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(71) Applicant: **CORNING INCORPORATED** [US/US]; 1 Riverfront Plaza, Corning, New York 14831 (US).

(72) Inventors: **BECKWITH, Jared David**; 11472 S Eagle Valley Rd., Port Matilda, Pennsylvania 16870 (US). **CEM-**

PA, Matthew John; 6510 Tyrone Pike, Tyrone, Pennsylvania 16686 (US). **HOQUE, Aziz**; 2986 South Oakwood Drive, Painted Post, New York 14870 (US). **KEEBLER, Thomas Augustus**; 8 James St., Corning, New York 14830 (US). **MORGAN, Kenneth Spencer**; 46 S. Oakwood Drive, Painted Post, New York 14870 (US). **WASSON, Kevin Lee**; 45 Thornapple Drive, Elmira, New York 14903 (US). **WEST, William Lawrence**; 190 Dodge Avenue, Corning, New York 14830 (US).

(74) Agent: **MASON, Matthew J.**; Corning Incorporated, Intellectual Property Department, SP-TI-3-1, Corning, New York 14831 (US).

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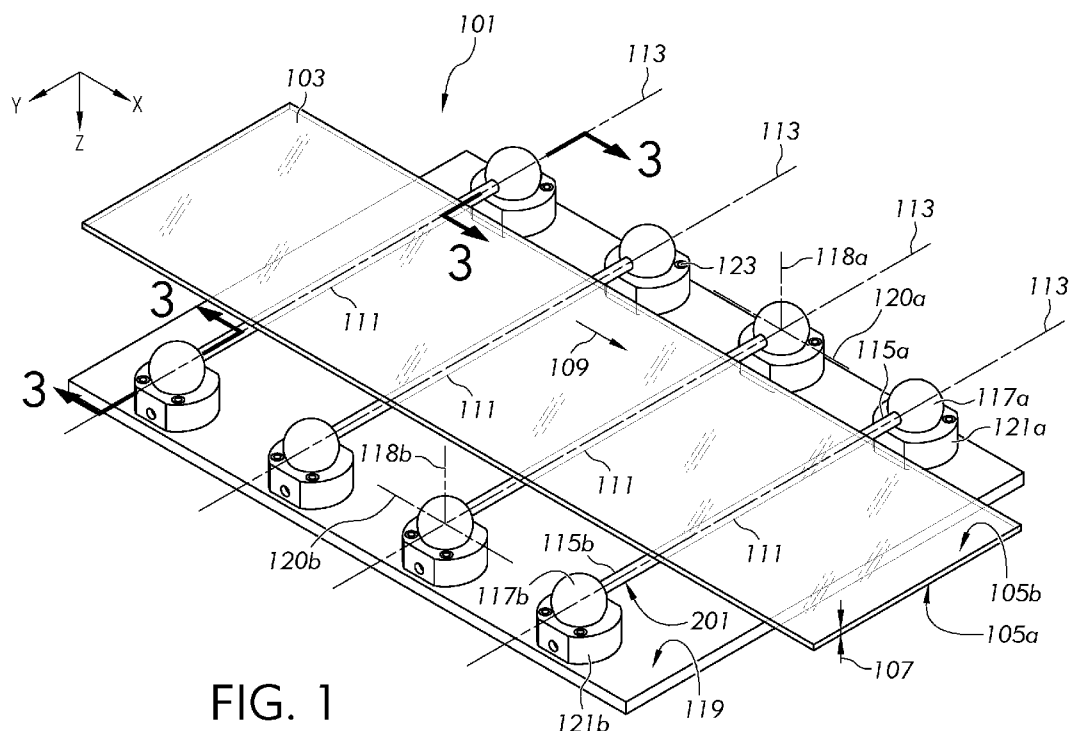


FIG. 1

(57) Abstract: A support apparatus can comprise a cylindrical rod extending along a first rotation axis and comprising a first end portion provided with a first convex spherical segment and a second end portion provided with a second convex spherical segment. A first area can be configured to receive a portion of the first convex spherical segment. A second area can be configured to receive a portion of the second convex spherical segment. The cylindrical rod can be pivotable about a first pivot axis perpendicular to the first rotation axis. In some embodiments, methods of supporting an object can comprise engaging a surface of the object with the outer surface of the cylindrical rod wherein the first cylindrical rod supports a weight of the object while the first cylindrical rod is supported by the first fluid cushion and the second fluid cushion.



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APPARATUS AND METHODS FOR SUPPORTING AN OBJECT

FIELD

[0001] This application claims the benefit of priority to U.S. Provisional Application Serial No. 62/724,174 filed on August 29, 2018, the content of which is relied upon and incorporated herein by reference in its entirety.

[0002] The present disclosure relates generally to apparatus and methods for supporting an object and, more particularly, to apparatus and methods for supporting a weight of an object.

BACKGROUND

[0003] Glass ribbons often are transported from one location to another. In some embodiments, pressure can be provided against a major surface of the glass ribbon to help support the weight of the glass ribbon during conveyance. For example, it is known to support the glass ribbon on a cushion of air that contacts the glass ribbon to levitate the glass ribbon on the cushion of air.

SUMMARY

[0004] The following presents a simplified summary of the disclosure to provide a basic understanding of some embodiments described in the detailed description.

[0005] In some embodiments, a support apparatus can comprise a first cylindrical rod comprising a first end portion and a second end portion, wherein the first cylindrical rod extends along a first rotation axis from the first end portion to the second end portion of the first cylindrical rod. The first end portion can be provided with a first convex spherical segment and a second end portion can be provided with a second convex spherical segment. The support apparatus can further comprise a first area configured to receive a portion of the first convex spherical segment with the first cylindrical rod pivotable about a first pivot axis of the first convex spherical segment that is perpendicular to the first rotation axis of the cylindrical rod. A first fluid port can be in fluid communication with the first area. The support apparatus can further comprise a second area configured to receive a portion of the second convex spherical segment with the first cylindrical rod pivotable about a first pivot axis of the second convex spherical

segment that is perpendicular to the first rotation axis of the cylindrical rod and parallel to the first pivot axis of the first convex spherical segment. A second fluid port can be in fluid communication with the second area.

[0006] In some embodiments, the first area of the support apparatus can be configured to receive the portion of the first convex spherical segment with the first cylindrical rod pivotable about a second pivot axis of the first convex spherical segment that is perpendicular to the first rotation axis of the cylindrical rod and to the first pivot axis of the first convex spherical segment. The second area of the support apparatus can be configured to receive the portion of the second convex spherical segment with the first cylindrical rod pivotable about a second pivot axis of the second convex spherical segment that is parallel to the second pivot axis of the first convex spherical segment and perpendicular to the first rotation axis of the cylindrical rod and to the first pivot axis of the second convex spherical segment.

[0007] In some embodiments, the first area of the support apparatus can be configured to receive the portion of the first convex spherical segment with the first cylindrical rod pivotable by from about 10° to about 30° about the second pivot axis of the first convex spherical segment. The second area of the support apparatus can be configured to receive the portion of the second convex spherical segment with the first cylindrical rod pivotable from about 10° to about 30° about the second pivot axis of the second convex spherical segment.

[0008] In some embodiments, the first spherical segment can be configured to be freely supported by the first area. The second spherical segment can be configured to be freely supported by the second area.

[0009] In some embodiments, the first area of the support apparatus can be configured to receive the portion of the first convex spherical segment with the first cylindrical rod pivotable by from about 10° to about 30° about the first pivot axis of the first convex spherical segment. The second area of the support apparatus can be configured to receive the portion of the second convex spherical segment with the first cylindrical rod pivotable by from about 10° to about 30° about the first pivot axis of the second convex spherical segment.

[0010] In some embodiments, the first area of the support apparatus can be configured to receive the portion of the first convex spherical segment with the first cylindrical rod pivotable by 360° about the first pivot axis of the first convex spherical segment. The second area of the support apparatus can be configured to receive the portion of the second convex spherical segment with the first cylindrical rod pivotable by 360° about the first pivot axis of the second convex spherical segment.

[0011] In some embodiments, the support apparatus may comprise a joint configured to adjustably mount the first area relative to a support surface in a direction of the first rotation axis of the first cylindrical rod.

[0012] In some embodiments, the support apparatus may comprise a first lip circumscribing the first area and a second lip circumscribing the second area.

[0013] In some embodiments, the support apparatus may comprise the first area recessed below the first lip at a maximum depth within a range from about 20% to about 80% of a first radius of a first convex spherical segment. Also, the second area can be recessed below the second lip at a maximum depth within a range from about 20% to about 80% of a second radius of the second convex spherical segment.

[0014] In some embodiments, the support apparatus may comprise a cylindrical rod comprising one or more materials selected from the group consisting of: alumina, fused quartz, mullite, silicon carbide, and graphite.

[0015] In some embodiments, the support apparatus can comprise the first area defined by a first concave segment.

[0016] In some embodiments, the support apparatus can comprise the first concave segment comprising a first concave spherical segment.

[0017] In some embodiments, the support apparatus can comprise the second area defined by a second concave segment.

[0018] In some embodiments, the support apparatus can comprise the second concave comprising a second concave spherical segment.

[0019] In some embodiments, the support apparatus may comprise a second cylindrical rod.

[0020] In some embodiments, the support apparatus may comprise a first rotation axis of the first cylindrical rod parallel to a second rotation axis of the second cylindrical rod.

[0021] In some embodiments, the support apparatus may comprise a first rotation axis of the first cylindrical rod that extends at an acute angle relative to a second rotation axis of the second cylindrical rod.

[0022] In some embodiments, the first rotation axis and the second rotation axis do not extend along a common plane.

[0023] In some embodiments, the first rotation axis and the second rotation axis extend along a common plane.

[0024] In accordance with some embodiments, a method may comprise supporting an object with the support apparatus of any one of the support apparatus discussed above. Methods may comprise passing a first fluid stream through the first fluid port to form a first fluid cushion that can levitate the first convex spherical segment. Also, methods can comprise passing a second fluid stream through the second fluid port to form a second fluid cushion that can levitate the second convex spherical segment. Additionally, methods can include engaging a surface of the object with an outer surface of the first cylindrical rod, where the first cylindrical rod can support a weight of the object while the first cylindrical rod is supported by the first fluid cushion and the second fluid cushion.

[0025] In some embodiments, methods can further comprise traversing the object along a travel direction, wherein the object drives the first cylindrical rod to rotate while the first cylindrical rod is supported by the first fluid cushion and the second fluid cushion.

[0026] In some embodiments, methods can be used to support an object comprising a glass ribbon.

[0027] In some embodiments, methods can be used to support an object comprising a temperature within a range from about 500°C to about 1200°C.

[0028] In some embodiments, methods can freely support the first spherical segment by the first area. The second spherical segment can freely support the second area. At the same time, the first cylindrical rod can support the object.

[0029] In some embodiments, methods can further comprise adjusting a distance between the first area and the second area while the first cylindrical rod supports the object.

[0030] BRIEF DESCRIPTION OF THE DRAWINGS

[0031] These and other features, aspects and advantages are better understood when the following detailed description is read with reference to the accompanying drawings, in which:

[0032] **FIG. 1** illustrates a perspective view of some embodiments of the support apparatus supporting an object according to embodiments of the disclosure;

[0033] **FIG. 2** illustrates an elevational front-end view of the support apparatus of **FIG. 1**;

[0034] **FIG. 3** is a cross-sectional view of the support apparatus taken along lines line 3-3 in **FIG. 1**;

[0035] **FIG. 4** is another elevational front-end view of the support apparatus of **FIG. 1**; and

[0036] **FIG. 5** illustrates a top plan view of an alternative embodiments of the support apparatus of **FIG. 1**.

DETAILED DESCRIPTION

[0037] Embodiments will now be described more fully hereinafter with reference to the accompanying drawings in which example embodiments are shown. Whenever possible, the same reference numerals are used throughout the drawings to refer to the same or like parts. However, this disclosure may be embodied in many different forms and should not be construed as limited to the embodiments set forth herein.

[0038] It is to be understood that specific embodiments disclosed herein are intended to be exemplary and therefore non-limiting. For purposes of the disclosure, although not required, the support apparatus or method of supporting an object can be used in a glass manufacturing apparatus. Such a glass manufacturing apparatus can optionally comprise a glass forming apparatus that forms a glass sheet and/or glass ribbon

from a quantity of molten material. For example, the glass manufacturing apparatus can optionally include a glass forming apparatus such as a slot draw apparatus, float bath apparatus, down-draw apparatus, up-draw apparatus, press-rolling apparatus or other glass forming apparatus. Furthermore, for purposes of the disclosure, although not required, such a glass manufacturing apparatus can include a storage device for storing a previous-formed glass ribbon. For example, although not shown, the glass manufacturing apparatus may optionally include a storage spool including a length of the glass ribbon wound on the storage spool. In some embodiments, the apparatus can support glass ribbon as it is formed with the glass manufacturing apparatus while the glass ribbon has a temperature greater than room temperature. In alternative embodiments, the apparatus can be used to support glass ribbon that has cooled to room temperature. In further embodiments, apparatus of the disclosure can support glass ribbon in the form of a glass sheet. For purposes of the disclosure, reference to a glass ribbon refers to glass ribbon that is being drawn from a glass manufacturing apparatus, glass ribbon that is be uncoiled from a storage spool of glass ribbon, and/or glass sheets separated from a larger length of glass ribbon.

[0039] Alternatively, the support apparatus or method of supporting an object can be used in a silicon wafer manufacturing apparatus or during conveyance of silicon wafers produced by a silicon wafer manufacturing apparatus. Embodiments of a silicon wafer manufacturing apparatus that can incorporate aspects of the disclosure can optionally comprise an ingot growth apparatus, a slicing apparatus, a lapping apparatus, and/or a cleaning apparatus.

[0040] FIG. 1 illustrates an elevational view of embodiments of the support apparatus 101 for supporting an object. The object can comprise a sheet of material (e.g., glass ribbon, silicon wafer) or other objects including a surface that may be engaged by the support apparatus 101 as discussed more fully below. In the illustrated embodiment, the object comprises a glass ribbon 103 in the form of a glass sheet although the object may comprise a glass ribbon prior to separating into a sheet of glass ribbon 103. For example, the glass ribbon 103 can be drawn from a spool of glass ribbon or drawn from a forming apparatus that forms molten material into the glass ribbon. The support apparatus 101 may engage a surface of the object when the support apparatus 101 is

supporting the object to support at least a portion of a weight of the object. For instance, as shown in **FIG. 1**, the glass ribbon **103** may include a first major surface **105a** and a second major surface **105b** with a thickness **107** defined between the first major surface **105a** and the second major surface **105b** of the glass ribbon **103**. As shown, the support apparatus **101** can engage (e.g., physically contact) the first major surface **105a** of the glass ribbon **103** to support at least a portion of the weight of the glass ribbon **103**. In some embodiments, as shown, the support apparatus **101** can engage the first major surface **105a** of the glass ribbon **103** to support at least a portion of the weight of the glass ribbon **103** while the glass ribbon **103** travels along travel direction **109** relative to the support apparatus **101**. In the illustrated embodiment, the travel direction **109** can extend horizontally along illustrated directional coordinate “**x**” that is perpendicular to gravity along illustrated directional coordinate “**z**”. In some embodiments, the travel direction **109** may have an elevational incline, where the travel direction **109** includes a directional component opposite the direction of gravity. Alternatively, the travel direction **109** may have an elevational decline where the travel direction **109** includes a directional component in the direction of gravity. In some embodiments, the travel direction **109** may elevationally alternate between one or more of a horizontal travel path, an elevationally inclined path, and/or an elevationally declined path. Furthermore, in any of the embodiments, the glass ribbon **103** may tilt in one or more directions about the travel direction illustrated as the directional coordinate “**x**”. Such tilting, for example, is illustrated in phantom lines in **FIG. 4**.

[0041] **FIG. 1** illustrates a perspective view of the support apparatus **101** of embodiments of the present disclosure. As shown, the support apparatus **101** can comprise one or more cylindrical rods **111**. The illustrated embodiments feature four cylindrical rods **111** although further embodiments may include one, two, three or more than four cylindrical rods **111**. Furthermore, as shown, in some embodiments, each cylindrical rod **111** may be identical to one another, although different cylindrical rod designs may be provided in further embodiments.

[0042] In some embodiments, each cylindrical rod **111** can extend along a rotation axis **113** from a first end portion **115a** to a second end portion **115b** of the cylindrical rod **111**. As shown, the rotation axis **113** can comprise a linear rotation axis

extending through a symmetrical center of the cylindrical rod 111. In some embodiments, the rotation axis 113 of one or more of a plurality of cylindrical rods 111 may be parallel to the rotation axis 113 of one or more other cylindrical rods 111 of the plurality of cylindrical rods 111. For instance, with reference to FIG. 1, the rotation axis 113 of all of the cylindrical rods 111 of the plurality of cylindrical rods 111 can extend parallel with respect to one another in a horizontal direction in the directional coordinate “y”. Alternatively, in some embodiments, the rotation axis 113 of one or more of the cylindrical rods 111 can be positioned to extend at an acute angle with respect to the rotation axis 113 of one or more other cylindrical rods 111 of a plurality of cylindrical rods 111. For instance, with reference to the top plan view of the alternative embodiments of the support apparatus 501 shown in FIG. 5, each rotation axis 113 of each cylindrical rod 111 can extend at an acute angle with respect to each of the other cylindrical rods 111 although the rotational axis 113 of one cylindrical rod 111 may be parallel to the rotational axis 113 of one or more other cylindrical rods 111 in further embodiments. The elevational end view of FIGS. 2 and 4 can be representative of the support apparatus 101 shown in FIG. 1 and/or the support apparatus 501 of FIG. 5. Thus, as represented by FIGS. 2 and 4, in some embodiments, the rotation axis 113 of the cylindrical rods 111 can optionally extend along a common plane regardless of whether the rotation axis 113 of the cylindrical rods 111 are parallel to one another (as shown in FIG. 1) or angled relative to one another (as shown in FIG. 5).

[0043] In some embodiments, a rotation axis 113 of one of the cylindrical rods 111 does not extend along a common plane with a rotation axis 113 of another of the cylindrical rods 111. For instance, with reference to FIG. 4, the rotation axis 113 of the cylindrical rod 111 shown in phantom lines and the rotation axis 113 of the cylindrical rod 111 shown in solid lines extend at an acute angle relative to one another and do not extend along a common plane with the rotation axis 113 of the cylindrical rod 111.

[0044] As shown in FIG. 2, one or all of the cylindrical rods 111 may include an outer peripheral surface 201. As shown, the outer peripheral surface can include the same diameter 203 across a central portion of the cylindrical rods 111 between the first end portion 115a and the second end portion 115b of the cylindrical rod 111. As such, in some embodiments, the outer peripheral surface 201 may comprise a circular cylindrical

surface as shown in **FIGS. 1-5**. Although not shown, the outer peripheral surface **201** may have shapes other than a circular cylindrical surface with the same diameter **203** across the central portion of the cylindrical rod. For instance, the outer peripheral surface may include a shape that matches a curvature of the glass ribbon **103** being supported by the support apparatus **101**. In further embodiments, the outer peripheral surface **201** may be designed to facilitate alignment of the glass ribbon **103** during conveyance of the glass ribbon **103**. For instance, in some embodiments, a middle portion of the central portion of the cylindrical rod **111** may have a reduced diameter that increases in each direction toward the first end portion **115a** and the second end portion **115b**. In such embodiments, the outer peripheral surface **201** flares outwardly toward the first and second end portions **115a, 115b**. Such embodiments can be helpful to conform to the shape of a bowed glass ribbon **103**. Furthermore, the glass ribbon **103** may be flexible in which case the glass ribbon **103** may temporarily bend into the bowed configuration to help align the glass ribbon **103** so that the glass ribbon **103** will tend to track to the middle of the central portion of the cylindrical rod **111** in proper alignment during conveyance. In further embodiments, the diameter **203** of the cylindrical rod **111** can change continuously or even non-continuously across its length. In further embodiments, the cylindrical rod **111** can comprise a different diameter in the region where it contacts the object (e.g., glass ribbon **103**) being supported than it has elsewhere.

[0045] In some embodiments, the cylindrical rod **111** may be made of a material that has a high melting point, a low thermal conductivity, a low coefficient of thermal expansion, and a moderate coefficient of static friction. The cylindrical rod **111** can be designed to maintain its mechanical properties at the temperature of the object (e.g., glass ribbon **103**) that is being supported, which can be considered the operating temperature of support apparatus **101**. In some embodiments, the object may be freshly drawn glass ribbon **103**. In such embodiments, the cylindrical rod **111** can be made of a material that has a melting temperature above 1600°C. If the cylindrical rod **111** comprises an amorphous material, the operating temperature can be below the glass transition temperature of that material. In some embodiments, the temperature of the object (e.g., glass ribbon **103**) being supported can be within a range from about -50°C to about 1200°C or from about 500°C to about 1200°C.

[0046] Also, the cylindrical rod **111** may be made of a material that has a low thermal conductivity. In such embodiments, the cylindrical rod **111** may not act as a significant heat sink and/or may not significantly impact any heating or cooling operations that can be performed on the object (e.g., glass ribbon **103**) being supported. In some embodiments, the object can be cooled quickly while in other embodiments, the object can be held in a given temperature range in order to anneal it. For such embodiments, the material may comprise a thermal conductivity about $30 \text{ W m}^{-1} \text{ K}^{-1}$ or less, from about $0.01 \text{ W m}^{-1} \text{ K}^{-1}$ to about $50 \text{ W m}^{-1} \text{ K}^{-1}$, or from about $0.25 \text{ W m}^{-1} \text{ K}^{-1}$ to about $30 \text{ W m}^{-1} \text{ K}^{-1}$. In other embodiments, higher thermal conductivities may be permissible.

[0047] Additionally, the cylindrical rod **111** can be made a material that has a low coefficient of thermal expansion. While not necessary, a low coefficient of thermal expansion can allow relatively consistent dimensional stability of the cylindrical rod **111** even if the cylindrical rod **111** experiences thermal inhomogeneities across its length. For example, in some embodiments, a specific thermal profile may be imposed on the object being supported in order to obtain a target internal tension or compressive stress profile. Further, cylindrical rod **111** may not deform or warp under such conditions. For embodiments where a low coefficient of thermal expansion is desirable, the material may comprise a coefficient of thermal expansion about $10 \times 10^{-6} \text{ K}^{-1}$ or less, from about $0.15 \times 10^{-6} \text{ K}^{-1}$ to about $30 \times 10^{-6} \text{ K}^{-1}$, or from about $3 \times 10^{-6} \text{ K}^{-1}$ to about $20 \times 10^{-6} \text{ K}^{-1}$.

[0048] In some embodiments, the cylindrical rod **111** may be made a material with a moderate coefficient of static friction for embodiments where the supported object (e.g., glass ribbon **103**) is being traversed. The cylindrical rod **111** can rotate about the rotation axis **113** while the object translates relative to a support surface **119** without resisting the movement of the object as long as the force transmitted to the cylindrical rod **111** in the object's travel direction **109** is less than the product of a normal force generated by the weight of the object that is transmitted to the cylindrical rod **111** and the coefficient of static friction between the object and the cylindrical rod **111**. In some embodiments, the cylindrical rod **111** may comprise a hollow tube to provide a cylindrical rod **111** with less mass and a correspondingly lower moment of inertia in order to minimized resistance to rotation of the cylindrical rod **111** upon engagement

with the object. As such, sliding of the object (e.g. glass ribbon **103**) relative to outer peripheral surface **201** of the cylindrical rod **111** can be avoided, thereby avoiding wear of the cylindrical rod **111** and/or damage to the first major surface **105a** of the glass ribbon **103**. In some embodiments, the cylindrical rod **111** may not be provided with an excessively low coefficient of static friction in order to prevent sliding of the outer peripheral surface **201** of the cylindrical rod **111** relative to the supported surface of the object. In some embodiments, the material of the cylindrical rod **111** may comprise a coefficient of static friction within a range from about 0.3 to about 1.0, from about 0.2 to about 1.5, or from about 0.35 to about 0.75.

[0049] In some embodiments, the cylindrical rod **111** may comprise alumina. In other embodiments, the cylindrical rod **111** may comprise fused quartz. In yet other embodiments, the cylindrical rod **111** may comprise mullite, which is a mineral comprising a combination of aluminum oxide and silicon dioxide. In still other embodiments, the cylindrical rod **111** may comprise silicon carbide, SiC. In some embodiments, the cylindrical rod **111** may comprise graphite. In further embodiments, the cylindrical rod **111** may comprise a combination of two or more of materials selected from the group of alumina, fused quartz, mullite, and silicon carbide.

[0050] As further shown in **FIGS. 1-5**, embodiments of the support apparatus **101**, **501** may provide each cylindrical rod **111** with a first convex spherical segment **117a** at the first end portion **115a** of the cylindrical rod **111** and a second convex spherical segment **117b** at the second end portion **115b** of the cylindrical rod **111**. Throughout the disclosure, a convex spherical segment can comprise a property that any two points in a portion bounded by an outer convex surface of the convex spherical segment can be connected by a line that does not cross the outer surface of the convex spherical segment. For instance, the convex spherical segments **117a**, **117b** are bounded by an outer convex surface **319** (see **FIG. 3**) of the convex spherical segments **117a**, **117b**. As further shown in **FIG. 3**, the convex spherical segments **117a**, **117b** may be substantially solid although hollow convex spherical segments may be provided in further embodiments.

[0051] In some embodiments, the first convex spherical segment **117a** and/or the second convex spherical segment **117b** may be attached to the corresponding first and

second end portions **115a**, **115b**. For instance, as shown in **FIG. 3**, the first and second end portions **115a**, **115b** may each be provided with an exterior threaded portion **301** that can be threadedly received within an internally threaded bore **303** of the first and second convex spherical segments **117a**, **117b**. In some embodiments, the threaded connection may permit for removal of the first and second convex spherical segments **117a**, **117b** from the corresponding first and second end portions **115a**, **115b** of the cylindrical rod **111**. In further embodiments, the threaded connection may comprise a permanent connection, for example where the threaded connections are press fit with respect to one another. In further embodiments, an adhesive may be used to facilitate connection. In further embodiments, a threaded connection may not be provided. For instance, the first and second end portions **115a**, **115b** may be press fit within a bore of the convex spherical segments **117a**, **117b** without a threaded connection. In still further embodiments, the convex spherical segments **117a**, **117b** may be integrally formed with the cylindrical rod **111**. For example, a monolithic body of material may be machined (e.g., turned on a lathe) to form the cylindrical rod **111** and the convex spherical segments **117a**, **117b** from the same monolithic body. In additional further embodiments, the first and second convex spherical segments **117a**, **117b** may be welded to the corresponding end portions **115a**, **115b** of the cylindrical rod **111**.

[0052] In some embodiments, the first and second convex spherical segments **117a**, **117b** may be solid with a bore (e.g., internally threaded bore **303**) although the first and second convex spherical segments may comprise a hollow body in further embodiments. Providing the spherical segments as a hollow body can reduce the force to rotate the cylindrical rod **111** in use and therefore avoid unintended slipping between the outer peripheral surface **201** of the cylindrical rod **111** and the supported surface of the object (e.g., first major surface **105a** of the glass ribbon **103**). In some embodiments, the convex spherical segments **117a**, **117b** may comprise the same composition as the cylindrical rod **111**. In other embodiments, the convex spherical segments **117a**, **117b** may comprise one or combination of the exemplary materials discussed above for the cylindrical rod **111**. In yet other embodiments, the convex spherical segments **117a**, **117b** can comprise material with a coefficient of thermal expansion that has a difference from

the coefficient of thermal expansion for the material of the cylindrical rod **111** of about $10 \times 10^{-6} \text{ K}^{-1}$ or less, about $5 \times 10^{-6} \text{ K}^{-1}$ or less, or about $1 \times 10^{-6} \text{ K}^{-1}$ or less.

[0053] The first convex spherical segment **117a** and the second convex spherical segment **117b** can be configured to reduce frictional resistance to a rotational motion of the associated cylindrical rod **111** about the rotation axis **113**. As such, slipping between the outer peripheral surface **201** of the cylindrical rod **111** and the supported surface of the object (e.g., the supported first major surface **105a** of the glass ribbon **103**) can be reduced to help preserve the pristine first major surface **105a** of the glass ribbon **103** and, in some embodiments, to help reduce damage to the cylindrical rods **111**. In some embodiments, as discussed below, the first convex spherical segment **117a** and the second convex spherical segment **117b** can each be levitated on a fluid cushion **325** to help reduce friction during rotation of the cylindrical rod **111**.

[0054] Levitation of the first and second convex spherical segment **117a**, **117b** on a fluid cushion **325** (e.g., gas cushion) can be achieved in a wide variety of ways. In some embodiments, the support apparatus **101**, **501** can include a first area receiving a portion of the first convex spherical segment **117a** and a second area receiving a portion of the second convex spherical segment **117b**. The first and second areas that receive the first and second convex spherical segments **117a**, **117b** can be included within the support surface **119** (i.e., as an integral part of the support surface **119**). Alternatively, as shown in **FIG. 1**, the first and second areas can be provided by first and second bases **121a**, **121b** that may be provided for mounting relative to the support surface **119**. In such a manner, the support apparatus **101**, **501** may be customized and installed on a prefabricated support surface **119**. For example, as shown in **FIG. 1**, each first and second convex spherical segment **117a**, **117b** can be included with the corresponding first and second base **121a**, **121b** that can each be mounted to the support surface **119** at predetermined locations, depending on the particular application. The first and second base **121a**, **121b** can be secured to the support surface **119** via an attachment member **123**. In some embodiments, the attachment member **123** can be a snap, a clasp, a screw, a bolt, a buckle, a hook-and-loop fastener, a latch, a cable tie, a strap, a pin, or a peg.

[0055] In other embodiments, as shown schematically in **FIG. 2**, the support apparatus may also optionally be provided with one or more joint(s) **125** configured to

adjustably mount the corresponding base(s) **121a**, **121b** including the corresponding area **305** relative to a support surface **119** in a direction **124** of the rotation axis **113** of the cylindrical rod **111**. For example, as shown, the first base **121a** may be mounted relative to the support surface **119** with a joint **125** for translation of the first base **121a** relative to the support surface along the direction **124** of the rotation axis **113** of the corresponding cylindrical rod **111**. In addition, or alternatively, the second base **121b** may be mounted relative to the support surface **119** with a joint **125** for translation of the second base **121b** relative to the support surface **119** along the direction **124** of the rotation axis **113** of the corresponding cylindrical rod **111**. In such embodiments, the adjustable mounting of at least one base **121a**, **121b** relative to the support surface **119** with the joint(s) **125** to translate along the direction **124** of the rotation axis **113** of the cylindrical rod **111** can allow for adjustment of a distance between the first base **121a** and the second base **121b** to compensate for a thermal expansion or contraction of the cylindrical rod **111** along the rotation axis **113** as well as other parts of the support apparatus **101** due to temperature changes during use. In some embodiments, the joint(s) **125** can comprise a slider joint, a pin-slot joint, or an air bearing.

[0056] As shown in **FIG. 3**, the first and second base **121a**, **121b** can each include a corresponding area **305**, that receives a corresponding portion **311** of each of the first and second convex spherical segment **117a**, **117b**. As shown in **FIG. 3**, each of the first and second base **121a**, **121b** can include a corresponding lip **307** that circumscribes the area **305**. As shown in **FIG. 3**, a protruding portion **309** of the first and second convex spherical segment **117a**, **117b** can protrude above the corresponding lip **307** and outside of the area **305** while the corresponding portion **311** (e.g., lower corresponding portion) of each of the first and second convex spherical segment **117a**, **117b** can extend below the corresponding lip **307** and within the area **305**. In some embodiments, the portion of the outer convex surface **319** of the first and second convex spherical segment **117a**, **117b** extending below the corresponding lip can include an arc defined by an angle “**A**” between two vectors including the center point of the outer convex surface **319** and intersecting opposed outer peripheral points of a spherically concave recessed surface **313**. Rotation of the arc defined by the angle “**A**” about an axis extending through the center point of the outer convex surface **319** and through a central

axis of symmetry of the spherically concave recessed surface **313** can define a portion of the outer convex surface **319** that extends below the lip **307**. In some embodiments, the angle “A” can be within a range from about 10° to about 180°, such as from about 20° to about 175°, from about 45° to about 170°, or from about 70° to about 165°, although other angles may be provided. In some embodiments, the angle “A” may be about 180° or less to allow the first and second convex spherical segment **117a**, **117b** to be lifted vertically out of the area **305**.

[0057] Throughout the disclosure, a convex spherical segment is considered freely supported by the base if, during operation with the support apparatus with the cylindrical rod supporting the object while the convex spherical segments are supported by the air cushions, the convex spherical segment may be removed from the area **305** of the base **121a**, **121b** and away from the base **121a**, **121b**. In some embodiments, the convex spherical segment can be freely supported by the base in that, during operation with the support apparatus with the cylindrical rod supporting the object while the convex spherical segments are supported by the air cushions, there is no structure preventing the convex spherical segments from being lifted vertically out of the area **305** of the base **121a**, **121b** and vertically away from the base **121a**, **121b**. For example, as shown in **FIG. 2**, as each convex spherical segment **117a**, **117b** is freely supported by the corresponding base **121a**, **121b**, disassembly of the cylindrical rod **111** and corresponding convex spherical segments **117a**, **117b** may be achieved by simply lifting the cylindrical rod **111** vertically in a direction opposite gravity. As there is no structure prohibiting the convex spherical segments **117a**, **117b** from being lifted vertically out of the area **305**, disassembly of the cylindrical rod **111** can be simplified since there are no parts to be disconnected or removed before disassembly is possible. Furthermore, as the convex spherical segment **117a**, **117b** is configured to be freely supported by the corresponding base **121a**, **121b**, installation of the cylindrical rod **111** relative to the bases **121a**, **121b** is simplified because a functional unit may be provided by simply dropping the convex spherical segments **117a**, **117b** attached to a cylindrical rod **111** into the area **305** of the corresponding base **121a**, **121b** without further assembly to provide the ability of the support apparatus to function as intended.

[0058] Referring to **FIG. 3**, the shown convex spherical segment **117a**, **117b** is supported by a corresponding base **121a**, **121b** with an angle “**A**” of about 180° or less, which means that the convex spherical segment **117a**, **117b** can be lifted vertically out of the area **305**. In other embodiments, a clam-shell attachment top (e.g., cage) may be provided to allow the effective angle “**A**” to be about 180° or more while preventing inadvertent removal of the first and second convex spherical segment **117a**, **117b** from the corresponding area **305**. However, some embodiments may not trap the spherical segment, (e.g., with an effective angle “**A**” of about 180° or less) to simplify assembly and disassembly of the support apparatus **101**, **501** as well as to facilitate cleaning and/or cooling of the first and second convex spherical segments **117a**, **117b** and adjacent areas with the fluid stream **329** being fed into the gap **323**. Furthermore, in some embodiments, a reduced angle “**A**” can allow clearance of the diameter **203** of the cylindrical rod **111** as well as tilting between the position shown in solid lines in **FIG. 4** and the position shown in phantom lines in **FIG. 4** that, in some embodiments, may be limited by interference between the cylindrical rod **111** and associated lip **307** of the base. Furthermore, the angle “**A**” may be selected to be large enough to prevent inadvertent jumping of the convex spherical segment **117a**, **117b** out of the area **305** during operation.

[0059] As shown, a recessed surface **313** of the first and second base **121a**, **121b** can define corresponding area **305**. As shown, the area **305** of the first and second base **121a**, **121b** can be recessed below the lip **307** by a maximum depth **315**. The maximum depth **315** of the area **305** may be defined as the vertical distance between the lip **307** and the lowermost point of the recessed surface **313** of defining the area **305**. In some embodiments, the maximum depth **315** may be within a range from about 20% to about 100%, about 40% to about 90%, about 60% to about 90%, or about 80% of a radius **317** of the outer convex surface **319** of the corresponding first and second convex spherical segment **117a**, **117b**. The maximum depth **315** of the area **305** associated with the corresponding first and second base **121a**, **121b** associated with the convex spherical segments of each cylindrical rod **111** may be the same or different from one another.

[0060] As shown, the radius **317** of the outer convex surface **319** of the first convex spherical segment **117a** may be identical to the radius **317** of the outer convex

surface **319** of the second convex spherical segment **117b**. Although not shown, in some embodiments, the radius **317** of the outer convex surface **319** of the first convex spherical segment **117a** may be different than the radius **317** of the outer convex surface **319** of the second convex spherical segment **117b**. For instance, as shown, in some embodiments, the first convex spherical segment **117a** and corresponding first base **121a** may be an identical mirror image of the second convex spherical segment **117b** and the corresponding second base **121b**. Although not shown, in some embodiments, the first convex spherical segment **117a** and corresponding first base **121a** may not be an identical mirror image of the second convex spherical segment **117b** and the corresponding second base **121b**. For instance, the first convex spherical segment **117a** and corresponding first base **121a** may be a different size (e.g., a larger or smaller size) than the second convex spherical segment **117b** and corresponding second base **121b** or may have other characteristics that are not the same as the characteristics of the second convex spherical segment **117b** and/or corresponding second base **121b**.

[0061] The recessed surface **313** defining the area **305** can comprise a wide range of shapes and sizes. For instance, in some embodiments, the recessed surface can comprise a vertical circular cylinder side surface with a flat or otherwise shaped bottom surface. In other embodiments, the recessed surface can comprise an upwardly conical or frustoconical shape. In still other embodiments, the recessed surface may comprise an upwardly concave shape such as an upwardly ellipsoidal shape. In further embodiments, as shown in **FIG. 3**, the recessed surface can comprise a spherically concave recessed surface **313** of a spherically concave segment with a radius **321**. In some embodiments, as shown, the radius **321** of the spherically concave recessed surface **313** of the spherically concave segment can be greater than the radius **317** of the outer convex surface **319** of the corresponding first and second convex spherical segments **117a**, **117b** although the radius **321** can be equal to the radius **317** in further embodiments.

[0062] In embodiments where the radius **321** is greater than the radius **317**, the difference in radii can define a consistent gap **323** between the spherical convex surface **319** and the spherical concave recessed surface **313** of the spherically concave segment. When a fluid stream **329** is circulated, the consistent gap **323** can allow a fluid cushion **325** with a constant thickness (e.g., the difference between the radius **321** and the radius

317) to develop and levitate the first and second convex spherical segments **117a**, **117b** with respect to the first and second bases **121a**, **121b** and prevent physical contact therebetween to minimize friction and thereby minimize resistance to rotational motion of the associated cylindrical rod **111**. In some even further embodiments, the radius **317** of the outer convex surface **319** can be less than the radius **321** of the spherically concave recessed surface **313** of the spherically concave segment by about 20% or less, by about 15% or less, by about 10% or less, by about 5% or less, by about 2% or less, by about 1% or less. In further embodiments, the radius **317** of the outer convex surface **319** can be less than the radius **321** of the spherically concave recessed surface **313** of the spherically concave segment within a range from about 1% to about 20%, by from about 1% to about 15%, by from about 1% to about 10%, or by about 1% to about 5%.

[0063] The support apparatus **101**, **501** can further include a fluid port **327** in fluid communication with the area **305** of each of the first and second base **121a**, **121b**. In some embodiments, as shown in **FIG. 3**, the fluid port **327** may consist of a single orifice in the bottom of the recessed surface **313** of first and second base **121a**, **121b**. In other embodiments, the fluid port may comprise a plurality of orifices in the recessed surface **313**. In further embodiments, the plurality of orifices may be equally spaced along a cross-section of the recessed surface **313**. In other further embodiments, the plurality of orifices may be distributed across a plurality of cross-sections of the recessed surface **313**. In any of these further embodiments, the fluid stream **329** flowing through each orifice or a subset of the orifices may be controlled independently of the other orifices using a restrictor, a throttle, a valve, or a relay-controlled actuator. In some embodiments, the fluid port **327** may simply comprise an opening. In other embodiments, the fluid port **327** may comprise a one-way valve. In yet other embodiments, as shown in **FIG. 3**, the fluid port **327** may comprise a pocket compensated orifice, where a restriction portion, such as the illustrated plug **328** with a plug opening **330**. As shown, in some embodiments, the plug opening **330** includes a cross-sectional area along a plane perpendicular to the flow direction that is less than the cross-sectional area of the conduit **333** along a plane perpendicular to the flow area at a position upstream and downstream from the restriction portion. Indeed, in some embodiments, as shown in **FIG. 3**, the plug **328** with plug opening **330** may be press-fit

within the conduit **333** and recessed within the conduit **333** to a position upstream from the fluid port **327**. In such embodiments, pneumatic hammer instability can be avoided because a volume of a pocket **332** of the conduit behind the restriction portion (e.g., plug **328**) can be sufficient to dampen fluctuations in the fluid stream **329** caused by changes in the gap **323** or loading of the corresponding cylindrical rod **111**. The fluid port **327** can comprise one or more openings, as described above, through the respective recessed surface **313** to feed a fluid stream **329** into the gap **323** to develop and maintain the fluid cushion **325** to levitate the first and second convex spherical segments **117a**, **117b** relative to the corresponding base **121a**, **121b**. In some embodiments, a fluid supply such as the illustrated pressurized hose **331** can be coupled to a conduit **333** of each corresponding base **121a**, **121b** to deliver the fluid stream **329** to the fluid port **327** and thereafter to the area **305**.

[0064] In some embodiments, the fluid stream **329** can comprise a gas, for example, air, nitrogen, helium, argon, carbon dioxide, or a mix of the above gases. In such embodiments, the portion of the support apparatus **101** shown in **FIG. 3** may be referred to as an air bearing and the fluid cushion **325** within the gap **323** may be referred to as an air cushion even if the fluid stream **329** comprises a gas other than air. In such embodiments, the fluid may be readily compressible. As such, the fluid stream **329** can naturally cool structures associated with the gap **323** because a compressed gas from a fluid supply will expand as it is passed through the fluid port **327** and gap **323** proportional to the pressure change of the gas, as predicted by Boyle's law and the ideal gas law. In other embodiments, the fluid stream **329** can comprise a vapor, for example steam, or a supercritical fluid, for example supercritical carbon dioxide. In yet other embodiments, the fluid stream **329** can comprise a liquid, for example water. In some embodiments, the fluid supply can comprise a pump, a cannister, a cartridge, a boiler, a compressor, and/or a pressure vessel.

[0065] The fluid stream **329** circulated through the gap **323** can provide at least one of several technical benefits in addition to feeding and maintaining the fluid cushion **325**. For example, circulation of the fluid stream **329** may convectively cool the surfaces **319**, **313** defining to the gap **323**. Also, circulation of fluid stream **329** may perform a self-cleaning function that removes and/or prevents accumulation of undesired debris or

other particles from the outer convex surface **319** and in the vicinity of the gap **323**. In embodiments where the fluid stream **329** is compressible, the compressible fluid stream may, upon expansion, cool or provide temperature control to the surfaces **319**, **313** defining the gap **323**, as discussed above. Additionally, the compressible fluid stream may help to isolate the object (e.g., glass ribbon **103**) being supported from environmental vibrations. In embodiments where the fluid stream **329** has a low viscosity, there may be low friction and low heat generation upon rotation of the convex spherical segment **117a**, **117b** being supported by the fluid cushion **325**. For example, gas streams can comprise a dynamic viscosity of about 2×10^{-5} Pa s or less while water has a dynamic viscosity about 0.001 Pa s. In such embodiments, a low viscosity may be about 10^{-3} Pa s or less, about 10^{-4} Pa s or less, or about 2×10^{-5} Pa s or less. Low frictional forces for rotation of the convex spherical segment **117a** levitated on the fluid cushion **325** can reduce resistance to movement of the object (e.g., glass ribbon **103**) being supported, which will help reduce the incidence of sliding friction between the surface (e.g., first major surface **105a**) of the object (e.g., glass ribbon **103**) and the outer peripheral surface **201** of the cylindrical rod **111**.

[0066] Embodiments of methods of assembling the support apparatus **101**, **501** will now be described. As shown in **FIG. 1**, in one embodiment, the first and second bases **121a**, **121b** may be fastened with respect to the support surface **119**. For example, in some embodiments, all of the first bases **121a** may be aligned with respect to one another along a linear path and then attached to the support surface **119** with the attachment member **123** (e.g., a self-tapping screw or other fastener). Next, a first convex spherical segment **117a** may be inserted into the area **305** of each corresponding first base **121a**. Next, the second bases may be positioned in alignment with one another and with the corresponding second convex spherical segment **117b** positioned within the area **305** of each corresponding second base **121b**. As such, proper distancing between the corresponding pairs of bases **121a**, **121b** can be achieved since the first and second convex spherical segments **117a**, **117b** associated with the cylindrical rod **111** of the corresponding pair of bases **121a**, **121b** are already properly seated within the corresponding area **305**. Once the bases **121a**, **121b** are spaced with the first and second convex spherical segments **117a**, **117b** properly seated within the corresponding area

305, the second bases **121b** may be fastened to the support surface **119** with the attachment member **123**.

[0067] Furthermore, the geometry of the convex spherical segments **117a**, **117b** can tolerate a misalignment of one or more rotation axis **113** with respect to another rotation axis **113** without significantly impacting performance of the support apparatus **101**, **501**. For example, although a parallel alignment of the rotation axis **113** of each cylindrical rod **111** may be achieved in some embodiments, during installation, misalignment may nonetheless occur due to installation error or due to the characteristics of the support surface **119**. As such, a nonparallel arrangement between the rotation axis **113** of one or more cylindrical rods **111** may ultimately occur as shown in **FIGS. 4-5**. However, even with a misalignment, conveyance may still occur along the travel direction **109**. For instance, a slight misalignment may not significantly impact a rigid object (e.g., a rigid glass ribbon **103**). Furthermore, even significant misalignments may allow conveyance of a flexible object (e.g., flexible glass ribbon **103**) as the flexible ribbon would merely flex along any nonplanar conveyance path defined by the cylindrical rods **111**. Indeed, the rotation of the cylindrical rods **111** in the direction out the page in **FIG. 4** (i.e., in the **x-y** plane) is not impeded by the receiving portions when the lip **307** is lower than the cylindrical rod **111** when a fluid stream **329** creates an air cushion supporting the first and second convex spherical segments **117a**, **117b** of the cylindrical rod. Additionally, rotation of the cylindrical rod is not impeded by the receiving portion or lip **307** for slight or even moderate misalignments in the “**z**” direction as long as angle formed by a line connecting a first point at the center of the convex spherical segment **117a**, **117b** and a second point on the lip **307** furthest from the first point is greater than the vertical misalignment between the convex spherical end portions of the cylindrical rod **111**. Thus, the convex spherical segments **117a**, **117b** can simplify and reduce the expense of installing the support apparatus **101**, **501**, can allow installation of a support apparatus **101**, **501** on irregular support surfaces **119** and can help reduce frictional resistance to rotation of the cylindrical rods **111** during conveyance of the object (e.g., glass ribbon **103**).

[0068] In some embodiments, the cylindrical rod **111** can be pivotably adjusted about a first pivot axis of the first convex spherical segment **117a** and/or the second

convex spherical segment **117b** that can be perpendicular to the first rotation axis **113** of the first cylindrical rod **111**. In further embodiments, the first pivot axis may be in the “z” direction, as indicated by reference numbers **118a, 118b** in **FIGS. 1-2 and 4-5**. In some embodiments, the cylindrical rod **111** can be pivoted by an adjustment angle of about 10° to about 30°, and in some embodiments by an adjustment angle of about 10° to about 360°, about the first pivot axis (e.g., **118a, 118b**) of the corresponding convex spherical segment **117a, 117b**. In even further embodiments, the cylindrical rod **111** can be pivotably adjusted about a second pivot axis of the first convex spherical segment **117a** and/or the second convex spherical segment **117b** that can be perpendicular to both the first rotation axis **113** of the cylindrical rod **111** and the first pivot axis (e.g., **118a, 118b**). In such embodiments, the first pivot axis may be in the “x” direction, as indicated by reference numbers **120a, 120b** in **FIGS. 1-2 and 4-5**. In some embodiments, the cylindrical rod **111** can be pivoted by an adjustment angle of about 10° to about 30° about the second pivot axis (e.g., **120a, 120b**) before further pivoting is prevented by engagement between the cylindrical rod **111** and the base **121a, 121b**. For instance, as shown in **FIG. 4**, the cylindrical rod **111** can be pivoted about the second pivot axis (e.g., **120a**) of the first convex spherical segment **117a** by an adjustment angle of about 10° to about 30° before the interaction between the cylindrical rod **111** and the lip **307** of the base **121b** prevents further pivoting due to the contact therebetween as shown in dashed lines in **FIG. 4**.

[0069] In other embodiments, the first pivot axis may be in the “x” direction, as indicated by reference number **120a** in **FIGS. 1-2 and 4-5**. In some embodiments, the first cylindrical rod **111** can be pivoted by an adjustment angle of about 10° to about 30° about the first pivot axis (e.g., **120a, 120b**) of the first convex spherical segment **117a** and/or the second convex spherical segment **117b**. In some embodiments, the cylindrical rod **111** can be pivoted by an adjustment angle of about 10° to about 30° about the first pivot axis (e.g., **120a, 120b**) before further pivoting is prevented by engagement between the cylindrical rod **111** and the base **121a, 121b**. For instance, as shown again in **FIG. 4**, the cylindrical rod **111** can be pivoted about the first pivot axis (e.g., **120a**) of the first convex spherical segment **117a** by an adjustment angle of about 10° to about 30° before

the interaction between the cylindrical rod **111** and the lip **307** of the base **121b** prevents further pivoting due to the contact therebetween as shown in dashed lines in **FIG. 4**.

[0070] Some embodiments involve methods of supporting an object (e.g., glass ribbon **103**) with the support apparatus **101**, **501** discussed above. In some embodiments, the fluid stream **329** can be passed from a pressurized hose **331** through the conduit **333** and through the fluid port **327** into the area **305** of each corresponding base **121a**, **121b** to levitate the first and second convex spherical segment **117a**, **117b** on respective fluid cushions **325**. In some embodiments, the fluid stream **329** can comprise an air stream wherein the fluid cushions **325** comprise air cushions. In such embodiments, an object (e.g. glass ribbon **103**) can be supported by such the support apparatus **101**, **501** by engaging the first major surface **105a** of the object with the outer peripheral surface **201** of the cylindrical rod **111** so that the cylindrical rod **111** supports a weight of the object (e.g., a weight of the glass ribbon **103**). In further embodiments, the cylindrical rod **111** may rotate together with the associated first and second convex spherical segments **117a**, **117b** as the object (e.g., glass ribbon **103**) translates along the travel direction **109** and while the first and second convex spherical segments **117a**, **117b** are each levitated on respective fluid cushions **325**. In further embodiments, the first and second convex spherical segments **117a**, **117b** can be freely supported by the area **305** of the corresponding base **121a**, **121b** while the first cylindrical rod **111** is supporting an object (e.g., glass ribbon **103**) and the first and second convex spherical segments **117a**, **117b** are each levitated on respective fluid cushions. In other fluid embodiments, the first base **121a** may be translated in the direction of the first rotation axis **113** of the first cylindrical rod **111** relative to a support surface **119** (e.g., by way of using the joint **125**) to adjust the distance between the first base **121a** and the second base **121b** while the first cylindrical rod **111** is supporting an object (e.g., glass ribbon **103**) in order to compensate for thermal expansion or contraction of the first cylindrical rod **111**.

[0071] Various objects may be supported by the support apparatus **101**, **501** of the present disclosure. In some embodiments, as discussed above, the objects may comprise a glass ribbon **103** such as a glass sheet. Glass sheets are commonly used, for example, in display applications, for example liquid crystal displays (LCDs), electrophoretic displays (EPD), organic light emitting diode displays (OLEDs), plasma display panels

(PDPs), or the like. Glass sheets are commonly fabricated by a flowing molten glass to a forming body whereby a glass ribbon **103** may be formed by a variety of ribbon forming processes, for example, slot draw, float, down-draw, fusion down-draw, rolling, tube drawing, or up-draw. Edge portions of the glass ribbon **103** may be separated from a central portion of the glass ribbon **103** and/or the glass ribbon **103** may be periodically separated into individual glass sheets. The glass ribbon **103** may be supported with the support apparatus **101**, **501** prior to separating the central portion of the glass ribbon **103**, prior to separating a glass sheet from the glass ribbon **103**, or after separating the glass sheet from the glass ribbon **103**.

[0072] In some embodiments, the support apparatus **101**, **501** can support the glass ribbon **103** shortly after being formed prior to separation and/or after separation into a portion of glass ribbon **103** comprising a glass sheet. The support apparatus **101**, **501** can support the glass ribbon **103** to avoid introducing excess tension or slack into the glass ribbon before it has cooled sufficiently to hold its shape. Typically, the glass will be sufficiently cooled by the time it reaches the strain point, which is commonly defined as the temperature at which the viscosity of the glass ribbon **103** exceeds $10^{14.5}$ Poise. Support with the support apparatus **101**, **501** provides direct physical contact between the outer peripheral surface **201** of the cylindrical rods **111** and therefore does not require an air cushion to directly impact the glass ribbon **103**. Therefore, the direct contact provided by the cylindrical rods **111** can avoid use of air cushions to directly contact the glass ribbon **103** that may undesirably cool the glass ribbon **103** too quickly, in some embodiments. Furthermore, maintenance of the pristine surfaces of the major surfaces **105a**, **105b** of the glass ribbon **103** can be maintained, despite being physically contacted by the outer peripheral surface **201** of the cylindrical rods **111**, due to the reduced frictional resistance to rotation provided by the levitation of the first and second convex spherical segments **117a**, **117b** on the respective fluid cushions **325**.

[0073] The methods of supporting an object can be used for various applications. In some applications, the object supported may be a glass ribbon, a cut glass sheet, a silicon wafer, a plastic film, or a sheet of other material. In further applications, the object supported may be moved continuously or intermittently to convey the object.

[0074] As used herein the terms "the," "a," or "an," mean "at least one," and should not be limited to "only one" unless explicitly indicated to the contrary. Thus, for example, reference to "a component" includes embodiments having two or more such components unless the context clearly indicates otherwise.

[0075] As used herein, the term "about" means that amounts, sizes, formulations, parameters, and other quantities and characteristics are not and need not be exact, but may be approximate and/or larger or smaller, as desired, reflecting tolerances, conversion factors, rounding off, measurement error and the like, and other factors known to those of skill in the art. When the term "about" is used in describing a value or an end-point of a range, the disclosure should be understood to include the specific value or end-point referred to. Whether or not a numerical value or end-point of a range in the specification recites "about," the numerical value or end-point of a range is intended to include two embodiments: one modified by "about," and one not modified by "about." It will be further understood that the endpoints of each of the ranges are significant both in relation to the other endpoint, and independently of the other endpoint.

[0076] As used herein, the terms "comprising" and "including, and variations thereof, shall be construed as synonymous and open-ended, unless otherwise indicated.

[0077] The terms "substantial," "substantially," and variations thereof as used herein are intended to note that a described feature is equal or approximately equal to a value or description. For example, a "substantially planar" surface is intended to denote a surface that is planar or approximately planar. Moreover, as defined above, "substantially similar" is intended to denote that two values are equal or approximately equal. In some embodiments, "substantially similar" may denote values within about 10% of each other, for example within about 5% of each other, or within about 2% of each other.

[0078] The above embodiments, and the features of those embodiments, are exemplary and can be provided alone or in any combination with any one or more features of other embodiments provided herein without departing from the scope of the disclosure.

[0079] It will be apparent to those skilled in the art that various modifications and variations can be made to the present disclosure without departing from the spirit and

scope of the disclosure. Thus, it is intended that the present disclosure cover the modifications and variations of this disclosure provided they come within the scope of the appended claims and their equivalents.

What it claimed is:

1. A support apparatus comprising:

a first cylindrical rod comprising a first end portion and a second end portion, wherein the first cylindrical rod extends along a first rotation axis from the first end portion to the second end portion of the first cylindrical rod, and wherein the first end portion is provided with a first convex spherical segment and the second end portion is provided with a second convex spherical segment;

a first area configured to receive a portion of the first convex spherical segment with the first cylindrical rod pivotable about a first pivot axis of the first convex spherical segment that is perpendicular to the first rotation axis of the cylindrical rod;

a first fluid port in fluid communication with the first area;

a second area configured to receive a portion of the second convex spherical segment with the first cylindrical rod pivotable about a first pivot axis of the second convex spherical segment that is perpendicular to the first rotation axis of the cylindrical rod and parallel to the first pivot axis of the first convex spherical segment; and

a second fluid port in fluid communication with the second area.

2. The support apparatus of claim 1, wherein the first area is configured to receive the portion of the first convex spherical segment with the first cylindrical rod pivotable about a second pivot axis of the first convex spherical segment that is perpendicular to the first rotation axis of the cylindrical rod and to the first pivot axis of the first convex spherical segment, and the second area is configured to receive the portion of the second convex spherical segment with the first cylindrical rod pivotable about a second pivot axis of the second convex spherical segment that is parallel to the second pivot axis of the first convex spherical segment and perpendicular to the first rotation axis of the cylindrical rod and to the first pivot axis of the second convex spherical segment.

3. The support apparatus of claim 2, wherein the first area is configured to receive the portion of the first convex spherical segment with the first cylindrical rod pivotable by from about 10° to about 30° about the second pivot axis of the first convex spherical

segment, and the second area is configured to receive the portion of the second convex spherical segment with the first cylindrical rod pivotable by from about 10° to about 30° about the second pivot axis of the second convex spherical segment.

4. The support apparatus of any one of claims 1-3, wherein the first spherical segment is configured to be freely supported by the first area and the second spherical segment is configured to be freely supported by the second area.

5. The support apparatus of any one of claims 1-4, wherein the first area is configured to receive the portion of the first convex spherical segment with the first cylindrical rod pivotable by from about 10° to about 30° about the first pivot axis of the first convex spherical segment, and the second area is configured to receive the portion of the second convex spherical segment with the first cylindrical rod pivotable by from about 10° to about 30° about the first pivot axis of the second convex spherical segment.

6. The support apparatus of claim 5, wherein the first area is configured to receive the portion of the first convex spherical segment with the first cylindrical rod pivotable by 360° about the first pivot axis of the first convex spherical segment, and the second area is configured to receive the portion of the second convex spherical segment with the first cylindrical rod pivotable by 360° about the first pivot axis of the second convex spherical segment.

7. The support apparatus of any one of claims 1-6, further comprising a joint configured to adjustably mount the first area relative to a support surface in a direction of the first rotation axis of the first cylindrical rod.

8. The support apparatus of any of claims 1-7, wherein a first lip circumscribes the first area and a second lip circumscribes the second area.

9. The support apparatus of claim 8, wherein the first area is recessed below the first lip at a maximum depth of from about 20% to about 80% of a first radius of the first

convex spherical segment and the second area is recessed below the second lip at a maximum depth of from about 20% to about 80% of a second radius of the second convex spherical segment.

10. The support apparatus of any one of claims 1-9, wherein the first cylindrical rod comprises one or a combination of materials selected from the group consisting of: alumina, fused quartz, mullite, silicon carbide, and graphite.

11. The support apparatus of any one of claims 1-10, wherein the first area is defined by a first concave segment.

12. The support apparatus of claim 11, wherein the first concave segment comprises a first concave spherical segment.

13. The support apparatus of any one of claims 1-12, wherein the second area is defined by a second concave segment.

14. The support apparatus of claim 13, wherein the second concave segment comprises a second concave spherical segment.

15. The support apparatus of any one of claims 1-14, further comprising a second cylindrical rod.

16. The support apparatus of claim 15, wherein the first rotation axis of the first cylindrical rod is parallel to a second rotation axis of the second cylindrical rod.

17. The support apparatus of claim 15, wherein a first rotation axis of the first cylindrical rod extends at an acute angle relative to a second rotation axis of the second cylindrical rod.
18. The support apparatus of claim 17, wherein the first rotation axis and the second rotation axis do not extend along a common plane.
19. The support apparatus of any one of claims 16 and 17, wherein the first rotation axis and the second rotation axis extend along a common plane.
20. A method of supporting an object with the support apparatus of any one of claims 1-19, the method comprising:
- passing a first fluid stream through the first fluid port to form a first fluid cushion that levitates the first convex spherical segment;
 - passing a second fluid stream through the second fluid port to form a second fluid cushion that levitates the second convex spherical segment; and
 - engaging a surface of the object with an outer surface of the first cylindrical rod, wherein the first cylindrical rod supports a weight of the object while the first cylindrical rod is supported by the first fluid cushion and the second fluid cushion.
21. The method of supporting an object of claim 20, further comprising traversing the object along a travel direction, wherein the object drives the first cylindrical rod to rotate about the first rotation axis while the first cylindrical rod is supported by the first fluid cushion and the second fluid cushion.
22. The method of supporting an object of any one of claims 20 and 21, wherein the object comprises a glass ribbon.

23. The method supporting an object of any one of claims 20-22, wherein the object comprises a temperature within a range from about 500°C to about 1200°C.

24. The method of supporting an object of any one of claims 20-23, wherein the first spherical segment is freely supported by the first area and the second spherical segment is freely supported by the second area while supporting the object.

25. The method of supporting an object of any one of claims 20-24, further comprising adjusting a distance between the first area and the second area while supporting the object.

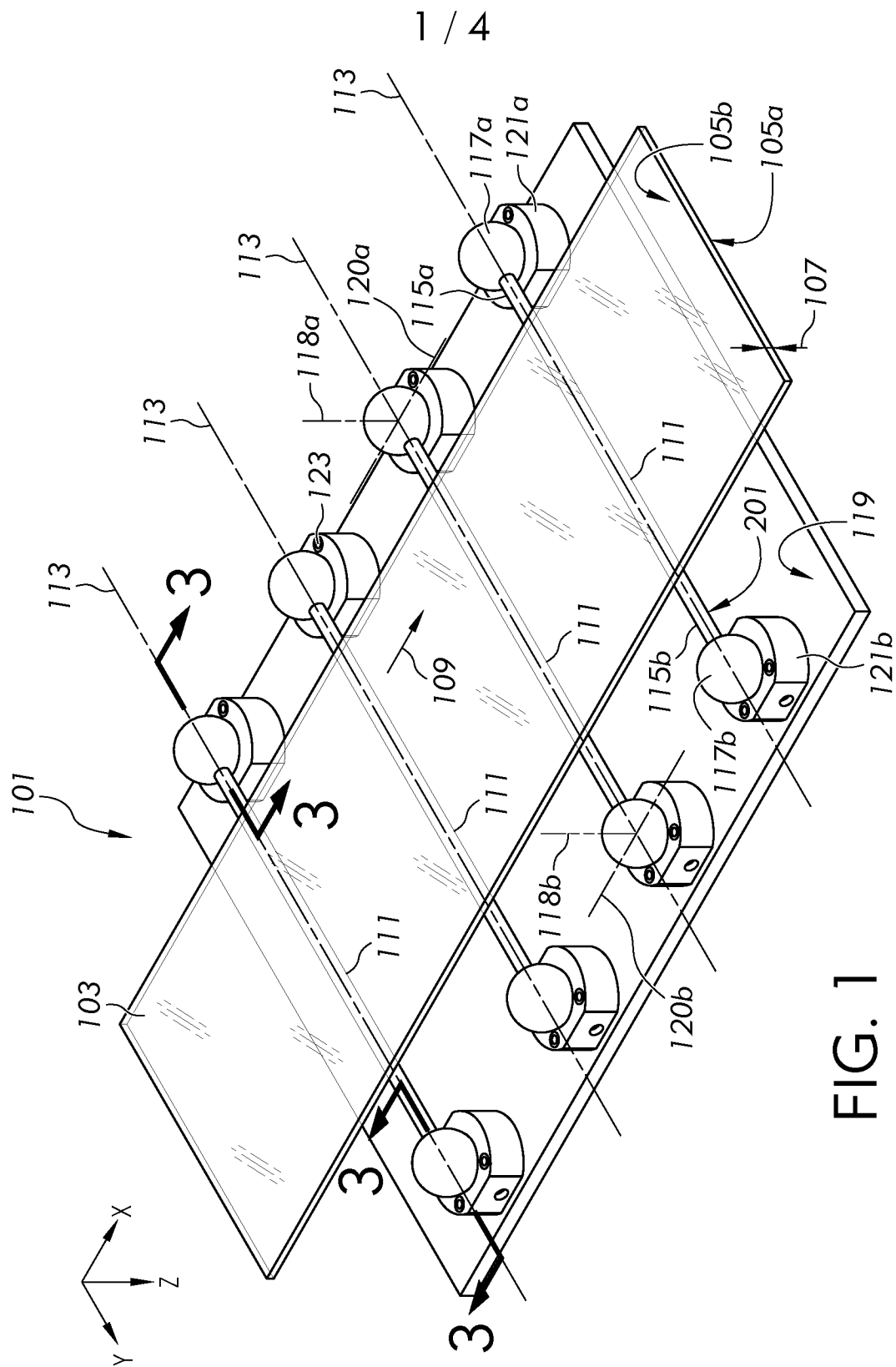


FIG. 1

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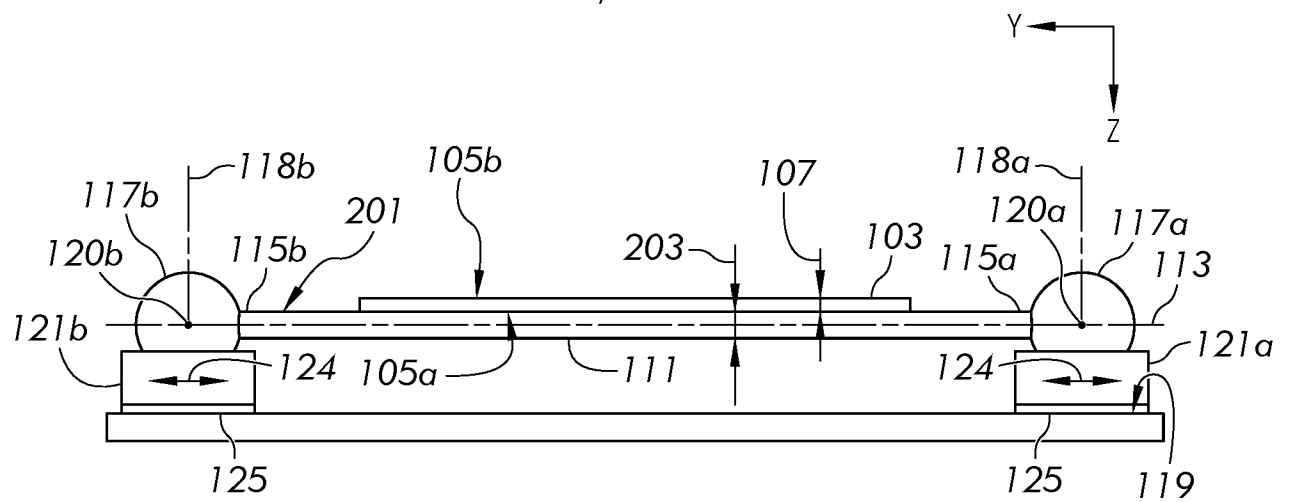


FIG. 2

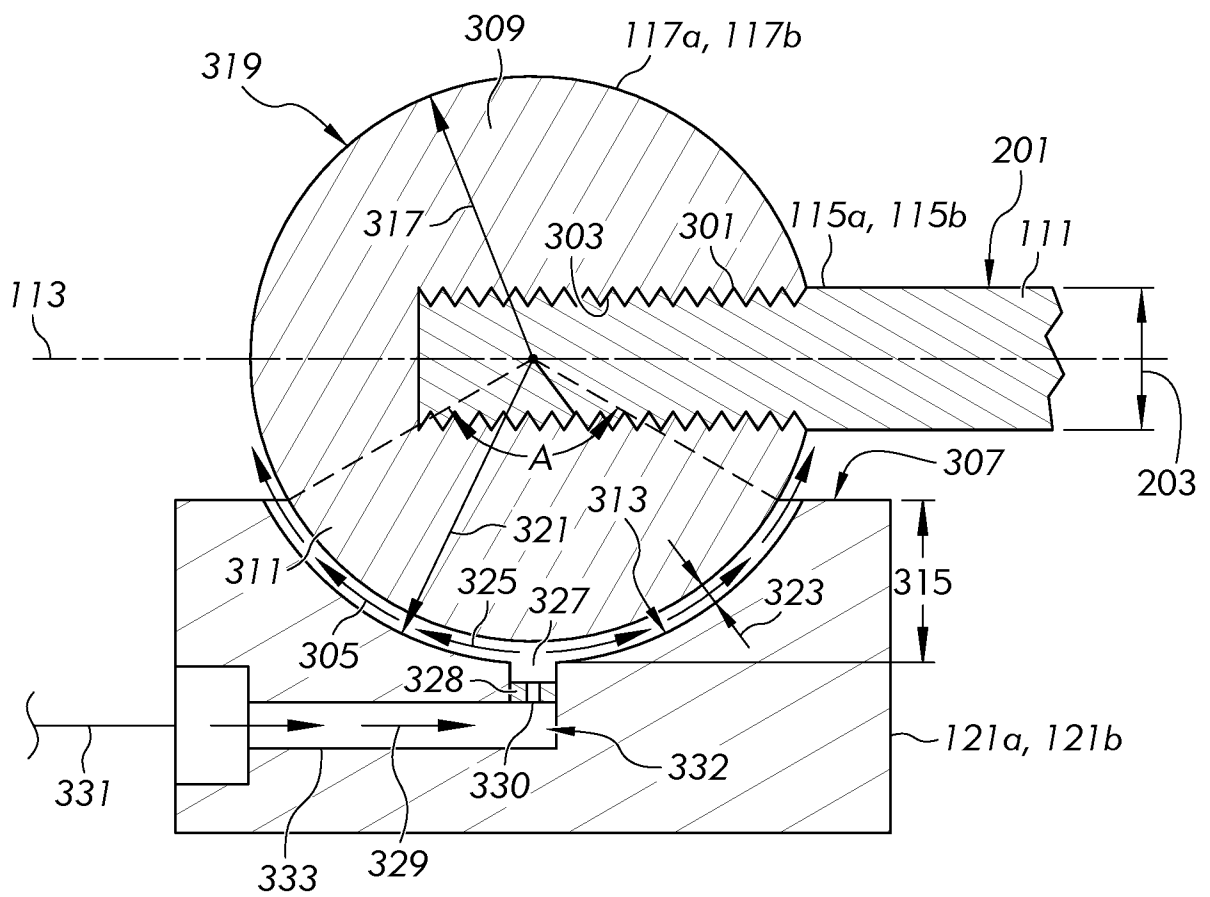


FIG. 3

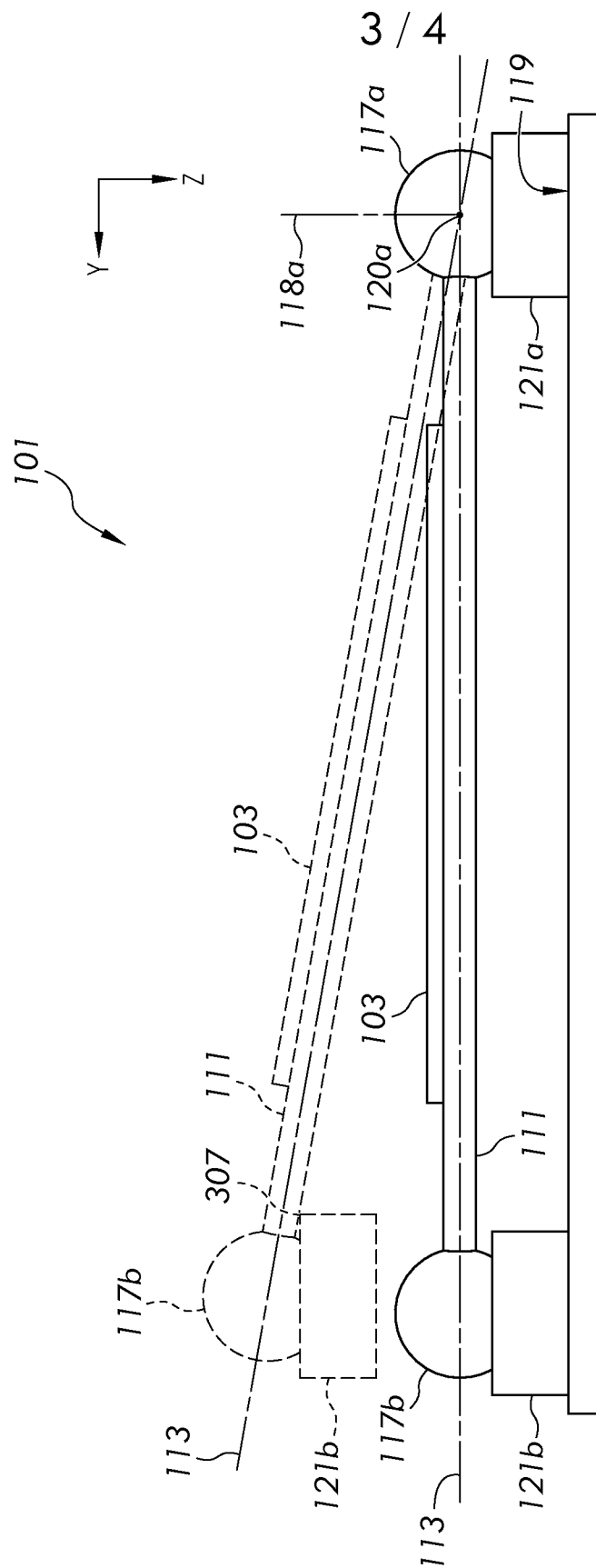


FIG. 4

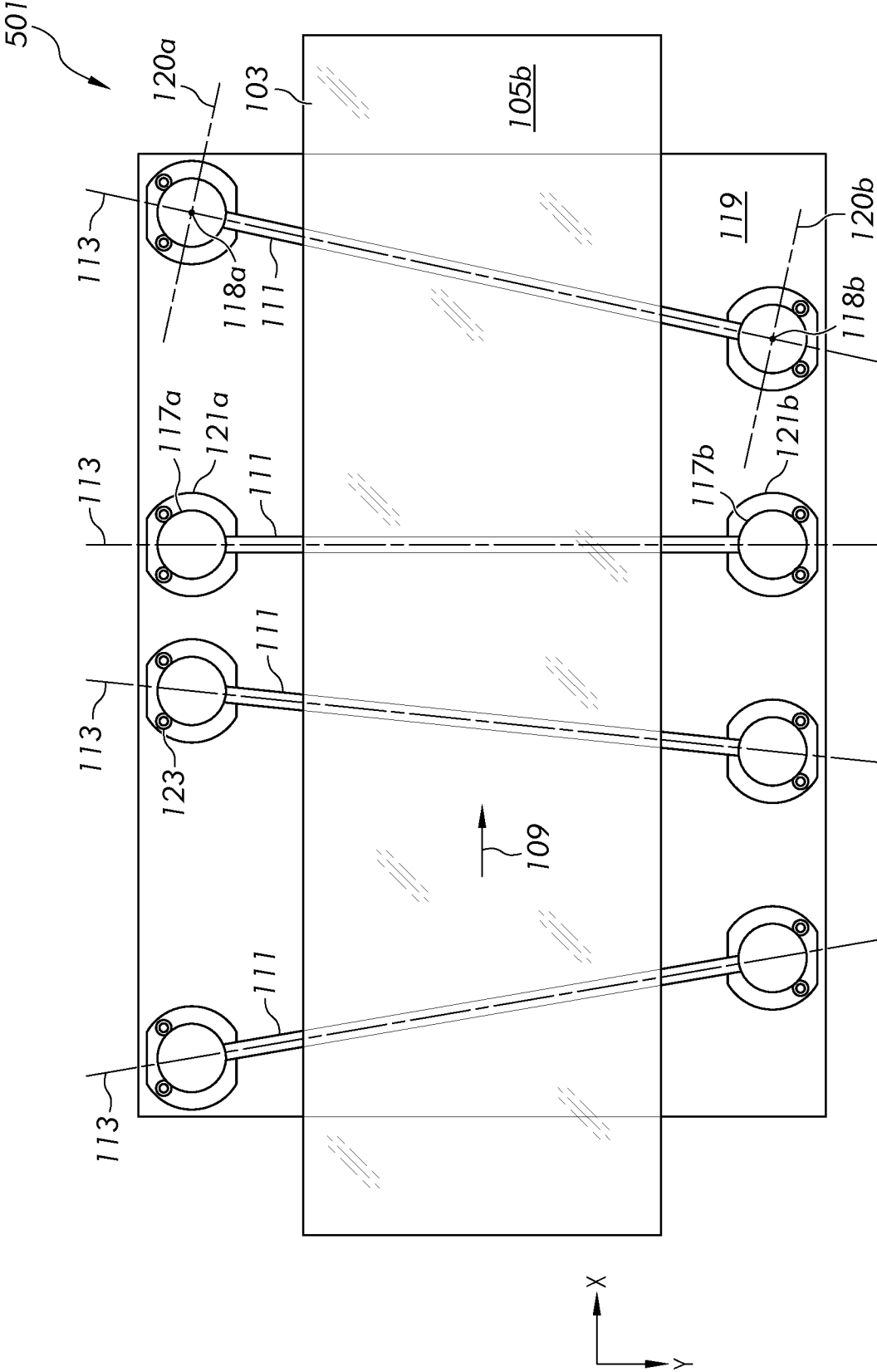


FIG. 5

INTERNATIONAL SEARCH REPORT

International application No.
PCT/US2019/047835**A. CLASSIFICATION OF SUBJECT MATTER****B65G 49/06(2006.01)i, B65G 13/00(2006.01)i, C03B 35/18(2006.01)i**

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

B65G 49/06; B65G 023/04; B65G 13/00; B65G 39/09; B65G 49/07; C03B 35/18; F16C 39/04; H01L 21/68

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Korean utility models and applications for utility models

Japanese utility models and applications for utility models

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

eKOMPASS(KIPO internal) & keywords: support apparatus, glass ribbon, fluid, spherical segment, rotation, pivot

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	KR 10-0706182 B1 (DMS CO., LTD.) 11 April 2007	1-6, 8-9, 11-21, 24
Y	See paragraphs [0016]-[0026], [0033]-[0036], claims 1-4, and figures 1-6.	7, 10, 22-23, 25
Y	JP 2015-024942 A (NIPPON ELECTRIC GLASS CO., LTD.) 05 February 2015 See paragraphs [0006], [0037], [0041] and figures 2-4.	7, 22-23, 25
Y	KR 10-0927998 B1 (CDS CO., LTD.) 24 November 2009 See paragraph [0033] and figure 1.	10
A	US 3874749 A (MANIAK, DOMINIC J.) 01 April 1975 See claims 1-2 and figures 1-3.	1-25
A	US 2001-0037929 A1 (BOND, JR. et al.) 08 November 2001 See paragraph [0017] and figures 1, 3.	1-25



Further documents are listed in the continuation of Box C.



See patent family annex.

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"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

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Date of the actual completion of the international search

04 December 2019 (04.12.2019)

Date of mailing of the international search report

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Name and mailing address of the ISA/KR

International Application Division

Korean Intellectual Property Office

189 Cheongsa-ro, Seo-gu, Daejeon, 35208, Republic of Korea

Facsimile No. +82-42-481-8578

Authorized officer

LEE, Eon Su

Telephone No. +82-42-481-8539



INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No.

PCT/US2019/047835

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		US 6622853 B2	23/09/2003