

ABSTRACT

The present technique relates to an image processing device and method capable of suppressing a decrease in encoding efficiency. The image processing device includes: a predictive vector generating unit that generates a predictive vector of a current parallax vector of a current block used in prediction using correlation in a parallax direction using a reference parallax vector referred when generating a predictive motion vector, when encoding the current parallax vector; and a difference vector generating unit that generates a difference vector between the current parallax vector and the predictive vector generated by the predictive vector generating unit. The present disclosure can be applied to an image processing device.

CLAIMS

1. An image processing device comprising:
 - a predictive vector generating unit that generates
 - 5 a predictive vector of a current parallax vector of a current block used in prediction using correlation in a parallax direction using a reference parallax vector referred when generating a predictive motion vector, when encoding the current parallax vector; and
 - 10 a difference vector generating unit that generates a difference vector between the current parallax vector and the predictive vector generated by the predictive vector generating unit.
- 15 2. The image processing device according to claim 1, wherein
 - the predictive vector generating unit generates a predictive vector of the current parallax vector using a parallax vector of a co-located block included in a co-
 - 20 located picture of a time different from a current picture of the same view as a current view.
3. The image processing device according to claim 2, wherein
 - 25 the predictive vector generating unit sets the co-located block to be available when a property of a vector of the current block is identical to a property of a vector of the co-located block.
- 30 4. The image processing device according to claim 3, wherein

the property of the vector is a type of a vector,
and

the predictive vector generating unit sets the co-located block to be available when the property of the
5 vector of the current block is a parallax vector and the property of the vector of the co-located block is a parallax vector.

5. The image processing device according to claim 3,
10 wherein

the predictive motion vector generating unit determines the property of the vector of the current block and the property of the vector of the co-located block using POC (Picture Order Count) that indicates an
15 output order of pictures.

6. The image processing device according to claim 5,
wherein

the predictive motion vector generating unit
20 determines the property of the vector of the current block and the property of the vector of the co-located block using the POC of the current picture, the POC of a current reference picture referred from the current picture, the POC of the co-located picture, and the POC
25 of a co-located reference picture referred from the co-located picture.

7. The image processing device according to claim 6,
wherein

30 the predictive motion vector generating unit determines that the property of the vector of the current

block and the property of the vector of the co-located block are parallax vectors when the POC of the current picture is identical to the POC of the current reference picture referred from the current picture and the POC of
5 the co-located picture is identical to the POC of the co-located reference picture referred from the co-located picture.

8. The image processing device according to claim 2,
10 wherein

the predictive vector generating unit sets the co-located block to be not available when the property of the vector of the current block is different from the property of the vector of the co-located block.

15

9. The image processing device according to claim 8,
wherein

the property of the vector is a type of a reference picture, and

20

the predictive vector generating unit sets the co-located block to be not available when the type of the reference picture of the current block is different from the type of the reference picture of the co-located block.

25 10. The image processing device according to claim 8,
wherein

the property of the vector is a type of a reference picture, and

the predictive vector generating unit skips a
30 process of searching a reference index when the type of the reference picture of the current block is a long

reference type and the type of the reference picture of the co-located block is a long reference type.

11. The image processing device according to claim 1,
5 wherein

the predictive vector generating unit generates a predictive vector of the current parallax vector using a parallax vector of a reference block included in a picture of the same time as a current picture of a view
10 different from the current view.

12. The image processing device according to claim 1,
wherein

the predictive vector generating unit scales the
15 reference parallax vector based on a positional relationship between a current picture and a reference picture referred when generating a predictive motion vector to generate a predictive vector of the current parallax vector.

20

13. The image processing device according to claim 1,
wherein

the predictive vector generating unit generates a predictive vector of the current motion vector using a
25 reference motion vector referred when generating a predictive motion vector, when encoding the current motion vector of the current block used in prediction using correlation in a temporal direction, and

the difference vector generating unit generates a
30 difference vector between the current motion vector and the predictive vector generated by the predictive vector

generating unit.

14. The image processing device according to claim 13,
wherein

5 the predictive vector generating unit generates the
predictive vector of the current motion vector using a
motion vector of the reference block included in a
picture of the same time as the current picture of a view
different from the current view.

10

15. The image processing device according to claim 13,
wherein

 the predictive vector generating unit generates a
predictive vector of the current motion vector using a
15 motion vector of a reference block included in a picture
of a time different from the current picture of the same
view as the current view.

16. The image processing device according to claim 15,
20 wherein

 the predictive vector generating unit scales the
reference motion vector based on a positional
relationship between the current picture and a reference
picture referred when generating a predictive motion
25 vector to generate a predictive vector of the current
motion vector.

17. The image processing device according to claim 1,
wherein

30 the predictive vector generating unit generates the
predictive vector using a vector of a block located at

the same position as the current block in a state where a position of a pixel of a picture of the same time as the current picture of a view different from the current view is shifted.

5

18. The image processing device according to claim 17, wherein

the predictive vector generating unit sets a shift amount of the image according to a parallax vector of a neighboring region of the current block.

10

19. The image processing device according to claim 18, wherein

the predictive vector generating unit uses a parallax vector in an X-direction, of the neighboring block in which the value of a parallax vector in a Y-direction is not zero as the shift amount.

15

20. The image processing device according to claim 18, wherein

20

the predictive vector generating unit uses a value calculated from parallax vectors in an X-direction, of a plurality of the neighboring blocks in which the value of a parallax vector in a Y-direction is not zero as the shift amount.

25

21. The image processing device according to claim 20, wherein

the predictive vector generating unit uses an average value or a median value of the parallax vectors in the X-direction, of the plurality of the neighboring

30

blocks in which the value of the parallax vector in the Y-direction is not zero as the shift amount of the image.

22. The image processing device according to claim 17,
5 wherein

the predictive vector generating unit sets the shift amount of the image according to a global parallax vector.

10 23. An image processing method of an image processing device, for allowing the image processing device to execute:

generating a predictive vector of a current parallax vector of a current block used in prediction
15 using correlation in a parallax direction using a reference parallax vector referred when generating a predictive motion vector, when encoding the current parallax vector; and

generating a difference vector between the current
20 parallax vector and the generated predictive vector.

24. An image processing device comprising:

a predictive vector generating unit that generates a predictive vector of a current parallax vector of a
25 current block used in prediction using correlation in a parallax direction using a reference parallax vector referred when generating a predictive motion vector, when decoding the current parallax vector; and

an arithmetic unit that performs an operation of
30 adding the predictive vector generated by the predictive vector generating unit to a difference vector between the

current parallax vector and the predictive vector to reconstruct the current parallax vector.

25. An image processing method of an image processing
5 device, for allowing the image processing device to execute:

generating a predictive vector of a current
parallax vector of a current block used in prediction
using correlation in a parallax direction using a
10 reference parallax vector referred when generating a
predictive motion vector, when decoding the current
parallax vector; and

performing an operation of adding the generated
predictive vector to a difference vector between the
15 current parallax vector and the predictive vector to
reconstruct the current parallax vector.

26. An image processing device comprising:

a predictive vector generating unit that sets a co-
20 located block to be not available when a type of a
reference picture of a current block is different from a
type of the reference picture of a co-located block
included in a co-located picture of a different time from
a current picture when encoding a current motion vector
25 of the current block used in prediction using correlation
in a temporal direction and generates a predictive vector
of the current motion vector using a reference motion
vector referred when generating a predictive motion
vector; and

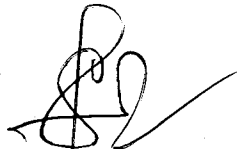
30 a difference vector generating unit that generates
a difference vector between the current motion vector and

the predictive vector generated by the predictive vector generating unit.

27. An image processing method of an image processing
5 device, for allowing the image processing device to execute:

setting a co-located block to be not available when
a type of a reference picture of a current block is
different from a type of the reference picture of a co-
10 located block included in a co-located picture of a
different time from a current picture when encoding a
current motion vector of the current block used in
prediction using correlation in a temporal direction, and
generating a predictive vector of the current motion
15 vector using a reference motion vector referred when
generating a predictive motion vector; and
generating a difference vector between the current
motion vector and the generated predictive vector.

Dated this December 23, 2013



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FIG. 1

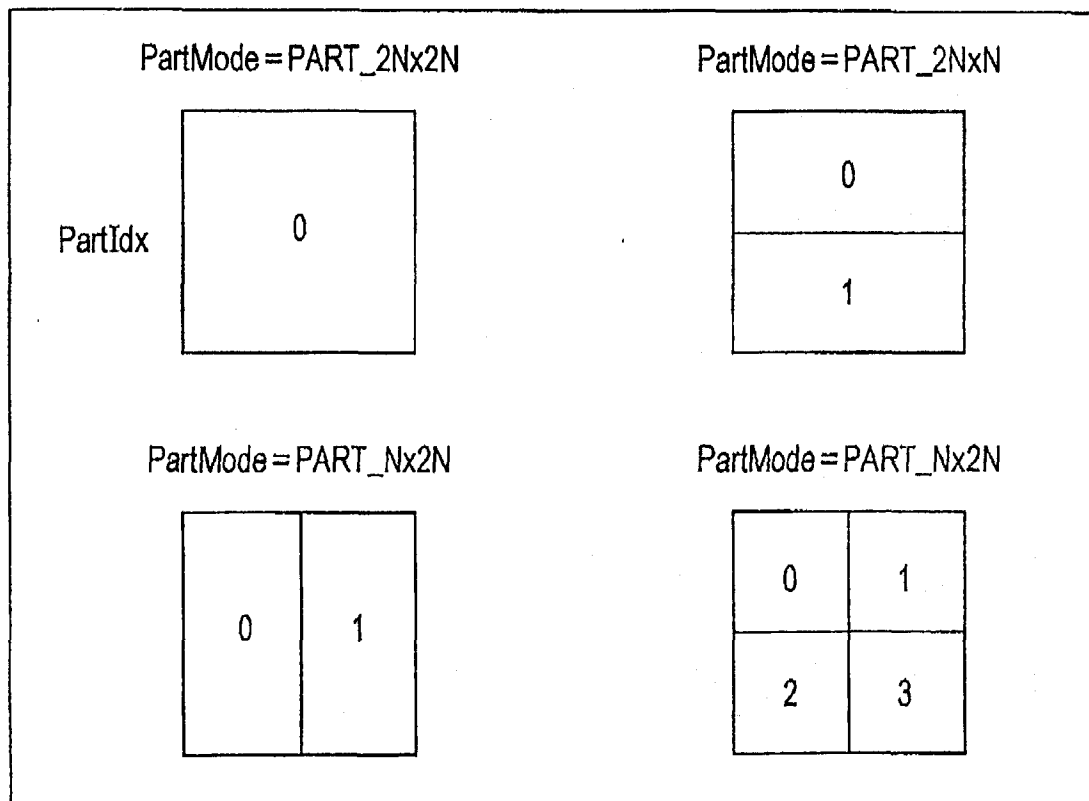


FIG. 2

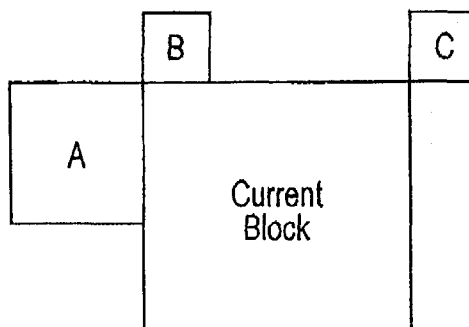
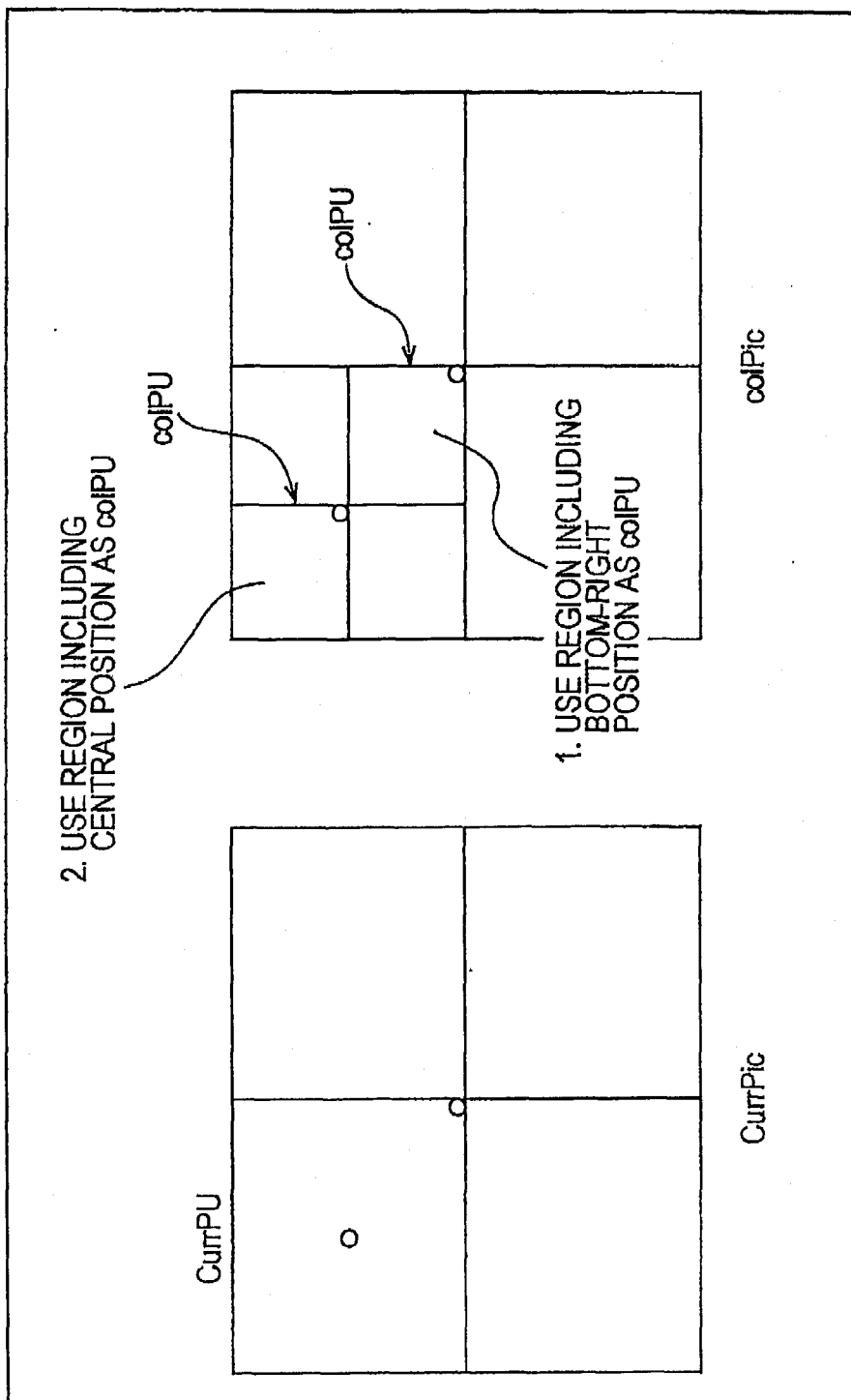


FIG. 3

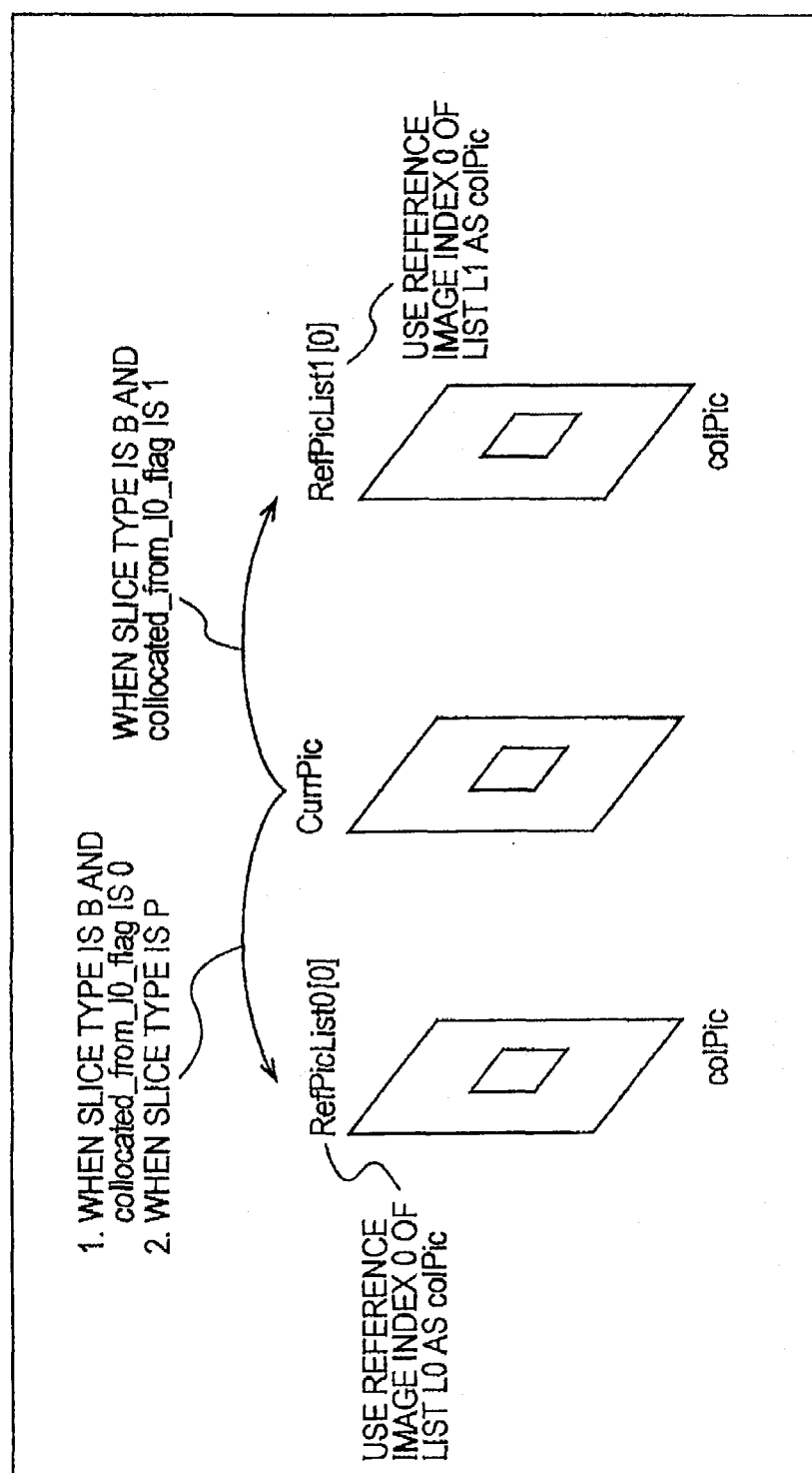
refIdxLX	refIdxLA	refIdxLB	refIdxLC
refIdxLA	x	-1	-1
refIdxLB	-1	x	-1
refIdxLC	x	-1	-1
refIdxLA	x	x	-1
refIdxLA	x	-1	x
refIdxLB	-1	x	x
0	-1	-1	-1
min(refIdxLB,refIdxLC)	-1	x	y
min(refIdxLA,refIdxLC)	x	-1	y
min(refIdxLA,refIdxLB)	x	-1	y
min(min(refIdxLA,refIdxLB),refIdxLC)	x	y	z

FIG. 4



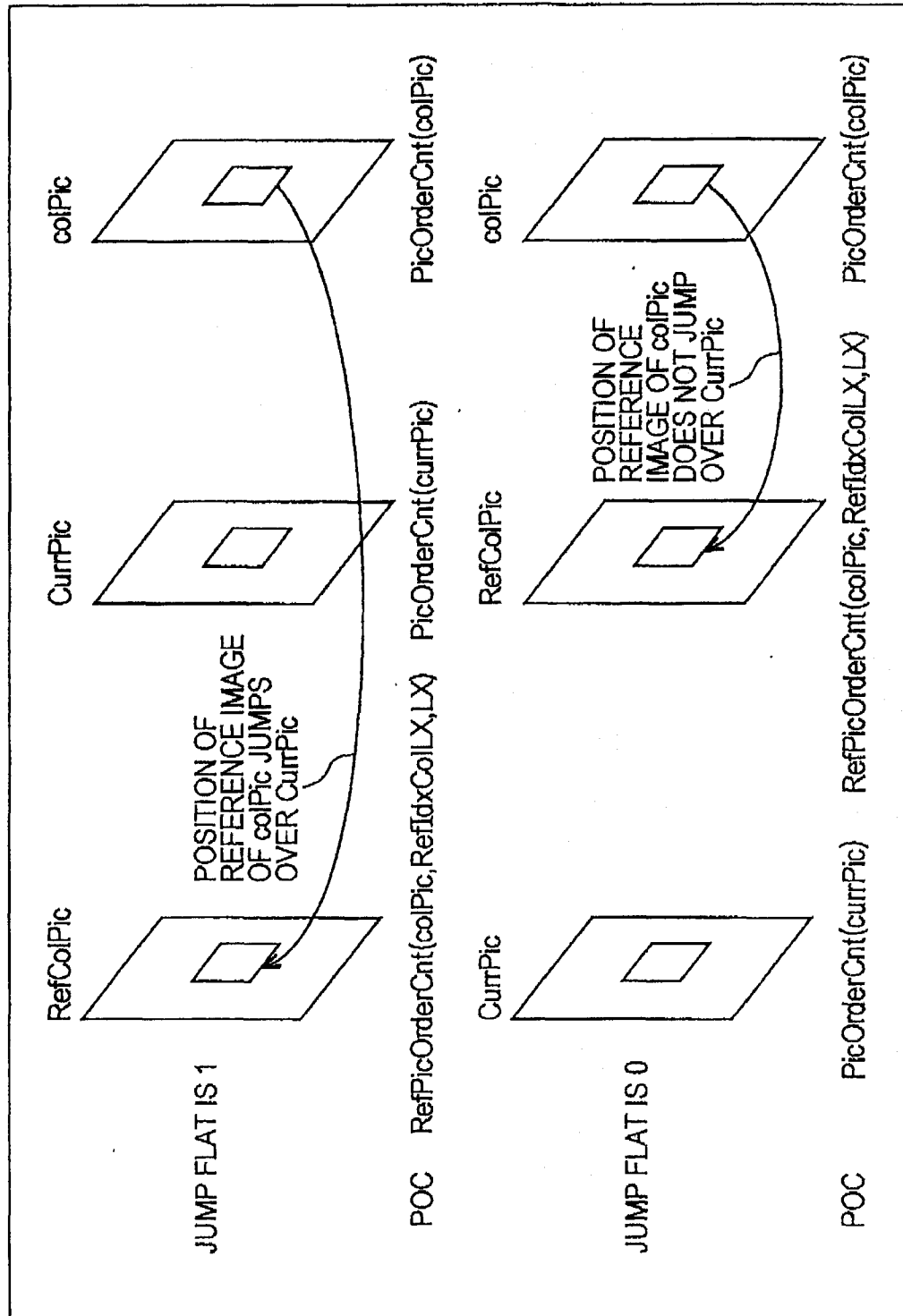
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FIG. 5



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FIG. 6



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FIG. 7

A = TEMPORAL DISTANCE BETWEEN TARGET PICTURE AND PICTURE THAT TARGET PICTURE REFERS TO
 B = TEMPORAL DISTANCE BETWEEN PICTURE USED IN TEMPORAL CORRELATION AND PICTURE THAT TEMPORAL CORRELATION REGION REFERS TO

mvCol = MOTION VECTOR OF TEMPORAL CORRELATION REGION
 pmv = PREDICTIVE VECTOR OF TARGET REGION

WHEN A AND B ARE IDENTICAL pmv = mvCol
 WHEN A AND B ARE NOT IDENTICAL pmv = mvCol * A/B

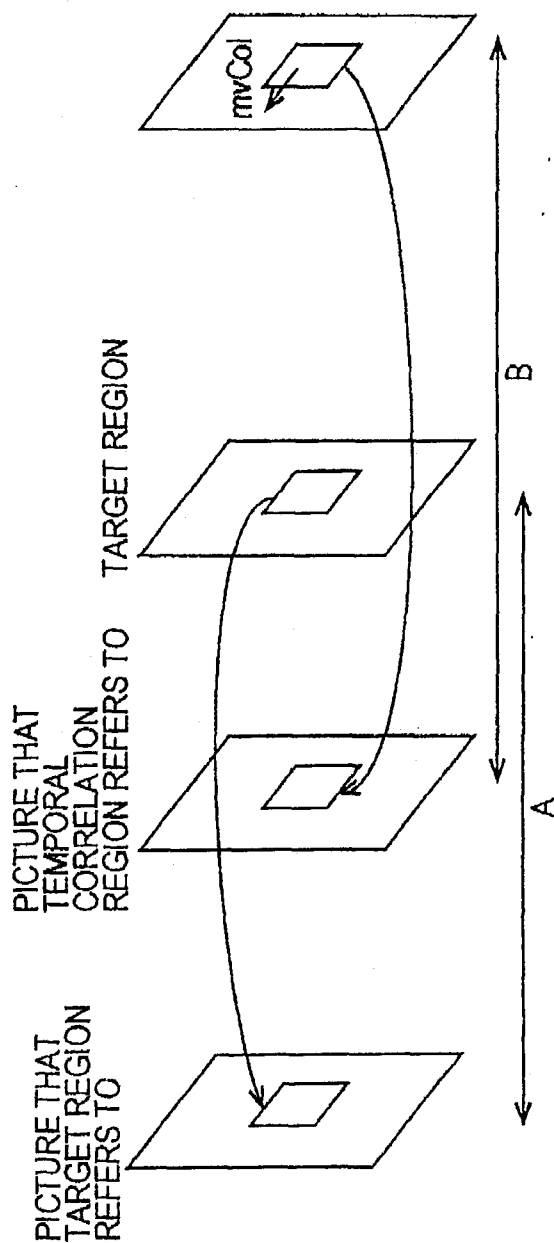
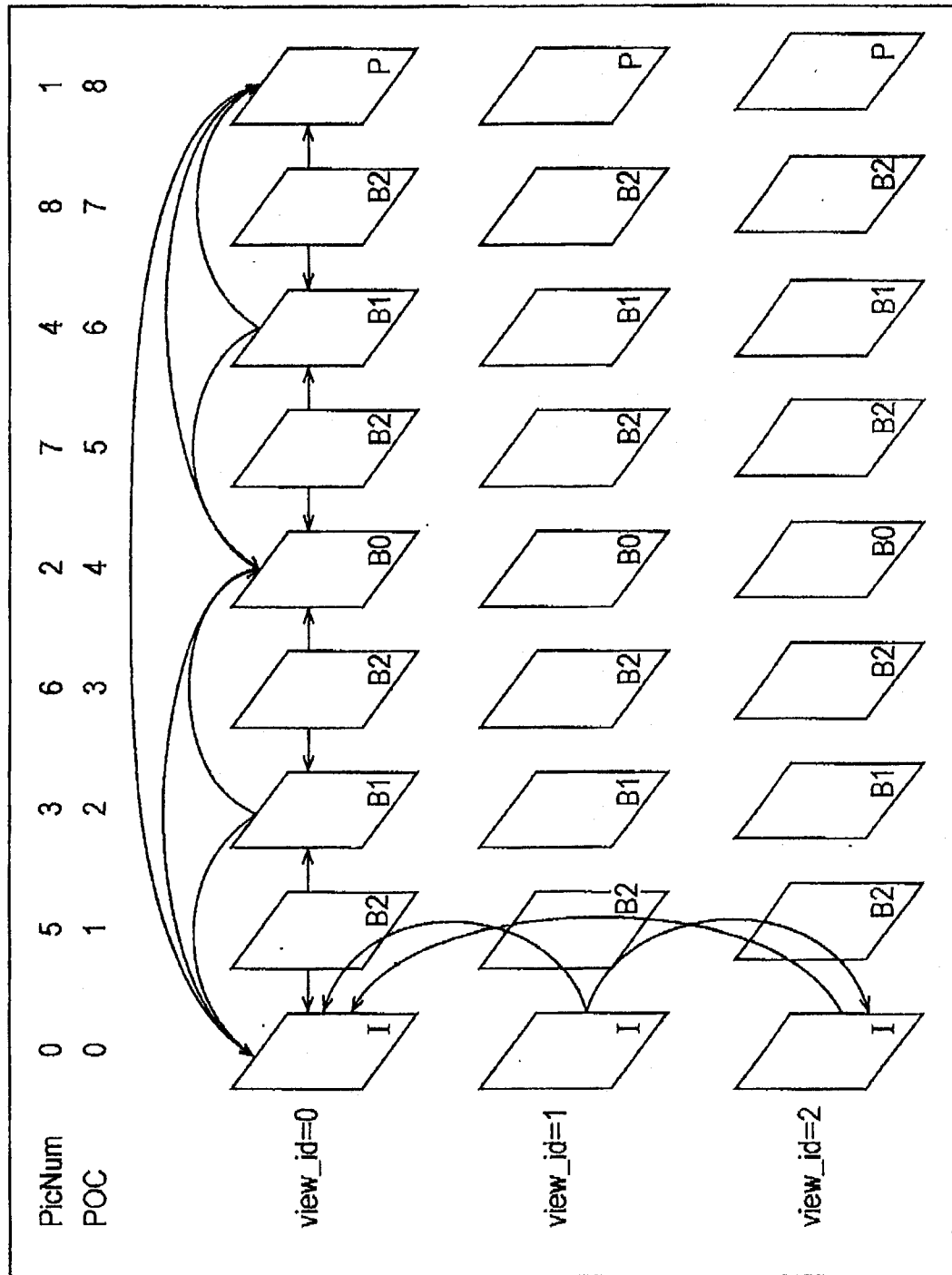
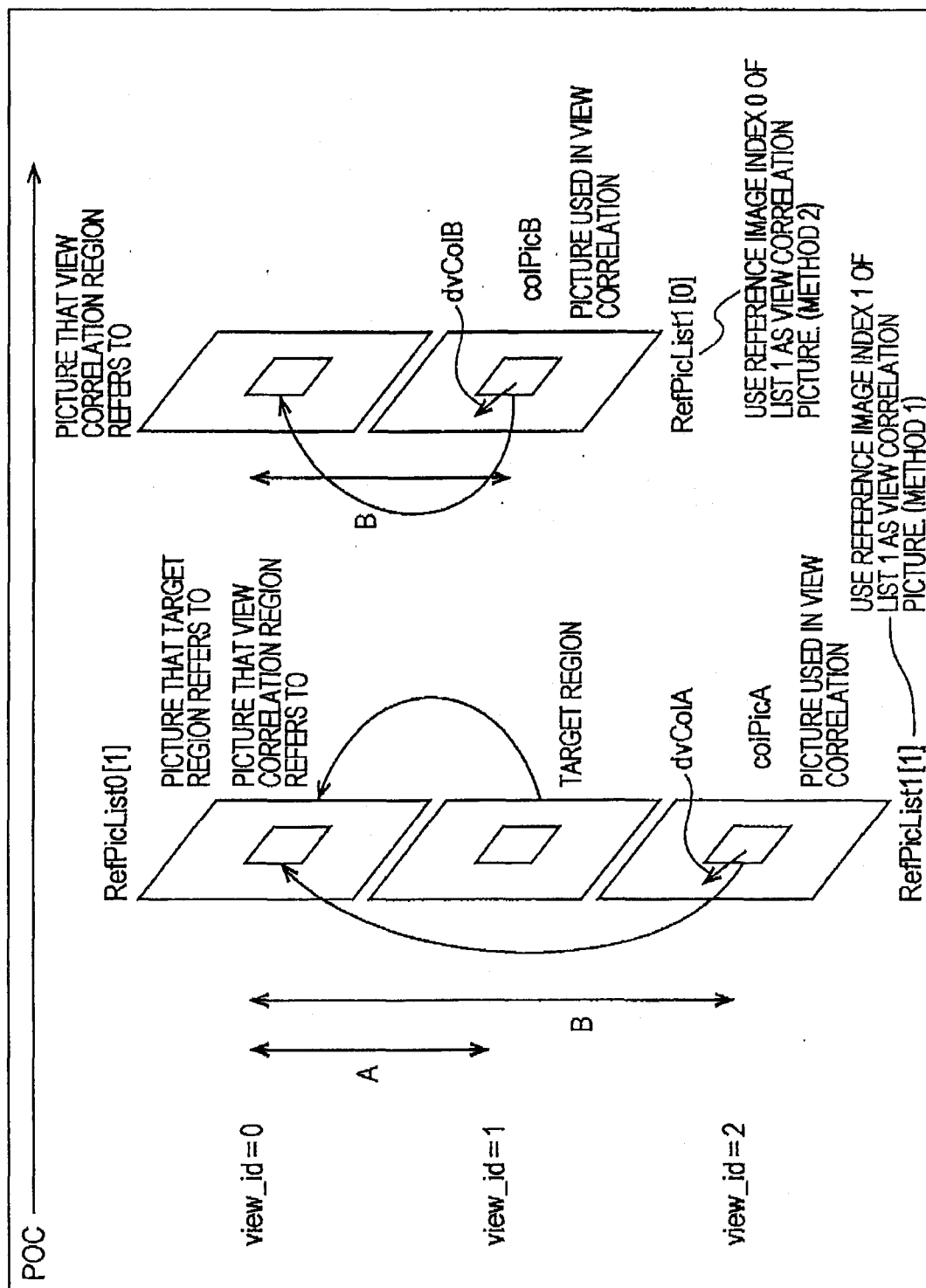


FIG. 8



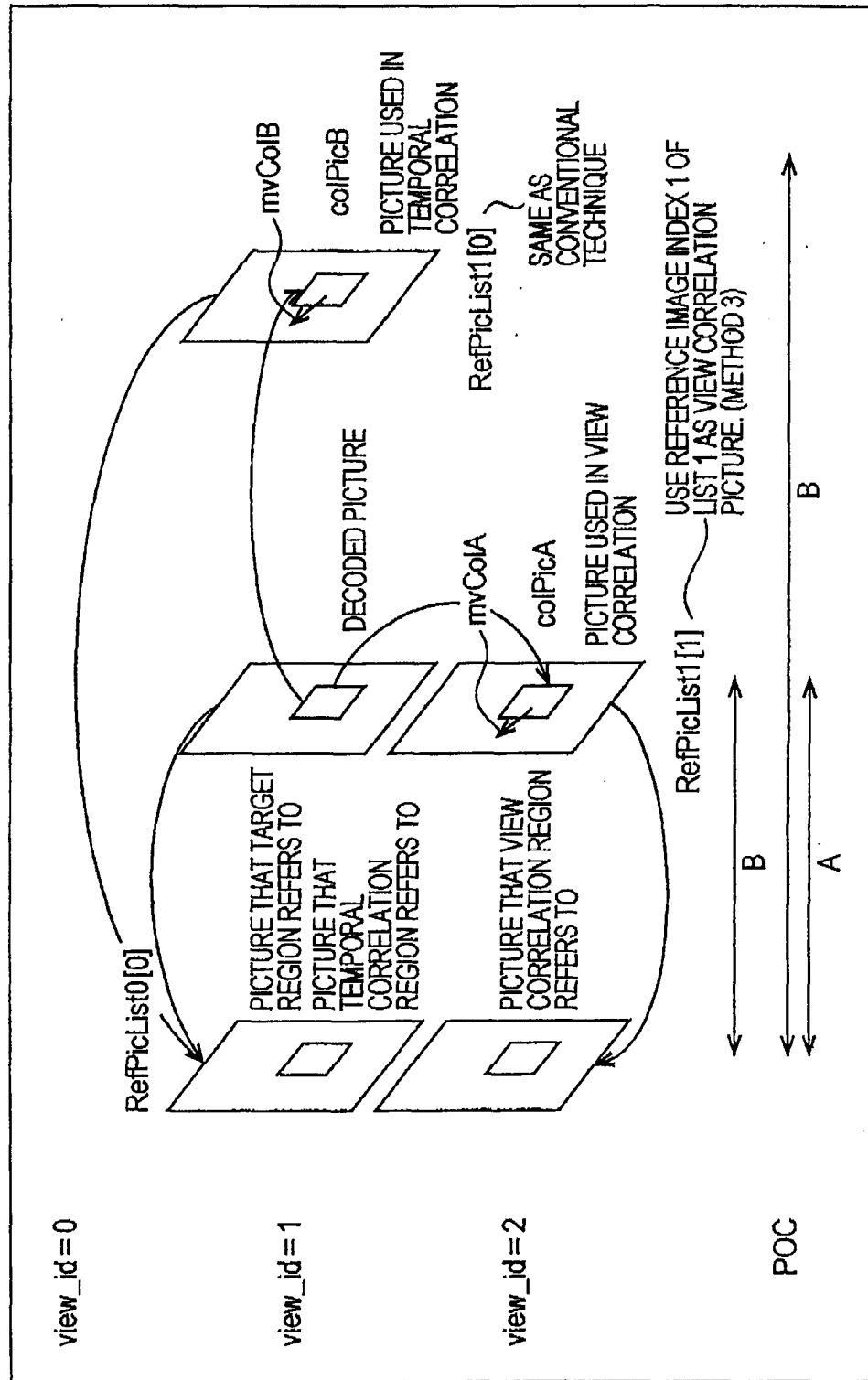
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FIG. 9

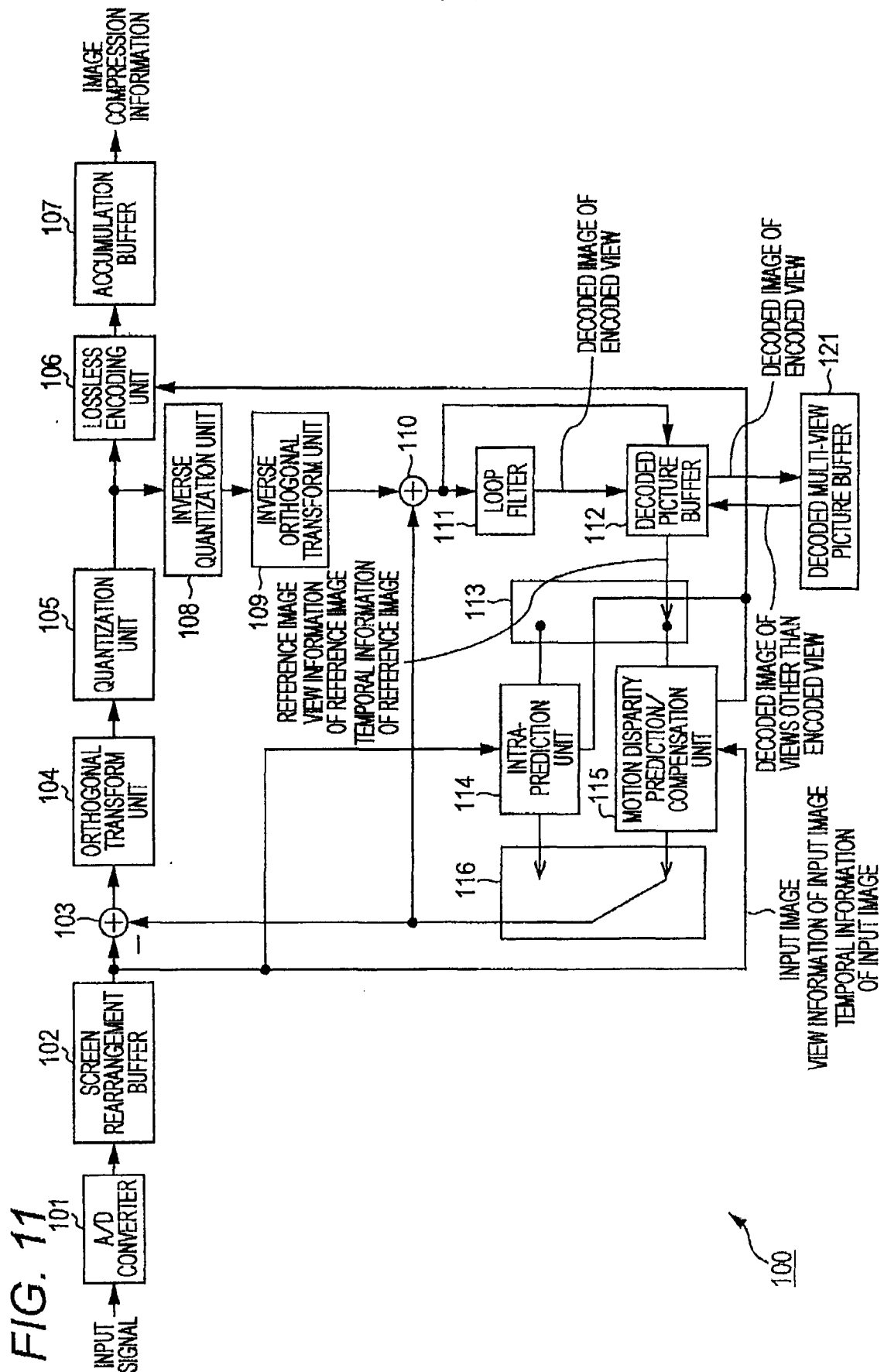


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FIG. 10

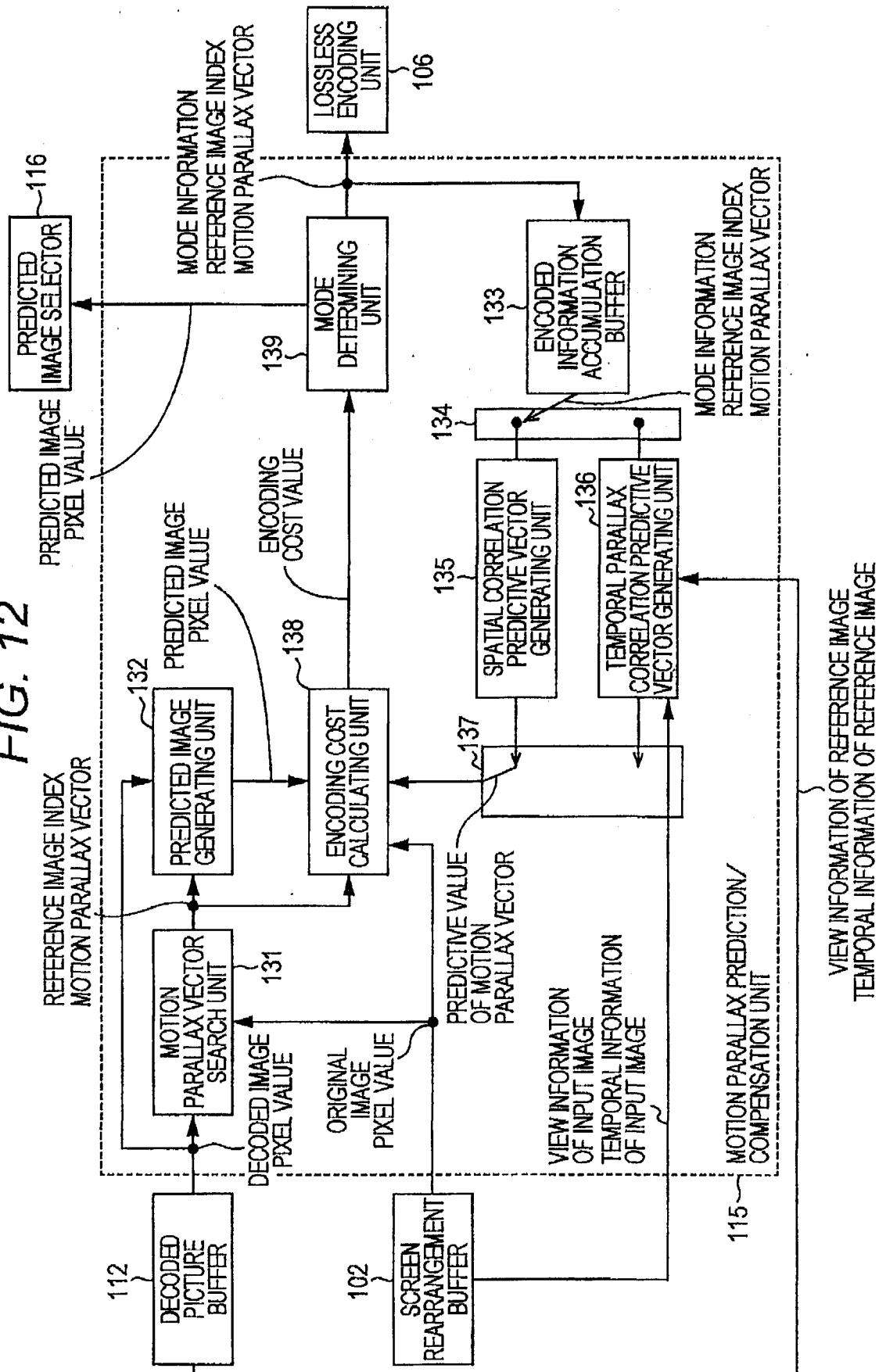


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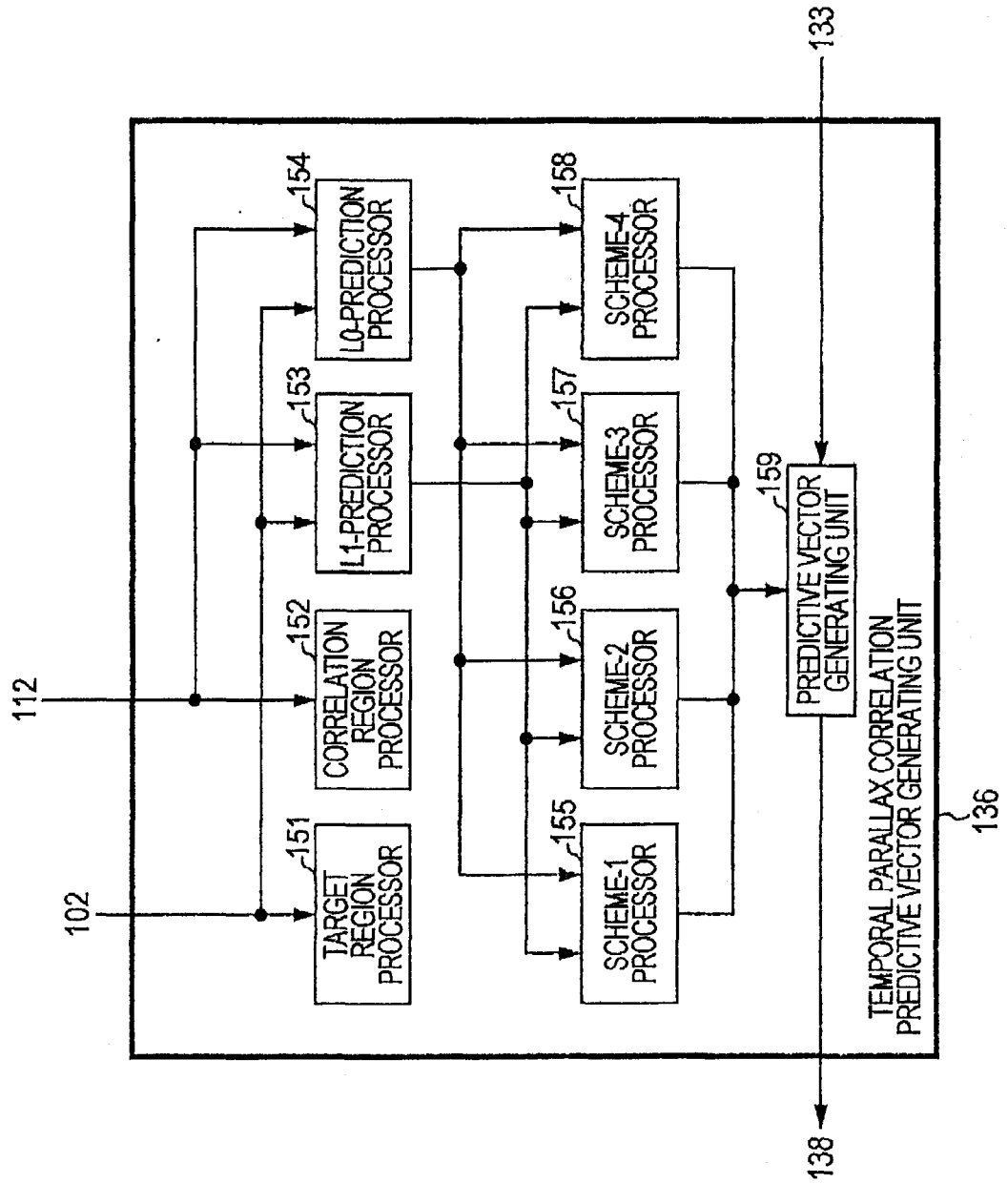
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FIG. 12



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FIG. 13



))

FIG. 14

TARGET REGION		REFERENCE IMAGE OF TARGET REGION		CORRELATION REGION		REFERENCE IMAGE OF CORRELATION REGION		
VIEW ID	POC	VIEW ID	POC	VIEW ID	POC	VIEW ID	POC	
A	E	C	E	B	E	D	E	SCHEME 1
A	D	B	D	A	E	C	E	SCHEME 2
A	C	A	D	B	C	B	E	SCHEME 3
A	B	A	C	A	D	A	E	SCHEME 4

FIG. 15

Availability decision using POC

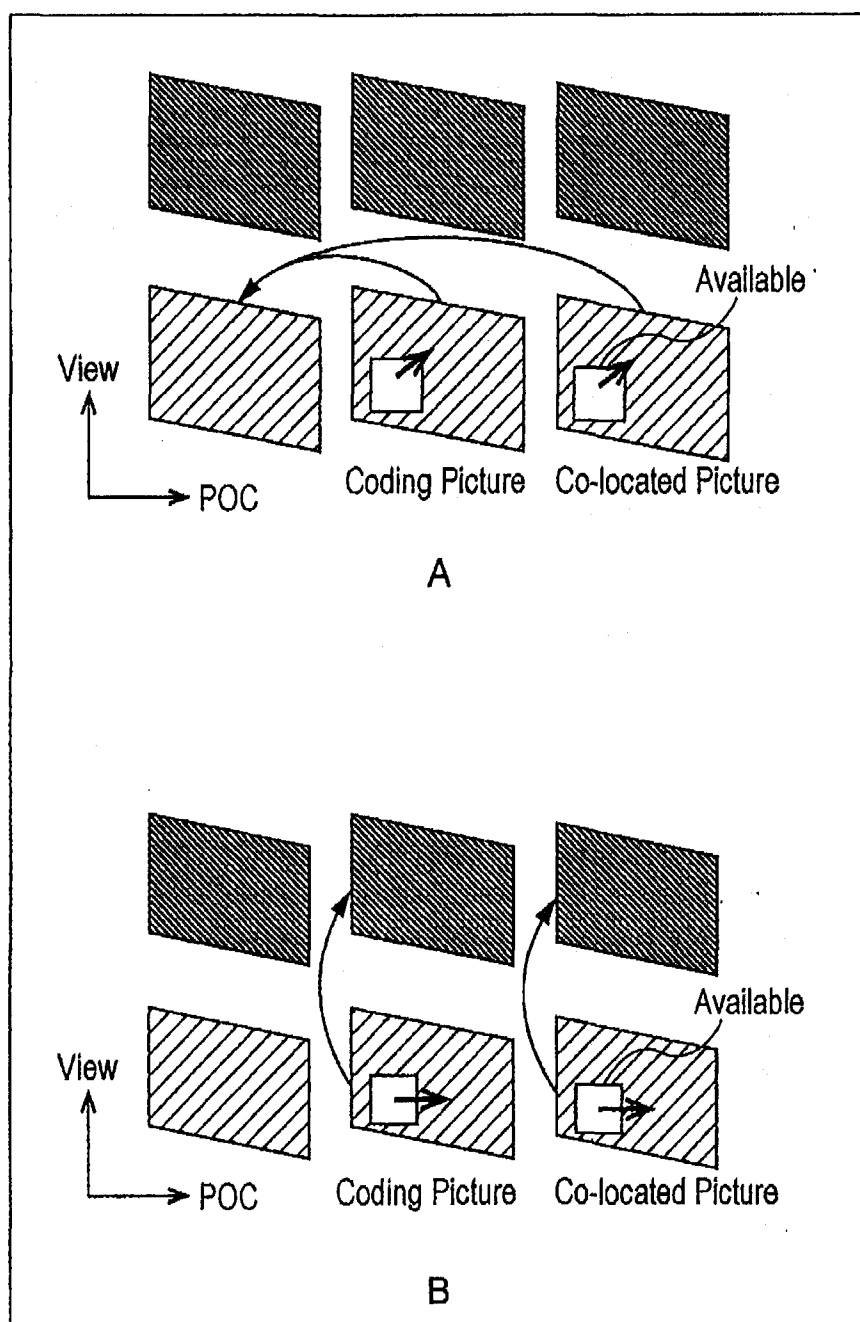
1. $(\text{CurrPOC} \neq \text{CurrRefPOC}) \ \&\& \ (\text{ColPOC} \neq \text{ColRefPOC})$
 $\Rightarrow$ Both coding vector and co-located vector are motion vector.
2. $(\text{CurrPOC} == \text{CurrRefPOC}) \ \&\& \ (\text{ColPOC} == \text{ColRefPOC})$
 $\Rightarrow$ Both coding vector and co-located vector are Inter-view vector.

CurrPOC: POC of current picture
 ColPOC: POC of co-located picture
 CurrRefPOC: POC of picture referred from current picture
 ColRefPOC: POC of picture referred from co-located picture

Availability of co-located vector	Coding vector	Co-located vector
Available	Motion vector	Motion vector
Not-available	Motion vector	Inter-view vector
Not-available	Inter-view vector	Motion vector
Available	Inter-view vector	Inter-view vector

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FIG. 16



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FIG. 17

seq_parameter_set_rbsp0 [	Descriptor
profile_idc	u(8)
reserved_zero_8bits /* equal to 0 */	u(8)
level_idc	u(8)
seq_parameter_set_id	ue(v)
pic_width_in_luma_samples	u(16)
pic_height_in_luma_samples	u(16)
bit_depth_luma_minus8	ue(v)
bit_depth_chroma_minus8	ue(v)
log2_max_frame_num_minus4	ue(v)
pic_order_cnt_type	ue(v)
if(pic_order_cnt_type == 0)	
log2_max_pic_order_cnt_lsb_minus4	ue(v)
else if(pic_order_cnt_type == 1)	
delta_pic_order_always_zero_flag	u(1)
offset_for_non_ref_pic	se(v)
num_ref_frames_in_pic_order_cnt_cycle	ue(v)
for(i = 0; i < num_ref_frames_in_pic_order_cnt_cycle; i++)	
offset_for_ref_frame[i]	se(v)
]	
max_num_ref_frames	ue(v)
gaps_in_frame_num_value_allowed_flag	u(1)
log2_min_coding_block_size_minus3	ue(v)
log2_diff_max_min_coding_block_size	ue(v)
log2_min_transform_block_size_minus2	ue(v)
log2_diff_max_min_transform_block_size	ue(v)
max_transform_hierarchy_depth_inter	ue(v)
max_transform_hierarchy_depth_intra	ue(v)
adaptive_loop_filter_enabled_flag	u(1)
cu_qp_delta_enabled_flag	u(1)
num_views	
for(i=0; i < num_views; i++){	
view_id[i]	
num_ref_views_l0[i]	
for(j=0; j < num_ref_views_l0[i]; j++){	
ref_view_id_l0[i][j]	
num_ref_views_l1[i]	
for(j=0; j < num_ref_views_l1[i]; j++){	
ref_view_id_l1[i][j]	
}	
rbbsp_trailing_bits ()	
}	

TOTAL NUMBER OF VIEWS

ID FOR IDENTIFYING
VIEWSNUMBER OF PARALLAX
PREDICTIONS IN LIST L0ID OF VIEW REFERRED
TO IN PARALLAX
PREDICTION IN LIST L0NUMBER OF PARALLAX
PREDICTIONS IN LIST L1ID OF VIEW REFERRED
TO IN PARALLAX
PREDICTION IN LIST L1

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FIG. 18

slice_header() {	Descriptor
first_tb_in_slice	ue(v)
entropy_slice_flag	u(1)
if(!entropy_slice_flag) {	
slice_type	ue(v)
pic_parameter_set_id	ue(v)
frame_num	u(v)
view_id	u(v)
if(!idrPicFlag)	
idr_pic_id	ue(v)
if(pic_order_cnt_type == 0)	
pic_order_cnt_lsb /*	u(v)
if(slice_type == P slice_type == B) {	
num_ref_idx_active_override_flag	u(1)
if(num_ref_idx_active_override_flag) {	
num_ref_idx_l0_active_minus1	ue(v)
if(slice_type == B)	
num_ref_idx_l1_active_minus1	ue(v)
}	
}	
ref_pic_list_modification()	
ref_pic_list_combination()	
if(nal_ref_idc != 0)	
dec_ref_pic_marking()	
if(entropy_coding_mode_flag && slice_type != I)	
cabac_init_idc	ue(v)
slice_qp_delta	se(v)
if(adaptive_loop_filter_enabled_flag)	
alf_param()	
if(deblocking_filter_control_present_flag) {	
disable_deblocking_filter_idc	
if(disable_deblocking_filter_idc != 1) {	
slice_alpha_c0_offset_div2	
slice_beta_offset_div2	
}	
}	
if(slice_type == B)	
collocated_from_l0_flag	u(1)
} else	
if(entropy_coding_mode_flag && slice_type != I)	
cabac_init_idc	ue(v)
}	

ID FOR IDENTIFYING
VIEWS

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FIG. 19

prediction_unit(x0,y0,log2PUWidth,log2PUHeight, PartIdx, InferredMergeFlag) {	Descriptor
if(skip_flag[x0][y0]) {	
if(NumMergeCand > 1)	
merge_idx[x0][y0]	ue(v) ae(v)
} else if(PredMode == MODE_INTRA) {	
prev_intra_luma_pred_flag[x0][y0]	u(1) ae(v)
if(!prev_intra_luma_pred_flag[x0][y0]	
if(NumMPMCand > 1)	
mpm_idx[x0][y0]	u(1) ae(v)
else	
rem_intra_luma_pred_mode[x0][y0]	ue(v) ae(v)
intra_chroma_pred_mode[x0][y0]	ue(v) ae(v)
} else /* MODE_INTER */	
if(!InferredMergeFlag)	
merge_flag[x0][y0]	u(1) ae(v)
if(merge_flag[x0][y0] && NumMergeCand > 1) {	
merge_idx[x0][y0]	ue(v) ae(v)
} else {	
if(slice_type == B)	
inter_pred_flag[x0][y0]	ue(v) ae(v)
if(inter_pred_flag[x0][y0] == Pred_L0) {	
if(num_ref_idx_l0_active_minus1 > 0)	
ref_idx_l0[x0][y0]	ue(v) ae(v)
mvd_l0[x0][y0][0]	se(v) ae(v)
mvd_l0[x0][y0][1]	se(v) ae(v)
if(NumMVPcand(L0) > 1)	
mvp_idx_l0[x0][y0]	ue(v) ae(v)
}	
else /* Pred_L0 or Pred_BI */	
if(num_ref_idx_l0_active_minus1 > 0)	
ref_idx_l0[x0][y0]	ue(v) ae(v)
mvd_l0[x0][y0][0]	se(v) ae(v)
mvd_l0[x0][y0][1]	se(v) ae(v)
if(NumMVPcand(L0) > 1)	
mvp_idx_l0[x0][y0]	ue(v) ae(v)
}	
if(inter_pred_flag[x0][y0] == Pred_BI) {	
if(num_ref_idx_l1_active_minus1 > 0)	
ref_idx_l1[x0][y0]	ue(v) ae(v)
mvd_l1[x0][y0][0]	se(v) ae(v)
mvd_l1[x0][y0][1]	se(v) ae(v)
if(NumMVPcand(L1) > 1)	
mvp_idx_l1[x0][y0]	ue(v) ae(v)
}	
}	
}	
}	

EXPAND TYPE OF
SYNTAX OR CHANGE
PROCESSING CONTENT

EXPAND TYPE OF
SYNTAX OR CHANGE
PROCESSING CONTENT

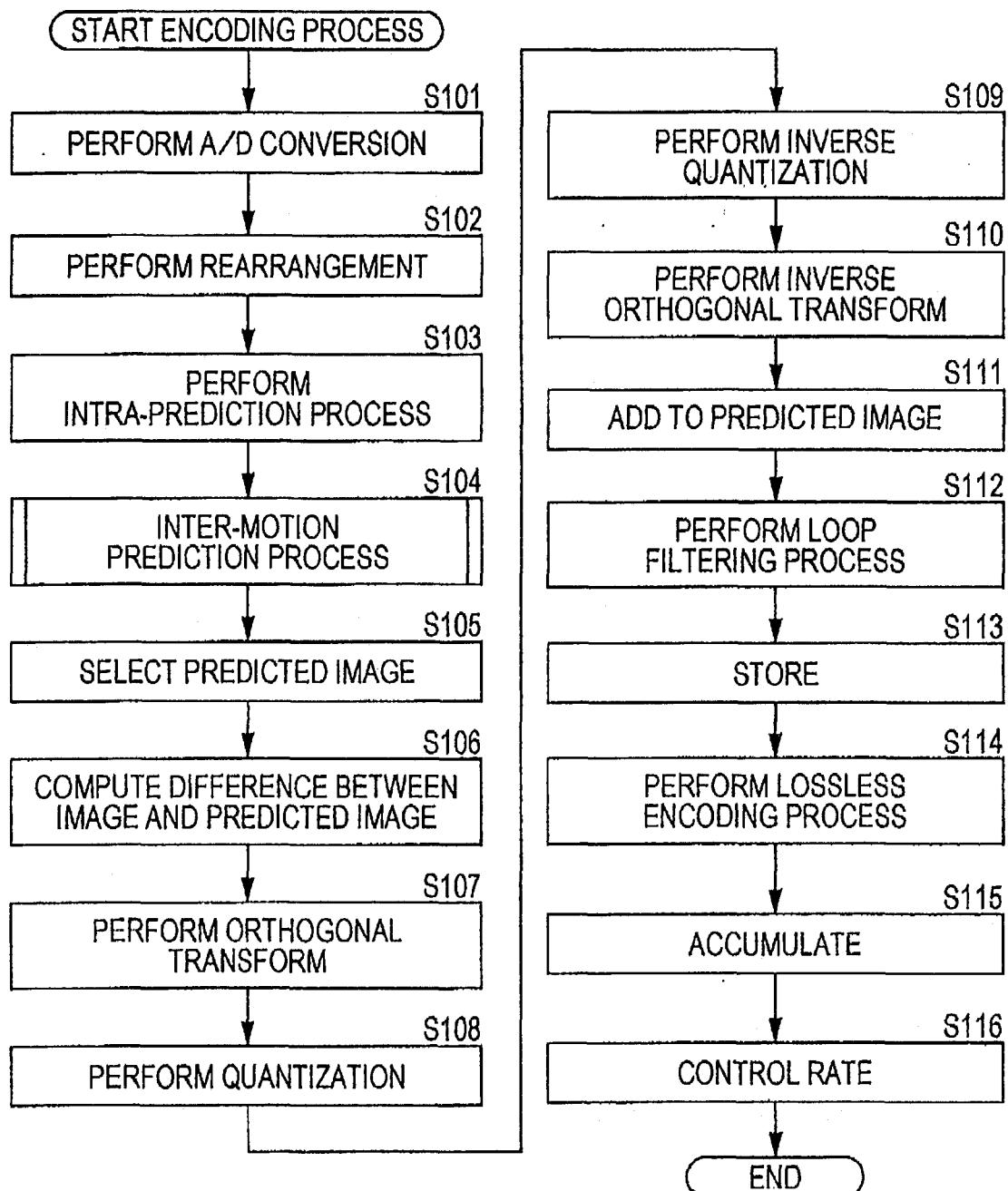
EXPAND TYPE OF
SYNTAX OR CHANGE
PROCESSING CONTENT

EXPAND TYPE OF
SYNTAX OR CHANGE
PROCESSING CONTENT

EXPAND TYPE OF
SYNTAX OR CHANGE
PROCESSING CONTENT

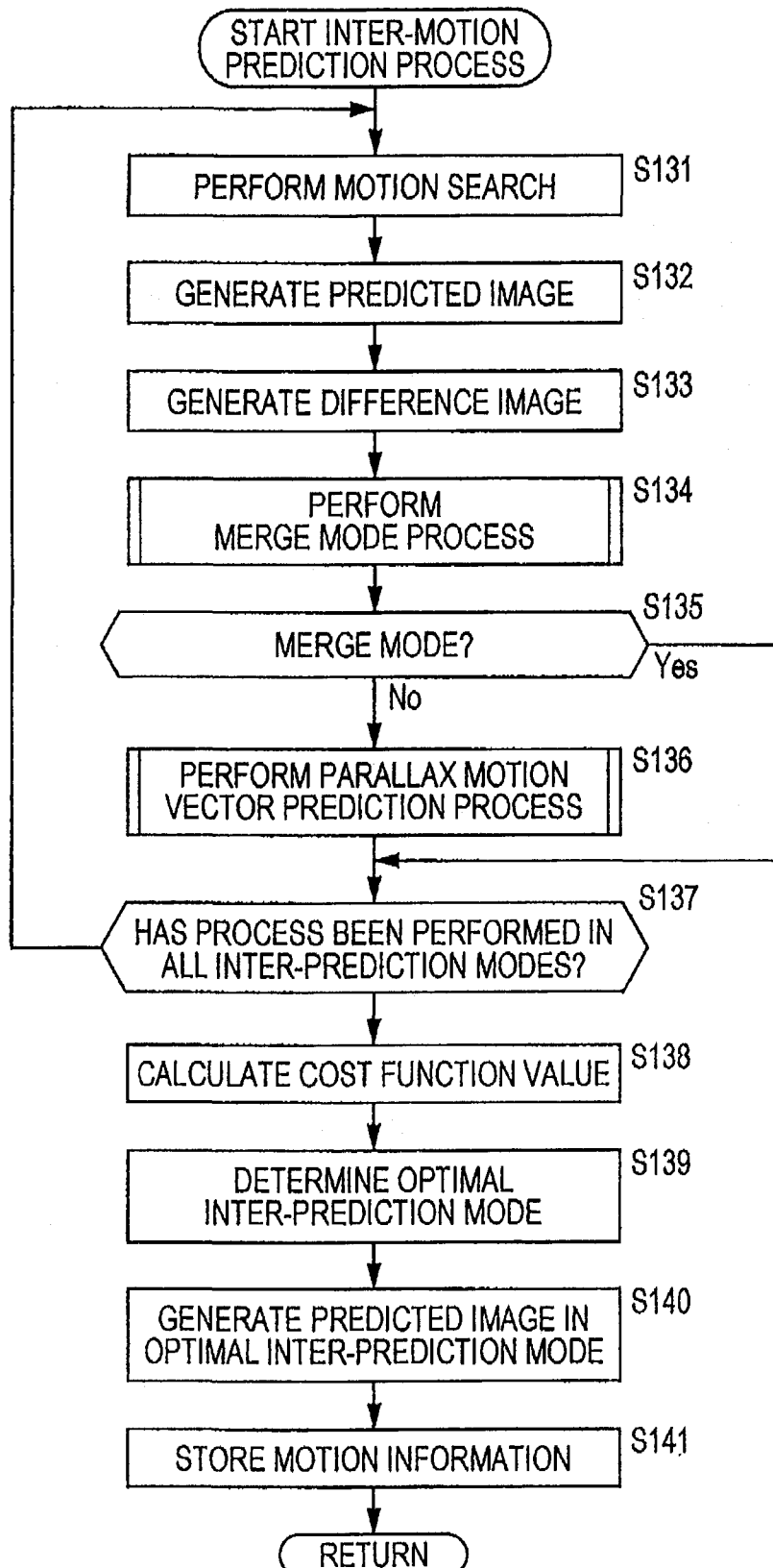
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FIG. 20



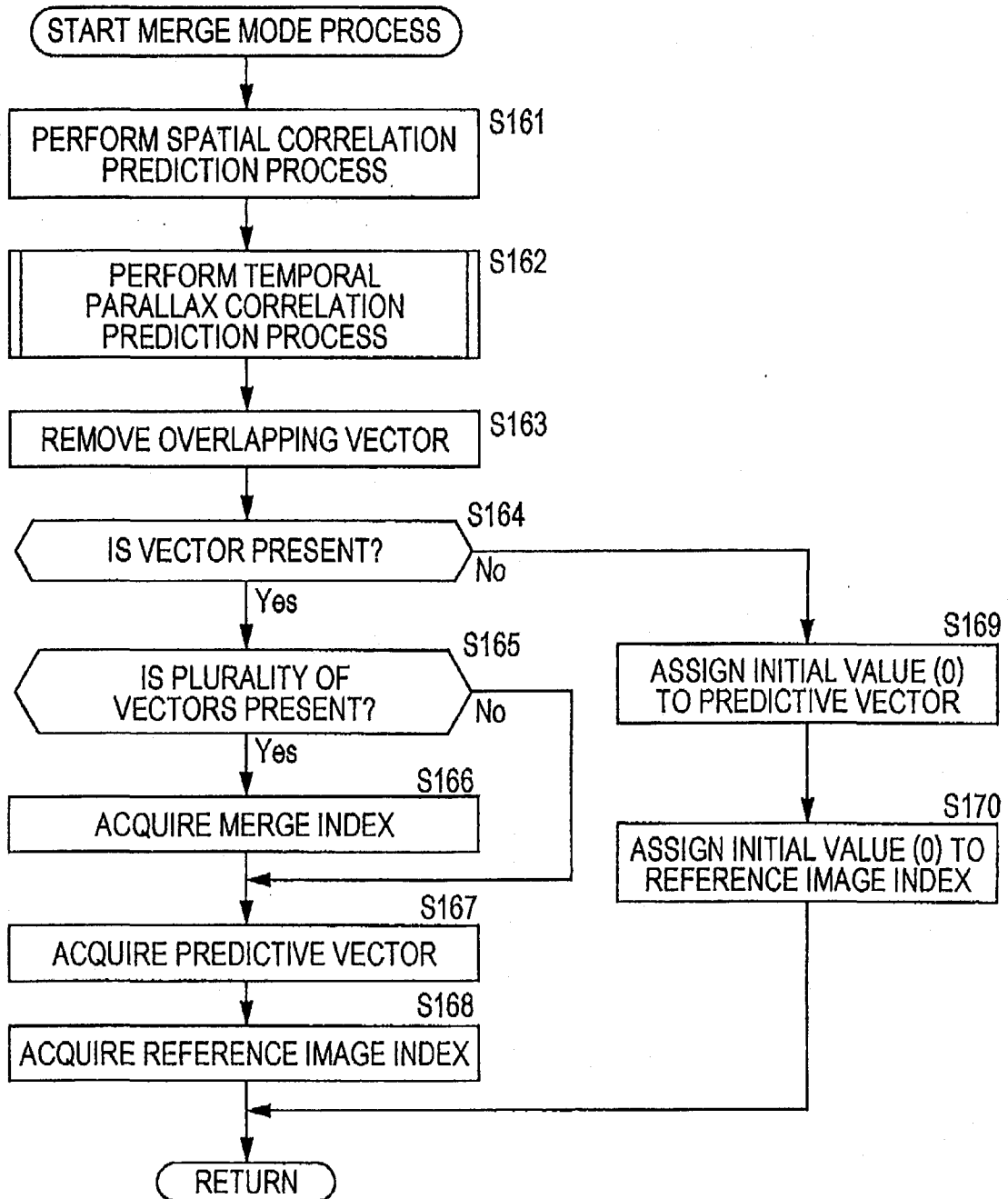
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FIG. 21



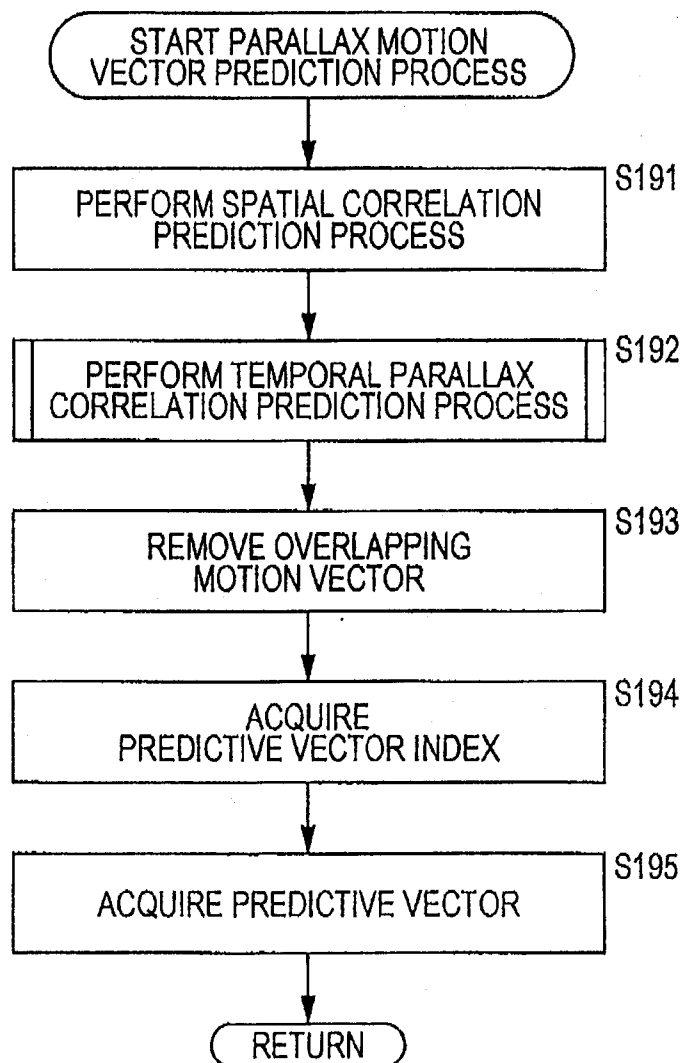
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FIG. 22



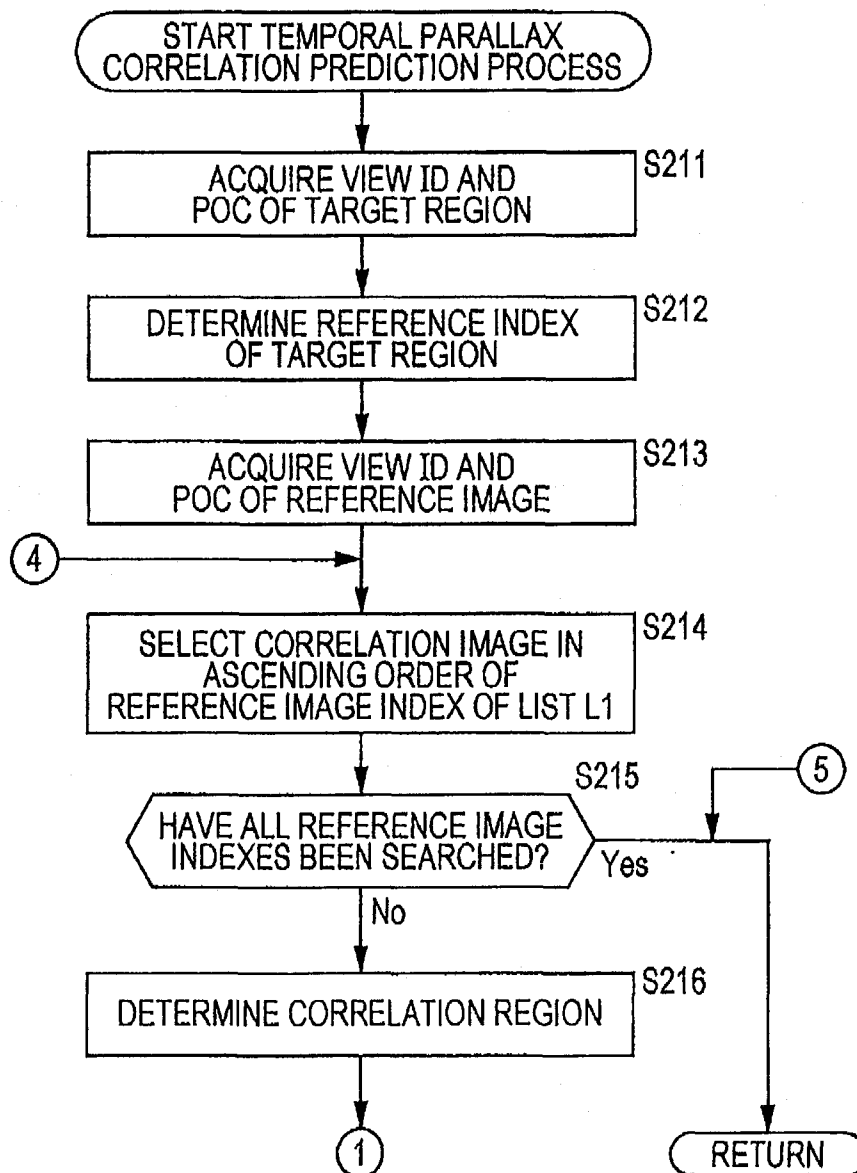
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FIG. 23



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FIG. 24



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FIG. 25

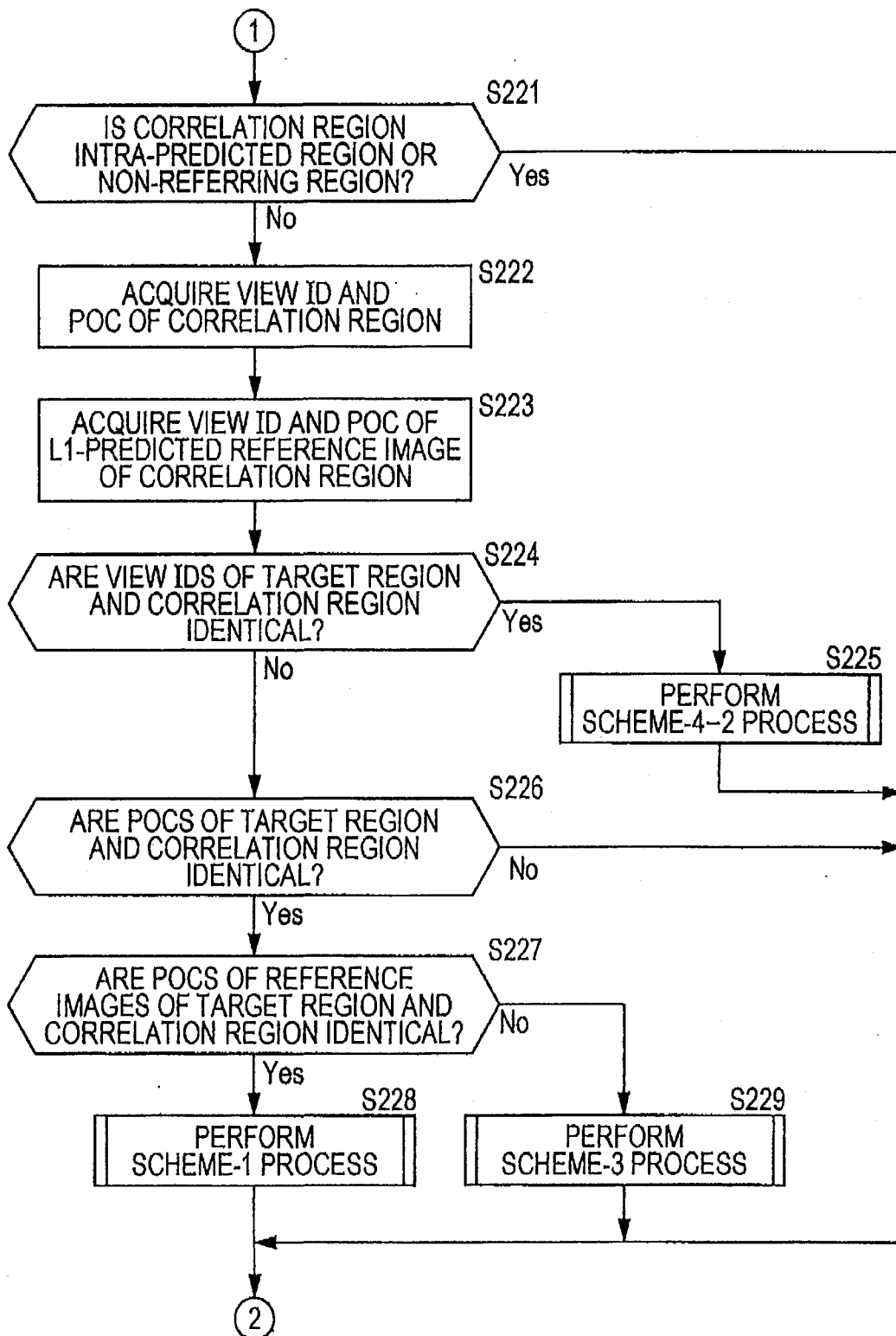
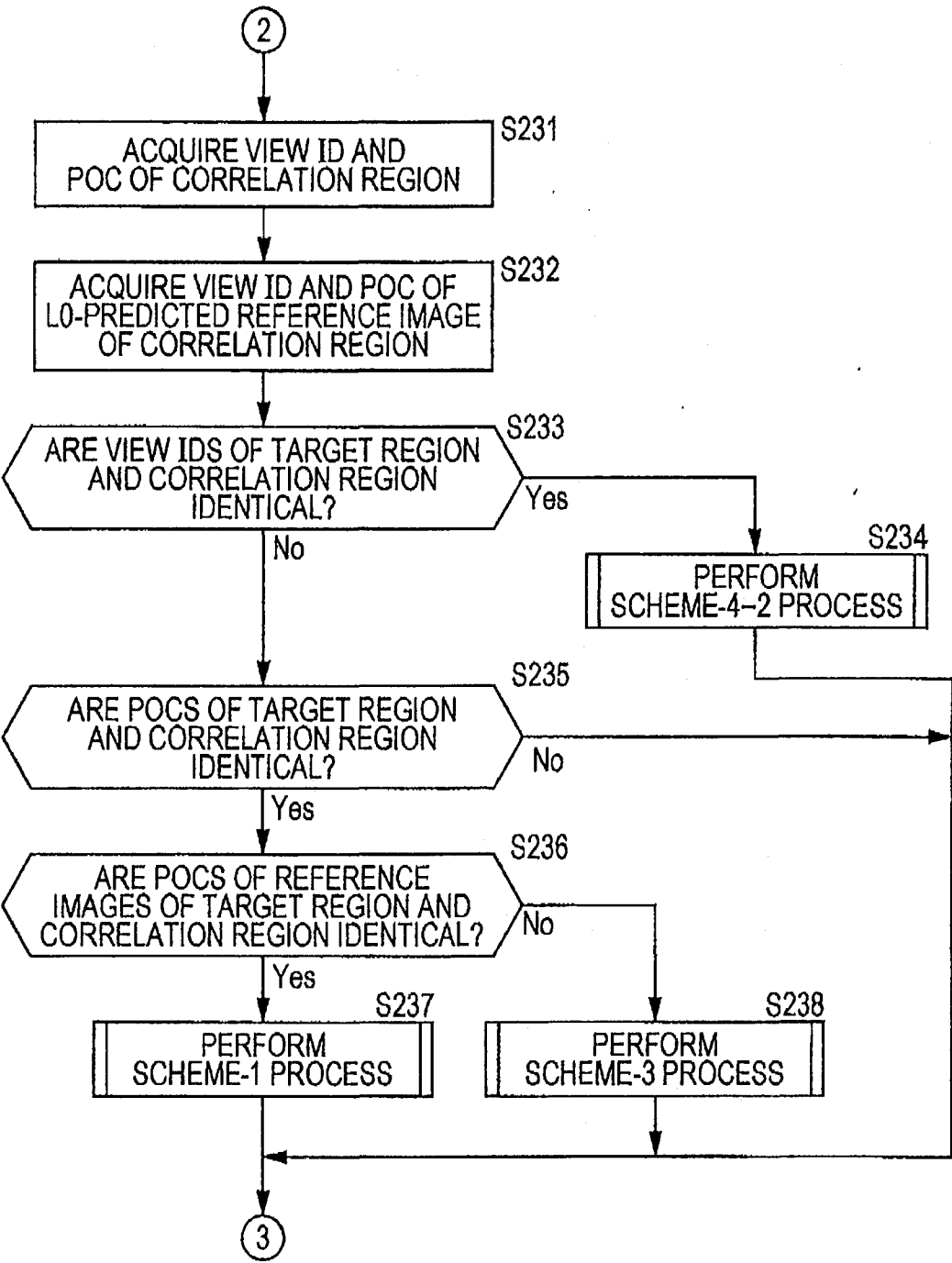
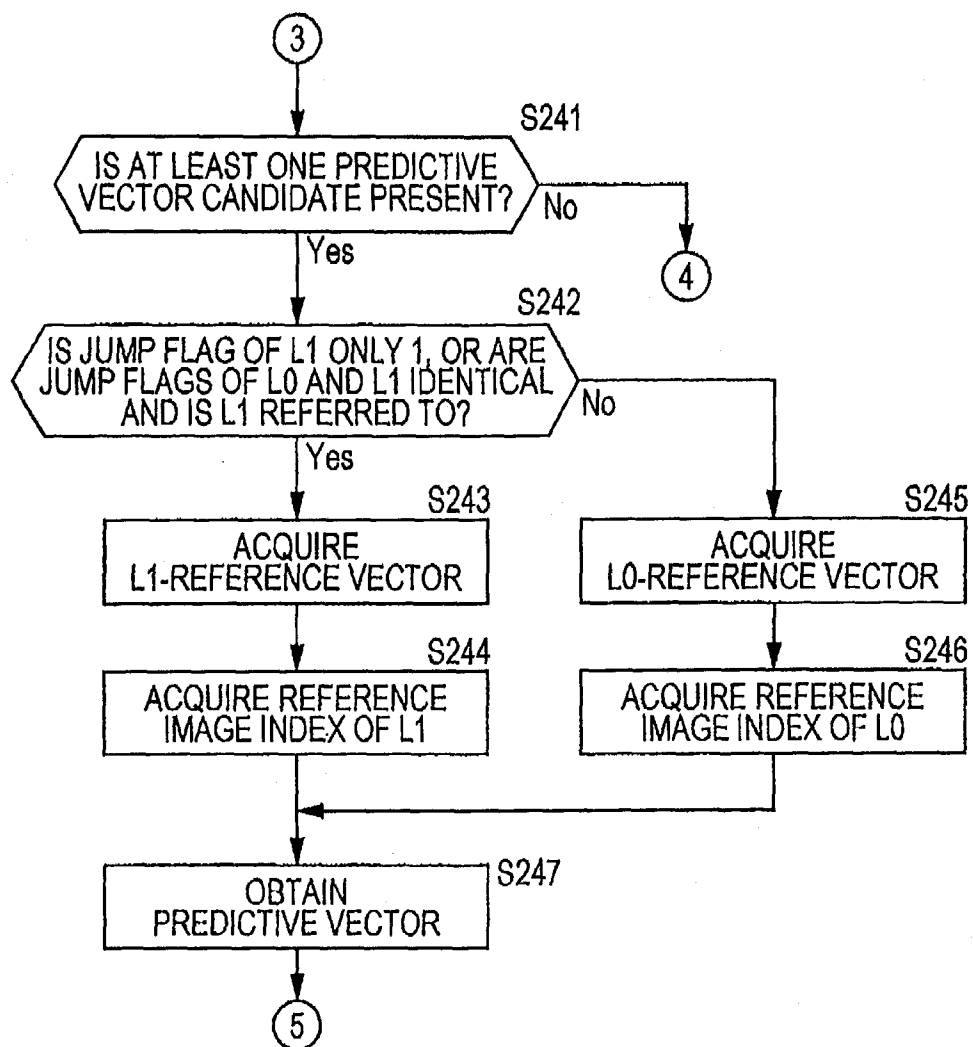


FIG. 26



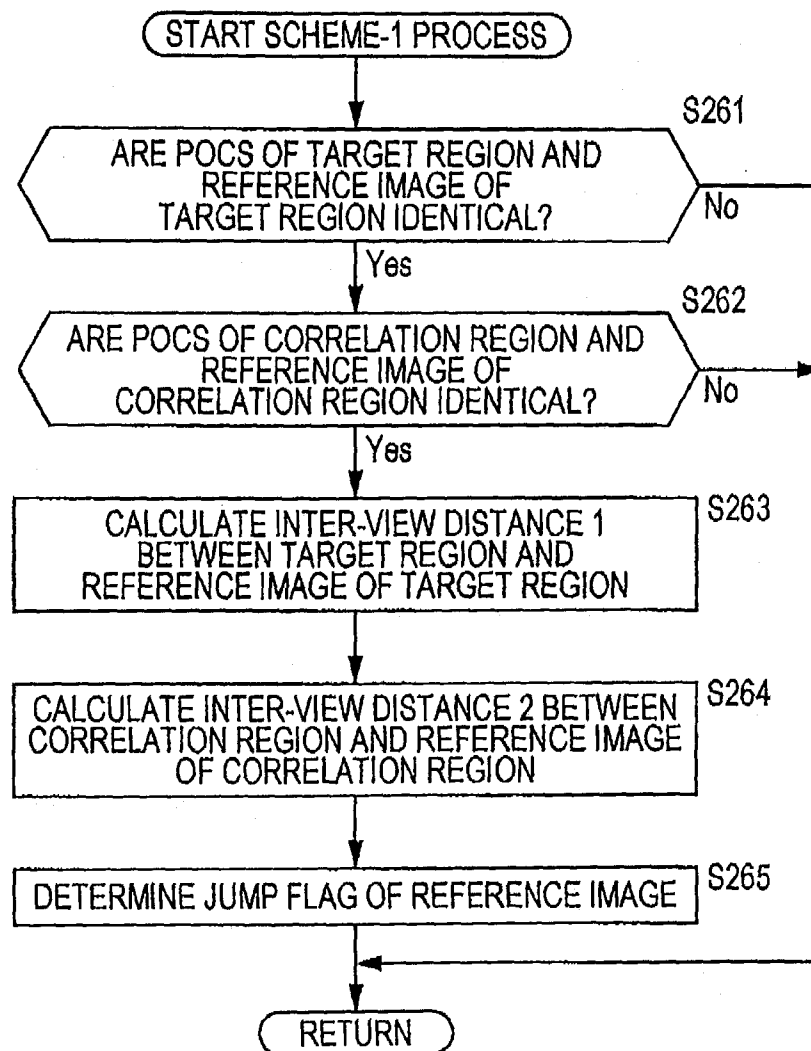
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FIG. 27



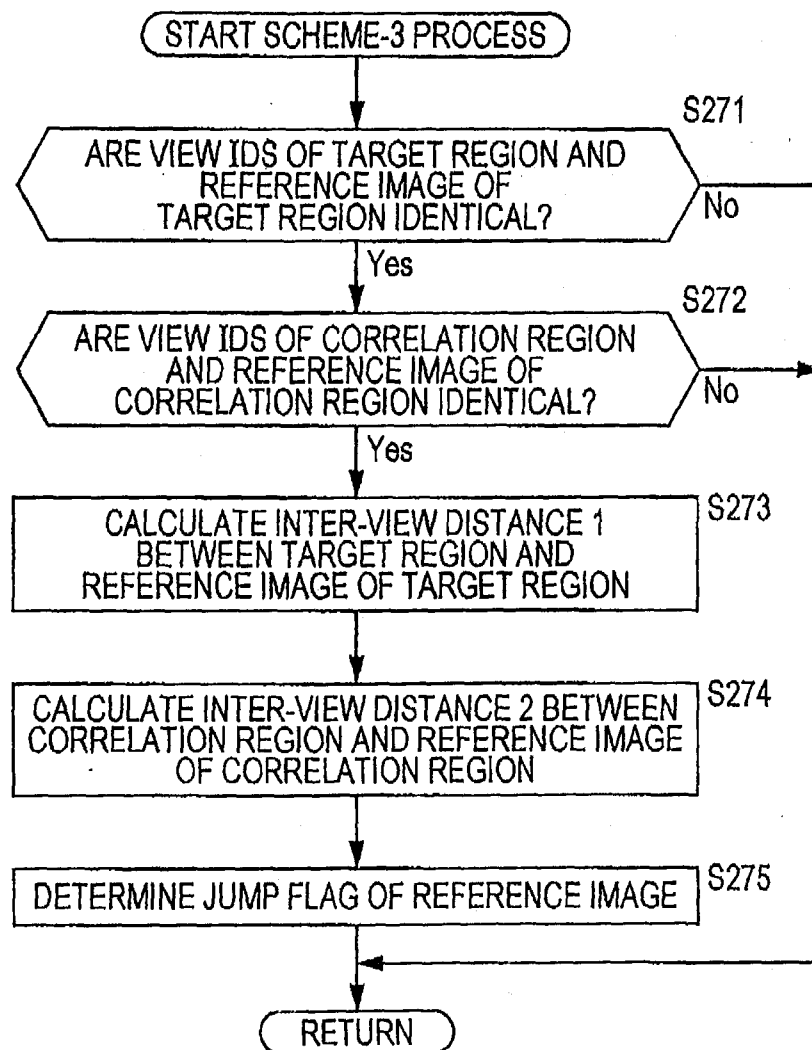
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FIG. 28



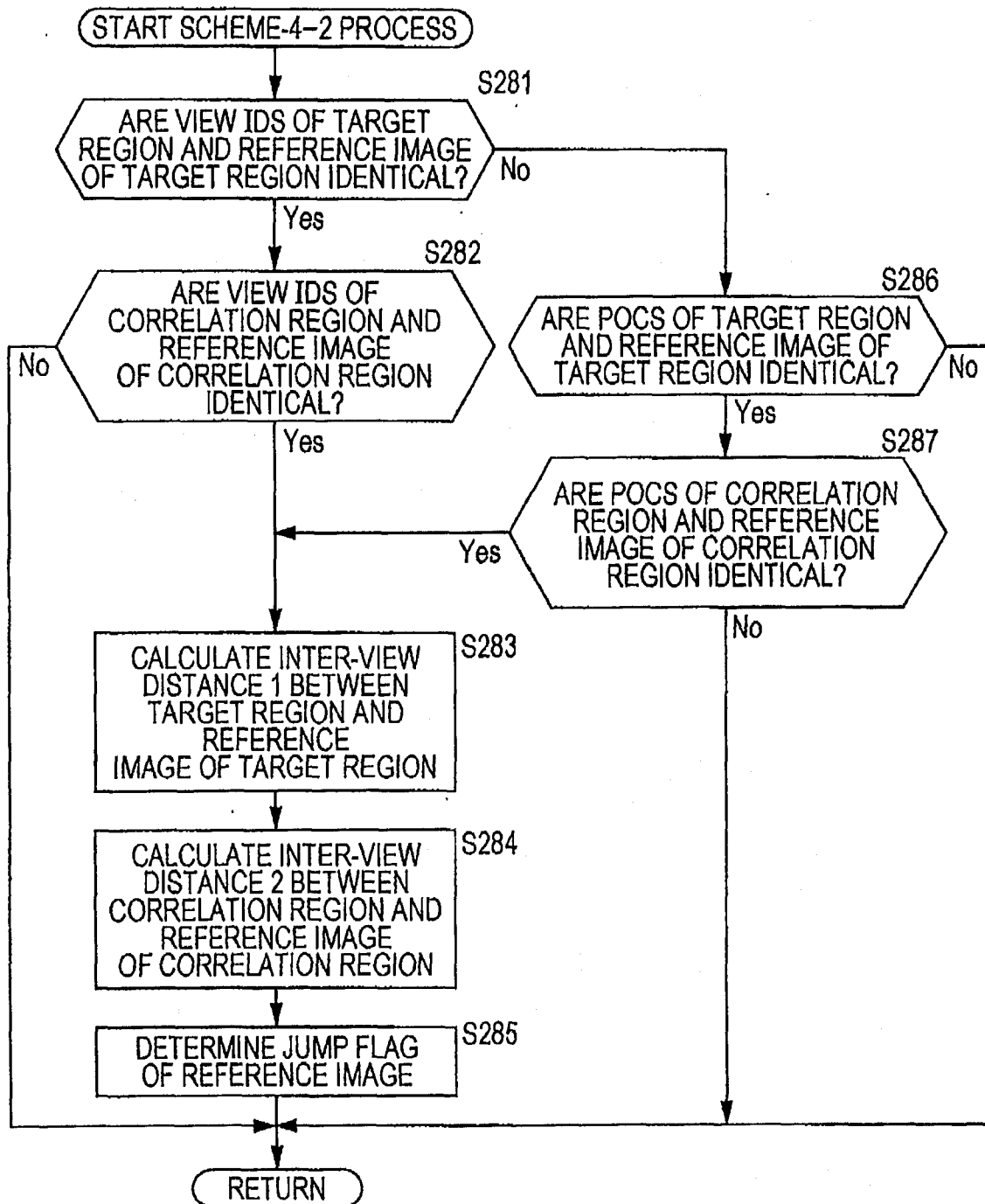
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FIG. 29



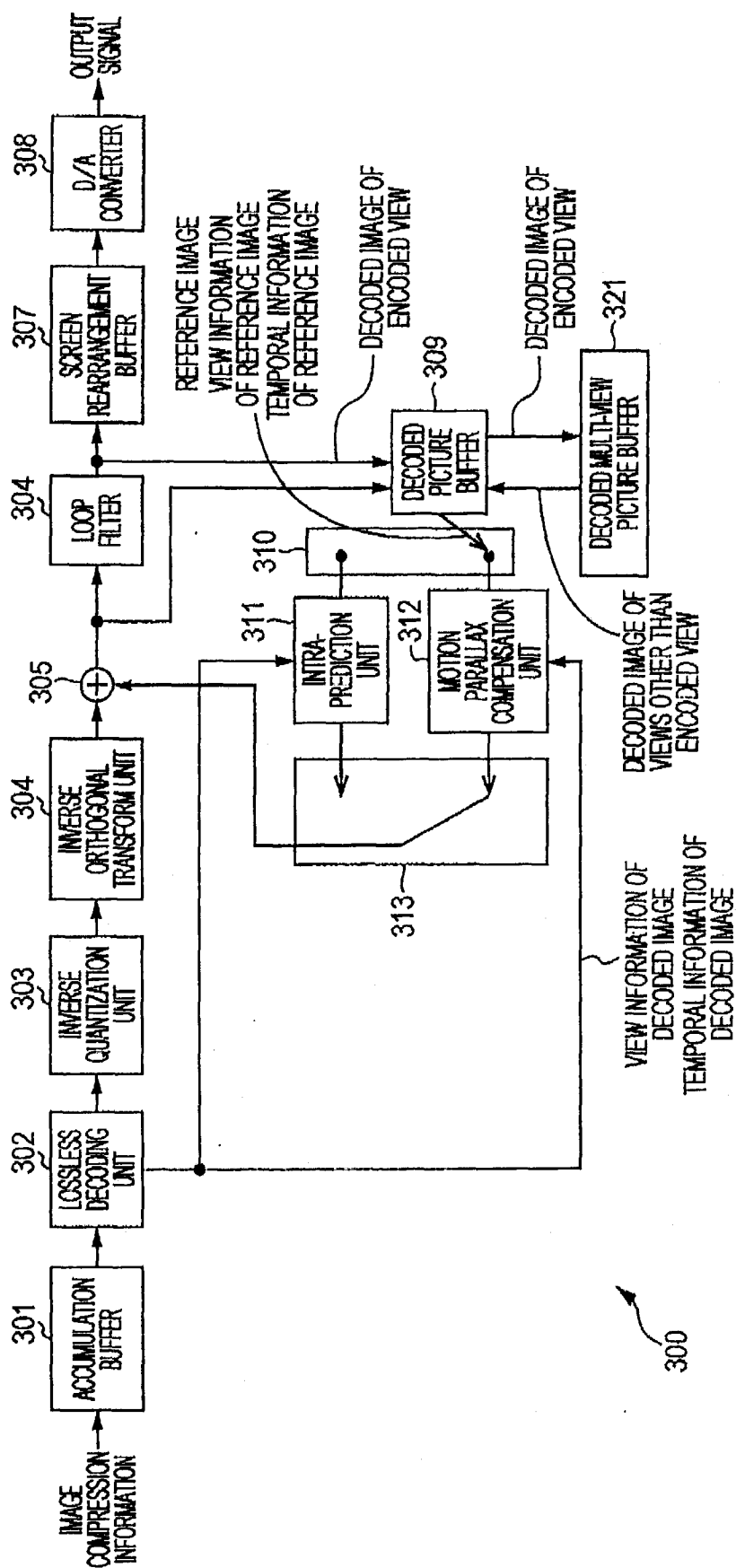
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FIG. 30



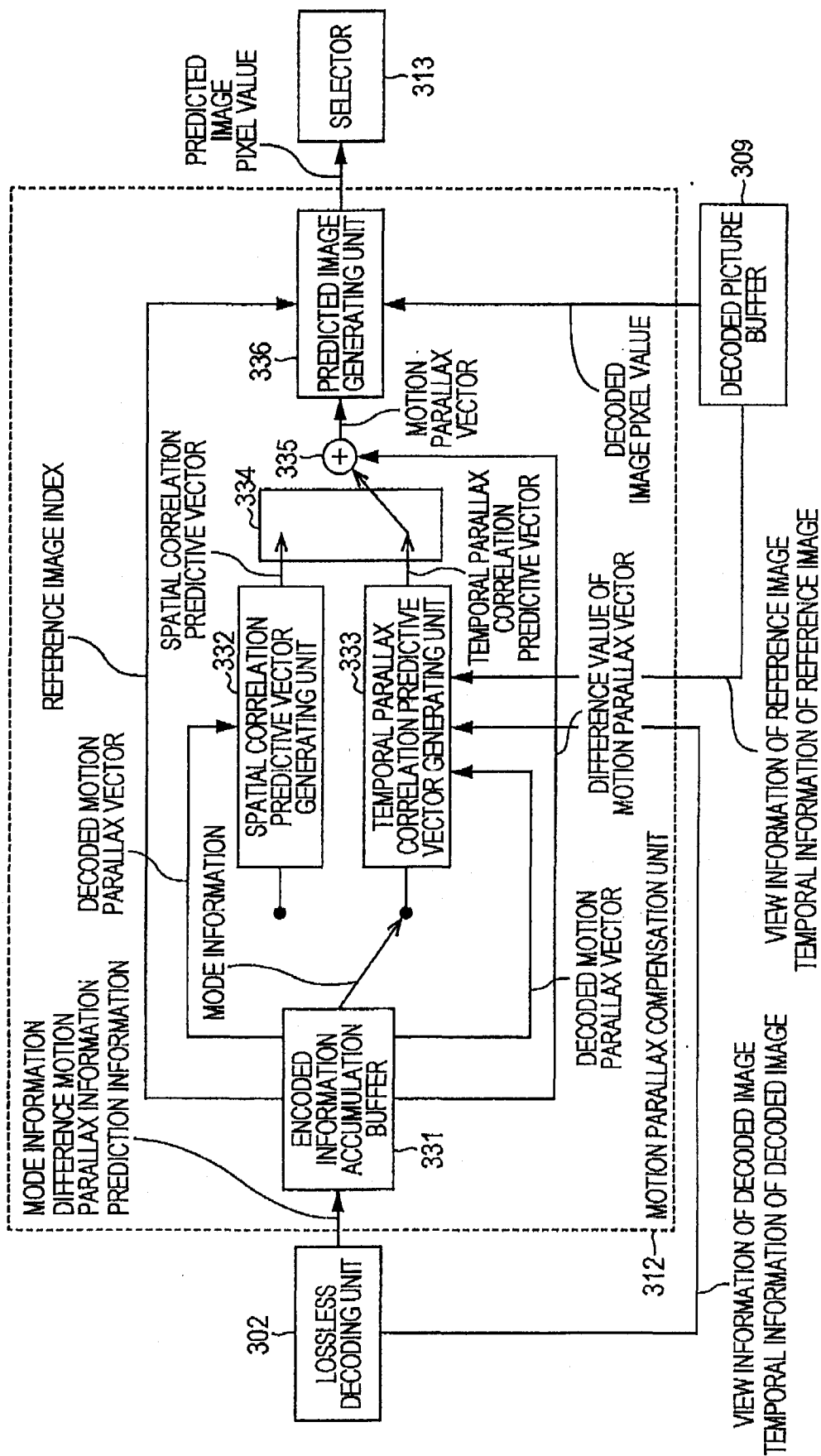
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FIG. 31



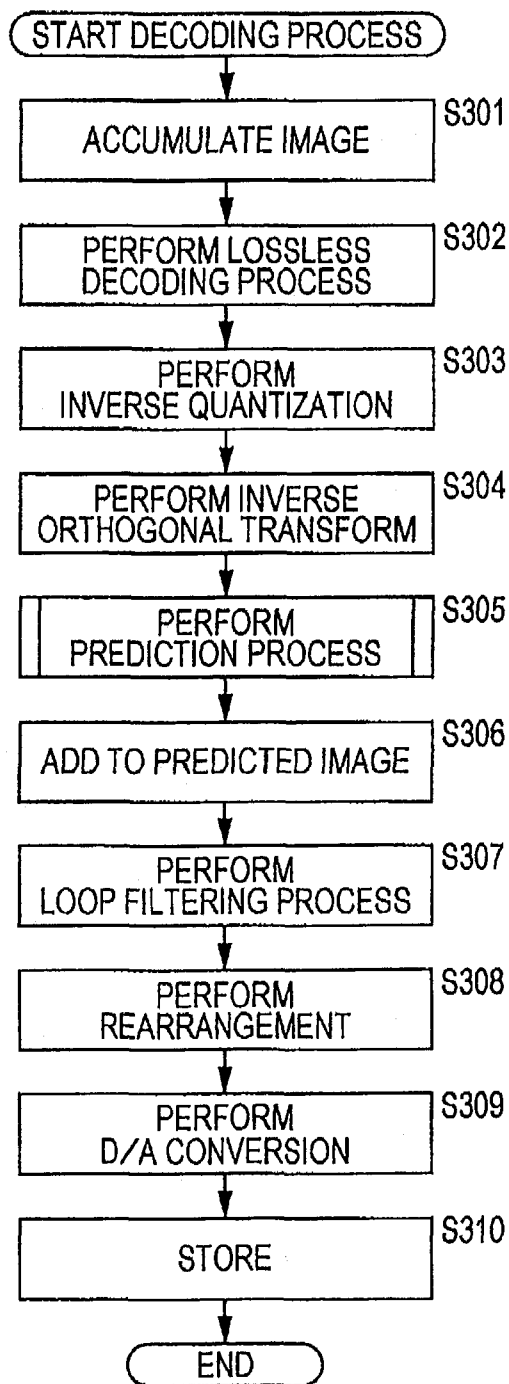
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FIG. 32



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FIG. 33



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FIG. 34

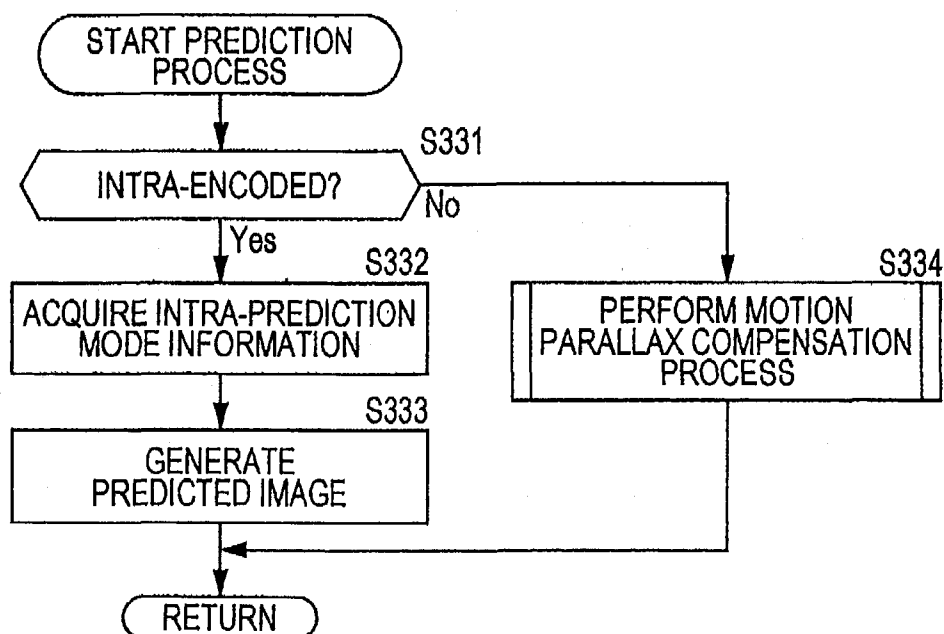
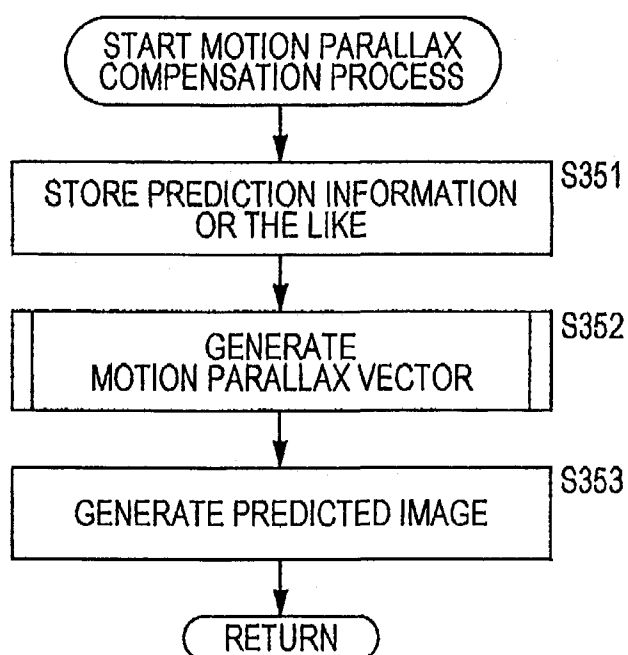


FIG. 35



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FIG. 36

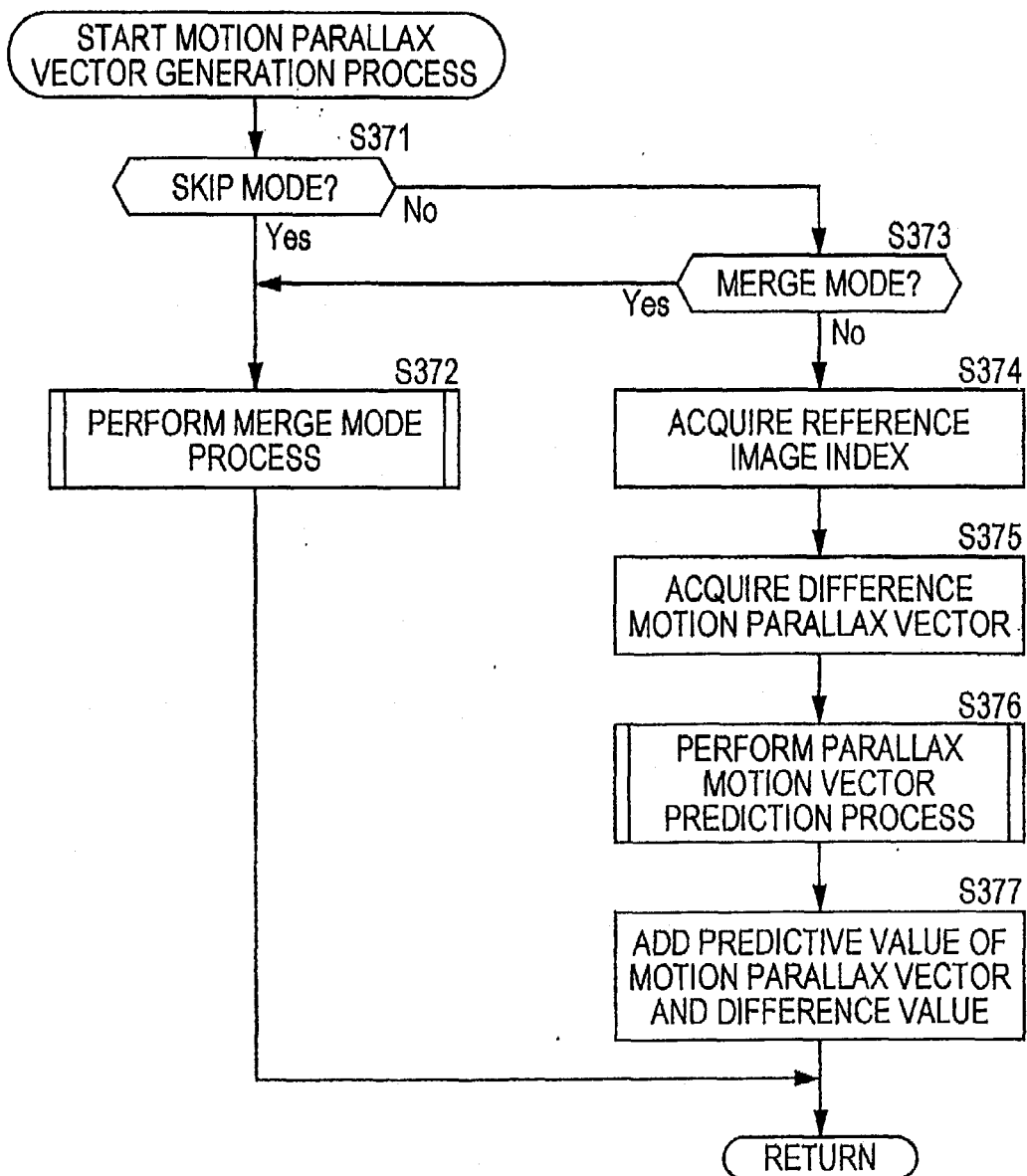


FIG. 37

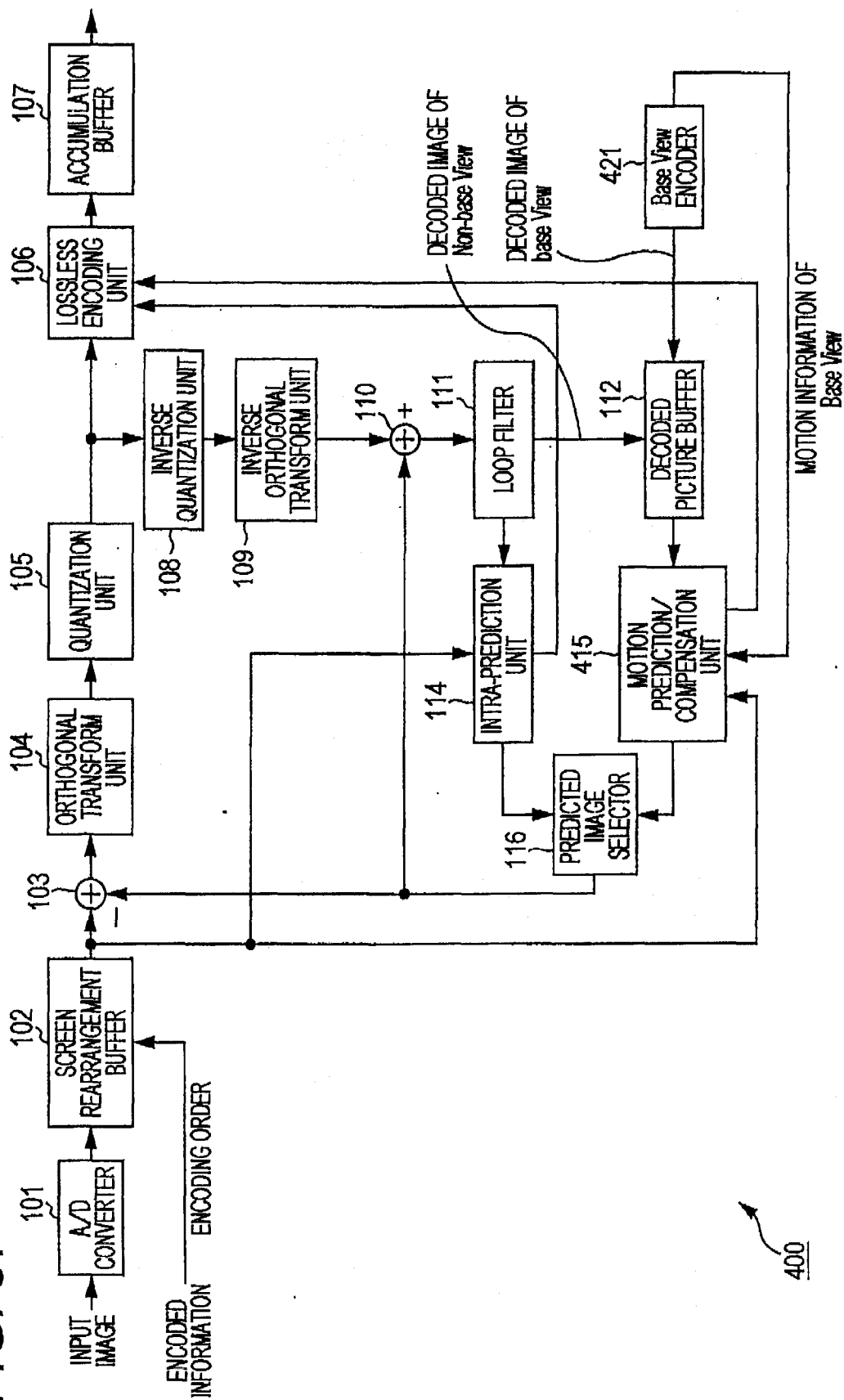


FIG. 38

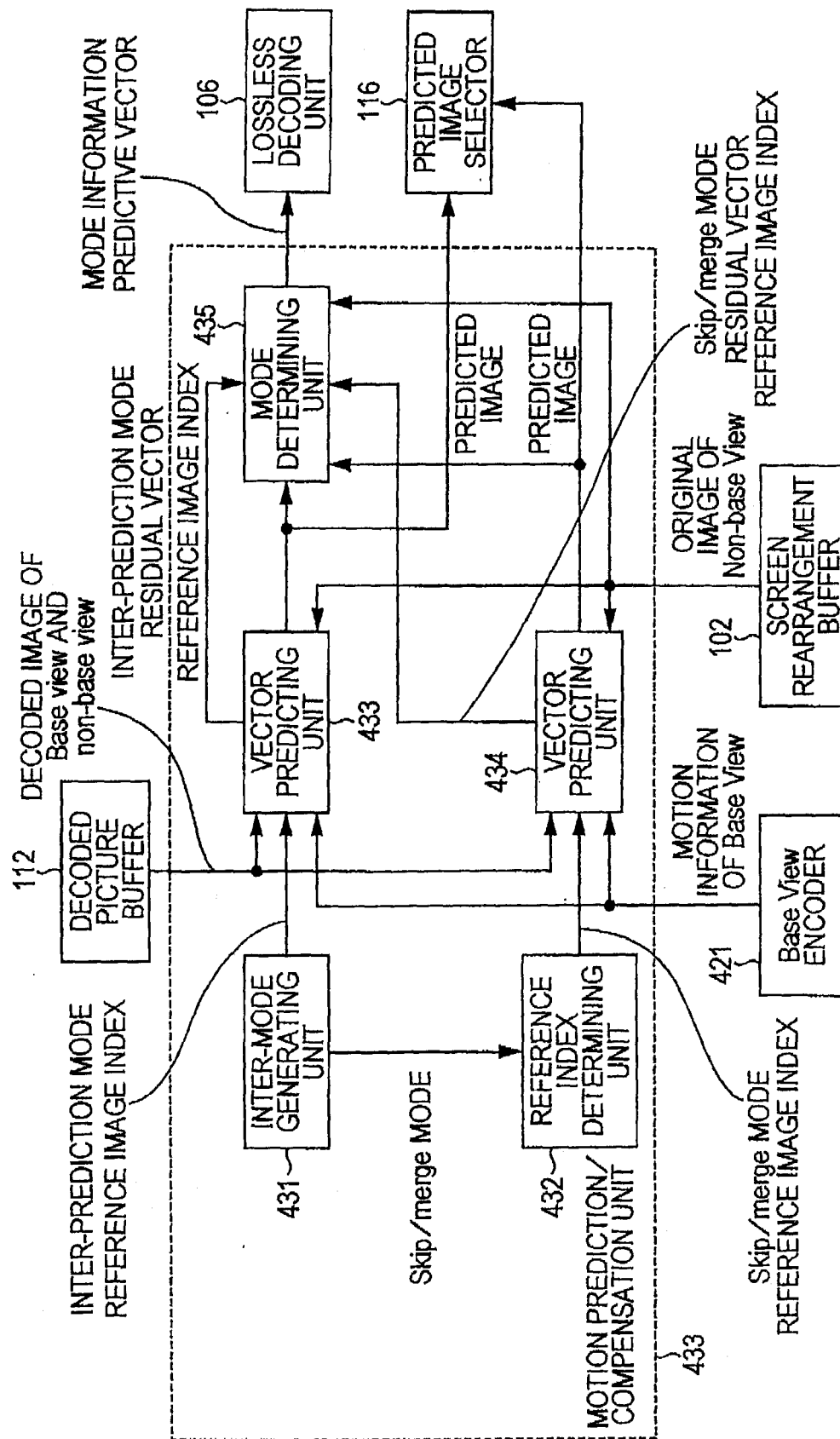


FIG. 39

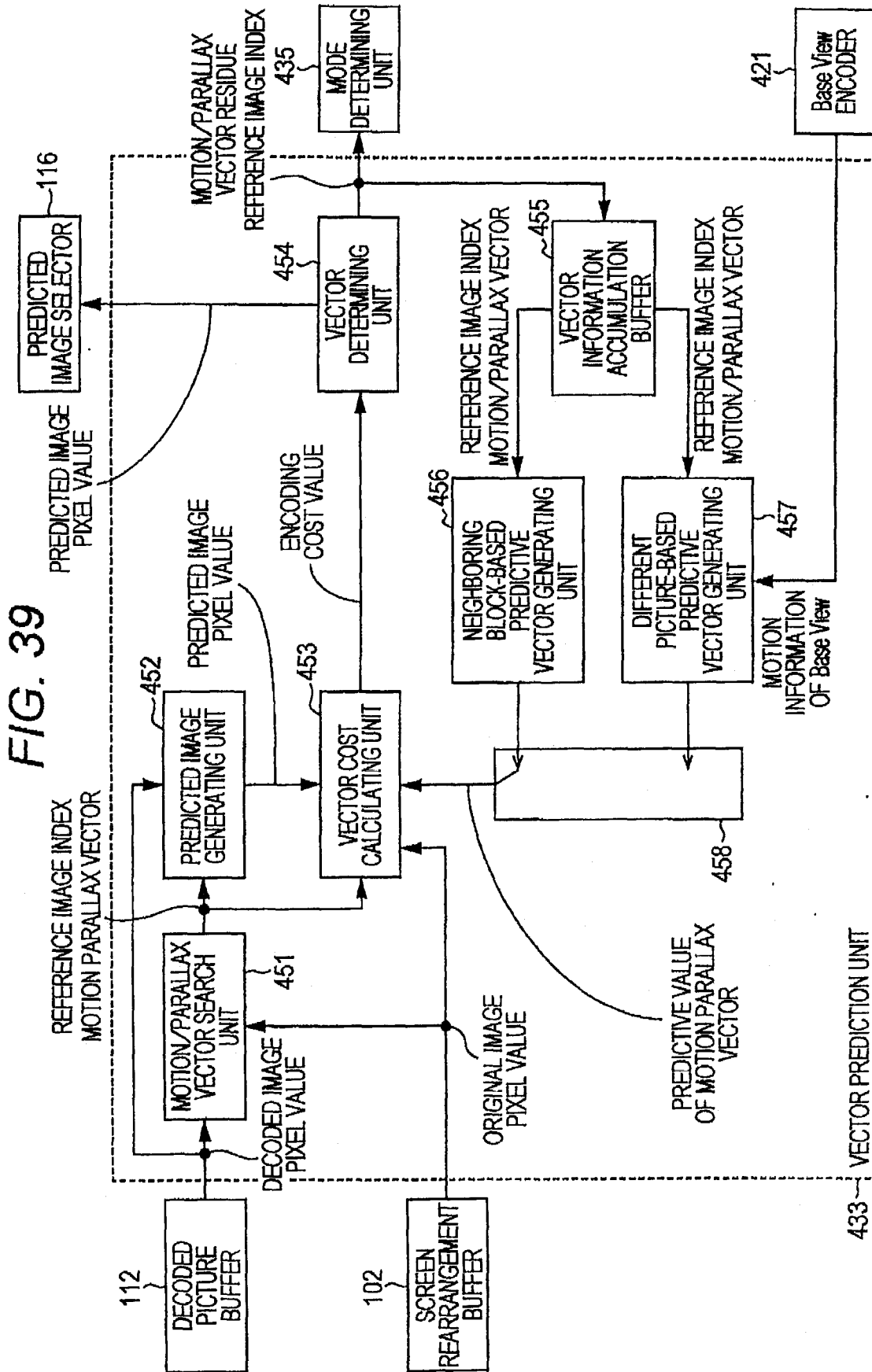
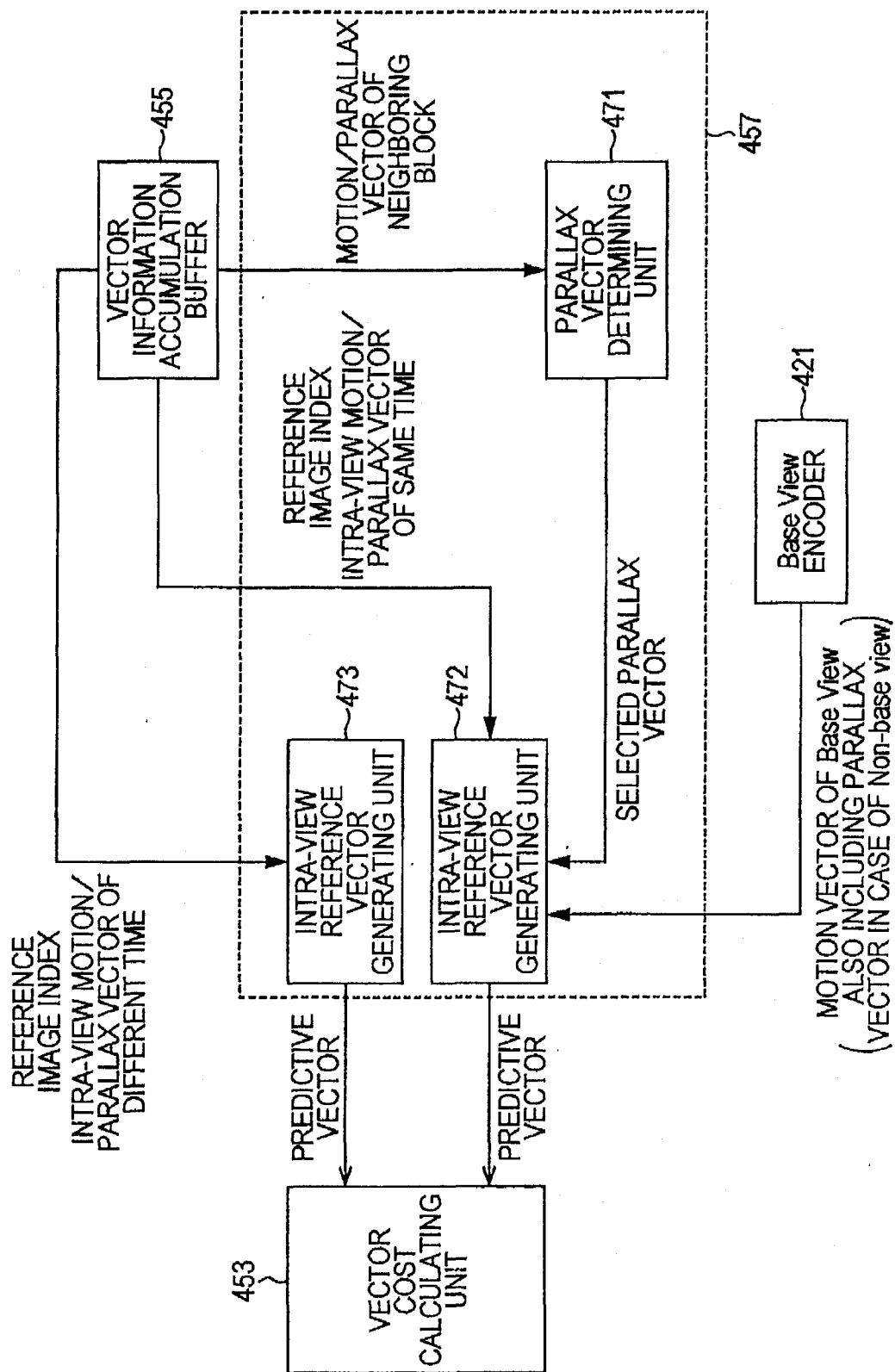
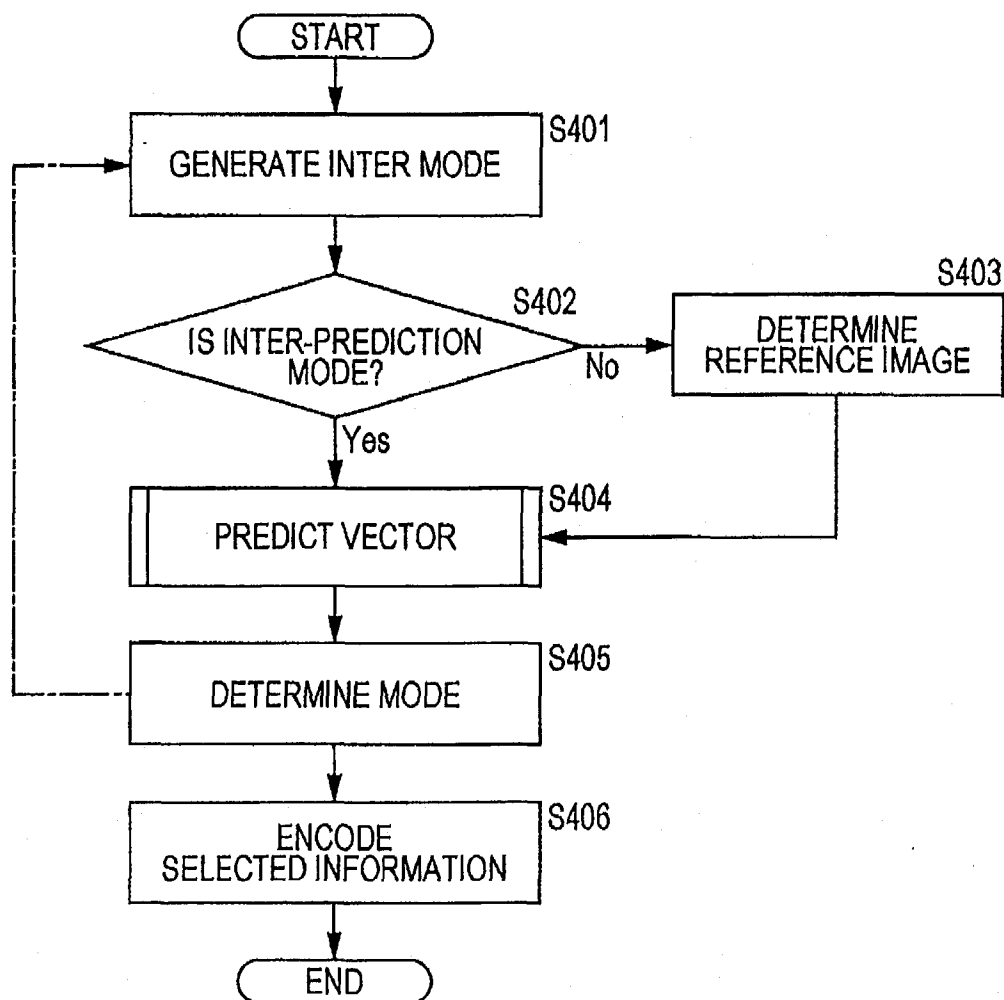


FIG. 40

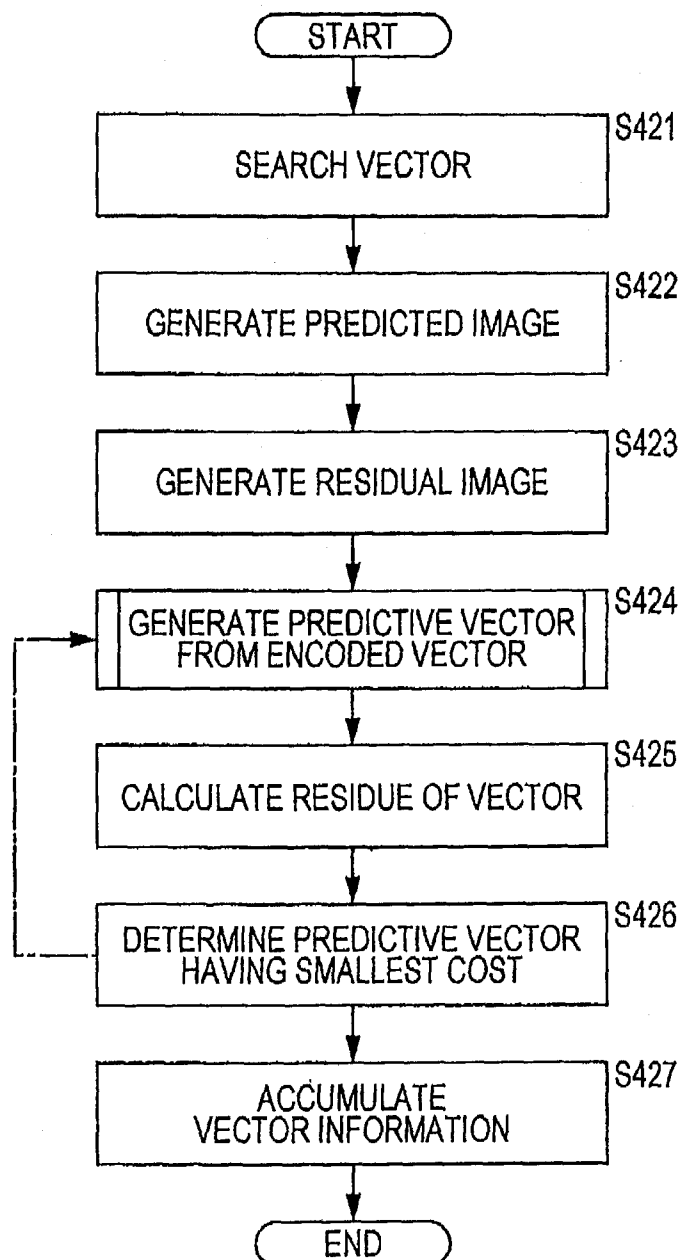


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FIG. 41

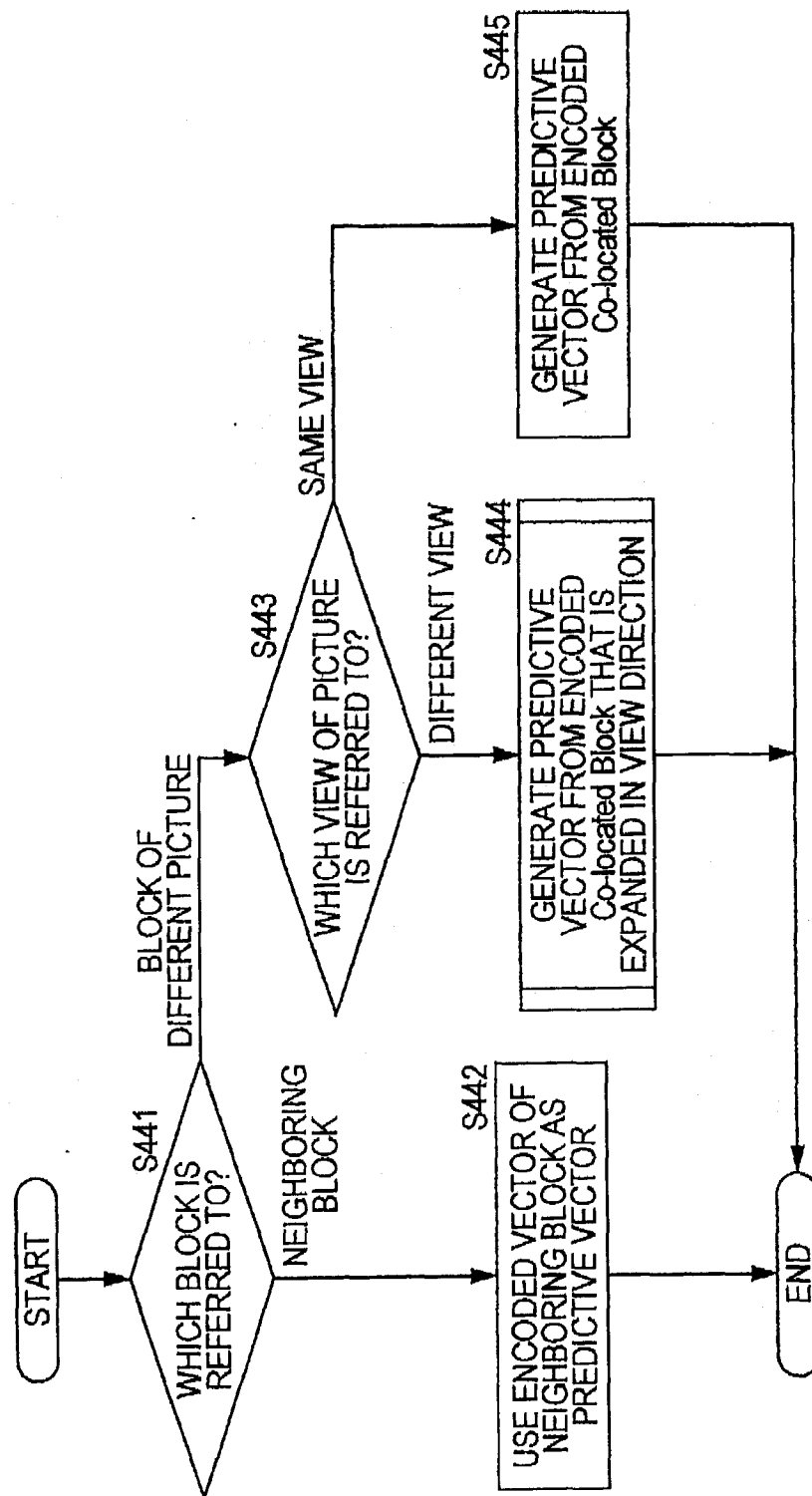


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FIG. 42

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FIG. 43



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FIG. 44

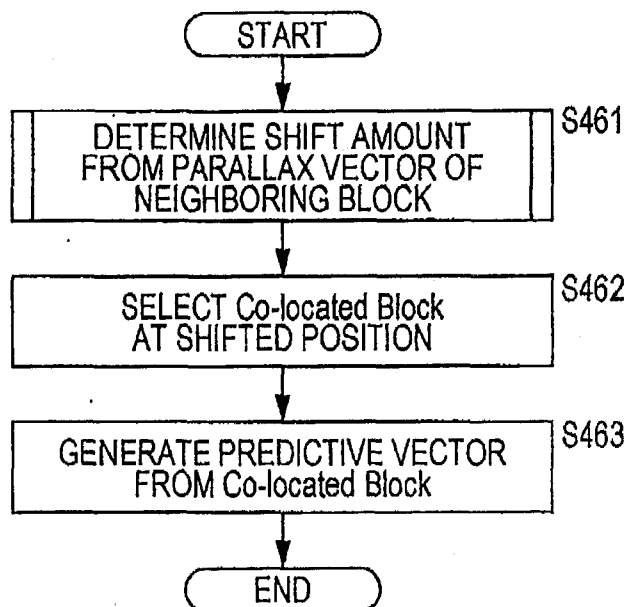
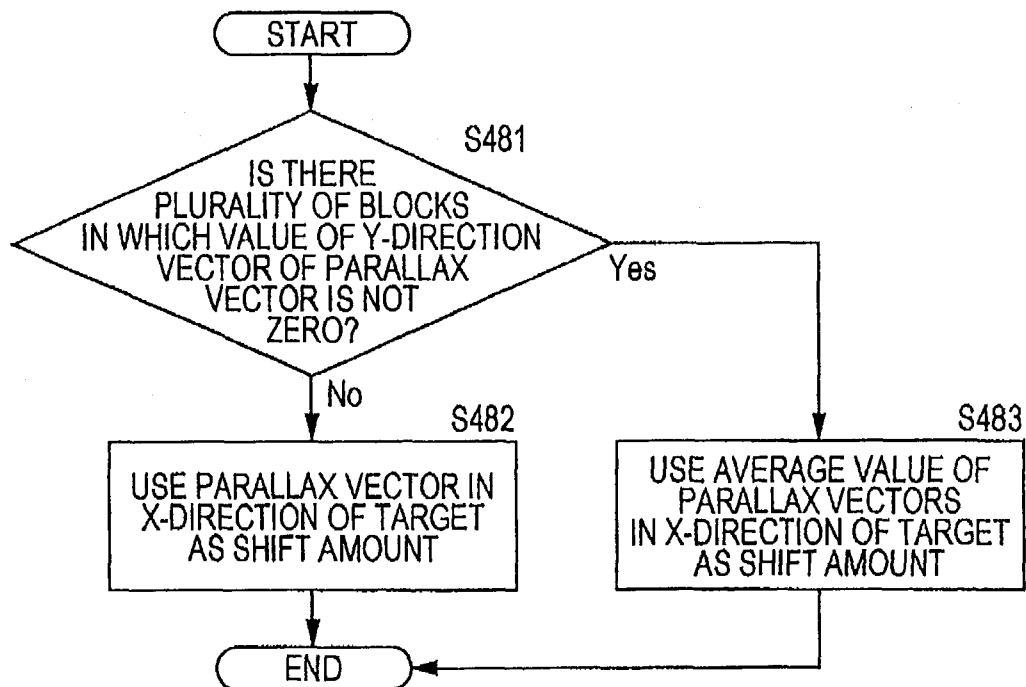


FIG. 45



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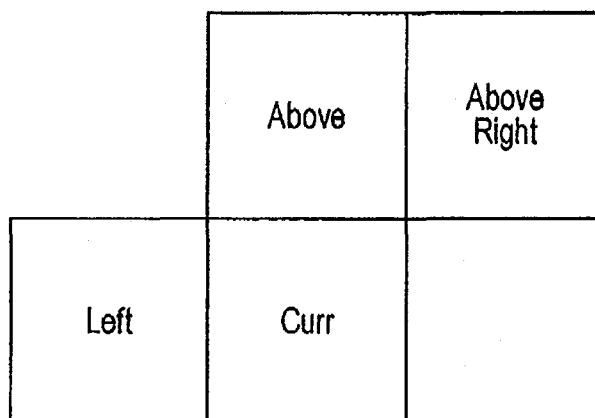
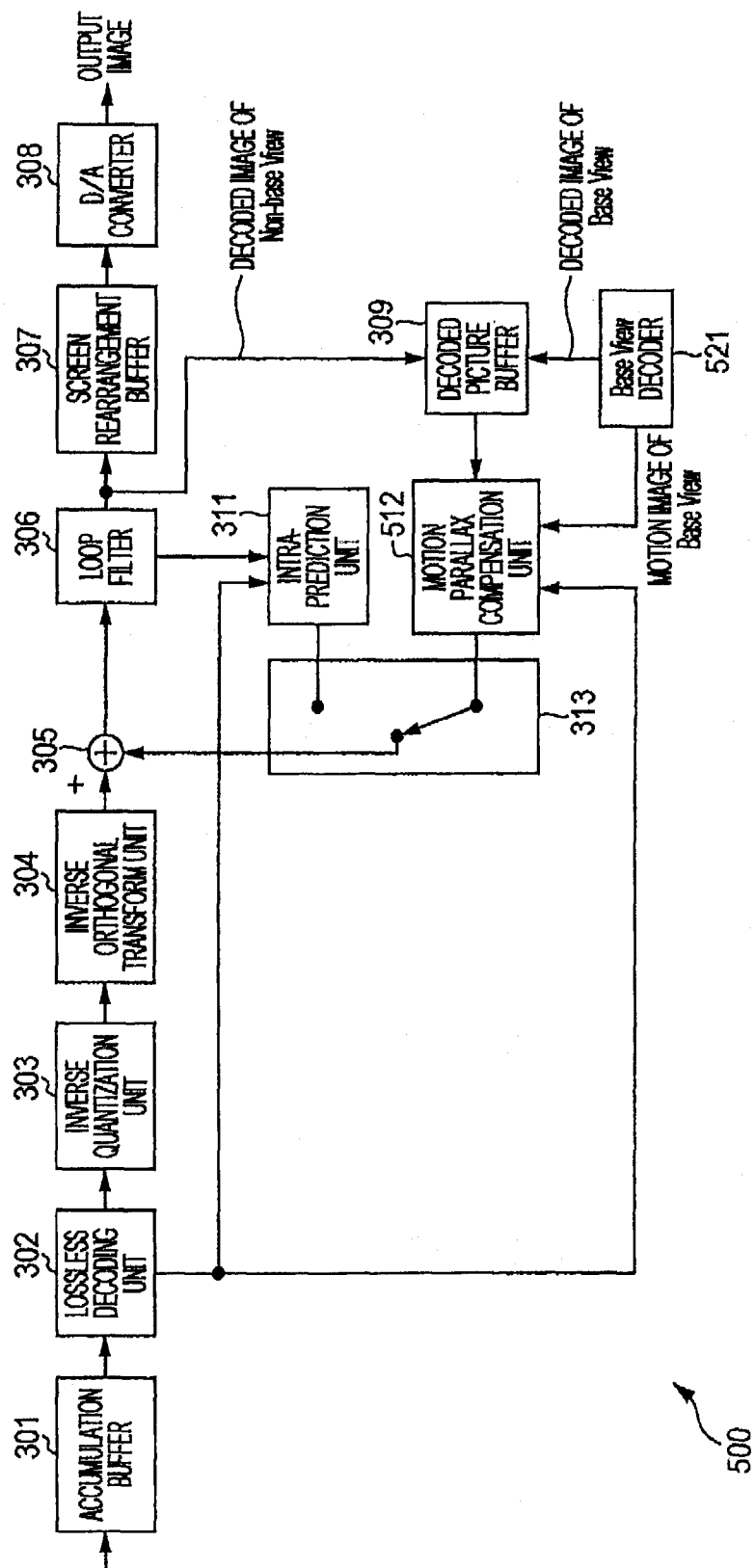
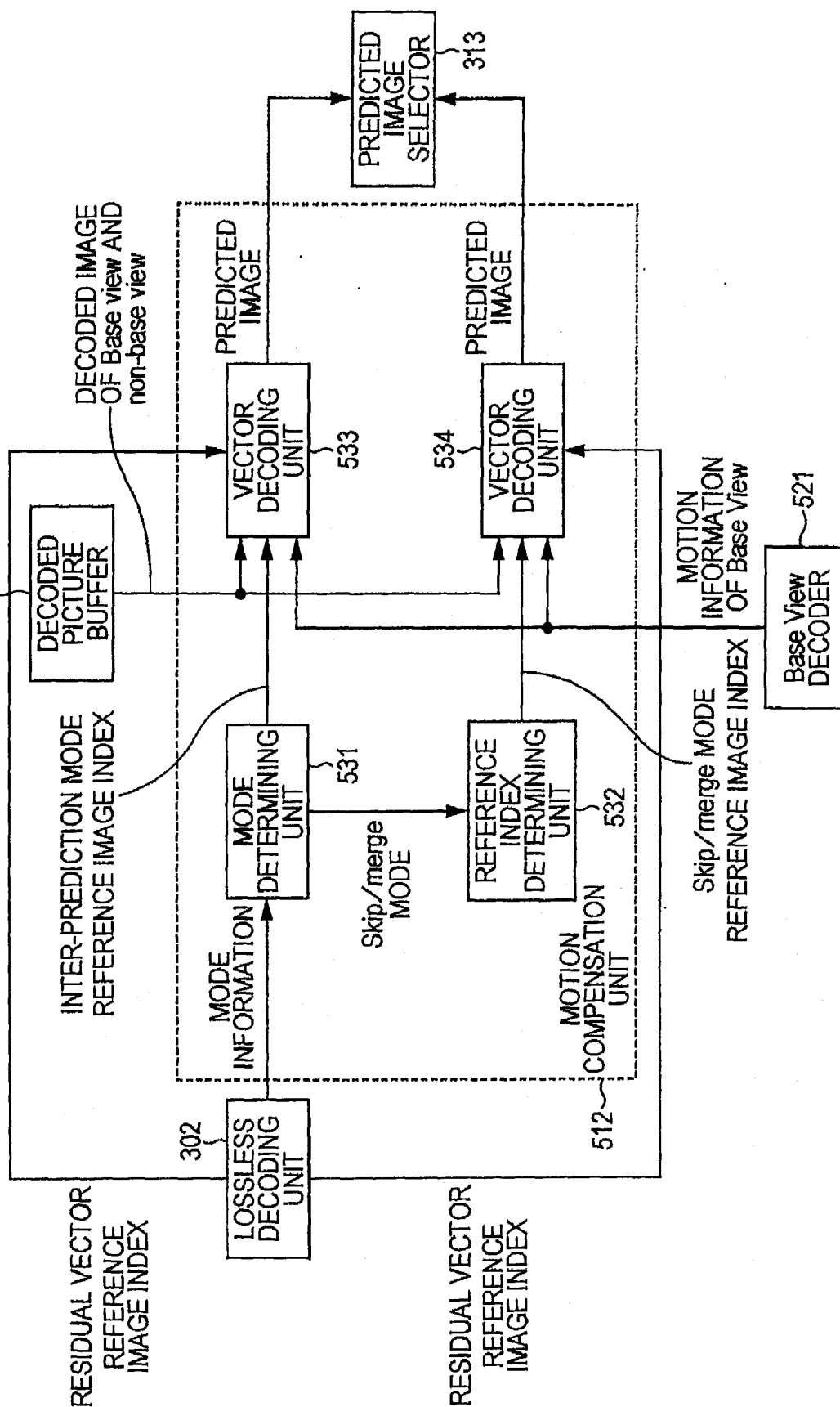
FIG. 46

FIG. 47



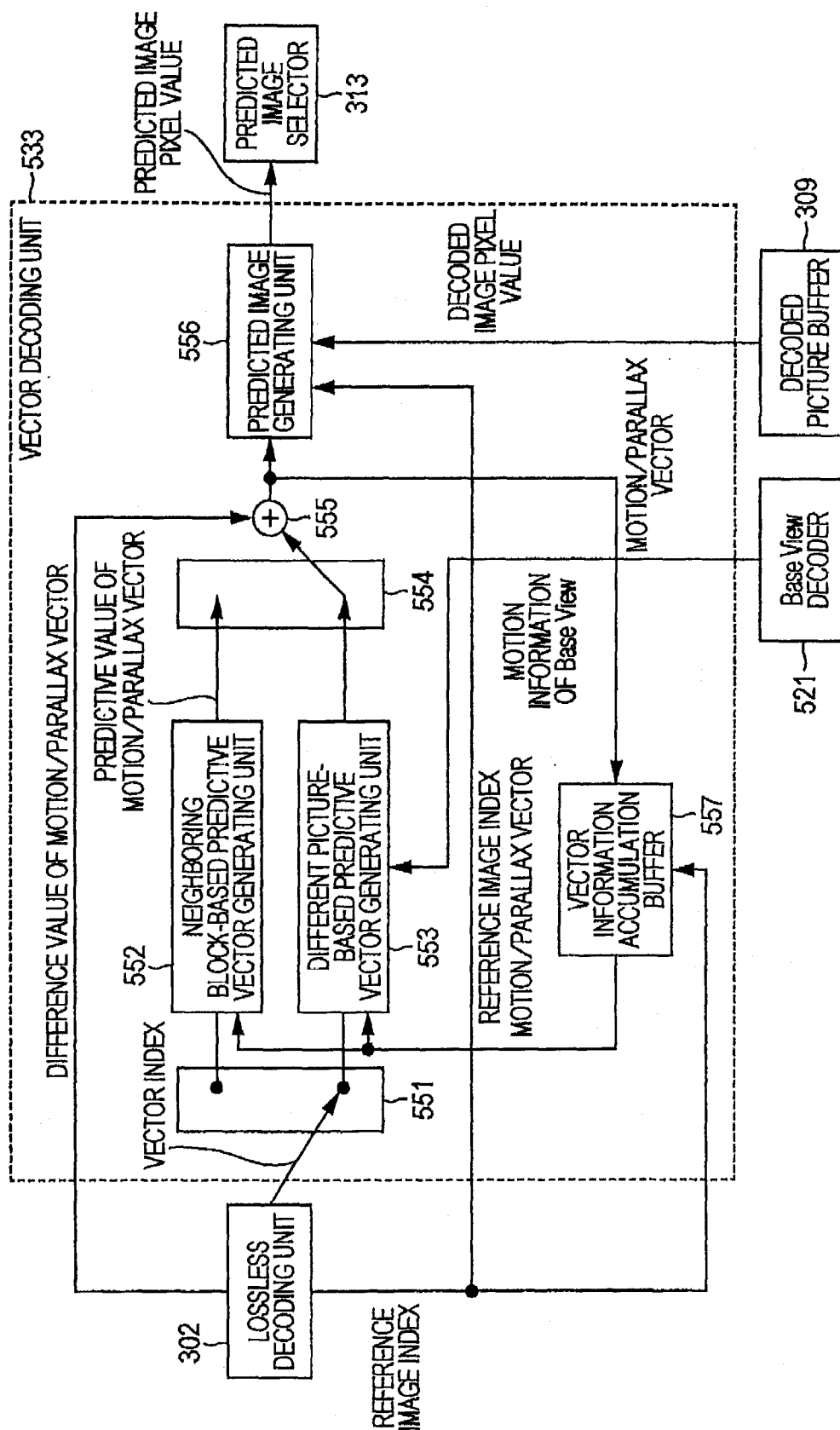
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FIG. 48



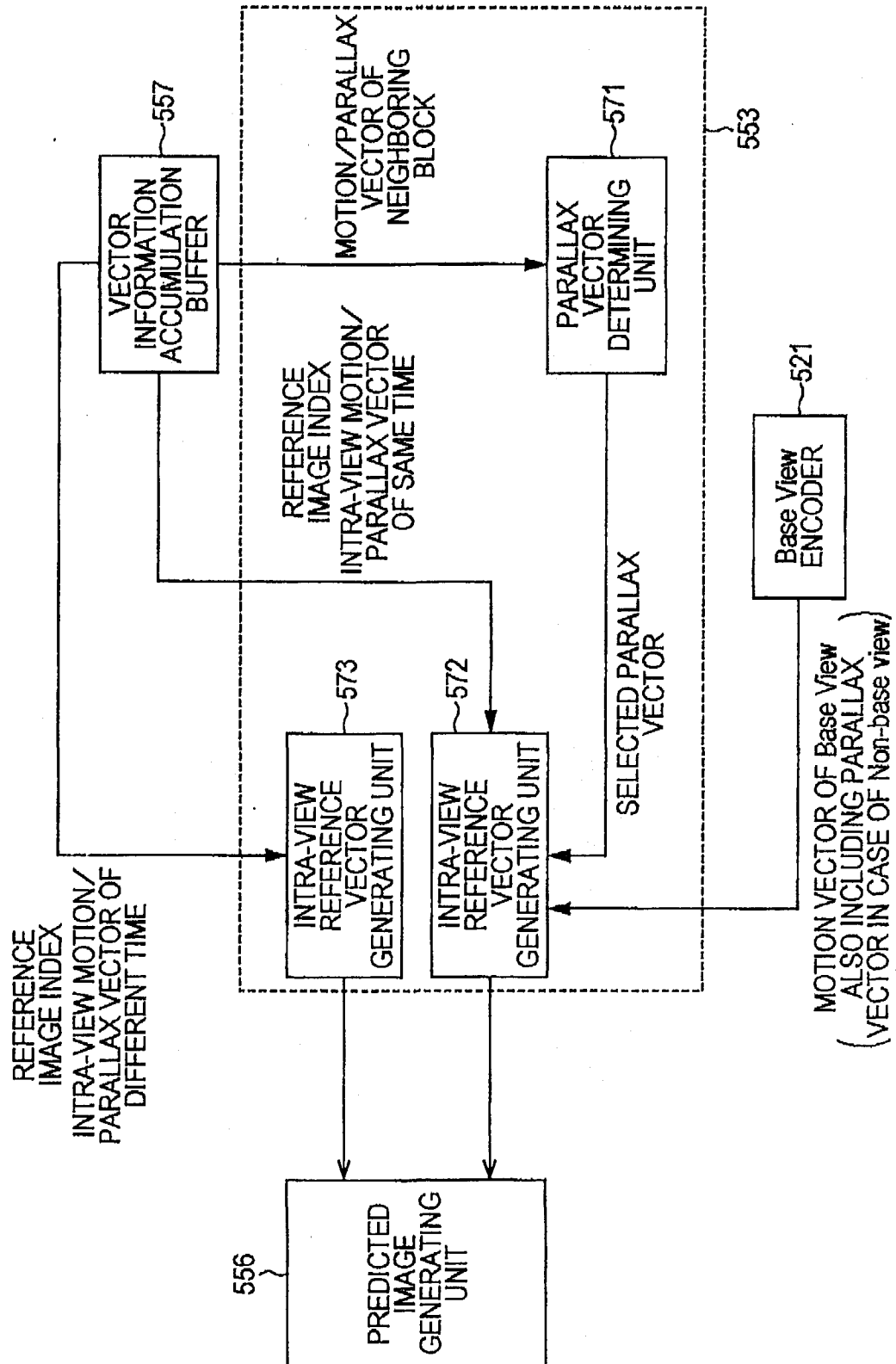
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FIG. 49



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FIG. 50



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FIG. 51

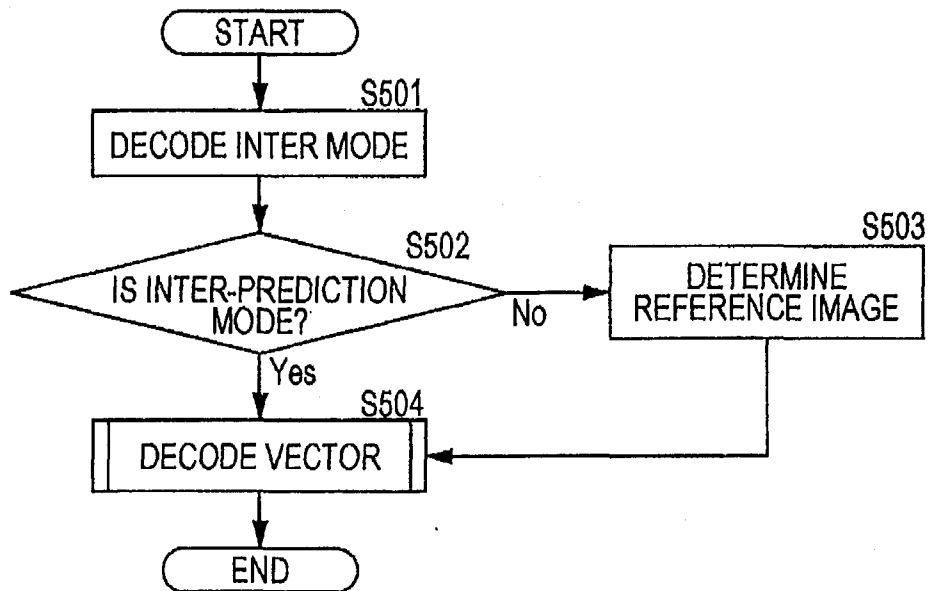
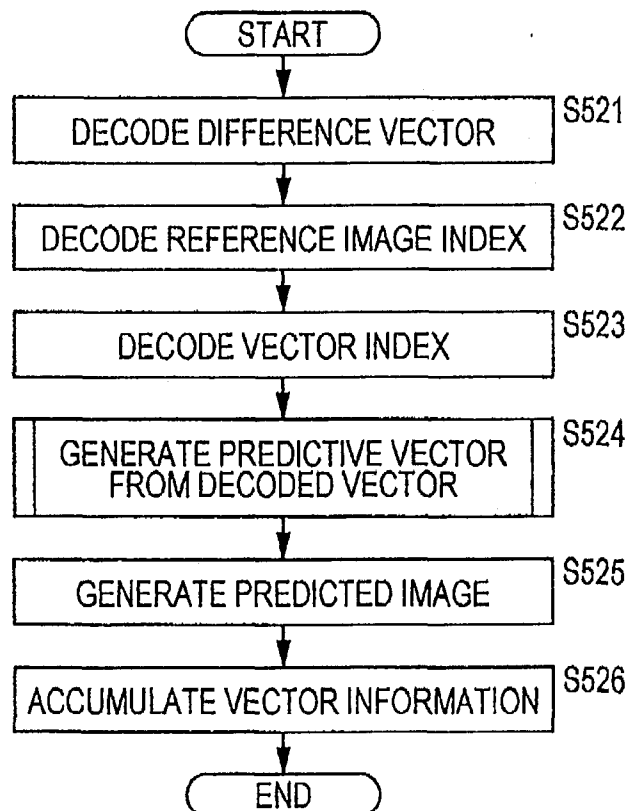
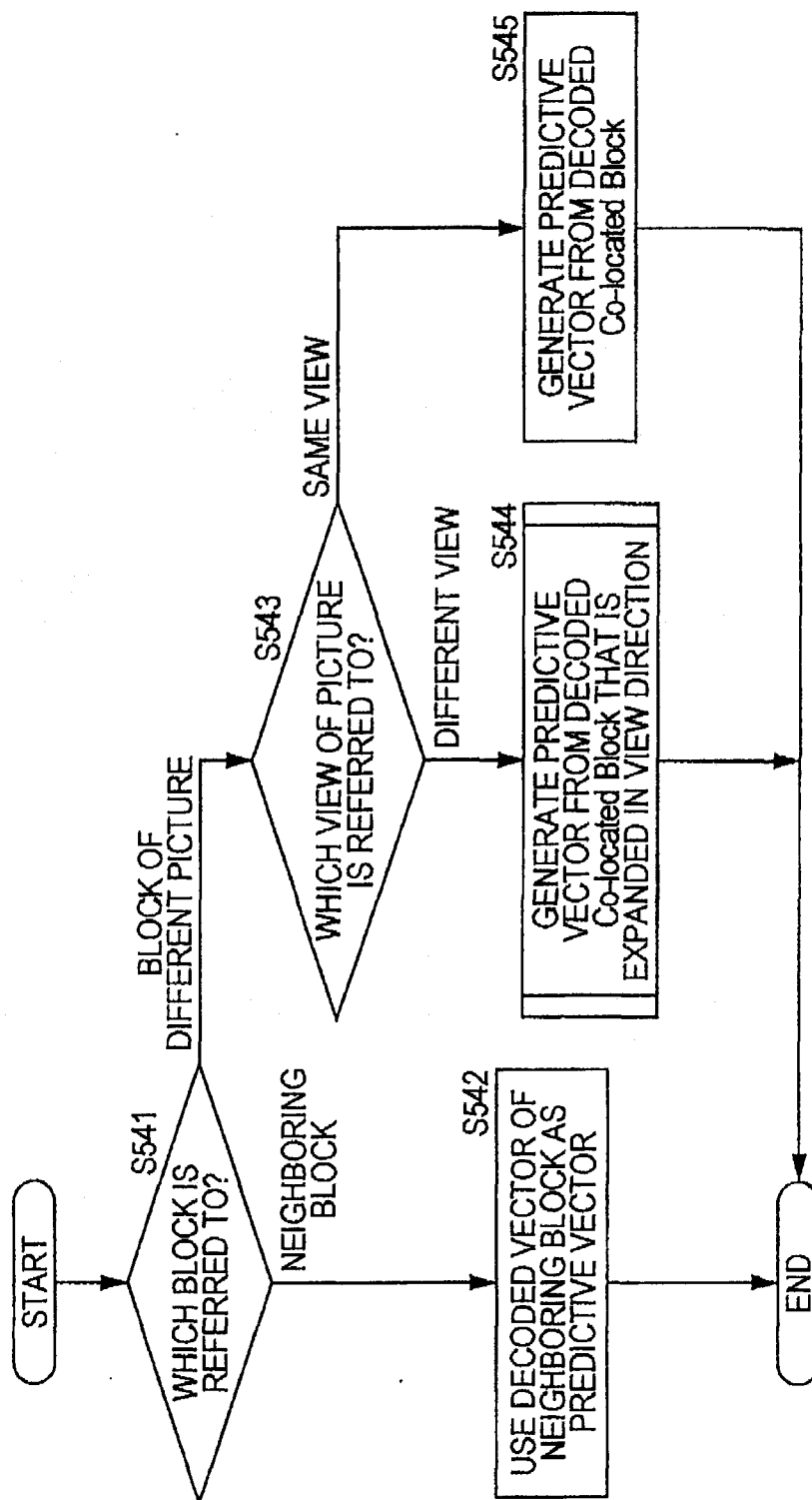


FIG. 52



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FIG. 53



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FIG. 54

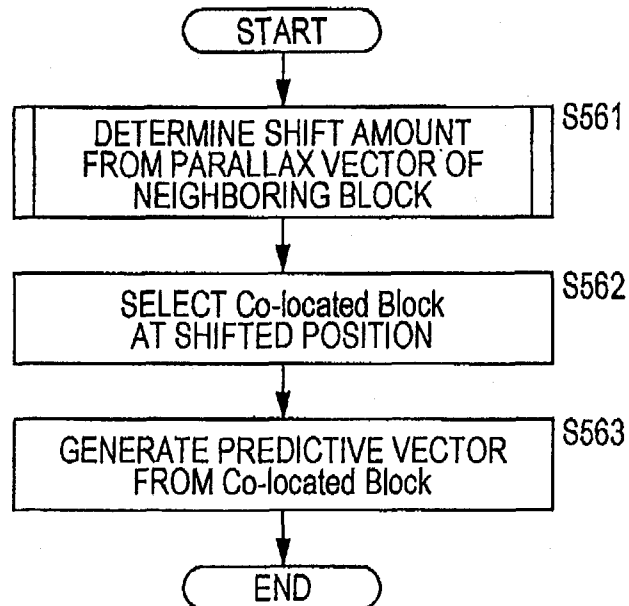


FIG. 55

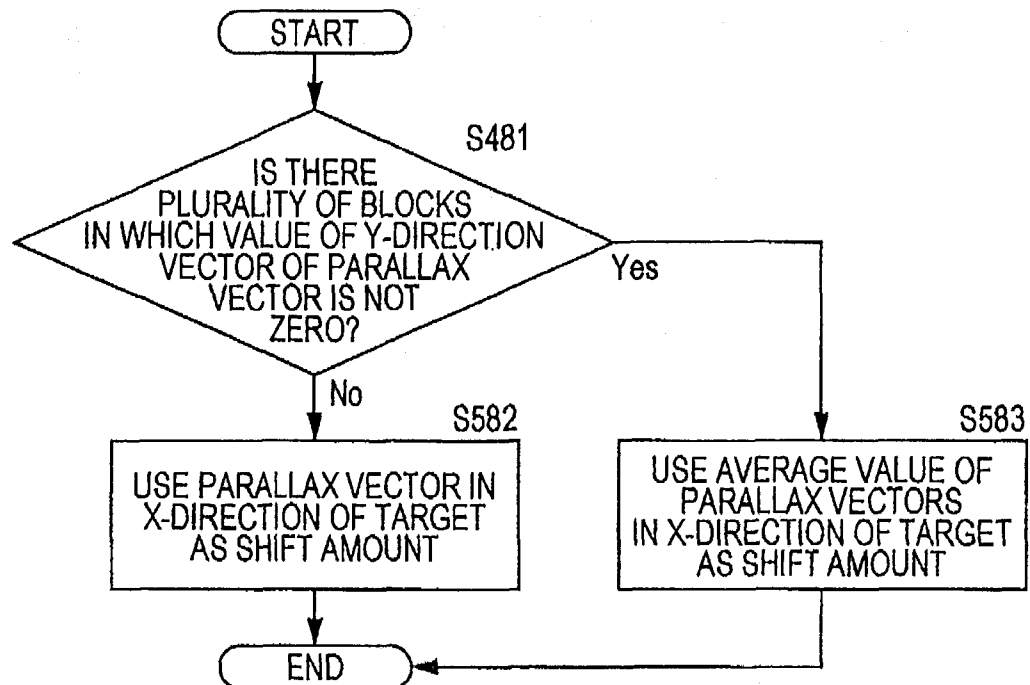
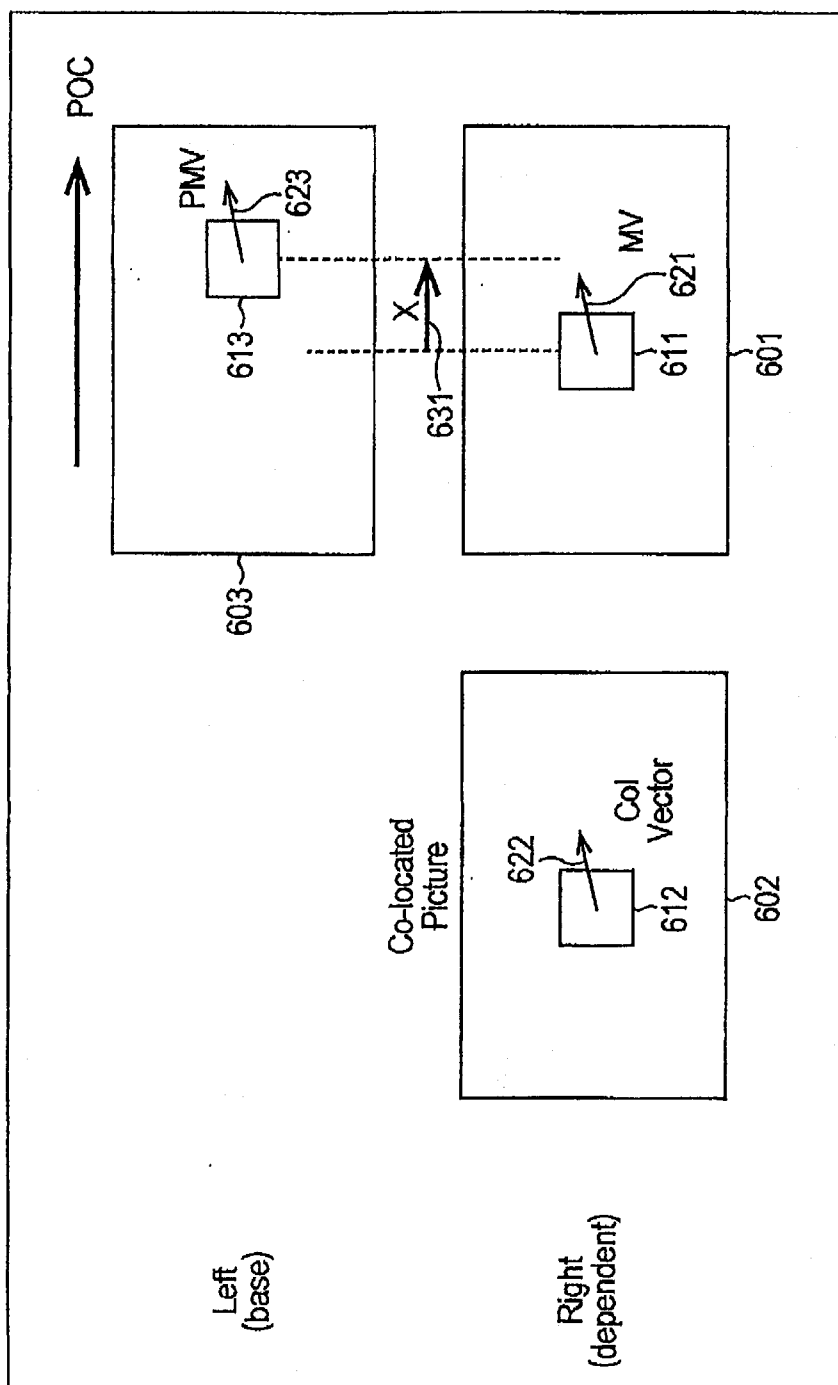


FIG. 56



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FIG. 57

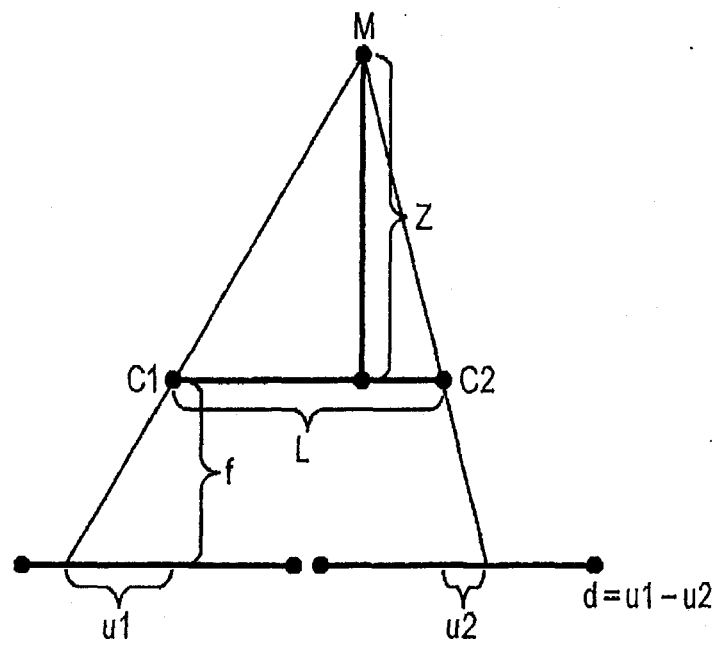


FIG. 58

CODING VECTOR	Co-located VECTOR	PROCESS
Motion vector	Motion vector	USE Co-located VECTOR AS PREDICTIVE VECTOR CANDIDATE
Motion vector	Inter-view vector	USE MOTION VECTOR OF Base View OF BLOCK SHIFTED BY Co-located VECTOR AS PREDICTIVE VECTOR CANDIDATE.
Motion vector	Intra mode	USE MOTION VECTOR OF Base View OF BLOCK SHIFTED BY GLOBAL PARALLAX VECTOR AS PREDICTIVE VECTOR CANDIDATE.
Inter-view vector	Motion vector	USE GLOBAL PARALLAX VECTOR AS PREDICTIVE VECTOR CANDIDATE.
Inter-view vector	Inter-view vector	USE Co-located VECTOR AS PREDICTIVE VECTOR CANDIDATE
Inter-view vector	Intra mode	USE GLOBAL PARALLAX VECTOR AS PREDICTIVE VECTOR CANDIDATE.

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FIG. 59

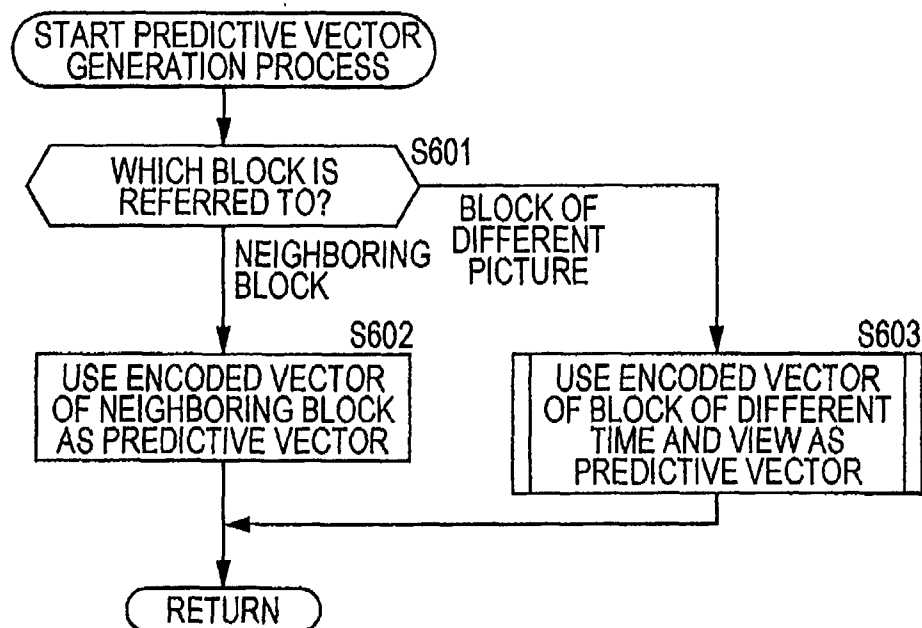
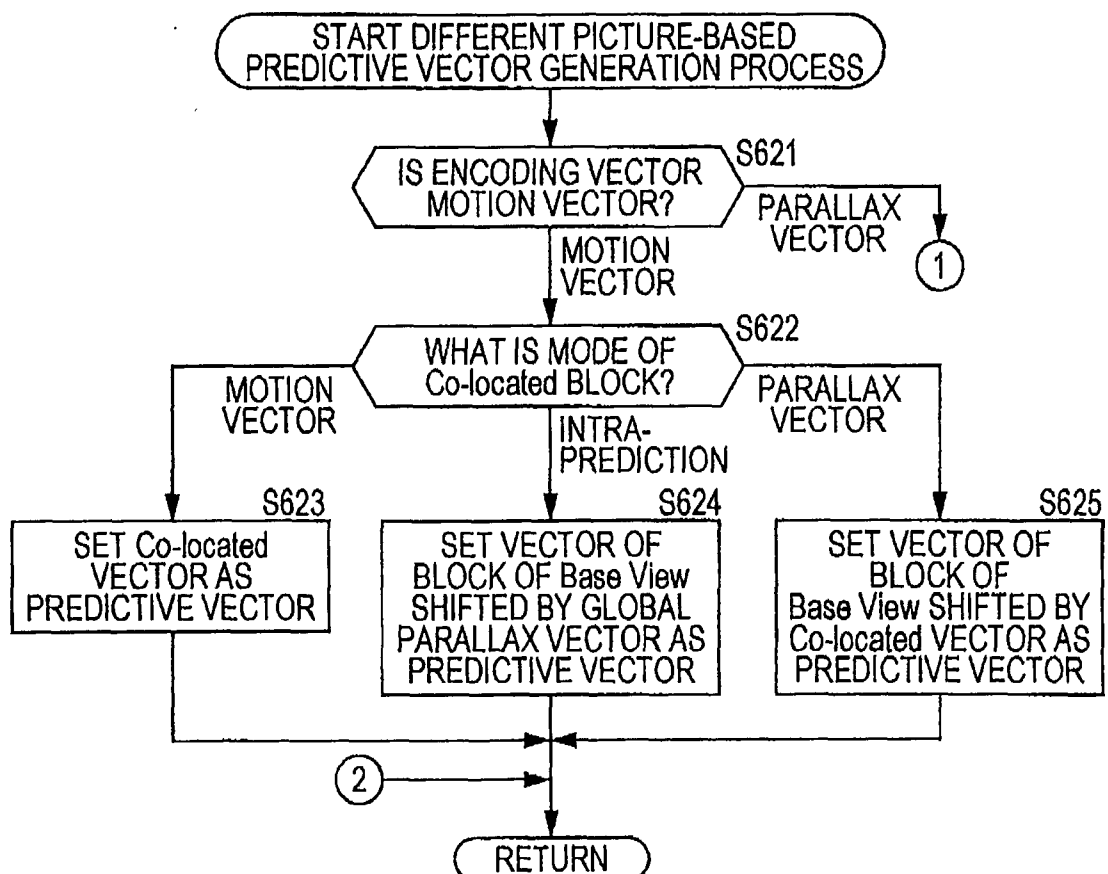


FIG. 60



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FIG. 61

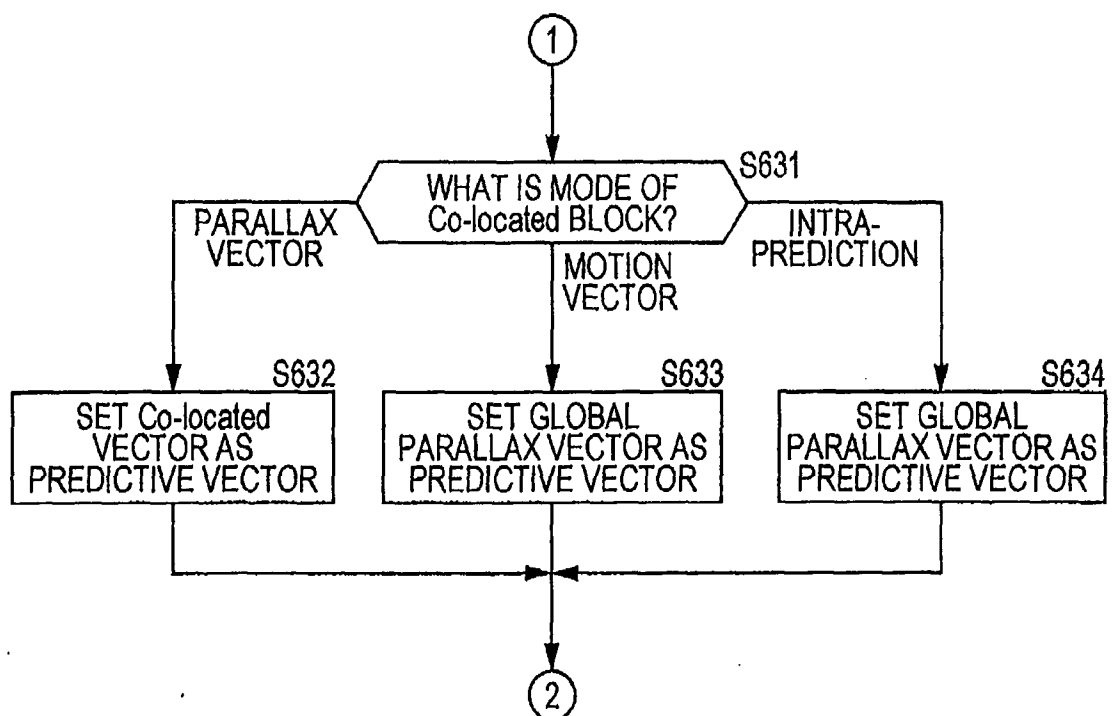


FIG. 62

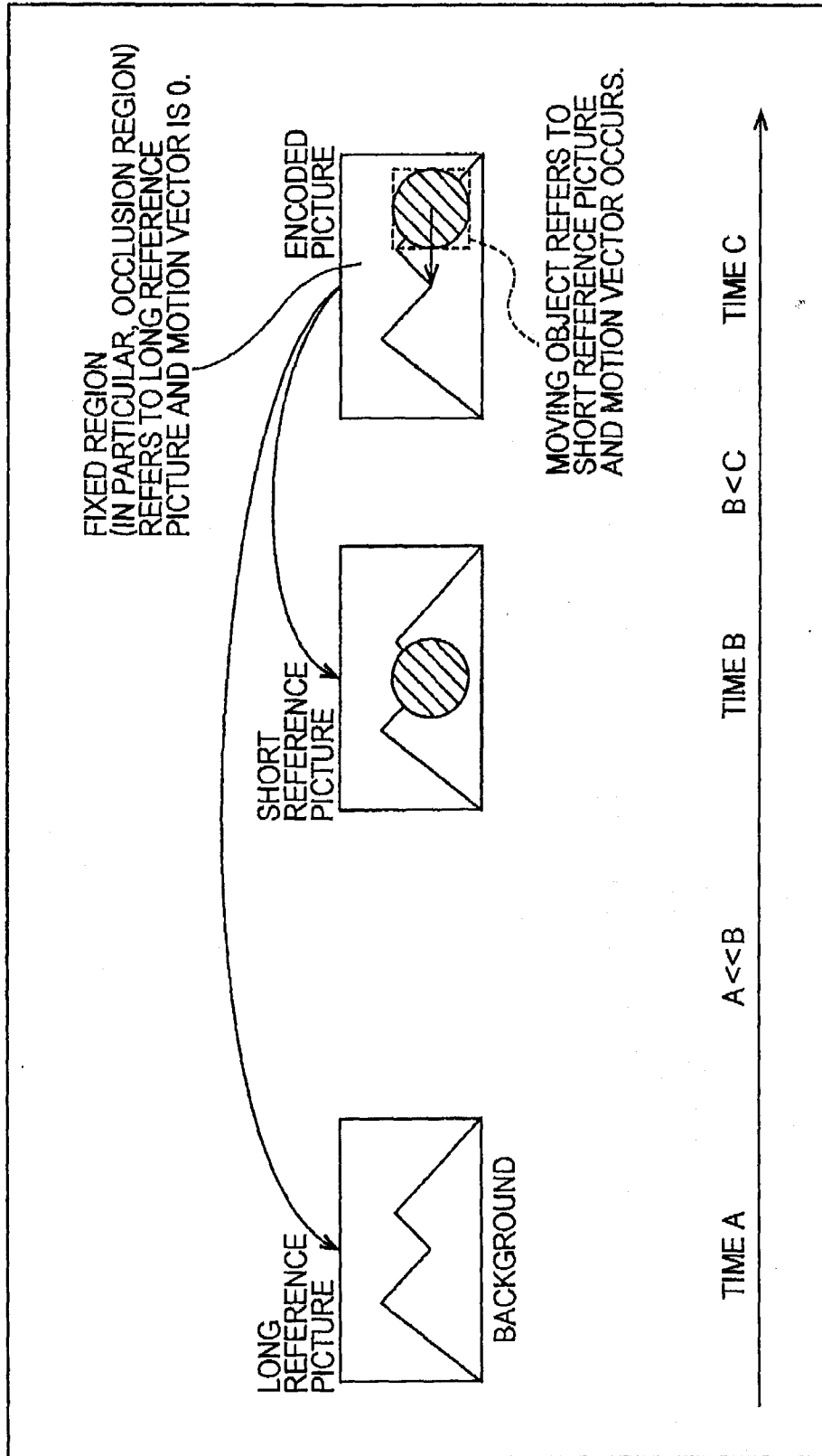


FIG. 63

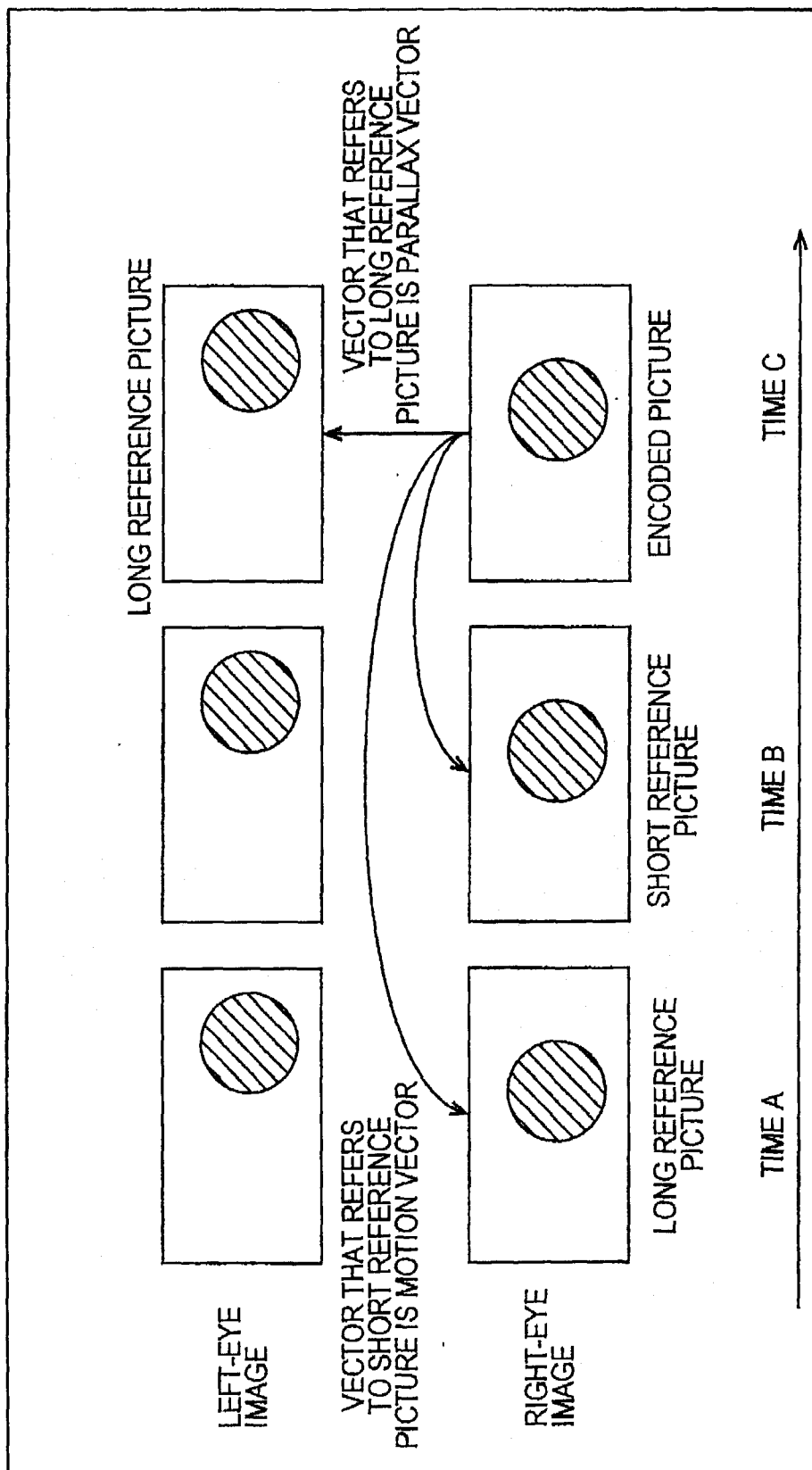


FIG. 64

FIXED BACKGROUND APPLICATION

TYPE OF REFERENCE IMAGE	VECTOR PROPERTY
SHORT REFERENCE PICTURE	MOTION VECTOR OCCURS (IS LONG) BECAUSE IT IS MAINLY REFERRED TO FOR MOVING OBJECT
LONG REFERENCE PICTURE	MOTION VECTOR IS 0 (IS SHORT) BECAUSE IT IS MAINLY REFERRED TO FOR FIXED REGION (IN PARTICULAR, OCCLUSION REGION)

A

STEREO APPLICATION

TYPE OF REFERENCE IMAGE	VECTOR PROPERTY
SHORT REFERENCE PICTURE	MOTION VECTOR OCCURS BECAUSE IT IS REFERRED TO FOR TEMPORAL PREDICTION
LONG REFERENCE PICTURE	PARALLAX VECTOR OCCURS BECAUSE IT IS REFERRED TO FOR PARALLAX PREDICTION

B

FIG. 65

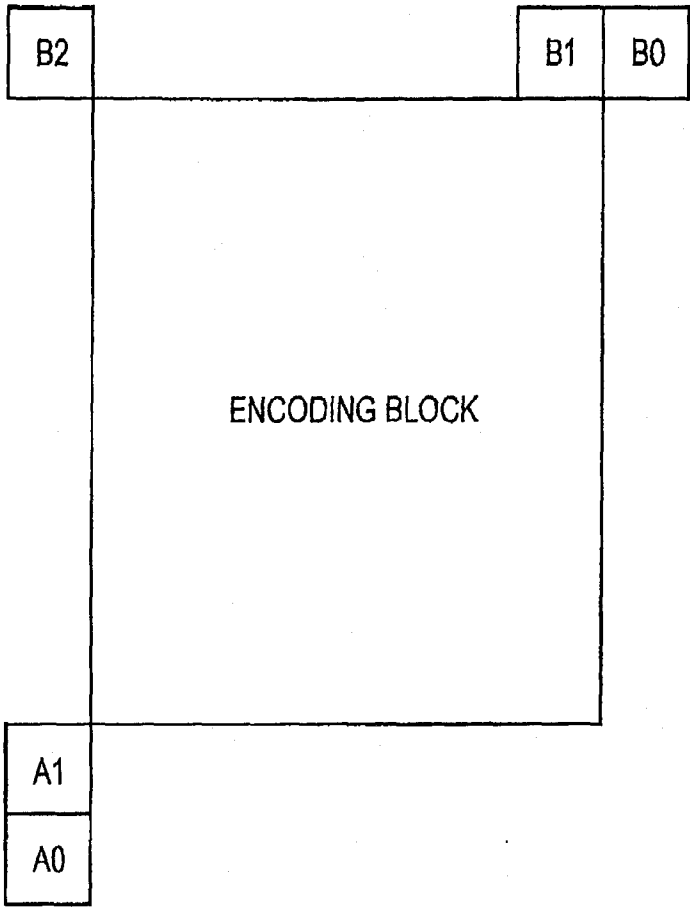


FIG. 66

Index	REFERENCE IMAGE OF ENCODING BLOCK	REFERENCE IMAGE OF TEMPORAL CORRELATION BLOCK	PRESENCE OF CANDIDATE MOTION (PARALLAX) VECTOR OF TEMPORAL CORRELATION BLOCK	SCALING OF MOTION (PARALLAX) VECTOR OF TEMPORAL CORRELATION BLOCK
1	SHORT REFERENCE PICTURE	SHORT REFERENCE PICTURE	INCLUDED IN CANDIDATE	YES
2	SHORT REFERENCE PICTURE	LONG REFERENCE PICTURE	EXCLUDED FROM CANDIDATE	—
3	LONG REFERENCE PICTURE	LONG REFERENCE PICTURE	INCLUDED IN CANDIDATE	NO
4	LONG REFERENCE PICTURE	SHORT REFERENCE PICTURE	EXCLUDED FROM CANDIDATE	—

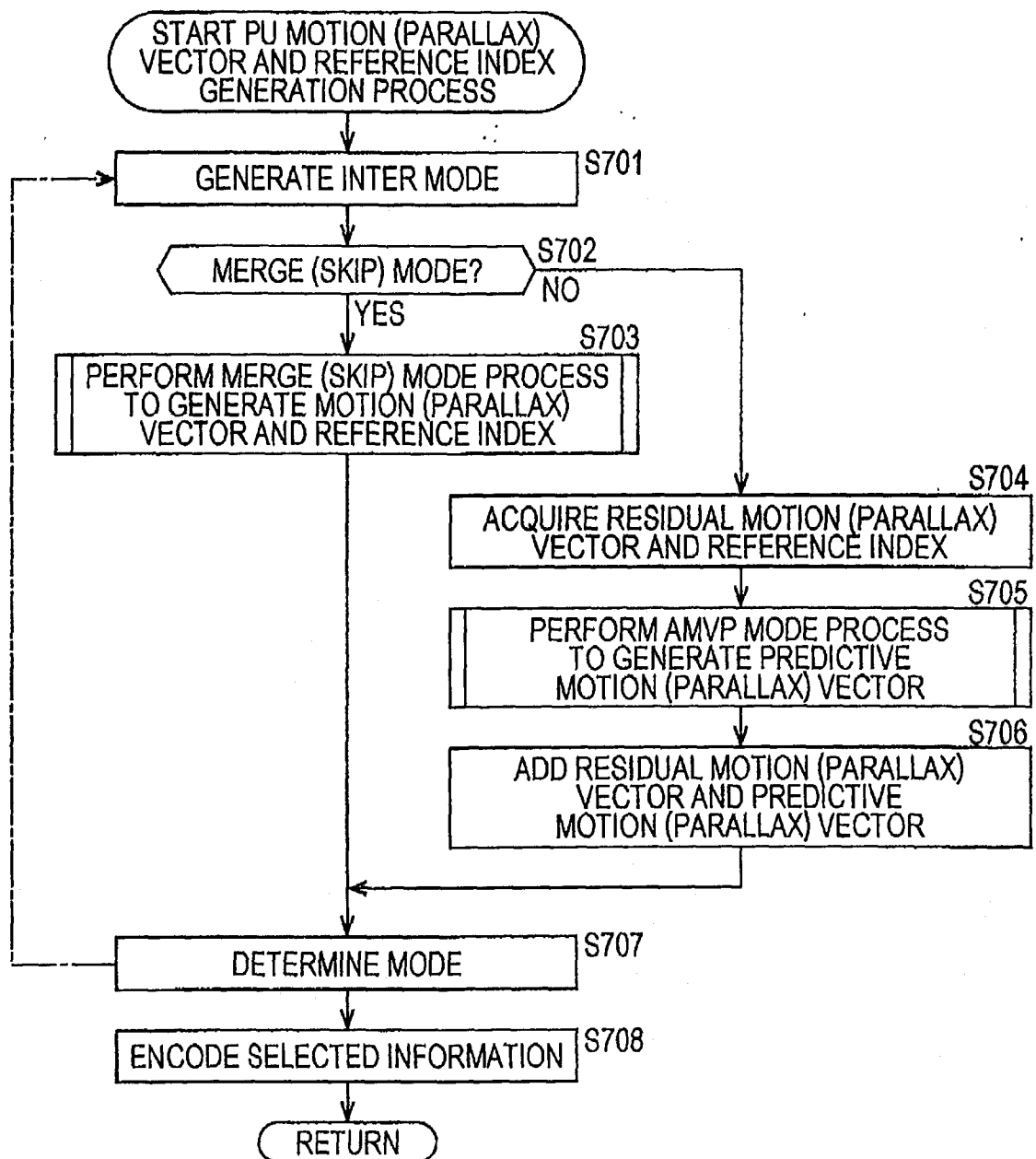
A

Index	REFERENCE IMAGE OF ENCODING BLOCK	REFERENCE IMAGE OF NEIGHBORING BLOCK	PRESENCE OF CANDIDATE MOTION (PARALLAX) VECTOR OF NEIGHBORING BLOCK	SCALING OF MOTION (PARALLAX) VECTOR OF NEIGHBORING BLOCK
1	SHORT REFERENCE PICTURE	SHORT REFERENCE PICTURE	INCLUDED IN CANDIDATE	YES
2	SHORT REFERENCE PICTURE	LONG REFERENCE PICTURE	EXCLUDED FROM CANDIDATE	—
3	LONG REFERENCE PICTURE	LONG REFERENCE PICTURE	INCLUDED IN CANDIDATE	NO
4	LONG REFERENCE PICTURE	SHORT REFERENCE PICTURE	EXCLUDED FROM CANDIDATE	—

B

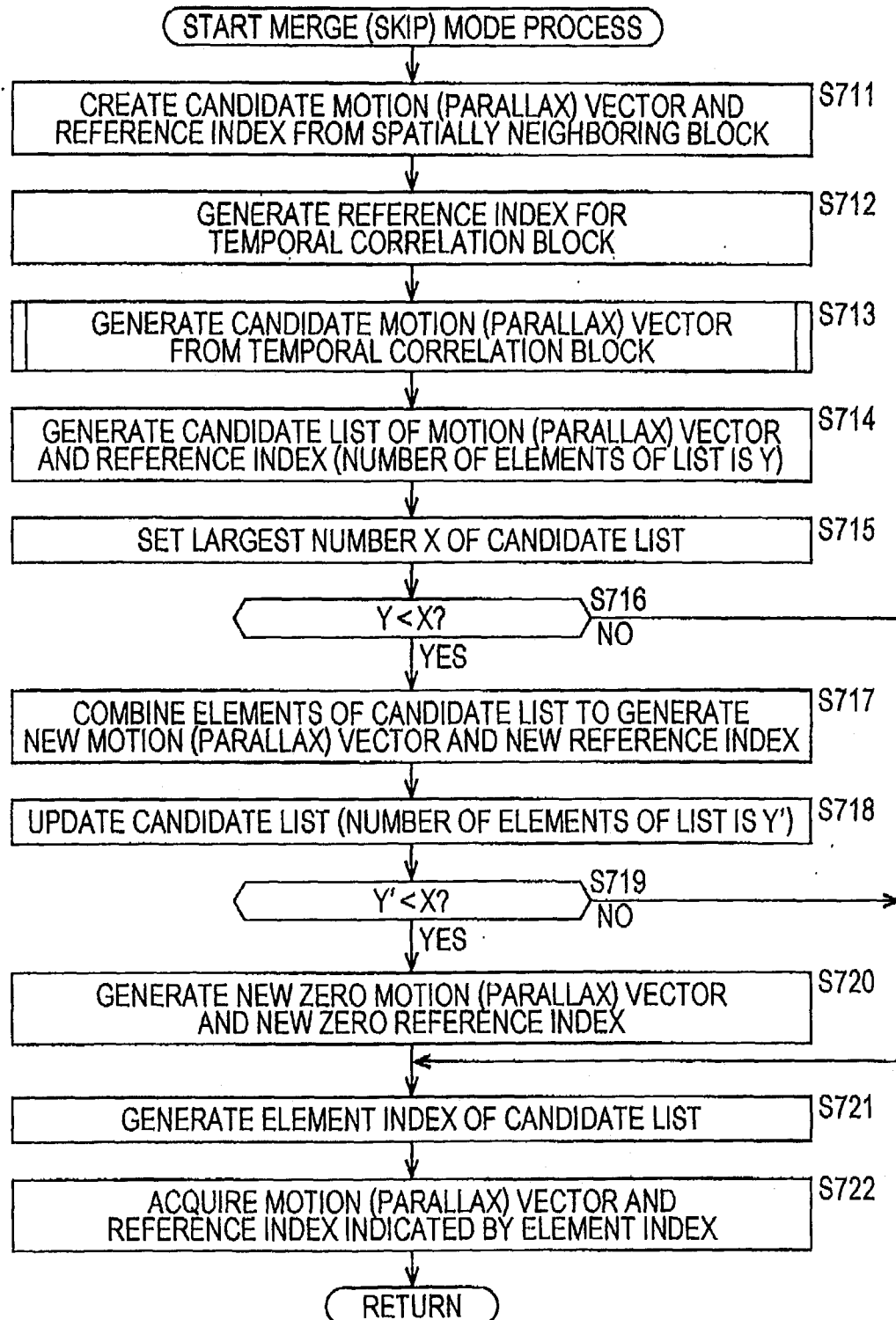
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FIG. 67



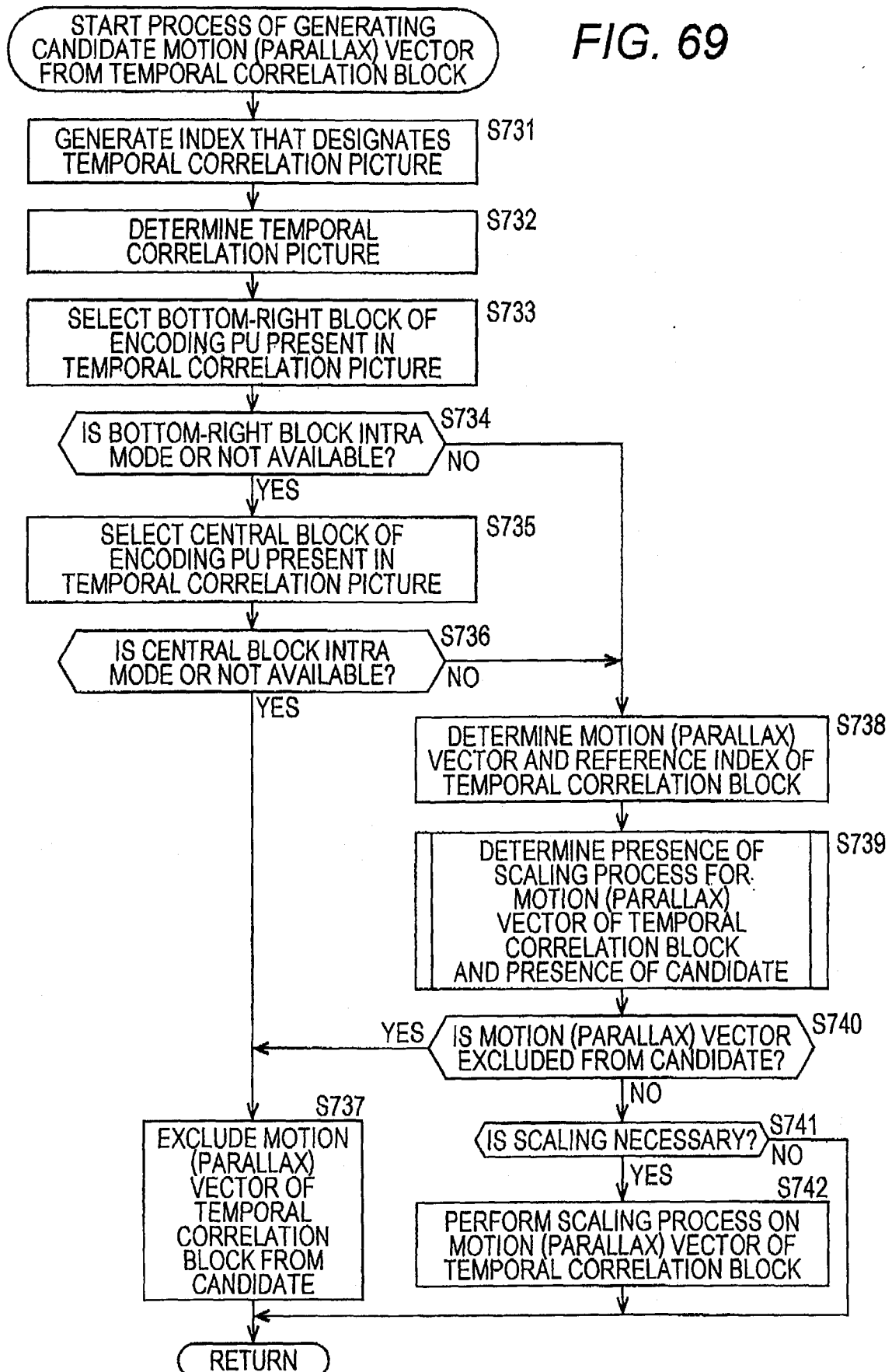
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FIG. 68



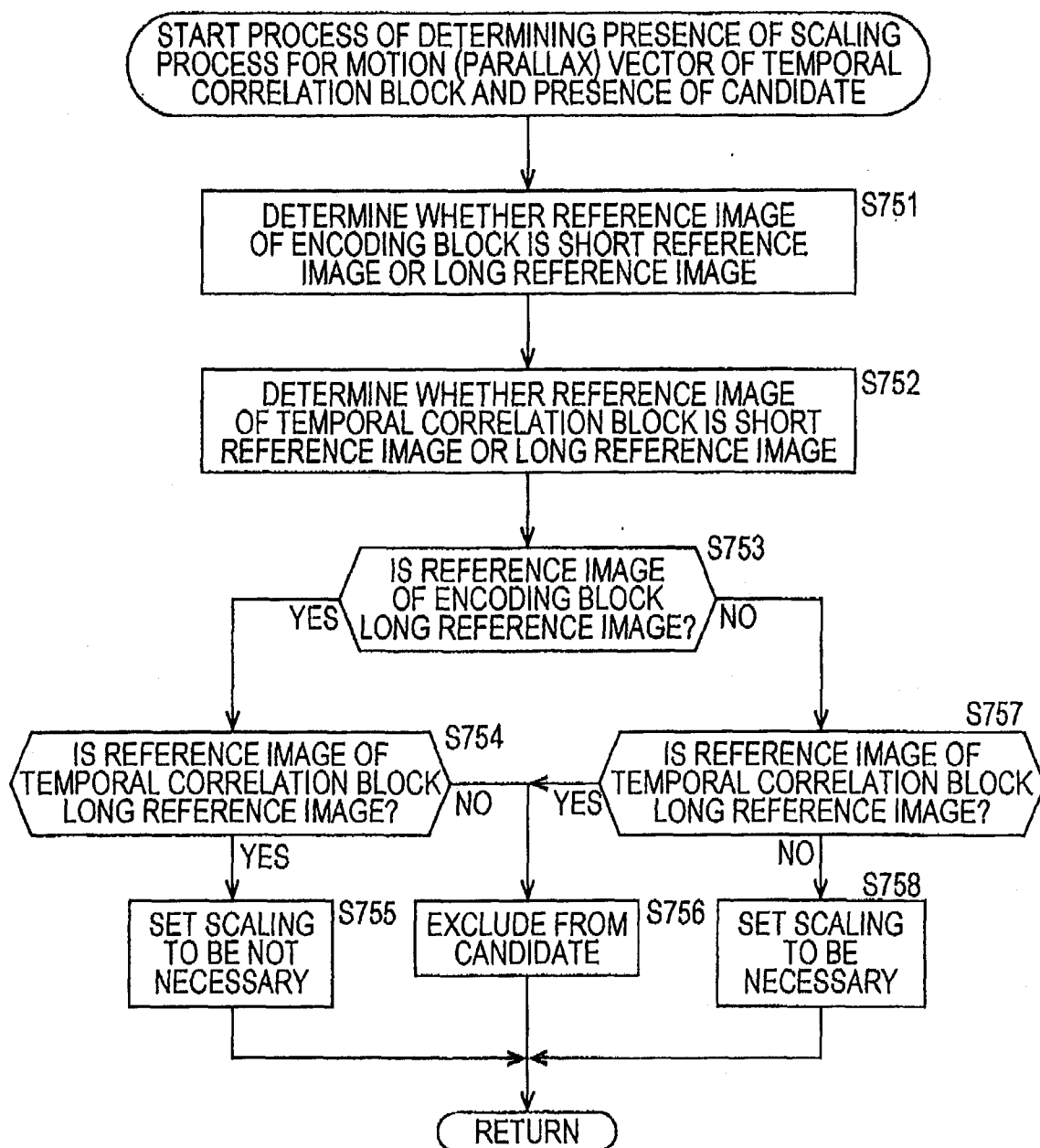
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FIG. 69



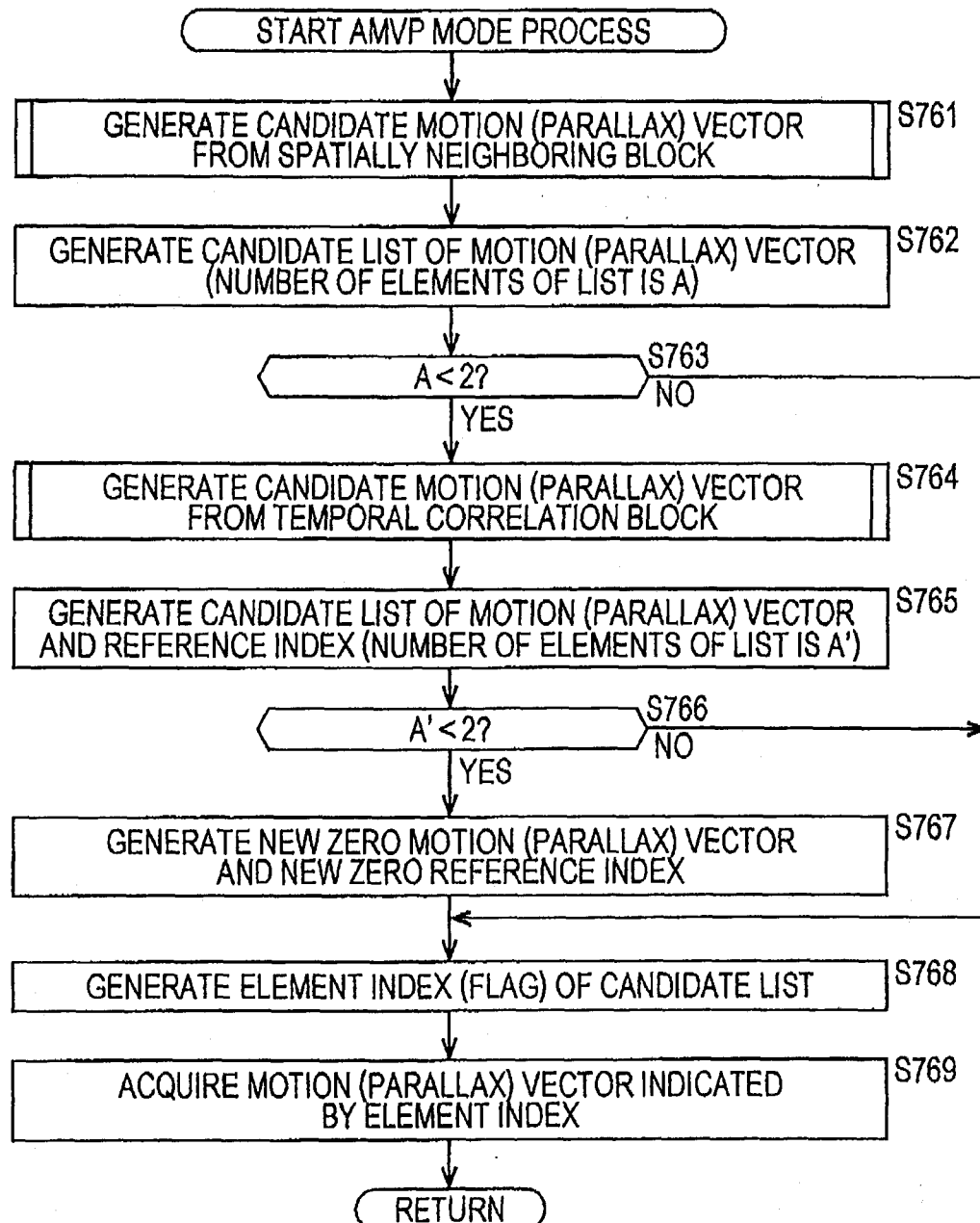
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FIG. 70



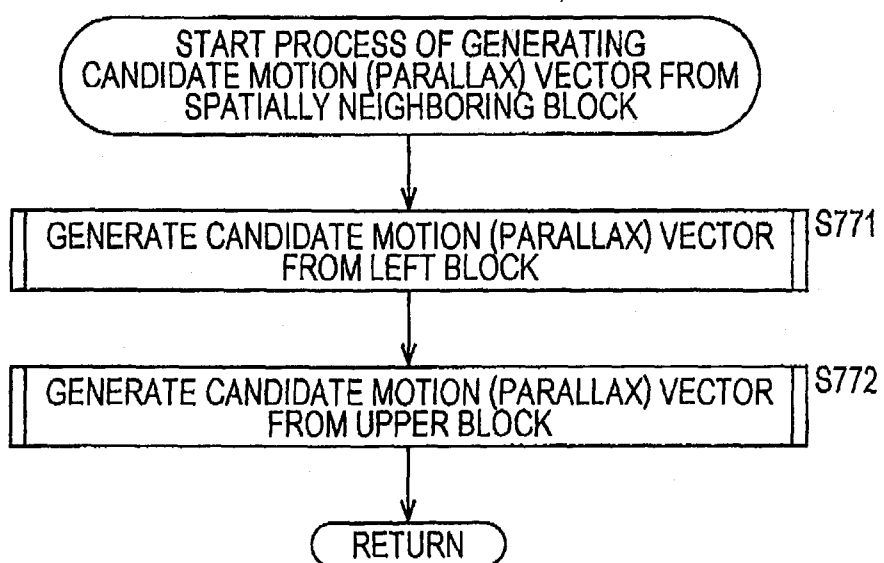
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FIG. 71



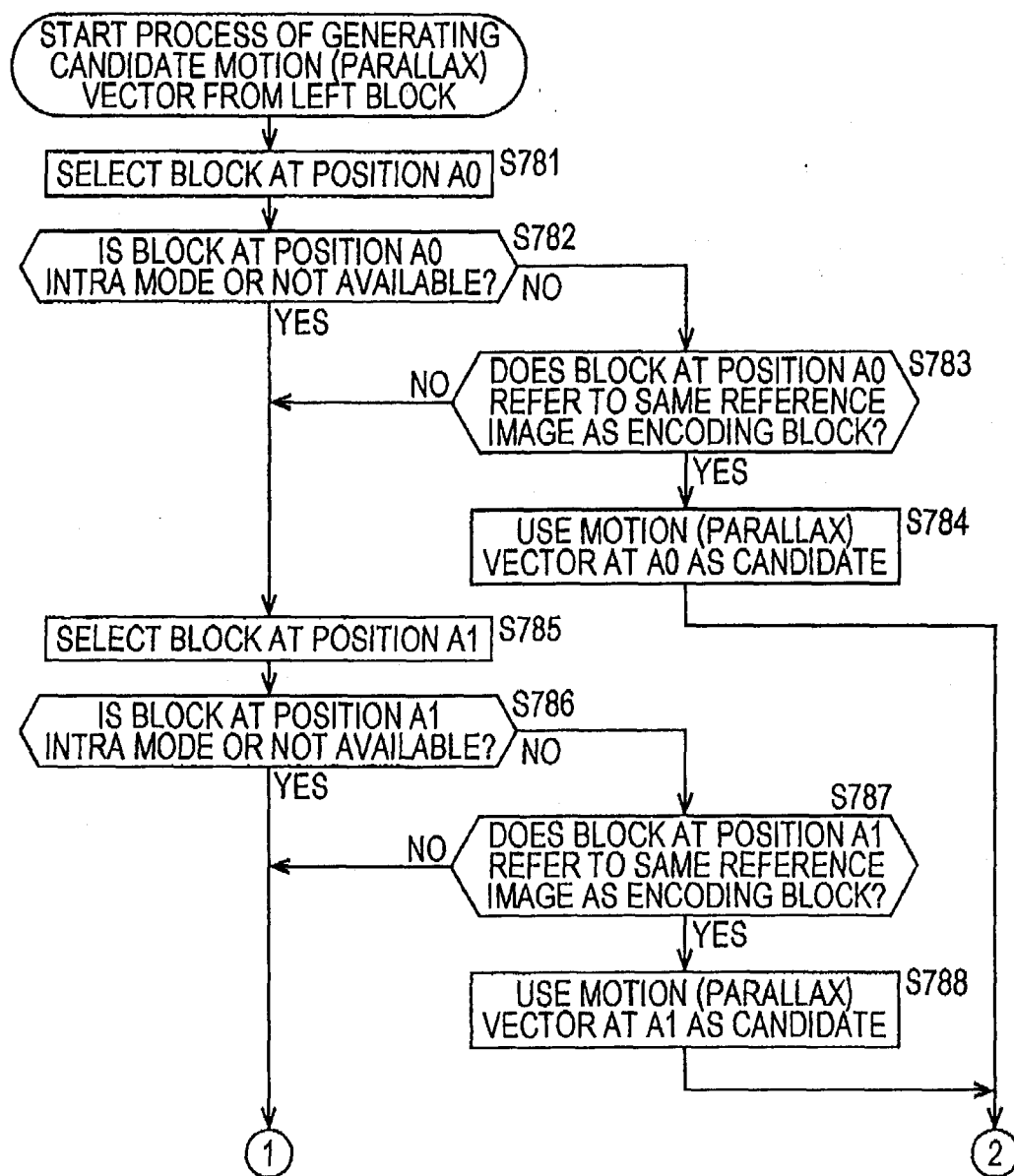
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FIG. 72



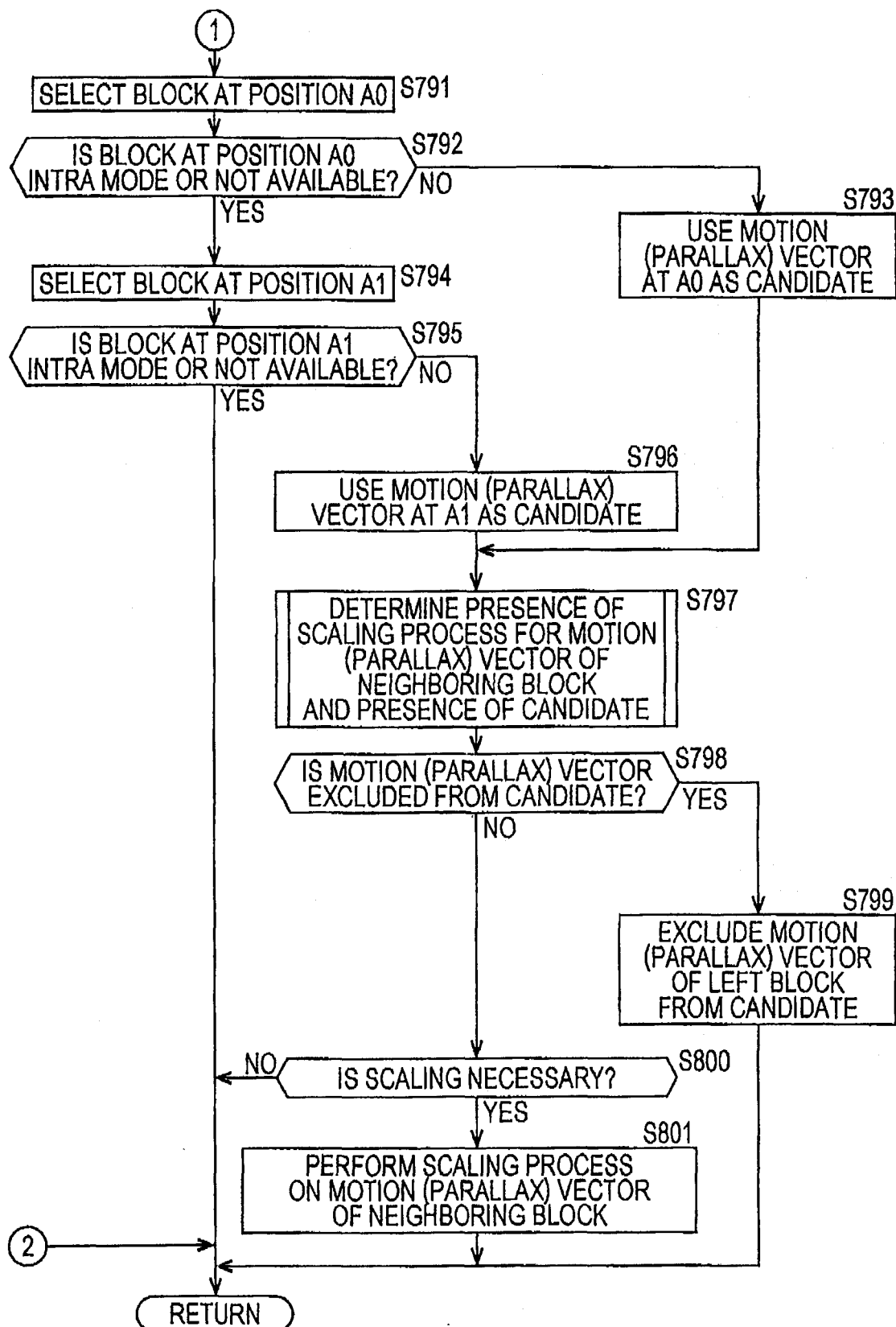
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FIG. 73



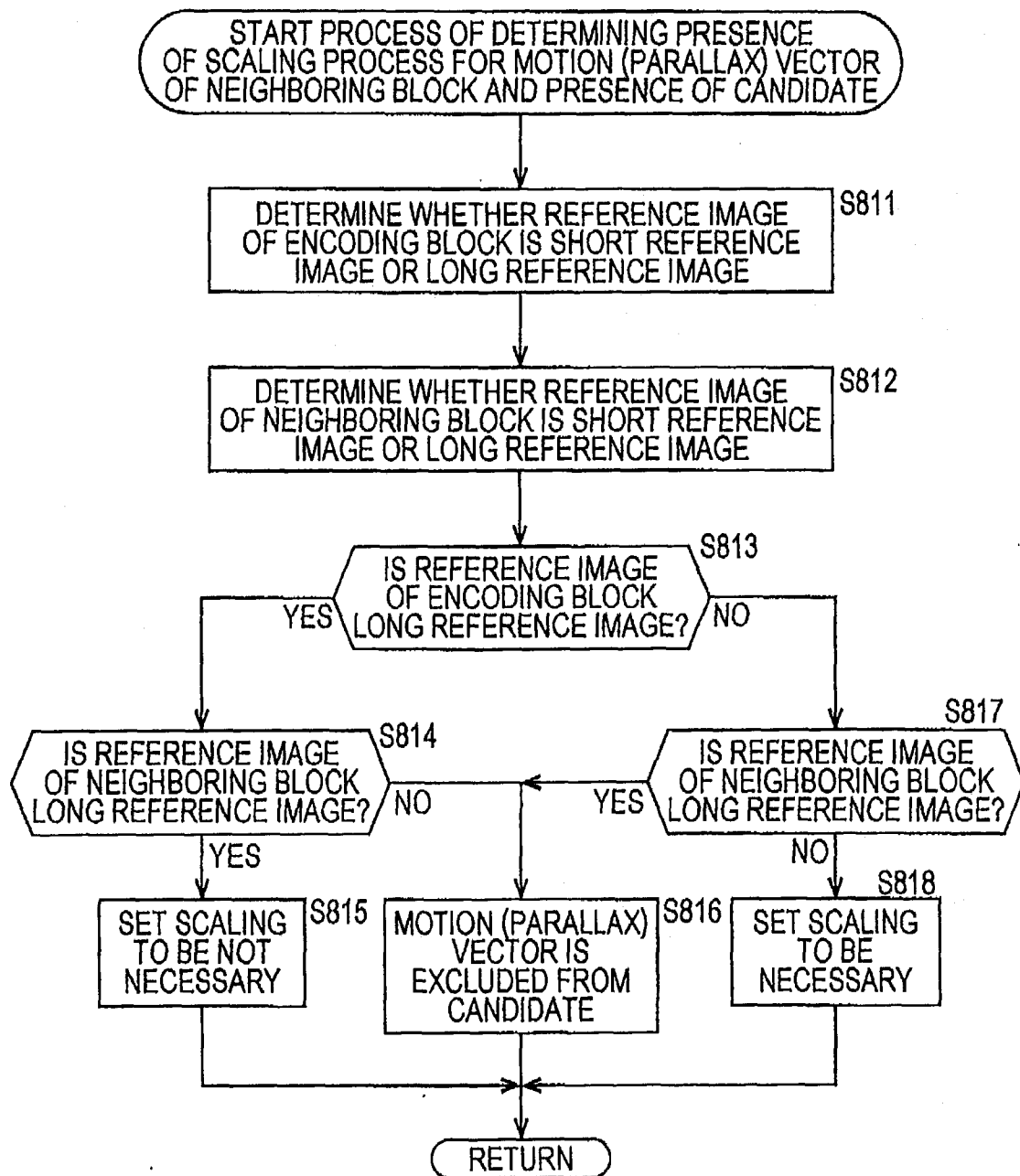
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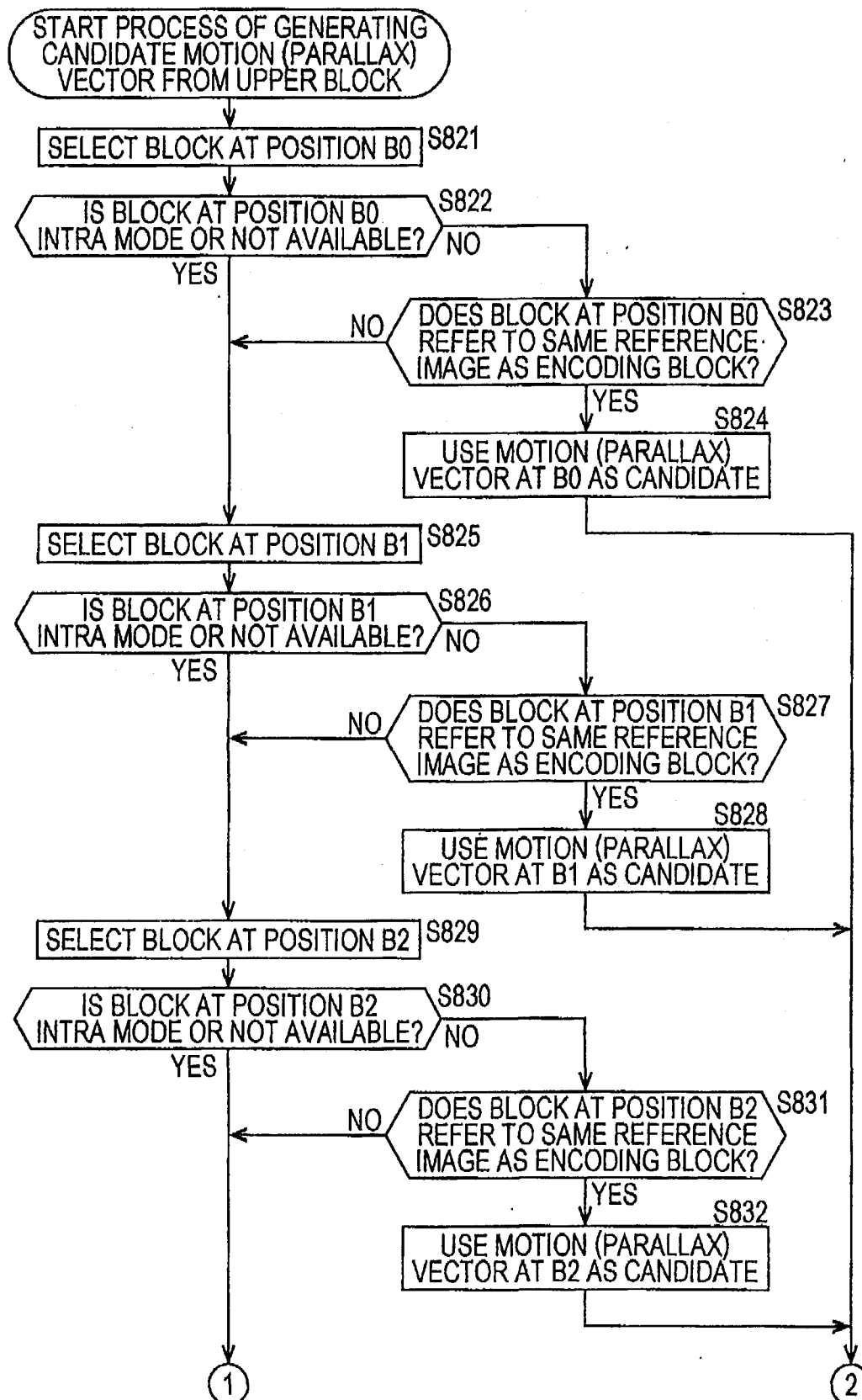
FIG. 74



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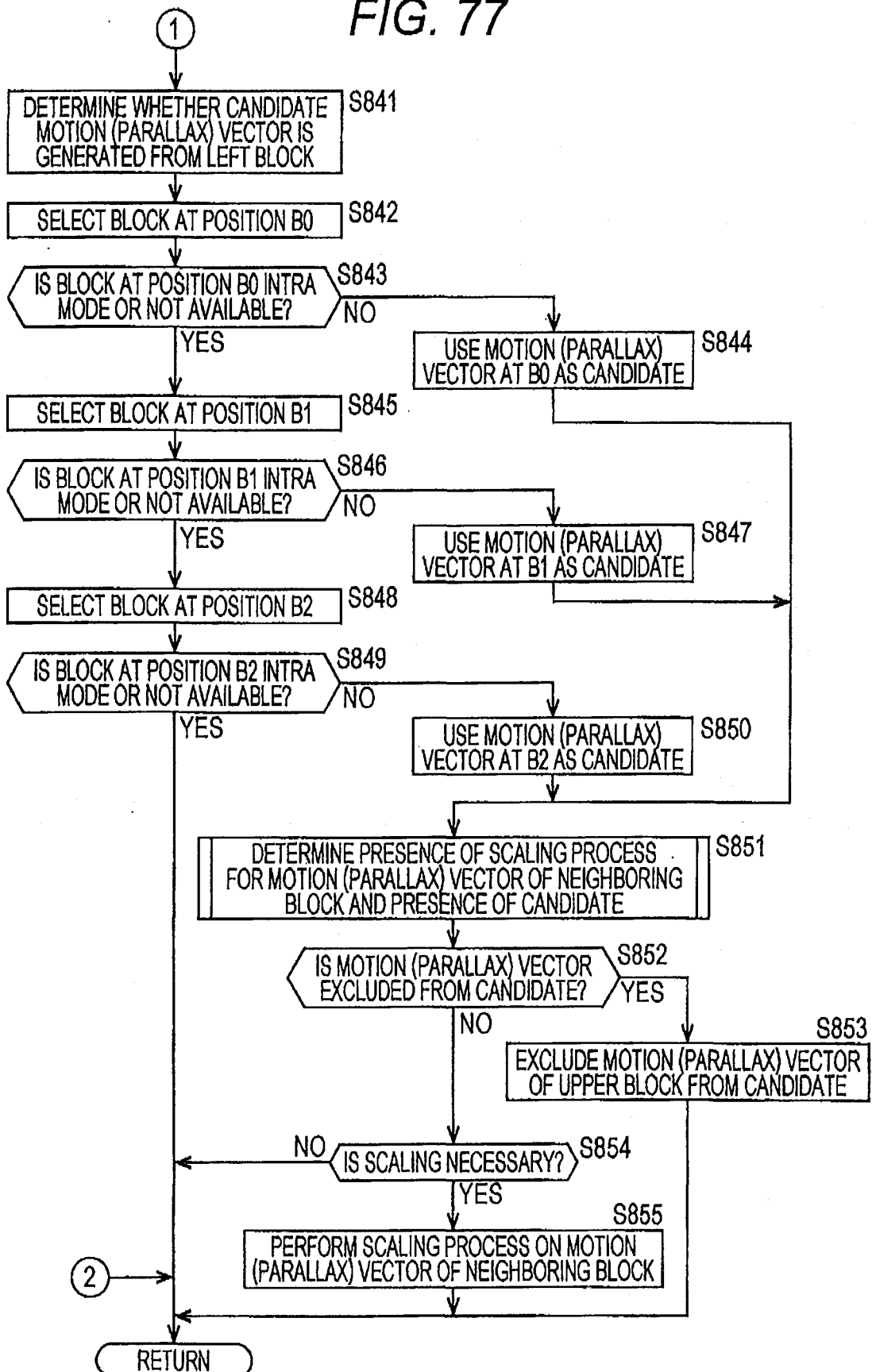
FIG. 75



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FIG. 76

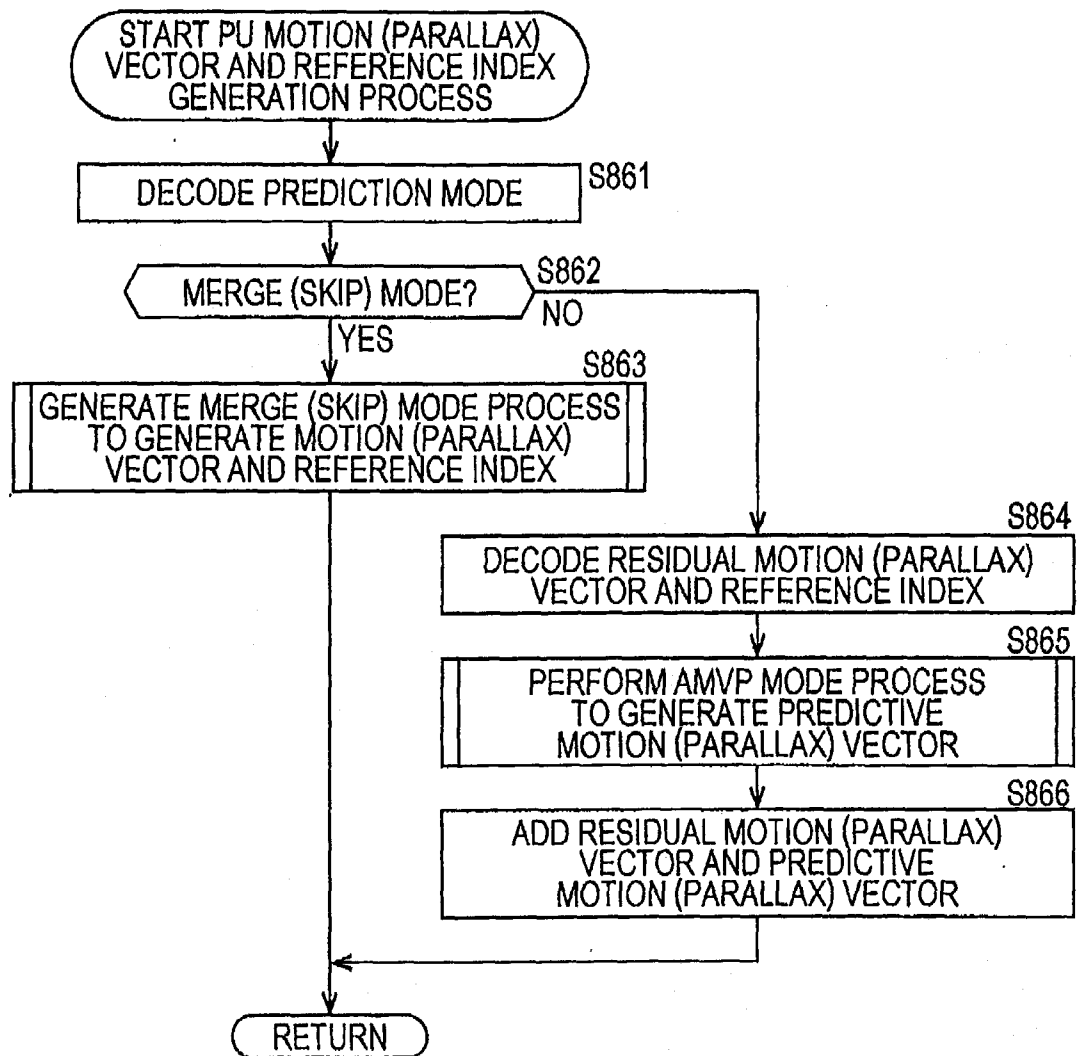
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FIG. 77



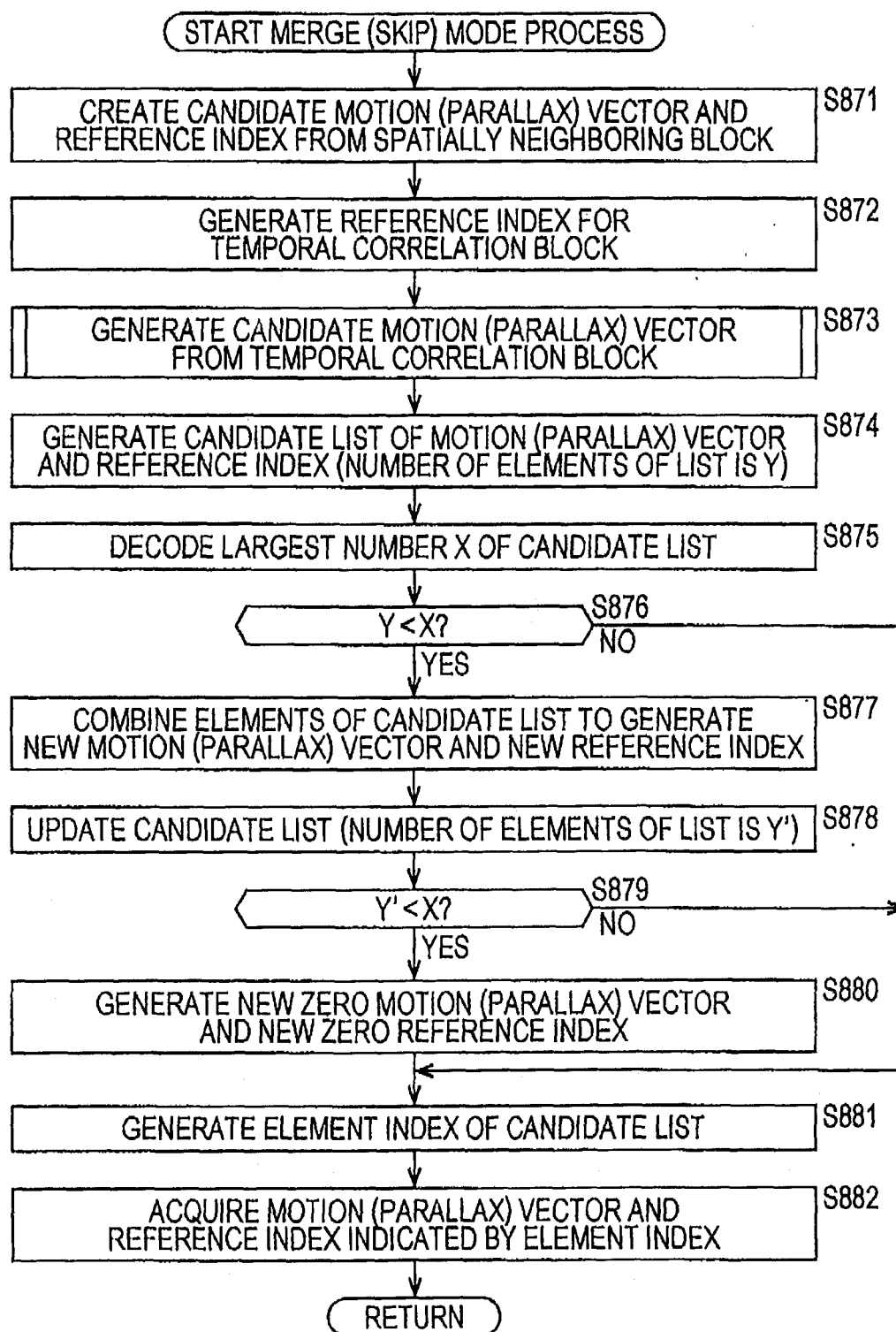
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FIG. 78



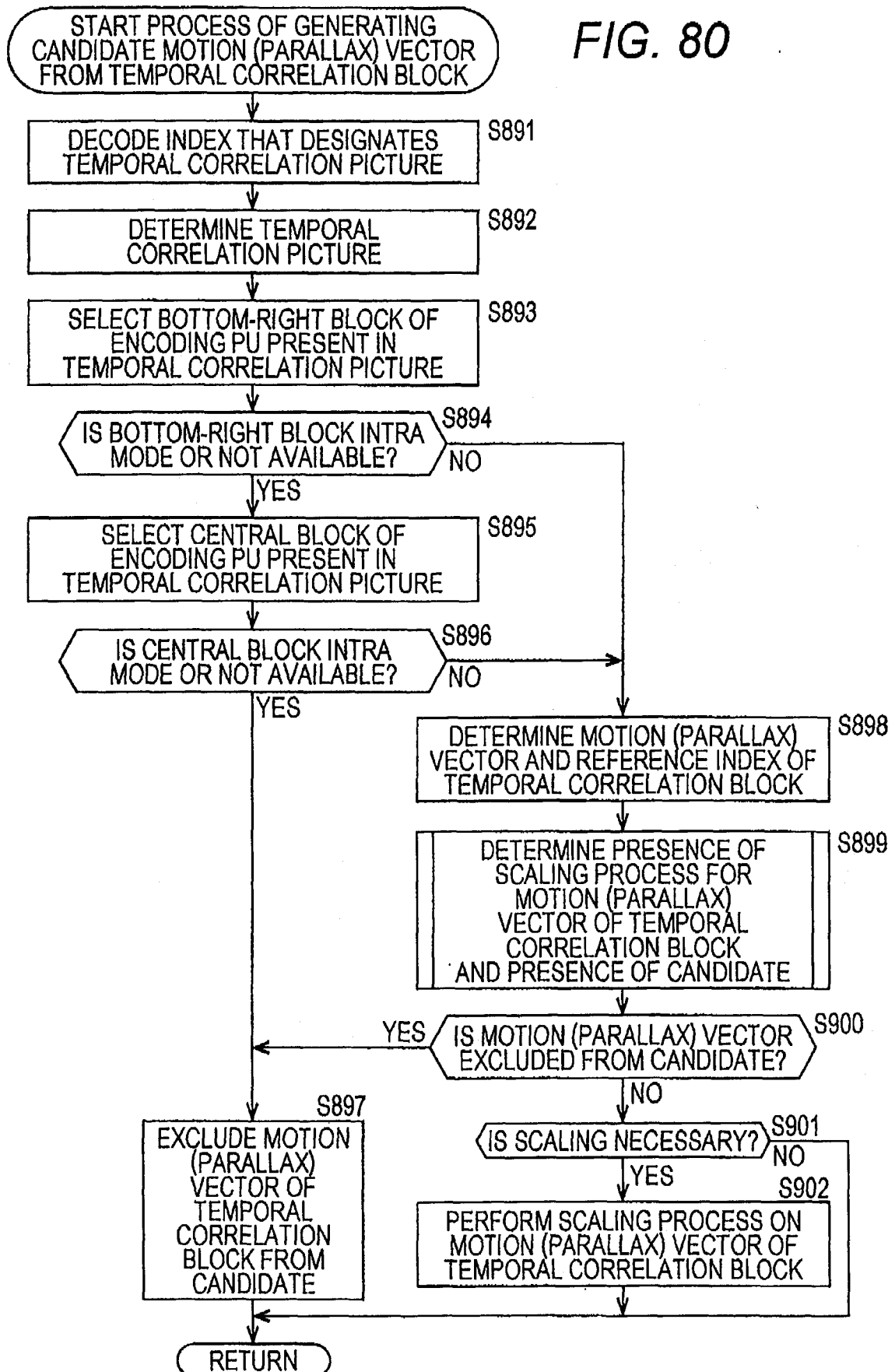
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FIG. 79



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FIG. 80



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FIG. 81

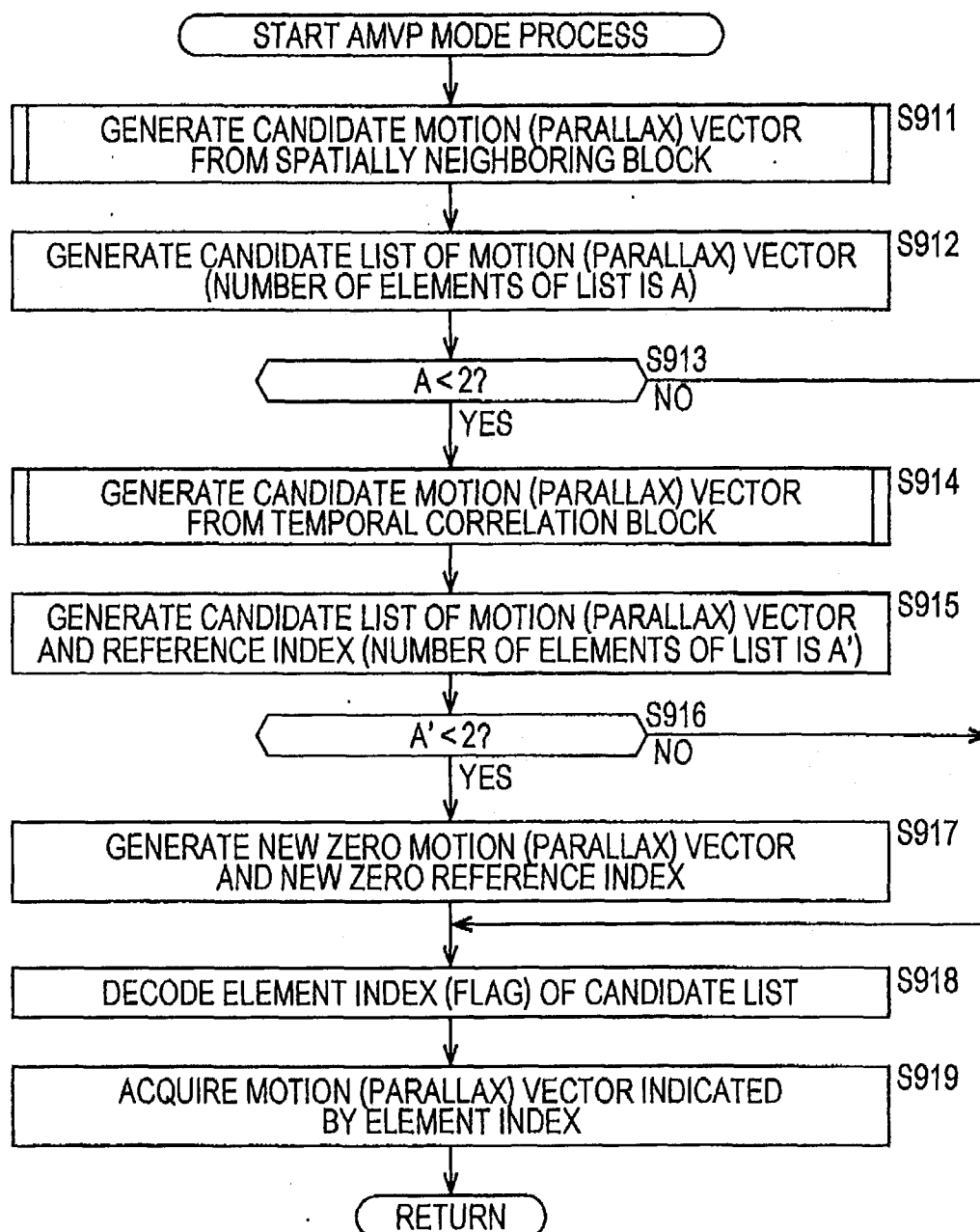


FIG. 82

Index	REFERENCE IMAGE OF ENCODING BLOCK	REFERENCE IMAGE OF NEIGHBORING BLOCK	PRESENCE OF CANDIDATE MOTION (PARALLAX) VECTOR OF NEIGHBORING BLOCK
1	SHORT REFERENCE PICTURE	SHORT REFERENCE PICTURE	INCLUDED IN CANDIDATE
2	SHORT REFERENCE PICTURE	LONG REFERENCE PICTURE	EXCLUDED FROM CANDIDATE
3	LONG REFERENCE PICTURE	LONG REFERENCE PICTURE	INCLUDED IN CANDIDATE
4	LONG REFERENCE PICTURE	SHORT REFERENCE PICTURE	EXCLUDED FROM CANDIDATE

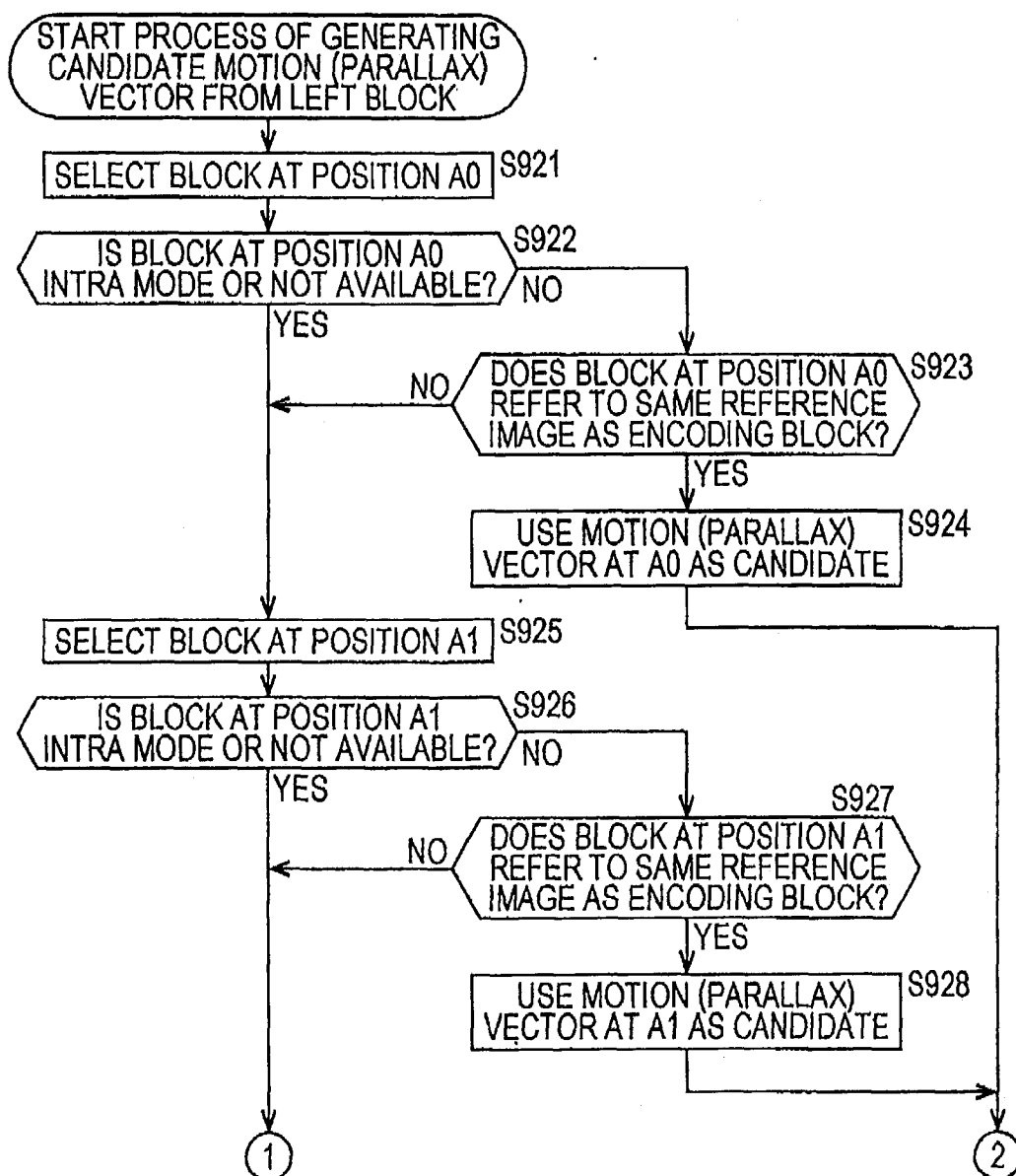
A

Index	REFERENCE IMAGE OF ENCODING BLOCK	REFERENCE IMAGE OF NEIGHBORING BLOCK	SCALING OF MOTION (PARALLAX) VECTOR OF NEIGHBORING BLOCK
1	SHORT REFERENCE PICTURE	SHORT REFERENCE PICTURE	YES
2	SHORT REFERENCE PICTURE	LONG REFERENCE PICTURE	NO
3	LONG REFERENCE PICTURE	LONG REFERENCE PICTURE	NO
4	LONG REFERENCE PICTURE	SHORT REFERENCE PICTURE	NO

B

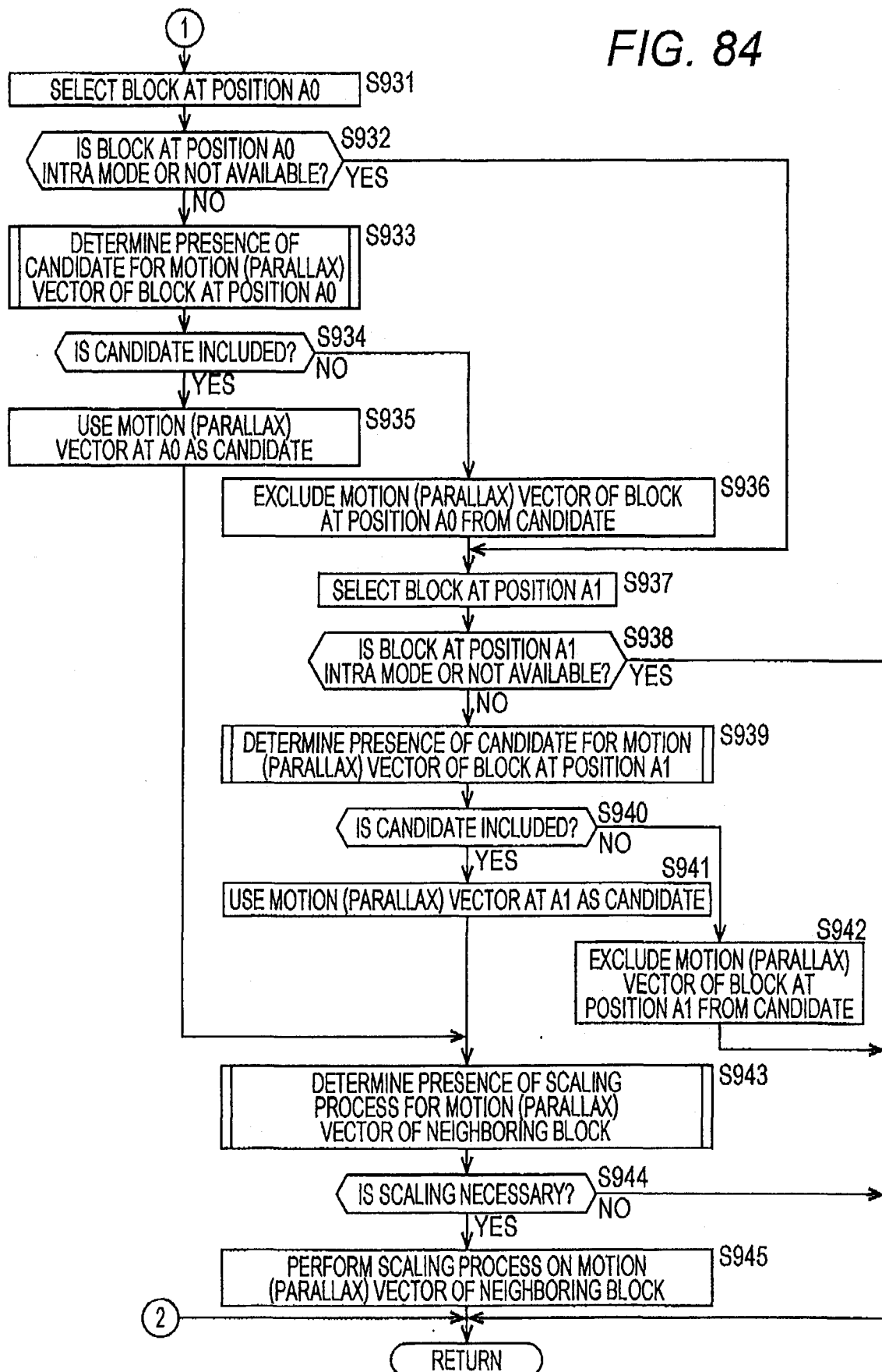
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FIG. 83



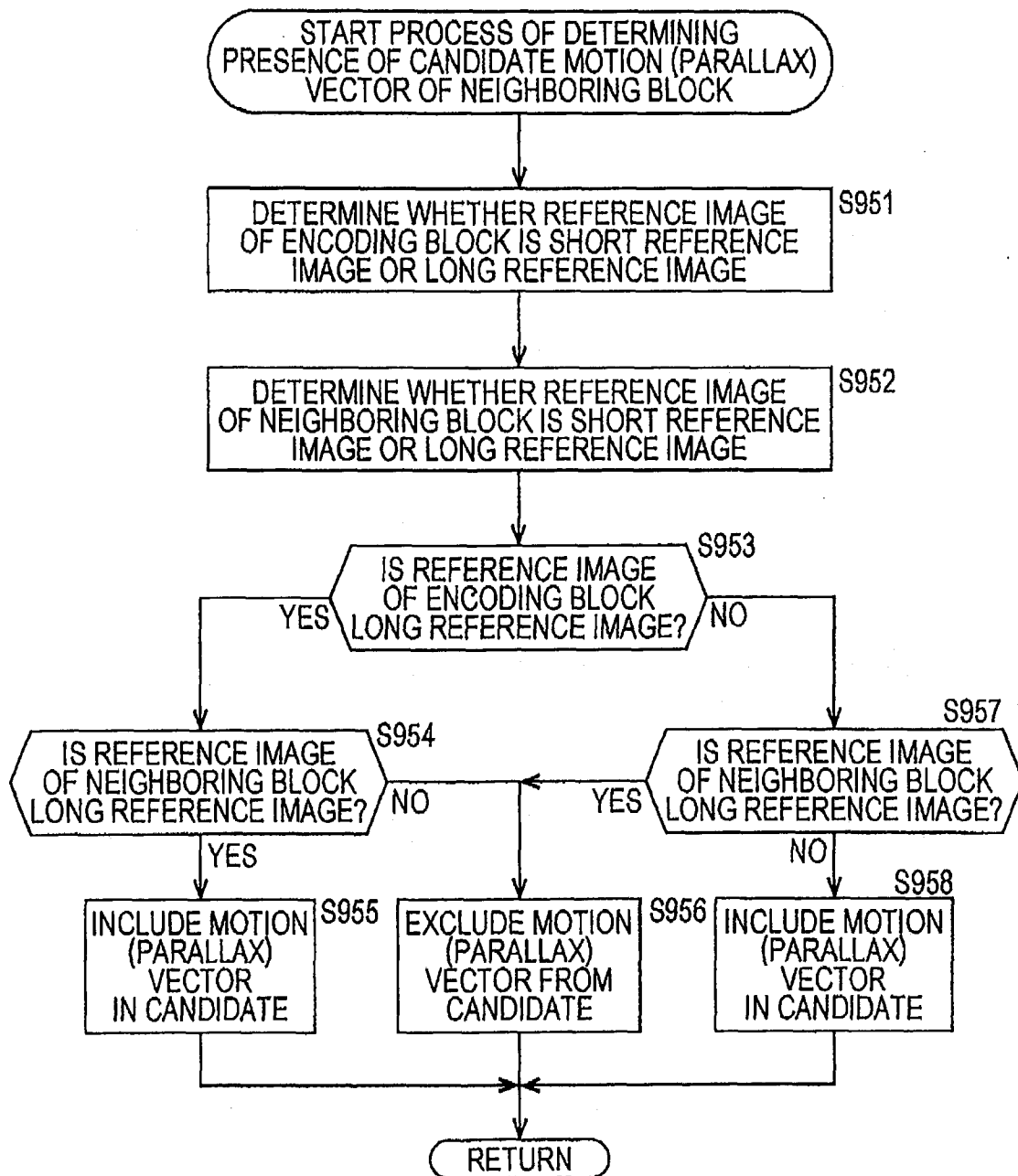
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FIG. 84



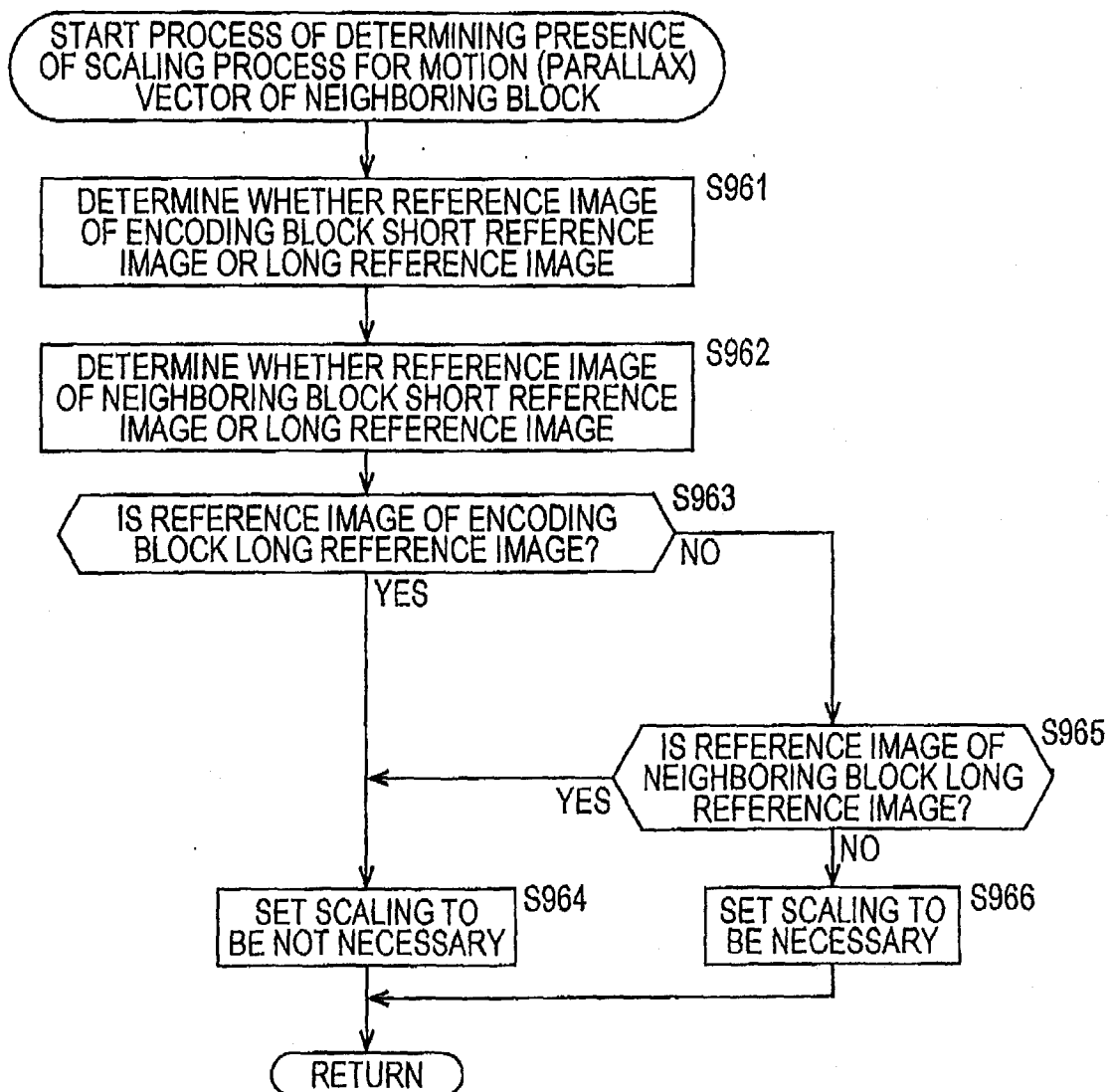
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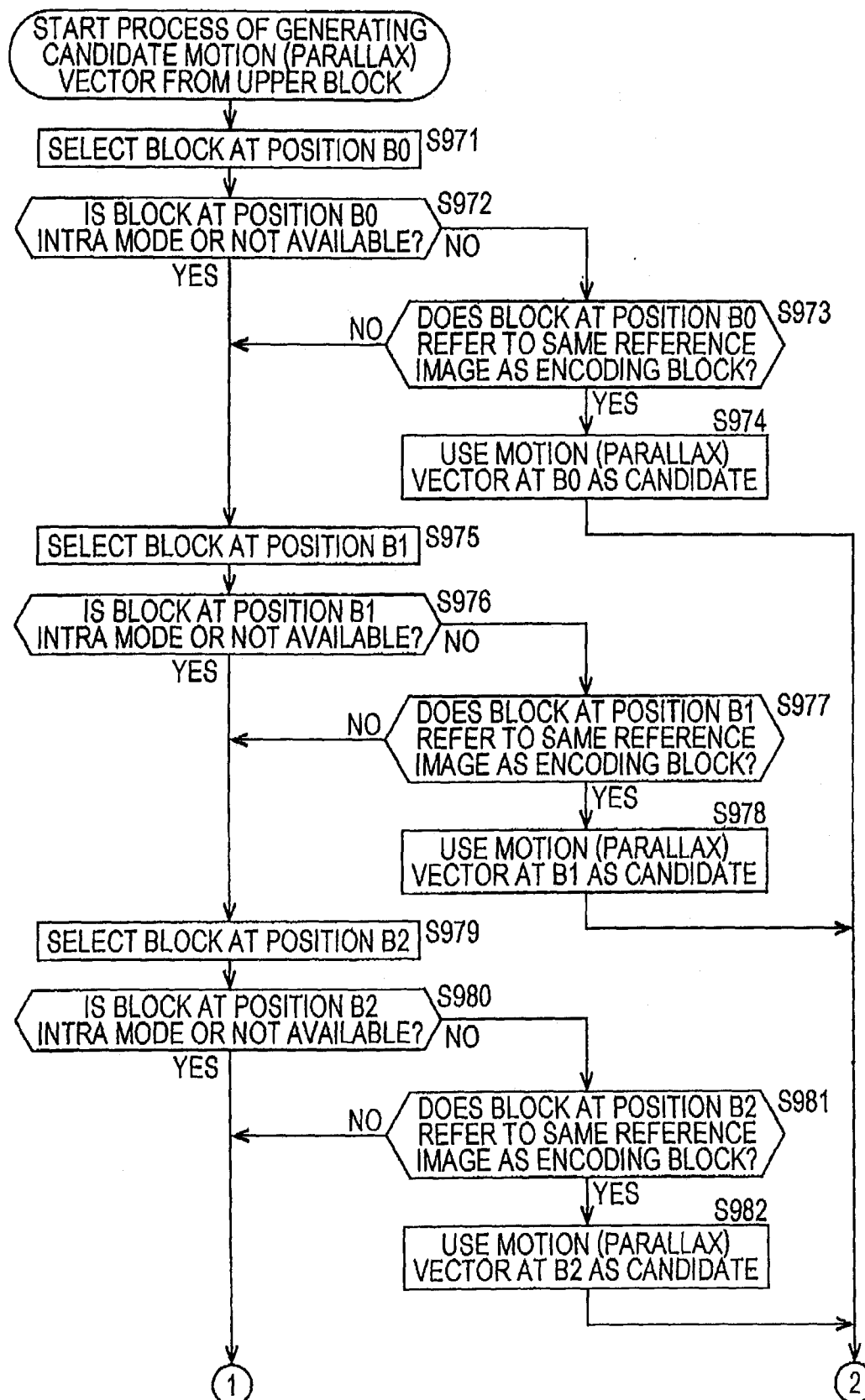
FIG. 85

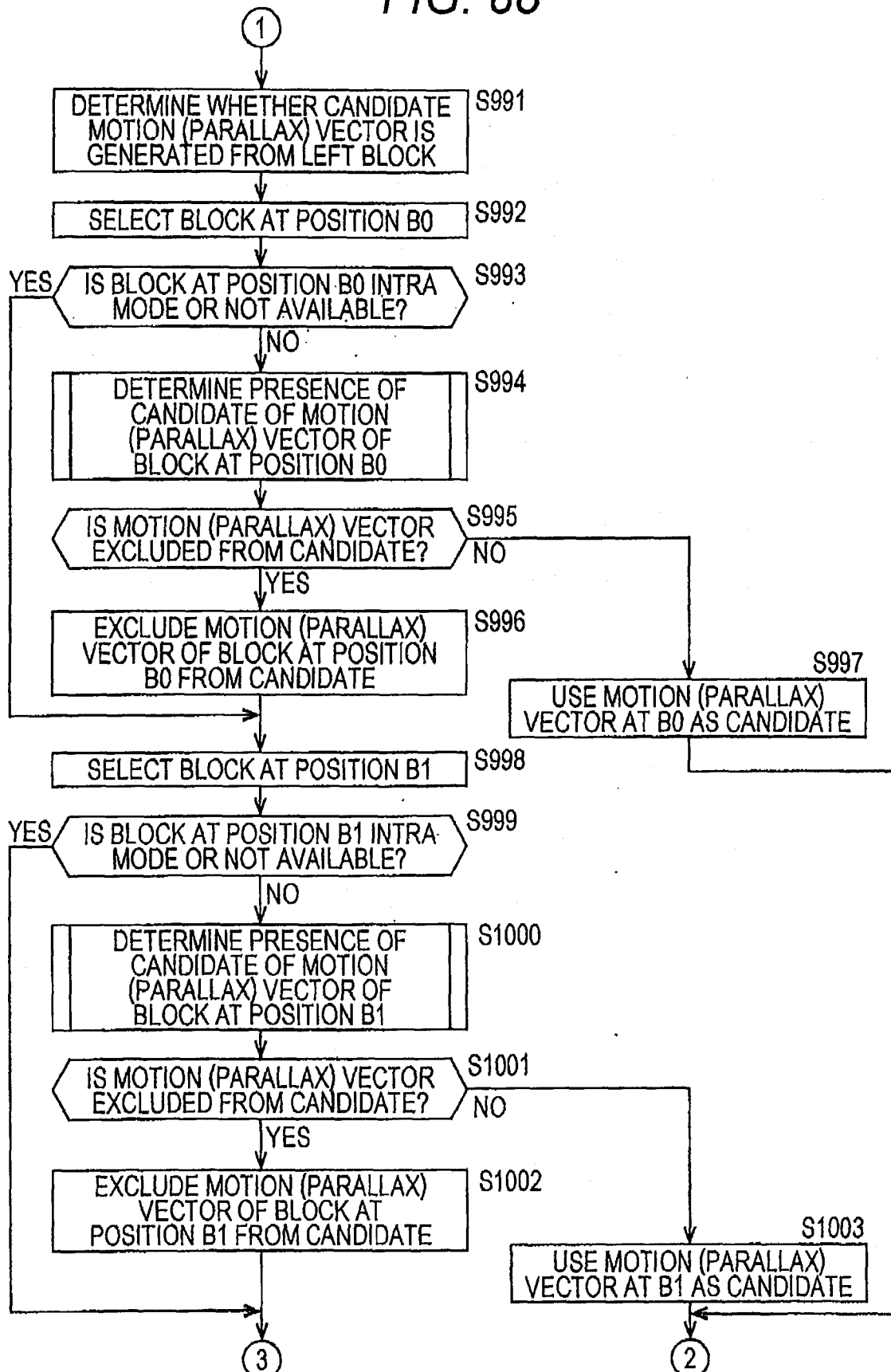


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FIG. 86

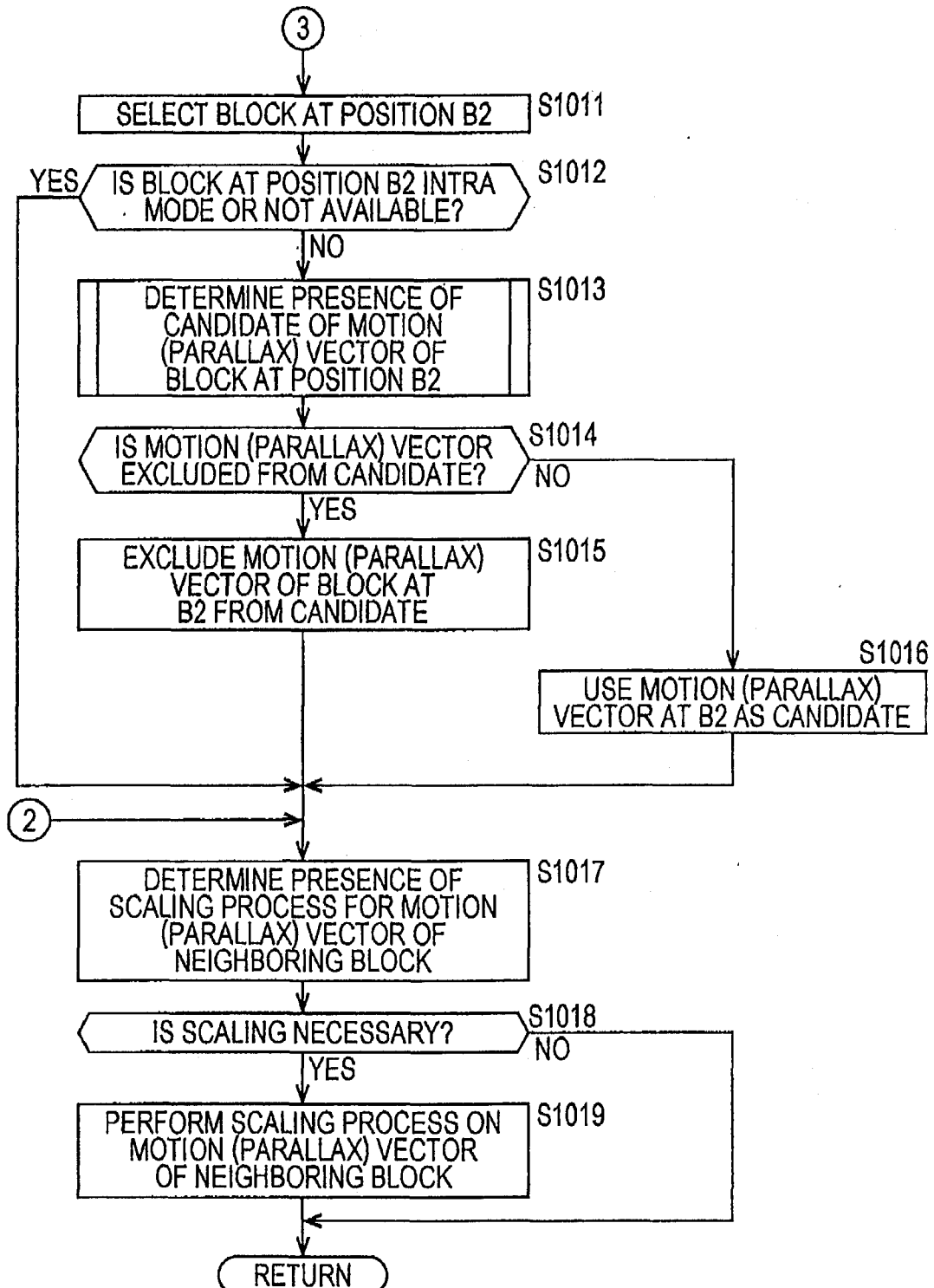


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FIG. 87

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FIG. 88

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FIG. 89



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FIG. 90

Index	REFERENCE IMAGE OF ENCODING BLOCK	REFERENCE IMAGE OF TEMPORAL CORRELATION BLOCK	PRESENCE OF CANDIDATE MOTION (PARALLAX) VECTOR OF TEMPORAL CORRELATION BLOCK	SCALING OF MOTION (PARALLAX) VECTOR OF TEMPORAL CORRELATION BLOCK
1	SHORT REFERENCE PICTURE	SHORT REFERENCE PICTURE	INCLUDED IN CANDIDATE	YES
2	SHORT REFERENCE PICTURE	LONG REFERENCE PICTURE	EXCLUDED FROM CANDIDATE	—
3	LONG REFERENCE PICTURE	LONG REFERENCE PICTURE	INCLUDED IN CANDIDATE	NO
4	LONG REFERENCE PICTURE	SHORT REFERENCE PICTURE	EXCLUDED FROM CANDIDATE	—

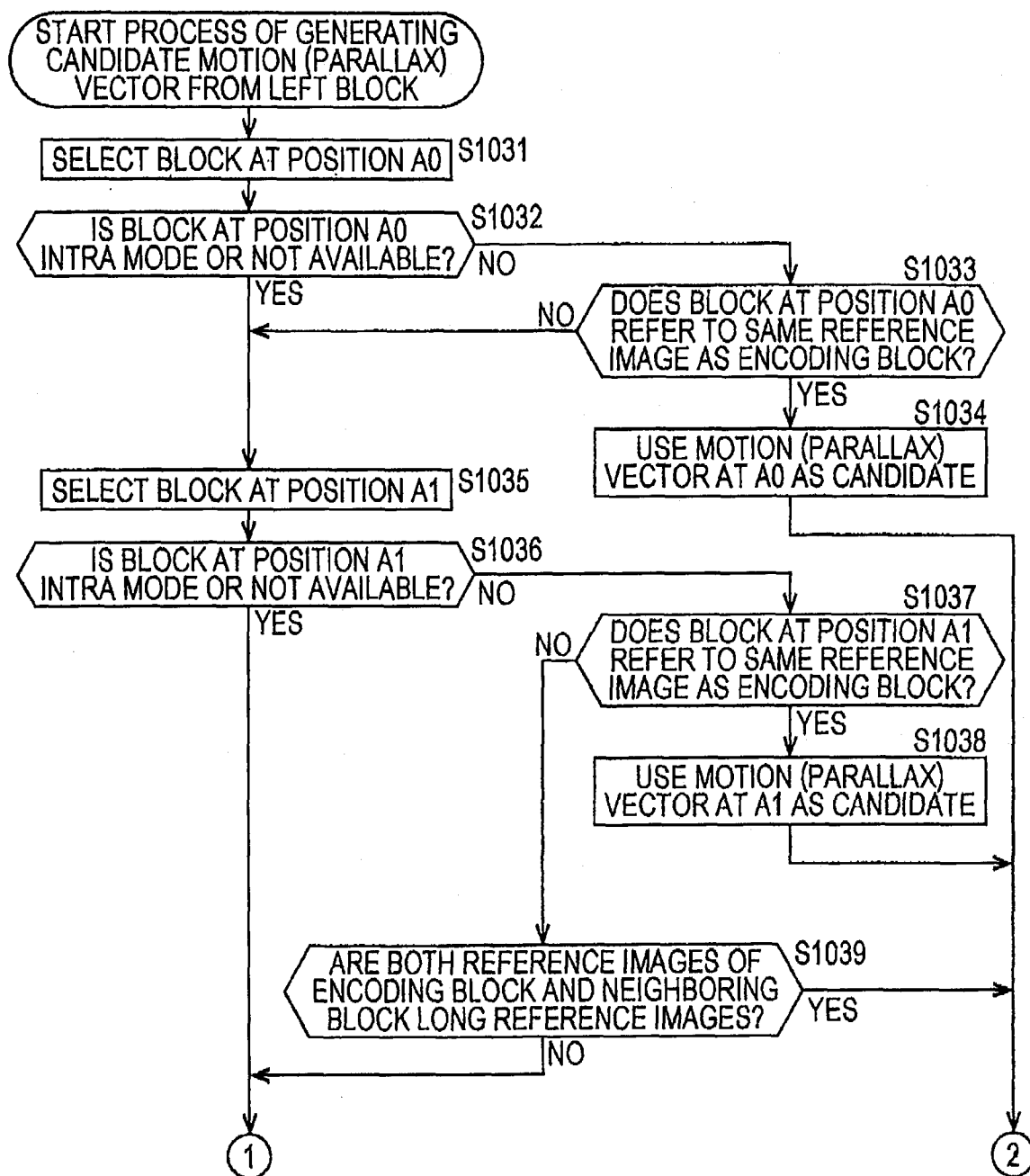
A

Index	REFERENCE IMAGE OF ENCODING BLOCK	REFERENCE IMAGE OF NEIGHBORING BLOCK	PRESENCE OF CANDIDATE MOTION (PARALLAX) VECTOR OF NEIGHBORING BLOCK	SCALING OF MOTION (PARALLAX) VECTOR OF NEIGHBORING BLOCK
1	SHORT REFERENCE PICTURE	SHORT REFERENCE PICTURE	INCLUDED IN CANDIDATE	YES
2	SHORT REFERENCE PICTURE	LONG REFERENCE PICTURE	EXCLUDED FROM CANDIDATE	—
3	LONG REFERENCE PICTURE	LONG REFERENCE PICTURE	INCLUDED IN CANDIDATE (ONLY WHEN REFERENCE IMAGES ARE IDENTICAL)	NO
4	LONG REFERENCE PICTURE	SHORT REFERENCE PICTURE	EXCLUDED FROM CANDIDATE	—

B

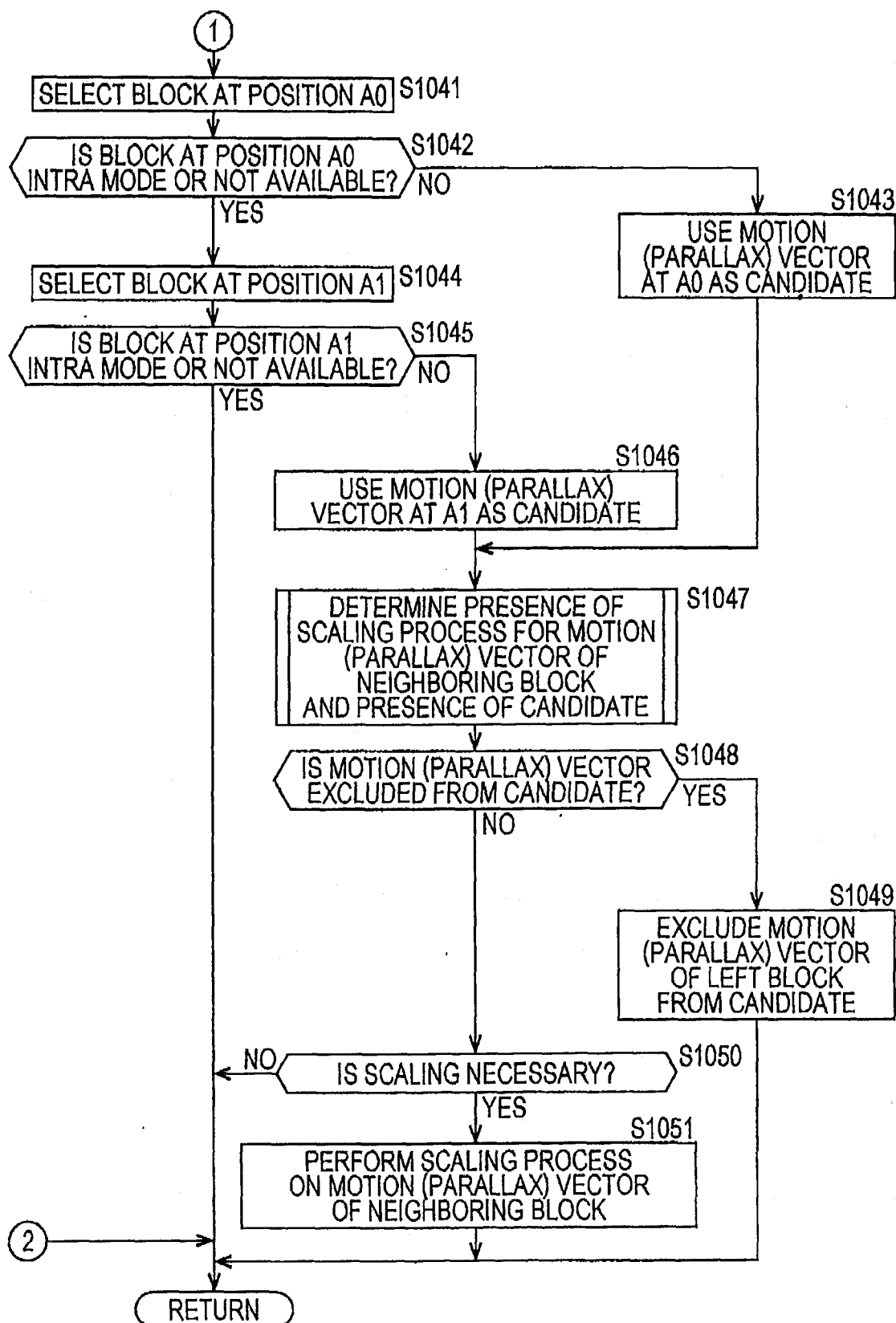
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FIG. 91

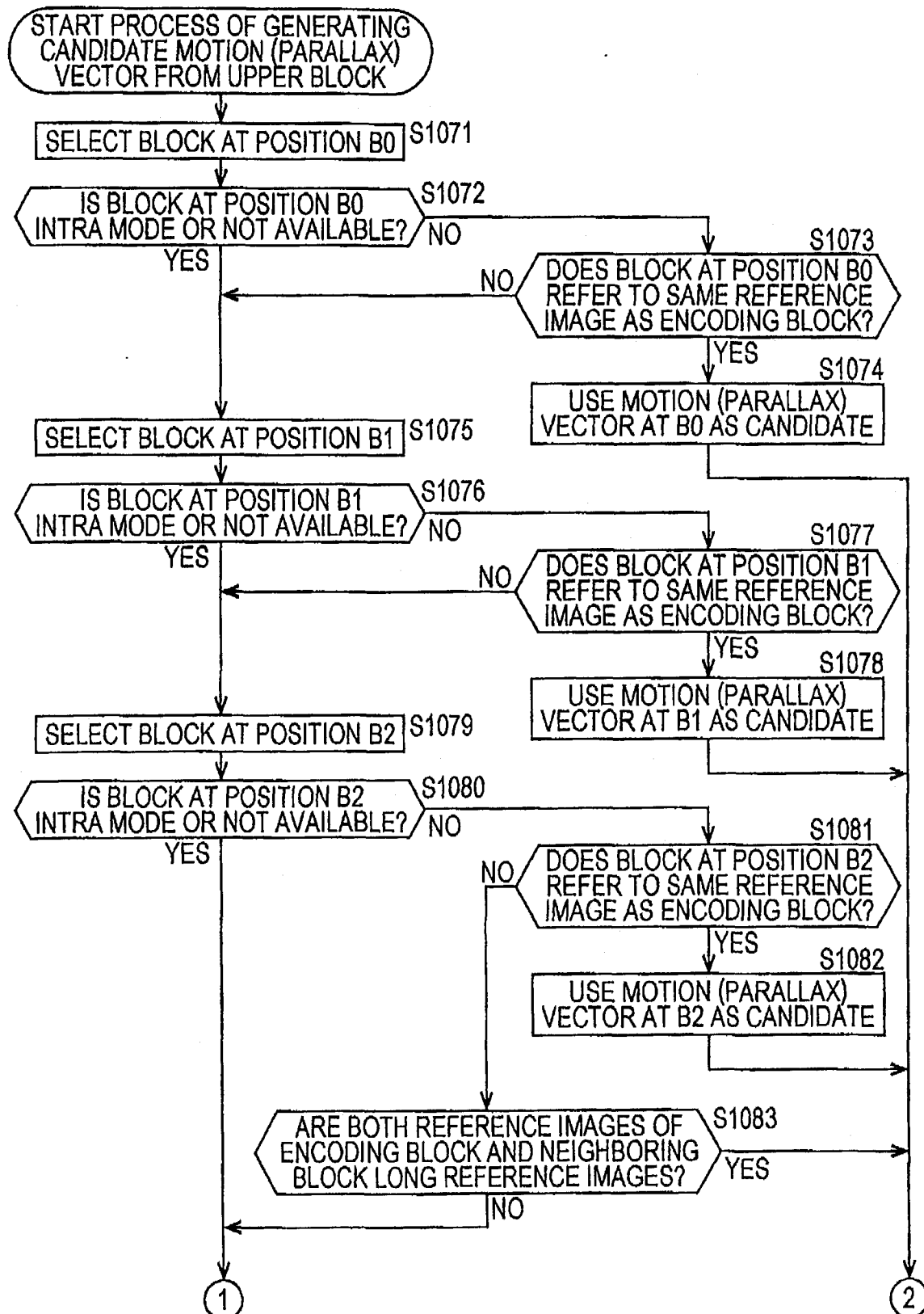


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FIG. 92



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FIG. 93



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FIG. 94

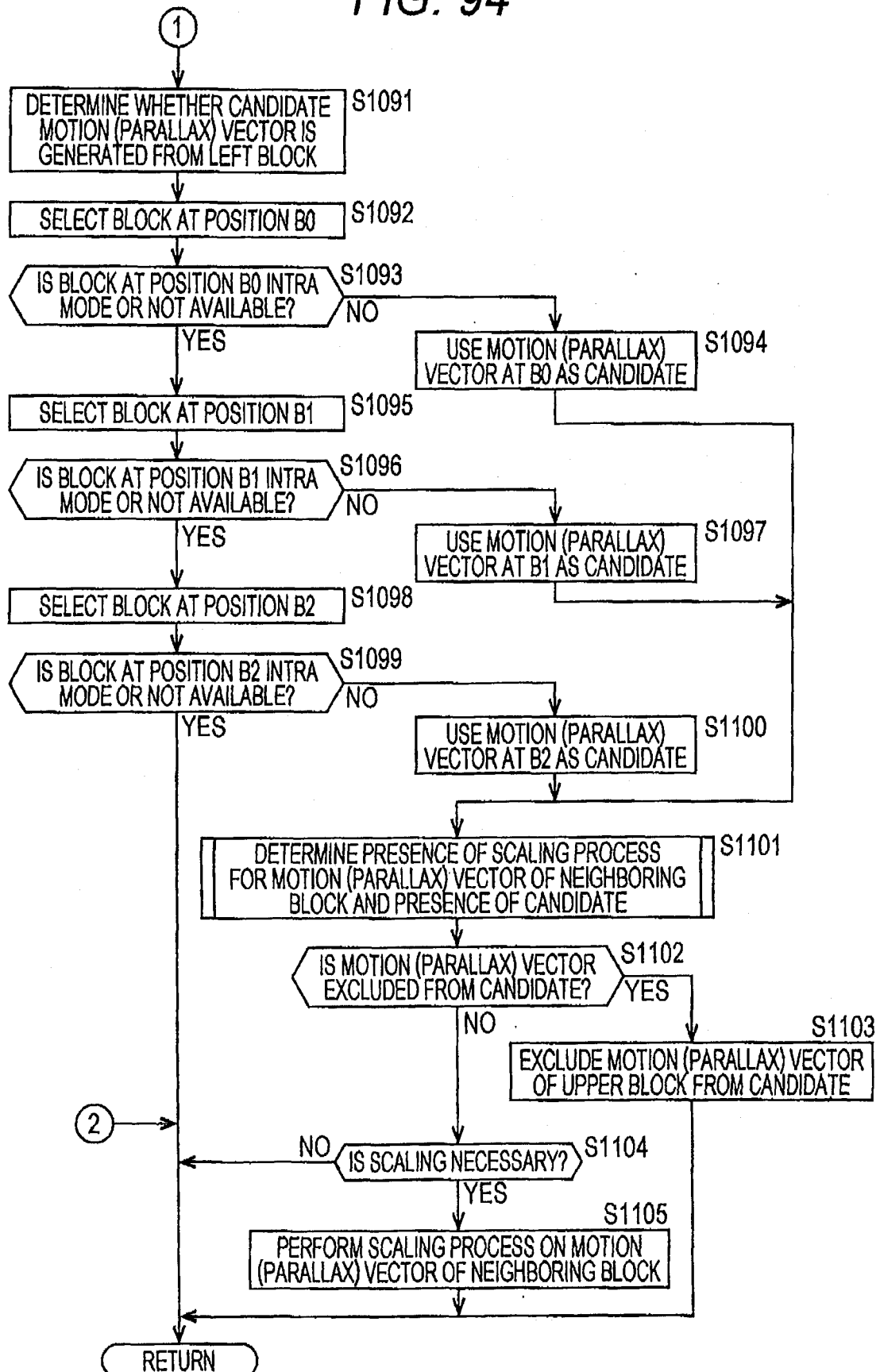


FIG. 95

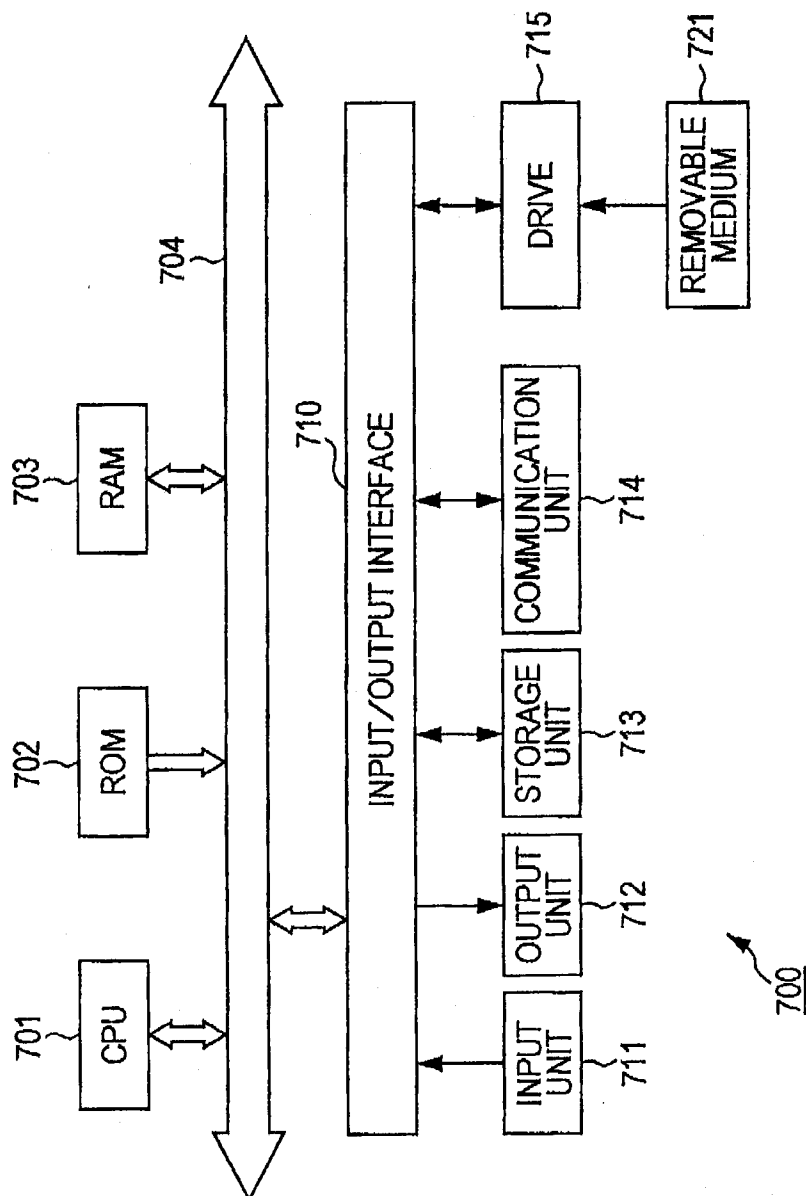


FIG. 96

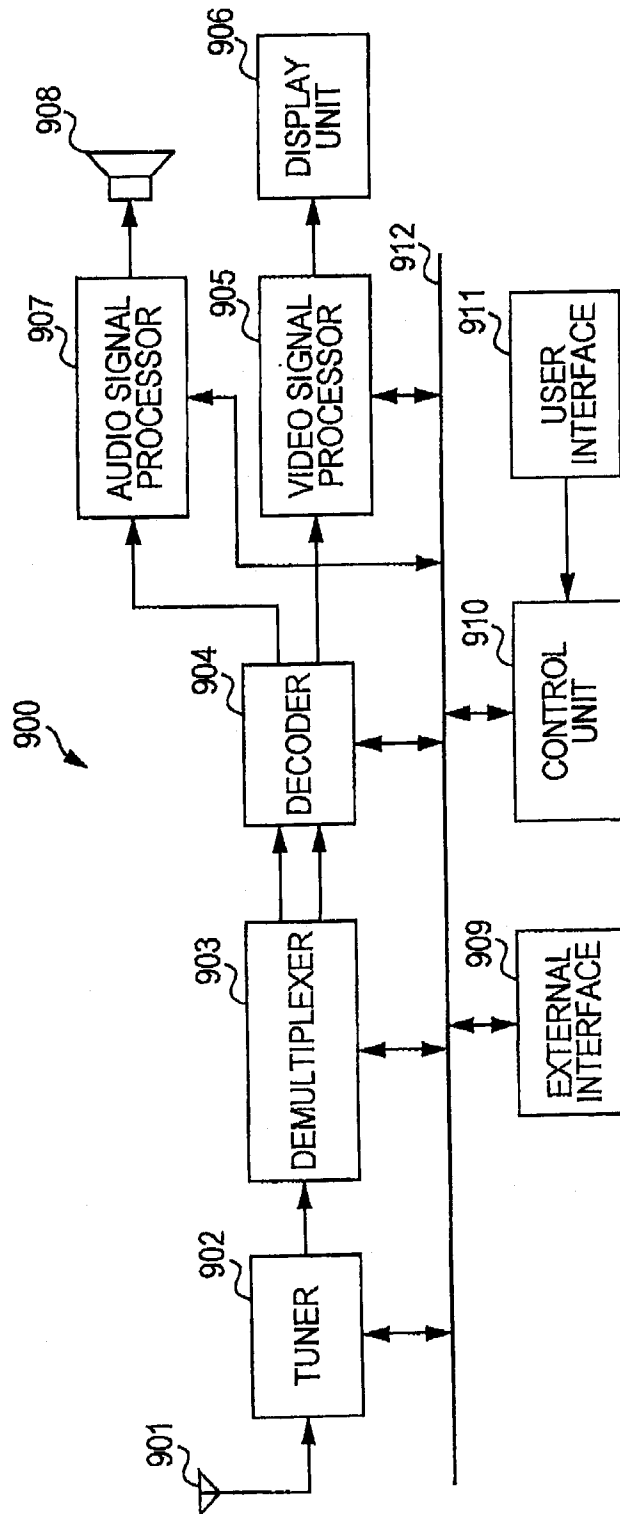
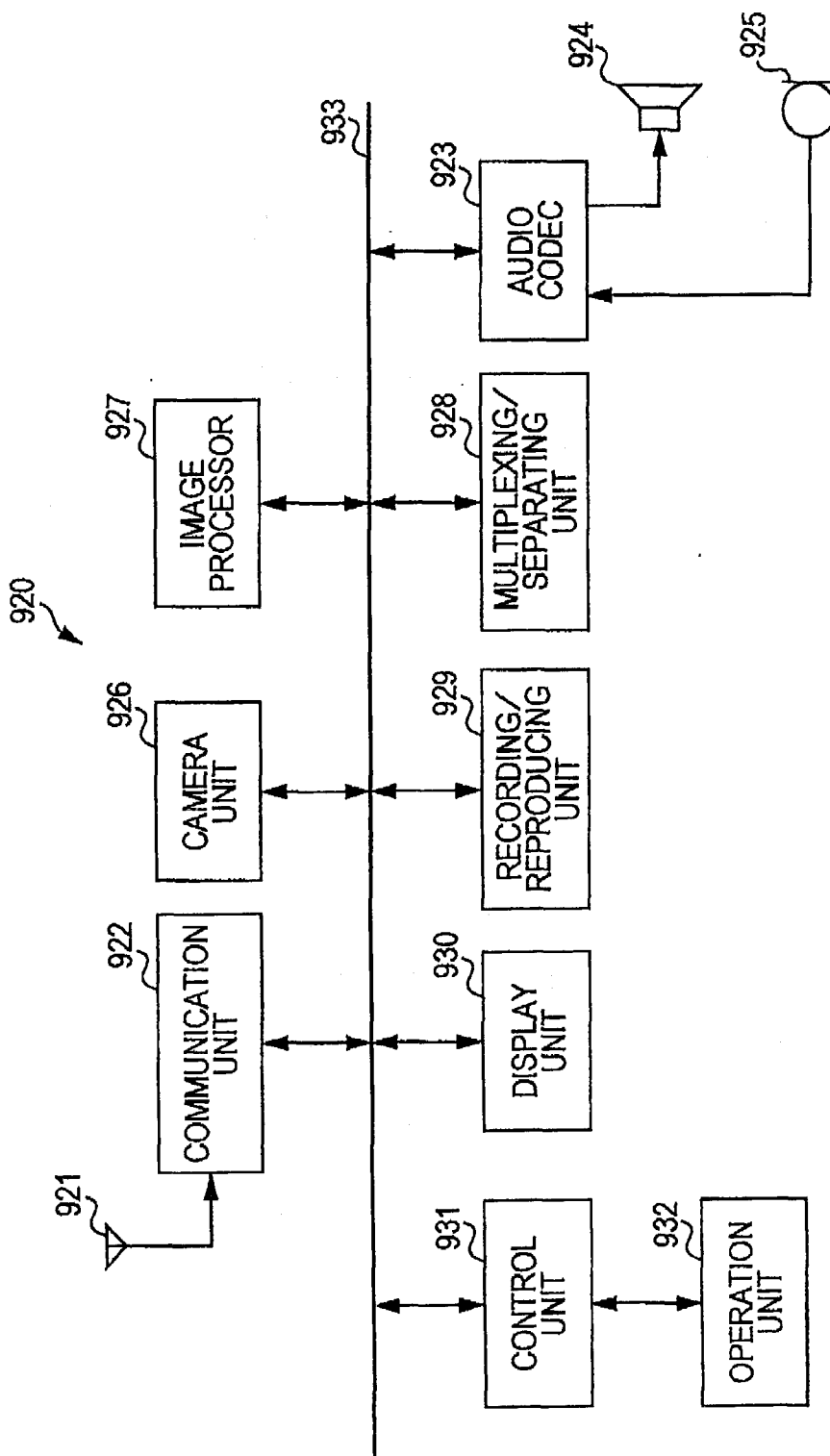


FIG. 97



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FIG. 98

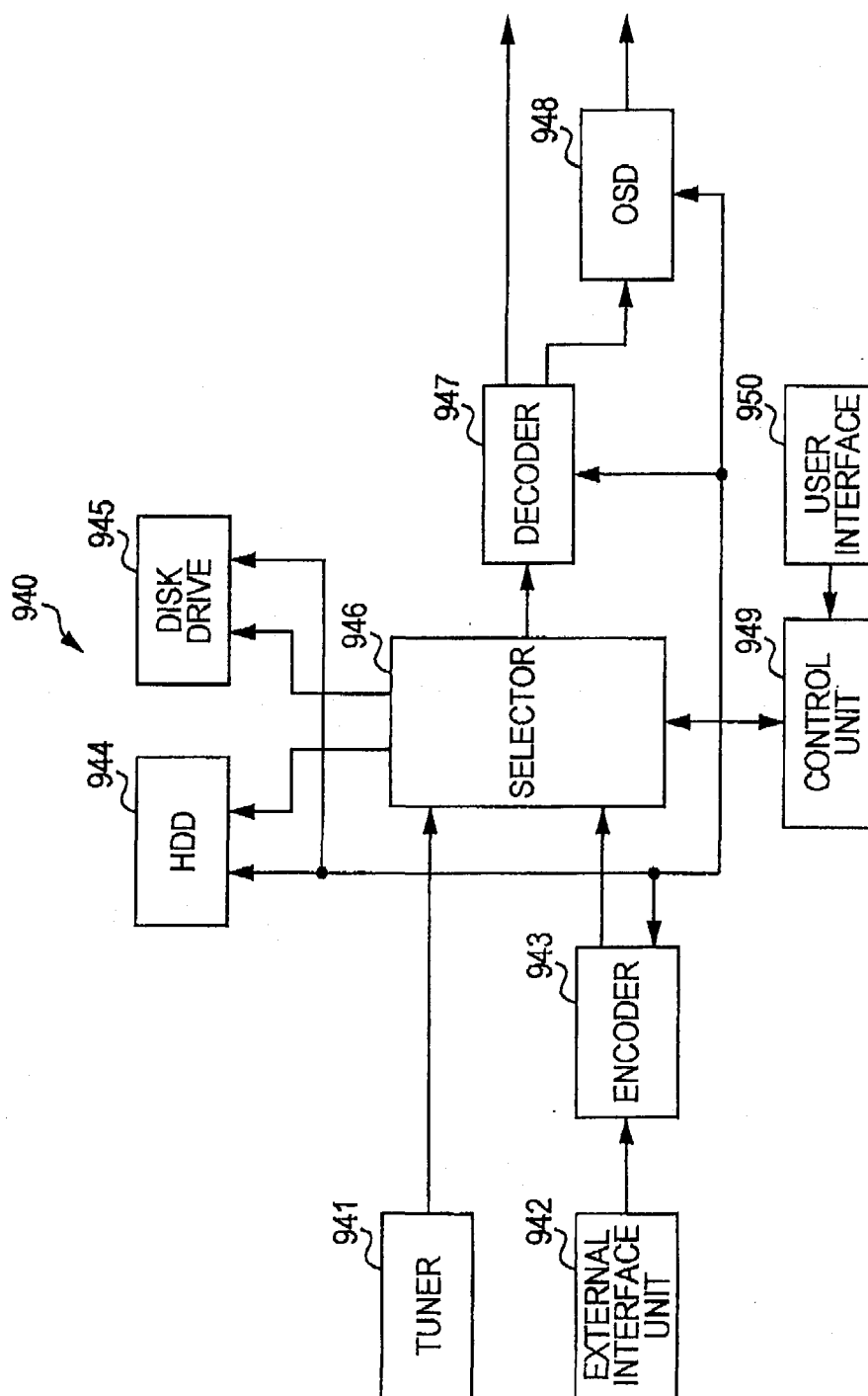
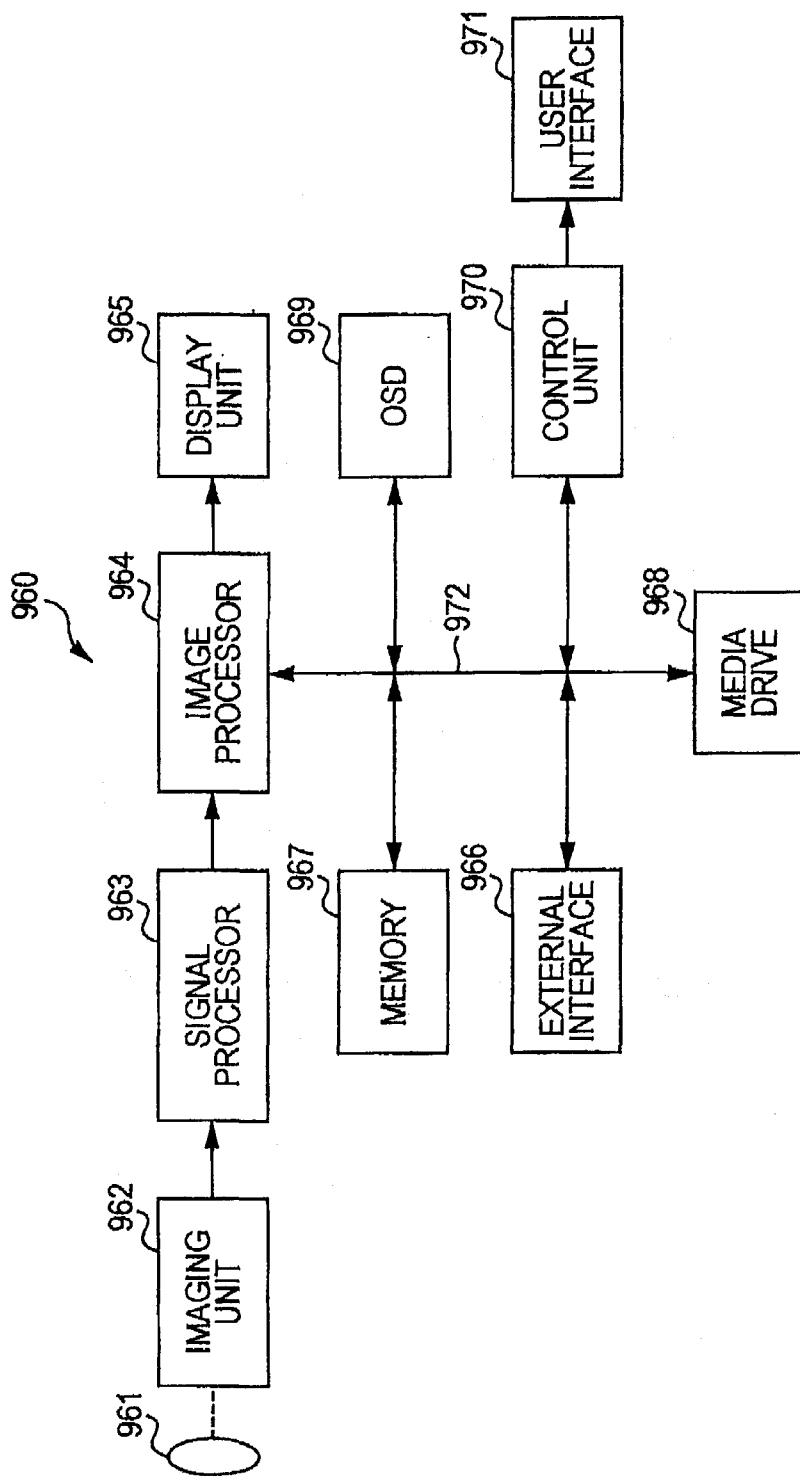


FIG. 99



units.

[0333]

The different picture-based predictive vector generating unit 457 generates a predictive vector that refers to different pictures. That is, the different picture-based predictive vector generating unit 457 refers to different pictures in the temporal direction and the view direction to generate the predictive vector. When generating the predictive vector that refers to different pictures in the view direction, the different picture-based predictive vector generating unit 457 acquires the motion information of the base view from the base view encoder 421 and generates a predictive vector using the motion information.

15 [0334]

The predictive vector generated by the different picture-based predictive vector generating unit 457 is supplied to the vector cost calculating unit 453 via the selector 458, and the cost function value used for the mode determination is calculated.

[0335]

[Different picture-based predictive vector generating unit]

Fig. 40 is a block diagram illustrating a main configuration example of the different picture-based predictive vector generating unit 457.

[0336]

As illustrated in Fig. 40, the different picture-based predictive vector generating unit 457 includes a parallax vector determining unit 471, an inter-view reference vector generating unit 472, and an intra-view

reference vector generating unit 473.

[0337]

The parallax vector determining unit 471 calculates a shift amount of the reference image from the parallax vector of the neighboring block. The shift amount calculating method is optional. For example, any one of the parallax vectors of the neighboring blocks may be selected and may be used as the shift amount. Moreover, for example, an average value or a median value of the parallax vectors of the neighboring blocks may be used as the shift amount.

[0338]

The parallax vector determining unit 471 supplies the shift amount obtained in this manner to the inter-view reference vector generating unit 472 as the parallax vector.

[0339]

The inter-view reference vector generating unit 472 generates a predictive vector that refers to different pictures in the view direction.

[0340]

The inter-view reference vector generating unit 472 generates the predictive vector by taking the parallax vector into consideration using the parallax vector (shift amount) selected by the parallax vector determining unit 471, the motion vector (also including the parallax vector in the case of the non-base view) of the base view supplied from the base view encoder 421, and information such as the reference image index or the inter-view motion/parallax vector of the same time, which is read from the vector information accumulation buffer

455.

[0341]

That is, the inter-view reference vector generating unit 472 aligns (shifts) the images of the view referring to using the shift amount calculated by the parallax vector determining unit 471. Moreover, the inter-view reference vector generating unit 472 generates the predictive vector from the aligned blocks.

[0342]

10 The inter-view reference vector generating unit 472 supplies the generated predictive vector to the vector cost calculating unit 453 via the selector 458 (not illustrated in Fig. 40).

[0343]

15 The intra-view reference vector generating unit 473 generates the predictive vector that refers to different pictures in the temporal direction.

[0344]

By doing so, the inter-view reference vector generating unit 472 can create an appropriate predictive vector with high prediction accuracy. In this way, the image encoding device 400 can improve the encoding efficiency.

[0345]

25 [Flow of motion prediction/compensation process]

An example of the flow of the motion prediction/compensation process will be described with reference to the flowchart of Fig. 41.

[0346]

30 When the motion prediction/compensation process starts, in step S401, the inter-mode generating unit 431

selects any one of an inter-prediction mode, a skip mode, a merge mode, and the like and generates an inter mode which is information designating the selected mode.

[0347]

- 5 In step S402, the inter-mode generating unit 431 determines whether the generated inter mode is the inter-prediction mode.

[0348]

- 10 When the inter mode is the inter-prediction mode, the inter-mode generating unit 431 determines the reference image in step S403, and the vector predicting unit 433 executes the vector prediction process in step S404.

[0349]

- 15 Moreover, when the inter mode is not the inter-prediction mode, in step S404, the vector predicting unit 434 performs a vector prediction process.

[0350]

- 20 In step S405, the mode determining unit 435 determines the mode based on the predictive vector or the like generated in step S404. This mode is used in the process of step S401.

[0351]

- 25 In step S405, the lossless encoding unit 106 encodes the information of the mode determined in step S405.

[0352]

[Flow of vector prediction process]

- 30 An example of the flow of the vector prediction process executed by the vector predicting unit 433 in step S404 of Fig. 41 will be described with reference to

the flowchart of Fig. 42.

[0353]

When the vector prediction process starts, the motion/parallax vector search unit 451 searches vectors
5 in step S421.

[0354]

In step S422, the predicted image generating unit 452 generates a predicted image.

[0355]

10 In step S423, the vector cost calculating unit 453 generates a residual image.

[0356]

In step S424, the neighboring block-based predictive vector generating unit 456 and the different
15 picture-based predictive vector generating unit 457 generates a predictive vector from the encoded vector.

[0357]

In step S425, the vector cost calculating unit 453 calculates the residue of the vector.

20 [0358]

In step S426, the vector determining unit 454 determines a predictive vector having the smallest cost. This processing result is reflected on the process of step S424.

25 [0359]

In step S427, the vector information accumulation buffer 455 accumulates the vector information and the flow returns to the flowchart of Fig. 41.

[0360]

30 [Flow of predictive vector generation process]

Next, an example of the flow of the predictive

vector generation process executed in step S424 of Fig. 42 will be described with reference to the flowchart of Fig. 43.

[0361]

- 5 When the predictive vector generation process starts, in step S441, the selector 458 determines which block is to be referred to.

[0362]

- 10 When it is determined that the neighboring block of the picture is to be referred to, in step S442, the neighboring block-based predictive vector generating unit 456 sets the encoded vector of the neighboring block to the predictive vector and the flow returns to the flowchart of Fig. 42.

- 15 [0363]

- 20 Moreover, when it is determined in step S441 that the block of a different picture is to be referred to, the selector 458 proceeds to the process of step S443 to determine a view of which the picture is to be referred to.

[0364]

- 25 When it is determined that the picture of a different view is to be referred to, in step S444, the different picture-based predictive vector generating unit 457 generates a predictive vector of the view direction from a encoded co-located block that is expanded in the view direction and the flow returns to the flowchart of Fig. 42.

[0365]

- 30 Moreover, when it is determined in step S443 that the picture of the same view is to be referred to, in

step S445, the different picture-based predictive vector generating unit 457 generates the predictive vector of the temporal direction from the encoded co-located block and the flow returns to the flowchart of Fig. 42.

5 [0366]

[Flow of different picture-based predictive vector generation process]

Next, an example of the flow of the different picture-based predictive vector generation process executed in step S444 of Fig. 43 will be described with reference to the flowchart of Fig. 44.

[0367]

When the different picture-based predictive vector generation process starts, in step S461, the parallax vector determining unit 471 determines a shift amount from the parallax vector of the neighboring block.

[0368]

In step S462, the inter-view reference vector generating unit 472 selects a co-located block at a shifted position.

[0369]

In step S463, the inter-view reference vector generating unit 472 generates the predictive vector from the co-located block and the flow returns to the flowchart of Fig. 43.

[0370]

[Flow of shift amount determining process]

Next, an example of the flow of the shift amount determining process executed in step S461 of Fig. 44 will be described with reference to the flowchart of Fig. 45.

[0371]

In step S481, the parallax vector determining unit 471 determines whether there is a plurality of blocks in which the value of the Y-direction vector of the parallax vector of the neighboring block is not zero.

5 [0372]

The neighboring block is a block located near (including "adjacent") a current block (current block) of a processing target. For example, as illustrated in Fig. 46, a block (Left) adjacent to the left of a current block (Curr), a block (Above) adjacent above the current block, and a block (Above Right) adjacent to the top right corner of the current block are used as the neighboring blocks. Naturally, a block other than these blocks may be included in the neighboring block, and part or all of these blocks may not be used as the neighboring block.

[0373]

The positions of the neighboring blocks may be the same for all blocks and may be different from block to block. For example, when a block adjacent to a screen end or a slice boundary are used as the current block, part of the neighboring blocks may be set to be not usable.

[0374]

25 When it is determined in step S481 that there is not a plurality of blocks in which the value of the Y-direction vector is non-zero, the parallax vector determining unit 471 proceeds to the process of step S482 to use the parallax vector in the X-direction of the target as the shift amount, and the flow returns to the flowchart of Fig. 44.

