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# DESCRIPTION

Description

## [Technical Field]

**[0001]** The present invention relates to methods for generating a prediction block in intra prediction, and more particularly, to an encoding method and a decoding method for generating a prediction block in intra prediction using neighboring intra prediction modes.

## [Background Art]

**[0002]** In H.264/MPEG-4 AVC, one picture is divided into macroblocks, the respective macroblocks are encoded by generating a prediction block using inter prediction or intra prediction. The difference between an original block and the prediction block is transformed to generate a transformed block, and the transformed block is quantized using a quantization parameter and quantization matrix. The quantization parameter is adjusted per macroblock and is encoded using a previous quantization parameter as a quantization parameter predictor.

**[0003]** Meanwhile, in HEVC (High Efficiency Video Coding) under construction, various sizes of coding unit are introduced to obtain two times of compression efficiency. The coding unit has a role similar to the macroblock of H.264.

**[0004]** W-J CHIEN ET AL: "Parsing friendly intra mode coding", 6. JCT-VC MEETING; 97. MPEG MEETING; 14-7-2011 - 22-7-2011; TORINO; (JOINT COLLABORATIVE TEAM ON VIDEO CODING OF ISO/IEC JTC1/SC29/ WG11 AND ITU-TSG.16) discloses coding method for intra prediction mode. In the HEVC Test Model at this time, different codeword binarizations are defined based on the intra prediction modes of neighboring partitions for the luma intra prediction mode coding. It also uses different codeword binarization for chroma intra prediction mode based on the luma intra prediction mode of the current partition. This method unifies different binarizations by utilizing constant number of candidate modes. The simulation results show average performance gain of 0.2% in Intra only configurations.

**[0005]** Thomas Wiegand ET AL: "WD3: Working Draft 3 of High-Efficiency Video Coding (JCTVC-E603)" is the corresponding HEVC working draft.

**[0006]** It is therefore the object of the invention to provide an improved decoding method and encoding method for generating a prediction block in intra prediction.

**[0007]** This object is solved by the subject matter of the independent claims.

**[0008]** Preferred embodiments are defined by the dependent claims.

**[Disclosure]**

**[Technical Problem]**

**[0009]** The present invention is directed to methods for generating a prediction block in intra prediction.

**[Technical Solution]**

**[0010]** One aspect of the present invention provides methods for generating a prediction block in intra prediction as specified in the independent claims.

**[Advantageous Effects]**

**[0011]** A method according to the present invention can improve the generation of a prediction block.

**[Description of Drawings]**

**[0012]**

FIG. 1 is a block diagram of an image coding apparatus.

FIG. 2 is a conceptual diagram illustrating intra prediction modes according to the present invention.

FIG. 3 is a flow chart illustrating a method of encoding quantization parameter.

FIG. 4 is a block diagram of an image decoding apparatus.

FIG. 5 is a flow chart illustrating a method of decoding quantization parameter.

FIG. 6 is a flow chart illustrating a procedure of restoring intra prediction mode according to the present invention.

FIG. 7 is a block diagram illustrating an apparatus of generating a prediction block in intra prediction.

FIG. 8 is a conceptual diagram illustrating positions of reference pixels of a current block.

FIG. 9 is a block diagram illustrating an apparatus of generating a prediction block in intra prediction.

### **[Mode for Invention]**

**[0013]** Hereinafter, various embodiments of the present invention will be described in detail with reference to the accompanying drawings.

**[0014]** FIG. 1 is a block diagram of an image coding apparatus 100.

**[0015]** Referring to FIG. 1, the image coding apparatus 100 includes a picture division unit 101, a transform unit 103, a quantization unit 104, a scanning unit 105, an entropy coding unit 106, an inverse quantization unit 107, an inverse transform unit 108, a post-processing unit 110, a picture storing unit 111, an intra prediction unit 112, an inter prediction unit 113, a subtracter 102 and an adder 109.

**[0016]** The picture division unit 101 divides a picture or a slice into a plurality of largest coding units (LCUs), and divides each LCU into one or more coding units. The picture division unit 101 determines prediction mode of each coding unit and a size of prediction unit and a size of transform unit.

**[0017]** An LCU includes one or more coding units. The LCU has a recursive quad tree structure to specify a division structure. Information specifying the maximum size and the minimum size of the coding unit is included in a sequence parameter set. The division structure is specified by one or more split coding unit flags (split\_cu\_flags). The coding unit has a size of  $2N \times 2N$ .

**[0018]** A coding unit includes one or more prediction units. In intra prediction, the size of the prediction unit is  $2N \times 2N$  or  $N \times N$ . In inter prediction, the size of the prediction unit is  $2N \times 2N$ ,  $2N \times N$ ,  $N \times 2N$  or  $N \times N$ . When the prediction unit is an asymmetric partition in inter prediction, the size of the prediction unit may also be one of  $hN \times 2N$ ,  $(2-h)N \times 2N$ ,  $2N \times hN$  and  $2N \times (2-h)N$ . The value of  $h$  is  $1/2$ .

**[0019]** A coding unit includes one or more transform units. The transform unit has a recursive quad tree structure to specify a division structure. The division structure is specified by one or more split transform unit flags (split\_tu\_flags). Information specifying the maximum size and the minimum size of the transform unit is included in a sequence parameter set.

**[0020]** The intra prediction unit 112 determines an intra prediction mode of a current prediction unit and generates one or more prediction blocks using the intra prediction mode. The prediction block has the same size of the transform unit. The intra prediction unit 112 generates reference pixels if there are unavailable reference pixels of a current block, filters adaptively the reference pixels of the current block according to the size of the current block and the intra prediction mode, and generates a prediction block of the current block. The current block has the same size of the prediction block.

**[0021]** FIG. 2 is a conceptual diagram illustrating intra prediction modes according to the present invention. As shown in FIG. 2, the number of intra prediction modes is 35. The DC mode and the planar mode are non-directional intra prediction modes and the others are directional intra prediction modes.

**[0022]** The inter prediction unit 113 determines motion information of the current prediction unit using one or more reference pictures stored in the picture storing unit 111, and generates a prediction block of the prediction unit. The motion information includes one or more reference picture indexes and one or more motion vectors.

**[0023]** The transform unit 103 transforms residual signals generated using an original block and a prediction block to generate a transformed block. The residual signals are transformed in transform units. A transform type is determined by the prediction mode and the size of the transform unit. The transform type is a DCT-based integer transform or a DST-based integer transform.

**[0024]** The quantization unit 104 determines a quantization parameter for quantizing the transformed block. The quantization parameter is a quantization step size. The quantization parameter is determined per quantization unit having a size of coding unit equal to or larger than a reference size. The reference size is a minimum size of the quantization unit. If a size of the coding unit is equal to or larger than the minimum size of the quantization unit, the coding unit becomes the quantization unit. A plurality of coding units may be included in the minimum quantization unit. The minimum size of the quantization unit is one of allowable sizes of the coding unit.

**[0025]** The quantization unit 104 generates a quantization parameter predictor and generates a differential quantization parameter by subtracting the quantization parameter predictor from the quantization parameter. The differential quantization parameter is encoded and transmitted to the decoder. If there are no residual signals to be transmitted within the coding unit, the differential quantization parameter of the coding unit may not be transmitted.

**[0026]** The following examples do not fall under the scope of the invention but are examples of generating a quantization predictor that are suitable for better understanding the invention.

**[0027]** The quantization parameter predictor is generated by using quantization parameters of

neighboring coding units and/or a quantization parameter of previous coding unit.

**[0028]** In one example, the quantization unit 104 sequentially retrieves a left quantization parameter, an above quantization parameter and an above left quantization parameter in this order, and generates the quantization parameter predictor using one or two available quantization parameters. For example, an average of the first two available quantization parameters retrieved in that order is set as the quantization parameter predictor when at least two quantization parameters are available. When only one quantization parameter is available, the available quantization parameter is set as the quantization parameter predictor. The left quantization parameter is a quantization parameter of a left neighboring coding unit. The above quantization parameter is a quantization parameter of an above neighboring coding unit. The above left quantization parameter is a quantization parameter of an above left neighboring coding unit.

**[0029]** In another example, the quantization unit 104 sequentially retrieves a left quantization parameter, an above quantization parameter and a previous quantization parameter in this order, and generates the quantization parameter predictor using one or two available quantization parameters. An average of the first two available quantization parameters retrieved in that order is set as the quantization parameter predictor when at least two quantization parameters are available. When only one quantization parameter is available, the available quantization parameter is set as the quantization parameter predictor. That is, if both of the left quantization parameter and the above quantization parameter are available, the average of the left quantization parameter and the above quantization parameter is set as the quantization parameter predictor. If one of the left quantization parameter and the above quantization parameter is available, the average of the available quantization parameter and the previous quantization parameter is set as the quantization parameter predictor. If both of the left quantization parameter and the above quantization parameter are unavailable, the previous quantization parameter is set as the quantization parameter predictor. The previous quantization parameter is a quantization parameter of a previous coding unit in coding order. The average is rounded off.

**[0030]** The quantization unit 104 quantizes the transformed block using a quantization matrix and the quantization parameter to generate a quantized block. The quantized block is provided to the inverse quantization unit 107 and the scanning unit 105.

**[0031]** The scanning unit 105 determines a scan pattern and applies the scan pattern to the quantized block. When CABAC (Context adaptive binary arithmetic coding) is used for entropy coding, the scan pattern is determined as follows.

**[0032]** In intra prediction, the distribution of the quantized transform coefficients varies according to the intra prediction mode and the size of the transform unit. Thus, the scan pattern is determined by the intra prediction mode and the size of the transform unit. The scan pattern is selected among a diagonal scan, vertical scan and horizontal scan. The quantized transform coefficients of the quantized block are split into significant flags, coefficient signs and

coefficient levels. The scan pattern is applied to the significant flags, coefficient signs and coefficient levels respectively.

**[0033]** When the size of the transform unit is equal to or smaller than a first size, the horizontal scan is selected for the vertical mode and a predetermined number of neighboring intra prediction modes of the vertical mode, the vertical scan is selected for the horizontal mode and the predetermined number of neighboring intra prediction modes of the horizontal mode, and the diagonal scan is selected for the other intra prediction modes. The first size is 8x8.

**[0034]** When the size of the transform unit is larger than the first size, the diagonal scan is selected for all intra prediction modes.

**[0035]** In inter prediction, the diagonal scan is used.

**[0036]** When the size of the transform unit is larger than a second size, the quantized block is divided into a plurality of subsets and scanned. The second size is 4x4. The scan pattern for scanning the subsets is the same as the scan pattern for scanning quantized transform coefficients of each subset. The quantized transform coefficients of each subset are scanned in the reverse direction. The subsets are also scanned in the reverse direction.

**[0037]** Last non-zero position is encoded and transmitted to the decoder. The last non-zero position specifies position of last non-zero quantized transform coefficient within the transform unit. Non-zero subset flags are determined and encoded. The non-zero subset flag indicates whether the subset contains non-zero coefficients or not. The non-zero subset flag is not defined for a subset covering a DC coefficient and a subset covering last non-zero coefficient.

**[0038]** The inverse quantization unit 107 inversely quantizes the quantized transform coefficients of the quantized block.

**[0039]** The inverse transform unit 108 inversely transforms the inverse quantized block to generate residual signals of the spatial domain.

**[0040]** The adder 109 generates a reconstructed block by adding the residual block and the prediction block.

**[0041]** The post-processing unit 110 performs a deblocking filtering process for removing blocking artifact generated in a reconstructed picture.

**[0042]** The picture storing unit 111 receives post-processed image from the post-processing unit 110, and stores the image in picture units. A picture may be a frame or a field.

**[0043]** The entropy coding unit 106 entropy-codes the one-dimensional coefficient information received from the scanning unit 105, intra prediction information received from the intra prediction unit 112, motion information received from the inter prediction unit 113, and so on.



**[0044]** FIG. 3 is a flow chart illustrating a method of encoding quantization parameter.

**[0045]** A minimum size of the quantization unit is determined (S110). The minimum size of the quantization unit is equal to a size of LCU or a size of sub-block of LCU. The minimum size of the quantization unit is determined per picture.

**[0046]** A quantization parameter is determined (S120). The quantization parameter is determined per quantization unit. If the size of the current coding unit is equal to or larger than the minimum size of the quantization unit, the current coding unit becomes the quantization unit. If the minimum quantization unit includes plural coding units, the quantization parameter is determined for the all the coding units within the minimum quantization unit.

**[0047]** A quantization parameter predictor is generated (S130). The quantization parameter predictor is also determined per quantization unit. If the size of the current coding unit is equal to or larger than the minimum size of the quantization unit, the quantization parameter for the current coding unit is generated. If the minimum quantization unit includes a plurality of coding unit, the quantization parameter predictor for the first coding unit in coding order is determined and used for the remaining coding units within the minimum quantization unit.

**[0048]** The quantization parameter is generated by using quantization parameters of neighboring coding units and quantization parameter of previous coding unit.

**[0049]** In one example, a left quantization parameter, an above quantization parameter and an above left quantization parameter are sequentially retrieved in this order, and the quantization parameter predictor is generated using one or two available quantization parameters. For example, an average of the first two available quantization parameters retrieved in that order is set as the quantization parameter predictor when at least two quantization parameters are available. When only one quantization parameter is available, the available quantization parameter is set as the quantization parameter predictor. The left quantization parameter is a quantization parameter of a left neighboring coding unit. The above quantization parameter is a quantization parameter of an above neighboring coding unit. The above left quantization parameter is a quantization parameter of an above left neighboring coding unit.

**[0050]** In another example, a left quantization parameter, an above quantization parameter and a previous quantization parameter are sequentially retrieved in this order, and the quantization parameter predictor is generated using one or two available quantization parameters. An average of the first two available quantization parameters retrieved in that order is set as the quantization parameter predictor when at least two quantization parameters are available. When only one quantization parameter is available, the available quantization parameter is set as the quantization parameter predictor. That is, if both of the left quantization parameter and the above quantization parameter are available, the average of the left quantization parameter and the above quantization parameter is set as the quantization parameter predictor. If one of the left quantization parameter and the above quantization

parameter is available, the average of the available quantization parameter and the previous quantization parameter is set as the quantization parameter predictor. If both of the left quantization parameter and the above quantization parameter are unavailable, the previous quantization parameter is set as the quantization parameter predictor. The previous quantization parameter is a quantization parameter of a previous coding unit in coding order. The average is rounded off.

**[0051]** A differential quantization parameter (dQP) is generated by using the quantization parameter of the current coding unit and the quantization parameter predictor of the current coding unit (S140).

**[0052]** The differential quantization parameter is entropy-coded (S150). The dQP is converted into an absolute value of the dQP and a sign flag indicating the sign of the dQP. The absolute value of the dQP is binarized as truncated unary. Then, the absolute value and the sign flag are arithmetically coded. If the absolute value is zero, the sign flag does not exist.

**[0053]** Meanwhile, the minimum size of the quantization unit is also signaled to a decoding apparatus.

**[0054]** Two steps are required to signal the minimum size of the quantization unit in the current HM (HEVC Test Model) under construction. Firstly, it is determined whether the quantization parameter is adjusted per LCU or sub-block of LCU in sequence level, and if it is determined that the quantization parameter is adjusted per sub-block of LCU in sequence level, then the minimum size of the quantization unit is determined in picture level. A first parameter (cu\_qp\_delta\_enabled\_flag) indicating whether the quantization parameter is adjusted per LCU or sub-block of LCU is included in the SPS (sequence parameter set). If the first parameter indicates that the quantization parameter is adjusted per sub-block of LCU, a second parameter (max\_cu\_qp\_delta\_depth) is included in the PPS (picture parameter set). The second parameter specifies the minimum size of the quantization unit smaller than the size of LCU. Therefore, complexity of coding process increases and two parameter should be transmitted if the minimum size of the quantization unit is used at least one picture.

**[0055]** In the present example, it is omitted to determine whether the minimum size of the quantization unit is smaller than the size of LCU or not on sequence level. That is, the minimum size of the quantization unit is determined for each picture. Therefore, one parameter (for example, cu\_qp\_delta\_enabled\_info) may be used for specifying the minimum size of the quantization unit. The parameter specifies depth of the minimum quantization unit. The minimum size of the quantization unit may be equal to a size of LCU or a size of sub-block of LCU. Accordingly, the coding bits required for signaling the minimum size of the quantization unit decreases and the complexity of coding process also decreases.

**[0056]** A predetermined quantization matrix and a user-defined quantization matrix may be used for quantizing the transformed block. When one or more user-defined quantization matrices are used, the one or more user-defined quantization matrices should be included in

the SPS or PPS. To reduce signaling bits of the user-defined quantization matrix, the coefficients of the user-defined quantization matrix are coded using DPCM (differential pulse code modulation). A diagonal scan is applied to the coefficients for DPCM.

**[0057]** When a size of the user-defined quantization matrix is larger than a predetermined size, the coefficients of the user-defined quantization matrix are down-sampled to reduce the signaling bits and then coded using DPCM. The predetermined size may be 8x8. For example, if the size of the user-defined quantization matrix is 16x16, coefficients other than DC coefficient of the user-defined quantization matrix are down-sampled using 4:1 down sampling. The DC coefficient is signaled separately from the down sampled matrix.

**[0058]** FIG. 4 is a block diagram of an image decoding apparatus 200.

**[0059]** The image decoding apparatus 200 includes an entropy decoding unit 201, an inverse scanning unit 202, an inverse quantization unit 203, an inverse transform unit 204, an adder 205, a post processing unit 206, a picture storing unit 207, an intra prediction unit 208 and an inter prediction unit 209.

**[0060]** The entropy decoding unit 201 extracts the intra prediction information, the inter prediction information and the one-dimensional coefficient information from a received bit stream. The entropy decoding unit 201 transmits the inter prediction information to the inter prediction unit 209, the intra prediction information to the intra prediction unit 208 and the coefficient information to the inverse scanning unit 202.

**[0061]** The inverse scanning unit 202 uses an inverse scan pattern to generate two dimensional quantized block. It is supposed that CABAC is used as entropy coding method. The inverse scan pattern is one of the diagonal scan, the vertical scan and the horizontal scan.

**[0062]** In intra prediction, the inverse scan pattern is determined by the intra prediction mode and the size of the transform unit. The inverse scan pattern is selected among a diagonal scan, vertical scan and horizontal scan. The selected inverse scan pattern is applied to the significant flags, the coefficient signs and the coefficient levels respectively generate the quantized block.

**[0063]** When the size of the transform unit is equal to or smaller than the first size, the horizontal scan is selected for the vertical mode and a predetermined number of neighboring intra prediction modes of the vertical mode, the vertical scan is selected for the horizontal mode and the predetermined number of neighboring intra prediction modes of the horizontal mode, and the diagonal scan is selected for the other intra prediction modes. The first size is 8x8.

**[0064]** When the size of the transform unit is larger than the first size, the diagonal scan is selected for all intra prediction modes.

**[0065]** In inter prediction, the diagonal scan is used.

**[0066]** When the size of the transform unit is larger than the second size, the significant flags, the coefficient signs and the coefficient levels are inversely scanned in the unit of the subset to generate subsets. And the subsets are inversely scanned to generate the quantized block. The second size is 4x4.

**[0067]** The inverse scan pattern used for generating each subset is the same as the inverse scan pattern used for generating the quantized block. The significant flags, the coefficient signs and the coefficient levels are scanned in the reverse direction. The subsets are also scanned in the reverse direction.

**[0068]** The last non-zero position and the non-zero subset flags are received from the encoder. The last non-zero position is used to determine the number of subsets to be generated. The non-zero subset flags are used to determine the subsets to be generated by applying the inverse scan pattern. The subset covering the DC coefficient and the subset covering the last non-zero coefficient are generated using the inverse scan pattern because the non-zero subset flags for a subset covering a DC coefficient and a subset covering last non-zero coefficient are not transmitted.

**[0069]** The inverse quantization unit 203 receives the differential quantization parameter from the entropy decoding unit 201 and generates the quantization parameter predictor. The quantization parameter predictor is generated through the same operation of the quantization unit 104 of FIG. 1. Then, the inverse quantization unit 203 adds the differential quantization parameter and the quantization parameter predictor to generate the quantization parameter of the current coding unit. If the current coding unit is equal to or larger than the minimum quantization unit and the differential quantization parameter for the current coding unit is not received from the encoder, the differential quantization parameter is set to 0.

**[0070]** The inverse quantization unit 203 inversely quantizes the quantized block.

**[0071]** The inverse transform unit 204 inversely transforms the inverse-quantized block to restore a residual block. The inverse transform type is adaptively determined according to the prediction mode and the size of the transform unit. The inverse transform type is the DCT-based integer transform or the DST-based integer transform.

**[0072]** The intra prediction unit 208 restores the intra prediction mode of the current prediction unit using the received intra prediction information, and generates a prediction block according to the restored intra prediction mode. The size of the prediction block is the same as that of the transform unit. The intra prediction unit 208 generates reference pixels if there are unavailable reference pixels of a current block, and filters adaptively the reference pixels of the current block according to the size of the current block and the intra prediction mode. The size of the current block is the same as that of the transform unit.

**[0073]** The inter prediction unit 209 restores the motion information of the current prediction unit using the received inter prediction information, and generates a prediction block using the motion information.

**[0074]** The post-processing unit 206 operates the same as the post-processing unit 110 of FIG. 1.

**[0075]** The picture storing unit 207 receives post-processed image from the post-processing unit 206, and stores the image in picture units. A picture may be a frame or a field.

**[0076]** The adder 205 adds the restored residual block and a prediction block to generate a reconstructed block.

**[0077]** FIG. 5 is a flow chart illustrating a method of decoding quantization parameter.

**[0078]** The minimum size of the quantization unit is derived (S210). The parameter (cu\_qp\_delta\_enabled\_info) specifying the depth of the minimum quantization unit is extracted from PPS. The minimum size of the quantization unit is derived per picture as follows:  

$$\text{Log2}(\text{MinQUSize}) = \text{Log2}(\text{MaxCUSize}) - \text{cu\_qp\_delta\_enabled\_info}$$

**[0079]** The MinQUSize is the minimum size of the quantization unit. The MaxCUSize is the size of LCU.

**[0080]** The differential quantization parameter (dQP) of the current coding unit is restored (S220). The dQP is restored per quantization unit. For example, if the size of the current coding unit is equal to or larger than the minimum size of the quantization unit, the dQP is restored for the current coding unit. If the current coding unit does not contain an encoded dQP, the dQP is set to zero. If the quantization unit includes plural coding units, a first coding unit containing at least one non-zero coefficient in the decoding order contains the encoded dQP.

**[0081]** The encoded dQP is arithmetically decoded to generate an absolute value of the dQP and a sign flag indicting the sign of the dQP. The absolute value of the dQP is bin string binarized as truncated unary. Then, the dQP is restored from the bin string of the absolute value and the sign flag. If the absolute value is zero, the sign flag does not exist.

**[0082]** The quantization parameter predictor of the current coding unit is generated (S230). The quantization parameter predictor is generated using the same operation of step 130 of FIG. 3. If a quantization unit includes plural coding units, the quantization parameter predictor of the first coding unit in the decoding order is generated, and the generated quantization parameter predictor is used for all the coding units within the quantization unit.

**[0083]** The quantization parameter is generated using the dQP and the quantization

parameter predictor (S240).

**[0084]** Meanwhile, the user-defined quantization matrices are also restored. A set of the user-defined quantization matrices is received from the encoding apparatus through the SPS or the PPS. The user-defined quantization matrix is restored using inverse DPCM. The diagonal scan is used for the DPCM. When the size of the user-defined quantization matrix is larger than 8x8, the user-defined quantization matrix is restored by up-sampling the coefficients of the received 8x8 quantization matrix. The DC coefficient of the user-defined quantization matrix is extracted from the SPS or the PPS. For example, if the size of the user-defined quantization matrix is 16x16, coefficients of the received 8x8 quantization matrix are up-sampled using 1:4up-sampling.

**[0085]** FIG. 6 is a flow chart illustrating a method of generating a prediction block in intra prediction according to the present invention.

**[0086]** Intra prediction information of the current prediction unit is entropy-decoded (S310).

**[0087]** The intra prediction information includes a mode group indicator and a prediction mode index. The mode group indicator is a flag indicating whether the intra prediction mode of the current prediction unit belongs to a most probable mode group (MPM group). If the flag is 1, the intra prediction unit of the current prediction unit belongs to the MPM group. If the flag is 0, the intra prediction unit of the current prediction unit belongs to a residual mode group. The residual mode group includes all intra prediction modes other than the intra prediction modes belonging to the MPM group. The prediction mode index specifies the intra prediction mode of the current prediction unit within the group specified by the mode group indicator.

**[0088]** The intra prediction mode of the current prediction unit is derived using the intra prediction information (S320).

**[0089]** FIG. 7 is a flow chart illustrating a procedure of deriving intra prediction mode according to the present invention. The intra prediction mode of the current prediction unit is restored using the following ordered steps.

**[0090]** The MPM group is constructed using intra prediction modes of the neighboring prediction units (S321). The intra prediction modes of the MPM group are adaptively determined by a left intra prediction mode and an above intra prediction mode. The left intra prediction mode is the intra prediction mode of the left neighboring prediction unit, and the above intra prediction mode is the intra prediction mode of the above neighboring prediction unit. The MPM group is comprised of three intra prediction modes.

**[0091]** If the left or above neighboring prediction unit does not exist, the intra prediction mode of the left or above neighboring unit is set as unavailable. For example, if the current prediction unit is located at the left or upper boundary of a picture, the left or above neighboring prediction unit does not exist. If the left or above neighboring unit is located within other slice or

other tile, the intra prediction mode of the left or above neighboring unit is set as unavailable. If the left or above neighboring unit is inter-coded, the intra prediction mode of the left or above neighboring unit is set as unavailable. If the above neighboring unit is located within other LCU, the intra prediction mode of the left or above neighboring unit is set as unavailable.

**[0092]** When both of the left intra prediction mode and the above intra prediction mode are available and are different each other, the left intra prediction mode and the above intra prediction mode are included in the MPM group and one additional intra prediction mode is added to the MPM group. Index 0 is assigned to one intra prediction mode of small mode number and index 1 is assigned to the other. Or index 0 is assigned to the left intra prediction mode and index 1 is assigned to the above intra prediction mode. The added intra prediction mode is determined by the left and above intra prediction modes as follows.

**[0093]** If one of the left and above intra prediction modes is a non-directional mode and the other is a directional mode, the other non-directional mode is added to the MPM group. For example, if the one of the left and above intra prediction modes is the DC mode, the planar mode is added to the MPM group. If the one of the left and above intra prediction modes is the planar mode, the DC mode is added to the MPM group. If both of the left and above intra prediction modes are non-directional modes, the vertical mode is added to the MPM group. If both of the left and above intra prediction modes are directional modes, the DC mode or the planar mode is added to the MPM group.

**[0094]** When only one of the left intra prediction mode and the above intra prediction mode is available, the available intra prediction mode is included in the MPM group and two additional intra prediction modes are added to the MPM group. The added two intra prediction modes are determined by the available intra prediction modes as follows.

**[0095]** If the available intra prediction mode is a non-directional mode, the other non-directional mode and the vertical mode are added to the MPM group. For example, if the available intra prediction mode is the DC mode, the planar mode and the vertical mode are added to the MPM group. If the available intra prediction mode is the planar mode, the DC mode and the vertical mode are added to the MPM group. If the available intra prediction mode is a directional mode, two non-directional modes (DC mode and planar mode) are added to the MPM group.

**[0096]** When both of the left intra prediction mode and the above intra prediction mode are available and are same each other, the available intra prediction mode is included in the MPM group and two additional intra prediction modes are added to the MPM group. The added two intra prediction modes are determined by the available intra prediction modes as follows.

**[0097]** If the available intra prediction mode is a directional mode, two neighboring directional modes are added to the MPM group. For example, if the available intra prediction mode is the mode 23, the left neighboring mode (mode 1) and the right neighboring mode (mode 13) are added to the MPM group. If the available intra prediction mode is the mode 30, the two

neighboring modes (mode 2 and mode 16) are added to the MPM group. If the available intra prediction mode is a non-directional mode, the other non-directional mode and the vertical mode are added to the MPM group. For example, if the available intra prediction mode is the DC mode, the planar mode and the vertical mode are added to the MPM group.

**[0098]** When both of the left intra prediction mode and the above intra prediction mode are unavailable, three additional intra prediction modes are added to the MPM group. The three intra prediction modes are the DC mode, the planar mode and the vertical mode. Indexes 0, 1 and 2 are assigned to the three intra prediction modes in the order of the DC mode, the planar mode and the vertical mode or in the order of the planar mode, the DC mode and the vertical mode.

**[0099]** It is determined whether the mode group indicator indicates the MPM group (S322).

**[0100]** If the mode group indicator indicates the MPM group, the intra prediction of the MPM group specified by the prediction mode index is set as the intra prediction mode of the current prediction unit (S323).

**[0101]** If the mode group indicator does not indicate the MPM group, the intra prediction of the residual mode group specified by the prediction mode index is set as the intra prediction mode of the current prediction unit (S324). The intra prediction mode of the current unit is derived using the prediction mode index and the intra prediction modes of the MPM group as the following ordered steps.

**[0102]** Among the three intra prediction modes of the MPM group, the intra prediction mode with lowest mode number is set to a first candidate, the intra prediction mode with middle mode number is set to a second candidate, and the intra prediction mode with highest mode number is set to a third candidate.

1. 1) The prediction mode index is compared with the first candidate. If the prediction mode index is equal to or greater than the first candidate of the MPM group, the value of the prediction mode index is increased by one. Otherwise, the value of the prediction mode index is maintained.
2. 2) The prediction mode index is compared with the second candidate. If the prediction mode index is equal to or greater than the second candidate of the MPM group, the value of the prediction mode index is increased by one. Otherwise, the value of the prediction mode index is maintained.
3. 3) The prediction mode index is compared with the third candidate. If the prediction mode index is equal to or greater than the third candidate of the MPM group, the value of the prediction mode index is increased by one. Otherwise, the value of the prediction mode index is maintained.
4. 4) The value of the final prediction mode index is set as the mode number of the intra prediction mode of the current prediction unit.



**[0103]** A size of the prediction block is determined based on the transform size information specifying the size of the transform unit (S330). The transform size information may be one or more `split_transform_flags` specifying the size of the transform unit.

**[0104]** If the size of the transform unit is equal to the size of the current prediction unit, the size of the prediction block is equal to the size of the current prediction unit.

**[0105]** If the size of the transform unit is smaller than the size of the current prediction unit, the size of the prediction block is equal to the size of the transform unit. In this case, a process of generating a reconstructed block is performed on each sub-block of the current prediction unit. That is, a prediction block and a residual block of a current sub-block are generated and a reconstructed block of each sub-block is generated by adding the prediction block and the residual block. Then, a prediction block, a residual block and a reconstructed block of the next sub-block in decoding order are generated. The restored intra prediction mode is used to generate all prediction blocks of all sub-block. Some pixels of the reconstructed block of the current sub-block are used as reference pixels of the next sub-block. Therefore, it is possible to generate a prediction block which is more similar to the original sub-block.

**[0106]** Next, it is determined whether all reference pixels of the current block are available, and reference pixels are generated if one or more reference pixels are unavailable (S340). The current block is the current prediction unit or the current sub-block. The size of the current block is the size of the transform unit.

**[0107]** FIG. 8 is a conceptual diagram illustrating the positions of reference pixels of the current block according to the present invention. As shown in FIG. 8, the reference pixels of the current blocks are comprised of above reference pixels located at  $(x=0, \dots, 2N-1, y=-1)$ , left reference pixels located at  $(x=-1, y=0, \dots, 2M-1)$  and a corner pixel located at  $(x=-1, y=-1)$ .  $N$  is the width of the current block and  $M$  is the height of the current block.

**[0108]** If reconstructed pixels do not exist at corresponding positions or reconstructed pixels are located within another slice, the reference pixels are set as unavailable. In constrained intra prediction mode (CIP mode), the reconstructed pixels of inter mode are also set as unavailable.

**[0109]** If one or more reference pixels are unavailable, one or more reference pixels are generated for the one or more unavailable reference pixels as follows.

**[0110]** If all reference pixels are unavailable, the value of  $2^{L-1}$  is substituted for the values of all the reference pixels. The value of  $L$  is the number of bits used to represent luminance pixel value.

**[0111]** If available reference pixels are located at only one side of the unavailable reference pixel, the value of the reference pixel nearest to the unavailable pixel is substituted for the

unavailable reference pixel.

**[0112]** If available reference pixels are located at both sides of the unavailable reference pixel, the average value of the reference pixels nearest to the unavailable pixel in each side or the value of the reference pixel nearest to the unavailable pixel in a predetermined direction is substituted for each unavailable reference pixel.

**[0113]** Next, the reference pixels are adaptively filtered based on the intra prediction mode and the size of the current block (S350). The size of the current block is the size of the transform unit.

**[0114]** In the DC mode, the reference pixels are not filtered. In the vertical mode and the horizontal mode, the reference pixels are not filtered. In the directional modes other than the vertical and horizontal modes, the reference pixels are adaptively according to the size of the current block.

**[0115]** If the size of the current block is 4x4, the reference pixels are not filtered in all intra prediction modes. For the size 8x8, 16x16 and 32x32, the number of intra prediction mode where the reference pixels are filtered increases as the size of the current block becomes larger. For example, the reference pixels are not filtered in the vertical mode and a predetermined number of neighboring intra prediction mode of the vertical mode. The reference pixels are also not filtered in the horizontal mode and the predetermined number of neighboring intra prediction mode of the horizontal mode. The predetermined number is one of 0~7 and decreases as the size of the current block increases.

**[0116]** Next, a prediction block of the current block is generated using the reference pixels according to the restored intra prediction mode (S360).

**[0117]** In the DC mode, the prediction pixel of the prediction block which is not adjacent to the reference pixel is generated by averaging the N reference pixels located at  $(x=0, \dots, N-1, y=-1)$  and the M reference pixels located at  $(x=-1, y=0, \dots, M-1)$ . The prediction pixel adjacent to the reference pixel is generated using the average value and one or two adjacent reference pixels.

**[0118]** In the vertical mode, the prediction pixels which are not adjacent to the left reference pixel are generated by copying the value of the vertical reference pixel. The prediction pixels which are adjacent to the left reference pixel are generated by the vertical reference pixel and variance between the corner pixel and the left neighboring pixel.

**[0119]** In the horizontal mode, the prediction pixels are generated using the same method.

**[0120]** FIG. 9 is a block diagram illustrating an apparatus of generating a prediction block in intra prediction.

**[0121]** The apparatus 300 includes a parsing unit 310, a prediction mode decoding unit 320, a

prediction size determining unit 330, a reference availability checking unit 340, a reference pixel generating unit 350, a reference pixel filtering unit 360 and a prediction block generating unit 370.

**[0122]** The parsing unit 310 restores the intra prediction information of the current prediction unit from the bit stream.

**[0123]** The intra prediction information includes the mode group indicator and a prediction mode index. The mode group indicator is a flag indicating whether the intra prediction mode of the current prediction unit belongs to a most probable mode group (MPM group). If the flag is 1, the intra prediction unit of the current prediction unit belongs to the MPM group. If the flag is 0, the intra prediction unit of the current prediction unit belongs to a residual mode group. The residual mode group includes all intra prediction modes other than the intra prediction modes belonging to the MPM group. The prediction mode index specifies the intra prediction mode of the current prediction unit within the group specified by the mode group indicator.

**[0124]** The prediction mode decoding unit 320 includes a MPM group constructing unit 321 and a prediction mode restoring unit 322.

**[0125]** The MPM group constructing unit 321 constructs the MPM group of the current prediction unit. The MPM group is constructed using intra prediction modes of the neighboring prediction units. The intra prediction modes of the MPM group are adaptively determined by a left intra prediction mode and an above intra prediction mode. The left intra prediction mode is the intra prediction mode of the left neighboring prediction unit, and the above intra prediction mode is the intra prediction mode of the above neighboring prediction unit. The MPM group is comprised of three intra prediction modes.

**[0126]** The MPM group constructing unit 321 checks the availability of the left intra prediction mode and the above intra prediction mode. If the left or above neighboring prediction unit does not exist, the intra prediction mode of the left or above neighboring unit is set as unavailable. For example, if the current prediction unit is located at the left or upper boundary of a picture, the left or above neighboring prediction unit does not exist. If the left or above neighboring unit is located within other slice or other tile, the intra prediction mode of the left or above neighboring unit is set as unavailable. If the left or above neighboring unit is inter-coded, the intra prediction mode of the left or above neighboring unit is set as unavailable. If the above neighboring unit is located within other LCU, the intra prediction mode of the left or above neighboring unit is set as unavailable.

**[0127]** The MPM group constructing unit 321 constructs the MPM group as follows.

**[0128]** When both of the left intra prediction mode and the above intra prediction mode are available and are different each other, the left intra prediction mode and the above intra prediction mode are included in the MPM group and one additional intra prediction mode is added to the MPM group. Index 0 is assigned to one intra prediction mode of small mode

number and index 1 is assigned to the other. Or index 0 is assigned to the left intra prediction mode and index 1 is assigned to the above intra prediction mode. The added intra prediction mode is determined by the left and above intra prediction modes as follows.

**[0129]** If one of the left and above intra prediction modes is a non-directional mode and the other is a directional mode, the other non-directional mode is added to the MPM group. For example, if the one of the left and above intra prediction modes is the DC mode, the planar mode is added to the MPM group. If the one of the left and above intra prediction modes is the planar mode, the DC mode is added to the MPM group. If both of the left and above intra prediction modes are non-directional modes, the vertical mode is added to the MPM group. If both of the left and above intra prediction modes are directional modes, the DC mode or the planar mode is added to the MPM group.

**[0130]** When only one of the left intra prediction mode and the above intra prediction mode is available, the available intra prediction mode is included in the MPM group and two additional intra prediction modes are added to the MPM group. The added two intra prediction modes are determined by the available intra prediction modes as follows.

**[0131]** If the available intra prediction mode is a non-directional mode, the other non-directional mode and the vertical mode are added to the MPM group. For example, if the available intra prediction mode is the DC mode, the planar mode and the vertical mode are added to the MPM group. If the available intra prediction mode is the planar mode, the DC mode and the vertical mode are added to the MPM group. If the available intra prediction mode is a directional mode, two non-directional modes (DC mode and planar mode) are added to the MPM group.

**[0132]** When both of the left intra prediction mode and the above intra prediction mode are available and are same each other, the available intra prediction mode is included in the MPM group and two additional intra prediction modes are added to the MPM group. The added two intra prediction modes are determined by the available intra prediction modes as follows.

**[0133]** If the available intra prediction mode is a directional mode, two neighboring directional modes are added to the MPM group. For example, if the available intra prediction mode is the mode 23, the left neighboring mode (mode 1) and the right neighboring mode (mode 13) are added to the MPM group. If the available intra prediction mode is the mode 30, the two neighboring modes (mode 2 and mode 16) are added to the MPM group. If the available intra prediction mode is a non-directional mode, the other non-directional mode and the vertical mode are added to the MPM group. For example, if the available intra prediction mode is the DC mode, the planar mode and the vertical mode are added to the MPM group.

**[0134]** When both of the left intra prediction mode and the above intra prediction mode are unavailable, three additional intra prediction modes are added to the MPM group. The three intra prediction modes are the DC mode, the planar mode and the vertical mode. Indexes 0, 1 and 2 are assigned to the three intra prediction modes in the order of the DC mode, the planar

mode and the vertical mode or in the order of the planar mode, the DC mode and the vertical mode.

**[0135]** The prediction mode restoring unit 322 derives the intra prediction mode of the current prediction unit using the mode group indicator and the prediction mode index as follows.

**[0136]** The prediction mode restoring unit 322 determines whether the mode group indicator indicates the MPM group.

**[0137]** If the mode group indicator indicates the MPM group, the prediction mode restoring unit 322 determines the intra prediction of the MPM group specified by the prediction mode index as the intra prediction mode of the current prediction unit.

**[0138]** If the mode group indicator does not indicate the MPM group, the prediction mode restoring unit 322 determines the intra prediction of the residual mode group specified by the prediction mode index as the intra prediction mode of the current prediction unit. The intra prediction mode of the current unit is derived using the prediction mode index and the intra prediction modes of the MPM group as the following ordered steps.

**[0139]** Among the three intra prediction modes of the MPM group, the intra prediction mode with lowest mode number is set to a first candidate, the intra prediction mode with middle mode number is set to a second candidate, and the intra prediction mode with highest mode number is set to a third candidate.

1. 1) The prediction mode index is compared with the first candidate. If the prediction mode index is equal to or greater than the first candidate of the MPM group, the value of the prediction mode index is increased by one. Otherwise, the value of the prediction mode index is maintained.
2. 2) The prediction mode index is compared with the second candidate. If the prediction mode index is equal to or greater than the second candidate of the MPM group, the value of the prediction mode index is increased by one. Otherwise, the value of the prediction mode index is maintained.
3. 3) The prediction mode index is compared with the third candidate. If the prediction mode index is equal to or greater than the third candidate of the MPM group, the value of the prediction mode index is increased by one. Otherwise, the value of the prediction mode index is maintained.
4. 4) The value of the final prediction mode index is set as the mode number of the intra prediction mode of the current prediction unit.

**[0140]** The prediction size determining unit 330 determines the size of the prediction block based on the transform size information specifying the size of the transform unit. The transform size information may be one or more `split_transform_flags` specifying the size of the transform unit.

**[0141]** If the size of the transform unit is equal to the size of the current prediction unit, the size of the prediction block is equal to the size of the current prediction unit.

**[0142]** If the size of the transform unit is smaller than the size of the current prediction unit, the size of the prediction block is equal to the size of the transform unit. In this case, a process of generating a reconstructed block is performed on each sub-block of the current prediction unit. That is, a prediction block and a residual block of a current sub-block are generated and a reconstructed block of each sub-block is generated by adding the prediction block and the residual block. Then, a prediction block, a residual block and a reconstructed block of the next sub-block in decoding order are generated. The restored intra prediction mode is used to generate all prediction blocks of all sub-block. Some pixels of the reconstructed block of the current sub-block are used as reference pixels of the next sub-block. Therefore, it is possible to generate a prediction block which is more similar to the original sub-block.

**[0143]** The reference pixel availability checking unit 340 determines whether all reference pixels of the current block are available. The current block is the current prediction unit or the current sub-block. The size of the current block is the size of the transform unit.

**[0144]** The reference pixel generating unit 350 generates reference pixels if one or more reference pixels of the current block are unavailable.

**[0145]** If all reference pixels are unavailable, the value of  $2^{L-1}$  is substituted for the values of all the reference pixels. The value of L is the number of bits used to represent luminance pixel value.

**[0146]** If available reference pixels are located at only one side of the unavailable reference pixel, the value of the reference pixel nearest to the unavailable pixel is substituted for the unavailable reference pixel.

**[0147]** If available reference pixels are located at both sides of the unavailable reference pixel, the average value of the reference pixels nearest to the unavailable pixel in each side or the value of the reference pixel nearest to the unavailable pixel in a predetermined direction is substituted for each unavailable reference pixel.

**[0148]** The reference pixel filtering unit 360 adaptively filters the reference pixels based on the intra prediction mode and the size of the current block.

**[0149]** In the DC mode, the reference pixels are not filtered. In the vertical mode and the horizontal mode, the reference pixels are not filtered. In the directional modes other than the vertical and horizontal modes, the reference pixels are adaptively according to the size of the current block.

**[0150]** If the size of the current block is 4x4, the reference pixels are not filtered in all intra

prediction modes. For the size 8x8, 16x16 and 32x32, the number of intra prediction mode where the reference pixels are filtered increases as the size of the current block becomes larger. For example, the reference pixels are not filtered in the vertical mode and a predetermined number of neighboring intra prediction mode of the vertical mode. The reference pixels are also not filtered in the horizontal mode and the predetermined number of neighboring intra prediction mode of the horizontal mode. The predetermined number is one of 0~7 and decreases as the size of the current block increases.

**[0151]** The prediction block generating unit 370 generates a prediction block of the current block using the reference pixels according to the restored intra prediction mode.

**[0152]** In the DC mode, the prediction pixel of the prediction block which is not adjacent to the reference pixel is generated by averaging the N reference pixels located at  $(x=0, \dots, N-1, y=-1)$  and the M reference pixels located at  $(x=-1, y=0, \dots, M-1)$ . The prediction pixel adjacent to the reference pixel is generated using the average value and one or two adjacent reference pixels.

**[0153]** In the vertical mode, the prediction pixels which are not adjacent to the left reference pixel are generated by copying the value of the vertical reference pixel. The prediction pixels which are adjacent to the left reference pixel are generated by the vertical reference pixel and variance between the corner pixel and the left neighboring pixel.

**[0154]** In the horizontal mode, the prediction pixels are generated using the same method.

**[0155]** While the invention has been shown and described with reference to certain exemplary embodiments thereof, it will be understood by those skilled in the art that various changes in form and details may be made therein without departing from the scope of the invention as defined by the appended claims.

## REFERENCES CITED IN THE DESCRIPTION

### Cited references

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## P A T E N T K R A V

1. Afkodningsfremgangsmåde til at generere en forudsigelsesblok i intra-forudsigelse, hvilken fremgangsmåde omfatter:

5 at genoprette en tilstandsgruppeindikator og et forudsigelsestilstandsindex, hvor tilstandsgruppeindikatoren angiver, om en intra-forudsigelsestilstand af en aktuel blok er én af forudsigelsestilstande i en mest sandsynlig tilstand, MPM-gruppe, eller ej, og forudsigelsestilstandsindexet angiver en intra-forudsigelsestilstand til at være intra-forudsigelsestilstanden af den aktuelle blok;

10 at konstruere den mest sandsynlige tilstand, MPM-gruppen, indbefattende tre intra-forudsigelsestilstande;

at bestemme en intra-forudsigelsestilstand specificeret af forudsigelsestilstandsindexet i MPM-gruppen som intra-forudsigelsestilstanden af den aktuelle blok, hvis tilstandsgruppeindikatoren angiver MPM-gruppen, og at opnå intra-forudsigelsestilstanden af den aktuelle blok ved brug af forudsigelsestilstandsindexet og de tre intra-forudsigelsestilstande af MPM-gruppen, hvis tilstandsgruppeindikatoren ikke angiver MPM-gruppen;

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at bestemme en størrelse af forudsigelsesblokken baseret på transformationsstørrelsesinformation, hvor transformationsstørrelsesinformationen er størrelsen af en transformationsenhed, i hvilken et residualsignal, som genereres ved brug af en original blok og en forudsigelsesblok, transformeres;

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at bestemme om alle referencepixler af den aktuelle blok er tilgængelige;

at generere referencepixler, hvis én eller flere referencepixler af den aktuelle blok er utilgængelige;

at adaptivt filtrere referencepixlerne baseret på intra-forudsigelsestilstanden af den aktuelle blok og størrelsen af den aktuelle blok; og

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at generere forudsigelsesblokken ved brug af referencepixlerne baseret på intra-forudsigelsestilstanden af den aktuelle blok,

hvor hvis kun én af en venstre intra-forudsigelsestilstand og en øvre intra-forudsigelsestilstand er tilgængelig, så indbefatter MPM-gruppen den tilgængelige intra-forudsigelsestilstand og to yderligere intra-forudsigelsestilstande, og hvis den tilgængelige intra-forudsigelsestilstand er én af to ikke-retningsbestemte intra-forudsigelsesblokke, så er de to yderligere intra-forudsigelsestilstande den anden af de to ikke-retningsbestemte intra-forudsigelsestilstande og en vertikal tilstand, og hvis den tilgængelige intra-forudsigelsestilstand er én af retningsbestemte intra-forudsigelsestilstande, så er de to yderligere intra-forudsigelsestilstande to ikke-retningsbestemte intra-forudsigelsestilstande, og

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hvor hvis tilstandsgruppeindikatoren ikke angiver MPM-gruppen, at bestemme intra-forudsigelsestilstanden af den aktuelle blok ved at udføre de ordnede trin:

at øge en værdi af forudsigelsestilstandsindexet med én, hvis forudsigelsestil-

standsindexet er lig med eller større end en første intra-forudsigelsestilstand af MPM-gruppen;

at øge værdien af forudsigelsestilstandsindexet med én, hvis forudsigelsestilstandsindexet er lig med eller større end en anden intra-forudsigelsestilstand af MPM-gruppen;

5 at øge værdien af forudsigelsestilstandsindexet med én, hvis forudsigelsestilstandsindexet er lig med eller større end en tredje intra-forudsigelsestilstand af MPM-gruppen; og

at bestemme værdien af forudsigelsestilstandsindexet som tilstandsnummeret af intra-forudsigelsestilstanden af den aktuelle blok,

10 hvor den første intra-forudsigelsestilstand er en intra-forudsigelsestilstand med det laveste tilstandsnummer, den anden intra-forudsigelsestilstand er en intra-forudsigelsestilstand med midtertilstandsnummer og den tredje intra-forudsigelsestilstand er en intra-forudsigelsestilstand med det højeste tilstandsnummer, og hvor de to ikke-retningsbestemte intra-forudsigelsestilstande er en DC-tilstand og en plan tilstand.

15 2. Fremgangsmåde ifølge krav 1, hvor når den venstre intra-forudsigelsestilstand er lig med den øvre intra-forudsigelsestilstand, og den venstre intra-forudsigelsestilstand er en ikke-retningsbestemt intra-forudsigelsestilstand, så indbefatter MPM-gruppen to ikke-retningsbestemte intra-forudsigelsestilstande og den vertikale tilstand.

3. Fremgangsmåde ifølge krav 1, hvor hvis størrelsen af den aktuelle blok er 4x4, så 20 filtreres referencepixlerne ikke, og hvis størrelsen af den aktuelle blok er større end 4x4, så stiger antallet af intra-forudsigelsestilstande, hvor referencepixlerne filtreres, når størrelsen af den aktuelle blok bliver større.

4. Fremgangsmåde ifølge krav 1, hvor i den vertikale tilstand genereres forudsigelsepixels af forudsigelsesblokken, som er nærliggende venstre referencepixels, ved brug af 25 en vertikal referencepixel og en varians mellem en hjørnepixel og en venstre nabopixel.

5. Kodningsfremgangsmåde til at generere en forudsigelsesblok i intra-forudsigelse, hvilken fremgangsmåde omfatter:

at generere en tilstandsgruppeindikator og et forudsigelsestilstandsindex, hvor tilstandsgruppeindikatoren angiver, om en intra-forudsigelsestilstand af en aktuel blok er én 30 af forudsigelsestilstande i en mest sandsynlig tilstand, MPM-gruppe, eller ej, og forudsigelsestilstandsindexet angiver en intra-forudsigelsestilstand til at være intra-forudsigelsestilstanden af den aktuelle blok;

at konstruere en mest sandsynlig tilstand (MPM) gruppe indbefattende tre intra-forudsigelsestilstande af den aktuelle blok;

35 at bestemme om alle referencepixels er tilgængelige;

at generere referencepixels hvis én eller flere referencepixels af den aktuelle blok er utilgængelige;

at adaptivt filtrere referencepixlerne baseret på intra-forudsigelsestilstanden af den aktuelle blok og en størrelse af den aktuelle blok; og

at generere forudsigelsesblokken ved brug af referencepixlerne baseret på intra-forudsigelsestilstanden af den aktuelle blok,

hvor hvis kun én af en venstre intra-forudsigelsestilstand og en øvre intra-forudsigelsestilstand er tilgængelig, så indbefatter MPM-gruppen den tilgængelige intra-forudsigelsestilstand og to yderligere intra-forudsigelsestilstande, og hvis den tilgængelige intra-forudsigelsestilstand er én af to ikke-retningsbestemte intra-forudsigelsesblokke, så er de to yderligere intra-forudsigelsestilstande den anden af de to ikke-retningsbestemte intra-forudsigelsestilstande og en vertikal tilstand, og hvis den tilgængelige intra-forudsigelsestilstand er én af retningsbestemte intra-forudsigelsestilstande, så er de to yderligere intra-forudsigelsestilstande to ikke-retningsbestemte intra-forudsigelsestilstande, og

hvor, når en intra-forudsigelsestilstand af en aktuel blok tilhører MPM-gruppen, så angiver tilstandsgruppeindikatoren MPM-gruppen, og forudsigelsestilstandsindexet angiver intra-forudsigelsestilstanden af den aktuelle blok blandt de tre intra-forudsigelsestilstande i MPM-gruppen, og når intra-forudsigelsestilstanden af den aktuelle blok ikke tilhører MPM-gruppen, så angiver tilstandsgruppeindikatoren ikke MPM-gruppen, og forudsigelsestilstandsindexet specificerer intra-forudsigelsestilstanden af den aktuelle blok blandt intra-forudsigelsestilstande foruden de tre intra-forudsigelsestilstande i MPM-gruppen ved at udføre de ordnede trin:

at øge en værdi af forudsigelsestilstandsindexet med én, hvis forudsigelsestilstandsindexet er lig med eller større end en første intra-forudsigelsestilstand af MPM-gruppen;

at øge værdien af forudsigelsestilstandsindexet med én, hvis forudsigelsestilstandsindexet er lig med eller større end en anden intra-forudsigelsestilstand af MPM-gruppen;

at øge værdien af forudsigelsestilstandsindexet med én, hvis forudsigelsestilstandsindexet er lig med eller større end en tredje intra-forudsigelsestilstand af MPM-gruppen; og

at bestemme værdien af forudsigelsestilstandsindexet som tilstandsnummeret af intra-forudsigelsestilstanden af den aktuelle blok,

hvor den første intra-forudsigelsestilstand er en intra-forudsigelsestilstand med det laveste tilstandsnummer, den anden intra-forudsigelsestilstand er en intra-forudsigelsestilstand med midtertilstandsnummer, og den tredje intra-forudsigelsestilstand er en intra-forudsigelsestilstand med det højeste tilstandsnummer, og hvor de to ikke-retningsbestemte intra-forudsigelsestilstande er en DC-tilstand og en plan tilstand.

6. Fremgangsmåde ifølge krav 5, hvor når den venstre intra-forudsigelsestilstand er lig med den øvre intra-forudsigelsestilstand, og den venstre intra-forudsigelsestilstand er en ikke-retningsbestemt intra-forudsigelsestilstand, så indbefatter MPM-gruppen to ikke-retningsbestemte intra-forudsigelsestilstande og den vertikale tilstand.

## DRAWINGS

Drawing

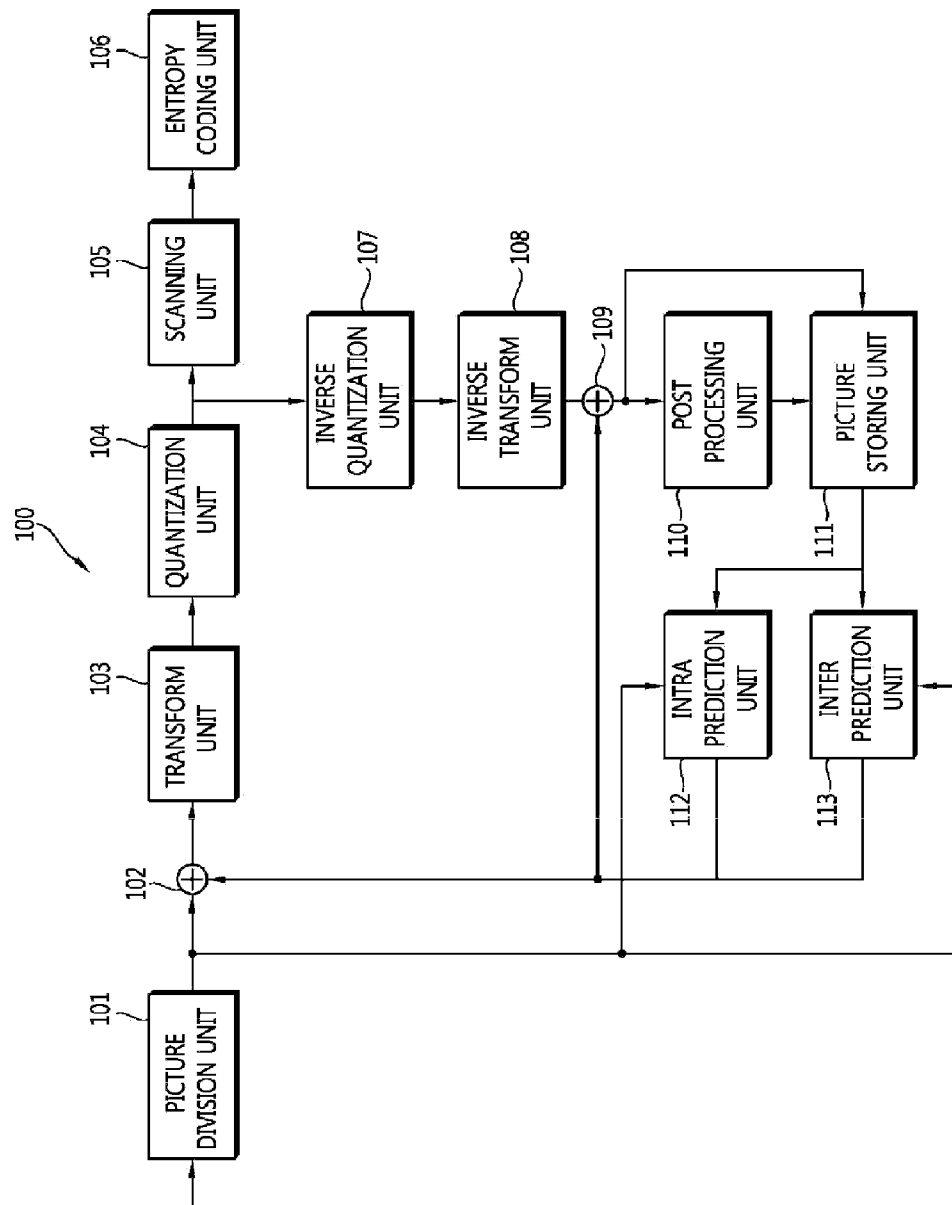


Fig. 1

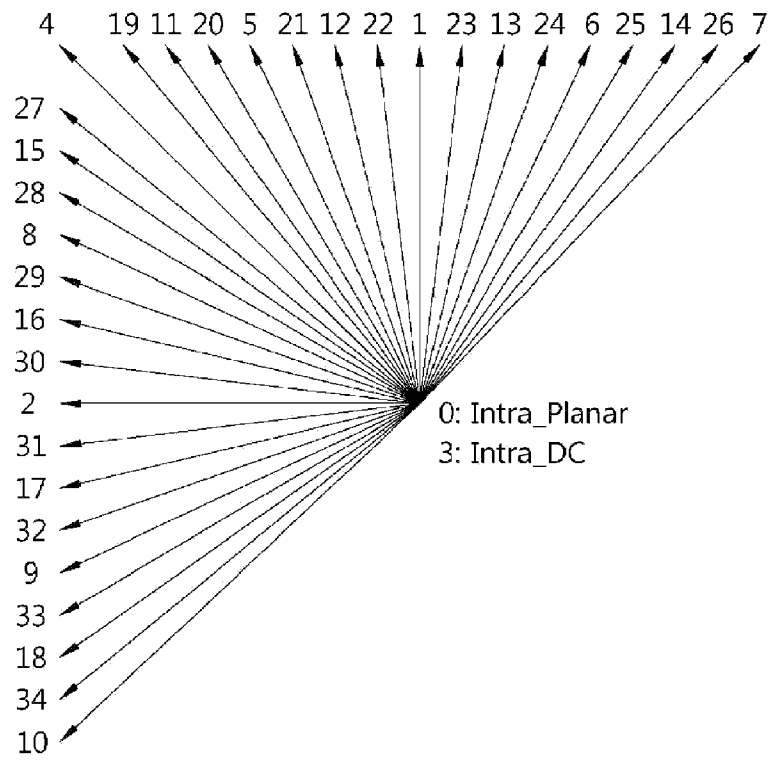


Fig. 2

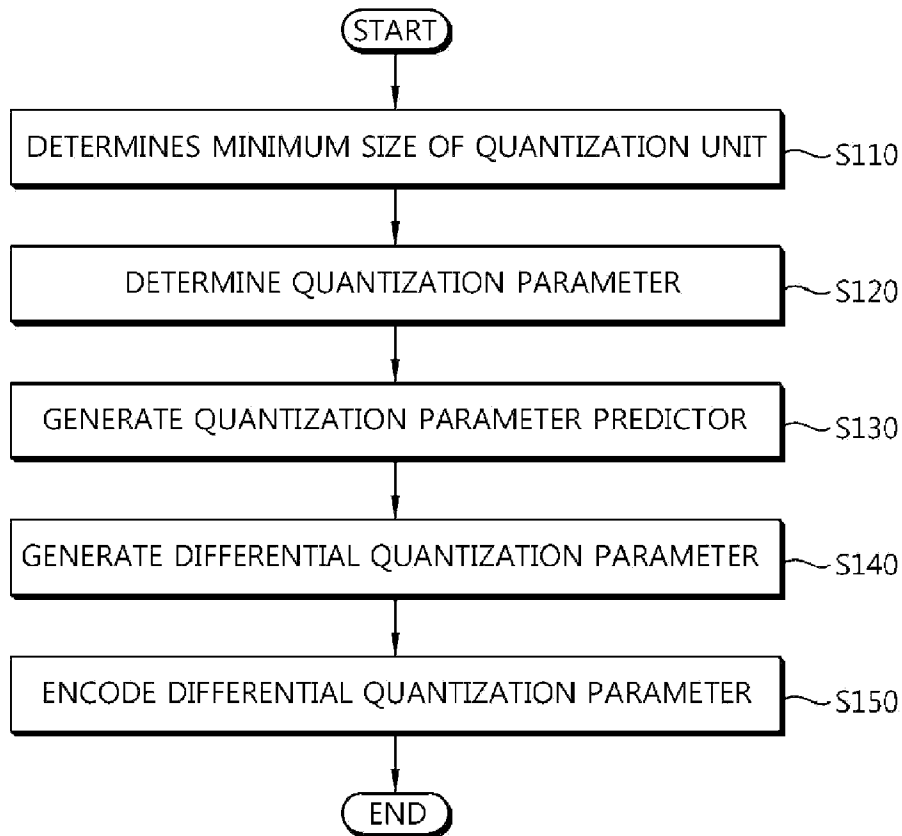


Fig. 3

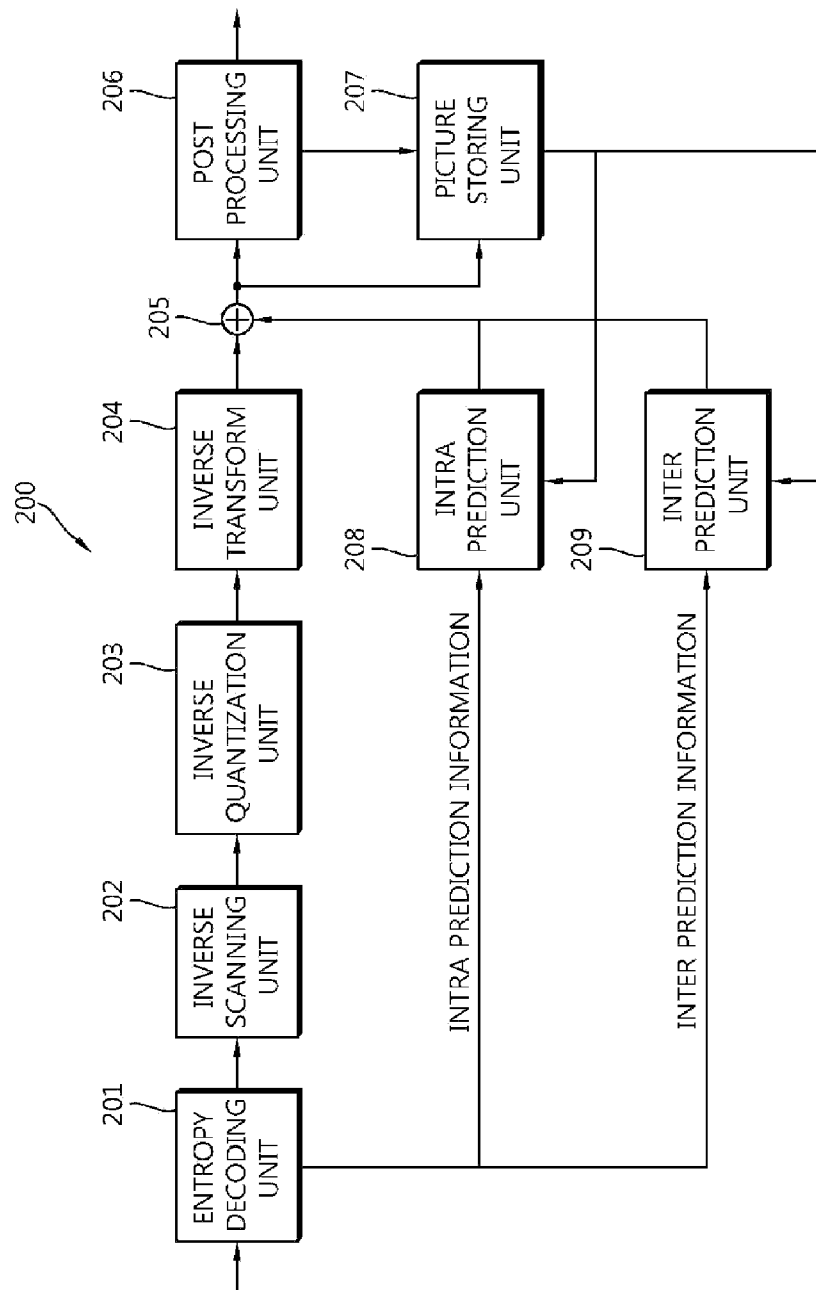
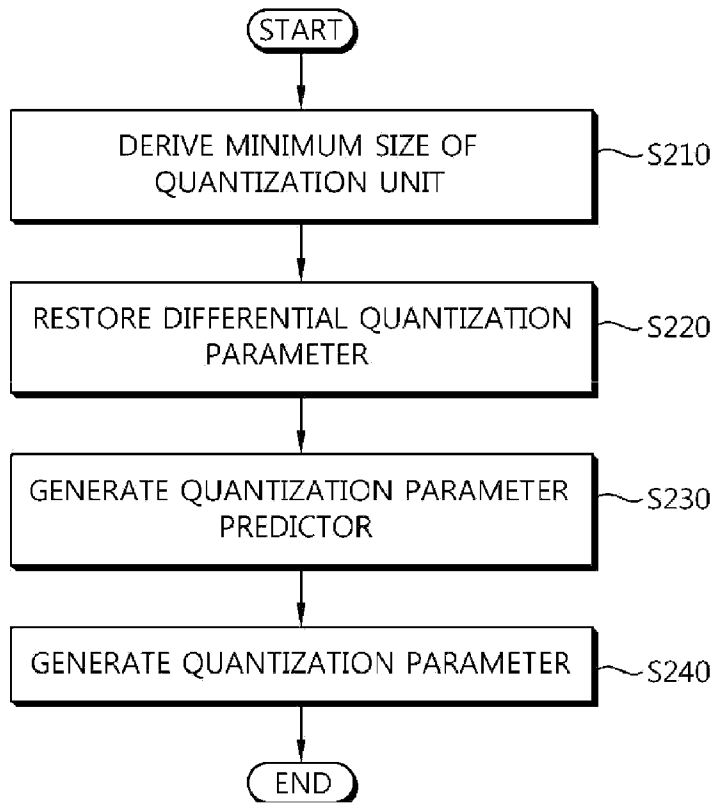


Fig. 4

**Fig. 5**



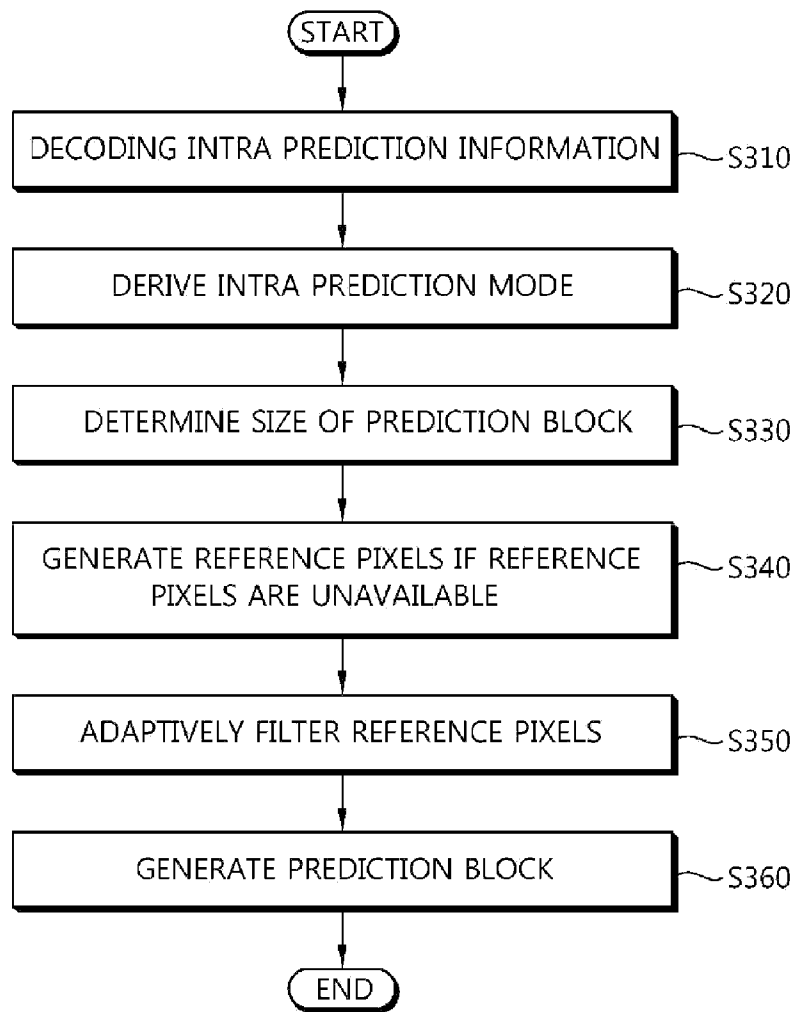


Fig. 6

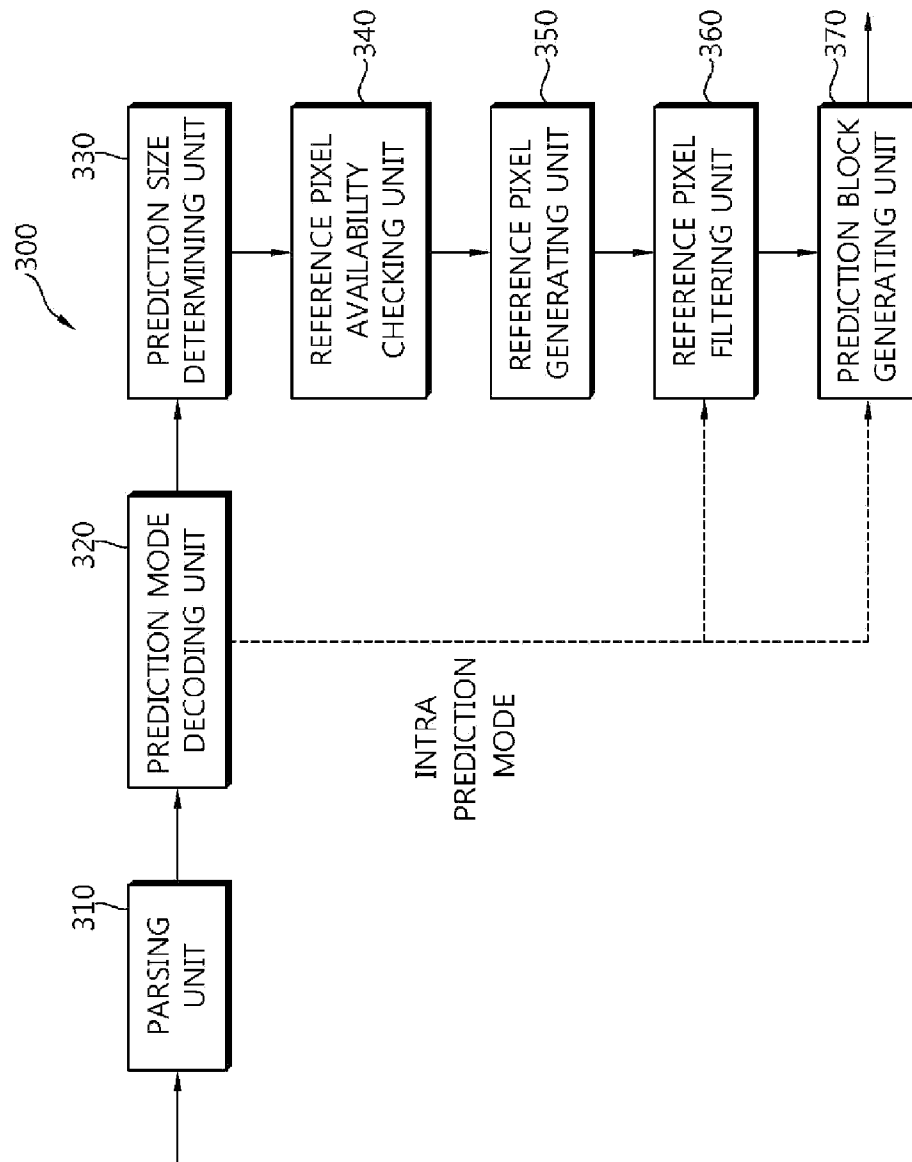


Fig. 7

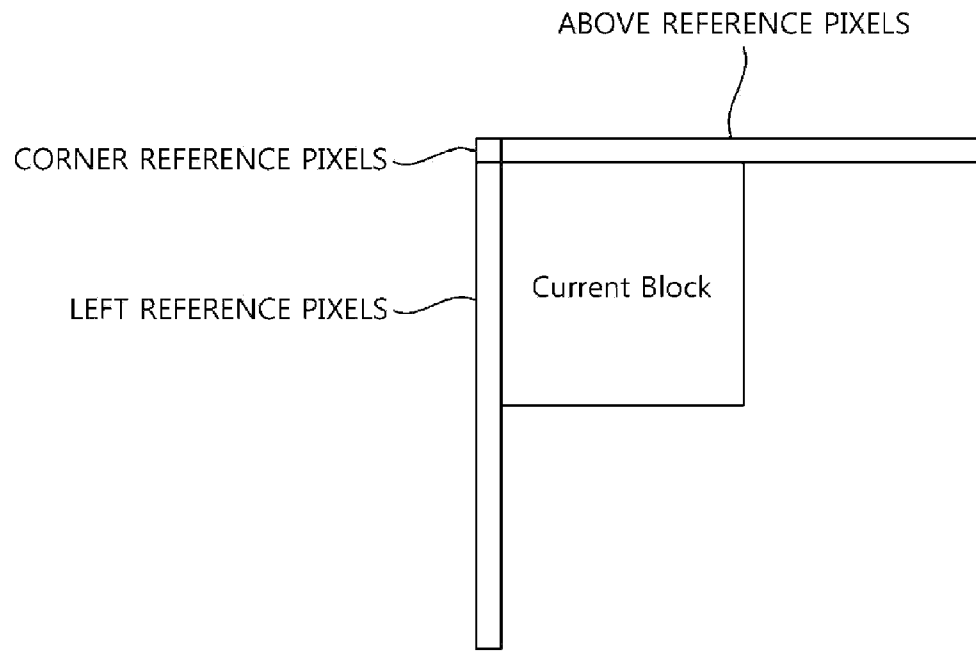


Fig. 8

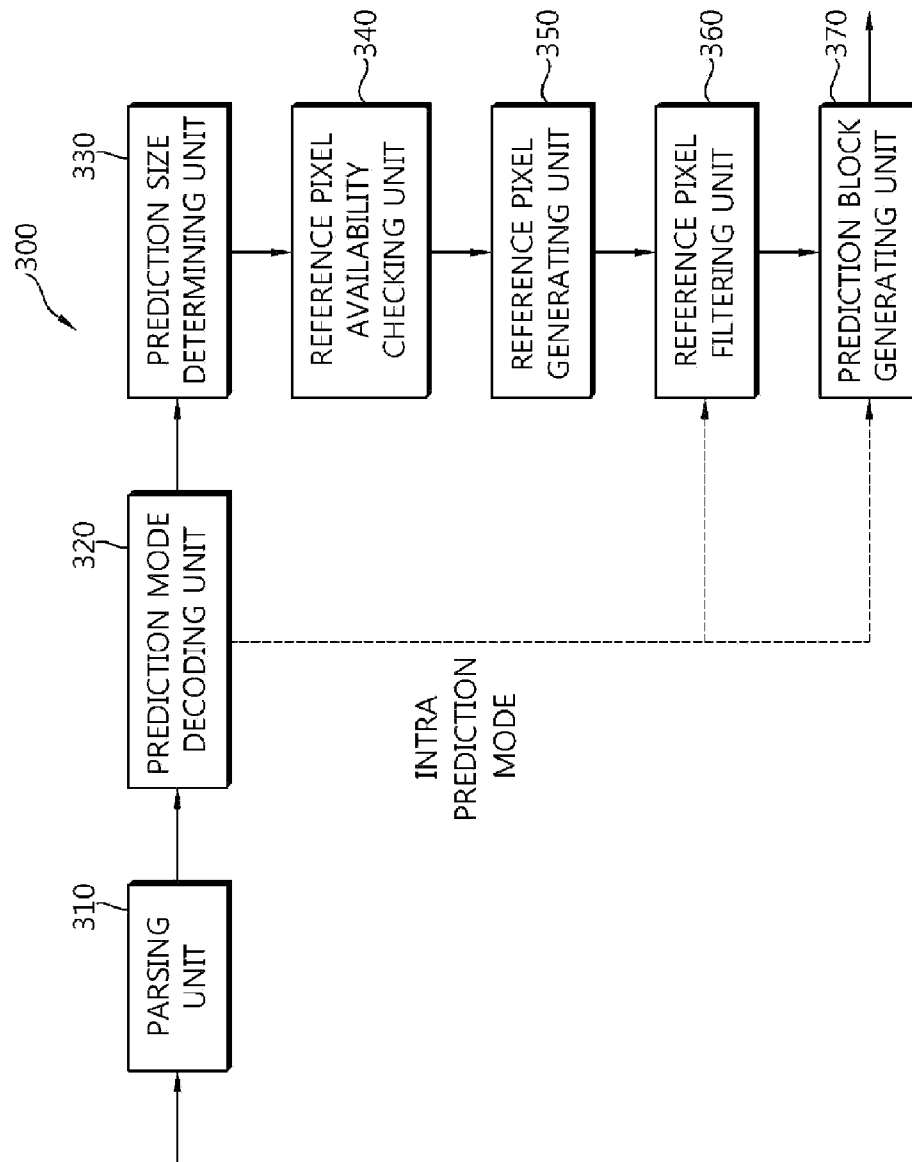


Fig. 9