



- (51) **International Patent Classification:**
G01S 7/52 (2006.01) *G01S 15/89* (2006.01)
- (21) **International Application Number:**
PCT/EP2015/051369
- (22) **International Filing Date:**
23 January 2015 (23.01.2015)
- (25) **Filing Language:** English
- (26) **Publication Language:** English
- (30) **Priority Data:**
61/930,805 23 January 2014 (23.01.2014) US
- (71) **Applicant:** SUPER SONIC IMAGINE [FR/FR]; Les
jardins de la Duranne, 510 rue René Descartes, Bât. E, F-
13857 Aix en Provence Cedex (FR).
- (72) **Inventor:** BRUCE, Matthew; 340 avenue Célestin Bressi-
er, 2 Lot. Elisa, F-13290 Les Milles (FR).
- (74) **Agents:** CABINET PLASSERAUD et al.; 52 rue de la
Victoire, F-75440 Paris Cedex 09 (FR).
- (81) **Designated States** (unless otherwise indicated, for every
kind of national protection available): AE, AG, AL, AM,

AO, AT, AU, AZ, BA, BB, BG, BH, BN, BR, BW, BY,
BZ, CA, CH, CL, CN, CO, CR, CU, CZ, DE, DK, DM,
DO, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, GT,
HN, HR, HU, ID, IL, IN, IR, IS, JP, KE, KG, KN, KP, KR,
KZ, LA, LC, LK, LR, LS, LU, LY, MA, MD, ME, MG,
MK, MN, MW, MX, MY, MZ, NA, NG, NI, NO, NZ, OM,
PA, PE, PG, PH, PL, PT, QA, RO, RS, RU, RW, SA, SC,
SD, SE, SG, SK, SL, SM, ST, SV, SY, TH, TJ, TM, TN,
TR, TT, TZ, UA, UG, US, UZ, VC, VN, ZA, ZM, ZW.

- (84) **Designated States** (unless otherwise indicated, for every
kind of regional protection available): ARIPO (BW, GH,
GM, KE, LR, LS, MW, MZ, NA, RW, SD, SL, ST, SZ,
TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, RU,
TJ, TM), European (AL, AT, BE, BG, CH, CY, CZ, DE,
DK, EE, ES, FI, FR, GB, GR, HR, HU, IE, IS, IT, LT, LU,
LV, MC, MK, MT, NL, NO, PL, PT, RO, RS, SE, SI, SK,
SM, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ,
GW, KM, ML, MR, NE, SN, TD, TG).

Published:

— with international search report (Art. 21(3))

(54) **Title:** METHOD FOR DETERMINING A PHYSICAL CHARACTERISTIC ON A PUNCTUAL LOCATION INSIDE A ME-
DIUM, A METHOD FOR DETERMINING AN IMAGE OF A MEDIUM AND APPARATUS IMPLEMENTING SAIDS METH-
ODS

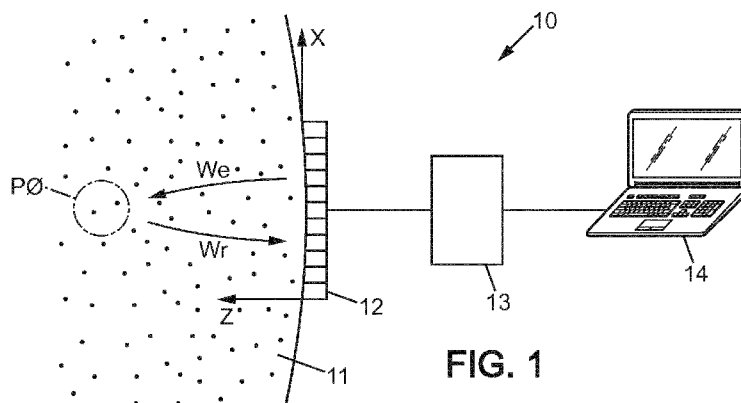


FIG. 1

(57) **Abstract:** A method for determining a physical characteristic on a punctual location (P0) inside a medium (11), comprising the
steps of: sending an emitted sequence comprising emitted pulses having different amplitudes, receiving a received sequence compris-
ing received pulses corresponding to echoes of said emitted pulses, calculating a phase difference between the received pulses relat-
ive to the emitted pulses, and determining the physical characteristic on the bases of said phase difference.

**Method for determining a physical characteristic on a
punctual location inside a medium,
a method for determining an image of a medium, and
an apparatus implementing said methods**

5

FIELD OF THE INVENTION

The present invention concerns a method for characterizing a punctual location inside a medium with
10 ultrasound, and for determining an image of a region inside said medium, in using ultrasound waves propagation inside said medium. The present invention also concerns the apparatus implementing said methods.

15

BACKGROUND OF THE INVENTION

Ultrasound imaging of a medium is a very common technique for imaging a medium, and in particular for imaging a human body. Lots of ultrasound imaging techniques
20 are known.

For example, the patent US 6,095,980 discloses an imaging system and method for detecting linear and nonlinear scatterers inside the medium, called "pulse inversion Doppler". This system measures the ultrasound
25 response under multiple excitation levels, so as to improve sensitivity in the detection of non-linear responses. Additionally, this method often uses the injection of contrast agents inside the medium for again improving the sensitivity of ultrasound imaging.

30 Unfortunately, with such an imaging system, the user still gets a weak contrast and in spite of the use of contrast agents, some tissue signals (i.e. without contrast agents) remain in the image and then the bloods vessels contours are insufficiently defined in the image.

35

OBJECTS AND SUMMARY OF THE INVENTION

One object of the present invention is firstly to provide a method for determining a physical characteristic on a punctual location inside the medium.

To this effect, the method comprises the following steps:

a) sending an emitted sequence of ultrasound waves into the medium towards the location, the emitted sequence comprising at least two emitted pulses having different amplitudes,

b) receiving a received sequence of ultrasound waves from the location, the received sequence comprising two received pulses corresponding to echoes of said emitted pulses,

c) calculating a phase difference between the received pulses relative to the two emitted pulses, and

d) determining the physical characteristic on the bases of said phase difference.

Thanks to these features, the physical characteristic on the punctual location of the medium is determined with an improved accuracy.

In various embodiments of the method, one and/or other of the following features may optionally be incorporated.

In an aspect of the method, the step c) of calculating a phase difference comprises the following sub-steps:

c1) determining a phase for each one of the received pulses in the received sequence, and

c2) calculating the phase difference by combining said phases.

In an aspect of the method, the step c) of calculating a phase difference comprises the following sub-steps:

c3) received signals corresponding to said received

pulses are weighted by weighting factors and summed for producing a combined signal, said weighting factors being determined so that to compensate the different amplitudes of the emit pulses, and

- 5 c4) the phase difference is a phase of said combined signal.

In an aspect of the method, the physical characteristic is proportional to the phase difference.

10 In an aspect of the method, the succession of steps a) to c) are repeated several times for providing a plurality of phase differences, and wherein:

- during step d), the physical characteristic is determined by a mean or a standard deviation or a variance of said plurality of phase differences.

15 In an aspect of the method, the emitted sequence comprises a number greater than two emitted pulses, the received sequence comprises at least the same number of received pulses than the number of emitted pulses, and wherein:

20 - during step c), a plurality of phase differences between couples corresponding to two received and emitted pulses is calculated, each couple of emitted pulses having a different amplitude, and

25 - during step d), the physical characteristic is determined by a mean or a standard deviation or a variance of said plurality of phase differences.

In an aspect of the method:

30 - the physical characteristic is of a first type if it is lower than or equal to a first limit, and
- the physical characteristic is of a second type if it is higher than a second limit.

In an aspect of the method, the second limit is higher than the first limit.

35 In an aspect of the method, the first limit is 0.3 radian, and preferably 0.1 radian.

In an aspect of the method, the second limit

is 0.3 radian, and preferably 0.5 radian.

Another object of the invention is secondly to provide an apparatus for determining physical characteristic on a punctual location inside a medium. The apparatus comprises:

- a probe comprising an ultrasound transducer,
- an electronic unit controlling the transducer,
- and
- a processing unit for controlling the electronic unit and for processing signals from said electronic unit.

The processing unit implements the method for determining a physical characteristic on a punctual location above specified.

15

Another object of the invention is thirdly to provide a method for determining an image of a region inside a medium, the image being composed of a plurality of pixels, and wherein the method comprises for a plurality of locations inside the region.

The method comprises the following steps:

- a) sending an emitted sequence of ultrasound waves towards the location into the region, the emitted sequence comprising at least two emitted pulses of different amplitudes,
- b) receiving a received sequence of ultrasound waves from the location, the received sequence comprising at least two received pulses corresponding to said emitted pulses,
- c) calculating a phase difference between the received pulses relative to the emitted pulses, and
- d) determining the pixel of the image on the bases of said phase difference.

Thanks to these features, the image of the medium is determined with an improved sensitivity and accuracy. The image contrast of the image is improved compared to

35

known ultrasound techniques.

In various embodiments of the method, one and/or other of the following features may optionally be incorporated.

5 In an aspect of the method, the step c) of calculating a phase difference comprises the following sub-steps:

c1) determining a phase for each one of the received pulses in the received sequence, and

10 c2) calculating the phase difference by combining said phases.

In an aspect of the method, the step c) of calculating a phase difference comprises the following sub-steps:

15 c3) received signals corresponding to said received pulses are weighted by weighting factors and summed for producing a combined signal, said weighting factors being determined so that to compensate the different amplitudes of the emit pulses, and

20 c4) the phase difference is a phase of said combined signal.

In an aspect of the method: during step d), the pixel is proportional to the phase difference.

25 In an aspect of the method, the succession of steps a) to c) are repeated several times for providing a plurality of phase differences for each location inside the region, and:

- during step d), the pixel is determined by calculating a mean or a standard deviation or a variance of said plurality of phase differences.

30 In an aspect of the method, the emitted sequence comprises a number greater than two emitted pulses, the received sequence comprises at least the same number of received pulses, and:

35 - during step c), a plurality of phase differences between couples of corresponding to two received and

emitted pulses is calculated, each couple of emitted pulses having a different amplitudes, and

- during step d), the pixel is determined by calculating a mean or a standard deviation or a variance of said plurality of phase differences.

In an aspect of the method, each pixel in the image corresponds to a location inside the region.

In an aspect of the method:

- the region is subdivided in a plurality of sub-regions,

- between step c) and step d), a sub-region phase difference is calculated, said sub-region phase difference being a mean value of the plurality of phase differences of the locations belonging to said sub-region, and

- each pixel in the image corresponds to a sub-region.

In an aspect of the method:

- each pixel is of a first type if it is lower than or equal to a first limit, and
- each pixel is of a second type if it is higher than a second limit.

In an aspect of the method, the second limit is higher than the first limit.

In an aspect of the method, the first limit is 0.3 radian, and preferably 0.1 radian.

In an aspect of the method, the second limit is 0.3 radian, and preferably 0.5 radian.

In an aspect of the method, two emitted pulses of the emitted sequence have an amplitude ratio of greater or equal to two.

In an aspect of the method, before step a), a contrast agent is introduced into the medium.

In an aspect of the method, the contrast agents comprises microbubbles.

Another object of the invention is fourthly to

provide an apparatus for determining an image of a region inside a medium, said apparatus comprising

- a probe comprising an ultrasound transducer,
- an electronic unit controlling the transducer,

5 and

- a processing unit for controlling the electronic unit 13 and for processing signals from said electronic unit.

10 The processing unit implements the method for determining an image of a region inside a medium above specified.

BRIEF DESCRIPTION OF THE DRAWINGS

15 Other features and advantages of the invention will be apparent from the following detailed description of its embodiments given by way of non-limiting example, with reference to the accompanying drawings.

In the drawings:

20 - Figure 1 is schematic drawing of an apparatus for implementing a first configuration of the method according to the invention (method for punctual measurement);

- Figure 2a is a time domain curve showing an emitted sequence of signals used by the method implemented
25 by the apparatus of figure 1;

- Figure 2b is a time domain curve showing a received sequence of signals corresponding to the emitted sequence of figure 2a;

30 - Figure 3a is a distribution of phase difference of received signals relative to emitted signal for a location inside a medium having a quasi-linear material behaviour;

- Figure 3b is a distribution of phase difference of received signals relative to emitted signal for a
35 location inside a medium having a non-linear material behaviour;

- Figure 4 is a schematic drawing of an apparatus for implementing a second configuration of the method according to the invention (imaging method);

5 - Figure 5 is an example of image produced by the apparatus and method represented on figure 4 and showing two sub-area of segmentation of said image for pointing out two organs included inside the medium.

10 In the figures, the same references denote identical or similar elements.

MORE DETAILED DESCRIPTION

15 **Figure 1** shows an apparatus 10 for implementing the method of the invention, for instance for the purpose of determining a characteristic of a location inside a medium 11, or for instance for the purpose of imaging an area in a medium 11.

20 The medium 11 is for instance a living body and in particular human or animal bodies, or can be any other biological or physic-chemical medium (e.g. in vitro medium). The volume of medium comprises variations in its physical properties. For example, the medium may comprise tissues and blood vessels, each one having various physical
25 properties. For example, the tissue may comprise an area suffering from an illness (e.g. cancerous cells), or any other singular area, having various physical properties in comparison to other area of the medium. Some portions of the medium 11 may include some added contrast agent (e.g.
30 micro bubbles) for improving the contrast of physical properties of these portions. When insonified by ultrasound waves, such contrast agents generate non-linear echoes. Therefore, a well-known use of such contrast agents is the injection of a fluid containing a predetermined quantity of
35 contrast agents inside blood vessels. Then, the physical characteristic of such blood vessels can be more easily

detected in comparison to a physical characteristic of a tissue that does not comprise the contrast agent, said contrast agent only flowing in the vessels.

The physical characteristics, that can be detected
5 by the method that senses the medium via ultrasound waves, are mechanical properties of the medium, like stiffness, or else. The method distinguishes values and/or variations of said physical properties. For example, the method may detect mechanical interface between two materials in the
10 medium: e.g. it can detect bubbles shell.

The apparatus 10 may include:

- a probe 12 comprising one ultrasound transducer or a plurality of ultrasound transducers (a transducer array), each transducer being adapted to transform a signal
15 into an ultrasound wave (emit) and/or to transform an ultrasound wave into a signal (receive),

- an electronic unit 13 controlling the transducers in the probe in both mode (receive and/or emit), and

- a processing unit 14 for controlling the
20 electronic unit 13, processing signals, and determining characteristics of the medium and/or images of said characteristics.

In a variant, a single electronic device could fulfil all the functionalities of the electronic unit 13
25 and of the processing unit 14. The processing unit 14 may be a computer.

The probe 12 can comprise a curved transducer so as to perform an ultrasound focussing to a predetermined position in front of the probe. The probe 12 can comprise a
30 linear array of transducers, few tens of transducers (for instance 100 to 300) juxtaposed along an axis X so as to perform ultrasound focussing into a bi-dimensional (2D) plane. The probe 12 can comprise a bi-dimensional array so as to perform ultrasound focussing into a tri-dimensional
35 (3D) volume.

A first configuration of the method represented on figure 1 is for determining a physical characteristic of a location P0 inside the medium 11, said location P0 being substantially a punctual location or a small region inside the medium around said location P0 (near location P0).

The above processing unit 14 controls the electronic unit 13 and the probe 12 for:

a) sending an emitted sequence ES of ultrasound waves We into the medium 11 towards the location P0, the emitted sequence ES comprising at least two emitted pulses Se1, Se2 having different amplitudes,

b) receiving a received sequence RS of ultrasound waves 4 from the location P0, the received sequence RS comprising at least two received pulses Sr1, Sr2, each one corresponding to said emitted pulses Se1, Se2.

The ultrasound waves We, Wr toward and from the location can be a focussed wave (beam) or a non focussed beam.

A well-known beamforming method can be used:

- the emitted ultrasound wave We is generated by a plurality of transducers signals that are delayed and transmitted to each transducer of a transducer array, and

- the received ultrasound wave Wr is composed of a plurality of transducers signals that are combined by delay and summation to produce a received sequence RS.

The at least two different amplitudes of emitted pulses can be produced by varying the transmit voltage or preferably by varying the aperture size (i.e. by varying the number of transducers elements contributing to emit the emitted ultrasound wave). The aperture may also be divided into two or more groups of elements.

Figures 2a shows an example of an emitted sequence ES comprising two signals Se1 and Se2, each one being an ultrasound pulse. For simplicity, these pulses (signals) are a portion of a sine signal (comprising only a single frequency component), but such pulses may be more

complex signals comprising a plurality of frequency components.

Figure 2b shows the received sequence RS corresponding to the emitted sequence of figure 2a, and comprising two received signals Sr1 and Sr2 corresponding to two ultrasound pulses in the received sequence RS. The first received signal Sr1 corresponds to an echo (reflexion) of the first emitted signal Se1, and the second received signal Sr2 corresponding to an echo (reflexion) of the second emitted signal Se2.

In the first configuration of the method, the processing unit 14 further operates the following steps:

c) Calculating a phase difference δ between the at least two received pulses (sensed by the received signals Sr1, Sr2), relative to the two emitted pulses (emitted signals Se1, Se2, known by the system), and

d) Determining the physical characteristic of the medium at the location P0 on the bases of said phase difference δ .

Each emitted sequence ES of ultrasound waves We comprises several emitted pulses (at least two). Also, each received sequence RS of ultrasound waves Wr comprises several received pulses.

Each pulse in these sequences may be a more complex signal, for example being a combination of a plurality of sine signals. However, we will consider in the present description that the pulses are only sine signals for the sake of simplicity.

A sine signal or pulse comprises a phase Φ and amplitude X. The phase of such sine signal is the angle at its origin in a time scale representation of the signal. The amplitude is the maximum value of the sine signal over time. Such phase can be determined or estimated by various methods: time shift relative to a reference clock signal, inter-correlation with said reference clock signal, calculation of $\text{Arctan}(\text{Im}/\text{Re})$ in case the signal is

represented by complex values (for example, in case of IQ demodulation), or any other known method.

A phase difference between two sine signals or pulses can be also determined by any one of the above-cited methods, and e.g. simply by differences of predetermined phases of each signal.

Then, the phase difference of step c) can be determined by various methods. Only two of them will be presented in the following description.

According to a first method for determining phases, the phase difference δ between two sequences of two sine signals (as used in step c) of the method) can be defined as the difference of:

- a first phase difference concerning the received signals δ_r , i.e. $\delta_r = \Phi(Sr2) - \Phi(Sr1)$, said first phase difference being measured, and

- a second phase difference concerning the emitted signals δ_e , i.e. $\delta_e = \Phi(Se2) - \Phi(Se1)$, said second phase difference being known by the system.

The defined phase difference δ is $\delta = \delta_r - \delta_e$.

This phase difference can also be calculated by the time shifts of the signals relative one to another: in this case, the phase difference δ is given by:

$$\delta = 2.\pi.f.(T_r - T_e) = 2.\pi.f.(\Delta t)$$

where

f is the frequency of the sine signal,

T_e is the time shift between the two emitted signals $Se1$, $Se2$ as illustrated on figure 2a, and

T_r is the time shift between the two received signals $Sr1$, $Sr2$ as illustrated on figure 2b.

If the time difference $(T_r - T_e)$ is greater than $2.\pi$, it should be reduced to the value modulo $2.\pi$.

According to a second method for determining phases, the two received sine signals may be scaled (weighted) so as to have the same amplitude, and then the resulted weighted signals are subtracted one to the other,

i.e.:

$$\delta_r = \Phi(a.Sr2-b.Sr1).$$

Eventually, the first weight coefficient a may be unity, and only b is determined so as b.Sr1 has the same
5 amplitude as Sr2.

The inventors have found that the above defined phase difference δ of the received signals (received pulses) relative to the emitted signals (emitted pulses) surprisingly depends on the nature of the medium 11 at the
10 focussed point P0. Therefore, the physical characteristic of said medium at the location P0 can be determined.

This effect is due to the difference of amplitude of first and second emitted pulses (Se1, Se2), and to the non-linear behaviour of the medium at point P0. This non-
15 linear behaviour of medium is usually analysed in ultrasound imaging via amplitude harmonics analysis (second harmonic, third harmonic ...). This is an amplitude and frequency analysis. In present case, the method uses phase difference analysis. Of course, such phase technique can
20 also be combined with harmonic analysis.

Advantageously, the first and second emitted signals ultrasound pulses (signals Se1, Se2) have a ratio of amplitudes greater or equal to two.

Additionally, a sum of the emitted signals in the
25 emitted sequence (ES) is null. Therefore, a simple method of summing the received signals cancels the first harmonic and this sum can be directly used to estimate the phase and/or harmonic behaviour of the material in the medium 11.

More specifically, the emit sequence ES can
30 comprise only two emit pulses of inverted amplitudes, denoted as a +1, -1 sequence, such as in pulse inversion method as described in patent US 6,095,980. In that case, the weighting factors a, b in the above second method for calculating the phase difference should also be preferably
35 (+1, +1) so that the sum of the signals is null.

More specifically, the emit sequence ES can

comprise three emit pulses of +1/2, -1, +1/2 amplitudes, such as in power modulated method as described in patent US 6,638,228. In that case, the above second method for calculating the phase difference should for example use
 5 the following formula:

$$\delta_r = \Phi(Sr1+Sr2+Sr3),$$

i.e. having the following weighting factors (+1, +1, +1).

Such method may be generalized as follow:

- the emit sequence ES comprises pulses having e1,
 10 e2, e3 amplitudes,
- the received signals Sr1, Sr2, Sr3 are combined into a combined signal CS by weighting factors r1, r2, r3 as follow: $CS = r1.Sr1+r2.Sr2+r3.Sr3$, and
- the phase difference δ is then the phase of the
 15 combined signal CS: $\delta = \Phi(CS)$.

In the method, the amplitudes and the weighting factors are chosen so that $e1.r1+e2.r2+e3.r3 = 0$. Then, the combined signal CS should be a null signal if the medium at the location P0 behaves as a linear material.

20 The inventors have discovered that looking at the phase of the resulting signal (the phase of the combined signal), that is the phase difference δ , is representative of the nature of the medium 11 at the location P0.

Thus, the phase difference δ measured at the given
 25 punctual location P0 can be used for determining the type or nature of medium at this punctual location P0.

In a first variant, the physical characteristic PC of the material of medium 11 at or near the punctual location P0 is proportional to the value of the previously
 30 determined phase difference δ .

In a second variant, the succession of steps a) to c) are repeated several times, for example M iterations, for providing a plurality of phase differences δ , said plurality having then M values of phase difference:
 35 $\delta_1, \dots, \delta_M$.

Then, during the step d), the physical

characteristic PC is determined by:

- a mean value of the plurality of phase differences, i.e. $PC = \text{mean}(\delta_1, \dots, \delta_M)$, or
 - 5 - a standard deviation value of the plurality of phase differences, i.e. $PC = \text{std}(\delta_1, \dots, \delta_M)$, or
 - a variance value of the plurality of phase differences, i.e. $PC = \text{variance}(\delta_1, \dots, \delta_M)$,
- these mathematical functions being usually well known defined or being equivalents of these well-known as many
- 10 variations in these definitions may be applied.

The M iterations can be proceeded with the same first and second amplitudes for the first and second emitted pulses (signals Se1, Se2) in the emitted sequence ES.

15 The M iterations can be proceeded with predetermined varying values of amplitudes for the first and second emitted signal Se1, Se2 in the emitted sequence ES, so as to test various variations of amplitudes and to test various possibilities of non-linearities in the

20 medium. Therefore, thanks to the above variant, a non-linear behaviour of the medium 11 at location P0 can be more easily distinguished from a linear behaviour.

In a third variant, the emitted sequence ES may comprise more than two signals of various amplitudes: it

25 may comprise a number N of pulses (signals): three, four, five or even more. The received sequence RS then comprises at least the same number N of received pulses (signals), and preferably the same number N of received pulses (signals). Each received signal Sri of index i must be

30 correctly associated to the corresponding emitted signal Sei of same index i.

Then, during the step c), a plurality of couples or pairs (index i and index j, $i \neq j$, and $i, j \leq N$) of emitted-received signals can be extracted, each couple of

35 emitted signals Sei, Sej having a different amplitude. For each couple, a phase difference δ_{ij} is determined as

explained above, so as to provide a plurality of phase differences.

Then, during the step d), the physical characteristic PC is determined by (ij being all the
5 predetermined couples)):

- a mean value of the plurality of phase differences, i.e.: $PC = \text{mean}(\delta_{ij})$, or

- a standard deviation value of the plurality of phase differences, i.e.: $PC = \text{std}(\delta_{ij})$, or

- 10 - a variance value of the plurality of phase differences, i.e.: $PC = \text{variance}(\delta_{ij})$.

The above mathematical functions are usually well known defined or equivalent of them.

The N signals may all have different amplitudes or
15 some of them can be identical. Then, various variations of amplitudes can be tested or experienced during the process. Therefore, a non-linear behaviour inside the medium 11 at location P0 can be more easily distinguished from a linear behaviour.

20

Figure 3a shows an example of a first distribution 20 of a plurality of phase differences δ for a location inside a medium having a substantially linear behaviour. Such distribution is a count of a number of
25 tests (ordinate of the curve) providing a given value of phase difference δ (abscissa of the curve).

This distribution curve 20 comprises a mean value (abscissa of the maximum of the curve) near zero radian, and a small standard deviation or variance (the width S of
30 the curve).

The absolute value of the mean value A is for instance lower than 0.1 radian, and the standard deviation is higher than 0.1 radian.

Such measurement corresponds to a location in the
35 medium 11 having a substantially linear behaviour: It may be a location or region of tissue, or not including any

contrast agent (e.g. micro-bubbles).

Figure 3b shows an example of a second distribution 21 of a plurality of phase differences δ for a location inside a medium having a substantially non-linear behaviour. It may be a location or region of blood vessel, or including a contrast agent (e.g. micro-bubbles).

This distribution curve 20 comprises a mean value A (abscissa of the maximum of the curve) that is non zero radian, and a standard deviation S or variance much higher (the width of the curve) than in the case of the figure 3a.

The absolute value of the mean value A is for instance higher than 0.3 radian, and the standard deviation is higher than 0.3 radian. Both values can therefore be used to distinguish a first type of material (physical characteristic) inside the medium from a second type of material (physical characteristic).

Therefore, all the above variants of the method can then include the following steps for classifying or segmenting the nature or type of physical characteristic at the location P0 inside the medium 11:

- if the physical characteristic PC is lower than or equal to a first limit L1, the physical characteristic corresponds to a first type of material, and
- if the physical characteristic PC is higher than a second limit L2, the physical characteristic corresponds to a second type of material.

Eventually, the second limit L2 is higher than the first limit L1, and if the physical characteristic is inside the interval of these two limits (L1, L2), the type of material is not determined.

Eventually, the second limit L2 is equal to the first limit L1.

Thanks, to these classification steps, the type of physical characteristic is determined.

For example, the first limit L1 is 0.3 radian, or 0.1 radian, so as to determine if the physical

characteristic is low (linear behaviour).

For example, the first second limit L2 is 0.3 radian, or 0.5 radian, so as to determine if the physical characteristic is high (non-linear behaviour).

5 These limits can be adapted to each application of the method: distinguishing a region including a contrast agent from another region not including the contrast agent, or distinguishing tissue to blood vessels, or distinguishing illness cells to healthy cells.

10

A second configuration of the method is, illustrated on **figure 4**, such method is used for determining an image of a region R inside a medium 11.

15 The method uses identical or similar elements of the above disclosed apparatus 10 of figure 1.

20 The image produced by the method is composed of a plurality of pixels (for example, a number K of pixels), each pixel corresponding to a different location (Pk) inside the region R, k being an index to identify each pixel in the image or each location in the region R. Eventually, the image may be composed of only one pixel. However, the image may preferably comprise more than one ten thousand pixels (100x100 image).

25 The second configuration of the method (imaging method) mainly differs from the previous first configuration of the method by the scanning of a plurality of locations inside a region R so as to generate an image of said region.

30 At each location Pk inside the region R, the processing unit 14 controls the electronic unit 13 and the probe 12 for:

35 a) sending an emitted sequence ES of ultrasound waves We towards the location, the emitted sequence ES comprising at least two emitted pulses (corresponding to emitted signals Se1, Se2), said pulses having different amplitudes,

b) receiving a received sequence RS of ultrasound waves W_r from the location, the received sequence RS comprising at least two received pulses (corresponding to received signals S_{r1} , S_{r2}), said received pulses being
5 responses (echoes) from said emitted pulses.

Similarly as for the first configuration, the ultrasound waves W_e , W_r can be focused or non focused waves, according to known techniques.

The emitted and received signals (representing the
10 pulses) are also similar or identical to those as represented on figures 2a and 2b, and the corresponding above description also applies to the second configuration of the method.

In the method of the second configuration of the
15 invention, the processing unit 14 operates then the following steps for each location P_k inside the region R:

c) Calculating a phase difference δ between the two received signals S_{r1} , S_{r2} , relative to the two emitted signals S_{e1} , S_{e2} , and

20 d) Determining the pixel value in the image, corresponding to the location P_k inside the region R on the bases of the phase difference.

The definitions given for a signal phase and a phase difference δ during the first configuration of the
25 method are still valid. There are various methods for determining a phase or phase difference.

The phase difference δ at step c) can be determined by various methods, and least one of the following two methods.

30 According to a first method, the phase difference δ is a difference of two phase differences: the one concerning the received signals (δ_r : measured) and the one concerning the emitted signals (δ_e : known). The phase difference is then for example calculated by the following
35 formula (explained in the first configuration of the method):

$$\delta = \delta_r - \delta_e = \Phi(Sr2) - \Phi(Sr1) - \delta_e.$$

Then, the method comprises the following sub-steps:

c1) determining a phase for each one of the two pulses in the received sequence (RS), and

5 c2) calculating the phase difference δ by subtracting said phases.

According to a second method, the phase difference δ is a phase of a combined signal, said combined signal being a weighted sum of the received signals.

10 For example, in case of two pulses (signals), the phase difference can be calculated by the following formula:

$$\delta_r = \Phi(a.Sr2-b.Sr1),$$

The weighting factors a, b being determined to have
15 cancelation of the weighted signals (a.Sr2, b.Sr1) if the medium has a linear behaviour.

More generally, the phase difference δ is:

$$\delta = \Phi(CS) = \Phi(r1.Sr1+r2.Sr2+r3.Sr3).$$

The amplitudes e1, e2, e3 for the emit pulses and
20 the weighting factors r1, r2, r3 for the received signals are chosen so that $e1.r1+e2.r2+e3.r3 = 0$.

Then, the method comprises the following sub-steps:

c3) received signals corresponding to received pulses are weighted by weighting factors and summed for
25 producing a combined signal CS, the amplitudes of the emit pulses and the weighting factors for the received signals being predetermined so that their inner product is null, and

c4) the phase difference δ is a phase of said
30 combined signal CS. In other words, if amplitudes are firstly defined, the weighting factors are determined so that to compensate the predetermined amplitudes.

In a first variant, the pixel value corresponding to each location P_k inside the region R is directly the
35 value of the previously determined phase difference δ .

In a second variant, the succession of steps a)

to c) are repeated several times, for example M iterations, for providing a plurality of phase differences δ , said plurality having then M values of phase difference: $\delta_1, \dots, \delta_M$.

5 Then, during the step d), the pixel value is determined by a mean value or standard deviation value or a variance value of the plurality of phase differences.

 The M iterations can be proceeded with the same first and second amplitudes for the first and second
10 emitted pulses (signals Se1, Se2) in the emitted sequence ES.

 The M iterations can be proceeded with predetermined varying values of amplitudes for the first and second emitted pulses (signals Se1, Se2) in the emitted
15 sequence ES, so as to test various variations of amplitudes and to test various possibilities of non-linearities of the medium at each location Pk. Therefore, a non-linear behaviour of each location Pk in the region can be more easily distinguished from a linear behaviour.

20 In a third variant, the emitted sequence ES may comprise more than two pulses of various amplitudes: it may comprise a number N of pulses: three, four, five or more pulses. The received sequence RS then comprises at least the same number N of received pulses, and preferably the
25 same number N of received pulses. Each received signal Sri of index i (corresponding to a pulse i) must be correctly associated to the corresponding emitted pulse (i.e. emitted signal Sei) of same index i.

 Then, during the step c), a plurality of couples or
30 pairs (index i and index j, $i \neq j$, and $i, j \leq N$) of emitted-received signals can be extracted, each couple of emitted signals Sei, Sej having a different amplitude. For each couple, a phase difference δ_{ij} is determined as explained above, so as to provide a plurality of phase
35 differences.

 Then, during the step d), the pixel value is

determined by a mean value e or standard deviation value or a variance value of the plurality of phase differences

The N emitted pulses (signals) may all have different amplitudes or some of them can be identical.
5 Then, various variations of amplitudes can be tested during the process. Therefore, a non-linear behaviour of the medium 11 at each location P_k inside the region R can be more easily distinguished from a linear behaviour.

10 In a fourth variant, the region R is subdivided in a plurality of sub-regions, corresponding to sub-area in the image.

Between step c) and step d) of the method, a sub-region phase difference (δ_{sr}) is calculated, said sub-region phase difference (δ_{sr}) being a mean value of the
15 plurality of phase differences (δ) of the locations belonging to said sub-region calculated during step c).

Then, a pixel in the image corresponds to a sub-region.

20 Additionally, any of the above variant can be combined to another one to have a method that provides a more sensitive image of the medium: non-linear behaviour are more easily distinguished from a linear behaviour.

Figure 5 shows an example of such image IM
25 determined for a rectangular region inside a body of a patient. The grey scale represents directly the phase difference values determined at each locations of the matrix or grid.

Similarly to the first configuration of the
30 invention, all the variants of the method can then include following steps for classifying or segmenting the image:

- if a pixel value is lower than or equal to a first limit L_1 , the pixel corresponds to a first type and
- if a pixel value is higher than a second
35 limit L_2 , the physical characteristic corresponds to a second type.

Eventually, the second limit L2 is higher than the first limit L1, and if the pixel value is inside the interval of these two limits (L1, L2), the type the pixel is not determined.

5 Eventually, the second limit L2 is equal to the first limit L1.

Thanks, to these classification steps, the image can be segmented into sub-areas having different properties.

10 For example, the first limit L1 is 0.3 radian, or 0.1 radian, so as to determine a sub-area of a first type (linear behaviour).

For example, the second limit L2 is 0.3 radian, or 0.5 radian, so as to determine a sub-area of a second type
15 (non-linear behaviour).

These limits can be adapted to each application of the method: distinguishing tissue to blood vessels, or distinguishing illness cells to healthy cells.

For example, the figure 5 shows:

20 - a first sub-area R1 of a first type (linear), and being a sub-area corresponding to a portion of the medium 11 being tissue, and

- a second sub-area R2 of a second type (non-linear), and being a sub-area corresponding to a
25 portion of the medium 11 being a blood vessel.

Then, in all the present methods can take advantage in using contrast agents inside the medium 11.

For example, contrast agents penetrate blood vessels but not into the tissues. Then, the contrast
30 between the different area of the medium 11 with and without contrast agents will be increased, as illustrated on figure 5.

Ultrasound contrast agents could be small gas-filled micro-bubbles contrast agents. Small gas-filled
35 micro-bubbles could be for example seeded into a blood stream or from encapsulated micro-bubbles. Contrast agents

could consist of gas-filled microscopically small bubbles encapsulated by an elastic shell. There are a variety of micro-bubbles contrast agents. Micro-bubbles could be heavy gas/air mixture (PFC, SF₈), encapsulated (shell - lipid, 5 albumin, polymer). Micro-bubbles differ in their shell makeup, gas core makeup, and whether or not they are targeted. Micro-bubble size is fairly uniform. They lie within a range of 1 to 10 micro-meters in diameter. That makes them smaller than red blood cells, which allows them 10 to flow easily through the circulation as well as the microcirculation. Micro-bubbles could be administrated by intravenous injection to the systemic circulation. They could be removed dissolved in circulation, filtered by liver and cleared 15 minutes.

15 Micro-bubbles have a high degree of ability to reflect the ultrasound waves. When micro-bubbles are caught in an ultrasonic frequency field, they compress, oscillate, and reflect a characteristic echo, generating a non-linear ultrasound backscatter. The ultrasound pulses are thus 20 reflected in a different way by the gas in the medium containing micro-bubbles and by the soft tissue surroundings.

CLAIMS

1. A method for determining a physical characteristic on a punctual location (P0) inside a medium (11),

5 comprising the following steps:

a) sending an emitted sequence (ES) of ultrasound waves (We) into the medium (11) towards the location (P0), the emitted sequence (ES) comprising at least two emitted pulses having different amplitudes,

10 b) receiving a received sequence (RS) of ultrasound waves (Wr) from the location (P0), the received sequence (RS) comprising at least two received pulses corresponding to echoes of said emitted pulses,

c) calculating a phase difference (δ) between the
15 received pulses relative to the emitted pulses, and

d) determining the physical characteristic on the bases of said phase difference (δ).

2. The method according to claim 1, wherein the
20 **step c) of calculating a phase difference comprises the following sub-steps:**

c1) determining a phase for each one of the received pulses in the received sequence (RS), and

c2) calculating the phase difference (δ) by
25 combining said phases.

3. The method according to claim 1, wherein the
step c) of calculating a phase difference comprises the following sub-steps:

30 c3) received signals corresponding to said received pulses are weighted by weighting factors and summed for producing a combined signal (CS), said weighting factors being determined so that to compensate the different amplitudes of the emit pulses, and

35 c4) the phase difference (δ) is a phase of said combined signal (CS).

4. The method according to any one of claims 1 to 3, wherein the physical characteristic is proportional to the phase difference (δ).

5

5. The method according to any one of claims 1 to 4, wherein the succession of steps a) to c) are repeated several times for providing a plurality of phase differences (δ), and wherein:

10 - during step d), the physical characteristic is determined by a mean or a standard deviation or a variance of said plurality of phase differences.

6. The method according to any one of claims 1 to 5, wherein the emitted sequence comprises a number greater than two emitted pulses, the received sequence comprises at least the same number of received pulses than the number of emitted pulses, and wherein:

20 - during step c), a plurality of phase differences between couples corresponding to two received and emitted pulses is calculated, each couple of emitted pulses having a different amplitude, and

25 - during step d), the physical characteristic is determined by a mean or a standard deviation or a variance of said plurality of phase differences.

7. The method according to any one of claim 1 to 6, wherein:

30 - the physical characteristic is of a first type if it is lower than or equal to a first limit, and

- the physical characteristic is of a second type if it is higher than a second limit.

8. The method of claim 7, wherein the second limit is higher than the first limit.

35

9. An apparatus for determining physical characteristic on a punctual location (P0) inside a medium (11), said apparatus comprising

- a probe 12 comprising an ultrasound transducer,
 - 5 - an electronic unit 13 controlling the transducer, and
 - a processing unit 14 for controlling the electronic unit 13 and for processing signals from said electronic unit, and
- 10 wherein the processing unit 14 implements the method according to any one of claims 1 to 8.

10. A method for determining an image of a region (R) inside a medium (11), the image being composed of a plurality of pixels, and wherein the method comprises for a plurality of locations (Pk) inside the region (R), the following steps:

- a) sending an emitted sequence (ES) of ultrasound waves (We) towards the location (Pk) into the region (R),
- 20 the emitted sequence (ES) comprising at least two emitted pulses of different amplitudes,
- b) receiving a received sequence (RS) of ultrasound waves (Wr) from the location (Pk), the received sequence (RS) comprising at least two received pulses
- 25 corresponding to said emitted pulses,
- c) calculating a phase difference (δ) between the received pulses relative to the emitted pulses, and
- d) determining the pixel of the image on the bases of said phase difference (δ).

30

11. The method according to claim 10, wherein the step c) of calculating a phase difference comprises the following sub-steps:

- c1) determining a phase for each one of the
- 35 received pulses in the received sequence (RS), and
- c2) calculating the phase difference (δ) by

combining said phases.

12. The method according to claim 10, wherein the step c) of calculating a phase difference comprises the following sub-steps:

c3) received signals corresponding to said received pulses are weighted by weighting factors and summed for producing a combined signal (CS), said weighting factors being determined so that to compensate the different amplitudes of the emit pulses, and

c4) the phase difference (δ) is a phase of said combined signal (CS).

13. The method according to any one of claims 10 to 12, wherein during step d), the pixel is proportional to the phase difference (δ).

14. The method according to any one of claims 10 to 13, wherein the succession of steps a) to c) are repeated several times for providing a plurality of phase differences (δ) for each location inside the region, and wherein:

- during step d), the pixel is determined by calculating a mean or a standard deviation or a variance of said plurality of phase differences.

15. The method according to any one of claims 10 to 11, wherein the emitted sequence comprises a number greater than two emitted pulses, the received sequence comprises at least the same number of received pulses, and wherein:

- during step c), a plurality of phase differences between couples of corresponding to two received and emitted pulses is calculated, each couple of emitted pulses having a different amplitude, and

- during step d), the pixel is determined by calculating a mean or a standard deviation or a variance of

said plurality of phase differences.

16. The method according to any one of claims 10 to 15,
wherein each pixel in the image corresponds to a
5 location (Pk) inside the region.

17. The method according to any one of claims 10 to 16,
wherein:

10 - the region (R) is subdivided in a plurality of
sub-regions,

- between step c) and step d), a sub-region phase
difference (δ_{sr}) is calculated, said sub-region phase
difference (δ_{sr}) being a mean value of the plurality of
phase differences (δ) of the locations belonging to said
15 sub-region, and

- each pixel in the image corresponds to a
sub-region.

18. The method according to any one of claim 10 to 17,
20 wherein:

- each pixel is of a first type if it is lower than
or equal to a first limit, and

- each pixel is of a second type if it is higher
than a second limit.

25

19. The method according to claim 18, wherein the
second limit is higher than the first limit.

20. The method according to claim 18 or claim 20,
30 wherein the first limit is 0.3 radian, and preferably
0.1 radian.

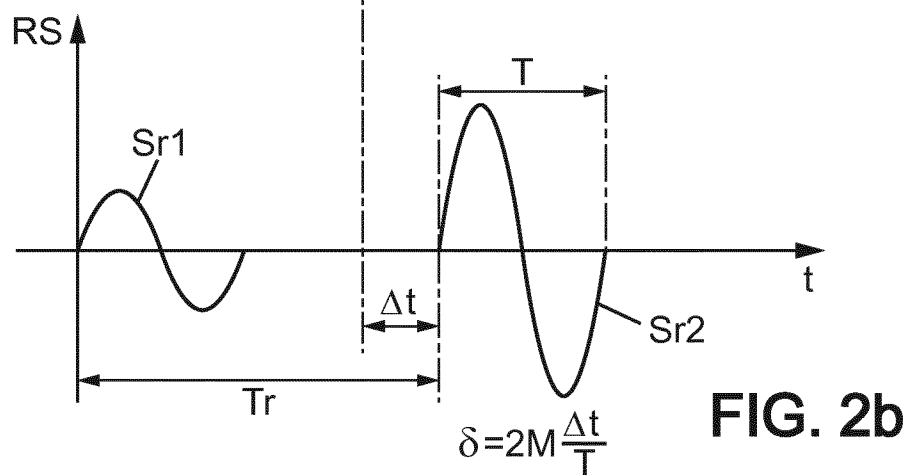
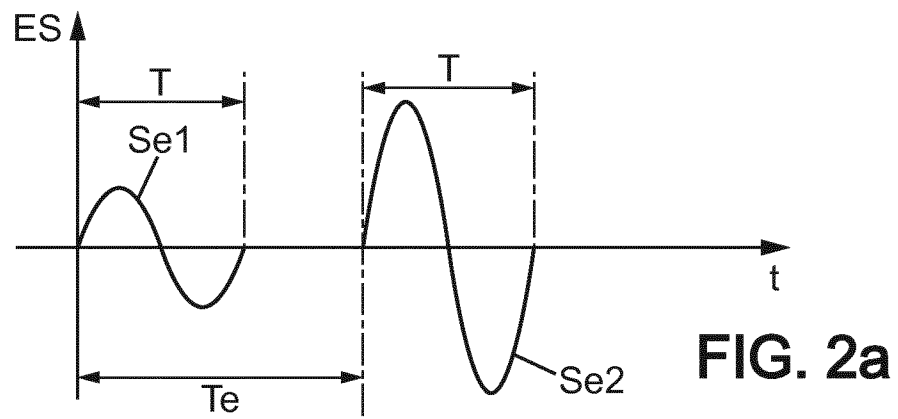
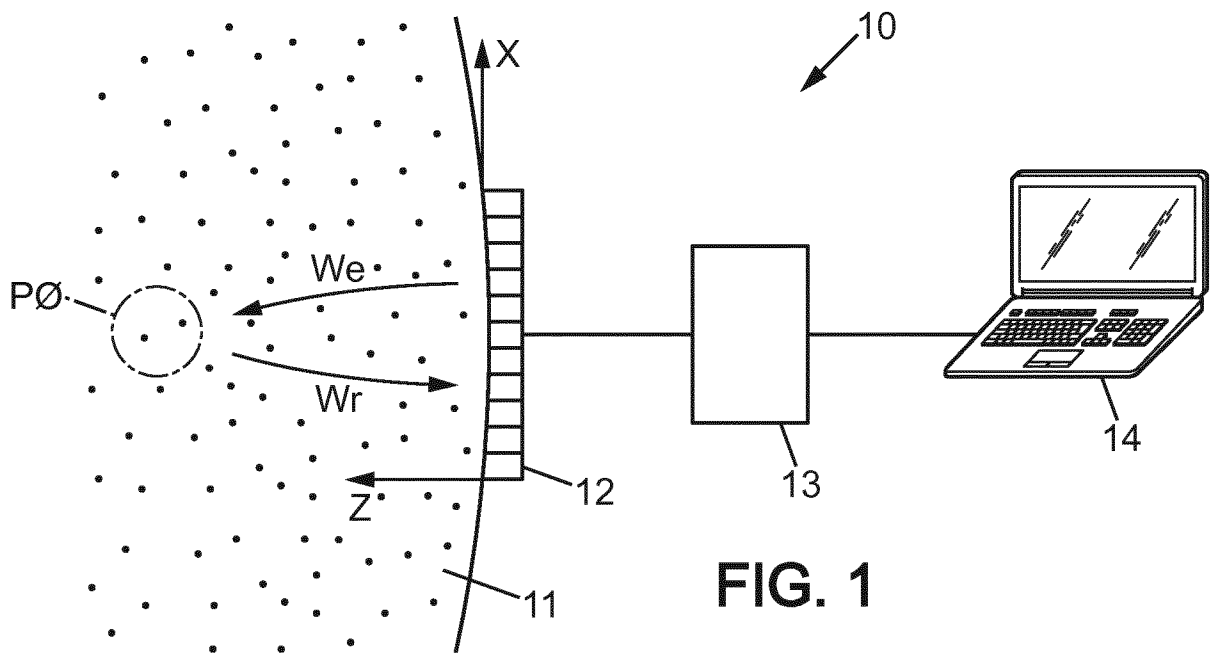
21. The method according to any one of claims 18 to 20,
wherein the second limit is 0.3 radian, and
35 preferably 0.5 radian.

22. The method according to any one of claims 10 to 21, wherein two emitted pulses of the emitted sequence (ES) have an amplitude ratio of greater or equal to two.

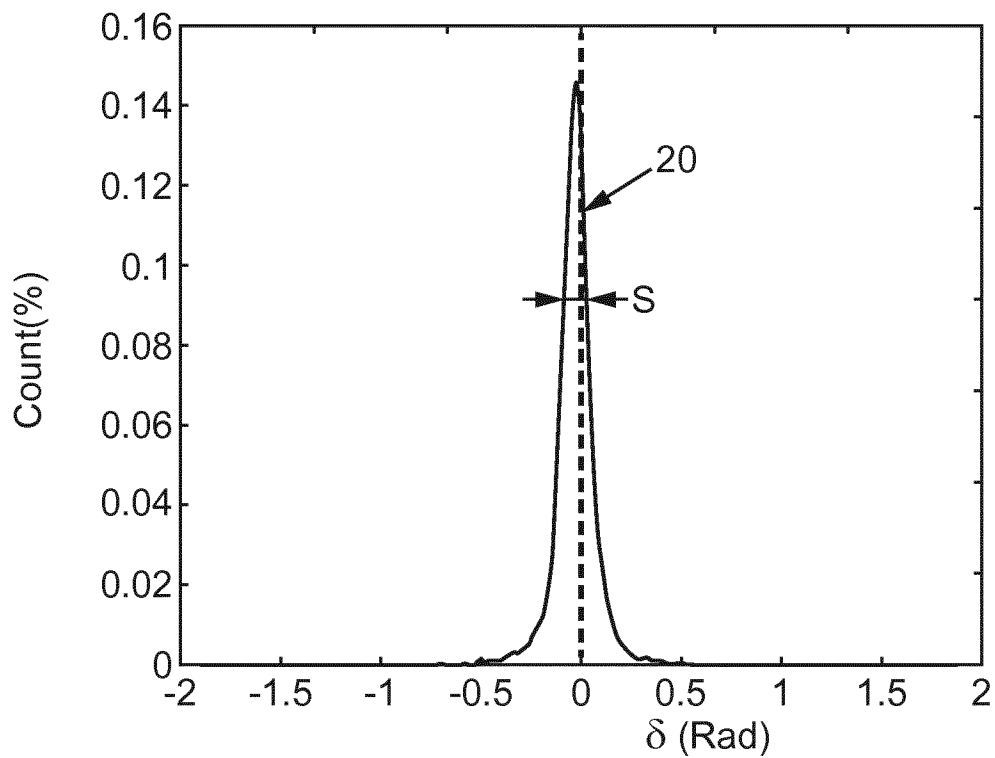
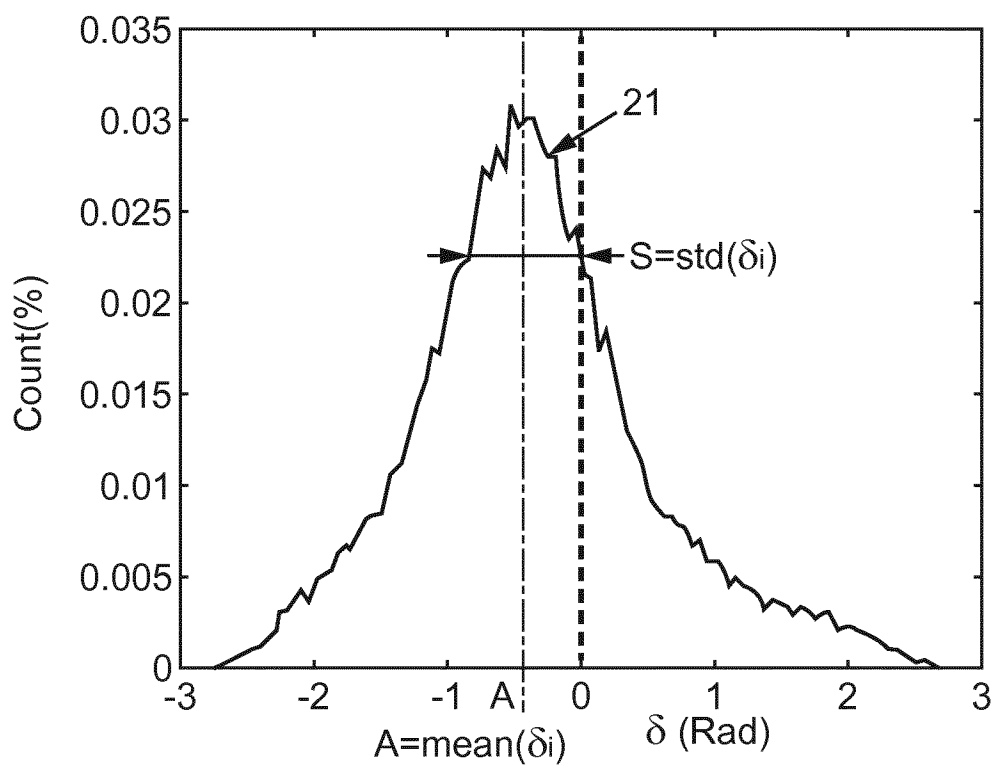
5 23. The method according to any one of claims 10 to 22, wherein before step a), a contrast agent is introduced into the medium.

24. The method according to claim 23, wherein the
10 contrast agents comprises microbubbles.

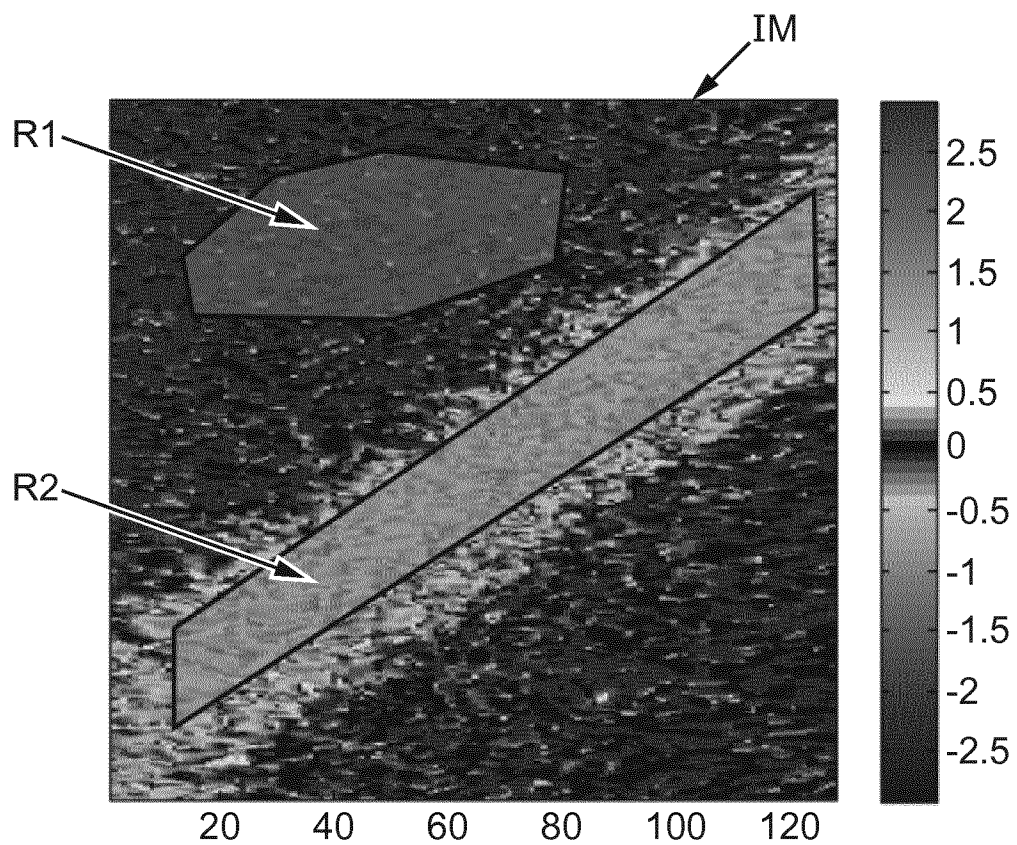
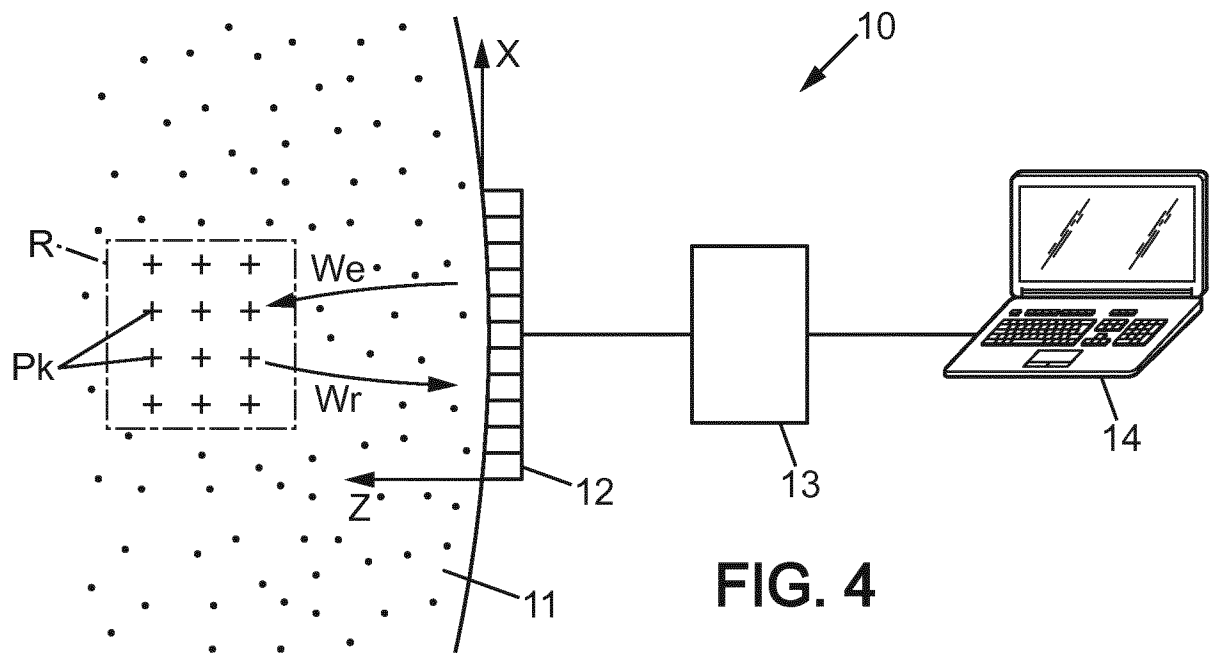
25. **An apparatus for determining an** image of a region (R) inside a medium (11), said apparatus comprising
- a probe 12 comprising an ultrasound transducer,
15 - an electronic unit 13 controlling the transducer,
and
- a processing unit 14 for controlling the electronic unit 13 and for processing signals from said electronic unit, and
20 wherein the processing unit 14 implements the method according to any one of claims 10 to 24.



2/3

**FIG. 3a****FIG. 3b**

3/3



INTERNATIONAL SEARCH REPORT

International application No

PCT/EP2015/051369

A. CLASSIFICATION OF SUBJECT MATTER

INV. G01S7/52 G01S15/89
ADD.

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

G01S A61B

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

EPO-Internal, WPI Data

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 6 398 732 B1 (BROCK-FISHER GEORGE A [US] ET AL) 4 June 2002 (2002-06-04) abstract; figure 4 column 1, line 22 - line 63 column 2, lines 15-24, 47-54 column 3, line 36 - column 5, line 12 -----	1-25
A	WO 2010/121265 A1 (VISUALSONICS INC [CA]; NEEDLES ANDREW [CA]; MEHI JAMES I [CA]; HIRSON) 21 October 2010 (2010-10-21) abstract; figures 2C, 2D page 2, line 21 - line 23 page 8, line 10 - page 9, line 19 page 11, line 16 - page 12, line 14 ----- -/--	1-25



Further documents are listed in the continuation of Box C.



See patent family annex.

* Special categories of cited documents :

"A" document defining the general state of the art which is not considered to be of particular relevance

"E" earlier application or patent but published on or after the international filing date

"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)

"O" document referring to an oral disclosure, use, exhibition or other means

"P" document published prior to the international filing date but later than the priority date claimed

"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone

"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art

"&" document member of the same patent family

Date of the actual completion of the international search

29 April 2015

Date of mailing of the international search report

11/05/2015

Name and mailing address of the ISA/

European Patent Office, P.B. 5818 Patentlaan 2
NL - 2280 HV Rijswijk
Tel. (+31-70) 340-2040,
Fax: (+31-70) 340-3016

Authorized officer

Knoll, Bernhard

INTERNATIONAL SEARCH REPORT

International application No
PCT/EP2015/051369

C(Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	US 6 638 228 B1 (BROCK-FISHER GEORGE A [US] ET AL) 28 October 2003 (2003-10-28) cited in the application abstract column 10, line 33 - column 12, line 13 -----	1-25

INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No

PCT/EP2015/051369

Patent document cited in search report	Publication date	Patent family member(s)	Publication date	
US 6398732	B1	04-06-2002	US 6398732 B1	04-06-2002
			US 2002111553 A1	15-08-2002

WO 2010121265	A1	21-10-2010	CN 102458257 A	16-05-2012
			EP 2419020 A1	22-02-2012
			JP 2012523904 A	11-10-2012
			US 2010298709 A1	25-11-2010
			WO 2010121265 A1	21-10-2010

US 6638228	B1	28-10-2003	AU 2003214575 A1	10-11-2003
			EP 1501419 A1	02-02-2005
			JP 2005523743 A	11-08-2005
			US 2003204142 A1	30-10-2003
			US 2004030253 A1	12-02-2004
			WO 03090624 A1	06-11-2003
