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(12) **United States Design Patent**
Wakisaka et al.

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(54) **CONTROLLER FOR FORCEPS FOR MEDICAL ROBOT**

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(**) Term: **14 Years**

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(51) **LOC (8) Cl.** **13-03**

(52) **U.S. Cl.** **D13/168**

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D10/104, 106; D14/218, 247, 409, 417; 340/825.22,
340/825.24, 825.25, 825.31, 825.36, 825.69,
340/825.71, 825.72; 341/20, 22, 23, 34, 173,
341/174, 176; 345/156, 168, 169; 348/734;
455/92, 95, 100, 128, 151.1-151.4, 325-355;
463/39; 700/17, 19, 20, 245, 247, 253; 606/130;
D24/143

See application file for complete search history.

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(57) **CLAIM**

The ornamental design for a controller for forceps for medical robot, as shown and described.

DESCRIPTION

FIG. 1 is a front, top and left side perspective view of a controller for forceps for medical robot, showing our new design;

FIG. 2 is a front, top and right side perspective view thereof; FIG. 3 is a front elevational view thereof; the opposite side being a mirror image thereof;

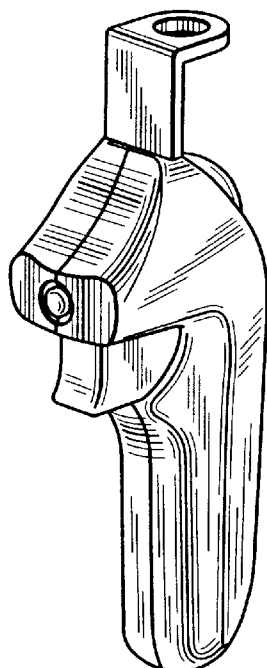
FIG. 4 is a top plan view thereof;

FIG. 5 is a bottom plan view thereof;

FIG. 6 is a left side elevational view thereof; and,

FIG. 7 is a right side elevational view thereof.

1 Claim, 3 Drawing Sheets



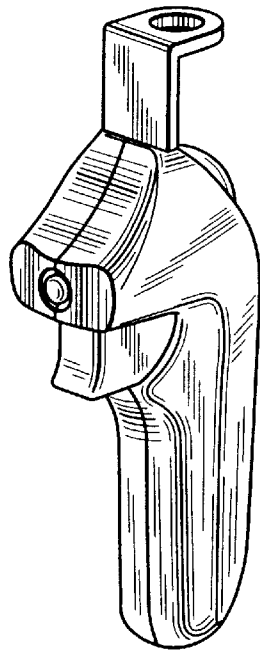


FIG. 1

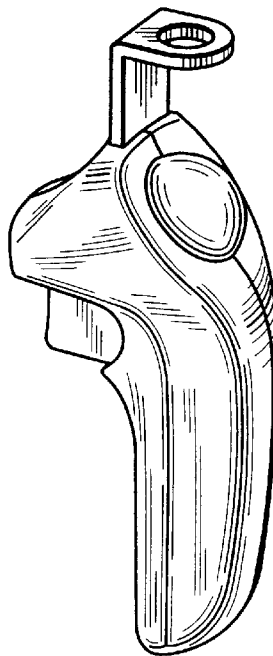


FIG. 2

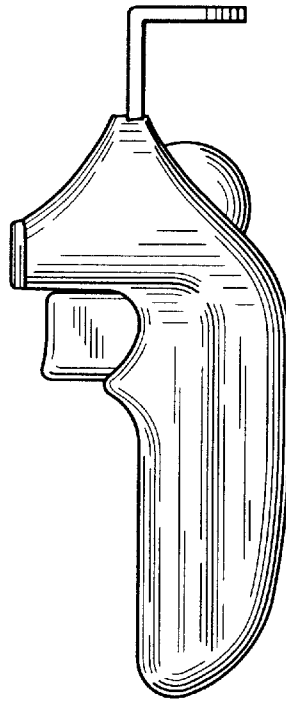


FIG. 3

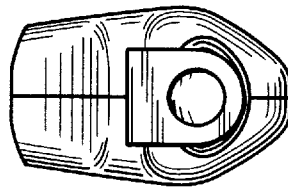


FIG. 4

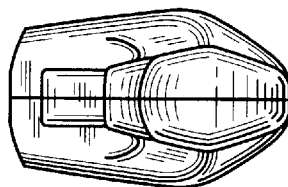


FIG. 5

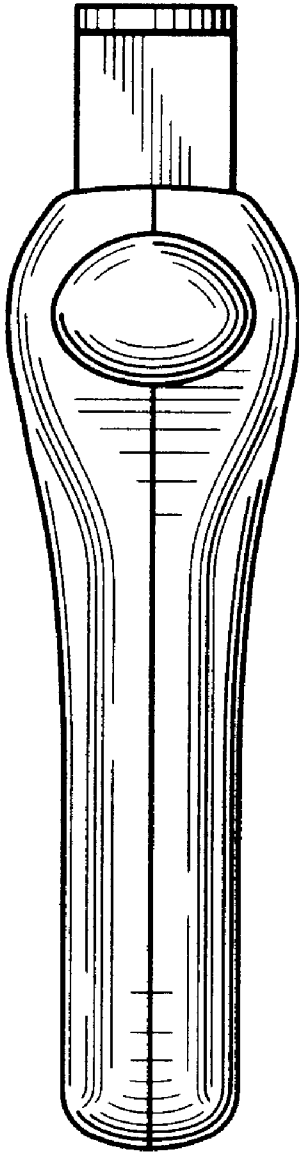


FIG. 7

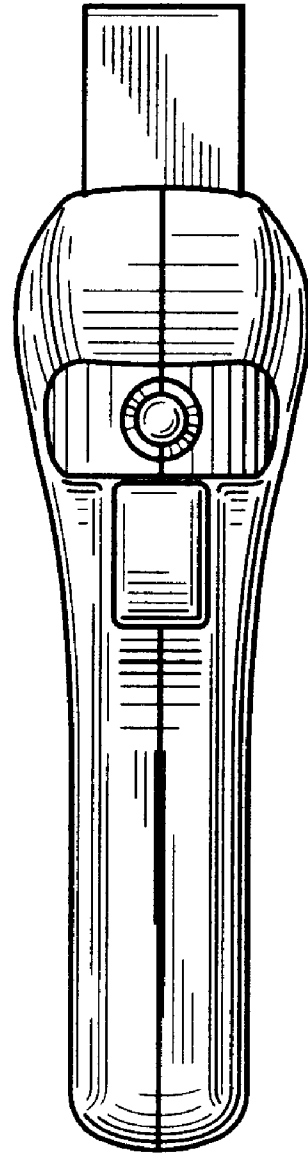


FIG. 6