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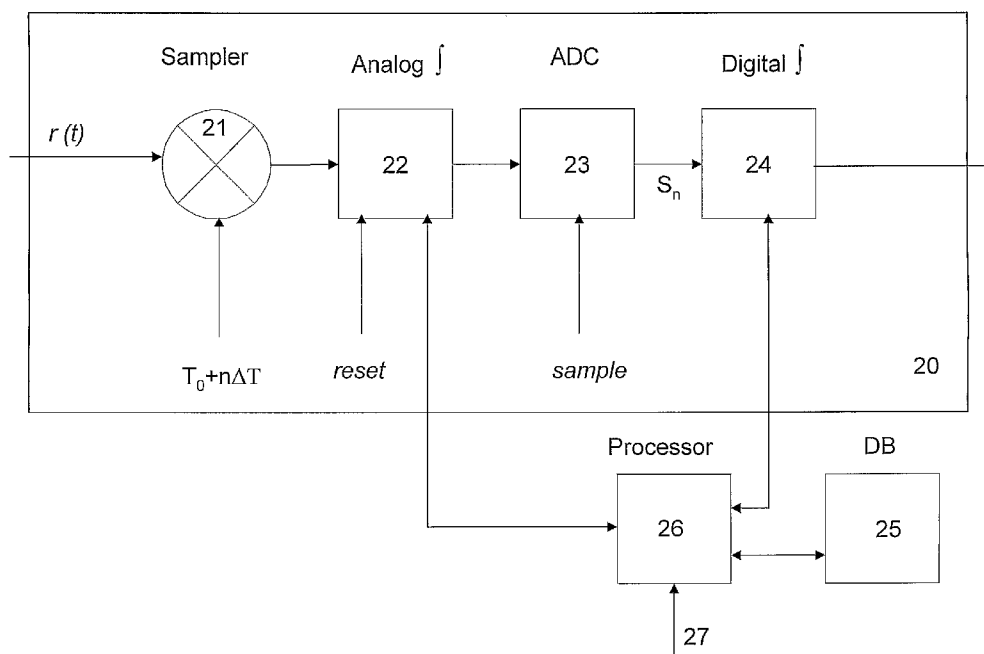
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(54) Title: SIGNAL ACQUISITION SYSTEM AND METHOD FOR ULTRA-WIDEBAND (UWB) RADAR



(57) Abstract: An acquisition channel (20) includes a UWB sampler block (21) coupled to an analog integration block (22) further coupled to a digital integration block (24) via an analog/digital converter (23). For each range cell the UWB sampler block (21) repeatedly samples the received signal by tuning the sampling instants to the range cells to be acquired. The acquisition channel (20) is further coupled to a processor (26) and a database (25).

WO 2007/029227 A1

- 1 -

Signal Acquisition System and Method for Ultra-Wideband (UWB) Radar

FIELD OF THE INVENTION

The invention relates to radar imaging systems and, more particular, to signal acquisition in imaging systems based on ultra-wide band radars.

5 BACKGROUND OF THE INVENTION

Ultra-Wideband (UWB) is a term for a classification of signals that occupy a substantial bandwidth relative to their centre frequencies (for example, according to the Federal Communications Commission (FCC) Rules, UWB signal is a signal whose fractional bandwidth (the ratio between its bandwidth to its center frequency) is equal or
10 greater than 0.2 or its bandwidth is equal or greater than 500 MHz.). Their very high bandwidth allows UWB based radar systems to obtain more information about targets, and makes it possible to build radar with better spatial resolution compared to conventional radar. Therefore the UWB radar devices are widely implemented for radar-based imaging systems, including ground penetrating radars, wall and through-
15 wall radars, surveillance and medical imaging devices, etc.

For most radar systems, the received signal SNR (signal to noise ratio) is a crucial factor, which determines the detection/imaging performance. A well known approach for improving detection capabilities is to perform coherent integration. In this approach, the received signal is summed up repeatedly (on different transmit/receive
20 cycles), and, as a result, the deterministic (repetitive) part on the signal builds up much faster compared to the noise, thus improving signal SNR; the longer the integration lasts, the larger the SNR improvement.

This problem has been recognized in prior art and various systems have been developed to provide a solution, for example:

25 US Patent 5,132,688 (Shima *et al.*) entitled "Pulsed Doppler radar system having an improved detection probability" discloses a pulsed Doppler radar system having an improved detection probability, comprising an antenna unit, a transmitter for transmitting a signal through the antenna unit, a receiver for receiving a signal reflected by a target through the antenna unit to provide a reception signal. A processing unit
30 which receives the reception signal from the receiver determines, in accordance with a range of the target and a signal-to-noise ratio and bandwidth of the reception signal, an

- 2 -

optimum integration number which maximizes the detection probability and performs coherent integration on the reception signal by the number of times equal to the determined optimum integration number thereby outputting a signal having a predetermined level. Such a signal is fed to a display and an image of the target can be
5 viewed on a display.

US Patent 5,457,462 (Mitsumoto *et al.*) entitled "Radar signal processor and pulse Doppler radar system therewith" discloses a radar signal processor for use in a pulse radar system. Reception signals are given from a range divide and output circuit to a plurality of integration point variable coherent integrators, each of which is
10 allocated to a different range domain. The range domain is given to an integration point setting section provided corresponding to each integration point variable coherent integrator. The integration point setting section determines the number of coherent integration points based on the given range domain and sets it in the corresponding integration point variable coherent integrator. The signal resulting from coherent
15 integration by the integration point variable coherent integrator is discriminated to frequencies, and then supplied to any square detector for square detection for each frequency component. Square detection output is fed into a CFAR detector, which then makes its false alarm rate constant for a supply to a display, etc.

SUMMARY OF THE INVENTION

20 There is a need in the art to provide for a new system and method of signal acquisition in UWB radar imaging system with configurable signal-to-noise ratio and dynamic range. The invention, in some of its aspects, is aimed to provide a novel solution capable of providing desired SNR profile and decreasing the requirement for dynamic range and rate of analog to digital conversions and other digital electronics.

25 In accordance with certain aspects of the present invention, there is provided a signal acquisition system capable of integrating at least one received signal whereby compensating a signal loss, the system comprising:

- (a) at least one sampler configured to sample the received signal and to provide samples of different range cells;
- 30 (b) at least one analog integrator coupled to the sampler and configured to integrate the said samples whereby compensating at least part of the signal loss and giving rise to analog samples;

- 3 -

- (c) at least one analog/digital converter coupled to the analog integrator and configured to convert said analog samples into digital samples;
- (d) at least one digital integrator coupled to the analog/digital converter and configured to integrate said digital samples.

5 In accordance with further aspects of the present invention, there is provided a method of signal acquisition with integrating at least one received signal whereby compensating a signal loss; the method comprising:

- (a) sampling the received signal giving rise to samples of different range cells;
- (b) analog integrating of said samples whereby compensating at least part of the
10 signal loss and giving rise to analog samples;
- (c) analog/digital converting said analog samples into digital samples;
- (d) digital integrating said digital samples.

The system and method are designated for use with radar and, in particular, with ultra-wideband radar. According to certain aspects of the present invention the signal
15 loss may be caused by at least one of the following: a free space propagation path loss depending on the range, an obstacles-originated loss and a loss caused by variations of radar cross section. The compensation of the signal loss via integration may be provided for improving the signal to noise ratio (SNR) of the received signals.

In accordance with further aspects of the present invention, for samples of at
20 least one range cell, the analog integrator is configured to provide N_a analog integration cycles, the digital integrator is configured to provide N_d digital integration cycles and overall number N of integration cycles for said samples substantially complies with the equation $N = N_a \times N_d$. According to further aspects of the present invention, the overall number of integration cycles and/or number of analog and/or digital integrations
25 vary for samples of different range cells, for example, in accordance with desired SNR profile, frame rate of the radar and/or desired dynamic range.

BRIEF DESCRIPTION OF THE DRAWINGS

In order to understand the invention and to see how it may be carried out in practice, a preferred embodiment will now be described, by way of non-limiting
30 example only, with reference to the accompanying drawings, in which:

Fig. 1 is generalized block diagram of radar imaging system as known in the art;

- 4 -

Fig.2 is generalized diagram of a signal acquisition system in accordance with certain embodiments of the present invention; and

Fig. 3 is generalized diagram of operation of signal acquisition system in accordance with certain embodiments of the present invention.

5 DETAILED DESCRIPTION OF EXEMPLARY EMBODIMENTS

In the following detailed description, numerous specific details are set forth in order to provide a thorough understanding of the invention. However, it will be understood by those skilled in the art, that the present invention may be practiced without these specific details. In other instances, well-known methods, procedures,
10 components and circuits have not been described in detail so as not to obscure the present invention.

Unless specifically stated otherwise, as apparent from the following discussions, it is appreciated that throughout the specification discussions utilizing terms such as "processing", "computing", "calculating", "determining", or the like, refer to the action
15 and/or processes of a computer or computing system, or processor or similar electronic computing device, that manipulate and/or transform data represented as physical, such as electronic, quantities within the computing system's registers and/or memories into other data, similarly represented as physical quantities within the computing system's memories, registers or other such information storage, transmission or display devices.

20 Embodiments of the present invention may use terms such as, processor, computer, apparatus, system, sub-system, module, unit, device (in single or plural form) for performing the operations herein. This may be specially constructed for the desired purposes, or it may comprise a general purpose computer selectively activated or reconfigured by a computer program stored in the computer. Such a computer program
25 may be stored in a computer readable storage medium, such as, but not limited to, any type of disk including optical disks, CD-ROMs, flash memory (e.g. Disk-on-Key), magnetic-optical disks, read-only memories (ROMs), random access memories (RAMs), electrically programmable read-only memories (EPROMs), electrically erasable and programmable read only memories (EEPROMs), magnetic or optical
30 cards, or any other type of media suitable for storing electronic instructions, and capable of being coupled to a computer system bus.

Various general purpose systems may be used with programs in accordance with

- 5 -

the teachings herein, or it may prove convenient to construct a more specialized apparatus to perform the desired method. The desired structure for a variety of these systems will appear from the description below. In addition, embodiments of the present invention are not described with reference to any particular programming language. It
5 will be appreciated that a variety of programming languages may be used to implement the teachings of the inventions as described herein.

Also it should be noted that the terms "range cell", "sampling phase", and "sampling instant" used in this patent specification are all equivalent and can freely be interchanged.

10 Attention is drawn to **Fig. 1**, illustrating a generalized diagram of a UWB radar imaging system as known in the art.

The UWB radar imaging system comprises $N \geq 1$ transmitters **11** and $M \geq 1$ receivers **12** arranged in (or coupled to) an antenna array **13**. At least one transmitter transmits a pulse signal (or other form of UWB signal, such as M-sequence coded
15 signal) to a space to be imaged and at least one receiver captures the scattered/reflected waves. To enable high quality imaging, sampling is provided from several receive channels. The process is repeated for each transmitter separately or simultaneously with different coding per each transmitter (e.g. M-sequence UWB coding). The received signals are transferred to a signal acquisition system **14** coupled to the antenna **13**.

20 The signal-to-noise ratio (SNR) of the received signal decreases with the target range due to increasing free space propagation of the waves. It is well known that integrating a signal for N cycles amplifies the signal by a factor N , and the noise root mean square (RMS) amplitude by a factor $\sqrt{N}$. Therefore, integrating the signal over multiple reception cycles may compensate signal losses and improve the SNR. The
25 signal acquisition system is capable of receiving the signals from a plurality of receivers, of providing the integration of the received signals and of controlling the signal acquisition process.

The resulting integrated signals **15** (typically from all receivers for each transmitter) are transferred to an image reconstruction and display system **16** coupled to
30 the signal acquisition system. The image reconstruction may be provided by using different appropriate techniques, such as, for example, ellipsoidal back-projection (e.g. see US Pat. No. 5,601,083 (Anderson) entitled "Real time 3D imaging device using filtered ellipsoidal back projection").

- 6 -

In many radar systems the signal acquisition system **14** provides integration by way of a digital sampling. In this case the received signal is sampled on a uniform grid over the time domain, at a given sampling rate (obeying the Nyquist criterion), and converted to discrete digital samples. In order to achieve required SNR, the signal
5 sampling at a given time instant is repeated several times, and the digitized signal is integrated using well known digital signal processing techniques.

The signal losses in the radar systems may be caused by several reasons. For example, according to the scattering theory of waves, the power of a received signal is attenuated by 12 dB for each doubling of a target range (this stems from the fact that the
10 received power is inversely proportional to the 4th power of the target range). Additionally, the scene to be imaged can be located behind some obstacles (e.g. walls or underground environment) that may introduce additional loss which can reach 30 dB and even higher. The magnitude of scattering for different targets can also vary, and typical imaging system should take a range of 20 dB and even higher for expected
15 variations of targets radar cross-section (RCS). Therefore UWB radar systems require a high dynamic range of the signal acquisition system, which particularly should be handled by an analog/digital converter (ADC). For example, the dynamic range in a signal acquisition system designed to work with a target range from 1m to 8m shall be about 86 dB, and in a system designed to work with a target range from 1m to 32m the
20 dynamic range shall be about 110 dB, etc.

In cases when real-time performance is crucial (e.g. real-time radar imaging systems, critical radar systems, etc.), the signal acquisition period is bound by the required imaging frame rate or detection responsiveness, and the signal acquisition must be completed within the imaging frame duration. It means that within a frame period,
25 the number of transmission/reception cycles required for integration must not exceed the total number of transmitted pulses within the frame duration (hereinafter referred as the maximal integration number) defined by the transmission pulse repetition frequency (PRF), and the number of transmitters (N). In many cases this maximal integration number is not enough to achieve a required SNR.

30 A possible way to cope with this constraint is to perform a parallel sampling, when at each receive cycle the received signal is sampled on $L > 1$ different instants. Such an approach will shorten the total signal acquisition time by a factor L . The price paid for this parallelism is a need for very fast ADC samplers (one per each receive

- 7 -

channel), which also have to be very accurate (having enough bits) in order to fit the required dynamic range, and very fast digital electronics designed to pump the samples from the plurality of ADCs. Such samplers and digital electronics, turn out to be expensive and high power consumers.

5 The present invention, in some of its aspects, is aimed to decrease the requirement for dynamic range and rate of the ADC and other digital electronics.

Note that the invention is not bound by the specific UWB radar structure described with reference to **Fig. 1**. Those versed in the art will readily appreciate that the invention is, likewise, applicable to any other UWB radar. Also it should be noted
10 that the functionality of the plurality of physical transmitters and receivers may be also provided by synthetic aperture radar techniques.

Bearing this in mind, attention is drawn to **Fig.2**, illustrating generalized diagram of the signal acquisition system **14**. In accordance with certain embodiments of the present invention the signal acquisition system includes a UWB sampler block **21**
15 coupled to an analog integration block **22** further coupled to a digital integration block **24** via an analog/digital converter (ADC) **23**. The sampler block, the analog integration block, the ADC and the digital integration block may constitute an acquisition channel **20**. Typically, each receiver is provided with a separate acquisition channel.

If a target is static or moving considerably slowly (compared to the shortest
20 transmitted wavelength during a frame interval), we can assume that the received signal $r(t)$ is a periodic one, with a period T equal to $1/PRF$, where PRF is the transmission pulse repetition frequency. For each range cell the sampler block **21** repeatedly samples the received signal $r(t)$ by tuning the sampling instants to the range cells to be acquired. As illustrated in **Fig. 2**, the n^{th} sampling phase corresponds to a target range of $n\Delta Tc/2$
25 (where c is the speed of light in vacuum, ΔT is the sampling time interval; T_0 in the figure corresponds to the time of transmission of short (UWB) pulse by selected transmitter in the current transmit/receive cycle. The factor of 2 is due to the round trip of the scattered wave). The sampled signal is fed into the analog integration block, which shall be reset before the beginning of acquisition of each range cell. The
30 sampling and analog integration process is repeated for desired number of cycles as will be detailed below.

The output signal from the analog integration block is converted into a digital sample by the analog/digital converter **23**. The stream of digital samples S_n ,

- 8 -

corresponding to the integrated signal received at a correspondent n^{th} range cell is transferred to the digital integration block **24**. This block provides further signal integration, by means of discrete time signal processing.

In accordance with certain embodiments of the present invention, the analog
5 integration block is configured to provide integration enabling compensation of at least part of the signal losses, while the digital integration block is configured to provide the rest of the desired compensation. In certain embodiments of the invention the analog integration block is configured to substantially compensate the nominal free space propagation path loss and the digital integration block is configured to compensate, for
10 example, obstacle-originated losses, RCS variations, etc. In certain embodiments of the invention at least some of obstacle-originated losses and/or expected RCS variations may be compensated by the analog integration block. In certain embodiments of the present invention the analog integration block may compensate only a part of propagation path losses, wherein the rest of desired compensation of signal losses may
15 be compensated by the digital integration block.

In accordance with certain aspects of the present invention, the integration is provided with variable number of integration cycles in accordance with range (reception time) and desired SNR profile (desired values of SNR for different range cells for a given radar cross section) or signal loss compensation. For example, to achieve the
20 range-independent SNR profile for a predefined target RCS, the near range cells will be integrated with smaller number of integration cycles compared to far ones. For yet another example, to maximize SNR for a sub-range of a special interest under constraints of limited overall integration time, the number of integration cycles for corresponding range cells may be increased on account of integration of other range
25 cells.

The term "integration plan" used in this patent specification, should be expansively construed to cover any kind of pre-defined relationship between a number of integration cycles and a range/reception time (range cell index). The integration plan may be configured, for example, to desired SNR profile and/or to desired compensation
30 of signal losses.

In certain embodiments of the present invention, the acquisition system **14** may comprise a database **25** and processor **26** operatively coupled with the digital integration block **24** and/or the analog integration block **22**. Those skilled in the art will readily

- 9 -

appreciate that functionality of the database and the processor or parts thereof may be integrated with one or more other blocks of the signal acquisition system (e.g. with the digital integration block). The database may comprise, for example, pre-calculated integration plan(s) (e.g. for range-independent SNR profile, for maximized SNR per a selectable sub-range, etc.). The numbers of integration cycles may be calculated as detailed below based on known dependency between the nominal propagation path loss and the target range/reception time. In certain embodiments of the present invention the database may further comprise pre-calculated numbers of integrated cycles required for desired compensation of other types of signal losses, for example, caused by pre-defined obstacle. The obstacles may be predefined in accordance with the nature of the obstacle and/or expected loss. In certain embodiments of the present invention the processor may be configured to facilitate calculating the required numbers of integration cycles. The calculation may be also provided with the help of adaptive and/or learning algorithms, and the processor, accordingly, will comprise external interface 27 for obtaining data, for example, from image reconstruction system, from a user, etc. These adaptive/learning algorithms may complement the pre-calculated integration plan(s), e.g. by enabling compensation of propagation path loss in real conditions (e.g. for airborne radars) or replace (partly or fully) the pre-calculated integration plan(s) by providing on-demand and/or on-line calculations of the required integration.

The number of integration cycles N required to increase SNR from some initial value SNR_0 to a target value SNR_t is given by the following equation (SNRs are assumed to be given in dB):

$$N = 10^{(SNR_t - SNR_0)/10} \quad (1)$$

According to a well known radar equation [see for example "Electromagnetic Wave propagation, Radiation, and Scattering", by A. Ishimaru, Prentice Hall], for a given target with a fixed RCS, the SNR of a received echo signal depends on reception time t as follows:

$$SNR(t) = SNR(t_0) - 40 * \log_{10}(t/t_0) \text{ [dB]} \quad (2)$$

where $SNR(t_0)$ is the SNR at the starting receive time t_0 .

These two equations facilitate calculation of an integration plan in accordance with required SNR as a function of receiving range (SNR profile). For example, the

- 10 -

integration plan for range-independent SNR_t profile (for a target with a fixed RCS) is defined as:

$$N(t) = \left(\frac{t}{t_0} \right)^4 10^{[SNR_t - SNR(t_0)]/10} \equiv N_0 \left(\frac{t}{t_0} \right)^4 \quad (3)$$

where $N(t)$ is the number of required integration cycles for different range cells (reception time) and N_0 is the number of integration cycles for $t = t_0$, given by:

$$N_0 = 10^{[SNR_t - SNR(t_0)]/10}.$$

This integration plan enables compensation of the free space nominal propagation path losses and facilitates range-independent SNR profile. In accordance with certain embodiments of the present invention the above integration plan is predefined and stored in a database comprised in the signal acquisition system. It has to be noted that an integration plan should be designed for each transmitter/receiver couple. In many cases, when the antenna array aperture is smaller compared to the range under consideration, the integration plan can be the same for all receivers.

By way of non-limiting example, the advantages of some aspects of the present invention will be illustrated in case of integration plan with range-independent SNR profile. It should be noted that the invention is not bound by this illustrated case and the following calculations may be done in a similar manner for any other integration plan.

As follows from **Eq. 3**, the gains for the signal and the noise may be described as the following function of reception time (or range):

$$\begin{aligned} G_{signal}(t) &= N_0 \left(\frac{t}{t_0} \right)^4 \\ G_{noise}(t) &= \sqrt{N_0} \left(\frac{t}{t_0} \right)^2 \end{aligned} \quad (4)$$

Accordingly, since the received signal amplitude v (for a given RCS without noise) is proportional to $v(t) \propto v_0 \left(\frac{t_0}{t} \right)^2$ (the receive power is inversely proportional to t^4 thus the amplitude is inverse proportional to t^2), the signal amplitude v_{is} , and RMS noise amplitudes v_{iN} at the output of an integrator operated according to the integration plane of **Eq. 3**, are expected to, respectively, be:

- 11 -

$$v_{i_s}(t) = v_0 N_0 \left(\frac{t}{t_0} \right)^2$$

$$v_{i_N}(t) = v_{N_{rms}} \sqrt{N_0} \left(\frac{t}{t_0} \right)^2 \quad (5)$$

5 where $v_{N_{rms}}$ is the additive white noise RMS amplitude.

From **Eq. 5** it can be seen that constant SNR was achieved, and the integrated signal (and noise) level turns out to be increasing with range. Being implemented with the analog integrator only, this integration plan requires a large number of bits in order to cope with the extended signal dynamic range in the ADC input. As was illustrated
 10 with reference to **Fig.1**, a similar problem arises when implementing the integration plan using digital integrator only. In view of that, in accordance with certain aspects of the present invention, it is proposed to split the integration process into two parts: an analog integration followed by a digital integration. Such approach facilitates an additional degree of freedom, as the integration plan may be designed for two separate
 15 integrators according to different criteria, e.g. to minimize signal dynamic range at the input of the ADC (thus enabling selection of cheap components), to get adequate SNR at the output of the digital integrator, etc.

In accordance with certain embodiments of the present invention, the overall number of integration cycles $N(t)$ is split into $N_a(t)$ analog integration cycles and $N_d(t)$
 20 digital integration cycles, wherein $N_a(t) \times N_d(t) = N(t)$. For a case when $N_a(t) = N_d(t) = \sqrt{N(t)}$, the amplitude of received signal at the output of the analog integration block is given by: $v_{i_s}(t) = v_0 \sqrt{N_0}$. It can be seen that, according to the proposed integration plan, the signal received from a target with a given RCS becomes range independent after the analog integration. Thus, the free space path loss
 25 was compensated, and the expected signal dynamic range at the input of the ADC port is minimized. For example, the ADC dynamic range requirements have been seriously reduced from 86-110 dB described with reference to **Fig. 1** to less than, in some environments, 50 dB, where e.g. 30 dB is contributed by obstacle-caused loss variations, and 20 dB is by diversity of targets RCS.

- 12 -

As will be further detailed with reference to **Fig. 3**, in accordance with certain embodiments of the present invention, the analog to digital conversion of the analog integrator output may be done once for each period of analog integration. Thus, the required rate of ADC conversions may be considerably reduced for integration plans
 5 with the number of analog integrations strictly greater than 1. Therefore certain aspects of the present invention facilitate using relatively low-cost slow ADC. As the signal acquisition power consumption is proportional to the ADC conversion rate, it can also be reduced in accordance with certain embodiments of the present invention.

Those skilled in the art will readily appreciate that the invention is not bound by
 10 the configuration described in reference of **Fig. 2**; equivalent and/or modified functionality may be consolidated or divided in another manner.

The integration plan may be calculated and implemented in several manners; some of them are detailed below by way of non-limiting example.

1) Off-line nominal integration plan calculation based on *a priori* known
 15 information about fixed losses and/or noise sources expected to be present during system operation. This information is taken into account during the system design phase or its preparation for usage. The *a priori* information is generally given by the following:

$$SNR(t) = F_1(t)$$

$$P(t) = F_2(t) \tag{6}$$

$$FR$$

20 where $SNR(t)$ is the expected SNR vs. reception time (or range) given by the *a priori* known function $F_1(t)$, $P(t)$ is the expected receive power at reception time t (corresponding to a target of a given RCS located at range $ct/2$) given by the *a priori* function $F_2(t)$, and FR is the required imaging frame rate. Both $F_1(t)$ and $F_2(t)$ can be supplied using a mathematical representation (e.g. as in the example shown in **Eq. 2**)
 25 or as a table. In general, $F_1(t)$ depends on $F_2(t)$, since the received signal SNR depends on the received power and the receiver front-end additive noise profile - $F_1(t) = F_2(t) / P_{noise}(t)$, where $P_{noise}(t)$ is the additive noise power profile (in a typical situation the noise stems from thermal sources at the receiver front-end, and thus its

- 13 -

profile $P_{noise}(t) = const$). Additional information may be required for calculating the integration plan as follows:

- The SNR profile goal, $SNR_i(t)$: the required integrated signal SNR vs. reception time (or range) is given;
- 5 - The admissible maximum ADC input voltage (the power above which the ADC saturates) - $V_{max}(ADC)$;
- A_{FE} - front end gain (between antenna and ADC with no integration);
- Z_0 - front end characteristic impedance;
- PRF: the system transmission pulse repetition rate.

10 Using these equations the integration plan may be calculated according to the following equations:

$$N_a(t) \leq \frac{V_{max}(ADC)}{A_{FE} \sqrt{Z_0 P(t)}} \quad (7)$$

$$N_d(t) = \frac{N(t)}{N_a(t)} \quad (8),$$

where $N(t)$ is the total integration plan given, according to the required
15 integrated signal SNR profile, by:

$$N(t) = 10^{[SNR_i(t) - F_1(t)]} \quad (9)$$

subject to the constraint:

$$\sum_t N(t) \leq PRF / FR \quad (10)$$

This constraint ensures that the total number of cycles used to acquire the signal
20 does not exceed the number of transmitted pulses in frame duration. In cases when this constraint is not satisfied, either the system PRF may be increased or the imaging frame rate may be decreased.

In accordance with certain aspects of the present invention, this integration plan may provide more efficient utilization of the ADC bits, and produce an integrated
25 signal with the desired SNR profile ($SNR_i(t)$). It should be noted that due to the fact that $N_a(t)$ and $N_d(t)$ are integers, in cases when their calculation yield non-integer values, the result should be rounded to the closest integer, subject to $N_a(t), N_d(t) \geq 1$ (at least one cycle of integration for each range cell).

- 14 -

2) On-line setting of the integration plan by a user via a user interface enabling a user to set the integration plan ($N_a(t)$ and $N_d(t)$). For example, during the system operation, the user can recognize a sub-range with poor imaging or detection performance. The user may enhance the system performance at this sub-range by
 5 changing the integration plan in a manner providing more transmission cycles to be used for integrating the received signal at this sub-range.

3) On-line automatic adaptive integration plan including special purpose algorithms, capable of adapting the integration plan to a predefined goal (e.g. by means of feedback from the integrated received signals and/or reconstructed images). For
 10 example, during the system operation, the processor/database may collect statistics about integrated signal received power vs. range. A possible outcome of these statistics might be, e.g., an abrupt decrease at some range (corresponding to reception time denoted by t') in the mean received power; this change might be related to an existence of an obstacle at the corresponding range. In order to better utilize the ADC bits, the
 15 processor may use these algorithms to increase $N_a(t)$ for $t > t'$ such that the observed discontinuity will vanish. Also here $N_a(t)$ and $N_d(t)$ are related through **Eq. 8** and the constraint given in **Eq. 10** has to be fulfilled.

Attention now is drawn to **Fig. 3** illustrating, by way of non-limiting example, generalized diagram of operation of the signal acquisition system in accordance with
 20 certain embodiments of the present invention.

A signal for each transmitter (**TX1**, **TX2**, etc.) is captured sequentially during a frame **31** in a manner enabling, for each transmitter, acquiring the received signals **32** for the entire range. Per each transmitter the different simultaneously sampled range cells (t_0 , t_1 , etc.) are integrated for all receivers (**RX1**, **RX2**, etc.), wherein for each
 25 range cell a number of N_d digital integrations is performed on N_a times analogically integrated samples. Prior to each analog integration section, the analog integrators (typically one per receiver) are reset. In **Fig.3**, $r_{1,M}(t_3)$ and $r_{1,M}(t_i)$ stand for the integrated received sample corresponding to the received signal at receiver M at, accordingly, time t_3 and t_i as a result of transmission from the transmitter **TX1**. In
 30 accordance with the integration plan illustrated in the **Fig.3** by way of non-limiting

- 15 -

example, the number of integration cycles (N_d, N_a , etc.) differs for different range cells.

It should be noted that other signal acquisition schemes are possible. For example, the frame might be captured sequentially, range cell after range cell (in an increasing order), such that each range cell runs sequentially over all transmitters.

It will also be understood that the system according to the invention, may be a suitably programmed computer. Likewise, the invention contemplates a computer program being readable by a computer for executing the method of the invention. The invention further contemplates a machine-readable memory tangibly embodying a program of instructions executable by the machine for executing the method of the invention.

It is also to be understood that the invention is not limited in its application to the details set forth in the description contained herein or illustrated in the drawings. The invention is capable of other embodiments and of being practiced and carried out in various ways. Hence, it is to be understood that the phraseology and terminology employed herein are for the purpose of description and should not be regarded as limiting. As such, those skilled in the art will appreciate that the conception, upon which this disclosure is based, may readily be utilized as a basis for designing other structures, methods, and systems for carrying out the several purposes of the present invention.

Those skilled in the art will readily appreciate that various modifications and changes can be applied to the embodiments of the invention as hereinbefore described without departing from its scope, defined in and by the appended claims.

- 16 -

CLAIMS:

1. For use in a radar, a signal acquisition system capable of integrating at least one received signal whereby compensating a signal loss; the system comprising:
 - (a) at least one sampler configured to sample the received signal and to provide samples of different range cells;
 - (b) at least one analog integrator coupled to the sampler and configured to integrate said samples whereby compensating at least part of the signal loss and giving rise to analog samples;
 - (c) at least one analog/digital converter coupled to the analog integrator and configured to convert said analog samples into digital samples;
 - (d) at least one digital integrator coupled to the analog/digital converter and configured to integrate said digital samples.
2. The system of Claim 1 wherein the radar is ultra-wideband radar.
3. The system of Claim 1 wherein the compensation of the signal loss is provided for improving a signal to noise ratio (SNR).
4. The system of Claim 1, wherein the signal loss is caused by at least one of the following: a free space propagation path loss depending on the range, an obstacles-originated loss and a loss caused by variations of radar cross section.
5. The system of Claim 4 wherein the analog integrator is configured to compensate at least part of the free space propagation path loss.
6. The system of Claim 4 wherein the analog integrator is configured to substantially compensate the nominal free space propagation path loss.
7. The system of Claim 4 wherein the analog integrator is configured to compensate at least part of the obstacle-originated loss.
8. The system of Claim 4 wherein the analog integrator is configured to compensate at least part of the loss caused by variations of radar cross section.
9. The system of Claim 1 wherein the digital integrator is configured to substantially provide the rest of desired signal loss compensation.
10. The system of Claim 1 wherein, for samples of at least one range cell, the analog integrator is configured to provide N_a analog integration cycles, the digital integrator is configured to provide N_d digital integration cycles and overall number N of integration cycles for said samples substantially complies with the equation $N = N_a \times N_d$.

- 17 -

11. The system of Claim 10 wherein said overall number of integration cycles varies for samples of different range cells.

12. The system of Claim 11 wherein, for samples of each range cell, the overall number of integration cycles $N(t)$ for different range cells substantially complies with
 5 the equation $N(t) = N_a(t) \times N_d(t)$, where $N_a(t)$ and $N_d(t)$ are numbers of, respectively, analog and digital integration cycles for different range cells.

13. The system of Claim 12 wherein the number $N(t)$ of integration cycles for different range cells substantially complies with the following equation:

$$N(t) = \left(\frac{t}{t_0} \right)^4 10^{[SNR_t - SNR(t_0)]/10} \equiv N_0 \left(\frac{t}{t_0} \right)^4$$

10 where t_0 is a starting receive time, and N_0 is the number of integration cycles for $t = t_0$, given by: $N_0 = 10^{[SNR_t - SNR(t_0)]/10}$.

14. The system of Claim 12 wherein said number of integration cycles is configured in accordance with desired SNR profile.

15 15. The system of Claim 14 wherein the desired SNR is substantially equal for all range cells for a given target radar cross section.

16. The system of Claim 12 wherein a number of integration cycles for samples of given range cells is less than a number of integration cycles for samples of more distant range cells.

17. The system of Claim 14 wherein the desired SNR profile is maximized for
 20 desired sub-range.

18. The system of Claim 17 wherein the desired sub-range is predefined.

19. The system of Claim 12 wherein said number of integration cycles is configured in accordance with a frame rate of the radar.

20. The system of Claim 1 wherein the analog integrator is configured to provide
 25 integration with a number of integration cycles variable for samples of different range cells.

21. The system of Claim 20 wherein said number of integration cycles is configured in accordance with a dynamic range of the analog/digital converter.

22. The system of Claim 20 wherein said number of integration cycles is
 30 configured in accordance with conversion rate of the analog/digital converter.

- 18 -

23. The system of Claim 11 comprising a database storing data related to a pre-defined relationship between numbers of integration cycles and different range cells.

24. The system of Claim 23, wherein said relationship is adapted to desired SNR profile.

5 25. The system of Claim 11 comprising a processor configured to execute at least one algorithm for adapting the number of integration cycles for samples from different range cells in accordance with a desired SNR profile.

26. The system of Claim 11 comprising a processor configured to execute at least one learning algorithm facilitating configuration of the number of integration cycles for
10 samples of different range cells in accordance with a desired SNR profile.

27. For use in a radar, a method of signal acquisition with integrating at least one received signal whereby compensating a signal loss; the method comprising:

- (a) sampling the received signal giving rise to samples of different range cells;
- (b) analog integrating of said samples whereby compensating at least part of the
15 signal loss and giving rise to analog samples;
- (c) analog/digital converting said analog samples into digital samples;
- (d) digital integrating said digital samples.

28. The method of Claim 27 wherein the radar is ultra-wideband radar.

29. The method of Claim 27 wherein the compensation of the signal loss is
20 provided for improving a signal to noise ratio (SNR).

30. The method of Claim 27, wherein the signal loss is caused by at least one of the following: a free space propagation path loss depending on the range, an obstacles-originated loss and a loss caused by variations of radar cross section.

31. The method of Claim 30 wherein the analog integrating enables to compensate
25 at least part of the free space propagation path loss.

32. The method of Claim 30 wherein the analog integrating enables to substantially compensate the nominal free space propagation path loss.

33. The method of Claim 30 wherein the analog integrating enables to compensate at least part of the obstacle-originated loss.

30 34. The method of Claim 30 wherein the analog integrating enables to compensate at least part of the loss caused by variations of radar cross section.

35. The method of Claim 27 wherein the digital integrating enables to substantially provide the rest of desired signal loss compensation.

- 19 -

36. The method of Claim 27 wherein, for samples of at least one range cell, the analog integrating comprises N_a analog integration cycles, the digital integrating comprises N_d digital integration cycles and overall number N of integration cycles for said samples substantially complies with the equation $N = N_a \times N_d$.

5 37. The method of Claim 36 wherein said overall number of integration cycles varies for samples of different range cells.

38. The method of Claim 37 wherein, for samples of each range cell, the overall number of integration cycles $N(t)$ for different range cells substantially complies with the equation $N(t) = N_a(t) \times N_d(t)$, where $N_a(t)$ and $N_d(t)$ are numbers of, respectively,
10 analog and digital integration cycles for different range cells.

39. The method of Claim 38 wherein the number $N(t)$ of integration cycles for different range cells substantially complies with the following equation:

$$N(t) = \left(\frac{t}{t_0} \right)^4 10^{[SNR_t - SNR(t_0)]/10} \equiv N_0 \left(\frac{t}{t_0} \right)^4$$

where t_0 is a starting receive time, and N_0 is the number of integration cycles for $t = t_0$,
15 given by: $N_0 = 10^{[SNR_t - SNR(t_0)]/10}$.

40. The method of Claim 38 wherein said number of integration cycles is configured in accordance with desired SNR profile.

41. The method of Claim 40 wherein the desired SNR is substantially equal for all the ranges within radar cross section.

20 42. The method of Claim 38 wherein a number of integration cycles for samples of given range cells is less than a number of integration cycles for samples of more distant range cells.

43. The method of Claim 40 wherein the desired SNR profile is maximized for desired sub-range.

25 44. The method of Claim 43 wherein the desired sub-range is predefined.

45. The method of Claim 40 wherein said number of integration cycles is configured in accordance with a frame rate of the radar.

46. The method of Claim 27 wherein the analog integrating is provided with a number of integration cycles variable for samples of different range cells.

30 47. The method of Claim 46 wherein said number of integration cycles is configured in accordance with a dynamic range of the analog/digital converter.

- 20 -

48. The method of Claim 46 wherein said number of integration cycles is configured in accordance with conversion rate of the analog/digital converter.

49. The method of Claim 37 wherein a relationship between numbers of integration cycles and different range cells is pre-defined.

5 50. The method of Claim 49, wherein said relationship is adapted to desired SNR profile.

51. The method of Claim 37 comprising adapting the number of integration cycles for samples from different range cells in accordance with desired SNR profile with the help of an adapting algorithm.

10 52. The method of Claim 37 comprising configuring the number of integration cycles for samples of different range cells in accordance with desired SNR profile with the help of a learning algorithm.

53. For use in a radar, a program storage device readable by machine, tangibly embodying a program of instructions executable by the machine to perform method
15 steps for signal acquisition with integrating at least one received signal whereby compensating a signal loss; the method comprising:

- (a) sampling the received signal giving rise to samples of different range cells;
- (b) analog integrating of said samples whereby compensating at least part of the signal loss and giving rise to analog samples;
- 20 (c) analog/digital converting said analog samples into digital samples;
- (d) digital integrating said digital samples.

54. For use in a radar, a computer program product comprising a computer useable medium having computer readable program code embodied therein for signal acquisition with integrating at least one received signal whereby compensating a signal
25 loss; the computer program product comprising:

- (a) computer readable program code for causing the computer to sample the received signal giving rise to samples of different range cells;
- (b) computer readable program code for causing the computer to analog integrating of said samples whereby compensating at least part of the signal
30 loss and giving rise to analog samples;
- (c) computer readable program code for causing the computer to analog/digital converting said analog samples into digital samples;

- 21 -

- (d) computer readable program code for causing the computer to digital integrating said digital samples.

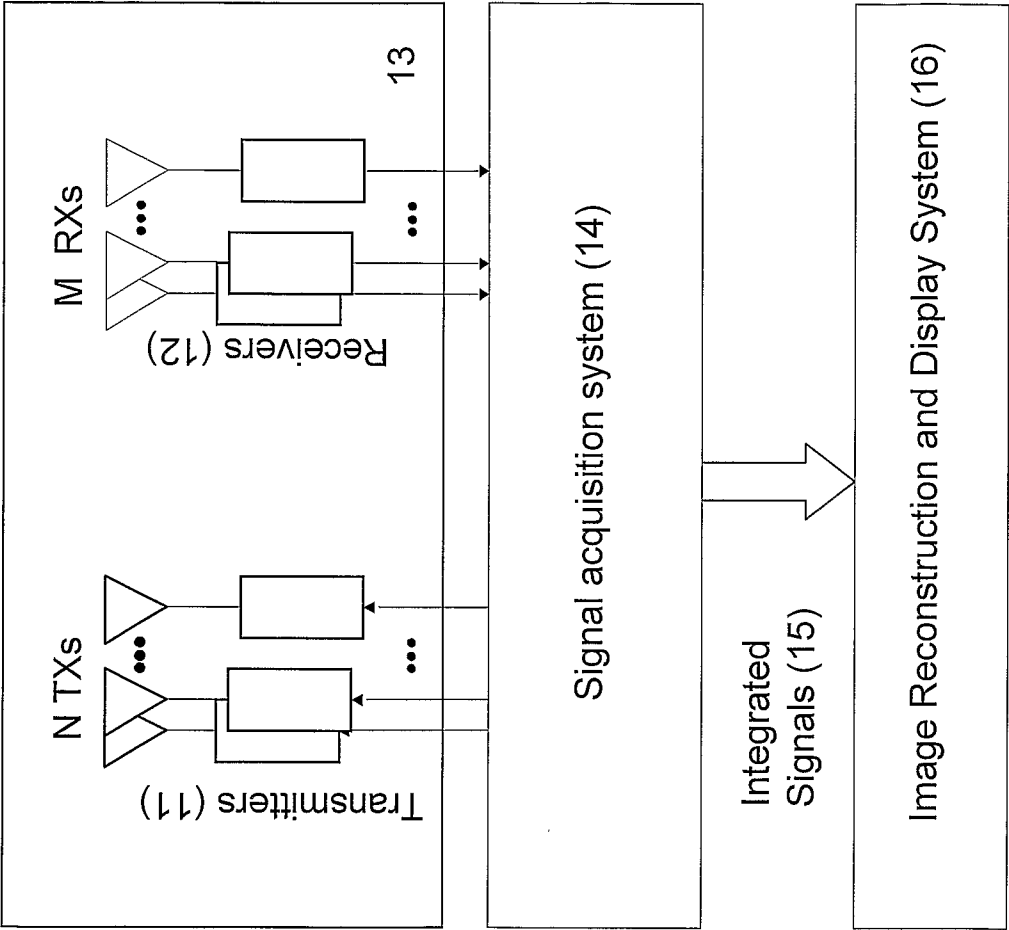


Figure 1

Prior Art

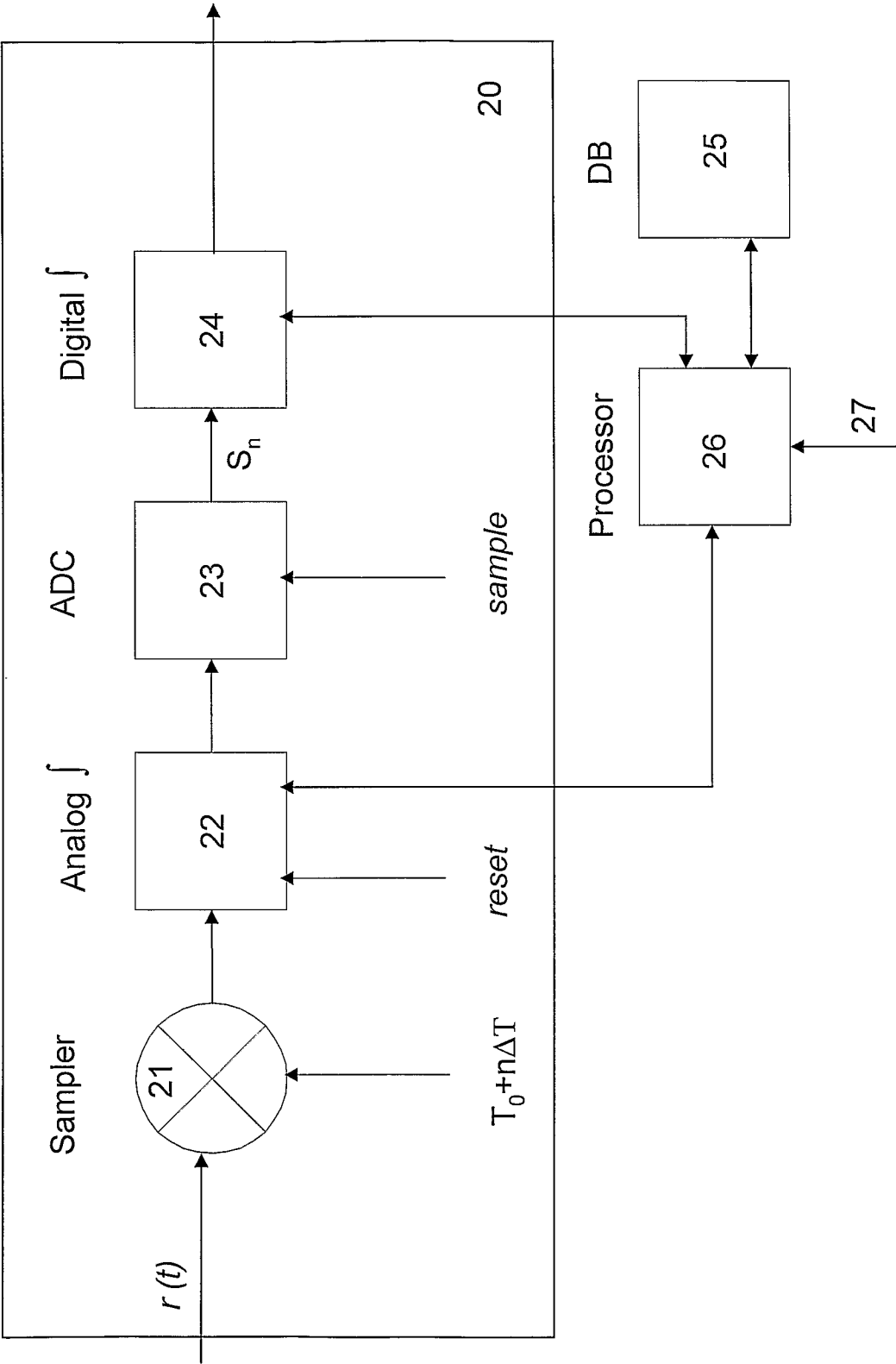


Figure 2

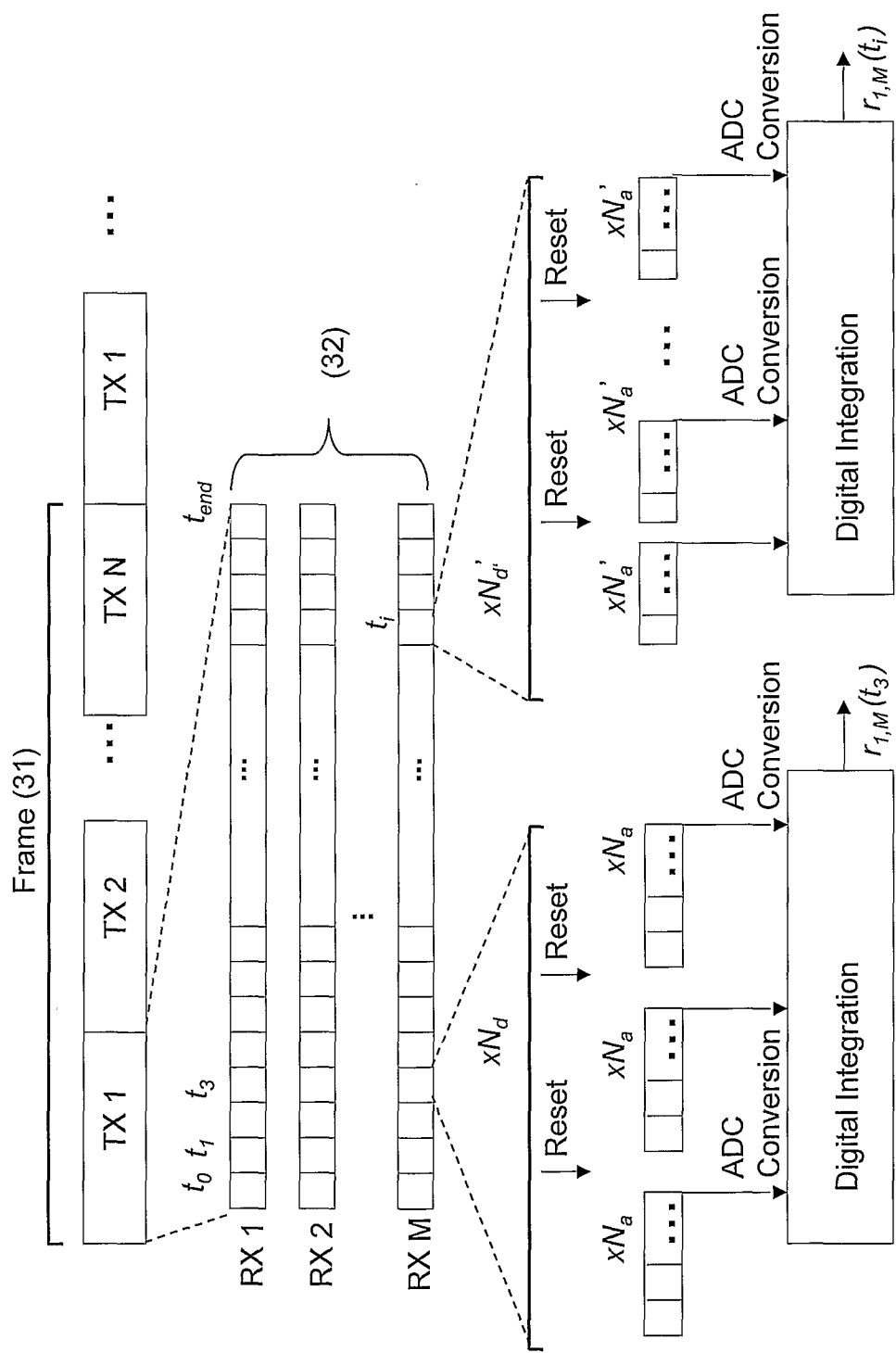


Figure 3

INTERNATIONAL SEARCH REPORT

International application No.

PCT/IL06/00703

A. CLASSIFICATION OF SUBJECT MATTER

IPC: **G01S 7/00**(2007.01)
G01S 13/00(2007.01)

USPC: 342/21,22,89

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

U.S. : 342/21, 22, 89, 90-103, 135, 147, 168, 171, 175, 191-197, 203; 375/242, 244, 247; 331/78; 327/73; 708/1, 3, 6, 200, 444

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	US 3,422,435 A (CRAGON et al) 14 January 1969 (14.01.1969), column 1, lines 1-27.	1-54
A	US 3,683,380 A (CANTWELL, JR. et al) 08 August 1972 (08.08.1972), see abstract.	1-54
A	US 3,868,685 A (WILMOT) 25 February 1975 (25.02.1975), see abstract.	1-54
A	US 3,927,405 A (POINSARD et al) 16 December 1975 (16.12.1975), see abstract.	1-54
A	US 4,145,743 A (DICIURCIO) 20 March 1979 (20.03.1979), see abstract.	1-54
A	US 4,301,446 A (PETIT) 17 November 1981 (17.11.1981), see abstract.	1-54
A	US 4,672,361 A (KOKUBO et al) 09 June 1987 (09.06.1987), see abstract.	1-54



Further documents are listed in the continuation of Box C.



See patent family annex.

* Special categories of cited documents:		
"A"	document defining the general state of the art which is not considered to be of particular relevance	"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention
"E"	earlier application or patent published on or after the international filing date	"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone
"L"	document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)	"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art
"O"	document referring to an oral disclosure, use, exhibition or other means	
"P"	document published prior to the international filing date but later than the priority date claimed	"&" document member of the same patent family

Date of the actual completion of the international search
20 November 2006 (20.11.2006)

Date of mailing of the international search report

11 JAN 2007

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INTERNATIONAL SEARCH REPORTInternational application No.
PCT/IL06/00703**C. (Continuation) DOCUMENTS CONSIDERED TO BE RELEVANT**

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	US 4,818,955 A (HWANG) 04 April 1989 (.04.04.1989), see abstract.	1-54
A	US 4,996,529 A (CONNELL) 26 February 1991 (26.02.1991), see abstract.	1-54
A	US 6,404,368 B1 (YAMAGUCHI) 11 June 2002 (11.06.2002), see abstract.	1-54
A	US 6,424,279 B1 (KIM et al) 23 July 2002 (23.07.2002), see abstract.	1-54