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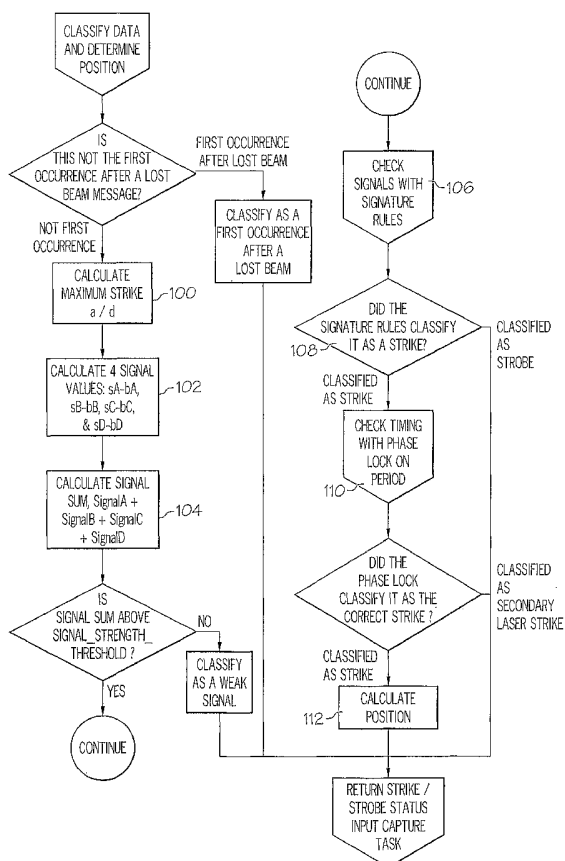
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[Continued on next page]

(54) Title: STROBE LIGHT AND LASER BEAM DETECTION FOR LASER RECEIVER



(57) Abstract: A device and method detect a moving, relatively thin beam of laser light, and distinguishing between illumination of photodetectors by the beam, and illumination of the photodetectors by an omnidirectional pulse of light. A plurality of photodetector arrays are arranged in a generally vertical row, with each array having a generally vertical row of photodetector elements. Weighting circuits associated with the arrays provide first and second reference signals for each array related to the elements illuminated in the array. The ratio of sum of the reference signals to the difference between the largest and smallest of the reference signals is determined and interpreted as indicating illumination by a relatively thin beam of laser light when the ratio is less than a predetermined level, and as indicating illumination by an omnidirectional pulse of light when the ratio is greater than the predetermined level.

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STROBE LIGHT AND LASER BEAM DETECTION
FOR LASER RECEIVER

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The present invention relates to equipment of the type used in surveying and construction and, more particularly, to a detector device for such applications which has an improved photodetector arrangement for detecting the position of reference light. The light may typically be a rotating laser beam that defines a reference plane of light or a
10 stationary reference plane or cone of laser light. The reference plane may be horizontal or inclined, as dictated by the application. Additionally, a transmitter projecting the reference light may also regularly project a strobe light in synchronization with rotation of the beam so that the beam defines a specific azimuth angle.

Laser systems have commonly been employed in surveying and construction in
15 which a laser beam is rotated in either a horizontal or a graded plane. U.S. Pat. No. 4,062,634, issued Dec. 13, 1977, to Rando, illustrates a laser transmitter which provides such a rotating reference beam. The rotating beam defines a plane, and various measurements can be made using the plane as a reference. For example, the elevation of a point remote from the laser transmitter may be measured using a rod on which a laser
20 receiver is mounted. The bottom of the rod rests on the ground at the point where the measurement is to be made, and the operator moves the receiver along the rod to a position where it intercepts the laser beam, as indicated by a display on the receiver. One such laser receiver is shown in U.S. Pat. No. 4,240,208, issued Jun. 30, 1987, to Pehrson.

Additionally, laser systems have provided an indication of the azimuth angle of the
25 laser beam relative to a reference direction (for example, true north) by transmitting a pulse of light, for example a strobe pulse, once during each rotation when the beam is directed in the reference direction. Such a system is shown, for example, in U.S. Pat. No. 6,643,004, issued Nov. 4, 2003, to Detweiler et al. Further, it is common for strobe lights to be used as warning lights at a construction site while machine control and surveying
30 operations are taking place.

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A laser receiver operating in such an environment must be able to distinguish between those times when the receiver is illuminated by the laser beam and those times when it is illuminated by a pulse of light from a strobe source. One way to distinguish between the two is to provide separate detector elements for the laser light and the strobe light, with optical filters to screen out all light except for light at the appropriate frequencies. This may not always be completely effective, however, and in addition to the unwanted interference, the optical filters may also attenuate light at the frequencies of interest, making such light harder to detect.

It is seen, therefore, that there is a need for a device and method for utilizing a plurality of photodetector arrays including a large number of photodetectors, and for accurately defining which one or ones of the photodetectors have been illuminated and by which light source the photodetectors have been illuminated by processing a number of output signals that have a continuously varying relationship.

This need is met by a method according to the present invention for detecting a moving, relatively thin beam of laser light, and distinguishing between illumination of photodetectors by such a moving, relatively thin beam of laser light, and illumination of photodetectors by an omnidirectional pulse of light. This method includes the steps of positioning a plurality of photodetector arrays in a generally vertical row, with each array including a plurality of photodetector elements arranged in a generally vertical array row. The photodetector elements in the arrays are collectively arranged in a generally vertically oriented, extended row. Each of said photodetector elements provides an electrical output when illuminated. For each array, a portion of the electrical output of each photodetector element in the array is provided as a first reference signal related to the spacing of the photodetector element from a first end of the array row, and as a second reference signal related to the spacing of the photodetector element from the second end of the array row. The sum of the first and second reference signals from said photodetector arrays is determined, as is the difference between the largest and smallest of the first and second reference signals from said photodetector arrays. The sum of the first and second reference signals from said photodetector arrays is divided by the difference between the largest and smallest of the first and second reference signals from said photodetector arrays and the smallest of the first and second reference signals from said photodetector

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arrays. The resulting quotient is then interpreted as indicating illumination of the photodetectors by a moving, relatively thin beam of laser light when the quotient is less than a predetermined level, and interpreting the quotient as indicating illumination of said photodetectors by an omnidirectional pulse of light when said quotient is greater than this
5 predetermined level. In the event that the quotient indicates illumination of said photodetectors by the moving, relatively thin beam of laser light, the position of the beam of laser light is determined with respect to the extended row based on the levels of the first and second reference signals from each of the arrays.

A device for detecting a moving, relatively thin beam of laser light, and
10 distinguishing between illumination of photodetectors by such a moving, relatively thin beam of laser light, and illumination of photodetectors by an omnidirectional pulse of light, includes a plurality of photodetector arrays arranged in a generally vertical row. Each array includes a plurality of photodetector elements arranged in a generally vertical array row, such that the photodetector elements in the arrays are arranged in a generally
15 vertically oriented, extended row. Each of the photodetector elements provides an electrical output when illuminated. A plurality of weighting circuits are provided, each weighting circuit associated with a respective one of the plurality of photodetector arrays. Each weighting circuit provides a portion of the electrical output of each photodetector element in the associated array as a first reference signal related to the spacing of the
20 photodetector element from a first end of the array row, and provides a portion of the electrical output of each photodetector element in the associated array as a second reference signal related to the spacing of the photodetector element from the second end of the array row. The weighting circuit associated with each array row is connected to the weighting circuits associated with adjacent array rows. Circuitry is associated with and
25 responsive to the reference signals from connected weighting circuits for determining the ratio of sum of the reference signals to the difference between the largest and smallest of the reference signals, and interpreting this ratio as indicating illumination of the photodetectors by a moving, relatively thin beam of laser light when the ratio is less than a predetermined level, and interpreting the ratio as indicating illumination of the
30 photodetectors by an omnidirectional pulse of light when the quotient is greater than the predetermined level.

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Accordingly, it is an object of the present invention to provide a device and method for detecting the relative position of reference light; to provide such a device and method in which a plurality of photodetector arrays are positioned such that the photodetector elements in all of the arrays are arranged in an extended row; and to provide such a device and method in which a plurality of weighting circuits are responsive to the arrays and a plurality of output circuits are responsive to the weighting circuits for determining the position of the reference light, and for determining whether the device is illuminated by a laser beam or by a strobe light pulse.

Other objects and advantages of the invention will be apparent from the following description, the accompanying drawings and the appended claims.

FIG. 1 is a schematic diagram of a portion of the circuitry which forms the device of the present invention;

FIG. 2 is a schematic diagram of a portion of the photodetector arrays and weighting circuits of the device of FIG. 1, showing four arrays of photodetectors connected to four concatenated weighting circuits;

FIG. 3 is a schematic diagram of a portion of the circuitry which forms the device of the present invention, showing m arrays connected to m concatenated weighting circuits; and

FIG. 4 is a flow chart illustrating the process by which the system of the present invention distinguishes between illumination by a pulse of strobe light and illumination by a relatively narrow beam of laser light.

Reference is made to FIG. 1, which generally illustrates a portion of a detection device 10 according to the present invention. The device detects reference light, such as laser light, and provides an indication of the location of the reference light with respect to the device. The device may also detect reference strobe pulses, as well. Reference light may, for example, be produced by laser transmitters as shown in U.S. Pat. No. 4,062,634, issued Dec. 13, 1977, to Rando et al, or in U.S. Pat. No. 4,732,471, issued Mar. 22, 1988, to Cain et al. Other light transmitters may also be used.

The detector device 10 includes a display 12, and a photodetector arrangement 14 including a plurality of photodetector arrays 15^1 , 15^2 , 15^3 , and 15^4 , shown in FIG. 2, arranged in a generally vertical row. Although for purposes of FIGS. 1 and 2 four

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photodetector arrays are shown, a greater or lesser number may be positioned in an extended row to permit light detection over a larger or lesser dimensional range. Each array includes a plurality of photodetector elements, CR1 through CR12, arranged in a generally vertical array row. The photodetector elements in these arrays 15¹, 15², 15³, and 15⁴, are collectively arranged in a generally vertically oriented, extended row. It will be appreciated that the terms "vertical" and "horizontal" are used here in only a relative sense, and are not intended to refer to any particular absolute orientation. The detector device may be operated with its extended row of photodetector elements in any orientation; it is preferable, however, that the row of photodetector elements be generally perpendicular to the reference plane of laser light which is to be detected. Each of the photodetector elements CR1-CR12 comprises a PIN diode that provides an electrical output when illuminated with the reference light. When the photodetector arrangement 14 is illuminated, output circuits 22 provide an indication on display 12 of the position of the reference plane of light with respect to the detector device 10. As an example, the display 12 may indicate whether the light is above, below, or within a reference band. Alternatively, the display 12 may provide more precise information regarding the position of the reference light, such as a numerical indication of position, or a multi-level display. Other display arrangements may be used or, alternatively, the device may be provided with no display, and with the output from the output circuits 22 being utilized by a machine control circuit to control machine position automatically.

The output circuits 22 are responsive to the relative levels of the first and second reference signals on lines 23 and 24, respectively, provided by the photodetector arrangement 14 for determining the position of the reference light. The output circuits 22 are also responsive to levels of reference signals on lines 25 and 26 from photodetectors in the other arrays.

The device further includes four weighting circuits 30¹, 30², 30³, and 30⁴, shown in FIG. 2. As discussed more fully below, weighting circuits 30¹, 30², 30³, and 30⁴ are associated with photodetector arrays 15¹, 15², 15³, and 15⁴, respectively. It will be appreciated that fewer photodetector arrays may be utilized if desired. The weighting circuit 30¹ includes resistors R1-R4 and R6-R13, inductors L1 and L2 (shunting D.C. sunlight current), and tapped transformer T1. Each of the plurality of photodetector

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elements CR1-CR12 is connected to the transformer T1, either directly or through one or more of the resistors. The weighting circuit 30¹ provides a portion of the electrical output of each photodetector element, when illuminated, as a component of a first reference signal on line 23, related to the spacing of the illuminated photodetector element from the upper end of the row of photodetectors in the array 15¹. The weighting circuit 30¹ also provides a portion of the electrical output of each photodetector element, when illuminated, as a component of a second reference signal on line 24, related to the spacing of the illuminated photodetector element from the lower end of the row of photodetectors in array 15¹. The weighting circuit 30¹ is configured such that the first reference signal on line 23 increases as the light moves toward the upper end of the row of PIN diodes, and the second reference signal on line 24 increases as the light moves toward the lower end of the row. Conversely, the first reference signal on line 23 decreases as the light moves toward the lower end of the row of PIN diodes CR1-CR12 in array 15¹, and the second reference signal on line 24 decreases as the light moves toward the upper end of the row. When the light is in the middle of the row, the levels of the two reference signals on lines 23 and 24 are equal. The output circuits 22 respond to the levels of the first and second reference signals on lines 23 and 24 to determine the position of the reference light. As discussed below, the output circuits 22 respond to the reference signals on lines 25 and 26 to determine the position of the reference light when photodetectors in other arrays are illuminated.

Each of the weighting circuits 30¹, 30², 30³, and 30⁴ is associated with a respective one of the plurality of photodetector arrays 15¹, 15², 15³, and 15⁴ and provides a portion of the electrical output of each illuminated photodetector element in its associated array as a first reference signal related to the spacing of the illuminated photodetector element from a first end of the array row, and provides a portion of the electrical output of each illuminated photodetector element in its associated array as a second reference signal related to the spacing of the illuminated photodetector element from the second end of the array row. The weighting circuit associated with each array row is connected to the weighting circuits associated with adjacent array rows.

The weighting circuit 30¹ provides reference current level signals on lines 23 and 24 in the following manner. Assume that only PIN diode CR3 is illuminated. The output

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current from diode CR3 will be supplied to node 32 of transformer T1. Approximately 5/6 of the current will pass through coil 34 to line 23, while 1/6 of the current will pass through coils 36, 38, 40, 42, and 44 to line 24. In similar fashion, assume that the reference light has moved such that only PIN diode CR9 is illuminated. The output
5 current from PIN diode CR9 will be supplied to node 46 of transformer T1. Approximately {fraction (4/6)} of the current from diode CR9 will pass through coils 42 and 44 to line 24, while {fraction (2/6)} of the current will pass through coils 34, 36, 38, and 40 to line 23. Thus the way in which the diode current is split and supplied to lines 23 and 24 gives an indication of which of the diodes are illuminated and, therefore, the
10 position of the reference light.

It will be noted that a number of the photodetector elements are not connected directly to a tap of the transformer T1. For example, diode CR2 has its output supplied to node 48. The current at node 48 is then split, with half passing through resistor R1 to line 23, and the other half passing through resistor R2 to node 32. At node 32, 5/6 of this half
15 of the current passes through coil 34 to line 23, and the remaining 1/6 of this half of the passes through coils 36, 38, 40, 42, and 44 to line 24. This results in approximately {fraction (11/12)} of the current being supplied to line 23.

It will be appreciated that the reference light may commonly illuminate more than one of the PIN diodes CR1-CR12 of array 15¹ at a time. This may occur because the size
20 of the reference beam of laser light is significantly greater than the size of the photodetector elements. Further, thermal gradients in the air through which the laser light passes may result in rapid positional fluctuation of the beam, effectively illuminating a number of photodetector elements at once as the beam flutters between the elements. The weighting circuit 30¹ splits the current from each of the multiple photodetector elements in
25 dependence upon the position of the photodetector element in array row. As a consequence, the resulting signal levels on lines 23 and 24 are the sums of the various illuminated photodetector elements, and these signal levels accurately reflect the average position of the middle of the beam.

The photodetector elements CR1-CR12 in array 15¹ are evenly spaced along a
30 generally vertically oriented row. It is desired that the elements CR1-CR12 be spaced apart by distances that are small as compared to the dimension of the beam of reference

light that is to be detected. As a consequence, as the light moves vertically with respect to the row of elements it will move onto one photodetector element as it moves off of the adjacent photodetector element. If the spaces between adjacent elements were too large, the levels of the signals on lines 23 and 24 might fluctuate undesirably, even though their
5 relative amplitudes continued to reflect accurately the position of the light.

The output circuits 22 are associated with, and responsive to, reference signals on lines 23, 24, 25, and 26 from connected weighting circuits. The output circuits 22 assess the relative levels of the reference signals from the weighting circuits 30^1 , 30^2 , 30^3 , and 30^4 such that the position of the reference light may be determined with respect to the
10 detector device. Each output circuit preferably includes a separate filter circuit, current-to-voltage amplifier circuit, and peak detection and hold circuit for processing the reference signals on lines 23, 24, 25, and 26. Preferably, the reference signals are converted to digital form. The relative levels of the processed reference signals are assessed by output circuits 22, including microprocessor 50, to determine the position of the reference plane
15 of light with respect to the row of PIN diodes in arrays 15^1 , 15^2 , 15^3 , and 15^4 .

This can be accomplished in a variety of ways. For instance, if the relative levels of the first and second reference signals on lines 23 and 24 change linearly as the light moves up and down the row of photodetectors in array 15^1 , the reference light will be spaced along the row by a fraction of the row length that is equal to the fraction of one of
20 the reference signals divided by the sum of the reference signals on lines 23 and 24. By this technique, it will be appreciated that the absolute intensity of the light striking the photodetector elements is immaterial. Rather, it is the relative levels of the two reference signals from the circuit 30^1 that define the position of the reference light. Alternatively, the ratio of the first and second reference signals may be taken and used as the address for
25 a table look up algorithm. It will be appreciated that the position of the reference light may be categorized in broad or narrow bands, or specified with any level of precision desired.

Since the device of FIGS. 1 and 2 includes four photodetector arrays, the position of the light with respect to the extended row defined by the arrays may be determined as
30 follows. Array 15^1 connects to weighting circuit 30^1 and lines 23 and 24 on which reference signals A1 and A2 are provided, respectively. Array 15^2 connects to weighting

circuit 30² and lines 24 and 25 on which reference signals A2 and A3 are provided, respectively. Array 15³ connects to weighting circuit 30³ and lines 25 and 26 on which reference signals A3 and A4 are provided, respectively. Finally, array 15⁴ connects to weighting circuit 30⁴ and lines 26 and line 27 on which reference signals A4 and A5 are provided.

The position of the reference light can be determined by the formula $(A1-A2)/(A1+A2)$ if it is on the first array 15¹, $(A2-A3)/(A2+A3)$ if it is on the second array 15², $(A3-A4)/(A3+A4)$ if it is on the third array 15, and so on. It is, of course, possible for the reference light to illuminate photodetectors in two adjacent arrays simultaneously, falling across the boundary of two adjoining photodetector arrays. This results in signals being produced by both arrays. The formulae for the individual arrays can be combined into one formula which deals with simultaneous illumination of multiple arrays. For two concatenated arrays, the combined formula is $(2xA1-2xA3)/(A1+A2+A3)$. For three concatenated arrays, the combined formula is $(3xA1+A2-A3-3xA4)/(A1+A2+A3+A4)$. For four concatenated arrays, the combined formula is $(4xA1+2xA2-2xA4-4xA5)/(A1+A2+A3+A4+A5)$. The formula may be chosen for any desired number of arrays. The microprocessor 50 performs these simple calculations in a straightforward fashion.

FIG. 3 is a schematic diagram, illustrating the generalization of the device of the present invention to include m weighting circuits 30¹, 30², . . . 30^m, which respond to m corresponding photodetector arrays 15¹, 15², . . . 15^m. As will be appreciated, most photodetectors, such as PIN diodes and phototransistors, are relatively small, and are therefore spaced on about 0.10 to 0.30 inch centers. Close spacing of the photodetectors permits detection of a relatively narrow beam of laser light, for example. Consequently the number of photodetectors required to build a receiver from about 6 inches up to 6 feet in length ranges from about 25 to over 250. This would be increased, of course, depending upon the number of rows of receivers that are used to receive light from different sides of the device. A practical device may typically include an extended row of photodetectors that is 18 inches high and includes seven or eight arrays and seven or eight associated weighting circuits. Connecting photodetector arrays and weighting circuits in concatenated fashion produces a relatively small number of reference signals that

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nevertheless define the position of the detected reference light quite precisely. As will be noted, the connections of the PIN diodes of FIG. 3 are opposite to those of the PIN diodes of FIG. 2, illustrating that either connection arrangement may be utilized in conjunction with appropriate circuitry.

5 The device described above detects the relative position of a reference plane of laser light. Initially a plurality of photodetector arrays are arranged in a generally vertical row. Each array includes a plurality of photodetector elements also arranged in a generally vertical array row. As a result, the photodetector elements are arranged in a generally vertically oriented, extended row. Each of the photodetector elements provides
10 an electrical output when illuminated with the reference plane of light. A portion of the electrical output of each photodetector element in each array is provided as a first reference signal related to the spacing of the photodetector element from a first end of the array row. A portion of the electrical output of each photodetector element in the array is provided as a second reference signal related to the spacing of the photodetector element
15 from the second end of the array row. The position of the reference plane of laser light with respect to the extended row is determined based on the levels of the first and second reference signals from each of the arrays.

Portions of the electrical outputs may be separated using a tapped transformer, with each of the plurality of photodetector elements being connected to the transformer. A
20 plurality of tapped transformers are provided. Each of the plurality of transformers is connected to an associated photodetector array. The transformers are connected in series in the same order as the arrangement of the arrays with which they are associated in said extended row. The portions of the electrical outputs are separated using a tapped transformer, with each of the plurality of photodetector elements being connected to the
25 transformer. For each photodetector array, the photodetector elements are connected to the transformer using one or more resistors.

A number of changes and variations may be made to the device of the present invention. For example, the output circuits 22 may be reduced in number by supplying more than one weighting circuit output to the same amplifier circuit. The lower of the two
30 outputs 36 from weighting circuit 30^m may be supplied in parallel with the output on line 23 from weighting circuit 30¹. In such an arrangement, the microprocessor will have no

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difficulty in distinguishing between the situation in which array 15¹ is illuminated and the situation in which array 15^m is illuminated, since in the former a signal will be received on line 23, and in the latter a signal will be received on line 38.

Other variations in the construction and implementation of the device of the present invention may be made, as well. The number of arrays concatenated together can be more or fewer than the implementation shown, to make a longer or shorter receiver. The number of photodetectors in each array may be more or fewer than the implementation shown. This may be accomplished by using different components to make up the weighting networks, such as transformers with a different number of taps, or using a different arrangement of resistors between the transformer taps.

If desired, the weighting function may be implemented by means other than a transformer. For example, a resistor network may be used. Such an arrangement may require applying a reverse bias voltage to the photodetectors in the arrays, depending on their parameters and the intensity of the incident light and the ambient light.

As will be appreciated, laser detectors are subject to various errors, including incorrectly identifying an illumination of the detectors by an extraneous light source as a laser strike. This problem is further complicated by transmitters that also produce a periodic pulse of strobe light, typically one pulse of strobe light during each rotation of the laser beam. Thus, while time windowing (recognizing only beam strikes that occur during regularly occurring time windows) can be used to exclude from consideration much extraneous, random illumination, it cannot be used to block out light from strobes where the strobes are pulsed at the same frequency as the rotational frequency of the laser beam.

The present invention is, however, capable of making this distinction. Basically the present invention recognizes that a great many of the photodetector elements are likely to be illuminated simultaneously by a pulse of strobe light, while a much smaller number of the photodetector elements will be illuminated simultaneously by a relatively narrow beam of laser light.

For example, if there were three detector arrays 15¹ through 15^m in FIG. 3 which were illuminated by a pulse of strobe light, the pulse outputs on lines 23, 24, 36 and 38 from weighting circuits 30¹, 30², . . . 30^m would all be expected to be substantially equal. If, on the other hand, a relatively narrow beam of laser light were to sweep across the

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detector arrays 15^1 through 15^m , it would be expected that at least one of the pulse outputs on lines 23, 24, 36 and 38 would be relatively low, even if the illumination by the beam occurred over an area bridging two adjacent arrays.

Consider the case where the maximum weighting circuit outputs over a brief
5 period of time are equal to sA , sB , sC , and sD , and the minimum weighting circuit outputs, generally associated with background light levels, are equal to bA , bB , bC , and bD . The processor 50 takes the difference between maximum and minimum outputs in each case to determine four reference signals, A , B , C , and D , associated with the arrays 15 and weighting circuits 30. The processor then assesses the value of signals A , B , C , and D to
10 determine if at least one of these reference signals is below a predetermined threshold. If all of the signals are above the threshold then the processor categorizes the illumination as an omnidirectional pulse of light. If, however, at least one of the signals A , B , C , and D , has a value less than the predetermined threshold, then a second test is applied. The processor 50 determines the difference between the largest and smallest of the reference
15 signals, as well as the sum of all of the reference signals. The processor then determines the ratio of the sum of the reference signals to the difference between the largest and smallest of the reference signals. This ratio is interpreted as indicating illumination of the photodetectors by a moving, relatively thin beam of laser light when the ratio is less than a predetermined level. This ratio is also interpreted as indicating illumination of the
20 photodetectors by an omnidirectional pulse of light when said quotient is greater than the predetermined level. It has been found that for four reference signals, a predetermined level which works well is 2.5. When the ratio is less than 2.5, a laser beam strike is detected, and when the ratio is above 2.5 a strobe pulse is detected.

Additional filtering may be useful. For example, time windowing may be used to
25 detect laser beam illumination coming from a second transmitter. Further, spike filtering of the background readings may advantageously be used to extraneous light noise from the system. It will also be appreciated that the reciprocal of the ratio of the sum of the reference signals to the difference between the largest and smallest of the reference signals may be computed and the categorization made based on this reciprocal ratio.

30 This method is illustrated in greater detail by the flow chart of FIG. 4. When a beam has not been acquired and a series of detections are received, the maximum strike is

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detected at 100. The four reference signal values are calculated at 102, as well as the sum of the four reference signal values at 104. Next, the signal strength is detected and, if less than a threshold, the signal is classified as a weak signal the input capture task is re-initiated. If, however, a sufficiently strong signal is detected then the reference signals are
5 checked with signature rules at 106, including for example a determination as to whether the ratio of the sum of the reference signals to the difference between the largest and smallest of the reference signals is less than a predetermined level, such as 2.5. If this is the case, then the illumination is classified as a laser beam strike at 108. If the ratio is greater than 2.5, however, the incident is classified as the receipt of a pulse of light from
10 an omnidirectional source, such as a strobe. If desired, an indication can be given that strobe interference is detected. When the beam strike is detected, the timing of the beam strike is checked with a phase lock circuit at 110. If the beam strike is detected outside the expected time frame, then the beam strike is classified as a illumination from a second laser source. If the beam strike is detected as occurring within the expected time window,
15 however, it is determined to be a valid beam strike, which may be used for position calculation at 112.

It should be appreciated that the present invention is appropriately used with any number of arrays, and can be generalized for use with other types of light detection devices. The invention may be used with any detector having multiple arrays, where each
20 array provides two signals that provide an indication of the detectors in the array that are illuminated.

While certain representative embodiments and details have been shown for purposes of illustrating the invention, it will be apparent to those skilled in the art that various changes in the methods and apparatus disclosed herein may be made without
25 departing from the scope of the invention, which is defined in the appended claims.

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CLAIMS

1. A method for detecting a moving, relatively thin beam of laser light, and distinguishing between illumination of photodetectors by such a moving, relatively thin beam of laser
5 light, and illumination of photodetectors by an omnidirectional pulse of light, comprising the steps of:
 - positioning a plurality of photodetector arrays in a generally vertical row, each array including a plurality of photodetector elements arranged in a generally vertical array row, such that the photodetector elements in said arrays are collectively arranged in a
10 generally vertically oriented, extended row, each of said photodetector elements providing an electrical output when illuminated,
 - for each array, providing a portion of the electrical output of each photodetector element in the array as a first reference signal related to the spacing of the photodetector element from a first end of the array row, and providing a portion of the electrical output
15 of each photodetector element in the array as a second reference signal related to the spacing of the photodetector element from the second end of said array row,
 - determining the sum of the first and second reference signals from said photodetector arrays,
 - determining the difference between the largest of the first and second reference
20 signals from said photodetector arrays and the smallest of the first and second reference signals from said photodetector arrays,
 - dividing said sum of the first and second reference signals from said photodetector arrays by said difference between the largest of the first and second reference signals from said photodetector arrays and the smallest of the first and second reference signals from
25 said photodetector arrays, thereby providing a quotient,
 - interpreting the quotient as indicating illumination of said photodetectors by a moving, relatively thin beam of laser light when said quotient is less than a predetermined level, and interpreting the quotient as indicating illumination of said photodetectors by an omnidirectional pulse of light when said quotient is greater than said predetermined level,
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in the event that said quotient indicates illumination of said photodetectors by said moving, relatively thin beam of laser light, determining the position of said beam of laser light with respect to said extended row based on the levels of said first and second reference signals from each of the arrays.

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2. The method according to claim 1, further comprising the step of displaying an indication of said position of said reference light with respect to said row.

3. The method according to claim 1, in which the step of positioning a plurality of
10 photodetector arrays includes the step of positioning a plurality of PIN diodes in a plurality of arrays.

4. The method according to claim 1, in which the step of, for each photodetector array, providing a portion of the electrical output of each photodetector element in the array as a
15 first reference signal related to the spacing of the photodetector element from a first end of the array row, and providing a portion of the electrical output of each photodetector element in the array as a second reference signal related to the spacing of the photodetector element from the second end of said array row includes the step of separating said portions of said electrical outputs using a tapped transformer with each of
20 said plurality of photodetector elements being connected to said transformer.

5. The method according to claim 1, in which a plurality of tapped transformers are provided, with each of said plurality of transformers being connected to an associated photodetector array, and with the transformers connected in series in the same order as the
25 arrangement of the arrays with which they are associated in said extended row.

6. The method according to claim 5, in which the step of separating said portions of said electrical outputs using a tapped transformer with each of said plurality of photodetector elements being connected to said transformer further includes the step of, for each
30 photodetector array, connecting said photodetector elements to said transformer using one or more resistors, and electrically connecting said tapped transformer.

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7. The method according to claim 1, in which the step of positioning a plurality of photodetector arrays in a generally vertically oriented row comprises the step of evenly spacing said plurality of photodetector arrays along said generally vertically oriented row,
5 and evenly spacing said plurality of photodetector elements within each array.

8. The method according to claim 5, further comprising the step of receiving said first reference signals and said second reference signals from the ends of the plurality of tapped transformers.

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9. The method according to claim 1, in which there are four reference signals, and in which the predetermined level used for interpretation of the quotient is approximately 2.5.

10. The method according to claim 9, in which said photodetector arrays are electrically
15 connected such that the second reference signal from each of the first three arrays is connected to the first reference signal from the adjacent arrays.

11. A method for distinguishing between illumination of photodetectors by a moving, relatively thin beam of laser light, and illumination of photodetectors by an
20 omnidirectional pulse of light, comprising the steps of:

positioning a plurality of photodetector elements in a generally vertical row, said elements being connected into a plurality of arrays and each photodetector element providing an electrical output when illuminated,

for each array providing a portion of the electrical output of each photodetector
25 element in the array as a first reference signal, and providing a portion of the electrical output of each photodetector element in the array as a second reference signal,

determining the sum of the first and second reference signals from said photodetector arrays,

determining the difference between the largest of the first and second reference
30 signals from said photodetector arrays and the smallest of the first and second reference signals from said photodetector arrays,

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dividing said sum of the first and second reference signals from said photodetector arrays by said difference between the largest and smallest of the first and second reference signals to provide a quotient, and

when said quotient is less than a predetermined level, interpreting the quotient as
5 indicating illumination of said photodetectors by a moving, relatively thin beam of laser light.

12. The method of claim 11 for distinguishing between illumination of photodetectors by a moving, relatively thin beam of laser light, and illumination of photodetectors by an
10 omnidirectional pulse of light, comprising the additional step of interpreting the quotient as indicating illumination of said photodetectors by an omnidirectional pulse of light when said quotient is greater than a predetermined level.

13. The method of claim 12 for distinguishing between illumination of photodetectors by
15 a moving, relatively thin beam of laser light, and illumination of photodetectors by an omnidirectional pulse of light, in which there are four reference signals, and in which the predetermined level used for interpretation of the quotient is approximately 2.5.

14. The method of claim 13 for distinguishing between illumination of photodetectors by
20 a moving, relatively thin beam of laser light, and illumination of photodetectors by an omnidirectional pulse of light, in which said photodetector arrays are electrically connected such that the second reference signal from each of the first three arrays is connected to the first reference signal from the adjacent arrays.

25 15. A method for distinguishing between illumination of photodetectors by a moving, relatively thin beam of laser light, and illumination of photodetectors by an omnidirectional pulse of light, comprising the steps of:

positioning a plurality of photodetector elements in a generally vertical row, said elements being connected into a plurality of arrays and each photodetector element
30 providing an electrical output when illuminated,

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for each array providing a portion of the electrical output of each photodetector element in the array as a first reference signal, and providing a portion of the electrical output of each photodetector element in the array as a second reference signal,

determining the sum of the first and second reference signals from said

5 photodetector arrays,

determining the difference between the largest of the first and second reference signals from said photodetector arrays and the smallest of the first and second reference signals from said photodetector arrays,

dividing said sum of the first and second reference signals from said photodetector
10 arrays by said difference between the largest and smallest of the first and second reference signals to provide a quotient, and

when said quotient is greater than a predetermined level, interpreting the quotient as indicating illumination of said photodetectors by an omnidirectional pulse of light.

15 16. The method of claim 15 for distinguishing between illumination of photodetectors by a moving, relatively thin beam of laser light, and illumination of photodetectors by an omnidirectional pulse of light, comprising the additional step of interpreting the quotient as indicating illumination of said photodetectors by a moving, relatively thin beam of laser light when said quotient is less than a predetermined level.

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17. A device for detecting a moving, relatively thin beam of laser light, and distinguishing between illumination of photodetectors by such a moving, relatively thin beam of laser light, and illumination of photodetectors by an omnidirectional pulse of light, comprising:

a plurality of photodetector arrays arranged in a generally vertical row, each array
25 including a plurality of photodetector elements arranged in a generally vertical array row, such that the photodetector elements in said arrays are arranged in a generally vertically oriented, extended row, each of said photodetector elements providing an electrical output when illuminated,

a plurality of weighting circuits, each weighting circuit associated with a respective
30 one of said plurality of photodetector arrays, each weighting circuit providing a portion of the electrical output of each photodetector element in the associated array as a first

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reference signal related to the spacing of the photodetector element from a first end of said array row, and providing a portion of the electrical output of each photodetector element in the associated array as a second reference signal related to the spacing of the photodetector element from the second end of said array row, the weighting circuit associated with each
5 array row being connected to the weighting circuits associated with adjacent array rows, and

circuitry, associated with and responsive to the reference signals from connected weighting circuits, for determining the ratio of sum of the reference signals to the difference between the largest and smallest of the reference signals, and interpreting this
10 ratio as indicating illumination of said photodetectors by a moving, relatively thin beam of laser light when said ratio is less than a predetermined level, and interpreting the ratio as indicating illumination of said photodetectors by an omnidirectional pulse of light when said quotient is greater than said predetermined level.

15 18. The device for detecting the relative position of reference light according to claim 17, in which said photodetector elements comprise PIN diodes.

19. The device for detecting the relative position of reference light according to claim 17, in which each of said weighting circuit comprises a tapped transformer circuit with each of
20 said plurality of photodetector elements in an array being connected to said tapped transformer circuit of said associated weighting circuit.

20. The device for detecting the relative position of reference light according to claim 19, in which said weighting circuit further comprises one or more resistors connecting said
25 photodetector elements to said transformer.

21. A method for distinguishing between illumination of photodetectors by a moving, relatively thin beam of laser light, and illumination of photodetectors by an omnidirectional pulse of light, comprising the steps of:

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positioning a plurality of photodetector elements, said elements being connected into a plurality of arrays and each photodetector element providing an electrical output when illuminated,

for each array providing a first reference signal, and a second reference signal, the
5 difference between the reference signals indicating the position of photodetector elements in the array being illuminated,

determining the sum of the first and second reference signals from said photodetector arrays,

determining the difference between the largest of the first and second reference
10 signals from said photodetector arrays and the smallest of the first and second reference signals from said photodetector arrays,

dividing said sum of the first and second reference signals from said photodetector arrays by said difference between the largest and smallest of the first and second reference signals to provide a quotient, and

15 when said quotient is greater than a predetermined level, interpreting the quotient as indicating illumination of said photodetectors by an omnidirectional pulse of light.

22. The method of claim 21 for distinguishing between illumination of photodetectors by a moving, relatively thin beam of laser light, and illumination of photodetectors by an
20 omnidirectional pulse of light, comprising the additional step of interpreting the quotient as indicating illumination of said photodetectors by a moving, relatively thin beam of laser light when said quotient is less than a predetermined level.

23. The method of claim 21 for distinguishing between illumination of photodetectors by
25 a moving, relatively thin beam of laser light, and illumination of photodetectors by an omnidirectional pulse of light, comprising the additional step of determining whether at least some of said reference signals are below a reference level and interpreting the situation where fewer than a predetermined number of said reference signals are below said reference level as an indication of illumination of photodetectors by an
30 omnidirectional pulse of light.

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24. A method for distinguishing between illumination of photodetectors by a moving, relatively thin beam of laser light, and illumination of photodetectors by an omnidirectional pulse of light, comprising the steps of:

positioning a plurality of photodetector elements, said elements being connected
5 into a plurality of arrays and each photodetector element providing an electrical output when illuminated,

for each array providing a first reference signal, and a second reference signal, the difference between the reference signals indicating the position of photodetector elements in the array being illuminated,

10 determining the sum of the first and second reference signals from said photodetector arrays,

determining the difference between the largest of the first and second reference signals from said photodetector arrays and the smallest of the first and second reference signals from said photodetector arrays,

15 dividing said difference between the largest and smallest of the first and second reference signals by said sum of the first and second reference signals from said photodetector arrays to provide a quotient, and

when said quotient is less than a predetermined level, interpreting the quotient as indicating illumination of said photodetectors by an omnidirectional pulse of light.

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25 The method of claim 24 for distinguishing between illumination of photodetectors by a moving, relatively thin beam of laser light, and illumination of photodetectors by an omnidirectional pulse of light, comprising the additional step of interpreting the quotient as indicating illumination of said photodetectors by a moving, relatively thin beam of laser light when said quotient is greater than a predetermined level.

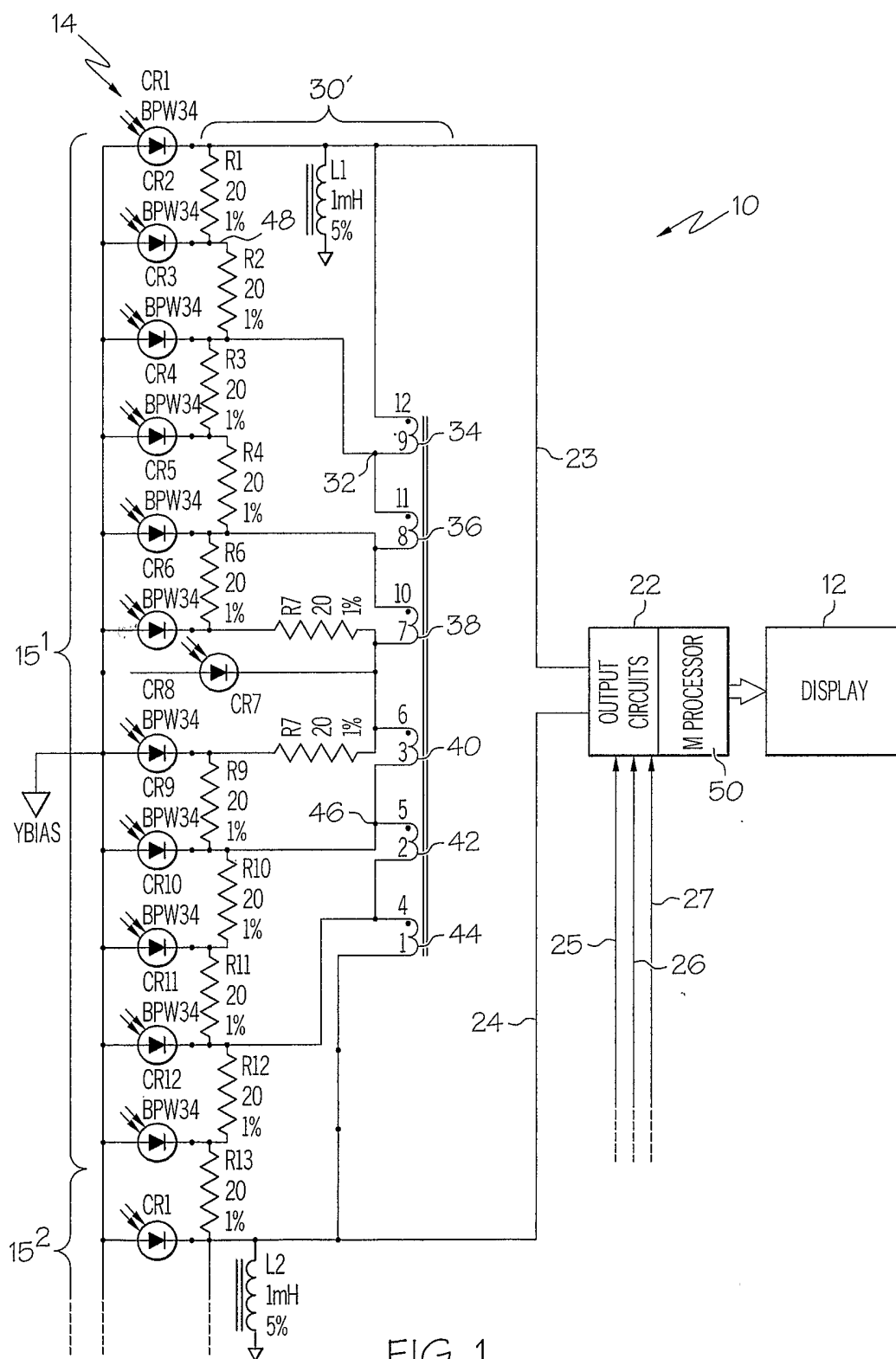
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26. The method of claim 24 for distinguishing between illumination of photodetectors by a moving, relatively thin beam of laser light, and illumination of photodetectors by an omnidirectional pulse of light, comprising the additional step of determining whether at
5 least some of said reference signals are below a reference level and interpreting the situation where fewer than a predetermined number of said reference signals are below said reference level as an indication of illumination of photodetectors by an omnidirectional pulse of light.

10 27. The method of claim 24 for distinguishing between illumination of photodetectors by a moving, relatively thin beam of laser light, and illumination of photodetectors by an omnidirectional pulse of light, comprising the additional step of providing an indication of strobe interference when illumination of said photodetectors by an omnidirectional pulse
of light is detected.

15 28. The method of claim 26 for distinguishing between illumination of photodetectors by a moving, relatively thin beam of laser light, and illumination of photodetectors by an omnidirectional pulse of light, comprising the additional step of providing an indication of strobe interference when illumination of said photodetectors by an omnidirectional pulse
20 of light is detected.

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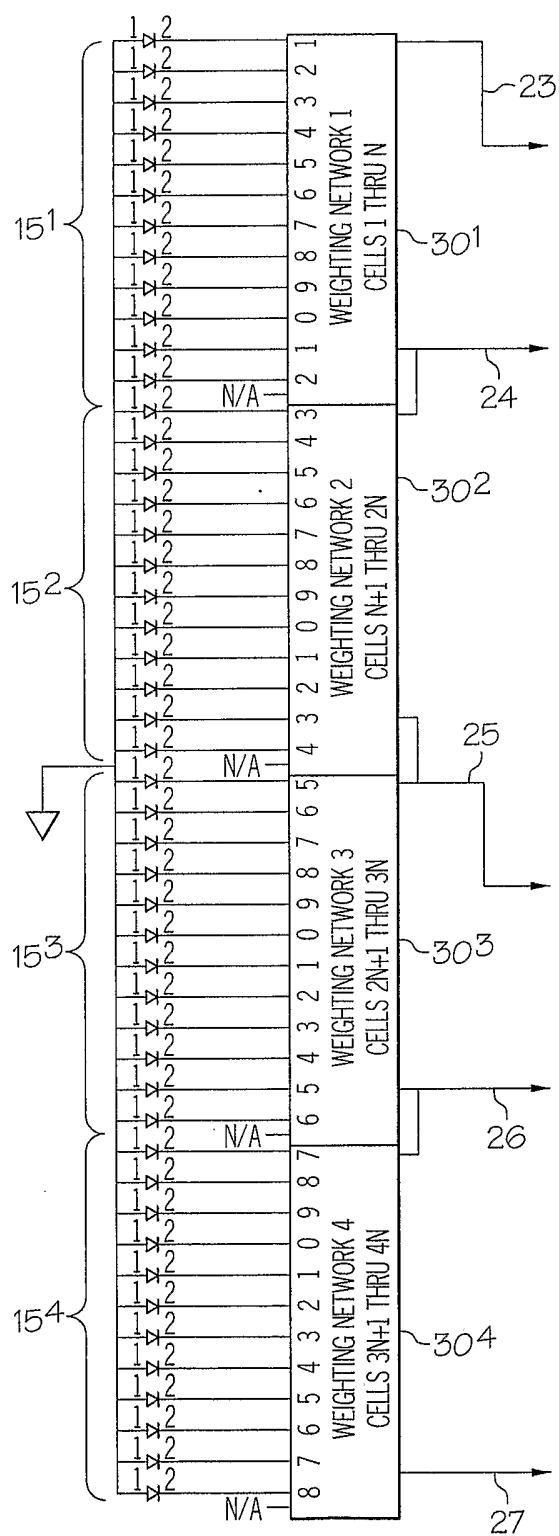


FIG. 2

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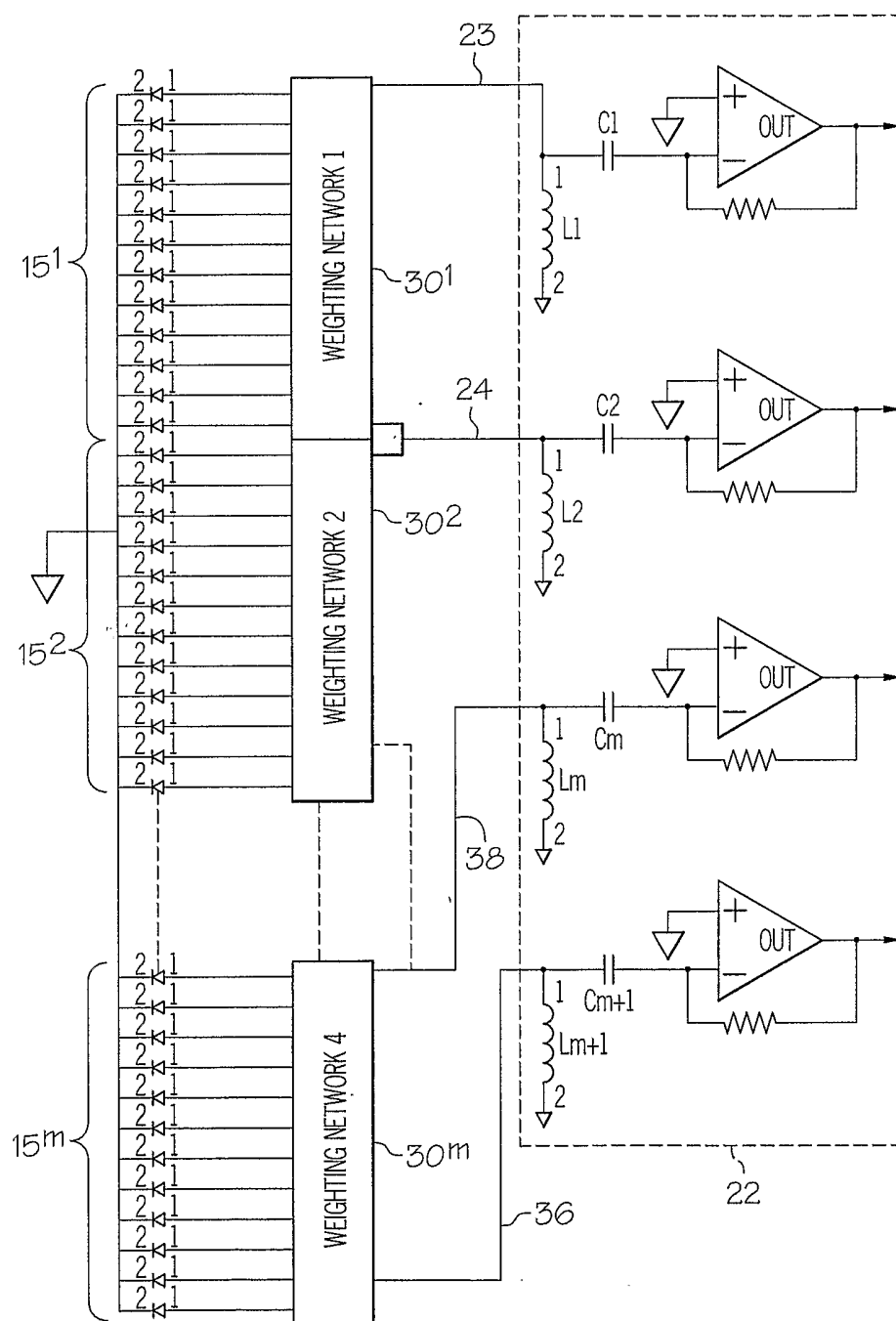
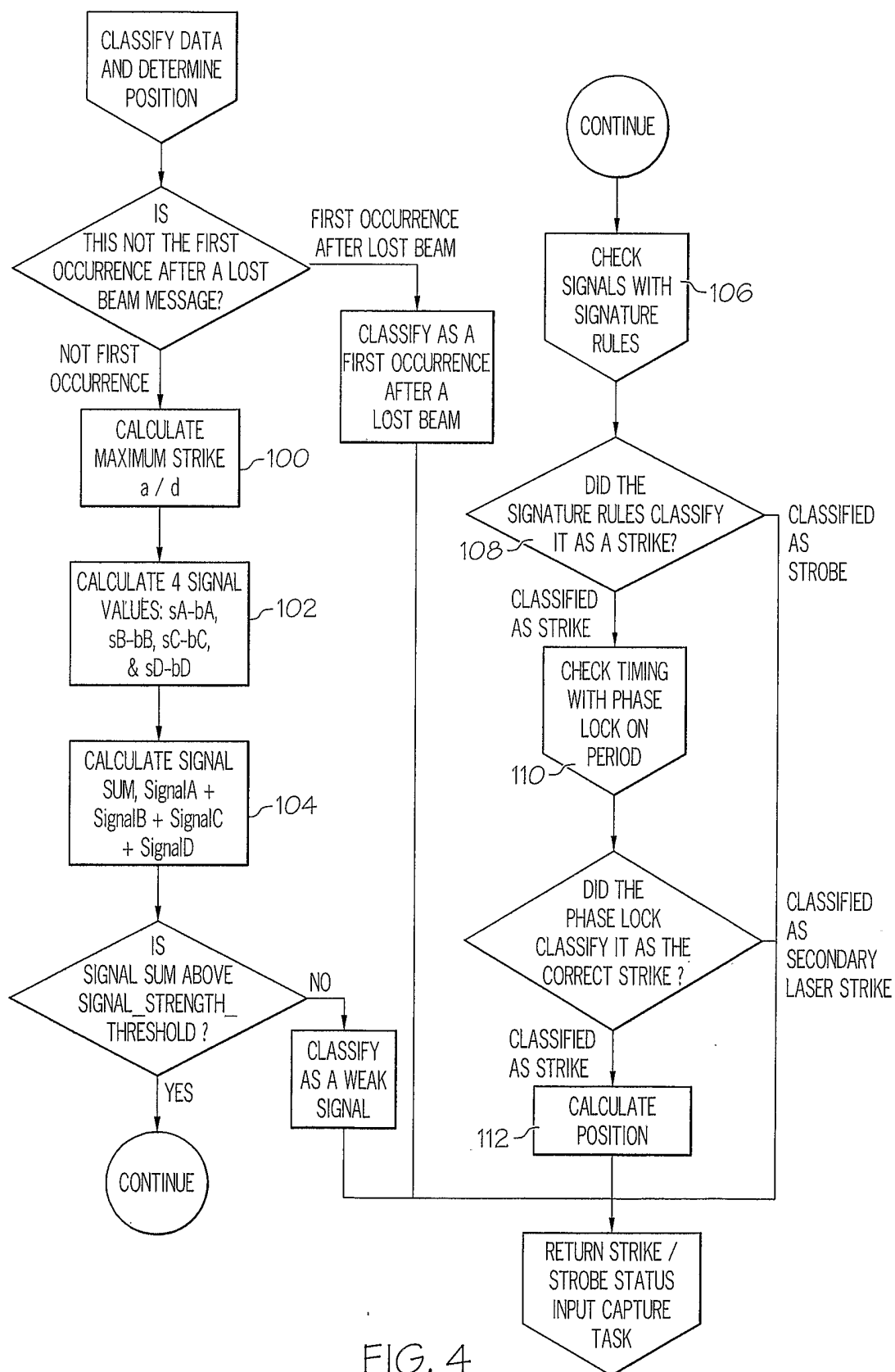


FIG. 3

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INTERNATIONAL SEARCH REPORT

International Application No

PC JS2005/031208

A. CLASSIFICATION OF SUBJECT MATTER
G01C15/00

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

G01C G01B G01S

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

EPO-Internal, WPI Data, PAJ

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category °	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	US 2003/202172 A1 (DOUGLAS FRANK B) 30 October 2003 (2003-10-30) the whole document	1-28
A	US 5 742 069 A (STEENWYK ET AL) 21 April 1998 (1998-04-21) abstract column 1, line 50 - column 2, line 34 column 4, line 56 - column 5, line 20 figures 1,2	1-28
P,A	US 2005/103974 A1 (HSIAO CHING-HORNG) 19 May 2005 (2005-05-19) column 2, paragraph 21 claim 2	1-28

☐ Further documents are listed in the continuation of box C.

☒ Patent family members are listed in annex.

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T later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

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Date of the actual completion of the international search

16 January 2006

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24/01/2006

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INTERNATIONAL SEARCH REPORT

Information on patent family members

International Application No

PCT/JP2005/031208

Patent document cited in search report		Publication date	Patent family member(s)	Publication date
US 2003202172	A1	30-10-2003	US 2003058446 A1	27-03-2003
US 5742069	A	21-04-1998	NONE	
US 2005103974	A1	19-05-2005	TW 248111 Y	21-10-2004