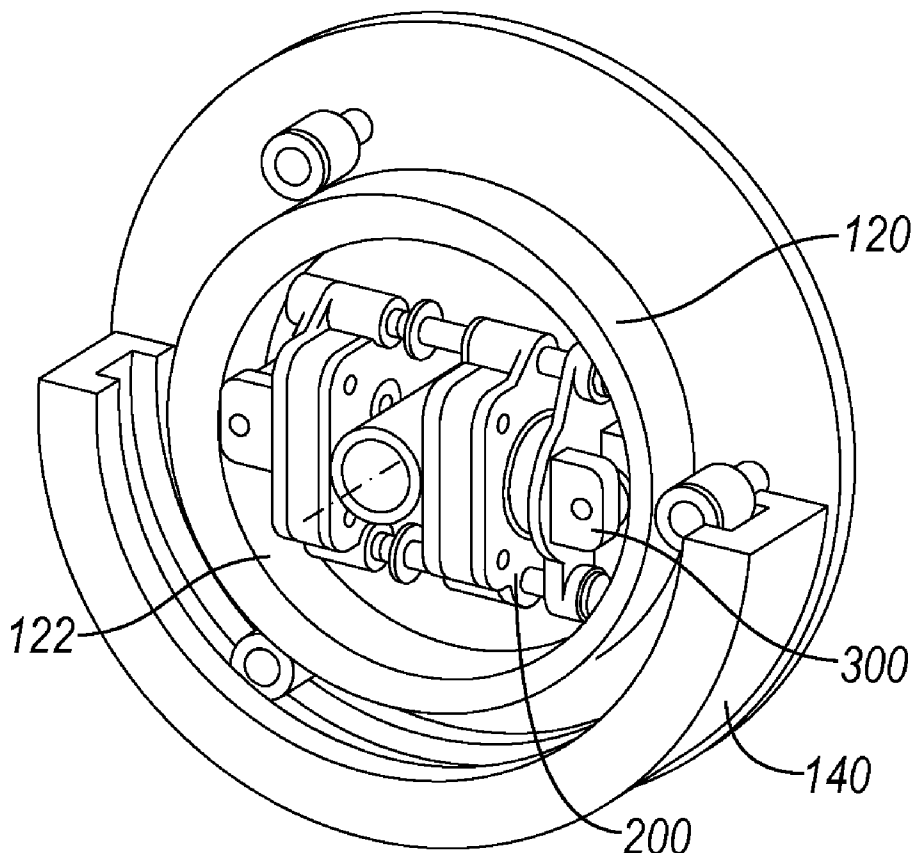
(19) **United States**(12) **Patent Application Publication**
Richardson et al.(10) **Pub. No.: US 2015/0367693 A1**(43) **Pub. Date: Dec. 24, 2015**(54) **TIRE INFLATION SYSTEM****Publication Classification**(71) Applicant: **Aperia Technologies, Inc.**, Burlingame, CA (US)(72) Inventors: **Brandon Richardson**, Burlingame, CA (US); **David Carlberg**, Burlingame, CA (US); **Agustus Shelander**, Burlingame, CA (US)(51) **Int. Cl.**
B60C 23/12 (2006.01)
F04B 49/08 (2006.01)
B60C 23/00 (2006.01)
F04B 35/01 (2006.01)(52) **U.S. Cl.**
CPC **B60C 23/12** (2013.01); **F04B 35/01** (2013.01); **F04B 49/08** (2013.01); **B60C 23/003** (2013.01)(21) Appl. No.: **14/839,009**(22) Filed: **Aug. 28, 2015****Related U.S. Application Data**

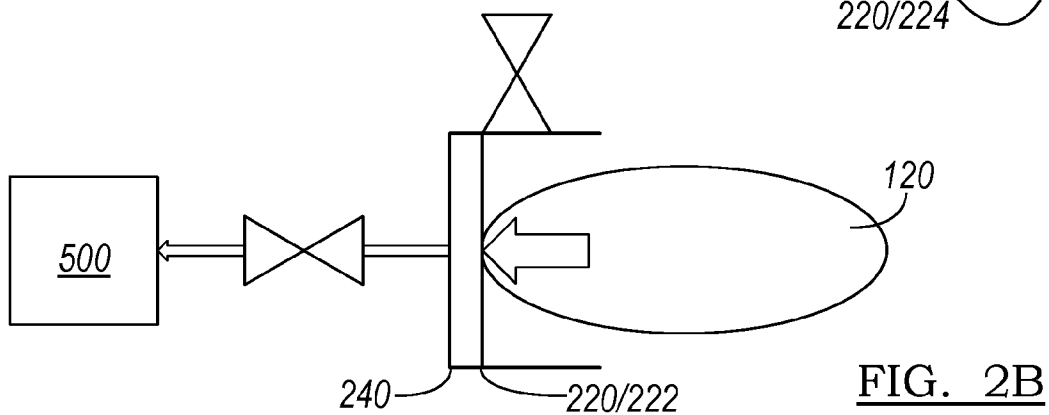
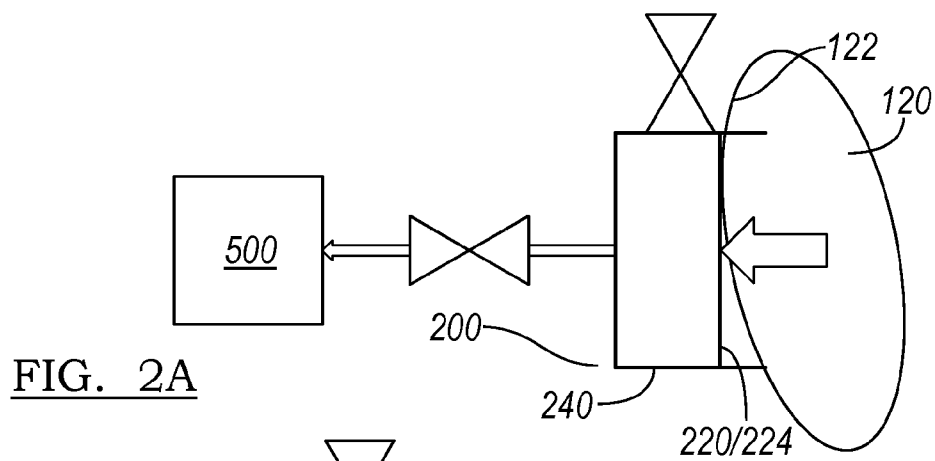
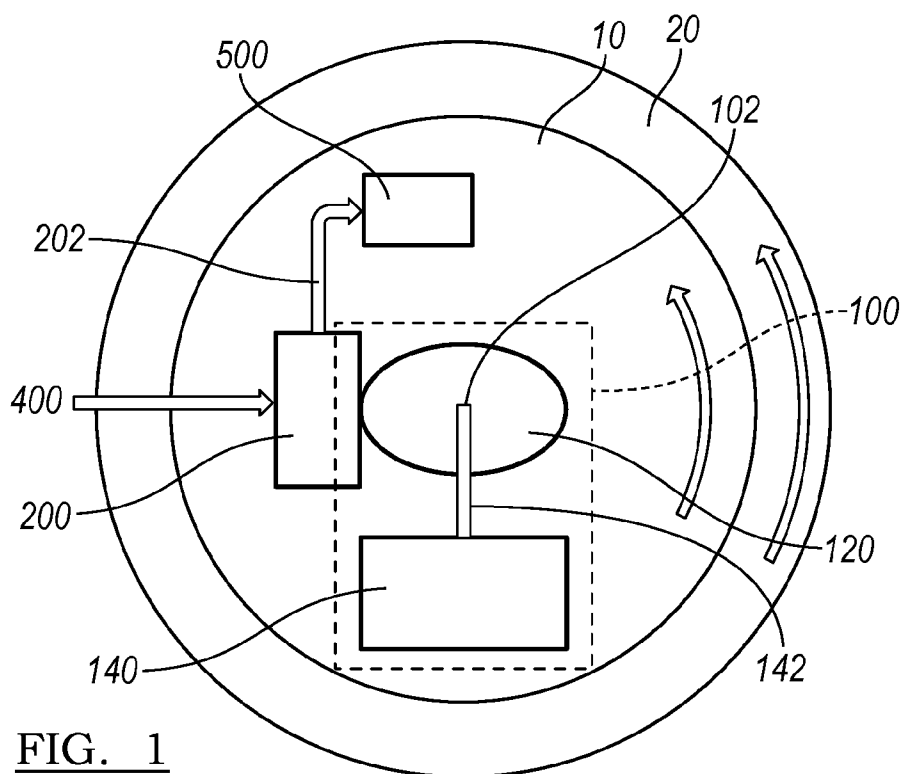
(63) Continuation of application No. 14/019,941, filed on Sep. 6, 2013, now Pat. No. 9,151,288, which is a continuation of application No. 13/797,826, filed on Mar. 12, 2013, now Pat. No. 9,039,392.

(60) Provisional application No. 61/613,406, filed on Mar. 20, 2012, provisional application No. 61/637,206, filed on Apr. 23, 2012, provisional application No. 61/672,223, filed on Jul. 16, 2012.

(57) **ABSTRACT**

A tire inflation system including a drive mechanism having a rotational axis, a pump cavity positioned a radial distance away from the axis of rotation, and a force translator coupling the rotational axis to the pump cavity. The drive mechanism includes a cam comprising an arcuate bearing surface having a non-uniform curvature, the cam rotatable about the rotational axis, and an eccentric mass couple to the cam that offsets a center of mass of the drive mechanism from the rotational axis. The pump cavity is rotatably coupled to the cam, wherein the pump cavity includes an actuating element and a chamber. The force translator couples the arcuate bearing surface to the actuating element, wherein the force translator includes an axis having an arcuate position fixed to an arcuate position of the pump cavity.





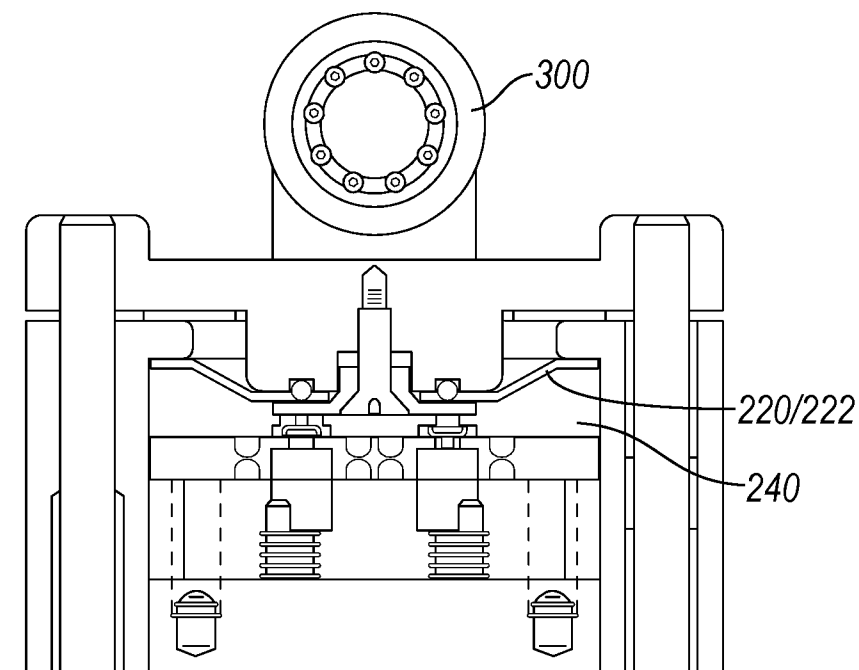


FIG. 3A

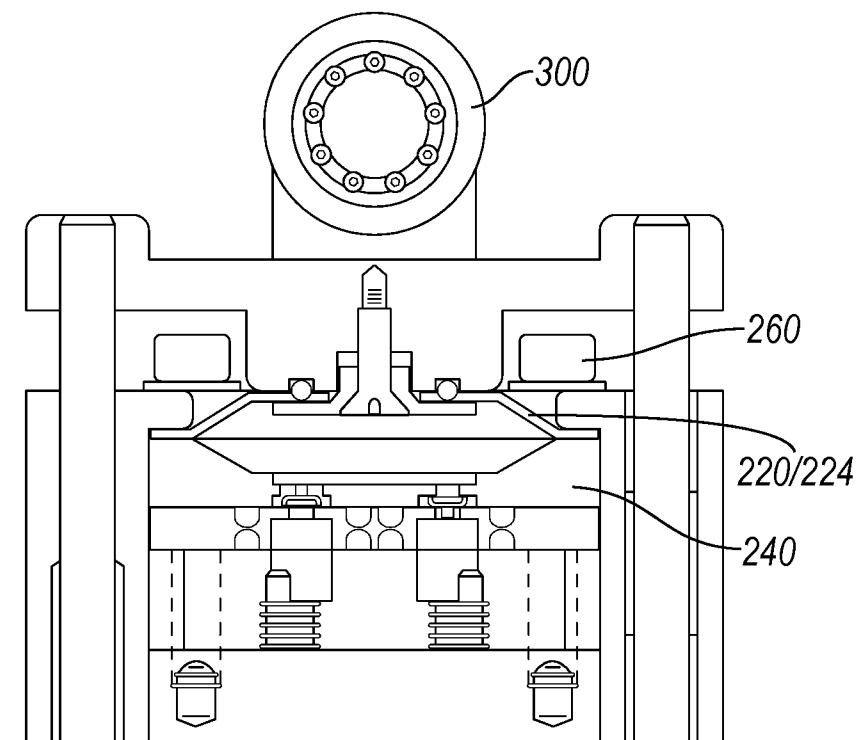


FIG. 3B

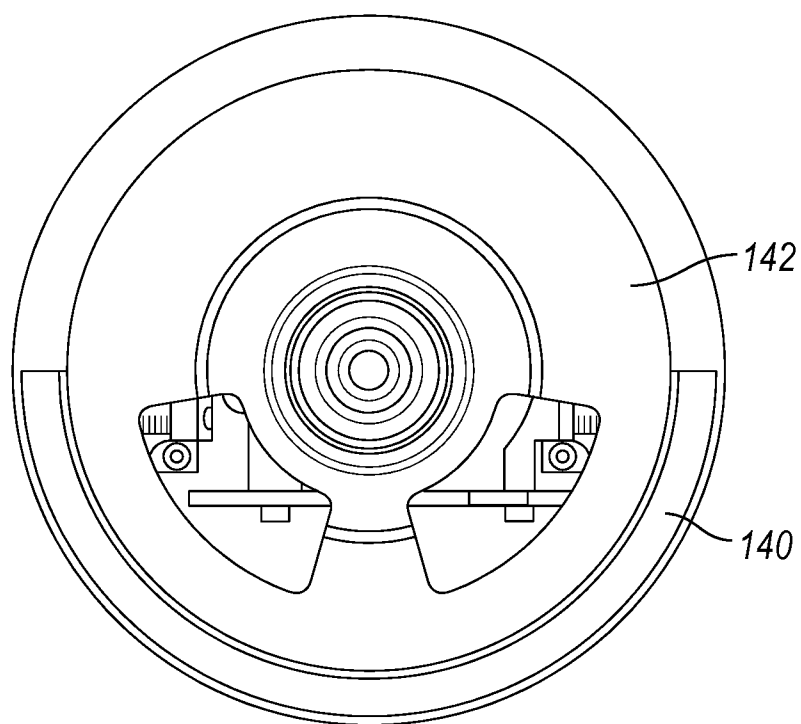


FIG. 4A

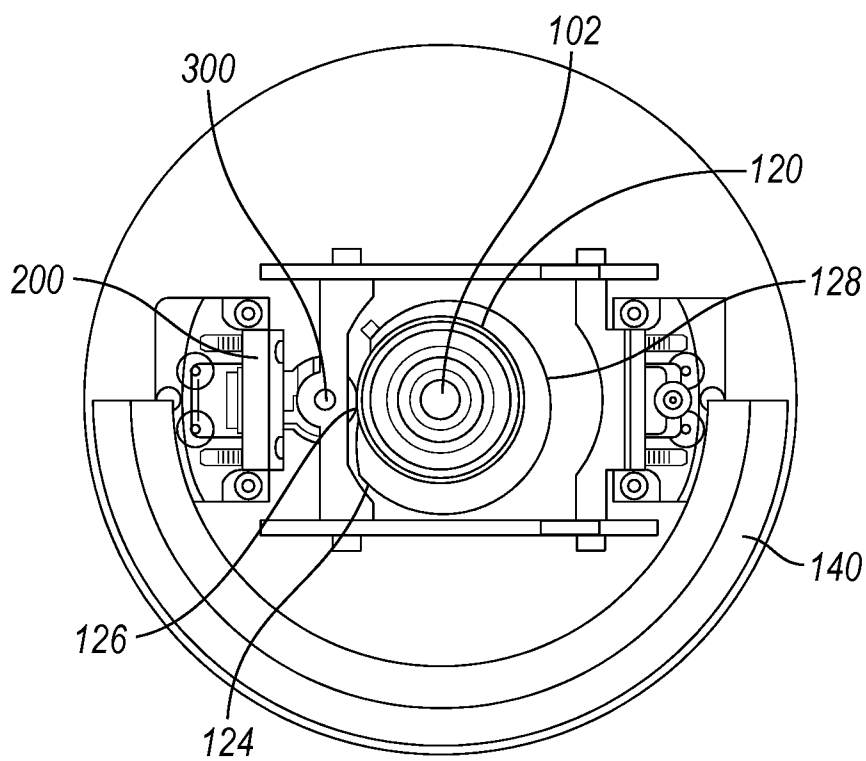
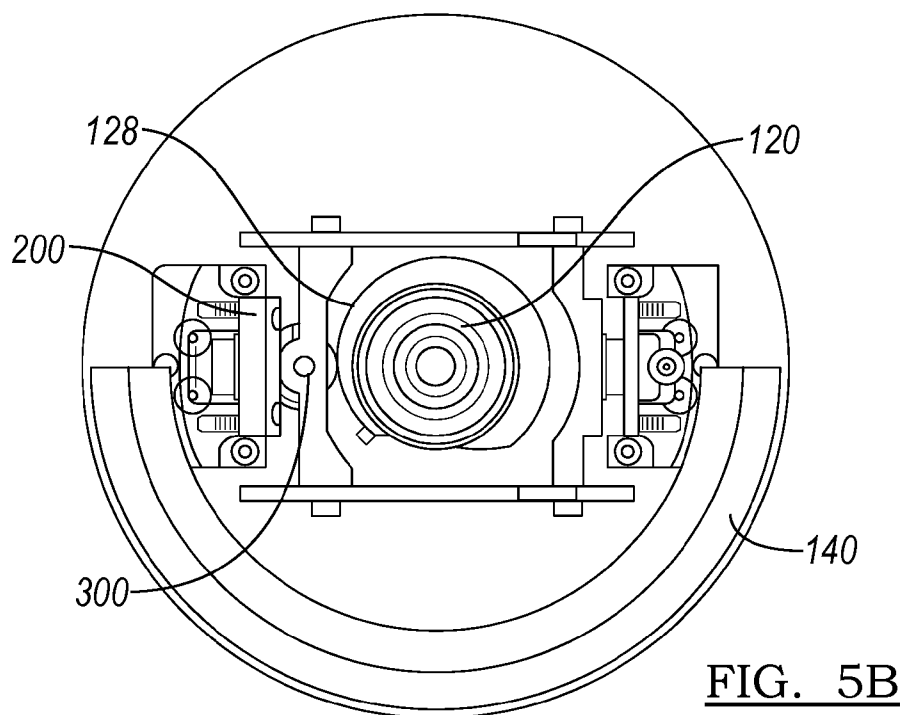
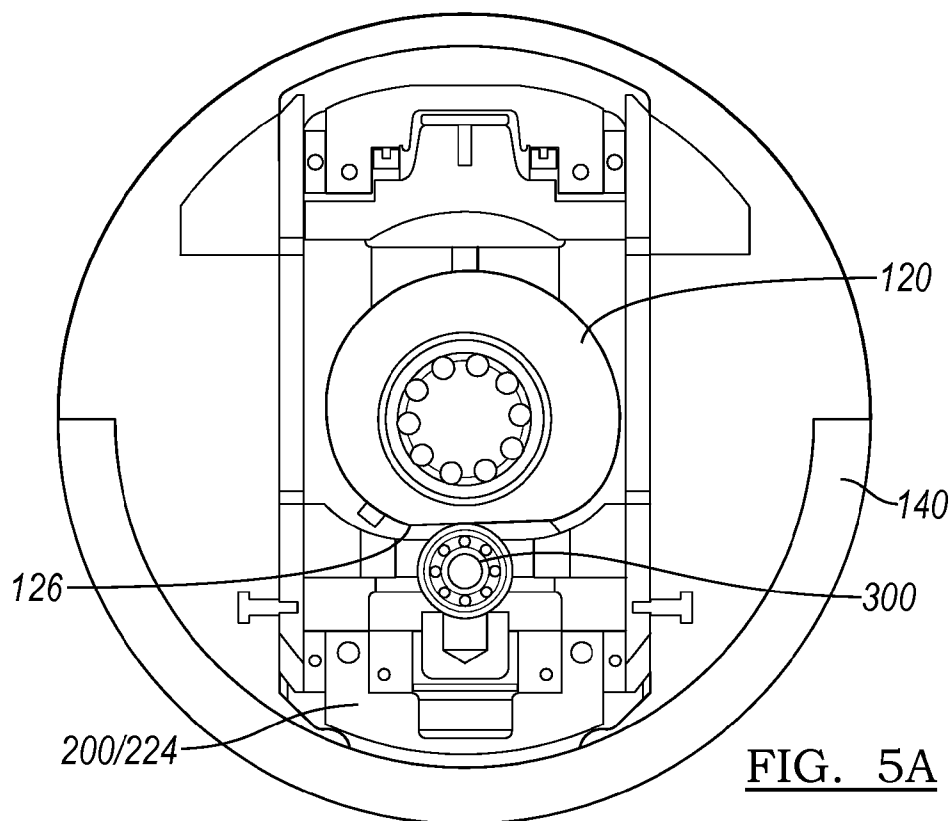


FIG. 4B



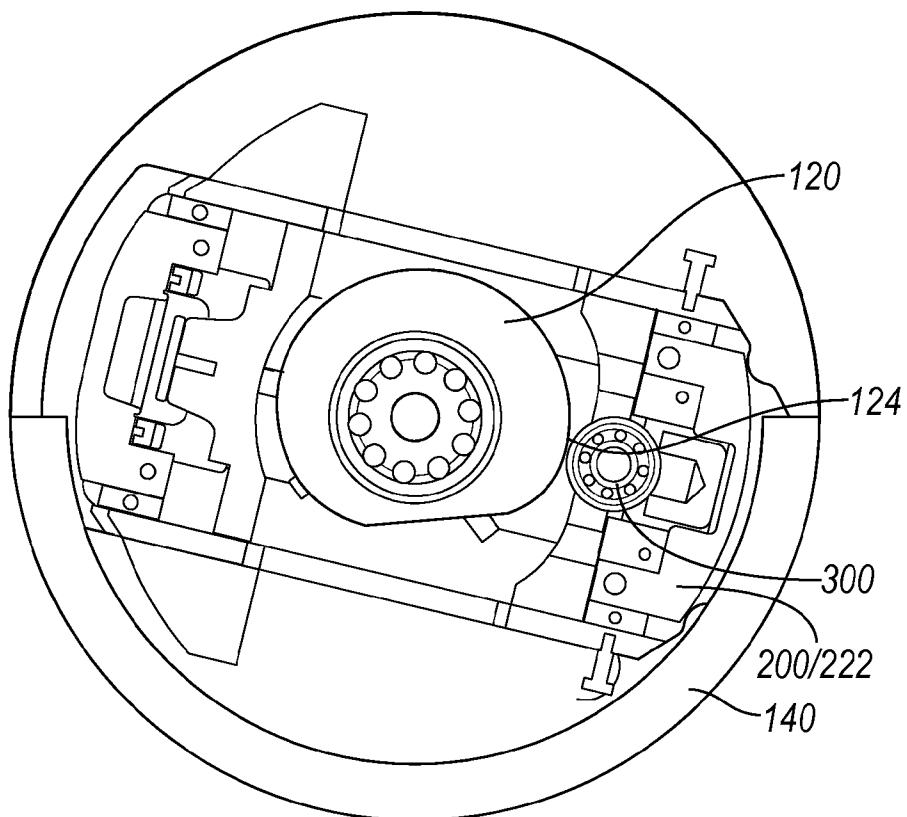


FIG. 5C

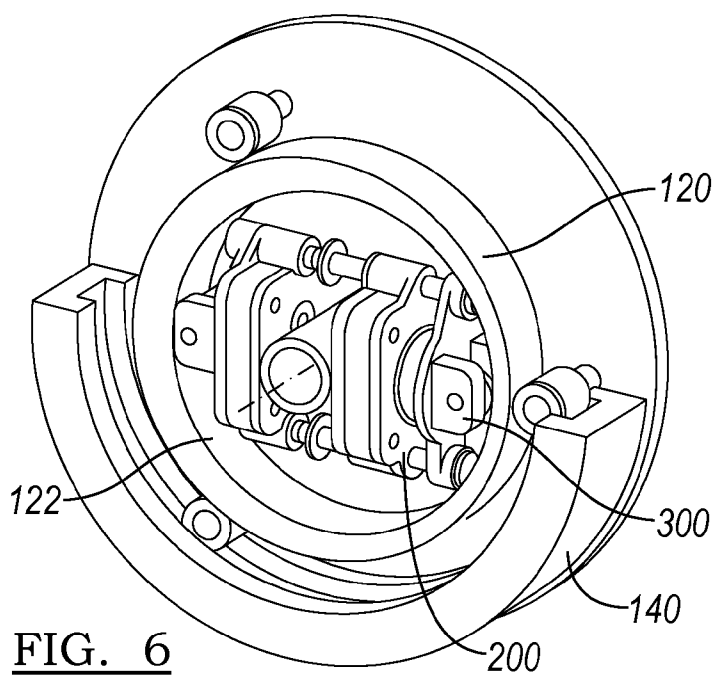


FIG. 6

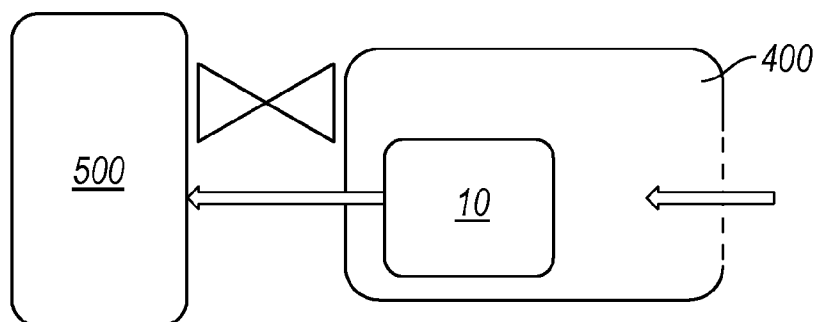


FIG. 7A

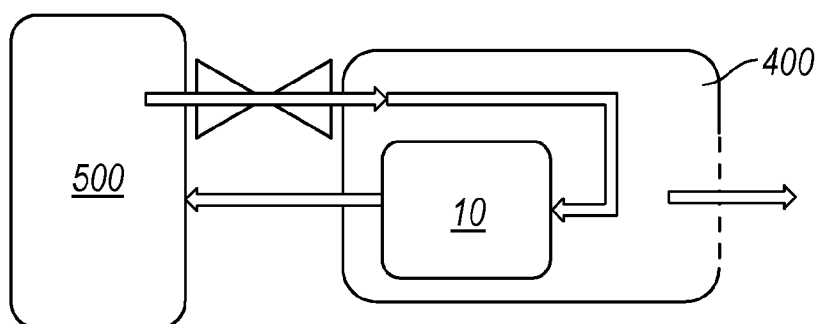


FIG. 7B

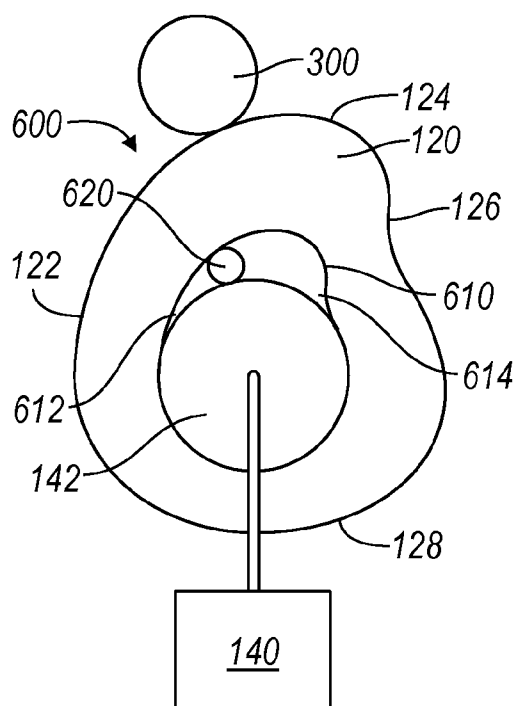


FIG. 8A

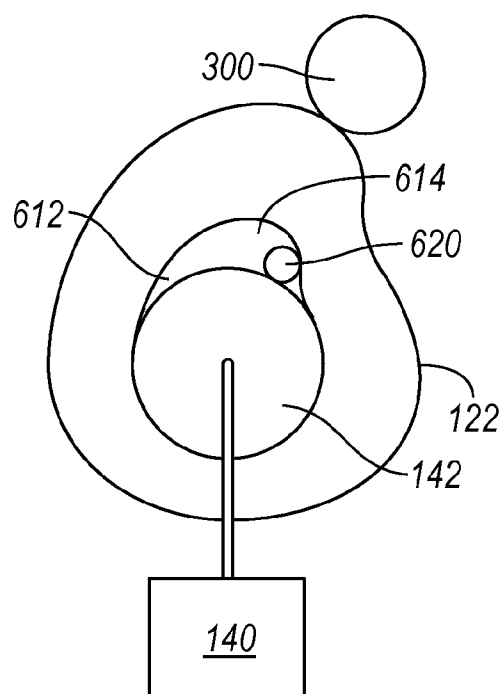


FIG. 8B

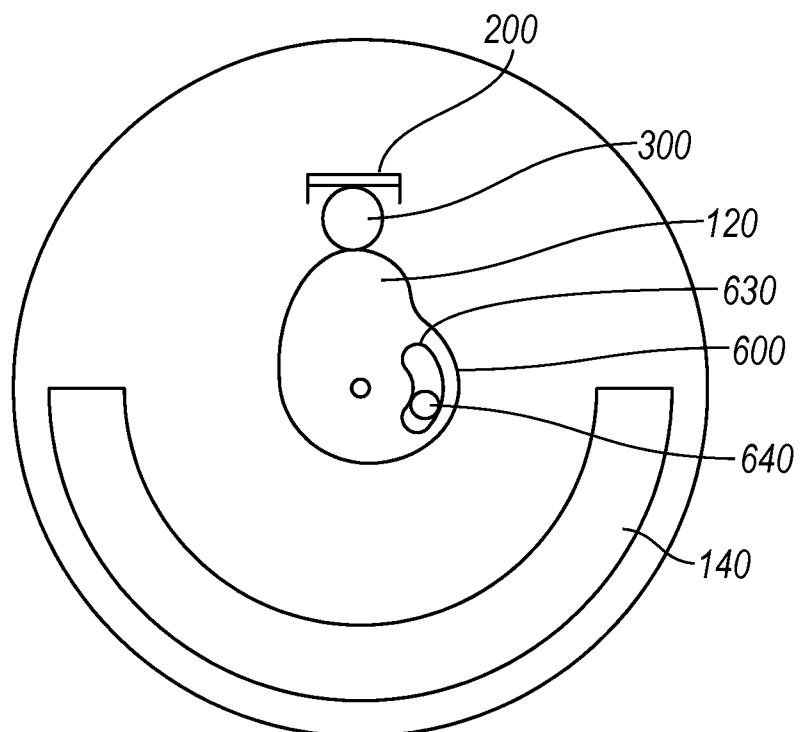


FIG. 9A

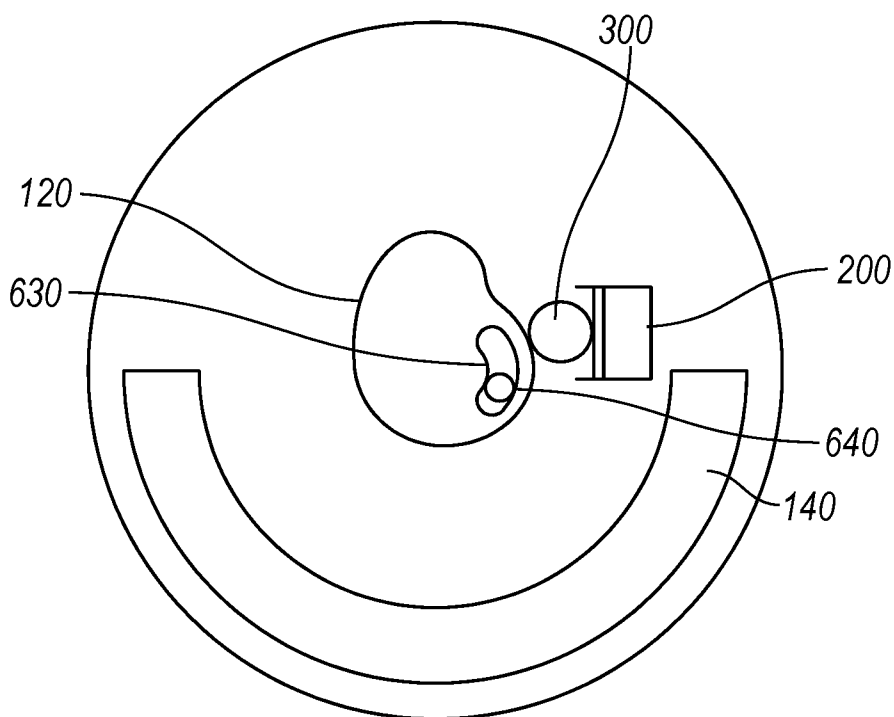


FIG. 9B

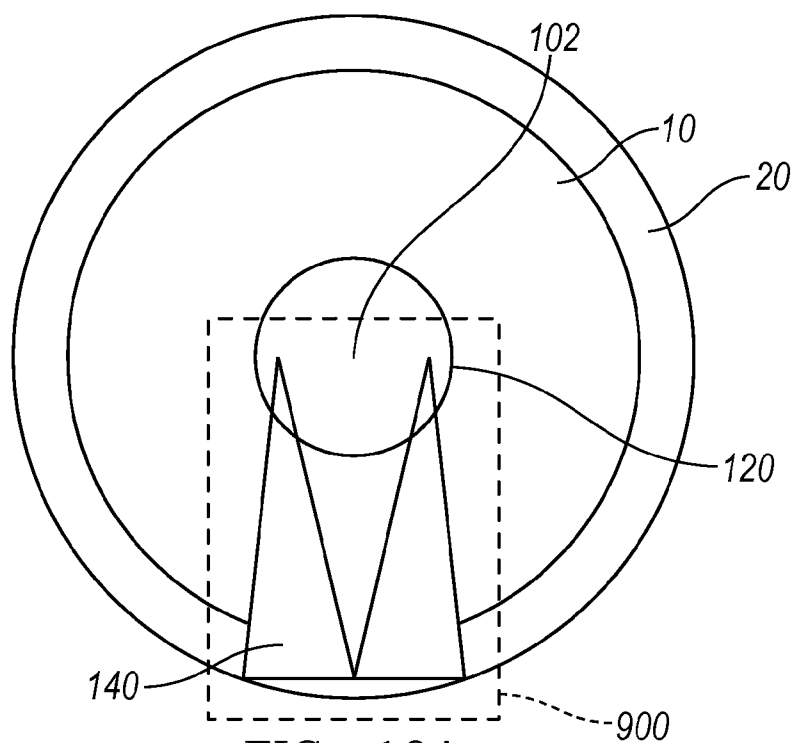


FIG. 10A

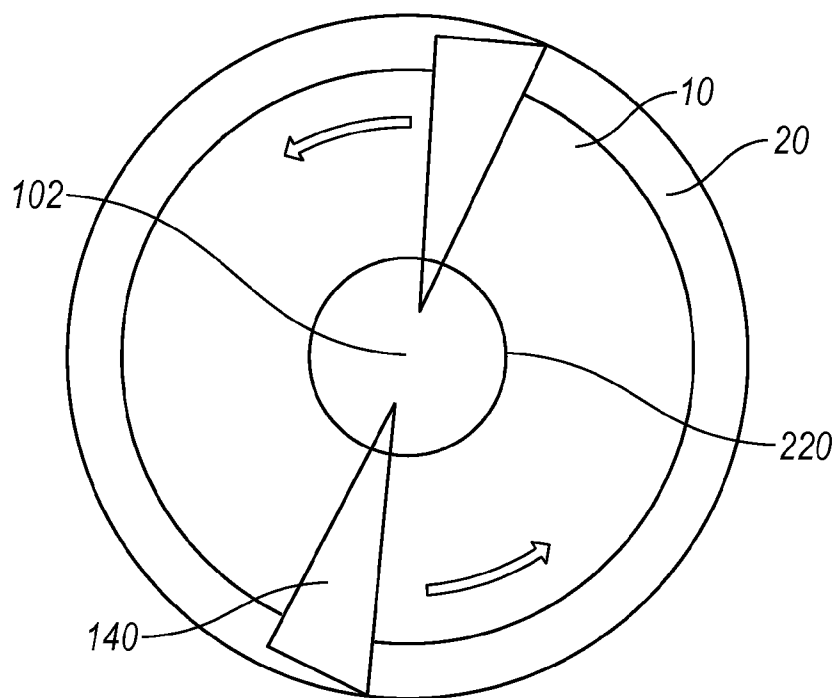


FIG. 10B

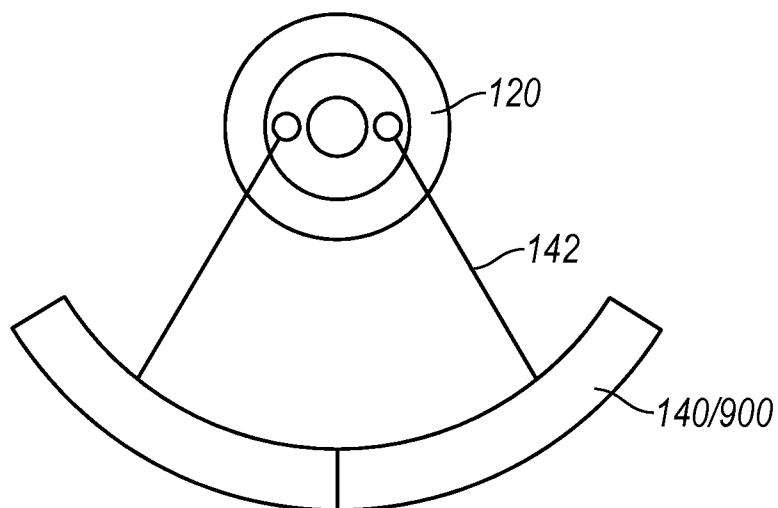


FIG. 11A

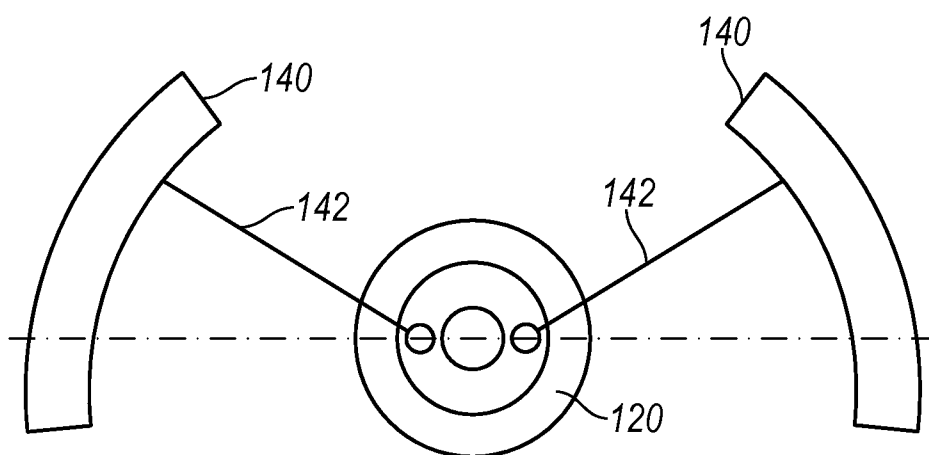


FIG. 11B

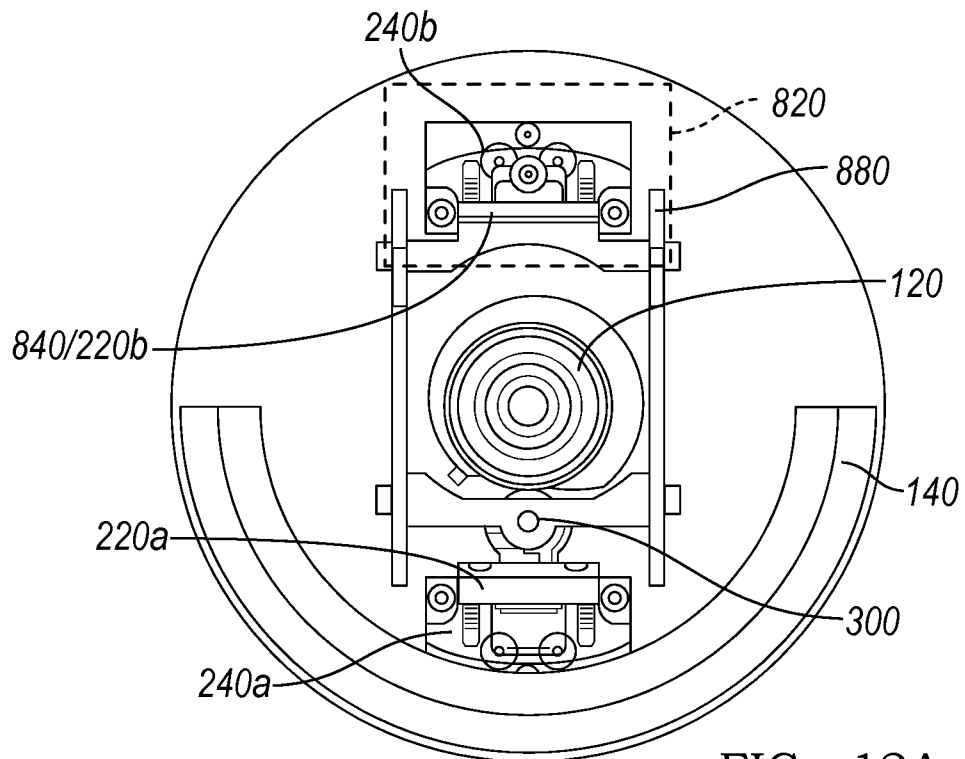


FIG. 12A

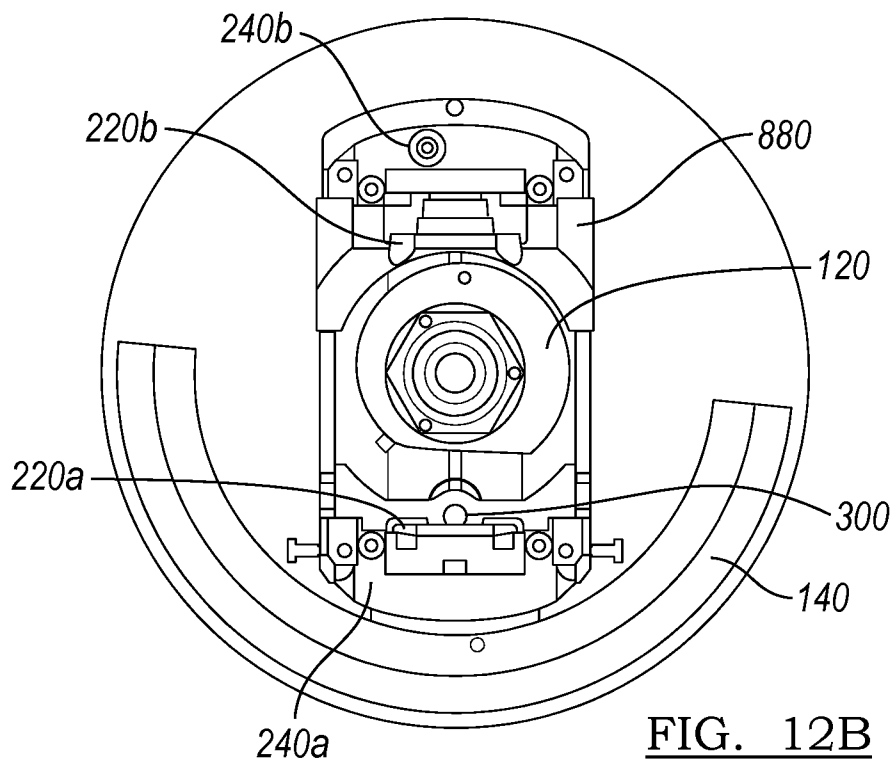


FIG. 12B

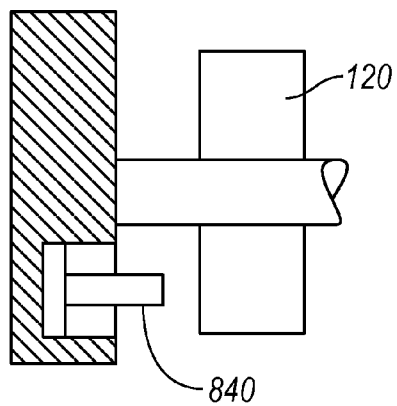


FIG. 13A

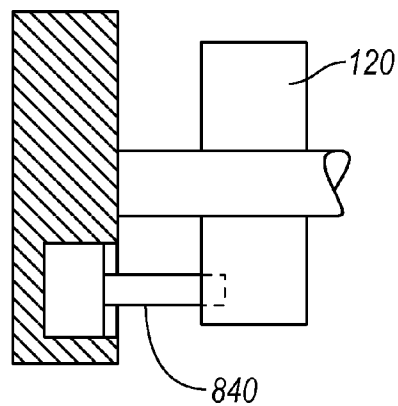


FIG. 13B

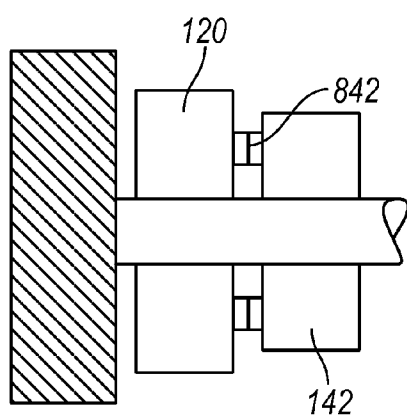


FIG. 14A

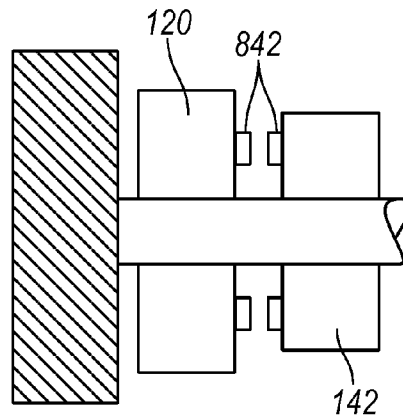


FIG. 14B

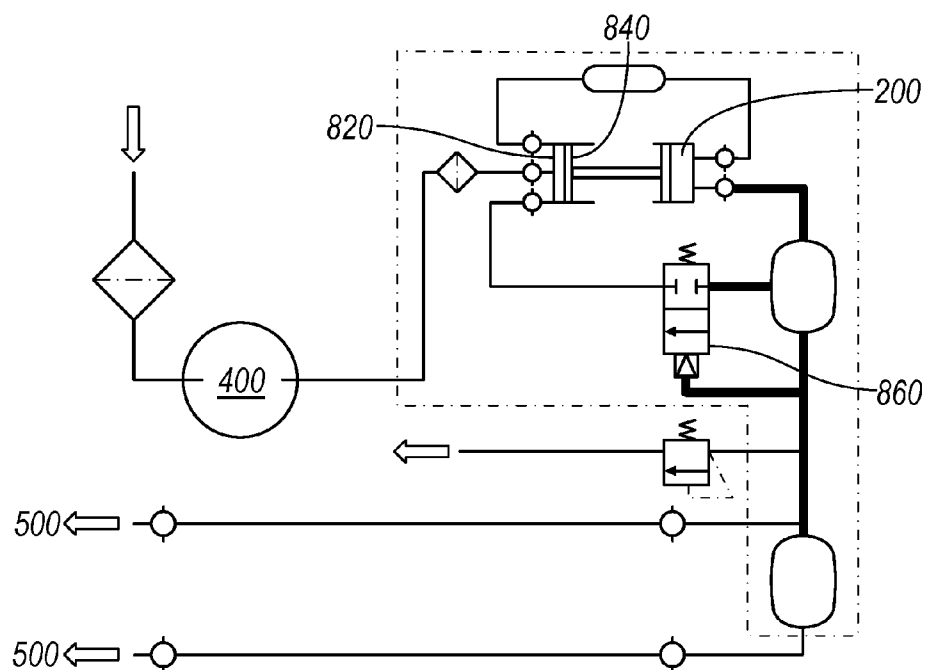


FIG. 15A

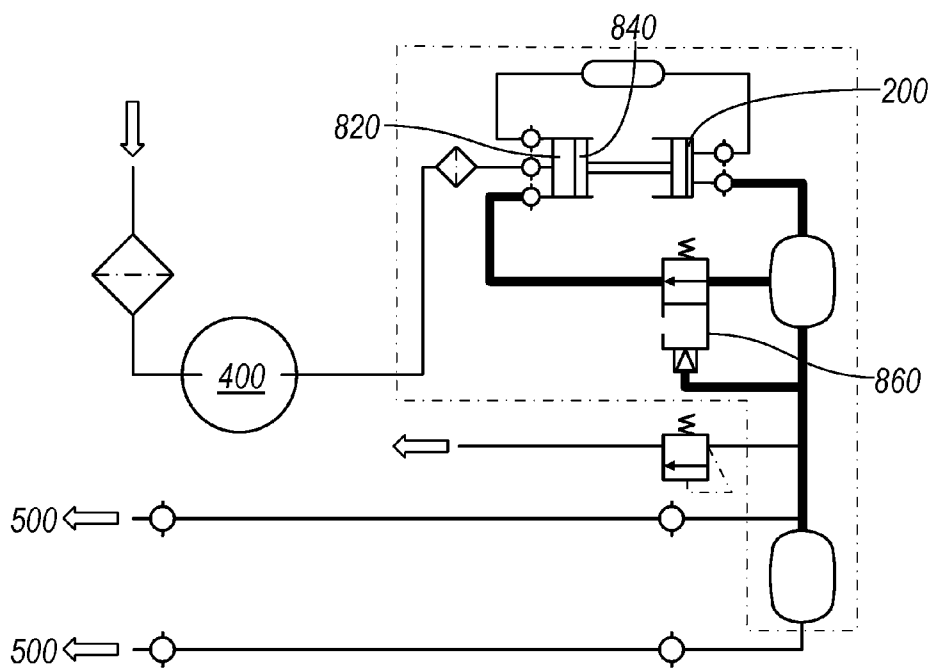


FIG. 15B

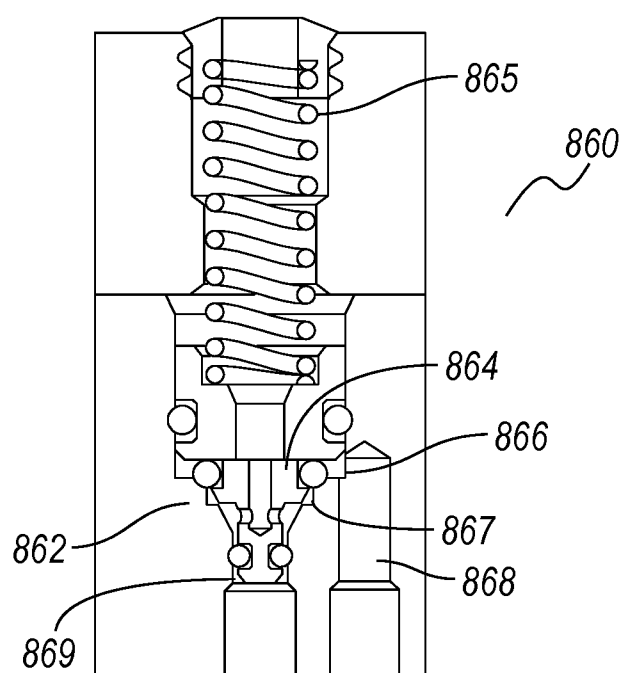


FIG. 16

TIRE INFLATION SYSTEM

CROSS-REFERENCE TO RELATED APPLICATIONS

[0001] This application is a continuation of co-pending U.S. patent application Ser. No. 14/019,941, filed 6 Sep. 2013, which is a continuation U.S. patent application Ser. No. 13/797,826, filed 12 Mar. 2013, which claims the benefit of U.S. Provisional Application No. 61/613,406 filed 20 Mar. 2012, U.S. Provisional Application No. 61/637,206 filed 23 Apr. 2012, and U.S. Provisional Application No. 61/672,223 filed 16 Jul. 2012, which are incorporated in its entirety by this reference.

[0002] This application is also related to U.S. application Ser. No. 13/469,007 filed 10 May 2012, which is incorporated in its entirety by this reference.

TECHNICAL FIELD

[0003] This invention relates generally to the pumping field, and more specifically to a new and useful passive pump system in the pumping field.

BACKGROUND

[0004] Tires that are not optimally pressurized contribute to low fuel efficiency. These effects are particularly felt in the trucking industry, where long distances and large loads amplify the effects of an underinflated tire. However, it is often inconvenient and inefficient for truck drivers to constantly stop, check, and inflate the vehicle tires to the optimal pressure, leading to the persistence of less-than-optimal fuel efficiency in most trucks. This problem has led to several auto-inflating tire systems. Conventional auto-inflating tire systems are either central or distributed, but each suffers from its own set of drawbacks. Central inflation systems are complex and expensive, and require significant work for aftermarket installation (drilling through axles, tapping existing air lines, etc). Distributed systems are mounted at each wheel and can be less expensive, but the potential for reduced cost is typically at the expense of the continuous replacement of the device (which fails due to the harsh wheel environment).

[0005] Furthermore, passive pressurization systems can be desirable for tire inflation applications, as electrical energy storage mechanisms and programming can be eliminated from the system. However, conventional passive pressurization systems suffer from several problems. First, conventional passive pressurization systems using reciprocating pumps oftentimes suffer from fatigue due to the high pressures and high number of pumping cycles that are demanded. Second, passive pressurization systems can suffer from over-pressurization of the reservoir, wherein the pressurization system continues to pump fluid into the reservoir even after the desired reservoir pressure is reached. Conventional systems typically resolve this problem with a relief valve, wherein the relief valve vents the reservoir contents into the ambient environment when the reservoir pressure exceeds the desired pressure. This results in a loss of the already-pressurized fluid, resulting in additional pump cycles to bring fluid at ambient pressure up to the desired pressure, thereby resulting in a shorter pump lifetime. Third, conventional eccentric-mass driven pump systems, such as pendulum systems, experience instabilities when the rotating surface to which the eccentric mass is coupled rotates near the excitation frequency for the given eccentric mass. More specifically, the

eccentric mass rotates with the system at this excitation frequency, resulting in radial oscillations that can be detrimental to the overall system or to the rotating surface to which the pump system is coupled.

[0006] Thus, there is a need in the pumping field to create a new and useful pump.

BRIEF DESCRIPTION OF THE FIGURES

[0007] FIG. 1 is a schematic representation of the pump system coupled to a rotating surface.

[0008] FIGS. 2A and 2B are schematic representations of a variation of the pump system in the recovered and compressed positions, respectively.

[0009] FIGS. 3A and 3B are cutaway views of a variation of the primary pump in the compressed and recovered positions, respectively.

[0010] FIGS. 4A and 4B are sectional views of a variation of the pump system with the mass couple and with the mass couple cut away, respectively.

[0011] FIGS. 5A, 5B, and 5C are cutaway views of a variation of the pump system in the recovery stroke, at the beginning of the compression stroke, and at the end of the compression stroke, respectively.

[0012] FIG. 6 is a perspective view of a variation of the pump system.

[0013] FIGS. 7A and 7B are schematic representations of a variation of the pump system wherein the first reservoir pressure is equal to or below the ambient pressure and wherein the first reservoir pressure is higher than the ambient pressure, respectively.

[0014] FIGS. 8A and 8B are schematic representations of a variation of the torque stabilization mechanism in the pumping and non-pumping mode, respectively.

[0015] FIGS. 9A and 9B are schematic representations of a second variation of the torque stabilization mechanism in the pumping and non-pumping mode, respectively.

[0016] FIGS. 10A and 10B are schematic representations of a variation of the stabilizing mechanism in the pumping and non-pumping modes, respectively.

[0017] FIGS. 11A and 11B are schematic representations of a second variation of the stabilizing mechanism in the pumping and non-pumping modes, respectively.

[0018] FIGS. 12A and 12B are sectional views of a variation of the pressure regulation mechanism in the pumping and non-pumping modes, respectively.

[0019] FIGS. 13A and 13B are sectional views of a second variation of the pressure regulation mechanism in the pumping and non-pumping modes, respectively.

[0020] FIGS. 14A and 14B are sectional views of a third variation of the pressure regulation mechanism in the pumping and non-pumping modes, respectively.

[0021] FIGS. 15A and 15B are schematic flow diagrams of a variation of the pressure regulation mechanism in the pumping and non-pumping modes, respectively.

[0022] FIG. 16 is a cutaway view of the valve within the pressure regulation mechanism.

DESCRIPTION OF THE PREFERRED EMBODIMENTS

[0023] The following description of the preferred embodiments of the invention is not intended to limit the invention to these preferred embodiments, but rather to enable any person skilled in the art to make and use this invention.

1. Pump System

[0024] As shown in FIG. 1, the pump system 10 includes a drive mechanism 100 including a cam 120 coupled to an eccentric mass 140, a primary pump 200 including a reciprocating element 220 and a pump body 240, and a force translator 300 coupling the cam 120 to the reciprocating element 220. The pump system 10 functions to translate rotational motion into linear motion. More preferably, the pump system 10 functions to translate relative motion between the primary pump 200 and cam 120 into a pumping force, wherein the eccentric mass 140 retains the cam position relative to a gravity vector while the primary pump 200 rotates relative to the cam 120 (e.g., with a rotating surface 20). The pump system 10 preferably additionally functions to pressurize the pumped fluid. The force translator 300 preferably translates the relative motion between the cam 120 and the primary pump 200 into the pumping force, which is preferably applied against the reciprocating element 220. More preferably, the force translator 300 moves the reciprocating element 220 through a compression stroke. The force translator 300 can additionally facilitate a recovery stroke (return stroke). However, the pump system 10 can alternatively convert the relative motion into linear force, electrical energy (e.g., via piezoelectric sensors, motion through an induced electric field, etc.), or any other suitable form of energy or motion. The pump system 10 is preferably passively controlled, but can alternatively be actively controlled, wherein the system further includes a power source, a plurality of sensors, and a controller that controls valve operation based on sensor measurements.

[0025] The pump system 10 is preferably couplable to a surface that rotates relative to a gravity vector (rotating surface 20). The rotating surface 20 is preferably a wheel of a vehicle, more preferably a truck, but can alternatively be any suitable rotating system, such as a windmill, waterwheel, or any other suitable rotating surface 20.

[0026] The pump system 10 preferably receives fluid from a first reservoir 400 and pumps the fluid into a second reservoir 500. The fluid received from the first reservoir 400 preferably has a first pressure, and the fluid pumped into the second reservoir 500 preferably has a second pressure higher than the first pressure but can alternatively have a pressure substantially similar to the first pressure. The fluid is preferably a gas, more preferably ambient air, but can alternatively be any other suitable gas, a liquid, or any other suitable fluid. The first reservoir 400 is preferably the ambient environment, but can alternatively be a fluid source (e.g., a fluid canister), an intermediary reservoir, or any other suitable reservoir. When the first reservoir 400 is an intermediary reservoir, the first reservoir 400 preferably receives fluid from a fluid source, such as the ambient environment or a fluid canister. The second reservoir 500 is preferably a tire interior, but can alternatively be any suitable reservoir. The pump system 10 can additionally treat the pumped fluid, preferably prior to primary pump ingress but alternatively after primary pump egress. The fluid is preferably treated (e.g., filtered) to remove debris, water, or any other suitable undesired component of the fluid. The fluid is preferably treated within the intermediary reservoir, when used. Alternatively, the fluid can be treated during primary pump ingress (e.g., wherein the inlet includes a filter) or at any suitable point within the fluid flow path.

[0027] The drive mechanism 100 of the pump system 10 functions to generate the pumping force and to control the

magnitude of the pumping force. The pumping force (occluding force) is preferably a variable force applied in a radial direction from a rotational axis of the drive mechanism 100, but can alternatively be a constant force, a force applied at any suitable angle to the rotational axis, or any other suitable force. The drive mechanism 100 preferably includes the cam 120 and the eccentric mass 140. The drive mechanism 100 includes a rotational axis about which the drive mechanism 100 rotates relative to the primary pump 200 (conversely, about which the primary pump 200 rotates relative to the drive mechanism 100). The rotational axis of the drive mechanism 100 is preferably the rotational axis of the cam 120, but can alternatively be the rotational axis of the eccentric mass 140, the rotational axis about which the primary pump 200 rotates, or any other suitable rotational axis. The pump system 10 is preferably configured such that the rotational axis of the drive mechanism 100 is substantially aligned with the rotational axis of the rotating surface 20 when the pump system 10 is coupled to the rotating surface 20, but the pump system 10 can alternatively be configured such that the rotational axis of the drive mechanism 100 is offset from the rotational axis of the rotating surface 20. The drive mechanism 100 additionally includes a center of mass, determined from the mass and positions of the cam 120 and the eccentric mass 140. The eccentric mass 140 is preferably coupled to the cam 120 such that the center of mass of the drive mechanism 100 is offset from the rotational axis of the drive mechanism 100.

[0028] The cam 120 of the drive mechanism 100 functions to control the magnitude of the pumping force. The cam 120 preferably functions to provide a substantially constant torque against the reciprocating element 220 throughout the compression stroke, but can alternatively provide a variable torque against the reciprocating element 220 throughout the compression or recovery strokes. The cam 120 preferably includes a bearing surface 122, wherein the profile of the bearing surface 122 preferably controls the magnitude of the pumping force throughout the compression stroke. The bearing surface 122 is preferably continuous, but can alternatively be discontinuous. The bearing surface 122 is preferably defined on the exterior of the cam 120 (exterior bearing surface or outer bearing surface) but can alternatively be defined within the interior of the cam 120 (interior bearing surface or inner bearing surface), as shown in FIG. 6, wherein the bearing surface 122 defines a lumen within the cam 120. The bearing surface 122 is preferably arcuate, and preferably has a non-uniform curvature (e.g., an oblong profile or a reniform profile, as shown in FIGS. 2 and 5, respectively). Alternatively, the bearing surface 122 can have a uniform curvature (e.g., a circular profile), an angular profile, or any other suitable profile. The bearing surface 122 preferably includes a compression portion and a recovery portion, corresponding to the compression stroke and the recovery stroke of the primary pump 200, respectively. The compression portion is preferably continuous with the recovery section, but can alternatively be discontinuous. The bearing surface 122 preferably has a first section 124 having a high curvature (preferably positive curvature or convex but alternatively negative curvature or concave) adjacent a second section 126 having low curvature (e.g., substantially flat or having negative curvature compared to the first section 124). The bearing surface 122 preferably additionally includes a third section 128 connecting the first and second sections, wherein the third section 128 preferably provides a substantially smooth transition between the first and second sections by having a low curvature adja-

cent the first section 124 and a high curvature adjacent the second section 126. The compression portion preferably begins at the end of the second section 126 distal the first section 124, extends along the third section 128, and ends at the apex of the first section 124, as shown in FIG. 5B. The compression portion is preferably convex (e.g., when the bearing surface 122 is an external bearing surface), but can alternatively be concave. The apex of the first section 124 preferably corresponds to the top of the compression stroke (compressed position 222), as shown in FIG. 5C. The recovery portion preferably begins at the apex of the first section 124, extends along the second section 126, and ends at the end of the second section 126 distal the first section 124, as shown in FIG. 5A. The recovery portion is preferably substantially flat or concave (e.g., when the bearing surface 122 is an external bearing surface 122), but can alternatively be convex. The end of the second section 126 preferably corresponds to the bottom of the recovery stroke (recovered position 224). The slope of the compression portion is preferably less than 30 degrees, but can alternatively have any suitable angle. When a roller is used as the force translator 300, the curvature of the bearing surface 122 is preferably at least three times larger than the roller curvature or roller diameter, but can alternatively be larger or smaller. However, the bearing surface 122 can have any suitable profile. The cam 120 is preferably substantially planar with the bearing surface 122 defined along the side of the cam 120, in a plane normal to the rotational axis of the cam 120 (e.g., normal the broad face of the cam 120). The bearing surface 122 is preferably defined along the entirety of the cam side, but can alternatively be defined along a portion of the cam side. The generated pump force is preferably directed radially outward of the rotational axis, more preferably along a plane normal to the rotational axis. Alternatively, the cam 120 can have a rounded or otherwise profiled edge segment (transition between the cam broad face and the cam side), wherein the bearing surface 122 can include the profiled edge. Alternatively, the arcuate surface is defined by a face of the cam parallel to the rotational axis of the cam 120, wherein the generated pump force can be directed at any suitable angle relative to the rotational axis, varying from parallel to the rotational axis to normal to the rotational axis. The compression portion preferably encompasses the majority of the cam profile, but can alternatively encompass half the cam profile or a small portion of the cam profile. In one variation, the compression portion covers 315 degrees of the cam profile, while the recovery portion covers 45 degrees of the cam profile. However, the compression and recovery portions can cover any other suitable proportion of the cam profile.

[0029] The eccentric mass 140 (hanging mass) of the drive mechanism 100 functions to offset the center of mass of the drive mechanism 100 from the rotational axis of the drive mechanism 100. This offset can function to substantially retain the angular position of the drive mechanism 100 relative to a gravity vector, thereby engendering relative motion between the drive mechanism 100 and the pump system components that are statically coupled to the rotating surface 20 (that rotates relative to the gravity vector). The eccentric mass 140 is preferably a substantially homogenous piece, but can alternatively be heterogeneous. The eccentric mass 140 is preferably a substantially singular piece, but can alternatively be made of multiple pieces or segments. In the latter variation, the multiple pieces are preferably substantially similar in shape, angular and radial position, and mass, but can alternatively

be substantially different in profile, mass, angular position, or radial position. The eccentric mass 140 is preferably a distributed mass (e.g., extends along a substantial portion of an arc centered about the rotational axis, as shown in FIG. 4B), but can alternatively be a point mass. In certain applications, particularly those applications with high rotational speeds, the distributed mass can be preferable since the distributed mass results in low oscillation frequencies, thereby resulting in a lower likelihood of eccentric mass excitation into spinning with the system in response to a linear oscillation introduced into the system (e.g., bumps, system pulsation, etc.). The eccentric mass 140 is preferably curved, but can alternatively be substantially flat, angled, or have other suitable shape. The radius of the eccentric mass curvature is preferably maximized, such that the eccentric mass traces an arcuate section of the pump system perimeter. However, the eccentric mass 140 can have any other suitable curvature. The eccentric mass 140 preferably extends at least 90 degrees about the rotational axis of the drive mechanism 100, more preferably 180 degrees about the rotational axis, but can extend more or less than 180 degrees about the rotational axis. The eccentric mass 140 preferably has substantially more mass than the cam 120, but can alternatively have a substantially similar mass or a smaller mass. The eccentric mass 140 preferably imparts 2 in-lb (0.225 Nm) of torque on the cam 120, but can alternatively impart more or less torque.

[0030] The eccentric mass 140 is preferably a separate piece from the cam 120, and is preferably coupled to the cam 120 by a mass couple 142. Alternatively, the eccentric mass 140 can be incorporated into the cam 120, wherein the eccentric mass 140 is incorporated along the perimeter of the cam 120, incorporated into a half of the cam 120, or incorporated along any other suitable portion of the cam 120. The eccentric mass 140 can be statically coupled to the cam 120 or rotatably coupled to the cam 120. In the variation wherein the eccentric mass 140 is statically coupled to the cam 120, the eccentric mass 140 can be coupled to the cam 120 at the rotational axis of the cam 120, at the rotational axis of the drive mechanism 100, offset from the rotational axis of the cam 120, or at any other suitable portion of the cam 120. The eccentric mass 140 can be permanently connected to the cam 120. Alternatively, the eccentric mass 140 can be transiently connected (removably coupled) to the cam 120, wherein the eccentric mass 140 can be operable between a pumping mode wherein the eccentric mass 140 is coupled to the cam 120 and a non-pumping mode wherein the eccentric mass 140 is disconnected from the cam 120. The mass couple 142 preferably has a high moment of inertia, but can alternatively have a low moment of inertia. The mass couple 142 is preferably a disk (as shown in FIG. 4A), but can alternatively be a lever arm, plate, or any other suitable connection. The mass couple 142 preferably couples to the broad face of the cam 120, but can alternatively couple to the edge of the cam 120, along the exterior bearing surface of the cam 120, to the interior bearing surface of the cam 120, to an axle extending from of the cam 120 (wherein the cam 120 can be statically fixed to or rotatably mounted to the axle), or to any other suitable portion of the cam 120. The mass couple 142 can couple to the cam 120 by friction, by a transient coupling mechanism (e.g., complimentary electric or permanent magnets located on the cam 120 and mass couple 142, a piston, a pin and groove mechanism, etc.), by bearings, or by any other suitable coupling means. When the mass couple 142 couples to the cam 120 by a transient coupling mechanism, the mass couple 142 is preferably operable

between a coupled mode, wherein the mass couple **142** connects the eccentric mass **140** to the cam **120**, and a decoupled mode, wherein the mass couple **142** disconnects the eccentric mass **140** from the cam **120**. The mass couple **142** can additionally function as a shutoff mechanism, wherein the mass couple **142** is switched from the coupled mode to the decoupled mode in response to the detection of a shutoff event (e.g., the reservoir pressure reaching a threshold pressure). In one variation, the mass couple **142** is a disk located within the lumen defined by an interior bearing surface of the cam **120**, wherein the disk can rotate relative to the interior bearing surface in the decoupled mode and is coupled to the interior bearing surface by a friction element in the coupled mode. In another variation, the mass couple **142** is rotatably mounted on an axle extending from the cam **120** by bearings, wherein the mass couple **142** can be statically coupled to the cam **120** by one or more sets of magnets or pistons extending from the adjacent broad faces of the cam **120** and mass couple **142**.

[0031] The primary pump **200** of the pump system **10** functions to pressurize a fluid with the pumping force generated between the cam **120** and the reciprocating element **220**. The primary pump **200** is preferably a positive displacement pump including an actuating element and a pump cavity, and is more preferably a reciprocating pump, wherein the primary pump **200** includes a reciprocating element **220** and a pump body **240**. The primary pump **200** preferably includes a lumen defined between the reciprocating element **220** and the pump body **240**, wherein the lumen is preferably substantially fluid impermeable. The primary pump **200** is preferably rotatably coupled to the rotational axis of the drive mechanism **100**. The primary pump **200** is preferably positioned a radial distance away from the rotational axis of the drive mechanism **100**, wherein the radial position of the primary pump **200** is preferably fixed, but can alternatively be adjustable. More preferably, the primary pump **200** is preferably statically mounted to a housing (wherein the housing is statically coupled to the rotating surface **20**) but can alternatively be transiently mounted to the housing (adjustably mounted). In operation, the primary pump **200** preferably rotates about the rotational axis. Throughout the rotation, the variable bearing surface profile preferably applies a variable force to the reciprocating element **220** as the distance between the bearing surface **122** and the pump body bottom varies. The primary pump **200** preferably includes an actuation axis, wherein the reciprocating element **220** preferably travels along the actuation axis through the compression stroke. The reciprocating element **220** can additionally travel along the same actuation axis during the return stroke. The primary pump **200** is preferably oriented such that the actuation axis is substantially normal to the rotational axis, but can alternatively be positioned such that the actuation axis is at any suitable angle to the rotational axis. The primary pump **200** and cam **120** preferably share a common plane, wherein the pumping force is preferably transmitted along the common plane, but can alternatively be substantially offset. The system preferably includes one primary pump **200**, and more preferably includes two pump cavities. However, the pump system **10** can include any suitable number of pump cavities. When the pump system **10** includes multiple pump cavities, the pump cavities are preferably substantially evenly distributed about the rotational axis (e.g., have substantially similar distances between the respective angular positions), but can alternatively be unevenly distributed. The pump cavities preferably have substantially similar radial positions relative to the rota-

tional axis, but can alternatively have different radial positions. The pump cavities can be substantially different (e.g., with different lumen volumes, different actuation areas, etc.) or can be substantially similar.

[0032] The reciprocating element **220** of the primary pump **200** functions to receive the pumping force from the cam **120** and translate within the lumen, actuating relative to the pump body **240**. This actuation preferably creates a variable pressure within the lumen. The reciprocating element **220** is preferably operable between a compressed position **222** and a recovered position **224**, as shown in FIGS. 3A and 3B, respectively. In the compressed position **222**, a portion of the reciprocating element **220** (e.g., the center) is preferably proximal the pump body bottom. In the recovered position **224**, the portion of the reciprocating element **220** is preferably distal the pump body bottom, and is preferably proximal the pump body opening. The reciprocating element **220** preferably travels along a compression stroke to transition from the recovered position **224** to the compressed position **222**, and travels along a recovery stroke to transition from the compressed position **222** to the recovered position **224**. The reciprocating element **220** can additionally be positioned at a pressurized position, wherein the reciprocating element **220** is located at a second position distal the pump body bottom, wherein the second position is further from the pump body bottom than the recovered position **224**. The reciprocating element **220** is preferably at the pressurized position when the force provided by the lumen pressure exceeds the force provided by the cam **120** on the reciprocating element **220**.

[0033] The reciprocating element **220** preferably translates along an actuation axis within the primary pump **200** throughout the compression stroke, and can additionally translate along the actuation axis throughout the recovery stroke. The reciprocating element **220** preferably includes an actuating area that provides the pressurization force. The actuating area is preferably the surface area of a broad face of the reciprocating element **220**, more preferably the surface area of the broad face proximal the lumen but alternatively any other suitable broad face. Alternatively, the actuating area can be the surface area of a section of the reciprocating element **220** that translates between the compressed position **222** and the recovered position **224** (e.g., the center portion).

[0034] The reciprocating element **220** preferably forms a fluid impermeable seal with the pump body **240**, more preferably with the walls defining the pump body opening, such that the reciprocating element **220** substantially seals the pump body opening. The reciprocating element **220** can be sealed to the pump body **240** by a retention mechanism. The retention mechanism is preferably a clamp that applies a compressive force against the reciprocating element edge and the pump body wall, but can alternatively be screws or bolts through the reciprocating element edge, adhesive between the reciprocating element **220** and the pump body wall or over the reciprocating element **220** and the pump body wall, or any other suitable retention mechanism. The reciprocating element **220** can also be sealed against the pump body wall by melting the interface between the reciprocating element **220** and pump body wall, or by any other suitable means of sealing the reciprocating element **220** against the pump body wall.

[0035] The reciprocating element **220** is preferably a flexible diaphragm, but can alternatively be a substantially rigid piston, a piston coupled to the diaphragm, or any other suitable element that actuates in response to the pumping force. The diaphragm is preferably a rolling diaphragm (e.g., with a

rolled perimeter, wherein the diaphragm is preferably coupled to the pump body **240** with the extra material distal the lumen) but can also be a flat diaphragm, a domed diaphragm (preferably coupled to the pump body **240** with the apex distal the lumen, but alternatively coupled to the pump body **240** with the apex proximal the lumen), or any other suitable diaphragm.

[0036] The pump body **240** of the primary pump **200** functions to cooperatively compress a fluid with the reciprocating element **220**. The pump body **240** is preferably substantially rigid, but can alternatively be flexible. The pump body **240** is preferably an open pump body with a closed end, wherein the pump body **240** preferably includes a closed end (bottom), walls extending from the closed end, and an opening opposing the closed end. However, the pump body **240** can alternatively have two open ends or any other suitable configuration. The closed end is preferably substantially flat, but can alternatively be curved or have any other suitable geometry. The walls are preferably substantially flat, but can alternatively be curved or have any other suitable geometry. The walls preferably join with the closed end at an angle, more preferably at a right angle, but the transition between the walls and the closed end can alternatively be substantially smooth (e.g., have a bell-shaped or paraboloid longitudinal cross section). The closed end is preferably substantially parallel to the opening defined by the walls, but can alternatively be oriented at an angle relative to the opening. The pump body **240** can be a groove defined in an arcuate or prismatic piece (e.g., in a longitudinal or lateral direction), a cylinder, a prism, or any other suitable shape. The pump body **240** preferably has a substantially symmetrical lateral cross section (e.g., circular, ovalar, or rectangular cross section, etc.), but can alternatively have an asymmetrical cross section. The pump body **240** is preferably oriented within the pump system **10** such that the closed end is substantially normal to a radial vector extending from the rotational axis of the drive mechanism **100** (e.g., the normal vector from the closed end is substantially parallel to the radial vector), but can alternatively be oriented with the closed end at an angle to the radial vector. The pump body **240** is preferably oriented with the opening proximal and the closed end distal the rotational axis, particularly when the primary pump **200** rotates about the cam exterior, but can alternatively be oriented with the opening distal and the closed end proximal the rotational axis, particularly when the primary pump **200** rotates about the cam interior, or oriented in any other suitable position relative to the rotational axis.

[0037] The primary pump **200** can additionally include a return element **260** that functions to return the reciprocating element **220** to the recovered position **224**. The return element **260** preferably provides a recovery force that is less than the compression force provided by the third section **128** of the cam **120**, but larger than the force applied by the cam **120** in the second section **126**. The recovery force is preferably provided in a direction substantially parallel to a radial vector extending from the rotational axis of the drive mechanism **100**, but can alternatively be provided in any suitable direction. The return element **260** is preferably located on the pump body **240** side of the reciprocating element **220** (distal the cam **120** across the reciprocating element **220**), wherein the return element **260** preferably pushes the reciprocating element **220** from the compressed position **222**, through the recovery stroke, and to the recovered position **224**. Alternatively, the return element **260** can be located on the cam side

of the reciprocating element (distal the pump body **240** across the reciprocating element **220**), wherein the return element **260** pulls the reciprocating element **220** back to the recovered position **224** from the compressed position **222**. The return element **260** is preferably coupled to the perimeter of the reciprocating element **220** or to a component (e.g., a brace) coupled to the reciprocating element **220** and extending past the pump body walls, but can alternatively be coupled to the body of the reciprocating element **220** (e.g., to the section actuating between the compressed position **222** and the recovered position **224**). The return element **260** is preferably coupled to the reciprocating element **220** external the pump body **240**, but can alternatively be coupled to the reciprocating element **220** within the pump body **240**. The return element **260** is preferably a spring, but can also include the intrinsic properties of the actuation element (e.g., the elasticity of the diaphragm) or any other suitable return element **260**.

[0038] The primary pump **200** preferably additionally includes one or more inlets that facilitate fluid ingress into the lumen from the first reservoir **400** and one or more outlets that facilitate fluid egress from the lumen to the second reservoir **500**. Alternatively, the primary pump **200** can include one fluid manifold that functions as both the inlet and outlet, wherein said fluid manifold is fluidly connected to and selectively permits fluid flow from the first and second reservoirs. The inlet and outlet are preferably defined through the walls of the pump body **240**, but can alternatively be defined through the reciprocating element **220**, through the junction between the pump body **240** and the reciprocating element **220**, or defined in any other suitable portion of the primary pump **200**. The inlet and outlet are preferably located on opposing walls, but can alternatively be adjacent on the same wall, be located on the closed end, or be located in any other suitable position.

[0039] The inlet and outlet of the pump **200** preferably include inlet and outlet valves that control fluid flow through the respective fluid channels. The valves are preferably passive valves, but can alternatively be active valves controlled by a controller based on system measurements made by sensors. The valves are preferably one-way valves, but can alternatively be two-way valves, or any other suitable valve. The valves are preferably each operable in an open mode and a closed mode, and preferably have a low threshold pressure at which the valve switches from the closed mode to the open mode. The inlet valve located within the inlet is preferably configured to control fluid ingress into the primary pump **200**, and prevents fluid egress out of the primary pump **200**. The inlet valve is preferably in the open mode to permit fluid ingress when the lumen pressure is lower than or equal to the pressure within the first reservoir **400**. Alternatively, the inlet valve can be in the open mode when the lumen pressure is negative. The inlet valve is preferably in the closed mode when the lumen pressure is higher than or equal to the pressure within the first reservoir **400**. The outlet valve located within the outlet is preferably configured to control fluid egress from the primary pump **200**, and prevents fluid ingress into the primary pump **200**. The outlet valve is preferably in the open mode to permit fluid egress when the lumen pressure exceeds the pressure within the second reservoir **500** and the outlet valve threshold pressure. The outlet valve is preferably in the closed mode when the lumen pressure is lower than or equal to the pressure within the second reservoir **500**.

[0040] The force translator **300** of the pump system **10** functions to actuate the reciprocating element **220** through

the compression stroke as the primary pump **200** rotates about the rotational axis, and can additionally function to translate the reciprocating element **220** through the recovery stroke. The force translator **300** preferably includes an axis having an arcuate position that is fixed relative to an arcuate position of the primary pump **200** (the angular position of the force translator **300** axis about the rotational axis is preferably fixed relative to the angular position of the primary pump **200**). More preferably, the force translator **300** or a portion thereof has an angular position fixed to and substantially similar to the angular position of the primary pump **200** about the rotational axis, such that the force translator **300** travels with the primary pump **200** about the rotational axis.

[0041] In a first variation of the force translator **300**, the force translator **300** travels along the arcuate bearing surface **122** of the cam **120**. The force translator **300** preferably maintains a substantially constant distance between the arcuate bearing surface **122** and the reciprocating element **220**, such that the force translator **300** applies a variable force against the reciprocating element **220** as the force translator **300** travels along the variable curvature of the arcuate bearing surface **122** of the cam **120**. The force translator **300** is preferably substantially rigid, and preferably has substantially fixed dimensions (e.g., diameter) that remain substantially constant throughout force translator motion relative to the cam **120**. The force translator **300** is preferably a roller or bearing, wherein the axis that is fixed to the primary pump angular position is preferably the rotational axis of the roller. The force translator **300** is preferably in non-slip contact with the arcuate bearing surface **122**, but can alternatively slide along the arcuate bearing surface **122**. The force translator **300** is preferably rotatably coupled to the reciprocating element **220**, but can alternatively be otherwise coupled to the reciprocating element **220**. When the reciprocating element **220** is a piston, the reciprocating element **220** preferably rotatably connects to the roller at the rotational axis of the roller, but can connect to the roller with a semi-circular cup that cups the roller, or through any other suitable coupling mechanism. When the reciprocating element **220** is a diaphragm, the reciprocating element **220** can directly contact the diaphragm, couple to the diaphragm through a piston, or couple to the diaphragm in any other suitable manner.

[0042] In another variation of the force translator **300**, the force translator **300** is rotatably coupled to the cam **120** at a fixed position on the cam **120** and rotatably coupled to a fixed position on the reciprocating element **220**. The force translator **300** is preferably rotatably coupled to the reciprocating element **220** (e.g., at a piston), but can alternatively be slidably coupled to the reciprocating element **220** or otherwise coupled to the reciprocating element **220**. In this variation, the force translator **300** preferably translates the varying distance between the respective fixed ends into the variable occluding force. The force translator **300** is preferably a linkage with two or more links, but can alternatively be any suitable force translator **300**.

[0043] However, the force translator **300** can alternatively be any suitable mechanism that translates cam rotation relative to the primary pump **200** into a variable occluding force against the reciprocating element **220**.

[0044] The pump system **10** preferably additionally includes a housing that functions to couple the pump system components to the rotating surface **20**. The housing is preferably configured to removably statically couple to the rotating surface **20**, but can otherwise couple to the rotating sur-

face **20**. More preferably, the housing is configured to mount (e.g., bolt, screw, etc.) to the hub of a tire, but can alternatively mount to the rim, axle, or any other suitable component of a tire. The housing is preferably rotatably coupled to the drive mechanism **100** and is preferably statically coupled to the pump body **240** of the primary pump **200**, such that the primary pump **200** rotates with the housing. The housing can additionally function to mechanically protect the pump system components, wherein the housing preferably substantially encloses the pump system components. The housing is preferably substantially rigid, but can alternatively be substantially flexible. The housing is preferably substantially fluid impermeable, but can alternatively be permeable to fluid. In one variation of the pump system **10**, the housing functions as the first reservoir **400**, wherein the primary pump **200** inlet is fluidly connected to and draws fluid from the housing interior. In this variation, the housing can include an inlet manifold fluidly connecting the housing interior with the ambient environment. As shown in FIGS. 7A and 7B, the inlet manifold preferably includes a water-selective membrane that preferentially permits gas flow therethrough (e.g., the gas flow rate through the water-selective membrane is higher than the water flow rate through the water-selective membrane). The water-selective membrane is preferably a GORE™ membrane, but can alternatively be any other suitable membrane. The inlet manifold can alternatively include an inlet valve that controls fluid flow into the housing interior, but can alternatively not include any valves. The inlet valve is preferably a passive one-way valve operable between an open mode in response to the housing interior pressure falling below or being equal to the ambient pressure and a closed mode in response to the housing interior pressure exceeding the ambient pressure. However, the inlet valve can be an active valve, a two-way valve, or any other suitable valve.

2. Relief Valve

[0045] The pump system **10** can additionally include a relief valve **700** which functions to leak air from the interior of the second reservoir **500** (e.g. tire interior) of the into the pump system **10**, more preferably into the housing of the pump system **10** (e.g. the first reservoir **400**), but can alternatively leak air from the second reservoir **500** to the ambient environment. Leaking air through the relief valve **700** can confer several benefits. First, leaking air through the relief valve **700** can prevent overpressurization of the second reservoir **500**. Second, leaking air through the relief valve **700** can allow the pump system **10** directly measure the internal pressure of the second reservoir **500**. Third, leaking air through the relief valve **700** into the housing (first reservoir **400**) effectively recycles the already-pumped air, reducing the amount of air treatment (e.g. desiccation) required. The relief valve **700** preferably connects to the second reservoir interior through the Schraeder valve of the second reservoir **500**, but can otherwise fluidly connect to the second reservoir **500**. The relief valve **700** preferably operates between an open mode wherein air flow through the relief valve **700** is permitted, and a closed mode wherein air flow through the relief valve is prevented. The relief valve preferably includes an open threshold pressure, and is preferably a fail closed relief valve. The shutoff threshold is preferably set to leak second reservoir pressure at a rate substantially close to the flow rate of the pump (e.g. 10 cubic inches/minute), but can alternatively leak at a rate substantially close to the normal second reservoir leakage rate (e.g., 1-3 psi per month), but can

alternatively leak second reservoir pressure at a higher or lower rate. The relief valve **700** is preferably a normally-closed relief valve, but can alternatively be a normally-open relief valve that is held closed, or any other suitable valve. The relief valve **700** is preferably passive, but can alternatively be active. The relief valve **700** is preferably a check relief valve, but can alternatively be any other suitable relief valve **700**. Examples of relief valves that can be used include a duckbill relief valve, a pilot-operated relief valve, a ball relief valve, a poppet relief valve, and a diaphragm relief valve. Alternatively, any other suitable relief valve can be used.

[0046] A measurement element functions to monitor an operational parameter and display a measurement indicative of internal second reservoir pressure. The measurement element is preferably located within the body of the pump system **10**, but can be partially or wholly external the pump system **10**. The measurement element is preferably fluidly coupled to the relief valve **700**, and preferably measures a parameter of the fluid that flows through the relief valve **700**. The measurement element is preferably passive, but in alternative embodiments the measurement element can be active.

[0047] The measurement element preferably includes a sensor and a display. The sensor preferably measures the operational parameter, and can be a pressure sensor, a flow rate sensor, a temperature sensor, or any other suitable sensor. The sensor can be mechanical or digital (e.g., generate a voltage/current, be powered, or leverage a voltage/current for measurements). The display is preferably passive, and can be a dial indicator, a ruler, or any other suitable gauge. However, the display can be active (e.g., powered, such as a digital display), wherein the displayed value can be calculated by a controller.

[0048] In a first variation, the measurement element includes a measurement reservoir and a pressure gauge. The reservoir is fluidly coupled to the relief valve **700**, such that air leaks from the second reservoir interior into the measurement reservoir when the valve opens. The measurement reservoir is preferably substantially small, such that the measurement reservoir pressure equilibrates with the second reservoir pressure even with the low air leakage rate permitted by the relief valve. However, the measurement reservoir can alternatively be any suitable size. The measurement reservoir is preferably a plenum, but can alternatively be a tube, channel, or any other suitable reservoir. The pressure gauge is preferably coupled to the reservoir and measures the pressure of the reservoir interior. The pressure measured is preferably the gauge pressure, but may alternatively be the differential pressure (e.g., between the reservoir interior and the second reservoir inflation system exterior/ambient) or the absolute pressure. The display portion of the pressure gauge is preferably located on the external surface of the pump system **10**, more preferably parallel to the face of the wheel to which the pump system **10** is mounted.

[0049] In a second variation, the measurement element includes a mass air flow meter coupled to a display. The flow meter preferably measures and fluidly couples to the inflator side of the relief valve (e.g., downstream from the relief valve), but can alternatively measure the flow into the relief valve (e.g., second reservoir **500** side flow) or flow through the relief valve body, wherein a portion of the flow meter is located within the relief valve. In this variation, the downstream side of the relief valve is preferably held at an approximately known pressure that is substantially higher than ambient, but slightly lower than the expected second reservoir

pressure. For example, the relief valve can be coupled to a downstream reservoir that includes a relief valve with a threshold opening pressure slightly lower than the expected second reservoir pressure, such that the downstream pressure will always be approximately the threshold opening pressure. In another example embodiment, the relief valve can be coupled to the second reservoir inflator reservoir holding the air to be pumped into the second reservoir **500**. The flow meter preferably produces a voltage or current indicative of the air flow rate, wherein the voltage/current is fed into a controller, converted into a pressure measurement by the controller, and displayed as a pressure readout. Alternatively, the flow meter can be passive and measure the flow rate mechanically, wherein the position of a gauge or indicator is converted into a pressure readout. The air flow meter can be a vane meter sensor, a hot wire sensor, a coldwire sensor, a Karman vortex sensor, a membrane sensor, a laminar flow element, a turbine flow meter, a rotary piston, or any other suitable flow meter. The display is preferably a digital display, but can alternatively be an analog display.

[0050] However, any other suitable relief valve can be included in the pump system **10** to facilitate second reservoir pressure regulation.

3. Torque Stabilization Mechanism

[0051] The pump system **10** can additionally include a torque stabilization mechanism **600** that compensates for the back force applied by the primary pump **200** to the cam **120** at the beginning of the recovery stroke. Compensation of the back force can be desirable as the back force can provide a radial force on the cam **120**, which in turn can be transmitted to the eccentric mass **140**, thereby disrupting the system. The torque stabilization mechanism **600** is preferably located on the cam **120**, but can alternatively be located on the force translator **300** (e.g., have an adjustable dimension that changes in response to the applied force), on the primary pump **200**, or on any other suitable pump system component.

[0052] In one variation of the pump system **10**, the cam profile functions as the torque stabilization mechanism **600**, wherein the low curvature of the second segment accommodates for the back force.

[0053] In another variation of the pump system **10**, the mass couple **142** functions as the torque stabilization mechanism **600**, wherein the mass couple **142** is operable in the coupled mode during the compression stroke (through the third section **128** up to the apex of the second section **126**) and operable in the decoupled mode during the recovery stroke. In one example, as shown in FIGS. **8A** and **8B**, the torque stabilization mechanism **600** includes a profiled channel **610** defined between the interior bearing surface of the cam and the mass couple **142** (e.g., wherein the mass couple **142** is a disk) by the interior bearing surface. The profiled channel **610** preferably includes a low clearance section **612** extending to a high clearance section **614**, wherein the clearance is the distance between the mass couple surface and the interior bearing surface. The apex of the high clearance section is preferably substantially radially aligned with the first section **124**, more preferably with the apex of the first section **124**, but can alternatively be aligned with the beginning of the second section **126**, slightly before the apex of the first section **124**, or aligned with any other suitable portion of the cam **120**. The beginning of the low clearance section is preferably radially aligned within the arc defined by the third section **128**, but can alternatively be aligned with any suitable portion of the cam

120. The torque stabilization mechanism **600** preferably additionally includes a mobile element **620** located within the profiled channel **610** that couples and decouples the mass couple **142** with the interior bearing surface. The mobile element preferably couples the mass couple **142** with the interior bearing surface with friction, but can alternatively be a ratcheting mechanism or any other suitable mechanism. The mobile element preferably has a dimension substantially equivalent to the distance between mass couple surface and the interior bearing surface at the low clearance section. The mobile element is preferably wedged in the low clearance section when the eccentric mass **140** is in the coupled mode, wherein the mobile element retains the position of the mass couple **142** relative to the interior bearing surface. The mobile element is preferably located in the high clearance section when the eccentric mass **140** is in the decoupled mode, wherein the mobile element is substantially free from the mass surface and/or interior bearing surface and permits relative motion between the mass couple **142** and the interior bearing surface. The mobile element is preferably a roller, but can alternatively be a cylinder or any other suitable mobile element. In operation, as the primary pump **200** reaches the apex of the first section **124** (compressed position **222**), the reciprocating element **220** exerts a radial back force on the force translator **300**, pushing the cam **120** radially away from the primary pump **200**. Furthermore, as this point is reached, the angular speed of the cam **120** relative to the primary pump **200** slows down. This radial motion, coupled with the slower angular cam speed, frees the mobile element from the low clearance section (wherein the mobile element is still travelling at the faster angular speed), and causes the mobile element to travel with the high clearance section as the primary pump **200** travels over the second section **126** of the arcuate surface, as shown in FIG. **8B**. The angular cam speed preferably increases as the primary pump **200** travels over the second section **126**, but can alternatively stay substantially constant or slow down. At the end of the second section **126**, the angular cam speed is preferably decreased due to the increased contact force between the cam **120**, force translator **300**, and primary pump **200**. This decreased angular speed preferably causes the mobile element to wedge into the low clearance section, as shown in FIG. **8A**.

[0054] In another variation, the torque stabilization mechanism **600** includes a groove **630** defined within the cam **120** and a pin **640** extending from the mass couple **142** into the groove. The groove preferably functions to accommodate for the radial back force by turning the linear back force into a rapid rotation of the cam **120** (relative to the primary pump **200**) through the first section **124**. The pin is preferably operable between a coupled position (shown in FIG. **9A**) and a decoupled position (shown in FIG. **9B**) within the groove. The groove is preferably defined through the cam body in a normal direction to the cam broad face, but can alternatively be defined any suitable portion of the cam body. The groove is preferably aligned with the second section **126** of the arcuate bearing surface **122**, but can be defined in any other suitable portion of the cam **120**. The groove preferably traces an arc, but can alternatively be substantially linear, serpentine, or have any other suitable shape. In operation, the back pressure applied by the primary pump **200** on the cam **120** forces the pin from the coupled position to the decoupled position, effectively rotating the cam **120** relative to the eccentric mass **140**. When the primary pump **200** reaches the

end of the second section **126**, the force applied by the cam **120** on the primary pump **200** preferably transitions the pin back to the coupled position.

[0055] However, any other suitable torque stabilization mechanism **600** that accommodates for the radial force applied by the pressurized primary pump **200** on the cam **120** can be used.

4. Passive Pressure Regulation Mechanism

[0056] The pump system **10** can additionally include a passive pressure regulation mechanism **800** that preferably functions to passively cease pressurization of the reservoir when a threshold reservoir pressure is reached. This is preferably accomplished by passively ceasing primary pump pumping. The passive pressure regulation mechanism **800** preferably ceases pumping by ceasing force application to the reciprocating element **220**, wherein force application can be ceased by decoupling the force translator **300** from the cam **120**, decoupling the primary pump **200** from the cam **120**, decoupling the force translator **300** from the primary pump **200**, or eliminating the relative motion between the primary pump **200** and the cam **120**, an example of which is shown in FIGS. **15A** and **15B**. The passive pressure regulation mechanism **800** of the pump system **10** preferably includes a secondary pump **820** including pump body **240** and an actuating mechanism **840**, and additionally includes a regulation valve **860** having an opening and a closing threshold pressure. Alternatively, the passive pressure regulation mechanism **800** can include a regulation valve **860** and the primary pump **200**. The passive pressure regulation mechanism **800** is preferably fluidly connected to the second reservoir **500**, wherein the regulation valve **860** selectively controls fluid flow into the secondary pump **820** based on the pressure of the second reservoir **500**.

[0057] The secondary pump **820** is preferably a reciprocating pump substantially similar to that described above, wherein the actuating mechanism **840** is the reciprocating element. The secondary pump **820** is more preferably a piston pump but can alternatively be a diaphragm pump. The secondary pump **820** can alternatively be any other suitable positive displacement pump. The pressure regulation mechanism **800** is preferably operable in a pressurized mode and a depressurized mode. The pressurized mode is preferably achieved when the reservoir pressure exceeds the threshold pressure. More preferably, the pressurized mode is achieved when the reservoir pressure exceeds the opening threshold pressure of the valve **860**. In the pressurized mode, the valve **860** is preferably in an open position and permits fluid flow from the reservoir into the pump body **240**, wherein the pressure of the ingressed fluid places the actuating mechanism **840** in the pressurized position. In the pressurized position, the actuating mechanism **840** preferably actuates or couples against the drive mechanism **100**, force translator **300**, or primary pump **200** to cease pumping force application to the primary pump **200**. In the depressurized mode, the valve **860** is preferably in a closed position and prevents fluid flow from the reservoir into the pump body **240**, wherein a return mechanism places the actuating mechanism **840** in a depressurized position, wherein the depressurized position is preferably the recovered position **224** but can alternatively be the compressed position **222** or any other suitable position therebetween. The pump system **10** preferably includes at least

one pressure regulation mechanism **800**, but can alternatively include any suitable number of pressure regulation mechanisms.

[0058] The position of the pressure regulation mechanism **800**, more preferably the position of the pump body **240**, is preferably statically coupled to the primary pump position, but can alternatively be moveably connected to the primary pump **200** position. The angular position of the pressure regulation mechanism **800** is preferably maintained relative to the primary pump position, but the radial or linear distance can alternatively be maintained. The actuation axis of the pressure regulation mechanism **800** is preferably in the same plane as the actuation axis of the primary pump **200**, but can alternatively be in different planes, perpendicular to the actuation axis of the primary pump **200**, or arranged in any other suitable manner. The pressure regulation mechanism **800** is preferably arranged relative to the primary pump **200** such that the direction of the compression stroke of the pressure regulation mechanism **800** differs from the direction of the compression stroke of the primary pump **200**. The direction of the compression stroke of the pressure regulation mechanism **800** directly opposes the direction of the compression stroke of the primary pump **200** (e.g., the closed end of the pump cavity is distal the closed end of the pump body **240**, and the actuating element is proximal the reciprocating element **220**, wherein the actuation axes are aligned or in parallel), but can alternatively be at an angle to the direction of the compression stroke of the primary pump **200**. Alternatively, the pressure regulation mechanism **800** can be arranged such that the compression stroke of the pressure regulation mechanism **800** and the compression stroke of the pressure regulation mechanism **800** have substantially the same direction (e.g., the actuation axes are aligned or in parallel).

[0059] In one variation of the pressure regulation mechanism **800**, the actuating mechanism **840** decouples the primary pump **200** or a primary pump component from drive mechanism **100** when in the pressurized position, and permits the primary pump **200** to couple with the drive mechanism **100** when in the depressurized position (as shown in FIGS. 12A and 12B). The actuating mechanism **840** preferably decouples the force translator **300** from the drive mechanism **100**, but alternatively decouples the reciprocating element **220** or the entirety of the primary pump **200** from the drive mechanism **100**. The actuating mechanism **840** preferably moves the primary pump component along the actuation axis of the primary pump **200**, away from the cam **120**, when transitioning from the depressurized position to the pressurized position. However, the actuating mechanism **840** can move the primary pump component at an angle to the actuation axis of the primary pump **200**, away from the cam **120** (e.g., in a perpendicular direction). The actuating mechanism **840** preferably translates the primary pump component within the plane encompassing the actuation axis or the pump body **240**, but can alternatively translate the primary pump component out of said plane. The force exerted on the actuating mechanism **840** by the return element **260** of the secondary pump **820** preferably couples the primary pump component with the drive mechanism **100** while returning the actuating mechanism **840** to the depressurized position, but the pump system **10** can alternatively include a second return element **260** that couples the primary pump component to the drive mechanism **100** (e.g., a spring biased such that the spring opposes the direction that the actuating mechanism **840** moves the primary pump component, etc.). The second

return element **260** preferably returns the primary pump component contact with the drive mechanism **100** when the decoupling force of the actuating mechanism falls below the return force provided by the second return element.

[0060] A portion of the actuating mechanism **840** is preferably statically coupled to a portion of the primary pump **200**, wherein actuating mechanism actuation results in a positional change of the primary pump **200** or a primary pump component. More preferably, actuating mechanism actuation preferably selectively couples and decouples the primary pump **200** from the drive mechanism **100** when the actuating mechanism **840** is in the depressurized and pressurized positions, respectively. The actuating mechanism **840** is statically coupled to the force translator **300**, but can alternatively be statically coupled to the reciprocating element **220**, statically coupled to the primary pump **200** as a whole, or statically coupled to any other suitable primary pump component. The actuating mechanism **840** is preferably statically coupled to the primary pump component by a frame **880**, but can alternatively be coupled by the housing encapsulating the pump system **10** or by any other suitable coupling mechanism. The frame **880** can be aligned within the plane encompassing the actuation axis of the primary pump **200**, within the plane encompassing the actuation axis of the pressure regulation mechanism **800**, extend out of either of said two planes, or be otherwise oriented relative to the pump system **10**. In a specific example, the force translator **300** is a roller, wherein the actuating mechanism **840** is coupled to the rotational axis of the roller by a frame **880** aligned with a plane encompassing both the actuation axis of the pressure regulation mechanism **800** and the actuation axis of the primary pump **200**, wherein the pressure regulation mechanism **800** and primary pump **200** preferably share a common plane. Alternatively, the actuating mechanism **840** transiently couples to the primary pump component when in the pressurized position, and is retracted away from the primary pump component when in the depressurized position.

[0061] In another variation of the pressure regulation mechanism **800**, the actuating mechanism **840** decouples the force translator **300** from primary pump **200** in the pressurized position, and permits force translator **300** coupling with the primary pump **200** when in the depressurized position. The actuating mechanism **840** preferably connects to and moves the force translator linear position relative to the drive mechanism **100** when in the pressurized position, but can alternatively connect to and move the primary pump linear position relative to the force translator **300** and drive mechanism **100**. The actuating mechanism **840** preferably moves the force translator **300** out of the common plane shared by the primary pump **200** and the drive mechanism **100**, but can alternatively move the force translator **300** out of line with the actuation axis (e.g., perpendicular, within the common plane). The actuating mechanism **840** can be statically coupled to the force translator **300** or primary pump **200** by a frame **880**, a weld, adhesive, or any other suitable coupling mechanism. Alternatively, the actuating mechanism **840** can be transiently coupled to the force translator **300** or primary pump **200**, wherein the actuating mechanism **840** can be a piston or rod that transiently couples to the force translator **300** or primary pump **200** through a coupling feature (e.g., a groove) or friction.

[0062] In another variation of the pressure regulation mechanism **800**, the actuating mechanism **840** ceases force generation. In one alternative, the pressure regulation mecha-

nism **800** statically couples the angular position of the drive mechanism **100** to the primary pump **200**, ceasing force generation by eliminating the relative motion between the drive mechanism **100** and the primary pump **200** (as shown in FIGS. 13A and 13B). For example, the actuating mechanism **840** can statically couple the angular position of the cam **120** with the angular position of the primary pump **200** in the pressurized position, and decouple the angular position of the cam **120** from the angular position of the primary pump **200** in the depressurized position. In a specific example, the actuating mechanism **840** is a rod that couples to the cam broad face by friction. In another specific example, the actuating mechanism **840** is a rod that extends into a groove in the cam broad face (e.g., the broad face proximal the housing or distal the housing) when in the pressurized position, and is retracted from the groove when in the depressurized position. In another specific example, the actuating mechanism **840** statically couples to the arcuate bearing surface **122** of the cam **120**. However, other mechanisms of transiently retaining the cam angular position can be used. In another example, the actuating mechanism **840** can statically couple the angular position of the eccentric mass **140** with the angular position of the primary pump **200**. In a specific example, the actuating mechanism **840** can include a rod that couples to the broad face of the eccentric mass **140** or to the mass couple **142** by friction. In another specific example, the actuating mechanism **840** is a rod that extends into a groove in the eccentric mass face when in the pressurized position and is retracted from the groove when in the depressurized position. However, other mechanisms of transiently retaining the eccentric mass angular position can be envisioned. In another example, the pump body **240** of the primary pump **200** can be statically coupled to the drive mechanism **100**, such that relative motion between the reciprocating element **220** and the pump body **240** is ceased (e.g., when a linear or rotary actuator is used). In another alternative, the pressure regulation mechanism **800** decouples the force generator from the drive interface of the drive mechanism **100**. For example, when the cam **120** and eccentric mass **140** are transiently coupled by a transient coupling mechanism, the actuating mechanism **840** can actuate the cam **120**, eccentric mass **140**, or coupling mechanism to decouple the cam **120** from the eccentric mass **140**. In one specific example as shown in FIGS. 14A and 14B, the cam **120** is coupled to the eccentric mass **140** along the respective broad faces by a ring of magnets **842** encircling the rotational axis, and the actuating mechanism **840** extends through a hole in the cam **120** (or eccentric mass **140**) and pushes against the broad face of the eccentric mass **140** (or cam **120**) to decouple the eccentric mass **140** from the cam **120**. The actuating mechanism **840** can be statically coupled to the force translator **300** or primary pump **200** by a frame **880** or other coupling mechanism. Alternatively, the actuating mechanism **840** can be transiently coupled to the force translator **300** or primary pump **200**, wherein the actuating mechanism **840** can be a piston or rod that couples to the force translator **300** or primary pump **200**.

[0063] In another variation of the pressure regulation mechanism, the pressure regulation mechanism **800** switches the primary pump **200** from the pumping mode and a locked mode. The primary pump **200** preferably pumps fluid in the pumping mode and does not pump fluid in the locked mode. More preferably, components of the pump system **10** are held in static relation relative to each other in the locked mode, such that the reciprocating element **220** is held substantially

static. The primary pump **200** is preferably placed in the locked mode when the pressure of the second reservoir **500** exceeds the opening threshold pressure of the valve **860**, and is preferably placed in the pumping mode when the pressure of the second reservoir **500** falls below the closing threshold pressure of the valve **860**. More specifically, when the pressure of the second reservoir **500** exceeds the opening threshold pressure, the valve **860** opens, allowing pressurized air to flow from the second reservoir **500** into the compression volume of the primary pump **200**, substantially retaining the reciprocating element **220** in the initial position of the compression stroke (e.g., in the recovered position). In this manner, the increased force of pressurized air on the reciprocating element **220** substantially opposes cam motion when the reciprocating element **220** is located at the second section **126** of the cam profile, but can alternatively or additionally oppose cam motion when the reciprocating element **220** is located at the first section **124** or third section **128** of the cam profile. Since the cam **120** is preferably configured to only apply a small force to the reciprocating element **220** at the second section **126**, the cam **120** cannot overcome the large back force applied by the backflow on the reciprocating element **220**. These aspects of the pump system **10** effectively cease pumping within the primary pump **200**. The force applied by the backflow prevents cam movement relative to the primary pump **200**, causing the cam **120** and subsequently, the eccentric mass **140**, to rotate with the pump system **10**. When the pump system **10** includes multiple pumps, all the pumps are preferably flooded with pressurized air. Alternatively, a single pump can be flooded with pressurized air, alternating pumps can be flooded with pressurized air, or any other suitable subset of the pumps can be flooded to cease pumping.

[0064] However, any other suitable means of ceasing pumping force application to the reciprocating element **220** can be used.

[0065] The valve **860** of the pressure regulation mechanism **800** functions to selectively permit fluid flow into the pump body **240** of the secondary pump **820**. The valve **860** preferably has an opening threshold pressure substantially equal to the desired reservoir pressure (e.g., the upper limit of a desired reservoir pressure range), and can additionally have a closing threshold pressure under, over, or equal to the desired reservoir pressure (e.g., the lower limit of a desired reservoir pressure range). The valve **860** can additionally function as a timer, and have a pumping resumption pressure at which primary pump pumping is resumed. The pumping resumption pressure is preferably determined by the ratio of the first and second pressurization areas within the valve. Alternatively, the pressure regulation mechanism **800** can include a timer that functions to delay the resumption of pumping after the closing threshold pressure is reached. The valve **860** is preferably located in the fluid manifold fluidly connecting the second reservoir **500** with the pump body **240**. However, the valve **860** can be located within the second reservoir **500** or within the pump body inlet. The opening threshold pressure is preferably a higher pressure than the closing threshold pressure, wherein the opening and closing threshold pressures are preferably determined by the return force applied by the return element. The valve state is preferably determined by the pressure within the second reservoir **500**. The pumping resumption pressure is preferably lower than the closing threshold pressure, but can alternatively be higher than the closing threshold pressure or be any suitable pressure. The valve **860** is preferably operable between an open mode when

the pressure of the second reservoir **500** exceeds an opening threshold pressure, wherein the valve **860** permits fluid flow from the second reservoir **500** into the pump body **240**, and a closed mode when the pressure of the second reservoir **500** is below the closing threshold pressure, wherein the valve **860** prevents fluid flow from the second reservoir **500** into the pump body **240**. Pumping by the primary pump **200** is preferably resumed when the pressure within the second pump **820** falls below the pumping resumption pressure, but can alternatively be resumed when the reservoir pressure falls below the closing threshold. The valve **860** is preferably a snap-action valve, but can alternatively be any other suitable valve **860**. The valve **860** is preferably passive but can alternatively be active. The valve **860** preferably includes a valve member **864** that seats within a valve body **862**, and can additionally include a return mechanism (e.g., a spring) that biases the valve member **864** against the valve body **862**. The valve member **864** and valve body **862** can be different materials (e.g., to compensate for material expansion due to temperature changes), or can be made of the same material or materials with similar expansion coefficients.

[0066] In one variation of the pressure regulation mechanism **800**, the snap-action valve **860** is substantially similar to the valve described in U.S. application Ser. No. 13/469,007 filed 10 May 2012.

[0067] In another variation of the pressure regulation mechanism **800**, as shown in FIG. 16, the snap-action valve **860** includes a valve body **862**, a valve member **864**, a spring **865**, a first volume **866**, a second volume **867**, a reservoir channel **868**, and a manifold channel **869**. The spring or return element **86**, biases the valve body **862** against the valve member **864**. The spring constant of the spring is preferably selected based on the desired reservoir pressure (threshold pressure or cracking pressure) and the desired valve operating characteristics. The first volume is preferably defined between the valve body **862** and valve member **864**, and preferably has a first pressurization area normal to a direction of spring force application. The second volume is preferably also defined between the valve body **862** and valve member **864**, and preferably has a second pressurization area normal to the direction of spring force application. The second reservoir channel preferably fluidly connects the first volume with the second reservoir **500**. The manifold channel is preferably defined through the valve body **862**, and is preferably fluidly connected to the pressure regulation mechanism **800**. The manifold channel is preferably defined along the axis of return force application, opposing the return element **260** across the valve member **864**, but can alternatively be defined in any other suitable location. The valve **860** can additionally include a timing channel fluidly coupling the second volume to an ambient environment, wherein the timing channel has a cross section selected based on a desired leak rate. The ratio of the first pressurization area to the second pressurization area is preferably selected based on the desired amount of time the valve **860** takes to recover the closed position, but can alternatively be any suitable ratio. The combined volume of the first and second volumes are preferably substantially insignificant relative to the second reservoir volume. The valve **860** is preferably operable between an open position and closed position. In the open position, the valve body **862** and valve member **864** cooperatively define a connection channel fluidly connecting the first volume with the second volume, wherein the valve member **864** is located distal the valve body **862**. The open position is preferably achieved when a pres-

sure force generated by a pressure within the first volume overcomes the spring force applied by the spring on the valve body **862**. In the closed mode, the valve member **864** and valve body **862** cooperatively seal the connection channel and the valve member **864** substantially seals the manifold channel, wherein the valve member **864** seats against the valve body **862**. The closed mode is preferably achieved when the pressure force is lower than the applied spring force. In one alternative of the valve **860**, the valve member **864** has a symmetric cross section including a stem configured to fit within the manifold channel, a first overhang extending from the stem, and a second overhang extending from the first overhang. The valve body **862** includes a cross section complementary to the valve member cross section, including a first step defining the manifold channel, a second step extending from the first step, and walls extending from the second step. The first volume is preferably defined between the second step and the second overhang, the second volume is preferably defined between the first step and the first overhang, and the connection channel is preferably defined between a transition from the first overhang to the second overhang and a transition between the first step to the second step. The valve **860** can further include gaskets bordering and cooperatively defining the first and second volumes. In one alternative of the valve **860**, the valve **860** includes a first gasket located within the connection channel that forms a first substantially fluid impermeable seal with the valve member **864** in the closed mode and a second fluid impermeable seal defined between the second overhang and the walls. The valve **860** can additionally include a gasket within the manifold channel that forms a fluid impermeable seal with the stem when the valve **860** is in the closed mode (e.g., to cooperatively define the second volume), and permits fluid flow therethrough when the valve **860** is in the open mode.

5. Stabilizing Mechanism

[0068] The pump system **10** can additionally include a stabilizing mechanism **900** that functions to reduce rotational surface imbalance when the eccentric mass **140** becomes excited (e.g., begins spinning) when the pump system **10** rotates at or near the excitation frequency of the eccentric mass **140**. The stabilizing mechanism **900** is preferably the eccentric mass **140**, wherein the eccentric mass **140** is collectively formed from multiple sections. However, the stabilizing mechanism **900** can alternatively be any other suitable stabilizing mechanism **900**. When the eccentric mass **140** begins to spin, the composite sections of the eccentric mass separate. This is particularly useful when system oscillations cause the eccentric mass **140** (and positioning mechanism) to spin about the shaft; the centrifugal forces cause the sections of the split eccentric mass **140** to separate and be evenly distributed about the axis of system rotation, as shown in FIGS. 10A and 10B. Not only does this have the effect of dynamically balancing the system and/or rotating surface **20**, but the even distribution of the eccentric mass **140** within the system also halts system pumping. The latter effect can allow the eccentric mass **140** to additionally function as a control mechanism, wherein the eccentric mass resonant frequency can be tailored such that pumping is ceased when a predetermined rotation speed or vibration frequency is reached. The multiple sections are preferably each positioned the same radial distance away from the rotational axis (the eccentric mass **140** is radially divided into multiple sections, wherein the multiple sections have different angular positions), but

can alternatively be positioned at different radial distances (e.g., wherein the multiple sections have substantially similar angular positions, etc.). The multiple sections preferably share a common plane, wherein the common plane is preferably substantially parallel to the rotational surface. The multiple sections can collectively form an arc, centered about the rotational axis, that intersects the common plane (e.g., the multiple sections are adjacent along an arc), form a block that intersects the common plane, or collectively form any other suitable structure. Alternatively, the multiple sections can be stacked along the thicknesses of the sections, wherein the section thicknesses are preferably parallel to the rotational axis. The multiple sections preferably have substantially the same mass, but can alternatively have different masses. The center of mass for each eccentric mass section is preferably offset from the mass couple connection point for each eccentric mass section, and is preferably arranged proximal an adjacent eccentric mass section. In operation, the eccentric mass sections separate until the centers of mass of the eccentric mass sections oppose each other across the axis of rotation.

[0069] When the eccentric mass **140** is cooperatively formed by multiple sections, the mass couple **142** preferably also includes multiple sections, wherein each mass couple section statically couples to an eccentric mass section. The mass couple sections are preferably rotatably coupled to the cam **120**, but can alternatively be statically coupled to the cam **120**. Each mass couple section is preferably rotatably coupled to the remaining mass couple sections, but can alternatively be statically coupled to one or more of the remaining mass couple sections. In one variation as shown in FIGS. **11A** and **11B**, the end of each mass couple section opposing the eccentric mass section is rotatably coupled to the housing. The angular positions of mass couple section ends are preferably static relative to the housing, wherein the mass couple section ends are preferably equally distributed about the axis of rotation. In another variation, the end of the each mass couple section opposing the eccentric mass section includes a bearing, wherein the bearing is slidably engaged within a circumferential groove statically coupled to the cam **120** and encircling the rotational axis. When the rotation frequency of the rotating surface **20** is below or above the excitation frequency for the cooperatively defined eccentric mass **140**, the centrifugal force of the rotation preferably retains the eccentric mass sections (and mass couple sections) in substantially adjacent positions. When the rotation frequency of the rotating surface **20** is at the excitation frequency, the centrifugal force preferably causes the bearings to slide within the groove, distributing the multiple eccentric mass sections substantially equally about the rotational axis. The bearings and/or the eccentric mass sections can each additionally include magnets, disposed in repulsive relation to adjacent magnets, which facilitate eccentric mass separation in response to the receipt of a system oscillation. In another variation, the mass couple sections rotatably couple along the longitudinal axis of an axle extending from the cam **120** (e.g., mass couple sections are stacked along the axle). In another variation, one mass couple section is statically connected to the cam **120** while the remaining mass couple sections are rotatably connected to the cam **120**. However, the mass couple sections can be otherwise connected to the cam **120**.

[0070] When the mass couple **142** couples to the cam **120** at the rotational axis, the mass couple **142** is preferably operable between the coupled mode, wherein the mass couple **142**

connects the eccentric mass **140** to the cam **120**, and the decoupled mode, wherein the mass couple **142** disconnects the eccentric mass **140** from the cam **120**. In one variation, the mass couple **142** is a disk located within the lumen defined by an interior bearing surface of the cam **120**, wherein the disk can rotate relative to the interior bearing surface in the decoupled mode and is coupled to the interior bearing surface by a friction element in the coupled mode. The mass couple sections are preferably rotatably coupled to the disk, but can alternatively be disk sections (e.g., concentric circles, arcuate pieces, etc.). The friction element can be a high-friction coating along the interior bearing surface, a high-friction coating along the mass couple **142** exterior, a roller or wedge, or any other suitable element capable of providing friction between the interior bearing surface and the mass couple **142**. The friction element is preferably selected such that the cooperative centrifugal force of the eccentric mass **140** in the coupled mode applies sufficient force to the mass couple **142** such that the friction between the mass couple **142** and the interior bearing surface retains the mass couple position relative to the cam **120**. The friction element is preferably selected such that the cooperative centrifugal force of the eccentric mass sections in a separated or decoupled mode does not provide enough force to interface friction to retain the mass couple position relative to the cam **120**, thereby allowing free mass couple rotation. In another variation, the mass couple **142** is rotatably mounted on an axle extending from the cam **120** by bearings, wherein the mass couple **142** can be statically coupled to the cam **120** by one or more sets of magnets or pistons extending from the adjacent broad faces of the cam **120** and mass couple **142**. However, the static mass couple connection to the cam **120** to achieve the coupled mode can be selectively controlled by any other suitable passive or active means.

[0071] The eccentric mass **140** can additionally include a connection mechanism that functions to couple the multiple sections together. The connection mechanism is preferably located on the interfaces of adjacent sections, but can alternatively be located within the section bodies, at the interfaces of adjacent mass couple sections, or at any other suitable location. The coupling force of the connection mechanism is preferably selected such that it is substantially equal to or lower than the angular separation force experienced by the individual eccentric mass sections when the system is rotating at the excitation frequency. However, the coupling force can have any other suitable magnitude. The connection mechanism can be a mechanical connection (e.g., adhesive, clips, Velcro, etc.) with a separation force substantially equivalent to the coupling force, a magnetic connection wherein adjacent eccentric mass or mass couple sections include complementary magnets, or any other suitable mechanism that can selectively connect adjacent eccentric mass sections together.

[0072] In one alternative, the eccentric mass **140** is collectively formed by a first and a second section (e.g., the eccentric mass **140** is divided radially into two sections), wherein the first section is a reflected duplication of the second section. In operation, the first and second sections are preferably diametrically opposed and spin about the axis of rotation of the positioning mechanism when the system vibration reaches the resonance frequency of the eccentric mass **140**. In a second alternative, the eccentric mass **140** is collectively formed by a first, second, and third section with substantially the same mass, wherein the first, second and third sections are preferably substantially evenly distributed about the rota-

tional axis when the system rotational speed reaches the resonance frequency of the eccentric mass **140**. However, the eccentric mass **140** can be formed from any number of constituent sections in any suitable configuration. Alternatively, the stabilizing mechanism **900** can be any other suitable mechanism.

[0073] The pump system **10** can additionally include a damping mechanism that functions to minimize oscillations of the eccentric mass **140** within the system. Oscillations of the eccentric mass **140** can result in eccentric mass excitation, wherein the eccentric mass **140** spins within the system instead of remaining substantially static relative to a gravity vector. Oscillations can arise from irregularities in the rolling surface (e.g., the road), dynamic unbalance (e.g., due to wheel mass distribution.), the pumping pulse (e.g., when the pumping pulse occurs at a frequency that excites the mass), or can arise from any suitable mechanism that can generate oscillations of the eccentric mass **140**.

[0074] In a first variation, the damping mechanism includes Dynabeads or other dynamic balancing mechanisms located within an internal channel encircling the rotational axis. In a second variation, the damping mechanism is a torsional mass-spring system, wherein the resonant vibration period of the mass-spring system is preferably matched to the gravitationally induced resonant frequency of the eccentric mass **140** oscillation. The torsion spring is preferably coupled to the cam **120** such that the eccentric mass **140** oscillations cause an inertial transfer, which excites the torsional mass-spring system into resonance at a phase shift that is 180 degrees out of phase with the oscillations of the eccentric mass **140**. The torsion spring is preferably coupled between the torsional mass and the cam **120**, but can alternatively be positioned between the cam **120** and the mass couple **142**, or in any suitable position.

6. Example Pump System

[0075] In one embodiment of the pump system **10**, as shown in FIGS. **12A** and **12B**, the pump system **10** includes a first and a second reciprocating pump (**200a** and **200b**, respectively), a drive mechanism **100**, a first and a second force translator (**300a** and **300b**, respectively) connected to the first and second reciprocating pumps, respectfully, the first and second force translators having a first and second axis in fixed relation, respectively, a fluid manifold **202** fluidly connecting the second reciprocating pump to a reservoir **500**, and a valve **860** located within the fluid manifold **202**. The first pump **200a** preferably includes an outlet fluidly connected to the second reservoir **500**, wherein the first pump **200a** pumps fluid to and pressurizes the second reservoir **500**. The first pump **200a** preferably includes an inlet fluidly connected to a fluid source, wherein the fluid source can be the ambient environment, the housing (e.g., wherein the housing encloses desiccated air), or any other suitable fluid source. The second pump **200b** can additionally include an inlet (separate from that coupled to the fluid manifold **202** but alternatively the same one) and outlet fluidly connected to the fluid source and reservoir, respectively, wherein the second pump **200b** can pump fluid to and pressurize the second reservoir **500**. Alternatively, the inlet and outlet of the second pump **200b** can be fluidly connected to the fluid source and to the inlet of the first pump **200**, respectively, thereby forming a two-stage pump. In this alternative, fluid is pressurized to a first pressure within the second pump **200b** and pressurized to a second pressure at the first pump **200a**. The first and second

reciprocating pumps preferably include a first and second pump body (**240a** and **240b**), respectively, and a first and second reciprocating element (**220a** and **220b**), respectively. The first and second reciprocating pumps preferably share a common plane (e.g., the respective actuating axes share a common plane), but can alternatively be located in different planes. The first and second reciprocating pumps are preferably equally radially distributed about the drive mechanism **100**, more preferably equally distributed about the rotational axis of the drive mechanism **100**. However, the pumps can be otherwise distributed. The positions of the first and second pump bodies are preferably statically fixed by a housing or other component, wherein the housing statically couples the pump system **10** to a rotating surface **20** and can additionally enclose the pump system **10**. The first and second reciprocating pumps preferably oppose each other, wherein the closed end of the first pump body **240a** is distal the closed end of the second pump body **240b** and the first reciprocating element **220a** is proximal the second reciprocating element **220b**. The first reciprocating element **220a** preferably has a first pressurization area (area that receives or generates a pressure force) and the second reciprocating element **220b** preferably has a second pressurization area. The first pressurization area is preferably smaller than the second pressurization area, but can alternatively be larger or smaller. The drive mechanism **100** preferably includes a rotational axis **102**, a cam **120** rotatable about the rotational axis, the cam **120** having a bearing surface **122**, and an eccentric mass **140** coupled to the cam **120** that offsets the center of mass of the drive mechanism **100** from the rotational axis. The first force translator **300a** is preferably couplable to the bearing surface **122** of the cam **120** in non-slip contact, and is preferably statically connected to the reciprocating element **220** of the first pump along an axis (e.g., rotational axis). The second force translator **300b** preferably slips relative to the bearing surface **122** of the cam **120**, but can alternatively couple in non-slip contact with the bearing surface **122**. The second force translator **300b** is preferably statically connected to the reciprocating element **220** of the second pump along an axis (e.g., rotational axis). The first and second force translators can each be a roller, a piston, a piston coupled to the roller at the rotational axis, or any other suitable force translator. The positions of the first and second force translators are preferably statically retained by a frame **880**, but can alternatively be retained by any other suitable mechanism. The frame **880** preferably encloses the drive mechanism **100**, such that the drive mechanism **100** is located within the area bounded by the frame **880**. However, the frame **880** can be otherwise arranged relative to the drive mechanism **100**. The frame **880** is preferably located in the common plane shared by the first and second pumps, but can alternatively be located in a separate plane (e.g., extend normal to said plane and extend along a second plane parallel to the first). In operation, a radial or linear position of the frame **880** preferably shifts from a first position to a second position relative to a point on the drive mechanism **100** (e.g., rotational axis) when second reciprocating element **220** moves from the depressurized position to the pressurized position, respectively. The distance between the first position and the second position is preferably substantially similar to the distance between the depressurized position and the pressurized position, but can alternatively be larger (e.g., wherein the frame **880** amplifies the change in reciprocating element position) or smaller. Frame **880** movement preferably results in simultaneous first and second force translator movement,

coupling the first force translator **300a** to the drive mechanism **100** in the first position and decoupling the first force translator **300a** from the drive mechanism **100** in the frame's second position. Alternatively, frame movement can result in first and second reciprocating pump movement relative to the drive mechanism **100**, wherein the frame **880** statically connects the positions of the first and second pump bodies. However, the force translators can be otherwise connected and disconnected to the drive mechanism **100**. The frame **880** can additionally include features; such as arcuate grooves on the surface of the frame **880** proximal the drive mechanism **100**, which facilitate second force translator **300b** slip relative to the bearing surface **122**. The fluid manifold preferably fluidly connects the second reservoir **500** to an inlet of the second pump, but can additionally fluidly connect the second reservoir **500** to an inlet of the first pump. In the latter alternative, the valve is preferably located upstream of the junction between the three fluid connections or within the junction. In this latter alternative; valve opening simultaneously floods both lumens of the first and second reciprocating pumps. Because the second reciprocating pump preferably has a larger pressurization area than the first reciprocating pump, the second reciprocating pump preferably exerts a linear (e.g., radial) decoupling force on the frame **880**, which is transferred by the frame **880** into a shift in the position of the first

force translator **300a** away from the drive mechanism **100**, effectively decoupling the first force translator **300a** from the drive mechanism **100**.

[0076] As a person skilled in the art will recognize from the previous detailed description and from the figures and claims, modifications and changes can be made to the preferred embodiments of the invention without departing from the scope of this invention defined in the following claims.

I claim:

1. A tire pressurization system configured to mount to a wheel having a rotational axis, the system comprising:
 - a casing configured to mount to the wheel;
 - a first compressor mounted to the casing and configured to fluidly connect to a fluid source, the first compressor comprising a first chamber and a first actuating element, the first actuating element having a first area;
 - a second compressor mounted to the casing, fluidly connected to the first compressor and configured to fluidly connect to a tire interior, the second compressor comprising a second chamber and a second actuating element, the second actuating element having a second area; and
 - a drive mechanism mounted to the casing and configured to actuate the second compressor between a compressed state and a recovered state.

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